Software-Defined Radio Lab 2: Data modulation and transmission Version 0.2

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1 Introduction

In this lab, you will build a transmitter and corresponding receiver for simple DBPSK modulated data framed with a correlation sequence in the beginning. The receiver prints the estimated SNR of the received data, as well as the computed bit error rate. You will then modify the transmitter to include an AWGN channel model and verify that the measured SNR and bit error rate correspond to the theoretical values. You will further modify the system to use DQPSK modulation instead of DBPSK.

2 Preparations

Read this memo through. Then determine suitable values of the parameters that are mentioned in Section 4.2.

3 Setup

The following hardware is needed for this lab:

- A computer with USB 2.0
- A USRP1 with an LFTX/LFRX daughterboard pair at the A side
- An oscilloscope with two channels

You need GNU Radio installed. The lab is tested and ensured to work with GNU Radio 3.3.0, and assumes that it is installed in /usr/local/gnuradio-3.3.0.

3.1 Initialization

If you are doing this lab in CommSys' research lab:

Log in to one of the lab computers as the user SDR lab user. Your lab teacher will give you the password. Your lab computer is prepared with all needed files in the directory

/home/sdrlabuser/labfolder/lab2

Open a terminal and cd to that directory. You do not need to worry about making changes to files there. That directory will be updated for the next occation.

If you are not following these instructions in CommSys' research lab:

Open a terminal. Create a directory labfolder somewhere and cd into it. If you have done Lab 1, you should already have that directory. Download and extract the accompanying lab files by executing the following commands:

\$ wget http://www.commsys.isy.liu.se/SDR/labs/gr/lab2.tar.gz \$ tar zxf lab2.tar.gz \$ cd lab2

All files needed in this lab are now in the directory lab2 that you just created.

4 Data Transmission

Full synchronization is assumed in many communications courses given at LiU and at other universities. That is also the assumption in the lectures and tutorials in TSKS01 Digital Communication. The reason for that is that syncronization provides problems and solutions enough to form a full course by itself. It is a significant problem in engineering reality, though. In this lab, we have real signals and there is no artificial syncronization of senders and receivers. Instead, our senders and receivers must include tricks to achieve an approximate syncronization, which then contains frequency correction and bit syncronization.

We also need to know where data starts. Our data will be grouped into frames and the sender prepends each frame by a pseudo-noise sequence that marks the beginning of the frame. The receiver knows that pseudo-noise sequence, and correlates the received bit-stream by that sequence. A large correlation marks - with high probability - that we have found the start of a frame. This is frame syncronization. The receiver then continues to detect the whole frame, and then waits for the next frame.

The absolute phase will be unknown in the receiver, but will essentially be unchanged from symbol to symbol. Therefore, we will use differential PSK in the communication systems in this lab. That simply means that the phase difference between adjacent symbols carry the information.

This is described in more detail below. Details about how and why this kind of syncronization works is discussed in the follow-up course TSKS04 Digital Communication Continuation Course.

4.1 Noise-Free Transmission Link

In the following, let M be the size of the modulation scheme used, and let $k = \log_2(M)$ be the number of bits per symbol.

The simple data transmitter is shown in Figure 1. It consists of a data source generating a stream of data vectors that are all equal. Each data vector is framed with a simple correlation sequence at the beginning, then converted to a stream of bits. The stream of bits is packed to a number of bits per sample, corresponding to the chosen modulation, then differentially encoded, mapped to a complex symbol, and then passed through a root-raised-cosine shaping filter. The signal is finally modulated to the carrier frequency by the USRP.

Figure 1: A transmitter for differential PSK modulated data.

Compare Figure 1 to the stub file psk_tx.py. The blocks perform the following operations in order:

```
src (pr.data source counter)
```
Generate data blocks of known data. The reason that we want to transmit known data is to give us the possibility to check if the received data is correct.

Uses the variable data size in the python code.

framer (pr.framer simple vbb)

Prepend each data block by a pseudo-noise sequence.

Uses the variables frame size and corrseq in the python code.

decap (pyblk.txmeta decap b)

Remove meta data header from packet.

Uses the variable frame_size in the python code.

v2s (pr.pvec to stream)

Convert frames to a stream of bits.

Uses the variable frame_size in the python code.

diffenc (gr.diff encoder bb)

Differential encoder. $y[n] = (x[n] + y[n-1]) \pmod{M}$. The result are the symbol indices. Uses the variable mod order in the python code.

```
symmap (gr.chunks to symbols bc)
```
This block maps symbol indices on the actual symbols, which are complex numbers.

Uses the variable constpoints in the python code.

```
rrc (gr.interp fir filter ccf)
```
An FIR filter that also upsamples (interpolates) the signal. This is a so-called root-raisedcosine filter, which shapes the signal to increases the spectral roll-off of the modulation. More about this in TSKS04.

Uses the variables samples per symbol and rrctaps in the python code.

```
txscale (gr.multiply const cc)
```
Amplify the signal to fit the USRP signal levels.

u (usrp.sink c)

Send the sampled complex baseband signal to the USRP transmit chain, resulting in the physical output signal.

Uses the variable usrp interp in the python code.

On the receiver side, the structure is shown in Figure 2. The baseband processing includes an automatic gain control followed by the gr_mpsk_receiver_cc block that does frequency correction and timing recovery. The output of the block contains complex symbol estimates. The symbol estimates are decoded and unpacked to a bit stream. A frame correlator searches for the correlation sequence, and frame sync samples the frame when the correlation sequence is found. The correlation sequence is removed, the header is stripped from the data vectors, and the resulting data stream is fed to a bit error rate computation block.

Figure 2: Simple receiver for differential PSK modulated data.

Compare Figure 2 to the stub file psk_rx.py. The pink blocks in Figure 2 constitute the actual signal path. Those blocks perform the following operations in somewhat rough order:

```
u (usrp.source c)
```
Receive the complex baseband signal from the USRP receive chain, which is a sampled and demodulated version of the physical input signal.

Uses the variable usrp decim in the python code.

rxscale (gr.multiply const cc)

An amplifier. Adjust signal levels.

```
agc (gr.agc cc)
```
Automatic gain control. Make sure that the output has the desired amplitude.

rrc (gr.fir filter ccf)

Again a root-raised-cosine filter, Matched filter to the root-raised-cosine filter of the sender. This block allows for decimation (down-sampling) as well, but that is not used here. Uses the variable rrctaps in the python code.

recv (gr.mpsk_receiver_cc)

Performs mpsk detection including carrier syncronization and symbol timing recovery. Uses a Costas loop for phase and frequency recovery and a method called Mueller and Muller for timing recovery. To some extent, these things are covered in the course TSKS04 Digital Communication Continuation Course. Outputs a sequence of most likely signal points. Both those recovery methods need a bunch of parameters.

Uses the variables mod_order, costas_alpha, costas_beta, costas_fmin, costas_fmax, mm mu, mm gain mu, mm omega, mm gain omega and mm omega rel in the python code. Those starting with "costas_" are parameters to the Costas loop, and those starting with "mm_" are parameters to the Mueller and Muller method.

diffdec (gr.diff_phasor_cc)

Differential decoder. Uses the phase difference between two symbols to determine the output symbol:

$$
out[i] = in[i] \cdot conj(in[i-1])
$$

Outputs a sequence of complex numbers, whose arguments are differences of arguments of consecutive symbols, i.e. a sequence of M-PSK symbols, where the differential encoding has been removed.

constdec (gr.constellation decoder cb)

Maps signal points on bits.

Uses the variable constpoints in the python code.

framecorr (pr.frame correlator simple bb)

Correlates the received stream of bits with a the known pseudo-noise sequence, to find the start of a frame.

Uses the variables frame_size, corrseq and ncorr_req in the python code.

delay – not explicitly called that in the Python code. $(gr.delay)$

Delay the signal by one sample.

framesync (pr.frame sync bb)

Sample frames when correlation sequence is found.

Uses the variable frame_size in the python code.

deframe (pr.deframer simple vbb)

Remove the pseudo-noise sequence from the start of the frame, and output only the information bits.

Uses the variables frame size and corrseq in the python code.

rxdecap (pyblk.rxframe decap b)

Remove meta data header from frame.

Uses the variable data_size in the python code.

```
rxv2s (pr.pvec_to_stream)
```
Map data to stream of bits.

Uses the variable data size in the python code.

The white blocks in Figure 2 perform analysis of the received signal and present that in the GUI. In order to provide reference data, a copy of the data generation chain in the transmitter is also included in the receiver. Also, the fftsink and constsink instances are used to visualize the spectrum and constellation of the received signal. Finally, the symbol estimates are fed to an SNR estimation block. The main loop of the program prints the estimated SNR and computed bit error rate regularly. Those blocks perform the following operations in somewhat rough order:

symscale – not explicitly called that in the Python code. $(gr.multiply_const_cc)$

An amplifier. Adjust signal levels.

sigview (pygui.signal_viewer)

Present the signal in the GUI.

Uses the variables usb rate and samples per symbol in the python code.

snrest (gr.probe_mpsk_snr_c)

Estimate the SNR of an MPSK signal using the Squared Signal to Noise Variance (SNV) technique, assuming an AWGN channel. This is done by computing the running average of the signal mean and noise variance. This SNR estimator is inaccurate below about 7dB SNR.

```
symrate (pr.rate estimate)
     Estimate the symbol rate.
datarate (pr.rate estimate)
     Estimate the bit rate.
refdata (pr.data source counter)
     Generate a sequence of known data, the same data as the sender uses. The reason for this
     is so that we can check the error rate by comparing this data to the received data.
     Uses the variable data size in the python code.
refdecap (pyblk.txmeta decap b)
     Remove meta data header from packet.
     Uses the variable data size in the python code.
refv2s (pr.pvec to stream)
     Convert frames to a stream of bits.
     Uses the variable data size in the python code.
berest (pr.ber estimate b)
     Estimate the bit-error-rate (BER).
```
4.2 Bulding a Noise-Free Transmission Link

Use the files $psk_tx.py$ and $psk_rx.py$ as stubs for building the flowgraphs in Figures 1 and 2, respectively. Design the transmitter and receiver according to the following requirements:

- Use a USRP transmitter interpolation rate of 128 and a receiver decimation rate of 64.
- The usable data rate shall be at least 180 kb/s. Remember that the correlation sequence adds some overhead.
- Use differential BPSK modulation.
- Use a correlation sequence of 64 bits (defined in the stub files).
- Use root-raised cosine filters with an excess bandwidth of 0.35.
- For the timing recovery to work, the number of samples per symbol must be at least 4.
- Use the following parameters for the mpsk_receiver block:

```
- costas alpha = 0.1- costas_beta = 0.25 * costas_alpha * costas_alpha
- costas_fmin = -0.1- costas_fmax = 0.1- mm mu = 0.5
- mm gain mu = 0.01- mm_omega = samples_per_symbol
- mm_gain_omega = 0.25 * mm_gain_mu * mm_gain_mu
- mm_omega_rel = 0.005
```
• Adjust the number of required correct bits in the frame correlator such that the probability of a false positive correlation (assuming random data) is at most 10[−]⁶ , and the probability of a successful correlation is at least 99.9% for an SNR of 5 dB. You may use octave or matlab and the bundled cseq.m for this.

To design the root-raised-cosine wave-shaping filters, use the function

gr.firdes.root_raised_cosine

This function requires both the sampling frequency and the symbol rate, but depends in reality only on the relation between the two. For a given number of samples per symbol (samples per symbol), the parameters for the root-raised-cosine filters can be determined according to the following guidelines, for the transmitter:

```
• gain = 1.0
```
- sampling freq = samples per symbol
- \bullet symbol rate = 1
- \bullet alpha = 0.35
- \bullet ntaps = 11 $*$ samples per symbol

For the receiver, use instead the following:

- gain = samples per symbol
- sampling freq = samples per symbol
- \bullet symbol rate = 1
- \bullet alpha = 0.35
- \bullet ntaps = 11 $*$ samples_per_symbol

Run the transmitter and receiver and verify that the transmission is flaw-less and that the rate corresponds to the expected.

4.3 Simulating a Channel

GNU Radio provides complete channel models for both AWGN and different fading channels. However, in this lab, you will build your own channel model using a noise source and an adder. Implement an AWGN channel according to Figure 3, and insert it before the shaping filter in the transmitter. This placement adds the distortion to the symbols rather than the samples (which would be more appropriate). However, it assures that all the added noise is in the same band as the signal, rather than spread out over the whole spectrum.

Figure 3: A simple implementation of an AWGN channel.

The parameter of the noise source can be set through the set _{mpplitude}() function. This sets the standard deviation if Gaussian noise is specified. In your program, you should be able to specify the desired SNR of the channel (assuming a unit signal energy), and the noise source should be set accordingly.

Your transmitter code already acknowledges the commandline command q to quit the program. We now want your receiver also to acknowledge the commandline command n SNR, where SNR should be the wanted Signal-to-noise ratio expressed as a number in dB.

Adjusting the if-statement near the bottom of the transmitter code to something similar to the following should give you the opportunity to set the SNR via the commandline:

```
if cmd[0] == 'q':quit = True
elif cmd[0] == 'n':
        SNRdB = eval(cmd[1])tb.noise.set_amplitude(10**(-SNRdB/20.0))
else:
        print "Invalid command"
```
You may want to add a suitable print statement above the if statement to inform the user about the changes in the user interface. This assumes that you have created the attribute noise of the class as self.noise, and it should be a set_amplitude() object. Note that it is imporant that the division is by the float 20.0 and not by the integer 20. Otherwise, you will get into trouble for integer SNR values.

4.4 Optional: Increasing the Data Rate

Double the data rate by changing the transmitter and receiver to use QPSK instead of BPSK. The following can come in handy:

 $j = complex(0,1)$ constellation = $[1,j,-1,-j]$

5 Resources

- Online USRP FAQ: http://gnuradio.org/redmine/wiki/gnuradio/UsrpFAQIntro
- Firas Abbas Hamza, The USRP under 1.5X Magnifying Lens!: http://gnuradio.org/redmine/attachments/129/USRP_Documentation.pdf Third-party documentation of USRP.
- GNU Radio C++ block documentation: file:///usr/local/gnuradio-3.3.0/share/doc/gnuradio-3.3.0/html/index.html
- OpenRD C++ block documentation: file:///usr/local/openrd/doc/index.html
- Firas Abbas, Simple Gnuradio User Manual: http://rapidshare.com/files/72169239/Simple-Gnuradio-User-Manual-v1.0.pdf Third-party documentation of GNU Radio. This one is a bit out of date, but still useful. A printed copy is available at the lab desk.