# Lexium MDrive®

Simplifying machine building with compact integrated motors



#### Lexium MDrive Pulse/Direction

Integrated stepper motors with 4 operation modes — pulse/direction, speed, torque and velocity control — and closed loop performance

C € ROHS REACH



Official UK & Ireland Distributor



### **Description**

### Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor





rotary stepper motor

2 microstepping drive

3 4 operating modes

4 4 I/O lines

5 internal encoder option

6 closed loop performance

#### **Product offer**

Lexium MDrive® Pulse/Direction products integrate a high-torque 1.8° 2-phase stepper motor with on-board drive electronics, and closed loop performance with internal encoder option. Products operate in 4 modes: pulse/direction input, variable speed control, constant velocity drive, and variable torque control in closed loop products only. Operating in pulse/direction mode requires a separate motion control master.

Lexium MDrive Pulse/Direction products (LMDxP) have an RS-422/485 serial interface. Product commissioning, parameterization and monitoring are accomplished via a user-friendly software GUI, included free as part of the Lexium MDrive Software Suite. Settings can be downloaded and stored in the product's nonvolatile memory.

Lexium MDrive Pulse/Direction closed loop products (LMDCP) are equipped with 1000 line (4000 count/rev) encoders internal to the unit, requiring no extra space in an application. Using the encoder to monitor motor shaft position, real time closed loop feedback is accomplished with hMTechnology.

Unlike traditional motor systems, hMT combines the best of servo and stepper motor technologies, while delivering unique capabilities and enhancements over both, including:

- real time closed loop control
- no loss of synchronization/stalling
- full use of motor torque
- torque mode control

#### **Application areas**

Lexium MDrive Pulse/Direction products are ideal for machine builders who want an optimized motor with on-board drive electronics, with closed loop performance providing a lower cost option to servo motors in many applications. The integrated electronics of Lexium MDrive products also reduce the potential for problems due to electrical noise by eliminating cabling between motor and drive.

These compact, powerful and cost effective motion control solutions deliver unsurpassed smoothness and performance that will reduce system cost, design and assembly time for a large range of motion applications.



- Integrated microstepping drive and high torque 1.8° 2-phase NEMA stepper motor
- Open loop control
  - Pulse/direction input
  - Variable speed control
  - Constant velocity drive
- Closed loop control with 1000 line internal encoder and hMTechnology (optional)
  - Torque mode control
- Prevents motor stalling while delivering numerous performance advantages
- Advanced current control for exceptional performance and smoothness
- RS-422/485 serial interface
- +12 up to +70 VDC input power range
- Cost effective
- Extremely compact
- 20 microstep resolutions to 51,200 steps/rev including: Degrees, Metric, Arc Minutes
- Motor stack length options
- Graphical user interface provided for quick and easy configuration
- Extended 4 year product warranty



## **Specifications**

## Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

			LMD•P57 (NEMA23)	LMD•P85 (NEMA34)			
Input power	Voltage		+12+60 VDC	+12+70 VDC			
	Current maximum (1)		3.5 A	4.0 A			
Thermal	Operating temp Heat sink maximum non-condensing Motor maximum		85°C				
			100°C				
Protection	Туре	Temp warning	084°C, user selectable				
		Earth grounding	via product chassis ground lug				
		IP rating	20				
Signal inputs	Number		2				
	Voltage range, isolated		+5+24 VDC sourcing or sink	ing			
Analog input	Number		1				
	Resolution		12 bit				
	Voltage range		0+5 VDC, 0+10 VDC, 020 mA, 420 mA				
Attention output	Current	Open collector/emitter	5.5 mA				
	Voltage Open collector		+60 VDC				
		Open emitter	+7 VDC				
Communication	Type		RS-422/485				
	Baud rate		4.8 115.2 kbps				
Motion	Microstep resolution	Number of settings	20				
	Steps per revolution		200, 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 20000, 25000, 25600, 40000, 50000, 51200, 36000 (0.01 deg/μstep), 21600 (1 arc minute/μstep), 25400 (0.001mm/μstep)				
	Open loop configuration	Operating modes	pulse/direction, speed control,				
	Closed loop configuration, requires LMD with encoder	Operating modes	pulse/direction input, variable speed control, constant velocity mode, var torque mode				
	Encoder	Line count	1000 lines (4000 edges per rev	<i>v</i> )			
		Style	internal, magnetic				
	Ouputs		6 TTL level compatible				
	Digital filter range		50 nS 12.9 μS (10 MHz 38.8 kHz)				
	Clock types (step mode)		Step/direction, quadrature, step up/step down, clockwise/counterclockwise				
	Step frequency	Maximum	5 MHz				
		Minimum pulse width	100 ns				

<sup>(1)</sup> Actual power supply current will depend on voltage and load.

Setup param	eters (2)		
			Overview
Operating modes			microstep resolution, run current, hold current, hold delay, clock mode, motion, enable active, input filters
	Advanced	Speed control	acceleration, decelaration, velocity, flags
		Torque mode (3)	set torque speed, % maintained motor torque, torque current, filtering
		Velocity control	acceleration, decelaration, velocity, slew, flags
Device	Analog input settings		select range and resolution
parameters			set baud rate, enable/disable party mode and features, check sum
			clock and filter settings, attention output with selectable pre-programmed fields
	Motion settings		select motion, analog and velocity settings as available by operating mode
	hMT settings (3)		hMT setup/status; hMT operation
Device ID			device information, restore settings

<sup>(2)</sup> Refer to the LMD Software Suite Manual for details.

An optional Communication Converter is recommended with first orders.



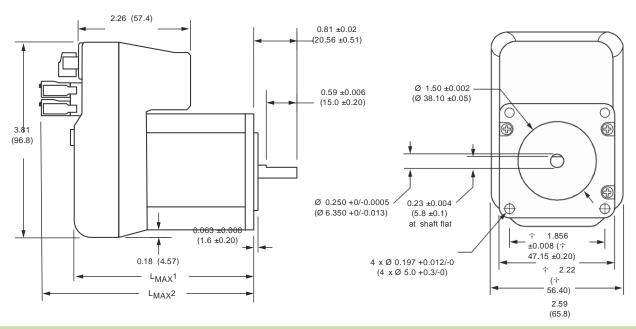
See User Manual for complete details: motion.schneider-electric.com/manuals.html

<sup>(3)</sup> Only with Lexium MDrive closed loop/encoder products.

## Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

#### LMD•57 NEMA23 motor – dimensions in inches (mm)



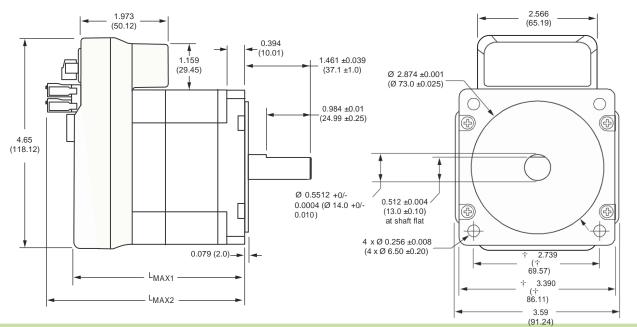
Motor stack length	Lmax1	Lmax2
Single	3.17 (80.5)	3.91 (99.3)
Double	3.52 (89.4)	4.26 (108.2)
Triple	4.38 (111.3)	5.13 (130.3)



## Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

#### LMD-85 NEMA34 motor – dimensions in inches (mm)



Motor stack length	Lmax1	Lmax2
Single	3.76 (95.5)	4.41 (112.0)
Double	4.33 (110.0)	4.98 (126.5)
Triple	5.90 (149.9)	6.55 (166.4)



## Connectivity and signal indicators

## Lexium MDrive® Pulse/Direction

Modes: pulse/direction, speed, torque, velocity integrated 2-phase stepper motor

#### Software interface

The free Lexium MDrive Software Suite includes a user interface GUI for product commissioning and programming via a PC.

PC interface is easily accomplished using the USB to RS-422/485 communication converter MD-CC404-000. Compatible with 32- and 64-bit Windows, Mac OS, and Linux operating systems. Each comm converter includes a 6.0'/1.8m cable with DB9 mating connectors.

#### **Connectors**

All Lexium MDrive connectors are conveniently grouped in the same location at the back of each product. The same style locking connectors are also used consistently on all motor sizes of Lexium MDrive products.

Mating connectors for P1 and P2 are provided, and extra connectors may be ordered. A #6-32 screw lug is provided for earth grounding.

Connector	Style	Assignment
P1	2-pin screw lock	Supply voltage
P2	2 keyed 7-pin spring lock, color coded for ease of use	Multifunction interface
P3	DB9 male	Communication
<b>Chassis ground</b>	#6-32 screw lug	Earth grounding

#### **Status indicators**

Lexium MDrive products include 2 LED signal indicators. The multi-color LEDs are programmed to indicate a range of pre-defined messages to aid users. See product user manual for details.



## **Lexium MDrive® Pulse/Direction**

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Part numbers								
Example	L	M	D	С	Р	5	7	1
Product LMD = Lexium MDrive	L	M	D	С	Ρ	5	7	1
Control type C = Closed loop / with hMT and encoder (1) O = Open loop / no hMT or encoder	L	M	D	С	P 1	5	7	
Communication type P = Pulse/Direction via RS-422/485 serial interface	L	M	D	С	Р	5	7	1
Flange size 57 = NEMA 23 / 57mm 85 = NEMA 34 / 85mm	L	M	D	С	Р	5	7	1
Motor length 1 = single stack 2 = double stack 3 = triple stack	L	N	l D	С	Р	5	7	1

 $(1) \ \ Closed\ loop\ control\ delivers\ hMT\ enhanced\ motor\ performance,\ including\ variable\ torque\ mode\ control.$ 



Installation accessories			
Description	Length m	Length feet	Reference
Communication converter, USB to RS	111	1001	
Communication Converter, 03B to K3			
USB-pluggable converter to set/program communication parameters in 32- or 64-bit. Includes pre-wired DB9 mating cable.			
■ For all RS-422/485 products	1.8	6.0	MD-CC404-000

Description	Quantity	Reference
Mating connector kit		
Mating connectors for power and multifunction interface are included with each new product. If additional mating connectors are needed for Lexium MDrive Pulse/Direction products, a single mating connector kit is offered which includes the following:		CK-14
■ 2-pin screw lock mate (DC voltage supply)	1 pc	
■ 7-pin locking mates (multifunction), keyed	2 pcs - 1 gray, 1 yellow	

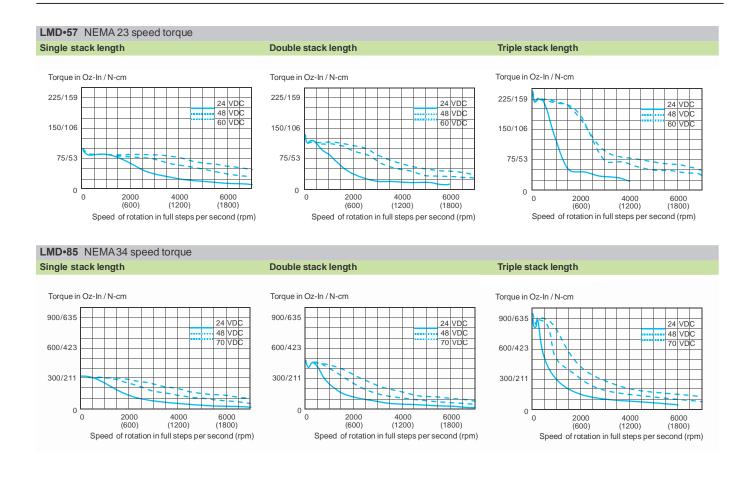
# **Lexium MDrive**® Motor specifications

LMD•57 NEMA 23 motor specifications						
	Motor stack length	Single	Double	Triple		
Holding torque	oz-in	103.4	158.6	242.2		
notating torque	N-cm	73.0	112.0	171.0		
Detent torque	oz-in	3.9	5.6	9.72		
Detent torque	N-cm	2.7	3.9	6.86		
Rotor inertia	oz-in-sec <sup>2</sup>	0.0025	0.0037	0.0065		
Rotor mertia	kg-cm <sup>2</sup>	0.18	0.26	0.46		
Radial load limit, center of shaft	lbs	15	15	15		
Radiai load illilit, center of shart	kg	6.8	6.8	6.8		
Axial load limit	lbs	20	20	20		
@ 1500rpm (5000full steps/sec)	kg	9	9	9		
Weight (motor+driver)	OZ	26.4	31.2	44.0		
weight (motor+driver)	g	748	885	1247		

LMD•85 NEMA34 motor specifications						
	Motor stack length	Single Double		Triple		
Holding torque	oz-in	336.0	480.0	920.0		
notating torque	N-cm	237.0	339.0	650.0		
Detent torque	oz-in	10.9	14.16	19.83		
Detent torque	N-cm	7.7	10.0	14.0		
Rotor inertia	oz-in-sec <sup>2</sup>	0.0127	0.0191	0.0382		
Rotor mertia	kg-cm <sup>2</sup>	0.90	1.35	2.70		
Radial load limit, center of shaft	lbs	65	65	65		
Radial load lillin, Center of Shart	kg	29.4	29.4	29.4		
Axial load limit	lbs	20	20	20		
@ 1500rpm (5000full steps/sec)	kg	9	9	9		
Maint (mater driver)	lb	4.45	5.65	9.0		
Weight (motor+driver)	kg	2.02	2.56	4.08		

## System performance

## **Lexium MDrive**® Speed torque characteristics



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