# Logix5000 Controllers Add-On Instructions



Catalog Numbers 1756 ControlLogix, 1756 GuardLogix, 1768 CompactLogix, 1768 Compact GuardLogix, 1769 CompactLogix, 1789 SoftLogix, PowerFlex with DriveLogix

# **Programming Manual**





## **Important User Information**

Solid state equipment has operational characteristics differing from those of electromechanical equipment. Safety Guidelines for the Application, Installation and Maintenance of Solid State Controls (publication <u>SGI-1.1</u> available from your local Rockwell Automation sales office or online at <u>http://www.rockwellautomation.com/literature/</u>) describes some important differences between solid state equipment and hard-wired electromechanical devices. Because of this difference, and also because of the wide variety of uses for solid state equipment, all persons responsible for applying this equipment must satisfy themselves that each intended application of this equipment is acceptable.

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Throughout this manual, when necessary, we use notes to make you aware of safety considerations.



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The information below summarizes the changes to this manual since the last publication.

To help you find new and updated information in this release of the manual, we have included change bars as shown to the right of this paragraph.

The Designing Add-On Instructions chapter was divided into two chapters, Designing Add-On Instructions and Defining Add-On Instructions, and some of the content was restructured.

Information on high-integrity Add-On Instructions and safety Add-On Instructions was added throughout the manual as well as the changes listed in this table.

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# **Purpose of This Manual**

This manual shows how to design, configure, and program Add-On Instructions. This manual is one of a set of related manuals that show common procedures for programming and operating Logix5000 controllers. For a complete list of common procedures manuals, see the Logix5000 Controllers Common Procedures Programming Manual, publication <u>1756-PM001</u>.

The term Logix5000 controller refers to any controller that is based on the Logix5000 operating system, including the following:

- CompactLogix and Compact GuardLogix controllers
- ControlLogix and GuardLogix controllers
- DriveLogix controllers
- FlexLogix controllers
- SoftLogix5800 controllers

# Additional Resources for Safety Applications

With the addition of safety Add-On Instructions in RSLogix 5000 software, version 18, you can use Add-On Instructions in GuardLogix and Compact GuardLogix safety-related functions. This manual provides information about safety Add-On Instructions.

For detailed information on safety application requirements, the safety task signature, and configuring and operating safety controllers, refer to these publications:

- GuardLogix Systems Safety Reference Manual, publication <u>1756-RM093</u>
- Compact GuardLogix Controllers User Manual, publication <u>1768-UM002</u>
- GuardLogix Controllers User Manual, publication 1756-UM020
- GuardLogix Safety Application Instruction Set Reference Manual, publication <u>1756-RM095</u>

# Understanding Terminology

This table defines some of the terms used in this manual when describing how parameters and arguments are used in Add-On Instructions.

Term	Definition
Argument	An argument is assigned to a parameter of an Add-On Instruction instance. An argument contains the specification of the data used by an instruction in a user program. An argument can contain the following:
	• A simple tag (for example, L101)
	• A literal value (for example, 5)
	• A tag structure reference (for example, Recipe.Temperature)
	• A direct array reference (for example, Buffer[1])
	<ul> <li>An indirect array reference (for example, Buffer[Index+1])</li> </ul>
	<ul> <li>A combination (for example, Buffer[Index+1].Delay)</li> </ul>
Parameter	Parameters are created in the Add-On Instruction definition. When an Add-On Instruction is used in application code, arguments must be assigned to each required parameter of the Add-On Instruction.
InOut parameter	An InOut parameter defines data that can be used as both input and output data during the execution of the instruction. Because InOut parameters are always passed by reference, their values can change from external sources during the execution of the Add-On Instruction.
Input parameter	For an Add-On Instruction, an Input parameter defines the data that is passed by value into the executing instruction. Because Input parameters are always passed by value, their values cannot change from external sources during the execution of the Add-On Instruction.
Output parameter	For an Add-On Instruction, an Output parameter defines the data that is produced as a direct result of executing the instruction. Because Output parameters are always passed by value, their values cannot change from external sources during the execution of the Add-On Instruction.
Passed by reference	When an argument is passed to a parameter by reference, the logic directly reads or writes the value that the tag uses in controller memory. Because the Add-On Instruction is acting on the same tag memory as the argument, other code or HMI interaction that changes the argument's value can change the value while the Add-On Instruction is executing.
Passed by value	When an argument is passed to a parameter by value, the value is copied in or out of the parameter when the Add-On Instruction executes. The value of the argument does not change from external code or HMI interaction outside of the Add-On Instruction itself.

# **Designing Add-On Instructions**

# Introduction

Add-On Instructions are available beginning with RSLogix 5000 software, version 16. Add-On Instructions are custom instructions that you design and create. Beginning in RSLogix 5000 software, version 18, high integrity and safety Add-On Instructions are available.

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# **About Add-On Instructions**

With Add-On Instructions, you can create new instructions for sets of commonly-used logic, provide a common interface to this logic, and provide documentation for the instruction.

Add-On Instructions are intended to be used to encapsulate commonly used functions or device control. They are not intended to be a high-level hierarchical design tool. Programs with routines are better suited to contain code for the area or unit levels of your application.

These are some benefits to using Add-On Instructions:

- Reuse code
  - You can use Add-On Instructions to promote consistency between projects by reusing commonly-used control algorithms.
  - If you have an algorithm that will be used multiple times in the same project or across multiple projects, it may make sense to incorporate that code inside an Add-On Instruction to make it modular and easier to reuse.
- Provide an easier to understand interface
  - You can place complicated algorithms inside of an Add-On Instruction, and then provide an easier to understand interface by making only essential parameters visible or required.
  - You can reduce documentation development time through automatically generating instruction help.

- Protect intellectual property
  - You can place your proprietary code inside of an Add-On Instruction, then use Source Protection to prevent others from viewing or changing your code.
- Simplify maintenance
  - You can simplify code maintenance because Add-On Instruction logic, monitored in RSLogix 5000 software, animates with tag values relative to that specific instance of the Add-On Instruction.
- Track revisions, and easily confirm instruction functionality with high-integrity Add-On Instructions
  - You can add an instruction signature to your Add-On Instruction, which generates a unique identifier and prevents the instruction from being edited without resulting in a change to the signature.

An Add-On-Instruction can be used across multiple projects. You can define the instructions, the instructions can be provided to you by someone else, or they can be copied from another project.

Once defined in a project, they behave similarly to the built-in instructions already available in RSLogix 5000 software. They appear on the instruction toolbar and in the instruction browser for easy access, just like built-in RSLogix 5000 software instructions.

Like standard Add-On Instructions, safety Add-On Instructions let you encapsulate commonly-used safety logic into a single instruction, making it modular and easier to reuse. In addition to the instruction signature used for high-integrity Add-On Instructions, safety Add-On Instructions feature a SIL 3 safety instruction signature for use in safety-related functions up to and including SIL 3.

Refer to the GuardLogix Controller Systems Safety Reference Manual, publication <u>1756-RM093</u>, for details on certifying safety Add-On Instructions and using them in SIL 3 safety applications.

# Components of an Add-On Instruction

Add-On Instructions are made up of the following parts.

#### **General Information**

The General tab contains the information you enter when you first create the instruction. You can use this tab to update that information. The description, revision, revision note, and vendor information is copied into the custom help for the instruction. The revision is not automatically managed by the software. You are responsible for defining how it is used and when it is updated.

🖲 Add-On	Instruction Definition - Simulation_DT_1st 🔲 🗖 🔀
General Param	eters Local Tags Scan Modes Signature Change History Help
<u>N</u> ame:	Simulation_DT_1st
<u>D</u> escription:	Simulation instruction which includes a dead time and a
Lype:	Tunction Block Diagram
<u>R</u> evision:	Major Minor Extended Text 0 0 Ist Sim DT 1st
Revision Note:	<u>^</u>
⊻endor:	Rockwell Automation
Copy all defau	It values of parameters and local tags whose values were modified to all tags of this instruction type
	Data Type Size: 276 byte (s) OK Cancel Apply Help

Class information for safety controller projects appears on the General tab as well. The class can be standard or safety. Safety Add-On Instructions must meet requirements specific to safety applications. See <u>Safety Add-On Instructions on page 19</u> for more information.

🖬 Add-On	Instruction Definition - SafetyAddOnInstru 📃 🗖 🔀
General Parar	meters Local Tags Scan Modes Signature Change History Help
<u>N</u> ame:	SafetyAddOnInstruction
Description:	~
	<u> </u>
<u>C</u> lass:	Safety 🗸
Туре:	Ladder Diagram Change Ivpe

#### **Parameters**

The parameters define the instruction interface; that is, how the instruction appears when used. The parameter order defines the order that the parameters appear on the instruction call.

_	Name	Usage	Data Type	Alias For	Default		Req	Vis	Description	External Access	Constant
_	EnableIn	Input	BOOL		1	Decimal			Enable Input - Sys	Read Only	
_	EnableOut	Output	BOOL		0	Decimal			Enable Output - S	Read Only	
	SimDTInv	Output	BOOL			Decimal		<ul> <li>Image: A start of the start of</li></ul>	If on, the dead tim	Read Only	
	SimInput	Input	REAL			Float	✓	✓	Enter the tag for t	Read/Write	
	SimDeadtime	Input	REAL			Float			Enter the dead tim	Read/Write	
	SimTimeConst	Input	REAL			Float		<b>~</b>	Enter the time con	Read/Write	
	SimOutput	Output	REAL		0.0	Float		<b>~</b>	Output value of th	Read Only	
	±-DA1	InOut	REAL[100]			Float	<b>~</b>	<b>~</b>	Enter an array of 1		
>											
N	fove <u>Up</u> Move <u>D</u>	lown									

## **Local Tags**

The Local Tags tab defines tags that are used by the logic within the Add-On Instruction and are not visible outside the instruction. Other Add-On Instructions or programs in the project cannot access these tags.

The only way to make a local tag or one of its members accessible from outside the instruction is by defining an alias parameter.

See Creating an Alias Parameter for a Local Tag on page 28.

ŧ	📾 Add-On Instruction Definition - Simulation_DT_1st v1.0 Sim 📰 🗖 🔀					
G	ieneral Parameters Loo	cal Tags Scan Mod	es Signature Cha	nge History Help		
	Name II A	Data Type	Default	Style	Description	
	+-DEDT_01	DEADTIME	{}			
	+-LDLG_01	LEAD_LAG	{}			
	2					
	ļ					
	Copy all default values of	f parameters and loca	l tags whose values v	vere modified to all ta	gs of this instruction ty	pe
	Logic Data Type	: Size: 276 byte (s)		ок 🗌	Cancel Ap	ply Help

## **Data Type**

Parameters and local tags are used to define the data type that is used when executing the instruction. The software builds the associated data type. The software orders the members of the data type that correspond to the parameters in the order that the parameters are defined. Local tags are added as hidden members.

## **Logic Routine**

The logic routine of the Add-On Instruction defines the primary functionality of the instruction. It is the code that executes whenever the instruction is called. Shown below is the interface of an Add-On Instruction and its primary logic routine that defines what the instruction does.



### **Optional Scan Mode Routines**

You can define additional routines for Scan mode behavior.

🛎 Add-On Instruction Definition - Simulation_DT_1st 📃 🗖 🔀
General Parameters Local Tags Scan Modes Signature Change History Help
The controller prescans and postscans the Add-On Instruction Logic routine but will not execute the Logic routine when EnableIn is false.
Optional Prescan, Postscan and EnableInFalse routines may be configured below.
Prescan routine: Executes prior to first scan on transition from program to run
Execute Prescan routine after the Logic routine is prescanned New Go To
Postscan routine: Executes on last scan of a step if SFC is configured for automatic reset
Execute Postscan routine after the Logic routine is postscanned New Go To
EnableInFalse routine: Executes when the EnableIn parameter is false
Execute EnableInFalse routine Go To
Copy all default values of parameters and local tags whose values were modified to all tags of this instruction type
Logic Data Type Size: 276 byte (s) OK Cancel Apply Help

# **Instruction Signature**

The instruction signature consists of an ID number that identifies the contents of the Add-On Instruction and a timestamp that identifies the specific date and time at which the instruction signature was generated or a signature history entry was made (whichever came last).

🖲 A do	l-On Instru	ction Def	inition - Simulatio	on_DT_1st 🔳 🗖 🔀
General	Parameters Loc	al Tags Scant	Nodes Signature Change Hist	ory Help
<b>Signa</b> Gener		niquely identify thi	s instruction and seal it from modi	iications.
Ac	Remove ID: d to History Tin ture History		9DE6 • • • • • • • • • • • • • • • • • • •	
	User	Signature ID	Timestamp	Description
	Clear Signature Hist	ory		
Сору	all default values of	parameters and	ocal tags whose values were mo	dified to all tags of this instruction type
Log	ic Data Type	Size: 276 byte (s	) OK Cano	cel Apply Help

Once generated, the instruction signature seals the Add-On Instruction, preventing it from being edited while the signature is in place. In addition, when a sealed safety Add-On Instruction is downloaded for the first time, a SIL 3 safety instruction signature is automatically generated. The safety instruction signature is an ID number that identifies the execution characteristics of the safety Add-On Instruction.

## **Signature History**

The signature history provides a record of signatures for future reference. A signature history entry consists of the name of the user, the instruction signature, the timestamp value, and a user-defined description. Up to six history entries can be stored. If a seventh entry is made, the oldest entry is automatically deleted.

## **Change History**

The Change History tab displays the creation and latest edit information that is tracked by the software. The By fields show who made the change based on the Windows user name at the time of the change.

🖗 Add-On Instruction Definition - Simulation_DT_1st 📃 🗖 🔀
General Parameters Local Tags Scan Modes Signature Change History Help
Created: 10/5/2005 2:56:13 PM By: NA\milted
Edited: 6/22/2009 1:04:18 PM By: NA\sellnid
<u>_</u> lear I dentities
Copy all default values of parameters and local tags whose values were modified to all tags of this instruction type
Logic Data Type Size: 276 byte (s) OK Cancel Apply Help

### Help

The name, revision, description, and parameter definitions are used to automatically build the Instruction Help. Use the Extended Description Text to provide additional Help documentation for the Add-On Instruction. The Instruction Help Preview shows how your instruction will appear in the various languages, based on parameters defined as required or visible.

🖲 Add-O	n Inst	ruction	Definit	ion - S	imulation <sub>.</sub>	_DT_1st	
General Pa	rameters	Local Tags	Scan Modes	Signature	Change History	Help	
Extended D	escription	Text:					
delay and a • Dead Tim	a first-orde e = 0 s. TI	lag. The defa nere is no dea	ault values are: d time delay.		The instruction gi I on a 1.0 s time c	ives the variable a o onstant.	dead time
Instruction I			۲_1st ۱	/1.0 S	im DT 1	lst	
Rockwe [Contact instructi	the Add		ction develop	er for que	stions or proble	ems with this	
Simulati	on instru	ction which	includes a	dead time	and a first orde	er lag.	
Availa	able L	anguag	es				<b>~</b>
<							>
Copy all de	L L	es of parametr ype Size: 276		gs whose va OK	lues were modifier	d to all tags of this in Apply	nstruction type

# Considerations for Add-On Instructions

When deciding whether to develop an Add-On Instruction, consider the following aspects.

### **Instruction Functionality**

Complex instructions tend to be highly application specific and not reusable, or require extensive configuration support code. As with the built-in instructions, Add-On Instructions need to do one thing, do it well, and support modular coding. Consider how the instruction will be used and manage interface complexity for the end user or application.

Add-On Instructions are best at providing a specific type of functionality or device control.

#### **Encapsulation**

Add-On Instructions are designed to fully encapsulate the code and data associated with the instruction. The logic inside an Add-On Instruction uses only the parameters and local tags defined by the instruction definition. There is no direct programmatic access to controller or program scope tags. This lets the Add-On Instruction be a standalone component that can execute in any application that calls it by using the parameters interface. It can be validated once and then locked to prevent edits.

#### Safety Add-On Instructions

Safety Add-On Instructions are used in the safety task of GuardLogix safety controllers. Create a safety Add-On Instruction if you need to use your instruction in a safety application. Safety Add-On Instructions are subject to a number of restrictions. These restrictions, enforced by RSLogix 5000 software and all GuardLogix controllers, are listed here for informational purposes only.

- They may use only safety-approved instructions and data types.
- All parameters and local tags used in a safety Add-On Instruction must also be safety class.
- Safety Add-On Instructions use relay ladder logic only and can be called in safety routines only, which are currently restricted to ladder logic.
- Safety Add-On Instructions may be referenced by other safety Add-On Instructions, but not by standard Add-On Instructions.
- Safety Add-On instructions cannot be created, edited, or imported when a safety project is safety-locked or has a safety task signature.

Refer to the GuardLogix Controller Systems Safety Reference Manual, publication <u>1756-RM093</u>, for information on how to certify a safety Add-On Instruction as well as details on requirements for safety applications, the safety task signature, and a list of approved instructions and data types.

#### **Instruction Signature**

The instruction signature, available for both standard and safety controllers, lets you quickly determine if the Add-On Instruction has been modified. Each Add-On Instruction has its own instruction signature on the Add-On Instruction definition. The instruction signature is required when an Add-On Instruction is used in SIL 3 safety-related functions, and may be required for regulated industries. Use it when your application calls for a higher level of integrity.

Once generated, the instruction signature seals the Add-On Instruction, preventing it from being edited until the signature is removed. This includes rung comments, tag descriptions, and any instruction documentation that was created. When an instruction is sealed, you can perform only these actions:

- Copy the instruction signature
- Create or copy a signature history entry
- Create instances of the Add-On Instruction
- Download the instruction
- Remove the instruction signature
- Print reports

The instruction signature does not prevent referenced Add-On Instructions or User-defined Data Types from being modified. Changes to the parameters of a referenced Add-On Instruction or to the members of a referenced User-defined Data Type can cause the instruction signature to become invalid. These changes include:

- adding, deleting, or moving parameters, local tags, or members in referenced User-defined Data Types.
- changing the name, data type, or display style of parameters, local tags, or members in referenced User-defined Data Types.

If you want to enable language switching or source protection on an Add-On Instruction that will be sealed with an instruction signature, you need to import the translated information or apply source protection before generating the signature. You must have the source key to generate a signature or to create a signature history entry for a source-protected Add-On Instruction that has an instruction signature.

See <u>Defining Source Protection for an Add-On Instruction on page 57</u> for more information on source protecting your Add-On Instruction.

#### Safety Instruction Signature

When a sealed safety Add-On Instruction is downloaded for the first time, a SIL 3 safety instruction signature is automatically generated.

For details on how to certify a safety Add-On Instruction, refer to the GuardLogix Controller Systems Safety Reference Manual, publication <u>1756-RM093</u>.

#### **Programming Languages**

Select the programming language based on the type of application you are developing. Ladder Diagram, Function Block Diagram, and Structured Text can be used for Add-On Instruction logic.

Each of the programming languages supported in RSLogix 5000 software is targeted for different types of applications and programming styles. In general, Ladder Diagram executes simple boolean logic, timers, and counters the fastest. Function Block Diagrams and Structured Text may be more efficient if you take advantage of the more advanced process and drives instructions available in those languages.

You cannot compare execution times for the same Add-On Instruction written in different programming languages. There are fundamental differences on how the different languages execute and are compiled.

You can change the programming language after you create the Add-On Instruction by clicking Change Type on the General tab of the Add-On Instruction Definition Editor. However, any existing logic will be lost.

#### **Transitional Instructions**

Some instructions execute (or retrigger) only when rung-condition-in toggles from false to true. These are transitional-relay ladder instructions. When used in an Add-On Instruction, these instructions will not detect the rung-in transition to the false state. When the EnableIn bit is false, the Add-On Instruction logic routine no longer executes, thus the transitional instruction does not detect the transition to the false state. Extra conditional logic is required to handle triggering of transitional instructions contained in an Add-On Instruction.

Some examples of transitional instructions include: ONS, MSG, PXRQ, SRT, some of the ASCII instructions, and some of the Motion instructions.

**TIP** The EnableInFalse routine can be used to provide the conditioning required to retrigger transitional instructions contained in an Add-On Instruction. However, this method will not work for calls to this Add-On Instruction contained in a Structured Text routine, since EnableIn is always true for calls in Structured Text.

#### **Instruction Size**

Add-On Instructions have one primary logic routine that defines the behavior of the instruction when executed. This logic routine is like any other routine in the project and has no additional restrictions in length. The total number of Input parameters plus Output parameters plus local tags can be up to 512. There are no limits on the number of InOut parameters. The maximum data instance supported (which includes Inputs, Outputs, and local tags) is two megabytes. The data type size is displayed on the bottom of the Parameters and Local Tags tab in the Add-On Instruction Definition.



#### **Runtime Editing**

Add-On Instructions can only be edited offline. If the intended functionality needs to be changed in a running controller, consider carefully if an Add-On Instruction is suitable.

## **Nesting Add-On Instructions**

Add-On Instructions can call other Add-On Instructions in their routines. This provides the ability to design more modular code by creating simpler instructions that can be used to build more complex functionality by nesting instructions. The instructions can be nested to seven levels deep.

Add-On Instructions cannot call other routines via a JSR instruction. You must use nested instructions if you need complex functionality consisting of multiple routines.

**TIP** To nest Add-On Instructions, both the nested instruction and the instruction that calls it must be of the same class type or the calling instruction will not verify. That is, standard Add-On Instructions may call only standard Add-On Instructions and safety Add-On Instructions may call only safety Add-On Instructions.

## **Routines Versus Add-On Instructions**

You can write your code in three basic ways: to run in-line as a main routine, to use subroutine calls, or as Add-On Instructions. The following table summarizes the advantages and disadvantages of each.

Aspect	Main Routine	Subroutine	Add-On Instruction
Accessibility	N/A	Within program (multiple copies, one for each program)	Anywhere in controller (single copy for the entire project)
Parameters	N/A	Pass by value	Pass by value via Input and Output parameters or by reference via InOut parameters
Numeric parameters	N/A	No conversion, user must manage	Automatic data type conversion for Input and Output parameters
Parameters data types	N/A	Atomic, arrays, structures	Atomic for any parameter Arrays and structures must be InOut parameters
Parameter checking	N/A	None, user must manage	Verification checks that correct type of argument has been provided for a parameter
Data encapsulation	N/A	All data at program or controller scope (accessible to anything)	Local data is isolated (only accessible within instruction)
Monitor/debug	In-line code with its data	Mixed data from multiple calls, which complicates debugging	Single calling instance data, which simplifies debugging
Supported programming languages	FBD, LD, SFC, ST	FBD, LD, SFC, ST	FBD, LD, ST
Callable from	N/A	FBD, LD, SFC, ST	FBD, LD, SFC via ST, ST
Protection	Locked and view only	Locked and view only	Locked and view only
Documentation	Routine, rung, textbox, line	Routine, rung, textbox, line	Instruction, revision information, vendor, rung, textbox, line, extended help

Advantages and Disadvantages of Routines and Add-On Instructions

Aspect	Main Routine	Subroutine	Add-On Instruction		
Execution performance	Fastest	JSR/SBR/RTN instructions add overhead All data is copied Indexed reference impact	Call is more efficient InOut parameters are passed by reference, which is faster than copying data for many types Parameter references are automatically offset from passed-in instruction tag location		
Memory use Most used		Very compact	Compact call requires more memory than a subroutine call All references need an additional word		
Edit	Online/offline	Online/offline	Offline only		
Import/export	Entire routine, including tags and instruction definitions to L5X	Entire routine, including tags and instruction definitions to L5X	Full instruction definition including routines and tags to L5X		
Instruction signature	N/A	N/A	32-bit signature value seals the instruction to prevent modification and provide high integrity		

Advantages and D	isadvantages of	<b>Routines and A</b>	dd-On Instructions

## **Programmatic Access to Data**

Input and Output parameters and local tags are used to define an instruction-defined data type. Each parameter or local tag has a member in the data type, although local tag members are hidden from external use. Each call to an Add-On Instruction uses a tag of this data type to provide the data instance for the instruction's execution.

The parameters of an Add-On Instruction are directly accessible in the controller's programming via this instruction-defined tag within the normal tag-scoping rules.

Local tags are not accessible programmatically through this tag. This has impact on the usage of the Add-On Instruction. If a structured (including UDTs), array, or nested Add-On Instruction type is used as a local tag (not InOut parameters), then they are not programmatically available outside the Add-On Instruction definition.

TIP

You can access a local tag via an alias parameter.

See Creating an Alias Parameter for a Local Tag on page 28.

#### Unavailable Instructions within Add-On Instructions

Most built-in instructions can be used within Add-On Instructions. The following instructions cannot be used.

Unavailable Instruction	Description
BRK	Break
EOT	End of Transition
EVENT	Event Task Trigger
FOR	For (For/Next Loop)
IOT	Immediate Output
JSR	Jump to Subroutine
JXR	Jump to External Routine
MAOC	Motion Arm Output Cam
PATT	Attach to Equipment Phase
PCLF	Equipment Phase Clear Failure
PCMD	Equipment Phase Command
PDET	Detach from Equipment Phase
POVR	Equipment Phase Override Command
RET	Return
SBR	Subroutine
SFP	SFC Pause
SFR	SFC Reset

Safety application instructions, such as Safety Mat (SMAT), may be used in safety Add-On Instructions only. For detailed information on safety application instructions, refer to the GuardLogix Safety Application Instruction Set Safety Reference Manual, publication <u>1756-RM095</u>.

In addition, the following instructions may be used in an Add-On Instruction, but the data instances must be passed as InOut parameters.

- ALMA (Analog Alarm)
- ALMD (Digital Alarm)
- All Motion Instructions
- MSG (Message)

### **Using GSV and SSV Instructions**

When using GSV and SSV instructions inside an Add-On Instruction, the following classes are supported:

- AddOnInstructionDefinition<sup>(1)(2)</sup>
- Axis
- Controller
- Controller Device
- CoordinateSystem
- CST
- DF1
- Fault Log
- Message

- MotionGroup
  Program<sup>(2)</sup>
- Routine<sup>(2)</sup>
- Redundancy
- Safety
- Serial Port
- $Task^{(2)}$
- Wall Clock Time
- (1) GSV-only. SSV instructions will not verify.
- (2) The classes that represent programming components Task, Program, Routine, AddOnInstructionDefinition - support only 'this' as the Instance Name.

When you enter a GSV or SSV instruction, RSLogix 5000 software displays the object classes, object names, and attribute names for each instruction. This table lists the attributes for the AddOnInstructionDefinition class.

#### AddOnInstructionDefinition Attributes

Attribute Name	Data Type	Attribute Description
MajorRevision	DINT	Major revision number of the Add-On Instruction
MinorRevision	DINT	Minor revision number of the Add-On Instruction
Name	String	Name of the Add-On Instruction
RevisionExtendedText	String	Text describing the revision of the Add-On Instruction
Vendor	String	Vendor that created the Add-On Instruction
LastEditDate	LINT	Date and time stamp of the last edit to an Add-On Instruction
SignatureID	DINT	32-bit instruction signature value
SafetySignatureID	DINT	32-bit safety instruction signature value

For more information on using GSV and SSV instructions, refer to the Logix5000 Controllers General Instructions Reference Manual, publication <u>1756-RM003</u>.

# **Considerations When Creating Parameters**

Consider the following information when you are creating parameters.

# Passing Arguments to Parameters by Reference or by Value

The following information will help you understand the differences between passing argument tags to parameters by reference or by value.

Aspect	By Value (Input or Output)	By Reference (InOut)	
Value	Synchronous - the argument's value does not change during Add-On Instruction execution.	Asynchronous- the argument's value may change during Add-On Instruction execution. Any access by the instruction's logic directly reads or writes the passed tag's value.	
Performance	Argument values are copied in and out of the parameters of the Add-On Instruction. This takes more time to execute a call to the instruction.	Parameters access argument tags directly by reference, which leads to faster execution of instruction calls.	
Memory usage	Most amount.	Least amount.	
Parameter data types supported	Atomic (SINT, DINT, INT, REAL, BOOL).	Atomic, arrays, and structures.	

## Selecting a Data Type for a Parameter

The Logix5000 controllers perform DINT (32 bit) and REAL (32 bit) math operations, which causes DINT data types to execute faster than other integer data types. Data conversion rules of SINT to INT to DINT are applied automatically, and can add overhead. Whenever possible, use DINT data types for the Add-On Instruction Input and Output parameters.

#### **Creating an Alias Parameter for a Local Tag**

Alias parameters simplify connecting local tags to an Input or Output tag that is commonly used in the Add-On Instruction's application without requiring that manual code be created to make the association. Aliases can be used to define an Input or Output parameter with direct access to a local tag or its member. Changing the value of an alias parameter changes the data of the local tag or local tag member it represents and vice versa.

Alias parameters are subject to these restrictions:

- Alias parameters must be either Input or Output parameters.
- You can only create an alias parameter for a local tag or its member.
- Only one Input and one Output parameter may be mapped to the same local tag or the same member of a local tag.
- Only BOOL, SINT, INT, DINT, and REAL data types may be used.
- Alias parameters may not be constants.
- The External Access type of an alias parameter matches the External Access type of the local tag to which it is mapped. For information on constants and External Access, see <u>Data Access Control on page 31</u>.

#### Using a Single Dimension Array as an InOut Parameter

The InOut parameter can be defined to be a single dimension array. When specifying the size of this array, consider that the user of your array can either:

- pass an array tag that is the same size as your definition.
- pass an array tag that is larger than your definition.

When developing your logic, use the Size instruction to determine the actual size of the referenced array to accommodate this flexibility.

TIP

When you monitor an array InOut parameter inside of the logic routine, the parameter definition is used to determine the size of the array. For example, assume you have defined an InOut parameter to be a 10-element array of DINTs and the end user passes in an array of 100 DINTs. Then if you open the Add-On Instruction logic, select the appropriate context for that call, and monitor the array parameter, only 10 elements will be displayed.

#### **Determining Which Parameters to Make Visible or Required**

To help be sure that specific data is passed into the Add-On Instruction, you can use required parameters. A required parameter must be passed an argument for a call to the instruction to verify. In Ladder Diagram and Structured Text, this is done by specifying an argument tag for these parameters. In a Function Block Diagram, required Input and Output parameters must be wired, and InOut parameters must have an argument tag. If a required parameter does not have an argument associated, as described above, then the routine containing the call to the Add-On Instruction will not verify.

For Output parameters, making a parameter visible is useful if you do not usually need to pass the parameter value out to an argument, but you do want to display its value prominently for troubleshooting.

Required parameters are always visible, and InOut parameters are always required and visible. All Input and Output parameters, regardless of being marked as required or visible, can be programmatically accessed as a member of the instruction's tag.



#### **Simulation Instruction in Function Block**

If you want a pin that is displayed in Function Block, but wiring to it is optional, set it as Visible.

#### Simulation Instruction in Ladder



- If you want the parameter's value displayed on the instruction face in Ladder, set the parameter as visible.
- An Output parameter of the BOOL tag type that is not required, but visible, will show as a status flag on the right side of the block in Ladder. This can be used for status flags like DN or ER.

This table explains the effects of the Required and Visible parameter settings on the display of the instruction.

			Ladder Diagram		Fun	Structured Text		
Parameter Type	ls the Parameter Required?	ls the Parameter Visible?	Does the Value display?	Does the Argument display?	Do You Need to Connect the Parameter?	Does the Argument display?	Can You Change Change the Visibility Setting Within the Function Block?	Does the Argument display?
Input	Y	Y	Y	Y	Y	N/A	Ν	Υ
Input	Ν	Y	Y	Ν	Ν	N/A	Y	N
Input	Ν	Ν	Ν	Ν	Ν	N/A	Y	N
Output	Y	Y	Y	Y	Y	N/A	Ν	Y
Output	N	Y	Y	Ν	Ν	N/A	Y	N
Output	N	Ν	N	Ν	N	N/A	Y	N
InOut	Y	Y	N	Y	N/A	Y	Ν	Y

Input, Output, and InOut Required and Visible Settings

If you have a parameter for which the user must specify a tag as its source for input or its destination as output, and you do not want this to be optional, set the parameter as required. Any required parameters are automatically set to visible.

The Visible setting is always set to visible for InOut parameters. All InOut parameters are required.

When you are using your Add-On Instructions, the Visible setting may be overridden in Function Block Diagram routines if the parameter is not required or already wired. Overriding the visibility at the instruction call does not affect this definition configuration.

## **Using Standard and Safety Tags**

TIP

When creating a safety Add-On Instruction, follow these guidelines for standard and safety tags:

- Standard tags may not be used as Input, Output, or InOut parameters of a safety Add-On Instruction.
- Safety tags may be used as Input parameters for standard Add-On Instructions.

#### **Data Access Control**

In RSLogix 5000 software, version 18 and later, you can prevent programmatic modification of InOut parameters by designating them as constants. You can also configure the type of access you will allow external devices, such as an HMI, to have to your tag and parameter data. You can control access to tag data changes with RSLogix 5000 software by configuring FactoryTalk security.

#### Constant Values

InOut parameters may be designated as constant value tags to prevent their data from being modified by controller logic. If the logic of an Add-On Instruction contains a write operation to a constant value parameter, the Add-On Instruction will not verify in the Add-On Instruction definition context.

Scope:	🔤 SafetyAddOnIn	struction 🛛 🗸	Show: All Tags			*	🖡 Enter Name Filter.			
Data Context:	🔋 SafetyAddOnIn	struction <d th="" 💙<=""><th><b>X B</b>.</th><th></th><th></th><th></th><th></th><th><math>\frown</math></th><th></th><th></th></d>	<b>X B</b> .					$\frown$		
Name	A	Usage	Alias For	Data Type	Class	Description	External Access /	Constant	Ştyle	
EnableIr	ו	Input		BOOL	Safety	Enable Input - Sys	. Read Only		Decimal	
Enable0	lut	Output		BOOL	Safety	Enable Output - S	Read Only		Depimal	
±-MNPara		InOut		DINT	Safety			<ul> <li>Image: A set of the set of the</li></ul>	Decimal	=
									/	

#### External Access

External Access defines the level of access that is allowed for external devices, such as an HMI, to see or modify tag values.

Add-On Instruction Parameters and Tags	External Access Options
Local tag	Read/Write
Input parameter	Read Only
Output parameter	None
EnableIn parameter	Read Only
EnableOut parameter	
InOut parameter	N/A

	Add-Or	Instructio	n Param	eters and L	.ocal Tags -	Simulate_I	eedback				×
S	cope:	🔝 Simulate_Feedb	back 🗸	Show: All Tags			🔽 🏹. Enter Nai	ne Filter			*
D	ata Context:	😢 Simulate_Feedb	oack <defini th="" 🔽<=""><th><u>»</u></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></defini>	<u>»</u>							
	Name	A	Usage	Alias For	Data Type	Description	External Access	Constant	Style	^	
	±-DelayTim	ne	Input		DINT	Enter the time in m	Read/Write		Decimal		
	±-DelayTim	her	Local		TIMER		Read/Write				Propertie
	EnableIn		Input		BOOL	Enable Input - Sys	Read Only		Decimal		iert.
	EnableO	ut	Output		BOOL	Enable Output - S	Read Only		Decimal		es S
	OutComr	nand	Input		BOOL	Enter the tag for t	Read/Write		Decimal		
	Simulate	Fault	Input		BOOL	To simulate a fault	Read/Write 🗸 🗸		Decimal		
ø							Read/Write				
							Read Only None			~	
•	Konitor Tags / Edit Tags / Konitor Tags / Konito										

# Planning Your Add-On Instruction Design

Take time to plan your instruction design. Advance planning can identify issues that need to be addressed. When defining the requirements of an instruction, you are also determining the interface. Keep the following aspects in mind when defining your instruction requirements and creating your Add-On Instruction.

#### **Intended Behavior**

- What is the purpose for creating the Add-On Instruction?
- What problem is it expected to solve?
- How is it intended to function?
- Do you need to higher level of integrity on your Add-On Instruction?

If so, you can generate an instruction signature as a means to verify that your Add-On Instruction has not been modified.

• Do you need to use safety application instructions and certify your safety Add-On Instruction to SIL-3 integrity?

For details on how to certify a safety Add-On Instruction, refer to the GuardLogix Controller Systems Safety Reference Manual, publication <u>1756-RM093</u>.

#### **Parameters**

- What data needs to be passed to the instruction?
- What information needs to be accessible outside of the instruction?
- Will alias parameters need to be defined for data from local tags that needs to be accessible from outside the Add-On Instruction?
- How will the parameters display? The order of the parameters defines the appearance of instruction.
- Which parameters should be required or visible?

### **Naming Conventions**

The instruction name will be used as the mnemonic for your instruction. Although the name can be up to 40 characters long, you will typically want to use shorter, more manageable names.

### **Source Protection**

- What type of source protection needs to be defined, if any?
- Who will have access to the source key?
- Will you need to manage source protection and an instruction signature?

Source protection can be used to provide read-only access of the Add-On Instruction or to completely lock or hide the Add-On Instruction and local tags.

Source protection must be applied prior to generating an instruction signature.

#### **Nesting - Reuse Instructions**

- Are there other Add-On Instructions that you can reuse?
- Do you need to design your instructions to share common code?

#### Local Tags

- What data is needed for your logic to execute but is not public?
- Identify local tags you might use in your instruction. Local tags are useful for items such as intermediate calculation values that you do not want to expose to users of your instruction.
- Do you want to create an alias parameter to provide outside access to a local tag?

#### **Programming Languages**

• What language do you want to use to program your instruction?

The primary logic of your instruction will consist of a single routine of code. Determine which RSLogix 5000 software programming language to use based on the use and type of application. Safety Add-On Instructions are restricted to Ladder Diagram.

• If execution time and memory usage are critical factors, refer to the Logix5000 Controllers Execution Time and Memory Use Reference Manual, publication <u>1756-RM087</u>.

#### **Scan Mode Routines**

• Do you need to provide Scan mode routines?

You can optionally define the scan behavior of the instruction in different Scan modes. This lets you define unique initialization behaviors on controller startup (Program -> Run), SFC step postscan, or EnableIn False condition.

• In what language do Scan mode routines need to be written?

#### Test

- How will you test the operation of your Add-On Instruction before commissioning it?
- What possible unexpected inputs could the instruction receive, and how will the instruction handle these cases?

## **Help Documentation**

• What information needs to be in the instruction help?

When you are creating an instruction, you have the opportunity to enter information into various description fields. You will also need to develop information on how to use the instruction and how it operates.

# Chapter **2**

# **Defining Add-On Instructions**

# Introduction

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# Create an Add-On Instruction

Follow these steps to create a new Add-On Instruction.

- **1.** Open a new or existing project.
- **2.** Right-click the Add-On Instructions folder in the Controller Organizer and choose New Add-On Instruction.

**3.** Type a unique name for the new instruction.

The name can be up to 40 characters long. It must start with a letter or underscore and must contain only letters, numbers, or underscores. The name must not match the name of a built-in instruction or an existing Add-On Instruction.

New Add	-On Instruction	×
<u>N</u> ame:	Motor_Starter	ОК
Description:	Starts and stops a motor	Cancel
	~	Help
<u>T</u> ype:	📔 Ladder Diagram 🗸 🗸	
-	Major Minor Extended Text	
<u>R</u> evision:		
Revision Note:	<u>^</u>	
	Y	
<u>V</u> endor:	Rockwell	
🔲 Open Logic	Routine	
🔽 O <u>p</u> en Defini	tion	

- **4.** Type a description for the new instruction, maximum 512 characters.
- 5. For safety projects, choose a class, either Standard or Safety.

The Class field is available on the New Add-On Instruction dialog box for safety controller projects.

**6.** Choose a programming language for Add-On Instruction logic.

The language Type defaults to Ladder Diagram for safety Add-On Instructions.

- 7. Assign a Revision level for the instruction.
- 8. Write a Revision note, if necessary.
- 9. Add information about the Vendor, if necessary.
- **10.** Click OK to create the instruction.
## **Create Parameters**

Use the Add-On Instruction Definition Editor to create the parameters for your instructions. Follow these steps to define the parameters for your instruction.

- **1.** In the Controller Organizer, right-click an Add-On Instruction and choose Open Definition.
- 2. Click the Parameters tab and enter a name for a parameter.

Name	Us	age	Data Type	Alias For	Default	Style	Req	Vis	Description	External Access	Constant	
EnableIn	Inp	out	BOOL			Decimal			Enable Input - Sys	Read Only		
EnableOu	t Ou	itput	BOOL		(	) Decimal			Enable Output - S	Read Only		
OutComm	and Inp	out	BOOL		(	) Decimal	<ul> <li>Image: A set of the set of the</li></ul>	<b>~</b>	Enter the tag for t	Read/Write		
SimulateF	ault Inp	out	BOOL		(	) Decimal		<b>V</b>	To simulate a fault	Read/Write		
+ DelayTim	e Inp	out	DINT		(	) Decimal			Enter the time in m	Read/Write		
×	Inp	out	DINT		(	) Decimal				Read/Write		
>												
Move Up Move Down												

**3.** Define the Usage, based on the type of parameter: Input, Output, InOut.



- An instruction with only Input parameters, except EnableOut, is treated as an input instruction in a Ladder diagram and is displayed left-justified. The EnableOut parameter is used for the rung-out condition.
- **4.** Select a data type, with the following options based on the parameter usage:
  - An Input parameter is passed by value into the Add-On Instruction and must be a SINT, INT, DINT, REAL, or BOOL data type.
  - An Output parameter is passed by value out of the Add-On Instruction and must be a SINT, INT, DINT, REAL, or BOOL data type.
  - An InOut parameter is passed by reference into the Add-On Instruction and can be any data type including structures and arrays.

# TIP

REAL data types are not permitted in safety Add-On Instructions.

**5.** If this parameter is intended as an alias for an existing local tag, click the Alias For pull-down menu to choose the local tag or its member.



You can also designate a parameter as an alias for a local tag by using the Tag Editor.

See Edit Parameters and Local Tags on page 41.

**6.** Set the default values.

Default values are loaded from the Add-On Instruction definition into the tag of the Add-On Instruction data type when it is created, and anytime a new Input or Output parameter is added to the Add-On Instruction.

#### TIP

Check the box at the bottom of the Add-On Instruction Definition Editor to 'Copy all default values of parameters and local tags whose values were modified to all tags of this instruction type' if you want to update existing invocations of the instruction to the new default values.

For details on copying default values, see <u>Copying</u>. Parameter or Local Tag Default Values on page 43.

- **7.** Set the display style.
- **8.** Check the box to make the parameter required or visible, as desired.

See <u>Determining Which Parameters to Make Visible or Required</u> on page 29.

If you decide to make the parameter required, it will also be visible.

9. Type a description, maximum 512 characters.

This description appears in the instruction's help.

- 10. Select an External Access type for Input or Output parameters.
- **11.** Check the Constant box for InOut parameters you want to designate as constant values.
- **12.** Repeat for additional parameters.

TIP

You can also create parameters by using the Tag Editor, New Parameter or Local Tag dialog box, or by right-clicking a tag name in the logic of your routine. The order that you create the parameters is how they will appear in the data type and on the instruction face. To rearrange the order on the Parameter tab of the Add-On Instruction Definition Editor, select the parameter row and click Move Up or Move Down.

A C	<b>d-On Instru</b> al Parameters Lo				Change Histor		1.0				
	Name	Usage	Data Type	Alias For	Default	Style	Reg	Vis	Description	External Access	Constant
	EnableIn	Input	BOOL		1	Decimal			Enable Input - Sys	Read Only	
	EnableOut	Output	BOOL		0	Decimal			Enable Output - S	Read Only	
	Stop	Input	BOOL		0	Decimal		<b>~</b>	Enter the tag that	Read/Write	
	Start	Input	BOOL		0	Decimal	<b>~</b>	<b>~</b>	Enter the tag that	Read/Write	
	Jog	Input	BOOL		0	Decimal			Jog command for t	Read/Write	
	AuxContact	Input	BOOL		0	Decimal			Auxiliary contact o	Read/Write	
	ClearFault	Input	BOOL		0	Decimal			To clear the fault	Read/Write	
	Out	Output	BOOL		0	Decimal	<ul> <li>Image: A set of the set of the</li></ul>	<b>~</b>	Output command t	Read Only	
	Fault	Output	BOOL		0	Decimal		<b>~</b>	If on, the motor di	Read Only	
		Input	DINT		0	Decimal			Enter the time (ms)	Read/Write	
Move Up Move Down											
C <u>o</u> p	y all default values o	f paramete	rs and local tags	whose valu	es were modif	ied to all tag	is of th	is insti	ruction type		
Lo	igic Data Type	Cine: 20 H	uto (a)				Í		OK Cance	Apply	Help

Add-On Instruction Definition Editor – Parameters Tab

# **Create Local Tags**

Use the Add-On Instruction Definition Editor to create the local tags for your instructions. Local tags contain data that will be used by your Add-On Instruction but that you do not want exposed to the user of your instruction. Local tags do not appear in the data structure for an Add-On Instruction because they are hidden members.

TIP	You can access local tag values from an HMI by specifying the
	name of the local tag as a member in an Add-On Instruction type tag. For example, the Motor_Starter v1.0 instruction, shown in <u>step 2</u> , has a tag called 'CheckAuxContact'. This tag can be referenced by an HMI via ' <i>instancetag</i> .CheckAuxContact', where instancetag is the tag used to call the instruction.

Follow these steps to define the local tags for your instruction.

**1.** In the Controller Organizer, right-click an instruction and choose Open Definition.

**2.** Click the Local Tags tab and type a name for a new tag and select a data type.

6	A	dd-On Instru	ction Defin	ition - Moto	or_Starter v	/1.0 📃 🗖 🔀
ſ	Gene	eral Parameters Loc	cal Tags Scan Mod	es Signature Chai	nge History Help	
		Name == 🗠	Data Type	Default	Style	Description
		CheckAuxCont	BOOL	0	Decimal	
			TIMER	{}		
		RunCommand	BOOL	0	Decimal	
	ø					
L						
		py all default values of	parameters and loca	l tags whose values v	vere modified to all ta	gs of this instruction type
[	L	ogic Data Type	Size: 20 byte (s)	ОК	Cancel	Apply Help

You cannot use these data types for local tags -

ALARM\_ANALOG, ALARM\_DIGITAL, MESSAGE, or any Motion data types, for example Axis or MOTION\_GROUP. To use these type of tags in your Add-On Instruction, define an InOut Parameter. Local tags also are limited to single dimension arrays, the same as User-Defined Data Types.



Refer to the GuardLogix Controller Systems Safety Reference Manual, publication <u>1756-RM093</u>, for a list of data types supported for safety instructions.

**3.** Set the default values.

Default values are loaded from the Add-On Instruction definition into the tag of the Add-On Instruction data type when it is created or any time a new tag is added to the Add-On Instruction.



Check the box at the bottom of the Add-On Instruction Definition Editor to 'Copy all default values of parameters and local tags whose values were modified to all tags of this instruction type' if you want to update existing invocations of the instruction to the new default values.

For details on copying default values, see <u>Copying</u> <u>Parameter or Local Tag Default Values on page 43</u>.

- **4.** Set the display style.
- 5. Type a description, a maximum of 512 characters.

6. Repeat for additional local tags.

TIP

When you create a local tag from the Local Tags tab, the External Access setting defaults to None. You can edit the External Access setting by using the Tag Editor.

See Edit Parameters and Local Tags on page 41.

# Edit Parameters and Local Tags

You can also add and edit parameters and local tags on the Edit Tags tab, shown below.

icope:	tor_Starter	*	Show: All Tags			🔽 🏹. Enter N	lame Filter		
)ata Context: 🔁 Mo	tor_Starter <del< th=""><th>finition&gt; 🔽</th><th><b>1</b></th><th></th><th></th><th></th><th></th><th></th><th></th></del<>	finition> 🔽	<b>1</b>						
Name	==  4 U	Isage	Alias For	Data Type	Description	External Access	Constant	Style	
AuxContact	In	nput		BOOL	Auxiliary contact o	Read/Write		Decimal	
CheckAuxConta	et Lo	ocal		BOOL		Read/Write		Decimal	
ClearFault	In	nput		BOOL	To clear the fault	Read/Write		Decimal	
EnableIn	In	nput		BOOL	Enable Input - Sys	Read Only		Decimal	
EnableOut	0	utput		BOOL	Enable Output - S	Read Only		Decimal	
Fault	0	utput		BOOL	If on, the motor di	Read Only		Decimal	
+-FaultTime	In	nput		DINT	Enter the time (ms)	Read/Write		Decimal	
+-FaultTimer	Lo	ocal		TIMER		Read/Write			
Jog	In	nput		BOOL	Jog command for t	Read/Write		Decimal	
Out	0	utput		BOOL	Output command t	Read Only		Decimal	
RunCommand	Lo	ocal		BOOL		Read/Write		Decimal	
Start	In	nput		BOOL	Enter the tag that	Read/Write		Decimal	
Stop	In	nput		BOOL	Enter the tag that	Read/Write		Decimal	

# Updates to Arguments Following Parameter Edits

If you edit an Add-On Instruction by adding, deleting, renaming, reordering, or changing the status or usage type of one or more parameters, RSLogix 5000 software, version 18 and later, automatically updates the arguments on calls to the instruction.

Source-protected routines and other source-protected Add-On Instructions that use the edited Add-On Instruction are not automatically updated if the source key is unavailable. The Add-On Instruction or routine may still verify, but the resulting operation may not be as intended.
 It is your responsibility to know where Add-On Instructions are used in logic when you make edits to existing Add-On Instructions.

A confirmation dialog box shows you the impacts of the edits and lets you review the pending changes before confirming or rejecting them.

ix 5000				X				
Changes pending for 'Conveyor_Control' instruction require updates to the calls of this instruction. Each call will be edited to maintain arguments passed to existing parameters. If you choose to apply the changes to the instruction, check all locations calling instruction 'Conveyor_Control' to								
ensure that they will execute correctly with the updates. Locations where instruction is called: Selected call's arguments:								
		Stop Start * JamClear	Conveyor_1_Stop_PB Conveyor_1_Entry_PE ?					
			nged Parameters Only					
		ch call?						
	Each call will be edited to maint f you choose to apply the chan ensure that they will execute co ocations where instruction is ca Container Routine Routine Routine Motor_Starter Routine Nester Motor_Starter Routine Nester Motor_Starter Routine Nester Ne	Changes pending for 'Conveyor_Control' instruction require Each call will be edited to maintain arguments passed to ex f you choose to apply the changes to the instruction, chec ensure that they will execute correctly with the updates. 	Changes pending for 'Conveyor_Control' instruction require updates to the calls Each call will be edited to maintain arguments passed to existing parameters. If you choose to apply the changes to the instruction, check all locations calling ensure that they will execute correctly with the updates. 	Changes pending for 'Conveyor_Control' instruction require updates to the calls of this instruction. Each call will be edited to maintain arguments passed to existing parameters. If you choose to apply the changes to the instruction, check all locations calling instruction 'Conveyor_Control' to ensure that they will execute correctly with the updates. Locations where instruction is called: Container Routine Location Stop Conveyor_1_Stop_PB Stop Conveyor_1_Stop_PB Start Conveyor_1_Entry_PE * JamClear ? <unknown> Conveyor_1_Out Show Changed Parameters Only This operation cannot be undone. Apply changes to the instruction and edit arguments for each call?</unknown>				

- An asterisk identifies parameters with changes pending.
- Existing arguments are reset to the parameters they were originally associated with.
- Newly added parameters are inserted with a '?' in the argument field, except for Structured Text, where the field is blank.
- Unknown parameters are created for arguments where associated parameters have been deleted.

To accomplish this update, RSLogix 5000 software tracks the changes made to the Add-On Instruction parameters from the original instruction to the final version. In contrast, the import and paste processes compare only parameter names to associate arguments with parameters. Therefore, if two different parameters have the same name, but different operational definitions, importing or pasting may impact the behavior of the instruction.

# Copying Parameter or Local Tag Default Values

In RSLogix 5000 software, version 18 or later, you can choose to copy parameter or local tag default values to all tags of the Add-On Instruction data type or just to specific tags. You can do so only when you are offline.



If you modify the default values of a parameter or local tag by using the Add-On Instruction Definition Editor, you can choose to copy the modified values to all of the tags of the Add-On Instruction data type by checking 'Copy all default values of parameters and local tags...'.

	Name	Usage	Data Type	Alias For	Default	Style	Req	Vis	Description	External Access	Constar
	EnableIn	Input	BOOL			<sup>1</sup> Decimal			Enable Input - Sys	Read Only	
	EnableOut	Output	BOOL			0 Decimal			Enable Output - S	Read Only	
	OutCommand	Input	BOOL			0 Decimal	<ul> <li>Image: A start of the start of</li></ul>	<b>V</b>	Enter the tag for t	Read/Write	
-	SimulateFault	Input	BOOL			<sup>0</sup> Decimal		<ul> <li>Image: A start of the start of</li></ul>	To simulate a fault	Read/Write	
	+-DelayTime	Input	DINT			0 Decimal			Enter the time in m	. Read/Write	
¢											
	Nove Up	Down									

You can also click the copy default values icon to copy default values to all tags the Add-On Instruction data type. The icon appears on the watch pane (as a context menu), data monitor, and logic editor when the Data Context is the Add-On Instruction's definition.

If you want to select which specific tags and values to copy, click the pull-down arrow of the copy default values icon and choose Copy Specified Values.



The Copy Default values dialog box shows the current default values for the parameters and local tags, and the instance tags where the Add-On Instruction is used or referenced.

Copy Default Values - 'Simulate	e_Feedback'
Default values of selected parameters and lo Specify which values to copy to which tags:	ocal tags in 'Simulate_Feedback' will be copied to specified tags of this type.
<u>D</u> efault Values:	Instances of 'Simulate_Feedback':
Image: Parameter   Image: Parameter	🗹 Tag Container Routine 🛆 Location
	I Motor_1_AuxContact G Motor_Starte I Motor_Starte Rung 2 I Conveyor_1_AuxContact G Motor_Starte I Nested_Motr Rung 2
Local Tag =8 △ Default	
✓ □ DelayTimer             ✓ □ DelayTimer.PRE	
▶ DelayTimer.ACC 0	
DelayTimer.EN 0	
✓ DelayTimer.TT 0 ✓ DelayTimer.DN 0	
	OK Cancel Help

Check the boxes to select which values to copy to which tags, and click OK.

Create Logic for the Add-On Instruction

Follow these steps to enter logic into your project.

**1.** In the Controller Organizer, expand the Add-On Instructions folder.



**2.** Expand the instruction and double-click the logic routine to open.



**3.** Edit your logic by using the available language editors.

### **Execution Considerations for Add-On Instructions**

An Add-On Instruction is executed just like any other routine belonging to a particular program. Because another task can preempt a program containing an Add-On Instruction that is being executed, an Add-On Instruction may be interrupted prior to completing its execution. In standard programs, you can use the User Interrupt Disable/Enable (UID/UIE) instructions to block a task switch if you want to be sure the Add-On Instruction executes uninterrupted before switching to another task.

TIP

UID and UIE instructions are not supported in the safety task of GuardLogix projects.

#### **Optimizing Performance**

The performance depends on the structuring, configuration, and the amount of code in an Add-On Instruction. You can pass large amounts of data through a structure by using an InOut parameter. The size of data referenced by an InOut parameter does not impact scan time and there is no difference between passing a user-defined type tag or an atomic tag because it is passed by reference.

When a rung condition is false, any calls to an Add-On Instruction are still processed even though the logic routine is not executed. The scan time can be affected when many instances of an Add-On Instruction are executed false. Be sure to provide instructions in your documentation if an Add-On Instruction can be skipped when the rung condition is false.

# Defining Operation in Different Scan Modes

To provide Add-On Instructions with the same flexibility as built-in instructions, optional Scan mode routines can be configured to fully define the behavior of the instruction. Scan mode routines do not initially exist for Add-On Instructions. You can create them depending upon the requirements of your instruction. Like all built-in instructions in the controller, Add-On Instructions support the following four controller Scan modes.

Scan Mode	Description				
True	The instruction is scanned as the result of a true rung condition or the EnableIn parameter is set True.				
False	The instruction is scanned as the result of a false rung condition or the EnableIn parameter is set False. Instructions in the controller may or may not have logic that executes only when that instruction is scanned false.				
Prescan	Occurs when the controller either powers up in Run mode or transitions from Program to Run. Instructions in the controller may or may not have logic that executes only when that instruction is executed in Prescan mode.				
Postscan <sup>(1)</sup>	Occurs as a result of an Action in an Sequential Function Chart (SFC) routine becoming inactive if SFCs are configured for Automatic Reset. Instructions in the controller may or may not have logic that executes only when that instruction is executed in Postscan mode.				

#### Scan Mode Types

 Postscan mode routines cannot be created for safety Add-On Instructions because safety instructions do not support SFC.

The default behavior for executing an Add-On Instruction with no optional scan routines created may be sufficient for the intended operation of the instruction. If you do not define an optional Scan Mode, the following default behavior of an Add-On Instruction occurs.

#### **Default Instruction Behavior**

Scan Mode	Result
True	Executes the main logic routine of the Add-On Instruction.
False	Does not execute any logic for the Add-On Instruction and does not write any outputs. Input parameters are passed values.
Prescan	Executes the main logic routine of the Add-On Instruction in Prescan mode. Any required Input and Output parameters' values are passed.
Postscan	Executes the main logic routine of the Add-On Instruction in Postscan mode.

For each Scan mode, you can define a routine that is programmed specifically for that Scan mode and can be configured to execute in that mode.

**User-programmed Routines for Specific Scan Modes** 

Scan Mode	Result
True	The main logic routine for the Add-On Instruction executes (not optional).
False	The EnableIn False routine executes normally in place of the main logic when a scan false of the instruction occurs. Any required (or wired in FBD) Input and Output parameters' values are passed.
Prescan	The Prescan routine executes normally after a prescan execution of the main logic routine. Any required Input and Output parameters' values are passed.
Postscan	The Postscan routine executes normally after a postscan execution of the main logic routine.

## **Enabling Scan Modes**

The Scan Modes tab in the Instruction Definition Editor lets you create and enable execution of the routines for the three Scan modes: Prescan, Postscan, and EnableInFalse.

#### **Prescan Routine**

When the controller transitions from Program mode to Run mode or when the controller powers up in Run mode, all logic within the controller is executed in Prescan mode. During this scan, each instruction may initialize itself and some instructions also initialize any tags they may reference. For most instructions, Prescan mode is synonymous with scanning false. For example, an OTE instruction clears its output bit when executed during Prescan mode. For others, special initialization may be done, such as an ONS instruction setting its storage bit during Prescan mode. During Prescan mode, all instructions evaluate false so conditional logic does not execute.

The optional Prescan routine for an Add-On Instruction provides a way for an Add-On Instruction to define additional behavior for Prescan mode. When a Prescan routine is defined and enabled, the Prescan routine executes normally after the primary logic routine executes in Prescan mode. This is useful when you want to initialize tag values to some known or predefined state prior to execution. For example, setting a PID instruction to Manual mode with a 0% output prior to its first execution or to initialize some coefficient values in your Add-On Instruction.

When an Add-On Instruction executes in Prescan mode, any required parameters have their data passed.

- Values are passed to Input parameters from their arguments in the instruction call.
- Values are passed out of Output parameters to their arguments defined in the instruction call.

These values are passed even when the rung condition is false in Ladder Diagram or when the instruction call is in a false conditional statement in Structured Text. When Function Block Diagram routines execute, the data values are copied to all wired inputs and from all wired outputs, whether or not the parameters are required.

Follow these steps to create a Prescan routine.

- **1.** In the Controller Organizer, right-click an instruction and choose Open Definition.
- 2. Click the Scan Modes tab.
- 3. Click New for Prescan Routine.



**4.** From the Type pull-down menu on the New Scan Mode Routine dialog box, choose the type of programming language: Ladder Diagram, Function Block, or Structured Text.

New Sca	an Mode Routine	×
Mode:	Prescan	ОК
<u>D</u> escription:		Cancel
<u>T</u> ype:	Function Block Diagram	Help
Instruction:	Simulation_DT_1st	
🔲 <u>O</u> pen Rou	itine	

- 5. Type a description of the Prescan behavior.
- 6. Click OK to create the routine and return to the Scan Modes tab.
- **7.** Define if the prescan routine executes (or not) by checking or clearing Execute Prescan routine after the logic routine is prescanned.

5	Prescan routine: Executes prior to first scan on transition from program to run		
	Execute Prescan routine after the Logic routine is prescanned	Delete	Go To

The Prescan routine can now be edited like any other routine.

## **Postscan Routine**

Postscan mode occurs only for logic in a Sequential Function Chart Action when the Action becomes inactive and the SFC language is configured for Automatic Reset (which is not the default option for SFC). When an SFC Action becomes inactive, then the logic in the Action is executed one more time in Postscan mode. This mode is similar to Prescan in that most instructions simply execute as if they have a false condition. It is possible for an instruction to have different behavior during Postscan mode than it has during Prescan mode.

When an Add-On Instruction is called by logic in an SFC Action or a call resides in a routine called by a JSR from an SFC Action, and the Automatic Reset option is set, the Add-On Instruction executes in Postscan mode. The primary logic routine of the Add-On Instruction executes in Postscan mode. Then if it is defined and enabled, the Postscan routine for the Add-On Instruction executes. This could be useful in resetting internal states, status values, or de-energizing instruction outputs automatically when the action is finished.

TIP

Because safety Add-On Instructions cannot be called from an SFC Action, this option is disabled for safety Add-On Instructions.

Follow these steps to create a postscan routine.

- **1.** In the Controller Organizer, right-click an instruction and choose Open Definition.
- 2. Click the Scan Modes tab.
- 3. Click New for Postscan Routine.

🛚 Add-On Instruction Definition - Simulation_DT_1st 📃 🗖 🔀
General Parameters Local Tags Scan Modes Signature Change History Help
The controller prescans and postscans the Add-On Instruction Logic routine but will not execute the Logic routine when EnableIn is false.
Optional Prescan, Postscan and EnableInFalse routines may be configured below.
Prescan routine: Executes prior to first scan on transition from program to run  Execute Prescan routine after the Logic routine is prescanned  New  Go To
Postscan routine: Executes on last scan of a step if SFC is configured for automatic reset
Execute Postscan routine after the Logic routine is postscanned
Execute EnableInFalse routine  Rew  Go To
Copy all default values of parameters and local tags whose values were modified to all tags of this instruction type           Logic         Data Type Size: 276 byte [s]         OK         Cancel         Apply         Help         ,

**4.** From the Type pull-down menu on the New Scan Mode Routine dialog box, choose the type of programming language: Ladder Diagram, Function Block, or Structured Text.

New Sca	an Mode Routine	×
Mode:	Postscan	ОК
<u>D</u> escription:		Cancel
<u>T</u> ype:	🔛 Function Block Diagram 💦	Help
Instruction:	🔝 Simulation_DT_1st	
🔲 <u>O</u> pen Rou	utine	

- **5.** Type a description of the postscan behavior.
- 6. Click OK to create the routine and return to the Scan Modes tab.
- **7.** Define if the postscan routine executes (or not) by checking or clearing Execute Postscan routine after the logic routine is postscanned.

ä	Postscan routine: Executes on last scan of a step if SFC is configured for au	tomatic reset	
	Execute Postscan routine after the Logic routine is postscanned	Delete	Go To

The Postscan routine can now be edited like any other routine.

### **EnableInFalse Routine**

When defined and enabled for an Add-On Instruction, the EnableInFalse routine executes when the rung condition is false or if the EnableIn parameter of the Add-On Instruction is false (0). This is useful primarily for scan false logic, when used as an output instruction in a Ladder routine. A common use of scan false is the setting of OTEs to the de-energized state when the preceding rung conditions are false. An Add-On Instruction can use the EnableInFalse capability to let you define behavior for the False conditions.

When the Add-On Instruction is executed in the false condition and has an EnableInFalse routine defined and enabled, any required parameters have their data passed.

- Values are passed to Input parameters from their arguments in the instruction call.
- Values are passed out of Output parameters from their arguments in the instruction call.

If the EnableInFalse routine is not enabled, the only action performed for the Add-On Instruction in the false condition is that the values are passed to any required Input parameters in ladder logic.

Follow these steps to create an EnableInFalse routine.

- 1. Right-click the instruction and choose Open Definition.
- 2. Click the Scan Modes tab.
- 3. Click New on EnableInFalse routine.

📾 Add-On Instruction Definition - Simulation_DT_1st 📃 🗖 🔀
General Parameters Local Tags Scan Modes Signature Change History Help
The controller prescans and postscans the Add-On Instruction Logic routine but will not execute the Logic routine when EnableIn is false.
Optional Prescan, Postscan and EnableInFalse routines may be configured below.
Prescan routine: Executes prior to first scan on transition from program to run         Execute Prescan routine after the Logic routine is prescanned         New
Postscan routine: Executes on last scan of a step if SFC is configured for automatic reset
Execute Postscan routine after the Logic routine is postscanned Rew Go To
EnableInFalse routine: Executes when the EnableIn parameter is false
Execute EnableInFalse routine Go To
Copy all default values of parameters and local tags whose values were modified to all tags of this instruction type           Logic         Data Type Size: 276 byte (s)         OK         Cancel         Apply         Help

**4.** From the Type pull-down menu on the New Scan Mode Routine dialog box, choose the type of programming language: Ladder, Function Block, or Structured Text.

New Sc	an Mode Routine		X
Mode:	EnableInFalse		OK
Description:		•	Cancel
		~	
<u>Т</u> уре:	🚯 Function Block Diagram	~	Help
Instruction:	Simulation_DT_1st		
Dpen Ro	utine		

- **5.** Type a description of the EnableInFalse behavior.
- **6.** Click OK to add an EnableInFalse routine to the Add-On Instruction definition.
- **7.** Define if EnableIn False routine executes (or not) by checking or clearing Execute EnableInFalse routine.

5	EnableInFalse routine: Executes when the EnableIn parameter is false		
	Execute EnableInFalse routine	Delete Go To	

The EnableInFalse routine can now be edited like any other routine.

Using the EnableIn and EnableOut Parameters

The EnableIn and EnableOut parameters that appear by default in every Add-On Instruction have behaviors that conform to the three language environments: Ladder Diagram, Function Block Diagram, and Structured Text.

To execute the primary logic routine in any of the language environments, the EnableIn parameter must be True (1). In general, the EnableIn parameter should not be referenced by the primary logic routine within the instruction definition. The EnableOut parameter will, by default, follow the state of the EnableIn parameter but can be overridden by user logic to force the state of this Parameter.



If EnableIn is False, then EnableOut cannot be made True in an EnableIn False routine.

If the EnableIn parameter of the instruction is False (0), the logic routine is not executed and the EnableOut parameter is set False (0). If an EnableInFalse routine is included in the instruction definition and it is enabled, the EnableInFalse routine will be executed.

#### **EnableIn Parameter and Ladder Diagram**

In the ladder diagram environment, the EnableIn parameter reflects the rung state on entry to the instruction. If the rung state preceding the instruction is True (1), the EnableIn parameter will be True and the primary logic routine of the instruction will be executed. Likewise, if the rung state preceding the instruction is False (0), the EnableIn parameter will be False and the primary logic routine will not be executed.

TIP

An instruction with only Input parameters, except EnableOut, is treated as an input instruction (left-justified) in a Ladder Diagram. The EnableOut parameter is used for the rung-out condition.

## **EnableIn Parameter and Function Blocks**

In the function block environment, the EnableIn parameter can be manipulated by the user through its pin connection. If no connection is made, the EnableIn parameter is set True (1) when the instruction begins to execute and the primary logic routine of the instruction will be executed. If a wired connection to this parameter is False (0), the primary logic routine of the instruction will not execute. Another reference writing to the EnableIn parameter, such as a Ladder Diagram rung or a Structured Text assignment, will have no influence on the state of this parameter. Only a wired connection to this parameter's input pin can force it to be False (0).

### **EnableIn Parameter and Structured Text**

In the Structured Text environment, the EnableIn parameter is always set True (1) by default. The user cannot influence the state of the EnableIn parameter in a Structured Text call to the instruction. Because EnableIn is always True (1) in Structured Text, the EnableInFalse routine will never execute for an instruction call in Structured Text.

# Change the Class of an Add-On Instruction

You can change the class of a safety Add-On Instruction so that it can be used in a standard task or standard controller. You can change the class in a safety project if the instruction does not have an instruction signature, you are offline, the application does not have a safety task signature, and is not safety-locked.

You can also change the class from standard to safety so that the Add-On Instruction can be used in the safety task.

Changing the class of an Add-On Instruction results in the same class change being applied to the routines, parameters, and local tags of the Add-On Instruction. The change does not affect nested Add-On Instructions or existing instances of the Add-On Instruction.

If any parameters or tags become unverified due to the change of class, they are identified on the Parameters and Local Tags tabs of the Add-On Instruction Editor.

If any of the restrictions for safety Add-On Instructions are violated by changing the class from standard to safety, one of the following errors is displayed and the change does not succeed:

- Routines must be of Ladder Diagram type.
- Safety Add-On Instructions do not support the Postscan routine.
- One or more parameters or local tags have an invalid data type for a safety Add-On Instruction.

You must edit the parameter, tag, or routine types before the class change can be made.

TIP

If the safety controller project contains safety Add-On Instructions, you must remove them from the project or change their class to standard before changing to a standard controller type.

# Testing the Add-On Instruction

You need to test and troubleshoot the logic of an instruction to get it working.

TIP

When a fault occurs in an Add-On Instruction routine, a fault log is created that contains extended information useful for troubleshooting.

#### **Before You Test**

Before you start to test an Add-On Instruction, do the following.

**1.** Open a project to debug offline.



Add-On Instructions can only be created or modified when offline. You can add, delete, or modify tag arguments in calls to Add-On Instructions while editing online, but you cannot edit arguments inside the Add-On Instruction while online.

**2.** Add the Add-On Instruction to the project, if it is not already there.

## **Test the Flow**

- **1.** Add a call to the instruction in a routine in the open project.
- 2. Assign any arguments to required parameters for your call.
- **3.** Download the project.

#### **Monitor Logic with Data Context Views**

You can simplify the online monitoring and troubleshooting of your Add-On Instruction by using Data Context views. The Data Context selector lets you select a specific call to the Add-On Instruction that defines the calling instance and arguments whose values are used to visualize the logic for the Add-On Instruction.



When troubleshooting an Add-On Instruction, use a non-arrayed instance tag for the call to the instruction. This lets you monitor and troubleshoot the instruction's logic routine with a data context. Variable indexed arrays cannot be used to monitor the logic inside an Add-On Instruction. Follow these steps to monitor the logic.

- **1.** Go into Run mode.
- **2.** Right-click the instruction call and choose Open Instruction Logic.



The logic routine opens with animated logic for the specific calling instance.

## **Verifying Individual Scan Modes**

The most straightforward method to verify Scan mode operation is to execute the instruction first with the Scan mode routine disabled, then again with it enabled. Then you can determine whether the Scan mode routine performed as expected.

Instruction	Description
True	This is simply the execution of the main logic routine.
False	In a ladder logic target routine, this entails placing an XIC before an instance of the instruction and evaluating instruction results when the XIC is false. In a Function Block target routine, this entails executing an instance of the instruction with the EnableIn parameter set to zero (0).
Prescan	Place the controller in Program mode, then place it in Run mode.
Postscan	With the controller configured for SFC Automatic Reset, place an instance of the instruction into the Action of an SFC. Run the SFC such that this Action is executed and the SFC proceeds beyond the step that is associated with this Action.

# Defining Source Protection for an Add-On Instruction

You can apply source protection to your Add-On Instruction to protect your intellectual property or prevent unintended edits of a validated source.

With source protection you can limit a user of your Add-On Instruction to read-only access or prevent access to the internal logic or local tags used by the instruction. You can protect the use and modification of your instructions with a source key file when you distribute them.

You have two options when using source protection.

• Source Protected

TIP

Users without the source key cannot view any routine or local tags, or make any edits to the Add-On Instruction. Choose this option if you want to protect the source definition of an Add-On Instruction from the view of a user. This may be due to the proprietary nature of the algorithms or for strict revision control.

• Source Protected with Viewable Option

Users without the source key can view all components of the Add-On Instruction including its logic and local tags, but are prevented from making any edits to the instruction.

Apply source protection before generating an instruction signature for your Add-On Instruction definition. You will need the source key to create a signature history entry.

When source protection is enabled, you can still copy the instruction signature or signature history, if they exist.

## **Enable the Source Protection Feature**

If source protection is unavailable and not listed in your menus, you can enable it by using the RS5KSrcPtc.exe tool on your installation CD.

If it is the first time the source protection has been configured, a dialog box appears asking to configure a source key file location.

Specify Source Key File Locati	ion 🔀
Source Key File Location:	
	OK Cancel
· · · · · · · · · · · · · · · · · · ·	

- **1.** Enter the location of (or browse to) where the source key is kept, it may or may not exist yet.
- 2. Click OK.

## **Apply Source Protection**

To source protect your Add-On Instruction follow these steps.

- **1.** In RSLogix 5000 software, choose Tools > Security > Configure Source Protection, to access the source configuration dialog box.
- **2.** Click Specify to identify the location for the sk.dat Source Key File.

Component	Source Key	Viewable	
🕂 🕞 Motor_Starter_Program			Protect
🗄 🕞 Sim_Dead_Time_Program			
🖬 🕞 Sort_Program			Unprotect
🗄 🔄 Add-On Instructions			Carlos and
—[ Conveyor_Control			
— 🔄 Motor_Starter			
- 🔄 Simulate_Feedback			
- 🔄 Simulation_DT_1st			
└─ 💽 Under_Developement_	Insertio		
Source Key File (sk.dat)	$\frown$		Help
Location: C:\Program Files\Rock	well Software\R. Specify	View Clear	
Looddon. O. a rogram raco a root.			Close

- **3.** Click OK in both dialog boxes to accept.
- 4. Click Yes to confirm creation of the sk.dat Key File.
- **5.** Expand the Add-On Instructions folder to view the instructions available to apply source protection.

All routines and Add-On Instruction definitions in the project are listed.

**6.** Select the Add-On Instruction you want to protect and click Protect.

Component	Source Key	Viewable	
🛛 🕞 Motor_Starter_Program			Protect
	1		Unprotect
		-	Unprotect
Cor Apply Source k	ev	×	
- Constant Sim Source Key to . - Constant Sim	apply to selected component		
		Cancel	
Allow viewii	ng of component(s)		
			Help
Source Key File (sk.dat)			neip
Location: C:\Program Files\Roc	kwell Software\R Specify	y View Clear	Close
			and the second sec

**7.** On the Source Key Entry dialog box, enter the individual source key for this component.

These source keys follow the conventions for routine source keys which are defined in the online help.

**8.** If you want to allow users to be able to see the logic and local tags, check 'Allow viewing of component(s)'.

The Source Protection Configuration should now resemble the following dialog box.

👪 Sour	ce Protection Configuration			×
Compor	nent	Source Key	Viewable	Second Second
E-	Motor_Starter_Program Sim_Dead_Time_Program			Protect
	Sort_Program Add-On Instructions			Unprotect
	Conveyor_Control     Motor_Starter     Simulate Feedback	(sk)		
	Simulation_DT_1st Under_Developement_Insertion	5		
L Source	e Key File (sk.dat)			Help
Locati	on: C:\Program Files\Rockwell S	oftware\R Specify View	Clear	Close
Disable	e Ability To Configure Protection			

IMPORTANT

If you want to observe the source protection settings, before you click Close, you must first do one of the following:

- click Clear
- click Disable Ability to Configure Source Protection
- remove the sk.dat file from the personal computer so that the source key is no longer present.

9. Click Close.

**10.** Save the project.

IMPORTANT	If you export a source-protected Add-On Instruction and want the exported contents encrypted, you must first remove, rename, or move the source key file (sk.dat). This causes the exported Add-On Instructions to be encrypted.

## **Observe Source Protection**

If you want to observe how source protection works, follow these steps.

- **1.** Rename the sk.dat file to some other name.
- 2. Start RSLogix 5000 software and open the project.

There is now no valid key file available to this RSLogix 5000 project.



When the source key is available, the Add-On Instruction behaves the same as if it were not source protected.

**3.** Review how the instruction appears in the Add-On Instructions folder.

Now the protected Add-On Instruction definition's routines and tag folder are not shown if fully protected, and the definition cannot be edited.

# Generate an Add-On Instruction Signature

The Signature tab of the Add-On Instruction Definition Editor lets you manage the instruction signature, create signature history entries, and view the safety instruction signature, if it exists. Instruction signatures are applied to the definition of the Add-On Instruction. All instances of that Add-On Instruction are sealed when the signature is applied.

## Generate, Remove, or Copy an Instruction Signature

On the Signature tab of the Add-On Instruction Definition Editor, click Generate to create an instruction signature or Remove to delete the instruction signature.

You must be offline to generate or remove an instruction signature. Both actions change the Last Edited Date.

#### **IMPORTANT** If you remove an instruction signature when the Add-On Instruction also has a safety instruction signature, the safety instruction signature is also deleted.

You can click Copy to copy the instruction signature and the safety instruction signature, if it exists, to the clipboard to facilitate record-keeping.

	<b>Signature</b> Generate a signature	to uniquely ide	ntify this instruction and seal it fro	om modifications.
	Remove Add to History	ID: Timestamp:	F98C3DE6 2009-06-22T18:04:18:015Z	
IMPORTANT	lf an inva	lid instru	ction signature is	detected during

verification, an error message indicates that the signature is invalid. You must remove the instruction signature, review the Add-On Instruction, and generate a new instruction signature.

### **Create a Signature History Entry**

The signature history provides a record of signatures for future reference. A signature history entry consists of the name of the user, the instruction signature, the timestamp value, and a user-defined description. You can only create a signature history if an instruction signature exists and you are offline. Creating a signature history changes the Last Edited Date, which becomes the timestamp shown in the history entry. Up to six history entries may be stored.

Follow these steps to create a signature history entry.

- **1.** On the Signature tab of the Add-On Instruction Definition Editor, click Add to History.
- **2.** Type a description, up to 512 characters long, for the entry.
- 3. Click OK.

TIP

To facilitate record-keeping, you can copy the entire signature history to the clipboard by selecting all the rows in the signature history and choosing Copy from the Edit menu. The data is copied in tab separated value (TSV) format.

To delete the signature history, click Clear Signature History while the instruction does not have an instruction signature. You must be offline to delete the Signature History.

#### **Generate a Safety Instruction Signature**

When a sealed safety Add-On Instruction is downloaded for the first time, a SIL 3 safety instruction signature is automatically generated. Once created, the safety instruction signature is compared at every download.

If RSLogix 5000 software detects an invalid safety instruction signature value, it generates a new safety instruction signature value in the offline project and displays a warning indicating that the safety instruction signature was changed. The safety instruction signature is deleted if the instruction signature is removed.

**IMPORTANT** After testing the safety Add-On Instruction and verifying its functionality, you must record the instruction signature, the safety instruction signature and the timestamp value. Recording these values will help you determine if the instruction functionality has changed.

Refer to the GuardLogix Controller Systems Safety Reference manual, publication <u>1756-RM093</u>, for details on safety application requirements.

#### Viewing and Printing the Instruction Signature

When the instruction signature has been generated, RSLogix 5000 software displays the instruction with the blue seal icon in the Controller Organizer, on the Add-On Instruction title bar, and in the Logic Editor.





When an instruction is sealed, the instruction signature is displayed on the faceplate of the instruction in the Ladder Diagram Editor and the Function Block Diagram Editor.



You can turn off the display of the instruction signature in the Workstation Options dialog box of RSLogix 5000 software.

#### TIP

You can also view the instruction signature and the safety instruction signature on the Quick View pane of the Controller Organizer and on the Signature tab of the Instruction Definition Editor dialog box.

The Add-On Instruction name, revision, instruction signature, safety instruction signature, and timestamp are printed on the Add-On Instruction Signature Listing report. You can also choose to include the instruction signature, safety instruction signature, and signature history on the Add-On Instruction report by clicking Print Options on the Generate Report dialog box.

# **Creating Instruction Help**

Custom instruction help is generated automatically as you are creating your Add-On Instructions. RSLogix 5000 software automatically builds help for your Add-On Instructions by using the instruction's description, revision note, and parameter descriptions. By creating meaningful descriptions, you can help the users of your instruction.

In addition, you can add your own custom text to the help by using the extended description field. You can provide additional help documentation by entering it on the Help tab of the Add-On Instruction Definition Editor. The instruction help is available in the instruction browser and from any call to the instruction in a language editor by pressing F1.

#### Write Clear Descriptions

When writing your descriptions keep the following in mind:

- Use short sentences and simple language.
- Be brief and direct when you write.
- Include simple examples.
- Proofread your entries.

This is an example of the Extended Description Text field in the Help tab of the Add-On Instruction Definition Editor. This area lets you create directions on how to use and troubleshoot your instruction. The Instruction Help Preview window shows how your text will look as generated instruction help.



## **Document an Add-On Instruction**

TIP

Follow these steps to create custom help for an instruction.

- 1. Right-click an Add-On Instruction and choose Open Definition.
- **2.** On the General tab, enter a description and a revision note for the Add-On Instruction to explain the purpose of the instruction.
- **3.** Click the Parameters tab and enter a meaningful description for each Parameter.

- **4.** Right-click each routine located below the Add-On Instruction in the Controller Organizer and choose Properties.
- 5. Enter a description for execution of each routine.
  - a. For the logic routine, describe execution of the instruction when EnableIn is true.
  - b. For the EnableInFalse routine (if one exists), describe actions that will take place when EnableIn is false, such as any outputs that get cleared.
  - c. For the Prescan routine (if one exists), briefly describe actions that will take place during the Prescan routine, such as initialization of any parameters.
  - d. For the Postscan routine (if one exists), briefly describe actions that will take place during the Postscan routine, such as initialization of any parameters resetting any internal state of the instruction.
- **6.** Click the Help tab of the Add-On Instruction Definition Editor and enter additional information in the Extended Description field.

The extended description can include the following information:

- Additional parameter information
- Description of how the instruction executes
- Change history notes





#### Language Switching

With RSLogix 5000 software, version 17 and later, you have the option to display project documentation, such as tag descriptions and rung comments in any supported localized language. You can store project documentation for multiple languages in a single project file rather than in language-specific project files. You define all the localized languages that the project will support and set the current, default, and optional custom localized language. The software uses the default language if the current language's content is blank for a particular component of the project. However, you can use a custom language to tailor documentation to a specific type of project file user.

Enter the localized descriptions in your RSLogix 5000 project, either when programming in that language or by using the import/export utility to translate the documentation offline and then import it back into the project. Once you enable language switching in RSLogix 5000 software, you can dynamically switch between languages as you use the software.

Project documentation that supports multiple translations within a project includes:

- component descriptions in tags, routines, programs, user-defined data types, and Add-On Instructions.
- equipment phases.
- trends.
- controllers.
- alarm messages (in ALARM\_ANALOG and ALARM\_DIGITAL configuration).
- tasks.
- property descriptions for modules in the Controller Organizer.
- rung comments, SFC text boxes, and FBD text boxes.

If you want to allow language switching on an Add-On Instruction that is sealed with an instruction signature, you must enter the localized documentation into your Add-On Instruction before generating the signature. Because the signature history is created after the instruction signature is generated, the signature history is not translatable. If the translated information already exists when you generate the Add-On Instruction signature, you can switch the language while keeping the signature intact because the switch does not alter the instruction definition, it only changes the language that is displayed.

For more information on enabling a project to support multiple translations of project documentation, refer to the online help.

# Motor Starter Instruction Example

The Motor\_Starter Add-On Instruction starts and stops a motor.

If the stop pushbutton is closed and the start pushbutton is pressed then:

- the motor gets the command to run.
- the instruction seals in the command, so the motor keeps running even after you release the start pushbutton.

If the stop pushbutton is pressed (opened), then the motor stops.

**Motor Starter Example Definition Editor General Tab** 

📾 Add-On	Instruction Definition - Motor_Starter v1.0 🛛 🔲 🔀
General Param	eters Local Tags Scan Modes Signature Change History Help
Name:	Motor_Starter
Description:	Starts and stops a motor
Туре:	Ladder Diagram Change Type
Revision:	Major Minor Extended Text
Revision Note:	
Vendor:	Rockwell
Copy all defau	It values of parameters and local tags whose values were modified to all tags of this instruction type
Logic	Data Type Size: 20 byte (s) OK Cancel Apply Help

#### Motor Starter Example Definition Editor Parameter Tab

	-											
	Name	Usage	Data Type	Alias For	Default	Style	Req	Vis	Description	External Access	Constant	_
	EnableIn	Input	BOOL		1	Decimal			Enable Input	Read Only		
	EnableOut	Output	BOOL		0	Decimal			Enable Outpu	Read Only		
	Stop	Input	BOOL		0	Decimal	<b>~</b>	<b>~</b>	Enter the tag	Read/Write		
	Start	Input	BOOL		0	Decimal	<b>~</b>	✓	Enter the tag	Read/Write		
	Jog	Input	BOOL		0	Decimal			Jog command	Read/Write		
	AuxContact	Input	BOOL		0	Decimal			Auxiliary cont	Read/Write		
	ClearFault	Input	BOOL		0	Decimal			To clear the f	Read/Write		
	Out	Output	BOOL		0	Decimal	<b>~</b>	<b>~</b>	Output comm	Read Only		
	Fault	Output	BOOL		0	Decimal		<b>~</b>	If on, the mot	Read Only		
	±-FaultTime	Input	DINT		0	Decimal			Enter the time	Read/Write		
ø												
h	Nove Up	ve Down										

				Data Context: 🐨 Motor_Starter <de< th=""><th></th></de<>	
If the Stop button is closed,	the motor gets the comm when you	and to run when you p press (open) the Stop	ress the Start button. The mot button. The run command turr	tor runs even after you release the St ns off if there is a fault.	art button. The motor stop
Stop command for the	Start command for	If on, the motor didn't start or			
motor.	the motor.	stop.			
Stop	Start	Fault	_		RunCommand
	RunCommand				
	The motor starts if the	e run command is on. T	he motor also starts if the Jog	g input is on and there isn't a fault.	
					Output command to the motor starter.
					If on, the motor
					starts. If off, the motor
					stops.
RunCommand	,				Out
Jog command for the	9				
motor.					
To jog the motor, turn on this bit.	If on, the motor				
To stop the jog,	didn't start or				
turn off this bit. Jog	stop. Fault				
<u> </u>					
		-			
GRT- Greater Than (A>B) Source A FaultTime 0 Source B 0	I €			Move Source FaultTime 0 Dest FaultTimer.PRE	*
				0	*
If CheckAuvContect is on	the rung chacks for that	etata of the euviliary o	intert. The Fault hit turns on it	f the auxiliary contact doesn't match th	a commanded state of th
II CHECKAUXCORIDALI IS ON,		п	otor within FaultTime.	r the auxiliary contact upesint match th	le commanded state of th
	A Output command to	Auxiliary contact of the motor.			
	the motor starter.	Make sure you set			
	If on, the motor starts.	the FaultTime. Otherwise, this			
	If off, the motor stops.	input doesn't do anything.			
CheckAuxContact	Out	AuxContact		T	0N
		)/[		Timer On	Delay -(EN)
1	A Output command to	Auxiliary contact of the motor.		Preset	0 + (DN)-
		Make sure you set		Accum	0 ←
		the FaultTime.			If on, the motor
	If on, the motor starts.	Otherwise, this			didn't start or
	starts. If off, the motor	Otherwise, this input doesn't do			
	starts.	Otherwise, this input doesn't do anything. AuxContact		FaultTimer DN	
	starts. If off, the motor stops.	input doesn't do anything.		FaultTimer.DN	
	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact			Fault
To clear the fault	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact	of the motor, turn on the Fault		Fault
To clear the fault of the motor, turn	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact	of the motor , turn on the Faulto		Fault (L) If on, the motor didn't start or
of the motor, turn on this bit.	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact	of the motor, turn on the Faulto		Fault
of the motor, turn	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact	of the motor, turn on the Faulto		Fault (L) If on, the motor didn't start or
of the motor, turn on this bit. ClearFault	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact	of the motor, turn on the Feutr		Fault (L) If on, the motor didin't start or stop, Fault
of the motor, turn on this bit. ClearFault	starts. If off, the motor stops. Out	input doesn't do anything. AuxContact	of the motor , turn on the Feult		Fault (L) If on, the motor didin't start or stop, Fault

#### Motor Starter Example Ladder Logic

The following diagrams show the Motor Starter instruction called in three different programming languages.

#### **Motor Starter Ladder Diagram**





#### **Motor Starter Function Block Diagram**

#### **Motor Starter Structured Text**

Motor\_Starter(Motor\_Starter\_ST, Stop\_PB, Start\_PB, Motor\_Out\_ST);

# Simulation Instruction Example

The Simulation\_DT\_1st Add-On Instruction adds a dead time and a first-order lag to an input variable.

#### **Simulation Example Definition Editor General Tab**

🖲 Add-On	Instruction Definition - Simulation_DT_1st 📃 🗖 🔀
General Param	eters Local Tags Scan Modes Signature Change History Help
<u>N</u> ame:	Simulation_DT_1st
<u>D</u> escription:	Simulation instruction which includes a dead time and a first order lag.
Lype:	Tunction Block Diagram Change Type
<u>R</u> evision:	Major Minor Extended Text 1      D     Sim DT 1 st
R <u>e</u> vision Note:	
⊻endor:	Rockwell Automation
Copy all defau	t values of parameters and local tags whose values were modified to all tags of this instruction type
Logic	Data Type Size: 276 byte (s) OK Cancel Apply Help

_	Name	Usage	Data Type	Alias For	Default	Style	Req	Vis	Description	External Access	Constant
	EnableIn	Input	BOOL		1	Decimal			Enable Input	Read Only	
	EnableOut	Output	BOOL			Decimal			Enable Outpu	Read Only	
	SimInput	Input	REAL			Float	<b>~</b>	<b>~</b>	Enter the tag	Read/Write	
	SimDeadti	Input	REAL			Float			Enter the dea	Read/Write	
	SimTimeC	Input	REAL			Float		✓	Enter the time	Read/Write	
	SimOutput	Output	REAL		0.0	Float		✓	Output value	Read Only	
	SimDTInv	Output	BOOL		0	Decimal		<b>~</b>	If on, the dea	Read Only	
	±-DA1	InOut	REAL[100]			Float	<b>V</b>	<b>~</b>	Enter an array		
•											
M	fove <u>U</u> p Mo	ve <u>D</u> own									

#### Simulation Example Definition Editor Parameter Tab

#### **Simulation Example Logic**



## Ladder Diagram Configuration

In this example, the instruction simulates a deadtime and lag (first order) process.

The Simulation\_DT\_1st instruction reads the control variable from the PID instruction. The PID instruction reads the SimOutput Parameter of the Simulation\_DT\_1st instruction.


#### **Function Block Diagram Configuration**

The PIDE instruction sends the control variable to the Simulation\_DT\_1st instruction. The Simulation\_DT\_1st instruction calculates an output and sends it to the PIDE instruction as the process variable



## **Structured Text Configuration**



## Notes:

## **Using Add-On Instructions**

## Introduction

Add-On Instructions are used in your routines like any built-in instructions. You add calls to your instruction and then define the arguments for any parameters.

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## Accessing Add-On Instructions

The Add-On Instruction can be used in any one of the Ladder Diagram, Function Block, or Structured Text languages (including Structured Text within Sequential Function Chart actions). The appearance of the instruction conforms to the language in which it is placed.

The Add-On Instructions in the project can be accessed from any of the normal instruction selection tools.

The instruction toolbar has an Add-On tab that lists all of the currently available Add-On Instructions in the project.



#### IMPORTANT

Safety Add-On Instructions can be used only in safety routines, which are currently restricted to ladder logic. Safety Add-On Instructions are shown in the Language Element Toolbar only when the routine is a safety routine.

## Use the Add Element Dialog Box

Follow these instructions to access the Add (language) Element dialog box.

**1.** Press Alt + Insert anywhere in the editor or by right-clicking the logic in the Editor.



2. Locate the Add-On Instruction you want to add to your routine.



**3.** Select the Add-On Instruction and click OK.

Use [Instruction Help >>] to display the instruction help for any instruction in the browser.

Add Ladder Element		
Ladder <u>E</u> lement: Motor_Starter	<pre>&lt;&lt; Instruction Help</pre>	RSLogix 5000 Instruction Help
Name Description		Motor_Starter v1.0
Hereit Motion Coordinated	<u> </u>	
🖶 🔁 ASCII Serial Port		Rockwell
🕀 🔁 ASCII String		[Contact the Add-On Instruction develope
🕀 🔁 ASCII Conversion		
🖶 🦲 Debug		Starts and stops a motor
🕂 🔁 Add-On		-
Conveyor ContrcStarts and stops a c	convevor	
He Motor Starter Starts and stops a r		• Available Languages
→ Simulate FeedbaSimulates a digital f		- Available Languages
Simulation DT 1Simulation instruction		-
	n which includ 💌	🗒 Relay Ladder
Show Language Elements By Groups	ОК	
		1.412 21 2
	Cancel	Motor_Starter
		Starts and stops a motor
New Add-On Instruction	Help	

## Include an Add-On Instruction in a Routine

Follow this procedure when you want to use an Add-On Instruction in one of your routines.

**1.** Open the Add-On Instruction folder in the Controller Organizer and view the listed instructions.

If the instruction you want to use is not listed, you need to do one of the following:

- Create the instruction in your project.
- Copy and paste an instruction into your project.
- Get the file for an exported instruction definition and then import the instruction into your current project.
- 2. Open the routine that will use the instruction.
- 3. Click the Add-On tab on the instruction toolbar.
- **4.** Click the desired Add-On Instruction, for example Simulation, and drag the instruction from the toolbar into the routine.



5. Define arguments for each Parameter on the instruction call.

The instruction appears as follows in each of the languages.

#### Ladder Diagram

Simulation_DT	_1st	1
Simulation instruction wh	ich includes	
Simulation_DT_1st	?	-(SimDTInv
SimInput	?	
	??	
SimTimeConstant	??	
SimOutput	??	
DA1	?	

Parameter With	Description
Single question mark	This is a required InOut parameter. Enter a tag.
Single and double question marks	This is a required Input or Output parameter. Enter a tag.
Double question marks	<ul> <li>This is not a required parameter. You can either:</li> <li>leave as is and use the default value.</li> <li>enter a different value if it's an Input parameter.</li> </ul>

#### **Function Block Diagram**



ltem	Description		
Nub on the end of pin	This is a required Input or Output parameter.		
	You must wire the pin to an IREF, OREF, connector, or another block to verify.		
Single question mark	This is a required InOut parameter. Enter a tag.		
No nub on the end of pin	This is not a required parameter. You can either:		
	• leave as is and use the default value.		
	<ul> <li>enter a different value if it's an Input parameter.</li> </ul>		

#### **Structured Text**

Sinulation\_DT\_lst(\_) Simulation instruction which includes a ... Simulation\_DT\_1st(Simulation\_DT\_1st, SimInput, DA1)

The instruction expects arguments for required parameters as listed in the instruction tooltip.

TIP

For help with an instruction, select the instruction and then press F1. In Structured Text, make sure the cursor is in the blue instruction name.

## Tips for Using an Add-On Instruction

This table describes programming tips for you to reference when using Add-On Instructions.

Торіс	Description
Instruction Help	Use the instruction help to determine how to use the instruction in your code.
Ladder Rungs	In a ladder rung, consider if the instruction should be executed on a false rung condition. It may improve scan time to not execute it.
Data Types	A data type defined with the Add-On Instruction is used for the tag that provides context for the execution from your code. A tag must be defined of this Add-On Instruction-defined type on the call to the instruction.
Indexed Tag	You can use an indirect array indexed tag for the Instruction instance. One drawback is that you cannot monitor the Add-On Instruction by using this as a data context.
Passing Data	<ul> <li>Input and Output parameters are passed by value.</li> <li>InOut parameters are passed by reference.</li> </ul>

# Programmatically Access a Parameter

Follow these procedures for any language when you want to access a an Add-On Instruction parameter that isn't available on the instruction face by default. 

_Name Motor_Starter EnableIn	Data Type Motor_Starter		Description
_	Motor_Starter	InOut	
EnableIn		11102/046	
	BOOL	Input	
EnableOut	BOOL	Output	
Stop	BOOL	Input	Stop command for the motor.
Start	BOOL	Input	Start command for the motor.
Jog	BOOL	Input	Jog command for the motor. To jog the motor, turn on this bit. To stop the jog, turn off this bit
	Stop Start	Stop BOOL Start BOOL	Stop BOOL Input Start BOOL Input

The following procedures demonstrate how to use the Jog parameter of the Motor Starter Add-On Instructions.

## Using the Jog Command in Ladder Diagram

The first rung sets the Jog bit of Motor\_Starter\_LD = Jog\_PB.



Use another instruction, an assignment, or an expression to read or write to the tag name of the parameter. Use this format for the tag name of the parameter.

Add\_On\_Tag.Parameter

Where	ls
Add_On_Tag	An instance tag defined by the Add On data type.
Parameter	Name of the parameter.

#### Using the Jog Command In Function Block Diagram

Any parameter can be made visible or invisible except those defined as required. Required parameters are always visible. If the parameter is required, you will see it checked in the Properties dialog box.

**1.** Click Properties for the instruction.

	Motor_Starter	$\rangle$
	Starts and stops a motor	
Ξ	Stop Out	<u> </u>
ŝ	Start	

**2.** Check the Vis checkbox of the Jog parameter to use it in your diagram.

M	oto	or_9	Starter Pro	pertie	s - Moto	r_Starter	_FBD (Sheet 1,
F	<sup>o</sup> aran	neters	Тад				
		Vis	Name	Argument	Value	Data Type	Description
	T		EnableIn		1	BOOL	Enable Input - System Defi
	0		EnableOut		1	BOOL	Enable Output - System De
	1		Stop		0	BOOL	Enter the tag that gives the
	I.		Start		0	BOOL	Enter the tag that gives the
			Jog		0	BOOL	Jog command for the motor
	1		AuxContact		0	BOOL	Auxiliary contact of the mot
	1		ClearFault		0	BOOL	To clear the fault of the mo
	0		Out		0	BOOL	Output command to the mo
	0		Fault		0	BOOL	If on, the motor didn't start
			The second second		0	DINT	Fortes the Case (as it to make

- 3. Click OK.
- **4.** Wire to the pin for the parameter.



### Using the Jog Command in Structured Text



# Monitor the Value of a Parameter

Follow this procedure when you want to see or change a parameter value of an Add-On Instruction.

- **1.** Open the Properties of the instruction based on what language you are using.
  - a. For either a Function Block or Ladder Diagram, click Properties .... for the instruction.



b. For Structured Text, right-click the instruction name and choose Properties.

Motor\_Starter(Motor\_Starter\_ST, Stop\_PB,Start\_PB,Motor\_Out\_ST);

	Vis	Name	Argument	Value	Data Type	Description
		EnableIn		1	BOOL	Enable Input - System Defi
)		EnableOut		1	BOOL	Enable Output - System De
	<b>V</b>	Stop		0	BOOL	Enter the tag that gives the
L	<b>V</b>	Start		0	BOOL	Enter the tag that gives the
		Jog		0	BOOL	Jog command for the motor
		AuxContact		0	BOOL	Auxiliary contact of the mot
		ClearFault		0	BOOL	To clear the fault of the mo
)	<b>V</b>	Out		0	BOOL	Output command to the mo
)	✓	Fault			BOOL	If on, the motor didn't start
L		+ FaultTime		<mark>∼</mark> 4000	DINT	Enter the time (ms) to wait f
] S <u>c</u>	ort Pa	rameters				Insert Instruction Defaults Insert Definition Defaults <u>S</u> ave Instruction Defaults

- 2. Monitor the value of the parameters and change any if needed.
- **3.** Type a new value for each parameter as needed.
- 4. Click Apply and when finished, OK.

# View Logic and Monitor with Data Context

Follow this procedure when you want to view the logic of an Add-On Instruction and monitor data values with the logic.

**1.** Right-click the instruction call in any routine.



2. Choose Open Instruction Logic.



To edit the logic of the Add-On Instruction, you must select the instruction <definition> in Data Context.

Data Context: 😥 Motor\_Starter <definition>

You can't edit the instruction logic:

- online.
- when the logic is in the context of an instruction call.
- if the instruction is source-protected.
- if the instruction is sealed with an instruction signature.

## Determine if the Add-On Instruction is Source Protected

An Add-On Instruction may be source protected so you cannot view the logic. Follow these steps to see if an Add-On Instruction is source protected.

1. Select the Add-On Instruction in the Controller Organizer.

The Add-On Instruction cannot be expanded when fully protected.

2. Look in the Quick View pane for Source Protection.

If the Source Protection attribute isn't listed, then the instruction isn't protected.



## Copy an Add-On Instruction

You can copy an Add-On Instruction into your project when it exists in another RSLogix 5000 project. After you copy the Add-On Instruction, you can use the instruction as is or rename it, modify it, and then use it in your programs.

IMPORTANT	Use caution when copying and pasting components between different versions of RSLogix 5000 programming software. RSLogix 5000 software only supports pasting to the same version or newer version of RSLogix 5000 software. Pasting to an earlier version of RSLogix 5000 software is not supported. When pasting to an earlier version, the paste action may succeed, but the results may not be as expected.
TIP	When copying and pasting Add-On Instructions, consider these guidelines:
	<ul> <li>You cannot paste a safety Add-On Instruction into a standard routine.</li> </ul>
	<ul> <li>You cannot paste a safety Add-On Instruction into a safety project that has been safety-locked or one that has a safety task signature.</li> </ul>

• You cannot copy and paste a safety Add-On Instruction while online.

Follow these steps to copy the Add-On Instruction.

- **1.** Open the RSLogix 5000 project that contains the Add-On Instruction.
- 2. Find the instruction in the Add-On Instructions folder.



**3.** Right-click the instruction and choose Copy.

- **4.** Go to the other project where you want to paste the instruction.
- 5. Right-click the Add-On Instructions folder and choose Paste.

Controller My_Contr Controller My_Contr Tasks     Motion Groups     Add-On Instructions	_	2	
🗄 🧰 Data Types	6.	New Add-On Instruction	
		Import Add-On Instruction	
	Ж	Cut	Ctrl+X
	Ē	Сору	Ctrl+C
	Ê.	Paste	Ctrl+V

## Store Your Add-On Instructions

There are two ways to store a group of Add-On Instructions together. One is to save your Add-On Instructions in a project file. Another is to create an L5X export file, as described in <u>Chapter 4</u>.

Follow these steps to store your instructions by saving them in a project file.

- **1.** Identify what instructions you want to store.
- **2.** Place them in a project file called something like 'MyInstructions.ACD'.
- **3.** Open other projects in additional instances of RSLogix 5000 software and use copy and paste or drag and drop to move a copy of the instruction from 'MyInstructions.ACD' to another project.

If any of these instructions reference the same Add-On Instruction or User-Defined Data Type, there is only one shared copy in the project file. When an Add-On Instruction is copied to another project, it also copies any instruction it references to the target project. 

## Notes:

## **Import and Export Add-On Instructions**

## Introduction

	Торіс	Page
	Creating an Export File	89
	Importing an Add-On Instruction	92
	Update an Add-On Instruction to a Newer Revision via Import	95
Creating an Export File	When you choose to export an Add-On Instruction Add-On Instruction includes all of its parameters, le routines. These will be imported with the Add-On automatically.	ocal tags, and
	Optionally, you can include any nested Add-On In User-Defined Data Types that are referenced by the Instruction. Referenced Add-On Instructions and de exported to the L5X file if you check 'Include all re Instructions and User-Defined Types' during the ex	e exported Add-O ata types are eferenced Add-On
	Add-On Instruction definition references may also a program, routine, set of rungs, or User-Defined I exported.	-
	If an Add-On Instruction uses Message (M InOut parameters of type MESSAGE, you rung containing the Add-On Instruction to tags. This captures the message configura and path.	may wish to export a include the MESSAG
	In deciding how to manage your Add-On Instruction export files, you need to consider your goals in sto	
	lf	Then
	You want to store many Add-On Instructions that share a set of common Add-On Instructions or User-Defined Data Types in a common location	Export to separate files as described or page <u>90</u> .
	common Add-On Instructions or User-Defined Data Types in a	files as described or
	common Add-On Instructions or User-Defined Data Types in a common location	files as described or

upon export to prevent modifications to the export file.

#### **Export to Separate Files**

If you want to store many Add-On Instructions that share a set of common Add-On Instructions or User-Defined Data Types in a common location, you may want to choose to export each Add-On Instruction and User-Defined Data Types to separate files without including references.

Follow these steps to export to separate files.

- **1.** Right-click the Add-On Instruction in the Controller Organizer, and choose Export Add-On Instruction.
- **2.** Select the common location to store the L5X file.



- **3.** Type a name for the file.
- **4.** Clear 'Include referenced Add-On Instructions and User-Defined Types'.
- 5. Click Export.
- **6.** Follow the above steps to individually export the other shared Add-On Instructions and User-Defined Data Types.

Using export in this way lets you manage the shared Add-On Instruction and User-Defined Data Types independently of the Add-On Instructions that reference them. One advantage of this is the ability to update the shared component without having to regenerate all the export files for the instructions that reference it. That is, it is only stored in one file instead of in every file whose instruction references it. This can help with the maintenance of the instructions as you only have to update one export file. To use Add-On Instructions that have been exported in a separate file, without references, you must first import any User-Defined Data Types of Add-On Instructions that the exported instruction references before the import of the referencing instruction can be successful. To do this, work from the bottom up. Import the lowest-level User-Defined Data Types and any User-Defined Data Types that reference them. Then, import the lowest-level Add-On Instructions, followed by any Add-On Instructions that references are in place, the import of the Add-On Instruction will succeed.

#### **Export to a Single File**

If you manage each Add-On Instruction as a standalone, you may want to export the instruction and any referenced Add-On Instructions or User-Defined Data Types into one export file. By including any referenced Add-On Instructions or User-Defined Data Types, you also make it easier to preserve the instruction signature of an Add-On Instruction.

Follow these steps to export to a single file and include any referenced items.

- **1.** Right-click Add-On Instruction in Controller Organizer and choose Export Add-On Instruction.
- 2. Choose the location to store the L5X file.



- **3.** Type a name for the file.
- **4.** Check 'Include referenced Add-On Instructions and User-Defined Types'.
- 5. Click Export.

This exports the selected Add-On Instruction and all the referenced instructions into the same export file. This file can be used to distribute an Add-On Instruction. When the exported Add-On Instruction is imported into the project, the referenced instructions are imported as well in one step.

## Importing an Add-On Instruction

You can import an Add-On Instruction that was exported from another RSLogix 5000 project. When importing an Add-On Instruction, the parameters, local tags, and routines are imported as part of the Add-On Instruction. Once the project has the Add-On Instruction, you can use it in your programs.

#### **Import Considerations**



#### Editing an L5K or L5X File

The EditedDate attribute of an Add-On Instruction must be updated if the Add-On Instruction is modified by editing an L5K or L5X file. If RSLogix 5000 software detects edits to the Add-On Instruction, but the 'Edited Date' attribute is the same, the Add-On Instruction will not be imported. When importing Add-On Instructions directly or as references, consider these guidelines.

#### **Considerations when Importing an Add-On Instruction**

Imported tags that reference an Add-On Instruction in the import file may be affected if the Add-On
Instruction is not imported as well. In this case, the imported tag's data may be converted if the existing Add-On Instruction's data structure is different and tag data may be lost.
If an existing Add-On Instruction is overwritten, project tag data may be converted if the Add-On Instruction's data structure is different and tag data may be lost.
See Import Configuration on page 94 for more information.
Imported logic that references the Add-On Instruction in the import file may be affected if the Add-On Instruction is not imported. If an existing Add-On Instruction is used for the imported logic reference and the parameter list of the Add-On Instruction in the project is different, the project may not verify or it may verify but not work as expected.
If an existing Add-On Instruction is overwritten, logic in the project that references the Add-On Instruction may be affected. The project may not verify or may verify but not work as expected.
See Import Configuration on page 94 for more information.
An Add-On Instruction cannot be overwritten during import while online with the controller, though a new Add-On Instruction may be created while online.
If the Final Name of an Add-On Instruction is modified during import configuration, the edit date of the imported Add-On Instruction will be updated. In addition, all logic, tags, User-Defined Data Types, and other Add-On Instructions in the import file that reference the Add-On Instruction will be updated to reference the new name. As a result, the edit date of any Add-On Instruction that references the Add-On Instruction will be updated.
Add-On Instructions that have been sealed with an instruction signature cannot be renamed during import.
Add-On Instructions cannot overwrite User-Defined Data Types. Add-On Instructions and User-Defined Data Types must have unique names.
If you import an Add-On Instruction with an instruction signature into a project where referenced Add-On Instructions or User-Defined Data Types are not available, you may need to remove the signature.
You can overwrite an Add-On Instruction that has an instruction signature by importing a different Add-On Instruction with the same name into an existing routine. Add-On Instructions that have been sealed with an instruction signature cannot be renamed during import.
You cannot import a safety Add-On Instruction into a standard task.
You cannot import a safety Add-On Instruction into a safety project that has been safety-locked or one that has a safety task signature.
You cannot import a safety Add-On Instruction while online.
Class, instruction signature, signature history, and safety instruction signature, if it exists, remain intact when an Add-On Instruction with an instruction signature is imported.

#### IMPORTANT

Importing an Add-On Instruction created in version 18 or later of RSLogix 5000 software into an older project that does not support Add-On Instruction signatures causes the Add-On Instruction to lose attribute data and the instruction may no longer verify.

#### **Import Configuration**

When you select a file to import, the Import Configuration dialog box lets you choose how the Add-On Instruction and referenced components are imported.

If there are no issues, you can simply click OK to complete the import.

If your Add-On Instruction collides with one already in the project, you can:

- rename it, by typing a new, unique name in the Final Name field.
- choose Overwrite from the Operation pull-down menu.
- choose Use Existing from the Operation pull-down menu.

Import Configuration			
Find: Find: Find Within: Final Name		<u>F</u> ind/Replace	
Import Content:			
📇 Add-On Instructions	Configure Add-Or	Instruction Properties	
Conveyor_Control       Image: Control       Image: Control </td <td>Import Name:</td> <td>Conveyor_Control</td> <td>The component collides with a</td>	Import Name:	Conveyor_Control	The component collides with a
- 👪 Routines	Operation:	Overwrite	definition already in the project.
Add-On Instructions		References will be imported as configured in the References folders	s
Errors/Warnings	Final <u>N</u> ame:	Conveyor_Control	Collision Details
	Description:	Starts and stops a conveyor	
			<ul> <li>'Conveyor_Control' already exists in project and is different. Existing references to the instruction type may be affected including:</li> </ul>
	Revision:	v1.0	<ul> <li>logic that calls instruction</li> </ul>
	Revision Note:		- tags of this instruction type - add-on instructions and user-
	Vendor:	Rockwell	
	Conveyor	_Control" already exists in project and is di	ifferent. Existing references may be affected.
	Calls to th	e add-on instruction may verify with chang calls to instruction to ensure they will exec	ges applied although calling arguments may not be what is intended. cute correctly with updates.
		a layout is different, data values for tags us y tags using this type to ensure tag data c	sing this type will be converted if possible and some values may be lost, converts as expected.
			OK Cancel Help
Add-on instruction definition 'Conveyor_Contro	I' already exists in proj	ect. Existing references may be affected.	

TIP

You can only rename an Add-On Instruction if it has not been sealed with an instruction signature.

To rename an Add-On Instruction that has been source-protected, you need the source key.

The Collision Details button lets you view the Property Compare tab, which shows the differences between the two instructions, and the Project References tab, which shows where the existing Add-On Instruction is used.

Click Add-On Instructions to see the Configure Add-On Instruction References view. If any referenced instruction definitions collide, the References folder is flagged.

## Update an Add-On Instruction to a Newer Revision via Import

When you need to update an instruction to a newer revision, you can import it from an L5X file or copy it from an existing project. You must be offline to update an Add-On Instruction.

Follow these steps to update an Add-On Instruction to a newer revision by importing it.

- **1.** Right-click the Add-On Instruction folder and choose Import Add-On Instruction.
- 2. Select the file with the Add-On Instruction and click Import.

Import Ins	truction				×
Look jn:	C RSLogix5000	lexamples	• +	🗈 💣 🎟 <b>-</b>	
My Recent Documents Desktop My Documents My Computer	ੴConveyor_Co	ontrol.L5X			
My Network Places	File <u>n</u> ame: Files of type: Files <u>c</u> ontaining: Int <u>o</u> :	Conveyor_Control RSLogix 5000 XML Files (*.	L5X)	V           V           V           V	Import Cancel Help

**3.** Review the Import Configuration dialog box, and from the Operations pull-down menu, choose Overwrite.

Import Configuration			×
Find: Find Within: Final Name		<u>Find/Replace</u>	
Import Content:	Configure Add-Or Import Name: Operation: Final Name: Description:	Instruction Properties Conveyor_Control Overwrite  Teleferences will be imported as configured in the References folde Conveyor_Control Starts and stops a conveyor	<ul> <li>Collision Details</li> <li>Conveyor_Control<sup>®</sup> already exists in project and is different. Existing references to the instruction type</li> </ul>
	Revision: Revision Note:	v2.0	may be affected including: - logic that calls instruction - tags of this instruction type - add-on instructions and user-
×	Calls to th Check all If the data	e add-on instruction may verify with char calls to instruction to ensure they will ex-	different. Existing references may be affected. nges applied although calling arguments may not be what is intended. ecute correctly with updates. using this type will be converted if possible and some values may be lost.
OK Cancel Help Add-on instruction definition "Convevor Control" already exists in project. Existing references may be affected.			

**4.** Click Collision Details to see any differences in the Add-On Instructions and to view where the Add-On Instruction is used.

The Property Compare tab shows the differences between the instructions, in this case, the Revision, Edited Date, and Software Revision.

Differences are highlighted.		
	Import Add-On Instruction	Existing Add-On Instruction
Revision:	2.0	1.0
Revision Note:		
Vendor:	Rockwell	Rockwell
Created Date:	10/24/2005 6:50:43 PM	10/24/2005 6:50:43 PM
Created By:	NA\Mills	NA\Mills
Edited Date:	5/27/2009 4:39:12 PM	5/20/2009 9:15:59 PM
Edited By:	NA\srdennis	NA\srdennis
Execute Prescan:	No	No
Execute Postscan:	No	No
Execute Enable In False:	No	No
Software Revision:	v17.00	v16.03
Additional Help Text:	Use this instruction to start and	st Use this instruction to start a
Logic is different:	No	

TIP

The Compare dialog box only compares metadata for each instruction definition, such as description, revision, or edited date. For effective revision control, enter a detailed revision note.

The Project References tab shows where the existing Add-On Instruction is used.

Add-On Instruction Name Collision -	Conveyor_Control 🛛 🛛 🔀			
Property Compare Project References				
Locations where 'Conveyor_Control' is called in project:	Selected call's arguments:			
Container Routine Location	Parameter Argument			
ingMotor_Starte ⊟Nested_Moto Rung 1	Stop     Conveyor_1_JamCl       Start     Conveyor_1_Entry_PE       Out     ?       3am     ? <unknown>     Conveyor_1_Out</unknown>			
Show Changed Parameters Only  If existing instruction is overwritten, once import completes, check all locations calling 'Conveyor_Control' to ensure they will execute correctly with the updates.				
Current Operation: Overwrite Qverwrite Use Existing	Close Help			

IMPORTANT

Check each routine where your Add-On Instruction is used to make sure that your existing program code will work correctly with the new version of the instruction.

For more information on updates to arguments, see <u>Updates to</u> <u>Arguments Following Parameter Edits on page 41</u>.

**5.** Click Close and then OK to complete the operation.

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## **Rockwell Automation Support**

Rockwell Automation provides technical information on the Web to assist you in using its products. At <a href="http://www.rockwellautomation.com/support/">http://www.rockwellautomation.com/support/</a>, you can find technical manuals, a knowledge base of FAQs, technical and applicationnotes, sample code and links to software service packs, and a MySupport feature that you can customize to make the best use of these tools.

For an additional level of technical phone support for installation, configuration, and trouble shooting, we offer TechConnect support programs. For more information, contact your local distributor or Rockwell Automation representative, or visit <a href="http://www.rockwellautomation.com/support/">http://www.rockwellautomation.com/support/</a>.

#### **Installation Assistance**

If you experience an anomoly within the first 24 hours of installation, review the information that's contained in this manual. You can contact Customer Support for initial help in getting your product up and running.

United States or Canada	1.440.646.3434
	Use the <u>Worldwide Locator</u> at <u>http://www.rockwellautomation.com/support/americas/phone_en.html</u> , or contact your local Rockwell Automation representative.

#### **New Product Satisfaction Return**

Rockwell Automation tests all of its products to ensure that they are fully operational when shipped from the manufacturing facility. However, if your product is not functioning and needs to be returned, follow these procedures.

	Contact your distributor. You must provide a Customer Support case number (call the phone number above to obtain one) to your distributor to complete the return process.
Outside United States	Please contact your local Rockwell Automation representative for the return procedure.

## **Documentation Feedback**

Your comments will help us serve your documentation needs better. If you have any suggestions on how to improve this document, complete this form, publication <u>RA-DU002</u>, available at <u>http://www.rockwellautomation.com/literature/</u>.

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