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Software for the automatization of the analysis of eye tracker's data while used with the driving simulator

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Executive summary

This report documents activities 4.4 “Car simulator”, sub activities 3, which objective is the design of a software for the automatization of the analysis of eye tracker's data while used with the driving simulator. This tool will be used in WP5.2 for conducting experiments on car simulator about rider's conspicuity.

The method used for the automatization is a post treatment process, which allows researchers to analyse their recorded data and to easily change the interest areas. The areas may consist in either static or dynamic objects. The areas can be easily described using symbolic description or geometric faces. If the calibration of the eye tracker has been properly conducted, the software can be used in a reliable and efficient way.

The produced software has been designed for the INRETS SIM² class simulators and for French users (which are the users within 2BeSafe), but the method can be fairly easily adapted to other driving simulators as well as the man machine interface language.

As a final result, the software has been designed, implemented and delivered, it fit the user requirements.

1. Software for the automatization of the analysis of eye tracker's data

The aim of this activity was the design of tools which helps the « final user » in setting and operating the results of their experiments using eye tracker's on simulators. Three integrated tools have been designed:

1. An off-line one, allowing to precise elements in the visual scene which have to be considered for the visual activity,
2. An on-line one, aiming at synchronizing the data acquired by the simulator and them acquired by the eye tracker's,
3. An off-line one, which allows calculating the duration of the fixation point (object in space at which sight is aimed) for each considered elements.

It has to be considered that such tools are, to a large extent, simulator and eye tracker's dependant, as the 3D database format, the 3D rendering engine and the eye tracker's manufacturer are often different from simulator to simulator. Thus, the tools designed in this activity are dedicated to the simulator used in WP5.2, which is a INRETS SIM² class simulator, and to the FaceLab eye tracker's. The INRETS-SIM² simulator architecture is an open and modular architecture which is used in several research labs in France, and also in some foreign research labs.

Compare to existing systems, for example the Oktal one, the tools have been designed in such a way that they simplify the configuration and the analysis by non expert users. The first step, consisting in defining the elements considered for the visual activity, do not require skills in info graphics as the user can precise areas in the 3D database without using a 3D modeller.

The process, which assumes that the protocol of the experiment has been properly defined, consists in:

1. Achieving the experiment using the simulator and the FaceLab eye tracker's, in this step data from eye tracker's and data from the driving simulator are recorded,
2. Determining the elements or areas of interest for the visual activity. Three kinds of elements can be defined: vehicles, road signs and areas. Vehicles and road signs are identified symbolically, while areas are defined using the coordinates of 3D rectangle faces. The defined areas can be double checked visually, using the driving simulator visual loop,
3. Analysing the data, using a replay mode which allows correlating the data acquired by the eye tracker's, the data acquired by the driving simulator and the data defined for the study of the visual activity.

It has to be stressed that the step 1 can be achieved before the step 2, but has of course to be achieved before the step 3.

It has also to be noticed that the design of the tools in such a way allows the processing of the data acquired in previous experiments.

The following sections explain the process and may be used as a user manual. As the software is primarily intended to be used by French users, the language used is the French.

1.1. Identify static and dynamics areas of interest

The software allows selecting up to 20 areas of interest for the experiment. This characteristic has been defined jointly with the researchers of WP5.2, it can be easily increased up to 255.

Three categories of areas of interest can be specified:

- vhs (vehicles)
- *panneau* (sign or object)
- *face* (polygon)

These data have to be specified in an ASCII file named "*ZoneInteret.txt*". Figure 1 is an example of such a file:

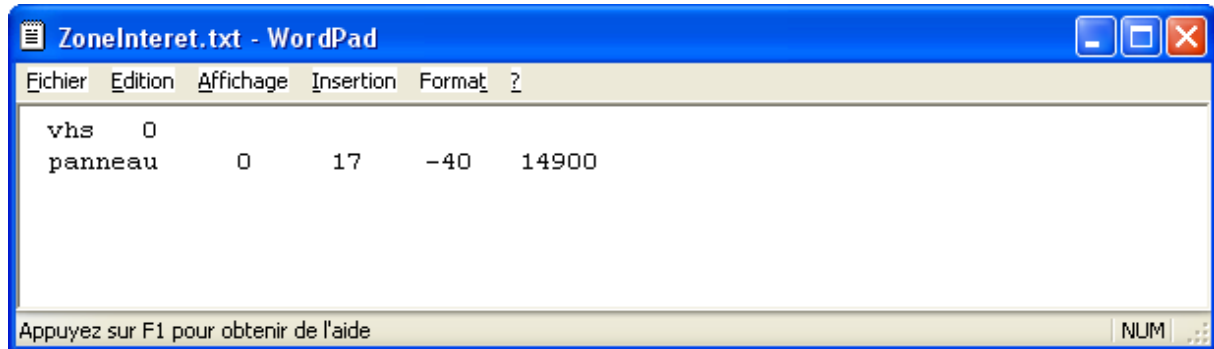


Figure 1 - Symbolic description of areas of interest (vehicles and signs)

The "vhs" (vehicles) category creates a dynamic area moving with the vehicle of which you specify the identification number within the simulation. The identification number consists in the DR2 ID of the vehicle, DR2 being the software in charge of the traffic simulation within the INRETS SIM² simulator architecture.

Syntax: vhs + DR2 ID of the vehicle

"vhs 0" means that we determine the time of fixation on vehicle # 0 when it is displayed.

The "panneau" (sign or object) category allows to create an area of interest related to an object from the static background (road sign, tree, house ...) you specify the identification number within the simulation. The identification number consists in the SIM² type of the object, as the objects of this category are not always managed by the traffic simulation. In order to avoid confusion, the location of the object is added, using the curvilinear position of the object along a specific road.

Syntax: panneau + SIM² ID of the object + road number + lateral position of the object (dm) + kilometeric position of the object (dm).

"panneau 0 1 80 30000" means that the area of interest will be linked to the object # 0 located on road number 1 at kilometeric point (KP) 3.0000 and located at a lateral position of 8 meters.

The "face" category allows creating a zone of fixed interest whose location is specified by the 4 vertices of the face.

Syntax: face + name + list of the co-ordinates of the 4 vertices

"face building 1 (674.932050,34.8886820,13.5751250)(674.024390,34.8777690,3.2048E-01)(651.215930,34.6028970,2.5106E-01)(654.450030,34.6420930,13.4708410)" means that the area of interest consists in a polygon defined by the co-ordinates which are précised.

There is no obligation to design a rectangle. The interior angles do not need to be straight.

An additional module has been added to the SIM² application, which provides an interface to select and specify the various parameters involved. To access them, you must:

1. Load and display your 3D base by choosing the right track in SIM²
2. Not be connected with DR2 (which mean off-line use of SIM²)
3. Select helicopter view by pressing F9.

Figure 2 is the dialog box which allows to precise the areas of interest.

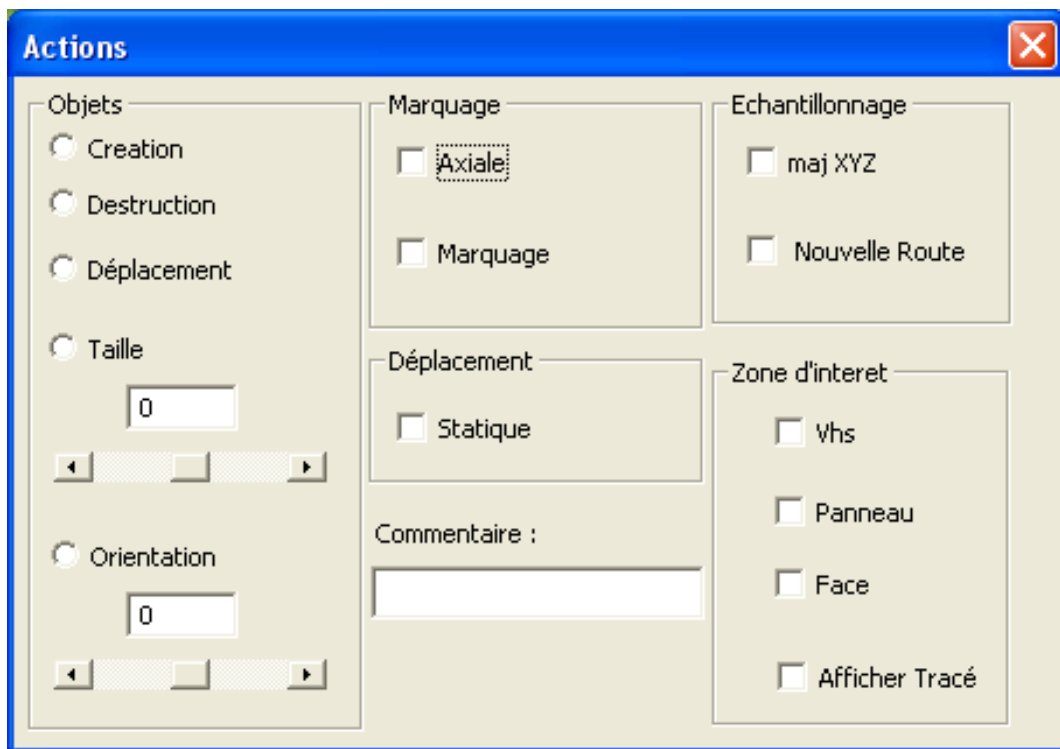


Figure 2 - Areas of interest selection dialog box

This dialog box is used for multiple purposes, only the « zone d'interet » part (bottom, right) is used for identifying the areas of interest.

1.1.1. Areas of interest: vehicles

If "Vhs" (vehicles) is checked, then appears on the screen a new dialog box (Figure 3):

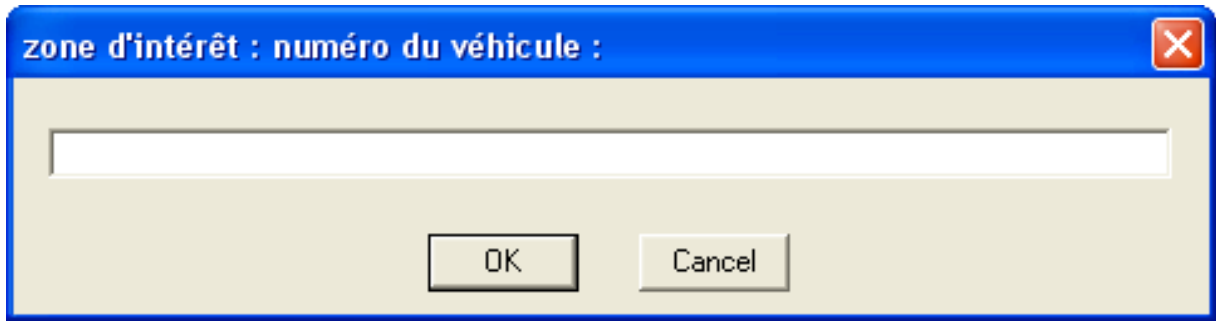


Figure 3 - Vehicle ID number specification

One must specify the DR2 identification number of the vehicle concerned.

1.1.2. Areas of interest: objects

If "panneau" (objects) is checked, the following dialogs will appear (Figure 4):

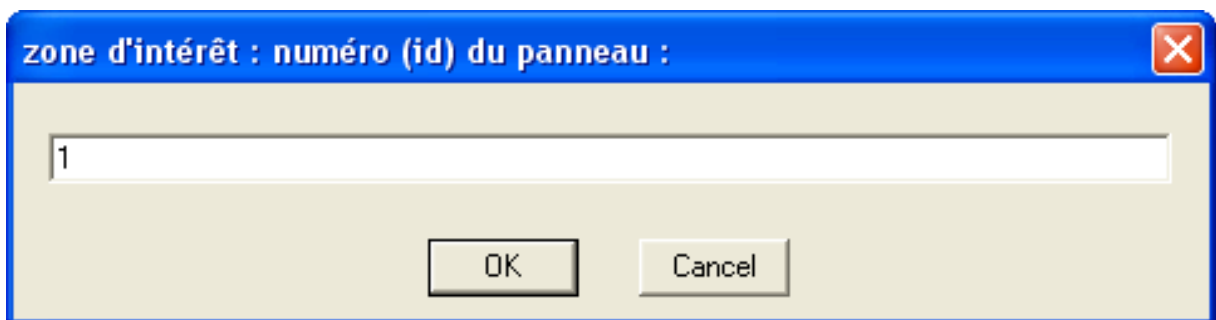


Figure 4 - "panneau" ID type specification

One must specify the position of the SIM² ID type for the object.

Then, one has to specify a position. First, one specifies the road's identification number (DR2 reference, Figure 5):

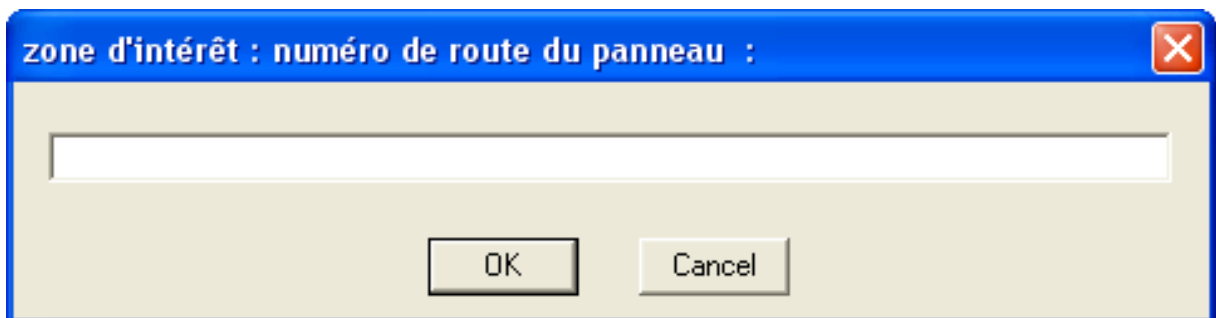


Figure 5 -Road ID number specification

As well as its lateral position (in dm, Figure 6):

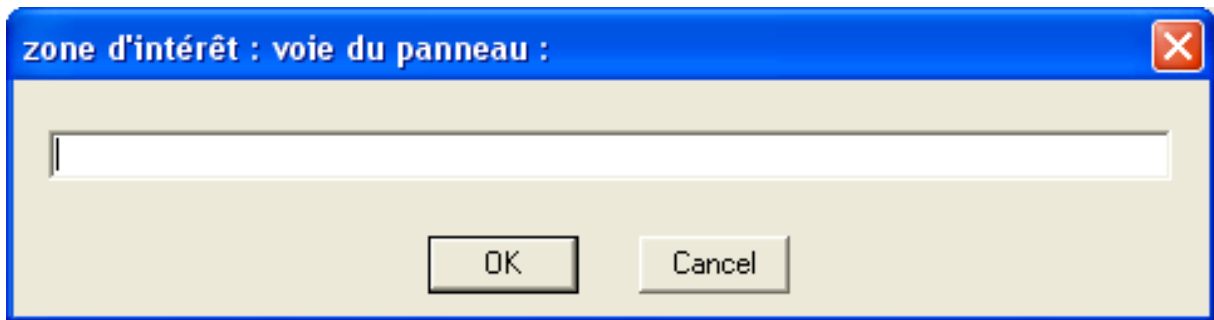


Figure 6 - Lateral position specification

And at last it's KP (in dm, Figure 7):

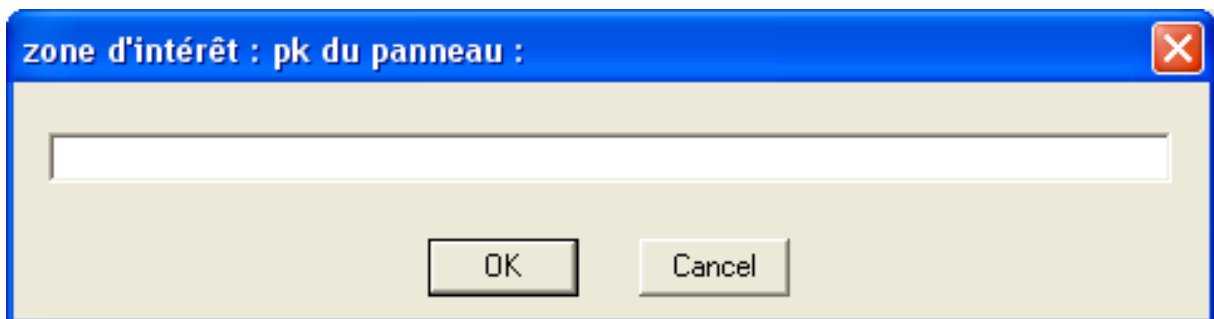


Figure 7 - KP specification

1.1.3. Areas of interest: 3D polygons

In the case of a "face", one has to press the space bar when the mouse cursor is in the right positions. The application determines the first polygons encountered in the virtual world automatically. When the fourth and last vertex is specified, the following dialog appears on the screen (Figure 8):

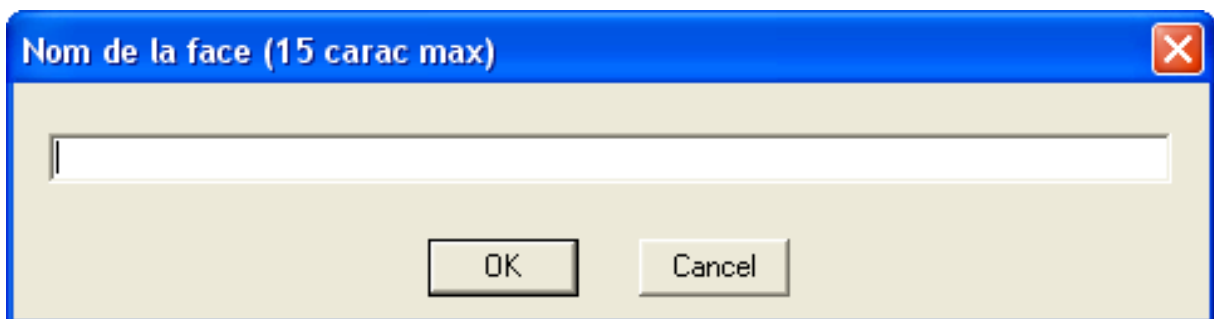


Figure 8 - Face name specification

This allows the user to remember more easily what this "face" represents. One will then be asked to confirm the choice of name (here, "tt", Figure 9):



Figure 9 - Confirmation for a "face" area of interest

If one click on "Oui", the "face" specification is stored in the file, otherwise not.

1.2. Displaying the areas of interest

Here is an example of an initial view of the driving area, with two objects:

- A dynamic, car number 0.
- A static, a speed limit sign (position: route 17 / lane position: -40 dm / KP: 14900 dm).



Figure 10 - Initial view taken during the experiment

We thus want to create two zones of interest, one for each object. This means creating a file containing all the required information. Figure 11 shows such an ASCII file.

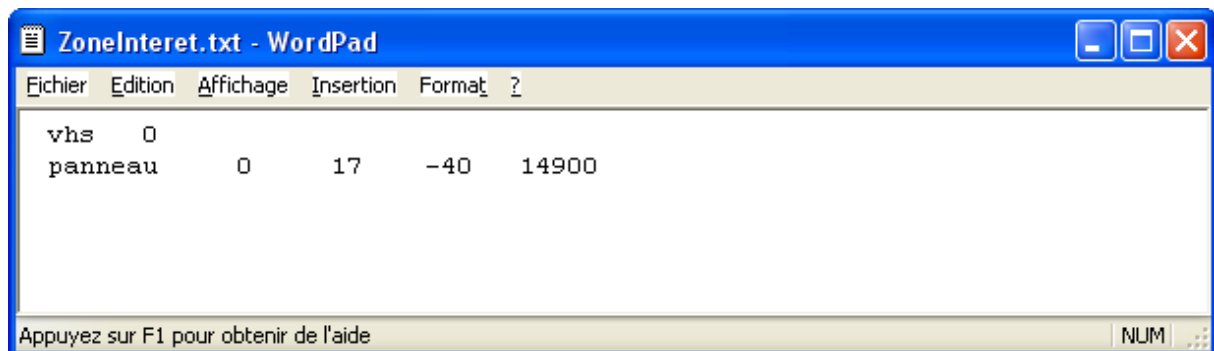


Figure 11 - Example of "ZoneInteret" parameter file

When one executes the application in eye tracker's replay mode, one gets the following display (Figure 12):

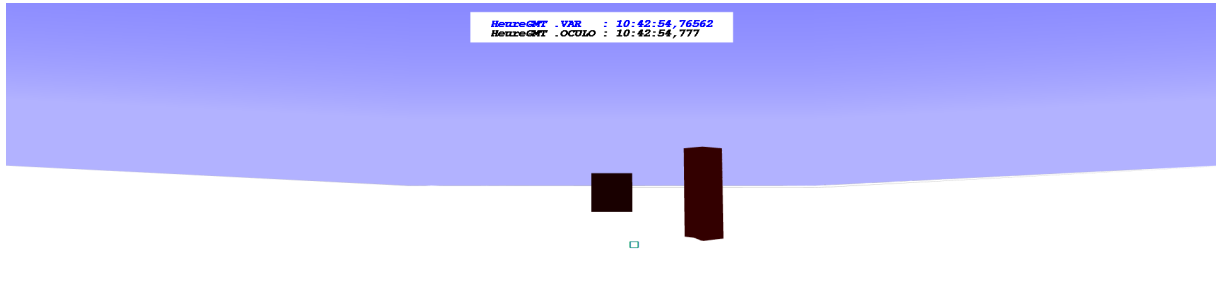


Figure 12 - Eye tracker's replay mode

Note that both objects are now encompassed by rectangular parallelepipeds that hug the shapes of objects. The notion of distance between the "faces" nearest to the object is very important. In fact, the calculation of fixation durations in each zone is based on the intersection of the measured gaze with the parallelepiped. An error may be induced if the object is too broadly embraced. A considerable amount of work has been done to minimise these errors.

Note: the entire visual base is completely white (no textures), except for the areas of interest.

2. Input files of the application

The application which analyse visual activity requires three input files. The first comes from the merging of the eye tracking files (1), the second from the data generated by DR2 (2) and the third is the previously defined parameters file describing the areas of interest (Figure 13).

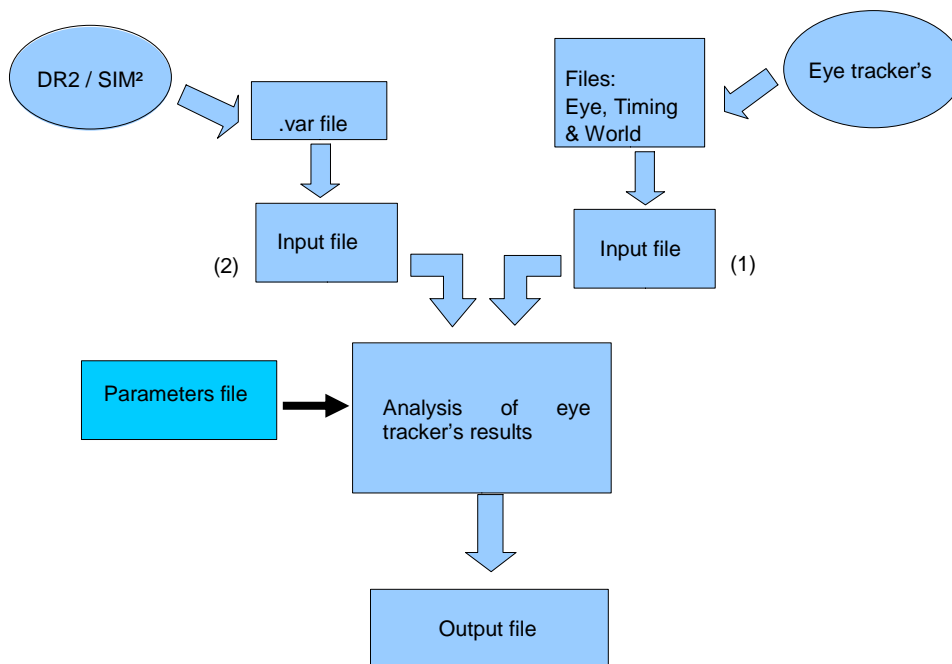


Figure 13 - Schematic representation of the application's inputs and outputs

2.1. Eye tracker's output data files

The FaceLab eye tracker generates four files. The first one, “<date>.entree“, contains the information of interest from the three other .txt files. The name of each of the files generated by the eye tracker precise the date of the experiment. The <date> string being composed of: Weekday + month + day + year + hour + minute + second corresponding to the start of the eye tracking acquisition (e.g. Timing_Tue_Sep_8_2009_14_26_36.txt).

The following sections details each data file generated by the eye tracker.

2.1.1. The FaceLab “Eye_<date>.txt” data file

This file contains 2 values: **GAZE_QUAL_R** and **GAZE_QUAL_L**. (see Figure 14)

These correspond to the pupil detection quality. A value of 2 is required to use the position values. This is a filter in the treatment of eye tracking data.

FRAME_NUM	RIGHT_EYE_CLOSE	LEFT_EYE_CLOSE	RIGHT_CLOS_CONF	LEFT_CLOS_CONF
100252	0.161591	0.104887	0.344594	
100253	0.115645	0.152077	0.44636	
100254	0.162485	0.0778482	0.407678	
100255	0.116146	0	0.289436	
100256	0.116313	0	0.31603	
100257	0.0814108	0	0.031558	
100258	0	0	0.0371423	
100259	0	0	0.033969	
100260	0	0	0.0330425	
100261	0	0.028913	0.0417664	
100262	0	0.0566473	0.031134	
100263	0	0.0714821	0.0360255	
100264	0	0.0437477	0.031412	
100265	0	0	0.0362847	
100266	0	0	0.033951	
100267	0	0	0.0260118	
100268	0	0.00319862	0.0292957	
100269	0	0.00795615	0.0304495	
100270	0	0.016182	0.031939	
100271	0	0.0460203	0.0331935	
100272	0	0.0345958	0.033245	
100273	0	0	0.0288397	
100274	0	0.0810152	0.029835	

Figure 14 - Example of FaceLab “Eye_<date>.txt” data file

2.1.2. The FaceLab “Timing_<date>.txt” data file

This file contains 2 values: **GMT_S** and **GMT_MS**

GMT_S is the GMT date in seconds of each acquisition. **GMT_MS** corresponds to the part in milliseconds to add to the previous value. A utility allows to rewrite the data in HH:MM:SS.sss notation to compare with the time from the DR2 recordings.

2.1.3. The FaceLab "World_<date>.txt" data file

This file contains 2 values: GSI_WORLD_X and GSI_WORLD_Y which give the FaceLab X and Y co-ordinates on the virtual screen (see Figure 15). The virtual screen is determined directly by the FaceLab system. Its dimensions have been integrated into our software in order to achieve a relevant normalisation and therefore a good positioning on one of our three screens.

FRAME_NUM	HEAD_OBJ_INDEX	HEAD_OBJ_NAME	CYC_SCR_INTSECT	CS
100252	-1	nothing	1	(
100253	-1	nothing	1	(
100254	-1	nothing	1	(
100255	-1	nothing	1	(
100256	-1	nothing	1	(
100257	-1	nothing	1	(
100258	-1	nothing	1	(
100259	-1	nothing	1	(
100260	-1	nothing	1	(
100261	-1	nothing	1	(
100262	-1	nothing	1	(
100263	-1	nothing	1	(
100264	-1	nothing	1	(
100265	-1	nothing	1	(
100266	-1	nothing	1	(
100267	-1	nothing	1	(
100268	-1	nothing	1	(
100269	-1	nothing	1	(
100270	-1	nothing	1	(
100271	-1	nothing	1	(
100272	-1	nothing	1	(
100273	-1	nothing	1	(
100274	-1	nothing	1	(

Figure 15 - Example of the FaceLab "World_<date>.txt" data file

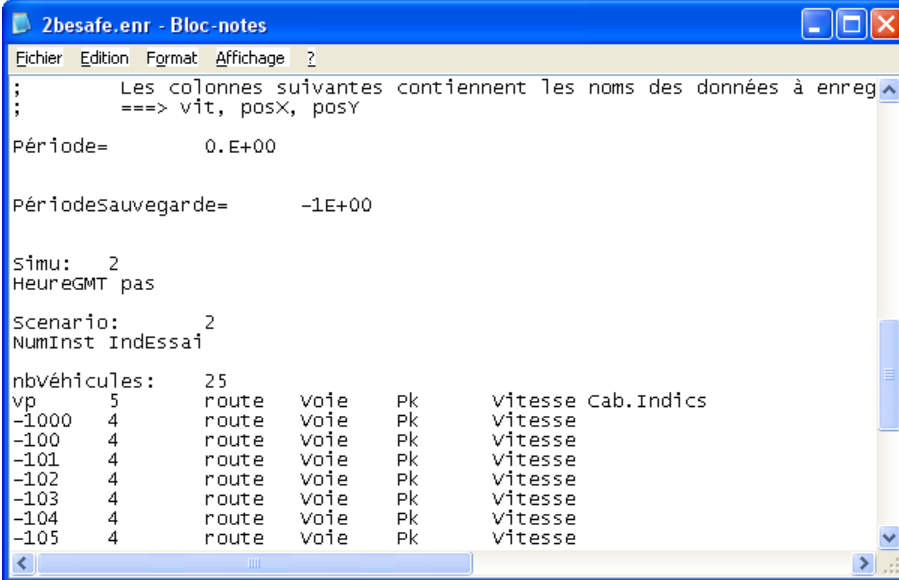
The software thus creates an input file for the eye tracker's values including the aforementioned 6 data.

GMT_S	GMT_MS	GAZE_QUAL_R	GAZE_QUAL_L	GSI_SCREEN_X	GSI_SCREEN_Y
1252665761	563	2	2	0.0797376	-0.472495
1252665761	579	2	2	0.0558399	-0.399988
1252665761	596	2	2	-0.00183827	-0.225001
1252665761	613	2	2	-0.0597621	-0.0491788
1252665761	629	2	2	-0.0838035	0.0240207
1252665761	646	2	2	-0.0842931	0.024297
1252665761	663	2	2	-0.084471	0.0243647
1252665761	679	2	2	-0.0844781	0.0204861
1252665761	696	2	2	-0.0845317	0.0161584
1252665761	713	2	2	-0.0848759	0.018192
1252665761	729	2	2	-0.0853259	0.0199902
1252665761	746	2	2	-0.0846077	0.0154941
1252665761	763	2	2	-0.082968	0.00671503
1252665761	779	2	2	-0.0820194	-0.0028368
1252665761	796	2	2	-0.0807581	-0.0115596
1252665761	813	2	2	-0.0793814	-0.0191691

Figure 16 - Example of the "entree" input data file

2.2. DR2 output data file

The DR2 software allows to precise the parameters which have to be recorded (Figure 17) during an experiment. The recording period is indicative and may slightly fluctuate during the recording due to, for example, a slowdown in the visual rendering process.



```

; Les colonnes suivantes contiennent les noms des données à enreg
; ==> vit, posX, posY

Période=          0.E+00

Périodesauvegarde=  -1E+00

simu:    2
HeureGMT pas

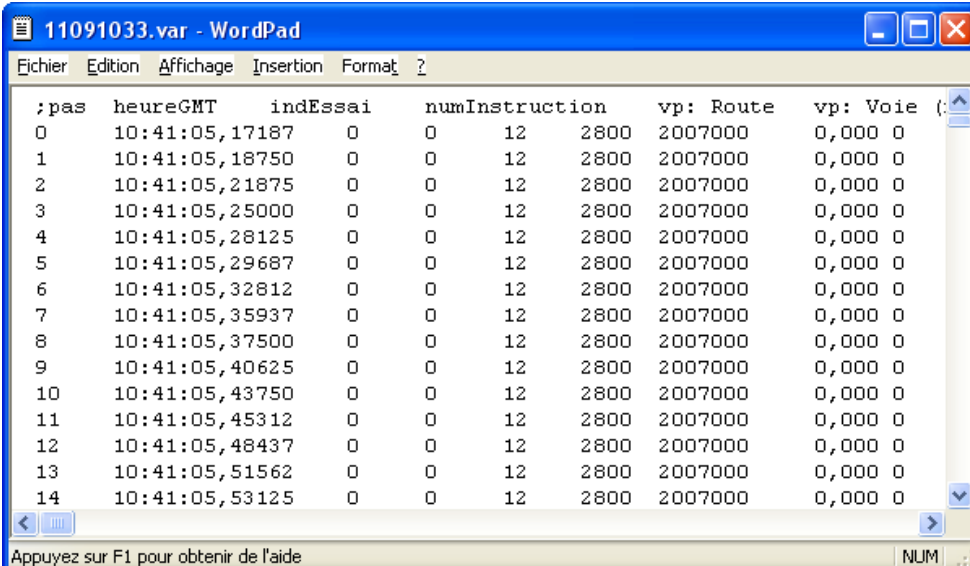
Scenario:    2
NumInst IndEssai

nbvéhicules:    25
vp      5      route  voie  Pk      vitesse Cab.Indics
-1000  4      route  voie  Pk      vitesse
-100   4      route  voie  Pk      vitesse
-101   4      route  voie  Pk      vitesse
-102   4      route  voie  Pk      vitesse
-103   4      route  voie  Pk      vitesse
-104   4      route  voie  Pk      vitesse
-105   4      route  voie  Pk      vitesse

```

Figure 17 - Sample of the .enr Dr2 recording parameters file

The output file (Figure 18) contains the requested information. In the example: the step number of the simulation, acquisition time and many other data specific to the experiment, among them the position of the subject vehicle's on the road network and of 25 traffic vehicles he interacts with.



```

;pas  heureGMT      indEssai  numInstruction  vp: Route  vp: Voie (
0     10:41:05,17187  0         0              12      2800  2007000  0,000 0
1     10:41:05,18750  0         0              12      2800  2007000  0,000 0
2     10:41:05,21875  0         0              12      2800  2007000  0,000 0
3     10:41:05,25000  0         0              12      2800  2007000  0,000 0
4     10:41:05,28125  0         0              12      2800  2007000  0,000 0
5     10:41:05,29687  0         0              12      2800  2007000  0,000 0
6     10:41:05,32812  0         0              12      2800  2007000  0,000 0
7     10:41:05,35937  0         0              12      2800  2007000  0,000 0
8     10:41:05,37500  0         0              12      2800  2007000  0,000 0
9     10:41:05,40625  0         0              12      2800  2007000  0,000 0
10    10:41:05,43750  0         0              12      2800  2007000  0,000 0
11    10:41:05,45312  0         0              12      2800  2007000  0,000 0
12    10:41:05,48437  0         0              12      2800  2007000  0,000 0
13    10:41:05,51562  0         0              12      2800  2007000  0,000 0
14    10:41:05,53125  0         0              12      2800  2007000  0,000 0

```

Figure 18 - Sample of the .var Dr2 output data file

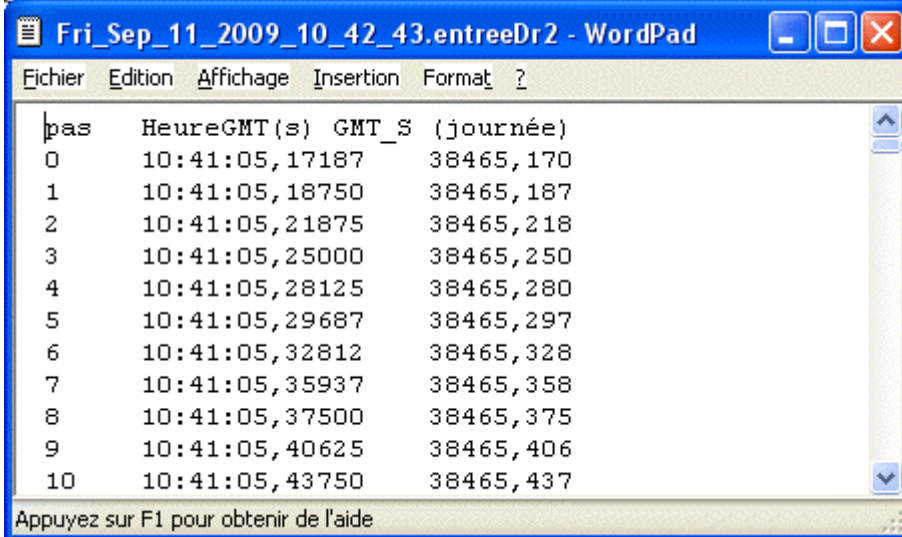
2.3. Input data merging and analysing

2.3.1. Pre-processing

One problem with this arrangement is that the eye tracker has a fixed acquisition rate of 60 Hz while the simulator has an *average* frequency of 60 Hz that may fluctuate during the experiment. It was therefore necessary to combine the data from both sources intelligently and automatically according to a common time.

The merging process assumes that both the step number of the simulation and the acquisition time has been recorded. It also assumes that each step of the simulation is recorded ("*PeriodeSauvegarde*" has to be set at -1).

A file "EntreeDr2" (Figure 19) is created based on the DR2 output file. A column corresponding to the number of seconds and milliseconds since the start of the day is added for the purpose of comparison with the eye tracking data.



pas	HeureGMT(s)	GMT_S (journée)
0	10:41:05,17187	38465,170
1	10:41:05,18750	38465,187
2	10:41:05,21875	38465,218
3	10:41:05,25000	38465,250
4	10:41:05,28125	38465,280
5	10:41:05,29687	38465,297
6	10:41:05,32812	38465,328
7	10:41:05,35937	38465,358
8	10:41:05,37500	38465,375
9	10:41:05,40625	38465,406
10	10:41:05,43750	38465,437

Figure 19 - The "EntreeDr2" intermediate data file

2.3.2. Data analysis

The analysis uses the SIM² visual loop but in a simplified mode. The entire environment is white (textures are not displayed), except for the areas of interest. The area of interest which have been specified by the user (see 1.1), are displayed using bounding boxes with a specific uniform colour which is created automatically

The colour code is: R XX G 0 B 0, where the R value is used to differentiate the AI (Areas of Interest). The first area has a value of 0.05 Red, the second 0.1, etc ...

The algorithm can be divided into five steps:

Step 1: Retrieval of the X and Y position co-ordinates of the FaceLab virtual window. This is done using information from the file "date.entree".

Step 2: Normalisation of these values to place them in the SIM² environment. Identification of which of the three views (left, centre, right) contains the gaze.

Step 3: Projection of this 2D coordinates display into the virtual world, using ray tracing to find the first polygon encountered in the 3D world.

Step 4: Testing the colour of the intersected polygon for its Red component. The value is compared with that of different areas until a match is found.

Step 5: Two possible cases:

The gaze was not within this AI at the previous time step. A new fixation period is thus created.

The gaze was within this AI at the previous time step. The duration of the current fixation period is thus updated.

Duration of the current fixation (step $t + 1$) = Duration of the current fixation (step t) + time between the two steps (t and $t + 1$).

Figure 20 describe the fixation algorithm.

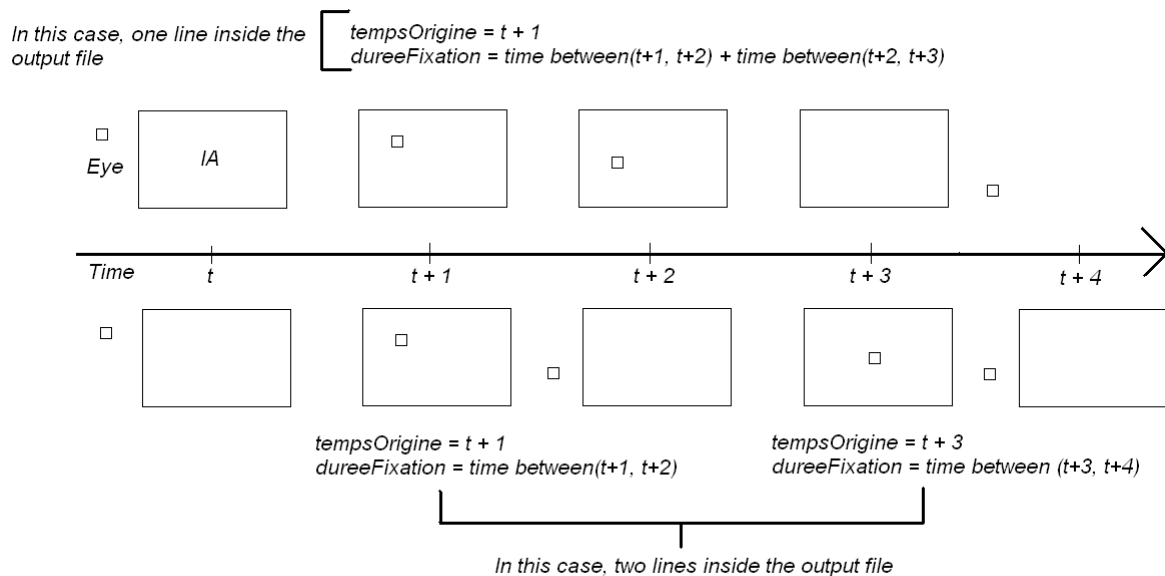


Figure 20 - Fixation time algorithm

2.3.3. Output file of the analysis software

At the end of the eye tracker data analysis process, the application has generated an output file containing all the areas of interest set during the experiment.

This file (Figure 21) specifies:

- *tempsOrigineOculoGMT*: to refer to the eye tracker input files. This gives the possibility to carry out offline cross comparisons.
- *tempsOrigine*: time since the beginning of the experiment. Value obtained from the simulator data.
- *noZone*: the number of the zone of interest. Remember, this number depends on the line number in the file "ZoneInteret.txt (the first line being number 0).
- *pas*: the step number in DR2's iterative loop. Also provides a reference to synchronise with respect to the .var file. Of interest mainly in relation to scenario data. With this, we may associate the simulation time and the experimentation timing (the position in scenario).
- *dureeFixation*: time during which the eye fixed the same IA without leaving this area.

tempsOrigineOculoGMT	tempsOrigine	noZone	dureeFixation	pas
10:42:41,945	00:00:03,197	0	0.036	69
10:42:44,527	00:00:05,785	0	0.090	189
10:42:49,695	00:00:13,849	0	0.090	497
10:42:51,527	00:00:16,858	0	0.016	594
10:42:52,062	00:00:17,392	0	0.018	626
10:42:52,195	00:00:17,512	0	0.021	634
10:42:53,878	00:00:20,725	0	0.035	736
10:42:53,945	00:00:20,805	0	0.016	739
10:42:57,992	00:00:27,853	0	0.117	983
10:42:58,894	00:00:28,901	1	0.139	1046
10:43:04,007	00:00:37,190	0	0.050	1346
10:43:07,890	00:00:43,743	0	0.085	1578
10:43:07,957	00:00:44,020	0	0.275	1586
10:43:15,589	00:00:56,575	0	0.019	2038
10:43:15,757	00:00:56,740	0	0.016	2048
10:43:16,324	00:00:57,374	0	0.034	2083
10:43:18,539	00:01:01,097	0	0.013	2214
10:43:18,871	00:01:02,000	0	0.056	2214

Figure 21 - Sample output of the eye tracker's data analysing tool

2.4. Operating mode

2.4.1. DR2 traffic simulation

In order to create DR2 playback files to be used in the eye tracker's replay mode, you have to request the creation of the following three files when launching your experiment:

- *res-mdv.bin*: recording the subject's actions on the controls (pedals, steering wheel, gearbox) so you can replay them later.
- *res-monde.bin*: traffic information
- *res-env.bin*: environmental information (time, ...)

These are binary files.

To generate these files, you have to tick "Enregistrement" as shown below:

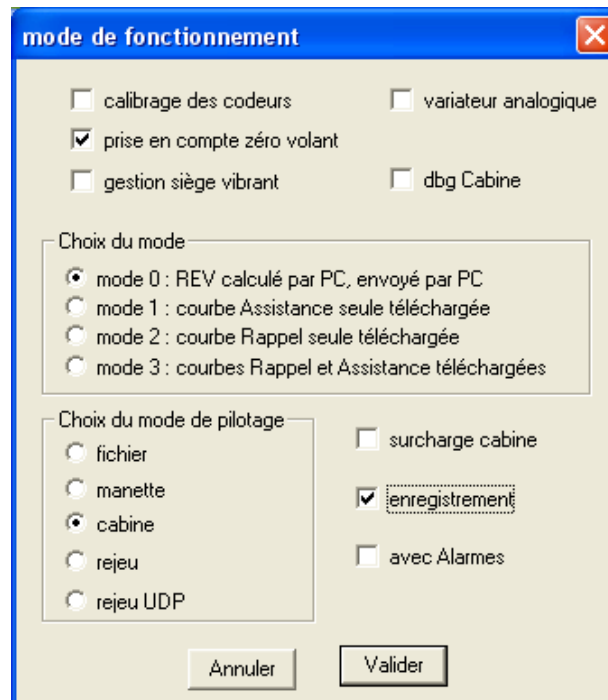


Figure 22 - Requestion the recording of playback data

When you want to obtain your output file with the fixation times on the different areas of interest, you must specify that you are in replay mode:

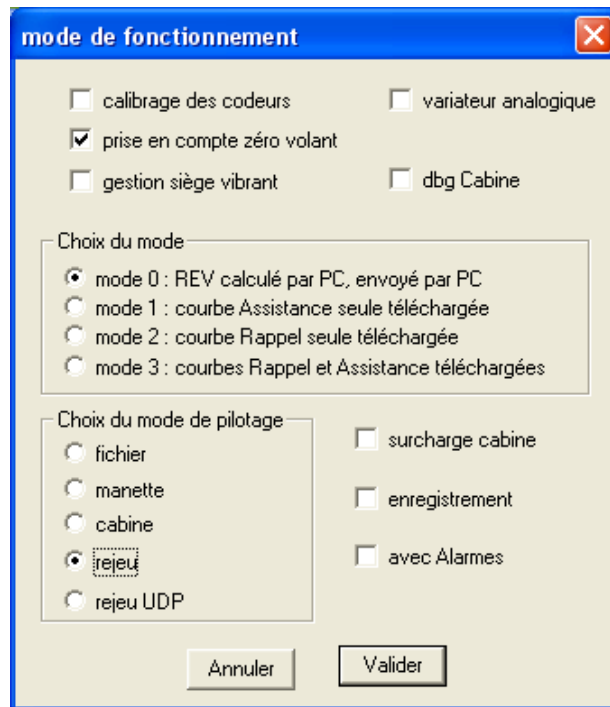


Figure 23 – Eye tracker's replay mode selection

2.4.2. SIM² driving simulator visual loop

To display the eye tracking mode in Sim² (all white with the ZI in shades of red) you have to modify the value of the "enregistrementOculo" option in the *info.simu* file as shown in figure 23.

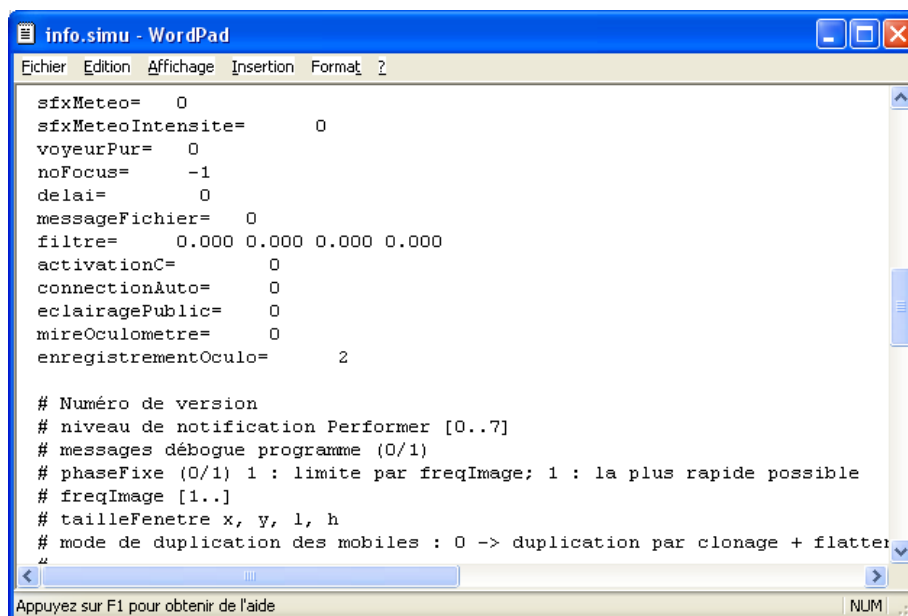


Figure 24 - Sample of the info.simu file set for eye tracker's replay mode

If this option is set to 0, you will obtain a standard, non-replay eye tracking display as shown below:

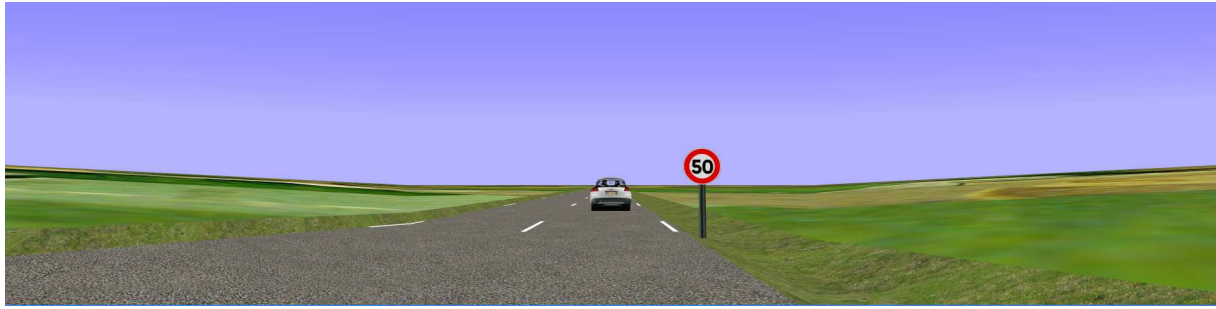


Figure 25 - Standard display during experimentation

If the option is set to 2, one obtains the eye tracker's replay mode:

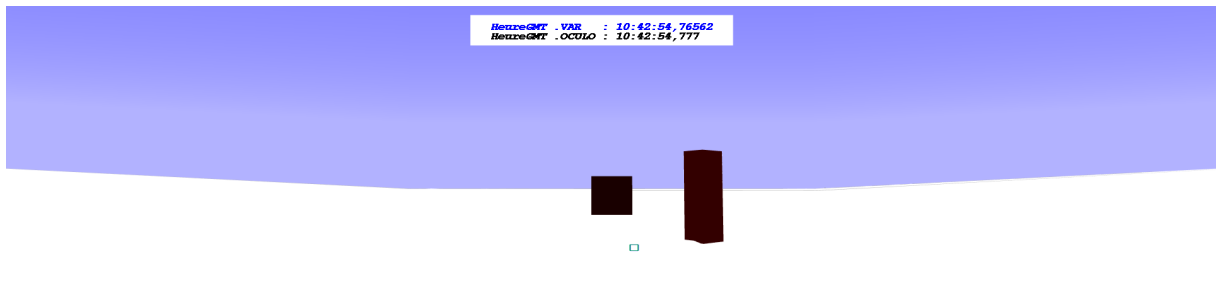


Figure 26 - Simplified view in the eye tracker's replay mode

2.5. Visual information

The software provides several visual indicators directly on the Sim² interface.

These are:

- *HeureGMT.var*: the GMT time obtained from the .var file generated by DR2.
- *HeureGMT.oculo*: the GMT time from the eyetracker.
- A cursor indicating the gaze.

Note: the difference between the GMT times should never exceed 16ms.

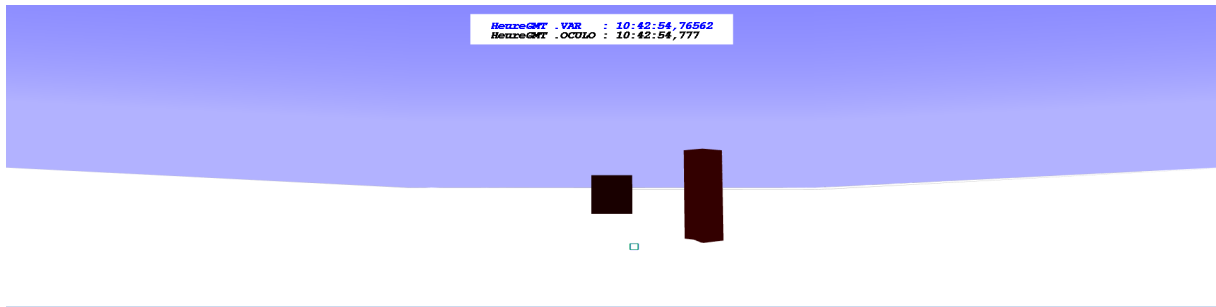


Figure 27 - Visual indicators in the simplified view

In order to configure the device in the best possible way, there is a possibility of adding an offset time between the timer of the DR2 and the eye tracking PCs. This allows compensating for a lack of synchronisation between the two clocks at the launch of the application in the eye tracker's replay mode.

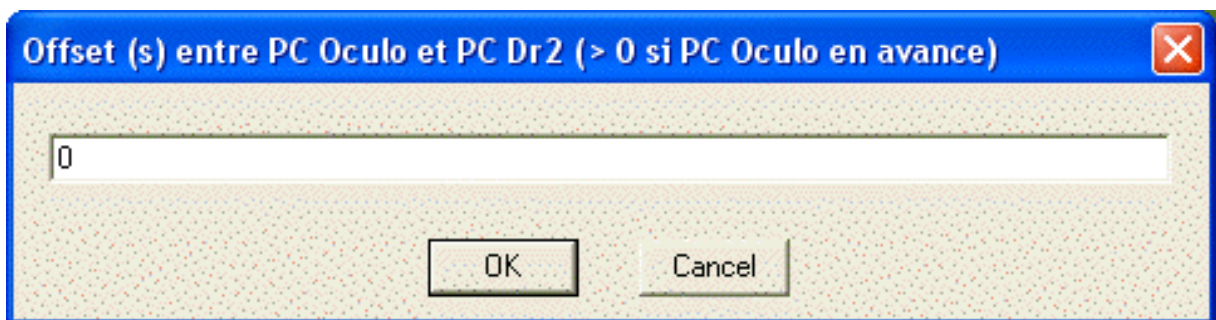


Figure 28 - Time offset specification when launching in eye tracker's replay mode

3. Conclusions

The aim of the 4.4 activities 3 was the design of a software tool for the automatization of eye tracker's data while used with the driving simulator. This activity has been conducted successfully and the software was "delivered" to researchers of WP5.2.

The method used for the automatization is a post treatment process, which allows researchers to analyse their recorded data and to easily change the interest areas. The areas may consist in either static or dynamic objects. The areas can be easily described using symbolic description or geometric faces. If the calibration of the eye tracker has been properly conducted, the software can be used in a reliable and efficient way.

The produced software has been designed for the INRETS SIM² class simulators and for French users (which are the users within 2BeSafe), but the method can be fairly easily adapted to other driving simulators as well as the man machine interface language.

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