

DataRay Inc. User Guide

WinCamD-LCM + M2DU M² system

Beam Profiling ... Engineered as a system
... Delivered as a Solution

Applies to: Software Ver. iDataRayLCMvA30.exe or higher, running under Windows 7 or 8.

Very Important: With full Administrator Rights, Install, Open and Close the latest Software before connecting the Camera or the Stage.

Short of time? Save yourself time by carefully following this User Guide the first time. Done properly once, the next time will be simple and fast.

Once done, for future convenience, so you need only look at page 1, copy your lens setup details from page 7.

Lens focal length	LD (User measured) See diagram pages 8	+(A-Zo Delta) See diagram page 8	= LPPSO (Enter in M2 dialog) Lens Principal Plane to Sensor at 0	Zo Delta (Enter in M2 dialog) Front of lens mount to Principal Plane

Applications

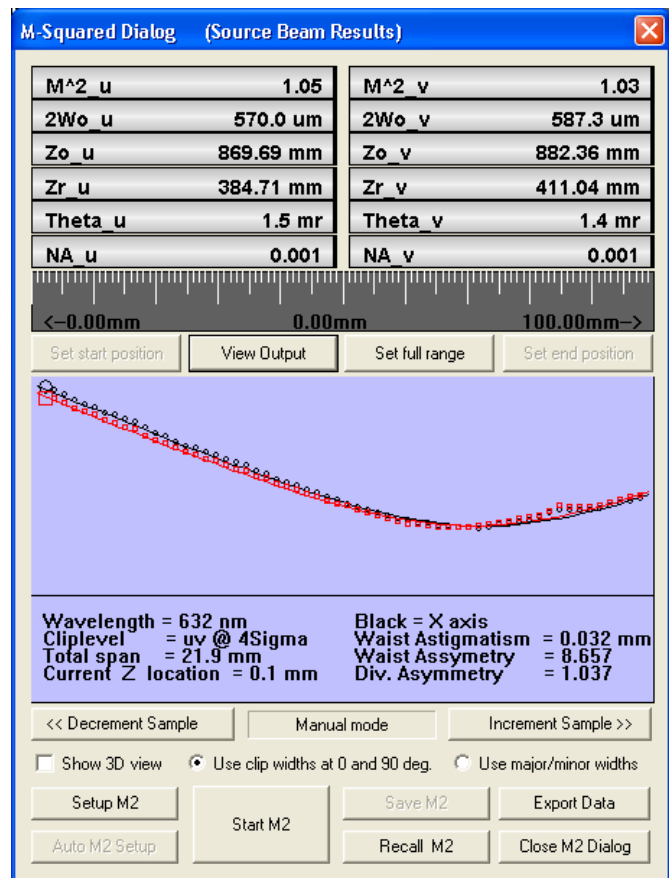
- M² measurement of CW & pulsed lasers
- M² measurement of focused beams
- Focus position of laser assemblies

Features

- **ASR™** Auto Scan Range for ISO compliant scan
- USB 2.0 & 3.0 for field service applications
- Fast, Compact, Portable system
L x W x H: 8 x 2.9 x 4.3" (200 x 109 x 74 mm)
Total weight 4 lb, (1.8 kg)
- Field-replaceable lens options

Contents

	Page
1) Description	2
2) Beam Modeling for Lens Selection	3
3) Parts List	4
4) Getting Started	4
5) Assemble the unit	5
6) Laser Safety	6
7) Preset the Attenuation level correctly	6
8) Start the Software	7
9) Align the Beam	8
10) Set the Capture Block	8
11) Check Exposure & optionally subtract residual noise	9
12) Perform a Coarse Scan	9
13) Perform a Final Scan	10
14) Source Beam Characteristics	10
15) Save the data	11
16) Second time around	12
17) Support	12
18) Manual M ² (with a different translation Stage)	13



Future software updates are downloadable from <http://www.dataray.com/downloads.html>

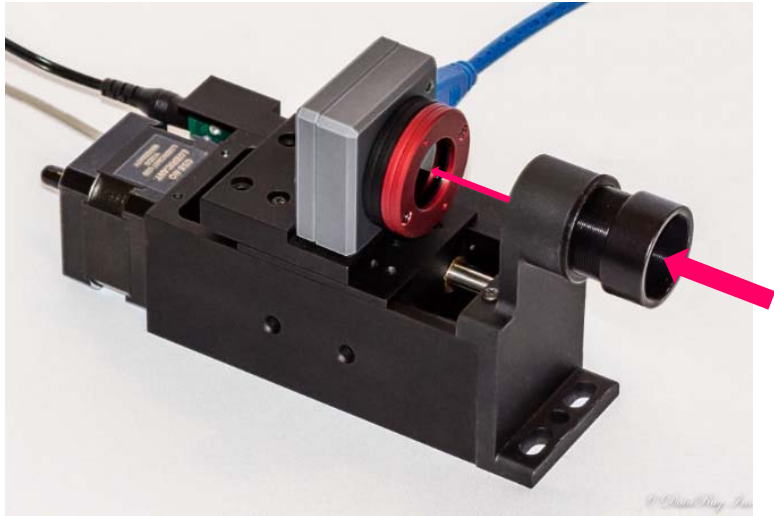
1) Description

The USB 2.0 **M2DU** accessory converts WinCamD-LCM beam profiling cameras into a compact fully ISO 11146 compliant, M^2 measurement system.

The **M2DU** system comprises a lens fixed to the front of a 42.5 mm travel stage on which the WinCamD is carried.

An achromat refocuses an input beam to a waist within the stage travel range. Lens focal lengths and coatings will be recommended/supplied. A spreadsheet simplifies the choice.

ASR™ auto-sampling measures the hyperbolic region about the waist and at $z_R > 2$ in accordance with the ISO standard. A least squares hyperbolic fit to the second moment diameter data allows calculation of the M^2 value and related parameters for both the focused beam and the source beam.



M^2 Beam Quality Factor - Explained

M^2 , or Beam Quality Factor, is a dimensionless parameter that characterizes the degree of imperfection of a real-world laser beam. The closer the M^2 value is to 1.0, - i.e. the closer the beam is to TEM_{00} Gaussian perfection - the closer the beam can be focused to its diffraction limited spot size.

Due to limitations of the optical cavity, the lasing medium, and/or the output/ancillary optics, most beams are not the 'perfect', diffraction-limited, Gaussian profile, pure TEM_{00} mode described in textbooks. Complex beams can contain multiple TEM_{xy} contributions leading to high values of M^2 .

At its simplest M^2 may be defined as: *The ratio of the divergence of the actual beam, to that of a theoretical, diffraction-limited TEM_{00} beam with the same waist diameter.*

Θ = The measured, far-field, full-angle divergence of the actual beam

θ = The theoretical far-field divergence of a 'perfect' TEM_{00} Gaussian beam which has the same waist diameter as the measured beam.

Where: $2W_0$ = The second moment (4σ) beam waist diameter.

The shape of the M^2 curve may be shown to be hyperbolic of the form:

$$2W(z) = 2W_0 \sqrt{1 + \left(\frac{z}{z_R}\right)^2}$$

Where z_R is the Rayleigh Range, defined as the distance at which the beam diameter is $\sqrt{2}$ greater than the diameter at the waist. z_R may be shown to be:

$$z_R = \frac{2W_0}{\Theta} = \frac{\pi W_0^2}{M^2 \lambda}$$

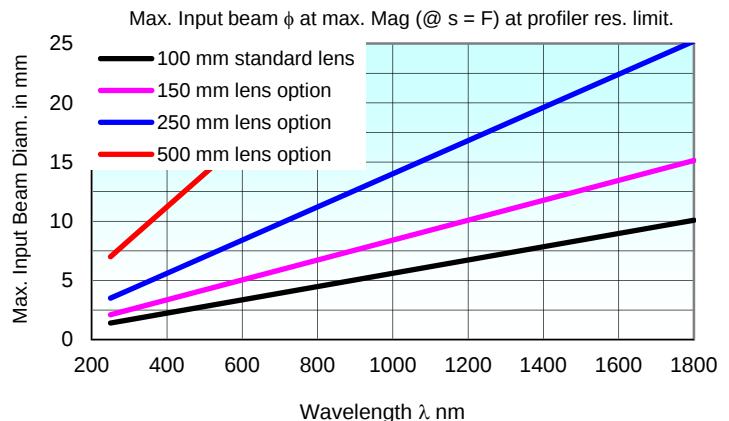
A definition of M^2 in terms of a measured diameter is:

$$M^2 = \left(\frac{\pi}{4\lambda}\right) \cdot \Theta \cdot 2W_0$$

Specifications

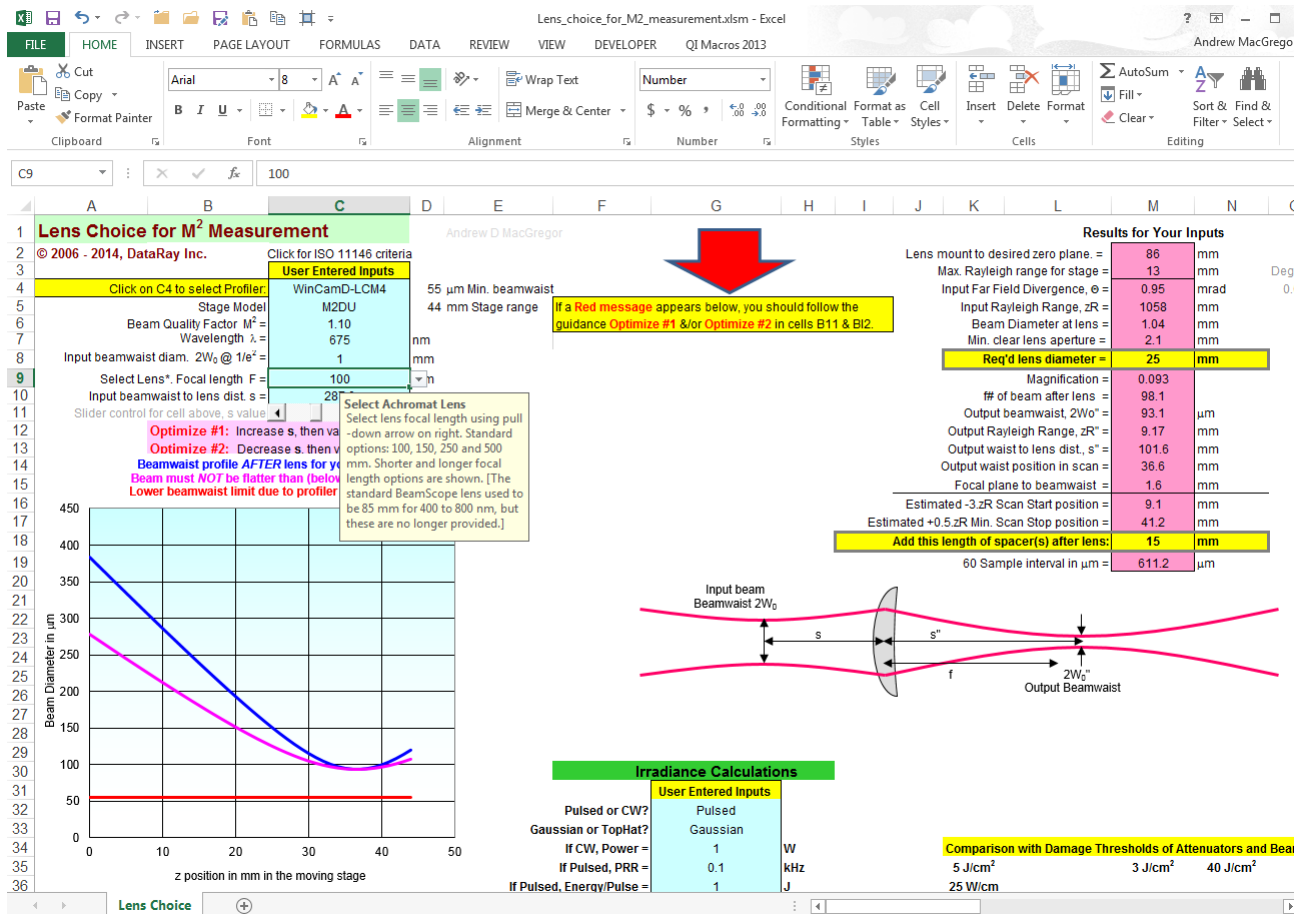
- **Max. beam diams.:** See graph right.
- **400 to 800 nm** with standard lens
- **266 to 1150 nm** with optional lenses
- To **1350 nm** on high power beams with optional lenses
- **M^2 Range*** 1 to >50
- **M^2 Accuracy*** $\pm 5\%$ typical
- **M^2 Repeatability*** $\pm 2\%$ typical

* Beam dependent. Achieving absolute accuracy better than $\pm 5\%$ is possible, but can be difficult.



2) Beam Modeling for Lens Selection

An intuitive Excel spreadsheet simplifies lens selection. You may have already received this spreadsheet during the purchase process. If not, download http://www.dataray.com/assets/xls/Lens_choice_for_M2_measurement.xlsm from the **Documentation** section at the website and model your beam in order to ensure that it can be correctly measured with the received system.



Enter the values for your beam in the light-blue shaded cells. The results of the Gaussian optics calculations appear in the dark pink shaded cells and a curve appears below.

The output data fields show several factors and highlights in yellow the required lens diameter plus the length of spacers required to place the beamwaist within the range of the stage.

The lines on the (auto-scaled) graph show:

- The estimated post-lens beamwaist profile.
- The calculated flattest acceptable beamwaist (maximum Rayleigh Range) for this stage.
- The minimum allowed beam waist for the chosen profiler.

If the beam waist is too small for the camera or the curve is too flat, warnings with advice will appear next to the values. You may need to be in the far field of the laser in order to form a beamwaist within the range of travel of the stage.

Avoid destruction of your camera sensor! For the calculated value of **2W₀'**, boxed in green above, from the curves in the WinCamD manual (page 1-7 for CW, 1-8 for pulsed), determine whether you will need to add additional sampling/attenuation in order to avoid saturation of the camera at the focus. If so add as required before proceeding.

An additional ND2.0 filter is provided as standard. Chapter 5 of the WinCamD manual describes attenuation and sampling solutions. DataRay offers additional ND filters, variable ND filters, wedge samplers, & holographic beam samplers to assist you.

3) Parts List

- **WinCamD-LCM** series head. The recommended default camera is the **WinCamD-LCM4**
- **M2DU-LCM** system comprising moving stage, lens mount and camera mount
- **LNZ-UV, -VIS, -NIR, or -TEL** lens system, with focal length options as below (may change)

Lens focal length options		Wavelength options
-75	100 mm focal length 22 mm aperture	
-100	100 mm focal length 22 mm aperture	
-150	150 mm focal length 22 mm aperture	-UV Fused silica singlet for 250-450 nm
LNZ -150-50	150 mm focal length 47 mm aperture	-VIS Achromat for 400-800 nm
-250	250 mm focal length 22 mm aperture	-NIR Achromat for 630-1100 nm
-250-50	250 mm focal length 47 mm aperture	-TEL Achromat for 1000-1800 nm
-500-50	500 mm focal length 47 mm aperture	

4) Getting Started

Short of time? Save yourself time by carefully following through this User Manual the first time that you use the equipment. Once you have done it properly once, the next time will be simple and fast.

This User Guide assumes that the WinCamD system is installed, has been run with the Version LCMvA30 or higher software in the PC you are to use, is working in your PC, and that you have already learned how to use the WinCamD in standard operation on beams from this laser. If this is not the case, first install the software, install and run the WinCamD, and understand its operation before working with the M2DU stage.

IMPORTANT: You will require Windows 7 or 8, **with ≥ 2 GB of RAM** for WinCamD-LCM. A *minimum* screen size of 1024 x 768 pixels is required. Recommended is 1280 x 1024 or higher.

If you do not have an M2DU stage and wish to perform an M² measurement using a different stage, manual or automatic, see Section 18).

Applicable Standard. ISO 11146, 'Test methods for laser beam parameters: Beam widths, divergence angle, and beam propagation factor' (Available from <http://webstore.ansi.org/ansidocstore/default.asp>), requires:

- Use of the Second Moment (4σ or Variance) definition of the beam diameter.
- Averaging of 5 samples at each position in z.
- A minimum of ten samples in z. '... half of them shall be distributed within one Rayleigh length on either side of the beam waist and half of them should be distributed beyond two Rayleigh lengths from the beam waist.' (DataRay offers from 10 to 60 samples in z). [Though this statement is slightly ambiguous, we interpret 'within one Rayleigh length' as $\pm(<z_R)$, and 'beyond two Rayleigh lengths' as $\pm(>2.z_R)$.]

For equi-spaced samples in z, and an initially unknown beam waist position, these sample position requirements of the standard are met by a minimum of 18 samples at $z_R/3$ intervals about the waist, e.g. from $-3.z_R$ to $+2.67z_R$. To ensure that we spatially sample the actual beamwaist diameter within 1% requires the z samples around the beamwaist to be spaced at $z_R/3.5$ intervals. [For equi-spaced samples, the samples in the $\pm z_R$ to $\pm 2.z_R$ region are additional to the specific requirements of the Standard, but may still be used in the calculation.]

The beam diameter equals: $2W_0$ at the beam waist

1% greater, = $2.02W_0$, at $\pm 0.14z_R$

2% greater, = $2.04W_0$, at $\pm 0.20z_R$

x 1.414 greater, = $2.83W_0$, at $\pm z_R$ (Rayleigh Ranges or 'length')

x 2.236 greater, = $4.47W_0$, at $\pm 2z_R$

$\times 2.692$ greater, = $5.38W_0$, at $\pm 2.5z_R$

$\times 3.162$ greater, = $6.32W_0$, at $\pm 3z_R$

ISO 11146 requirements can also be met by more samples at a higher sampling frequency in z_R .

- A least squares hyperbolic fit to the data.

Notes:

a) With a beam profile that is a pure Gaussian, the Variance (Second moment) definition is exactly the same as selecting a 13.5% Clip Level, but if your beam is non-Gaussian – which is most beams – the Variance method is more consistent. An exception to this general rule is that the presence of a significant background level above zero or background noise will skew the Variance reading to larger values.

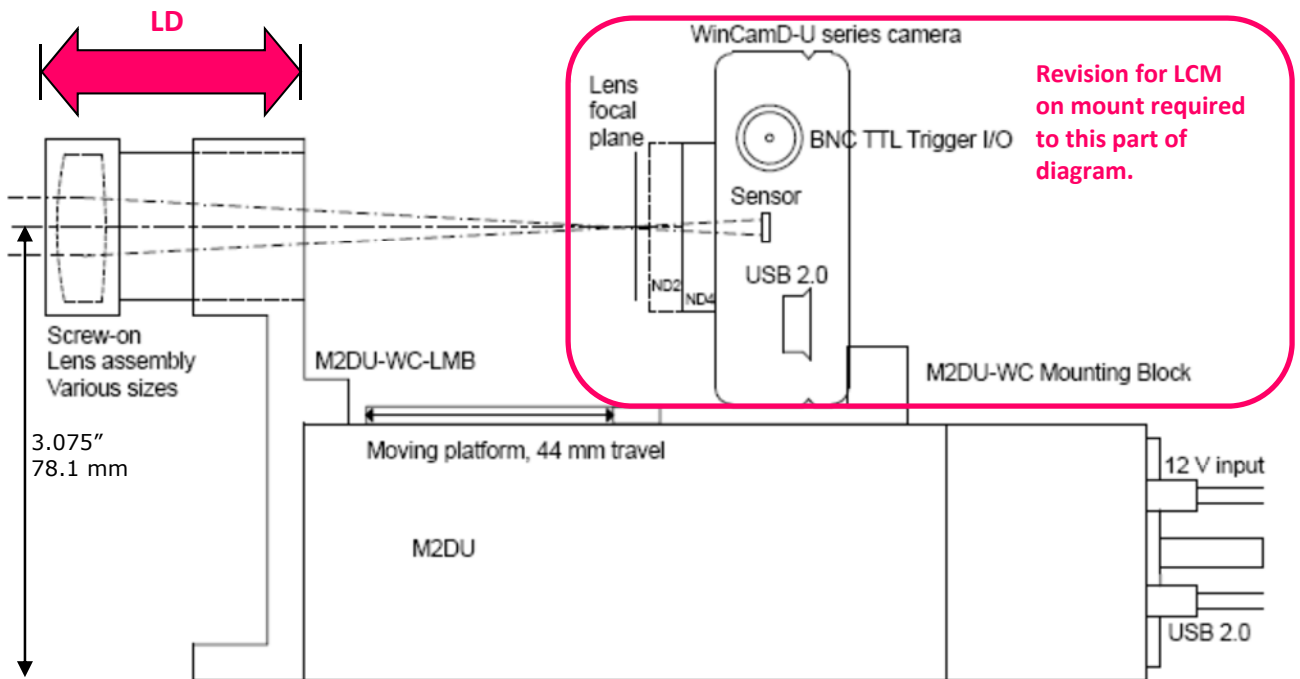
b) In accordance with Section 5.1 of the ISO 11146 Standard, the Second Moment calculation integrates over 99% of the total energy in the profile. See Appendix B in the main User Manual for Beam Diameter definitions.

c) If the beamwaist profile in the propagation direction – the z direction – is either too flat or too 'V' shaped, the fit will be poor.

d) With the lens provided/recommended, the system will measure the M^2 of collimated lasers. If you already have an appropriate beamwaist and can position it within the range of travel of the stage, you can measure the M^2 of the beam directly.

5) Assemble the unit

The diagram shows the unit with an 85 mm lens. For longer focal length lenses the lens assembly moves to the left, in the diagram below. The measurement **LD** mm is required for the calculation of the original beam characteristics.



You will/should have been supplied with the following parts:

- **WinCamD-LCM** series head
- **M2DU-LCM** system comprising the following items:
 - o **ND2.0** additional ND filter to screw onto the ND4.0 provided with the camera.
 - o **M2DU** UMove™ USB 2.0 stage
 - o 3 m (10 ft) USB 2.0 cable (A to mini-B 5)
 - o **12V-PSU** Power supply with power cord
 - o Lens mount bracket and **M2DU-LCM-AP** adaptor plate
 - o 8 pieces of #4-40 x 0.5" Philips panhead stainless steel black screws. (2 spares)
 - o 1 piece of #8-32 hex head screw.

- **LNZ-XXX-YYY** Achromatic lens in holder plus spacers.

Assembly

- Attach the **WinCamD-LCM** series head to the **M2DU-LCM-AP** mounting Block using the #8-32 screw. Use a 3/32" or 2.5 mm hex key.
- Attach the **M2DU-WC** Mounting Block to the **rear** of moving platform on the M2DU stage using two #4-40 x 0.5" screws and the two holes closest to the LCM. See image on page 1. The mounting block overhands the rear of the moving platform by
- Attach the **M2DU-WC-LMB** lens mount bracket to the front of the **M2DU** stage using two #4-40 x 0.5" screws.
- **Optional:** Attach the **M2DU-WC-LMB** lens mount bracket to an optical table, breadboard or other hardware using two 1/4"-20 x 0.5" screws (you supply). If your hardware is Metric use M6 x 12.5 mm caphead screws (you supply).
- **Optional:** To mount it higher, attach either through these holes or to the 1/4"-20 threaded holes in the base of the M2DU. **IMPORTANT:** If you use the threaded base holes, screw length inside the unit must never exceed 0.375" (10 mm).
- Add the **LNZ-XXX-YYY** lens assembly.
- **Important.** If connecting to USB through a hub, it must be a powered hub. Connect the 12 V power supply to the **M2DU**. Connect a USB 2.0 cable between the **M2DU** and the PC. After finding the hardware and installing the drivers the **Device Manager** should show them as shown right.

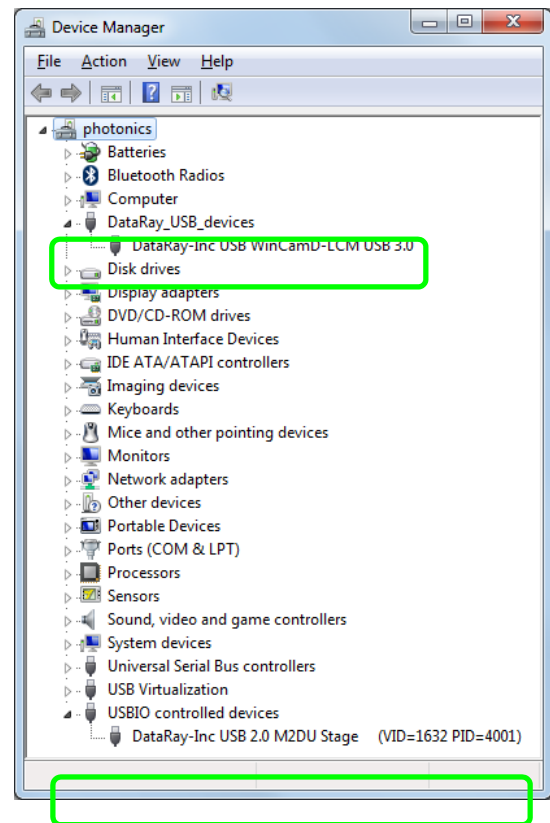
6) Laser Safety The beam will suffer some back-reflection from lens surfaces and ND filters and from the housings if the beam is misaligned. **You are totally responsible for your own laser and eye safety and that of others in the vicinity. If you cannot accept this responsibility, proceed no further.**

7) Preset the Attenuation level correctly

Avoid destruction of your camera! If you did not already do so earlier, for the value of **2Wo"** calculated in the Beam Modeling for Lens Selection Excel sheet above, from the curves in the WinCamD manual (page 1-7 for CW, 1-8 for pulsed), determine whether you will need to add additional sampling/attenuation in order to avoid saturation of the camera at the focus. If so add as required before proceeding. An additional **ND2.0** filter is provided with the M2DU.

Chapter 5 of the WinCamD manual describes attenuation and sampling solutions. DataRay offers additional ND filters, variable ND filters, wedge samplers, & holographic beam samplers to assist you,

Verify the lens incident power with a power meter.

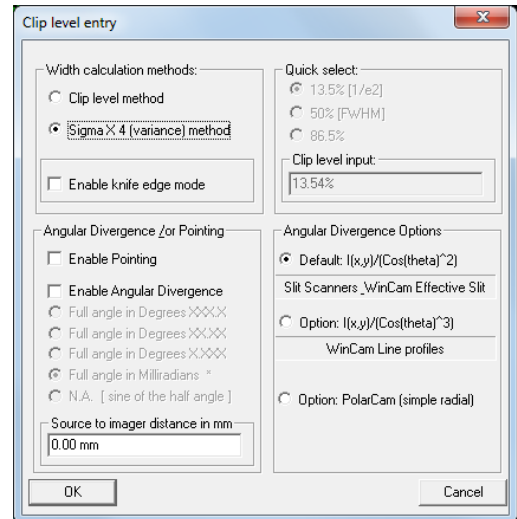
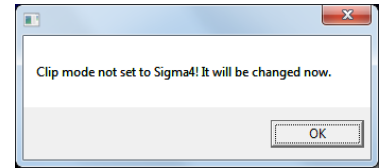
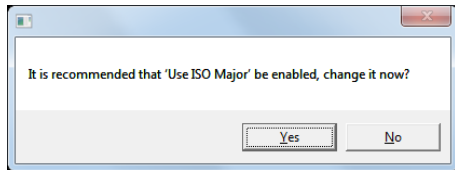
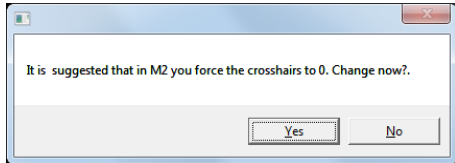
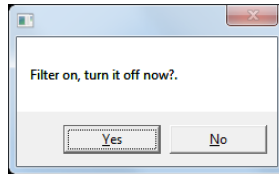
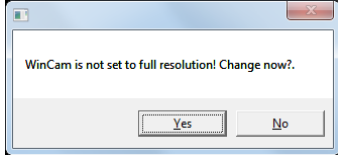


8) Start the Software

Start the software. Click the **M2** button. A series of warnings advise that the software will in turn:

- Set the Clip[a] level to 4sigma.
- Set Full resolution
- Turn off the filter
- Force the crosshairs to zero degrees

Accept all the offerings by clicking **Yes** or **OK**.



You will then see the **WinCam M-squared Setup** box.

a) Enter Wavelength in nm and Lens Focal Length.

b) LPPSO: If you require that the software calculate the source beam characteristics, you need to measure a critical distance.

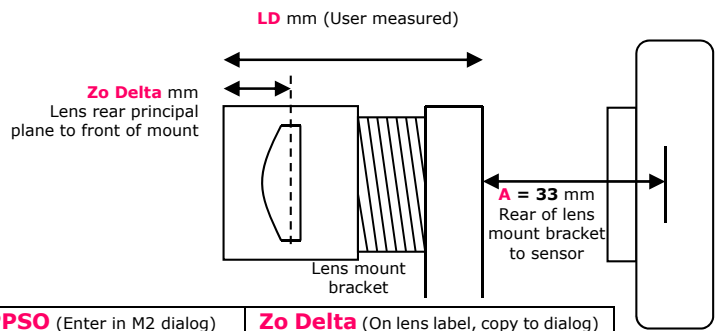
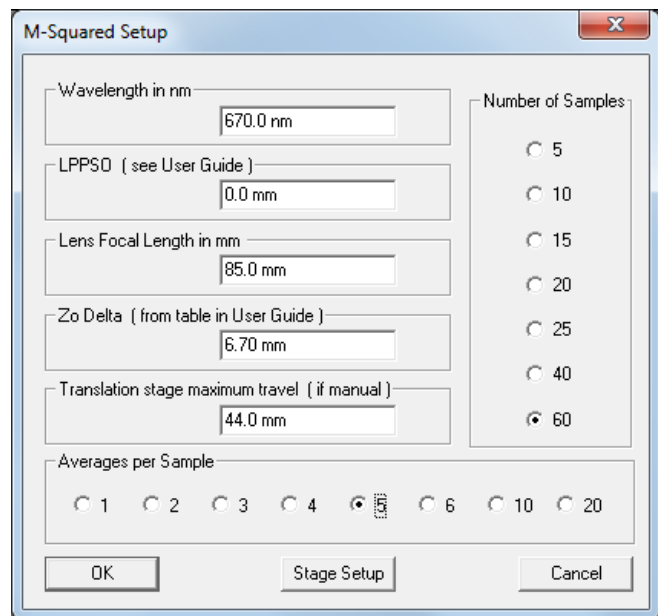
The flexible lens focal length, wavelength & spacer options means that lens Principal Plane to scan stage position is not fixed and must be entered.

Use a **mm** scale/tape to measure **LD**, the distance from the front of the lens flange (with dust cap removed) to the back of the Lens Mount Bracket - the red double arrow labeled **LD** on the diagram two pages earlier. This is a distance that is easy for you to measure. **LD** must then be corrected for the distance between the front of the lens and its Principal Plane, the **Zo Delta** value from the lens label, and for the distance **A** between the rear of the lens bracket and the sensor in the camera.

Add **LD** to **A - Zo Delta**, and enter this value as the **LPPSO (Lens Principal Plane to Sensor at 0)** entry in the dialog.

c) Enter the Zo Delta value from the lens label in the M-squared dialog.

d) Copy LPPSO & Zo Delta to the front page for your future convenience.



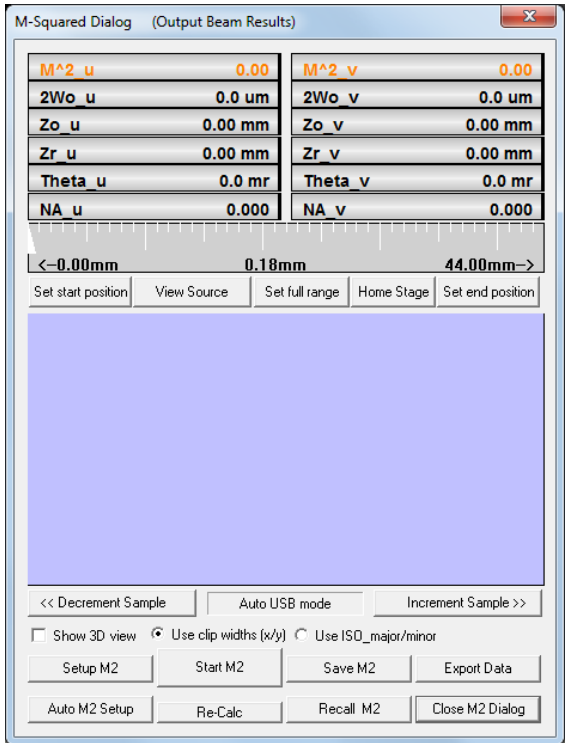
Lens LNZ - f mm - Diam.	LD (User measured) See diagram below	+(A-Zo Delta) See diagram	=LPPSO (Enter in M2 dialog) Lens Principal Plane to Sensor at 0	Zo Delta (On lens label, copy to dialog) Front of lens mount to Principal Plane
			=	

Let's double-check: You did all your calculations in mm and to ± 1 mm or better, correct?

Translation Stage maximum travel is automatically read from the stage EEPROM when a stage is present.

Click **OK**, and the **M Squared Dialog** shown right will appear.

Particularly on smaller displays, to stop it from blocking the screen, resize the main screen from its default full screen setting.  away



M ² u	0.00	M ² v	0.00
2W0 u	0.0 um	2W0 v	0.0 um
Zo u	0.00 mm	Zo v	0.00 mm
Zr u	0.00 mm	Zr v	0.00 mm
Theta u	0.0 mr	Theta v	0.0 mr
NA u	0.000	NA v	0.000

<-0.00mm 0.18mm 44.00mm->

Set start position View Source Set full range Home Stage Set end position

<< Decrement Sample Auto USB mode Increment Sample >>

☐ Show 3D view ☒ Use clip widths (x/y) ☐ Use ISO_major/minor

Setup M2 Start M2 Save M2 Export Data

Auto M2 Setup Re-Calc Recall M2 Close M2 Dialog

9) Align the Beam

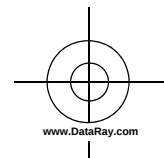
**** Correct alignment is critical to successful operation ****
A misaligned beam can lead to astigmatism and to overestimation of the M² value. You are aiming for on-axis to $\sim \pm 2$ mm max.

The M2DU stage sets the optical axis at a height of 3.08" (78.2 mm) above the base.

The lens and camera covers have black on white beam target crosshairs with 5 and 10 mm circles. These are useful for visible lasers. The lens cameras have a central hole. For NIR and telecom lenses the lens cap includes a pink fluorescent phosphor on the cap. For the camera end you may require suitable wavelength imaging plates or viewers.

With these covers in place:

- Click on the right hand edge of the gray scale to move the stage to the end closest to the motor.
- Align the beam on the target with a hole in it on the front of the lens.
- Rotating about the front lens cap center as pivot point, adjust the laser or the rear of the M2DU to center the laser beam on the camera target.
- Lock down the laser and the M2DU stage.
- Remove the lens & camera covers. Open & Start the software.
- Verify that Peak ADC is <90 %. If not, revisit Sec. 4.



10) Set the Capture Block

In order to minimize the size of saved M2 files, it is recommended that you minimize the **Capture Block**. If you ignore this advice, your default M² file size will be 100's of MB and your RAM will fill rapidly.

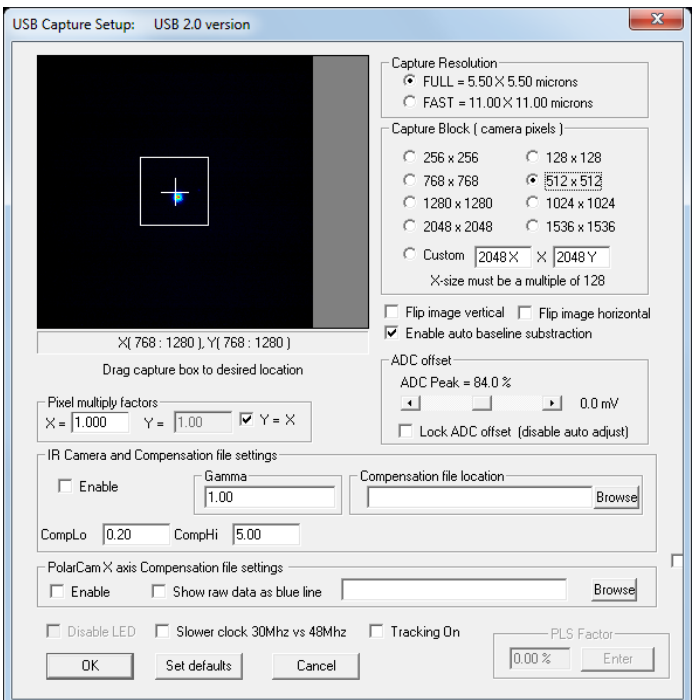
We suggest a **512 x 512 Capture block**.

Press **Alt S** to open the **Capture Setup** box. In the **M-Squared Dialog** box, click at the extreme ends of the gray scale and watch the image in the **Capture Setup** box.

If the image moves more than 25% of the screen, readjust your beam alignment until it moves less than this. With the stage at the lens end, select a **Capture Block** around five times the visible beam size. In most cases, 512 x 512 should suffice.

Click **OK**.

For CW lasers Auto-exposure sets correct exposure for all z values.



USB Capture Setup: USB 2.0 version

Capture Resolution:
☒ FULL = 5.50 x 5.50 microns
☐ FAST = 11.00 x 11.00 microns

Capture Block (camera pixels)
☐ 256 x 256 ☐ 128 x 128
☐ 768 x 768 ☒ 512 x 512
☐ 1280 x 1280 ☐ 1024 x 1024
☐ 2048 x 2048 ☐ 1536 x 1536
☐ Custom [2048 X] x [2048 Y]
 X-size must be a multiple of 128

☐ Flip image vertical ☐ Flip image horizontal
☒ Enable auto baseline subtraction

ADC offset
 ADC Peak = 84.0 %
 0.0 mV
☐ Lock ADC offset (disable auto adjust)

IRI Camera and Compensation file settings
☐ Enable Gamma [1.00] Compensation file location [Browse]
 CompLo [0.20] CompHi [5.00]

PolarCam X axis Compensation file settings
☐ Enable ☐ Show raw data as blue line [Browse]

☐ Disable LED ☐ Slower clock 30Mhz vs 48Mhz ☐ Tracking On

OK Set defaults Cancel PLS Factor [0.00 %] Enter

11) Check Exposure

Check Exposure. Move the stage in z by clicking on the scale until the beam diameter is at or close to minimum. **CW beams:** Adjust any attenuation/sampling until the **Peak ADC** is <90 % and that, at the beamwaist: **0.25 ms ≤ Exposure time ≤ 5 ms**. If it is not, revisit Section 4 above.

Pulsed laser beams: Currently the software averages multiple pulses and varying the Exposure time effectively varies the number of pulses averaged. The minimum PRR for which the system will work reliably in default mode is around 1000 Hz.

Ensure that at the beamwaist, both **(0.2 ms ≤ & (10,000/PRR) ms) ≤ Exposure time ≤ 20 ms**. A later release may extend these limits.

[Setting the maximum exposure limit to 1,000 ms instead of 200 ms can extend the upper exposure limit to 200 ms, but the increase in dark current spikes will affect the M² accuracy.]

12) Perform a Coarse Scan

Click on the left hand side of the scale to move the stage to the lens end.

Press **Go** to let the exposure adjust.

Press **Auto M2 Setup** to perform a coarse scan of 20 equally spaced points in z using the full length of the stage, with an Average of 2 images per z position.

Orange Data. During the scan through a beamwaist, the software changes the Exposure to accommodate the change in the irradiance as the beam diameter changes. During Exposure iteration, before the correct Exposure is determined, the **Peak %** will sometimes go to 100% and the numbers will turn **Orange** to warn of this saturation. Do not worry. The software *only* uses data taken when the exposure has stabilized and the **Peak %** is below 100%.

At the conclusion of the scan, the software performs a hyperbolic weighted least squares fit to the data to calculate the approximate position of the beamwaist, **z0**, and the Rayleigh Range, **zR**.

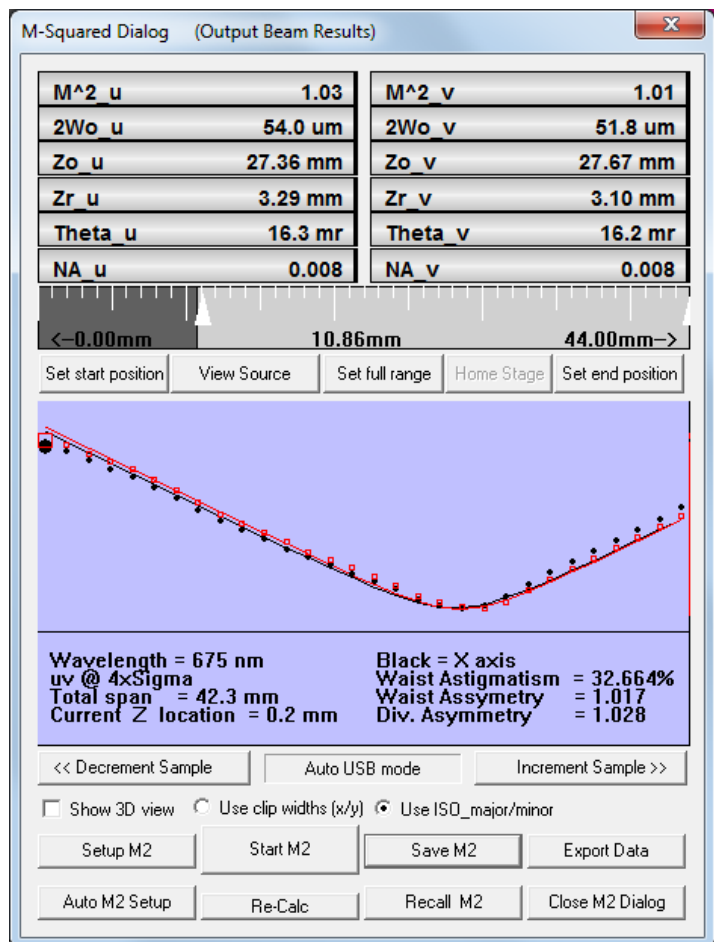
Select **Use ISO_major/minor** to get true M2 values.

Based on these values, the software produces estimates of the full results. More importantly the **ASR™** Auto Scan Range software module sets upward pointing white tick marks on the scale at the suggested **Start** and **End** positions for a 11146 compliant scan.

If the scan is too flat for an accurate M² fit because the far-field is not adequately reached within the range of the scan in accordance with the Standard, then **Warning: Beam waist too shallow** will appear.

If the exposure dips below 0.25 ms, **Warning: More attenuation recommended** will appear in the Exposure area, due to the risk of tailing with CCD's.

If the exposure rises above 200 ms, **Warning: Less attenuation recommended** will appear in the due to the risk of dark noise contribution to the ISO diameter.



13) Perform a Final Scan

Unless you have reason to disagree with the proposed scan range, press Start M2.

The software automatically performs a scan of 60 equally spaced points in z over the set range, with an Average of 5 images per z position.

At the conclusion of the scan, the software performs a weighted least squares hyperbolic fit to the data to calculate the final results.

M²_{u,v} the M² values.

Remember the anticipated specifications:

M² Accuracy* ± 5% typical

M² Repeatability* ± 2% typical

* Beam dependent. Absolute accuracy better than ±5 % is possible, but can be difficult.

If your beam M² is actually 1.03, the value that you see may vary from 0.98 to 1.08. If it is less than 1.0 it will show in orange, as 0.98, but this does not necessarily mean that it is a bad result.

2Wo_{u,v} the beamwaist diameters.

Zo_{u,v} the beamwaist positions with respect to the principal plane of the lens.

Zr_{u,v} the beams Rayleigh range

Theta_{u,v} and **NA_{u,v}**; the far-field divergence of the focused beam in mrad and as NA.

14) Source Beam Characteristics

Press the **View Source** button below the dialog to toggle between the **Output** beam and the source beam.

The software uses Gaussian beam calculations to calculate the position and dimensions of the source beam. Below the curve (see previous page) are calculations of:

Waist Astigmatism = $(s_v - s_u) / [(s_u + s_v) / 2]$

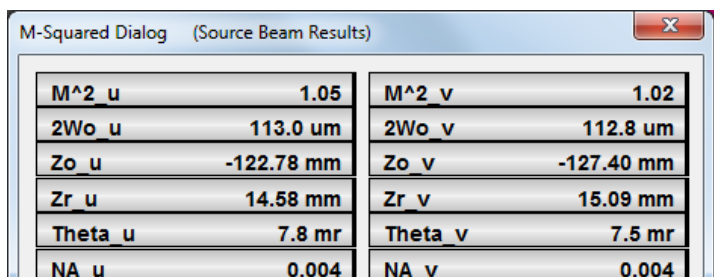
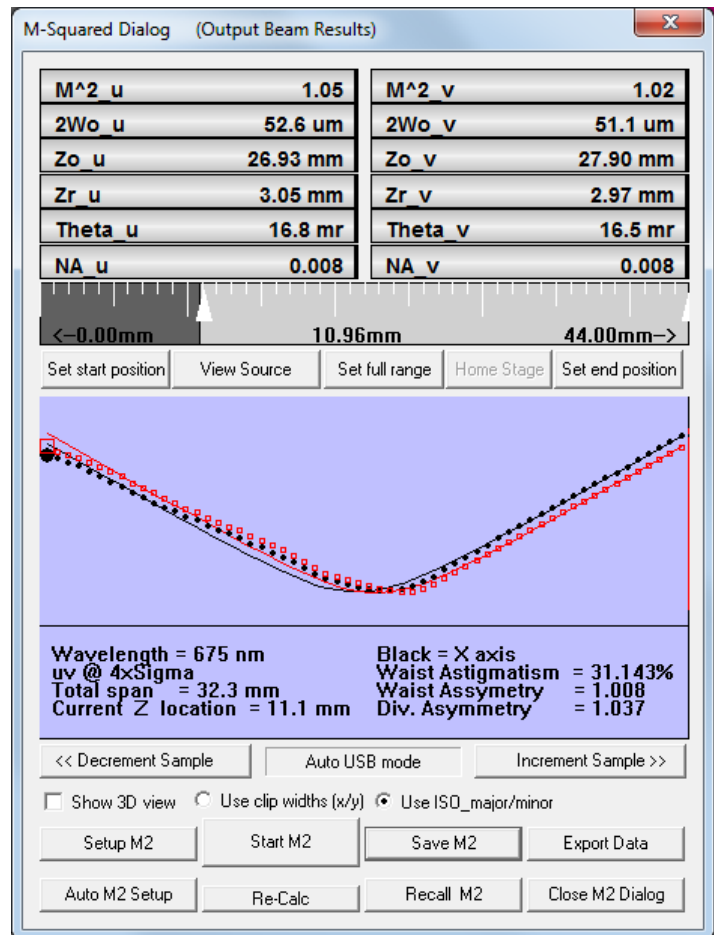
– the difference between the calculated source waist Zo distances from the lens principal plane divided by the average Zo distance.

Waist Asymmetry = $2Wo_u / 2Wo_v$ – the ratio of the calculated source diameters.

Divergence Asymmetry = $Theta_u / Theta_v$ – the ratio of the calculated source divergence angles.

Important: The source **Zo_u**, **Zo_v** values are given as measured from the front of the lens holder, not from the lens principal plane. This is because this is a distance you can easily measure.

For this particular beam **Zo** was 860 ±5 mm, so the estimates are accurate to a surprisingly good few %.



15) Save the Data

Press **Save M2** to save the results as a *.wcf file. If you forget to do so, a warning will appear before you start another M2 scan.

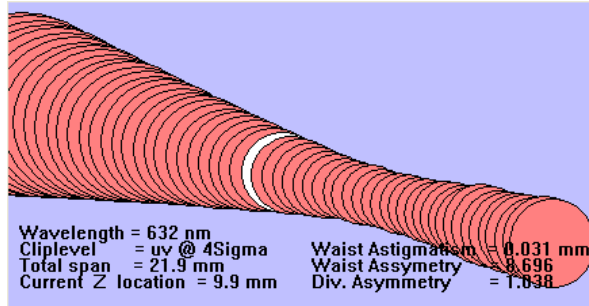
<<Decrement Sample and Increment Sample>> scan through the planes of the individual measurements.

Saved files contain the original images, so you may switch between **Use clip widths at 0 and 90 deg** and **Use major/minor widths**.

When **Use major/minor widths** is selected, **Use ISO 11146 compliant diameters and angles** is automatically selected and any clip level is ignored.

If the beamwaist profile in the propagation direction – the z direction – is either too flat or too 'V' shaped, the fit will be poor.

Click on **Show 3D view** to see the visually more satisfying 3D view shown right.



Click on **Export Data** to export the data to an **M2data.txt** file in Notepad, which may be saved for subsequent analysis, and from which the data may be exported into Excel.

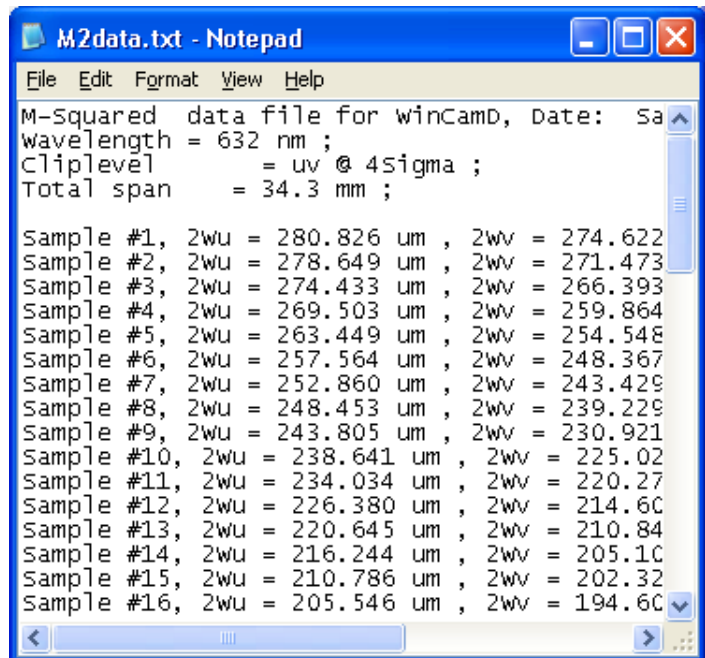
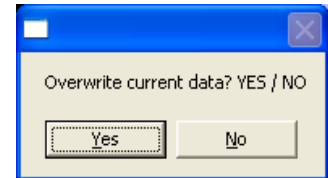
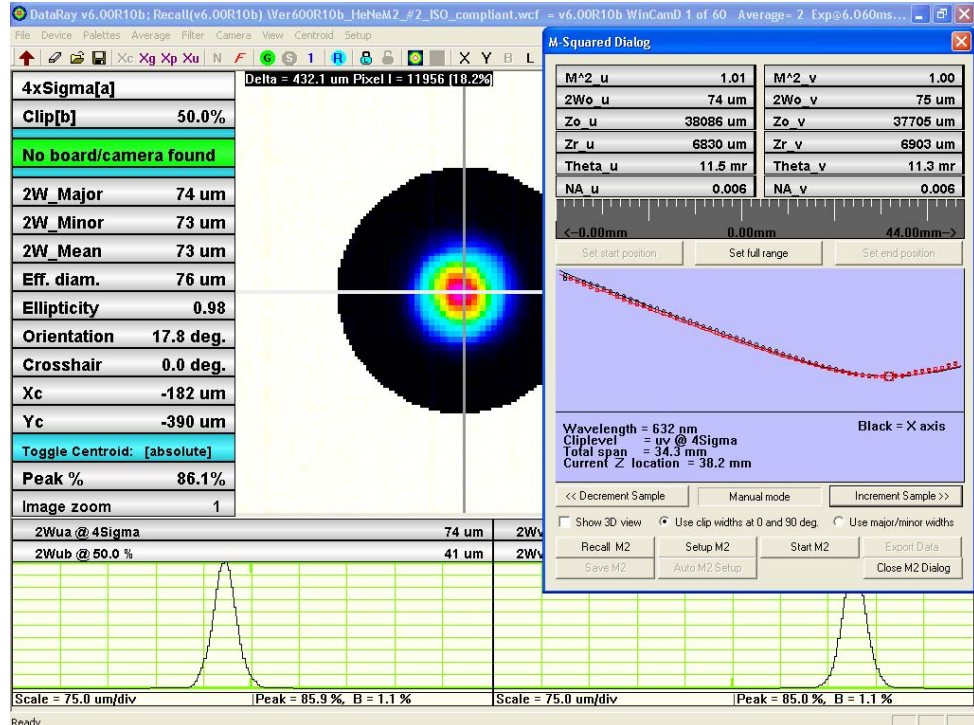
Click on **Recall M2** to browse for and open previously saved files.

16) Second time around

When the software is closed, it saves the current settings.

If the laser power and alignment have not changed substantially, all you need to do is rerun the software.

If anything has changed revisit that section only.



17) Support

If you get an error message, press Alt, **Prt Sc** to put it to the clipboard, and then **Ctrl V** to put it into an email message. Sometimes these are diagnostic warnings rather than something more significant, and clicking the **OK** button allows you to proceed.

If you get a result which makes no sense, and rechecking the procedure did not help, then:

- 1) Scan through the saved images to see whether or not you have a dirt, dust, exposure time or Capture block issue affecting the image.
- 2) If 1) showed nothing that explained the problem, then save a ***.m2_wcf** file or at least an ***.wcf** image saved from the data set. Email the file with comments to: support@dataray.com.

Then, as necessary, call 303-543-8235, 7:30 to 18:00, Mountain time zone. (GMT -7 hours).

[Note that ***.m2_wcf** files can be large, ten's of MB. We can receive large files, but your email server may restrict attachment size. In that case, either put them to an FTP location on your server and tell us how to download them, or try using <http://www.sendthisfile.com>.]

18) Manual M² (with a different translation Stage)

If you have a WinCamD camera but no M2DU unit, the procedure is identical, particularly with respect to alignment, exposure, laser safety, capture block, etc.

Before trying to perform a Manual M², you **must** first read and understand the full document carefully except for items relating *specifically* to the parts list and assembly of/with the M2DU unit.

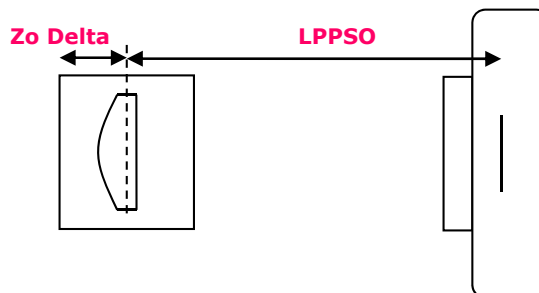
Exceptions to the procedure are as follows:

- Stage Travel:** Determine the length of travel of your alternative z 'stage', be it motorized or manual.
- Stage Readout:** The 'stage' must have a readout in mm, be it digital or manual.
- Source diameter & location.** To additionally determine the waist diameter & z location of the source beam:

Lens: You need to know the focal length (mm), and back focal length (mm) of your lens. Enter in the table below.

Lens mount: You need to determine the distance **Zo Delta** (mm) from the front of your lens mount to the rear principal plane of the lens. Enter in the table below.

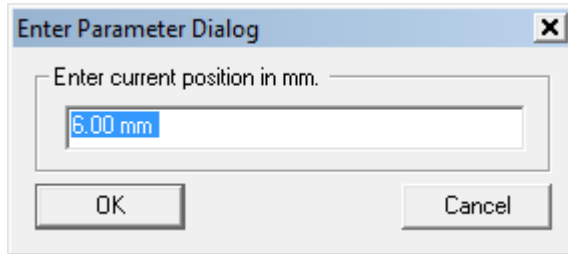
Lens mount: You need to determine the distance **LPPSO** (mm) from the lens rear principal plane to the sensor plane *when at 0 on your measurement scale*. Enter below.



Lens focal length	Lens back focal length	= LPPSO (Enter in M2 dialog) Lens Principal Plane to Sensor at 0	Zo Delta (Enter in M2 dialog) Front of lens mount to Principal Plane

- Move the camera in z and determine that the waist is around 50% to 75% along an attainable range of travel.
- At Step 8) above when the **M-Squared Setup** dialog screen opens, enter the listed parameters, *plus* the **Translation stage maximum travel**.

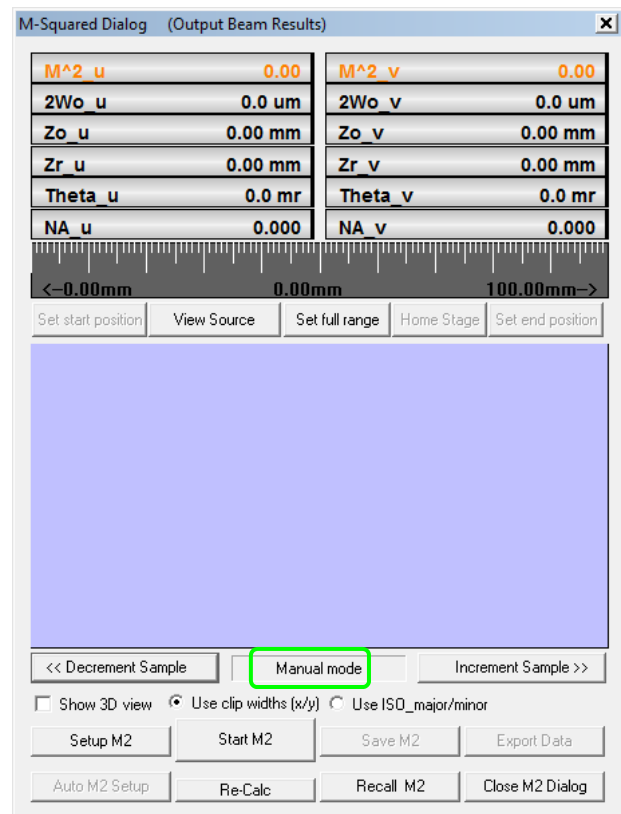
- f) When you start the software with no M2DU stage connected the **M-Squared Dialog** will say **Manual mode** below the graphic area of the dialog.
- g) Set the camera to your start position, which need not be zero on the scale. Press **Go** and let the image and exposure stabilize. Press **Start M2**. [Obviously **Auto M2 Setup** is grayed out if you do not have an M2 stage.] The following dialog will appear:



The position highlighted in blue is the software's best guess at what the position will be based upon the entered stage range and the number of steps.

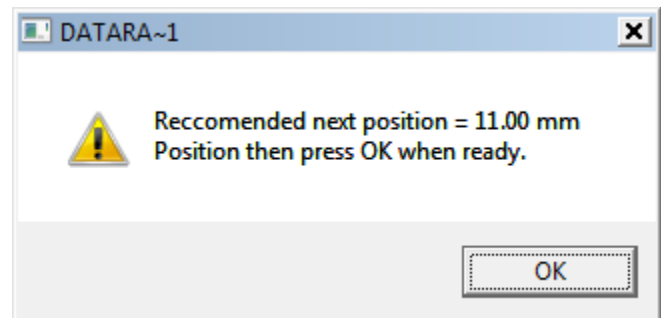
You may use these values or you may ignore them, your call.

Enter the actual z position (no need to include **mm**) rather than blue value. Press **OK**.



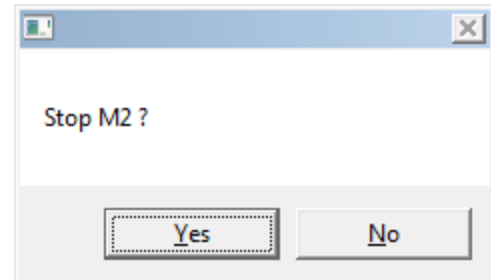
The screen right will appear. You may use the recommended position or one of your choosing. Once the position is set, press **OK** and after the image exposure has stabilized, the next reading will be taken.

The screen above will reappear with a different position option.



If you take too long between readings, the dialog shown right will appear. Simply select **No** to cancel it.

Follow through the sequence until the requested number of samples have been entered, at which stage the results will appear instead of a dialog box.



- h) As you read about using the M2DU stage, you will probably have to iterate the positioning and the number of samples until the curve looks right and there are no **Warnings**.