



Data Acquisition

UMDAS TH

USB Data Acquisition Module 8 Channels of TC / RTD / Thermistor / Semiconductor Temperature Input, 8 DIO

USER'S MANUAL

VER. 8.1C • MAY 2008

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About this User's Guide

What you will learn from this user's guide

This user's guide explains how to install, configure, and use the UMDAS TH so that you get the most out of its USB-based temperature measurement features.

This user's guide also refers you to related documents available on our web site, and to technical support resources.

Conventions in this user's guide

For more information on ...

Text presented in a box signifies additional information and helpful hints related to the subject matter you are reading.

Caution! Shaded caution statements present information to help you avoid injuring yourself and others, damaging your hardware, or losing your data.

<#:#> Angle brackets that enclose numbers separated by a colon signify a range of numbers, such as those assigned to registers, bit settings, etc.

bold text **Bold** text is used for the names of objects on the screen, such as buttons, text boxes, and check boxes. For example:
1. Insert the disk or CD and click the **OK** button.

italic text *Italic* text is used for the names of manuals and help topic titles, and to emphasize a word or phrase. For example:
The *InstaCal* installation procedure is explained in the *Quick Start Guide*.
Never touch the exposed pins or circuit connections on the board.

Introducing the UMDAS TH

Overview: UMDAS TH features

This user's guide contains all of the information you need to connect the UMDAS TH to your computer and to the signals you want to measure.

The UMDAS TH is a USB 2.0 full-speed, temperature measurement module that is supported under popular Microsoft® Windows® operating systems. The UMDAS TH is fully compatible with both USB 1.1 and USB 2.0 ports.

The UMDAS TH provides eight differential input channels that are software programmable for different sensor categories including thermocouple, RTDs, thermistors and Semiconductor sensors. Eight independent, TTL-compatible digital I/O channels are provided to monitor TTL-level inputs, communicate with external devices, and to generate alarms. The digital I/O channels are software programmable for input or output.

With the UMDAS TH, you can take measurements from four sensor categories:

- Thermocouple – types J, K, R, S, T, N, E, and B
- Resistance temperature detectors (RTDs) – 2, 3, or 4-wire measurements of 100 Ω platinum RTDs
- Thermistors – 2, 3, or 4-wire measurements
- Semiconductor temperature sensors – LM36 or equivalent

The UMDAS TH provides a 24-bit analog-to-digital (A/D) converter for each pair of differential analog input channels. Each pair of differential inputs constitutes a channel pair.

You can connect a different category of sensor to each channel pair, but you can not mix categories among the channels that constitute a channel pair (although it is permissible to mix thermocouple types).

The UMDAS TH provides two integrated cold junction compensation (CJC) sensors for thermocouple measurements, and built-in current excitation sources for resistive sensor measurements.

An open thermocouple detection feature lets you detect a broken thermocouple. An on-board microprocessor automatically linearizes the measurement data according to the sensor category.

The UMDAS TH is a standalone plug-and-play module which draws power from the USB cable. No external power supply is required. All configurable options are software programmable.

The UMDAS TH is fully software calibrated.

UMDAS TH block diagram

UMDAS TH functions are illustrated in the block diagram shown here.

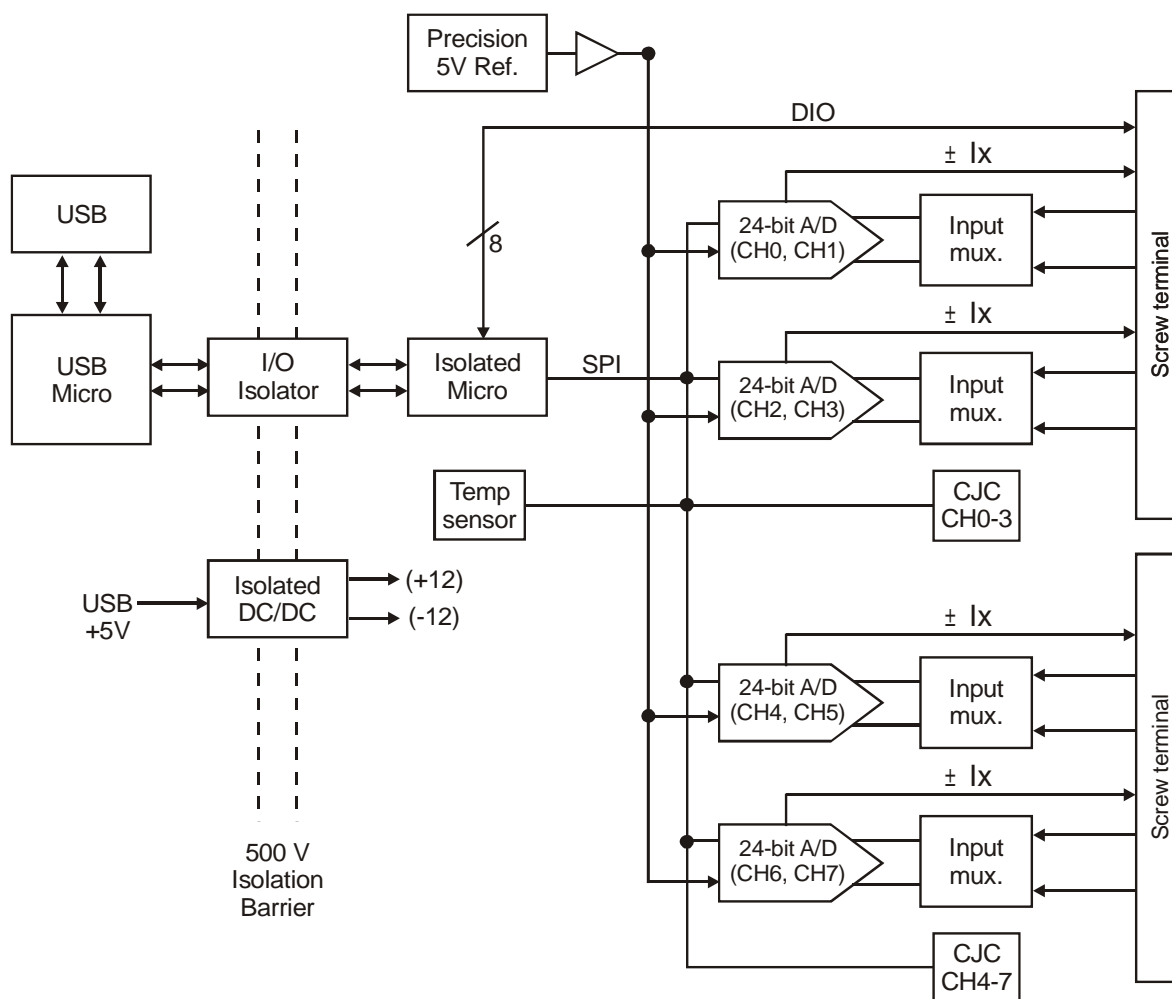


Figure 1-1. UMDAS TH functional block diagram

Connecting a UMDAS TH to your computer is easy

Installing a data acquisition device has never been easier.

- The UMDAS TH relies upon the Microsoft Human Interface Device (HID) class drivers. The HID class drivers ship with every copy of Windows that is designed to work with USB ports. We use the Microsoft HID because it is a standard, and its performance delivers full control and maximizes data transfer rates for your UMDAS TH. No third-party device driver is required.
- The UMDAS TH is plug-and-play. There are no jumpers to position, DIP switches to set, or interrupts to configure.
- You can connect the UMDAS TH before or after you install the software, and without powering down your computer first. When you connect an HID to your system, your computer automatically detects it and configures the necessary software. You can connect and power multiple HID peripherals to your system using a USB hub.
- You can connect your system to various devices using a standard four-wire cable. The USB connector replaces the serial and parallel port connectors with one standardized plug and port combination.
- You do not need a separate power supply module. The USB automatically delivers the electrical power required by each peripheral connected to your system.
- Data can flow two ways between a computer and peripheral over USB connections.

Installing the UMDAS TH

What comes with your UMDAS TH shipment?

The following items are shipped with the UMDAS TH.

Hardware

- UMDAS TH



- USB cable (2 meter length)



Unpacking the UMDAS TH

As with any electronic device, you should take care while handling to avoid damage from static electricity. Before removing the UMDAS TH from its packaging, ground yourself using a wrist strap or by simply touching the computer chassis or other grounded object to eliminate any stored static charge.

If your UMDAS TH is damaged, notify CyberResearch, Inc. immediately by phone, fax, or email.

- Phone: (203) 643-5000; or (800) 341- 2525
- Fax: (203) 643-5001 to the attention of Tech Support;
- Email: techsupport@cyberresearch.com

Installing the UMDAS TH

To connect the UMDAS TH to your system, turn your computer on, and connect the USB cable to a USB port on your computer or to an external USB hub that is connected to your computer. The USB cable provides power and communication to the UMDAS TH.

When you connect the UMDAS TH for the first time, a **Found New Hardware** popup balloon (Windows XP) or dialog (other Windows versions) opens as the UMDAS TH is detected.



When this balloon or dialog closes, the installation is complete. The **USB LED** should flash and then remain lit. This indicates that communication is established between the UMDAS TH and your computer.

Caution! Do not disconnect **any** device from the USB bus while the computer is communicating with the UMDAS TH, or you may lose data and/or your ability to communicate with the UMDAS TH.

If the LED turns off

If the LED is lit but then turns off, the computer has lost communication with the UMDAS TH. To restore communication, disconnect the USB cable from the computer, and then reconnect it. This should restore communication, and the LED should turn back *on*.

Configuring the UMDAS TH

All hardware configuration options on the UMDAS TH are programmable with software. Use *InstaCal* to set the sensor type for each channel. The configurable options dynamically update according to the selected sensor category. Configuration options are stored on the UMDAS TH's isolated microcontroller in EEPROM, which is non-volatile memory on the UMDAS TH module. Configuration options are loaded on power up.

Default configuration

The factory default configuration is *Disabled*. The Disabled mode disconnects the analog inputs from the terminal blocks and internally grounds all of the A/D inputs. This mode also disables each of the current excitation sources.

Warm up

Allow the UMDAS TH to warm up for 30 minutes before taking measurements. This warm up time minimizes thermal drift and achieves the specified rated accuracy of measurements.

For RTD or thermistor measurements, this warm-up time is also required to stabilize the internal current reference.

Calibrating the UMDAS TH

The UMDAS TH is fully calibrated via software. *InstaCal* prompts you to run its calibration utility when you change from one sensor category to another.

Allow the UMDAS TH to operate for at least 30 minutes before calibrating. This warm up time minimizes thermal drift and achieves the specified rated accuracy of measurements.

Sensor Connections

The UMDAS TH supports the following temperature sensor types:

- Thermocouple – types J, K, R, S, T, N, E, and B
- Resistance temperature detectors (RTDs) – 2, 3, or 4-wire measurement modes of 100 Ω platinum RTDs.
- Thermistors – 2, 3, or 4-wire measurement modes.
- Semiconductor temperature sensors – LM36 or equivalent

Sensor selection

The type of sensor you select will depend on your application needs. Review the temperature ranges and accuracies of each sensor type to determine which is best suited for your application.

Screw terminal pin out

The UMDAS TH has four rows of screw terminals — two rows on the top edge of the housing, and two rows on the bottom edge. Each row has 26 connections. Between each bank of screw terminals are two integrated CJC sensors used for thermocouple measurements. Signals are identified in Figure 3-1.

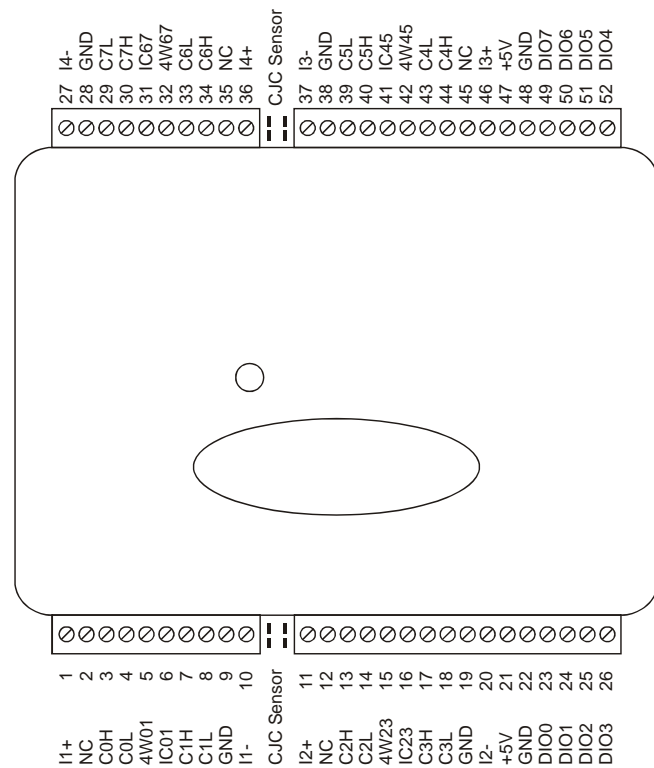


Figure 3-1. UMDAS TH screw terminal pin numbers

Table 3-1. UMDAS TH screw terminal descriptions

Pin	Signal Name	Pin Description	Pin	Signal Name	Pin Description
1	I1+	CH0/CH1 current excitation source	27	I4-	CH6/CH7 current excitation return
2	NC	Not connected	28	GND	Ground
3	C0H	CH0 sensor input (+)	29	C7L	CH7 sensor input (-)
4	C0L	CH0 sensor input (-)	30	C7H	CH7 sensor input (+)
5	4W01	CH0/CH1 4-wire, 2 sensor common	31	IC67	CH6/CH7 2 sensor common
6	IC01	CH0/CH1 2-sensor common	32	4W67	CH6/CH7 4-wire, 2 sensor common
7	C1H	CH1 sensor input (+)	33	C6L	CH6 sensor input (-)
8	C1L	CH1 sensor input (-)	34	C6H	CH6 sensor input (+)
9	GND	Ground	35	NC	Not connected
10	I1-	CH0/CH1 current excitation return	36	I4+	CH6/CH7 current excitation source
	CJC sensor			CJC sensor	
11	I2+	CH2/CH3 current excitation source	37	I3-	CH4/CH5 current excitation return
12	NC	Not connected	38	GND	Ground
13	C2H	CH2 sensor input (+)	39	C5L	CH5 sensor input (-)
14	C2L	CH2 sensor input (-)	40	C5H	CH5 sensor input (+)
15	4W23	CH2/CH3 4-wire, 2 sensor common	41	IC45	CH4/CH5 2 sensor common
16	IC23	CH2/CH3 2 sensor common	42	4W45	CH4/CH5 4-wire, 2 sensor common
17	C3H	CH3 sensor input (+)	43	C4L	CH4 sensor input (-)
18	C3L	CH3 sensor input (-)	44	C4H	CH4 sensor input (+)
19	GND	Ground	45	NC	Not connected
20	I2-	CH2/CH3 current excitation return	46	I3+	CH4/CH5 current excitation source
21	+5V	+5V output	47	+5V	+5V output
22	GND	Ground	48	GND	Ground
23	DIO0	Digital Input/Output	49	DIO7	Digital Input/Output
24	DIO1	Digital Input/Output	50	DIO6	Digital Input/Output
25	DIO2	Digital Input/Output	51	DIO5	Digital Input/Output
26	DIO3	Digital Input/Output	52	DIO4	Digital Input/Output

Use 16 AWG to 30 AWG wire for your signal connections.

Tighten screw terminal connections

When making connections to the screw terminals, be sure to tighten the screw until tight. Simply touching the top of the screw terminal is not sufficient to make a proper connection.

Sensor input terminals (C0H/C0L to C7H/C7L)

You can connect up to eight temperature sensors to the differential sensor inputs (C0H/C0L to C7H/C7L). Supported sensor categories include thermocouples, RTDs, thermistors, or semiconductor sensors.

Do not mix sensor categories within channel pairs. It is permitted to mix thermocouple types (J, K, R, S, T, N, E, and B) within channel pairs, however.

Do not connect two different sensor categories to the same channel pair

The UMDAS TH provides a 24 bit A/D converter for each channel pair. Each channel pair can monitor one sensor category. To monitor a sensor from a different category, connect the sensor to a different channel pair (input terminals).

Current excitation output terminals ($\pm I1$ to $\pm I4$)

The UMDAS TH has four dedicated pairs of current excitation output terminals ($\pm I1$ to $\pm I4$). These terminals have a built-in precision current source to provide excitation for the resistive sensors used for RTD and thermistor measurements.

Each current excitation terminal is dedicated to one pair of sensor input channels:

- $I1+$ is the current excitation source for channel 0 and channel 1
- $I2+$ is the current excitation source for channel 2 and channel 3
- $I3+$ is the current excitation source for channel 4 and channel 5
- $I4+$ is the current excitation source for channel 6 and channel 7

Four-wire, two sensor common terminals (4W01 to 4W67)

These terminals are used as the common connection for four-wire configurations with two RTD or thermistor sensors.

Two sensor common terminals (IC01 to IC67)

These terminals are used as the common connection for two-wire configurations with two RTD or thermistor sensors.

Ground terminals (GND)

The six ground terminals (**GND**) provide a common ground for the input channels and DIO bits and are isolated (500 VDC) from the USB GND.

Power terminals (+5V)

The two **+5V** output terminals are isolated (500 VDC) from the USB +5V.

Digital terminals (DIO0 to DIO7)

You can connect up to eight digital I/O lines to the screw terminals labeled **DIO0** to **DIO7**. Each terminal is software configurable for input or output.

CJC sensors

The UMDAS TH has two built in high-resolution temperature sensors. One sensor is located on the right side of the package, and one sensor is located at the left side.

Thermocouple connections

A thermocouple consists of two dissimilar metals that are joined together at one end. When the junction of the metals is heated or cooled, a voltage is produced that correlates to temperature.

The UMDAS TH makes fully differential thermocouple measurements without the need of ground-referencing resistors. A 32-bit floating point value in either a voltage or temperature format is returned by software. An open thermocouple detection feature is available for each analog input which automatically detects an open or broken thermocouple.

Use *InstaCal* to select the thermocouple type (J, K, R, S, T, N, E, and B) and one or more sensor input channels to connect the thermocouple.

Wiring configuration

Connect the thermocouple to the UMDAS TH using a differential configuration, as shown in Figure 3-2.

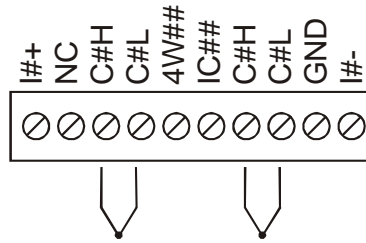


Figure 3-2. Typical thermocouple connection

The UMDAS TH **GND** pins are isolated from earth ground, so connecting thermocouple sensors to voltages referenced to earth ground is permissible as long as the isolation between the GND pins (9, 19, 28, 38) and earth ground is maintained.

When thermocouples are attached to conductive surfaces, the voltage differential between multiple thermocouples must remain within ± 1.4 V. For best results, we recommend the use of insulated or ungrounded thermocouples when possible.

Maximum input voltage between analog input and ground

The absolute maximum input voltage between an analog input and the isolated GND pins is ± 25 VDC when the UMDAS TH is powered on, and ± 40 VDC when the UMDAS TH is powered off.

If you need to increase the length of your thermocouple, use the same type of thermocouple wires to minimize the error introduced by thermal EMFs.

RTD and thermistor connections

A resistance temperature detector (RTD) measures temperature by correlating the resistance of the RTD element with temperature. A thermistor is a thermally-sensitive resistor that is similar to an RTD in that its resistance changes with temperature — thermistors show a large change in resistance that is proportional to a small change in temperature. The main difference between RTD and thermistor measurements is the method used to linearize the sensor data.

RTDs and thermistors are resistive devices that require an excitation current to produce a voltage drop that can be measured differentially across the sensor. The UMDAS TH features four built-in current excitation sources (± 11 to ± 14) for measuring resistive type sensors. Each current excitation terminal is dedicated to one channel pair.

The UMDAS TH makes two, three, and four-wire measurements of RTDs (100 Ω platinum type) and thermistors.

Use *InstaCal* to select the sensor type and the wiring configuration. Once the resistance value is calculated, the value is linearized in order to convert it to a temperature value. A 32-bit floating point value in either temperature or resistance is returned by software.

RTD maximum resistance

Resistance values greater than 660 Ω cannot be measured by the UMDAS TH in the RTD mode. The 660 Ω resistance limit includes the total resistance across the current excitation ($\pm I_x$) pins, which is the sum of the RTD resistance and the lead resistances.

Thermistor maximum resistance

Resistance values greater than 180k ohms cannot be measured by the UMDAS TH in the thermistor mode. The 180 k Ω resistance limit includes the total resistance across the current excitation ($\pm I_x$) pins, which is the sum of the thermistor resistance and the lead resistance.

Two-wire configuration

The easiest way to connect an RTD sensor or thermistor to the UMDAS TH is with a two-wire configuration, since it requires the fewest connections to the sensor. With this method, the two wires that provide the RTD sensor with its excitation current also measure the voltage across the sensor.

Since RTDs exhibit a low nominal resistance, measurement accuracy can be affected due to the lead wire resistance. For example, connecting lead wires that have a resistance of $1\ \Omega$ ($0.5\ \Omega$ each lead) to a $100\ \Omega$ platinum RTD will result in a 1% measurement error.

With a two-wire configuration, you can connect either one sensor per channel pair, or two sensors per channel pair.

Two-wire, single-sensor

A two-wire single-sensor measurement configuration is shown in Figure 3-3.

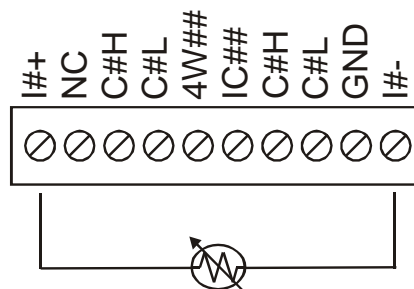


Figure 3-3. Two-wire, single RTD or thermistor sensor measurement configuration

When you select a two-wire single sensor configuration with *InstaCal*, connections to C#H and C#L are made internally.

Two-wire, two sensor

A two-wire, two-sensor measurement configuration is shown in Figure 3-4.

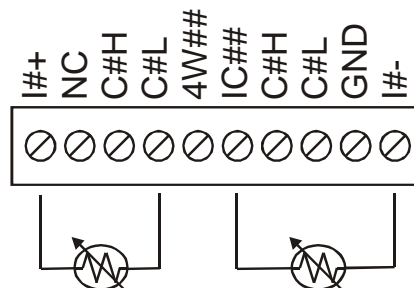


Figure 3-4. Two-wire, two RTD or thermistor sensors measurement configuration

When you select a two-wire, two sensor configuration with *InstaCal*, connections to C#H (first sensor) and C#H/C#L (second sensor) are made internally.

When configured for two-wire mode, both sensors must be connected to obtain proper measurements.

Three-wire configuration

A three-wire configuration compensates for lead-wire resistance by using a single voltage sense connection. With a three-wire configuration, you can connect only one sensor per channel pair. A three-wire measurement configuration is shown in Figure 3-5.

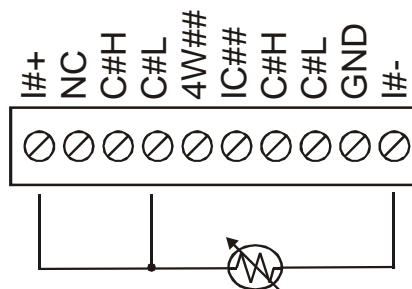


Figure 3-5. Three-wire RTD or thermistor sensor measurement configuration

When you select a three-wire sensor configuration with *InstaCal*, the UMDAS TH measures the lead resistance on the first channel (C#H/C#L) and measures the sensor itself using the second channel (C#H/C#L). This configuration compensates for any lead-wire resistance and temperature change in lead-wire resistance. Connections to C#H for the first channel and C#H/C#L of the second channel are made internally.

Three-wire compensation

For accurate three wire compensation, the individual lead resistances connected to the $\pm I\#$ pins must be of equal resistance value.

Four-wire configuration

With a four-wire configuration, connect two sets of sense/excitation wires at each end of the RTD or thermistor sensor. This configuration completely compensates for any lead-wire resistance and temperature change in lead-wire resistance.

Connect your sensor with a four-wire configuration when your application requires very high accuracy measurements. Examples of a four-wire single-sensor measurement configuration are shown in Figure 3-6 and Figure 3-7.

You can configure the UMDAS TH with either a single sensor per channel or two sensors per channel pair.

Four-wire, single-sensor

A four-wire, single-sensor connected to the first channel of a channel pair is shown in Figure 3-6.

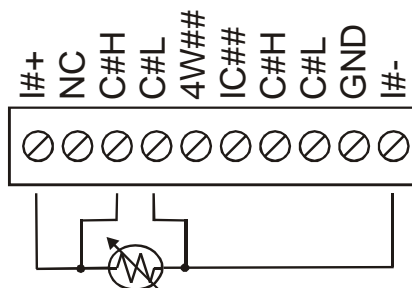


Figure 3-6. Four-wire, single RTD or thermistor sensor measurement configuration

A four-wire, single-sensor connected to the second channel of a channel pair is shown in Figure 3-7.

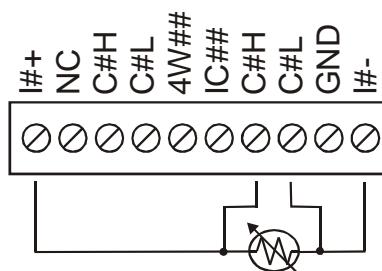


Figure 3-7. Four-wire, single RTD or thermistor sensor measurement configuration

A four-wire, two-sensor measurement configuration is shown in Figure 3-8.

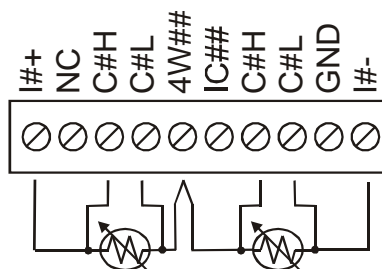


Figure 3-8. Four-wire, two RTD or thermistor sensors measurement configuration

When configured for four-wire, two sensor mode, both sensors must be connected to obtain proper measurements.

Semiconductor sensor measurements

Semiconductor sensors are suitable over a range of approximately $-40\text{ }^{\circ}\text{C}$ to $125\text{ }^{\circ}\text{C}$, where an accuracy of $\pm 2\text{ }^{\circ}\text{C}$ is adequate. The temperature measurement range of a semiconductor sensor is small when compared to thermocouples and RTDs. However, semiconductor sensors can be accurate, inexpensive and easy to interface with other electronics for display and control.

The UMDAS TH makes high-resolution measurements of semiconductor sensors, such as the LM36 or equivalent, and returns a 32-bit floating point value in either a voltage or temperature format.

Use *InstaCal* to select the sensor type (TMP36 or equivalent) and the sensor input channel to connect the sensor.

Wiring configuration

You can connect a TMP36 (or equivalent) semiconductor sensor to the UMDAS TH using a single-ended configuration, as shown in Figure 3-9. The UMDAS TH also provides **+5V** and **GND** pins for powering the sensor.

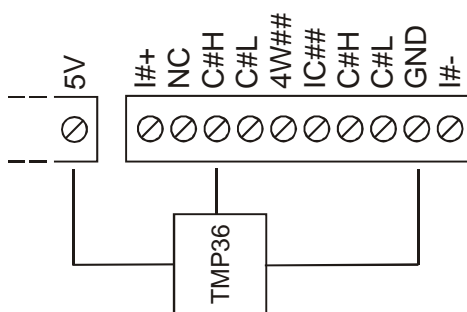


Figure 3-9. Semiconductor sensor measurement configuration

The software outputs the measurement data as a 32-bit floating point value in either voltage or temperature.

Digital I/O connections

You can connect up to eight digital I/O lines to the screw terminals labeled **DIO0** to **DIO7**. You can configure each digital bit for either input or output. All digital I/O lines are pulled up to +5V with a 47 K ohm resistor (default). You can request the factory to configure the resistor for pull-down to ground if desired.

When you configure the digital bits for input, you can use the UMDAS TH digital I/O terminals to detect the state of any TTL-level input. Refer to the schematic shown in Figure 3-10. If you set the switch to the +5V input, DIO0 reads *TRUE* (1). If you move the switch to GND, DIO0 reads *FALSE* (0).

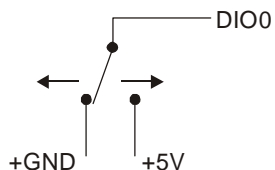


Figure 3-10. Schematic showing switch detection by digital channel DIO0

Caution! All ground pins on the UMDAS TH (pins 9, 19, 28, 38) are common and are isolated from earth ground. If a connection is made to earth ground when using digital I/O and conductive thermocouples, the thermocouples are no longer isolated. In this case, thermocouples must not be connected to any conductive surfaces that may be referenced to earth ground.

Chapter 4

Functional Details

Thermocouple measurements

A thermocouple consists of two dissimilar metals that are joined together at one end. When the junction of the metals is heated or cooled, a voltage is produced that correlates to temperature.

The UMDAS TH hardware level-shifts the thermocouple's output voltage into the A/D's common mode input range by applying +2.5 V to the thermocouple's low side at the C#L input. Always connect thermocouple sensors to the UMDAS TH in a floating fashion. Do not attempt to connect the thermocouple low side C#L to GND or to a ground referencing resistor.

Cold junction compensation (CJC)

When you connect the thermocouple sensor leads to the sensor input channel, the dissimilar metals at the UMDAS TH terminal blocks produce an additional thermocouple junction. This junction creates a small voltage error term which must be removed from the overall sensor measurement using a cold junction compensation technique. The measured voltage includes both the thermocouple voltage and the cold junction voltage. To compensate for the additional cold junction voltage, the UMDAS TH subtracts the *cold junction* voltage from the thermocouple voltage.

The UMDAS TH has two high-resolution temperature sensors that are integrated into the design of the UMDAS TH. One sensor is located on the right side of the package, and one sensor is located at the left side. The CJC sensors measure the average temperature at the terminal blocks so that the cold junction voltage can be calculated. A software algorithm automatically corrects for the additional thermocouples created at the terminal blocks by subtracting the calculated cold junction voltage from the analog input's thermocouple voltage measurement.

Increasing the thermocouple length

If you need to increase the length of your thermocouple, use the same type of thermocouple wires to minimize the error introduced by thermal EMFs.

Data linearization

After the CJC correction is performed on the measurement data, an on-board microcontroller automatically linearizes the thermocouple measurement data using National Institute of Standards and Technology (NIST) linearization coefficients for the selected thermocouple type.

The measurement data is then output as a 32-bit floating point value in the configured format (voltage or temperature).

Open-thermocouple detection (OTD)

The UMDAS TH is equipped with an open-thermocouple detection for each analog input channel. With OTD, any open-circuit or short-circuit condition at the thermocouple sensor is detected by the software. An open channel is detected by driving the input voltage to a negative value outside the range of any thermocouple output. The software recognizes this as an invalid reading and flags the appropriate channel. The software continues to sample all channels when OTD is detected.

Input leakage current

With open-thermocouple detection enabled, 105 nA (max.) of input leakage current is injected into the thermocouple. This current can cause an error voltage to develop across the lead resistance of the thermocouple that is indistinguishable from the thermocouple voltage you are measuring. You can estimate this error voltage with the following formula:

$$\text{error voltage} = \text{resistance of the thermocouple} \times 105 \text{ nA}$$

To reduce the error, reduce the length of the thermocouple to lower its resistance, or lower the AWG of the wire by using a wire with a larger diameter. With open-thermocouple detection disabled, 30 nA (max) of input leakage current is injected into the thermocouple.

RTD and thermistor measurements

RTDs and thermistors are resistive devices that require an excitation current to produce a voltage drop that can be measured differentially across the sensor. The UMDAS TH measures the sensor resistance by forcing a known excitation current through the sensor and then measuring (differentially) the voltage across the sensor to determine its resistance.

After the voltage measurement is made, the resistance of the RTD is calculated using Ohms law – the sensor resistance is calculated by dividing the measured voltage by the current excitation level ($\pm I_x$) source. The value of the $\pm I_x$ source is stored in local memory.

Once the resistance value is calculated, the value is linearized in order to convert it to a temperature value. The measurement is returned by software as a 32-bit floating point value in a voltage, resistance or temperature format.

Data linearization

An on-board microcontroller automatically performs linearization on RTD and thermistor measurements.

- RTD measurements are linearized using a Callendar-Van Dusen coefficients algorithm (you select DIN, SAMA, or ITS-90).
- Thermistor measurements are linearized using a Steinhart-Hart linearization algorithm (you supply the coefficients from the sensor manufacturer's data sheet).

USB connector

The USB connector provides +5V power and communication. No external power supply is required.

LED

The LED indicates the communication status of the UMDAS TH. It uses up to 5 mA of current. Table 4-2 defines the function of the UMDAS TH LED.

Table 4-2. LED Illumination

LED Illumination	Indication
Steady green	The UMDAS TH is connected to a computer or external USB hub.
Pulsing green	Data is being transferred. Upon connection, the LED should flash three times and then remain lit (indicates a successful installation).

Power

The two **+5V** terminals are isolated (500VDC) from the USB +5V.

Caution! Each +5V terminal is an output. Do not connect to an external power supply or you may damage the UMDAS TH and possibly the computer.

Specifications

Typical for 25 °C unless otherwise specified.

Specifications in *italic text* are guaranteed by design.

Analog input

Table 1. Generic analog input specifications

Parameter	Conditions	Specification
A/D converters		Four dual 24-bit, Sigma-Delta type
Number of channels		8 differential
<i>Input isolation</i>		<i>500 VDC minimum between field wiring and USB interface</i>
Channel configuration		Software programmable to match sensor type
Differential input voltage range for the various sensor categories	Thermocouple	±0.080 V
	RTD	0 to 0.5 V
	Thermistor	0 to 2 V
	Semiconductor sensor	0 to 2.5 V
<i>Absolute maximum input voltage</i>	<i>±C0x through ±C7x relative to GND (pins 9, 19, 28, 38)</i>	±25 V power on, ±40 V power off.
Input impedance		5 Gigohm, min.
Input leakage current	Open thermocouple detect disabled	30 nA max.
	Open thermocouple detect enabled	105 nA max.
<i>Normal mode rejection ratio</i>	<i>f_{IN} = 60 Hz</i>	<i>90 dB min.</i>
<i>Common mode rejection ratio</i>	<i>f_{IN} = 50 Hz/60 Hz</i>	<i>100 dB min.</i>
Resolution		24 bits
<i>No missing codes</i>		<i>24 bits</i>
Input coupling		DC
Warm-up time		30 minutes min.
Open thermocouple detect		Automatically enabled when the channel pair is configured for thermocouple sensor. The maximum open detection time is 3 seconds.
<i>CJC sensor accuracy</i>	<i>15 °C to 35 °C</i>	<i>±0.25 °C typ., ±0.5 °C max.</i>
	<i>0 °C to 70 °C</i>	<i>−1.0 to +0.5 °C max</i>

Channel configurations

Table 2. Channel configuration specifications

Sensor Category	Conditions	Specification
Disabled		
Thermocouple		8 differential channels
Semiconductor sensor		8 differential channels
RTD and thermistor	2-wire input configuration with a single sensor	4 differential channels
	2-wire input configuration with two sensors	8 differential channels
	3-wire configuration with a single sensor per channel pair	4 differential channels
	4-wire input configuration	8 differential channels

Note 1: Internally, the UMDAS TH has four, dual-channel, fully differential A/Ds providing a total of eight differential channels. The analog input channels are therefore configured in four channel pairs with CH0/CH1 sensor inputs, CH2/CH3 sensor inputs, CH4/CH5 sensor inputs, and CH6/CH7 sensor inputs paired together. This "channel-pairing" requires the analog input channel pairs be configured to monitor the same category of temperature sensor. Mixing different sensor types of the same category (such as a type J thermocouple on channel 0 and a type T thermocouple on channel 1) is valid.

Note 2: Channel configuration information is stored in the EEPROM of the isolated microcontroller by the firmware whenever any item is modified. Modification is performed by commands issued over USB from an external application, and the configuration is made non-volatile through the use of the EEPROM.

Note 3: The factory default configuration is *Disabled*. The Disabled mode will disconnect the analog inputs from the terminal blocks and internally ground all of the A/D inputs. This mode also disables each of the current excitation sources.

Compatible sensors

Table 3. Compatible sensor type specifications

Parameter	Conditions
Thermocouple	J: -210 °C to 1200 °C
	K: -270 °C to 1372 °C
	R: -50 °C to 1768 °C
	S: -50 °C to 1768 °C
	T: -270 °C to 400 °C
	N: -270 °C to 1300 °C
	E: -270 °C to 1000 °C
	B: 0 °C to 1820 °C
RTD	100 ohm PT (DIN 43760: 0.00385 ohms/ohm/°C)
	100 ohm PT (SAMA: 0.003911 ohms/ohm/°C)
	100 ohm PT (ITS-90/IEC751:0.0038505 ohms/ohm/°C)
Thermistor	Standard 2,252 ohm through 30,000 ohm
Semiconductor / IC	TMP36 or equivalent

Accuracy

Thermocouple measurement accuracy

Table 4. Thermocouple accuracy specifications, including CJC measurement error

Sensor Type	Maximum error	Typical error	Temperature range
J	$\pm 1.499\text{ }^{\circ}\text{C}$	$\pm 0.507\text{ }^{\circ}\text{C}$	-210 to $0\text{ }^{\circ}\text{C}$
	$\pm 0.643\text{ }^{\circ}\text{C}$	$\pm 0.312\text{ }^{\circ}\text{C}$	0 to $1200\text{ }^{\circ}\text{C}$
K	$\pm 1.761\text{ }^{\circ}\text{C}$	$\pm 0.538\text{ }^{\circ}\text{C}$	-210 to $0\text{ }^{\circ}\text{C}$
	$\pm 0.691\text{ }^{\circ}\text{C}$	$\pm 0.345\text{ }^{\circ}\text{C}$	0 to $1372\text{ }^{\circ}\text{C}$
S	$\pm 2.491\text{ }^{\circ}\text{C}$	$\pm 0.648\text{ }^{\circ}\text{C}$	-50 to $250\text{ }^{\circ}\text{C}$
	$\pm 1.841\text{ }^{\circ}\text{C}$	$\pm 0.399\text{ }^{\circ}\text{C}$	250 to $1768.1\text{ }^{\circ}\text{C}$
R	$\pm 2.653\text{ }^{\circ}\text{C}$	$\pm 0.650\text{ }^{\circ}\text{C}$	-50 to $250\text{ }^{\circ}\text{C}$
	$\pm 1.070\text{ }^{\circ}\text{C}$	$\pm 0.358\text{ }^{\circ}\text{C}$	250 to $1768.1\text{ }^{\circ}\text{C}$
B	$\pm 1.779\text{ }^{\circ}\text{C}$	$\pm 0.581\text{ }^{\circ}\text{C}$	250 to $700\text{ }^{\circ}\text{C}$
	$\pm 0.912\text{ }^{\circ}\text{C}$	$\pm 0.369\text{ }^{\circ}\text{C}$	700 to $1820\text{ }^{\circ}\text{C}$
E	$\pm 1.471\text{ }^{\circ}\text{C}$	$\pm 0.462\text{ }^{\circ}\text{C}$	-200 to $0\text{ }^{\circ}\text{C}$
	$\pm 0.639\text{ }^{\circ}\text{C}$	$\pm 0.245\text{ }^{\circ}\text{C}$	0 to $1000\text{ }^{\circ}\text{C}$
T	$\pm 1.717\text{ }^{\circ}\text{C}$	$\pm 0.514\text{ }^{\circ}\text{C}$	-200 to $0\text{ }^{\circ}\text{C}$
	$\pm 0.713\text{ }^{\circ}\text{C}$	$\pm 0.256\text{ }^{\circ}\text{C}$	0 to $600\text{ }^{\circ}\text{C}$
N	$\pm 1.969\text{ }^{\circ}\text{C}$	$\pm 0.502\text{ }^{\circ}\text{C}$	-200 to $0\text{ }^{\circ}\text{C}$
	$\pm 0.769\text{ }^{\circ}\text{C}$	$\pm 0.272\text{ }^{\circ}\text{C}$	0 to $1300\text{ }^{\circ}\text{C}$

Note 4: Thermocouple measurement accuracy specifications include linearization, cold-junction compensation and system noise. These specs are for one year, or 3000 operating hours, whichever comes first, and for operation of the UMDAS TH between $15\text{ }^{\circ}\text{C}$ and $35\text{ }^{\circ}\text{C}$. For measurements outside this range, add ± 0.5 degree to the maximum error shown. There are CJC sensors on each side of the module. The accuracy listed above assumes the screw terminals are at the same temperature as the CJC sensor. Errors shown do not include inherent thermocouple error. Please contact your thermocouple supplier for details on the actual thermocouple error.

Note 5: Thermocouples must be connected to the UMDAS TH such that they are floating with respect to GND (pins 9, 19, 28, 38). The UMDAS TH GND pins are isolated from earth ground, so connecting thermocouple sensors to voltages referenced to earth ground is permissible as long as the isolation between the GND pins and earth ground is maintained.

Note 6: When thermocouples are attached to conductive surfaces, the voltage differential between multiple thermocouples must remain within $\pm 1.4\text{ V}$. For best results we recommend the use of insulated or ungrounded thermocouples when possible.

Semiconductor sensor measurement accuracy

Table 5. Semiconductor sensor accuracy specifications

Sensor Type	Temperature Range ($^{\circ}\text{C}$)	Maximum Accuracy Error
TMP36 or equivalent	-40 to $150\text{ }^{\circ}\text{C}$	$\pm 0.50\text{ }^{\circ}\text{C}$

Note 7: Error shown does not include errors of the sensor itself. These specs are for one year while operation of the UMDAS TH unit is between $15\text{ }^{\circ}\text{C}$ and $35\text{ }^{\circ}\text{C}$. Please contact your sensor supplier for details on the actual sensor error limitations.

RTD measurement accuracy

Table 6. RTD measurement accuracy specifications

RTD	Sensor Temperature	Maximum Accuracy Error ($^{\circ}\text{C}$) $I_{x+} = 210\text{ }\mu\text{A}$	Typical Accuracy Error ($^{\circ}\text{C}$) $I_{x+} = 210\text{ }\mu\text{A}$
PT100, DIN, US or ITS-90	-200 $^{\circ}\text{C}$ to -150 $^{\circ}\text{C}$	± 2.85	± 2.59
	-150 $^{\circ}\text{C}$ to -100 $^{\circ}\text{C}$	± 1.24	± 0.97
	-100 $^{\circ}\text{C}$ to $0\text{ }^{\circ}\text{C}$	± 0.58	± 0.31
	$0\text{ }^{\circ}\text{C}$ to $100\text{ }^{\circ}\text{C}$	± 0.38	± 0.11
	$100\text{ }^{\circ}\text{C}$ to $300\text{ }^{\circ}\text{C}$	± 0.39	± 0.12

	300°C to 600°C	±0.40	±0.12
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Note 8: Error shown does not include errors of the sensor itself. The sensor linearization is performed using a Callendar-Van Dusen linearization algorithm. These specs are for one year while operation of the UMDAS TH unit is between 15 °C and 35 °C. The specification does not include lead resistance errors for 2-wire RTD connections. Please contact your sensor supplier for details on the actual sensor error limitations.

Note 9: Resistance values greater than 660 ohms cannot be measured by the UMDAS TH in the RTD mode. The 660 ohm resistance limit includes the total resistance across the current excitation ($\pm I_x$) pins, which is the sum of the RTD resistance and the lead resistances.

Note 10: For accurate three wire compensation, the individual lead resistances connected to the $\pm I_x$ pins must be of equal value.

Thermistor measurement accuracy

Table 7. Thermistor measurement accuracy specifications

Thermistor	Temperature Range	Maximum Accuracy Error (°C) $I_{x+} = 10 \mu A$
2252 Ω	-40 to 120 °C	±0.05
3000 Ω	-40 to 120 °C	±0.05
5000 Ω	-35 to 120 °C	±0.05
10000 Ω	-25 to 120 °C	±0.05
30000 Ω	-10 to 120 °C	±0.05

Note 11: Error shown does not include errors of the sensor itself. The sensor linearization is performed using a Steinhart-Hart linearization algorithm. These specs are for one year while operation of the UMDAS TH unit is between 15 °C and 35 °C. The specification does not include lead resistance errors for 2-wire thermistor connections. Please contact your sensor supplier for details on the actual sensor error limitations. Total thermistor resistance on any given channel pair must not exceed 180 k ohms. Typical resistance values at various temperatures for supported thermistors are shown in Table 8.

Table 8. Typical thermistor resistance specifications

Temp	2252 Ω thermistor	3000 Ω thermistor	5 k Ω thermistor	10 k Ω thermistor	30 k Ω thermistor
-40 °C	76 k Ω	101 k Ω	168 k Ω	240 k Ω (Note 12)	885 k Ω (Note 12)
-35 °C	55 k Ω	73 k Ω	121 k Ω	179 k Ω	649 k Ω (Note 12)
-30 °C	40 k Ω	53 k Ω	88 k Ω	135 k Ω	481 k Ω (Note 12)
-25 °C	29 k Ω	39 k Ω	65 k Ω	103 k Ω	360 k Ω (Note 12)
-20 °C	22 k Ω	29 k Ω	49 k Ω	79 k Ω	271 k Ω (Note 12)
-15 °C	16 k Ω	22 k Ω	36 k Ω	61 k Ω	206 k Ω (Note 12)
-10 °C	12 k Ω	17 k Ω	28 k Ω	48 k Ω	158 k Ω
-5 °C	9.5 k Ω	13 k Ω	21 k Ω	37 k Ω	122 k Ω
0 °C	7.4 k Ω	9.8 k Ω	16 k Ω	29 k Ω	95 k Ω

Note 12: Resistance values greater than 180 k ohms cannot be measured by the UMDAS TH in the thermistor mode. The 180 k ohm resistance limit includes the total resistance across the current excitation ($\pm I_x$) pins, which is the sum of the thermistor resistance and the lead resistances.

Note 13: For accurate three wire compensation, the individual lead resistances connected to the $\pm I_x$ pins must be of equal value.

Throughput rate

Table 9. Throughput rate specifications

Number of Input Channels	Maximum Throughput
1	2 Samples/second
2	2 S/s on each channel, 4 S/s total
3	2 S/s on each channel, 6 S/s total
4	2 S/s on each channel, 8 S/s total
5	2 S/s on each channel, 10 S/s total
6	2 S/s on each channel, 12 S/s total
7	2 S/s on each channel, 14 S/s total
8	2 S/s on each channel, 16 S/s total

Note 14: The analog inputs are configured to run continuously. Each channel is sampled twice per second. The maximum latency between when a sample is acquired and the temperature data is provided by the USB unit is approximately 0.5 seconds.

Digital input/output

Table 10. Digital input/output specifications

Digital type	CMOS
Number of I/O	8 (DIO0 through DIO7)
Configuration	Independently configured for input or output. Power on reset is input mode.
Pull-up/pull-down configuration	All pins pulled up to +5 V via 47 K resistors (default). Pull-down to ground (GND) also available.
Digital I/O transfer rate (software paced)	<ul style="list-style-type: none"> ▪ Digital input – 50 port reads or single bit reads per second typ. ▪ Digital output – 100 port writes or single bit writes per second typ.
Input high voltage	2.0 V min., 5.5 V absolute max.
Input low voltage	0.8 V max., –0.5 V absolute min.
Output low voltage (IOL = 2.5 mA)	0.7 V max.
Output high voltage (IOH = –2.5 mA)	3.8 V min.

Note 15: All ground pins on the UMDAS TH (pins 9, 19, 28, 38) are common and are isolated from earth ground. If a connection is made to earth ground when using digital I/O and conductive thermocouples, the thermocouples are no longer isolated. In this case, thermocouples must not be connected to any conductive surfaces that may be referenced to earth ground.

Memory

Table 11. Memory specifications

EEPROM	1,024 bytes isolated micro reserved for sensor configuration 256 bytes USB micro for external application use
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Microcontroller

Table 12. Microcontroller specifications

Type	Two high-performance 8-bit RISC microcontrollers
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USB +5V voltage

Table 13. USB +5V voltage specifications

Parameter	Conditions	Specification
USB +5V (VBUS) input voltage range		4.75 V min. to 5.25 V max.

Power

Table 14. Power specifications

Parameter	Conditions	Specification
Supply current	USB enumeration	<100 mA
Supply current (Note 16)	Continuous mode	140 mA typ.
User +5V output voltage range (terminal block pin 21 and pin 47)	Connected to self-powered hub. (Note 17)	4.75 V min. to 5.25 V max.
User +5V output current (terminal block pin 21 and pin 47)	Bus-powered and connected to a self-powered hub. (Note 17)	10 mA max.
Isolation	Measurement system to PC	500 VDC min.

Note 16: This is the total current requirement for the UMDAS TH which includes up to 10 mA for the status LED.

Note 17: Self-Powered Hub refers to a USB hub with an external power supply. Self-powered hubs allow a connected USB device to draw up to 500 mA.

Root Port Hubs reside in the PC's USB Host Controller. The USB port(s) on your PC are root port hubs. All externally powered root port hubs (desktop PC's) provide up to 500 mA of current for a USB device. Battery-powered root port hubs provide 100 mA or 500 mA, depending upon the manufacturer. A laptop PC that is not connected to an external power adapter is an example of a battery-powered root port hub.

USB specifications

Table 15. USB specifications

USB device type	USB 2.0 (full-speed)
Device compatibility	USB 1.1, USB 2.0
	Self-powered, 100 mA consumption max
USB cable type	A-B cable, UL type AWM 2527 or equivalent. (min 24 AWG VBUS/GND, min 28 AWG D+/D-)
USB cable length	3 meters max.

Current excitation outputs (I_x±)

Table 16. Current excitation output specifications

Parameter	Conditions	Specification
Configuration		4 dedicated pairs: ±I1 - CH0/CH1 ±I2 - CH2/CH3 ±I3 - CH4/CH5 ±I4 - CH6/CH7
Current excitation output ranges	Thermistor	10 μ A typ.
	RTD	210 μ A typ.
Tolerance		±5% typ.
Drift		200 ppm/°C
Line regulation		2.1 ppm/V max.
Load regulation		0.3 ppm/V typ.
Output compliance voltage (relative to GND pins 9, 19, 28, 38)		3.90 V max. -0.03 V min.

Note 18: The UMDAS TH has four current excitation outputs, with ±I1 dedicated to the CH0/CH1 analog inputs, ±I2 dedicated to CH2/CH3, ±I3 dedicated to CH4/CH5, and ±I4 dedicated to CH6/CH7. The excitation output currents should always be used in this dedicated configuration.

Note 19: The current excitation outputs are automatically configured based on the sensor (thermistor or RTD) selected.

Environmental

Table 17. Environmental specifications

Operating temperature range	0 to 70 °C
Storage temperature range	-40 to 85 °C
Humidity	0 to 90% non-condensing

Mechanical

Table 18. Mechanical specifications

Dimensions	127 mm (L) x 88.9 mm (W) x 35.56 (H)
User connection length	3 meters max.

Screw terminal connector type and pin out

Table 19. Screw terminal connector specifications

Connector type	Screw terminal
Wire gauge range	16 AWG to 30 AWG

Screw terminal pin out

Table 20. Screw terminal pin out

Pin	Signal Name	Pin Description	Pin	Signal Name	Pin Description
1	I1+	CH0/CH1 current excitation source	27	I4-	CH6/CH7 current excitation return
2	NC		28	GND	
3	C0H	CH0 sensor input (+)	29	C7L	CH7 sensor input (-)
4	C0L	CH0 sensor input (-)	30	C7H	CH7 sensor input (+)
5	4W01	CH0/CH1 4-wire, 2 sensor common	31	IC67	CH6/CH7 2 sensor common
6	IC01	CH0/CH1 2-sensor common	32	4W67	CH6/CH7 4-wire, 2 sensor common
7	C1H	CH1 sensor input (+)	33	C6L	CH6 sensor input (-)
8	C1L	CH1 sensor input (-)	34	C6H	CH6 sensor input (+)
9	GND		35	NC	
10	I1-	CH0/CH1 current excitation return	36	I4+	CH6/CH7 current excitation source
	CJC sensor			CJC sensor	
11	I2+	CH2/CH3 current excitation source	37	I3-	CH4/CH5 current excitation return
12	NC		38	GND	
13	C2H	CH2 sensor input (+)	39	C5L	CH5 sensor input (-)
14	C2L	CH2 sensor input (-)	40	C5H	CH5 sensor input (+)
15	4W23	CH2/CH3 4-wire, 2 sensor common	41	IC45	CH4/CH5 2 sensor common
16	IC23	CH2/CH3 2 sensor common	42	4W45	CH4/CH5 4-wire, 2 sensor common
17	C3H	CH3 sensor input (+)	43	C4L	CH4 sensor input (-)
18	C3L	CH3 sensor input (-)	44	C4H	CH4 sensor input (+)
19	GND		45	NC	
20	I2-	CH2/CH3 current excitation return	46	I3+	CH4/CH5 current excitation source
21	+5V	+5V output	47	+5V	+5V output
22	GND		48	GND	
23	DIO0	Digital Input/Output	49	DIO7	Digital Input/Output
24	DIO1	Digital Input/Output	50	DIO6	Digital Input/Output
25	DIO2	Digital Input/Output	51	DIO5	Digital Input/Output
26	DIO3	Digital Input/Output	52	DIO4	Digital Input/Output

Product Service

Diagnosis and Debug

CyberResearch, Inc. maintains technical support lines staffed by experienced Applications Engineers and Technicians. There is no charge to call and we will return your call promptly if it is received while our lines are busy. Most problems encountered with data acquisition products can be solved over the phone. Signal connections and programming are the two most common sources of difficulty. CyberResearch support personnel can help you solve these problems, especially if you are prepared for the call.

To ensure your call's overall success and expediency:

- 1) Have the phone close to the PC so you can conveniently and quickly take action that the Applications Engineer might suggest.
- 2) Be prepared to open your PC, remove boards, report back-switch or jumper settings, and possibly change settings before reinstalling the modules.
- 3) Have a volt meter handy to take measurements of the signals you are trying to measure as well as the signals on the board, module, or power supply.
- 4) Isolate problem areas that are not working as you expected.
- 5) Have the source code to the program you are having trouble with available so that preceding and prerequisite modes can be referenced and discussed.
- 6) Have the manual at hand. Also have the product's utility disks and any other relevant disks nearby so programs and version numbers can be checked.

Preparation will facilitate the diagnosis procedure, save you time, and avoid repeated calls. Here are a few preliminary actions you can take before you call which may solve some of the more common problems:

- 1) Check the PC-bus power and any power supply signals.
- 2) Check the voltage level of the signal between SIGNAL HIGH and SIGNAL LOW, or SIGNAL+ and SIGNAL- . It CANNOT exceed the full scale range of the board.
- 3) Check the other boards in your PC or modules on the network for address and interrupt conflicts.
- 4) Refer to the example programs as a baseline for comparing code.

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Warranty Notice

CyberResearch, Inc. warrants that this equipment as furnished will be free from defects in material and workmanship for a period of one year from the confirmed date of purchase by the original buyer and that upon written notice of any such defect, CyberResearch, Inc. will, at its option, repair or replace the defective item under the terms of this warranty, subject to the provisions and specific exclusions listed herein.

This warranty shall not apply to equipment that has been previously repaired or altered outside our plant in any way which may, in the judgment of the manufacturer, affect its reliability. Nor will it apply if the equipment has been used in a manner exceeding or inconsistent with its specifications or if the serial number has been removed.

CyberResearch, Inc. does not assume any liability for consequential damages as a result from our products uses, and in any event our liability shall not exceed the original selling price of the equipment.

The equipment warranty shall constitute the sole and exclusive remedy of any Buyer of Seller equipment and the sole and exclusive liability of the Seller, its successors or assigns, in connection with equipment purchased and in lieu of all other warranties expressed implied or statutory, including, but not limited to, any implied warranty of merchant ability or fitness and all other obligations or liabilities of seller, its successors or assigns.

The equipment must be returned postage prepaid. Package it securely and insure it. You will be charged for parts and labor if the warranty period has expired.

Returns and RMAs

If a CyberResearch product has been diagnosed as being non-functional, is visibly damaged, or must be returned for any other reason, please call for an assigned RMA number. The RMA number is a key piece of information that lets us track and process returned merchandise with the fastest possible turnaround time.

PLEASE CALL FOR AN RMA NUMBER!

Packages returned without an RMA number will be refused!

In most cases, a returned package will be refused at the receiving dock if its contents are not known. The RMA number allows us to reference the history of returned products and determine if they are meeting your application's requirements. When you call customer service for your RMA number, you will be asked to provide information about the product you are returning, your address, and a contact person at your organization.

Please make sure that the RMA number is prominently displayed on the outside of the box.

• Thank You •

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