# **Model 926 ADCAM® Multichannel Buffer Hardware Manual**

## Advanced Measurement Technology, Inc.

a/k/a/ ORTEC®, a subsidiary of AMETEK®, Inc.

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## **Quality Control**

Before being approved for shipment, each ORTEC instrument must pass a stringent set of quality control tests designed to expose any flaws in materials or workmanship. Permanent records of these tests are maintained for use in warranty repair and as a source of statistical information for design improvements.

## **Repair Service**

If it becomes necessary to return this instrument for repair, it is essential that Customer Services be contacted in advance of its return so that a Return Authorization Number can be assigned to the unit. Also, ORTEC must be informed, either in writing, by telephone [(865) 482-4411] or by facsimile transmission [(865) 483-2133], of the nature of the fault of the instrument being returned and of the model, serial, and revision ("Rev" on rear panel) numbers. Failure to do so may cause unnecessary delays in getting the unit repaired. The ORTEC standard procedure requires that instruments returned for repair pass the same quality control tests that are used for new-production instruments. Instruments that are returned should be packed so that they will withstand normal transit handling and must be shipped PREPAID via Air Parcel Post or United Parcel Service to the designated ORTEC repair center. The address label and the package should include the Return Authorization Number assigned. Instruments being returned that are damaged in transit due to inadequate packing will be repaired at the sender's expense, and it will be the sender's responsibility to make claim with the shipper. Instruments not in warranty should follow the same procedure and ORTEC will provide a quotation.

## **Damage in Transit**

Shipments should be examined immediately upon receipt for evidence of external or concealed damage. The carrier making delivery should be notified immediately of any such damage, since the carrier is normally liable for damage in shipment. Packing materials, waybills, and other such documentation should be preserved in order to establish claims. After such notification to the carrier, please notify ORTEC of the circumstances so that assistance can be provided in making damage claims and in providing replacement equipment, if necessary.

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## **CONTENTS**



## **SAFETY INSTRUCTIONS AND SYMBOLS**

This manual contains up to three levels of safety instructions that must be observed in order to avoid personal injury and/or damage to equipment or other property. These are:

- **DANGER** Indicates a hazard that could result in death or serious bodily harm if the safety instruction is not observed.
- **WARNING** Indicates a hazard that could result in bodily harm if the safety instruction is not observed.
- **CAUTION** Indicates a hazard that could result in property damage if the safety instruction is not observed.

Please read all safety instructions carefully and make sure you understand them fully before attempting to use this product. In addition, the following symbol may appear on the product:



Please read all safety instructions carefully and make sure you understand them fully before attempting to use this product.

## **SAFETY WARNINGS AND CLEANING INSTRUCTIONS**

**DANGER** Opening the cover of this instrument is likely to expose dangerous voltages. Disconnect the instrument from all voltage sources while it is being opened.

**WARNING** Using this instrument in a manner not specified by the manufacturer may impair the protection provided by the instrument.

#### **Cleaning Instructions**

To clean the instrument exterior:

- 
- **•** Unplug the instrument from the ac power supply.<br>• Remove loose dust on the outside of the instrum ■ Remove loose dust on the outside of the instrument with a lint-free cloth.<br>● Remove remaining dirt with a lint-free cloth dampened in a general-purpo
- Remove remaining dirt with a lint-free cloth dampened in a general-purpose detergent and water solution. Do not use abrasive cleaners.

**CAUTION** To prevent moisture inside of the instrument during external cleaning, use only enough liquid to dampen the cloth or applicator.

! Allow the instrument to dry completely before reconnecting it to the power source.







## **ORTEC MODEL 926 ADCAM MULTICHANNEL BUFFER**

## **1. DESCRIPTION**

## **1.1. GENERAL**

The ORTEC Model 926 Multichannel Buffer (MCB) is a NIM module designed for high-performance data acquisition in nuclear spectroscopy applications. ORTEC offers MCA emulation software and quantitative analysis software for almost every application.

The Model 926 can be configured to connect to a PC with our DPM-USB Dual-Port-Memory-to-USB Interface Converter, or via the legacy parallel printerport interface. The DPM-USB converter (one converter per 926 unit) makes it simple to connect multiple 926s and other ORTEC USB MCBs to the host PC's native USB ports and/or powered USB

hubs. You can also connect a daisy chain of 926s to the PC's printer port.

#### **1.2. INTENDED AUDIENCE**

This manual describes the initial installation and setup of the Model 926. Section 2 gives the Model 926 specifications for reference. Section 3 tells how to install and configure the Model 926. Section 4 describes the basics of MCA operation. Section 5 gives some troubleshooting information. The appendix is intended for the user who wishes to write custom software to control the Model 926. IT explains the commands used to control the system.

## **2. SPECIFICATIONS**

#### **2.1. PERFORMANCE**

**ADC** Successive-approximation type with slidingscale linearization.

**Max Resolution** Software selectable as 8192, 4096, 2048, 1024, and 512.

**Dead Time per Event** 8 µs, including memory transfer.

**Integral Nonlinearity**  $\leq \pm 0.025\%$  over the top 99% of the dynamic range.

**Differential Nonlinearity** <±1% over the top 99% of the dynamic range.

**Gain Instability**  $\leq \pm 50$  ppm/°C.

Dead-Time Correction Printed wiring board jumper selects either Extended Live-time correction according to the Gedcke-Hale method, $1$  or Simple Live-Time correction with the clock turned off during the conversion time.

**Data Memory** 8K channels of battery backed-up memory;  $2^{31}$ -1 counts per channel (over 2 billion).

#### **Presets**

- **Real Time/Live Time: Multiples of 20 ms.**<br> **Region-of-Interest: Peak count/Integral count.**
- **Region-of-Interest**: Peak count/Integral count.<br> **Data Overflow**: Terminates acquisition when
- **Data Overflow**: Terminates acquisition when<br>any channel exceeds 2<sup>31</sup>-1. any channel exceeds 231-1.

**Microprocessor** Intel 80C188; 32K Dual-Port RAM with battery backup; 16K "scratchpad" RAM with battery backup. 32K program memory.

## **2.2. INDICATORS AND CONTROLS**

**CPU BUSY** Red, busy-rate LED; intensity indicates the relative activity of the microprocessor.

**ADC BUSY** Red, busy-rate LED flashes once for each pulse digitized by the ADC.

**ADC ZERO** Front-panel screwdriver potentiometer, ±250 mV.

**ADC LLD** Front-panel screwdriver potentiometer, from 0 to 10% full scale.

<sup>1</sup> Ron Jenkins, R.W. Gould, and Dale Gedcke, *Quantitative X-Ray Spectrometry* (New York: Marcel Dekker, Inc.), 1981, pp. 266–267.

#### **2.3. INPUTS**

**INPUT** Accepts positive unipolar, positive gated integrator, or positive-leading bipolar analog pulses in the dynamic range from 0 to  $+10$  V;  $+12$  V maximum; semi-Gaussian-shaped or gatedintegrator-shaped time constants from 0.25 to 30 µs,<br>or delay-line-shaped with width >0.25 µs.  $Z_{in} \approx 1 \text{ k}\Omega$ , or delay-line-shaped with width >0.25 μs. Z<sub>in</sub> ≈ 1 kΩ,<br>dc-coupled. No internal delay. BNC connectors on front and rear panels.

**ADC GATE** Optional, slow-positive NIM input. Computer-selectable Coincidence Anticoincidence. Signal must occur prior to and extend 0.5 µs beyond the peak of the pulse; frontpanel BNC connector. Z<sub>in</sub> ~ 1 kΩ.<br>

**PUR** Pile-up rejection input; accepts slow-positive NIM signal; signal must occur prior to peak detect.  $Z_{\text{in}}$  > 1 kΩ. BNC connector on rear panel.

**BUSY** Busy input used by live-time correction circuits. Accepts slow-positive NIM signal; signal must occur prior to peak detect.  $Z_{in} > 1$  kΩ. BNC connector on rear panel.

#### **2.4. INTERFACE CONNECTORS**

**PARALLEL PORT** Provides for control of the instrument and access to the data memory from a standard PC printer port. Rear-panel mounted, 25-pin D-shaped male connector.

**PRINTER** Optional connection provided to either connect to another 926 MCB or a printer to the system. Rear-panel mounted, 25-pin D-shaped female connector.

**DUAL-PORT MEMORY** Optional 37-pin D connector provides the PC with a communication link and direct access to the Model 926's internal data memory. The DUAL-PORT MEMORY connector replaces the PRINTER connector on the rear panel when installed.

#### **2.5. ELECTRICAL AND MECHANICAL**

**POWER REQUIRED** +12 V, 200 mA; -12 V, 200 mA; +6 V, 600 mA.

**WEIGHT** Net 0.9 kg (2 lb), Shipping 2.25 kg (5 lb).

**DIMENSIONS** NIM-standard single-wide 3.43 x 22.13 cm (1.35 x 8.714 in.) front panel per DOE/ER-0457T.

## **3. INSTALLATION**

- 1. Install the accompanying version of our MAESTRO®-32 MCA Emulation Software (and the CONNECTIONS-32 Update Kit, if included) according to its instructions. Depending on the 926-to-PC interface you will use, mark the appropriate checkbox on the installation wizard's Instrument Family page as follows:
	- **.** If using a DPM-USB interface converter to attach the 926 to the PC, mark the **DPM-USB** checkbox.
	- **•** If connecting via the printer port, mark the **DART or any other printer-port based device** checkbox.
- 2. Select the live-time correction mode (Section 3.1).
- 3. If using a DPM-USB interface converter, the MCB address must be set to the factory default of 1. If this is a new instrument, it is ready to use

without modification. Install the DPM-USB converter according to its instructions.

- 4. If connecting via the printer port, see Section 3.3 for instructions on setting the MCB/PRN addressing jumper.
- 5. To switch between the DPM and printer-port interfaces, see Section 3.4.
- 6. Cable the spectroscopy system together and connect it to the PC.
- 7. Power on the 926. If the Windows "found new hardware" wizard opens, follow the prompts, choosing (a) to *not go to the internet* to find the driver, and (b) to *automatically* locate the driver. If the wizard cannot locate the driver, direct it to **C:\Program Files\Common Files\ORTEC Shared\UMCBI**.
- 8. Run the MCB Configuration program to build the list of available MCBs, according to the MAESTRO *User's Manual*.
- 9. To adjust the lower-level discriminator and the zero level, see Sections 3.6 and 3.7, respectively. Section 3.8 describes the gate input.

## **3.1. LIVE-TIME MODE**

The Model 926 has two different live-time correction modes: Extended and Simple. The Extended mode is the Gedcke-Hale correction mode which corrects for losses caused by pileup in the shaping amplifier. This is the default setting and is usually the correct setting for energy spectroscopy systems. The Simple Live-Time correction mode simply stops the live-time clock when the BUSY signal is active, the Model 926 detects that a pulse is arriving at its input, or the 926 is busy digitizing data. The Simple Live-Time mode is appropriate only in very specialized situations and is not the correct setting for most users.

To change the live-time correction mode, remove the right side plate of the Model 926 by removing the four screws. Figure 2 shows the location of the livetime correction mode jumper. Place the jumper across the lower two pins for Extended Live-Time correction and across the upper two pins for Simple Live-Time correction.

## **3.2. MCB ADDRESS**

The Model 926 can be installed in a system with multiple ORTEC MCBs. However, to prevent hardware conflicts when using older MCBs it might be necessary for you to manually change the MCB address for one or more instruments.

If connecting to your PC with a DPM-USB interface converter, no MCB address change is needed; leave the unit's address at the factory default setting of 1. If changing older 926s from the legacy DPM ribbon cable interface to the DPM-USB converter, make

sure each unit is set to address 1. MAESTRO and other CONNECTIONS-32 programs support a maximum of 127 USB connections.

If connecting multiple 926s via the printer port, every MCB in the system must be assigned a unique MCB address. (You may find it useful to mark the front panel of each instrument with its MCB address.) Figures 3 and 4 show two printer-port systems with the jumper settings for the various 926s.

Once an address is established for each MCB in the system, the hardware must be set to that address. On the Model 926 the address is set with the rotary switch highlighted in Fig. 2. To access this switch, remove the right side plate. The switch should be set to 1 less than the MCB address. For example if the MCB address is 1, set the switch to 0.

## **3.3. MCB/PRN JUMPER FOR PRINTER-PORT CONNECTIONS**

The MCB/PRN jumper must be correctly set when the printer-port interface is used.

**To connect an MCB only** — If the jumper is in the MCB position, an MCB can be connected to the PRINTER connector.

**To connect a printer and MCB** — If the jumper is in the PRN position, a printer can be connected to the PRINTER connector on the rear panel of the Model 926.

The jumper is set to MCB when the Model 926 leaves the factory. To change the MCB/PRN jumper, remove the right side plate of the Model 926 by removing the four screws. Figure 1 shows the location of the jumper. Place the jumper across the right two pins for PRN and across the left two pins for MCB.

Figures 3 and 4 show how the MCB/PRN jumper should be set for a single-MCB and a multi-MCB system.



**Fig. 2. Model 926 Address Switch and Jumpers.**



**Fig. 3. Single Model 926 Using Printer-Port Interface.**



**Fig. 4. Printer Port System with Four 926s.**

## **3.4. PRINTER-PORT VS DUAL-PORT MEMORY INTERFACE**

You can purchase the Model 926 pre-set for use with either the DPM-USB Dual-Port-Memory-to-USB Interface Converter or the printer-port interface. The DPM-USB converter requires that the Dual-Port-Memory Interface option be installed. If your 926 is configured for the Dual-Port Memory Interface and you wish to convert to the printer-port interface, see Section 3.4.1. If the unit is configured for the printerport interface and you wish to convert to the Dual-Port Memory Interface, see Section 3.4.2.

#### **3.4.1. Installing the Printer-Port Interface**

If the Dual-Port Memory Option has been installed in the 926, the Printer Option must be reinstalled if a printer or second MCB is to be connected to the 926. To install the Printer Option do the following:

- 1. Remove the right side plate by removing the four screws which hold it in place.
- 2. Using a 3/16" nut driver, remove the two hex nuts which hold the Dual-Port Memory (DPM) connector to the rear panel.
- 3. Slide the connector out of the rear-panel slot.
- 4. Disconnect the DPM cable from the Model 926 board by pulling straight up on the header which connects the DPM cable to the board.
- 5. Store the cable, hex nuts, and washers in a safe place.
- 6. Carefully plug the Printer Option in to the row of pins close to the rear panel (see Figure 4). The connector is keyed for proper installation.
- 7. Slide the other end of the cable into the rear panel of the 926. Secure the connector with two screws.
- 8. Replace the side plate.

Figures 3 and 4 show wiring diagrams for several printer port systems. The cables used are 25-pin shielded male-female cables. The cable from the computer to the first Model 926 should be no longer than 10 feet (3 meters). Cables connecting additional 926s should be no longer than 2 feet (0.6 meters). These cables are available from ORTEC by ordering Model 926-C-10 for a 10-foot cable and Model 926-C-2 for a 2-foot cable. The cable used to connect a Model 926 to a printer is a standard printer cable which normally connects a computer to a printer.

#### **3.4.2. Installing the Dual-Port Memory Interface**

If your 926 is configured for the printer-port interface and you wish to use the Dual-Port Memory interface instead, two steps are necessary: the instrument must be reconfigured and you must purchase either the DPM-USB Dual-Port-Memory-to-USB Interface Converter or the classic Dual-Port Memory Interface ribbon cable from ORTEC.

To reconfigure the 926, you must install the Dual-Port Memory Option, which is included with each 926. It is a 37-pin ribbon cable with a 37-pin D connector on one end and a 40-pin header on the other end. To install the Dual-Port Memory Option, do the following, referring to Fig. 5:



**Fig. 5. Location of Option Connectors.**

- 1. Remove the right side plate by removing the four screws which hold it in place.
- 2. Remove the two Phillips screws that hold the PRINTER panel in place.
- 3. Slide the PRINTER panel out of the rear-panel slot.
- 4. Disconnect the PRINTER option from the Model 926 board by pulling straight up on the header which connects the ribbon cable to the board.
- 5. Store the cable and screws in a safe place.
- 6. Carefully plug the Dual-Port Memory option
- 7. Slide the connector into the rear panel of the 926. Secure the connector with 3/16" hex nuts and washers provided.
- 8. Replace the side plate.

## **3.5. CABLING A SYSTEM**

The standard cabling of a 926 in a HPGe detector system is shown in Fig. 6.



**Fig. 6. HPGe Cabling Diagram.**

the INHIBIT OUTPUT does not exist, so the connection to INHIBIT is not made. (INHIBIT is left open.)

## **3.6. ADJUSTING THE LOWER-LEVEL DISCRIMINATOR**

The Lower-Level Discriminator (LLD) adjustment is used to prevent small noise pulses from being converted by the ADC. Converting the noise pulses, causes the ADC to incur a large amount of dead time, thereby preventing the ADC from converting the actual pulses of interest. When the Model 926 is shipped from the factory, the LLD setting is approximately 75 mV, so no pulses smaller than 75 mV are converted or histogrammed. This setting is adequate for most systems.

If the system has high noise or there is a very low energy peak in the spectrum, it may be advantageous to adjust the LLD setting. In the high noise system, start collecting data and observe the dead time on the screen along with the number of counts arriving at the low end of the spectrum. With a small screwdriver, turn the LLD adjustment on the front panel clockwise, until the dead time drops or the peaks due to noise at the low end of the spectrum stop getting new counts. If there is a low energy peak in the spectrum, it may be necessary to lower the LLD setting to prevent the peak from being rejected. Start data acquisition and observe the low end of the spectrum while turning the LLD adjustment on the front panel counterclockwise. Continue the adjustment until the peak is in the spectrum. *Caution: Do not lower the adjustment such that the dead time goes to 100%.*

## **3.7. SETTING THE ZERO ADJUSTMENT**

The Zero Adjustment is provided to add or subtract a dc level from the input signal. The Zero Adjustment is on the front panel of the Model 926. Usually no zero adjustment is required or recommended, since most modern spectroscopy amplifiers have very little dc offset. Should offset adjustment be necessary, turn the screwdriver adjustment clockwise to move peaks in the spectrum to the right and counterclockwise to move them to the left.

## **3.8. ENABLING THE GATE INPUT**

The Gate on the front panel operates in one of three modes:

- Off The Gate Input does nothing.<br>● *Coincidence* For a pulse to be co
- *Coincidence* For a pulse to be converted, the Gate Input must be active (>2.5 V) when the Gate Input must be active (>2.5 V) when the pulse reaches its peak and for 0.5 µs thereafter.
- ! *Anticoincidence* For a pulse to be converted, the Gate Input must be inactive (<0.8 V) when the pulse reaches its peak and for 0.5 µs thereafter.

When the Model 926 is shipped from the factory, the Gate Input is set *Off*. To change the Gate Input mode, a SET GATE command must be sent to the 926. This command can be sent within MAESTRO-32 by creating an ASCII-text .JOB file.

Create a .JOB file as follows to set the gate to Coincidence:

- 1. Go to the **Services** menu.
- 2. Select **Job Control**.
- 3. Select **Edit File** (takes you to Notepad).
- 4. Type:

## **SEND\_MESSAGE "SET\_GATE\_COIN"**

- 5. Save as COIN.JOB then exit Notepad.
- 6. Refresh display by reentering **Job Control**.
- 7. Select COIN.JOB and click on **OK**.

To set gate to *Anticoincidence* or to disable the GATE, replace COIN in Steps 4 and 5 with ANTI or OFF. Refer to the MAESTRO *User's Manual* for more information on creating .JOB files. The Gate Mode setting is stored in the 926's memory, so the command or .JOB file need only be executed once, unless the battery fails.

## **4. MCA BASICS**

The first half of this section describes the circuitry found on the Model 926 board (MCB) while the second half describes the dead-time effects encountered in an MCA.

#### **4.1. MCB OPERATION**

This section contains a very basic description of the input circuitry and the chain of events that occurs in the Model 926 when an input pulse arrives to be histogrammed. Figure 7 shows the basic block diagram of the input section of the Model 926. First a description of each block in the circuit:

- ! **Buffer**  The buffer is provided to properly match impedances between the input and the Model 926 circuitry.
- ! **Linear Gate** The Linear Gate protects the peak stretcher during conversion of an event. When the Linear Gate is "open," its output is identical to its input. When the Linear Gate is "closed," its output is always zero.
- ! **Peak Stretcher** The peak stretcher operates in one of two modes: Track or Hold. In Track mode, the output of the peak stretcher is identical to its input. In Hold mode, the peak stretcher acts like a maximum function. It outputs the maximum

value which is applied to the input. The Peak Stretcher also has a Peak Detect output which goes active when its output is greater than the value at its input.

- ! **Analog-to-Digital Converter** The Analog-to-Digital Converter (ADC) takes an analog signal and converts it to a digital equivalent.
- ! **Zero-Level, Lower-Level, and Upper-Level Discriminators** — The discriminators provide 3 control signals which help control the conversion process. The Zero-Level Discriminator (ZLD) is active, when the input signal is greater than 1/2 of the Lower-Level Discriminator setting. The Lower-Level Discriminator (LLD) is active, when the input signal is greater than the Lower-Level Discriminator setting. The Upper-Level Discriminator (ULD) is active when the input signal is greater than the maximum possible ADC output. The Lower-Level Discriminator settings is set with a screwdriver adiustment on the front panel.
- ! **ADC Control**  This circuit accepts all of the various status signals and provides the control signals required to complete a conversion.



**Fig. 7. Model 926 Input Block Diagram.**

• Microprocessor — The microprocessor accepts the digital data and adds it to the spectrum.

Upon arrival of an input pulse, the sequence of events is as follows:

- ZLD goes active when the input reaches 1/2 of the LLD setting.
- When ZLD goes active, the peak stretcher is switched to Hold mode.
- ! When Peak Detect goes active, LLD, PUR, GATE, and ULD are sampled. If any of these signals rejects the pulse, then the Peak Stretcher is returned to Track mode. If the pulse is accepted, the Linear Gate is closed and the ADC is given the convert signal.
- ! When the ADC is finished converting, the data is transferred to the microprocessor for histogramming, the Linear Gate is opened, and the Peak Stretcher is returned to Track mode.

### **4.2. DEAD TIME IN MCA AND AMPLIFIER**

When a detector, preamplifier, spectroscopy amplifier, and MCA are combined to form a spectroscopy system, the dead times of the amplifier and the MCA are in series (see Fig. 8). The combination of the amplifier extending dead time followed by the MCA non-extending dead time  $T_{\text{M}}$ yields a throughput described by:

$$
r_0 = \frac{r_i}{\exp[r_i(T_W+T_P)]+r_i[T_M-(T_W-T_P)]U[T_M-(T_W-T_P)]}
$$

The rate of events arriving at the detector is  $r_i$ , and  $r_0$  is the rate of analyzed events in the MCA spectrum.  $T_w$  is the width of the amplifier pulse at the noise discriminator threshold (Figure 7).  $T<sub>p</sub>$  is the time from the start of the amplifier pulse to the point at which the MCA detects peak amplitude and closes the linear gate.  $U[T_M-(T_W-T_P)]$  is a unit step  $-(T_{\rm W}-T_{\rm P})$ ] is a unit step<br>) to 1 when  $T_{\rm M}$  is greater<br>version time of the ADC<br>ed to transfer the data to<br>ner utilizes the Gedcke-<br>r the dead-time losses function that changes from 0 to 1 when  $T_M$  is greater then  $(T_w - T_p)$ .  $T_w$  is the conversion time of the ADC and includes the time required to transfer the data to the subsequent memory.

 $-T_P$ ).  $T_M$  is the conversion time of the ADC<br>ides the time required to transfer the data to<br>equent memory.<br>Extended Live Timer utilizes the Gedcke-<br>thod to correct for the dead-time losses<br>by the equation above. When the The 926 Extended Live Timer utilizes the Gedcke-Hale method to correct for the dead-time losses implied by the equation above. When the counts in a full-energy peak are divided by the live time, the resulting counting rate is an accurate estimate of the true counting rate for that gamma-ray energy at the detector output. The Gedcke-Hale method uses the amplifier analog output, BUSY and PUR (Pile-Up-Reject) signals. The amplifier dead time is combined with the ADC conversion and readout dead time to

obtain the overall system dead time. For accurate live time, the PUR and BUSY signals must be connected from the amplifier to the 926.



**Fig. 8. The Sources of Dead Time with an Amplifier and MCA.**

The Gedcke-Hale live-time clock works as follow:

- Either the leading edge of the amplifier BUSY signal or the crossing of the ADC Lower-Level Discriminator (LLD) by the ADC input causes the live-time clock to start counting backwards.
- The live-time clock is turned off by the ADC peak detect or by the amplifier PUR signal.
- ! The live-time clock resumes counting forward after all of the following signal conditions are satisfied:
	- The ADC conversion and readout is complete.
	- The ADC input has returned below the LLD threshold.
	- The PUR and BUSY signals have returned to the inactive state.

Turning off the live-time clock compensates for the probability of losing a second pulse during the processing of the first pulse. Subtracting live time compensates for the probability of losing two pulses when the second pulse distorts the amplitude of the first pulse.

## **5. TROUBLESHOOTING GUIDE**

This section of the manual contains some troubleshooting hints to help when something goes wrong. Below are listed several common problems and possible solutions:

## **5.1. DUAL-PORT MEMORY DOES NOT EXIST**

! Carefully review the instructions in Section 3.2 and ensure that the MCB address has been properly set.

#### **5.2. BATTERY BACKUP FAILS**

The memory in the Model 926 has battery backup to maintain data when power is turned off. The battery used is a lithium battery with a nominal voltage of 3 V.

To replace battery: Remove the right-side plate. Locate battery on the top right corner of the 926 (see Figure 1). Remove the old battery from the holder and slide a new one in. It may be necessary to bend the battery holder down after removing the old battery to get good contact with the new battery.

**BATTERY SPECIFICATION**: Lithium coin cell, P/N 739480.

## **APPENDIX A. FIRMWARE COMMANDS AND RESPONSES**

Software communication with the DSPEC Pro takes place through the CONNECTIONS-32 software layer. CONNECTIONS-32 is used by all ORTEC software and can be accessed for other software development with our CONNECTIONS-32 Programmer's Toolkit with Microsoft ActiveX® Controls (A11-B32).

#### **A.1. CONNECTIONS-32**

In CONNECTIONS-32, the communication consists of sending command records to the MCB API and receiving response records from the MCB API. Both command and response records consist of a sequence of printable ASCII characters followed by an ASCII carriage return. The single exception to this rule is the "#B" response record for the WRITE command, which contains binary integer numbers. All commands eventually respond with a percent response record (so named because the response begins with an ASCII percent sign "%") which signifies the completion of the command. SHOW and STEP commands respond with a dollar response record (which begins with an ASCII dollar sign "\$") followed by a percent response record. The WRITE command can respond with multiple pound sign records (which begin with an ASCII pound sign "#") but eventually completes by sending a percent response record. All other commands result in a single percent response record upon completion.

## **A.2. COMMAND RECORDS**

The Model 926 commands consist of a command header, which may be followed by numeric parameter values. The header consists of a verb or a verb and noun separated by an underscore or a verb, noun, and modifier, each separated by underscores. The verbs, nouns, and modifiers in the command header are mnemonic words such as the verb ENABLE or the noun OVERFLOW that relate to the function performed by the MCB when it executes the command. The first four letters of any word will always be enough to uniquely identify the word when composing commands for an MCB. For example, the command **ENABLE\_OVERFLOW\_PRESET** can be abbreviated to **ENAB\_OVER\_PRES**.

Numeric parameters are unsigned integer numbers that follow the command header separated by one or more spaces. Specific commands require up to three parameters, separated by commas, which specify numeric quantities related to the operation of the MCB, such as live time or conversion gain. The command **SET WINDOW 0,8192** has two parameters, 0 and 8192, which set the window-ofinterest to start at channel 0 and continue for 8192 channels.

Some parameters listed in the command dictionary are considered optional and are distinguished from mandatory parameters by being surrounded by brackets in the command prototype line (e.g.,

**SET WINDOW [start,length]**). Commands that have optional parameters may be sent to the MCB without the optional parameters, in which case the behavior will be changed as explained in the command description.

An optional checksum may be added to the end of any command sent to an MCB. The checksum is a 1-byte unsigned integer sum of all of the characters in a command, treated as unsigned integers, up to and including the comma or space(s) that separates the checksum from the command. The checksum simply appears as an extra parameter added to the end of the command parameter list. For commands that do not normally have parameters, the checksum appears as the only parameter separated from the header by one or more spaces. All optional parameters must be included in a command if a checksum is to be provided so that the checksum is not mistaken by the MCB as a parameter. For example, the SET\_WINDOW command must include the two optional parameters, start and length, if the checksum is provided (e.g., **SET\_WINDOW 0,8192,159**).

#### **A.3. PERCENT RESPONSE RECORDS**

The 926 MCBs respond to all commands with a percent response record that signifies the completion of the command. Percent response records contain two error code numbers and a 1-byte checksum as follows:

#### **%aaabbbccc<CR>**

where % represents the ASCII % character, **aaa** represents the macro error code, **bbb** represents the micro error code, **ccc** represents the checksum, and <CR> represents the ASCII carriage return character signifying the end of the record. The macro error code represents the general class of error with 0 meaning no error, and the micro error code represents the sub-class of error with 0 meaning no error. The following table lists all percent responses for a Model 926:





## **A.4. DOLLAR RESPONSE RECORDS**

SHOW commands respond with a single dollar response record followed immediately by a percent response record. All valid dollar response records for each command are listed in the command dictionary.

The following table lists the general form of each dollar response record for a 926 MCB. In this table lowercase letters represent numeric values. The letters "**ccc**" always represent an 8-bit unsigned checksum of all characters on the record up to but not including the checksum characters, and **<CR>** represents the ASCII carriage return character.



## **A.5. COMMAND CATALOG**

This section lists each Model 926 command with a description of its operation. The descriptions include a list of any unusual responses that may result. As described in previous sections, the usual response from a command is a **%000000069<CR>** response, which represents a macro error code of 0 and a micro error code of 0 (no errors).

All execution error responses, if any, are listed for each command. Though syntax and communication error responses may result from any command, in practice, these error responses rarely occur on systems with reliable communication hardware running debugged software. Refer to the section on Percent Response Records in this Appendix for information about error responses.

In the following catalog the commands are listed in alphabetical order, each starting with a command prototype line. Uppercase letters, numeric digits, blank space, and special symbols such as the underscore "\_" and comma "," in the prototype line are literal text to be sent to the MCB exactly as it appears. Lowercase letters in the prototype line represent numeric values as described in the accompanying text and should not be sent literally to the

MCB but should be replaced by an appropriate numeric value. Items in the command prototype that are surrounded by brackets "[...]" are optional items and are not always required.

In this section the term **<CR>** represents the ASCII carriage return character, decimal value 13, and the character "\_" represents the ASCII underscore character, decimal value 95.







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**SHOW\_INTEGRAL** [start\_chan,number\_of\_chans] Reports the sum of the specified group of spectral data channels. If start\_chan and number\_of\_chans is not provided, SHOW\_INTEGRAL reports the sum of all channels that have their ROI flag set. Responses: **\$G0000000000075<CR>** Integral reported as 0 **... ... \$G4294967294131<CR>** Integral reported as 4294967294 **\$G4294967295132<CR>** Integral reported as greater than or equal to 4294967295 (maximum reportable value) **SHOW\_INTEGRAL\_PRESET** Reports the current ROI integral preset value. See SET\_INTEGRAL\_PRESET for more information about the ROI integral preset. See also SHOW\_INTEGRAL. Responses: **\$G0000000000075<CR>** Integral preset reported as 0 **... ... \$G4294967295132<CR>** Integral reported as 4294967295 **SHOW\_LIVE** Reports the contents of the live-time counter in units of 20 milliseconds (50 ticks per second). See also CLEAR\_COUNTERS and SET\_LIVE. Responses: **\$G0000000000075<CR>** Live time reported as 0 ticks **\$G0000000001076<CR>** Live time reported as 1 tick (20 milliseconds) **... ... \$G4294967295132<CR>** Live time reported as 4294967295 ticks (over 23000 days) **SHOW\_LIVE\_PRESET** Reports the current live-time preset in units of 20 milliseconds (50 ticks per second). See also CLEAR\_PRESETS and SET\_LIVE\_PRESET. Responses: **\$G0000000000075<CR>** Live-time preset reported as disabled **\$G0000000001076<CR>** Live-time preset reported as 1 tick **... ... \$G4294967295132<CR>** Live-time preset reported as 4294967295 ticks **SHOW\_MODE** This command is for compatibility with Model 918 systems. It always reports that the 926 operates in pulse-height analysis mode. Responses: **\$FPHA<CR>**







## **APPENDIX B. GLOSSARY**

### **ACQUISITION**

The process of collecting data from a detector and storing the data in memory.

### **ALARM RESPONSE RECORD**

The response record that is sent to the host computer when one or more devices are stopped.

#### **ASCII**

American Standard Code for Information Interchange. The ASCII code is defined by ANSI (American National Standards Institute) Standard X3.4 - 1977. This standard describes the representation of characters as 8-bit binary numbers. This representation for characters is used by most mini and personal computers.

#### **CHECKSUM**

The sum of bytes in a record used to detect when communication errors occur.

#### **CLOCK**

A component of a device that keeps track of some form of time. 926 MCBs have live-time and true-time clocks.

#### **COUNTER**

Another name for a 926 clock (live-time or true-time).

#### **DEAD TIME**

The time that data acquisition is active but the MCB cannot process detector pulses (is dead). Dead time is equal to the true time minus the live time for a device.

#### **DEVICE**

The entity within an MCB that collects and stores spectral data. A device corresponds to the MCB's inputs. Model 919 MCBs have 4 inputs and thus 4 devices, while 926 MCBs have only 1 input and thus 1 device. A device can be started, stopped, cleared, and selected.

#### **HOST**

The computer that sends commands to an MCB and receives responses from the MCB.

#### **LIVE TIME**

The time that data acquisition is active and the MCB is capable of processing detector pulses (is live). Live time is equal to the true time minus the dead time for a device.

#### **PRESET**

A limit set for a clock or region-of-interest count that if exceeded during an acquisition will cause the acquisition to stop. 926 MCBs have live time, true time, ROI integral, ROI peak, and overflow presets for each device in the MCB.

#### **PROGRAM MEMORY**

The ROM memory inside the 926 MCB that contains the microprocessor instructions and fixed data that control the operation of the MCB.

#### **RAM**

Random Access Memory.

#### **RECORD**

A sequence of related bytes. 926 command, percent, and dollar records are composed of printable ASCII characters and end with an ASCII carriage return.

#### **ROI CHANNEL**

A channel that has the ROI flag set.

#### **ROI FLAG**

A set of internal MCB flags (one for each channel) which, when set, identifies the channel as being part of the region-of-interest. All channels in a device that have the ROI flag set are considered when ROI integral or ROI peak presets are evaluated.

#### **ROM**

Read-Only Memory.

#### **SCRATCHPAD MEMORY**

The RAM memory inside the 926 MCB that is used for various overhead operations. The scratchpad memory is all the memory that is not used for storage of spectral data or mailbox communications.

#### **SEGMENT**

A subdivision of a device. Segments are not implemented on 926 MCBs and are referenced only for compatibility with other MCBs.

### **SELFTEST**

A test of internal MCB components initiated by the TEST command or MCB power-up..

#### **TICK**

The minimum unit of time associated with a clock such as the real-time or live-time clocks — a clock tick.

#### **TRUE (REAL) TIME**

The actual time that data acquisition is active regardless of the MCB's ability to process detector pulses. True time is also known as real time.

#### **WINDOW-OF-INTEREST**

The continuous group of channels affected by commands like CLEAR and SET\_DATA. The window-ofinterest is set by the SET\_WINDOW command, as well as by the SET\_DEVICE and SET\_SEGMENT commands.

## **INDEX**

