

Mitsubishi Programmable Logic Controller MELSEG = Q DATA BOOK



MELSEG-



Opening up new possibilities for Factory Automation with more compact, faster and easier to use PLCs.



The assets accumulated for the A and QnA series can be utilized effectively for the Q series.



Oseries

Providing Individual Solutions

SPACE EFFICIENT

Having about 60% of the conventional AnS series mounting area, the ultracompact Q series contributes to equipment space saving......Refer to P. 1-1.

OPTIMIZED CONFIGURATION

Program capacity Max. 252k steps, 8192 points of I/O control, allowing optimal configuration of small to large scale systems......Refer to P. 1-3.

HIGH PERFORMANCE

1ms processing of 12k steps opens up possibilities for high performance and precision control......Refer to P. 1-2.

Improved debugging

A wide variety of functions designed for program design and debugging efficiency......Refer to P. 1-8.

USER FRIENDLY

Development and maintenance efficiency is improved with a user-friendly, comfortable Windows comprehensive environment......Refer to P. 1-7.

Providing Total Solutions

INFORMATION CONSOLIDATION

Easy network configuration and high-performance networking in response to computerization of production facilities......Refer to P. 1-5.

RELIABILITY

Reliable products and easy troubleshooting functions for decreased downtime......Refer to P. 1-4.

UTILIZATION

Ease of developing Q programs using the existing A/QnA programs. Use of the A mode facilitates enhanced performance of the AnS system......Refer to P. 1-9.

The Q series is available in two different modes of operation: the Q mode which uses the Q series' inherent functions and performance capabilities; and the A mode which uses the conventional AnS series' programs and hardware and is significantly enhanced in CPU processing capabilities. (Refer to P. 1-9.)

Unless otherwise specified, this data book introduces the Q mode features, which applicable may not be for A mode use.

NDEX

Features

Q mode

A mode

PC-related



GOT-A900

Appendices

INTRODUGTION



SPACE SAVING AND WIRING SAVING

To save machinery and equipment space and to reduce costs by decreased wiring processes, the Q series is smaller in its mounting area and has higher freedom of installation. It also has increased affinity with CC-Link, for easier use.

Mounting Area

The mounting area of the Q series is 60% smaller than that of the conventional compact model (AnS series).



CC-Link

Mounting Freedom

The Q series has a wide assortment of 5-, 8- and 12-slot bases. The freedom of mounting space allows reduction in the number of required bases.



Base unit types

Number of I/O Slots	Main Base	Extension Base	Mounting Size (mm(inch))
5	Q35B	Q65B	245(9.65)X98(3.86)
8	Q38B	Q68B	328(12.92)X98(3.86)
12	Q312B	Q612B	439(17.30)X98(3.86)

Note 1: The base units are designed for the Q series I/O, intelligent function and network modules. The AnS series modules cannot be loaded on the base units given in the above table.

The Q series has increased affinity with CC-Link, for easier use. Using the GPPW network setting screen, you can set the network parameters and the automatic refresh of the remote I/O signals to the CPU internal memory. In addition, you can make automatic setting of initial setting data to remote device stations, such as the analog-to-digital converter and highspeed counter, so that you can carry out programming without needing to be aware of the network.

Input form	iat HEX.	_	-								
Execute	Operational		Exec	utior	al conditio	n	Т	Detail	s of	execution	
Flag	condition		Conc	lition	Device	Exec	ute	Writ	е	Device	Write
			Dev	ice	Number	Condi	tion	Devi	се	Number	Data
Execute	Set new	-	RX	•	01	ON	-	BY	•	10	ON 🗖
Execute	Same as prev.set	-	RX	Ŧ	01	ON	-	RWw	•	05	0000
Execute	Same as prev.set	•	RX	•	01	ON	-	RWw	•	06	001/
Execute	Same as prev.set	•	RX	•	01	ON	-	RWw	•	07	00F
Execute	Same as prev.set	•	RX		01	ON	•	RWw	۳	08	003
Execute	Same as prev.set	•	RX		01	ON	•	RWw	۳	0A	001
Execute	Set new	•	SB	۳	02	OFF	•	BY	۳	11	ON 🔻
Execute	Set new	•		۳			•		۳		
Execute	Set new	•		۳			•		۳		
Execute	Set new	•		۳			•		۳		
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JNTRODUGTION



INCREASED PERFORMANCE AND ACCURACY OF FACILITIES

The Q series has significantly improved CPU operation processing speeds, e.g. achieved a scan time of 0.5ms in programs of approx. 4k steps and 1ms in programs of approx. 12k steps (Note 2). Also, with the addition of a cyclic execution program run system and a program start interrupt function from network/intelligent function module, the Q series has opened up possibilities for shortened machinery/equipment tact time and increased machining accuracy.

Operation Processing Speeds

The Q series high-speed type CPU has realized speeds as high as 34ns for basic instruction processing time of and a PC MIX value of 10.3 (Note 3). It is about 5 times faster in performance than the conventional model A2USHCPU-S1 and about 2.7 times faster than the Q2ASHCPU. In addition, it has dramatically increased floating-point operation speeds for PID and other arithmetic functions.





CPU operation processing speeds

Instruction	Q02CPU	Q02HCPU Q06HCPU Q12HCPU Q25HCPU
LD (LD X0)	79ns	34ns
OUT (OUT Y0)	158ns	68ns
Timer (OUT T0 K5)	632ns	272ns
Transfer (MOV D0 D1)	237ns	102ns
Addition (+ D0 D1)	395ns	170ns
Floating-point addition (E+)	1815ns	782ns
PC MIX value	4.4	10.3

Also, the END instruction processing time has been reduced greatly by the use of a multi-processor configuration which is made up of the control processor for program execution and the information processing processor for communication processing, etc.

Note 2: Scan time varies with the program contents and system configuration. The scan times given are values that can be achieved under given conditions.

Note 3: The PC MIX value is the average number of instructions such as the basic and data processing instructions executed in 1 µs. A larger value indicates a higher processing speed.

Adoption of High-Speed System Bus

The Q series high-speed system bus is 4 to 8 times faster than that of the conventional series, giving rapid I/O refresh and network data refresh. (Refer to P. 9.)

Cyclic Execution Program

A cyclic execution program is started and run at predetermined time intervals. High accuracy can be provided if you use this program in the processing of areas which will particularly influence machining accuracy. The cyclic time intervals can be set to 0.5ms-60s.



Variable Time Constant of Input Module

The DC input modules input response time can be changed. The response time can be chosen from among 1, 5, 10, 20

and 70ms according to your application.

Event Interrupt

A CPU interrupt program can be started from a network or intelligent function module. Using this function, fast response can be made to an event which occurs asynchronously with the program scan of the PLC, e.g. data receiving from a network or count value match of high-speed counter.





OPTIMUM SYSTEM CONFIGURATION

Production facility control grows more and more sophisticated. Also, it is necessary to process large volumes of production data, e.g. more precision production control, quality control, and recently, resources/energy control in consideration of global environment. To meet such needs, the Q series is designed to handle large volumes of programs and data.

Program Capacities

The Q series has a wide assortment of CPU modules having 28k-, 60k-, 124k- and 252k-step program capacities, enabling a selection of the CPU module which matches the machinery/equipment control capacity.

CPU	program	capacities	(steps)

Q02CPU Q02HCPU	28k
Q06HCPU	60k
Q12HCPU	124k
Q25HCPU	252k

Number of Control I/O Points and Number of I/O Modules

The Q series can control a maximum of I/O. 4096 points (max. 8192 points when used with a remote I/O network such as CC-Link)regardless of the CPU module type.

Up to 7 Extension Bases Connectable

Up to seven extension bases (eight bases including the main) can be connected to accept up to 64 modules. Also, the overall distance of extension cables is max. 13.2m(43.28feet), enabling high freedom of extension base layout.

Extended Memory

Each CPU module is equipped with a small PC card slot to accept extended memory of up to 32MB (when using the ATA card). By loading large-capacity extended memory, you can perform large-capacity file management, and comment settings for all data devices and past programs can be stored in memory as a correction history.







EASE OF MAINTENANCE

Needless to say, maintenance is essential to exhibit the inherent performance of machinery and equipment. However, as business areas increase and machinery and equipment are installed all over the world, it will be important to smoothly carry out on-the-spot maintenance. The Q series has functions to minimize this maintenance-related problem.

Remote Programming



Built-In ROM

To reduce the possibility of program data erasure due to battery failure, built-in flash ROMs are included in all CPU types so there is no need to add a memory card to store programs onto ROM.

System Monitoring

System monitoring gives you an at-a-glance error detection condition of each module in a PLC system. It supports restoration at occurrence of trouble.

ystem Mo Base Inform												
	ne Main B	sse						of Sloi of Inst	t alled M	odule	5 4	Overal Information Number of Base Number of Module
Installed sta	stus											Product information
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Parameter	status						-			_		
/0 Addr		20	40	60	80		<u> </u>	<u> </u>		<u> </u>		
,	0	1	2	3	4	-	<u> </u>	<u> </u>	<u> </u>	<u> </u>		
	llig ent	llig ent	llig ent	llig	16pt							Status Status Unit system em Unit error Unit warning
PLC di	iagnostics	Mo	idule's l	Detaile	d Inforr	nation.		Sta	t monite	a I	Stop monitor	Close

Output Modules Provided with Short-Circuit Protection

Some transistor output modules use transistors provided with short-circuit protection to protect output modules from being burnt out due to a wiring mistake or external device failure.

Intelligent Function Module Monitoring

You can confirm the operating status and error detection condition of an intelligent function module (Note 2) on a monitor screen. In addition, the intelligent function module is monitored via a CPU module, eliminating the need for separate cable connection.



Note 2: An intelligent function module is a generic term for special modules other than digital I/O such as analog-to-digital converter and high-speed counter. Note 3: The utility package corresponding to the intelligent function module is needed.

INTRODUGTION



COMPUTERIZATION

With the increase of demands for production control, quality control and resources/energy control, to say nothing of control data, there is a demand for rapid transmission of production information data between PLCs and between PLC and host monitoring/controlling system. The Q series has increased network data transmission speed and reinforced its tools to configure a network system more easily.

Communication Support Software Package

The communication support software package is a software tool for Windows for easy connection of a host monitoring/controlling Windows personal computer to the Q series (connection to QnA, A or FX series also possible). You can easily create a monitoring/control application in Visual Basic, Visual C++ or Excel, without being conscious of the different complicated communication protocols of Ethernet, MELSECNET/10, CC-Link, RS-232 serial communication or CPU programming port (RS-232 or USB).

Utilization of the Internet

The Q series Ethernet module has an e-mail communication function which utilizes the Internet. You can transfer production control information to/from anywhere in the world and configure a remote monitoring/control system easily.



Mail address + attached file

GOT Connection

The GOT-A900 series graphic operation terminal can be connected using a CPU RS-232 port or serial communication



module. By connection to the Q series high-speed bus, you can achieve a much, faster-response graphic operation terminal.

Automatic Notice from PLC

A serial communication module (RS-232/422) connected to a personal computer has a function to automatically send data from the PLC to the personal computer when a given condition holds. Also, on Ethernet, this function can be used for e-mail transmission. Use of this function permits rapid transmission of alarm occurrence information or the like without waiting for polling from the personal computer.



Network Parameter Setting

In the Q series, the network parameter setting screens for Ethernet, MELSECNET/10(H) and CC-Link are included in the GPP function software. Ethernet, CC-Link or other network setting which had to be made in sequence programs can be made on the screen, reducing programs and improving viewability of settings.

	Proto	ol	Open syste	m	Fixed buf	fer	Fixed buffer communication		Pairing Existence open confirmation		1	Self station Board No.	Destination IP address	Dest. Board No.	
1	TCP	•	Active	•	Send	٠	No procedure	۳	No pairs	٠	No confirm	Ŧ	0000		
2	TCP	-	Unpassive	-	Receive	Ŧ	Procedure exist	Ŧ	No pairs	Ŧ	Confirm	Ŧ		150. 0. 0. 15	
3	TCP	-	Fullpassive	-	Receive	•	Procedure exist	Ŧ	No pairs	•	No confirm	•		No Settings	100
4	UDP	•		•	Send	٠	No procedure	٠	No pairs	•	No confirm	•			
5	UDP	•		-	Receive	¥	Procedure exist	¥	No pairs	Ŧ	Confirm	Ŧ	2000	10. 99. 25.170	300
6		-		-		-		Ŧ		•		Ŧ			
7		•		-		•		٠		•		•			
8		٠		•		٠		٠		٠		Ŧ			
9		-		-		Ŧ		Ŧ		-		Ŧ			
10		-		-		•		Ŧ		•		•			
11		•		-		٠		٠		•		•			
12		•		•		٠		٠		٠		¥			
13		-		-		Ŧ		Ŧ		•		Ŧ			
14		-		-		•		•		•		•			
15		•		-		٠		۳		٠		Ŧ			
16		-		-		-		-		-		Ŧ			



COMPUTERIZATION

In the Q series, Ethernet, MELSECNET/10(H) and CC-Link are placed as open networks having performance capabilities and functions required for information network, controller network and field network, respectively, to meet the needs requested for facility control and production control networks.

Seamless Communication



Increased Communication Data Capacities

To respond to increasing information volumes, the Q series network has been increased in the volume of data that can be read/written by one time of communication.

Number of link relays (LB)/link registers (LW) points per network



Increased Data Communication Speed

The system bus has been increased in speed to shorten the total transmission time if communication data capacity increases. The data transfer speed between CPU module and network module is about 4 to 8 times higher than that of the conventional QnA series. This increased speed can minimize the influence of large-capacity data communication on the CPU scan time. However, communication speed of Ethernet, MELSECNET/10H and CC-Link have not been changed to maintain communication compatibility with the conventional series.



INTRODUGTION



EASE OF PLC USE

Enhanced functions of PLCs tend to make them less user-friendly. The Q series offers easier-to-use PLCs with Windows comprehensive environment.

Added-In Functions



Batch Monitoring of CPU and Intelligent Function Modules

The Q series has utility packages available for intelligent function modules such as analog-to-digital conversion units. Using the utility packages allows you to make function setting needed to use the functions of intelligent function modules on the screen, e.g. make analog-to-digital conversion enable/disable setting and the automatic refresh setting of analog-to-digital conversion data to CPU internal memory in an analog-to-digital converter module, thus removing the need for programs. Also, sequence programs and various intelligent function modules can be monitored/tested at the same time to improve the debugging of programs related to the intelligent function modules.





PROGRAM DEVELOPMENT/DEBUGGING EFFICIENCY IMPROVEMENT

Sophisticated machinery and equipment and increased program scale result in the increased number of program development processes. The Q series has inherited and developed the program structuring and standardizing techniques achieved by the QnA series, and has functions to suppress and further reduce the increase in the number of program development processes. Also, debugging-related functional performance has been improved to increase the debugging efficiency in the stage of adjusting machinery and equipment.

Program Structuring/Standardization

The Q series allows multiple programs made on a machinery/equipment operating function basis to be created and executed. The programs divided function-by-function can increase program utilizability and viewability. The Q series-compatible GPPW function software enables SFC programming which is more suitable for structuring and standardization, in addition to ladder and list programming.



Offline debugging (simulation)

The LLT (ladder logic test tool) is a personal computer software tool designed to start a virtual PLC on a simulate PLC operations and debug sequence programs. You can debug programs on a personal computer right after designing, without waiting for the completion of PLC I/O wiring.



Online Program Correction

During adjustment of machinery/equipment, partial correction to a program may sometimes be made without stopping PLC processing. The Q series enables online correction to a program (write during RUN) and there are no restrictions on the corrected program capacity. Online rewriting of a program file is also possible, exhibiting the high performance of program correction during adjustment.

Creation of User-Defined Instructions

The Q series allows a given program block to be defined and registered as a single instruction (macro instruction function). Definition/registration of an frequently used program block as a macro instruction increases program utilization efficiency. In addition, viewability is improved since the program read from the PLC is displayed as-in the defined macro instruction format.

Increased Speeds of Programming Ports

The Q series CPU modules are standard-equipped with a RS-232 port operable at max. 115.2kbps and a 12Mbps USB port installed in recent personal computers (Q02CPU is equipped with RS-232 only). These high-speed programming ports have achieved much shorter program transfer time and faster monitoring, increasing the efficiency of machinery/equipment adjustment.



Note: The time may be longer than above depending on the performance of the personal computer and the conditions of communication with other devices.

Password Function

Programs and data within the Q series CPU module can be protected by a password. This function is effective for prevention of program damage due to accidental operation or copying of specifically developed programming techniques included in the programs and data.

INTRODUGTION



UTILIZATION OF EXISTING ASSETS (COMPATIBILITY MAINTAINED)

We offer the customers who already use the A/QnA series PLCs with the means to utilize the assets of the A/QnA series and use the excellent functions and performance capabilities of the Q series.

Mode Selection

The Q series CPU is available in two different CPUs: one for Q mode and the other for A mode. Use the Q mode CPU to make the most of the performance capabilities and functions of the Q series, or the A mode CPU to use the hardware configuration of the conventional AnS series as-is and improve the performance of the CPU only.



QnA series

program

Note 1: Some modules for the AnS series, e.g. MELSECNET/II and MELSECNET/B, are not usable or have operating restrictions.

When Using Q Mode CPU

FX series

program

The Q mode CPU requires Q series (Q mode) programs. As a conversion tool is available to convert A/QnA series programs into Q series (Q mode) programs, transition to the Q series can be made easily without wasting your program assets. (Note 2) Note 2: Conversion into Q series programs is needed when you use the Q mode which makes the most of the Q series CPU functions. A series programs can be used as-is when you use the A mode.

A series

program

When Using A Mode CPU

Using the A mode CPU in the your current system, you can enhance the CPU performance easily.



Note 4: The RS-232/422 conversion cable FA-CNV2402CBL (0.2m(0.66feet)) or FA-CNV2405CBL (0.5m(1.64feet)) is available from Mitsubishi Electric Engineering Co., Ltd.

2. Q MODE

CONTENTS

1. OVERVIEW

Overview of Q Mode	2-1
Comparison between Q Mode and A Mode	2-2
Compatibility of Q Mode PLC with AnS/Q2AS	
2. MODEL SELECTION	
General Specifications	
Applicable Model List	2-5
• Q Mode CPU Modules: Q02CPU, Q02HCPU,	
Q06HCPU, Q12HCPU, Q25HCPU	
CPU Built-in Memories/Memory Cards	2-24
Network Overview	
• Ethernet: QJ71E71, QJ71E71-B2	
• MELSECNET/10H: QJ71LP21, QJ71BR11	2-43
MELSECNET/10H: A6BR10, A6BR10-DC	2-53
• CC-Link: QJ61BT11	
MELSECNET/MINI-S3: A1SJ71PT32-S3, A1SJ7	'1T32-
S3	2-66
MELSEC-I/O LINK: A1SJ51T64	2-68
• B/NET: A1SJ71B62-S3	2-69
JPCN-1 Field Network: A1SJ71J92-S3, A1SJ72	J95
	2-70
• S-LINK: A1SJ71SL92	2-71
Profibus-FMS/Profibus-DP interface: A1SJ71PB	96F
/A1SJ71PB92D	2-72
DeviceNet: A1SJ71DN91	2-73
Modbus interface: A1SJ71UC24-R2-S2/	
A1SJ71UC24-R4-S2	2-74
Intelligent Communication: A1SD51S	2-75
ID Interface: A1SJ71ID1-R4, A1SJ71ID2-R4,	
A1SD32ID1, A1SD32ID2	2-76
 Serial Communication Modules: QJ71C24, 	
QJ71C24-R2	2-77

Utility Package for Serial Communication Modules:
SW0D5C-QSCU-E2-83
• I/O Modules2-85
Input Modules
Output Modules2-93
 Analog-to-Digital Conversion Modules: Q64AD,
Q68ADV, Q68ADI2-100
 Utility Package for Analog-to-Digital Conversion
Modules: SW0D5C-QADU-E2-103
Digital-to-Analog Conversion Modules: Q62DA, Q64DA
 Utility Package for Digital-to-Analog Conversion
Modules: SW0D5C-QDAU-E2-107
High-Speed Counter Modules: QD62, QD62E, QD62D
 Utility Package for High-Speed Counter Modules:
SW0D5C-QCTU-E
 Positioning Module: QD75P1, QD75P2, QD75P4,
QD75D1, QD75D2, QD75D4 2-115
Positioning Module Software: SW0D5C-QD75P-E.2-123
Current Consumption Calculation2-125
• Power Supply Modules: Q61P-A1, Q61P-A2, A1S61PN,
A1S62PN, A1S63P2-126
• Base Units: Q3 🗌 B, Q6 🗌 B, QA1S6 🗌 B 2-129
Accessories: Batteries, Cables, Connectors
• External Dimensions 2-136
3. PROGRAMMING
Sequence Programs
Network Setting: SW5D5C-GPPW-E
• Data Conversion Software: SW0D5C-CNVW-E 2-160
Peripheral Devices2-161
4. SIMULATION/DEBUGGING FUNCTIONS
Sequence Program Simulation

Overview of Q Mode

The Q series CPU modules are available in either Q mode and A mode products, which offers a wide selection of products for different purposes.

The Q series has been developed to be higher in performance and easier to use while simultaneously having the heritage of MELSEC's programming capabilities, network capabilities, various functions and operation procedures. The Q mode is designed to exhibit the inherent functions and performance capabilities of the Q series. It can improve functions and performance capabilities in the whole PLC system including not only the CPU but also the I/O and network modules and various intelligent function modules.

The A mode is designed to merely improve the performance capabilities of the CPU for users with AnS PLC. With the A mode, only the CPU modules, base units and extension base cables need to be changed in a current AnS series system. The other modules and programs can be used as they are, the new CPU brings about an increase in the CPU processing speed and program capacity.

OVERVIEW

Comparison between Q Mode and A Mode

Comparison between Q Mode and A Mode

	QN	Node	A Mode				
CPU type	Q02CPU, Q02HCPU,Q06HCF	PU, Q12HCPU,Q25HCPU	Q02CPU-A, Q02HCPU	J-A, Q06HCPU-A			
Available functions, modules	**						
Program	Inherits the basic programming methods of MELSEC. Howeve codes, A/AnS/QnA/Q2AS prog conversion into Q mode.	er, because of different internal	Programs for the current AnS series				
Function	Functions given in the "Feature are usable.	es" Chapter of this data book	Basically, there are only functions that are usable with the AnS series though some specifications have been expanded in performance. For expanded specifications, refer to the Chapter for the A mode.				
I/O, special modules	For Q series and AnS series A6SIM-X64Y64 cannot be use	ed.	For AnS series A6SIM-X64Y64 canno	t be used.			
Base unit	For loading Q series modules: For loading AnS series module		For loading AnS series	s modules: QA1S3 B, QA1S6 B			
Extension cable	QC B		QC B				
Power supply module	For loading into Q series base For loading into AnS series ba		A1S6 P				
Connectable networks			•				
Ethernet	Allowed		Allowed				
MELSECNET/10H	Allowed		Disallowed				
(Inter-PC network)							
MELSECNET/10	Allowed		Allowed				
(Inter-PC network)							
MELSECNET/10	Disallowed		Allowed				
(Remote I/O network) MELSECNET/II	Disallowed		Allowed				
MELSECNET/B	Disallowed		Allowed				
CC-Link	Allowed (with automatic refres	h parameter setting)	Allowed (without autor	natic refresh parameter setting)			
MELSECNET/MINI-S3	Allowed (without automatic ref			ic refresh parameter setting)			
RS-232/422/485	Allowed	room parameter ootanig,	Allowed	io forfoor paramotor ootting,			
Other networks	Same as the networks compati	tible with AnS series		compatible with AnS series			
Usable peripheral devices ar							
Windows personal computer	Allowed	SW4D5C-GPPW-E or later	Allowed	SW2D5C/F-GPPW-E or later (Note 1)			
DOS/V (DOS)	Disallowed	•	Allowed	SW2IVD-GPPA-E or later (Note 1)			
A6GPP/HGP/PHP	Disallowed		Allowed	SW3GP-GPPAEE or later (Note 1)			
Usable GOTs and connection	n method						
Usable GOT	GOT-A900		GOT-A900/800				
Software	SW2D5C-GOTRE-PACK vers	ion C or later	SW1D5C-GOTRE-PA later	CK or later, SW0NIW-A8GOTP or			
Bus connection	Allowed		Disallowed				
CPU RS-232 port connection	Allowed (ladder monitor will be	e supported soon)	Allowed (ladder monito	pr possible)			
CPU USB port connection	Allowed		Disallowed				
Serial communication (RS-232/422)	Allowed (ladder monitor will be	e supported soon)	Allowed (ladder monito	or possible)			
MELSECNET/10	Allowed (ladder monitor will be	supported soon)	Allowed (ladder monito	or possible)			
MELSECNET/II	Disallowed		Allowed (ladder monito				
MELSECNET/B	Disallowed		Allowed (ladder monito				
CC-Link	Allowed (ladder monitor will be		Allowed (ladder monito				

Note 1: Depending on the software version, there are restrictions on the program capacities, CPU internal device capacities, etc. For details, refer to Programming, A MODE.

Note 2: The above table gives general usability and connectability for comparison of the Q mode and A mode. Since there may be restrictions on usable/connectable products, always check details in the applicable model list and corresponding model explanation sections.

Compatibility of Q Mode PLC with AnS/Q2AS

The following table indicates the compatibility between Q mode PLC programs and AnS/Q2AS series programs. Note that the following table gives general information only and details should be checked in the corresponding module explanation sections.

lte	em	Compatibility with AnS	Compatibility with Q2AS
General pro	gram	Programs upwardly compatible with AnS. Can be used after conversion into Q program by GPPW software.	Programs upwardly compatible with Q2AS. Can be used after conversion into Q program by GPPW software.
Ethernet	Host system side program	Compatible. Note that sequence program accessing programs need corrections.	Compatible. Note that sequence programs and other file accessing programs need corrections.
	PLC side	Incompatible.	Compatible.
MELSECNE	T/10	Compatible in LB/LW/LX/LY/SB/SW assignment. Compatible in MELSECNET/10 dedicated instructions.	Compatible in LB/LW/LX/LY/SB/SW assignment. Compatible in MELSECNET/10 dedicated instructions.
CC-Link		Compatible in sequence programs.	Compatible in sequence programs.
Serial communic ation	Host system side program	Compatible. Note that sequence program accessing programs need corrections.	Compatible. Note that sequence programs and other file accessing programs need corrections.
	PLC side	Incompatible.	Compatible.

Note: If there is program compatibility, some of the instructions, e.g. special and network module dedicated instructions, have been deleted in Q or changed in specifications. For full information, refer to the "Programming" section.



General Specifications

General Specifications

General specifications indicate the specifications of the environment where these products can be installed and operated. Unless otherwise exceptional specifications are indicated, the general specifications apply to all Q series products. Install and operate the Q series products in the environment given in the general specifications.

Item			Specifications								
Operating ambient temperature	0 to 55 °C										
Storage ambient temperature	-25 to 75 °C (Note 5	-25 to 75 °C (Note 5)									
Operating ambient humidity	5 to 95%RH, non-co	5 to 95%RH, non-condensing (Note 4)									
Storage ambient humidity	5 to 95%RH, non-co	5 to 95%RH, non-condensing (Note 4)									
Vibration resistance	Conforming to JIS	Under intermittent vi	bration		Sweep count						
	B 3502, IEC	Frequency	Acceleration	Amplitude	10 times each in X,						
	61131-2	10 to 57Hz	_	_	Y, Z directions (for 80 min.)						
		57 to 150Hz	9.8m/s ²	_	50 mm.)						
		Under continuous vi									
		Frequency	Acceleration	Amplitude							
		10 to 57Hz	0.035mm (0.001inch)								
		57 to 150Hz	4.9m/s ²	—							
Shock resistance	Conforming to JIS B	3502, IEC 61131-2 14	17 m/s ² , 3 times in each	n of 3 directions X, Y	, Z						
Operating atmosphere	No corrosive gases										
Operating altitude	2000m (6557.38ft.) ı	max. (Note 3)									
Installation location	Inside control panel										
Overvoltage category (Note 1)	II or less										
Pollution level (Note 2)	2 or less										

Note 1: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises. Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

Note 2: This index indicates the degree to which conductive material is generated in the environment where the equipment is used. In pollution level 2, only non-conductive pollution occurs but temporary conductivity may be produced due to condensation.

Note 3: The PLC cannot be used under pressure higher than the atmospheric pressure of altitude 0m (0ft.). Doing so may cause a failure.

Note 4: When used with the AnS series modules, the Q series PLC should be operated within 10 to 90%RH.

Note 5: When used with the AnS series modules, the Q series PLC should be stored at -20 to 75 $^\circ\text{C}$.

Overview

The following applicable model list gives models usable with the Q mode. Note that the AnS series modules are also available for the Q mode but there may be functional restrictions. Also, among Q series network-related modules, there may be restrictions on the number of modules loaded.

the table. For details of restrictions, refer to the corresponding module specification explanation sections. The following applicable model list provides only the modules loaded to base units. Accessories and others which are not directly connected to the base units, e.g. optional connectors, are given in the model list at the end of this manual.

Whether the modules are restricted or not is indicated in

Applicable Model List

Product	Туре	Description	Number of Points Occupied [I/O Allocation]	Cur Consum 5VDC	rent ption (A) 24VDC	Remarks
CPU module	Q02CPU	Program capacity: 28k steps, number of I/O points: 4096 points, basic instruction processing speed: 79ns		0.60	_	
	Q02HCPU	Program capacity: 28k steps, number of I/O points: 4096 points, basic instruction processing speed: 34ns	_	0.64	_	
	Q06HCPU	Program capacity: 60k steps, number of I/O points: 4096 points, basic instruction processing speed: 34ns	_	0.64		
	Q12HCPU	Program capacity: 124k steps, number of I/O points: 4096 points, basic instruction processing speed: 34ns	_	0.64	_	
	Q25HCPU	Program capacity: 252k steps, number of I/O points: 4096 points, basic instruction processing speed: 34ns	_	0.64	—	
Memory card	Q2MEM-1MBS	SRAM card: 1M bytes	_	0.150	_	
•	Q2MEM-2MBF	Flash card: 2M bytes	_	0.130	_	
	Q2MEM-4MBF	Flash card: 4M bytes	_	0.130	_	
	Q2MEM-8MBA	ATA card: 8M bytes	_	0.054	_	
	Q2MEM-16MBA	ATA card: 16M bytes	—	0.054	—	
	Q2MEM-32MBA	ATA card: 32M bytes		0.054	—	
Battery	Q6BAT	Battery for program memory, standard RAM	—	—	—	

When using Q3 □ B, Q6 □ B base unit (For details of whether there are restrictions or not, refer to the next section "System Configuration".)

Product	Туре	Description	Number of Points Occupied [I/O Allocation]		rrent ption (A) 24VDC	Restrictions
Main base unit	Q33B	Q series module loading base For power supply + CPU + 3 slots	—	0.105	—	No
	Q35B	Q series module loading base For power supply + CPU + 5 slots	—	0.110	-	No
	Q38B	Q series module loading base For power supply + CPU + 8 slots	_	0.114	-	No
	Q312B	Q series module loading base For power supply + CPU + 12 slots	—	0.121	—	No

MODEL SELECTION

Applicable Model List

When using Q3 the next section		base unit (For details of whe guration".)	ether there are	e restrie	ctions c	or not, refer to
Product	Туре	Description	Number of Points Occupied [I/O Allocation]	Consum	ption (A)	Restrictions
Extension base unit	Q63B	Q series module loading base For power supply + 5 slots		5VDC 0.105	24VDC —	No
	Q65B	Q series module loading base For power supply + 5 slots	—	0.110	—	No
	Q68B	Q series module loading base For power supply + 8 slots	—	0.114	—	No
	Q612B	Q series module loading base For power supply + 12 slots	_	0.121		No

■ When using Q3 □ B, Q6 □ B base unit (F	or details of whether there are restrictions or not, refer to
the next section "System Configuration".)	

	QODE	Q series module loading base		0.110		INO
		For power supply + 5 slots				
	Q68B	Q series module loading base	—	0.114	—	No
		For power supply + 8 slots				
	Q612B	Q series module loading base	—	0.121	—	No
		For power supply + 12 slots				
Extension cable	QC06B	0.6m (1.97ft.) cable for extension base			—	No
	QC12B	1.2m (3.93 ft.) cable for extension base	_	—	—	No
	QC30B	3m (9.84 ft.) cable for extension base	—	—	—	No
	QC50B	5m (16.39 ft.) cable for extension bas	_		_	No
	QC100B	10m (32.79 ft.) cable for extension	_	_	_	No
		base				
Power supply module	Q61P-A1	Power supply for Q3 B/Q6 B,				No
,		100-120VAC, 5VDC 6A output				
	Q61P-A2	Power supply for Q3 B/Q6 B,	_			No
	QUIT //2					NO
la a vita a a alvela	01/40	200-240VAC, 5VDC 6A output	40 [40-+ V]	0.050		NI-
Input module	QX10	16-point 120VAC input module	16 [16pt X]	0.050	—	No
	QX40	16-point 24VDC positive common	16 [16pt X]	0.050		No
	QX41	32-point 24VDC positive common	32 [32pt X]	0.075		No
	QX42	64-point 24VDC positive common	64 [64pt X]	0.090		No
	QX80	16-point 24VDC negative common	16 [16pt X]	0.050	—	No
	QX81	32-point 24VDC negative common	32 [32pt X]	0.075	—	No
Output module	QY10	16-point relay contact output module	16 [16pt Y]	0.430	—	No
	QY40P	16-point 12/24VDC transistor (sink)	16 [16pt Y]	0.065	0.010	No
	QY41P	32-point 12/24VDC transistor (sink)	32 [32pt Y]	0.105	0.020	No
	QY42P	64-point 12/24VDC transistor (sink)	64 [64pt Y]	0.150	0.040	No
	QY50	16-point 12/24VDC transistor (sink)	16 [16pt Y]	0.080	0.020	No
	QY80	16-point 12/24VDC transistor (source)	16 [16pt Y]	0.080	0.020	No
	QY81P	32-point 12/24VDC transistor (source)	32 [32pt Y]	0.095	0.020	No
Blank module	QG60	Dustproof module for unused slot	16 [16pt S]	0.000		No
MELSECNET/10H module	Q300 QJ71LP21	Duplex optical loop (control station,	32 [32pt F]	0.55		Yes
MELSECINE I/ TOH MODUle		normal station)				
	QJ71BR11	Coaxial bus (control station, normal station)	32 [32pt F]	0.75	—	Yes
Ethernet module	QJ71E71	Ethernet interface module (10BASE-T,	32 [32pt F]	0.80		Yes
	GOTIET	10BASE5)	02 [02pt 1]	0.00		105
	QJ71E71-B2	Ethernet interface module (10BASE2)	32 [32pt F]	0.80	_	Yes
Serial communication	QJ71C24	RS-232, RS-422/485, 1 channel each	32 [32pt F]	0.00	_	No
Senar communication	QJ71C24-R2	RS-232, 2 channels	32 [32pt F]	0.20		No
CC-Link module	QJ61BT11	Master station, local station	32 [32pt F]	0.46		Yes
Analog/digital conversion module	Q64AD	Analog input (voltage, current), 4 channels	16 [16pt F]	0.630	—	No
	Q68ADV	Analog input (voltage), 8 channels	16 [16pt F]	0.640		No
	Q68ADI	Analog input (current), 8 channels	16 [16pt F]	0.640	_	No
Digital/analog conversion	Q62DA	Analog output, 2 channels (voltage,	16 [16pt F]	0.330	0.125	No
module	QOZDA	current)	io [iopt F]	0.330	0.125	NO
module	Q64DA	Analog output, 4 channels (voltage,	16 [16pt F]	0.345	0.180	No
	Q64DA	current)		0.345	0.180	INO
High-speed counter module	QD62		46 [46 pt []	0.30	┣────┣─	No
nigh-speed counter module		DC input sink output	16 [16pt F]			
	QD62E	DC input source output	16 [16pt F]	0.33		No
	QD62D	Differential input sink output	16 [16pt F]	0.38		No
Positioning module	QD75P1	Pulse train open collector output, 1 axis	32 [32pt F]	0.40		No
	QD75P2	Pulse train open collector output, 2 axes	32 [32pt F]	0.46	—	No
	QD75P4	Pulse train open collector output, 4 axes	32 [32pt F]	0.58	—	No
	QD75D1	Pulse train differential output, 1 axis	32 [32pt F]	0.52	_	No
	QD75D2	Pulse train differential output, 2 axes	32 [32pt F]	0.56		No
	QD75D4	Pulse train differential output, 4 axes	32 [32pt F]	0.82	┌───┟	No

Note: The "positive common" input module is used by applying a positive \oplus voltage to the common terminal, and the "negative common" input module is used by applying a negative \bigcirc voltage to the common terminal.



■ When using QA1S6 □ B base unit (For details of whether there are restrictions or not, refer to the next section "System Configuration".)

Product	Type Description	Number of Points Occupied	Current Consumption (A)		Restrictions	
	туре	Description	[I/O Allocation]	5VDC	24VDC	Restrictions
Extension base	QA1S65B	AnS series module loading base, for		0.117	—	No
	QA1S68B	power supply + 5 slots AnS series module loading base, for		0.118	_	No
Extension cable	QC06B	power supply + 8 slots				No
	QC12B	0.6m (1.97ft.) cable for extension base				No
	QC30B	1.2m (3.93 ft.) cable for extension base				
	QC50B	3m (9.84 ft.) cable for extension base	—			No No
	QC100B	5m (16.39 ft.) cable for extension bas 10m (32.79 ft.) cable for extension		_	_	No
Power supply module	A1S61PN	base Power supply for QA1S6 B, 100- 240VAC, 5VDC 5A output			-	No
	A1S62PN	Power supply for QA1S6 B, 100- 200VAC, 5VDC 3A/24VDC 0.6A output	_	—	-	No
	A1S63P	Power supply for QA1S6 B, 24VDC, 5VDC 5A output		—	-	No
AC input module	A1SX10	100-120VAC, 16 input points, terminal block	16 [16pt X]	0.050	-	No
	A1SX10EU	100-120VAC, 16 input points, terminal block	16 [16pt X]	0.050		No
	A1SX20	200-240VAC, 16 input points, terminal block	16 [16pt X]	0.050		No
	A1SX20EU	200-240VAC, 16 input points, terminal block	16 [16pt X]	0.050	—	No
DC/AC input module	A1SX30	12/24VDC, 12/24VAC, 16 input points, terminal block	16 [16pt X]	0.050	—	No
DC input module	A1SX40	12/24VDC, 16 input points, terminal block (sink)	16 [16pt X]	0.050	—	No
	A1SX40-S1	24VDC, 16 input points, terminal block, for high-speed input (sink)	16 [16pt X]	0.050	—	No
	A1SX40-S2	24VDC, 16 input points, terminal block, for high leakage current sensor (sink)	16 [16pt X]	0.050	—	No
	A1SX41	12/24VDC, 32 input points, connector (sink)	32 [32pt X]	0.080	—	No
	A1SX41-S1	24VDC, 32 input points, connector, for high-speed input (sink)	32 [32pt X]	0.120	—	No
	A1SX41-S2	24VDC, 32 input points, connector, for high leakage current sensor (sink)	32 [32pt X]	0.080	—	No
	A1SX42	12/24VDC, 64 input points, connector (sink)	64 [64pt X]	0.090	—	No
	A1SX42-S1	24VDC, 64 input points, connector, for high-speed input (sink)	64 [64pt X]	0.160	—	No
	A1SX42-S2	24VDC, 64 input points, connector, for high leakage current sensor (sink)	64 [64pt X]	0.090	—	No
	A1SX42X	12/24VDC dynamic, 64 input points, connector (sink)	64 [64pt X]	0.080	—	No
	A1SX71	5/12VDC, 32 input points, connector (sink)	32 [32pt X]	0.075		No
Ą	A1SX80	24VDC, 16 input points, terminal block, for high-speed input (sink/source)	16 [16pt X]	0.050		No
	A1SX80-S1	24VDC, 16 input points, terminal block, for high-speed input (sink/source)	16 [16pt X]	0.050	—	No
	A1SX80-S2	24VDC, 16 input points, terminal block, for high leakage current sensor (sink/source)	16 [16pt X]	0.050		No
	A1SX81	12/24VDC, 32 input points, connector (sink/source)	32 [32pt X]	0.080	—	No
	A1SX81-S2	24VDC, 32 input points, connector, for high leakage current sensor (sink/source)	32 [32pt X]	0.080	—	No
	A1SX81-S1	24VDC, 64 input points, connector (sink/source)	64 [64pt X]	0.16	-	No



■ When using QA1S6 □ B base unit (For details of whether there are restrictions or not, refer to the next section "System Configuration".)

Product	Turpo Description	Description	Number of Points	Current Consumption (A)		Restrictions
Product	Туре	Description	Occupied [I/O Allocation]	5VDC	24VDC	Restrictions
Contact output module	A1SY10	240VAC/24VDC 2A, 16 output points,	16 [16pt Y]	0.120	0.090	No
	A1SY10EU	terminal block 240VAC/24VDC 2A, 16 output points, terminal block	16 [16pt Y]	0.120	0.090	No
	A1SY14EU	240VAC/24VDC 2A, 12 output points, terminal block	12 [16pt Y]	0.120	0.100	No
	A1SY18A	240VAC/24VDC 2A, 8 independent contact output points, terminal block	8 [16pt Y]	0.240	0.075	No
	A1SY18EU	240VAC/24VDC 2A, 8 output points, terminal block	8 [16pt Y]	0.240	0.075	No
Triac output module	A1SY22	100-240VAC 0.6A, 16 output points	16 [16pt Y]	0.270	0.002	No
	A1SY28A	100-240VAC 1A, 8 output points, all points independent	8 [16pt Y]	0.130	—	No
	A1SY28EU	100-240VAC 0.6A, 8 output points, all points independent	8 [16pt Y]	0.270	—	No
Transistor output module	A1SY40	12/24VDC 0.1A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.270	0.016	No
	A1SY41	12/24VDC 0.1A, 32 output points, terminal block, with fuse (sink)	32 [32pt Y]	0.500	0.008	No
	A1SY42	12/24VDC 0.1A, 64 output points, terminal block, with fuse (sink)	64 [64pt Y]	0.930	0.016	No
	A1S42Y	12/24VDC dynamic, 64 output points, connector, with fuse (sink)	64 [64pt Y]	0.100	0.008	No
	A1SY50	12/24VDC 0.5A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.120	0.120	No
	A1SY60	24VDC 2A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.120	0.030	No
	A1SY60E	5/12/24VDC 2A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.200	0.020	No
	A1SY68A	5/12/24/48VDC 2A, 8 output points (independent common), terminal block	16 [16pt Y]	0.11	—	No
	A1SY71	5/12VDC, 32 output points, 16mA, connector, with fuse	32 [32pt Y]	0.400	—	No
	A1SY80	12/24VDC 0.8A, 16 output points, terminal block, with fuse (source)	16 [16pt Y]	0.120	0.040	No
	A1SY81	12/24VDC 0.1A, 32 output points, connector, with fuse (source)	32 [32pt Y]	0.500	0.008	No
	A1SY81EP	12/24VDC 0.1A, 32 output points, connector (with short-circuit protection)	32 [32pt Y]	0.500	0.160	No
	A1SY82	12/24VDC, 64 output points, connector (source)	64 [64pt Y]	0.930	0.016	No
/O composite module	A1SH42	12/24VDC, 32 input points, transistor 0.1A, 32 output points	32 [32pt Y]	0.500	0.008	No
	A1SH48-S1	24VDC, 32 input points, transistor 0.1A, 32 output points	32 [32pt Y]	0.500	0.008	No
	A1SX48Y58	24VDC, 8 input points, transistor 0.5A, 8 output points, terminal block	16 [16pt Y]	0.060	0.060	No
	A1SX48Y18	24VDC, 8 input points, 2A contact, 8 output points, terminal block	16 [16pt Y]	0.085	0.045	No
High-speed counter	A1SD61 A1SD62	High-speed counter	32 [32pt F]	0.35		Yes Yes
	A1SD62 A1SD62D	DC input sink output type Differential input sink output type (preset DC input)	32 [32pt F] 32 [32pt F]	0.14 0.25		Yes
	A1SD62D-S1	Differential input sink output type (preset differential input)	32 [32pt F]	0.25	-	Yes
	A1SD62E	DC input source output type	32 [32pt F]	0.14	┼╂	Yes
Analog-to-digital converter	A1S64AD	Analog input, 4 channels	32 [32pt F]	0.40	_	No
module	A1S68AD	Analog input, 8 channels	32 [32pt F]	0.40	-	No
Digital-to-analog converter	A1S62DA	Analog output, 2 channels	32 [32pt F]	0.80	_	No
module	A1S68DAV	0 to 10V, analog output, 8 channels	32 [32pt F]	0.65		No
	A1S68DAI	0 to 20mA, analog output, 8 channels	32 [32pt F]	0.85		No



■ When using QA1S6 □ B base unit (For details of whether there are restrictions or not, refer to the next section "System Configuration".)

	Type Description		Number of Points	Current		Destrictions
Product		Description	Occupied		ption (A)	Restrictions
-	44000000		[I/O Allocation]	5VDC	24VDC	
Temperature-digital converter module	A1S62RD3	Pt100 (3 wire type) input, 2 channels	32 [32pt F]	0.54	_	No
	A1S62RD4	Pt100 (4 wire type) input, 2 channels	32 [32pt F]	0.44		No
	A1S68TD	Thermocouple input, 8 channels	32 [32pt F]	0.32		No
Analog I/O module	A1S63ADA	Analog input 2 channels, analog output 1 channel	32 [32pt F]	0.80	-	No
	A1S66ADA	Analog input 4 channels, analog output 2 channels	64 [64pt F]	0.16	—	No
Temperature control module	A1S64TCTT-S1	Thermocouple input, 4 channels	32 [32pt F]	0.42	—	No
	A1S64TCTTBW- S1	Thermocouple input, 4 channels, with heater wire breakage detection function	32 [32pt F]	0.42	—	No
	A1S64TCRT-S1	Pt100 input, 4 channels	32 [32pt F]	0.42	_	No
	A1S64TCRTBW- S1	Pt100 input, 4 channels, with heater wire breakage detection function	32 [32pt F]	0.42	—	No
	A1S62TCTT-S2	Thermocouple input, 2 channels	32 [32pt F]	0.28	_	No
	A1S62TCTTBW- S2	Thermocouple input, 2 channels, with heater wire breakage detection function	32 [32pt F]	0.28	—	No
	A1S62TCRT-S2	Pt100 input, 2 channels	32 [32pt F]	0.28	_	No
	A1S62TCRTBW- S2	Pt100 input, 2 channels, with heater wire breakage detection function	32 [32pt F]	0.28	—	No
Pulse catch	A1SP60	Pulse catch input	16 [16pt Y]	0.055	_	No
Analog timer	A1ST60	8 timer points	16 [16pt Y]	0.055	_	No
Interrupt module	A1SI61	Interrupt input, 16 points	32 [32pt F]	0.057	—	Yes
Positioning module	A1SD70	Analog output, 1 axis	48 [first half 16pt	0.30		No
	A1SD71-S2	Pulse train output, 2 axes	S, latter half 32pt	0.80		No
	A1SD71-S7	Pulse output, 2 axes, manual pulse generator usable	F]	0.80	—	No
	A1SD75M1	SSC network compatible, 1 axis	32 [32pt F]	0.70	—	Yes
	A1SD75M2	SSC network compatible, 2 axes				
	A1SD75M3	SSC network compatible, 3 axes				
	A1SD75P1-S3	Pulse train output, 1 axis	32 [32pt F]	0.70	—	Yes
	A1SD75P2-S3	Pulse train output, 2 axes				
	A1SD75P3-S3	Pulse train output, 3 axes				
	A1SD774M	4 axes, motion control module	32 [32pt F]	0.90	—	No
MELSECNET/MINI-S3 master module	A1SJ71PT32-S3	Master module for optical/twisted pair cables	32/48 [32/48pt F]	0.35	—	Yes
	A1S71T32-S3	Master module for twisted pair cables only		0.30	-	Yes
Intelligent communication	A1SD51S	BASIC program module	32 [32pt F]	0.40	_	Yes
Position detection module	A1S62LS	Absolute position detection by dedicated sensor	32 [32pt F]	0.55	-	No
PLC diagnostic module	A1SS91	PLC diagnostic module	16 [16pt Y]	0.080	_	No
Memory card module	A1SD59J-S2	Memory card interface module	32 [32pt F]	0.05 (Note		No
				1)		



■ When using QA1S6 □ B base unit (For details of whether there are restrictions or not, refer to the next section "System Configuration".)

Product	Туре	Description	Number of Points Occupied [I/O Allocation]		rent ption (A) 24VDC	Restrictions
ID interface module	A1SJ71ID1-R4	1 connectable reader/writer		0.25	24VDC	Yes
ID Interface module	A1SJ71ID1-R4	2 connectable readers/writers	32 [32pt F]	0.25	0.15	Yes
			32 [32pt F]			
	A1SD32D1	1 connectable reader/writer	32 [32pt F]	0.25	0.15	No
	A1SD32D2	2 connectable readers/writers	32 [32pt F]	0.25	0.30	No
MELSEC-I/OLINK	A1SJ51T64	Max. 16 master stations, total of 128 I/O points	64 [64pt Y]	0.115	0.09	No
B/NET module	A1SJ71B62-S3	For B/NET transmission terminal control	32 [32pt F]	0.08	-	No
S-LINK master	A1SJ71SL92	For control of S-LINK equipment, max. 128 control I/O points	32 [32pt F]	0.20	—	No
JEMANET (JPCN-1) master module	A1SJ71J92-S3	JEMANET (JPCN-1) interface, for master station	32 [32pt F]	0.40	—	Yes
Profibus	A1SJ71PB96F	Profibus-FMS Client/Server	32 [32pt F]	0.56	_	Yes
	A1SJ71PB92D	Profibus-DP Master	32 [32pt F]	0.56	_	No
DeviceNet	A1SJ71DN91	DeviceNet Master	32 [32pt F]	0.24	_	No
Modbus	A1SJ71UC24-R2-S2	Modbus RTU/ASCII Slave, RS-232	32 [32pt F]	0.10	_	Yes
	A1SJ71UC24-R4-S2	Modbus RTU/ASCII Slave, RS-422/485	32 [32pt F]	0.10	—	Yes
Blank cover	A1SG60	Blank cover for I/O slot	16 [16pt vacant]	_	—	No
	A1SG62	16/32/64-point dummy module	16/32/64 [16/32/64pt X]	0.060	-	No

Note 1: When A1SD59J-MIF is connected



System Configuration

With the Q mode, you can use the Q series modules and AnS series modules given in the applicable model list. Because of the difference in size between Q and AnS series modules, bases for loading the Q series modules and AnS series modules are available, respectively. Choose the loading bases according to the modules used. For extension base cables, use the Q series extension cables with both the Q series and AnS series module bases. The AnS series main/extension bases and extension cables are unusable.

Basic configuration

This section provides components, peripheral devices and configuration outline in a QCPU system.

(1) Components in QCPU system





(2) Peripheral devices for QCPU



Instructions for system configuration

- (1) The total number of I/O and intelligent function modules that may be loaded into the main and extension bases is up to 64. This total of loadable modules is the same whether you use the Q6 B (extension) or the QA1S6 B (extension). Also, you have a selection of base units from the 3 I/O slot model to the 12 I/O slot model. Whichever base units you combine, the total number of loadable modules is up to 64.
- (2) You may combine the Q6 B and QA1S6 B up to 7 extension bases as you like. (Up to 8 bases including the main)

- (3) You can use the Q6 B and QA1S6 B in combination, but you must set the extension numbers of Q6 B to lower than those of the QA1S6 B.
- (4) The overall distance of extension cables is within 13.2m (43.28ft.).
- (5) Different from the A and QnA series CPU modules, the Q mode CPU module automatically recognizes the number of slots of the connected main and extension bases and allocates the I/O numbers. Refer to the QCPU (Q Mode) User's Manual (Hardware Design/Maintenance and Inspection). The next page shows the I/O numbers assigned when the base unit setting is the automatic mode and I/O assignment is not made.





(6) Modules having restrictions on the number of modules loaded

Module	Modules Loaded
MELSECNET/10H network	Up to 4
module	
QJ71LP21, QJ71BR11	
Ethernet interface module	Up to 4
QJ71E71(-B2)	
CC-Link interface module	4
QJ61BT11	
Interrupt module A1SI61	1
MELSECNET/MINI-S3 data link	No restriction
module	(However, automatic refresh
A1SJ71PT32-S3, A1SJ71T32-S3	function cannot be set)
AnS series special function	Up to a total of 6
module (Note 1)	

Note 1: The following modules correspond to restrictions on the number of modules loaded. The other modules have no restrictions on the number of modules loaded.

AnS modules having restrictions on the number of modules loaded

Product	Туре	Modules Loaded
Intelligent communication module	A1SD51	6
ID interface module	A1SJ71ID1-R4, A1SJ71ID2-R4	6
Profibus module	A1SJ71PB96F	6
Modbus module	A1SJ71UC24-R2-S2 A1SJ71UC24-R4-S2	6
JEMANET (JPCN-1) master module (Only when using GET/PUT service)	A1SJ71J92-S3	6

Note 2: The modules given in Note 1 have also functional restrictions. For details, refer to the corresponding module explanation sections.



(7) The instructions dedicated to the following modules which existed in the QnA/A series program instructions are unusable with the Q mode CPU. They must be rewritten using the FROM/TO instruction.

Product	Туре
High-speed counter module	A1SD61, A1SD62
	A1SD62D-S1, A1SD62E
MELSECNET/MINI-S3	A1SJ71PT32-S3, A1SJ71T32-S3
Positioning module	AISD75P1/P2/P3-S3
	A1SD75M1/M2/M3
ID interface	A1SJ71ID1-R4, A1SJ71ID2-R4

(8) Only the GOT-A900 series graphic operation terminals are usable (Q mode-compatible system OS and communication driver must be installed).

Note that the Q series bus interface is required for bus connection.

The GOT800 series, A77GOT and A64GOT are not usable.



Overview

In order to build optimal high-performance equipment, the Q mode CPU modules have greatly improved processing performance capabilities, program memory capacities, etc. and also improved performance capabilities for data communication with network modules and programming peripheral devices.

The Q mode CPU modules have the following features.

High-speed program processing

The Q mode CPU modules have realized processing speed about three times greater than that of the existing models (Q4ACPU, Q2ASHCPU) in terms of PC MIX value.

 Use of base units adopting high-speed bus system

The Q series base units have significantly improved data transfer speed to and from I/O, intelligent function and network modules (approx. 4 to 8 times higher than existing models). Especially, they can reduce the influence of large amounts of data transfer to/from network modules on the scan time.

Cyclic execution program

In addition to normal scan execution programs, you can create cyclic execution programs. Repeatedly run at preset intervals of 0.5ms to 60s, a cyclic execution program can achieve fast response uninfluenced by the entire program scan time.

Event interruption

Network modules and some intelligent function modules have a function to interrupt CPU modules. This function allows fast response to events which take place asynchronously with the PLC program scan, e.g. receiving of network module data. Also, the scan time can be reduced because data transfer-related programs can be removed from scan execution programs.

Large-capacity programs

The Q mode CPU modules are available in a total of five models having program capacities of 28k steps up to 252k steps. You can choose the optimum CPU module for your equipment.

Large-capacity extra memory

The Q mode CPU module is equipped with a small PC card slot to accept a max. 32M byte memory card. A memory card can save previously used programs intact as a history as well as comment files, extension file registers and other CPU module internal devices.

Number of control I/O points

Any model of the Q mode CPU can control up to 4096 points of I/O. Also, when used with a remote I/O network

such as CC-Link, any model can control max. 8192 points of I/O.

Extensibility of up to 64 I/O slots

In the Q series, up to seven extension bases can be connected and up to a total of 64 I/O slots can be used if more I/O slots are needed in addition to those of the main base (max. 12 I/O slots).

Secrecy

The Q mode manages sequence programs as files. You can specify passwords which restricts third-party access to individual files.

Function Explanations

The Q mode CPU module functions are described below. Note that the programming-related functions are given in Section 3 "Programming".

I/O control system

The I/O control system of the Q mode CPU modules is refresh mode. In refresh mode, acquisition of input data from an input module and output of output data to an output module are batch-performed when the END instruction of a sequence program is processed. When there are two or more scan execution programs, you can select whether refresh processing is carried out at the END instruction of the last run scan execution program or at the END instruction of the corresponding scan execution program.



To increase the response capability, I/O control in an interrupt program may require updating of I/O data at a point during program run before refresh processing is carried out at the END instruction. In that case, devices DX (input) and DY (output) may be used as I/O. For example, when you describe X100, X100 data obtained by refresh processing is used for operation. When you describe DX100, operation is executed using the X100 data of the same input module acquired at the point of executing its contact instruction. This also applies to output.



Operation processing

MODEL SELECTION

CPU

The Q mode CPU has three operation modes: RUN, STOP and PAUSE. Each operation mode performs the following operation processing.

- Operation processing in RUN mode
- In the RUN mode, sequence program operation alternates between step 0 and END (FEND) instruction.
- (2) When the CPU goes into the RUN mode, the output (Y) status saved at STOP is re-output according to the parameter setting (STOP → RUN output mode setting). (Saved output data may be cleared to perform RUN.)
- Operation processing in STOP mode
- In the STOP mode, sequence program operation is stopped by the RUN/STOP switch or remote STOP, or operation is stopped due to error detection.
- (2) When the CPU goes into the STOP mode, the current output (Y) status is saved and all outputs (Y) are turned off. Data memory other than the output (Y) is held. Note that the Q series output module can be set to hold the output at a STOP due to error detection.
- Operation processing in PAUSE mode
- (1) In the PAUSE mode, sequence program operation is stopped with the output (Y) and data memory status held. This mode should be used carefully because outputs which are ON are kept ON and inputs which should turn OFF the outputs are ignored.

Data type

There are five data types that can be handled by the Q mode CPU: bit, word, double word, real number and character string. The following table lists the numerical ranges that can be handled and the CPU module's internal devices which can store those values.

	Numerical Range		
Bit	0 (OFF), 1 (ON)		
Word	-32768 to 32767		
	Value can be handled as a collection of 4, 8, 12 and 16 bits. (Note 1)		
Double word	-2147483648 to 2147483647		
	Value can be handled as a collection of 4, 8, 12, 16, 20, 24, 28 and 32 bits. (Note 2)		
Real number	±1.17549E-38 to ±3.40282E+38 (Note 3)		
Character string	JIS8 code (Note 4)		

Note 1: Bit devices can also handle numerical data by using digit designation. In digit designation, bit devices are represented by designating them in 4-bit increments.



Example: Setting range by digit designation of inputs X0

(16 points)

Designated Digits	Numerical Range That Can Be Handled
K1 (4 points)	0 to 15
K2 (8 points)	0 to 255
K3 (12 points)	0 to 4095
K4 (16 points)	-32768 to 32767

Values in parentheses are the numbers of bit device points. Note 2: Bit devices can also handle numerical data by carrying out digit designation. In digit designation, bit devices are represented by designating them in 4-bit increments.

Example: Setting range by digit designation of inputs X0 to XF



(32 points)

Designated Digits	Numerical Range That Can Be Handled		
K1 (4 points)	0 to 15		
K2 (8 points)	0 to 255		
K3 (12 points)	0 to 4095		
K4 (16 points)	0 to 65535		
K5 (20 points)	0 to 1048575		
K6 (24 points)	0 to 167772165		
K7 (28 points)	0 to 268435455		
K8 (32 points)	-2147483648 to 2147483647		

Values in parentheses are the numbers of bit device points.

- Note 3: For 32-bit data, a real number uses two consecutive registers.
- Note 4: A character string is stored in multiple consecutive registers and NULL (00) is used as a code to indicate the end of the character string. There are no restrictions on the number of characters handled. Note that the character string that may be handled as a
- constant in a program is up to 32 characters long. Note 5: Numerical values cannot be handled in an unsigned format (example: 0 to 65535 numerical range for word).



Timers' timing performance capabilities

The internal timers of the Q mode CPU modules are all on-delay timers and available in four types: low-speed timer, high-speed timer, low-speed retentive timer and high-speed retentive timer.

The timing increments and timing errors of the timers are indicated below.

	Timing Increments	Timing Error
Low-speed timer Low-speed retentive timer	Variable between 1 and 1000ms	+1 scan time
High-speed timer High-speed retentive timer	Variable between 0.1 and 100ms	+1 scan time

Note that the timing range is up to the preset timing increments \times 32767. Timing error of max. 1 scan time is produced since the timer times by adding the value timed every scan at each END instruction to the timer's current value at processing of the OUT instruction.

Instructions for use of timers

Timers cannot be used in initial execution, standby, cyclic execution and interrupt programs.

Cyclic execution program performance capabilities

A cyclic program is run according to user's preset time (execution cycle) and its cycle time can be set from 0.5ms to 60s.

Starting overhead time

The following overhead time is required to start a cyclic execution program.

CPU Type	Starting Time (µs)
Q02CPU	380
Q02HCPU, Q06HCPU,	165
Q12HCPU, Q25HCPU	

• Start inhibiting factor

A cyclic execution program is not started when the interrupt status is not enabled. It can be started after interrupt is enabled by the EI instruction.

Start delaying factors

In any of the following cases, the start of a cyclic execution program is delayed.

- (1) During execution of any instruction
- (2) During processing of request for read/write of data in CPU's internal memory from GPPW, network module, GOT, etc.
- (3) During execution of another cyclic program or interrupt program
- (4) When multiple cyclic programs are started at the same time, the execution of the lower numbered program in program setting has priority and the other programs have to wait.

(5) When a cyclic program and an interrupt program are started simultaneously, the interrupt program has priority.

Instructions for setting of cycle time

The execution processing time (including the starting overhead time) of a cyclic program must be set to less than the cycle setting time of that program.

Also, if the ratio of the cyclic execution program processing time compared to the total processing time is too high, it may delay the scan execution program processing, resulting in WDT error. Be careful when setting the cycle time.

If any of real-time interrupt programs I28 to I31 is used, automatic I/O (X/Y) refresh is not made at the start and end of the interrupt program. As required, the partial refresh instruction must be executed to perform I/O refresh processing.

In contrast, a cyclic program automatically performs input X and output Y refresh processing in the parameter-preset range at the start and end of the cyclic program.

Interrupt program performance capabilities

Any of the following starting factors can be used to initiate interrupt programs.

- (1) Interrupt from the A1SI61 interrupt module
- (2) Interrupt from the intelligent function module or network module
- (3) Cyclic interrupt by CPU's internal timer (0.5ms to 1000ms)
- (4) Interrupt due to CPU error occurrence
- Starting overhead time

The following overhead time is required to start an interrupt program.

СРИ Туре	Starting Time (μ s)
Q02CPU	380
Q02HCPU, Q06HCPU,	165
Q12HCPU, Q25HCPU	

• Start inhibiting factor

An interrupt program is not started when the interrupt status is not enabled. It can be started after interrupt is enabled by the EI instruction.

Start delaying factors

In any of the following cases, the start of an interrupt program is delayed.

- (1) During execution of any instruction
- (2) During processing of request for read/write of data in CPU's internal memory from GPPW, network module, GOT, etc.
- (3) During execution of another cyclic program or interrupt program

(4) When multiple interrupt programs are started at the same time, the programs of lower priority wait until the processing of higher-priority programs is complete.
Instructions for use of interrupt programs

MODEL SELECTION

CPU

If the ratio of the interrupt program processing time compared to the total processing time is too high, it may delay the scan execution program processing, resulting in WDT error. Take care when setting the interrupt factor.

High-speed execution of interrupt program

To shorten the overhead time from when an interrupt condition holds until interrupt program processing starts, you can choose the high-speed execution mode for an interrupt program. Selection of this mode can reduce the overhead time as follows.

СРИ Туре	Starting Time (μ s)		
	Normal mode	High-speed	
		mode	
Q02CPU	380	230	
Q02HCPU, Q06HCPU,	165	100	
Q12HCPU, Q25HCPU			

Note that if you select the high-speed mode, the following processings performed in the normal mode are not performed, and care must be taken for programming.

• Save processing of index register

In the normal mode where the save/return processing of the index register Z is automatically performed at a shift to an interrupt program, use of the index register in the interrupt program does not corrupt the value of the index register.



In the high-speed mode, however, this save/return processing is not performed. Hence, use of the index register in the interrupt program may produce an illegal index register value at a return to the main program. To prevent this, use the ZPUSH/ZPOP instruction in the interrupt program to perform the save/return processing of the index register in the user program.

• Save processing of file register file name In the normal mode, the save and return processings of the file register name being used are automatically performed at a shift to and a return from an interrupt program. Hence, using the QDRSET instruction in the interrupt program to change the file register file name resets the original file register file name automatically at a return.

In the high-speed mode, this save/return processing is not performed and this should be processed in the user program as required.

Constant scan function

In the program processing of the CPU module, the scan time changes per scan because the processing time differs depending on whether an instruction used in a sequence program is executed or not. The constant scan function is designed to run the sequence program repeatedly while simultaneously keeping the scan time uniform.

When the scan time is uniform, time delays in external signal input, operation processing and output are uniform, increasing the equipment control accuracy. The constant scan setting is 0.5 to 2000ms.



Processing at instantaneous power failure

When the input power supply voltage supplied to the power supply module has become less than the rated voltage, the Q mode CPU module detects an instantaneous power failure and performs the following operation processing.



- When an instantaneous power failure occurrs for the permissible instantaneous power failure time or shorter
- (1) When an instantaneous power failure occurs, the output status is held and operation processing is suspended.

However, timer timing and watchdog timer (WDT) timing continue. (For example, when the scan time is 190ms at the WDT setting of 200ms, the occurrence of a 15ms instantaneous power failure causes a watchdog timer error.)

(2) When the instantaneous power failure is cleared, operation processing resumes.



 When an instantaneous power failure occurred for longer than permissible instantaneous power failure time

The Q mode CPU module performs the same operation processing as performed when it is reset and powered on or when it is reset by the reset switch.

Self-diagnostics

The Q mode CPU has a self-diagnostic function to determine whether if a fault is present. Self-diagnostics are designed to prevent PLC malfunctions and for preventive maintenance. On detection of a fault, an error is displayed and the PLC operation is stopped, for example. The diagnostic items are listed below.

Diagnostic Item	Description
CPU hardware fault	Diagnoses the hardware of the CPU module.
END instruction unexecuted	Diagnoses the execution status of the END instruction.
RAM check	Diagnoses the memory status.
Arithmetic circuit check	Diagnoses the execution status of the CPU module arithmetic circuit.
Fuse blown	Diagnoses the status of the output module fuse.
I/O interrupt error	Diagnoses the interrupt input.
Intelligent function module error	Diagnoses the statuses of the intelligent function modules.
Control bus error	Diagnoses the bus status on the base unit.
Instantaneous power failure occurrence	Diagnoses the occurrence of an instantaneous power failure.

	1
Diagnostic Item	Description
Battery low	Diagnoses the voltage of the battery.
I/O module verify	Diagnoses the loading statuses of I/O modules.
Intelligent function module assignment error	Diagnoses the I/O assignment status of the intelligent function modules.
No parameters	Diagnoses the parameter write status.
Boot error	Diagnoses the setting status of boot operation.
Memory card operation error	Diagnoses the handling of the memory card.
File setting error	Diagnoses the file setting status.
File access error	Diagnoses the access status to the file.
Instruction inexecutable	Diagnoses the presence/absence of the program file to be executed.
Parameter setting check	Diagnoses the set data of the parameters.
Link parameter error	Diagnoses the set data of the link parameters.
SFC parameter error	Diagnoses the set data of the SFC parameters.
Instruction code check	Diagnoses the code of the instruction to be executed.
No END instruction	Diagnoses missing END instruction.
Pointer setting error	Diagnoses the pointer setting status.
Operation check error	Diagnoses the operation results.
FOR-NEXT instruction loop error	Diagnoses the FOR-NEXT instruction loop.
CALL-RET instruction loop error	Diagnoses the CALL-RET instruction loop.
Interrupt program error	Diagnoses the interrupt program construction.
Extension instruction error	Diagnoses the instruction data.
SFC error	Diagnoses the SFC program running status.
Watchdog timer error	Diagnoses the program running status.
Program time-out	Diagnoses the program running time.

Failure history

The Q mode CPU allows the results of detection by the self-diagnostic function with additional detection time data to be stored in memory as a failure history. Failure confirmation can be made after restoration from error.

System protective functions

MODEL SELECTION

CPU

The Q mode CPU has several protective functions (system protections) against program changes from the third party.

System protections have different means for different objects to be protected.

Protecting the whole CPU

Use the CPU module DIP switches.

You can batch-inhibit external write to all files. This is the simplest way of protection.

However, a third party can easily clear the protection.

Protecting the memory card

Use the write protect switch of the memory card. You can batch-inhibit external write to all files. This is also a simple way of protection.

However, a third party can also easily clear the protection. • Protection on a file basis

Register passwords file-by-file. You can inhibit either or both external read and write from/to the specified file. Proper management of passwords achieves high protection capability against a third party. Use this method when you want to protect the required files only. A password can be set with four alphanumeric characters.

ROM operation

Debugged parameters and programs can be stored in ROM. The processing of the parameters and programs stored in ROM is started after they have been transferred to the program memory (drive 0) at power-on (or CPU reset). (Boot operation setting necessary) The CPU's built-in standard ROM (drive 4) or memory card (ROM) (drive 2) may be used.

Clock function

The Q mode CPU module has an internal clock function. As the clock data can be read with a sequence program, it may also be used for system time management. The clock data is also used for a failure history. The clock function is battery-backed during power-off of the PLC.

Clock data

Data Name	Description			
Year	4 digits			
Month	1 to 12			
Day	1 to 31 (automatic leap year judgment)			
Hour	0 to 23 (24 hour system)			
Minute	0 to 59			
Second	0 to 59			
Day of week	0 Sunday			
	1	Monday		
	2	Tuesday		
	3	Wednesday		
	4	Thursday		
	5	Friday		
	6 Saturday			

Accuracy

Refer to the CPU performance specifications for accuracy. ● Timing range

The clock can time between January 1, 1980 to December 31, 2079.



Performance Specifications

Item				Туре				Bomorko
		nem	Q02CPU	Q02HCPU	Q06HCPU	Q12HCPU	Q25HCPU	Remarks
Control system			Repeated or	peration using s	stored program			
I/O control method			Refresh mod	de				Direct I/O possible
								using device name
Programm	ing language			edicated to seq				
			Relay symbo (SFC)	ol type (ladder)	logic symbolic	language, MEI	LSAP-3	
Processing		LD	79	34				
(sequence (ns)	instruction)	MOV	237	102				
Constant s	can (ms) start at given tim	ne intervals)	0.5 to 2000r	ns (can be spe	cified in 0.5ms i	increments)		Parameter setting
Program c		Number of steps	28k	28k	60k	124k	252k	
		Number of files	28	28	60	124	124	Two SFC files included (Note 3)
Number of I/O device points			8192 (X/Y0 to 1FFF)				(Note 1)	
Number of	I/O points		4096 (X/Y0 to FFF)				(Note 2)	
Number	Internal relay	[M] (points)	Default 8192 (M0 to 8191)			Each number of device		
of device	Latch relay [L] (points)		Default 8192 (L0 to 8191)				points can be changed by parameters. Note	
points	Link relay [B] (points)		Default 8192 (B0 to 1FFF)					
	Timer [T] (points)		Default 2048 (T0 to 2047) (used as low-speed or high-speed timer)				that the overall device	
			Switching between low-speed and high-speed timers is set by					capacity is uniform.
			instruction.					
			Low-speed/h					
			(Low-speed					
	Detentive time		(High-speed timer: 0.1 to 100ms, 0.1ms increments, default 10ms)					
	Retentive timer [ST] (points)		Default 0 (ST0 to 2047) (used as low-speed or high-speed timer) Switching between low-speed and high-speed timers is set by					
			instruction.					
			Low-speed/high-speed timer timing increments are parameter-set.					
			(Low-speed timer: 1 to 1000ms, 1ms increments, default 100ms)					
			(High-speed timer: 0.1 to 100ms, 0.1ms increments, default 10ms)					
	Counter [C] (points)	Normal counters Default 1024 (C0 to 1023)					
	1		Interrupt counters Max. 256 (Default 0 points, parameter setting)					

(Continued on next page)

MODEL SELECTION

CPU

Item			Туре					
		Q02CPU						
Number	Data register [D] (points)	Default 1228	Default 12288 (D0 to 12287)					
of device points	Link register [W] (points)	Default 8192	Default 8192 (W0 to 1EEE)				points can be changed by parameters. Note	
	Annunciator [F] (points)	Default 2048	Default 2048 (F0 to 2047) 1			that the overall device		
	Edge relay [V] (points)	Default 2048	Default 2048 (V0 to 2047)				capacity is uniform.	
	File register [R] (points)		nts (ZR0 to 517 mory" on the fo oints.			,	When using Q2MEM- 1MBS	
	Special link relay [SB] (points)	2048 (SB0 to					Number of device	
	Special link register [SW] (points)	2048 (SW0 to	1				points is fixed	
	Step relay [S] (points)	8192 (S0 to 8	1					
	Index register [Z] (points)	16 (Z0 to 15)	,					
	Pointer [P] (points)		1095), set in pa	rameters the ra	ange in which t	he		
			mon pointers a		3			
	Interrupt pointer [I] (points)	256 (10 to 255	•					
		`	,	intervals of the	e system interr	upt pointers		
		-	In parameters, set the cyclic intervals of the system interrupt pointers I28 to I31 (5 to 1000ms, 5ms increments).					
	Special relay [SM] (points)	2048 (SM0 to	2047)					
	Special register [SD] (points)	2048 (SD0 to	2047)					
	Function input [FX] (points)	5 (FX0 to 4)						
	Function output [FY] (points)	16 (FY0 to F)	16 (FY0 to F)					
	Function register [FD] (points)	16 (FD0 to F)						
Link direct	device	Device for direct access to link device. Dedicated. Specified format: J						
Intelligent f	unction module direct device	Device for dir	ect access to b	ouffer memory	of intelligent fu	nction		
		module.						
		Specified for	mat: U	G				
Latch (pow	er failure compensation) range	L0 to 8191 (d	efault)				Parameter setting	
		(Latch range	(Latch range setting can be made for B, F, V, T, ST, C, W and D)					
Remote RI	JN/PAUSE contact	1 point can b	1 point can be set for each RUN and PAUSE contacts from X0-1FFF.					
Clock func	tion	Year, month,	Year, month, day, hour, minute, second, day of week					
		(Automatic le	ap year judgm	ent)				
			Accuracy –3.18 to +5.25 (TYP +2.12) s/d @ 0°C					
			Accuracy –3.93 to +5.25 (TYP +1.90) s/d @ 25°C					
		Accuracy –14	Accuracy –14.69 to +3.53 (TYP –3.67) s/d @ 55°C					
Permissible	e instantaneous power failure time	Depends on	power supply n	nodule.			Refer to the power supply module section.	
5VDC inter	nal current consumption (A)	0.60	0.64	0.64	0.64	0.64		
Weight (kg	(lb))	0.20 (0.44)	0.20 (0.44)	0.20 (0.44)	0.20 (0.44)	0.20 (0.44)		
External di	mensions (mm (inch))	98 (3.86) (H)	98 (3.86) (H) × 27.4 (1.08) (W) × 89.3 (3.52) (D)					

(Continued from preceding page)

MODEL SELECTION

CPU

Note 1: Sum of the number of I/O points on the main/extension base directly controlled by the CPU module and the number of I/O points controlled as remote I/O by the remote I/O network

Note 2: Number of I/O points on the main/extension base directly controlled by the CPU module

Note 3: In a total of two SFC files that may be created, one is the program execution management SFC.

MODEL SELECTION CPU

Battery Life

The Q6BAT battery built in the CPU module is used to back up the programs and various data stored in the RAM memory of the CPU module during a power failure and to back up the clock element continuously during a power failure.

The Q6BAT is not used while 5VDC is supplied from the power supply module. The battery life of the Q6BAT depends on the total power failure time when 5VDC is not supplied from the power supply module. Note that the SRAM card contains a battery (Q2MEM-BAT) in itself and is independent of the consumption of the Q6BAT.

Battery life

СРИ Туре	Total Pow Time (Backup Time after
	Guaran- teed value	Actual value	Battery Error ON (Hours)
Q02CPU	5433	13120	120
Q02HCPU Q06HCPU	2341	6435	120
Q12HCPU Q25HCPU	1260	4228	48

Note 1: If the total power failure time is less than the above value, the battery must be changed in 10 years as a guideline.

Accessories

Product	Туре	Quantity		
Battery	Q6BAT	1		

Manuals

The following manuals are related to the Q mode CPU.

Name	Remarks			
QCPU (Q Mode) User's Manual	Packed with Q3 B main base			
(Hardware)				
QCPU (Q Mode) User's Manual	Optional			
(Hardware Design/Maintenance				
and Inspection)				
QCPU (Q Mode) User's Manual	Optional			
(Function Explanation/Program				
Fundamentals)				
QCPU (Q Mode)/QnACPU	Optional			
Programming Manual (Common				
Instructions)				
QCPU (Q Mode)/QnACPU	Optional			
Programming Manual (SFC)				
QCPU (Q Mode) Programming	Optional			
Manual (MELSAP-L)				
QCPU (Q Mode)/QnACPU	Optional			
Programming Manual (PID				
Control Instructions)				

CPU Built-In Memories/Memory Cards

Overview

MODEL SELECTION MEMORY

This section describes the memory configuration of PLC memories which store user-created data, such as programs and device comment files, and how to calculate necessary memory capacities. Note that the Q mode is different in concept from the A mode. Refer to the Chapter of the A Mode for the memory concept of the A mode.

Memory Makeup

The Q mode uses multiple memories according to the purpose of use in the CPU. These memories are identified by the drive numbers for access. The memories used in the Q mode are as follows. It should be noted that the Q mode CPU is equipped with only one memory card slot, which accepts only one card.



List of data that may be stored into each memory

	CPU Built-In Memory			Memory Card		
Memory Name	Program memory	Standard RAM	Standard ROM	Memory card (RAM)	Memory card (ROM) Flash card	Memory card (ROM) ATA card
Drive number	0	3 4 1 2				2
File size increment	4kB	512B				
Program	0	×	0	0	0	0
Parameter	0	×	0	0	0	0
Intelligent parameter	0	×	0	0	0	0
Device comment	0	\times	0	0	0	0
Device initial value	0	×	0	0	0	0
File register	×	0	×	0	0	×
Local device	×	0	×	0	×	×
Debugging data	×	×	×	0	×	×
Failure history	×	×	×	0	×	×
General-purpose file	×	×	×	×	×	0

A program stored in the standard ROM, memory card (RAM) or memory card (ROM) is transferred to the program memory at power-on and executed in the program memory. Hence, if the program is stored in the standard ROM, memory card (RAM) or memory card (ROM), the program memory needs a sufficient free space to accept that program.

For use of the debugging data for trace function, a failure history or a general-purpose file, the memory card must be loaded.

Program

Ladder, list or SFC sequence program file. When running multiple programs, multiple program files are also stored in memory.

Parameter

File storing PLC parameters and network parameters set during programming.

Intelligent parameter

Intelligent function module parameter file set using the intelligent function module utility software. This file does not exist if you do not use the setting made with the utility software.

Device comment

File of device comments annotated to each device of the CPU.

Device initial value

Initial value file required when setting given initial values to devices in the CPU at power-on.

File register

File register (R, ZR) file. Setting different file names allows multiple file register files to be stored.

Note that the file registers can be stored in the memory card (ROM) (drive number: 2), but not in the ATA card (Q2MEM-8MBA/16MAB/32MBA).

The file registers stored in the flash card allow read only in the program and do not allow data changes in the program.

Local device

Local devices are devices exclusively used with the corresponding programs in the presence of multiple programs.

When processing any program, the corresponding local device data is transferred from the local device area to the executing device area and program processing is then performed.
CPU Built-In Memories/Memory Cards

Debugging data

Trace result storage file for the trace function used for program debugging.

• General-purpose file

Data file written by the FWRITE instruction.

Note that the general-purpose file can be stored in the ATA card (Q2MEM-8MBA/16MBA/32MBA) only.

Program memory (Drive number: 0)

Memory equipped as standard inside the CPU.

The memory capacity depends on the CPU type.

Туре	Memory Capacity (Bytes)	Number of Files Stored
Q02 (H) CPU	112k	28
Q06HCPU	240k	60
Q12HCPU	496k	124
Q25HCPU	1008k	252

Up to 124 program files can be executed.

Memory card (RAM) (Drive number: 1)

Memory used in the memory card interface of the CPU, where the SRAM card can be used.

Туре	Memory Capacity (Bytes)	Number of Files Stored
Q2MEM-1MBS	1011k	128

The above capacity is achieved after formatting.

The program stored in the RAM memory card is transferred to the program memory at power-on of the system and executed in the program memory. (When boot operation setting has been made)

Memory card (ROM) (Drive number: 2)

Memory used in the memory card interface of the CPU, where the flash card or ATA card can be used.

Туре	Memory Capacity (Bytes)	Number of Files Stored
Q2MEM-2MBF	2032k	256
Q2MEM-4MBF	4080k	288
Q2MEM-8MBA	7972k	512
Q2MEM-16MBA	15964k	512
Q2MEM-32MBA	31918k	512

The above capacity is achieved after formatting.

The program stored in the ROM memory card is transferred to the program memory at power-on of the system and executed in the program memory. (When boot operation setting has been made)

Standard RAM (Drive number: 3)

Memory equipped as standard inside the CPU.

Туре	Memory Capacity (Bytes)	Number of Files Stored
Q02 (H) CPU	64k	2 (Note 1)
Q06HCPU	64k	2 (Note 1)
Q12HCPU	64k	2 (Note 1)
Q25HCPU	64k	2 (Note 1)

Note 1: One file register file and one local device file can be stored.

Standard ROM (Drive number: 4)

Memory equipped as standard inside the CPU.

Туре	Memory Capacity (Bytes)	Number of Files Stored
Q02 (H) CPU	112k	28
Q06HCPU	240k	60
Q12HCPU	496k	124
Q25HCPU	1008k	252

The program stored in the standard ROM is transferred to the program memory at power-on of the system and executed in the program memory. (When boot operation setting has been made)

Capacity Calculation

Use the following table to calculate the capacity of the files stored in each memory (drive). Note that the file size increment of drive 0 is 4096 bytes, and those of drives 1 to 4 are each 512 bytes. If less than the size increment, the capacity is calculated in the size increment. Choose the memory with enough allowance since the system may set several files (about 4k to 20k bytes) to each memory (drive) automatically.

File Function	File Capacity (Bytes)
Parameter	11k + network parameter capacity (Note 2)
Intelligent parameter	(Note 2)
Program	(Number of steps × 4) + 136
Device comment	Number of comment characters × total number of comments + number of comment ranges × 10
Device initial value	Assuming that n = setting number, $44 \times n +$ (number of device points of setting 1 + + number of device points of setting n) $\times 2 + 66$
File register	Number of file register points x 2 (Note 2)

CPU Built-In Memories/Memory Cards

File Function	File Capacity (Bytes)
Local device	72 + (set device type \times 6) + ((total number of set M and V points ÷ 16) + (total number of set T, ST and C points ÷ 16 \times 18) + (number of set D points)) \times 2 \times number of program files
Failure history data	(Number of failures stored × 54) + 72
Debugging data	Specified devices traced: (20 + (number of word device points × 2) + (number of bit device points ÷ 16) × 2) × trace count + (device range × 12) + 362
General-purpose file	Number of write points set by FWRITE instruction

MODEL SELECTION MEMORY

Note 2: The network parameter and intelligent parameter sizes are listed below. The following table indicates the maximum capacity per corresponding module and the capacity will be less than the given size according to the setting.

Corresponding Module	Capacity
Ethernet	With e-mail setting: 12488 (bytes/module) Without e-mail setting: 2060 (bytes/module)
MELSECNET/10(H)	11466 (bytes/module) + 1548 bytes
CC-Link	1423 (bytes/module) + 6 bytes
Analog-to-digital conversion module	76 (bytes/module)
Digital-to-analog conversion module	24 (bytes/module)
Serial communication module	1000 (bytes/module)

Note 3: The maximum number of file register points that may be stored in each memory is as listed below. However, if other files exist in the same memory, the capacity usable by file registers reduces. Note that if the file registers are stored separately in different memories (drives), the file register file used must be selected by the QDRSET instruction. In addition, the file registers stored in the ROM memory card are read-only and cannot be rewritten with a program.

Memory Type		Max. Number of File Register Points
RAM memory card (Drive: 1)	Q2MEM-1MBS	517,120 points
ROM memory	Q2MEM-2MBF	1,040,384 points
card (Drive: 2)	Q2MEM-4MBF	1,042,432 points
Standard RAM (Drive: 3)		32,768 points

Performance Specifications

Memory cards are available in SRAM type, linear flash ROM type and ATA flash ROM type. They are classified as follows according to their applications and capacities.

Туре	Memory Type	Memory Capacity (bytes)	Write Count (times)
Q2MEM-1MBS	SRAM	1011k	No restriction
Q2MEM-2MBF	Linear flash	2032k	100,000
Q2MEM-4MBF	ROM	4080k	100,000
Q2MEM-8MBA	ATA flash	7972k	1,000,000
Q2MEM-	ROM	15964k	1,000,000
16MBA			
Q2MEM-		31918k	1,000,000
32MBA			

Note 4: Both the linear flash ROM and ATA flash ROM are rewritable non-volatile memories.

Battery Life of Q2MEM-1MBS

The Q2MEM-1MBS built in battery has the following battery life. Note that the Q2MEM-1MBS is loaded into the PLC CPU and consumes battery current if power is ON.

	Memory Backup Time (Hours)		Backup Time after
	Guaran- teed (MIN.)	Actual (TYP.)	Battery Error ON (Hours)
During storage	690	6336	8
During operation	11784	13872	8

During storage: Loaded in PLC CPU with power off or card is stored alone. During operation: Loaded in PLC CPU with power on.

Overview

In production locations, the introduction of a network system suited to applications and objectives is significant to ensure efficient production and appropriate quality control and to achieve reductions in equipment sizes and costs by labor saving and wiring reduction.

The Q mode inherits the conventional MELSEC network and offers a network with advanced performance, functions and user-friendliness.

Features

Hierarchical network

Assuming a three-level network, the Q mode offers network products optimum for respective applications.

Information network/Ethernet:

We assume that an information network is on the highest network level in production fields. Designed to transfer production control information, quality control information, facility operating status and other information between the PLC or facility controller and the production control computer, the information network assumes the use of the most general-purpose Ethernet. Ethernet accepts not only a wide variety of computers such as Windows and UNIX type personal computers but also various Factory Automation equipment. The Q mode has functions which make the best use of the Ethernet features and utilize Ethernet easily.

Control network/MELSECNET/10H

We assume that a control network which links control devices, e.g. PLC and CNC, is on the middle network level in production sites. Designed to transfer data directly related to the operations and motions of machinery and equipment between the control devices, the control network is required to have excellent real-time capabilities. MELSECNET(II/10), MELSEC's control network, is highly regarded in the market for its excellent real-time capabilities, simple network settings, highly redundant reliability typified by duplex loop, and boasts the largest share in Japan and a great number of installations throughout the world. In the Q mode, the MELSECNET(II/10H), and has also extra real-time

capabilities and data capacities to meet further market needs.

Field network/CC-Link

We assume that a field network which links control devices, such as PLC, with sensors and drive equipment is on the lowest network level in production locations. While control devices were previously linked with sensors and drive equipment by wires on a point-by-point basis, the field network can connect multiple sensors and drive equipment with a single network cable, reducing the number of wires and wiring processes. When connected with intelligent equipment such as the ID system, barcode reader, inverter and display, the field network allows production data control at network ends through transfer of various data, in addition to ON/OFF data, and serves for improved maintenance efficiency by centralized control of equipment operating statuses. In the Q mode, the CC-Link functions having high speed and excellent data transmission performance has been improved to ensure further ease of use.

Seamless communication

The Q mode networks are seamless networks which remove the feeling of difference between network types. You can send/receive data, remote-monitor or correct/change programs regardless of differences in network level and type.

Ease of setting network parameters

For the Ethernet, MELSECNET/10H and CC-Link networks for Q mode, you can set the parameters and various functions required for network connection in GPPW, greatly reducing programs related to network setting. Also, you can easily confirm the settings on screen.

Also, a dedicated utility package is available for the RS232/422/485 serial communication module, and you can set the functions and communication parameters of the module on screen.

Cyclic communication

MODEL SELECTION NETWORK

The basis of MELSECNET/10H or CC-Link

communication having close relationships with machine control is cyclic communication. Since the data of the prespecified region is transferred periodically (cyclically) and automatically, cyclic communication does not need a sequence program for data transfer.

The cyclic communication data of MELSECNET/10H or CC-Link is sent by broadcast. Broadcasting is a method in which the data sent from a given station is received by all other stations. Broadcasting allows data to be transmitted to multiple stations at once and to be shared by all stations.

Network modules unusable with the Q mode

MELSECNET(II) and MELSECNET/B can not be used with Q mode.

Also, the Ethernet, MELSECNET/10, CC-Link and serial communication/computer link modules for AnS/Q2AS series cannot be used. Use the Q series modules.

Other networks

In addition to the Ethernet, MELSECNET/10(H), CC-Link network and RS232C/422/485 serial communication modules developed for the Q mode, the Q mode allows you to use the other network-compatible modules developed for the AnS series. When using those network modules, use the QA1S6 \square B extension base for AnS series modules.

Since there are restrictions on use, refer to the explanation sections of the corresponding modules.

AnS series network modules usable with the Q mode

Network Name	Module Type
MELSECNET/MINI-S3	A1SJ71PT32-S3
	A1SJ71T32
I/O LINK	A1SJ51T64
JPCN-1	A1SJ71J92-S3
S-LINK	A1SJ71SL92
B-NET	A1SJ71B62-S3
Intelligent communication	A1SD51S
ID interface	A1SJ71D1-R4
	A1SJ71ID2-R4
	A1SD32ID1
	A1SD32ID2
Profibus-FMS	A1SJ71PB96F
Profibus-DP	A1SJ71PB92D
DeviceNet	A1SJ71DN91
Modbus	A1SJ71UC24-R2/R4-S2

Ranges accessible by GPPW/CSKP using the routing function

The ranges accessible with GPPW and CSKP using the routing function are given below. Refer to the following table for the PLC types given in the description.

Туре	CPU Type	Ethernet Module Type	MELSECNET/10 Module Type	Serial Communication Module Type	CC-Link Module Type
I	Q02/Q02H/Q06H/ Q12H/Q25H	QJ71E71 QJ71E71-B2	QJ71LP21,QJ71BR11	QJ71C24 QJ71C24-R2	QJ61BT11
II	Q2A(S1)/Q3A/Q4A/ Q2AS(S1)/Q2ASH(S1)	AJ71QE71 AJ71QE71-B5 A1SJ71QE71-B2 A1SJ71QE71-B5	AJ71QLP21 AJ71QBR11 A1SJ71QLP21 A1SJ71QBR11 A1SJ71QBR11 A1SJ71LP21 A1SJ71BR11	AJ71QC24N AJ71QC24N-R2 A1SJ71QC24N A1SJ71QC24N-R2/R4	AJ61QBT11 A1SJ61QBT11
	A2U(S1)/A3U/A4U/ Q02-A/Q02H-A/ Q06H-A/ A2AS(S1)/A2USH-S1 Other than above	AJ71E71-S3 A1SJ71E71-B2-S3 A1SJ71E71-B5-S3	AJ71LP21, AJ71BR11 A1SJ71LP21 A1SJ71BR11	AJ71UC24 AISJ71UC24-R2/R4	AJ61BT11 A1SJ61BT11

If the combination of CPU module and communication module on a type basis is other than that shown in the above list, the accessible range may differ from the one given.

When connecting via MELSECNET/10 or Ethernet



	Condition 1	Condition 2	Condition 3	Condition 4	Condition 5	
Request Source	Type of network 1	Type of relay station 1	Type of networks 2 to 8	Type of relay stations 2 to 7	Type of target station 1	Access Range
GPPW	Ethernet	1	MELSECNET/10	I, II or III	1	PLC on path up to target station 2
		I		I, II or III	II, III or IV	PLC on path up to target station 1
		Ш		I, II or III	_	PLC of type II on path up to target station 1
		ш		—	—	Inaccessible
		IV		_	_	PLC of type IV on network 2
	MELSECNET/10	I, II or III		I, II or III	I	PLC on path up to target station 2
		I, II or III		I, II or III	II, III or IV	PLC on path up to target station 1
		IV		IV	—	PLC of type III or IV on network 2
CSKP	Ethernet	I		I, II or III	I, II, III or IV	PLC on path up to target station 1
		ll or III		I, II or III	_	PLC of the same type as relay station 1 on path up to target station 1
		IV		_	—	PLC of type III or IV on network 2
	MELSECNET/10	I, II or III		I, II or III	I, II, III or IV	PLC on path up to target station 1
		IV		IV	—	PLC of type III or IV on network 2

Note 1: The ISA bus MELSECNET/10 board and SW3DNF-MNET10 driver are required to connect a GPPW or CSKP-installed personal computer to MELSECNET/10. The access ranges for use of the driver of SW3DNF-MNET10 or earlier are different from those in the above table.



When connecting via CC-Link



Note 2: The PCI bus CC-Link board and SW3DNF-CCLINK driver are required to connect a GPPW or CSKP-installed personal computer to CC-Link. The access ranges for use of the driver of SW3DNF-CCLINK or earlier are different from those in the above table.

• When connecting via CPU port or serial communication/computer link module (1)



	Condition 1	Condition 2	Condition 3	Condition 4	
Request source	Type of connected PLC	Type of networks 1 to 8	Type of relay stations 1 to 7	Type of target station 1	Access Range
GPPW	1	MELSECNET/10	I, II or III	1	PLC on path up to target station 2
	1		I, II or III	II, III or IV	PLC on path up to target station 1
	11		I, II or III	II, III or IV	PLC of type II on path up to target station 1
	111		I, II or III	II, III or IV	PLC of type III or IV on path up to target station 1
	IV		_	_	PLC of type III or IV on network 1
CSKP	1		I, II or III	II, III or IV	PLC on path up to target station 1
	11		I, II or III	II, III or IV	PLC of type II on path up to target station 1
	111		I, II or III	II, III or IV	PLC of type III or IV on path up to target station 1
	IV		_	—	PLC of type III or IV on network 1

• When connecting via CPU port or serial communication/computer link module (2)



GPPW or CSKP	1	CC-Link	I, II or III	MELSECNET /10	I, II or III	PLC of type I on path up to target station 1
	II, III or IV		—	—	—	Accessible to connected PLC only

Ranges accessible by MELSEC communication protocol of Ethernet module

The ranges accessible using the MELSEC communication protocol of the Ethernet module are given below. Refer to the following table for the PLC types given in the description.

Туре	CPU Type	Ethernet Module Type	MELSECNET/10 Module Type	CC-Link Module Type
1	Q02/Q02H/Q06H/Q12H/ Q25H	QJ71E71 QJ71E71-B2	QJ71LP21,QJ71BR11	QJ61BT11
11	Q2A(S1)/Q3A/Q4A/ Q2AS(S1)/Q2ASH(S1)	AJ71QE71 AJ71QE71-B5 A1SJ71QE71-B2 A1SJ71QE71-B5	AJ71QLP21 AJ71QBR11 A1SJ71QLP21 A1SJ71QBR11	AJ61QBT11 A1SJ61QBT11
111	A2U(S1)/A3U/A4U/ Q02-A/Q02H-A/ Q06H-A/ A2AS(S1)/A2USH-S1	AJ71E71-S3 A1SJ71E71-B2-S3 A1SJ71E71-B5-S3	AJ71LP21, AJ71BR11 A1SJ71LP21 A1SJ71BR11	AJ61BT11 A1SJ61BT11
IV	Other than above			

If the combination of CPU module and communication module on a type basis is other than that shown in the above list, the accessible range may differ from the one given.

The levels of the MELSEC communication protocol supported by the Ethernet modules are as listed below.

Ethernet Module Type	Protocol Level
QJ71E71, QJ71E71-B2	1, 2, 3, 4
AJ71QE71, AJ71QE71-B5, A1SJ71QE71-B2, A1SJ71QE71-B5	1, 2, 3
AJ71E71-S3, A1SJ71E71-B2-S3, A1SJ71E71-B5-S3	1

Protocol level 1 and level 2

MODEL SELECTION NETWORK



Protocol level 3



Request Source	Condition 1	Condition 2	Condition 3	Access Range	
Request Source	Type of relay station 1	Type of networks 2 to 8	Type of relay stations 2 to 7		
Personal computer	l or ll	MELSECNET/10	I, II or III	PLC on path up to target	
				station	
	III or IV	—	—	Protocol level 3 is unusable.	

Protocol level 4



	Condition 1	Condition 2	Condition 3	Condition 4	
Request source	Type of relay station 1	Type of networks 2 to 8	Type of relay stations 2 to 7	Type of target station 1	Access Range
Personal computer	1	MELSECNET/10	I, II or III	I	PLC on path up to target station 2
	1	MELSECNET/10	I, II or III	ll or III	PLC on path up to target station 1
	II, III or IV	—	—	_	Protocol level 4 is unusable.

Ranges accessible by MELSEC communication protocol of serial communication module

The ranges accessible using the MELSEC communication protocol of the serial communication module are given below. Refer to the following table for the PLC types given in the description.

Туре	СРИ Туре	Serial Communication Module Type	MELSECNET/10 Module Type	CC-Link Module Type
Ι	Q02/Q02H/Q06H/Q12H/ Q25H	QJ71C24 QJ71C24-R2	QJ71LP21,QJ71BR11	QJ61BT11
II	Q2A(S1)/Q3A/Q4A/ Q2AS(S1)/Q2ASH(S1)	AJ71QC24N AJ71QC24N-R2 A1SJ71QC24N A1SJ71QC24N-R2/R4	AJ71QLP21 AJ71QBR11 A1SJ71QLP21 A1SJ71QBR11	AJ61QBT11 A1SJ61QBT11
	A2U(S1)/A3U/A4U/ Q02-A/Q02H-A/ Q06H-A/ A2AS(S1)/A2USH-S1	AJ71UC24 AISJ71UC24-R2/R4	AJ71LP21, AJ71BR11 A1SJ71LP21 A1SJ71BR11	AJ61BT11 A1SJ61BT11
IV	Other than above			

If the combination of CPU module and communication module on a type basis is other than that shown in the above list, the accessible range may differ from the one given.

The levels of the MELSEC communication protocol supported by the serial communication modules are as listed below.

Serial Communication Module Type	Protocol Level
QJ71C24, QJ71C24-R2	1, 2, 3, 4
AJ71QC24N, AJ71QC24N-R2, A1SJ71QC24N, A1SJ71QC24N-R2/R4	1, 2, 3
AJ71UC24, AISJ71UC24-R2/R4	1

Protocol level 1 and level 2



PLC on path up to target station

Protocol level 3

Personal computer

Request Source

I, II, III or IV

III or IV

MELSECNET/

10



_

Protocol level 3 is unusable.

MODEL SELECTION NETWORK



	Condition 1	Condition 2	Condition 3	Condition 4	
Request source	Type of relay station	Type of networks 1	Type of relay	Type of target	Access Range
	1	to 8	stations 2 to 8	station 1	
Personal computer	1	MELSECNET/10	I, II or III	I	PLC on path up to target station 2
	1	MELSECNET/10	I, II or III	ll or III	PLC on path up to target station 1
	II, III or IV	—	—	_	Protocol level 4 is unusable.

MODEL SELECTION NETWORK

Network Overview

Whole network system configuration



Note 1: Usable in MELSECNET/10 mode. Unusable in MELSECNET/10H mode. (Driver of version SW3DNF-MNET10 or later is required.)

Ethernet: QJ71E71, QJ71E71-B2

Overview

MODEL SELECTION NETWORK

The Ethernet interface module (hereafter referred to as the "QJ71E71") is used on the PLC side to connect a host system, e.g. personal computer or work station, and Q mode PLC via Ethernet (10BASE5, 10BASE2, 10BASE-T) to collect/change PLC data, monitor CPU module operation, control the status, and transfer any data by TCP/IP or UDP/IP communication.

Currently, Ethernet is the most widespread network for connection of information processors such as personal computers and work stations. By using an Ethernet interface with the PLC, production-related management information can be transmitted rapidly to personal computers or work stations.

Features

10BASE5/10BASE2/10BASE-T

You can choose from three different network types of 10BASE5, 10BASE2 and 10BASE-T.

Communications with personal computer

For access from a personal computer to the PLC CPU, there is a communications function (Note 1) using the MELSEC communication protocol.

In data communications using the MELSEC communication protocol (hereafter referred to as the "MC protocol"), PLC data and program file read/write, PLC CPU status control (remote RUN/STOP), etc. can be performed from a host system. In this protocol, sequence programs are not needed since the PLC sends and receives all data under the commands of the host system. In communications using the MC protocol, one communication allows read/write of up to 960 points (960 words) of word devices.

Note 1: Equivalent to the PLC CPU data read/write communications function of the A/QnA series PLC.

Communication support software package

When the host system is a Windows personal computer, you can easily create a host system side communication program, without needing to be aware of the MC protocol by use of the optionally available communication support software package (SW3D5F-CSKP-E). CSKP offers general-purpose functions for Visual Basic and Visual C++.

Communications with personal computer and other PLCs

The communications function using fixed buffers is available to transfer data between the PLC and personal computer or another PLC.

In fixed buffer communications, the PLC can transmit data actively, so it can send data to the host system when a given condition holds at the occurrence of a machinery/equipment error. In data communications using fixed buffers, up to 1k word of data can be sent or received between PLCs or between PLC and host system. The 16 1k-word fixed buffers available for the QJ71E71 are used by allocating them as sending or receiving buffers to or from any equipment.

Communications of large volumes of data with personal computer

The communications function using random access buffer is available as a way to transfer 1k word or more data. In data communications using random access buffer, up to 6k words of data can be transferred. Large amounts of data can be transferred by use of the random access buffer communications function if data capacity is insufficient in fixed buffer communication (max. 1k word).

Communications with remote locations, automatic notice

Using the e-mail communication function, you can send or receive up to 6k words of data to or from a remote computer as an attached e-mail file. By setting automatic notice in transmission from the PLC, the QJ71E71 monitors the user-set notice conditions (PLC CPU status and device value) at fixed intervals and automatically sends e-mail when the notice conditions are true. Note that up to 16 e-mail addresses can be registered for transmission.

Communications with other PLCs

The communication function using data link instructions is available for read/write of device data and any data to/from other PLCs.

In communications using data link instructions, read/write of device data and any data from one PLC to another PLC, PLC CPU status control (remote RUN/STOP), etc. can be performed if data communication with other PLCs is made using Ethernet.

Ethernet is a registered trademark of XEROX CORP, U.S.A.

Number of simultaneously opened communication lines

Up to 16 communication lines can be opened (logical lines connected) for concurrent data communications. Two communication lines are used for sending and receiving by fixed buffer communications with the same equipment.

* Opening one communication line allows communications by MC protocol from host system, random accessing buffer communications, and fixed buffer communications from host system/PLC CPU (sending or receiving with protocol). The communication line for fixed buffer communications (sending or receiving) with no protocol does not permit combined use with another data communications system (such as communications using MC protocol).

Ease of parameter setting (programless)

Using the network parameter setting of "GPPW", you can make on-screen setting of the initial processing of the QJ71E71 and logical link processing (open processing) with other nodes, significantly simplifying sequence programs and enhancing the visual recognition of the network setting status.

Programming via Ethernet

PLC programming and monitoring can be performed from GPPW on a personal computer via Ethernet. With this function, you can perform programming/monitoring at a remote location utilizing the fast communication of Ethernet.

Communications via multiple networks

When accessing the PLC from the host system using the MC protocol, or when accessing the PLC from the GPPWinstalled personal computer, access can be made to the PLC located beyond multiple MELSECNET/10 and Ethernet networks.

Ethernet Module-Dedicated Instructions

The following Ethernet dedicated instructions can be used to program the QJ71E71 and QJ71E71-B2.

Class- ification	Inst- ruction Name	Description	Remarks
Connect- ion	OPEN	Opens connection.	Fundamental
process- ing	CLOSE	Closes connection.	Fundamental
	BUFRCV	Reads data received by fixed buffers.	Fundamental
	BUFRCV S	Reads data received by fixed buffers in interrupt program.	Fundamental
	BUFSND	Uses fixed buffers to send data of other- end equipment.	Fundamental
	MRECV	Receives e-mail.	Application
	MSEND	Sends e-mail.	Application
	RECVS	Reads channel data sent to own station (1 scan completion).	Application
	READ	Reads word device of other station.	Application
	RECV	Receives message.	Application
Comm- unication process-	REQ	Makes transient request to other station.	Application
ing	SEND	Sends message.	Application
	SREAD	Reads data from word device of other station (with completion device).	Application
	SWRITE	Writes data to word device of other station (with completion device).	Application
	WRITE	Writes data to word device of other station.	Application
	ZNRD	Reads data from word device of other station.	Application
	ZNWR	Writes data to word device of other station.	Application
Error process-	ERRCLR	Clears error (ERROR LED off, error log clear)	Fundamental
ing	ERRRD	Reads error information.	Fundamental

Ethernet: QJ71E71, QJ71E71-B2

"Fundamental" in the Remarks field indicates the instructions explained in the Ethernet User's Manual (Fundamentals) and "Application" indicates the instructions explained in the Ethernet User's Manual (Applications).

Program Compatibility

MODEL SELECTION NETWORK

The sequence program of the system which uses the A series/QnA series Ethernet interface module (e.g. A1SJ71E71-B2-S3, A1SJ71QE71-B2, hereafter referred to as the "E71") and the program of its host system can be utilized for the system using the QJ71E71.

E71 program usability for data communications which uses the QJ71E71 is be described below.

	Compatibility with Program for A Series Ethernet Module	Compatibility with Program for QnA Series Ethernet Module
Host system side program (Note 1)	Compatible However, only data in PLC is accessible in MC protocol. (Note 7)	Compatible (Note 5, 6)
PLC side program (Note 1)	Incompatible	Compatible (Note 2, 3,4)

- Note 1: In any of the above cases, performance and communications timings are incompatible, so communications may not be made by utilizing the program as it is. Always check operation when utilizing the program.
- Note 2: The QJ71E71 has no E^2 PROM. Delete an access program to E^2 PROM.
- Note 3: For the QJ71E71, it is not neccessary to set in the program whether communications are possible or not during PLC CPU STOP (GPPW parameters are used for setting). Delete the sequence program used for this setting.
- Note 4: The LED ON status/switch setting status read from the buffer memory of the QJ71E71 are different from those of the AJ71QE71.
- Note 5: When using the file transfer (FTP server) function, the default value of the FTP login name and FTP password specified on the external device side changes from "AJ71QE71" to "QJ71E71".
- Note 6: For file access in the Q series CPU using MC protocol, create a new program since a dedicated new command will be used.
- Note 7: Can be used in the same range as that of the conventional A series CPU for read/write communications (MC protocol level 1) of data in the PLC CPU compatible with the conventional A series E71.



*1 When connecting a cable, its flexing radius (R1: guideline value) near the connector should be (cable outline x 4) or more.

Function List

	Function	Outline
	MC protocol communications	Reads/writes data from/to CPU module in accordance with MC protocol from host system. PLC always performs passive processing.
Main functions	Communications using fixed buffers Random access buffer communications	Sends or receives data using 16 1k-word fixed buffers. Sequence program is required for data transfer. Sends or receives data using random accessing buffer (6k words) in QJ71E71. PLC reads/writes data from/to random accessing buffer, and host system accesses that data to make
2	Sending/receiving by e-mail	communications. Communicates data using e-mail. Can also be used with PLC monitoring function to transmit alarm information, etc. automatically by e-mail. Number of registerable e-mail addresses: 16 Number of monitoring function conditions: 1

MODEL SELECTION NETWORK

Ethernet: QJ71E71, QJ71E71-B2

	Function	Outline
	Router relay function	Can send data to personal computer, etc. located beyond router.
	Data link instruction	Instructions for data communication with other PLCs (MELSEC) via Ethernet.
	File transfer	Can transfer file by FTP. Can read/write programs and data stored in CPU module as files.
(0	Broadcasting	Sends data to all other personal computers, etc. within same segment using UDP/IP.
Sub functions	Existence check	Checks whether other nodes are operating properly or not if communications had not been made with other nodes for given period. (Use GPPW to set existence confirmed/not confirmed and time interval.)
	Error information	At occurrence of data communications error, stores in buffer memory up to 16 sets of error history information including message sub-headers, other-end equipment IP addresses, etc.
	Self loopback test	Checks hardware including communication circuit of Ethernet module. (Set from GPPW)

Performance Specifications

Item		Q	J71E71	QJ71E71-B2
Compatible cable		10BASE5	10BASE-T	10BASE2
Data transmission spe (bps)		10Mbps		
	Transmission method	Base band		
Transmission specifications	Max. inter-node distance (m (ft.))	2500 (8196.72)	4000 (13114.75)	925 (3032.79)
	Max. segment length (m (ft.))	500 (1639.34)	100 (327.87)	185 (606.56)
	Max. number of nodes	100 units/segment	1024 units/all hub (12 units)	30 units/segment
	Min. node interval (m (ft.))	2.5 (8.2)	—	0.5 (1.64)
	Number of simultaneously openable connections	16 connections (connections	s usable in sequence program)	
Data size	Fixed buffer size	1k word × 16 areas		
Data 320	Random accessing buffer size (E-mail attached file size)	6k words × 1 area		
	MC protocol communication	960 words		
	Fixed buffer communication	1k words		
	Random buffer communication (E-mail attached file)	6k words		
Max. number of data per communication	Data communication instructions RECVS, RECV, READ, SREAD, SEND, WRITE, SWRITE	480 words		
	Data communication instructions ZNRD, ZNWR	230 words		
Loadable station		Q series CPU (Q mode)		
Number of loadable modules		Max. 4 modules		
Number of I/O signals occupie		32 points		
5VDC internal current consum		0.8		
External dimensions (mm (inc	h))	98 (3.86) (H) × 27.4 (1.08) (W) × 90 (3.55) (D)		
Weight (kg (lb))		0.5 (1.1)		

Ethernet: QJ71E71, QJ71E71-B2



E-mail specifications

MODEL SELECTION NETWORK

Item	Specifications
Data size	6k words × 1
Data transfer method	Send/receive in the form of an attached file
	When two or more files are received, the first file is received and the others are discarded.
Attached file format	MIME format
MIME	Version 1.0
Data of attached file	Binary data or ASCII data may be selected.
	File name: *******.bin (binary), *******.asc (ASCII)
Encode/decode of attached file	base64
Subject	us=ascII format or ISO-2022-JP (base64)
Division	Attached file cannot be divided (max. 6k words/file)
	When divided files are received, the first file portion is received and the others are discarded.
Encryption function	No
Compression function	No
Communications with mail server	SMTP (sending server) port number=25 POP3 (receiving server) port number=110

System Equipment

The following equipment is required for configuring an Ethernet system.

10BASE-5: QJ71E71



<QJ71E71 accessories>

Product	Description
Manual	Ethernet Interface Module User's Manual (Hardware)

<Separately prepared products>

The following equipment must be prepared separately.

Product	Description
Transceiver	Ethernet Standard-compatible product. Product where SQETEST (Signal Quality
	Error Test) or heartbeat will operate.
Coaxial cable	Ethernet Standard-compatible product.
AUI cable	Ethernet Standard-compatible product.
N type terminator	Ethernet Standard-compatible product.
12VDC power supply	Power supply for transceiver

Note: Refer to <separately prepared manuals> on the next page for separately prepared manuals.

<Connectable products>

Product	Maker	Туре
Transceiver	Mitsubishi Cable Industries	ET-10081/ET-10071
	Optic Dai-Ichi Denko	CNT-101
	Makunika	JET-803
	TDK	CIU-1000
	Allied Telesys	CentreCOM106
		CentreCOM116
AUI cable	Hirakawa Hutech	HLTC-100B 4022

Ethernet: QJ71E71, QJ71E71-B2

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E or later	For sequence programming For Ethernet parameter setting	0
SW3D5F-CSKP-E	Communication support	\triangle
	software for personal computer	

 \bigcirc : Must be prepared. \triangle : Prepared as required.

Note: The software of the above products or later version are usable.



<QJ71E71 accessories>

Product	Description
Manual	Ethernet Interface Module User's Manual (Hardware)

<Separately prepared products>

The following separately prepared equipments are required up to hub connection.

Product	Description
Non-shielded twisted	Ethernet Standard-compatible product.
pair cable	Category 3 (4, 5)
Jack	Ethernet Standard-compatible product.
	RJ45
Hub	Ethernet Standard-compatible product. For
	10BASE-T.

Note: Refer to <separately prepared manuals> on the next page for separately prepared manuals.

The following product is usable as the hub for 10BASE-T. <Connectable products>

Product	Maker	Туре
Hub for 10Mbps	Allied Telesys	CentreCOM SB3012TR
		CentreCOM RH509S

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E	For sequence programming	0
or later	For Ethernet parameter setting	
SW3D5F-CSKP-E	Communication support	\triangle
	software for personal	
	computer	

 \bigcirc : Must be prepared. \triangle : Prepared as required.

Note: The software of the above products or later version are usable.

10BASE-2: QJ71E71-B2



<QJ71E71-B2 accessories>

Product	Description
Manual	Ethernet Interface Module User's Manual
	(Hardware)

<Separately prepared products>

The following equipment must be prepared separately.

Product	Description
Coaxial cable	Ethernet Standard-compatible product. RG-58A/U (50 Ω)
BNC type terminator	Ethernet Standard-compatible product (Nippon AMP's 221629-4 or equivalent)
T type connector	Ethernet Standard-compatible product (Hirose Electric's UG-274/U(1S) or equivalent)

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E	For sequence programming	0
or later	For Ethernet parameter setting	
SW3D5F-CSKP-E	Communication support	\triangle
	software for personal	
	computer	

 \bigcirc : Must be prepared. \bigtriangleup : Prepared as required.

Note: The software of the above products or later version are usable.

MODEL SELECTION NETWORK

Ethernet: QJ71E71, QJ71E71-B2

<Separately prepared manuals>

Ethernet Interface Module User's Manual (Fundamentals)

Specifications

Pre-operation settings and procedures Maintenance, inspection, troubleshooting Logical line connection method Communications using MC protocol (Note 1) Communications using fixed buffers Communications using random accessing buffer Dedicated instructions (instructions related to open processing) Ethernet Interface Module User's Manual (Applications)

How to confirm existence of other nodes E-mail function PLC CPU's monitoring function Function to make communications via MELSECNET/10 Function to make communications by data link instructions For use of file transfer (FTP server)

Dedicated instructions (instructions related to data transfer)

MELSEC Communication Protocol Reference Manual

Protocol specification manual that describes the functions with which the MC protocol for serial communication module/Ethernet module is compatible, their send and receive frames, and send and receive procedures.

Note 1: The description of the MC protocol is not given. For its description, refer to the MELSEC Communication Protocol Reference Manual.

Overview

MELSECNET/10H is a network system which has improved performance capabilities compared to MELSECNET/10, it has the functions and performance capabilities required to exercise centralized control of manufacturing lines by connection of multiple PLCs and a personal computer.

MELSECNET/10H network module has the functions of both MELSECNET/10 mode designed for connection to the existing MELSECNET/10 system constructed with the A series/QnA series PLCs and MELSECNET/10H mode where only the Q series PLCs are used to configure a network for higher performance. You have the choice between these modes.

Note 1: QJ71LP21 and QJ71BR11 may be used only for inter-PLC network. Note that they cannot be used as master station modules of a remote I/O network system. To make a remote I/O network system, use the CC-Link system (CC-Link master module QJ61BT11).

Features

High-speed network

The MELSECNET/10 and MELSECNET/10H are 10Mbps token passing networks. Since the transmission right is always assigned cyclically in a token passing network, data transmission can always be made if the number of connections or communications with the network increase. Hence, this network is suitable for facility control requiring real-time capabilities.

MELSECNET/10H is identical in communication speed to MELSECNET/10, the network module has shorter processing time to reduce the link scan time.

User-friendly network

MELSECNET/10 and MELSECNET/10H have a cyclic communication system for data communications. The cyclic communication system is designed to transfer periodically or automatically the data pre-specified in the network parameters and does not need programming for data transfer.

It also has dedicated devices of link relays B (ON/OFF data) and link registers W (16-bit numerical data) used for cyclic communication. B and W operate as the shared memories of that network and can be handled as ordinary

internal relays and data registers in programs, so you can create programs without having to think about the network configuration. (Note 2)

Note 2: The link relays B and link registers W are the names of data in the CPU. They are called LB and LW in the network module, respectively, and the data actually shared on the network are LB and LW. Since the CPU cannot handle LB and LW directly, LB/LW data are read into the CPU module after they are shifted to B/W.

To transfer larger volumes of data than MELSECNET/10, MELSECNET/10H has been increased from the 8k points LB and LW capacities of MELSECNET/10 to 16k points. If link relays B and link registers W are insufficient, you can use link inputs (LX) and link outputs (LY). Note that the link inputs and link outputs are different in usage from link relays and link registers, and they may be used only in 1-to-1 communications.



You can handle B000 controlled in one PLC as contact data in the other PLCs, without thinking about the network configuration.

Applicable cables

When configuring the MELSECNET/10H network system, optical fiber and coaxial cables are usable.

They have the following features.

- Optical fiber cables
- (1) Optical fiber has high noise immunity.
- (2) Long, 500m (1639.34ft.) / 1km (3278.69ft.) distance between stations for long-distance configuration.
- Coaxial cables
- (1) Cables can be fabricated easily by the user.
- (2) Cables are low in price.

High reliability

MODEL SELECTION NETWORK

When a problem occurs, network recovery may take a long time since many PLCs are connected over a wide range and cables are run in ducts and ceilings which are difficult to replace, etc. With emphasis on this point, the MELSECNET/10 and MELSECNET/10H have functions to increase reliability.

 Loopback function (Optical duplex loop system only)

With the optical loop cables duplexed, a faulty portion is separated at occurrence of a fault such as cable breakage or PLC failure to continue normal transmission with operable stations.



Station separating function (Coaxial bus system only)

When a station becomes faulty due to power-off, for example, that station is separated to continue normal transmission with operable stations.



Control station shifting function

When the specified control station is disconnected due to a fault such as power-off, the ordinary station replaces the specified control station (to act as a sub-control station) to continue communication.

Automatic return function

When the station disconnected as a faulty station is recovered from its cause of fault, it returns to the network automatically to resume data link.

Network monitoring

In the MELSECNET/10 and MELSECNET/10H network systems, the network status can be diagnosed easily by GPPW. If a fault occurs in the network, a fast search for a faulty portion can be made for ease of troubleshooting. Here are the following ways to diagnose:

- (1) Network diagnosis (own station information): Checks the status of the network of the connected host station.
- (2) Other station information: Checks the status of the network of the other specified station.
- (3) Network test: Makes link start/stop of the host station, specified station or all stations.
- (4) Setting confirmation test: Checks the station number, network number and group number set for each station.
- (5) Station sequence confirmation test: For optical loop system, checks the station sequence of forward/reverse loop on the network.
- (6) Loop test: Checks the loop status of the optical loop system.
- (7) Communications test: Checks whether communications can be made between the host station and specified station.

MELSECNET/10H mode system

When a network is made up of the Q mode PLCs only, choose the MELSECNET/10H mode. It can achieve fast, large-capacity communication, compared to MELSECNET/10 mode.

When using the QCPU (A mode), you cannot use the MELSECNET/10H modules. Use the AnS series MELSECNET/10 modules.

Optical or coaxial cables are used in the MELSECNET/10 network system.





MELSECNET/10 mode system

Choose the MELSECNET/10 mode when connecting the Q mode PLC to the existing MELSECNET/10 network system configured with the ACPU, QnACPU, etc. The QCPU (A mode) can also be connected to the MELSECNET/10 network.



MELSEC/10(H) Dedicated Instructions

For the QJ71LP21 and QJ71BR11, the

MELSECNET/10(H) dedicated instructions listed below can be used to create programs for data transfer other than cyclic communication.

Instruction	Description	Target Station
SEND	Writes data to target station network module	Q mode QnA/Q2AS
RECV RECVS	Reads data written by SEND instruction from network module. (RECVS is executed in interrupt program.)	QHA/QZAS
READ SREAD	Writes data to target station CPU module.	
WRITE SWRITE	Reads data from target station CPU module.	
REQ	Performs remote operation for target station CPU.	
ZNRD	Reads data from target station CPU module.	Q mode QnA/Q2AS
ZNWR	Writes data to target station CPU module.	A mode AnU/A2AS



Optical loop module



Comparison between MELSECNET/10H and MELSECNET/10

MODEL SELECTION NETWORK

		MELSECNET/10H	MELSECNET/10	MELSECNET/10	MELSECNET/10	Remarks
Host PLC type		Q mode	Q mode	QnA/Q2AS	A mode, AnU/A2AS	
Applicable other stat	ion PLC type	Q mode		de, QnA/Q2AS, A/AnS MELSECNET/10 board		
Number of cyclic points per network	LX/LY (1Bit)	0 to 1FFF (8192 points)		0 to 1FFF (8192 points))	
	LB (1Bit)	0 to 3FFF (16384 points)		0 to 1FFF (8192 points))	
	LW (16Bit)	0 to 3FFF (16384 points)		0 to 1FFF (8192 points))	
Number of cyclic transmission points	Cyclic communications	Max. 2000 bytes		Max. 2000 bytes		Total of LY, LB and LW
per station	Low-speed cyclic	Max. 2000 bytes		No		
Communication spee	ation speed 10Mbps 10Mbps 10Mbps 10Mbps				10Mbps	
Link scan time		Short	Normal	Normal	Normal	
Inter-PLC network an network	nd remote I/O	Inter-PLC network	Inter-PLC network	er-PLC network Inter-PLC network, remote I/O network		
Cable	Optical SI/QSI- 200/250	0	0	0	0	(Note 2)
	Optical GI/50/125	×	×	0	0	
	Coaxial (3C/5C- 2V)	0	0	○ (simplex bus, duplex loop)	○ (simplex bus, duplex loop)	
Max. number of netw	vorks	239	239	239	255	
Dedicated	ZCOM	0	0	0	0	Check the details
instructions	REQ	0	0	0	×	of the dedicated
	ZNRD, ZNWR	0	0	0	0	instructions in the
	READ, WRITE, SREAD, SWRITE	0	0	0	×	relevant programming
	SEND, RECV	0	0	0	×	manual.
	ZNFR, ZNTO	×	×	0	0	
	RFRP, RTOP	×	×	0	0	
Routing function		(Note 1)	(Note 1)	(Note 1)	(Note 1)	
32-bit data split preve	ention function	Yes	No	Yes	No	

Note 1: Accessible to the PLC on the network located beyond seven relay (gateway) PLCs which connect two MELSECNET/10H,

MELSECNET/10 or Ethernet networks. Note that the A mode does not have the Ethernet relay function.

Note 2: Some cables are not compatible with some CPU types. Check details in the corresponding catalog.

Connection with the Existing Network System

This section describes the compatibility of the Q mode PLC for additional connection to the existing

MELSECNET network.

- Note 1: The compatibility specifications of the A mode PLC with the existing network are different from those of the Q mode PLC. The A mode PLC has the same network connectability as that of the AnS and can be connected to all networks to which the AnS can be connected.
- Connecting the Q mode PLC to the existing MELSECNET/10 (inter-PLC network)



MODEL SELECTION NETWORK

MELSECNET/10H: QJ71LP21, QJ71BR11

[Modules required for Q mode PLC] QJ71LP21: For optical SI/QSI cable QJ71BR11: For coaxial 75 ohm cable [Instructions]

Use the QJ71LP21/QJ71BR11 in the MELSECNET/10 mode. They are not compatible with the GI optical cable.

Connecting the existing MELSECNET/10 (inter-PLC network) and new MELSECNET/10H network (Method 1)



[Modules required for relay PLC]

Module 1

QJ71LP21: For optical SI/QSI cable

QJ71BR11: For coaxial 75 ohm cable

Module 2

QJ71LP21: For optical SI/QSI cable

QJ71BR11: For coaxial 75 ohm cable

[Instructions]

Use module 1 in the MELSECNET/10 mode.

Module 2 may also be used in the MELSECNET/10H mode.

Connecting the existing MELSECNET/10 (inter-PC network) and new MELSECNET/10 network (Method 2)



[Modules required for relay PLC] Module 1 (existing module) MELSECNET/10 module compatible with A/AnS/QnA/Q2AS Module 2 (newly added module) AJ71LP21/A1SJ71LP21/AJ71QLP21(S)/A1SJ71QLP21 (S): For optical SI/QSI cable AJ71BR11/A1SJ71BR11/AJ71QBR11/A1SJ71QBR11: For coaxial 75 ohm cable [Instructions] Module 1 is the existing MELSECNET/10 module. Module 2 is a MELSECNET/10 module for A/AnS/QnA/Q2AS.

Changing the master module of the existing MELSECNET/10 (remote I/O network) for the Q mode PLC

You cannot replace the master module of the existing MELSECNET/10 (remote I/O network) with the Q mode PLC. The Q mode PLC is not compatible with the MELSECNET/10 remote I/O network.



Connecting the Q mode PLC to the existing MELSECNETII or MELSECNET/B network

You cannot connect the Q mode PLC to the existing MELSECNETII or MELSECNET/B network.



MODEL SELECTION NETWORK

MELSECNET/10H: QJ71LP21, QJ71BR11

Connecting the existing MELSECNET (II) or MELSECNET/B network and new MELSECNET/10 network



[Modules required for relay PLC] Module 1 (existing module)

Function List

MELSECNET (II) or MELSECNET/B module compatible with A/AnS/QnA/Q2AS

Module 2 (newly added module)

AJ71LP21/A1SJ71LP21/AJ71QLP21(S)/A1SJ71QLP21

(S): For optical SI/QSI cable

AJ71BR11/A1SJ71BR11/AJ71QBR11/A1SJ71QBR11:

For coaxial 75 ohm cable

[Instructions]

Module 1 is the existing MELSECNET (II) or

MELSECNET/B module.

Module 2 is an MELSECNET/10 module for A/AnS/QnA/Q2AS.

			Usable Mode			
	Function	Outline	MELSECNET/ 10H	MELSECNET/ 10		
	Cyclic communication	Refreshes link relays and link registers assigned in network common parameters periodically to all stations in the same network.	0	0		
	Low-speed cyclic communication	Using this system to communicate data which does not require high-speed communication reduces ordinary cyclic communication data volumes and increases speed.	0	×		
	Transient communication	Uses network instructions in sequence program to transfer data to/from stations specified in instructions. Several different instructions give choice of data transfer methods.	0	0		
function	Group function	You can specify multiple stations on the same network as a certain group. By specifying a group for data transmission in transient communication, data can be broadcasted to specific stations only.	0	0		
Data communication function	Multiplex transmission function	In duplex loop system, data can be transmitted using each loop of duplex loop. This enables faster communication than 10Mbps.	0	0		
Inww	Refresh data split prevention	Prevents data from being transmitted 16 bits-by-16 bits during 32-bit data transmission.	0	×		
ata cc	Network debugging mode	When adding PLC to existing network, data transmission from that station is shut off and only data receiving is performed until its program debugging is completed.	0	×		
ä	Interrupt program start	Can cause some station to interrupt CPU module of another station to start sequence program.	0	×		
	Inter-data link transfer	When there are multiple networks, some of data communicated cyclically in one network is automatically transferred to another network	0	0		
	Routing function	When there are multiple networks, data can be transferred to/from station on network where own station is not connected directly. This function is used when monitoring PLC located beyond multiple networks on GPPW software.	0	0		
	Reserved station designation	When there are no stations set in network common parameters, it is recognized as an error and affects link scan time. Error recognition and link scan time delay are not caused if stations planned to be added in future are specified as reserved stations.	0	0		
	Control station shift function	If control station fails to make communication due to some fault, another station automatically serves as control station to continue network control, preventing whole system from being faulty.	0	0		
u	Specified control station return mode selection	You can select whether faulty control station that has returned to normal will return as ordinary station or control station.	0	×		
RAS function	Automatic return function	When station that suspended communication due to some fault returns to normal, it participates in communication automatically.	0	0		
RASf	Loopback function	If cable breakage occurs in duplex loop type network, communication is continued as long as transmission route is established.	0	0		
	Station separation function	If some station is powered off in simplex bus type network, it does not affect other normal stations.	0	0		
	Network duplexing	One CPU module can each be loaded with two network modules to duplex network.	0	0		
	Network diagnostics	Network status and each station status can be monitored using GPPW software.	0	0		

2-48

Performance Specifications

		MELS	MELSECNET/10H				
Item		QJ71LP21	QJ71BR11				
Connection form		Duplex loop type	Simplex bus type				
Max. number of link	LX/LY	8192 points (8k bits)					
points per network	LB	MELSECNET/10 mode: 8192 points (8k bits), ME	LSECNET/10H mode: 16384 points (16k bits)				
	LW	MELSECNET/10 mode: 8192 points (8k bits), ME	LSECNET/10H mode: 16384 points (16k words)				
Max. number of link po	ints per station	[LW+LB+LY<=2000 bytes (cyclic communication) communication)]]+[LW+LB+LY<=2000 bytes (low-speed cyclic				
Transient transmission	capacity	Max. 1920 bytes/frame					
Communication speed		10Mbps					
Communication system	n	Token passing					
Synchronous system		Flag synchronization (frame synchronization syste	Flag synchronization (frame synchronization system)				
Modulation system		Base band system					
Transmission sign		NRZI (Non Return to Zero Inverted)	Manchester				
Cable type		Optical (SI/QSI)	Coaxial 75 Ω (3C-2V/5C-2V)				
Transmission frame fo	rmat	HDLC conformance (frame format)					
Error control system		CRC (X16+X12+X5+1) and time-out retry					
Max. number of netwo	rks	239					
Max. number of groups	3	32					
Number of stations cor	nected	64 stations (1: control station, 63: normal station)	32 stations (1: control station, 31: normal station)				
Max. number of modul	es loaded per CPU	4 modules					
Overall distance		30km (98360.66ft.) (inter-station distance SI: 500m (1639.34ft.) /QSI: 1km (3278.69ft.)	500m (1639.34ft.) (5C-2V) / 300m (983.61ft.) (3C- 2V)				
Distance extension rep	eater	_	Up to 2.5km (8196.72ft.) by connection of max. four repeaters				
Number of I/O points o	ccupied	32 points (I/O assignment, 32 intelligent points)	· · ·				
Internal current consur	nption (5VDC)	0.55A	0.75A				
Weight (kg (lb))		0.11 (0.24)	·				

Cyclic Communications Time

The following calculation expressions are used to find the normal values of cyclic communications time (transmission delay time) in the MELSECNET/10H mode and MELSECNET/10 mode. (Since they are not the worst values, the time taken may become longer than the values given depending on the timing.)

	MELSECNET/10H Mode	MELSECNET/10 Mode
Transmission delay time TD1	$ \begin{array}{c} TD1=ST+\ \pmb{\alpha}\ T+(LSx1)+(SRx2)+\ \pmb{\alpha}\ R \\ \\ \hline ST\ : Sending\ side\ sequence\ program\ scan\ time \\ SR\ : Receiving\ side\ link\ refresh\ time \\ \hline \pmb{\alpha}\ T:Sending\ side\ link\ refresh\ time \\ \hline \pmb{\alpha}\ R:Receiving\ side\ link\ refresh\ time \\ \hline LS\ : Link\ scan\ time \\ \end{array} $	TD1=ST+ α T+(LSx2)+(SRx2)+ α R
	LS : Link scan time	

MODEL SELECTION NETWORK

MELSECNET/10H: QJ71LP21, QJ71BR11

		MELSECN	NET/10H	Mode				MEL	SECNET	/10 Mode	
Max. link refresh time $ lpha $ T,	ατ, α	α T, α R=KM1+KM2×{LB+LX+LY+SB+(LW×16)+(SW×16)						+8+(number of network modules-1)			
α R [ms]	LB: Total number of link relay LB points refreshed by that station										
	LW: Total number of link register LW points refreshed by that station										
	LX: Total number of link input LX points refreshed by that station										
		LY: Total	number c	of link outp	ut LY point	ts refreshe	ed by that	station			
		SB: Numb	per of link	special re	lays						
		SW: Num	ber of linl	k special re	egisters						
		KM1, KM2	2: Consta	nts							
			Netv	vork Modu	le Loaded	in Main B	ase	Network N	lodule Loa Bas	aded in Exte e	nsion
				KM1	ł	KM2 (X10 ⁻	-3)	KM1		KM2 (X1	0 ⁻³)
		QnCPU		0.30		0.48		0.30		1.20	
		QnHCPU		0.13		0.41		0.13		0.97	
	Ν	Nore time will be ta	ken if the	e data refre	esh destina	ation is a f	ile register	on the me	emory card	d or inter-dat	a link tra
	function is to be performed.										
Link scan time LS [ms]	LS=KB+0.45× total number of stations					LS	LS=KB+0.75× total number of stations				
	+(LB+LY+LW×16)÷8×0.001+(T×0.001)+(F×4)						+(LB+LY+LW×16)÷8×0.001+(T×0.001)+(F×4)				
	L	_B: Total number o	f link rela	ıy (B) point	ts of all sta	itions on n	network				
	L	W: Total number of	of link reg	gister (W) p	points of al	Il stations	on networ	k			
	L	Y: Total number o	f link out	out (Y) poi	nts of all st	tations on	network				
	٦	T: Total number of	f bytes tra	ansient-tra	nsmitted d	luring one	link scan				
		When transien						le stations	s during or	ne link scan,	this
		value is the tota		•							
	F	= : Number of retu	•	•				,		•	
		indicates the nu		stations wi	nich will re	turn to net	twork wher	n faulty sta	itions retui	n to normal	and
		reenter data linl	K.								
	r	KB: Constant									
		Total	1 to 8	9 to 16	17 to 24	25 to 32	33 to 40	41 to 48	49 to 56	57 to 64	
		number									
		of									
		stations KB	4.0	4.5	4.0	5.3	5.7	6.2	66	7.0	
		KB I	4.0	4.5	4.9	0.3	15/	6.2	6.6	10	

The following expressions are used to calculate the transmission delay time.

(Conditions)	
Sending and receiving side CPU modules	: Q06HCPU
Position where network module is loaded	: Main base unit
Number of stations	: Total number of stations = 8
Number of cyclic data points of all stations on network	: LB=1024 points, LW=1024 points, LX, LY=0 points
Sending side sequence program scan time ST	: 1ms
Receiving side sequence program scan time SR	: 1ms
On both sending and receiving sides, cyclic data of all s	stations on network are to be refreshed

On both sending and receiving sides, cyclic data of all stations on network are to be refreshed.

	MELSECNET/10H Mode	MELSECNET/10 Mode		
Sending side link refresh time $ lpha $ T [ms]	α T=KM1+KM2x{LB+LX+LY+SB+(LW×16)+(S W×16)}÷8+(number of network modules-1) =0.13+0.41×10 ⁻³ x{1024+0+0+512+ (1024×16)+(512×16)}÷8+(1-1) =1.47ms			
Receiving side link refresh time $ lpha $ R [ms]	α T=KM1+KM2x{LB+LX+LY+SB+(LWx16)+(S Wx16)}÷8+(number of network modules-1) =0.13+0.41×10 ⁻³ x{1024+0+0+512+ (1024x16)+(512×16)}÷8+(1-1) =1.47ms	 		
Link scan time LS [ms]	LS=KB+0.45×total number of stations+ (LB+LY+LW×16)÷8×0.001+(T×0.001)+ (F×4) =4.0+0.45×8+ ((1024+0+1024×16) ÷8×0.001)+(0×0.001)+ (0×4) =9.78ms	LS=KB+0.75×total number of stations+ (LB+LY+LW×16)÷8×0.001+(T×0.001)+ (F×4) =4.0+0.75×8+ ((1024+0+1024×16) ÷8×0.001)+(0×0.001)+ (0×4) =12.18ms		
Transmission delay time TD1 [ms]	TD1=ST+ α T+(LSx1)+(SRx2)+ α R =1+1.47+(9.78x1)+(1x2)+1.47 =15.72ms	TD1=ST+ α T+(LSx2)+(SRx2)+ α R =1+1.47+(12.18x2)+(1x2)+1.47 =30.30ms		





<QJ71LP21 accessories>

Product	Description	
Manual	QJ71LP21/BR11 MELSECNET/10H	
	Network Module User's Manual	

<Separately prepared products>

The following equipment (manual) must be prepared separately.

Product	Description	
Optical cable	SI/QSI cable	
Manual	MELSECNET/10H Reference Manual	

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E	For sequence	0
or later	programming	
	For MELSECNET/10H	
	parameter setting	

 \bigcirc : Must be prepared. \bigtriangleup : Prepared as required.

Note1: The software of the above products or later version are usable.



<QJ71BR11 accessories>

Product	Description	
Manual	QJ71LP21/BR11 MELSECNET/10H	
	Network Module User's Manual	
Connector	F type BNC connector	

<Separately prepared products>

MODEL SELECTION NETWORK

The following equipment (manual) must be prepared separately.

Product	Description	
Coaxial cable	3C-2V/5C-2V (JISC3501 conformance)	
Connector plug	Connector plug for 3C-2V/5C-2V	
Termination resistor	A6RCON-R75 (75 Ω termination resistor)	
Manual	MELSECNET/10H Reference Manual	

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E	For sequence	0
or later	programming	
	For MELSECNET/10H	
	parameter setting	

 \bigcirc : Must be prepared. \bigtriangleup : Prepared as required.

Note2: The software of the above products or later version are usable.

Applicable Optical Cables

Optical fiber cable specifications

For purchasing of optical fiber cables, consult your sales representative.

Applicable optical cables

	SI Cable	QSI Cable
Core/clad diameter	200/220 µ m	185/230 µ m
Transmission loss (@wavelength 830 to 880nm)	Max. 12dB/km	Max. 5.5dB/km
Applicable connector	CA7003 DL-72ME	CA7003

MELSECNET/10H: A6BR10, A6BR10-DC

Repeater Module for Coaxial Bus

The A6BR10 and A6BR10-DC coaxial bus repeater modules are designed to increase an overall distance in the coaxial bus system of the MELSECNET/10 or MELSECNET/10H network system.

Functions

(1) One module can increase the distance by 500m (10000 oth) (200 0)



(2) Up to four modules can be used in one network. The overall distance can be increased to 2.5km

(8196.72ft.) (five networks 500m (1639.34ft.)).



(3) If the A6BR10 becomes faulty, the network is broken at the A6BR10 and communication continues in respective networks.

In the following example, data link is made between 1) and 2) and between 3) and 4) when the A6BR10 becomes faulty.



MELSECNET/10H: A6BR10, A6BR10-DC

Performance Specifications				
Item			A6BR10	A6BR10-DC
Comm	nunicatio	n	10Mbps	
Numb	er of mo cted/net		Max. 4 modules	
Exten			300m (983.61ft.) (3C-2V)	
-	ce/unit Il distanc	e	500m (1639.34ft.) (5C- 300m (983.61ft.)×5=1.5	
			(3C-2V) 500m (1639.34ft.)×5=2 (5C-2V)	· · · ·
Numb conne	er of stat	ions	Max. 32 stations	
conne	Voltag	e	100 to 240VAC (+10%/-15%)	24VDC (+30%/-35%)
	Freque	ency	50/60Hz±5%	—
ply	Max. appare power	ent	21VA	-
dns	Max. p	ower	—	9W
Input power supply	Inrush	ł	40A, within 8ms	17A, within 1ms
rt bo	Efficier		65% or more	65% or more
ndul	Permiss instanta power fi time	sible ineous	20ms	10ms
	Curren consur		0.2A	0.6A
	uous ala		ERR1: On when A6BR10 becomes faulty	
	nission ng outpu	t	(power off, error occurrence). ERR2: On when A6BR10 is normal.	
	Isolatio		Non-isolated	
	metho Rated	b		
	switchi voltage	÷	24VDC 2A (resistive load) 240VAC 2A (COS ϕ =1)	
	/curren Minimu switchi	ım	5VDC 1mA	
	load Maxim		264VAC 125VDC	
	switchi load	ng		
	Respo time	nse	OFF to ON: 10ms or less ON to OFF: 12ms or less	
	Life	Mec-	10 million times or more	
		han- ical		
		Elec-	Rated switching voltage	
		trical	thousand times or more 200VAC 1.5A, 200VAC	
			thousand times or more	9
			200VAC 1A, 200VAC 0	0.5A (COS <i>ϕ</i> =0.35) 100
			thousand times or more 24VDC 1A, 100VDC 0.1A (L/R=7ms) 100	
			thousand times or more	
	Surge suppre	ssor	No	
suppressor External wiring				ERR1 External load
			Internal circuit	External load
Weigh	it (kg (lb))	0.5 (1.1)	

MODEL SELECTION NETWORK

Equipment

<A6BR10, A6BR10-DC accessories>

Product Description		
Manual	A6BR10, A6BR10-DC User's Manual	
Connector	T type BNC connector (2 pcs.)	

<Separately prepared products>

The following equipment (manual) must be prepared separately.

opulatoly

Product	Description	Remarks
Coaxial cable	3C-2V/5C-2V (JISC3501 conformance)	0
Connector plug	Connector plug for 3C- 2V/5C-2V	0
Termination resistor	A6RCON-R75 (75 Ω termination resistor)	0

 \bigcirc : Must be prepared. \bigtriangleup : Prepared as required.

Overview

CC-Link (Control & Communication Link) designed for merger of control and communication is a wiring-saving and information network which has the industry's latest advanced functions and performance capabilities, e.g. real-time capability, decentralized control, communication with intelligent equipment and RAS (Note 1) function, and also offers multi-vendor environment in conjunction with various field equipment manufacturers.

The QJ61BT11 CC-Link modules for Q mode inherit the features of the MELSEC-A/QnA series and newly adopt useful functions such as remote device station initial setting function.

Note 1: RAS stands for Reliability, Availability, Serviceability.

Features

System configuration

A total of 64 remote I/O, remote device, local, standby master and intelligent device stations can be connected to one master station.



CC-Link station types

CC-Link has the following station types.

CC-Link Station Type	Description
Master station	Controls all stations on CC-Link. One station is required in one system.
Local station	Has CPU and can communicate with master and other local stations.
Standby master station	Replaces master station when it becomes faulty and continues data link as master station.
Remote I/O station	Handles bit data only.
Remote device station	Handles bit and word data.
Intelligent device station	Handles bit and word data. Can also make data transfer irregularly.

Communication speed and distance

The industry's fastest class communication speed (10Mbps) ensures compatibility with the sensor input which requires fast response and with communication with intelligent equipment which needs large volumes of data communication. Also you can choose the optimum communication speed and overall distance according to your system.

Communication Speed	Overall Distance
10Mbps	100m (327.87ft.)
5Mbps	150m (491.8ft.)
2.5Mbps	200m (655.74ft.)
625Mbps	600m (1967.21ft.)
156Mbps	1200m (3934.43ft.)

Cyclic communication system

MODEL SELECTION NETWORK

The CC-Link cyclic communication system is shown below. In CC-Link, the cyclic data areas of the master and local stations are assigned to respective remote I/O, remote device and intelligent device stations, and remote I/O and remote register data are refreshed automatically. Also, since information from the master station to the remote I/O, remote device and intelligent device stations are transmitted to other local stations, the operating statuses of the remote stations can also be acquired by the local stations.



CC-Link cyclic communication data

Communica	tion Method	Description		
Cyclic communication	Bit transmission	32 points I/O data communications per station.		
	Word transmission	4-point write/read data communications per station.		

Link devices

In addition to a total of 4096 points of bit data per CC-Link system, the cyclic communication of a total of 512 points of word data permits rapid communication with Factory Automation equipment products such as remote I/O and analog modules, indicators and inverters.

lte	Specifications		
Max. number of link	Remote input (RX)	2048 points	
points	Remote output (RY)	2048 points	
	Remote register (RWw)	256 points	
	Remote register (RWr)	256 points	
Number of link points	Remote input (RX)	32 points	
per station	Remote output (RY)	32 points	
	Remote register (RWw)	4 points	
	Remote register (RWr)	4 points	

- Note 1: Remote input (RX) indicates ON/OFF data (bit data) input from remote station to master station and is represented by RX for convenience.
- Note 2: Remote output (RY) indicates ON/OFF data (bit data) output from master station to remote station and is represented by RY for convenience.
- Note 3: Remote register (RWw) indicates numerical data (word data) output from master station to remote station and is represented by RWw for convenience.
- Note 4: Remote register (RWr) indicates numerical data (word data) input from remote station to master station and is represented by RWr for convenience.

Transient communication

In addition to cyclic communication where data are transmitted periodically and automatically, CC-Link can use the transient communication system where data are transferred irregularly. Transient communication can be made by the master, local and intelligent device stations and can perform the following processes.

- (1) A PLC reads/writes device data, etc. from/to another PLC.
- (2) The master PLC transfers data to/from an intelligent device station.

- (3) GPPW programming software is used to read/write or monitor the program of another PLC.
- (4) The host personal computer, etc. reads/writes device data from/to a PLC.

Automatic CC-Link start

In a system consisting of only the master and remote I/O stations, simply switching power on initiates data link automatically without setting of the network and automatic refresh parameters.

- Note 5: Data link is started on the assumption that there are 64 remote I/O stations. If there are less than 64, the link scan time is not optimized. To optimize, set the network and automatic refresh parameters.
- Note 6: This function cannot be used if there are stations other than the master and remote I/O stations (e.g. remote device, intelligent device stations).

High-speed link scan

In a system consisting of only the master and remote I/O stations, choosing the remote I/O network mode reduces the link scan time.

(At communication speed of 10Mbps)

Number of Stations	Remote I/O Network Mode	Remote Network Mode (Normal Mode)		
16	1.02ms	1.57ms		
32	1.77ms	2.32ms		
64	3.26ms	3.81ms		

Multi-vendor

We have gone into partnerships with many Japanese and foreign equipment manufacturers to connect a wide variety of field equipment directly to CC-Link in order to help reduce wiring.

We realized an open network where you can use the optimum field equipment worry-free from among many choices.

Refer to the CC-Link Catalog L(NA)74108143 for the partner maker products and remote I/O, remote device and intelligent device stations that may be connected to CC-Link.

Standby master function

MODEL SELECTION NETWORK

By setting a standby master station, data link can be continued if a fault occurs in the master station. When the master station returns to normal during operation performed by the standby master station, it can return to data link as a standby station. If the standby master station becomes faulty during operation in this status, the master station on standby continues data link.



Remote device station registration function

Using GPPW, initial setting can be made to a remote device station without creating a sequence program. The setting example and setting items are shown below.

Setting items for remote device station registration function

Setting Item	Description		
Execution flag	Setting of whether set data is valid or invalid.		
Operating condition/procedure execution condition	Set write conditions.		
Execution data	Set write devices and write data.		

Start of interrupt program (event interrupt)

The interrupt program of the CPU module can be started when data is received from the network and the set conditions hold.

This ensures compatibility with the system which requires faster processing.

You can set up to 16 interrupt program starting conditions. The conceptional diagram and execution conditions are shown below.



Interrupt program starting condition devices

Set Device	Description		
RX, RY, SB	ON/OFF		
RWr, SW	Match/mismatch with set value		

Remote operation

From the GPPW software linked to a PLC on CC-Link, remote programming can be performed for another PLC.





Dedicated instructions

The following dedicated instructions are available for transient transmission.

Target Station	Instru -ction	Description		
Master station	RIRD	Reads data from buffer memory or CPU device of target station.		
Local station	RIWT	Writes data to buffer memory or CPU device of target station.		
	RIRD	Reads data from buffer memory of target station.		
Intelligent device station	RIWT	Writes data to buffer memory of target station.		
	RIFR	Reads contents of automatic updating buffer of target station.		
	RITO	Writes data to automatic updating buffer of target station.		

Program Compatibility

The existing program can be utilized by using A to Q program conversion or QnA to Q program conversion of GPPW.

Note 1: The RLPA network parameter setting instruction and RRPA automatic refresh parameter setting instruction are not supported. After deleting the RLPA/RRPA instruction, set the CC-Link parameters using the network parameters of GPPW.



Part names

Name		Description		
LED indicators	RUN	ON: Module is normal. OFF: Module is abnormal.		
	ERR.	 ON: All stations in communications error Lit at occurrence of any of the following errors. Switch or control setting is abnormal. There is more than one master station on the same line. Parameter setting error Data link watchdog timer activated. Cable broken or transmission path affected by noise, etc. Flicker: There is a station with communications error. 		
	MST	ON: Master station operation		
	S MST	ON: Standby master station operation		
	L RUN	ON: Data link during execution (Host station) ON: Communications error (Host station) Flicker: Switch setup is changed during power-on.		
	L ERR.			
	SD	ON: Data being transmitted.		
	RD	ON: Data being received.		
Station number setting switches	Used to set the station number of the module. (Factory setting: 0) <settings> Master station: 0 Local stations: 1 to 64 Standby master stations: 1 to 64</settings>			
	Standby master stations: 1 to 64 "ERR." LED is lit if setting is other than 0 to 64.			

MODEL SELECTION NETWORK

CC-Link: QJ61BT11

Name	Description				
Transmission speed/mode setting switch	status o	Used to set the transmission speed and operating status of the module. (Factory setting: 0)			
	No.	Transmission speed Mode			
	0	Transmission speed 156kbps	Online		
	1	Transmission speed 625kbps			
	2	Transmission speed 2.5Mbps			
	3	Transmission speed 5Mbps			
	4	Transmission speed 10Mbps			
	5	Transmission speed 156kbps	Line test At station number		
	6	Transmission speed 625kbps	setting of 0: Line test 1		
	7	Transmission speed 2.5Mbps	At station number setting of 1 to 64:		
	8	Transmission speed 5Mbps	Line test 2		
	9	Transmission speed 10Mbps			

Name	Description				
Transmission	No.	Transmission speed	Mode		
speed/mode setting switch	А	Transmission speed 156kbps	Hardware test		
	в	Transmission speed 625kbps			
	с	Transmission speed 2.5Mbps			
	D	Transmission speed 5Mbps			
	E	Transmission speed 10Mbps			
	F	Must not be set (reserv	ved for system)		

Comparison of Q-Compatible CC-Link and AnS/Q2AS-Compatible CC-Link

		Rem	Remote I/O Network Mode			mote Network N	Remarks	
PLC type	LC type Q mode QnA/ A mode, Q2AS AnU/ A2AS		Q mode	QnA/ Q2AS	A mode, AnU/ A2AS			
CC-Link module ty	/pe	QJ61BT11 AJ61QBT11, AJ61BT11, A1SJ61QBT11 A1SJ61BT11			QJ61BT11	AJ61QBT11, A1SJ61QBT11	AJ61BT11, A1SJ61BT11	
Connectable remo	ote/local station	Remote I/O station		Remote I/O station, remote device station, intelligent device station, local station, standby master station				
Communication sp	beed	Max. 10Mbps						
Number of cyclic	RX (1Bit)	0 to 7FF (2048 points)		0 to 7FF (2048 points)				
points per	RY (1Bit)	0 to 7FF (204	0 to 7FF (2048 points)		0 to 7FF (2048 points)			
network	RWr (16Bit)	No	No		0 to FF (256 points)			
	RWw (16Bit)	No			0 to FF (256 points)			
Number of cyclic	RX	32 points			32 points			
points per	RY	32 points			32 points			
remote station	RWr	_	_		4 points			
	RWw	_	1_		4 points			
Link scan time	Link scan time Short		Normal					
CC-Link automation	c start function	No		Yes (Note 1)	No			
CC-Link: QJ61BT11

				(Continue	u)			
		Rer	note I/O Network	Mode	Rei	mote Network N	lode	Remarks
PLC type		Q mode	QnA/ Q2AS	A mode, AnU/ A2AS	Q mode	QnA/ Q2AS	A mode, AnU/ A2AS	
CC-Link module	e type	QJ61BT11	AJ61QBT11, A1SJ61QBT11	AJ61BT11, A1SJ61BT11	QJ61BT11	AJ61QBT11, A1SJ61QBT11	AJ61BT11, A1SJ61BT11	
Standby master function		No		Yes When master station returns to normal from failure status, it can return to network.	Yes When master station returns to normal from failure status, it can not return to network.			
Remote device function	station registration	No			Yes	No		
Interrupt progra	m start	Yes	/es No		Yes	No		
Network param GPPW	eter setting from	Yes	Yes	No	Yes	Yes	No	
Dedicated instructions	RLPA, RRPA	×	×	×	×	×	0	Network parameter, automatic refresh parameter setting (compatible with A1SJH/A1SH/A2SH only)
	CCL, CCLEND	×	×	×	×	0	×	Mail box registration
	SPCCLR, SPCBUSY	×	×	×	×	0	×	Suspension of transfer to/from intelligent device station Remote station status read
	RIRD, RIWT	×	×	×	0	0	0	Data transfer to/from target station
	RISEND, RIRCV	×	×	×	0	0	0	Transfer to/from RS232 module with handshake
	RIFR, RITO	×	×	×	0	0	0	Access to automatic updating buffer

(Continued)

Note 1: Only remote I/O stations are connectable.

Function List

Item	Outline
Cyclic communication function	Communication function by link device RX/RY/RWr/RWw between master, remote I/O, remote device, intelligent device and local stations
Transient communication function	Communication function for data transfer by CC-Link dedicated instructions or for program read/write by GPPW programming software between master, intelligent device and local stations
Automatic CC-Link start	If made up of remote I/O stations only, network can be started without parameter setting.
Remote device station initial setting function	Initial setting data to remote device stations is set in parameters for program deletion.
Scan synchronization function	Cyclic communication is synchronized with program scan of master station CPU module.
Standby master function	When master station is disconnected due to a fault, standby master station replaces it to continue
	communication.
Interrupt program start	When specified condition data is received, interrupt program of CPU module is started.
Slave station separation function	Only module that failed to make data link due to power-off, etc. is separated and data link continues with normal modules only.
Automatic return function	When returning to normal, module disconnected from data link due to power-off, etc. automatically takes part in data link.
Reserved station function	By setting remote and local stations to be connected in future as reserved stations, you can set them so that they will not be handled as data link error stations.
Error-invalid station setting function	You can set module that failed to make data link due to power-off, etc. so that they will not be handled as data link error stations.
Temporary error-invalid station setting function	Communications with station where communication error occurred is suspended temporarily to prevent delay in link scan time.
Station number overlap checking function	Checks for multiple remote stations of the same station number.

Performance Specifications

MODEL SELECTION NETWORK

	Item	Specifications				
ttions	Max. number of link points	Remote I/O (RX, RY): 2048 points each Remote register (RWw): 256 points (master → remote, local stations) Remote register (RWr): 256 points (remote, local stations → master)				
Control specifications	Number of link points per station	Remote I/O (RX, RY): 32 points each (30 points for local stations) Remote register (RWw): 4 points (master → remote, local stations) Remote register (RWr): 4 points (remote, local stations → master)				
Contro	Max. number of stations occupied (for local stations)	4 stations (max. number of I/O points 128 points, link register 32 points)				
	Transient transmission	Max. 1024 bytes/station				
Performance	Link scan time (at 10Mbps)	3.3ms (remote I/O 2048 points, in remote I/O network mode, normal value) 4.4ms (remote I/O 2048 points, remote register 512 points, in remote network mode, normal value)				
	Communication speed	10M/5M/2.5M/625k/156kbps				
	Communication system	Polling				
	Synchronous system	Frame synchronization system				
	Encryption system	NRZI system				
(0	Transmission path form	Bus (RS-485)				
iou	Transmission format	HDLC conformance				
ficat	Error control system	CRC (X ¹⁶ +X ¹² +X ⁵ +1)				
Communication specifications	Number of modules connected	64 modules Note that the following conditions must be satisfied. $(1xa)+(2xb)+(3xc)+(4xd) \le 64$ a: Number of 1 station occupying modules b: Number of 2 station occupying modules c: Number of 3 station occupying modules d: Number of 4 station occupying modules $(16xA)+(54xB)+(88xC)+(4xd) \le 2304$ A: Number of remote I/O stations ≤ 64 B: Number of remote device stations ≤ 42 C: Number of local, standby master and intelligent device stations26				
	Remote station number	1 to 64				



(Continued)

	Item					Specifica	ations				
	Max. overall cable length and inter- station cable length	System configuration (1) made up of remote I/O and/or remote	Remote statio or Remote devic station	e Mast	er station	Remote st or Remote de station	ation evice	Remo Remo st	te station or te device ation	Remote Remote stati	station r device ion
		device stations		*2		* 2	*			* 1]
		only	◄	ጥ ሬ		ax. overall c				τ I	
			* 1 Inter-station c * 2 Inter-station c	able length b CC-Link de	etween remot etween maste dicated cable	e I/O or remote er station and ac	device sta ljacent stat	tion and ion CC-Link	dedicated, h	igh-performa	ance cable
					tion resistor u tion cable	sed) Max.			0 Ω termina Inter-sta	tion resistor tion cable	used) Max.
			Commu- nication	ler	ngth	overall cable	nie	mmu-	ler	igth	overal cable
			speed	* 1	*2	length		peed	*1	* 2	length
			156kbps	30cm (11.82 inch) or	1m (39.4 inch) or	1200m (3934.43 ft.)	150	Skbps	30cm (11.82 inch) or	1m (39.4 inch) or	1200m (3934.4 ft.)
			625kbps	more	more	600m (1967.21 ft.)	62	ōkbps	more	more	900m (2950.8 ft.)
			2.5Mbps			200m (655.74 ft.)	2.5	Mbps			400m (1311.4 ft.)
			5Mbps	30cm (11.82 inch) to 59cm (23.25		110m (360.66 ft.)	5M	bps	No. of connected modules: 1 to 32 30 cm 30		160m (524.59 ft.)
ifications				inch) * 60cm (23.64 inch) or more	-	150m (491.8ft.)		ules: 1 to 32			100m (327.87 ft.)
Communication specifications			10Mbps	30cm (11.82 inch) to 59cm (23.25 inch) *		50m (163.93 ft.)		No. of connected mod			
0				60cm (23.64 inch) to 99cm (39.01 inch) *		80m (262.3ft.)		nodules: 33 to 48			80m (262.3f
				1m (39.4 inch) or more		100m (327.87 ft.)	10Mbps	of		•	100m (327.87 ft.)
								ules: 49 to 64	30cm (11.82 inch) to 39cm (15.37 inch) *		20m (65.57f
								of connected modules: 49	40cm (15.76 inch) to 69cm (27.19 inch) *		30m (98.36f
							_	No. 6	70cm (27.58 inch) or more		100m (327.87 ft.)

MODEL **SELECTION NETWORK**

			(Continue	ed)					
	Item					Specifications				
	Max. overall cable length and inter- station cable length	System configuration (2) made up of remote	Master station	n Rem	ote station or ote device tation	Remote station or Remote device station	Intellige	l station or ent device ation	Local s or Intelligen stati	r t device
		I/O, remote device, local, standby								
		master and intelligent device	H	*1		* 1 ax. overall cable	* 2		* 2	
Communication specifications		stations	* 2 Inter-station c	able length b CC-Link de ΩΩ termina Inter-sta	etween remo	ote I/O or remote device er station and adjacen	e station and t station CC-Link	t dedicated, h 0 Ω termina Inter-sta	ar remote dev high-performant tition resistor tition cable (39.4 inch) or more	ance cable
			•			within this range of t			•	
						and remote I/O or re	emote devi	ce station,	the max. ov	/erall
	Connection cable	<u> </u>	cable length is			cated, high-perform	ance cable			
	Number of I/O points	occupied	32 points (I/O as							
S	Internal current consu		0.46	Signment						
Others				09 (3 96) 🗆	× 00 (2 FE)					
0	External dimensions (mm (inch))		27.4 (1.08) W × 98 (3.86) H × 90 (3.55) D							

0.12 (0.26) Note 1: CC-Link dedicated cables and CC-Link dedicated, high-performance cables cannot be used together.

Weight (kg (lb))



<QJ61BT11 accessories>

Product	Description			
Termination resistor	110 Ω , 130 Ω , 2 pcs. each			
Manual	QJ61BT11 User's Manual (Hardware)			

<Separately prepared products>

The following equipment must be prepared separately. Product

Product	Description
CC-Link cable	Choose CC-Link cable partner maker product. For details, refer to CC-Link
	catalog.
Manual	QJ61BT11 User's Manual (Details)

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E	For sequence	0
or later	programming	
	For CC-Link parameter	
	setting	

O : Must be prepared. \triangle : Prepared as required.

Note 2: The software of the above products or later version are usable.

MODEL SELECTION NETWORK

MELSECNET/MINI-S3: A1SJ71PT32-S3, A1SJT32-S3

Overview

The MELSECNET/MINI-S3 is a wiring-saving remote I/O network using plastic fiber or twisted pair cables. The A2C series I/O and special modules, FX series PLC, partner maker solenoid valves and others can be connected to MELSECNET/MINI-S3 as remote modules.

Features

System configuration



The master module of the MELSECNET/MINI-S3 can be used with QAS1S3 B or QAS1S6 B.

Connectable remote modules

The modules which may be connected are all conventional remote I/O modules that may be connected to MELSECNET/MINI-S3, such as the remote I/O of MELSECNET/MINI-S3 and A2C series. For full information on the usable modules, refer to the MELSEC-AnS catalog.

Please note that the following software is necessary for remote I/O modules other than digital remote I/O modules. SW0IVD-MINIP-E

Twisted pair cable specifications

Item	Specifications
Cable type	Shielded twisted pair cable
Number of pairs	2P or more
Conductor resistance	88.0 Ω /km max. @20°C
Capacitance	Average 60nF/km max. @1kHz
Characteristic impedance	110 ± 10 Ω

Optical cable specifications

Item	Specifications
Туре	Plastic fiber cable
Transmission loss	260dB/km max.
Fiber OD	1000 µ m
Connector	1-core connector
Permissible flexing radius	25mm (0.99inch)

Optical fiber cables are available from Mitsubishi Electric System Service.

Restrictions on use with Q mode

The following MELSECNET/MINI-S3 dedicated instructions compatible with the A/QnA cannot be used with the Q mode. Programming must be performed using the FROM/TO and similar instructions.

Unusable instructions	INPUT, PRN, PR, MINI, MINIERR,
	SPBUSY, SPCLR

The Q mode CPU does not have the MELSECNET/MINI automatic refresh function.

MELSECNET/MINI-S3: A1SJ71PT32-S3, A1SJT32-S3

Performance Specifications

		A1SJ71	PT32-S3	A1SJ71T32-S3		
Compatible cable		Optical cable	Twisted pair cable	Twisted pair cable		
Number of master me	odules loaded	No restriction				
Per master module Max. number of link stations		64 stations (Note 1)				
	Number of I/O points	512 points				
I/O refresh time		3.2 to 18ms (when 64 stations are connected) (Note 2)				
Communication spee	ed	1.5Mbps				
Max. inter-station dis	tance	1 (3.28ft.) to 1 (3.28ft.) to 1 (3.28ft.) to 50m (163.93ft.) 100m (327.87ft.) 100m (327.87ft.) (Note 3) (Note 4) (Note 4)				
Number of I/O points	occupied	I/O dedicated mode: 32 points, extension mode: 48 points				
5VDC internal curren	t consumption	0.35A 0.3A				
Weight		0.6kg (1.32lb)				

Note 1: The max. number of link stations indicates that the total number of occupied stations assigned to remote modules is up to 64. However, the max. number of connectable remote terminal modules (number of occupied stations: 4) is 14.

Note 2: The I/O refresh time changes with the number of remote module stations connected, their type, and the operating mode of the master module.

Note 3: Communications may not be made if the inter-station distance of the optical cable is less than 1m (3.28ft.). When the 2VTPE-1 cable (Mitsubishi Cable Industries make) is used, the max. inter-station distance is 35m (114.75ft.).

Note 4: The max. inter-station distance changes with the twisted pair cable diameter used. It is 50m (163.93ft.) for cables of not less than 0.2mm² to less than 0.5mm², and 100m (327.87ft.) for cables of not less than 0.5mm².

MELSEC-I/O LINK: A1SJ51T64

Overview

MODEL SELECTION NETWORK

The MELSEC-I/O LINK is a simple, wiring-saving remote I/O network that does not need network parameter setting and can be programmed as if you are using ordinary I/O modules.

It can control 64 points of input or output (up to 128 points when 8- or 16-point composite modules are used) per network. This network uses a multidrop bus wiring system and is flexible enough to permit T branching. In addition, it does not require termination resistors.

Features

System configuration



The A1SJ51T64 can be used with QA1S6 B.

Connectable remote I/O

The I/O which may be connected are all conventional remote I/O modules that may be connected to the MELSEC-I/O LINK.

For full information on the usable modules, refer to the MELSEC-A [small/mid-scale-compatible types] catalog.

Twisted pair cable specifications

Item	Specifications		
Cable type	Shielded twisted pair cable	Cabtyre cable	
Wire diameter, number of pairs	0.75mm ² $ imes$ 1P	0.75mm ² ×2C	
Conductor resistance	29 Ω/km max. @20º C		
Capacitance	75nf/km max. @1kHz	_	
Characteristic impedance	100 ନ	_	
Insulation resistance	500M Ω or more		
Withstand voltage	500VAC 1 minute or longer		
OD	ϕ 8.5mm max. ϕ 9mm max.		

Restrictions on use with Q mode

No restrictions.

Item	Specifications
Max. number of I/O	128 points (when I/O composite
points	remote modules are used)
I/O refresh time	Approx. 5.4ms
Applicable	Twisted pair cable or cabtyre cable
communication cable	0.75mm ² or more
Communication speed	38.4kbps
Synchronous system	For frame synchronization and bit synchronization
Error control	Parity check
Transmission path	Bus system (T branching possible,
form	termination resistors not needed)
Transmission distance	Overall 200m (Overall 665.74feet)
Number of I/O points	64 points
occupied	
External power supply	24VDC (+15%/-10%)
rated voltage	(for transmission path)
External power current	Typ 90mA @24VDC
consumption	
Internal current	115mA
consumption (5VDC)	
Weight (kg (lb))	0.3 (0.66)

B/NET: A1SJ71B62-S3

Overview

B/NET is Mitsubishi Electric's network designed for power distribution control equipment. Connecting power distribution control equipment distributed within a building or plant to B/NET allows centralized management and centralized control of the power distribution control equipment.

The A1SJ71B62-S3 is an interface designed for B/NET PLC and accepts up to 63 stations of transmission terminals.

Features

System configuration



The A1SJ71B62-S3 can be used with QA1S6_B.

Connectable remote modules

B/NET transmission terminals are connectable. For details of the transmission terminal, refer to the Mitsubishi B/NET facility monitoring system catalog.

Twisted pair cable specifications

Item	Specifications
Cable type	Local pair polyethylene insulation vinyl
	sheathed cable (with shield) JCS 224B
Number of pairs	1
Conductor diameter	Φ 1.2
Conductor	16.5 Ω/km max. @20ºC
resistance	
Insulation	10,000M Ω / km or more
resistance	
Withstand voltage	1000VAC 1 minute or longer

Restrictions on use with Q mode

No restrictions.

Item	Specifications	
Max. number of transmission	63 stations	
terminals connected		
Data capacity	2048 words	
Max. transmission distance	1km (3278.69feet) (overall	
	distance)	
Transmission path	Bus	
Communication protocol	CSMA/CS survival system	
Data transfer volume	Max. 16 bytes	
Error control	Even parity, sumcheck	
Applicable cable	CPEV-S Ø 1.2	
	(Twisted pair cable)	
Number of I/O points	32 points	
occupied		
Internal current consumption	170mA	
(5VDC)		
Weight (kg (lb))	0.38 (0.84)	

JPCN-1 Field Network: A1SJ71J92-S3, A1SJ72J95

Overview

JPCN-1 is a field network for PLC standardized by the Japan Electrical Manufacturers' Association and can control JPCN-1-compatible slave stations, such as remote I/O, solenoid valves, robots and indicators, from the master PLC.

Features

System configuration



The A1SJ71J92-S3 can be used with QA1S6_B. The A1SJ72J95 can be used with A1S3_B.

Modules connectable to slave stations

The A1SJ72J95 slave station module may be loaded in the CPU slot of the A1S3 B to control the AnS series I/O modules (A1SX \Box , A1SY \Box).

The AnS series special, network and I/O composite modules cannot be loaded.

Twisted pair cable specifications

Item	Specifications
Cable type	Shielded twisted pair cable
Number of pairs	2P or more
Conductor resistance	88.0 Ω /km max. @20º C
Capacitance	Average 60nF/km max. @1kHz
Characteristic	110 ± 10 Ω
impedance	

Restrictions on use with Q mode

When device memory data in the master PLC are accessed by slave stations by the GET-PUT service, the accessible ranges are limited as indicated below.

Devi	се Туре	Range
Х		0 – 7FF
Y		0 – 7FF
M/L/S		0 – 8191
В		0 – FFF
Т	Contact	0 – 2047
	Coil	0 – 2047
	Current value	0 – 2047
	Set value	0 – 2047
С	Contact	0 – 1023
	Coil	0 – 1023
	Current value	0 – 1023
	Set value	0 – 1023
D		0 – 6143
W		0 – FFF
F		0 – 2047

Item	Specifications			
Item	A1SJ7	1J92-S3	A1SJ72J95	
JPCN-1 compliant class	TYPE-M52I (master	station)	TYPE-S52I (slave station)	
Communication speed	125k/250k/500k/1M	bps		
Communication system/modulation system/ electrical characteristic/transmission path	Half duplex synchror	Half duplex synchronous communication/NRZI system/EIA RS485/bus format		
Overall distance	Depends on communication speed. 125kbps: 1000m (3278.69feet),250kbps: 800m (2622.95feet), 500kbps:480m (1573.77feet), 1Mbps: 240m (786.89feet)			
Number of stations connected	Up to 31 slave stations to one master station			
Transmission right control	Polling/selecting			
Service type	Initial setting Broadcasting I/O Message write Reset Message read Data write GET Data read PUT		Initial setting I/O Reset	
Number of link points	Input + output \leq 2048	8	Input + output \leq 2048	
Number of I/O points occupied	32 points	32 points		
Internal current consumption (5VDC)	0.4A		0.4A	
Weight (kg (lb))	0.31(0.68)		0.43 (0.68)	

S-LINK: A1SJ71SL92

Overview

The A1SJ71LS92 is a master module connected to SUNX's S-LINK equipment to control it. S-LINK can control 128 points per master module and be used as a wiring-saving network.

Features

System configuration



The A1SJ71SL92 can be used with QA1S6_B.

Connectable remote modules

The S-LINK equipment of SUNX Ltd. can be connected.

Restrictions on use with Q mode

No restrictions.

Item		Specifications	
Transmission system		Bidirectional time-sharing	
		multiplex transmission	
		system	
Synchroniza	ation system	Bit synchronization system,	
		frame synchronization	
		system	
Transmissio	n protocol	S-LINK protocol	
Transmissio	n speed	28.5kbps	
Transmissio	n distance	Signal trunk: Max. overall	
		distance 200m (655.74feet)	
		(400m (1311.48feet)when	
		booster is used)	
Connection system		T-branching multidrop	
		connection/multidrop	
		connection[+24V•0V•D•G	
		(with short protection across	
		D-G)]	
Number of b	oranches	10 branches max.	
Number of c	ontrol I/O points	128 points	
External	24VDC ±10%	24VDC ±10% /permissible	
power	/permissible	ripple p-p±10% or less	
supply for	ripple p-p±10%		
S-LINK or less			
system	Across D-G:	Across D-G: 1.60A, across	
	1.60A, across	+24-0V: 5.00A	
+24-0V: 5.00A			
Number of I	O points occupied	32 points	
Internal curr	ent consumption	0.2A	
(5VDC)			
Weight (kg (lb))	0.27 (0.59)	

MODEL SELECTION NETWORK Profibu

Profibus-FMS / Profibus-DP interface: A1SJ71PB96F / A1SJ71PB92D

Overview

The A1SJ71PB96F is a Profibus-FMS network interface module to connect MELSEC PLC to a Profibus-FMS network.

Profibus-FMS is used to connect various kinds of controllers such as PLC, CNC, robot controllers, etc. produced by different manufacturers.

The A1SJ71PB92D is a Profibus-DP network interface module to connect various field sensors and actuators to a MELSEC PLC. Because Profibus-DP is an open network, sensors and actuators of various manufacturers can be connected to the network.

Features



A1SJ71PB96F and A1SJ71PB92D can be used with QA1S6 B.

Performance Specifications

Network configuration software

The following software is necessary to configure parameters in A1SJ71PB96F and A1SJ71PB92D. MELSEC PROFIMAP Ver.2.0 or later

Restrictions on use with Q mode

The ranges of devices in the PLC available as Local Object Dictionary for A1SJ71PB96F are limited as indicated below.

D	evice Type	Range
Х		0 – 7FF
Y		0 – 7FF
M/L/S		0 – 8191
В		0 – FFF
Т	Contact	0 – 2047
	Coil	0 – 2047
	Current value	0 – 2047
	Set value	0 – 2047
С	Contact	0 – 1023
	Coil	0 – 1023
	Current value	0 – 1023
	Set value	0 – 1023
D		0 - 6143
W		0 – FFF
F		0 – 2047

Item	A1SJ71P	B96F	A1SJ71PB92D		
Compatible network	Profibus-FMS		Profibus-DP		
Function	Client or Server		Master		
Transmission speed & distance	9.6k/19.2k/93.75k bps	1,200m (3.937ft)	9.6k/19.2k/93.75k bps	1,200m (3.937ft)	
	187.5k bps	600m (1.969ft)	187.5k bps	600m (1.969ft)	
	500k bps	200m (656ft)	500k bps	400m (1,312ft)	
	1.5M bps	1.5M bps 100m (328ft)		200m (656ft)	
			3M/6M/12M bps	100m (328ft)	
No. of nodes	32,62 with 1 repeater, 92	32,62 with 1 repeater, 92 with 2 repeaters, 122 with 3 repeaters			
No. of repeaters	3 repeaters max. per ne	3 repeaters max. per network			
Max. No. of slave nodes			60		
Transmission data size	Max 241 bytes/transmis	Max 241 bytes/transmission		Max. 32 bytes/transmission	
Current consumption (5VDC)	0.56A	0.56A			

DeviceNet: A1SJ71DN91

Overview

The A1SJ71DN91 is a DeviceNet network interface module to connect various field sensors and actuators to a MELSEC PLC. Because DeviceNet is an open network, senseors and actuators of various manufacturers can be connected to the network.

Features

System configuration



AISJ71DN91 can be used with QA1S6 B.

Performance Specifications

Network configuration software

Network parameter in A1SJ71DN91 can be configured by using PLC program. However, the following software may be used instead.

SysCon Ver.2.0.6.2 or later including DLL file Ver.2.5.0.1 or later.

Please contact to the following companies for pufchase of SysCon software.

Sysergetic Maicro Systems, Inc., USA:

+1-630-434-1770

Hilscher Gesellschaft, Germany:

+49-6190-9907-0

NPS Ltd., Japan

+81-3-3226-8110

Restrictions on use with Q mode

No restriction.

	Item	Specifications					
Node type		Group 2 dedicated client					
Station num	ber range	0 to 63					
No. of slave	nodes	Max.63					
Data size	I/O communication	2048 points	(256 bytes) each	for send receive	e		
	Message communication	240 bytes each for send and receive					
Communication speed & distance		Speed	Truck cable max. distance			Drop cable	
			Thick cable	Thin cable	Thick/thin cable combination	Max.	Total
		125k bps	500m	100m	See the	6m	156m
			250m		table below		78m
		500k bps	100m				39m
Consumption on network 2		26.5mA					
Occupied I/	O points	32					
Consumption current (5VDC)		0.24A					
Weight		0.23kg					

Combined distance of thick and thin cables

Communication speed Max. combined distance of thick and thin cables	
125k bps	(Thick cable distance + 5) × thin cable distance \leq 500m
250k bps (Thick cable distance + 2.5) × thin cable distance \leq 250m	
500k bps	Thick cable distance $ imes$ thin cable distance \leq 100m

Modbus interface: A1SJ71UC24-R2-S2 / A1SJ71UC24-R4-S2

Overview

The A1SJ71UC24-R2-S2 and A1SJ71UC24-R4-S2 are Modbus interface modules. These modules support slave functions of ASCII and RTU protocols to connect MELSEC PLC to SCADA system.

Features

System configuration



Main base: Q3⊟B – A1SJ71UC24-R2/R4-S2

Extension base: QA1S6 B

AISJ71UC24-R2-S2 and AISJ71UC24-R4-S2 can be used with QA1S6_B.

Supported Modbus functions

The following Modbus functions are supported by these modules. Please note that these modules support only Modbus slave functions.

Function	Description	
01	Read coil status	
03	Read holding register	
05	Present single coil	
06	Present single register	
07	Read exception status	
08	Loopback test	
11	Fetch event counter communication	
12	Fetch event communication event log	
15	Force multiple coils	
16	Force multiple registers	
17	Report slave ID	
20	Read general reference-584 only	
21	Write general reference-584 only	

Restrictions on use with Q mode

The ranges of devices in the PLC available to be accessed through the Modbus modules are limited as indicated below.

Device	е Туре	Range
Х		0 – 7FF
Y		0 – 7FF
M/L/S		0 – 8191
В		0 – FFF
Т	Contact	0 – 2047
	Coil	0 – 2047
	Current value	0 – 2047
С	Contact	0 – 1023
	Coil	0 – 1023
	Current value	0 – 1023
D		0-6143
W		0 – FFF
F		0 – 2047

Item	A1SJ71UC24-R2-S2	A1SJ71UC24-R4-S2		
Supported protocol	Modbus ASCII and Modbus RTU	Modbus ASCII and Modbus RTU		
Interface	RS-232	RS-422/485		
Transmision mode	Half-duplex			
Syncronization	USART	USART		
Speed	300, 600, 1200, 2400, 4800, 9600, 1	300, 600, 1200, 2400, 4800, 9600, 19200bps		
Data format	Start bit: 1, Data bits: 7 or 8, Parity:	Start bit: 1, Data bits: 7 or 8, Parity: even/odd/none, Stop: 1 or 2		
Frame check	LRC for ASCII, CRC for RTU	LRC for ASCII, CRC for RTU		
Distance	15m			
Occupied I/O points	32	32		
Consumptiion current	0.1A	0.1A		

Overview

The A1SD51S is a module equipped with two RS232C ports and one RS422 port to permit creation of two BASIC language programs which operate in multitask mode. Communication protocols which are too complex to be created in a sequence program can be created using the BASIC language.

Features

System configuration



Main base: Q3∏B A1SD51S

Extension base: QA1S6 B

The A1SD51S can be used with QA1S6_B.

Programming software

The following software programs are available as a console for BASIC programming and for saving created programs.

SW1IX-AD51HP-E

Restrictions on use with Q mode

When the A1SD51S accesses the devices in the PLC, their ranges are limited as indicated below.

D	evice Type	Range
Х		0 – 7FF
Y		0 – 7FF
M/L/S		0 – 8191
В		0 – FFF
Т	Contact	0 – 2047
	Coil	0 – 2047
	Current value	0 – 2047
	Set value	0 – 2047
С	Contact	0 – 1023
	Coil	0 – 1023
	Current value	0 – 1023
Set value		0 – 1023
D		0 – 6143
W		0 – FFF
F		0 – 2047

Item	Specifications
Programming	D51H-BASIC
language	
Number of tasks	2 tasks
Task starting condition	At power-on, start from PLC CPU, start from other task
Internal memory	Program memory: 64k bytes/2 tasks
	Common memory: 8k bytes
	Expanded register: 1024 points (2k
	bytes)
	Expanded relay: 1024 points
I/O to/from PLC CPU	Input 27 points, output 17 points
Buffer memory	3k words
Communication port	RS232C 2ch, RS422 1ch
Number of I/O points	32 points
occupied	
Internal current	0.4A
consumption (5VDC)	
Weight (kg (lb))	0.3 (0.66)

ID Interfaces: A1SJ71ID1-R4, A1SJ71ID2-R4, A1SD32ID1, A1SD32ID2

Overview

The A1SJ71ID1-R4, A1SJ71ID2-R4, A1SD32ID1 and A1SD32ID2 are interface modules designed to connect one or two reader/writers of the Mitsubishi D series/D-NS series ID system.

Using the ID system moves information together with the object to be controlled. Therefore, information management can be facilitated and you can easily perform exceptional processing in production.

Features

System configuration



The A1SJ71ID1-R4, A1SJ71ID2-R4, A1SD32ID1 and A1SD32ID2 can be used with QA1S6_B.

Performance Specifications

Specifications Item A1SJ71ID1-R4 A1SJ71ID2-R4 A1SD32ID1 A1SD32ID2 D-422RW, D-422RWL D-NS422RW Compatible reader/writer Number of modules 1 2 1 2 connectable Connectable cable D-422CAB10 (10 (32.79)), D-NS422CAB10 (10 (32.79)), (m (feet)) D-422CAB30 (30 (98.36)), D-NS422CAB20 (20 (65.57)), D-422CAB50 (50 (163.93)), D-NS422CAB40 (40 (131.15)), D-422CAB100 (100 (327.87)) D-NS422CAB100 (100 (327.87)) D-03C, D-03CS, D-03P, D-8P, D-8PS, D-8PX D-NS03P, D-NS03PS, D-NS03PM Usable data carrier Number of I/O points 32 points occupied Internal current 0.1A 0.1A 0.15A 0.3A consumption (5VDC) Weight (kg (lb)) 0.63 (138.60) 0.26 (57.20) 0.27 (59.40)

Restrictions on use with Q mode

The following QnA-compatible instructions dedicated to ID interfaces cannot be used with the Q mode. The FROM/TO instruction, etc. must be used for programming.

Unusable	IDINT1, IDINT2, IDRD1, IDRD2, IDWD1, IDWD2, IDARD1, IDARD2, IDAWD1, IDAWD2, IDCMP1, IDCMP2, IDFILL1, IDFILL2, IDCOPY1, IDCOPY2
instructions	IDWD2, IDARD1, IDARD2, IDAWD1,
	IDAWD2, IDCMP1, IDCMP2, IDFILL1,
	IDFILL2, IDCOPY1, IDCOPY2

IMPORTANT

These ID products are radio transmitting devices. Please confirm these products comply with local laws and regurations for radio transmitting devices before use.

Overview

The serial communication module (hereafter referred to as the "QJ71C24") can connect an external device and Q series PLCs by a serial communication line (RS-232, RS-422, RS-485) to achieve the following functions. Also, connection of an external modem/terminal adaptor permits data communications to be made with a remote external device via a dialup line/ISDN line.

- (1) An external device (e.g. personal computer, display) performs the collection/changing of PLC data and the operation monitoring and status control of the CPU module to manage and monitor the PLC side facilities.
- (2) Measurement data, etc. is collected from external devices (e.g. temperature controller, bar-code reader).
- (3) Messages and numerical data, etc. is output to an external device (e.g. printer) for printing.
- (4) Data is transferred to/from external devices and other PLCs.
- (5) A personal computer in which the GPPW function software package (SW4D5C-GPPW-E or later, hereafter referred to as "GPPW") has been installed is connected to perform programming and other operations for the Q series CPU.

Features

Fast, large-capacity communication

The communication port of the QJ71C24 permits communication at max. speed of 115.2kbps and can make max. 960 words of data communications in one communication with MC protocol communications.

Communications with personal computer

To exercise PLC monitoring control from a personal computer, the MELSEC communication protocol (Note 1) can be used to perform PLC data read/write, etc. Using this protocol, PLC device data and program file read/write, PLC CPU status control (remote RUN/STOP), etc. can be performed from an external device (e.g. personal computer, display).

The PLC transfers all data under commands from the external device and does not need sequence programs. Note 1: This protocol is called "dedicated protocol" in the A/QnA series PLC and referred to as the MC protocol.

Communication support software package

When an external device is a Windows personal computer, using the optionally available basic communication support tool (SW3D5F-CSKP-E) allows you to create external device side communication programs without being concerned with the details of the protocol (communication procedure) for MC protocol.

Transmission of data from PLC to personal computer

Communication using MC protocol cannot transmit data at the desired timing of the PLC since it transfers all data under commands from the personal computer (PLC always performs passive processing).

The on-demand function is designed to interrupt MC protocol communications to actively send data from the PLC. Using this function, data can be transmitted to the external device when a machinery/equipment error occurs or when a given condition holds.

- Note 2: The on-demand function is unavailable for a system which uses the communication support software package on the personal computer side.
- Note 3: To use the on-demand function to send data, a sequence program is required.

Communications with measuring instruments such as bar-code reader

The data communications function using the no protocol mode can be used to transfer data between the PLC and printer/bar-code reader/measuring instrument, etc, in the communication protocol determined by the external device. The no protocol mode is a function designed to communicate any data using a sequence program and can be used in accordance with the protocol of the external device. Note that data generation, transmission frame generation, receiving frame data extraction, send/receive procedure control and others must all be performed in sequence programs.

SELECTION NETWORK Serial (

Serial Communication Modules: QJ71C24, QJ71C24-R2

Communications with personal computer and other PLCs

The bidirectional protocol can be used to communicate any data with other PLCs or the external device which can be matched in communication procedure with the PLC. For example, this protocol is applicable to a case where mutual communication is made between a certain PLC and another remote PLC which would be difficult to use Ethernet or MELSECNET/10 with.

Notification function from PLC

MODEL

The notification function is available to facilitate the external monitoring of PLC equipment. With notification conditions preset to the QJ71C24, the notification function automatically collects and sends data within the CPU to external devices when those conditions (time intervals and CPU data states) hold. When an alarm occurs, it can also transmit alarm data to external devices without sequence program. If modems are connected, it can notify pagers.

This function can be used when the MC protocol or no protocol is used.

Communications using user-registered frame

A user-registered frame is a transferred frame whose header (head of the transferred frame) and footer (end of the transferred frame) are preregistered. These header and footer are added automatically when the data is sent, and are automatically removed when the data is received. This function is applicable to the data frames which are transferred in the no protocol mode and those sent by the on-demand function and notification function in the MC protocol. Normally, the transmission destination and source addresses included in the headers need not be added for each transmission in sequence programs. Also, checksum can be calculated as required and added when data is sent, and frame check can be made when data is received.

Independent operation of communication ports

The two channels of communication ports (interfaces) of the QJ71C24 allow any of the different operation modes (MELSEC communication protocol, no protocol, bidirectional protocol) to be set per port for use in separate communication applications.

Programming via QJ71C24

You can perform PLC programming and monitoring from GPPW on a personal computer through the RS-232 serial communication line. When the peripheral device connecting interface of the Q series CPU is already used, programming/monitoring can be made from GPPW via the QJ71C24.

Communications via multiple networks

When access to the PLC is made from the GPPWinstalled personal computer in data communications made from the host system in the MC protocol, other PLCs located beyond MELSECNET/10 and Ethernet are accessible.

Remote communications using modem function

The QJ71C24 has a telephone line modem-compatible function which initializes the modems used and performs connection processing with devices to allow communications with remote devices and modems through a telephone line.

After the line has been connected, data communications can be made by full duplex communication in the MC protocol/no protocol/bidirectional protocol.

Serial Communication Modules: QJ71C24, QJ71C24-R2

Instructions Dedicated to Serial Communication Modules

The following serial communication-dedicated instructions can be used to program the QJ71C24 and QJ71C24-R2.

Instruction	Description	Protocol	Target Station	
ONDEMAND	Data transmission using on- demand function	М	Funda- mental	
OUTPUT	Transmission of specified data	Ν		
INPUT	Data receiving (Read of receive data)	N		
BIDOUT	Data sending	Bi		
BIDIN	Data receiving (Read of receive data)	Bi		
BUFRCVS	Receiving of data in interrupt program (Read of receive data)	N/bi	Appli- cation	
PRR	Data sending in user-registered N frame using transmission schedule table			
SPBUSY	Read of data sending/receiving status using each dedicated instruction	M/N/ bi		
PUTE	Registration (write) of user- registered frame to flash ROM	M/N/ bi		
GETE	Read of user-registered frame M/N/ bi registered on flash ROM			
CSET	Setting of PLC CPU monitoring registration/deregistration and of the unit (word/byte) of the number of transferred data	M/N		

The following protocol symbols indicate usable protocols. M: MC protocol, N: No protocol, bi: bidirectional protocol "Fundamental" in the Remarks field indicates the instruction explained in the Serial Communication Module User's Manual (Fundamentals) and "Application" indicates the instruction explained in the Serial Communication Module User's Manual (Applications).

Program Compatibility

The sequence programs of the system using the A series/QnA series serial communication modules (A1SJ71UC24-R2, A1SJ71QC24N, etc., hereafter referred to as the "C24") and the programs of external devices can be utilized in the system using the QJ71C24. The C24 program compatibility for data communications using the QJ71C24 are described in the next column.

	Compatibility with Programs for A Series Computer Link Modules	Compatibility with Programs for QnA Series Serial Communication Modules
Other-end	Compatible.	Compatible.
external	Note that only data	(Note 5)
device side	within PLC is accessible	
program (* 1)	in MC protocol. (Note 6)	
PLC side	Incompatible.	Compatible.
program (* 1)		(Note 2, 3, 4)

- Note 1: In any of the above cases, performance capabilities and communications timings are incompatible, and therefore utilization of programs as they are may not permit communications. When utilizing programs, always confirm their operations.
- Note 2: The following instructions cannot be used with the QJ71C24.

Instructions unavailable	READ, SWRITE, SEND,	
for QJ71C24	RECV, REQ	

- Note 3: The QnA series serial communication modules (such as A1SJ71QC24N) contain E²PROM but the QJ71C24 includes flash memory instead of E²PROM. Namely, if access to E²PROM is executed in the conventional program, access to flash memory is made. Note that communications will stop during write to flash memory.
- Note 4: The LED ON states/switch setting states read from the buffer memory of the QJ71C24 are different from those of the AJ71QC24.
- Note 5: Access to a file in the Q series CPU by the MC protocol uses a new dedicated command and a new program should be created.
- Note 6: The conventional A series computer link modulecompatible dedicated protocol (MC protocol level 1) has an area inaccessible to the internal device memory of the Q mode CPU expanded from the conventional A series CPU.

Serial Communication Modules: QJ71C24, QJ71C24-R2

Appearance



● QJ71C24-R2

 $\ast\,$ R1 (flexing radius near terminal block): Cable diameter $\times4$

* R2 (flexing radius near connector): Cable diameter \times 4

* r1 (flexing radius near crimping terminal): Connectable to the degree that it is not flexed extremely.

Function List

Main Function	Outline	MC Protocol C	Communications ON-demand transmission	No Protocol	Bidirectional Protocol
User frame registration	User-defined header/footer is added to sent data for transmission. Also header/footer is removed from received data.	×	0	0	×
Notice function	When specified conditions hold, data is sent to exterior automatically.	×	0	0	×
Global transmission function	Data is broadcast to multiple QJ71C24's connected in RS-422 multidrop.	0	×	×	×
Mode changing	Communications protocol switching function	0	×	0	0
Transparent code setting	Transparent code/added code is set to enable data communication of the same value as transmission control code.	×	×	0	0
ASCII-BIN conversion	Sent data is automatically converted into ASCII and received data is converted into BIN.	×	×	0	0
Interrupt function	When specified data is received, CPU module interrupt program is started.	×	×	0	0
GPP communications	Interface function for GPPW programming software to access CPU module.	0	×	×	×
Modem function	Makes modem initialization and telephone line connection.	0	0	0	0

Serial Communication Modules: QJ71C24, QJ71C24-R2

Performance Specifications

	Item		Specifications				
liem		QJ71C24		QJ71C24-R2			
Interface CH. 1			RS-232 compliant (D-sub 9P)		RS-232 compliant (D-sub 9P)		
	CH. 2		RS-422/485 complian	t (two-piece terminal	RS-232 compliant (D	D-sub 9P)	
			block)				
Communication			Protocol	Line	Protocol	Line	
system	MELSEC of	communication protocol	Half duplex	Full duplex/half	Half duplex	Full duplex/half	
	No protoco	bl	Full duplex/half	duplex	Full duplex/half	duplex	
			duplex		duplex		
	Bidirection	al protocol	Full duplex/half		Full duplex/half		
			duplex		duplex		
Synchronization s	system		Asynchronous system	l			
Transmission spe	ed (bps) (No	ite 2)	300, 600, 1200, 2400,	4800, 9600, 14400, 192	00, 28800, 38400, 57600,	115200	
			* Usable when the to	tal transmission speed of	two interfaces is within 1	15200bps.	
Transmission	RS-2	32 (m (feet))	Max. 15 (49.18)				
distance	RS-4	22/485 (m (feet))	Max. 1200 (3934.43) (overall distance)				
Data format	Start	bit	1				
	Data	bit	7 or 8				
	Parity	/ bit	1 (lateral parity) or none (to be selected)				
Stop		bit	1 or 2 (to be selected)				
Error detection			Parity check, sumcheck				
Flow control			DTR/DSR (ER/DR) control (only RS-232 controllable) or DC1/DC3 (Xon/Xoff), DC2/DC4 control				
Line configuration	n RS-2	232	1:1				
(connection)(Note	e1) RS-4	122/485	Total of 1:1, 1:n, n:1, r	m:nn and m+n is max. 3	x. 32		
Line configuration	n MEL	SEC communication	1:1, 1:n, m:n		1:1		
(data	proto	ocol					
communications)	No p	rotocol	1:1, 1:n, n:1		1:1		
(Note 1)	Bidir	ectional protocol	1:1		1:1		
Max. number of d	ata MC p	protocol communication	960 words				
per communication No protocol communication/bidirectional communication		3839 words (No protocol and bidirectional communications cannot transfer 3839 words, respectively.)					
Loadable station			Q series CPU (Q mode)				
Number of loadab	ole modules p	per CPU	No restrictions (loadable within I/O signal points)				
Number of I/O po	ints occupied	1	32 points				
Internal current co	onsumption (5VDC)	0.28 0.24				
External dimensions (mm (inch))			98 (3.86)(H) × 27.4 (1.08)(W) × 90 (3.55)(D)				
Weight (kg (lb))			0.2 (0.44)		0.2 (0.44)		

Note 1: Indicates the combination for connection of external device and CPU. (External device side:PLC CPU side) Note 2: Depending on the characteristics of the cable used, the transmission distance may be less than the distance given above.

Usable modem specifications

Item	Specifications		
Telephone line	Subscriber telephone/private line/cellular phone/PHS	ISDN	
Connection line	Analog 2-wire type/4-wire type	ISDN line	
Initialization	Hayes AT command-compatible product	Hayes AT command-compatible product	
Communication standard	V.34/V.32bis/V.32/V.22bis/V.22/V.21V.fc, 212A/103	V.110 (B-channel circuit exchange, D-channel packet switching)	
Error correction	Class 4, class 10 compatible, V.42 compatible		
Data compression	Class 5 compatible, V.42bis compatible		
Others	One which can turn on only DR (DSR) signal independentlyShould be able to exercise flow control (RS/CS control)		

* When using a cellular phone/PHS, it is recommended to use a modem whose error correction function supports MNP class 10. Note that communications may not be made depending on the line status.

Serial Communication Modules: QJ71C24, QJ71C24-R2

Equipment



<QJ71C24 accessories>

Product	Description
Termination resistor	110 Ω , 130 Ω , 2 pcs. each
Manual	Serial Communication Module User's
	Manual (Hardware)

<Separately prepared products>

The following equipment must be prepared separately.

(Recommended cables)

² roduc	Description
RS232	7/0x127 P HRV-SV, 8.5mm (0.33inch) or more in
cable	7/0x127 P HRV-SV, 8.5mm (0.33inch) or more in OD(Oki Electric Cable make, specify the number of
	pairs in .)
	QJ71C24 is equipped with D-Sub 9P (female)
	connector.
RS422	SPEV(SB)-MC-0.2 \times 3P, about 6.5mm (0.26inch) in
RS422 cable	OD
	SPEV(SB)- $0.2 \times 3P$, about 7.5mm (0.30inch) in OD(Mitsubishi Cable Industries make)
	OD(Mitsubishi Cable Industries make)

Note 1: Refer to <Separately prepared manuals> for separately prepared manuals.

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E or later	For sequence programming For Ethernet parameter setting	0
SW0D5C-QSCU-E	Data package for serial communication module	Δ
SW3D5F-CSKP-E	Communication support software for personal computer	Δ

 $\bigcirc:$ Must be prepared. $\bigtriangleup:$ Prepared as required.

Note2 : The software products shown above or later version are usable.

QJ71C24-R2



<QJ71C24-R2 accessories>

Product	Description
	Serial Communication Module User's Manual (Hardware)

<Separately prepared products>

The following equipment must be prepared separately.

Product	Description
RS-232 cable	Description 7/0x127 P HRV-SV, 8.5mm (0.33inch) or more in OD(Oki Electric Cable make, specify the number of pairs in .) QJ71C24-R is equipped with D-Sub 9P (female) connector.
	efer to <separately manuals="" prepared=""> for separately epared manuals.</separately>
<separa< td=""><td>tely prepared manuals></td></separa<>	tely prepared manuals>
Serial Cor	nmunication Module User's Manual (Fundamentals)
Pre-oper Maintena Basic co protocol About da	ations, functions ration procedures ance, inspection, troubleshooting mmunications method in MC/No protocol/bidirectional (Note 5) ata package ed instructions
Serial Cor	nmunication Module User's Manual (Applications)
On-dema PLC CPI Modem- ASCII-bi Transpa Transmis commun Half dup m:n com Interrupt	istered frame function and function U monitoring function compatible function nary conversion function rent code usage method ssion control method, communications mode, data ication watchdog timer changing lex communication munications between external device and PLC CPU program Communication Protocol Reference Manual
which the module/l	specification manual that describes the functions with e MC protocol for serial communication Ethernet module is compatible, their send and receive and send and receive procedures.

Note 5: The description of the MC protocol is not given. For details, refer to the MC Protocol Reference Manual.

Overview

SW0D5C-QSCU-E is a utility package designed to set the condition data needed to use the QJ71C24 or QJ71C24-R2 serial communication module and to read and set the error codes and other status data. It is added to SW4D5C-GPPW-E or later.

The use of QSCU is not required for use of the QJ71C24 or QJ71C24-R2, and initial value and other settings can be made in sequence programs. However, the use of QSCU removes the need for these programs and facilitate checking of the setting and operating statuses. Especially when using the modem, notification or other application function of the serial communication module, it is recommended to use QSCU for various data settings.

Monitoring and Testing Functions

The monitoring and testing functions are designed to set data and conditions necessary to use various functions of the QJ71C24 and change the transmission control system on the screen and to register them in the flash memory of the QJ71C24. Also, they can display the registration status of the buffer memory (Note 1) or flash memory and the operating status of the module on the screen. Major items that may be monitored and tested are indicated below.

Q mode

Main monitoring and testing (data setting) function list

Item	Outline	Detailed Items
Transmission control	Performs transmission control method setting and status monitoring.	DR control/DC control selection, DC1/DC3 code designation, DC2/DC4 code designation, half duplex/full duplex selection, CD terminal enable/disable, priority designation for half-duplex simultaneous communication, transmission method for half-duplex transmission resumption, no-receive monitoring time, response monitoring time, transmission monitoring time, unit selection (word/byte), sending and receiving buffer first addresses, sending and receiving buffer lengths, sending and receiving transparent code designation, ASCII-BIN conversion designation
MC protocol communications	Performs necessary condition and other settings and status monitoring when on-demand function is used in MC protocol communications.	On-demand transmission data storage first address and data length, user- registered frame number designation for on-demand, message waiting time
No protocol communications	Performs necessary condition and other settings and status monitoring when No protocol communications are used.	Number of receiving end data, receiving end code, receiving user-registered frame use yes/no designation, receiving user-registered frame number, sending user-registered frame number, CR/LF output designation, output first pointer designation, output quantity designation
Bidirectional protocol communications	Performs necessary condition and other settings and status monitoring when bidirectional protocol communications are used.	Data enable/disable designation for simultaneous transmission
PLC CPU supervisory function	Supervises PLC CPU periodically and monitors status of function notifies external system by message when given condition holds.	Cyclic time unit selection, cyclic time, supervising function designation, sending means designation, cyclic transmission pointer, output quantity/connecting data number designation, registered word block quantity designation, registered bit block quantity designation, abnormality supervising designation, supervising device designation
Modem	Performs condition settings and status monitoring necessary to make communications with remote equipment using modems.	Connection channel designation, notice execution designation, connection retry count, connection retry intervals, initialization/connection time-out period, initialization retry count, initializing data number designation, connection data number designation, GPPW connection designation, no-communication interval time, RS-CS control yes/no selection, DR signal enable/disable selection for modem initialization, notice waiting time

Note 1: The buffer memory is interfacing volatile memory designed to transfer data between the CPU module and QJ71C24. At power-off or system reset, data are all erased and the initial values are set from the flash memory in the QJ71C24. To make the contents set on QSCU valid at every power-on, the set contents must have been registered to the nonvolatile flash memory.

Utillity Package for Serial Communication Modules: SW0D5C-QSCU-E

Telephone number setting screen sample

Data for modem connection		_ 🗆 ×
Module information		
Module model name: QJ71C24-R2	Start I/D No.:	0000
Module type: Serial Communications Module	3	
Setting item		Setting value
Data for modern connection 1(H0bb8) Pager receiver designation		Notification Other than above
Telephone number		052nnnnnn
External line dialing		No external-line dialing 💌
Line types		Tone 💌
Wait time for message transmission "(units:sec.)"		
Message		
Comment		
Data for modem connection 2(H0bb9) Pager receiver designation		No notification
Telephone number		_
External line dialing		No external-line dialing 🔹 💌
Flash ROM setting	Details	
Write to module File save		
Read from File read		Select input
Make text file	Select test	Close

CPU status monitoring function setting screen sample

PLC CPU monitoring system setting			_ 🗆 ×
Module information Module model name: 0J71C24-B2	Start I/0 No :	0000	
Module type: Serial Communications Modul	e		
Setting item		Setting valu	le 🔺
Cycle time units designation		min.	*
Cycle time designation			10
PLC CPU monitoring function designation		Condition agreement	-
PLC CPU monitoring transmission measure des	ignation	Notification	-
Constant cycle transmission Transmission pointer designation			0
Number of outputs designation			0
Data No. for connection designation			0000
Number of registered word blocks designation			1
Number of registered bit blocks designation			2
PLC CPU abnormal monitoring designation		Monitoring	-
No.1 block monitoring device Monitoring device designation		D	• •
Flash ROM setting	Details		
Write to module File save		He	exadecimal input
Read from File read		Setting range : 00000	000 · FFFFFFFF
Make text file	Select test		Close

Automatic Refresh Setting

QSCU has an automatic refresh setting function. Automatic refresh is a function to automatically read the data of the QJ71C24 buffer memory, which stores the operating status, error codes and others, to the internal device memory of the CPU module. With this function, you need not create sequence programs for reading. Automatically refreshed data are various error codes, LED ON states, modem connection status, PLC CPU monitoring function, RS-232 signal status, mode setting status, transmission control setting states, etc. Automatic refresh cannot be set for the transfer of data communicated in the No protocol, bidirectional protocol, etc. which occurs irregularly.

Automatic refresh setting screen sample

Module side Buffer size Module side Transfer word Flash R0M access register/read/delete 1 1 > Flush R0M access register/read/delete 1 1 > CH LED 0N status, communications error 1 1 >	PLC side Device	
result		
CH11ED ON status communications area 1 1		
status	D1000	D1000
CH2 LED ON status, communications error 1 1 -> I status	D1001	D1001
Switch setting error, mode switching error 1 1 -> status		
Number of registered user frame 1 1 ->		
Flash ROM system parameters write result 1 1 ->		
Modem function error code 1 1 ->	D1002	D1002
		D1003

I/O Modules

Overview

The Q series I/O modules are compatible with the bus of the high-function/high-performance Q series CPU modules (Q mode only). They have the world's smallest unit size to meet the Q series, and are designed to be compact/power-saving in consideration of the environment.

Features

Ultracompact

These I/O modules are the smallest in the world for building block type units.

98mm (3.86inch) height × 27.4mm (1.08inch)

width × 90mm (3.55inch) depth

Note 1: The Q series I/O modules are designed to be used with Q3_B or Q6_B. They cannot be used with QA1S3_B or QA1S6_B. They cannot be used with the A mode, either.

Multi-functional

- The DC input modules allow the input time constant to be changed (1/5/10/20/70ms). The input time constant can be set from GPPW. It can be decreased if fast input is needed, and be increased for use in a hostile environment (e.g. noise).
- (2) The lineup of the DC transistor output modules have a short-circuit protective function.

The short-circuit protective function prevents transistors from being damaged by a short circuit, etc.

- Wiring capability improvement
- (1) The relay output modules do not require external supply power.
- Maintainability improvement
- (1) The modules can be loaded/unloaded with a single motion (screwing not needed).
 * Screwing may be needed under some operating conditions.
- (2) For a CPU error, output hold/clear setting can be made per output module.
- (3) The loaded module configuration can be confirmed on the programming software screen making it very useful for maintenance.

Energy-saving

(1) Reduction in input current of DC input modules

Туре	Input Current
QX40	Approx. 4mA
A1SX40	Approx. 7mA

(2) Reduction in 5VDC current consumption of transistor output modules

Туре	Input Current
QY81P	Approx. 95mA
A1SY81EP	Approx. 500mA

Safety

 The 100/200VAC rated modules are enhanced in insulation between the external hazardous voltage and internal circuit.

Compatibility

(1) Since the connector shape and pin layout of the 32and 64-point modules are the same as those of the A/AnS series, the connector terminal block conversion modules of the A/AnS series and the connectors wired for the AnS series I/O modules can be used.

Instructions

- (1) Note that the screw terminal block layout is different between the MELSEC-Q series 16-point I/O modules and MELSEC-AnS series 16-point I/O modules.
- (2) The external wiring connectors of the 32- and 64-point modules are not provided for the products. Please purchase them after confirming the external wiring applicable connector types given in the specification field of the corresponding modules. The external wiring terminal blocks of the 16-point modules are provided for (fitted to) the products.
- (3) When using the 16-point modules, use wires of 0.3 to 0.75mm² core and 2.8mm (0.11inch) OD max. It is also recommended to cover the power connections of the crimping terminals with insulation or mark tubes. (Use the insulation or mark tubes which are compatible with the crimping terminals used.)



I/O Modules

Input Derating (Temperature-Dependent Input ON Ratio Restriction)

Some input module models may require their input specifications to be derated. This restriction is provided to prevent a failure due to excessive heat generated in the input section, and is influenced by the ambient temperature, input voltage, number of input ON points, and input ON time. The derating diagrams are provided for the modules which require derating of the input specifications. Use them within those ranges.

Relay Life of Relay Output Module

The following chart shows the service life of a relay output module relay.



Applicable module.....QY10

QX10 AC input module

	Туре	AC Input Module	
Specifications		QX10	Appearance
Number of input	points	16 points	
Isolation method		Photocoupler	
Rated input volta	age, frequency	100-120VAC (+10/-15%) 50/60Hz (±3Hz) (distortion factor within 5%)	QX10 0 1 2 3 4 5 6 7
Rated input curre	ent	Approx. 8mA (100VAC, 60Hz), approx. 7mA (100VAC, 50Hz)	89ABCDEF
Input derating		Refer to the derating chart.	<u>A</u>
Inrush current		Max. 200mA within 1ms (at 132VAC)	
ON voltage/ON of	current	80VAC or higher/5mA or higher (50Hz, 60Hz)	
OFF voltage/OF	F current	30VAC or lower/1mA or lower (50Hz, 60Hz)	
Input impedance		Approx. 15k Ω (60Hz), approx. 18k Ω (50Hz)	
Response time	$\text{OFF}{\rightarrow}\text{ON}$	15ms or less (100VAC 50Hz, 60Hz)	$\frac{-\overline{a}\overline{a}}{\overline{a}\overline{a}}$
	$ON \rightarrow OFF$	20ms or less (100VAC 50Hz, 60Hz)	005 (3 4
Dielectric withsta	and voltage	1780VAC rms/3 cycles (altitude 2000m (6557.38feet))	-00_6 5
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 1500Vp-p noise voltage, 1μ s noise width and 25 to	00⁹ 8 7
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	<u>∞∞</u> ∞∞_C
Common termina	al arrangement	16 points/common (common terminal: TB17)	
Operation indica	tor	ON indication (LED)	
External connect	tions	18-point terminal block (M3×6 screws)	
Applicable wire s	size	Core: 0.3 to 0.75mm ² , OD: 2.8mm (0.11inch) max.	NC 100VAC 8mA60Hz
Applicable crimp	ing terminal	R1.25-3 (sleeved crimping terminals cannot be used.)	8mA60Hz 7mA50Hz
5VDC internal cu	urrent	50mA	
consumption (A)			
Weight (kg (lb))		0.17 (0.37)	

Derating Chart	Terminal Block Number	Signal Name
	TB1	X00
	TB2	X01
90 80 92 70 80 80 80 80 80 80 80 80 80 80 80 80 80	TB3	X02
2 60 50 50 132VAC	TB4	X03
	TB5	X04
Ambient temperature (°C)	TB6	X05
External Connections	TB7	X06
	TB8	X07
	TB9	X08
	TB10	X09
	TB11	X0A
	TB12	X0B
	TB13	X0C
	TB14	X0D
	TB15	X0E
	TB16	X0F
TD 47	TB17	COM
00VAC	TB18	NC

Input Modules

QX40 DC input module (positive common type)

	Туре	DC Input Module (Positive Common Type)	
Specifications		QX40	Appearance
Number of input	points	16 points	
Isolation method		Photocoupler	QX40
Rated input volta	age	24VDC (+20/-15%, ripple ratio within 5%)	01234567 89ABCDEF
Rated input curre	ent	Approx. 4mA	SGABCDEF
Input derating		No	
ON voltage/ON of	current	19V or higher/3mA or higher	
OFF voltage/OF	F current	11V or lower/1.7mA or lower	
Input resistance		Approx. 5.6k Ω	
Response time	$OFF\!\rightarrow\!ON$	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value:	
		10ms) *	$\frac{-\overline{00^3}}{\overline{00^4}}$
	ON→OFF	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value: 10ms) *	-005 V(S 4
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1 µs noise width and 25 to	
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
Common termina	al arrangement	16 points/common (common terminal: TB17)	
Operation indica	tor	ON indication (LED)	
External connect	tions	18-point terminal block (M3 \times 6 screws)	
Applicable wire s	size	Core: 0.3 to 0.75mm ² , OD: 2.8mm (0.11inch) max.	
Applicable crimp	ing terminal	R1.25-3 (sleeved crimping terminals cannot be used.)	24VDC
5VDC internal cu	urrent	50mA	
consumption (A)			\square
Weight (kg (lb))		0.16 (0.35)	



*: For the setting method, refer to the SW5D5C-GPPW-E Operating Manual.

Note that OFF \rightarrow ON and ON \rightarrow OFF response times cannot be set separately.

Input Modules

■ QX41 DC input module (positive common type)

	Туре	DC Input Mc	odule (Positive C	Common Type)	_		
Specifications		QX41				Арр	earance
Number of input	points	32 points					
Isolation method		Photocoupler					
Rated input volta	age	24VDC (+20/-15%, ripple ratio within 5%)				QX41	
Rated input curre	ent	Approx. 4mA	Approx. 4mA				
Input derating		Refer to the derating chart.				0123	3CDEF 34567
ON voltage/ON o	current	19V or higher/3mA or higher				89AE	BCDEF
OFF voltage/OFF	F current	11V or lower/1.7mA or lower				24VDC	QX41
Input resistance		Approx. 5.6k Ω				4mA	
Response time	OFF→ON	1ms/5ms/10ms/20ms/70ms or less (CPU 10ms) *	parameter setti	ng, default value	e:		0
	ON→OFF	1ms/5ms/10ms/20ms/70ms or less (CPU 10ms) *	parameter setti	ng, default valu	e:		
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (65	57.38feet))				
Insulation resista	ance	$10M_{\Omega}$ or more by insulation resistance te	ster				
Noise immunity		By noise simulator of 500Vp-p noise voltage	ge, 1µs noise w	idth and 25 to			
		60Hz noise frequency					
		Fast transient noise IEC61000-4-4: 1kV					
Common termina	al arrangement	32 points/common (common terminal: B01	1, B02)				
Operation indicat		ON indication (LED)					
External connect		40-pin connector					
Applicable wire s		0.3mm ²					
External wiring c		A6CON1, A6CON2, A6CON3 (optional)					
Applicable conne		A6TBXY36, A6TBXY54, A6TBX70					
block conversion							
5VDC internal cu consumption (A)		75mA				E	
Weight (kg (lb))		0.15 (0.33)					
	De	erating Chart	Signal Name	² in Number	Signa	l Name	vin Number
			B20	X00	A20		X10
	§ 90		B19	X01	A19		X10 X11
1	e) 30		513	701	713		711

Derating Chart	Signal Name	⁹ in Number	Signal Name	³ in Number
100	B20	X00	A20	X10
	B19	X01	A19	X11
28.8VDC	B18	X02	A18	X12
8 90 90 90 90 90 90 90 90 90 90	B17	X03	A17	X13
	B16	X04	A16	X14
Ambient temperature (°C)	B15	X05	A15	X15
External Connections	B14	X06	A14	X16
	B13	X07	A13	X17
	B12	X08	A12	X18
	B11	X09	A11	X19
	B10	X0A	A10	X1A
	B09	X0B	A09	X1B
	B08	X0C	A08	X1C
	B07	X0D	A07	X1D
	B06	X0E	A06	X1E
	B05	X0F	A05	X1F
	B04	NC	A04	NC
	B03	NC	A03	NC
	B02	COM	A02	NC
	B01	COM	A01	NC

*: For the setting method, refer to the SW5D5C-GPPW-E Operating Manual. Note that OFF \rightarrow ON and ON \rightarrow OFF response times cannot be set separately.

Q mode

Input Modules

QX42 DC input module (positive common type)

	Туре	DC Input Module (Positive Common Type)	
Specifications		QX42	Appearance
Number of input Isolation method		64 points Photocoupler	
Rated input volta		24VDC (+20/-15%, ripple ratio within 5%)	QX42 01234567
Rated input curr	0	Approx. 4mA	89ABCDEF
Input derating		Refer to the derating chart.	0 1 2 3 4 5 6 7 8 9 ABCDEF
ON voltage/ON	current	19V or higher/3mA or higher	QX42
OFF voltage/OF	F current	11V or lower/1.7mA or lower	24VDC DISPLAY 4mA EOL
Input resistance		Approx. 5.6k Ω	
Response time	OFF→ON	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value: 10ms) *	
	ON→OFF	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value: 10ms) *	
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1μ s noise width and 25 to 60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
Common termina	al arrangement	32 points/common (common terminal: 1B01, 1B02, 2B01, 2B02)	
Operation indica	tor	ON indication (LED), 32 point switch-over using switch	
External connec	tions	40-pin connector	
Applicable wire		0.3mm ²	
External wiring c		A6CON1, A6CON2, A6CON3 (optional)	
Applicable conne		A6TBXY36, A6TBXY54, A6TBX70	
block conversior			
5VDC internal cu consumption (A)		90mA	
Weight (kg (lb))		0.18 (0.40)	

Derating Chart	Pin √umbe	Signal Name	Pin √umbe	Signal Name	Pin √umbe	Signal Name	Pin √umbe	Signal Name
	1B20 1B19	X00 X01	1A20 1A19	X10 X11	2B20 2B19	X20 X21	2A20 2A19	X30 X31
	1B18	X02	1A18	X12	2B18	X22	2A18	X32
0 70 24VDC	1B17	X03	1A17	X13	2B17	X23	2A17	X33
Z 50 26.4VDC	1B16	X04	1A16	X14	2B16	X24	2A16	X34
O 40 30 28.8VDC	1B15	X05	1A15	X15	2B15	X25	2A15	X35
20 40 50 55	1B14	X06	1A14	X16	2B14	X26	2A14	X36
Ambient temperature (°C)	1B13	X07	1A13	X17	2B13	X27	2A13	X37
External Connections	1B12	X08	1A12	X18	2B12	X28	2A12	X38
	1B11	X09	1A11	X19	2B11	X29	2A11	X39
1B20	1B10	X0A	1A10	X1A	2B10	X2A	2A10	X3A
	1B09	X0B	1A09	X1B	2B09	X2B	2A09	X3B
	1B08	X0C	1A08	X1C	2B08	X2C	2A08	X3C
	1B07	X0D	1A07	X1D	2B07	X2D	2A07	X3D
Left side LED	1B06	X0E	1A06	X1E	2B06	X2E	2A06	X3E
(first half) SW Indication	1B05	X0F	1A05	X1F	2B05	X2F	2A05	X3F
Right side • selector circuit	1B04	NC	1A04	NC	2B04	NC	2A04	NC
(latter half)	1B03	NC	1A03	NC	2B03	NC	2A03	NC
	1B02	COM1	1A02	NC	2B02	COM2	2A02	NC
1B2 1B1 24VDC	1B01	COM1	1A01	NC	2B01	COM2	2A01	NC

* : For the setting method, refer to the SW5D5C-GPPW-E Operating Manual. Note that OFF \rightarrow ON and ON \rightarrow OFF response times cannot be set separately.

Input Modules

QX80 DC input module (negative common type)

	Туре	DC Input Module (Negative Common Type)	
Specifications		QX80	Appearance
Number of input	points	16 points	
Isolation method	1	Photocoupler	QX80 01234567
Rated input volta	age	24VDC (+20/-15%, ripple ratio within 5%)	89ABCDEF
Rated input curr	ent	Approx. 4mA	
Input derating		No	
ON voltage/ON	current	19V or higher/3mA or higher	
OFF voltage/OF	F current	11V or lower/1.7mA or lower	
Input resistance		Approx. 5.6k Ω	
Response time	OFF→ON	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value:	$\frac{\overline{00^2}}{\overline{00^3}}$ (0^2)
		10ms) *	$\frac{\overline{\sigma\sigma^3}}{\overline{\sigma\sigma^4}}$
	ON→OFF	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value:	<u>∞∞</u> <u>∞∞</u> (§ 4
		10ms) *	$\overline{\circ \circ}_{-6}$ $\overline{5}$
Dielectric withsta	<u> </u>	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1μ s noise width and 25 to	
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	00B (89
Common termina	al arrangement	16 points/common (common terminal: TB18)	
Operation indica	itor	ON indication (LED)	
External connec	tions	18-point terminal block (M3×6 screws)	TO C
Applicable wire s	size	Core: 0.3 to 0.75mm ² , OD: 2.8mm(0.11inch) max.	
Applicable crimp	oing terminal	R1.25-3 (sleeved crimping terminals cannot be used.)	H ^{COM}
5VDC internal cu	urrent	50mA	24VDC
consumption (A)			
Weight (kg (lb))		0.16 (0.35)	



*: For the setting method, refer to the SW5D5C-GPPW-E Operating Manual.

Note that OFF \rightarrow ON and ON \rightarrow OFF response times cannot be set separately.

Input Modules

QX81 DC input module (negative common type)

	Туре	DC Input Module (Negative Common Type)	
Specifications		QX81	Appearance
Number of input	points	32 points	
Isolation method		Photocoupler	
Rated input volta	age	24VDC (+20/-15%, ripple ratio within 5%)	QX81 01234567
Rated input curr	ent	Approx. 4mA	89ABCDEF 01234567
Input derating		Refer to the derating chart.	89ABCDEF
ON voltage/ON	current	19V or higher/3mA or higher	QX81
OFF voltage/OF	F current	11V or lower/1.7mA or lower	24VDC 4mA
Input resistance		Approx. 5.6k Ω	
Response time	OFF→ON	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value: 10ms) *	
	ON→OFF	1ms/5ms/10ms/20ms/70ms or less (CPU parameter setting, default value: 10ms) *	
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	-0-
Insulation resista	ance	$10M_{\Omega}$ or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1 µs noise width and 25 to	
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
Common termin	al arrangement	32 points/common (common terminal: 17, 18, 36)	
Operation indica	tor	ON indication (LED)	
External connec	tions	37-pin D-sub connector	
Applicable wire		0.3mm ²	
External wiring of	connector	A6CON1E, A6CON2E, A6CON3E (optional)	
Applicable connection		A6TBX36-E, A6TBX54-E, A6TBX70-E	
5VDC internal cu		75mA	
consumption (A)		0 16 (0 35)	
Weight (kg (lb))		0.16 (0.35)	



*: For the setting method, refer to the SW5D5C-GPPW-E Operating Manual.

Note that OFF \rightarrow ON and ON \rightarrow OFF response times cannot be set separately.

Output Modules

QY10 contact output module

	Туре	Contact Output Module	
Specifications		QY10	Appearance
Number of out	tput points	16 points	
Isolation meth	od	Relay	
Rated switchin	ng voltage,	24VDC 2A (resistive load) 240/4C 2A (resistive load) /point, 8A/common	
current		240VAC 2A (COS ϕ =1)	
Minimum swite		5VDC 1mA	
Maximum swit	U	264VAC 125VDC	QY10 01234567
Response	OFF→ON	10ms or less	89ABCDEF
time	ON→OFF	12ms or less	
Life	Mechanical	20 million times or more	
	Electrical	Rated switching voltage/current load More than 100 thousand times or	
		more	
		200VAC 1.5A, 240VAC 1A (COS ϕ =0.7) 100 thousand times or more	
		200VAC 0.4A, 240VAC 0.3A (COS ϕ =0.7) 300 thousand times or more 200VAC 1A, 240VAC 0.5A (COS ϕ =0.35) 100 thousand times or more	
		200VAC 1A, 240VAC 0.5A (COS ϕ =0.35) 100 thousand times of more 200VAC 0.3A, 240VAC 0.15A (COS ϕ =0.35) 300 thousand times or more	
		24VDC 1A, 100VDC 0.1A (L/R=7ms) 100 thousand times or more	11 ⁵ X8 4
		24VDC 0.3A, 100VDC 0.03A (L/R=7ms) 300 thousand times or more	
Maximum swit	tching frequency	3600 times/hour	
Surge suppres	ssor	No	
Fuse		No	
Dielectric with	stand voltage	2830VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resi	stance	10M Ω or more by insulation resistance tester	
Noise immunit	ty	By noise simulator of 1500Vp-p noise voltage, 1μ s noise width and 25 to	
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
	inal arrangement	16 points/common (common terminal: TB17)	24VDC 240VAC 2A
Operation indi		ON indication (LED)	
External conn		18-point terminal block (M3×6 screws)	
Applicable wir		Core: 0.3 to 0.75mm ² , OD: 2.8mm (0.11inch) max.	
Applicable crir		R1.25-3 (sleeved crimping terminals cannot be used.)	
5VDC internal		430mA	
consumption (0.22 (0.49)	
Weight (kg (lb))	0.22 (0.48)	



Output Modules

■ QY40P transistor output module (sink type)

	Туре	Transistor Output Module (Sink Type)	
Specifications		QY40P	Appearance
Number of output	ut points	16 points	
Isolation method	l	Photocoupler	
Rated load volta	ge	12-24VDC (+20/-15%)	
Maximum load c	urrent	0.1A/point, 1.6A/common	
Maximum inrush	current	0.7A, 10ms or less	QY40P 01234567
Leakage current	at OFF	0.1mA or less	89ABCDEF
Maximum voltag	e drop at ON	0.1VDC (TYP.) 0.1A, 0.2VDC (MAX.) 0.1A	
Response time	$OFF \rightarrow ON$	1ms or less	
	ON→OFF	1ms or less (rated load, resistive load)	
Surge suppresso	or	Zener diode	
Fuse		No	
External	Voltage	12-24VDC (+20/-15%) (ripple ratio within 5%)	
supply power	Current	10mA (at 24VDC) (Max. all points ON)	
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1 µs noise width and 25 to	
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
Common termina	al arrangement	16 points/common (common terminal: TB18)	
Short circuit prot	ection	Yes (thermal protection, short circuit protection)	
		 Thermal protection is activated in increments of 1 point. 	
		 Short circuit protection is activated in increments of 1 point. 	
Operation indica	tor	ON indication (LED)	
External connect	tions	18-point terminal block (M3 \times 6 screws)	12VDC 24VDC 0.1A
Applicable wire s	size	Core: 0.3 to 0.75mm ² , OD: 2.8mm (0.11inch) max.	
Applicable crimp	ing terminal	R1.25-3 (sleeved crimping terminals cannot be used.)	
5VDC internal cu	urrent	65mA	
consumption (A)			
Weight (kg (lb))		0.16 (0.35)	



Output Modules

QY41P transistor output module (sink type)

	Туре	Transistor Output Module (Sink Type)	
Specifications		QY41P	Appearance
Number of output	ıt points	32 points	
Isolation method		Photocoupler	
Rated load volta	ge	12-24VDC (+20/-15%)	
Maximum load c	urrent	0.1A/point, 2A/common	
Maximum inrush	current	0.7A, 10ms or less	OY41P
Leakage current	at OFF	0.1mA or less	01234567 89ABCDEF
Maximum voltag	e drop at ON	0.1VDC (TYP.) 0.1A, 0.2VDC (MAX.) 0.1A	01234567
Response time	$\text{OFF} \! \rightarrow \! \text{ON}$	1ms or less	89 ABCDEF
	$ON \rightarrow OFF$	1ms or less (rated load, resistive load)	QY41P 12/24\/DC
Surge suppresso	or	Zener diode	12/24VDC 0.1A
Fuse		No	
External	Voltage	12-24VDC (+20/-15%) (ripple ratio within 5%)	
supply power	Current	20mA (at 24VDC) (Max. all points ON)	
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1µs noise width and 25 to	
		60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
Common termina	al arrangement	32 points/common (common terminal: A01, A02)	
Short circuit prot	ection	Yes (thermal protection, short circuit protection)	
		 Thermal protection is activated in increments of 1 point. 	
		Short circuit protection is activated in increments of 1 point.	
Operation indica		ON indication (LED)	
External connect	tions	40-pin connector	
Applicable wire s	size	0.3mm ²	
External wiring c	onnector	A6CON1, A6CON2, A6CON3 (optional)	
Applicable conne		A6TBXY36, A6TXY54	
block conversion			
5VDC internal cu	urrent	105mA	
consumption			
Weight (kg (lb))		0.15 (0.33)	



Output Modules

QY42P transistor output module (sink type)

	Туре	Transistor Output Module (Sink Type)	
Specifications		QY42P	Appearance
Number of output	ut points	64 points	
Isolation method		Photocoupler	
Rated load volta	ge	12-24VDC (+20/-15%)	
Maximum load c	urrent	0.1A/point, 2A/common	
Maximum inrush	current	0.7A, 10ms or less	QY42P
Leakage current		0.1mA or less	01234567 89ABCDEF
Maximum voltag	e drop at ON	0.1VDC (TYP.) 0.1A, 0.2VDC (MAX.) 0.1A	0 1 2 3 4 5 6 7 8 9 ABCDEF
Response time	$OFF \rightarrow ON$	1ms or less	QY42P
	$ON \rightarrow OFF$	1ms or less (rated load, resistive load)	12/24VDC DISPLAY 0.1A EOL
Surge suppresso	or	Zener diode	
Fuse		No	
External	Voltage	12-24VDC (+20/-15%) (ripple ratio within 5%)	
supply power	Current	20mA (at 24VDC)/common (Max. all points ON)	
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))	
Insulation resista	ance	10M Ω or more by insulation resistance tester	
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1μ s noise width and 25 to 60Hz noise frequency	
		Fast transient noise IEC61000-4-4: 1kV	
Common termina	al arrangement	32 points/common (common terminal: 1A01, 1A02, 2A01, 2A02)	
Short circuit prot	ection	Yes (thermal protection, short circuit protection) • Thermal protection is activated in increments of 1 point. • Short circuit protection is activated in increments of 1 point.	
Operation indica	tor	ON indication (LED), 32 point switch-over using switch	
External connect	tions	40-pin connector	
Applicable wire s	size	0.3mm ²	
External wiring c	onnector	A6CON1, A6CON2, A6CON3 (optional)	
Applicable conne block conversion		A6TBXY36, A6TBXY54	
5VDC internal cu consumption	urrent	150mA]
Weight (kg (lb))		0.17 (0.37)	1

External Connections	Pin Number	Signal Name	Pin Number	Signal Name	Pin Number	Signal Name	Pin Number	Signal Name
LED Left side (first half) selector circuit Right side (latter half) A01,A02 The above diagram shows the first half of 32 points (F). The latter half of 32 points (L) are similar.	1B20	Y00	1A20	Y10	2B20	Y20	2A20	Y30
	1B19	Y01	1A19	Y11	2B19	Y21	2A19	Y31
	1B18	Y02	1A18	Y12	2B18	Y22	2A18	Y32
	1B17	Y03	1A17	Y13	2B17	Y23	2A17	Y33
	1B16	Y04	1A16	Y14	2B16	Y24	2A16	Y34
	1B15	Y05	1A15	Y15	2B15	Y25	2A15	Y35
	1B14	Y06	1A14	Y16	2B14	Y26	A14	Y36
	1B13	Y07	1A13	Y17	2B13	Y27	2A13	Y37
	1B12	Y08	1A12	Y18	2B12	Y28	2A12	Y38
	1B11	Y09	1A11	Y19	2B11	Y29	2A11	Y39
	1B10	Y0A	1A10	Y1A	2B10	Y2A	2A10	Y3A
	1B09	Y0B	1A09	Y1B	2B09	Y2B	2A09	Y3B
	1B08	YOC	1A08	Y1C	2B08	Y2C	2A08	Y3C
	1B07	Y0D	1A07	Y1D	2B07	Y2D	2A07	Y3D
	1B06	Y0E	1A06	Y1E	2B06	Y2E	2A06	Y3E
	1B05	Y0F	1A05	Y1F	2B05	Y2F	2A05	Y3F
	1B04	NC	1A04	NC	2B04	NC	2A04	NC
	1B03	NC	1A03	NC	2B03	NC	2A03	NC
	1B02	12/24VDC	1A02	COM1	2B02	12/24VDC	2A02	COM2
	1B01	12/24VDC	1A01	COM1	2B01	12/24VDC	2A01	COM2
Output Modules

QY50 transistor output module (sink type)

	Туре	Transistor Output Module (Sink Type)				
Specifications		QY50	Appearance			
Number of output	ıt points	16 points				
Isolation method		Photocoupler				
Rated load volta	ge	12-24VDC (+20/-15%)				
Maximum load c	urrent	0.5A/point, 4A/common				
Maximum inrush	current	4A, 10ms or less	QY50 01234567			
Leakage current	at OFF	0.1mA or less	89ABCDEF FUSED			
Maximum voltag	e drop at ON	0.2VDC (TYP.) 0.5A, 0.3VDC (MAX.) 0.5A				
Response time	$OFF \rightarrow ON$	1ms or less				
	ON→OFF	1ms or less (rated load, resistive load)				
Surge suppresso	or	Zener diode				
Fuse		$1.4A \times 2pcs$ connected in parallel (6.7A equivalent). (unchangeable)				
		(fuse blow capacity: 50A)				
Fuse blow indica	tion	Yes (When fuse blows, LED indicates it and signal is output to CPU)				
External	Voltage	12-24VDC (+20/-15%) (ripple ratio within 5%)	5			
supply power	Current	20mA (at 24VDC) (Max. all points ON)				
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))				
Insulation resista	ance	10M Ω or more by insulation resistance tester				
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1μ s noise width and 25 to				
		60Hz noise frequency				
		Fast transient noise IEC61000-4-4: 1kV				
Common termina	al arrangement	16 points/common (common terminal: TB18)				
Operation indicator		ON indication (LED)				
External connections		18-point terminal block (M36 screws)				
Applicable wire size		Core: 0.3 to 0.75mm ² , OD: 2.8mm max.				
Applicable crimp	ing terminal	R1.25-3 (sleeved crimping terminals cannot be used.)				
5VDC internal current		80mA				
consumption						
Weight (kg (lb))		0.17 (0.37)				

External Connections	Terminal Block Number	Signal Name
	TB1	Y00
	TB2	Y01
	TB3	Y02
	TB4	Y03
	TB5	Y04
	TB6	Y05
	TB7	Y06
	TB8	Y07
	TB9	Y08
	TB10	Y09
	TB11	Y0A
	TB12	Y0B
	TB13	YOC
	TB14	Y0D
	TB15	Y0E
	TB16	Y0F
	TB17	12/24VDC
	TB18	COM

MODEL SELECTION I/O MODULES

Output Modules

QY80 transistor output module (source type)

	Туре	Transistor Output Module (Source Type)		
Specifications		QY80	Appearance	
Number of output	It points	16 points		
Isolation method		Photocoupler		
Rated load voltage	ge	12-24VDC (+20/-15%)		
Usable load volta	age range	10.2VDC to 28.8VDC		
Maximum load c	urrent	0.5A/point, 4A/common		
Maximum inrush	current	4A, 10ms or less	QY80 01234567 89ABCDEF	
Leakage current	at OFF	0.1mA or less	FUSED	
Maximum voltag	e drop at ON	0.2VDC (TYP.) 0.5A, 0.3VDC (MAX.) 0.5A		
Response time	$\text{OFF}\!\rightarrow\!\text{ON}$	1ms or less		
	$\text{ON}\!\rightarrow\!\text{OFF}$	1ms or less (rated load, resistive load)		
Surge suppresso	or	Zener diode		
Fuse		$4A \times 2pcs$ connected in parallel (6.7A equivalent). (unchangeable)		
		(fuse blow capacity: 50A)		
Fuse blow indica	tion	Yes (When fuse blows, LED indicates it and signal is output to CPU)		
External	Voltage	12-24VDC (+20/-15%) (ripple ratio within 5%)		
supply power	Current	20mA (at 24VDC) (Max. all points ON)		
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))		
Insulation resista	ance	10M Ω or more by insulation resistance tester		
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1μ s noise width and 25 to		
		60Hz noise frequency		
		Fast transient noise IEC61000-4-4: 1kV		
Common termina	al arrangement	16 points/common (common terminal: TB17)		
Operation indicator		ON indication (LED)	12VDC 24VDC 0.5A	
External connections		18-point terminal block (M3×6 screws)		
Applicable wire size		Core: 0.3 to 0.75mm ² , OD: 2.8mm (0.11inch) max.		
Applicable crimping terminal		R1.25-3 (sleeved crimping terminals cannot be used.)		
5VDC internal current		80mA		
consumption				
Weight (kg (lb))		0.17 (0.37)		

External Connections	Terminal Block Number	Signal Name
	TB1	Y00
	TB2	Y01
	TB3	Y02
	TB4	Y03
	TB5	Y04
	TB6	Y05
	TB7	Y06
	TB8	Y07
	TB9	Y08
	TB10	Y09
	TB11	Y0A
Fuse TB17	TB12	Y0B
	TB13	Y0C
	TB14	Y0D
	TB15	Y0E
	TB16	Y0F
	TB17	СОМ
	TB18	0V

Output Modules

■ QY81P transistor output module (source type)

	Туре	Transistor Output Module (Source Type)			
Specifications		QY81P	Appearance		
Number of output	ut points	32 points			
Isolation method	1	Photocoupler			
Rated load volta	ge	12-24VDC (+20/-15%)			
Usable load volta	age range	10.2VDC to 28.8VDC			
Maximum load c	urrent	0.1A/point, 2A/common			
Maximum inrush	current	0.7A, 10ms or less	QY81P 01234567		
Leakage current		0.1mA or less	89ABCDEF 01234567		
Maximum voltag	e drop at ON	0.1VDC (TYP.) 0.1A, 0.2VDC (MAX.) 0.1A	89ABCDEF		
Response time	$OFF \rightarrow ON$	1ms or less	QX81P		
	$ON \rightarrow OFF$	1ms or less (rated load, resistive load)	12/24VDC 0.1A		
Surge suppresso	or	Zener diode			
Fuse		No			
External	Voltage	12-24VDC (+20/-15%) (ripple ratio within 5%)			
supply power	Current	40mA (at 24VDC) (Max. all points ON)			
Dielectric withsta	and voltage	560VAC rms/3 cycles (altitude 2000m (6557.38feet))			
Insulation resista	ance	10M Ω or more by insulation resistance tester			
Noise immunity		By noise simulator of 500Vp-p noise voltage, 1μ s noise width and 25 to			
		60Hz noise frequency	-		
		Fast transient noise IEC61000-4-4: 1kV			
Common termina	Ū.	32 points/common (common terminal: 17, 18, 36)			
Short circuit prot	ection	Yes (thermal protection, short circuit protection)			
		 Thermal protection is activated in increments of 2 points. Short circuit protection is activated in increments of 1 point. 	• •		
Operation indica	tor	ON indication (LED)			
External connect	tions	37-pin D-sub connector			
Applicable wire size		0.3mm ²			
External wiring connector		A6CON1E, A6CON2E, A6CON3E (optional)			
Applicable connector/terminal		A6TBX36-E, A6TBX54-E, A6TBX70-E			
block conversion module					
5VDC internal current		95mA			
consumption			4		
Weight (kg (lb))		0.15 (0.33)			



Analog-to-Digital Conversion Modules: Q64AD, Q68ADV, Q68ADI

Overview

External analog voltage or current signals are converted into digital values and read by the CPU module. With the analog data, e.g. voltage, pressure, temperature, current and speed, of external devices such as sensors converted into digital data, they can be processed by the CPU module.

Features

- Model selection according to applications
- 1) Q64AD 4 channels. Voltage or current input can be chosen per channel.
- 2) Q68ADV...... 8 channels, voltage input
- 3) Q68ADI 8 channels, current input
- Fast conversion processing

Conversion speed is as high as 80 µs/channel.

Also, the temperature drift compensation is achieved in the processing time of all-channel conversion time + 160μ s.

High accuracy

Conversion accuracy is as high as $\pm 0.1\%$ (operating ambient temperature $25\pm5^{\circ}$ C).

Input range switching

Input range (Note 1) switching can be set easily from the GPPW.

Note 1: The input range indicates the offset/gain setting type. The types generally often used are provided as defaults, and the user can use others by offset/gain setting.

Simple setting by utility package

The optional SW0D5C-QADU-E utility package is available. The use of the utility package is not required, but using the utility package allows initial setting and automatic refresh setting to be made on the screen to reduce sequence programs, and facilitate the checking of the setting status and operating status.

Functions

Averaging function

This function averages analog-to-digital conversion data per channel in terms of count or time and outputs an average value in digital form. (Sequential digital output processing is called sampling.)

• Temperature drift compensation function This function automatically compensates for an error due to a change in ambient temperature of the module to improve conversion accuracy. • Maximum and minimum value holding function This function holds the maximum and minimum values of a digital output value within the module. The maximum and minimum values can be detected without creation of sequence programs.



<Q64AD, Q68ADV, Q68ADI accessories>

Product Description					
Manual	Q64AD, Q68ADV, Q68ADI User's Manual				
	(Hardware)				

<Separately prepared products>

The following manual must be prepared separately.

Product	Description
Manual	Q64AD, Q68ADV, Q68ADI User's Manual (Details)

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E or later	For sequence programming	0
SW0D5C-QADU-E	Analog-to-digital module utility package	

 \bigcirc : Must be prepared. \triangle : Prepared as required.

Note: The software of the above products or later version are usable.

Analog-to-Digital Conversion Modules: Q64AD, Q68ADV, Q68ADI

Performance Specifications

Type			Q64	4AD	Q68ADV		Q68ADI
Number of analog input points			4 points (4 channels)		8 points (8 channels)		8 points (8 channels)
Analog input Voltage		-1	0 to 10VDC	(input resistan	ce value	1MΩ)	—
	Current		to 20mADC sistance va	`	_		0 to 20mADC (input resistance value 250Ω)
Digital output	•	-4	096 to 4095	5			
I/O characteristics							
Max. resolution			Input	Analog input	range	Max. resolution	Digital output value
			Voltage	0 to 10V		2.5mV	0 to 4000
				0 to 5V		1.25mV	
				1 to 5V		1.0mV	
				-10 to 10		2.5mV	-4000 to 4000
			Current	0 to 20mA		5µA	0 to 4000
				4 to 20mA		4µA	
Accuracy (accuracy to full-scale)	Ambient temperature 25±5°C	±0.1%					
,	Ambient temperature 0 to 55°C	W	With temperature drift compensation: $\pm 0.3\%$, without: $\pm 0.4\%$				
Conversion time		80μ s/channel (With temperature drift compensation, time is increased by 160μ s					
		independently of the number of channels used.)					
Absolute max. input				/, current: ±30r			
Insulation system		Across I/O terminals and PLC power supply: Photocoupler insulation Across channels: No insulation					
Number of points occupied			16 points				
Connection terminal			18-point terminal block				
Applicable wire size			Core: 0.3 to 0.75mm ² , OD: 2.8mm (0.11inch) max.				
Applicable crimping terminal			RAV 1.25-3 R1.25-3 (sleeved crimping terminal cannot be used)				e used)
Internal current consu			30mA	<u></u>	640mA	V	640mA
Weight (kg (lb))		0.	14 (0.31)		0.19 (0	.42)	0.19 (0.42)

V+

V-

A.G.

FG

l+

۱-

A.G.

FG

External Wiring



Terminal			Signal	Signal Name			
Number	Q64AD		Q68	Q68ADV		A68ADI	
1	CH1	V+	CH1	V+	CH1	l+	
2		V-		V-		l-	
3		l+	CH2	V+	CH2	l+	
4		SLD		V-		-	
5	CH2	V+	CH3	V+	CH3	l+	
6		V-		V-		l-	
7		l+	CH4	V+	CH4	l+	
8		SLD		V-		I-	
9	CH3	V+	CH5	V+	CH5	l+	
10		V-		V-	1	l-	
11		l+	CH6	V+	CH6	l+	
12		SLD		V-		I-	
13	CH4	V+	CH7	V+	CH7	l+	
14		V-		V-		I-	
15		l+	CH8	V+	CH8	l+	
16		SLD		V-		I-	
17	A.G (ANALOG GND)						
18	FG						

Analog-to-Digital Conversion Modules: Q64AD, Q68ADV, Q68ADI

I/O and Buffer Memory Lists

I/O list

Device No.	Signal Name	Device No.	Signal Name
X00	Module ready	Y00 to Y08	Not used
X01	Temperature drift compensation status flag		
X02 to X08	Not used		
X09	Operating condition setting completion flag	Y09	Operating condition setting request
X0A	Offset/gain setting mode status flag	Y0A	User range write request
X0B	Channel changing completion flag	Y0B	Channel changing request
X0C to X0D	Not used	YOD	Max/minimum value reset request
X0E	Analog-to-digital conversion completion flag	Y0C, 0E	Not used
X0F	Error occurrence flag	Y0F	Error clear request

Buffer memory list

\ddres:	Description	Addres:	Description	Address	Description	Address	Description
0	Analog-to-digital conversion enable/disable setting	11	CH1. digital output value	21	Setting range check (CH.5 to CH.8)	35	CH.3 minimum value
1	CH1 average time, average count	12	CH2. digital output value	22	Offset/gain setting mode	36	CH.4 maximum value
2	CH2 average time, average count	13	CH3. digital output value		Offset designation	37	CH.4 minimum value
3	CH3 average time, average count	14	CH4. digital output value	23	Offset/gain setting mode	38	CH.5 maximum value
4	CH4 average time, average count	15	CH5. digital output value		Offset designation	39	CH.5 minimum value
5	CH5 average time, average count	16	CH6. digital output value	24 to 29	Reserved for system	40	CH.6 maximum value
6	CH6 average time, average count	17	CH7. digital output value	30	CH.1 maximum value	41	CH.6 minimum value
7	CH7 average time, average count	18	CH8. digital output value	31	CH.1 minimum value	42	CH.7 maximum value
8	CH8 average time, average count	19	Error code	32	CH.2 maximum value	43	CH.7 minimum value
9	Averaging designation	20	Setting range	33	CH.2 inimum value	44	CH.8 maximum value
10	Analog-to-digital conversion completion flag		(CH.1 to CH.4)	34	CH.3 maximum value	45	CH.8 minimum value

Note 1: The Q64AD having 4 channels of analog inputs does not have the areas corresponding to CH.5 to CH.8.

Analog-to-digital conversion enable/disable

setting



● CH average time, average count

For count-based averaging, set within the range 4 to 62500 times.

For time-based averaging, set within the range 2 to 5000ms.

CH digital output value, CH maximum value, CH minimum value

16-bit signed binary values are stored.

Setting range check

Area used to check the setting ranges set from GPPW.

	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0	_
CH4			CH3				CH2				CH1				Address 20		
CH8				CH7				CH6				CH5				Address 21	
	0н: 4~20mA, 4н: - 10~+10V,			<i>'</i>		н:0~ н:0~		'		1~ user	- /		kn:0∽ inge	~ 5V,			

Averaging designation



Conversion completion flag



Offset/gain setting mode designation

Specify the channels where offset/gain selection will be set by the user.



Overview

SW0D5C-QADU-E is a utility package designed to set initial data needed to use the Q64AD, Q68ADV or Q68ADI analog-to-digital conversion module and to set automatic reading of analog-to-digital converted data to the CPU device memory. It is used by adding it onto SW4D5C-GPPW-E or later.

When using the Q64AD, Q68ADV or Q68ADI, QADU is not required as initial value setting and others can be made in sequence programs, but using QADU can reduce sequence programs and facilitate the checking of the setting status and operating status.

Initial Data Setting

Initial value setting necessary to use the analog-to-digital conversion module can be made on the screen. The following table lists the types of initial values that may be set.

Item	Description
Analog-to-digital conversion enable/disable	Specifies the channel where analog-to-digital conversion will be made.
Sampling/averaging	Chooses sampling or averaging.
Time average/count average selection	Chooses time average or count average for averaging selection.
Time/count	Specifies average count or average time.

Initial value setting screen sample

Initial setting	
	art I/O No.: 0000
Module type: A/D Conversion Module	
Setting item	Setting value
CH1 A/D conversion enable/disable setting	Enable 👻
CH1 Sampling process/averaging process setting	Sampling 🗸
CH1 Time/number of times specifying	Number of times -
CH1 Average time/average number of times setting (Setting range) Time: 2 to 5000 ms Number of times: 4 to 62500 times	4
CH2 A/D conversion enable/disable setting	Enable 👻
CH2 Sampling process/averaging process setting	Sampling 🗸 🗸
	- Details
Make text file Er	nd setup

Automatic Refresh Setting

By making automatic refresh setting, you can automatically read analog-to-digital converted data, etc. from the analog-to-digital conversion module into the CPU, reducing programs. In automatic refresh setting, assignment is made to set the CPU devices to which the analog-to-digital conversion module data will be read. The following data can be refreshed automatically.

Analog-to-digital converted value of each channel Error code detected by the analog-to-digital conversion module Maximum and minimum values of the analog-to-digital converted value of each channel

Automatic refresh setting screen sample

Module model name: Q68ADV Module type: A/D Conversion Module	Start I/O	No. 000	0			
Setting item	Module side Buffer size	Module side Transfer word count		ransfer irection	PLC side Device	-
CH1 Digital output value	1	1		÷	DO	-
CH2 Digital output value	1	1		÷	D1	
CH3 Digital output value	1	1		·>	D2	-
CH4 Digital output value	1	1		•>	D3	-
CH5 Digital output value	1	1		·>	D4	-
CH6 Digital output value	1	1		·>	D5	-
CH7 Digital output value	1	1		·>	D6	-
CH8 Digital output value	1	1		·>	D7	-
CH1 Maximum value	1	1		•>	D8	٦.
Make text file			End setup		Cancel	

Monitoring and Testing Functions

The monitoring and testing functions are designed to monitor the data states and operating status in the analog-to-digital conversion module to force the set values to be changed as required. Since you can acquire the operating status without needing to know the addresses in the analog-to-digital conversion module, these functions are effective for system adjustment and troubleshooting. The following data can be monitored and tested.

Target	Item
Analog-to-digital converted value	Module ready Analog-to-digital conversion completion flag Analog-to-digital converted value of each channel Temperature drift compensation status flag Maximum/minimum value of each channel Maximum/minimum value reset request
Error	Error code Error occurrence flag Error clear request
Operating condition	Analog-to-digital conversion enable/disable setting Sampling/averaging setting Averaging condition
Input range	Input range setting status Offset/gain setting

Digital-to-Analog Conversion Modules: Q62DA, Q64DA

Overview

Digital data given by the CPU module are converted into analog signals and output to an external device. With the CPU module-processed data converted into analog data, information can be sent to equipment which handles analog data, e.g. an inverter.

Features

- Model selection according to applications
 - 1) Q62DA 2 channels. Voltage or current output can be chosen per channel.
- 2) Q64DA 4 channels. Voltage or current output can be chosen per channel.
- Fast conversion processing
- Conversion speed is as high as 80μ s/channel.
- High accuracy

Conversion accuracy is as high as $\pm 0.1\%$ (operating ambient temperature $25\pm5^{\circ}$ C).

Output range switching

Output range (Note 1) switching can be set easily from the GPPW function software package.

- Note 1: The output range indicates the offset/gain setting type. The types often used are provided as defaults, and the user can use others by offset/gain setting.
- Simple setting by utility package

The optional SW0D5C-QDAU-E utility package is available. The use of the utility package is not required, but using the utility package allows initial setting and automatic refresh setting to be made on the screen to reduce sequence programs and facilitate the checking of the setting status and operating status.

Functions

Synchronous output function

This function sets a constant time $(120\mu s)$ between CPU's digital value write and analog value output. This function can be used with the constant scan function of the PLC CPU to exercise precision analog control.



Note 2: Using this function makes only one channel available and the other channels unavailable.

Analog output hold/clear function

When the CPU module is in error or STOP status, this function allows the analog value to be held or cleared. (Setting can be made per channel.)





<Q62DA, Q64DA accessories>

Product	Description
Manual	Q62DA, Q64DA User's Manual (Hardware)

<Separately prepared products>

The following manual must be prepared separately.

Product	Description
Manual	Q62DA, Q64DA User's Manual (Details)

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E or later	For sequence programming	0
SW0D5C-QDAU-E	Digital-to-analog module utility package	Δ

 \bigcirc : Must be prepared. \triangle : Prepared as required.

Note 3: The software of the above products or later version are usable.

Digital-to-Analog Conversion Modules: Q62DA, Q64DA

Performance Specifications Туре Q62DA Q64DA Item Number of analog output points 2 points (2 channels) 4 points (4 channels) Digital input -4096 to 4095 Voltage -10 to 10VDC (external load resistance 1k to 1M Ω) Analog output 0 to 20mADC (external load resistance 0 to 600 Ω) Current I/O characteristics Max. resolution Digital input value Input Analog output range Max. resolution 0 to 4000 0 to 5V 1.25mA Voltage 1 to 5V 1.0mV -4000 to 4000 -10 to 10V 2.5mV Current 0 to 4000 0 to 20mA 5µA 4 to 20mA 4μA Accuracy Ambient temperature ±0.1% 25±5°C (accuracy to full-Ambient temperature ±0.3% scale) 0 to 55° C Conversion time 80 µs/channel Voltage Absolute max. ±12V 21mA output Current Yes Output short circuit protection Insulation system Across I/O terminals and PLC power supply: Photocoupler insulation Across output channels: No insulation Across external supply power and analog output: No insulation Number of points occupied 16 points Connection terminal 18-point terminal block Core: 0.3 to 0.75mm², OD: 2.8mm (0.11inch) max. Applicable wire size Applicable crimping terminal R1.25-3 (sleeved crimping terminal cannot be used) 24VDC+20%, -15% External supply power Ripple, spike, 500mVp-p max. 125mA 180mA Internal current consumption 330mA 345mA (5VDC) Weight (kg (lb)) 0.19 (0.42)

External Wiring



Terminal		Sigr	nal Name	al Name			
Number	Q6	2DA	Q64DA				
1	CH1	V+	CH1	V+			
2		COM		COM			
3		l+		l+			
4	Vacant		Vacant				
5	CH2	V+	CH2	V+			
6		COM		COM			
7		l+		l+			
8	Vacant		Vacant				
9	Vacant		CH3	V+			
10	Vacant			COM			
11	Vacant			l+			
12	Vacant		Vacant				
13	Vacant		CH4	V+			
14	Vacant			COM			
15	Vacant			l+			
16	24V						
17	24G						
18	FG						

Digital-to-Analog Conversion Modules: Q62DA, Q64DA

I/O and Buffer Memory Lists

I/O list

Device No.	Signal Name	Device No.	Signal Name
X00	Module ready	Y00	Vacant
X01 to X08	Not used	Y01	CH.1 output enable/disable flag
		Y02	CH.2 output enable/disable flag
		Y03	CH.3 output enable/disable flag
		Y04	CH.4 output enable/disable flag
		Y05 to Y08	Not used
X09	Operating condition setting completion flag	Y09	Operating condition setting request
X0A	Offset/gain setting mode status flag	Y0A	User range write request
X0B	Channel changing completion flag	Y0B	Channel changing request
X0C	Set value changing completion flag	YOC	Set value changing request
X0D	Synchronous output mode status flag	YOD	Synchronous output request
X0E	Not used	Y0E	Not used
X0F	Error occurrence flag	Y0F	Error clear request

Note 1: Signals to CH.3 and CH.4 are valid for the 4-channel output Q64DA.

Buffer memory list

Address	Description	Address	Description	Address	Description
0	Digital-to-analog conversion enable/disable	11	CH.1 set value check code	21	Vacant
1	CH.1 digital value	12	CH.2 set value check code	22	Offset/gain setting mode Offset
2	CH.2 digital value	13	CH.3 set value check code		designation
3	CH.3 digital value	14	CH.4 set value check code	23	Offset/gain setting mode
4	CH.4 digital value	15 to 18	Vacant		Gain designation
5 to 9	Vacant	19	Error code	24	Offset/gain adjustment value designation
10	Vacant	20	Setting range		

Note 1: Data for CH3 and CH4 are valid for the 4-channel output Q64DA.

Digital-to-analog conversion enable/disable

setting



● CH set value check code

The range check result of the written digital value is stored.

000FH: The digital value written is more than the setting range. 00F0H: The digital value written is less than the setting range. 00FFH: The digital value written is outside the setting range.

• Offset/gain setting mode designation

Specify the channels where offset/gain selection will be set by the user.



● CH digital value

Write the digital value as a 16-bit signed binary value. Setting range

For voltage output: -4096 to 4095 For current output: 0 to 4095

• Setting range check

Area used to check the setting ranges set from GPPW.

Ł	515	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0	
	CH4					C	CH3			CH2				CH1			
	0н: 4~20mA,					1н: 0 ~ 20mA, 2н: 1 ~ 5V,					,	3н:	0~:	5V,			
	4н: - 10 ~ +10V,					FH: user setting range											

• Offset/gain adjustment value designation To adjust the analog output value in the offset/gain selection mode, write a digital value of -3000 to 3000 to determine the offset or gain value.

Set value designation	
Set value changing request (Y0C)	
Set value changing completion flag (X0C)	

Overview

SW0D5C-QDAU-E is a utility package designed to set initial data needed to use the Q62DA or Q64DA digital-toanalog conversion module and to set automatic writing of digital-to-analog converted data from the CPU device memory to the digital-to-analog conversion module, and is used by adding it onto SW4D5C-GPPW-E or later. When using the Q62DA or Q64DA, the use of QDAU is not required and initial value setting and others can be made in sequence programs, but using QDAU can reduce their sequence programs and facilitate the checking of the setting status and operating status.

Initial Data Setting

Initial value setting necessary to use the digital-to-analog conversion module can be made on the screen. The following table lists the types of initial values that may be set.

Item	Description
Digital-to-analog	Specifies the channel where digital-to-
conversion enable/disable	analog conversion will be made.

Initial value setting screen sample



Automatic Refresh Setting

By making automatic refresh setting, you can automatically write digital-to-analog converted data, etc. from the CPU to the digital-to-analog conversion module, reducing programs. In automatic refresh setting, assignment is made to set the CPU device data which will be written to the digital-to-analog conversion module and the CPU devices to which the digital-to-analog conversion module data will be read. The following data can be refreshed automatically.

Digital-to-analog converted value of each channel Range check code for digital-to-analog converted digital value Error code detected by the digital-to-analog conversion module

Automatic refresh setting screen sample

Module type: D/A Conversion Module				
Setting item	Module side Buffer size	Module side Transfer word count	Transfer direction	PLC side _
CH1 Digital value	1	1	<-	DO
CH2 Digital value	1	1	<.	D1
CH3 Digital value	1	1	<-	D2
CH4 Digital value	1	1	<-	D3
CH1 Set value check code	1	1	·>	D4
CH2 Set value check code	1	1	·>	D5
CH3 Set value check code	1	1	÷	
CH4 Set value check code	1	1	÷	
Error code	1	1	÷	

Monitoring and Testing Functions

The monitoring and testing functions are designed to monitor the data states and operating status in the digitalto-analog conversion module to force the set values to be changed as required. Since you can acquire the operating status without needing to know the addresses in the digital-to-analog conversion module, these functions are effective for system adjustment and troubleshooting. The following data can be monitored and tested.

Target	Item
Digital-to-analog	Module ready
conversion	Synchronous output mode status flag
	Synchronous output request
	Digital-to-analog converted value of each
	channel
	Each channel output enable/disable flag
Error	Digital value check code
	Error code
	Error occurrence flag
	Error clear request
Operating condition	Digital-to-analog conversion enable/disable
	setting
Output range	Output range setting status
	Offset/gain setting

Monitoring/testing screen sample

onitor		
Module information		
Module model name: Q64DA Sta	rt I/O No.: 0000	
Module type: D/A Conversion Module		
Setting item	Current value	Setting value
CH1 Digital value	750	750
CH2 Digital value	880	880
CH3 Digital value	0	0
CH4 Digital value	0	0
CH1 Set value check code	0000	
CH2 Set value check code	0000	
CH3 Set value check code	0000	
CH4 Set value check code	0000	
Error code	0	
Setting range	0000	
X/Y monitor/test		X/Y monitor/test
Operating condition setting		Operating setting
Offset/gain setting		Offset/gain setting
Flash ROM setting	- Details-	
Write to File save display	Monitoring	Cannot execute tes
Read from File read Make text file		
Start monitor Stop monitor	Execute test	Close

High-Speed Counter Modules: QD62, QD62E, QD62D

Overview

The QD62, QD62E and QD62D are high-speed counter modules designed to count high-speed pulse trains. They can be used with external encoders to exercise control such as positioning. These three modules differ as indicated below and are selected according to your applications.

Item	QD62	QD62E	QD62D
	DC input	DC input	Differential input
Max. counting	Sink output 200kPPS	Source output	Sink output 500kPPS
speed			00011110

Features

32-bit counting range

There are two input channels which are independent and can count signed 32-bit binary values (-2147483648 to 2147483647), respectively.

Counting speed switching function

The max. counting speed can be changed to count a wide range of pulses from high-speed pulses to low-frequency pulses of slow leading/trailing edge.

Input system selection

The input system can be selected from among singlephase multiplied by one, single-phase multiplied by two, two-phase multiplied by one, two-phase multiplied by two, two-phase multiplied by four, and CW/CCW.

Counter type selection

You can choose either of the linear counter and ring counter types.

• CPU module interrupt function

When the preset count value is reached, an interrupt signal is output to the CPU module to start an interrupt program.

Counter selection function

One function can be chosen for use from among four different counter functions.

Function control from external terminal

The preset or counter function can be selected by applying a voltage to the external preset terminal or function start terminal.

Maintainability improvement

The X input signal and module indicator LED indicate that a fuse blown in the external output section is detected.

• Ease of setting by utility package

The optional utility package (SW0D5C-QCTU-E) is available. The use of the utility package is not required, but using the utility package allows initial setting and automatic refresh setting to be made on the screen to reduce sequence programs and facilitate the checking of the setting status and operating status.

Function List

Ν	lame	Description
	nter function	Can count in the range - 2147483648 to 2147483647. Detects overflow if this range is exceeded.
Ring counter function		 Counting alternates between the maximum and minimum values of the ring counter.
Coincidence output function		 Outputs an ON/OFF signal after comparing the preset coincidence detection point of any channel with the present value of the counter. On detection of coincidence, produces a PLC CPU interrupt signal to start an interrupt program.
Preset function		 Changes the present value of the counter to any value. Preset operation can be done either by a sequence program or by an external preset input.
Counter selection	Count disable	• Stops counting pulses while the count enable command is ON.
function	Latch counter	 Stores the present value of the counter when the signal of the counter function selection start command is input.
Sampling counter Periodic pulse counter		 After the counter function selection start command is input, input pulses are counted during a preset sampling period and stored in the buffer memory.
		• While the signal of the counter function selection start command is input, the present value is stored in the buffer memory at preset intervals.

These functions can be used together. However, you can choose only one of the linear counter and ring counter functions. Also, you can choose and use only one of the four counter function selection functions.

High-Speed Counter Modules: QD62, QD62E, QD62D

MODEL SELECTION INTELLIGENT FUNCTION MODULES



Indicator LED	Description
ϕ A	A-phase pulse input indication
ϕ B	B-phase pulse input indication
DEC.	Counter down-counting indication
FUNC.	Function start input indication
FUSE.	Coincidence signal output section fuse blow
	indication

External I/O Terminals

QD62 external I/O terminals

	Terr	ninal	
Internal Circuit	1	bers	Signal Name
	CH1	CH2	
	A20	A13	A-phase pulse input 24V
	B20	B13	A-phase pulse input 12V
	A19	A12	A-phase pulse input 5V
	B19	B12	ABCOM
	A18	A11	B-phase pulse input 24V
	B18	B11	B-phase pulse input 12V
	A17	A10	B-phase pulse input 5V
	_		_
	B17	B10	Preset input 24V
	A16	A09	Preset input 12V
	B16	B09	Preset input 5V
	A15	A08	CTRLCOM
	B15	B08	Function start input 24V
	A14	A07	Function start input 12V
	B14	B07	Function start input 5V
	_	_	_
	A06	A05	EQU1 Coincidence output point No. 1
	B06	B05	EQU2 Coincidence output point No. 2
To fuse blow detection Fuse	B02, B01		12/24V
circuit	A02, A01		0V

Terminal numbers A03, A04, B03 and B04 are not used.

High-Speed Counter Modules: QD62, QD62E, QD62D

QD62E external I/O terminals

Internal Circuit	Terminal Numbers		Signal Name
internal offcult	CH1	CH2	Signar Name
	A20	A13	A-phase pulse input 24V
	B20	B13	A-phase pulse input 12V
	A19	A12	A-phase pulse input 5V
	B19	B12	АВСОМ
	A18	A11	B-phase pulse input 24V
	B18	B11	B-phase pulse input 12V
	A17	A10	B-phase pulse input 5V
	_	_	_
	B17	B10	Preset input 24V
	A16	A09	Preset input 12V
	B16	B09	Preset input 5V
	A15	A08	CTRLCOM
	B15	B08	Function start input 24V
	A14	A07	Function start input 12V
	B14	B07	Function start input 5V
			_
	A06	A05	EQU1 Coincidence output point No. 1
	B06	B05	EQU2 Coincidence output point No. 2
To fuse blow detection	B02, B01		12/24V
circuit	A02, A01		0V

Terminal numbers A03, A04, B03 and B04 are not used.

QD62D external I/O terminals

	Terr	ninal	
Internal Circuit	Numbers		Signal Name
	CH1	CH2	
→ +5V (DC/ DC converter)	A20	A14	A-phase pulse input
	B20	B14	A-phase pulse input
→ +5V (DC/ DC converter)	A19	A13	B-phase pulse input
	B19	B13	B-phase pulse input
	A18	A12	Preset input 24V
	B18	B12	Preset input 12V
	A17	A11	Preset input 5V
	B17	B11	PRSTCOM
	A16	A10	Function start input 24V
	B16	B10	Function start input 12V
	A15	A09	Function start input 5V
	B15	B09	FUNCCOM
	A06	A05	EQU1 Coincidence output point No. 1
	B06	B05	EQU2 Coincidence output point No. 2
To fuse blow detection Fuse	B02, B01		12/24V
circuit	A02, A01		0V

Terminal numbers A08, A07, A04, A03, B08, B04 and B03 are not used.

High-Speed Counter Modules: QD62, QD62E, QD62D

Performance Specifications

	Item		QD62	QD62E	QD62D	
Counting speed changing setting			100k (10k to 100kPPS) 10k (10kPPS max.)		500k (200k to 500kPPS) 200k (100k to 200kPPS) 100k (10k to 100kPPS) 10k (10kPPS max.)	
Number of c	nannels		2 channels			
Count input Phase signal			Single-phase multiplied by one/single-phase multiplied by two/two-phase multiplied by one/two-phase multiplied by two/two-phase multiplied by four/CW/CCW			
0	Rated input v	oltage	5/12/24VDC (positive or negative common) EIA Standard RS-422-A			
	ON/OFF	5V	ON: 4.5 to 5.5V/2 to 5mA, OFF: 2V m	,	Differential line driver (Note 1) level	
	characteristic	s 12V	ON: 10.8 to 13.2V/2 to 5mA, OFF: 4V	max./0.1mA max.	1	
		24V	ON: 21.6 to 26.4V/2 to 5mA, OFF: 5V	max./0.1mA max.	1	
	Counting ran	qe	32-bit signed binary (-2147483648 to 2	2147483647)		
	Туре	•	UP/DOWN preset counter + ring coun	ter functions		
	Counting spe	ed	Refer to the separate list: counting sp			
External	Rated input v	oltage	5/12/24VDC (positive or negative com	imon)	5/12/24V (Note 2)	
nput	ON/OFF characteristic	5V s	ON: 4.5 to 5.5V/2 to 5mA, OFF: 2V max./0.1mA max.		ON: 2.5 to 5.5V/2 to 5mA, OFF: 1V max./0.1mA max.	
	endideteriorio	12V	ON: 10.8 to 13.2V/2 to 5mA, OFF: 4V	max./0.1mA max.		
		24V	ON: 21.6 to 26.4V/2 to 5mA, OFF: 5V max./0.1mA max.			
	Response tim	ne	OFF→ON: 0.5ms max., ON→OFF: 1ms max.			
Coincidence	Comparison I	range	32-bit signed binary (-2147483648 to 2147483647)			
output	Comparison s	system	Set value <count set="" value="" value,="">count value</count>			
	Number of points		2 points/channel	2 points/channel	2 points/channel	
	Output rating		Transistor (sink) 12/24VDC 0.5A/point 2A/common	Transistor (source) 12/24VDC 0.1A/point 0.4A/common	Transistor (sink) 12/24VDC 0.5A/point 2A/common	
ſ	Max. voltage drop		1.5V	· · ·	· · ·	
	Response	OFF→ON	0.1ms max.	0.3ms max.	0.1ms max.	
	time	$ON \rightarrow OFF$	0.1ms max.	0.3ms max.	0.1ms max.	
			(rated load, resistive load)	(rated load, resistive load)	(rated load, resistive load)	
	External supp	bly power	Voltage range: 10.2 to 30V, current consumption: 8mA (typ @24VDC)			
	External wirin	g protection	Fuse protection			
Number of I/	O points occup	vied	16 points (I/O assignment: 16 intellige	nt points)		
VDC intern	al current cons	umption (A)	0.30	0.33	0.38	
Veight (kg (b))		0.11 (0.24)		0.12 (0.26)	
External dimensions (mm (inch))			27.4 (1.08)(W) × 98 (3.86)(H) × 90 (3.	55)(D)		

Note 1: Japan Texas Instruments make Am216LS31 or equivalent

Note 2: EIA Standard RS-422-A differential line driver may also be used.

Separate list: counting speeds

Counting Speed Setting		10kPPS	100kPPS	200kPPS	500kPPS
Counting speed range	For 1-phase input	10k max.	10k to 100k	100k to 200k	200k to 500k
(PPS)	For 2-phase input	10k max.	10k to 100k	100k to 200k	200k to 500k
Minimum input pulse width tL, tH (μs)		50	5	2.5	1
Minimum input phase difference (for 2-phase input) (μ s)		25	2.5	1.25	0.5
Permissible ris		25 @10kPPS 500 @500PPS	2.5 @100kPPS 25 @10kPPS	1.25 @200kPPS 2.5 @100kPPS	0.5 @500kPPS 1.25 @200kPPS



Note 3: Inputting a waveform of long rise/fall time may cause false input. Enter a waveform within permissible rise/fall time.

High-Speed Counter Modules: QD62, QD62E, QD62D

I/O Signals to/from PLC CPU

Inpu	ıt Signal	s (Signal Direction QD62(E/D)→CPU)	Outpu	ut Signa	ls (Signal Direction CPU→ QD62(E/D))	
Device No.		Signal name	Device No.	Signal name		
X00	Modul	e ready	Y00		Coincidence signal No. 1 reset command	
X01		Counter value greater (point No. 1)	Y01		Preset command	
X02		Counter value coincidence (point No. 1)	Y02		Coincidence signal enable command	
X03		Counter value less (point No. 1)	Y03	CH1	Down count command	
X04	CH1	External preset request detection	Y04		Count enable command	
X05		Counter value greater (point No. 2)	Y05		External preset detection reset command	
X06		Counter value coincidence (point No. 2)	Y06		Counter function selection start command	
X07		Counter value less (point No. 2)	Y07		Coincidence signal No. 2 reset command	
X08		Counter value greater (point No. 1)	Y08		Coincidence signal No. 1 reset command	
X09		Counter value coincidence (point No. 1)	Y09		Preset command	
X0A		Counter value less (point No. 1)	Y0A		Coincidence signal enable command	
X0B	CH2	External preset request detection	Y0B	CH2	Down count command	
X0C		Counter value greater (point No. 2)	Y0C		Count enable command	
X0D		Counter value coincidence (point No. 2)	Y0D		External preset detection reset command	
X0E		Counter value less (point No. 2)	Y0E		Counter function selection start command	
X0F	Fuse b	blown detection flag	Y0F		Coincidence signal No. 2 reset command	

The I/O numbers (X/Y) and I/O addresses listed above assume that the QD62(E/D) is loaded in I/O slot 0 of the main base unit.

Buffer Memory Relative to PLC CPU

	Address					Cotting Dange and Dead Value	Initial Value	A
CH1 CH2		H2	Setting		Setting Range and Read Value	*1	Access from CPU	
Hex.	Dec.	Hex.	Dec.			Range	小]	IIOIII CPU
0H	0	20H	32	Preset value setting	(L)	-2147483648 to 2147483647	0	Read/write
1H	1	21H	33		(H)			
2H	2	22H	34	Present value	(L)	-2147483648 to 2147483647	0	Read only
ЗH	3	23H	35		(H)			
4H	4	24H	36	Coincidence output point	(L)	-2147483648 to 2147483647	0	Read/write
5H	5	25H	37	No. 1 setting	(H)			
6H	6	26H	38	Coincidence output point	(L)	-2147483648 to 2147483647		
7H	7	27H	39	No. 2 setting	(H)			
8H	8	28H	40	Overflow detection		0: no detection, 1: during detection	0	Read only
9H	9	29H	41	Counter function selection s	etting	0: count disable function	0	Read/write
						1: latch counter function		
						2: sampling counter function		
						3: periodic pulse counter function		
AH	10	2AH	42	Sampling/periodic time setti	ng	1 to 65535, increments: 10ms		
BH	11	2BH	43	Sampling/periodic counter fl	ag	0: during stop, 1: during operation	0	Read only

(Continued on next page)

High-Speed Counter Modules: QD62, QD62E, QD62D

	Add	ress			Sotting Range and Read Value	Initial Value	Access	
CI	H1	Cl	H2	Setting		Setting Range and Read Value Range	*1	from CPU
Hex.	Dec.	Hex.	Dec.			Kange	Φ Τ	IIOIII CFO
СН	12	2CH	44	Latch count value	(L)	-2147483648 to 2147483647	0	Read only
DH	13	2DH	45		(H)			
EH	14	2EH	46	Sampling count value	(L)	-2147483648 to 2147483647		
FH	15	2FH	47		(H)			
10H	16	30H	48	Periodic pulse count last	(L)	-2147483648 to 2147483647		
11H	17	31H	49	value	(H)			
12H	18	32H	50	Periodic pulse count	(L)	-2147483648 to 2147483647		
13H	19	33H	51	present value	(H)			
14H	20	34H	52	Ring counter lower limit	(L)	-2147483648 to 2147483647	0	Read/write
15H	21	35H	53	value setting	(H)			
16H	22	36H	54	Ring counter upper limit	(L)	-2147483648 to 2147483647		
17H	23	37H	55	value setting	(H)			
18H	24	38H	56	Reserved				
to	to	to	to			—	—	—
1FH	31	3FH	63					

(Continued)

*1: Initial values set at power-on or PLC CPU reset.

Equipment

<QD62, QD62E, QD62D accessories>

Product	Description
Manual	QD62, QD62E, QD62D User's Manual
	(Hardware)

<Separately prepared products>

Product	Description
Manual	QD62, QD62E, QD62D User's Manual (Details)
Connector	External wiring connector
	A6CON1, A6CON2, A6CON3

Note 1: As the external wiring connector is not packed with the module, always prepare it separately.

<Software>

Туре	Description	Remarks
SW4D5C-GPPW-E	For sequence	0
or later	programming	0
SW0D5C-QCTU-E	High-speed counter	
	module utility package	Δ

 \bigcirc : Must be prepared. \triangle : Prepared as required.

Note: The software of the above products or later version are usable.

Utility Package for High-speed Counter Modules: SW0D5C-QCTU-E

Overview

SW0D5C-QCTU-E is a utility package designed to set initial data needed to use the QD62, QD62E or QD62D high-speed counter module and to set automatic reading of count values to the CPU device memory, and is used by adding it onto SW4D5C-GPPW-E or later.

When using the QD62, QD62E or QD62D, the use of QCTU is not required and initial value setting and others can be made in sequence programs, but using QCTU can reduce sequence programs and facilitate the checking of the setting status and operating status.

Initial Data Setting

Initial value setting necessary to use the high-speed counter module can be made on the screen. The following table lists the types of initial values that may be set.

- (1) Preset value
- (2) Coincidence output point No. 1 setting
- (3) Coincidence output point No. 2 setting
- (4) Counter function selection setting
- (5) Sampling/periodic time setting
- (6) Ring counter upper limit value
- (7) Ring counter lower limit value

Initial value setting screen sample

- Module information						
Module model name: QD62 Start I/O No.: 0000						
Module type: High speed counter module						
Setting item	Setti	ng				
Preset value setting		0				
Coincidence output point set No.1		1200				
Coincidence output point set No.2		2400				
Counter function selection setting	Cycle PLS count	•				
Sampling/cycle set [unit:10ms]		1000				
Ring counter minimum value		0				
Ring counter maximum value		0				
	☐ Details	Decimal input				
	Setting range : -	2147483648 - 2147483647				

Automatic Refresh Setting

By making automatic refresh setting, you can automatically read count values, etc. from the high-speed counter module into the CPU, reducing programs. The following data can be refreshed automatically.

- (1) Present value
- (2) Latch count value
- (3) Sampling count value
- (4) Periodic pulse count present value

- (5) Periodic pulse count last value
- (6) Sampling/periodic counter flag
- (7) Overflow detection

Automatic refresh setting screen sample

Module model name: QD62 Module type: High speed counter modu	Start I/O 1 le	No. 0000		
Setting item	Module side Buffer size	Module side Transfer word count		PLC side Device
CH1 Present value	2	2	->	W100
CH1 Latch count value	2	2	->	W102
CH1 Sampling count value	2	2	->	W104
CH1 Cycle PLS count previous value	2	2	->	W106
CH1 Cycle PLS count present value	2	2	->	W108
CH1 Sampling/cycle counter flag	1	1	->	W10A
CH1 Overflow detection flag	1	1	->	W108
CH2 Present value	2	2	->	W200
CH2 Latch count value	2	2	->	W202 ,
			I	

Monitoring and Testing Functions

The monitoring and testing functions are designed to monitor the data states and operating status in the highspeed counter module to force the set values to be changed as required. Since you can acquire the operating status without needing to know the addresses in the highspeed counter module, these functions are effective for system adjustment and troubleshooting. The following data and functions can be monitored and tested.

- (1) X/Y device
- (2) Preset function
- (6) Present value
- (3) Coincidence output function
- (7) Overflow detection
- (8) Down count command
- (4) Counter function selection function
- (9) Count enable command

(5) Ring counter function

Monitoring/testing screen sample

lonitor		_ []			
Module information Module model name: QD62 S Module type: High speed counter module	tart 1/0 No.: 0000				
Setting item	Current value	Setting value	Ŀ		
CH1 Present value			1		
CH1 Overflow detection flag	No detection		1		
CH1 Down count instr	OFF	OFF 🔻	1		
CH1 Count enable instr	Disable	Disable 💌	1		
CH2 Present value	0		1		
CH2 Overflow detection flag	No detection		1		
CH2 Down count instr	OFF	OFF 🗸			
CH2 Count enable instr	Disable	Disable 🗸 🗸	1		
X/Y monitor/test		X/Y monitor/test	1		
Preset function		Preset	1		
Coincidence output function		Coincidence output	L		
Counter selection function		Counter selection			
Ring counter function		Bing counter	•		
Flash ROM setting Current value Details Write to module File save Current value Monitoring Read from module He read Make text file Monitoring					
Start monitor Stop monitor S	elect test	Close			

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

MODEL SELECTION INTELLIGENT FUNCTION MODULES

Overview

The QD71P1, QD75P2, QD75P4, QD75D1, QD75D2 and QD75D4 (hereafter referred to as the "QD75") are modules used with stepping motors or servo amplifiers to exercise machine position or speed control.

Features

Two different output systems

Two different output systems, open collector and differential driver systems, are available as command signals to a stepping motor or servo amplifier.

QD71P1, QD75P2, QD75P4: Open collector system QD75D1, QD75D2, QD75D4: Differential driver system The differential driver system can increase the distance from the QD75 to the servo amplifier and exercise fast, precision control.

Max. 1Mpps high-speed command

The differential driver system can give a max. 1Mpps high-speed command, achieving fast, precision control. The command pulse for the open collector system is max. 200kpps.

Assortment of 1-, 2- and 4-axis products

1-, 2- and 4-axis models are available in terms of the number of axes per module.

QD75P1, QD75D1: 1 axis

QD75P2, QD75D2: 2 axes

QD75P4, QD75D4: 4 axes

Also, since there are no restrictions on the number of modules loaded, multiple modules can be loaded and used if more than four control axes are needed.

Fast start

The QD75 can be started as fast as approx. 6ms after the CPU module has given it a start command, reducing the machine tact time.

 4-axis linear interpolation, 2-axis circular interpolation

You can exercise 2-, 3- or 4-axis linear interpolation control and 2-axis circular interpolation control. Note 1: Interpolation control can be performed when multiple

axes are used on the same QD75 module.

Wide selection of control systems

You have a choice of control systems such as PTP (Point to Point) control, fixed-feed control, equal-speed control and speed-position switching control.

<u> </u>	FUNCTION LIST					
	Main F	unction	Description			
ing trol	Machin control	e zero return	Sets up a positioning start point mechanically using a zeroing dog, stopper or like.			
Zeroing control	Fast zeroing control		Performs positioning to zero address stored in QD75 by machine zero return.			
	Linear control Linear interpolation control Fixed-feed control Fixed-feed control (interpolation) 2-axis circular interpolation control		Performs positioning in linear path to a position specified by address or travel. Performs positioning of specified travel. In 2-, 3- or 4-axis, fixed- feed control, fixed-feed is performed in linear path by interpolation. Performs positioning in circular path to position specified by address, travel, sub point, center point, etc.			
ltrol	Speed control	Linear control Linear interpolation control	Outputs consecutive pulses according to command speed.			
Major positioning control	Speed-position switching control		First exercises speed control, and then turns on "speed-position switching signal" to perform position control (positioning of specified travel).			
Major p		n-speed ng control	First exercises position control, and then turns on "position-speed switching signal" to perform speed control (output of consecutive pulses according to specified command speed).			
	Other control	Current value changing	Changes current feed value into address set in positioning data (mechanical feed value unchangeable).			
		NOP instruction	No-operation control mode. Shifts to operation of next data when this instruction has been set.			
		JUMP instruction	Makes an unconditional or conditional jump to specified positioning data No.			
	Diaska	FOR (count) ~ NEXT	Repeats FOR~NEXT loop control.			
ntrol	Block start (Ordinary start) Conditional start		processings by a single start. Judges conditions of "condition data" and executes "start block data". If conditions do not hold, executes "start block data" of next point.			
oning co	Wait start		Waits until conditions of "condition data" hold to execute "start block data".			
High-level positioning contro		neous start	Performs positioning of axes specified in "condition data" simultaneously (output of pulses at the same timing).			
Higł	Repeat (FOR lo	ed start pop)	Repeats positioning processing of start block data across "FOR~ NEXT" by the preset number of times.			
		ed start ondition)	Repeats positioning processing of start block data across "FOR~ NEXT" until "condition data" hold.			

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

	Main Function	Description					
	Restart	Gives stop signal to suspend					
g	ricoldit	positioning processing being					
High-level positioning control		executed, and then resumes					
itio		positioning to move over					
cos		remaining travel.					
o el p	Continuous operation	During continuous positioning processing, processing of					
è o	suspension function	positioning data being executed					
gh-		when suspension command is					
Î		given is suspended on completion					
		of its processing.					
	Jog operation	Outputs pulses only while jog start					
		signal is on.					
Manual control	Inching operation	Outputs one shot pulses for slight					
out		travel in manual operation.					
al c		(Makes fine adjustment with jog					
nu	Manual pulsa gaparatar	start signal.)					
Mai	Manual pulse generator	Outputs to servo amplifier the					
~	operation	pulses commanded by manual pulse generator. (Makes fine					
		adjustment, etc. on pulse level.)					
	Independent positioning	Executes only specified					
	control	positioning data and ends					
E	(Positioning end)	positioning.					
itte	Continuous positioning	After executing specified					
ba	control	positioning data, makes a stop,					
ion		and then executes next					
rat		continuous positioning data.					
Operation pattern	Continuous path control	Executes specified positioning					
0		data, and without deceleration to					
		stop, executes next continuous positioning data.					
		positioning data.					
	Sub Function	Description					
	OPR retry function	Makes OPR possible if axis is not					
	OPR retry function	returned to position before near					
r		returned to position before near point dog by jog operation, etc.					
DR	Home position shift	returned to position before near point dog by jog operation, etc. After machine OPR, compensates					
OPR		returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified					
OPR	Home position shift	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR					
OPR	Home position shift	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified					
-	Home position shift	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as					
-	Home position shift function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address.					
-	Home position shift function Backlash compensation	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical					
-	Home position shift function Backlash compensation function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness).					
-	Home position shift function Backlash compensation	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical					
Compensation	Home position shift function Backlash compensation function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness).					
-	Home position shift function Backlash compensation function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness).					
-	Home position shift function Backlash compensation function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse.					
-	Home position shift function Backlash compensation function Electronic gear function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse.					
-	Home position shift function Backlash compensation function Electronic gear function Speed limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value".					
-	Home position shift function Backlash compensation function Electronic gear function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated					
-	Home position shift function Backlash compensation function Electronic gear function Speed limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of					
-	Home position shift function Backlash compensation function Electronic gear function Speed limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that					
-	Home position shift function Backlash compensation function Electronic gear function Speed limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit.					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in					
_	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters.					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function Hardware stroke limit	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters. Makes deceleration to stop using					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters.					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function Hardware stroke limit function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters. Makes deceleration to stop using limit switch connected to external					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function Hardware stroke limit	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters. Makes deceleration to stop using limit switch connected to external input connector of QD75. Changes speed during positioning operation.					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function Hardware stroke limit function Speed changing	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters. Makes deceleration to stop using limit switch connected to external input connector of QD75. Changes speed during positioning varies speed during positioning					
Compensation function	Home position shift function Backlash compensation function Electronic gear function Speed limit function Torque limit function Software stroke limit function Hardware stroke limit function Speed changing function	returned to position before near point dog by jog operation, etc. After machine OPR, compensates for position over specified distance from machine OPR position to use that position as OPR address. Compensates for mechanical system backlash (looseness). Sets travel per pulse. Limits command speed to within setting range of "speed limit value". Limits servo motor-generated torque to within setting range of "torque limit value". Note that digital-to-analog conversion module is also needed for torque limit. Does not execute positioning to outside the setting range of upper and lower stroke limits set in parameters. Makes deceleration to stop using limit switch connected to external input connector of QD75. Changes speed during positioning operation.					

	Sub Function	Description
tion	Acceleration/deceleration time changing function	Changes acceleration/deceleration time at speed change.
Limit function	Torque changing function	Changes "torque limit value" during control.
Ē	Absolute position restoration function	Restores absolute value of specified axis.
	Step function	Can make a stop per "automatic deceleration" or "positioning data".
	Skip function	Suspends (decelerates to stop) currently executed positioning at entry of skip signal and starts next positioning.
	M code output function	Can set number between 0 and 65535 per positioning data as M code.
ſS	Teaching function	Registers address positioned by manual control as address of positioning data.
Others	Target position changing function	Changes target position during positioning. Can also change speed.
	Command in-position function	Sets "command in-position flag" when remaining distance up to positioning address has become less than preset distance at end of positioning.
	Acceleration/deceleration processing function	Adjusts acceleration/deceleration of control.
	Multiple-axis simultaneous start function	Starts multiple axes simultaneously. (Equivalent to simultaneous start in special start)
		-
Param	Other Function eter initialization function	Description Returns "set data" stored in flash ROM of QD75 to factory settings. The following two methods are available. 1) Using sequence program 2) Using QD75 software package
Execut	ed data backup function	Stores (backs up) currently executed "set data" in flash ROM. The following two methods are available. 1) Using sequence program 2) Using QD75 software package
I/O log	c switching function	Switches signal logic according to externally connected device.

Positioning Module: QD75P1, QD75P2, QD75P4, MODEL SELECTION INTELLIGENT FUNCTION MODULES

Main-sub function combination list

Sub Function			O	PR	Con nsa func		Liı	nit fu	uncti	on		Changing function					Oth	ners			
Main Fur	nction			OPR retry function	Home position shift function	Backlash compensation function	Electronic gear function	Speed limit function	Torque limit function	Software stroke limit function	Hardware stroke limit function	Speed changing function	Override function	Acceleration time changing function	Torque changing function	Step function	Skip function	M code output function	Teaching function	Command in-position function	Acceleration/deceleration processing function
	Machine OPR return ×		Combination with operation pattern	0	0	0	0	0	0	×	0	\triangle	\triangle	×	0	×	×	×	×	×	0
OPR	Fast OPR ×		×	—	—	0	0	0	0	×	0	0	0	0	0	×	×	×	×	×	0
	Line	Linear Linear interpolation	0	_	_	0	0	0	0	0	0	0	0	0	0	0	0	0	×	0	0
	Position control	Fixed-feed Fixed-feed interpolation		_	_	0	0	0	0	0	0	0	0	0	0	0	0	0	×	0	0
		Circular interpolation	0	_	_	0	0	0	0	0	0	0	0	0	0	0	0	0	×	0	0
ntrol	Speed control		(Only independent positioning control may be set)	_	_	0	0	0	0	0	0	0	0	0	0	×	0	0	×	×	0
Positioning control	Speed-position control Position-speed control	-	Control may be set) △ (Continuous path control setting disallowed)	_	_	0	0	0	0	0	0	0	0	0	0	0	0	0	×	0	0
		Current value changing																			
	Other	NOP			_	_	_	—	_	—	0	_	_	_	_	_	_	_	_	_	-
		JUMP																			
	FOR ~ NEXT		×																		
	Jog operation	•		_	_	0	0	0	0	0	0	0	0	0	0	×	×	×	0	×	0
Man- ual	Inching operat	tion		_	_	0	0	0	0	0	\odot	×	×	×	0	×	×	×	0	×	×
uui	Manual pulse	generator		_	_	0	0	0	0	0	\odot	×	×	×	0	×	×	×	0	×	×

QD75D1, QD75D2, QD75D4

 \odot : Must be combined, \bigcirc : May be combined, \triangle : Restrictions on combination, \times : Must not be combined, - : Setting invalid.

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

Overview

The following QD75 dedicated instructions may be used to create sequence programs for the QD75.

Dedicated Instruction Name	Instruction Specifications
ABRST1, ABRST2,	Used to restore the absolute
ABRST3, ABRST4	position of the specified axis.
PSTRT1, PSTRT2,	Used to start positioning of the
PSTRT3, PSTRT4	specified axis.
TEACH1, TEACH2,	Used to teach the specified axis.
TEACH3, TEACH4	
PFWRT	Used to write the parameters and
	positioning data on the QD75
	buffer memory to the flash ROM
	built in the QD75.
PINIT	Initializes the parameters and
	positioning data on the buffer
	memory and flash ROM.
ERRCLR	Clears an error and extinguishes
	the ERROR LED.
ERRRD	Read the error code.

Appearance



Note 1: For the QD71D1, QD75D2 and QD75D4, the type name printed is different from the one in the above diagram.



External I/O Terminals

Input terminals

Signal Name		Internal Circuit	Wir- ing	
Near point dog signal	DOG		Δ	
Upper limit switch signal	FLS		0	
Lower limit switch signal	RLS		0	
Stop signal	STOP		\triangle	
Speed-position switching	CHG		\triangle	
Common	СОМ	 -+	0	
	COM			
Manual pulse generator	PULSER A+			
A phase	PULSER A-		_	
Manual pulse generator	PULSER B+			
B phase	PULSER B-	* (\$3K)		
Drive unit ready	READY		0	
Common	RDY COM		0	
Zero signal	PG0 (24V) PG0 (5V)			
Common	PG0 COM			

Wiring: \bigcirc : wiring required, \triangle : wiring as required.

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

MODEL SELECTION INTELLIGENT FUNCTION MODULES

Output terminals (QD71P1, QD75P2, QD75P4)





Wiring: \bigcirc : wiring required, \bigtriangleup : wiring as required.

	Model	QD75P1	QD75P2	QD75P4					
Item		QD75D1	QD75D2	QD75D4					
Number of cont	rol axes	1 axis	2 axes	4 axes					
Interpolation fur	nction	No	2-axis linear interpolation 2-, 3-, 4-axis li 2-axis circular interpolation 2-axis circular						
Control system		PTP (Point To Point) control, path control (can be set for both linear and circular), speed control, speed-position switching control, position-speed switching control							
Control unit		mm, inch, degree, pulse							
Positioning data	a	600 pieces of data (positioning data N (Can be set using peripheral device or							
Backup		Parameters and positioning data can b	be saved in flash ROM (without battery).						
Positioning system Positioning Positioning Positioning Positioning Positioning Positioning Position, position-speed switching control Incremental system Incremental system Incremental system Path control Incremental system				2					
Positioning	Positioning range	In absolute system -214748364.8 to 214748364.7 (μm) -21474.83648 to 2147483647 (inch) 0 to 359.99999 (degree) -2147483648 to 2147483647 (pulse) In incremental system -21474.83648 to 2147483647 (µm) -21474.83648 to 2147483647 (µm) -21474.83648 to 2147483647 (µcgre) -21474.83648 to 21474.83647 (pulse) In speed-position switching control/po 0 to 214748364.7 (µm) 0 to 2147483647 (inch) 0 to 21474.83647 (pulse) 0 to 21474.83647 (pulse)	ee)						
	Speed command	0.01 to 2000000.00 (mm/min) 0.001 to 2000000.000 (inch/min) 0.001 to 200000.000 (degree/min) 1 to 1000000 (pulse/s)	0.001 to 2000000.000 (degree/min)						
	Acceleration/ deceleration processing	Automatic trapezoidal acceleration/de	celeration, automatic S-pattern accelerat	tion/deceleration					
	Acceleration/ deceleration time	1 to 8388608 (ms) Four patterns can be set for both acce	eleration and deceleration times.						
	Sudden-stop deceleration time	1 to 8388608 (ms)							

Performance Specifications

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

Item	QD75P1 QD75D1	QD75P2 QD75D2	QD75P4 QD75D4						
Applicable connector	A6CON1, A6CON2, A6CON3	A6CON1, A6CON2, A6CON3							
Applicable wire size	0.3mm ²	0.3mm ²							
Max. output pulse	For connection to differential driver: 1Mbps For connection to open collector: 200kbps								
Max. connection distance from servo	For connection to differential driver: 10m (32.79ft.) For connection to open collector: 2m (6.56ft.)								
Internal current consumption (5VDC)	QD75P1: 0.40A, QD75P2: 0.46A, QD75P4: 058A, QD75D1: 0.52A, QD75D2: 0.56A, QD75D4: 0.82A								
Number of I/O points occupied	32 points (I/O assignment: intelligent fu	Inction module 32 points)							
External dimensions (mm (inch))	QD75P /QD75D : 98 (3.86) (H) × 27.4 (1.08) (W) × 90 (3.55) (D)								
Weight (kg (lb))	QD75P1/P2/D1/D2: 0.15kg, QD75P4/D4: 0.16kg								

External I/O Specifications

Input specifications

Signal Name	Rated Input Voltage	Rated Input Current	ON Voltage/Current	OFF Voltage/Current	Input Resistance	Response Time			
Drive unit ready (READY) Stop signal (STOP) Upper limit signal (FLS) Lower limit signal (RLS)	24VDC (-20/+10%)	5mA	17.5VDC or more/3.5mA or more	7VDC or less/1.7mA or less	Αpprox. 4.7k Ω	4ms max.			
	5VDC (-10/+22%)	5mA	2VDC or more/ 2mA or more	0.5VDC or less/ 0.5mA or less	Approx. 0.3k Ω	1ms max.			
	24VDC (-50/+10%)	5mA	10VDC or more/ 3mA or more	3VDC or less/ 0.2mA or less	Approx. 4.7k Ω	1ms max.			
Zero signal (Z24/Z5)	$3 \mu s \text{ or less} \rightarrow / \leftarrow 3 \mu s \text{ or less}$								
	5VDC (-10/+22%)	5mA	2.5VDC or more/ 2mA or more	1VDC or less/ 1mA or less	Approx. 1.5k Ω	1ms max.			
Manual pulse generator A phase (PULSER A) Manual pulse generator B phase (PULSER B)	 Pulse width Phase difference 	2ms or n 2ms or n 1ms or more 1 (Duty ratio 50%) Pe A phase B phase	Ims or more	When A phas positioning ac (current value	e leads B phase, ddress) increases.				
Near point dog signal (DOG) External command signal (CHG)	24VDC (-10/+22%)	5mA	17.5VDC or more/ 3.5mA or more	7VDC or less/ 1.7mA or less	Approx. 4.3k Ω	1ms max.			

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

Output specifications (QD75P1, QD75P2, QD75P4)

Signal Name	Rated Load Voltage	Max Load Current		Max. Inrush ON-Time Max. Current Voltage Drop		Response Time
	5-24VDC (-5/+25%)	50mA/point	200mA 10ms max.	0.5V (TYP)	0.1mA max.	—
Pulse output (CW/PULSE/A phase) Pulse sign (CCW/SIGN/B phase)	ON / OFF	, rise/fall time and du	uty ratio are as giver 1: See the following	, , , , , , , , , , , , , , , , , , ,	*	
Deviation counter clear (CLEAR)	5-24VDC (-5/+25%)	0.1A/point	0.4A 10ms max.	1VDC (TYP) 2.5VDC (MAX)	0.1mA max.	2ms max. (resistive load)

Note 1: Pulse rise/fall time on QD75P (unit tr, tf: µs Duty: %) ... When ambient temperature is room temperature

Load vo	ltage(V)			26	6.4			4.75					
Cable le	ength(m)		1			2			1		2		
Load current (mA)	Pulse speed (kpps)	tf (Rise)	tr (Fall)	Duty									
	200	0.08	2.33	6.6	0.08	0.20	14.6	0.07	0.57	44.8	0.07	0.95	39.0
2	100	0.09	2.42	34.7	0.10	4.44	12.6	0.07	0.57	47.5	0.08	1.01	45.3
	10	0.09	2.44	48.7	0.10	4.52	47.7	0.07	0.60	49.7	0.08	1.04	49.5
	200	0.09	1.00	39.8	0.11	1.77	24.5	0.07	0.32	48.4	0.08	0.45	45.8
5	100	0.09	1.01	45.3	0.10	1.76	40.3	0.07	0.31	49.2	0.08	0.45	48.7
	10	0.10	1.00	49.6	0.10	1.72	49.2	0.08	0.33	49.9	0.08	0.49	49.8
	200	0.10	0.27	50.1	0.11	0.44	48.0	0.08	0.15	50.7	0.08	0.15	51.3
20	100	0.10	0.29	49.8	0.11	0.48	49.1	0.08	0.15	50.4	0.08	0.18	50.4
	10	0.10	0.30	49.9	0.12	0.48	49.9	0.08	0.17	50.1	0.08	0.18	49.9
	200	0.11	0.19	50.5	0.12	0.24	50.6	0.10	0.15	51.8	0.11	0.14	51.7
50	100	0.11	0.19	50.4	0.12	0.24	50.4	0.10	0.14	50.7	0.10	0.15	50.8
	10	0.12	0.18	50.0	0.13	0.22	50.1	0.10	0.14	50.1	0.12	0.15	50.1

Output specifications (QD75D1, QD75D2, QD75D4)

Signal Name	Rated Load Voltage	Max Load Current		OFF-Time Leakage Current	Response Time	
Pulse output (CW/PULSE/A phase) Pulse sign (CCW/SIGN/B phase)		lent differential driver .8V or more, OFF: 0.6V	′ or less)			
Deviation counter clear (CLEAR)	5-24VDC (-5/+25%)	0.1A/point	0.4A 10ms max.	1VDC (TYP) 2.5VDC (MAX)	0.1mA max.	2ms max. (resistive load)

Positioning Module: QD75P1, QD75P2, QD75P4, QD75D1, QD75D2, QD75D4

	QD75 to PLC	CPU	PLC CPU to QD75					
X0	QD75 ready		Y0	PLC ready				
X1			Y1					
X2	Must not be	used.	Y2	Must not be	used.			
X3			Y3					
X4	Axis 1		Y4	Axis 1				
X5	Axis 2	M code	Y5	Axis 2	Avia atan			
X6	Axis 3	ON	Y6	Axis 3	Axis stop			
X7	Axis 4		Y7	Axis 4				
X8	Axis 1		Y8	Axis 1	Forward rotation jog start			
Х9	Axis 2	Error	Y9	Axis 1	Reverse rotation jog start			
ХА	Axis 3	detection	YA	Axis 2	Forward rotation jog start			
ХВ	Axis 4		YB	Axis 2	Reverse rotation jog start			
XC	Axis 1		YC	Axis 3	Forward rotation jog start			
XD	Axis 2		YD	Axis 3	Reverse rotation jog start			
XE	Axis 3	BUSY	YE	Axis 4	Forward rotation jog start			
XF	Axis 4		YF	Axis 4	Reverse rotation jog start			
X10	Axis 1		Y10	Axis 1				
X11	Axis 2	Start	Y11	Axis 2	Position- ing			
X12	Axis 3	completion	Y12	Axis 3	start			
X13	Axis 4		Y13	Axis 4				
X14	Axis 1		Y14					
X15	Axis 2	Position- ing	Y15					
X16	Axis 3	completion	Y16					
X17	Axis 4		Y17					
X18	Axis 1		Y18					
X19	Axis 2		Y19	Must not be	used			
X1A	Axis 3		Y1A	Must HULDE	useu.			
X1B	Axis 4	Must not	Y1B					
X1C	Axis 1	be used.	Y1C					
X1D	Axis 2		Y1D					
X1E	Axis 3		Y1E]				
X1F	Axis 4		Y1F					

I/O Signals to/from PLC CPU

Equipment

<Accessories>

Product	Description
Manual	QD75P/QD75D User's Manual (Hardware)

<Separately prepared products>

Product	Description				
Manual	QD75P/QD75D User's Manual (Details)				
Connector	External wiring connector A6CON1, A6CON2, A6CON3				
External wiring cable	Cables having external wiring connectors (A6CON1, A6CON2, A6CON3) with wiring for specific servo amplifiers and stepping motors are also available. Refer to "MODEL SELECTION- ACCESSORIES".				

Note 1: As the external wiring connector is not packed with the module, always prepare it separately.

<Software>

Product	Description	Remarks
SW4D5C-GPPW-E	For sequence	\Box
or later	programming	
SW0D5C-QD75P-E	Software for QD75	\triangle

 \bigcirc : Must be prepared. \triangle : Prepared as required.

Note 2: The software of the above products or later version are usable.

Positioning Module Software: SW0D5C-QD75P-E

Overview

SW0D5C-QD75P-E is a software package for QD75 positioning module which allows various parameters and positioning data to be set to the QD75, the control status of the QD75 to be monitored, and the QD75 to be testoperated. Simple operation in Windows permits you to fully utilize a wide range of functions of the QD75.

Features

 Windows compatibility ensures outstanding operability

You can cut, copy and paste positioning data and start block data efficiently. You can also copy Microsoft Excelor Word-created data for use as positioning data.

• Ease of checking wiring connections In the software, you can check the status of I/O wiring connected to the QD75. You can also start the system efficiently by initializing the QD75 or performing jog operation.

 Full line of functions assists debugging and maintenance

The module has a full line up of functions, e.g. function to perform (offline) simulation based on the preset positioning data, and monitoring functions useful for debugging and maintenance, such as sampling monitoring which shows the positioning module I/O signals, external I/O signals and buffer memory status in the form of a timing chart.

<Offline simulation example>



<Sampling monitoring examples>





• Ease of checking error and warning causes The online help function ensures ease of checking the cause and corrective action of the error or warning code displayed by positioning system operation monitoring or error history monitoring.



 Simultaneous monitoring of sequence programs
 When used with the GPPW function software package, this software can perform efficient debugging.
 <Example of simultaneously starting SWD5C-QD75P-E and GPPW>

Positioning Module Software: SW0D5C-QD75P-E



Function List

	Function	Description
	Parameter setting	Sets parameters of each axis.
	Positioning data setting	Sets positioning data.
	Positioning data	Monitors data of positioning being
	monitoring	executed.
	Positioning data test	Performs test operation of
		positioning control.
	Teaching	Sets axis to address of positioning
		data by teaching operation.
Edit	M code comment setting	Sets comment to M code.
ш	Simulation	Performs offline/real-time
	Block start data setting	simulation. Sets block start data.
	Block start data setting	Monitors point under positioning
	monitoring	control.
	Block start data test	Performs test operation of
		positioning control from block start
		point.
	Condition data setting	Sets start conditions of start block
		data.
	Running monitoring	Monitors running states such as
		feed current value, axis feedrate
	l listen en en literie e	and axis status.
	History monitoring	Monitors error, warning, start and error-time start history.
	Signal monitoring	Monitors X/Y devices, external
	Signal monitoring	signals and status signals.
Monitoring	Operation monitoring	Monitors control status, preset
nito		parameters, etc.
Moi	Operation test	Tests positioning data number-
		specified start, current value
		changing, speed changing,
		zeroing, jog operation and manual
	0 11 11 1	pulse generator operation.
	Sampling monitoring	Simultaneously samples and monitors specified signals and
		buffer memory.
	Connection check	Initializes QD75 and displays
ion		signals from external devices.
connectior		Also performs initial operation test
conr liagr		by jog operation.
90		

Operating Environment

Item	Description
Peripheral device	Pentium 133MHz or more (recommended) personal computer on which Windows operates
Operating system software	Microsoft Windows 95/98, Microsoft Windows NT workstation 4.0
Required memory	Recommended 32MB or more
Hard disk	40Mbyte or more free space needed
Disk drive	CD-ROM drive required
Display	Resolution 800 × 600 pixels or more

Connection with QD75

When set data is downloaded to the QD75 or the operating status is monitored, SW0D5C-QD75P-E is not directly connected to the QD75. Since SW0D5C-QD75P-E and QD75 make data communications via the Q mode CPU module, the SW0D5C-QD75P-E installed personal computer is connected to the Q mode CPU module by RS-232 or USB.

For the RS-232 and USB cables, refer to the explanation section of "Programming"-"Peripheral Devices".

Separately Prepared Product

Product	Description
Manual	SW0D5C-QD75P-E Operating Manual

Note 1: The PDF format data of the same contents as those of the above separately prepared manual are included in the CD-ROM of SW0D5C-QD75P-E.

Current Consumption Calculation

Overview

The PLC system operates on 5VDC supplied from the power supply module.

The sum of 5VDC current consumption values of the CPU, I/O, intelligent function and network modules loaded on one base unit should not exceed the rated output current of the power supply module. If so, the number of modules loaded on the base unit must be reduced.

Calculation Method

Make sure that the current consumption is as indicated in the following relational expression.

(Rated output current of power supply module) \geq (sum of 5VDC current consumption values of modules)



Refer to "Applicable Equipment List" for the current consumption value of each module.

Calculation example) System configuration							(Bas	e unit: Q	312B]	
CPL Q02 Q61	Input module QX10	Output module QY10	Intelligent function module Q64AD	module Q62DA								

Rated output current of power supply module

Туре	Rated Output Current (A)			
Q61P-A1	6			

5VDC current consumption of each module

Туре	Module Type	5VDC Current Consumption (A)
Q02CPU	CPU module	0.500
Q312B	Base unit	0.121
QX10	Input module	0.050
QY10	Output module	0.430
Q64AD	Analog-to-digital conversion module	0.550
Q62DA	Digital-to-analog conversion module	0.375

Sum of 5VDC current consumption values

=0.500+0.121+(0.050×5)+(0.430×5)+0.55+0.375 =3.946(A)

Rated output current of Q61P-A1 [6(A)]

> sum of 5VDC current consumption values [3.946(A)]

Hence, this system has no current consumption problem.

MODEL SELECTION POWER SUPPLY MODULE

Overview

The power supply module is designed to supply 5VDC to each PLC module loaded on the base unit. Note that the power supply module type that may be loaded depends on the base unit. Use the Q61P-A _ power supply modules with the Q3 _ B and Q6 _ B where the Q series modules will be loaded. Use any of the AnS series A1S61PN, A1S62PN and A1S63PN power supply modules with the QA1S3 _ B or QA1S6 _ B where the AnS series modules will be loaded.

Performance Specifications

Performance specifications

ltem		Q61P-A1	Q61P-A2	A1S61PN	A1S62PN	A1S63P				
Applica	ble base unit	Q3 B, Q6 B		QA1S3 B, QA1S6	В					
Input po	ower supply	100-120VAC +10%/-15%	200-240VAC +10%/-15%	100-120VAC +10%/-15%						
Input fre	equency	50/60Hz±3Hz				—				
Input vo factor	bltage distortion	5% or less	5% or less							
Input m power	ax. apparent	105VA				41W				
Inrush o	current	20A within 8ms				81A within 1ms				
Rated output	5VDC	6A		5A	3A	5A				
current	24VDC	—			0.6A	-				
Over- current	5VDC	6.6A or more		5.5A or more	3.3A or more	5.5A or more				
protecti	on 24VDC	_			0.66A or more	-				
	Itage protection	5.5 to 6.5V								
Efficien	су	65% or more								
Permiss instanta failure t	aneous power	Within 20ms		Within 10ms						
Dielectr voltage	ic withstand	Across inputs/LG-outputs 2,830VAC rms/3 cycles (500VAC across primary-5VDC						
Insulation	on resistance	Inputs-outputs (LG/FG set 10M Ω or more by 500V		5M Ω or more by 500VDC insulation resistance tester						
Noise ir	nmunity	By noise simulator of 1,5	00Vp-p noise voltage, 1 μs	s noise width and 25 to 60H	Iz noise frequency	By noise simulator of 500Vp-p noise voltage, 1 μ s noise width and 25 to 60Hz noise frequency				
Operati	on indication	LED indication (Lit at 5VDC output)								
Fuse		Built-in (unchangeable by	y user)							
	Application	ERR contact (Contact tur normally closed contact)		-	-	-				
c	Rated switching voltage/current	24VDC, 0.5A		—	—	-				
Contact output section	Minimum switching load	5VDC 1mA		-	-	-				
outpr	Response time	OFF \rightarrow ON: 10ms or less ON \rightarrow OFF: 12ms or less		-	-	-				
Contact	Life	Mechanical: 20 million tir Electrical: Rated switchin thousand time	ng voltage/current, 100	-	-	-				
	Surge suppressor	No		-	-	-				
	Fuse	No		-	—	-				

MODEL SELECTION POWER SUPPLY MODULE

Power Supply Modules: Q61P-A1, Q61P-A2, A1S61PN, A1S62PN, A1S63P

Item	Q61P-A1	Q61P-A2	A1S61PN	A1S62	PN	A1S63P
Terminal screw size	M3.5 × 7					
Applicable wire size	0.3 to 2mm ²					
Applicable crimping terminal	RAV1.25-3.5, RAV2-3.5					
Applicable tightening torque	59 to 88N•cm					
Weight (kg (lb))	0.3 (0.66)	0.3 (0.66)	0.6 (1.32)	0.6 (1.32)	0.5 (1	1.1)
Appearance an Appearance	MELSEC MELSEC POWER POULL MITSUBISHI			ce and Wirin A1S63P ce	ng/A1S61Pl	
Wiring External wiring	Terminal	Description				
	ERR	Output turned	M/inin a			
Load 24VDC (off when CPU detects error.	Wiring External wiring			
	FG	Ground			Terminal	Description
Ē	LG	terminals			+24V 24G	24VDC 0.6A output terminals. Provided for A1S62PN only. Vacant for
= AC100-120	N 100-120VAC (200-240VAC) L 120-120VAC (200-240VAC) (200-240VAC)	Power supply terminals			FG	A1S61PN and A1S63P. Ground terminals
\ Apply 200-240 for Q61P-A2.					FG LG LG	
				VDC for	100-120VAC (24VAC (+)) 120-120VAC (24VAC (-))	Power supply terminals

Apply 24VDC for A1S63P.

2-127

MODEL SELECTION POWER SUPPLY MODULE

Power Supply Modules: Q61P-A1, Q61P-A2, A1S61PN, A1S62PN, A1S63P

Instructions

- (1) Always earth the LG and FG ground terminals to the protective earth conductor.
- (2) Wire the power supply module properly after checking the rated voltage and terminal layout of the product.
- (3) Tighten the terminal screws to the specified torque.
- (4) The fuse cannot be changed by the user. Consult your sales representative.
- (5) The sum of the 5VDC current consumption values of the modules loaded in the base unit should not exceed the rated output current of the power supply module.
- (6) Use the ERR contact as required. It need not be wired if the external output of ERR is unnecessary.
- (7) The ERR contact is valid for only the power supply module on the main base unit. The ERR contact of the power supply module on the extension base is always OFF.
- (8) Do not apply 200-240VAC to the Q61P-A1 and 100-120VAC to the Q61P-A2.

Overview

The base unit serves to supply the CPU, I/O and intelligent function modules with 5VDC generated by the power supply module. It also serves to exchange control data among the CPU, I/O and intelligent function modules.

Function List

Main base unit

Туре		Q33B	Q35B	Q38B	Q312B		
Number of I/O modules loaded		3	5	8	12		
Applicable I/ modules	0	I/O modules for Q					
Mounting ho size	le	5 ϕ pear-shaped hole (for M4 screw)					
External dimensions	W	189 (7.44)	245 (9.65)	328 (12.92)	439 (17.30)		
(mm (inch))	Н	98 (3.86)					
Weight (kg (lb))		0.23 (0.51)	0.25 (0.55)	0.35 (0.77)	0.45 (0.99)		
Accessories		4- M4 × 14 b	ase unit moun	ting screws			

Extension base unit

Туре		Q63B	(Q65B	Q68E	3	Q612B
Number of I/O modules loaded		3	5		8		12
Applicable I/O modules		I/O modules for Q					
Mounting ho size	le	5 ϕ pear-s	5 ϕ pear-shaped hole (for M4 screw)				
External dimensions (mm (inch))	W H	189 (7.44) 98 (3.86)	245 (9.6	-	328 (12.92)		439 (17.30)
Weight (kg (lb))		0.23 0.2	25 55)	0.35 (0.77)		0.4 (0.9	-5 99)
Accessories		4- M4 x 14 base unit mounting screws					
Туре		QA1S65B		QA1S68B			
Number of I/O modules loaded		5		8			
Applicable I/O modules		I/O modules for AnS					
Mounting hole size		6 ϕ pear-shaped hole (for M5 screw)					
External dimensions (mm (inch))		315 (12.41) (W) × 130 (5.12) (H)		420 (16.55) (W) × 130 (5.12) (H)			
Weight (kg (lb))		0.75 (1.65) 1.0 (2.2)					
Accessories		4- M5 x 25 base unit mounting screws					

Handling instructions

- (1) The right-hand side mounting screws of the base unit cannot be removed when an I/O module is loaded in its rightmost slot. Remove the mounting screws after unloading the I/O module.
- (2) When mounting the base unit into a control panel, etc., leave a 30mm (1.18inch) or more clearance between its top and the structure or parts to ensure ease of module replacement and reduce the influence of radiated noise or heat. (When the wiring duct is not more than 50mm (1.97inch) in height. 40mm (1.58inch) or more clearance for other cases.) Also leave 5mm (0.20inch) or more clearances in the left-to-right direction. (20mm (0.79inch) or more clearance on the left-hand side when an extension cable is plugged without removal of an adjacent unit.
- (3) Mount the base unit on a flat surface to prevent possible flexing of the printed circuit boards.

Accessories

The Q3 B main base unit is provided with "Q02/Q02H/Q06H/Q12H/Q25HCPU User's Manual (Hardware)".

DIN Rail Mounting Adaptors

When mounting the Q3 B or Q6 B onto a DIN rail, the optional DIN rail mounting adaptor is needed.

Туре	Applicable Base		
Q6DIN1	Q38B, Q312B, Q68B, Q612B		
Q6DIN2	Q35B, Q65B		
Q6DIN3	Q33B, Q63B		

Note that the QA1S6 B can be mounted onto a DIN rail as it is.

Accessories: Batteries, Cables, Connectors

Batteries

MODEL SELECTION ACCESSORIES

Overview

The Q6BAT battery is loaded into a CPU module and used to back up the built-in RAM memory of the CPU module at a power failure.

The Q2MEM-BAT battery is used to back up the Q2MEM-1MBS memory card at a power failure.

Appearance



Specifications

Туре	Q6BAT	Q2MEM-BAT
Nominal voltage	3VDC	3VDC
Battery type	Manganese dioxide lithium battery	Graphite fluoride lithium battery
Current capacity	1800mAh	48mAh
Storage life	10 years (Note 1)	4 years (Note 1)
Applicable model	Q02/Q02H/Q06H/ Q12H/Q25HCPU	Q2MEM-1MBS

Note 1: The storage life indicates the life during which the battery can be used independently of how much battery current is consumed.

Extension Base Cables

Overview

An extension cable is used for connection between the main and extension base units, or between the extension base units.

Appearance



Model list

Туре	QC06B	QC12B	QC30B	QC50B	QC100B
Cable length (m (ft.))	0.6 (1.97)	1.2 (3.93)	3 (9.84)	5 (16.39)	10 (32.79)
Usable base unit	Main base unit (Q35B, Q38B, Q312B) Extension base unit (Q65B, Q68B, Q612B, QA1S65B, QA1S68B)				
Weight (kg (lb))	0.16 (0.35)	0.22 (0.48)	0.40 (0.88)	0.60 (1.32)	1.11 (2.44)

Directions for use

When the above extension cables are used together, the overall distance of the extension cables should be within 13.2m (43.28ft.).

External Wiring Connectors for I/O Modules

Overview

Loaded onto a connector type I/O module and used for wiring an external device. These connectors are classified into six different types according to the used connector and I/O module types.

Appearance A6CON1, A6CON2, A6CON3



A6CON1E, A6CON2E, A6CON3E



Model list

Туре	A6CON1	A6CON2	A6CON3	
Connector type	Soldering type	Crimp-contact type	Pressure- displacement type	
Applicable module	Positive common (sink) type input module, sink type output module			
Applicable wire size	0.3mm ²	AWG#24 to 28	AWG#28, AWG#30	



Crimp-contact tool for A6CON2

FCN-363T-T005/H

• Pressure-displacement tool for A6CON3

FCN-367T-T012/H (locator plate) FCN-707T-T001/H (cable cutter) FCN-707T-T101/H (hand press)

Contact for crimp-contact and pressure-displacement tools

Туре	A6CON1E	A6CON2E	A6CON3E
Connector type	Soldering type	Crimp-contact type	Pressure- displacement type
Applicable module	Negative common (source) type input module, source type output module		
Applicable wire size	0.3mm ²	AWG#20 to 24	AWG#28, AWG#30

- Crimp-contact tool for A6CON2E
- Pressure-displacement tool for A6CON3E

91257-1 (die set)

91220-1 (cable cutter)

91085-2 (hand mini-press)

Contact for crimp-contact and pressure-displacement tools

Connector/Terminal Block Convertor Modules, Cables

Overview

The connector/terminal block converter module is designed to convert the connector of a connector type I/O module into a terminal block to ensure ease of external wiring.

To use this module, plug a dedicated cable to the connector of an I/O module and plug the opposite side of that cable to the connector/terminal block convertor module. Perform external wiring at the terminal block of the connector/terminal block convertor module.

Appearance



Model list

(1) Connector/terminal block convertor modules

Туре	Description	Weight (kg (lb))
A6TBXY36	For positive common (sink) type	0.4
	input modules and sink type output modules (standard type)	(0.88)
A6TBXY54	For positive common (sink) type	0.5
	input modules and sink type output modules (2-wire type)	(1.1)
A6TBX70	For positive common (sink) type	0.6
	input modules (3-wire type)	(1.32)
A6TBX36-E	For negative common (source)	0.4
	type input modules (standard type)	(0.88)
A6TBY36-E	For source type output modules	0.4
	(standard type)	(0.88)
A6TBX54-E	For negative common (source)	0.5
	type input modules (2-wire type)	(1.1)
A6TBY54-E	For source type output modules (2-	0.5
	wire type)	(1.1)
A6TBX70-E	For negative common (source)	0.6
	type input modules (3-wire type)	(1.32)

MODEL SELECTION ACCESSORIES

Accessories: Batteries, Cables, Connectors

(2) Cables

Туре	Description	Weight (kg (LB))	Applicable Model
AC05TB	0.5m (1.64ft.) for sink modules	0.17 (0.37)	A6TBXY36 A6TBXY54
AC10TB	1m (3.28ft.) for sink modules	0.23 (0.51)	A6TBX70
AC20TB	2m (6.56ft.) for sink modules	0.37 (0.81)	
AC30TB	3m (9.84ft.) for sink modules	0.51 (1.12)	
AC50TB	5m (16.39ft.) for sink modules	0.76 (1.67)	
AC80TB	8m (26.23ft.) for sink modules (common current not exceeding 0.5 A)	1.2 (2.64)	
AC100TB	10m (32.79ft.) for sink modules (common current not exceeding 0.5 A)	1.5 (3.3)	
AC05TB-E	0.5m (1.64ft.) for source modules	0.17 (0.37)	A6TBX36-E A6TBY36-E
AC10TB-E	1m (3.28ft.) for source modules	0.23 (0.51)	A6TBX54-E A6TBY54-E
AC20TB-E	2m (6.56ft.) for source modules	0.37 (0.81)	A6TBX70-E
AC30TB-E	3m (9.84ft.) for source modules	0.51 (1.12)	
AC50TB-E	5m (16.39ft.) for source modules	0.76 (1.67)	

Connector/terminal block convertor module connection diagrams

(1) A6TBXY36



(2) A6TBXY54

<When connecting an input module>



<When connecting an output module>


Accessories: Batteries, Cables, Connectors

MODEL



MODEL SELECTION ACCESSORIES

Accessories: Batteries, Cables, Connectors

Terminal Block Convertor Modules

The terminal block convertor module available is designed to facilitate wiring by drawing the wiring to the terminal block out of the Q series 16-point I/O module (terminal block type).

Features

- (1) Usable with both AC and DC 16-point I/O modules.
- (2) Single-wire and two-wire type (with common terminal per point) terminal blocks are available.
- (3) The lead-out cable is printed with wire numbers for ease of wiring.
- (4) The terminal block uses self-tapping screws for ease of wiring round crimping terminals.
- (5) Can be mounted using a DIN rail or screws.
- Appearance



FA-TB161ACC1/2,-TB162ACC



	QY80
FA-TB161ACC1	Terminal block convertor module, 2-wire type Applicable I/O modules: QX80, QY40P, QY50
FA-CBL05TD	Dedicated cable 0.5m (1.64ft.)
FA-CBL07TD	Dedicated cable 0.7m (2.30ft.)
FA-CBL10TD	Dedicated cable 1m (3.28ft.)
FA-CBL15TD	Dedicated cable 1.5m (4.92ft.)
FA-CBL20TD	Dedicated cable 2m (6.56ft.)
FA-CBL25TD	Dedicated cable 2.5m (8.20ft.)
FA-CBL30TD	Dedicated cable 3m (9.84ft.)





MODEL SELECTION ACCESSORIES

Accessories: Batteries, Cables, Connectors

External Wiring Cables for Positioning Modules (QD75)

Control signal cable for connection between the positioning module (QD75) and servo amplifier or stepping motor driver. (With external device connection cable)

These cables can save time and trouble for cable fabrication, noise reduction shielding, etc. on the user side for easy use of the QD75.

Туре	Description
FA-CBLQ75M2H	For Mitsubishi Electric MR-HA series
FA-CBLQ75M2J2	For Mitsubishi Electric MR-J2A/J2SA series
FA-CBLQ75M2C	For Mitsubishi Electric MR-C series
FA-CBLQ75Y2 Σ II	Yaskawa Electric Σ -II series
FA-CBLQ75P2A	For Matsushita Electric Industrial MINAS A series
FA-CBLQ75S2PY	Sanyo Electric PY0 series
FA-CBLQ75G2	Loose-wire type mating side for QD75P For connection of Oriental's stepping motor, etc.

A single cable of 2m (6.56ft.) length is compatible with up to two axes.

Cables other than the FA-CBLQ75G2P are for use with the QD75D (differential output).



External Dimensions





External Dimensions



Sequence Programs

Programming Software/SW5D5C-GPPW-E

Q mode sequence programs use SW5D5C-GPPW-E GPP function software package for Windows (hereafter referred to as "GPPW"). GPPW permits sequence programming in ladder, list and SFC (sequential function chart) languages, entry of comments to the I/O/CPU module internal relays, registers and others, network parameter setting, sequence program operating status monitoring, network operating status monitoring, forced data changes, I/O signal ON/OFF, and others.

Note 1: The product of the above type is allowed to be installed into a personal computer only once. As there are also versions which allow 5 or 10 installations on different personal computers, confirm their types in the model list given at the end of this manual.

The ladder logic test tool used to simulate designed sequence programs, the utility packages for setting data of various intelligent function modules such as analog-todigital converter and digital-to-analog converter modules, and other software programs can be added in (additionally installed in) GPPW for use. GPPW is an easy-tounderstand, easy-to-operate software environment since various software programs can be used in the same operating environment with similar operability.

Function List

The chief functions of GPPW are listed below.

Compatible series	FX, A, QnA, Q (Q mode/A mode) series
Connection method	USB, RS232C, Ethernet, MELSECNET/10, CC-Link, serial communication module (including via modem)
Programming language	Ladder, list, SFC
File format conversion	Read/write of GPPA, GPPQ, FXGP (DOS/WIN) format files
Program editing	Editing of ladder, list, SFC
Program conversion	A/FX conversion, A/QnA conversion, A/Q conversion, Q/QnA conversion
Comment editing	Device comment, note, statement editing
Network setting	Ethernet, MELSECNET/10, CC-Link parameter settings
Monitoring	Ladder/SFC monitoring, program monitoring, network monitoring, CPU module internal device data monitoring
Test	Timer/counter set value changing, CPU module internal device data changing
Help	CPU module error, special relay/ register, key operation

Operating Environment

GPPW operates on Windows 95, Windows 98 and Windows NT. Its operating environment is as follows.

OS	Windows95, Windows98, WindowsNT4.0	
CPU		Pentium 133MHz or more recommended
Memory		32MB or more recommended
Hard disk free	At installation	50MB or more
space	At execution	50MB or more
Display		800 × 600 pixels or more

Programming Languages

The Q mode can be programmed in the ladder, list and SFC (MELSAP3) languages.

Ladder mode

The ladder mode is a programming method based on the concept of a relay control circuit and allows programming in representations close to the sequence circuit of relay control.

Programming is done by placing contacts, coils and other symbols and used device numbers on the screen. The ladder programmed on the screen is converted into a sequence program executable in the Q mode by conversion operation.







List mode

The list mode is a programming method in which Q mode instructions are described in execution order in a list format.

Contacts, coils and other symbols are replaced by Q mode instructions for programming.

The sequence program created in the list mode can be displayed in the ladder mode for confirmation.



-	2 LD X2•••3)
	3 AND X3•••4)
Execution of step	4 ORB •••••5)
0 to END instruction	5 OR X4•••6)
in order	6 AND X5•••7)
in order	7 AND X6•••8)
	8 AND X7•••9)
	9 OUT Y10 •• 10)
*	10 END •••••11)
	1 I
Step	number

SFC Programming

In addition to programming in the ladder and list languages, the Q mode PLC allows programming in the SFC (Sequential Function Chart) language. SFC is a language suitable to structure and standardize programs, and enhances ease of understanding since the operation sequence of the object to be controlled is represented asis in program form. The features of the SFC as compared to those of the ladder are described below.

Features of SFC

• Complicated interlocks in the ladder

Processing in ladder programs uses the scanning system which repeats all steps from the first to the last in a program corresponding to all operation processes of equipment to be controlled. Namely, whichever process the equipment is operating in, this system manipulates the steps of the pre- and post-processes concurrently. Hence, a program is designed to include many interlock signals to prevent the pre- and post-process steps from being manipulated. To define interlocks, you must fully understand what devices are used in the pre- and postprocesses. If you do not understand or examine them sufficiently, meaningless or duplex interlock signals may be defined, causing a program to be more difficult to understand.

As opposed to this, SFC processes only the program step corresponding to the present operation process of the equipment and does not execute the steps of the pre- and post-processes. Therefore, only interlock signals in the currently executed process are needed, simplifying program description. Operation sequence cannot be represented by ladder

A ladder is basically represented by combinations of contacts and coils and its program does not have representations corresponding to the operation sequence of the equipment. For example, if the equipment has stopped due to some fault, the whole program must be examined to find where the step corresponding to the process at a stop is described.

In contrast, an SFC chart is represented in a flowchart format and basically matches the operation processes of the equipment. Hence, if an aforementioned fault has occurred, once the process which stopped is found you will know where in the program the corresponding step is described.

High freedom of design in the ladder

A ladder is designed in accordance with the rule that a closed contact turns on a coil. In other words, it is extremely high in program design freedom and a single operation process of equipment may be programmed in multiple ways. This enables different programs to be written by different engineers, making it difficult to standardize programs. It also hinders other persons than the designer from understanding that program. Compared to this, SFC creates an SFC chart which matches the operation processes of equipment. Hence, the freedom of program design is limited, but it is limited to match the operation processes, and therefore, persons other than the designer can understand the program easily, producing program standardizing effect.

• Unsequential control is enabled in the ladder

Since an operation sequence is not described in a ladder, it may also be applied to programs designed to perform operations using external interrupt signals and to perform monitoring continuously, for example.

Oppositely, a sequence is described in an SFC chart and SFC is not appropriate for such controls that require processing independently of the sequence.

The Q mode PLC allows use of both the SFC and ladder programs, either of which can therefore be used as necessary.

Sequence Programs

Basics of SFC

An SFC chart consists of a "step" which describes the processing of each operation process in a series of machine operation processes and a "transition condition" which describes the transition condition from one process to another. Also, a fine operation in each step and each transition condition are described in ladders. The operation of an SFC program starts at an initial step, the next step is executed every time a transition condition holds, a series of operations ends at an end step, and the program is restarted at the initial step (Note 1).

Note 1: Only the SFC program in block 0 is restarted at the initial step, and the SFC programs in and after block 1 terminate processing at the end step and wait to be restarted from another block.



Sequence Programs

Performance Specifications of SFC

Item	Specifications	
Number of files	1 file (Note 1)	
Number of blocks	Max. 320 blocks (0 to 319)	
Number of QEO store	Max. 8192 steps in all blocks	
Number of SFC steps	Max. 512 steps in one block	
Number of branches	Max. 32	
Number of simultaneously	Max. 1280 steps in all blocks	
activated steps	Max. 256 steps in one block	
Number of operation output	Max. 2K steps in one block	
sequence steps	No restrictions per step	
Number of transition condition	Max. 2K steps in one block	
	No restrictions per transition	
sequence steps	condition	

Note 1: The other "program execution controlling SFC program" may be created. The "program execution controlling SFC program" indicates an SFC program designed to control the start/stop of a program file necessary to match the operation process of equipment.

Operations in SFC Chart

Name	Symbol	Function		
Main functions				
Step		A step is an equipment process unit, and is processed until the transition condition described next to that step holds. Note that when a transition to the next step is made, the current step is deactivated and the coil described in the OUT instruction automatically turns off.		
Initial step		A step at the beginning of each block is called an initial step. Its operation is the same as that of a step.		
Dummy step	\boxtimes	As the name indicates, this step is a dummy and does not include a ladder program.		
Block start step (With end check)		Starts another block and waits for the started block to reach its end step.		
Block start step (Without end check)		Starts another block. Transits to the next step when the transition condition holds, independently of whether the started block has reached its end step or not.		

Name	Symbol		Function		
Optional functions					
Coil holding	SC	Providing the SC option transits execution to the next step with a coil described in the OUT instruction being kept ON.			
Operation holding (Without transition check)	SE	Providing the SE option holds the current step active to continue program processing if the transition condition holds and the next step is activated. Note that if the transition condition holds again, the next step is not activated again.			
Operation holding (With transition check)	ST	Providing the ST option holds the current step active to continue program processing if the transition condition holds and the next step is activated. Note that if the transition condition holds again, the next step is activated again.			
Reset	R	Providing the R step allows the coil held by the SC option to be reset or the step kept activated by the SE or ST option to be deactivated, in addition to the operation in an ordinary step.			
Name	SFC Sy	/mhol	Function		
Series transition	+	a	Transits execution to the next step when the transition condition holds.		
Selective branch	[] + a +	b + n	Executes only the step whose condition occurs first among multiple transition conditions arranged in parallel.		
Parallel branch			Simultaneously executes all of multiple steps arranged in parallel.		
Jump	 + a → j	j −	Causes a jump to the step specified within the same block.		

 \pm

Block end

Terminates a series of processings in that block.

Sequence Programs

Memory Capacity

How to calculate the memory capacity of an SFC program is indicated below.

2 + 8 × (largest block number +
1) + capacity of block 0 +
capacity of block 1 + +
capacity of block n
2 + number of SFC chart steps
(refer to the following table) +
number of ladder program steps
within one SFC step + number
of ladder program steps within
one transition condition

Number of SFC chart steps

Symbol	Number of Steps
Symbol	Number of Steps
Step (initial, dummy), block	3
start	
Series transition, selective	4 × number of transition
branch, selective coupling	conditions
Parallel branch	2 + 2 × number of branches
Parallel coupling	2 + 2 × (number of coupling
	branches - 1) + 2 \times number of
	re-branches after coupling
Block end, jump	0

Sequence Programs

Multiple Programs

In a PLC, control is generally exercised with a single program. Hence, facility initialization processing, automatic operation, manual operation, data collection, communication-related processing and others are described in one program, resulting in a large program for a complex system thus making it difficult to create, debug and maintain the program. This will also make it difficult for maintenance staff members other than the engineer who created it to understand the operations of that program.

The Q mode allows a program to be divided into multiple programs and processed function-by-function or processby-process. It has such advantages that program division by purposes makes individual programs smaller and clear purposes make programs easy to understand. In addition, purpose-based program division will increase program utilization efficiency, standardizing the programs.





Creation of programs function-by-function



For programs to be controlled by the Q mode, specify "which program will be run" and "how it will be run" in the parameters.

Specifying "which program will be run"

In the Q mode, every program is managed under a program name.

Use a program name to specify "which program will be run".

Set a program name with 8 characters.

Since the program name and registration time are written when registering the program in the CPU module, you will know the program contents and correction time, improving maintainability.

Specifying "how program will be run"

The program execution types of the Q mode available are the initial execution type, scan execution type, low-speed execution type, cyclic execution type, and standby type. To determine "how program will be run", specify any of the above execution types in the parameters.

Sequence Programs

Program Execution Types

The following five different execution types can be specified for the Q mode.

- (1) Initial execution type
- (2) Scan execution type
- (3) Low-speed execution type
- (4) Cyclic execution type
- (5) Standby type

When running multiple programs on the CPU module, any of these execution types must be set for each program. It should be noted that at least one scan execution type program must be set. When there is only one program, it need not be set. (A program written to the CPU module is run as the "scan execution type".)



Sequence programs

Initial execution type

An initial execution type program is run only once when the PLC is powered on or switched from STOP to RUN. A program that may be run only once to fulfill its purpose, e.g. the initial processing for an intelligent function module, can be set as an initial execution type. Removal of a program to be run only once from scan execution programs reduces the processing time of the scan execution programs. When multiple programs have been set as "initial execution type", they are run in order of lower to higher program numbers, and END processing is performed when all initial execution type programs are run. In initial execution type programs, you cannot use instructions which specify completion devices (instructions which need several scans until completion of program run, e.g. network-dedicated instructions).



Scan execution type

This program is run every scan after the scan where the initial execution type program has been run, and exercises actual control.

In the absence of the initial execution type program, the scan execution type program is run when the PLC is powered on or switched from STOP to RUN.

When multiple programs have been set to the "scan execution type", they are run in order of lower to higher program numbers.

END processing is performed when all scan execution type programs are run.



Sequence Programs

Low-speed execution type

A low-speed execution type program is run only during "constant scan surplus time" or preset "low-speed program execution time".

If it cannot be completed in the "constant scan surplus time" or "low-speed program execution time", the program is suspended once and the remainder of that program is run at the next scan. This type can be used as a processing program which need not be run every scan, e.g. output to printer and data transmission to host personal computer or the like.

When multiple programs have been set to the "low-speed execution type", they are run in order of lower to higher program numbers, and low-speed END processing is performed when all low-speed execution type programs are run.

Note 1: The constant scan function is designed to keep the program operation processing time (i.e. scan time) constant so that the signal input - program operation processing - signal output delay time is constant to increase the control accuracy of a device. When the constant scan function is used, the scan time which normally varies per scan is fixed to a given period. If the scan time is shorter than that fixed period, surplus time is produced and can be used to process a low-speed execution program.

Wait type

A wait type program is run only when an execution request is given.

A subroutine program may be described in each scan program, but may be independent of the scan program and be used as a wait program. When used as a wait program, that subroutine can be called not only from that scan program but also from other scan programs. Interrupt may take place during execution of any scan program. An interrupt program will be easier to understand when it is managed as a wait program.



Cyclic execution type

A cyclic execution type program is run every user-set time (execution cycle).

The execution cycle can be set to each cyclic execution type program within the range 0.5ms to 60s.

When multiple cyclic execution type programs have reached their execution cycles at the same time, they are run in order of lower to higher program numbers until all of them are run.

Program Run Control Instructions

Program run control instructions are used to change the program execution type when the CPU module is during RUN (during program execution).

These instructions cannot change the execution types of the programs stored in the built-in flash ROM and memory card which are not read to the program memory.

There are four different program run control instructions.

- (1) PSCAN instruction
- (2) PLOW instruction
- (3) POFF instruction
- (4) PSTOP instruction

PSCAN instruction

Changes an initial execution type program, low-speed execution type program or wait type program into a scan execution type program at END processing.

PLOW instruction

Changes an initial execution type program, scan execution type program or wait type program into a lowspeed execution type program at END processing.

Sequence Programs

PSTOP instruction

Changes an initial execution type program, scan execution type program or low-speed execution type program into a wait type program at END processing. When any program is changed into the wait type program, the external output (Y) is held. Use the POFF instruction to ensure that the external output (Y) is switched off at a change to wait type program.

POFF instruction

Turns off the output of an initial execution type program, scan execution type program or low-speed execution type program at END processing and changes that program into a wait type program at the END processing of the next scan.

This instruction is used to ensure that the external output (Y) is switched off at a change to wait type program.



Main Routine Program

A main routine program is any of the initial execution, scan, wait, cyclic and other programs which start at its beginning (step 0) and ends at END/FEND.

(FEND is used when creating a subroutine program or interrupt program after a main program.)

When the run condition of a program holds, operation is performed from step 0 to END/FEND.

If multiple programs have been set to the same execution type, END processing is performed when the END/FEND instruction of the last run program is executed.



Subroutine Program

A subroutine program is run when it is called by CALL P , and starts at a pointer (P) and ends at the RET instruction.

The number of steps can be reduced if a program executed several times during one scan or a program executed only when a condition holds is written as a subroutine program. Create a subroutine program after any of the main routine programs such as initial execution, scan, wait and cyclic programs (after FEND) or create them together as wait programs.

Pointers used in subroutine programs are local and common pointers. For use in a wait program, the common pointers must be assigned. When creating a subroutine in any of the initial execution, scan, wait, cyclic and other programs, assign the common or local pointers. The subroutine program having local pointers described in any of the initial execution, scan, wait, cyclic and other programs cannot be called from the other initial execution, scan, wait and cyclic programs. Q

mode

Sequence Programs



An interrupt program is run after a temporary suspension of a main or sub routine program when an interrupt condition holds, and starts at an interrupt pointer (I \square) and ends at the IRET instruction.

This program can respond quickly without influencing of the scan time of a sequence program.

Create an interrupt program after any of the main routine programs such as initial execution, scan, wait and cyclic programs (after FEND) or create them together as wait programs.

For interrupt pointers used in interrupt programs, the same interrupt pointer cannot be specified in any of the initial execution, scan, wait, cyclic and other programs. An interrupt program can be run by

- (1) Interrupt request from interrupt module (A1SI61)
- (2) Interrupt request from intelligent function or network module
- (3) Interrupt request by internal timer
- (4) Interrupt request due to error occurrence
- Interrupt from A1SI61 interrupt module

An interrupt program is run under an external interrupt condition.

Only one A1SI61 module may be used with one CPU module and one module can run 16 different interrupt programs (I0 to I15).

Interrupt from intelligent function or network module

The Q series intelligent function and network modules have predetermined interrupt channels (SI) and applications, and parameters are used to assign interrupt programs to interrupt pointers (I50 to I255). For example, SI0 is assigned to CH1 count value coincidence interrupt and SI1 to CH2 count value coincidence interrupt on the QD61, and setting I50 and I51 to the QD61 assigns I50 to SI0 and I51 to SI1, allowing the I50 or I51 interrupt program to be run on count value match.

Interrupt request by internal timer

An interrupt program can be run at intervals of 10ms, 20ms, 40ms or 100ms (these are default values and can be changed in increments of 0.5ms between 0.5ms and 100ms).

• Interrupt request due to error occurrence An interrupt program can be run when an error is detected by the self-diagnosis of the CPU module.

Macro Instructions

The macro instruction function is designed to register a ladder pattern often used by the user as a single instruction to utilize it any number of times (macro utilization), i.e. the user can create an original instruction. Using a macro instruction allows a ladder pattern made up of multiple instructions to be represented as a single-line instruction, producing effects on program viewability improvement and program standardization.

In macro registration, registering the devices to be changed for utilization (variables) as VD0 to VD9 ensures ease of device changes.

By setting actual devices to variables VD0 to VD9 for macro utilization, the preset devices are used for conversion into a sequence program.

Note 1: In the QnA PLC, reading a program created using a macro instruction will cause that macro instruction to be disassembled into and displayed as individual instructions, reducing the viewability of the program. In the Q mode PLC, this disadvantage has been corrected so that reading a program from the PLC will display a macro instruction in its original form.

Sequence Programs

Device Type List

Device type list

The following table lists the device names usable with the Q mode and their numbers of points (default values). Note that the devices can be changed according to the number of points and user application.

0	Туре		Default Value		Parameter Setting
Class		Device Name	Number of points	Range of use	Range
		Input	8192 points	X0 to X1FFF	
		Output	8192 points	Y0 to Y1FFF	
		Step relay	8192 points	S0 to S511/block	
		Link special relay	2048 points	SB0 to SB2047	
	Bit device	Internal relay	8192 points	M0 to M8191	
		Latch relay	8192 points	L0 to L8191	
		Annunciator	2048 points	F0 to F2047	
Internal user device		Edge relay	2048 points	V0 to V2047	
		Link relay	8192 points	B0 to B8191	Changeable within
		Timer	2048 points	T0 to T2047	28.8k words
		Retentive timer	0 points	(ST0 to ST2047)	
		Counter	1024 points	C0 to C1023	
	Word device	Data register	12288 points	D0 to D12287	
		Link register	8192 points	W0 to W8191	
		Link special register	2048 points	SW0 to SW2147	
	Bit device	Function input	5 points	FX0 to FX4	
		Function output	5 points	FY0 to FY4	Fixed
		Special relay	2048 points	SM0 to SM2047	
Internal system device	Word device	Function register	5 points	FD0 to FD4	
		Special register	2048 points	SD0 to SD2047	
	Other	Macro instruction argument	10 points	VD0 to VD9	
Index register	Word device	Index register	16 points	Z0 to Z15	
File register	Word device	File register	0 points	—	0 to 1018K points (1k point increments)
Nesting	—	Nesting	15 points	N0 to N14	
Delinter		Pointer	4096 points	P0 to P4095	
Pointer	_	Interrupt pointer	256 points	10 to 1255	
	Ditulacian	SFC block	320 points	BL0 to BL319	Fixed
Othere	Bit device	SFC transition device	512 points	TR0 to TR511	
Others		Network No. setting	—	J1 to J255	
	—	I/O No. setting	_	U0 to UFF	
		Decimal constant	K-2147483648 to K2147483647		
		Hexadecimal constant	H0 to HFFFFFFF		
Constant	—	Real number constant	E ± 1.17549-38 to E ± 3	.40282+38	
		Character string constant	"ABC", "123"		

Note 1: The contacts and coils of the timers, retentive timers and counters are bit devices and their current values are word devices. Note 2: The inputs, outputs, step relays, link special relays and link special registers cannot be changed from their default values.

Sequence Programs

Device explanations

Inputs (X)

Inputs are designed to give commands and data from external devices, such as pushbuttons, select switches, limit switches and digital switches, to the PLC.

Inputs are available as "refresh inputs" and "direct access inputs".

(1) Refresh inputs

Input signals batch-imported from all input modules at the refresh of END processing.

These inputs are specified as $X \square$ in a sequence program.

(2) Direct access inputs

Input signal imported from an input module every time a contact instruction is executed.

These inputs are specified as $\underline{D}X \square$ in a sequence program.

(They cannot be used with digit-specified instructions or as inputs used for MELSECNET/10.)

Outputs (Y)

Outputs are used to provide the control results of a program to external solenoids, signal lamps, digital displays, etc.

Outputs are available as "refresh outputs" and "direct access outputs".

(1) Refresh outputs

Output signals batch-exported from all output modules at the refresh of END processing.

These outputs are specified as Y in a sequence program.

(2) Direct access outputs

Output signal exported from an output module every time a coil instruction is executed.

These outputs are specified as $\underline{D}Y$ in a sequence program.

(They cannot be used with digit-specified instructions or as outputs used for MELSECNET/10.)

Internal relays (M)

Internal relays are auxiliary relays used in a CPU module and not latched (not backed up at power failure).

(They turn off at power-on, QnCPU reset or latch clear operation.)

Outputs (Y) are used to export the control results of a program.

• Latch relays (L)

Latch relays are auxiliary relays used in a CPU module and latched (backed up at power failure).

(Operation results are held at power-on or CPU reset.) They turn off when latch clear operation is performed. Outputs (Y) are used to export the control results of a program.

Annunciators (F)

Annunciators are internal relays convenient for equipment fault/failure detection.

When annunciators are turned on, the special relay (SM62) turns on and the quantity of annunciators turned on and their numbers are stored in the special registers (SD62 to SD79). Therefore, using annunciators in a failure detection program allows you to check for equipment faults/failures and their definitions by monitoring the special registers (SD62 to SD79) after the special relay (SM62) has turned on.

Note that turning any annunciator on lights up the USER LED.



Edge relays (V)

Edge relays are devices which record operation results, starting at the beginning of a ladder block, and can be used as contacts only.

An edge relay is used to perform operation on its leading edge (OFF \rightarrow ON) in an index-qualified structured program.



Sequence Programs

Link relays (B)

Link relays are CPU module side devices (relays) used to refresh link relays (LB) in an MELSECNET/10 network module to the CPU module or to refresh the CPU module data to the link relays (LB) in the network module. Use the refresh parameters in the network parameters to set the refresh ranges of LB and B.



Link special relays (SB)

Link special relays are internal relays which indicate the communication states/fault detections of MELSECNET/10 network modules.

Step relays (S)

Step relays are devices for SFC.

Timers (T)

Timers are up-timing type, they start timing when its coil turns on, and times out with its contact turned on when its current value reaches or exceeds its set value.

There are low-speed, high-speed, low-speed retentive and high-speed timers, which are different in specifying method.

A retentive timer is designed to hold its current value if its coil turns off, and resumes timing from the held current value when the coil turns on again.

A timer turns on/off its coil, updates its current value, and turns on/off its contact when the OUT T _ or OUTH T _ instruction is executed.

(Current value updating and contact on/off are not executed in END processing.)

Instructions for use of timers

- (1) Do not describe the same timer in multiple OUT T or OUTH T instructions during one scan.
- (2) Do not use a CJ instruction or the like to jump the coil processing of a timer while the coil of the timer is on.
- (3) Do not use timers in an initial execution, wait, cyclic and interrupt programs.

Specifying methods and timing ranges of timers

	Specifying	Timing	Timing	
	Method	Default	Setting range	Range
Low-speed timer		100ms	1ms to 1000ms (1ms increments)	Setting increments on the left × 32767
High-speed timer		10ms	0.1ms to 100ms (0.1ms increments)	
Low-speed retentive timer	OUT ST	100ms	1ms to 1000ms (1ms increments)	
High-speed retentive timer	OUTH ST	10ms	0.1ms to 100ms (0.1ms increments)	

• Counters (C)

Counters are up-counting type, they count out and the contact turns on when its current value reaches its set value.

A counter turns on/off its coil, updates its current value, and turns on its contact when the OUT C instruction is executed.

An interrupt counter is designed to count the number of interrupts that occurred, and updates its current value when an interrupt factor is generated.

Set in the parameters the first counter number used with interrupt counters. (256 points are occupied, starting with the first counter number.)

An interrupt counter does not count out. Therefore, when using it for control, read the current value of the interrupt counter using the MOV or similar instruction, compare it with the set value using comparison instructions (=, <=, etc.), and turn on/off the internal relay (M), etc.

Use RST C \square to reset the count value of an interrupt counter.

Data registers (D)

Data registers are devices designed to handle numerical data in a CPU module.

One data register can store 16-bit data (-32768 to 32767 or 0H to FFFFH) and two consecutive points (e.g. D0 and D1) can store 32-bit data (-2147483648 to 2147483647 or 0H to FFFFFFFH).

Sequence Programs

Link registers (W)

CPU module side devices for refreshing the data of link registers (LW) in an MELSECNET/10H network module. One link register can store 16-bit data (-32768 to 32767 or 0H to FFFFH) and two consecutive points (e.g. W0 and W1) can store 32-bit data (-2147483648 to 2147483647 or 0H to FFFFFFFH).



Link special registers (SW)

Link special registers are designed to store the communication states and fault definitions of an MELSECNET/10H network module.

Function devices (FX, FY, FD)

Function devices are used in a subroutine program provided with arguments.

As devices used in each subroutine program call source can be determined by use of the function devices, you can use the same subroutine program without needing to know the other subroutine program call sources.

(1) Function inputs (FX)

Used to pass ON/OFF data to a subroutine program.

(2) Function output (FY)

Used to pass the operation result (ON/OFF data) of a subroutine program to a subroutine program call source.

(3) Function register (FD)

Used to transfer data between a subroutine call source and subroutine program.



Special relays (SM)

Special relays store the states (failure diagnoses, system information, etc.) of a CPU module.

Special registers (SD)

Special registers store the states (failure diagnoses, system information, etc.) of a CPU module.

• Link direct devices $(J \square \setminus \square)$

Link direct devices are a way to specify direct access to link devices in a network module of an MELSECNET/10H network system.

Link direct devices can access only one network module with a single network number. When multiple network modules are loaded with the same network number, the network module with the lowest first I/O number is the target of access.

● Intelligent function module devices (U _ \G _) Intelligent function module devices are a way to specify direct access from a CPU module to the buffer memory of an intelligent function module loaded in a main or extension base unit. Intelligent function modules loaded in remote stations of an MELSECNET/10H network system can not be the target of access.

Index registers (Z)

An index register is used for index qualification (indirect designation) of a device used in a sequence program. Index qualification uses one index register and is specified by 16-bit data (-32768 to 32767 or 0H to FFFFH).



• File registers (R)

File registers are devices for constant data storage application or data register expansion application and are stored in the CPU module built-in standard RAM (drive 3), memory card (RAM) (drive 1) or memory card (ROM) (drive 2). Note that the file registers stored in the memory card (ROM) are read-only. When the ATA card is used as a memory card (ROM), file registers cannot be stored in the memory card (ROM). Unlike those of the data registers (D), the stored values of the file registers are not cleared at power-on/key reset.

File registers can be "designated by block changing" or "designated consecutively".

(1) Designation by block changing

The file registers used are specified by separating them in increments of 32k points (R0 to R32767). When more than 32k points are used, use the RSET instruction to select the block used. (Specify file registers with R0 to R32767 in any block.)



(2) Consecutitve designation

The device symbol ZR is used to specify file registers beyond 32k points without changing blocks.

File registers in multiple blocks can be managed as a single series of file registers.



The file register capacity is not fixed. For the register capacity that may be secured, refer to the explanation section of "MODEL SELECTION", "MEMORY".

Nestings (N)

Nestings are devices used with master control (MC, MCR instructions).

Pointers

Pointers are devices used with branch instructions and 4096 points can be used in all programs run by a CPU module.

The pointers are used in the following applications.

- Designation of jump destination of jump instruction (CJ, SCJ, JMP)
- (2) "Local pointers" and "common pointers" are available as the call destination designating pointers of the subroutine call instruction (CALL, CALLP).

Local pointers

Local pointers are used for a jump and subroutine program call in each program. A call can only be made from the program of the program file where that pointer is described.



Common pointers

Common pointers are used in a subroutine program called from multiple programs.

Common pointers cannot be used to jump to other programs.



Interrupt pointers (I)

An interrupt pointer is a device used as a label at the beginning of an interrupt program and 256 points (I0 to I255) can be used in all programs. (The same interrupt pointer number cannot be used.) The interrupt pointer numbers and interrupt factors are as follows.

Sequence Programs

I No.	Interrup	ot Factor	Priority	l No.	Interrupt Factor		Priority
10	Interrupt by	First point	237	I32 (Note	Error	General stopping error	1
	A1SI61			2)	occurrence		
l1		Second point	238	133	interrupt	Vacant	-
12		Third point	239	134	(Note 3)	UNIT VERIFY ERR.	2
13		Fourth point	240			FUSE BREAK OFF	
14		Fifth point	241			SP. UNIT ERROR	
15		Sixth point	242	135		OPERATION ERROR	3
16		Seventh point	243			SFCP OPE. ERROR	
17		Eighth point	244			SFCP EXE. ERROR	
18		Ninth point	245	136		ICM. OPE ERROR	4
19		Tenth point	246			FILE OPE. ERROR	
l10		Eleventh point	247	137		WXTEND INS. ERROR	5
l11		Twelfth point	248	138		PRG. TIME OVER	6
112		Thirteenth	249	139		CNK instruction execution	7
		point				Annunciator detection	
113		Fourteenth	250				
		point					
114		Fifteenth point	251	140 to 146		Vacant	—
l15		Sixteenth point	252				
116	Interrupt	First module	224	147	—	PRASET instruction label	—
117	generated by	Second	225	148 to 149		Vacant	—
	sequence start	module					
118	generating module	Third module	226				
119	module	Fourth module	227	150 to	Intelligent	Using parameter, set which intelligent function	18 to 223
120	_	Fifth module	228	1255	function	module will use.	
l21		Sixth module	229		module		
122		Seventh	230		interrupt		
	_	module		_			
123	_	Eighth module	231	_			
124	_	Ninth module	232				
125	_	Tenth module	234				
126		Eleventh	235				
107	_	module					
127		Twelfth	236				
100	Internuction	module	250				
128	Interrupt by internal timer	100ms	256				
129	(Note 1)	40ms	255	-			
130		20ms	254	-			
131		10ms	253				

Note 1: The internal timer time limits indicated are default values. They can be changed using the parameters between 0.5ms and 1000ms in 0.5ms increments.

Note 2: When a stopping error occurs, the CPU module stops after performing I32 processing.

Note 3: Error occurrence interrupt is disabled at power-on or reset. When using I32 to I255, enable interrupt with the IMASK instruction.

Sequence Programs

SFC block devices (BL)

An SFC block device is used to check whether the specified block of an SFC program is activated or not.

SFC transition devices (TR)

An SFC transition device is used to check whether the specified transition condition of an SFC program is designated for forced transition or not.

Network number designation devices (J) A network number designation device is a symbol used to specify a network number in a data link instruction.

Macro instruction argument devices (VD)

Macro instruction argument devices are used for macro registration.

Global Devices and Local Devices

Among the CPU module devices, "local device" range assignment can be made to the internal relays M, edge relays V, timers T, retentive timers ST, counters C and data registers D. Note that the ranges and devices where local device assignment is not made are global devices.

Global devices

Global devices mean devices which can be shared by all programs when there are multiple programs. Normally, the ranges where local device assignment has not been made and the devices where local device assignment cannot be made are all global devices and they can be used from any program.



Local devices

Local devices can be used exclusively in each of multiple programs, and local devices in a certain program cannot be accessed by other programs. Hence, using local devices allows you to do programming without being concerned with other programs.

Local device data are stored into the CPU module built-in standard RAM (drive 3) or memory card (RAM) (drive 1). The devices usable as local devices are the internal relays (M), edge relays (V), timers (T, ST), counters (C) and data registers (D) and their ranges are set in parameters.

In the QnACPU module, the devices set as local devices act as local devices in all programs. In the Q mode, however, you can select whether local devices are used or not per program.

Using local devices exchanges the local device data of the memory card (RAM) or standard RAM and the device data of the CPU module after program run, increasing the scan time by the exchange time.

In a program which does not use local devices, data exchange is not made and program switching time is shortened.

Exchange time

(when the number of local device points is 1k word)

	Exchange Time (ms)		
CPU Type	Standard RAM	Memory card (RAM)	
Q02CPU	0.35	1.2	
Q02HCPU,	0.15	0.9	
Q06HCPU,			
Q12HCPU,			
Q25HCPU			

Note 1: Exchange time differs from the above when both the memory card (RAM) and standard RAM are selected as the save areas of local devices.



Sequence Programs

Comparison between Q Mode and QnA/Q2AS

As compared to the QnA/Q2AS series instructions, the following instructions and others have been changed.

Common instructions

Added instructions

The following instructions have been added to the Q mode.

Class	Instruction Name
Module data read	UNIRD
Trace set	TRACE
Trace reset	TRACER
Binary data write	S.FWRITE
Binary data read	S.FREAD
Program loading from RAM card	PLOAD
Program unloading from SPM	PUNLOAD
Loading and unloading	PSWAP
High-speed file register block transfer	PBMOV

Deleted instructions

The following instructions have been deleted from the Q mode.

Class	Instruction Name
Write to EEPROM	EROMWR
Sampling trace set (Note 1)	STRA
Sampling trace reset (Note 1)	STRAR
Status latch set	SLT
Status latch reset	SLTR
Program trace trigger	PTRA
Program trace reset	PTRAR
Program trace execution	PTRAEXE, PTRAEXEP
LED indication of ASCII code	LED
LED indication of comment	LEDC

The above instructions have been deleted since the Q mode CPU does not have the corresponding functions, LEDs, etc. Note 1: Can be replaced by TRACE and TRACER instructions.

• Instructions to be noted for utilization

The following instructions must be noted when a program is utilized because there usage methods are different from those of QnA/Q2AS.

Class	Instruction Name
Annunciator output, set, reset	OUT, SET, RST
Device comment data read	COMRD
ASCII code print	PRC
Error/annunciator display reset	LEDR
BCD 4 digit to BIN data conversion	BIN
BCD 8 digit to BIN data conversion	DBIN
Clock data read	DATERD
Clock data registration	DATEWR
Interrupt mask	IMASK
Refresh	COM
Network refresh	ZCOM
Routing data read	RTREAD
Routing data write	RTWITE
PID control data setting	PIDINT
PID control	PIDCONT
1/2-phase input up/down counter	UDCNT1, UDCNT2
Pulse density measurement	SPD
Cyclic pulse output	PLSY
Pulse width modulation	PWM

Instructions for intelligent function modules/special function modules

When using a QnA series program after conversion into a Q mode program, the following should be noted if the conversion source QnA series program includes special function module-dedicated instructions.

When continuously using AnS series special function modules/network modules with Q mode

The Q mode CPU is not compatible with the A/AnS series special function module/network module-dedicated instructions. Rewrite all corresponding instructions using the FROM/TO instruction.

When changing QnA/Q2AS/A/AnS series special function modules/network modules for Q series intelligent function gas dules for Q series.

intelligent function modules/network modules Dedicated instructions may be used with some of the Q series intelligent function modules/network modules. Usable dedicated instructions are given in the explanation sections of the corresponding intelligent function modules/network modules.

Sequence Programs

Comparison between Q Mode and A/AnS

As compared to the A/AnS series instructions, the following instructions and others have been changed.

Common instructions

Added instructions

As compared to the A/AnS series, a large number of instructions have been added to the Q mode. Use the most appropriate instructions from among the great variety of instructions available for programming.

Instructions to be corrected for utilization The following instructions must be corrected when a program is utilized because they are different in usage method from those of the A/AnS.

Class	Instruction Name
Main/subprogram switching	CHG
Failure check	СНК
Carry reset	CLC
Index qualification circuit	IX
LED indication instruction	LEDA, LEDB
Local station data read	LRDP
Local station data write	LWTP
Remote I/O station data read	RFRP
Remote I/O station data write	RTOP
Partial refresh	RFS
Carry set	STC
Microcomputer program call	SUB
Extended file register 1-word increment	ZRRD
read	
Extended file register 1-word increment	ZRWR
write	
Extended file register 1-byte increment read	ZRRDB
Extended file register 1-byte increment write	ZRWRB
Extended file register block transfer	BMOVR
Extended file register block change	BXCHR
16-bit integer=>real number conversion	FLOAT
32-bit integer=>real number conversion	DFLOAT
Direct output, set, reset	DOUT, DSET, DRST
Retentive timer	OUT T
Rotation	RCL, RCR, ROL, ROR,
	DRCL, DRCR, DROL,
	DROR
Direct reset	DRST
Bit check	SUM, DSUM
Character string data coupling	SADD
Character string data transfer	SMOV
ASCII character string conversion	ASC
Character string data comparison	SCMP
Search	SER
Other AnA/AnU dedicated instructions	LEAD/LEDB

 Differences in timer and counter processing systems

Since the timer and counter processing systems are different between the A/AnS and Q mode CPUs, note the following when utilizing a program.

Instruction	Processing
Timer	Current value updating and contact ON/OFF, which were performed at END processing, are executed when OUT T instruction is executed.
Counter	Current value updating and contact ON/OFF, which were performed at END processing, are executed when OUT C instruction is executed.

Instructions for intelligent function modules/special function modules

When using an AnS series program after conversion into a Q mode program, the following should be noted if the conversion source A series program includes special function module-dedicated instructions.

When continuously using AnS series special

function modules/network modules with Q mode The Q mode CPU is not compatible with the A/AnS series special function module/network module-dedicated instructions. Rewrite all corresponding instructions using the FROM/TO instruction.

 When changing A/AnS series special function modules/network modules for Q series intelligent function modules/network modules

Dedicated instructions may be used with some of the Q series intelligent function modules/network modules. Usable dedicated instructions are given in the explanation sections of the corresponding intelligent function modules/network modules.

Sequence Programs

Online Write, Online File Write

Online write is a function to make partial correction or entire change to a program which is being executed by the CPU module (during RUN). As a program can be corrected without stopping equipment operation, this function is convenient for use during equipment adjustment.

Online write

When partial correction is made to a program, there are no restrictions on the size of the program that can be corrected by online write. Online write can be performed if the program size after correction is within the program memory size that can be secured by the CPU module.

Online file write

This function is not used to make partial correction but allows a program to be exchanged on a file basis. When performing this function, the CPU continues the processing of the original program file and simultaneously writes a new program file to the free area (Note 1) of the memory. On completion of new program write, the CPU suspends the processing of the original program and starts the processing of the new program. To perform the above processing, the memory must have the free space where the new program file can be written.

Note 1: You can use the free area of the program memory (drive 0), RAM card (drive 1) or ROM card (drive 2) (only the

ATA card may be used as a ROM card).



In this system, you can exchange not only program files but also device comment files or file register files.

- Note 2: When a device comment file or file register file is stored in the RAM card (drive 1) or ROM card (drive 2), it must not be accessed by a program to perform online file write.
- Note 3: Performing online write or online file write causes a delay in program scan time. Depending on the program file size to be online-written, a significant delay may take place, so fully ensure safety when performing this operation.

Remote Operation

Remote operation is executed from GPPW to the CPU module to perform RUN, STOP, PAUSE, reset or latch clear of the CPU module, without operating the RUN-STOP switch of the CPU module. Remote operation can be done to the CPU module connected with GPPW or to the CPU module connected by MELSECNET/10H, MELSECNET/10, Ethernet, CC-Link or serial communication.



Performing remote run causes the CPU module put in the STOP/PAUSE mode by remote stop/pause to go into the RUN mode.

Remote stop

Performing remote stop causes the CPU module in the RUN/PAUSE mode to go into the STOP mode (output (Y) is switched off and operation stopped).

Remote pause

Performing remote pause causes the CPU module in the RUN mode to go into the PAUSE mode (output (Y) is held and operation stopped).

Remote reset

Performing remote reset causes the CPU module in the STOP mode or being stopped by the self-diagnostic function to be reset (initialized). Device data other than the latch-specified data are cleared.

Remote latch clear

Performing remote latch clear causes the CPU module in the STOP mode to clear the latch-specified/non-latched device data.

Network Setting: SW5D5C-GPPW-E

Overview

With MELSECNET/10H, Ethernet and CC-Link placed as major networks of the Q mode, network-compatible functions are incorporated in the GPP function software package for Windows (hereafter referred to as the "GPPW") to enhance the functions and performance capabilities and ensure ease of use.

Network Parameter Setting

In the network parameter settings of MELSECNET/10H, Ethernet and CC-Link, the following settings can be made on the GPPW screen without programming.

MELSECNET/10H

Parameter Name	Function
Туре	Used to choose operating mode of MELSECNET/10(H).
Refresh parameter	Used to assign devices in CPU module as transfer destination of communication data in network module and CPU module device data to be transferred to network module as communication data.
Common parameter	Used to allocate LB/LW/LX/LY link device range to each station.
Station-specific parameter	Needed to assign parameters different from common parameters to a certain station. Normally not needed.
Inter-link transfer parameter	Used to exchange communication data partially between two or more networks using CPU module connected to two or more networks.
Routing parameter	Used to determine message sending path when accessing remote CPU module which spans networks.
Event interrupt	Used to set condition for generating interrupt signal to CPU module to start interrupt program.

Ethernet

Parameter Name	Function
Initial setting	Used to set various watchdog timer values of TCP and IP address of DNS server.
Open setting	Used to set TCP/UDP protocol selection, open system, connection target IP address/port number, etc.
Operation setting	Used to set host station IP address, communication data ASCII/BIN selection, etc.
E-mail setting	Used to set host station e-mail address, mail server, etc.
Transmission mail address	Used to set mail address for sending e-mail.
Notice setting	Used to set notice condition, etc. for use of notice function.
MNET/10 routing	Used to set communication path needed to access CPU module connected to MELSECNET/10(H) via Ethernet.
FTP parameter	Used to set parameters necessary to use FTP (file transfer) function.
Routing data	Used to set sub-net mask and router IP address for communication via Ethernet router.
Event interrupt	Used to set condition for generating interrupt signal to CPU module to start interrupt program.

CC-Link

Parameter Name	Function
Operation setting	Used to select CC-Link between high-speed remote I/O network mode consisting of remote I/O only and ordinary mode.
Network parameter	Used to set the number of modules connected to CC-Link, refresh devices, etc.
Station data	Used to set type of each remote station.
Initial processing setting	Used to set initial processing performed for remote device stations.
Event interrupt	Used to set condition for generating interrupt signal to CPU module to start interrupt program.

Network Monitoring

In GPPW, you can monitor the network operating status of MELSECNET/10(H) and CC-Link. For MELSECNET/10(H), you can monitor the network line status, operating/communication status of each station, link scan time indicating communication frequencies, and other data. For CC-Link, you can monitor the link scan time, communications status of each station, and error status.

Data Conversion Software: SW0D5C-CNVW-E

Overview

The SW0D5C-CNVW-E data conversion software package for Windows (hereafter referred to as the "CNVW") is software designed to make mutual data conversion between other format data (text format data, CSV format data) and GPPW-handled data (instruction list, device comment). It allows CAD-created data to be utilized on GPPW for facility design or GPPW-created data to be utilized for design on CAD, increasing design efficiency.

Operating environment

Since CNVW is used by adding it to GPPW (SW3D5F/C-GPPW-E or later), GPPW must be installed in advance.

Data conversion function

The following data can be converted by CNVW.

Conversion Factor	Conversion Data
CSV format data \rightarrow GPPW	Instruction list
format data	Device comment
Text format data \rightarrow GPPW format	Instruction list
data	Device comment
GPPW format data \rightarrow text format	Instruction list
data	Device comment
GPPW format data \rightarrow CSV	Instruction list
format data	Device comment



Peripheral Devices

Overview

The Q mode PLC is programmed on a Windows personal computer and connected to the CPU module via the COM port (RS-232) or USB port of the personal computer. The Q mode CPU module is equipped with an RS-232 interface operable at up to 115.2kbps and a USB interface operating at 12MBps.

Note: The USB interface is not provided for the Q02CPU.

RS-232 Connection

Connection configuration diagram

The following diagram shows a configuration for connection with a personal computer by an RS-232 interface.



RS-232 cable

Туре	QC30R2
Length	3m (9.84ft.)
Connector shape	Personal computer side: 9-pin D-Sub
	PLC side: 6-pin Mini-DIN

RS-232 cable connection example



Note: Do not make connection to the PLC side pin number 4.

Instructions

 The Q mode CPU can communicate at up to 115.2kbps, but depending on the performance of the personal computer connected, it may not be able to communicate at 115.2kbps. If so, choose any of 57.6k, 38.4k, 19.2k and 9.6kbps communication speeds.

- (2) When using the QC30RC (3m (9.84ft.) cable), we have confirmed that communication can be made at 115.2kbps.
- (3) The usable communication speed and distance of the cable fabricated by the user should be checked by the user.
- (4) When fast, long-distance communication is needed, consider using RS-232 optical cable converters (FA OPT232).

USB Connection

Connection configuration diagram

The following diagram shows a configuration for connection with a personal computer by a USB interface.



Usable USB cables

Please choose a cable that complies with USB Standard Rev.1.1, and examine operability with the CPU module and the computer.

Instructions

- (1) The longest usable distance of USB is 5m (16.39ft.).
- (2) USB may be used with Windows 98 only.

Other Connection Systems

When using SW5D5C-GPPW-E, you can use the following connection systems in addition to the RS-232 port and USB connection of the CPU module.

Personal Computer Side Port	Communication System	Q Mode PLC Side Module
COM	RS-232	QJ71C24 QJ71C24-R2
Ethernet board	Ethernet	QJ71E71 QJ71E71-B2
A70BDE-J71QLP23(GE) (Note 1) A70BDE-J71QBR13 (Note 1)	MELSECNET/10	QJ71LP21 QJ71BR11
A80BDE-J61BT13 A80BDE-J61BT11 (Note 2)	CC-Link	QJ61BT11

Note 1: SW3DNF-MNET10 driver is necessary. Note 2: SW3DNF-CCLINK driver is necessary.

SIMULATION/ DEBUGGING FUNCTIONS

Sequence Program Simulation

Software

The SW5D5C-LLT-E ladder logic test tool (hereafter reffered to as "LLT") is software designed to add simulation functions onto GPPW. This comprehensive software is compatible with the A series, QnA series, FX series and motion controller, in addition to the Q series, to allow GPPW created sequence programs to be simulated on a personal computer without writing them to the PLC. If the intelligent function module software packages have also been added, you can simulate the initial parameter setting and automatic refresh parameter setting states of intelligent function modules (such as analog-to-digital converter module, digital-to-analog converter module and communication module).

Features

Program run can be checked on a personal computer, making debugging efficient.

- Without connection of a PLC, program run can be checked on the personal computer where that program was created.
- (2) The target PLC type (MELSEC-A/QnA/FX/Q/motion controller) of the program created is judged automatically and the corresponding virtual CPU is started.
- (3) Simple setting allows the machine side I/O to be operated simulatively. (Example: X0 turns on 10 seconds after Y10 has turned on.)
- (4) Debugging is enabled in the stage of program design. When used with the program modularization function (multiple programs can be created per control purpose for operation) of the Q series CPU, the software permits debugging on a module basis, further increasing debugging efficiency and reducing on-thespot adjustment time.
- (5) PLC, basic and application instructions are supported.

I/O System Setting Function

The I/O system setting function allows external input generated for the PLC output to be given simulatively by simple setting. The following No. 1 indicates the setting that X2 and X3 are turned on 5 seconds after X0 has turned on and X2 turned off.

No.	Condition	Timer	Input (Simulation Device)	Status
1	X0=0N C OR	500 ×10ms	2X3 © ON C OFF	🔽 Enable
2	Y70=OFF C AND C OR	300 ×10ms	0 OFF	🔽 Enable

Monitoring and Testing Functions

The monitoring and testing functions are designed to monitor the statuses of the device memory and buffer memory in a virtual CPU, and also permits forced ON/OFF and current value changing as well as device ON/OFF state and value monitoring, like the device batchmonitoring and buffer memory batch-monitoring functions of GPPW. In addition, the monitoring and testing functions of the ladder logic test tool include a function to display ON/OFF states and values in a timing chart format. It enables time-series operation to be acquired.



Tool Function

The tool function is designed to temporarily save the data of the virtual CPU device memory and special function module buffer memory and read and use the saved data when resuming debugging work.

Error Detail Display Function

Error detail explanation appears when an operation or similar error occurs during simulation made LLT. This function saves time and trouble to refer to the manuals, etc. and facilitates finding the error occurrence cause.

ERROR DETAILS		
Error and Cause		Corrective Action
There is no special function module in the area specified by the FROM/TO instruction.	A 	(1) Check the error step and correct the content of the FROM/TO instruction. (2) Correct the I/O unit allocation parameter
Error Step No. 9		
File Name		UK

Differences and Restrictions

As compared to the operation of the Q mode CPU, LLT has the following restrictions.

- (1) LLT cannot support SFC programs.
- (2) LLT does not support interrupt programs. No operation will be performed if a sequence program is created.
- (3) The operation result in any instruction that uses a floating point value is not equal to the actual operation result of the CPU because of a rounding error.
- (4) LLT cannot simulate the functions of intelligent function/network modules. However, it has a buffer memory area of 64k points × 64 modules for intelligent function/network modules. Data write/read can be performed to/from this area.
- (5) For the timing of LLT, processing time taken for one scan is calculated as 100ms (default value). By changing the constant scan setting, you can change the time taken for one scan.
- (6) In LLT, the timing method of the timer changes with the scan time (= constant scan setting) of the logic test function. At a scan time of 100ms, the current value of the 100ms timer is incremented by 1 every scan and the current value of the 10ms timer is incremented by 10 every scan. At a scan time of 10ms, the current value of the 100ms timer is incremented by 10 every scan and the current value of the 10ms timer is incremented by 1 every scan.

- (7) In LLT, one low-speed execution program is always run after a scan execution program, independently of whether the constant scan setting and low-speed execution program running time setting have been made or not.
- (8) A cyclic execution program is run if its cyclic time interval has been reached on completion of the processing of scan execution program and cyclic program.
- (9) LLT can use all device memories of the Q mode CPU. Note that it cannot use the link direct devices JnXn, JnYn, JnBn, JnWn, JnSBn and JnSWn (resulting in no operation).
- (10)"OPERATION ERROR" occurs if a device range is exceeded in indirect designation using the index register.
- (11)In real number processing instructions, the ladder logic test tool (LLT) checks their real number ranges strictly. "OPERATION ERROR" occurs if any value entered cannot be evaluated as a real number.

(12) The following parameters are invalid if set.

Parameter	Setting Item			
PLC name setting	All invalid.			
PLC system setting	Items except "timer time limit setting", "STOP-RUN/output mode" and "common pointer No." are invalid.			
PLC file setting	 "Target memory" of "file register" is invalid. "Comment file used for instructions" is invalid. "Target memory" of "device initial value" is invalid. "Target memory" of "file for local devices" is invalid. 			
PLC RAS setting	 "Error check" is invalid. Items other than "operation error" and "special function module access error" in "error-time operation mode" are invalid. "Fault history" and "low-speed program running time" are invalid. 			
I/O assignment	"Type", "switch setting" and "detail setting" of "I/O assignment" are invalid. "Basic setting" (base, power supply module, extension cable) is invalid.			
Device setting	"Latch range" is invalid.			
Program setting	"Comment" of "file using method setting" is invalid. "I/O refresh setting" is invalid.			
Boot file setting	All invalid.			
SFC setting	All invalid.			
Network parameters	All invalid.			

Sequence Program Simulation

(13)The following SM devices are supported by LLT.

The unsupported SM devices not given below can be accessed since their device areas are secured, but they do not have inherent SM functions.

In addition, the unsupported SM devices have the initial values of OFF.	In addition.	, the unsupported	SM devices have	the initial values	of OFF.
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Device Name	Remarks	Device Name	Remarks	Device Name	Remarks	Device Name	Remarks
SM0	Diagnostic error	SM409 (*1)	0.01 sec. clock	SM434	User clock No. 9	SM1021	User clock No. 1
SM1	Self-diagnostic error	SM410 (* 1)	0.1 sec. clock	SM510	Low-speed program run	SM1022	User clock No. 2
SM5	Error common information	SM411 (* 1)	0.2 sec. clock	SM620	Card B use flag normally OFF	SM1023	User clock No. 3
SM16	Error individual information	SM412 (*1)	1 sec. clock	SM621	Card B protect flag normally OFF	SM1024	User clock No. 4
SM50	Error reset	SM413 (* 1)	2 sec. clock	SM622	Drive 3 flag normally ON	SM1030	0.1 sec. clock
SM56	Operation error	SM414 (* 1)	2n sec. clock	SM623	Drive 4 flag normally ON	SM1031	0.2 sec. clock
SM62	Annunciator detection	SM415 (* 1)	2n millisec. clock	SM640	File register use	SM1032	1 sec. clock
SM203	STOP contact	SM420	User clock No. 0	SM700	Carry flag	SM1033	2 sec. clock
SM205	STEP-RUN contact	SM421	User clock No. 1	SM703	Sort order	SM1034	2n sec. clock
SM213	Clock data read request	SM422	User clock No. 2	SM704	Block comparison	SM1036	Normally ON
SM400	Normally ON	SM423	User clock No. 3	SM715	EI flag	SM1037	Normally OFF
SM401	Normally OFF	SM424	User clock No. 4	SM722	BIN/DBIN error processing switch- over	SM1038	ON only 1 scan after RUN
SM402	ON only 1 scan after RUN	SM430	User clock No. 5	SM1008	Self-diagnostic error	SM1039	OFF only 1 scan after RUN
SM403	OFF only 1 scan after RUN	SM431	User clock No. 6	SM1009	Annunciator detection	SM1042	STOP contact
SM404	ON only 1 scan after RUN	SM432	User clock No. 7	SM1010	Operation error	SM1054	STEP-RUN contact
SM405	OFF only 1 scan after RUN	SM433	User clock No. 8	SM1020	User clock No. 0		

*1: Derived from the constant scan setting and scan count. The time set as a constant scan is the time of 1 scan. Therefore, 1 scan time = constant scan time.

Sequence Program Simulation

(14)The following SD devices are supported by LLT.

The unsupported SD devices not given below can be accessed since their device areas are secured, but they do not have inherent SD functions.

In addition, the unsupported SD devices have the initial values of 0 (zero).

Device Name	Remarks	Device Name	Remarks	Device Name	Remarks	Device Name	Remarks
SD0	Diagnostic error	SD67	Detection table	SD295	Device assignment		
SD1	Error occurrence time	SD68	Detection table	SD296	Device assignment		
SD2	Error occurrence time	SD69	Detection table	SD297	Device assignment		
SD3	Error occurrence time	SD70	Detection table	SD298	Device assignment		
SD4	Error information segment	SD71	Detection table	SD299	Device assignment	SD647	File register capacity
SD5	Error common information	SD72	Detection table	SD300	Device assignment	SD648	R block No.
SD6	Error common information	SD73	Detection table	SD301	Device assignment		
SD7	Error common information	SD74	Detection table	SD302	Device assignment		
SD8	Error common information	SD75	Detection table	SD303	Device assignment		
SD9	Error common information	SD76	Detection table	SD304	Device assignment		
SD10	Error common information	SD77	Detection table	SD412 (*2)	1 sec. counter		
SD11	Error common information	SD78	Detection table	SD414 (*2)	2n sec. clock setting		
SD12	Error common information	SD79	Detection table	SD415 (*2)	2n millisec. clock setting		
SD13	Error common information	SD200	CPU switch status	SD420	Scan counter		
SD14	Annunciator number	SD201	LED status	SD430	Low-speed scan counter		
SD15	Error common information	SD203	CPU operation status	SD500	Run program No.	SD1008	Diagnostic error
SD16	Error individual information	SD210	Clock year, month	SD510	Low-speed program No.	SD1009	Annunciator detection
SD17	Error individual information	SD211	Clock day, hour	SD520 (*1)	Current scan time	SD1015	CPU operation status
SD18	Error individual information	SD212	Clock minute, second	SD521 (*1)	Current scan time	SD1017 (*1)	Minimum scan time
SD19	Error individual information	SD213	Year, day of the week	SD522 (*1)	Initial scan time	SD1018 (*1)	Current scan time
SD20	Error individual information	SD220	Display data	SD523 (*1)	Initial scan time	SD1019 (*1)	Maximum scan time
SD21	Error individual information	SD221	Display data	SD524 (*1)	Minimum scan time	SD1021 (*1)	Current scan time
SD22	Error individual information	SD222	Display data	SD525 (*1)	Minimum scan time	SD1022 (*2)	1 sec. counter
SD23	Error individual information	SD223	Display data	SD526 (*1)	Maximum scan time	SD1035	R block No.
SD24	Error individual information	SD224	Display data	SD527 (*1)	Maximum scan time	SD1124	Annunciator quantity
SD25	Error individual information	SD225	Display data	SD528 (*1)	Current scan time	SD1125	Annunciator number
SD26	Error individual information	SD226	Display data	SD529 (*1)	Current scan time	SD1126	Annunciator number
SD50	Error reset	SD227	Display data	SD532 (*1)	Minimum scan time	SD1127	Annunciator number
SD62	Annunciator No.	SD290	Device assignment	SD533 (*1)	Minimum scan time	SD1128	Annunciator number
SD63	Annunciator quantity	SD291	Device assignment	SD534 (*1)	Maximum scan time	SD1129	Annunciator number
SD64	Detection table	SD292	Device assignment	SD535 (*1)	Maximum scan time	SD1130	Annunciator number
SD65	Detection table	SD293	Device assignment		1	SD1131	Annunciator number
SD66	Detection table	SD294	Device assignment			SD1132	Annunciator number

*1: Same as all constant scan settings. Default is 100ms.

*2: Derived from the constant scan setting and scan count. The time set as a constant scan is the time of 1 scan.

SIMULATION/ DEBUGGING FUNCTIONS

Sequence Program Simulation

- (15)LLT supports the instructions of the Q25H. However, some instructions have restrictions or are not supported. No operation is performed for unsupported instructions. The following instructions are not operated or have processing restrictions.
 When a no-operation instruction is executed, the logic test function screen lamp is lit, and that no-op instruction and its step number can be displayed.
- Non-operated and processing-restricted instruction list

Class	Instruction Symbol	Processing
Output instruction	DELTA (P)	No operation
Program run control	DI	No operation
instruction	EI	No operation
	IMASK	No operation
	IRET	No operation
Refresh instruction	RFS	No operation
	RFRDB	No operation
	RFRDW	No operation
	RFRDDB	No operation
	RFRDDW	No operation
	COM	No link refresh
Display instruction	PR	No operation
	PRC	
Debugging,	CHKST	No operation
troubleshooting	СНК	No operation
instruction	CHKCIR	No operation
	CHKEND	No operation
	TRACE	No operation
	TRACER	No operation
Clock instruction	DATERD (P)	Personal computer
		clock data used
	DATEWR (P)	No operation
Peripheral device	MSG	No operation
instruction	PKEY	No operation
PID control	PIDINIT	No operation
instruction	PIDINITP	No operation
	PIDCONT	No operation
	PIDCONTP	No operation
	PIDSTOP	No operation
	PIDSTOPP	No operation
	PIDRUN	No operation
	PIDRUNP	No operation
	PIDRMW	No operation
	PIDPRMWP	No operation

Class	Instruction Symbol	Processing
Data link instruction	ZCOM	No operation
	READ	No operation
	SREAD	No operation
	WRITE	No operation
	SWRITE	No operation
	SEND	No operation
	RECV	No operation
	REQ	No operation
	ZNFR	No operation
	ZNTO	No operation
	ZNRD	No operation
	ZNWR	No operation
	RFRP RTDP	No operation
	RTREAD	No operation
	RTWRITE	No operation No operation
Serial	PRR	No operation
communication/comp	INPUT	No operation
uter link module	SPBUSY	No operation
control instruction	CANCEL	No operation
	PUTE	No operation
	GATE	No operation
	ONDEMAND	No operation
	UTPUT	No operation
	PRR	No operation
	INPUT	No operation
	BIDOUT	No operation
	BIDIN	No operation
	SPBUSY	No operation
CC-LINK control	RIRD	No operation
instruction	RIWT	No operation
	RIFR	No operation
	RITO	No operation
	RDGET	No operation
	RDPUT	No operation
<u></u>	RDMON	No operation
Other instructions	NOPLF	No operation
	PAGE UDCNT1	No operation
	UDCNT2	No operation No operation
	TTMR	ON time on LLT
		measured
	STMR	Operation based on
		time on LLT
	ROTC	No operation
	SPD	No operation
	PLSY	No operation
	PWM	No operation
	UNIRD	No operation
	S.FWRITE	No operation
	S.FREAD	No operation
	PLOAD	No operation
	PUNLOAD	No operation
	PSWAP	No operation
	RBMOV	Processed as BMOV
		instruction
	WDT (P)	No operation
	KEY	No operation

3. A MODE

1. OVERVIEW	
Overview of A Mode	
Comparison between Q Mode and A mode	3-2
Compatibility of A Mode PLC with Ans	3-3
2. MODEL SELECTION	
General Specifications	3-4
Applicable Model List	3-5
System Configuration	3-9
• CPU Modules: Q02CPU-A, Q02HCPU-A, Q06HCF	
CPU Built-in Memories/Memory Cards	3-15
Network/Special Function Modules I/O Modules	
Current Consumption Calculation	
Power Supply Modules: A1S61PN, A1S62PN, A1S	
Base Units/Extension Cables	
Accessories: Batteries, Connectors	
Accessories: Connectors, Terminal Block Convert	
Modules	
External Dimensions	3-24
3. PROGRAMMING	
Sequence Programs	
Peripheral Devices	3-26
4. SIMULATION/DEBUGGING FUNCTION	٧S
Sequence Program Simulation	3-28

Overview of A Mode

The A mode is designed to improve the CPU processing capabilities of the AnS series systems already in use. You can use the AnS series programs as they are and can use the AnS series hardware products, such as I/O modules, without changing. (Note that the CPU modules, base units and extension base cables must be changed.) This mode is recommended for those who want to use the current model and improve performance with minimum modifications.

Note: The A mode is designed to improve the CPU processing capabilities of the AnS series, as described above. Namely, note that the functional capabilities of the CPU other than the processing capabilities (refer to the section of CPU modules) are the same as those of the conventional AnS series and you cannot use the functional capabilities extended and developed inherently for the Q series (Q mode). We recommend you to examine the Q mode if you are considering new equipment design, etc.

CONTENTS

OVERVIEW

Comparison between Q Mode and A Mode

Comparison between Q Mode and A Mode

	Q	Mode		A Mode	
CPU type	Q02CPU, Q02HCPU, Q06H0	CPU, Q12HCPU, Q25HCPU	Q02CPU-A, Q02HCPU-A, Q06HCPU-A		
Available functions, modules,	etc.				
Program	Inherits the programming and methods of the MELSEC. Ho internal codes, the programs be used after conversion.		Programs for the current AnS series		
Functions	Functions given in the Chapte book are usable.	er of "Features" in this data	Basically, there are only functions that are usable with the AnS series though some specifications have been expanded in performance. For expanded specifications, refer to section 2 "CPU modules" in this chapter.		
I/O, special modules	For Q series and AnS series A6SIM-X64Y64 cannot be us	ed.	For AnS series A6SIM-X64Y64 canr	not be used.	
Base unit	For using Q series modules: For using AnS series module		For using AnS series	s modules: QA1S3 B, QA1S6 B	
Extension cable	QCB		QC B		
Power supply module	For using with Q series base For using with AnS series base		A1S6 P		
Connectable networks		Language -			
Ethernet	Allowed		Allowed		
MELSECNET/10H	Allowed		Disallowed		
MELSECNET/10 (Inter-PC network)	Allowed		Allowed		
MELSECNET/10 (Remote-I/O network)	Disallowed		Allowed		
MELSECNET/II MELSECNET/B	Disallowed		Allowed		
CC-Link	Allowed (with automatic refresh parameter setting)		Allowed (without auto	omatic refresh parameter setting)	
MELSECNET/MINI	Allowed (without automatic refresh parameter setting)		Allowed (with automa	atic refresh parameter setting)	
RS-232/422/485	Allowed		Allowed		
Other networks	Networks compatible with An	S series	Networks compatible	e with AnS series	
Usable peripheral devices an	d software				
Windows personal computer	Allowed	SW4D5C-GPPW-E or later	Allowed	SW2D5C-GPPW-E or later (Note 1)	
DOS	Disallowed		Allowed	SW2IVD-GPPA or later (Note 1)	
A6GPP/HGP/PHP	Disallowed		Allowed	SW3GP-GPPAEE or later (Note 1)	
Usable GOTs and connectior	nmethod				
Usable GOT	GOT-A900		GOT-A900/800		
Software	SW2D5C-GOTRE-PACK ver	sion C or later	SW1D5C-GOTRE-PACK or later, SW0NIW-A8GOTP or later		
Bus connection	Allowed		Disallowed		
CPU RS-232 port connection	Allowed (ladder monitor will b	e compatible soon)	Allowed (ladder monitor possible)		
CPU USB port connection	Disallowed		Disallowed		
Serial communication (RS- 232/422)	Allowed (ladder monitor will b	e compatible soon)	Allowed (ladder monitor possible)		
MELSECNET/10	Allowed (ladder monitor will b	e compatible soon)	Allowed (ladder monitor possible)		
MELSECNET/II	Disallowed		Allowed (ladder mon	itor possible)	
MELSECNET/B	Disallowed		Allowed (ladder mon	itor possible)	
CC-Link	Allowed (ladder monitor will b	e compatible soon)	Allowed (ladder mon	itor possible)	

Note 1: Depending on the software version, there are restrictions on the program capacities, CPU internal device capacities, etc. For details, refer to Programming, A MODE.

Note 2: The above table gives general usability and connectability for comparison of the Q mode and A mode. Since there may be restrictions on usable/connectable products, always check details in the applicable model list and corresponding model explanation sections.
Compatibility of A Mode PLC with Ans

Compatibility of A Mode PLC with AnS

The following table indicates the compatibility between A mode PLC programs and AnS series programs. Note that the following table gives general information only and details should be checked in the corresponding module explanation sections.

	Item	Compatibility with AnS
General program		The same programs as in AnS are usable.
Ethernet	Ethernet Host system side program The same programs as in AnS are usable.	
PLC side		The same programs as in AnS are usable.
MELSECNET/10		The same network parameters and programs as in AnS are usable.
CC-Link		The same programs as in AnS are usable.
Serial Host system side communication program		The same programs as in AnS are usable.
	PLC side	The same programs as in AnS are usable.

Other Precautions for Replacing AnS with A Mode





General Specifications

General Specifications Specifications Item 0 to 55 °C Operating ambient temperature -20 to 75 °C Storage ambient temperature Operating ambient humidity 10 to 90%RH, non-condensing Storage ambient humidity 10 to 90%RH, non-condensing Vibration resistance Conforming to JIS Under intermittent vibration Sweep count B 3502, IEC Frequency Acceleration Amplitude 10 times each in 61131-2 X, Y, Z directions 10 to 57Hz 0.075mm (for 80 min.) (0.003inch) 57 to 150Hz 9.8m/s² Under continuous vibration Amplitude Frequency Acceleration 10 to 57Hz 0.035mm (0.001inch) 57 to 150Hz 4.9m/s² Conforming to JIS B 3502, IEC 61131-2 (147 m/s², 3 times in each of 3 directions X, Y, Z) Shock resistance Operating atmosphere No corrosive gases Operating altitude (Note 3) 2000m (6557.38ft.) max. Installation location Inside control panel Overvoltage category (Note 1) II or less Pollution level (Note 2) 2 or less

Note 1: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises. Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

Note 2: This index indicates the degree to which conductive material is generated in the environment where the equipment is used. In pollution level 2, only non-conductive pollution occurs but temporary conductivity may be produced due to condensation.

Note 3: The PLC cannot be used under pressure higher than the atmospheric pressure of altitude 0m (0ft.). Doing so can cause a failure.



Applicable Model List

Applicable Model List

The following applicable model list gives models usable in an A mode system.

Product	Туре	Description	Number of Points Occupied		onsumption (A)	Remark
		·	[I/O Allocation]	5VDC	24VDC	Remark
CPU module	Q02CPU-A	Program capacity: 28k steps, number of I/O points: 4096 points, basic instruction processing speed: 79ns	_	0.600	-	
	Q02HCPU-A	Program capacity: 28k steps, number of I/O points: 4096 points, basic instruction processing speed: 34ns	_	0.640	-	
	Q06HCPU-A	Program capacity: 30k steps, number of I/O points: 4096 points, basic instruction processing speed: 34ns	—	0.640	-	
Memory card	Q2MEM-1MBS	SRAM card: 1M bytes (including usable space of 302k bytes)	-	0.150	-	
Main base unit	QA1S33B	AnS series module loading base, for power supply + 3 slots	_	0.107	-	
	QA1S35B	AnS series module loading base, for power supply + CPU + 5 slots	—	0.117	-	
	QA1S38B	AnS series module loading base, for power supply + CPU + 8 slots	—	0.118	—	
Extension base unit	QA1S65B	AnS series module loading base, for power supply + 5 slots	—	0.117	—	
	QA1S68B	AnS series module loading base, for power supply + 8 slots	—	0.118	—	
Extension	QC06B	0.6m (1.97ft.) cable for extension base	—	—		
cable	QC12B	1.2m (3.93ft.) cable for extension base	—	—		
	QC30B	3m (9.84ft.) cable for extension base	—	—		
	QC50B	5m (16.39ft.) cable for extension base	—	—	1	
	QC100B	10m (32.79ft.) cable for extension base	—	—		
Battery	Q6BAT	Battery for program memory, standard RAM	-	-	-	
Power supply module	A1S61PN	100-240VAC input, 5VDC 5A output	—	—	—	
	A1S62PN	100-240VAC input, 5VDC 3A/24VDC 0.6A output	_	_	—	
	A1S63P	24VDC input, 5VDC 5A output	—	—	—	
AC input module	A1SX10	100-120VAC input, 16-points, terminal block	16 [16pt X]	0.050	—	
	A1SX10EU	100-120VAC input, 16-points, terminal block	16 [16pt X]	0.050	—	
	A1SX20	200-240VAC input, 16-points, terminal block	16 [16pt X]	0.050	-	
	A1SX20EU	200-240VAC input, 16-points, terminal block	16 [16pt X]	0.050	-	
DC/AC input module	A1SX30	12/24VDC, 12/24VAC input, 16-points, terminal block	16 [16pt X]	0.050	—	
DC input module	A1SX40	12/24VDC input, 16-points, terminal block (sink)	16 [16pt X]	0.050	—	
	A1SX40-S1	24VDC, 16 input points, terminal block, for high-speed input (sink)	16 [16pt X]	0.050	_	
	A1SX40-S2	24VDC, 16 input points, terminal block, for high leakage current sensor (sink)	16 [16pt X]	0.050	_	
	A1SX41	12/24VDC, 32 input points, connector (sink)	32 [32pt X]	0.080	_	
	A1SX41-S1	24VDC, 32 input points, connector, for high-speed input (sink)	32 [32pt X]	0.120	_	
	A1SX41-S2	24VDC, 32 input points, connector, for high leakage current sensor (sink)	32 [32pt X]	0.080	_	
	A1SX42	12/24VDC, 64 input points, connector (sink)	64 [64pt X]	0.090	-	
	A1SX42-S1	24VDC, 64 input points, connector, for high-speed input (sink)	64 [64pt X]	0.160	—	
	A1SX42-S2	24VDC, 64 input points, connector, for high leakage current sensor (sink)	64 [64pt X]	0.090	—	
	A1S42X	12/24VDC dynamic, 64 input points, connector (sink)	64 [64pt X]	0.080	-	
	A1SX71	5/12VDC, 32 input points, connector (sink)	32 [32pt X]	0.075	—	

MODEL SELECTION

Applicable Model List

Product	Туре	Description	Number of Points	Current Consumption (A)		Remarks
Product	туре		Occupied [I/O Allocation]	5VDC	24VDC	Remark
DC input module	A1SX80	24VDC, 16 input points, terminal block, for high-speed input (sink/source)	16 [16pt X]	0.050	-	
	A1SX80-S1	24VDC, 16 input points, terminal block, for high-speed input (sink/source)	16 [16pt X]	0.050	-	
	A1SX80-S2	24VDC, 16 input points, terminal block, for high leakage current sensor (sink/source)	16 [16pt X]	0.050	-	
	A1SX81	12/24VDC, 32 input points, connector (sink/source)	32 [32pt X]	0.080	-	
	A1SX81-S2	24VDC, 32 input points, connector, for high leakage current sensor (sink/source)	32 [32pt X]	0.080	-	
	A1SX82-S1	24VDC, 64 input points, connector (sink/source)	64 [64pt X]	0.160	-	
Contact output module	A1SY10	240VAC/24VDC 2A, 16 output points, terminal block	16 [16pt Y]	0.120	0.090	
	A1SY10EU	240VAC/24VDC 2A, 16 output points, terminal block	16 [16pt Y]	0.120	0.090	
	A1SY14EU	240VAC/24VDC 2A, 12 output points, terminal block	12 [16pt Y]	0.120	0.100	
	A1SY18A	240VAC/24VDC 2A, 8 independent contact output points, terminal block	8 [16pt Y]	0.240	0.075	
	A1SY18AEU	240VAC/24VDC 2A, 8 output points, terminal block	8 [16pt Y]	0.240	0.075	
Triac output	A1SY22	100-240VAC 0.6A, 16 output points	4 [16pt Y]	0.270	0.004	
module	A1SY28A	100-240VAC 1A, 8 output points, all points independent	8 [16pt Y]	0.130	-	
	A1SY28EU	100-240VAC 0.6A, 8 output points, all points independent	8 [16pt Y]	0.270	—	
Transistor output module	A1SY40	12/24VDC 0.1A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.270	0.016	
	A1SY41	12/24VDC 0.1A, 32 output points, terminal block, with fuse (sink)	32 [32pt Y]	0.500	0.008	
	A1SY42	12/24VDC 0.1A, 64 output points, terminal block, with fuse (sink)	64 [64pt Y]	0.930	0.016	
	A1SY42Y	12/24VDC dynamic, 64 output points, connector, with fuse (sink)	64 [64pt Y]	0.100	0.008	
	A1SY50	12/24VDC 0.5A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.120	0.120	
	A1SY60	24VDC 2A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.120	0.030	
	A1SY60E	5/12/24VDC 2A, 16 output points, terminal block, with fuse (sink)	16 [16pt Y]	0.200	0.020	
	A1SY68A	5/12/24/48VDC 2A, 8 output points (independent common), terminal block	16 [16pt Y]	0.11	-	
	A1SY71	5/12/24/48VDC 2A, 8 output points (independent common), terminal block	32 [32pt Y]	0.400	0.150	
	A1SY80	5/12VDC, 32 output points, 16mA, connector, with fuse	16 [16pt Y]	0.120	0.040	
	A1SY81	12/24VDC 0.8A, 16 output points, terminal block, with fuse (source)	32 [32pt Y]	0.500	0.008	
	A1SY81EP	12/24VDC 0.1A, 32 output points, connector (with short-circuit protection)	32 [32pt Y]	0.500	0.160	
	A1SY82	12/24VDC, 32 output points, connector, with fuse (source)	64 [64pt Y]	0.930	0.016	
I/O composite module	A1SH42	12/24VDC, 32 input points, 0.1A, 32 output points, connector, fuse	32 [32pt Y]	0.500	0.008	
	A1SH42-S1	24VDC, 32 input points, 0.1A, 32 output points, connector, fuse	32 [32pt Y]	0.500	0.008	
	A1SH48Y58	24VDC, 8 input points, transistor 0.5A, 8 output points, terminal block	16 [16pt Y]	0.060	0.060	
DC input, contact output	A1SX48Y18	24VDC, 8 input points, 2A contact, 8 output points, terminal block	16 [16pt Y]	0.085	0.045	
High-speed	A1SD61	High-speed counter	32 [32pt F]	0.35	—	
counter	A1SD62	DC input sink output type	32 [32pt F]	0.14		
	A1SD62D	Differential input sink output type (preset	32 [32pt F]	0.14	$+$ _	+
	A1SD62D A1SD62D-S1	Differential input sink output type (preset DC input) Differential input sink output type (preset	32 [32pt F] 32 [32pt F]	0.25		
		differential input)		-		
	A1SD62E	DC input source output type	32 [32pt F]	0.14	—	

Symbol examples in Number of Points Occupied (I/O Allocation) field X: input, Y: output, F: special, S: vacant

MODEL SELECTION

Applicable Model List

			Number of Points	Current C	onsumption (A)	Dorrer
Product	Туре	Description	Occupied [I/O Allocation]	5VDC	24VDC	Remarks
Analog-to- digital	A1S64AD	Analog input, 4 channels	32 [32pt F]	0.40	-	
converter A1S68AD module		Analog input, 8 channels	32 [32pt F]	0.40	—	
Digital-to-	A1S62DA	Analog output, 2 channels	32 [32pt F]	0.80	—	
analog	A1S68DAV	0 to ± 10V, analog output, 8 channels	32 [32pt F]	0.65	_	
converter module	A1S68DAI	0 to ± 20mA, analog output, 8 channels	32 [32pt F]	0.85	—	
Temperature-	A1S62RD3	Pt100 (3 wire type) input, 2 channels	32 [32pt F]	0.54	—	
digital	A1S62RD4	Pt100 (4 wire type) input, 2 channels	32 [32pt F]	0.44	—	
converter module	A1S68TD	Thermocouple input, 8 channels	32 [32pt F]	0.32	—	
Analog I/O module	A1S63ADA	Analog input 2 channels, analog output 1 channel	32 [32pt F]	0.80	-	
	A1S66ADA	Analog input 4 channels, analog output 2 channels	64 [64pt F]	0.16	—	
Temperature	A1S64TCTT-S1	Thermocouple input, 4 channels	32 [32pt F]	0.42	_	1
control module	A1S64TCTTBW-S1	Thermocouple input, 4 channels, with heater wire breakage detection function	32 [32pt F]	0.42	—	
	A1S64TCRT-S1	Pt100 input, 4 channels	32 [32pt F]	0.42	1_	
	A1S64TCRTBW-S1	Pt100 input, 4 channels, with heater wire breakage detection function	32 [32pt F]	0.42	-	
	A1S64TCTT-S2	Thermocouple input, 2 channels	32 [32pt F]	0.28		
	A1S64TCTTBW-S2	Thermocouple input, 2 channels, with	32 [32pt F]	0.28		
		heater wire breakage detection function				
	A1S64TCRT-S2	Pt100 input, 2 channels	32 [32pt F]	0.28		
	A1S64TCRTBW-S2	Pt100 input, 2 channels, with heater wire breakage detection function	32 [32pt F]	0.28	_	
Pulse catch	A1SP60	Pulse catch input	16 [16pt Y]	0.055	—	
Analog timer	A1ST60	8 timer points	16 [16pt Y]	0.055	_	
Interrupt module	A1SI61	Interrupt input, 16 points	32 [32pt F]	0.057	_	
Computer link	A1SJ71UC24-R2	RS-232 1 channel	32 [32pt F]	0.10	—	
module	A1SJ71UC24-R4	RS-422/RS-485 1 channel	32 [32pt F]	0.10	—	
	A1SJ71UC24-PRF	RS-232 1 channel	32 [32pt F]	0.10	—	
Positioning	A1SD70	Analog output, 1 axis	48 [first half 16pt S	0.30	—	
module	A1SD71-S2	Pulse train output, 2 axes	, latter half 32pt F]	0.80	—	
	A1SD71-S7	Pulse output, 2 axes, manual pulse generator usable		0.80	-	
	A1SD75M1	SSC network compatible, 1 axis	32 [32pt F]	0.70	_	
	A1SD75M2	SSC network compatible, 2 axes				
	A1SD75M3	SSC network compatible, 3 axes				
	A1SD75P1-S3	Pulse train output, 1 axis	32 [32pt F]	0.70	—	
	A1SD75P2-S3	Pulse train output, 2 axes				
	A1SD75P3-S3	Pulse train output, 3 axes				
	A1SD774M	4 axes, motion control module	32 [32pt F]	0.90	—	
MELSECNET/ MINI-S3	A1SJ71PT32-S3	Master module for optical/twisted pair cables	32/48 [32/48pt F]	0.35	—	
master module	A1S71T32-S3	Master module for twisted pair cables only		0.30		
MELSECNET	A1SJ71AP21	For master/local, optical SI/QSI cable	32 [32pt F]	0.33	—	
II module	A1SJ71AP21-S3	For master/local, optical GI cable	32 [32pt F]	0.33	—	
	A1SJ71AR21	For master and local, coaxial cable	32 [32pt F]	0.33	—	
MELSECNET/ B module	A1SJ71AT21B	For master/local, twisted pair cable	32 [32pt F]	0.66	—	
MELSECNET/ 10 module	A1SJ71LP21	SI/QSI Optical Loop, For Control/Normal/Master	32 [32pt F]	0.65	_	
	A1SJ71LP21GE	GI62.5 Optical Loop, For	32 [32pt F]	0.65	-	
		Control/Normal/Master				
	A1SJ71BR11	Coaxial bus, For Control/Normal/Master	32 [32pt F]	080	—	
Ethernet	A1SJ71E71-B2-S3	10BASE2	32 [32pt F]	0.52	_	1
interface	A1SJ71E71-B5-S3	10BASE5	32 [32pt F]	0.35	—	1
module						

Symbol examples in Number of Points Occupied (I/O Allocation) field X: input, Y: output, F: special, S: vacant



Applicable Model List

	_		Number of Points	Current C	onsumption (A)	
Product Type		Description	Occupied [I/O Allocation]	5VDC	24VDC	Remarks
CC-Link module	A1SJ61BT11	Master station, local station	32 [32pt F]	0.40	-	
Intelligent communication	A1SD51S BASIC program module		32 [32pt F]	0.40	-	
Position detection module	A1S62LS	Absolute position detection by dedicated sensor	32 [32pt F]	0.55	-	
PLC simple monitoring module	A1SS91	PLC simple monitoring module	16 [16pt Y]	0.080	-	
Memory card interface module	A1SD59J-S2	Memory card interface module	32 [32pt F]	0.05 (Note1)		
ID interface	A1SJ71ID1-R4	1 connectable reader/writer	32 [32pt F]	0.25	0.1	
module (Note 2)	A1SJ71ID2-R4	2 connectable readers/writers	32 [32pt F]	0.25	0.15	
(Note 2)	A1SD32D1	1 connectable reader/writer	32 [32pt F]	0.25	0.15	
	A1SD32D2	2 connectable readers/writers	32 [32pt F]	0.25	0.30	
MELSEC-I/O LINK	A1SJ51T64	Max. 16 master stations, total of 128 I/O points	64 [64pt Y]	0.115	0.09	
B/NET module	A1SJ71B62-S3	For B/NET transmission terminal control	32 [32pt F]	0.08	—	
S-LINK master	A1SJ71SL92	For control of S-LINK equipment, max. 128 control I/O points	32 [32pt F]	0.20	—	
JEMANET (JPCN-1) master module	A1SJ71J92-S3	JEMANET (JPCN-1) interface, for master station	32 [32pt F]	0.40	-	
Profibus	A1SJ71PB96F	Profibus-FMS Client/Server	32 [32pt F]	0.56	-	Yes
	A1SJ71PB92D	Profibus-DP Master	32 [32pt F]	0.56	—	No
DeviceNet	A1SJ71DN91	DeviceNet Master	32 [32pt F]	0.24	—	No
Modbus	A1SJ71UC24-R2-S2	Modbus RTU/ASCII slave, RS-232	32 [32pt F]	0.10	—	Yes
	A1SJ71UC24-R4-S2	Modbus RTU/ASCII slave, RS-422/485	32 [32pt F]	0.10	—	Yes
Blank cover	A1SG60	Blank cover for I/O slot	16 [16pt vacant]	—	—	
	A1SG62	16/32/64-point dummy module	16/32/64 [16/32/64pt X]	0.060	-	

Symbol examples in Number of Points Occupied (I/O Allocation) field X: input, Y: output, F: special, S: vacant

For details of the performance specifications of the AnS series modules, refer to the MELSEC-A small/mid-scale-compatible type catalog. Note 1: Current consumption is the value when A1SD59J-MIF is loaded.

Note 2: Please confirm compliance of the ID products to local laws and regurations for radio transmitting devices.

System Configuration

System Configuration

The A mode uses the AnS series modules.

Use the main and extension bases and extension cables designed for Q series. You cannot use the AnS series main and extension bases and extension cables.

Basic configuration

Load the AnS series modules on the QA1S35B or QA1S38B main base unit and QA1S65B and QA1S68B extension base units.



Instructions for system configuration

- The total number of I/O, special function and network modules that may be loaded into the main and extension bases is up to 64.
- (2) Up to 7 extension bases may be connected. (Up to 8 bases including the main)
- (3) The overall distance of extension cables is within 13.2m (43.28ft.).
- (4) Modules having restrictions on the number of modules loaded

Module	Modules	Loaded
MELSECNET/10 network module: A1SJ71LP21, A1SJ71BR11	Up to 4	Up to a total of 4
MELSECNET(II)/B data link module: A1SJ71AP21, A1SJ71AR21, A1SJ71AT21B	Up to 2	
Interrupt module A1SI61	1	
AnS series special function module (Note 1)	Up to a total of 6	

Note 1: In the AnS series, the following modules have restrictions on the number of modules loaded. The other modules have no restrictions on the number of modules loaded.

MODEL SELECTION

AnS modules having restrictions on the number of modules loaded

Product	Туре
Ethernet interface module	A1SJ71E71-B2/B5-S3
Computer link module	A1SJ71UC24-R2/R4/PRF
CC-Link module (in intelligent mode)	A1SJ61BT11
Intelligent communication module	A1SD51S
ID interface module	A1SJ71ID1-R4
	A1SJ71ID2-R4
Profibus module	A1SJ71PB96F
Modbus module	A1SJ71UC24-R2-S2
	A1SJ71UC24-R4-S2
JEMA network (JPCN-1) master module (Only when using GET/PUT service)	A1SJ71J92-S3

(5) When any of the network modules given in the following table is used to read/write the PLC data from an external device, the accessible device ranges are restricted.

Applicable network module

Product	Туре
MELSECNET/II	A1SJ71AP21, A1SJ71AR21, A1SJ71AT21B
Ethernet interface module	A1SJ71E71-B2/B5-S3
Intelligent communication module	A1SD51S
ID interface module	A1SJ71ID1-R4
	A1SJ71ID2-R4
JEMA network (JPCN-1) master module	A1SJ71J92-S3
(Only when using GET/PUT	
service)	

Accessible device ranges

De	vice Type	Range
X		0-7FF
Y		0-7FF
M/L/S		0-8191
В		0-FFF
Special M		9000-9255
Т	Contact	0-2047
	Coil	0-2047
	Current value	0-2047
	Set value	0-2047
С	Contact	0-1023
	Coil	0-1023
	Current value	0-1023
	Set value	0-1023
D		0-6143
W		0-FFF
F		0-2047
R		0-8191
Special D		9000-9255

(6) Among the GOT series graphic operation terminals, the GOT-A900/800 series are usable. Note that bus connection is not available.

Overview

MODEL SELECTION CPU

The A mode CPU modules are designed to improve the processing capabilities of the AnS series system by applying the high-speed, high-performance CPU processing technology developed for the Q series to the conventional AnS series.

Functions and Performance Capabilities Extended in A Mode

The following functions and performance capabilities are extended by changing the AnS series CPU module for the A mode CPU.

Increased processing speeds

The instruction processing times have been improved significantly as compared to the AnS series CPU.

Processing speed comparison

CPU	LD	MOV	PC MIX Value
Q02HCPU-A	34ns	204ns	5.3
Q06HCPU-A			
Q02CPU-A	79ns	474ns	2.2
A2USHCPU	90ns	540ns	2.2
-S1			
A2ASCPU-S1	200ns	1,200ns	0.9
A2ASCPU			
A2SHCPU	250ns	9,100ns	0.61
A1SHCPU	330ns	11,800ns	0.46
A1SJHCPU			

The PC MIX value is the average number of instructions such as the basic and data processing instructions executable in $1 \mu s$. A larger value indicates a higher processing speed.

Increased program capacities

Using the A mode CPU can increase the program capacities.

	Program	capacity	/ com	narison
•	rogram	capacity		panson

CPU	Program Capacity
Q06HCPU-A	30k step × 2
Q02HCPU-A	28k step
Q02CPU-A	
A2USHCPU-S1	30k step
A2ASCPU-S1	14k step
A2ASCPU	
A2SHCPU	14k step
A1SHCPU	8k step
A1SJHCPU	

Increased number of I/O points

Using the A mode CPU, you can increase the number of I/O points up to 4096 points (8192 points when used with a remote I/O network).

I/O point comparison

CPU	I/O Points (Note1)	Total I/O Points (Note2)
Q02CPU-A Q02HCPU-A Q06HCPU-A	4096	8192
A2USHCPU-S1 A2ASCPU-S1	1024	8192
A2ASCPU	512	8192
A2SHCPU	512	2048
A1SHCPU A1SJHCPU	256	2048

Note 1: Number of CPU I/O points controlled on the main and extension bases.

Note 2: Total number of CPU I/O points controlled on the main and extension bases and remote I/O points controlled in the remote I/O network.

Fast communication with peripheral devices

Though the programming interface of the conventional AnS series CPU was RS422 (9.6k or 19.2kbps), the A mode CPU uses RS-232 to be compatible with the maximum communication speed of 115.2kbps. It facilitates connection with a personal computer, already acting as a general programming device, to shorten program write/read time.

Increased number of extension bases

In the conventional AnS series, the number of extension bases allowed was only 1. However, the A mode CPU accepts up to seven extension bases (eight bases including the main and having up to 64 I/O slots). You can increase the I/O points of the current AnS series system. Also, you can increase the overall distance of extension cables up to 13.2m (43.28ft.).

Standard-equipped flash ROM

The CPU has a built in flash ROM, allowing easy storage of programs in ROM.

Standard-equipped SRAM memory card loading slot

Max. 152k points of extended file register area can be secured in the SRAM card. When it is used with the builtin RAM of max. 64k points, a total of 216k points of file registers are available.

Note 3: The number of file register points that can be secured in the built-in RAM changes with the program size, etc. Check the number of file register points that can be secured in the section of "CPU Built-In Memories/Memory Cards".

1ms-increment timer instruction usable

Making setting with the new dedicated instruction "ZHTIME" makes the 1ms-increment timer instruction usable.

Appearance

The appearances and part names of the CPUs will be described.

Q02CPU-A





Q02HCPU-A, Q06HCPU-A



Note 1: In the A mode CPU module, the USB port cannot be used.

Performance Specifications

MODEL SELECTION CPU

	144	m	Q02CPU-A	Q02HCPU-A	Q06HCPU-A	Domorko			
Cont					Remarks				
	rol system		Refresh mode (partial refresh						
		language		nguage dedicated to sequence control (ladder, list, SFC)					
	essing sp		· · · · ·						
	uction)		79 (ns/step)	34 (ns/step)					
	ory capac	city	144k byte built-in RAM + 144k	byte standard ROM (built-in)	vte standard ROM (built-in)				
		Main			20k stans				
Prog capa		program	28k steps		30k steps				
сара	icity	Subprogram	No		30k steps				
		device points		nber of points usable in program		Note that device usable			
Num	ber of I/O		4096 (points) (number of point	s controllable on main and exter	nsion bases)	ranges are limited			
		l relay [M]	7144 (M0 to M999, M2048 to M	/8191))	depending on the programming software used			
	(points)			,	- Total of 8192 when M, L and	programming software used			
	Latch re (points)		1048 (L1000 to L2047)		S are shared				
		lay [S] (points)	0 (no initial status)		-]				
		ay [B] (points)	8192 (B0 to B1FFF)						
	2		2048 (default 256 points)						
					7S				
	Timer [T] (points)		ial) Setting time 0.1 to 3276.7					
				Count value setting by wo					
			• This timer (no initial)	Setting time 0.001 to 32.7 timers can be used by ZH					
			1024 (default 256 points)	timers can be used by Zi					
Number of device points) Setting range 1	to 32767 times				
bo	Counte	r [C] (points)	 Interrupt counters (no initial). 						
e			Extended counters (C256 to	C1023)) Count value set	by word devices (D, W, R)				
levi		gister [D]	8192 (D0 to D8191)						
of c	(points)		0.02 (20 10 20 10 1)						
ē		gister [W]	8192 (W0 to W1FFF)						
dm	(points)) ciator [F]	· · · ·						
Ŋ	(points)		2048 (F0 to F2047)						
	File register [B]								
	(points)		Max. built-in 64k points + mem	ory card 152k points					
	Accumi	ulator [A]	2 (A0, A1)						
	(points)		2 (A0; A1)						
		egister [Z]	14 (V, V1 to V6, Z, Z1 to Z6)						
	(points)								
		[P] (points)	256 (P0 to P255)						
	(points)	ot pointer [I]	32 (10 to 131)						
		/ I relay [M]							
	(points)		256 (M9000 to M9255)						
	/	/ I register [D]	256 (D0000 to D0255)			1			
	(points))	256 (D9000 to D9255)						
	ment (poi		Max. 4032 (set in 64 point incr	,					
Exte	nded com	nment (points)	Max. 3968 (set in 64 point incr						
STO	P→RUN	output mode		tatus at STOP is re-output (defa	ult)/output after operation				
switc	ching		execution						
Self-	diagnostic	c function	Watchdog error monitor (watch						
	5		Memory, CPU, I/O, battery and						
of eri		de at the time	STOP/CONTINUE selection						
	n (power f	failure							
	pensation		L1000 to L2047 (default) (Latc	h range setting can be made for	L, B, T, C, D, W)				
Remote RUN/PAUSE 1 point can be set to each RUN and PAUSE cor			and BALISE contacts from VO	1666					
conta				N AND FAUSE CONTACTS FROM XU-	911 F F.				
	title regis		Yes (128 characters)						
	vord regis		Yes						
	issignmen	nt	· · · · · ·	and module type can be registe	ered				
Step run Sequence program operation execu									
	rupt proce		Interrupt by interrupt module of	, ,					
Cons	stant scan	n (ms)	10 to 190 (setting can be made	e in TUMS increments)		l			



Item	Q02CPU-A	Q02HCPU-A	Q06HCPU-A	Remarks		
Clock function	Year, month, day, hour, minute (Automatic leap year judgmen Accuracy –3.18 to +5.25 (TYP Accuracy –3.93 to +5.25 (TYP Accuracy –14.69 to +3.53 (TY					
5VDC internal current consumption (A)	0.60	0.60 0.64				
Weight (kg (lb))	0.20 (0.44)	0.20 (0.44)				
External dimensions (mm (inch))	98 (3.86) × 27.4 (1.08) × 90 (3.55)					



Battery

The battery built in the CPU module is used to back up the programs and various data stored in the RAM memory of the CPU module during a power failure and to back up the clock element continuously during a power failure. The battery is not used while 5VDC is supplied from the power supply module. The battery life depends on the total power failure time when 5VDC is not supplied from the power supply module.

Note that the SRAM card contains a battery in itself and is independent of the consumption of the battery.

Battery life

	Total Power Fail	Backup Time		
CPU Type	Guaranteed value	Actual value	after Battery Error ON (Hours)	
Q02CPU-A	5433	13120	120	
Q02HCPU-A	2341	6435	120	
Q06HCPU-A				

Note 1: If the total power failure time is less than the above value, the battery must be changed every 10 years as a guideline.

Manuals

The following manuals are related to the A mode CPU.

Name	Remarks
QCPU-A (A Mode) User's Manual	Packed with QA1S3 B
(Hardware)	main base
QCPU-A (A Mode) User's Manual (Details)	Optional

Use the ACPU Programming Manual for programming.



CPU Built-in Memories/Memory Cards

Overview

This section describes the memory capacities of PLC memories which store user-created data, such as programs and device comment files, and how to calculate necessary memory capacities.

Memory Capacities

The A mode CPU contains the RAM memory and ROM memory and allows a RAM memory card to be loaded as external memory. The following diagram shows the memory makeup and stored data.



- Note 1: Online status latch and online sampling trace use the memory areas secured as extended file registers.
- Note 2: Extended comments are stored in the built-in RAM if it has free space, but if it does not, they use the memory area secured as the extended file registers on the RAM memory card.

Туре	Built-In RAM Memory Capacity (Bytes)	Built-In ROM Memory Capacity (Bytes)
Q02CPU-A	144k	144k
Q02HCPU-A		
Q06HCPU-A		

Built-in RAM

The A mode CPU module has 144k byte user memory RAM, where user data such as programs are stored.

Built-in ROM

The A mode CPU module has 144k byte user memory ROM to ensure ease of storing programs into ROM. Note that the program stored in ROM is transferred to the builtin RAM at power-on or key reset and run in RAM.

RAM memory card (optional)

Memory used in the memory card interface of the CPU. By loading the memory card, the memory capacity can be increased to 448k bytes. The RAM card can be used as extended file registers.

Туре	Usable Memory Capacity (Bytes)	Memory Capacity of Standard RAM Memory + Memory Card (Bytes)
Q2MEM-1MBS	304k	448k

MODEL SELECTION MEMORY

CPU Built-in Memories/Memory Cards

User memory area makeup example in A mode



Note 1: Subprogram may be used by Q06HCPU-A only.

CPU Built-in Memories/Memory Cards

Memory Capacity Calculation

Use the user memory after determining the stored data types and memory capacities by parameter setting. Use the following table to calculate the memory capacities.

<For Q02CPU-A/Q02HCPU-A>

	Item	Setting Increments	Capacity Calculation Method (Bytes)	Max. Setting Capacity (Bytes)		Remarks	
Parameter		—	3k	3k		Total 144k	
Main program	T/C set value	—	1k	1k			
	Sequence program	1k steps	Number of steps x 2	56k	Total		
	Microcomputer program	1k bytes	Set number of bytes	54k	60k		SFC only
MELSECNET/10	parameter	—	Note 1	16k			
Extended commer	nt	1k bytes	Set number of bytes (1k bytes = 64 points)	63k			(Note 3)
Extended file regis	ster (built-in)	8k points	Number of file register points x 2	128k			
File register		1k points	Number of file register points x 2	16k			
Comment		1k bytes	Set number of bytes (1k bytes = 64 points)	64k			(Note 3)
Extended file regis	ster (memory card)	8k points	Number of file register points x 2	302k			

<For Q06HCPU-A>

	Item	Setting Increments	Capacity Calculation Method (Bytes)	Max	Max. Setting Capacity (Bytes)		Remarks
Parameter		—	3k	3k		Total 144k	
Main program	T/C set value	—	1k	1k			
	Sequence program	1k steps	Number of steps x 2	60k	Total		
	Microcomputer program	1k bytes	Set number of bytes	58k	60k		SFC only
MELSECNET/10	parameter	—	Note 1	16k			
	T/C set value	1k bytes	1k	1k			
	Sequence program	1k steps	Number of steps x 2	58k			
	Microcomputer program	—	5k	5k			
Extended comme	nt	1k bytes	Set number of bytes (1k bytes = 64 points)	63k			(Note 3)
Extended file regis	ster (built-in)	8k points	Number of file register points x 2	128k			
File register		1k points	Number of file register points x 2	16k		1	
Comment		1k bytes	Set number of bytes (1k bytes = 64 points)	64k]	(Note 3)
Extended file regis	ster (memory card)	8k points	Number of file register points x 2	302k			

Note 1: The capacity used changes with the settings of the MELSECNET/10 network parameters. The area of the network parameter

capacity is secured in 2k byte increments on the basis of the total capacity of their settings.

The memory capacities of the network parameters are as follows.

Item	Memory Capacity (Bytes)
Internal data	30
Routing parameter	390
Inter-data link transfer parameter	246
Common parameter	2164/module (Note 2)
Refresh parameter	92/module
Station-specific parameter	1490/module

Note 2: 2722 bytes for remote master station.

The MELSECNET/10 network parameter capacity is determined by the above calculated memory capacity total.

Total Capacity of Setting	Capacity of Network Parameter Setting
30 to 2048 bytes	2k bytes
2049 to 4906 bytes	4k bytes
4097 to 6144 bytes	6k bytes
6145 to 8192 bytes	8k bytes
8193 to 10240 bytes	10k bytes
10241 to 12288 bytes	12k bytes
12289 to 14336 bytes	14k bytes
14337 to 16384 bytes	16k bytes

Note 3: When the comment and extended comment capacities are set, 1k bytes are occupied for each capacity for the system. Note 4: Online sampling trace and online status latch data are stored in the extended file registers.

MODEL SELECTION NETWORK SPECIAL FUNCTION I/O

Network/Special Function Modules I/O Modules

Network

The A mode can use the same network system as the AnS series.

You can use MELSECNET/B, MELSECNET/(II), CC-link and MELSECNET/MINI modules without any changes, to say nothing of MELSECNET/10. Refer to the applicable model list for the usable modules.

The Q2AS/Q series network modules cannot be used with the A mode.

Special Function Modules

Use the AnS series special function modules with the A mode. Refer to the applicable model list for the usable modules.

You cannot use the intelligent function modules designed for Q2AS/Q series.

I/O Modules

Use the AnS series I/O modules with the A mode. You cannot use the I/O modules designed for Q series.

For the specifications of the AnS series modules, refer to the MELSEC-AnS PLC catalog.

Current Consumption Calculation

Overview

The PLC system operates on 5VDC supplied from the power supply module.

The sum of 5VDC current consumption values of the CPU, I/O, intelligent function and network modules loaded on one base unit should not exceed the rated output current of the power supply module. If so, the number of modules loaded on the base unit must be reduced.

Calculation Method

Make sure that the current consumption is as indicated in the following relational expression.

(Rated output current of power supply module) \geq (sum of 5VDC current consumption values of modules)

Power supply module, e.g. A1S61PN, A1S62PN		Base unit, e.g. QA1S35B, QA1S65B
		CPU module, e.g. Q02CPU-A, Q06HCPU-A
	⊢	I/O module, e.g. A1SX10, A1SY10
		Special function module, e.g. A1SD61, A1SD75

Refer to "Applicable Equipment List" for the current consumption value of each module.

(Calculation example)

System configuration	۱				(<u> </u>	Base uni	t: QA1S3	8B)
CPU module Q02CPU-A Power supply module A1S61PN	Input module A1SX40	Input module A1SX40	Output module A1SX40	Output module A1SX40	Output module A1SY40	Output module A1SY40	High-speed counter module A1SD61	Positioning module A1SD75P1-S3

Rated output current of power supply module

Туре	Rated Output Current (A)		
A1S61PN	5		

5VDC current consumption of each module

Туре	Module Type	5VDC Current Consumption (A)
Q02CPU-A	CPU module	0.600
QA1S38B	Base unit	0.118
A1SX40	Input module	0.050
A1SY40	Output module	0.270
A1SD61	High-speed counter module	0.350
A1SD75P1-S3	Positioning module	0.700

Sum of 5VDC current consumption values

=0.600+0.118+(0.050×2)+(0.270×4)+0.350+0.700 =2.948(A)

Rated output current of A1S61PN [5(A)] > sum of 5VDC current consumption values [2.948(A)]

Hence, this system has no current consumption problem.

Overview

The power supply module is designed to supply 5VDC to each PLC module loaded on the base unit. Note that the power supply module type that may be loaded depends on the base unit. Use any of the AnS series A1S61PN, A1S62PN and A1S63PN power supply modules with the QA1S3 B or QA1S6 B where the AnS series modules will be loaded.

Performance Specifications

Performance specifications

	Item	A1S61PN	A1S62PN	A1S63P	
Applicable base	unit	QA1S3 B, QA1S6 B			
Input power sup	ply	100-240VAC + 10%/-15%	100-240VAC + 10%/-15%		
Input frequency		50/60Hz ± 3Hz		—	
Input voltage dis	tortion factor	Within 5%			
Input max. appa	rent power	105VA		41W	
Inrush current		20A within 8ms		81A within 1ms	
Rated output	5VDC	5A	3A	5A	
current	24VDC	—	0.6A	—	
Overcurrent	5VDC	5.5A or more	3.3A or more	5.5A or more	
protection	24VDC	—	0.66A or more	—	
Overvoltage pro	tection	5.5 to 6.5V			
Efficiency		65% or more	65% or more		
Permissible inst failure time	antaneous power	Within 20ms		Within 10ms	
Dielectric withsta	and voltage	Across inputs/LG-outputs/FG	Across inputs/LG-outputs/FG 2,830VAC rms/3 cycles (altitude 2000m (6557.38ft.))		
Insulation resista	ance	Inputs-outputs (LG/FG separated 10M Ω or more by 500VDC insul), inputs-LG/FG, outputs-LG/FG	5M Ω or more by 500VDC insulation resistance tester	
Noise immunity		By noise simulator of 1,500Vp-p r 60Hz noise frequency	By noise simulator of 1,500Vp-p noise voltage, 1μ s noise width and 25 to		
Operation indica	ition	LED indication (Lit at 5VDC output	ut)		
Fuse		Built-in (unchangeable by user)			
Terminal screw	size	M3.5 × 7			
Applicable wire	size	0.3 to 2mm ²			
Applicable crimp	oing terminal	RAV1.25-3.5, RAV2-3.5			
Applicable tighte	ening torque	59 to 88N / cm			
Weight (kg (lb))		0.60 (1.32)		0.50 (1.1)	



Base Units/Extension Cables

Base Units

The base unit serves to supply the CPU, I/O and special function modules with 5VDC generated by the power supply module. It also serves to exchange signal data among the CPU, I/O and special function modules. For combination for use of the base units, refer to the section of system configuration.

Model list

Main base unit

Туре		QA1S33B	QA1S35B	QA1S38B
Number of I/O modules loaded		3	5	8
Applicable I/O modules		AnS series		
External	W	255 (10.05)	325 (12.81)	430 (16.94)
dimensions (mm (inch))	н	130 (5.12)		
Weight (kg (lb))		0.57 (1.25)	0.75 (1.65)	1 (2.2)

<QA1S38B, QA1S35B accessories>

Product	Description
Dustproof cover	For AnS I/O module
Base mounting	M5×25 4 pcs.
screw	
Manual	QCPU-A (A Mode) User's Manual
	(Hardware)

Extension base unit

Туре	QA1S35B	QA1S38B	
Number of I/O modules loaded	5	8	
Applicable I/O modules	AnS series		
External dimensions	315(12.41)W	420(16.55)W	
(mm (inch))	×130(5.12)H	×130(5.12)H	
Weight (kg (lb))	0.75 (1.65)	1 (2.2)	

<QA1S65B, QA1S68B accessories>

Product	Description
Base mounting	M5×25 4 pcs.
screw	

Handling instructions

(1) When mounting the base unit into a control panel, etc., leave a 30mm (1.18inch) or more clearance between its top and the panel structure or parts to ensure ease of module replacement and reduce the influence of radiated noise or heat.

Also leave 20mm (0.79inch) or more clearances to the left and right of the PLC.

(2) Mount the base unit on a flat surface to prevent possible flexing of the printed circuit boards.

Extension Cables

An extension cable is used for connection between the main and extension base units, or between the extension base units.

The same extension cables are used for both the Q and A modes.

Appearance



Model list

Туре	QC06B	QC12B	QC30B	QC50B	QC100B
Cable length	0.6	1.2	3	5	10
(m (inch))	(0.02)	(0.05)	(0.12)	(0.20)	(0.39)
Usable base unit	Main base unit (QA1S35B, QA1S38B)				
	Extension base unit (QA1S65B, QA1S68B)				
Weight (kg (lb))	0.16	0.22	0.4	0.6	1.11
	(0.35)	(0.48)	(0.88)	(1.32)	(2.42)

Directions for use

When the above extension cables are used together, the overall distance of the extension cables should be within 13.2m (43.28ft.).

MODEL SELECTION ACCESSORIES

Accessories: Batteries, Connectors

Batteries/Q6BAT

Overview

The Q6BAT battery is loaded into a CPU module and used to back up the built-in RAM memory of the CPU module during power failure.

The Q2MEM-BAT battery is used to back up the Q2MEM-1MBS memory card at a power failure.

Appearance



Specifications

Туре	Q6BAT	Q2MEM-BAT
Nominal voltage	3VDC	3VDC
Battery type	Manganese dioxide	Graphite fluoride
	lithium battery	lithium battery
Current capacity	1800mAh	48mAh
Storage life (normal	10 years	4 years
temp.)		
Applicable model	Q02/Q02H/	Q2MEM-1MBS
	Q06HCPU-A	

Connectors/A6CON

The A6CON is an external wiring connector for connector type I/O module. These connectors are classified into six different types according to the soldering, crimp-contact and pressure-displacement types and I/O module types.

Appearance

A6CON1, A6CON2, A6CON3



A6CON1E, A6CON2E, A6CON3E



Model list

Туре	A6CON1	A6CON2	A6CON3	
Connector type	Soldering type	Crimp-contact type	Pressure- displacement type	
I/O module type	Positive common (sink) type input module, sink type output module			
Applicable wire size	0.3mm ²	AWG#24 to 28	AWG#28, AWG#30	

• Crimp-contact tool for A6CON2:

• Pressure-displacement tool for A6CON3:

FCN-367T-T012/H (locator plate) FCN-707T-T001/H (cable cutter) FCN-707T-T101/H (hand press)

Туре	A6CON1E	A6CON2E	A6CON3E
Connector type	Soldering type	Crimp-contact type	Pressure- displacement type
I/O module type	Negative common source type output	n (source) type inpu ut module	ut module,
Applicable wire size	0.3mm ²	AWG#20 to 24	AWG#28, AWG#30

Crimp-contact tool for A6CON2E

• Pressure-displacement tool for A6CON3E

91257-1 (die set) 91220-1 (cable cutter) 91085-2 (hand mini-press)

3-23

SELECTION ACCESSORIES

MODEL

Connectors, Terminal Block Convertor Modules

Connector/Terminal Block Convertor Modules/A6TB

The connector/terminal block converter module is designed to convert the connector of a connector type I/O module into a terminal block to ensure ease of external wiring.

To use this module, plug a dedicated cable to the connector of an I/O module and plug the opposite side of that cable to the connector/terminal block convertor module. Perform external wiring at the terminal block of the connector/terminal block convertor module.

Appearance



Model list

(1) Connector/terminal block convertor modules

Туре	Description	Weight (kg (lb))
A6TBXY30	For positive common (sink) type input modules and sink type output modules (standard type)	0.4 (0.88)
A6TBXY54	For positive common (sink) type input modules and sink type output modules (2-wire type)	0.5 (1.1)
A6TBX70	For positive common (sink) type input modules (3-wire type)	0.6 (1.32)
A6TBX36-E	For negative common (source) type input modules (standard type)	0.4 (0.88)
A6TBY36-E	For source type output modules (standard type)	0.4 (0.88)
A6TBX54-E	For negative common (source) type input modules (2-wire type)	0.5 (1.1)
A6TBY54-E	For source type output modules (2-wire type)	0.5 (1.1)
A6TBX70-E	For negative common (source) type input modules (3-wire type)	0.6 (1.32)

(2) Cables			
Туре	Description	Weight (kg (lb))	Applicable Model
AC05TB	0.5m (1.64ft.) for sink	0.17	A6TBXY36
	modules	(0.37)	A6TBXY54
AC10TB	1m (3.28ft.) for sink	0.23	A6TBX70
	modules	(0.51)	
AC20TB	2m (6.56ft.) for sink	0.37	
	modules	(0.81)	
AC30TB	3m (9.84ft.) for sink	0.51	
	modules	(1.12)	
AC50TB	5m (16.39ft.) for sink	0.76	
	modules	(1.67)	
AC80TB	8m (26.23ft.) for sink	1.2	
	modules	(2.64)	
	(common current not		
	exceeding 0.5 A)		
AC100TB	10m (32.79ft.) for sink	1.5	
	modules	(3.3)	
	(common current not		
	exceeding 0.5 A)		
AC05TB-E	0.5m (1.64ft.) for source	0.17	A6TBX36-E
	modules	(0.37)	A6TBY36-E
AC10TB-E	1m (3.28ft.) for source	0.23	A6TBX54-E
	modules	(0.51)	A6TBY54-E
AC20TB-E	2m (6.56ft.) for source	0.37	A6TBX70-E
	modules	(0.81)	
AC30TB-E	3m (9.84ft.) for source	0.51	
	modules	(1.12)	
AC50TB-E	5m (16.39ft.) for source	0.76	
	modules	(1.67)	

Directions for use

The tightening torque of the terminal screws (M3.5 screws) of the terminal blocks is 78.4N/cm (8kgf/cm).

Connection diagrams

Refer to "CHAPTER 2 Q MODE" - "MODEL SELECTION" - "Accessories".

MODEL SELECTION EXTERNAL DIMENSIONS

External Dimensions



Sequence Programs

Software

To create the sequence programs for the A mode CPU, you can continue to use the GPP function software package (hereafter referred to as "GPP") and programming unit (hereafter referred to as the "PU") which could be used with the AnS conventionally. GPP permits sequence programming in ladder, list and SFC (sequential function chart) languages, entry of comments to the I/O/CPU module internal relays, registers and others, network parameter setting, sequence program operating status monitoring, network operating status monitoring, forced data changes, I/O signal ON/OFF, and others.

The PU allows sequence programming in list, sequence program operating status monitoring, forced data changes, I/O signal ON/OFF, and others.

They can execute the functions which could be performed with the conventional AnS series.

Usable GPP and CPU types

The following table lists the usable software and the CPU types selected for use.

Peripheral Device	GPP Function Software Package	CPU Type
A6PHP	SW3-GPPAEE	A3H
	SW4GP-GPPAEE	A3A
	SW5GP-GPPAEE	A3A
A6GPP	SW3-GPPAEE	A3H
	SW4GP-GPPAEE	A3A
	SW5GP-GPPAEE	A3A
A6HGP	SW3-GPPAEE	A3H
DOS	SW IVD-GPPA	A4U
Windows personal	SW D5C/F-GPPW-E	A4U
computer	(Note 1)	
	SW D5C-GPPW-E	Corresponding
	(Note 2)	type

Note 1: For SW2 software or earlier

Note 2: For SW4 software or earlier, the A mode CPU type is listed, so choose the corresponding CPU type.

Note 3: When the CPU type chosen is A3A/A3H, there are restrictions on the device memory capacities usable within programs.

Usable GPP and CPU types

Туре	Restrictions	
A7PU	Hand-held connection possible	
A7PUS		

Instructions Different in Specifications

Instructions different from those of AnS

The following table lists the instructions that differ between the A mode and AnS.

Class	Instruction Name
Failure check	СНК
Interrupt disable	DI
Interrupt enable	EI
Microcomputer program call (Note 1)	SUB, SUBP

Note 1: When a PID, function arithmetic or other utility program is used, use the instructions after replacing them with the A mode dedicated instructions.

Instructions added to the A mode

The following table gives the dedicated instruction added to the A mode.

Class	Instruction Name
1ms timer setting	ZHTIME

PROGRAMMING

Peripheral Devices

Overview

The A mode CPU module may be programmed with the device used for programming the conventional AnS series or on a Windows personal computer. The A mode CPU module is equipped with an RS-232 interface.

RS-232 Connection

Connection configuration diagram

The following diagram shows a configuration for connection with a personal computer by an RS-232 interface.



Note 1: In the A mode, the USB port cannot be used.

PROGRAMMING

Peripheral Devices

RS-232 cable

Туре	QC30R2
Length	3m (9.84ft.)
	Personal computer side: 9-pin D-Sub PLC side: 6-pin Mini-DIN

RS-232 cable connection example

(For connection of Windows and DOS/V personal computer)



Note: Do not make connection to the PLC side pin number 4.

Instructions

- The A mode CPU can communicate at up to 115.2kbps, but depending on the performance of the personal computer connected, it may not be able to communicate at 115.2kbps. If so, choose any of 57.6k, 38.4k, 19.2k and 9.6kbps communication speeds.
- (2) When using the QC30R2 (3m (9.84ft.) cable), we have confirmed that communication can be made at 115.k2kbps.
- (3) The usable communication speed and distance of the cable fabricated by the user should be checked by the user.

RS-232/RS-422 conversion cables (introduced products)

When the dedicated peripheral device such as the A6GPP is used, the RS-232/RS-422 conversion cables given below are usable.

Cable Type	Specifications	Peripheral Device Type
FA- CNV2402CBL	 0.2m (0.66ft.) CPU side RS232C mini-DIN 6-pin AC30R4 side RS422 D-sub 25-pin 	A7PU A7PUS A6PHP
FA- CNV2405CBL	 0.5m (1.64ft.) CPU side RS232C mini-DIN 6-pin AC30R4 side RS422 D-sub 25-pin 	A6GPP A6HGP

RS-232/RS-422 conversion cable connection example

(For connection of A series peripheral device such as A6GPP)



Note 2: Do not make connection to PLC side pin 4.

- Note 3: 5V power supply is needed for use of portable peripheral device such as A8PUJ. (Current Capacity: 0.4A or more)
- Note 4: Operation of the RS-232/RS-422 conversion circuit manufactured by the user should be confirmed by the user.

Other Connection Systems

When using SW5D5C-GPPW, you can use the following connection systems in addition to the RS-232 port connection of the CPU module.

Personal Computer Side Port	Communication System	A Mode PLC Side Module
COM	RS-232	A1SJ71UC24-R2
	RS-232/422	AJ65BT-G4
	(Note 5)	
A70BDE-J71QLP23 (GE)	MELSECNET/10	A1SJ71LP21
A70BDE-J71QBR13 (GE)		A1SJ71BR11
A80BDE-J61BT13	CC-Link	A1SJ61BT11
A80BDE-J61BT11		

- Note 5: RS-232/422 converter is needed. Note that CC-Link connections are made between AJ65BT-G4 and A mode PLC.
- Note 6: Connections via Ethernet cannot be made for the A mode PLC.

SIMULATION/ DEBUGGING FUNCTIONS

Sequence Program Simulation

Software

The SW5D5C-LLT-E ladder logic test tool (hereafter reffered to as "LLT") is software designed to add simulation functions to the MELSEC PLC programming function software package (SW5D5C-GPPW-E GPP function software package for Windows, hereafter referred to as "GPPW"). This comprehensive software is compatible with the A series, QnA series, FX series and motion controller, in addition to the Q series, to allow GPPW-created sequence programs to be simulated on a personal computer without writing them to the PLC.

Features

Program run can be checked on a personal computer, making debugging efficient.

- Without connection of a PLC, program run can be checked on the personal computer where that program was created.
- (2) The target PLC type (MELSEC-A/QnA/FX/Q/motion controller) of the program created is judged automatically and the corresponding virtual CPU is started.
- (3) Simple setting allows the machine side I/O to be operated simulatively. (Example: X0 turns on 10 seconds after Y10 has turned on.)
- (4) Debugging is enabled in the stage of program design.
- (5) PLC, basic and application instructions are supported.

I/O System Setting Function

The I/O system setting function allows external input generated for the PLC output to be given simulatively by simple setting. The following No. 1 indicates the setting that X2 and X3 are turned on 5 seconds after X0 has turned on and X2 turned off.

No.	Condition	Timer	Input (Simulation Device)	Status
1	K0=0N © AND K2=0FF C 0B	500 ×10ms	2X3 © ON C OFF	🔽 Enable
2	Y70=OFF © AND C OR	300 ×10ms	223 C OFF	🔽 Enable

Monitoring and Testing Functions

The monitoring and testing functions are designed to monitor the status of the device memory and buffer memory in a virtual CPU, and also permits forced ON/OFF and current value changing as well as device ON/OFF state and value monitoring, like the device batchmonitoring and buffer memory batch-monitoring functions of GPPW. In addition, the monitoring and testing functions of the ladder logic test tool include a function to display ON/OFF states and values in a timing chart format. It enables time-series operation to be acquired.



Tool Function

The tool function is designed to temporarily save the data of the virtual CPU device memory and special function module buffer memory and read and use the saved data when resuming debugging work.

Error Detail Display Function

Error detail explanation appears when an operation or similar error occurs during simulation made by LLT. This function saves time and trouble taken to refer to the manuals, etc. and facilitates finding the error occurrence cause.

Differences and Restrictions

As compared to the operation of the A mode CPU, LLT has the following restrictions.

- (1) LLT cannot support SFC programs.
- (2) LLT does not support interrupt programs. No operation will be performed if a sequence program is created.
- (3) The operation result in any instruction that uses a floating point value is not equal to the actual operation result of the CPU since a rounding error is always produced.

- (4) LLT cannot simulate the functions of special function/network modules. However, it has a buffer memory area of 64k points × 64 modules for special function/network modules. Data write/read can be performed to/from this area.
- (5) For the timing of LLT, processing time taken for one scan is calculated as 100ms (default value). By changing the constant scan setting, you can change the time taken for one scan.
- (6) In LLT, the timing method of the timer changes with the scan time (= constant scan setting) of the logic test function. At the scan time of 100ms, the current value of the 100ms timer is incremented by +1 every scan and the current value of the 10ms timer is incremented by +10 every scan. At the scan time of 10ms, the current value of the 100ms timer is incremented by +10 every scan and the current value of the 10ms timer is incremented by +1 every scan.
- (7) "OPERATION ERROR" occurs if a device range is exceeded in indirect designation using the index register.
- (8) In real number processing instructions, the ladder logic test tool (LLT) checks their real number ranges strictly.
 "OPERATION ERROR" occurs if any value entered cannot be evaluated as a real number.
- (9) The following parameters are invalid if set.

Parameter	Setting Item	
Memory capacity	Items except "sequence" and "file register"	
setting	in "program capacity" are invalid.	
PLC system setting	Items other than "STOP \rightarrow RUN time output	
	mode" are invalid.	
PLC RAS setting	"Annunciator display mode" is invalid.	
	 Items other than "operation error" and 	
	"special function module access error" in	
	"error-time operation mode" are invalid	
I/O assignment	All valid.	
Device setting	"Latch range" is invalid.	
Network parameters	All invalid.	

(10)For the A mode CPU function, the following special	
relays are supported by LLT.	

Number	Name	Description	
M9008	Self-diagnostic	OFF: No error	
MOUO	error	ON: Error	
M9009	Annunciator	OFF: No detection	
	detection	ON: Detection	
M9010	Operation error	OFF: No error	
	flag	ON: Error	
M9011	Operation error	OFF: No error	
	flag	ON: Error	
M9012	Carry flag	OFF: Carry OFF ON: Carry ON	
M9020	User timing		
	clock No. 0		
M9021	User timing		
	clock No. 1	n2 n2	
M9022	User timing	Scan Scan	
	clock No. 2	n1	
M9023	User timing	Scan	
	clock No. 3		
M9024	User timing		
	clock No. 4		
M9028	Clock data read	OFF: No operation	
Maaaa	0.4	ON: Read request	
M9030 (Note 1)	0.1 sec. clock	0.05sec 0.05sec	
(Note 1) M9031	0.2 sec. clock		
(Note 1)	0.2 300. UUUK	0.1sec 0.1sec	
M9032	1 sec. clock		
(Note 1)		0.5sec 0.5sec	
M9033	2 sec. clock	1sec 1sec	
(Note 1)			
M9034	1 min. clock	30sec 30sec	
(Note 1)			
M9036	Normally ON	ON	
		OFF	
M9037	Normally OFF	ON	
		OFF	
M9038	ON only 1 scan	ON	
	after RUN	OFF	
M9039	RUN flag (OFF	ON	
	only 1 scan after	Iscan	
	RUN)	OFF IOSA	
M9042	Stop status	OFF: Not during stop	
	contact	ON: During stop	
M9051	CHG instruction	OFF: Enabled	
	execution	ON: Disabled	
	disable		
M9054	STEP RUN flag	OFF: Not during step run	
	la structi	ON: During step run	
M9091	Instruction error	OFF: No error	
	flag	ON: Error	

*1: Derived from the constant scan setting.

SIMULATION/ DEBUGGING FUNCTIONS

Sequence Program Simulation

(11)For the A mode CPU function, the following special registers are supported by LLT.

D9008Self-diagnostic errorSelf-diagnostic error numberD9009Annunciator detectionF number at which external failure occurredD9010Error stepStep number at which operation error occurredD9011Error stepStep number at which operation error occurredD9015CPU operating statusCPU operating statusD9016Program statusSequence program being run is stored in BIN valueD9017Scan timeMinimum scan time (10ms increments)D9018Scan timeScan time (10ms increments)D9019Maximum scan time (Note 2)Maximum scan (user-set in 10ms increments)D9020Constant scan (user-set in 10ms increments)D9025Clock dataClock data (day, hour)D9026Clock dataClock data (day, hour)D9027Clock dataClock data (day, hour)D9028Clock dataClock data (day of week)D9035Extended file registerUsed block number registerD9036For specifying extended file register device numberDevice number used to directly access each device of extended file registerD9031Detailed error numberSelf-diagnostic error number numberD9124Annunciator detection countAnnunciator detection countD9125Detailed error numberSelf-diagnostic error number numberD9036For specifying extended file register device numberSelf-diagnostic error numberD9124Annunciator detecti	Number	Name	Description
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D9130 D9131		1	
D9131		1	
		1	
	D9132	1	

(12)LLT is not compatible with the following instructions, and no operation will be performed if they are executed. When a no-operation instruction is executed, the logic test function screen lamp is lit, and that no-op instruction and its step number can be displayed.

Non-operated and processing-restricted instruction list

Class	Instruction Symbol	Remarks
Program run control instruction	DI	No operation
	EI	No operation
	IRET	No operation
	SUB(P)	No operation
Refresh instruction	COM	No operation
	SEG	No operation
Data link instruction	LRDP	No operation
	LWTP	No operation
	RFRP	No operation
	RTOP	No operation
	ZNFR	No operation
	ZNTO	No operation
	ZNRD	No operation
	ZNWR	No operation
	ZCOM	No operation
Display instruction	PR	No operation
	PRC	No operation
	LEDC	No operation
Other instructions	СНК	No operation
	CHKEND	No operation
	SLT	No operation
	SLTR	No operation
	STRA	No operation
	STRAR	No operation
	IX	No operation
	IXR	No operation
	KEY	No operation
	COMRD	No operation
	DATEWR(P)	No operation
	WDT(P)	No operation

In addition to the above, the following instructions are not operated.

(1) PID control instructions

- (2) Special function module dedicated instructions
- (3) CC-Link dedicated instructions

Note 1: Derived from the constant scan setting.

Note 2: Same as all constant scan settings. Default is 100ms. Note 3: The time set as a constant scan is the time of 1 scan.

4. PERSONAL COMPUTER-RELATED PRODUCTS

1. OVERVIEW

• Overview4-2	
2. SYSTEM CONFIGURATION	
 System Required for Use of Personal 	
Computer-Related Products4-3	
3. SOFTWARE PACKAGES	
Basic Communication Support Tool	
: SW3D5F-CSKP-E4-4	
 EXCEL Communication Support Tool 	
: SW3D5F-OLEX-E	
Monitoring Tool : SW3D5F-XMOP-E4-12	
Graphic Data Package	
: SW0D5C-PIC-B4-15	
4. NETWORK BOARDS	

MELSECNET/10 Boards: A70BDE-J71QLP23, A70BDE-J71QLP23GE, A70BDE-J71QBR13......4-17 CC-Link Boards: A80BDE-J61BT11, A80BDE-J61BT13

4-20
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Overview

Overview

In production locations, there are increasing demands for using personal computers for production control, quality control and energy control.

To meet these demands, MELSEC offers a wide variety of methods for communication with PLCs for choice according to the facility scale and data volumes to be controlled and the software tools designed for ease of personal computer program creation.

This chapter provides personal computer-related products which may be used with the Q series PLCs.

What Tools Can Do

Creation of monitoring screen



Easy setting of communication system



Link with applications such as Excel



Creation of daily and monthly reports in combination with database





System Required for Use of Personal Computer-Related Products





Basic Communication Support Tool: SW3D5F-CSKP-E

Overview

The SW3D5F-CSKP-E basic communication support tool is designed to create a communication program on a personal computer, without regard to the complex communication protocol of a network, for connection of the personal computer and PLC. Since CSKP can handle a number of communication methods for the MELSEC PLC using common functions, you can use a common application program if the communication method is changed according to your application. (Minimum program modification is needed, e.g. communication setting change.) In addition, the bit and word devices of the PLC can be used in the personal computer so that you can handle data as if you are using the PLC.



Note 1: Q mode CPU connection requires software version "W" or later.

Note 2: The CC-Link modules for A mode, QnACPU, ACPU and motion controller require software version "N" or later.



Connection Configuration List

The following table lists the connection configuration and required interfaces.

Connection System	Personal Computer Side Interface	PLC Type (Note 1)	PLC Side Interface	Cable Type	Remarks
Ethernet	General-purpose	QCPU (Q mode)	QJ71E71, QJ71E71-B2	10BASE-2/5/T	
	Windows-compatible	QnA	AJ71QE71-B5, AJ71QE71	10BASE-2/5	
	Ethernet board/card	Q2AS	A1SJ71QE71-B2,		
			A1SJ71QE71-B5		
		QCPU (A mode)	A1SJ71E71-B2-S3		
		AnSH, A2AS (H)	A1SJ71-E71-B5-S3		
		AnN/AnA/AnU	AJ71E71-S3		
MELSECNET/10	A70BDE-J71LP23 A70BDE-J71QLP23GE	QCPU (Q mode)	QJ71LP21, QJ71BR11	SI/QSI-200/250 optical 75 Ω coaxial	Incompatible with MELSECNET/10F
A70BDE-J71QBR13	QnA	AJ71QLP21 (S), AJ71QLP21G, AJ71QBR11	SI/QSI-200/250 optical GI-50/125 optical 75 Ω coaxial	mode.	
		Q2AS	A1SJ71QLP21 (S), A1SJ71QBR11	SI/QSI-200/250 optical 75 Ω coaxial	
		QCPU (A mode) AnSH, A2AS (H)	A1SJ71LP21, A1SJ71BR11		
		AnN/AnA/AnU	AJ71LP21, AJ71LP21G, AJ71BR11	SI/QSI-200/250 optical GI-50/125 optical 75 Ω coaxial	
	A80BDE-J61BT13 A80BDE-J61BT11	QCPU (Q mode)	QJ61BT11	Twisted pair	
		QnA	AJ61QBT11		
		Q2AS	A1SJ61QBT11		
		QCPU (A mode) /AnSH/A2AS(H)	A1SJ61BT11		
		AnN/AnA/AnU	AJ61BT11		
RS-232/422	Personal computer	QCPU (Q mode)	QJ71C24, QJ71C24-R2	RS-232/422 cable	For RS422
COM	COM port	QnA	AJ71QC24N, AJ71QC24N-R2, AJ71QC24N-R4	RS232C/ converter needed. Because RS232C	connection, RS232C/422 converter is
		Q2AS	A1SJ71QC24N, A1SJ71QC24N-R2		needed. Because of
		QCPU (A mode) /AnSH/A2AS(H)	A1SJ71UC24-R2, A1SJ71UC24-R4		RS232C interface, Q/A mode CPU
		AnN/AnA/AnU	AJ71UC24		does not need
		QCPU (Q mode) /QCPU (A mode)	CPU module RS232C		RS232C/422 converter.
		QnA/Q2AS/AnN/AnA /AnU/ AnSH/A2AS(H)	CPU module RS422		
		QCPU (A MODE) /QnA/Q2AS /AnN/AnA/AnU/AnSH /A2AS(H)	CC-Link via AJ65BT-G4		
USB	Personal computer USB port	QCPU (Q mode)	CPU module USB	USB cable	
Simulation		LLT			

Note 1: "AnU" includes motion controller "A273U". "AnSH" includes motion controller "A171SH/172SH".



Basic Communication Support Tool: SW3D5F-CSKP-E

Data Link Functions

CSKP offers the functions designed for Visual Basic and Visual C++, to allow you to make communication with the PLC CPU without regard to complex communication protocols.

Programming language

- Visual Basic Ver 4.0
- Visual Basic Ver 5.0
- Visual Basic Ver 6.0
- Visual C++ Ver 4.2
- Visual C++ Ver 5.0
- Visual C++ Ver 6.0

Many Useful Utilities

Setting is easy as communication parameter setting to each communication path can be made on the utility screen. Also, the testing utility designed to check whether settings are proper or not after making settings and the error viewer developed to confirm the error history are available to establish communication easily.

Communication setting utilities

Communication parameter setting utilities designed for respective communication systems, e.g. computer link (serial communication) and Ethernet, have a communication test function to set the communication speed, communication target and others and to confirm the settings.

• Computer link utility



Ethernet utility



• CPU COM utility



Shared device utility

Used to make settings required to provide a personal computer with shared device memories EM, which is equivalent to the internal relay of the PLC, and ED, which is equivalent to the data register.

Shared device server utility

Used to make settings necessary to share devices between personal computers or between personal computer and PLC.

Device monitor utility

The set communication system is used to perform batch monitoring and data change (test) of the device memories in the PLC. When debugging an application program created in Visual Basic/Visual C++, this utility can be used to check the device data in the PLC.

Offline Debugging

The ladder logic test function (LLT) starts a virtual PLC on a personal computer. Debugging can be made on the personal computer without connection of the PLC.





Instruction

To use the ladder logic test function (LLT), GPPW and ladder logic test tool (LLT) are required separately.

Error Viewer Function

The error viewer gives you a quick view of the errors that occurred.

Also, it leaves a history to tell you when errors had occurred.

Shared Device Function

Used to set bit and word devices on a personal computer. Via the shared devices, you can make inter-program communication on the same personal computer or make communication between personal computers on the MELSECNET/10.



Device Monitor Function

Use of the device monitor utility allows the monitoring and data changing of the specified devices.



Specifications

Operating environment

Item	Description
OS	Windows 95, Windows 98, Windows NT
	Workstation 4.0 (Note 1)
CPU	Pentium 100MHz or more (multiprocessor
	incompatible)
Display	Resolution 800 $ imes$ 600 pixels or more
	(recommended 1024 $ imes$ 768 pixels)
Required memory	32MB or more
capacity	
Hard disk free space	15MB or more
Disk drive	3.5 inch (1.44MB) floppy disk drive (needed
	for installation)
Programming	Visual Basic 4.0 (Note 2)
language	Visual Basic 5.0/6.0
	Visual C++ 4.2 (Note 2)
	Visual C++ 5.0/6.0

Note 1: Service Pack 3 or higher is required for use of Windows NT Workstation 4.0.

Note 2: Cannot be used for CC-Link communication.



Basic Communication Support Tool: SW3D5F-CSKP-E

Accessible CPU Device Ranges

		CPU			
		A/AnS Series	QnA/Q2AS Series	Q Series (A Mode)	Q Series (Q Mode)
Input	Х	X0 to X1FFF	X0 to X1FFF	X0 to X1FFF	X0 to X1FFF
Output	Y	Y0 to Y1FFF	Y0 to Y1FFF	Y0 to Y1FFF	Y0 to Y1FFF
Latch relay	L	L1000 to L2047	L0 to L8191	L1000 to L2047	L0 to L8191
Internal relay	М	M0 to M999, M2048 to M8191	M0 to M8191	M0 to M999, M2048 to M8191	M0 to M8191
Annunciator	F	F0 to F2047	F0 to F2047	F0 to F2047	F0 to F2047
Timer	Т	T0 to T2047	T0 to T2047	T0 to T2047	T0 to T2047
Retentive timer	ST	—	ST0 to ST2047	_	ST0 to ST2047
Counter	С	C0 to C1023	C0 to C1023	C0 to C1023	C0 to C1023
Data register	D	D0 to D8191	D0 to D12287	D0 to D8191	D0 to D12287
Accumulator	А	A0,A1	_	A0,A1	_
Index register	Z	Z,Z1 to Z6	Z,Z1 to Z15	Z,Z1 to Z6	Z,Z1 to Z15
Index register	V	V,V1 to V6	_	V,V1 to V6	_
Edge relay	V	—	V0 to V2047	_	V0 to V2047
File register	R	R0 to R8191	R0 to R32767	R0 to R8191	R0 to R32767
Link relay	В	B0 to B1FFF	B0 to B1FFF	B0 to B1FFF	B0 to B1FFF
Link register	W	W0 to W1FFF	W0 to W1FFF	W0 to W1FFF	W0 to W1FFF
Special link relay	SB	_	SB0 to SB7FF	—	SB0 to SB7FF
Special link register	SW	_	SW0 to SW7FF	_	SW0 to SW7FF
Step relay	S	Parameter setting	S0 to S8191	Parameter setting	S0 to S8191
Special relay	SM/M	M9000 to M9255	SM0 to SM2047	M9000 to M9255	SM0 to SM2047
Special register	SD/D	D9000 to D9255	SD0 to SD2047	D9000 to D9255	SD0 to SD2047

Note 1: The above table lists accessible device ranges of each series. Access cannot be made to the device ranges not supported by the CPU. Confirm the device ranges of the individual CPUs in the corresponding catalogs.

Note 2: There may be restrictions on the accessible device ranges depending on the combination of communication interface and CPU. Example: Accessible device ranges are restricted when the QnACPU and A series Ethernet module are used together.

Accessories

Accessory	Product	Description
Manuals	CSKP Operating Manual	Describes how to use each utility, how to make communication setting and other
		information.
	CSKP Programming Manual	Shows how to use the library.


SW3D5F-OLEX-E Excel Communication Support Tool

The SW3D5F-OLEX-E Excel communication support tool is software used by adding it in Microsoft Corporation's spreadsheet software "Excel".

You can read PC data into Excel and write data from Excel to the PLC without worrying about the communication program of the PLC.

To handle the data developed in Excel worksheets, you can use a wide selection of functions of Excel to print and graph them.

To use OLEX as Q series-compatible, SW3D5F-CSKP-E must have been installed in advance.



Ease of Setting

By simply connecting a personal computer with the PLC via a communication path supported by SW3D5F-CSKP-E, you can transfer PLC data directly to/from an Excel worksheet without programming.



Excellent Operability

- (1) Used as an add-in program in the menu, OLEX can be used easily by those who understand Excel.
- (2) The production command data under control of Excel can be written unchanged from the Excel screen onto the specified devices of the PLC, without using a program.
- (3) The operation results and quality data set to PLC devices can be read onto an Excel worksheet.
- (4) The read data can be printed with the Excel function. For data communication timing, you can set automatic communication such as periodic communication or conditional communication.

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EXCEL Communication Support Tool: SW3D5F-OLEX-E

Alarm Summary and Comment Indications

An alarm message preset for error occurrence can be displayed with the date/time and a comment can be shown with the change of the corresponding device value.



- Logging function accumulates data in more than one cell per collection timing
- (2) You can make a daily/monthly reports easily by making use of the function to save/print an Excel worksheet automatically at the set time.



OLEX Functions

By utilizing the OLEX functions as Excel macros, you can transfer the data of the specified cell area at any timing.

<When OLEX function is set to button (Read)>



Device values are read to the cell area specified with the OLEX function.

Simple Communication using Tags

When OLEX merely uses a tag having such information as the device types and device numbers in the environment where the tag management process is running, you can easily access the devices set to the tag.





EXCEL Communication Support Tool: SW3D5F-OLEX-E

Specifications

Operating environment

Operating environment required to use SW3D5F-OLEX-E

Item	Description
OS	Windows 95, Windows 98, Windows NT Workstation 4.0 (Note 1)
CPU	Pentium 100MHz or more (multiprocessor incompatible)
Display	Resolution 800 $ imes$ 600 pixels or more (recommended 1024 $ imes$ 768 pixels)
Required memory capacity	32MB or more
Hard disk free space	40MB or more
Disk drive (needed for installation)	3.5 inch (1.44MB) floppy disk drive
Corresponding application	Excel 97
Required application	Excel 97, SW3D5F-CSKP-E

Note 1: Service Pack 3 or higher is required for use of Windows NT Workstation 4.0.

Accessories

Accessory	Product	Description
Manual	OLEX Operating Manual	Explains how to set and use OLEX.



Monitoring Tool: SW3D5F-XMOP-E

SW3D5F-XMOP-E Monitoring Tool

The SW3D5F-XMOP-E monitoring tool offers a Visual Basic custom control group designed to create monitoring programs using Visual Basic.

You can create monitoring control programs by simply pasting input area, display area, check box, menu and other parts and pushbuttons and other controls and setting display conditions, etc. in a form window in Visual Basic.

To use XMOP as Q series-compatible, SW3D5F-CSKP-E must have been installed beforehand.



XMOP screen

User-friendly Development Environment

Visual Basic is a user-friendly programming language designed to create Windows applications easily. XMOP is a kind of control (custom control OCX) of Visual Basic and is operated in the same way as Visual Basic. In addition, a wide variety of commercially available graphic tools for Windows can be utilized to draw a monitor screen. User-friendly development environment is achieved by utilization of the tool you are accustomed to use.

Program-less Run

XMOP offers 23 different custom controls which are needed to exercise Factory Automation equipment monitoring control, e.g. graphic display, numeric display, level display and trend graph.

Without any specific expertise, you can use them like the other standard controls to make communication with the PLC by merely pasting the necessary custom controls to a form and executing them.

(Note that property page setting is required.)







Monitoring Tool: SW3D5F-XMOP-E

Expansion of Programmed Processing

Since the drawing functions and custom controls have one-for-one correspondence, monitor applications can be created without program. For functions with which the custom control functions are not compatible, programmed processing can be easily added later and monitor applications can be updated flexibly.

While maintaining compatibility with the conventional data, you can easily make modifications such as the addition of new functions.

Simple Communication Using Tags

When tags having such information as the device types and device numbers are used with the controls offered by XMOP in the environment where the tag management process is running, you can easily access the devices set to the tags.



Useful Parts Collection

The SW0D5C-PIC-B graphic data package (optional) includes graphic data usually used on monitor screens.



Monitoring Tool: SW3D5F-XMOP-E

Custom Control List

	Function	File Name	Description
Parts display	Graphic display	XMPICTUR.OCX	Shows a graphic file with set values.
	Blink display	XMBLINK.OCX	Provides a blink display when the specified bit device is ON.
	Comment display	XMCMNT.OCX	Shows a comment with the set device value.
Graph	Level display	XMLEVEL.OCX	Shows a level.
display	Line graph display	XMLINGRF.OCX	Shows a line graph.
	Trend graph display	XMTREND.OCX	Shows a trend graph.
	Bar graph display	XMBARGRF.OCX	Shows a bar graph.
	Pareto chart display	XMPALLET.OCX	Shows a Pareto chart.
	Historical trend graph display	XMHSTTRD.OCX	Shows a historical trend graph.
Block	Numeric block data display/input	XMNUMBLK.OCX	Shows/enters numeric values in block.
display/input	Character string block data display/input	XMSTRBLK.OCX	Shows/enters character strings in block.
Display/input	Numeric data display/input	XMNUMDAT.OCX	Shows/enters numeric value data.
	Character string data display/input	XMSTRDAT.OCX	Shows/enters character string data.
	Bit device operation (bit input)	XMBITOPR.OCX	Performs bit device operation.
Input	Word write	XMWRWORD.OCX	Writes data to a word device.
	Bit write	XMWRBIT.OCX	Writes data to a bit device.
Others	Event occurrence	XMEVENT.OCX	Causes an event at the specified timing.
	Snap shot	XMSNPSHT.OCX	Provides output, etc. to a printer.
	Alarm display	XMCATION.OCX	Shows an alarm on the screen on the basis of the
			set value.
	Alarm sound output	XMALARM.OCX	Provides an alarm sound on the basis of the set
			value.
	Alarm summary display	XMALMSMR.OCX	Shows an alarm summary.
	Error	XMERROR.OCX	Causes an error event.
	Clock display	XMCLOCK.OCX	Shows a clock on the screen.

Specifications

Operating environment

Operating environment required to use SW3D5F-XMOP-E

Item	Description
OS	Windows 95, Windows 98, Windows
	NT Workstation 4.0 (Note 1)
CPU	Pentium 100MHz or more
	(multiprocessor incompatible)
Display	Resolution 800 $ imes$ 600 pixels or more
	(recommended 1024 $ imes$ 768 pixels)
Required memory	32MB or more
capacity	
Hard disk free space	40MB or more
Disk drive (needed	3.5 inch (1.44MB) floppy disk drive
for installation)	
Corresponding	Visual Basic Ver 5.0/6.0
container application	
Required application	Visual Basic Ver 5.0 or 6.0,
	SW3D5F-CSKP-E

Note 1: Service Pack 3 or higher is required for use of Windows NT Workstation 4.0.

Accessories

Accessory	Product	Description
Manual	XMOP Operating	Describes custom control
	Manual	functions of XMOP and how
		to set control properties.

Overview

The SW0D5C-PIC-B graphic data package is a collection of graphic parts bitmap data which can be utilized for monitor screen development for Factory Automation. They can be used in Visual Basic, Excel and other software, reducing the number of graphic parts creation processes.

Features

Wealth of parts

You have a wide choice of 1351 different graphic data such as buttons, tanks, valves, pipes and ISO figures.

Bitmap format data

Graphic data are available in bitmap format so that you may use them in various application programs, e.g. Visual Basic and Excel.

No need to install

The graphic data are offered on CD-ROM. You can read the necessary data directly from CD-ROM without installation into the hard disk.

 Supporting two color modes, TrueColor and 256 colors

The package is compatible with two different color modes to correspond to various personal computer environments.

Operating Environment

Item	Description
OS	Windows 95, Windows 98, Windows NT
	Workstation 4.0
WWW browser	Internet Explorer 4.01 or later or Netscape
	4.06 or later
CPU	Pentium 100MHz or more (multiprocessor
	incompatible)
Display	Resolution 800×600 pixels or more
	(recommended 1024 × 768 pixels)
Required	32MB or more
memory	
Hard disk free	5MB or more
space	

Graphic Data

The following table lists the number of figures per type.

Туре	Number of Figures
ISO figure (Note 1)	348
Box	4
Automobile	16
Conveyor	21
Crane	20
Fan	8
Display frame	6
Keyboard	15
Lamp and pushbutton	361
MELSEC	313
Meter	2
Motor	10
Pipe	41
Pump	8
Robot	114
Speaker	11
Tank	18
Valve	18
Others	17

Note 1: Figures of the following numbers are stipulated in ISO7000 (1989) 1 to 100, 110, 111, 114, 130, 131, 134, 135, 137, 138, 151, 157, 159 to 200, 201 to 400 (except 263, 265, 281, 298, 396)

About the Copyright and Right to Use

The copyright of the figures contained in the SW0D5C-PIC-B graphic data package belongs to Mitsubishi Electric Corporation.

The figures contained in the SW0D5C-PIC-B graphic data package may only be used by those who purchased the software duly and returned the software agreement. Those who have not purchased it duly or those who have

not returned the software agreement cannot use the data package.

You cannot distribute or sell the figures contained in the SW0D5C-PIC-B graphic data package as-is or altered. You can distribute or sell the figures after incorporating them on monitor screens, etc.



Graphic Data Package: SW0D5C-PIC-B



NETWORK BOARDS

MELSECNET/10 Boards: A70BDE-J71QLP23, A70BDE-J71QLP23GE, A70BDE-J71QBR13

Overview



The MELSECNET/10 board can be loaded into an ISA bus slot as the optional board of a personal computer (Note 1) to connect the personal computer to the MELSECNET/10 (Note 2) network system.

Note 1: IBM PC/AT and its compatibles. Note 2: Not compatible with MELSECNET/10H mode.

Features

 Personal computer incorporated into MELSECNET/10 network system

You can load the interface board into a personal computer to use the personal computer as an ordinary station of MELSECNET/10.

Monitoring/testing utility

To check the status of connection to the network, you can confirm the network status and perform the test function on the personal computer screen.

Cyclic communication and transient communication

The board has two communication functions: cyclic communication in which data is refreshed in accordance with the network parameters set in the control station; and transient communication in which the PLC can be accessed at any timing of a personal computer program.

• Availability of user programming functions The functions designed for Microsoft Visual C++ and Microsoft Visual Basic allow you to easily create user applications, e.g. those for remote control of PLC and read/write of data from/to devices.

 Availability of drivers according to various operating system

You can configure a system according to your environment using any of the various drivers available.

Compatible OS	Microsoft Windows NT Workstation 4.0
	Microsoft Windows 95
	Microsoft Windows 98
	Microsoft MS-DOS 6.2 (Note 1)

Note 1: The Q mode PLC cannot be accessed by MS-DOS.

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NETWORK BOARDS

MELSECNET/10 Boards: A70BDE-J71QLP23, A70BDE-J71QLP23GE, A70BDE-J71QBR13

Function List

Name	Description
	Cyclic transmission function, transient transmission function
Data communications	Multiple transmission function (for duplex loop system)
RAS function	Loopback function, automatic return function, loop monitoring function, self-diagnostic function

Performance Specifications

	Specifications			
Item	Optical loop system			Coaxial bus system
	A70BDI	E-J71QLP23	A70BDE-J71QLP23GE	A70BDE-J71QBR13
Connection cable	S1-200/220	QSI-185/230	GI-50/125	3C-2V, 5C-2V or equivalent
MELSECNET/10 mode	MELSECNET/1	0 mode (incompatibl	e with MELSECNET/10H mode)	
Communication speed	10MBPS (equiv	alent to 20MBPS in	10MBPS	
Communication system	Token ring syste	em	Token bus system	
Transmission path format	Duplex loop		Simplex bus	
Stations connected in one network	64 stations (con	trol station: 1, ordina	ry stations: 63)	32 stations (control station: 1,
				ordinary station: 1)
Control station/ordinary station	Ordinary station (does not operate as control station)			
Other network specifications	Other specificat	ions conform to thos		
Loading slot	ISA bus slot			
Number of boards loaded	Max. 4			
Number of slots occupied	1 slot/board			



MELSECNET/10 Boards: A70BDE-J71QLP23, A70BDE-J71QLP23GE, A70BDE-J71QBR13

Operating Environment

Item	Description	
Personal computer	Personal computer where Pentium 133MHz or more and ISA bus slot (half size) are installed (Note 3)	
	Any of	
	Microsoft Windows 95	
Operating system (OS)	Microsoft Windows 98	
	Microsoft Windows NT Workstation 4.0	
	Microsoft MS-DOS Ver 6.2	
	Microsoft Visual Basic Ver 4.0/5.0/6.0	
Programming language	Microsoft Visual C++ Ver 4.2/5.0/6.0	
Required memory capacity	32MB or more	
Hard disk free space	9MB or more	
Disk drive (Needed for driver installation)	3.5 inch (1.44MB) floppy disk drive	

Note 3: A multiprocessor-compatible personal computer cannot be used since the driver is incompatible. Note 4: The driver for MS-DOS cannot access the Q mode PLC.

Accessories

Product	Description
Software	SWnDNF-MNET10 software (driver)
Connector	BNC F connector $ imes$ 1 pc. (attached to A70BDE-J71QBR13 only)
Manual	MELSECNET/10 Interface Board User's Manual

NETWORK BOARDS

CC-Link Boards: A80BDE-J61BT11, A80BDE-J61BT13

Overview



The CC-Link board can be loaded into a PCI bus slot as an optional board of a personal computer (Note 1) to connect the personal computer to the CC-Link system. Two kinds of CC-Link boards are available. A80BDE-J61BT11 supports both master function and local function of CC-Link while A80BDE-J61BT13 only supports local function of CC-Link.

Note 1: IBM PC/AT and its compatibles.

Features

 Personal computer incorporated into CC-Link system

You can load the CC-Link board into a personal computer and connect the personal computer to CC-Link as a local station.

Adoption of PCI bus

Because of compatibility with the PCI bus, troublesome switching setting is not needed. By merely loading the board into the PCI bus, initial setting is automatically made.

Monitoring/testing utility

To check the status of connection to the network, you can confirm the network status and perform the test function on the personal computer screen.

Availability of user programming functions

The functions compatible with Microsoft Visual C++ and Microsoft Visual Basic allow you to easily create user applications, e.g. those for remote control of PLC and read/write of data from/to devices.

Availability of drivers according to various operating systems

You can configure a system according to your environment using any of the various drivers available.

-		Master	Local
Compatible OS	Microsoft Windows NT Workstation 4.0	0	0
	Microsoft Windows 95	×	0
	Microsoft Windows 98	×	0

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Function List

Name	Description
Data communications	Cyclic transmission function, transient transmission function
RAS function	Offline test function, automatic return function, self-diagnostic function

Performance Specifications

Item	Specifications				
Туре	A80BDE-J61BT11	A80BDE-J61BT13			
Transmission speed	Can be selected from among 156kbps, 625bps, 2.5Mbps, 5Mbps and 10Mbps.				
Max. transmission distance	1km (3278.69feet) (depending on transmission speed)Max.				
Number of stations occupied	Master: None Local: 1 or 4 station selectable	1 or 4 stations selectable			
Compatible station	Master/Local station	Local station			
Number of boards loaded	Max. 4				
Loading slot	PCI bus slot				
Number of slots occupied	1 slot				
Internal current consumption (A)	0.4A				
Weight (kg (lb))	0.16 (0.35)				

Operating Environment

	Item	Description
Personal	computer	Personal computer where Pentium 133MHz or more and one or more PCI bus slot (half size) are installed and Microsoft Windows 95, Microsoft Windows 98 or Microsoft Windows NT Workstation 4.0 operates (Note 3)
	PCI bus specifications	5VDC, 32-bit bus, system clock: 33MHz
Operating	system (OS) (Note 4)	Any of Microsoft Windows 95, Microsoft Windows 98 and Microsoft Windows NT Workstation 4.0
Programn	ning language	Microsoft Visual Basic Ver 5.0/6.0, Microsoft Visual C++ Ver 5.0/6.0
Required	memory capacity	32MB or more
Hard disk	free space	20MB or more
Disk drive	ł	3.5 inch (1.44MB) floppy disk drive (needed for driver installation)

Note 3: A multiprocessor-compatible personal computer cannot be used as the driver is incompatible. Note 4: Please use Windows NT Workstation 4.0 when using CC-Link board as master station.

Accessories

Product	Description
Software	SWnDNF-CCLINK software (driver)
Manual	CC-Link Interface Board User's Manual
Termination resistor	110 Ω and 130 Ω , 2 pcs. each (attached to A80BDE-J61BT11 only)

5. GOT-A900

1. Overview and Features	5-2
2. System Configuration	5-6
3. General Specifications	. 5-12
4. Performance Specifications	. 5-13
5. Function List	. 5-17
6. External Dimensions	. 5-19

This chapter explains the features and functions of the GOT-A900 connected for use with the Q series PLC. For further information on the features, functions, etc. of the GOT-A900 connected for use with the A/QnA series PLC, refer to the "Mitsubishi Graphic Operation Terminal GOT-A900 Series" catalog (L(NA)74108142).

OPERATION PANEL GOT-A900

Overview and Features

GOT-A900 series

The GOT-A900 (graphic operation terminal) is graphic operation panel which has been achieved by a display device provided with a touch screen instead of the conventional pushbuttons, select switches, lamps and other controls. Since display data, switch operations, etc. are set by software, operation and display data can be changed/added easily. Also, as multiple screens can be selectively shown on one display, a

■ GOT-A900 series lineup

small operation panel can be achieved independently of the number of display and operation points.

The GOT-A900 series has a high degree of affinity for each MELSEC PLC series and has realized fast communication with other PLCs unachievable by ordinary display devices and a great variety of functions which are needed for maintenance. From a wide selection of models, choose the most adequate GOT-A900 for your equipment.

	Туре	Screen Size (Inch)	Display Section	Display Color (Colors)	Power Supply Type	
	A985GOT-TBA				100 to 240VAC	
A985GOT	A985GOT-TBA-EU	12	High-intensity TFT color liquid crystal		100 10 2 10 11 10	
	A985GOT-TBD				24VDC	
	A975GOT-TBA		Wide-angle vision TFT color liquid crystal	256		
	A975GOT-TBA-B		High-intensity TFT color liquid crystal		100 to 240VAC	
A975GOT	A975GOT-TBA-EU					
	A975GOT-TBD		Wide-angle vision TFT color liquid crystal		24VDC	
	A975GOT-TBD-B		High-intensity TFT color liquid crystal		21100	
	A970GOT-TBA		Wide-angle vision TFT color liquid crystal			
	A970GOT-TBA-B		High-intensity TFT color liquid crystal		100 to 240VAC	
	A970GOT-TBA-EU	10		16		
	A970GOT-TBD	10	Wide-angle vision TFT color liquid crystal		24VDC	
	A970GOT-TBD-B		High-intensity TFT color liquid crystal		24000	
A970GOT	A970GOT-SBA				100 to 240VAC	
	A970GOT-SBA-EU		D-STN color liquid crystal STN Monochrome liquid crystal	8 2 (monochrome)	100 10 240 070	
	A970GOT-SBD				24VDC	
	A970GOT-LBA				100 to 240VAC	
	A970GOT-LBA-EU				100 10 240 740	
	A970GOT-LBD				24VDC	
	A960GOT-EBA			2 (yellow/orange,	100 to 240VAC	
A960GOT	A960GOT-EBA-EU	9	High-intensity EL	2 (yellow/orange, black)	100 10 240 VAC	
	A960GOT-EBD			blacky	24VDC	
	A950GOT-SBD		STN color liquid crystal	8	24VDC	
A950GOT	A950GOT-SBD-M3				(RS-422	
A330001	A950GOT-LBD		STN Monochrome liquid crystal	2 (monochrome)	communication	
	A950GOT-LBD-M3			2 (monocinome)	interface built in)	
	A953GOT-SBD		STN color liquid crystal	8	24VDC	
A953GOT	A953GOT-SBD-M3	6		8	(RS-232C	
A90001	A953GOT-LBD	0	STN Monochrome liquid crystal	2 (monochrome)	communication	
	A953GOT-LBD-M3			2 (monochiome)	interface built in)	
	A956GOT-SBD		STN color liquid crystal	8	24VDC	
A956GOT	A956GOT-SBD-M3			0	(communication	
A90001	A956GOT-LBD		STN Monochrome liquid crystal2	2 (monochrome)	module	
	A956GOT-LBD-M3				connectable)	
	A951GOT-QSBD		STN oplar liquid ar rate	8	24VDC	
A951GOT	A951GOT-QSBD-M3	6	STN color liquid crystal	U	(Q bus	
A901001	A951GOT-QLBD	0	STN Monochromo liquid envetal?	2 (monochrome)	communication	
	A951GOT-QLBD-M3		STN Monochrome liquid crystal2	2 (monochrome)	interface built in)	

Overview and Features

Compact display

The GOT-A900 series models have extremely small external dimensions and depths, and the A975GOT(-B) and A970GOT(-B) have the smallest in-panel depth of 40mm (1.73inch) in the industry. The 12-inch, large-display A985GOT has the same panel cutting dimension as that of the GP70 series 10-inch color type (the smallest panel cutting dimension as a 12-inch type in the industry), and the 6-inch, mid-sized-display A95_GOT has the same panel cutting dimension as that of the GP70 series and MT260 6-inch types.

Designed to connect cables at its bottom, the GOT needs a minimum depth for connectors and flexing of cables when mounted in a control panel, etc.



Compatible with a wide variety of connection forms

To say nothing of bus connection which permits fast communication, the GOT-A900 is compatible with various connection forms such as MELSECNET connection, so you can make the best selection for your system. (Bus connection is not available for the A mode.)

- Bus connection (Q mode only)
- RS-232 connection to CPU module
- MELSECNET connection
- CC-Link connection (remote device station/intelligent device station)
- Serial communication module connection

256-color TFT, high intensity, 8-step brightness adjustment

Capable of providing a 256-color display, the A985GOT and A975GOT (-B) can show clear and high-grade photos as they are.

Also, the high-intensity TFT color liquid crystal models (A985GOT, A975GOT-B, A975GOT-TBA-EU, A970GOT-B, A970GOT-TBA-EU) have the industry's highest class brightness of 350cd/m² and are adjustable in eight steps of brightness. Further more, the 40,000-hour, long-life backlight makes it almost maintenance-free. (A958GOT, A975GOT (-B), A970GOT (-B), A95_GOT)

Voice output function (A985/A975/A970/A960GOT)

Voice output can be provided by connecting an amplifier builtin speaker to the voice output terminal (standard-equipped). This function can be used for alarm, work directive, etc. Specified bit device X1 turns on.



When X1 turns on, GOT recognizes it, and when condition holds, GOT plays specified voice file.

Item	Specifications
File format	Windows WAV
Data format	16-bit PCM
Sampling rate	8,000kHz
Channel	Monaural
Max. playing time/file	8s
Max. number of registrations	100

Functions for maintenance

The PLC CPU devices and special function module buffer memory can be monitored and tested.

A device checking maintenance screen need not be created as different PLC devices can be shown/changed at the same time on a four-window display.

		ATION			VK No.	BATCH			STATION		EVICE MO
	lleel	ATION	51/	[U]	VK NO.	INEIV		[FF]	STATION	NO.[U]	NETWK No
-500	18	D 1	'67 E	327	10	D		DW	147483648	15 -21	D 15
3234	19	D 1	0 0		11	D			-32767	10	D 10
0	20	D 2	0 [12	D			•	01	X 001
0	21	D 2	-1 [13	D			0		M 25
0	22				14	D			•	70	Y 70
2768	23 -3	D 2	3 [15	D			43	00	W 200
0	24	D 2	0 [16	D		DW	68378428		
0	25	D 2	0 [17	D			30000	00	D 300
A SET	U FOR	MEN	TEST	OR	MONIT	BM I	1 SET	U FORM	TEST MEN	NITOR	TC MONI
	[FF]	ATION	ST	[0]	VK No.	NETV I/O NO		[FF]	STATION	No.[0]	NETWK No
0	1118	BM	32767) -3	1110	BM	М∧		0 SV 0	PV	T 0 P
0	1119	BM	64		1111	BM				duction lin	
	1120	BM	149	2	1112	BM	Ю	++-<	0 SV 0	PV	T 1 P
150			1111		1113	BM				duction lir	
150 131	1121	BM									T 2 P
131 -32768	1121 1122	BM	126		1114	BM	•		0 SV 150		
131 -32768 555	1121 1122 1123	BM BM	126 160		1115	BM			ne C]	duction lin	[Produ
131 -32768	1121 1122	BM	126					-∎• -⊪-(neC] 0SV 0	duction lin	[Produ T 3 P

The alarm history function supports the failure occurrence counting function, cumulative failure time totalization function, history printing function and so on.

Overview and Features

Security function

OPERATION PANEL GOT-A900

You can set a 16-step password. This function can protect screen switching, hide a display partially, protect input operation, and protect screen data uploading.

Energy-saving mode using human sensor (A985GOT)

The human sensor detects a person within the sensor detection area to automatically turn the backlight on/off, reducing unnecessary power consumption. (Time can be set by the user)

Multi-language

The adoption of the uni-code (ISO/IEC10646 compliant), globally compatible character system, makes the GOT compatible as standard with about 26,000 characters in all countries of the world, including Japanese, Korean, Chinese, English, German and French.

By adoption of the high-level uni-code fonts, the GOT can display 32x32 or larger, beautiful characters and support highlighted and shaded characters.

* To use foreign language fonts, Windows which can support and enter those fonts is required. For example, Windows for Korean language is needed to enter Korean fonts.

Fast data transfer using PC card

Using a PC card, you can write the OS and screen data from a personal computer to the GOT-A900 at high speed.

(Conventional data transfer using RS-232C can also be made.) * To use the PC card on the A95 GOT, the memory card

interface module (A1SD59J-MIF) is required.

Recipe function

The GOT-A900 supports the recipe function which holds machining conditions, initial values and other machine data (device values) within the GOT-A900 as recipe data and exchanges necessary data from time to time.

Also, the GOT-A900 serves for process/production control, etc. since PLC data can be read to the PC card for use on the other GOT-A900 or read from Excel or other spreadsheet software on a personal computer for control.

(For control on personal computer)



- 1) On the personal computer, read the device value data (CSV format file) which were read from the PLC CPU and saved in the PC card in the CSV format file.
- 2) Read and edit the CSV format file in the PC card using spreadsheet software, etc.
- 3) Save in the PC card the device value data (CSV format file) edited on the personal computer, and use it on the GOT-A900.
- * To use the PC card on the A95 GOT, the memory card interface module (A1SD59J-MIF) is required.

Printer function

The GOT-A900 series supports the printer function for alarm history, daily/monthly report (forms), display screen color hard copy, etc. The A985GOT, A975GOT (-B), A970GOT (-B) and A960GOT are standard-equipped with an interface, and the A95 GOT should be fitted with the printer interface (A9GT-50PRF) to use the printer function.

- Connectable printers
- (1) ESC/P24-J84 compliant printer (color-compatible)
- (2) Hewlett Packard's printer (PLC command-compatible, color-incompatible)



Bar-code reader function

By connecting a bar-code reader to the GOT-A900, the data read by the bar-code reader can be written to the PLC CPU.

• Connectable bar-code readers

- (1) TCD-6100RMG (Token)
- (2) OPT-5125-RS232C(H) (Optoelectronics)
- (3) BL-500 series (Keyence) BL-80R Keyence bar-code reader
 - BL-100R Keyence bar-code reader
- (4) BB-530RS (Aimex)
- (5) LSH3502AHV (Olympus Symbol)



Overview and Features

Compatible with severe environment and operation

The display section of the GOT-A900 is compatible as standard with the IP65F waterproof, dustproof, oilproof standard for use in a wide variety of environments.

■ EC Directive compliant (A985/A975/A970/A960GOT)

The A985GOT-TBA-EU, A975GOT-TBA-EU, A970GOT-TBA-EU, A970GOT-SBA-EU, A970GOT-LBA-EU and A960GOT-EBA-EU comply with the EC Directives. The EC Directives are laws stipulated by the European Union (EU).

CRT output (A985GOT)

Containing a CRT interface (SVGA 1 channel), the A985GOT can show the same screen as the display screen of the GOT-A985 on its large-screen CRT.



Software packages

Drawing function

A screen can be created by merely choosing objects (moving image function) from among a wide selection of templates and placing them on the screen.

After completion of screen layout, you can set monitor devices, etc.



Project manager

The project manager provides project information and screen information at a glance. Also, it is convenient to manage screen data since screen copy, movement and deletion can be made easily.

Debugging function

By connection of a personal computer and GOT-A900, the personal computer acts as a PLC and screen debugging can be made in a place where there is no PLC.



Effective utilization of data

(1) GPPW comment data

When specifying the device name, you can refer to the comments created on the GPPW function software package and set the monitor device on the GOT-A900. This facilitates device setting, reducing device address setting mistakes.



Device comments created with GPPW are listed.

- (2) Character data on a word processor can be utilized.
- (3) BMP file data can be read to realize a beautiful, highgrade screen display easily.
- (4) Machine drawings and other data can be imported using DXF file (Release 14) CAD drawing data.
- (5) You can use the screen data of the GOT800 series 100%. Also, the screen data of Digital's GP (GP PRO/PB III for Windows/DOS) can be used on the GOT-A900 series after conversion is made with the simple converter function. (Some functions cannot be converted.)
- GP (GP-PRO/PB III for Windows/DOS) is a trademark of Digital.

System Configuration

Software Packages

Operating environment

SYSTEM CONFIGURATION

Use SW D5C-GOTRE-PACK on a personal computer in the following operating environment.

Personal computer	Pentium 133MHz or more (recommended) Personal computer where Windows 95, Windows 98 or Windows NT 4.0 operates
Disk drive	CD-ROM drive required (for installation)
Main memory	32M bytes or more recommended
Hard disk free space	130MB or more (Standard installation capacity: 80MB, free space of 50MB or more for execution)
CRT	One usable with Windows 95, Windows 98 or Windows NT 4.0
Resolution	Resolution 800 × 600 pixels or more
Mouse, keyboard, printer, CD-ROM drive	Ones usable with Windows 95, Windows 98 or Windows NT 4.0

Connection with personal computer

An RS-232C cable is used to download screen data from a personal computer to the GOT.

Data transfer can also be made using a PC card.



Connection Forms Available for GOT-A900

Connection F	Q Mode	A Mode	
Bus connection	0	×	
CPU direct connection	0	0	
Serial communication module connection	RS-422 communication	0	0
(Computer link connection)	RS-232C communication	0	0
	Optical loop network	0	0
MELSECNET/10 connection	Coaxial bus network	0	0
	Optical loop network	×	0
MELSECNET/II connection	Coaxial bus network	×	0
MELSECNET/B connection		×	0
	Remote device	0	0
CC-Link connection	Intelligent device	0	0

 \bigcirc : Usable, \times : Unusable

* Incompatible with MELSECNET/10H connection.

Recommended cables for connection between personal computer and GOT





System Configuration

Connection to Q Mode CPU

Bus connection



Usable GOT-A900		A985GOT, A97 GOT, A960GOT, A951GOT-Q, A956GOT			
Necessary	A985GOT	When multiple GOTs are connected	A9GT-QBUS22S		
interface module	A97□ GOT-(B) A960GOT	When one GOT is connected or the last GOT when multiple GOTs are connected	A9GT-QBUSS		
	A956GOT	When multiple GOTs are connected	A9GT-QBUS2SU		
	A951GOT-Q	When one GOT is connected or the last GOT when multiple GOTs are connected	Unnecessary (A951GOT-Q contains bus connection interface)		
Connection cable		QC06B	0.6m cable (1.97 feet)		
		QC12B	1.2m cable (3.94 feet)		
		QC30B	3m cable (9.84 feet)		
		QC50B	5m cable (16.39 feet)		
		QC100B	10m cable (32.79 feet)		
		A9GT-QC200BS	20m cable (65.57 feet)		
		A9GT-QC300BS	30m cable (98.56 feet)		
		A9GT-QC350BS	35m cable (114.75 feet)		
Overall dista	nce	37m (121.31 feet) (note that this overall distance is from main base and includes inter-base cable			
		distances)			
Max. number of GOTs connected		5			
Number of I/O points occupied		16 points (handled as intelligent function module)			
Bus extension connector box		A9GT-QCNB	A9GT-QCNB		

Note 1: When there are extension bases, connect the GOT-A900 after the extension bases. (Extension bases cannot be connected after the GOT-A900.)

Note 2: If the first GOT cannot be connected within 13.2m(43.28feet) of the last base, the bus extension connector box (A9GT-QCNB) must be connected between the extension cable connector of the base and the cable.

Note 3: Connection of the GOT-A900 occupies one extension stage.

System Configuration

CPU direct connection



* The A953GOT contains the RS-232C communication interface and does not need the interface module.

* The communication speed that can be used by the A9GT-RS2 is up to 38.4kbps.



* The A950GOT contains the RS-422 communication interface and the A953GOT contains the RS-232C communication interface, and they do not need the interface module.

* The communication speed that can be used by the A9GT-RS4 and A9GT-RS2 is up to 38.4kbps.

MELSECNET/10 connection



Usable GOT-A900	A985GOT, A97□GOT(-B), A960GOT, A956GOT
Necessary interface	Network module
module	A7GT-J71LP23, A7GT-J71BR13
Connection cohie	Optical fiber cable
Connection cable	Coaxial cable
O	Conforms to network
Overall distance	specifications

* Incompatible with MELSECNET/10H connection.

* CPU device ranges accessible via MELSECNET/10 are indicated below.

Device Name			Setting/Monitoring Range	
	Input (X)			X0 to X7FF
	Output (Y)			Y0 to Y7FF
	Internal relay	' (W)		M0 to M8191
	Annunciator	(F)		F0 to F2047
	Link relay (B))		B0 to BFFF
e	Latch relay (I	_)		L0 to L8191
Bit device	Timer	Contact (T	T)	TT0 to TT255
it d	Timer	Coil (TC)		TC0 to TC255
ш	A (Contact (T	T)	CT0 to CT255
	Counter	Coil (TC)		CC0 to CC255
				Specified bit of following word
	Bit of word d	evice		device (except index register and
				buffer memory)
	GOT bit regis	ster (GB)		GB64 to GB1023
	Data register (D)			D0 to D6143
	Link register (W)			W0 to WFFF
	Timer (currer	nt value) (T)		T0 to T255
	Counter (cur	rent value) (C)	C0 to C255
ice			(Z)	Z0 to Z6(Z0=Z)
dev	Index register		(V)	V0 to V6(V0=V)
Word device	Accumulator	(A)		A0 to A1
Ň	Buffer memory (special			
	function module) (BM)			BM0 to BMn
	Word of bit d	ovice		Conversion of above bit device into
		evice		word (except timer and counter)
	Data register o	of GOT-A900	(GD)	GD64 to GD1023

Serial communication module connection

System Configuration

CC-Link connection



or intelligent station.

Usable GOT-A900	A985GOT, A97□GOT, A960GOT, A956GOT
Necessary interface module	 Intelligent device station A8GT-J61BT13 Remote device station A8GT-J61BT15
Connection cable	Shielded twisted cable
Max. cable length	Conforms to network specifications

When the GOT is used as an intelligent station, device comment display and T/C set value monitor changing in system monitoring function are not available. When the GOT is used as a remote device station, the system monitoring function cannot be used.

Connection to A Mode CPU

CPU direct connection



Usable GOT-A900		A985GOT, A97⊡GOT, A960GOT, A953GOT
Necessary interface module		A9GT-RS2
Connection RS-232C cable cable		QC30R2 (cable length 3m [9.84feet])
Max. cable length		3m (9.84 feet)

* The A953GOT contains the RS-232C communication interface and does not need the interface module.

* The communication speed that can be used by the A9GT-RS2 is up to 9600kbps.

Senal communication module connection		
Usable GOT-A900		A985GOT, A97□GOT(-B), A960GOT, A950GOT, A953GOT
Necessary	interface module	A9GT-RS4, A9GT-RS2
Connecti	RS-232C cable	User made
on cable	RS-422 cable	User made
Max. cable	RS-232C connection	15m (49.18 feet)
length	RS-422 connection	200m (655.74 feet)

* The A950GOT contains the RS-422 communication interface and the A953GOT contains the RS-232C communication interface, so they do not need an interface module.

* The communication speed that can be used by the A9GT-RS4 and A9GT-RS2 is up to 19.2kbps.

MELSECNET connection



Serial communication module connection

System Configuration

CC-Link connection



Usable GOT-A900	A985GOT, A97□GOT, A960GOT, A956GOT
Necessary interface module	 Intelligent device station A8GT-J61BT13 Remote device station A8GT-J61BT15
Connection cable	Shielded twisted cable
Max. cable length	Conforms to network specifications

About Options

Extended memory (A985/A97 /A960GOT)

Using the memory board can expand the internal memory. It is also needed to perform the optional functions (e.g. recipe function, voice output function).



L		
Туре	Remarks	
A9GT-FNB	For optional function only	
A9GT-FNB1M	For optional function + built-in memory of 1M bytes	
A9GT-FNB2M	For optional function + built-in memory of 2M bytes	
A9GT-FNB4M	For optional function + built-in memory of 4M bytes	
A9GT-FNB8M	For optional function + built-in memory of 8M bytes	
A9GT-QFNB	For optional function only	
A9GT- QFNB4M	For optional function + built-in memory of 4M bytes	
A9GT- QFNB8M	For optional function + built-in memory of 8M bytes	

Backlight

The GOT-A900 series allows the user to change the backlight easily. (On-the-spot replacement can be made easily.)

The EL does not have a backlight and needs no replacement.



Туре	Remarks	
A9GT-80LTT	For 12-inch, high-intensity TFT color liquid crystal	
A9GT-70LTT	For 10-inch, wide-angle vision TFT color liquid crystal	
A9GT-70LTS	For 10-inch, D-STN color liquid crystal	
A9GT-70LTTB	For 10-inch, high-intensity TFT color liquid crystal	
A9GT-50LT	For 6-inch, STN color/monochrome liquid crystal	

Protective sheet

Sheet for protection of the GOT-A900 screen. The "MITSUBISHI" logo is removable. To protect the screen, always use the protective sheet.



Туре	Remarks
A9GT-80PSC	Protective sheet for 12 inch, logo removable
A9GT-70PSC	Protective sheet for 10 inch, logo removable
A9GT-60PSC	Protective sheet for 9 inch, logo removable
A9GT-50PSC	Protective sheet for 6 inch, logo removable

System Configuration

PC card

The PC card is used to transfer the data of the monitor screen and to store the data of the alarm history and recipe functions.



Туре	Remarks
A9GTMEM-10MF	For GOT, memory capacity 10M bytes
A9G TIVIEIVI-TUIVIF	Flash PC card (formatted)
A9GTMEM-20MF	For GOT, memory capacity 20M bytes
A9G I IVIEIVI-20IVIF	Flash PC card (formatted)
	For GOT, memory capacity 40M bytes
A9GTMEM-40MF	Flash PC card (formatted)

* To use the PC card in the A95□GOT, the memory card interface module (flash PC card is unusable) is needed.

Debugging stand

Stand used to place the GOT on a desk for debugging.



Туре	Remarks
A9GT-80STAND	For 12-inch mounting
A9GT-70STAND	For 10/9-inch mounting
A9GT-50STAND	For 6-inch mounting

External I/O interface module

Using the external I/O interface module, you can provide external inputs (such as pushbuttons) and outputs (such as lamps, relays).



Remarks	
External I/O interface module (For A985GOT, A97 GOT (-B),	
(POT A933GOT, A97 🗆 GOT (-B), A960GOT)	
External I/O interface module (For A95 GOT (-M3))	

■ Printer interface module (A95□GOT(-M3))

The printer interface module is needed to use the printer function on the A95 GOT. (The printer interface module is not needed for the A985GOT, A97 GOT (-B) and A960GOT since they contain the printer interface.)

Туре	Remarks
A9GT-50PRF	Printer interface module for A95 GOT

GENERAL SPECIFICATIONS

General Specifications

General specifications of GOT-A900

Item		Specifications						
Operating ambient	Display sectio	Display section		0 to 40°C (0 to 55°C for A975/A970GOT-TBA(-B)/TBD(-B))				
temperature	Other than dis	play section	0 to \$	55°C				
Storage ambient temperature	-20 to 60°C							
Operating ambient humidity	10 to 90%RH,	non-condens	ing					
Storage ambient humidity	10 to 90%RH,	non-condens	ing					
				Frequency	Acceleration	Amplitude	Sweep count	
	to JIS B vibrat 3502, IEC 1131-2 Unde	Under interm	ittent	10 to 57Hz	_	0.075mm (0.003 inch)	10 times	
Vibration resistance		vibration		57 to 150Hz	9.8m/S ²		each in X, Y,	
		Under contin	uous	10 to 57Hz	_	0.035mm (0.001 inch)	Z directions (for 80 min.)	
		vibration	ation	57 to 150Hz	4.8m/S ²	_		
Shock resistance	Conforming to	JIS B 3502, I	EC 11	31-2 (147 m/s ² ,	3 times in each	of 3 directions 2	X, Y, Z)	
Environmentally resistant protective structure	IP65F or equiv	valent (front se	ection)					
Operating atmosphere	No corrosive g	No corrosive gases						
Operating altitude	2000m max. (6557.38 feet)							
Installation location	Inside control panel							
Overvoltage category * 1	II or less	II or less						
Pollution level *2	2 or less							

* 1: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises.

Category ${\rm I\!I}$ applies to equipment for which electrical power is supplied from fixed facilities.

The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

* 2: This index indicates the degree to which conductive material is generated in the environment where the equipment is used. In pollution level 2, only non-conductive pollution occurs but temporary conductivity may be produced due to condensation.

Performance Specifications

Performance specifications of A985/A975/970/960GOT

				Specification	ons		
Item		A985GOT-TBA*1 A985GOT-TBD*1 A980GOT-TBA-EU*1	A975GOT-TBA*1 A975GOT-TBD*1 A975GOT-TBA-B*2 A975GOT-TBD-B*2 A975GOT-TBA- EU*2	A970GOT-TBA*1 A970GOT-TBD*1 A970GOT-TBA-B* A970GOT-TBD-B* A970GOT-TBD-B* A970GOT-TBA- EU*2	SBA 2 A970GOT-	A970GOT- LBA A970GOT- LBD A970GOT- LBA-EU	A960GOT-EBA A960GOT-EBD A960GOT-EBA-EU
	Туре	•	* 1 Wide-angle vision TFT color liquid crystal * 2 High-intensity TFT color liquid crystal			Monochro me liquid crystal	High-intensity EL
Display	Resolution (pixels)	800 × 600	Interisity (F) Color induct clystal Crystal Crystal 640 x 480 640 x 480				
section	Display size (mm (inch))	246×184.5 (11.19×7.27)	211 × 158 (8.31×6.2	23)			192 × 120(7.56×4.73)
	Display color (colors)	256		16	8	2 (Monochro)	2 (yellow/orange, black)
Backligh	t	Cold-cathode backlight (ba	acklight OFF/screen s	ave time can be se	t)		—
	Number of touch keys [points]	1900 (38 rows × 50 columns)	1200 (30 rows × 40 colur	nns)			1000 (25 rows × 40 columns)
Touch panel	Key size [pixels]	Minimum 16 × 16 (per key) 8 × 16 on bottom row only	Minimum 16 × 16 (p	er key)			
	Repeat function	No					
	Туре	Flash ROM					
Memory	Application	For storing monitor screen	data, for storing OS				
	Capacity	Built-in 1M bytes (user area), max. 9M bytes can be increased.					
Commur	nication board slot	1 slot for communication b	oard loading				
Commur interface	nication module	1 channel for communicat	ion module loading				
Option m	nodule interface	1 channel for option modu	le loading (e.g. A9GT	-70KBF)			
PC card	interface	1 channel for PC card load	ding				
Memory	board slot	1 slot for memory board lo	ading				
RS-2320	C interface	1 channel for personal cor	nputer connection, ba	r-code reader conn	ection		
CRT inte	erface	SVGA 1 channel for CRT connection	_				
Printer ir	nterface	1 channel for parallel print	er connection				
Voice ou	tput terminal	For external speaker conn playable voice file: Window					(under rated load 10 ର),
Buzzer o	output	Single tone (sound length	adjustable)				
Display section [h]		41,000 (operating ambient	t temperature: 25°C)		50,000 (operating a temperature		30,000 (initial brightness 70%, operating ambient tempereture: 25°C)
Life	Backlight [h]	40,000			10,000		
Life	Backlight [h]	(Period when display brigh	ntness becomes 50%	at operating ambier	t operating ambient temperature of 25°C)		
	Touch key	1 million times or more (op	perating force not more	e than 0.98N)			
Built-in/extra Number of write times: 100,000 times							
Weight (kg (lb))	TBA :2.35 (5.17) TBD :2.30 (5.06)	1.70 (3.74)	SI	BA/LBA :1.78 (3.9 BD/LBD :1.80 (3.9 BA-EU :1.78 (3.92	96) 2)	EBA :1.51 (3.32) EBD :1.60 (3.52) EBA-EU :1.58 (3.48)
Compati package	ble software	Q mode: SW2D5C-GOTR A mode: SW0D5C-GOTR LB : SW1D5C-GOTR-P/	E-PACK Version A or	later (bus connecti later (A985GOT-TE	ion: SW3D5C-GC	TRE-PACK or	

Performance Specifications

■ Performance specifications of A950/A951/A953/956GOT

			Speci	fications				
	ltem	A950GOT-SBD A950GOT-SBD-M3 A950GOT-LBD A950GOT-LBD-M3	A951GOT-QSBD A951GOT-QSBD-M3 A951GOT-QLBD A951GOT-QLBD-M3	A953GOT-SBD A953GOT-SBD-M3 A953GOT-LBD A953GOT-LBD-M3	A956GOT-SBD A956GOT-SBD-M3 A956GOT-LBD A956GOT-LBD-M3			
	Туре	(Q)SBD(-M3): STN color liquid (Q)LBD(-M3): Monochrome liq	(Q)SBD(-M3): STN color liquid crystal					
Display	Resolution (pixels)	320 × 240						
section	Display size (mm (inch))	115 × 86 (4.53 × 3.3)						
	Display color (colors)	(Q)SBD(-M3): 8 (Q)LBD(-M3): 2 (monochrome)					
Backligh	it	Cold-cathode backlight (backli	ght OFF/screen save time can b	e set)				
Touch	Number of touch keys [points]	300 (15 rows × 20 columns)						
panel	Key size [pixels]	Minimum 16 × 16 (per key)	Minimum 16 × 16 (per key)					
	Repeat function	No						
	Туре	Flash ROM						
Memory	Application	For storing monitor screen data, for storing OS						
	Capacity	Built-in 1M bytes (user area) (3M bytes (user area) for M3 type)						
RS-2320	C interface	_	—	1 channel built-in	—			
RS-422	interface	1 channel built-in	_	-	-			
Bus inter	rface	_	1 channel built-in	-	-			
Commur interface	nication module	_	_	_	1 channel built-in			
Optional	module interface	1 channel for optional module • A1SD59J-MIF • A8GT-50KBF • A9GT-50PRF	loading					
RS-2320	C interface	1 channel for personal comput	er connection, bar-code reader	connection				
Buzzer c	output	Single tone (sound length adju	stable)					
	Display section [h]	50,000 (initial brightness 70%, operating ambient temperature: 25 $^\circ extsf{C}$)						
Life	Backlight [h]	40,000 (period when display b	rightness becomes 50% at opera	ating ambient temperature of 25°	C)			
Life	Touch key	1 million times or more (operat	ing force not more than 0.98N)					
	Built-in/extra memory	Number of write times: 100,00	0 times					
Compati package	ble software	Q mode: SW2D5C-GOTRE-P A mode: SW1D5C-GOTRE-P	·	nection: SW3D5C-GOTRE-PAC	ς or later)			

Performance Specifications

Power supply section specifications of GOT-A900

			Speci	cations		
Item		A9□□GOT-□BA(-B,-EU)	A985GOT-TBD A97□GOT-□BD(-B) A960GOT-EBD	A950GOT-□BD (-M3) A951GOT-Q□BD (-M3) A953GOT-□BD (-M3)	A956GOT-[]BD - (M3)	
Input power sup	oply	100 to 240VAC (+10%, -15%)	24VDC (+25%, -20%)	24VDC (+10%, -15%)		
Input frequency	[Hz]	50/60Hz±3Hz	_			
Input max. appa	arent power	50VA max. (at 100VAC input). 60VA for other than RS-422, RS-232C, bus connection 63VA max. (at 200VAC input) 75VA for other than RS-422, RS-232C, bus connection	_		_	
Input max. pow	er	40W		12W	16W	
Inrush current		40Ap max. (264VAC, max. load)	61Ap max. (30VDC, max. load)	40Ap max. (26.4VDC, max. lo	ad)	
Permissible ins power failure tir		20ms (100VAC or more)	1ms (19.2VDC or more)	1ms (20.4VDC or more)		
Noise immunity	e immunity By noise simulator of 1,500Vp-p noise voltage, 1µs noise with and 25 to 60Hz noise frequency			o noise voltage, 1 μ s noise with a	nd 25 to 60Hz noise frequency	
Dielectric withst	Dielectric withstand voltage 1500VAC for 1 minute across AC external terminals-earth (EU: 3600VAC for 1 second)		500VAC for 1 minute across DC external terminals-earth			
Insulation resist	tance	10M Ω or more by insulation re	esistance tester			
External output		Transistor output, 2 points (RL	IN, OUTPUT)			
Insulation s	system	Photocoupler insulation				
Rated load	voltage	12V/24VDC				
Operating l range	oad voltage	10.2 to 30VDC (peak voltage 3	30V)			
Max. load o	current	0.1A/point, 0.2A/common				
Max. inrust	n current	0.4A, within 10ms		_		
OFF time lo current	eakage	0.1mA max.				
ON-time m drop	ax. voltage	1.0VDC(TYP.)0.1A, 2.5VDC(N	IAX.)0.1A			
Response	OFF to ON	10ms max. (resistive load)				
time	ON to OFF	10ms max. (resistive load)				
Surge supp	Surge suppressor Zener diode					
Applicable wire	size	0.75 to 2mm ²				
Applicable crim terminal	ping	RAV1.25-3, V2-S3.3, V2-N3A,	FV2-N3A			
Applicable tight torque	ening	58.8N / cm to 88.2N / cm				

Performance Specifications

Performance specifications of communication boards and communication modules

• Performance specifications of bus boards

Item	A9GT-QBUSS	A9GT-QBUS2S	A9GT-QBUS2SU
Application	For connection of 1 GOT	For connection of multiple GOTs	For connection of multiple GOTs for A950
Number of bus ports	1	2	2
Applicable PLC	Q mode PLC only	Q mode PLC only	Q mode PLC only
Weight (g(lb))	90 (0.20)	100 (0.22)	170 (0.37)

Performance specifications of serial communication boards

Item	A9GT-RS2	A9GT-RS4	
Interface connector	9-pin D-sub (male) inch screwing type	9-pin D-sub (male) inch screwing type	
Communication speed	38400bps	38400bps	
Weight (g(lb))	90 (0.20)	98 (0.22)	

• Performance specifications of network and data link modules

ltom	Network Module			Data Link Module				
Item	A7GT-J71LP23	A7GT-J71BR13		A7GT-J71AP23	A7GT-J71AR23	A7GT-J71AT23B		
Communication speed	10Mbps (20Mbps: multiple transmission)	10Mbps		10Mbps		0Mbps 1.25Mbps		125k/250k/500k/1 Mbps
Communication system	Token ring system	Token bus s	ystem	Polling system				
Synchronization system	Frame synchronization sys	Frame synchronization system						
Transmission path format	Duplex loop	Simplex bus		Duplex loop		Bus		
Overall distance	30km(98360.66feet) When using SI cable: 500m (639.34feet) between stations When using QSI cable: 1km(3278.69feet) between stations	3C-2V 300m (983.61feet) (300m between stations)	5C-2V 500m (1639.34 feet) (500m between stations)	10km (32786.89feet) (1km (3278.69feet) between stations)	10km (32786.89feet) (500m (1639.34feet) between stations)	125kbps: 1200m(3934.43feet) 250kbps: 600m(1967.21feet) 500kbps: 400m(131.48feet) 1Mbps: 200m(655.74feet)		
Weight (g(lb))	350 (0.77)			290 (0.64)	300 (0.66)	300 (0.66)		

Performance specifications of CC-Link communication modules

Item	A8GT-J61BT13	A8GT-J61BT15		
CC-Link station type	Intelligent device station	Remote device station		
Communication speed	156k/625k/2.5M/5M/10Mbps			
Overall distance	Depends on transmission speed. Independently of transmission speed setting, at least 2m (6.56feet) is required as inter-station cable length between master/local station and preceding or subsequent station At transmission speed of 5Mbps or 10Mbps, note that max. transmission distance differs according to inter- station cable length between remote I/O/remote device stations. 156kbps:1200m(3934.43feet) /625kbps:600m(1967.21feet) /2.5Mbps:200m(655.74feet) /5Mbps:110m to 150m(360.66 to 491.80feet) /10Mbps:50m to 100m(163.93 to 327.87feet)			
Max. number of modules connected	26 (when 1 station is occupied)	32 (when 2 stations are occupied)		
Weight (g(lb))	210 (0.46) 200 (0.44)			



Function List

Function list

	Function	Outline
	Numeric display function	Shows values stored in PLC devices.
Data display	Data list display function	Collects states of multiple word devices at given intervals and shows value in tabulated form.
function	ASCII display function	Regards data stored consecutively in word devices as a character code (ASCII code, shift JIS code) and shows a character string.
	Clock display function	Shows clock data of PLC CPU.
	Comment display function	 Comment display (bit) function Shows comment associated with ON/OFF of bit device. Comment display (word) function Shows comment associated with value of word device.
Message display	Alarm history display function	Shows as history data the ON states of specified bit devices and the occurrence times, comments and others when word device value condition holds.
function	Alarm list display function	 System alarm function Checks for GOT/PLC CPU/MELSECNET communication error at interva of 3 seconds and shows error code and error message at occurrence of error. User alarm function Associates multiple bit devices with comments and shows ON bit device in order of specified priority.
	Part display function	 Part display (bit) function Shows part associated with ON/OFF of bit device. Part display (word) function Shows part associated with value of word device.
Moving image	Part motion display function	Shows in motion or in path the part figure associated with bit device ON/O or word device value in the specified moving method.
display function	Lamp display function	 Lamp display (bit) function Lights/extinguishes lamp according to ON/OFF of bit device. Lamp display (word) function Changes lamp lit-up color according to value of word device.
	Panel meter display function	Shows on meter the ratio of word device value to high/low value.
	Trend graph display function	Gathers data stored in word device at specified timing, shows trend graph and after showing it to the end of display range, scrolls.
	Line graph display function	Batch-gathers data of multiple word devices and shows line graph.
Graph display	Bar graph display function	Shows data stored in multiple word devices in bar graph.
function	Statistic graph display function	Collects data of multiple word devices and graphs the ratio of each word device data to the whole.
	Level display function	Shows in level the ratio of word device value to high/low value in any close figure.
Touch key function	י <u></u>	Touching the screen allows device change, screen switching, etc.
Data input	Numeric input function	Writes any value to specified word device.
function	ASCII input function	Writes any ASCII and shift JIS code to specified word device.



Function List

		Function	Outline
		Report function	 Numerical data stored in word devices or special function module buffer memory are gathered and printed per data collection trigger, or comments associated with numerical data or bit device ON/OFF are printed. Logging report Data are gathered and printed per data collection trigger and data to be printed next are printed subsequently without page break of printer paper. Real-time report Data are gathered per data collection trigger, collected data are stored into PC card, and data stored in PC card are printed at printing trigger.
uo		Hardcopy function	ON/OFF of bit device or touching of touch key (extended function) causes currently displayed monitor screen of GOT to be printed or saved into PC card in BMP file format.
j functi	Other object	System information function	PLC CPU checks GOT operating status or transmits information on GOT900 series operating status to GOT.
Drawing function	functions	Status monitoring function	Performs write/operation to PLC CPU when specified condition holds (specified bit device turns ON/OFF).
		Alarm flow function	Used to associate comments with multiple bit devices and show comments of ON bit devices in order of occurrence in right-to-left flow of base screen.
		Recipe function	Writes/reads device value to specified device of PLC CPU under specified condition (device ON/OFF).
		Voice function	Used to set WAV-format voice file for playing voice as error warning sound message or as touch sound at touch of touch key.
		Test function	Used to show test window during monitor screen display to change device values. (This function is also valid during ladder monitor function.)
		Bar code function	Data read by bar-code reader connected to GOT is written to PLC CPU.
		Operation panel function	Operation panel is used to perform write to devices, e.g. touch input, numerical input and screen switching, from outside GOT.
Mainte	enance function	System monitor function	Monitors/tests PLC CPU devices and special function module buffer memory.
Security function			 Screen level security Can protect screen switching, hide display partially, and protect input operation. Can also protect switching to optional functions such as system monitor function. System level security Protects switching to system screen (utility function) such as setup screen. Project level security Protects uploading of screen data.
Other	functions	Printer function	Performs print-out of alarm history, output of daily/monthly report (report function), color hard copy of display screen, etc.



External Dimensions

A985/A97 /A960/A95 GOT





Туре	А	В	С	D	Е	F
A985GOT	312	301	238	227	43	49
	(12.29)	(11.86)	(9.38)	(10.91)	(1.58)	(1.93)
A97_GOT	297	288	208	199	40	46
(-B)	(11.70)	(11.35)	(8.20)	(7.84)	(1.58)	(1.81)
A960GOT	268	257	192	182	43	49
	(10.56)	(10.13)	(7.56)	(7.17)	(1.69)	(1.93)
A95_GOT	164.5	155.5	136	123	51	57
(-M3)	(6.48)	(6.13)	(5.36)	(4.85)	(2.01)	(2.25)

Unit : mm(inch)

Panel cutting dimension

▲ A(+1.0, -0)	Туре	А	В
Panel opening	A985GOT	302 (11.90)	228 (8.98)
B(+1.0, -0)	A97_GOT	289	200
B(+	(-B)	(11.39)	(7.88)
	A960GOT	258	183
Values in () are tolerance	s	(10.17)	(7.21)
in mm unit.	A95_GOT	156	123.5
	(-M3)	(6.15)	(4.87)

Unit : mm(inch)

Product mounting clearances



A-area dimensions

Since the connection cable of the GOT-A900 is pulled out in a downward direction, the following space is required in consideration of its flexing radius.

Туре	А	
A985GOT	130 (5.12) or more	
A97_GOT		
A960GOT	140 (5.52) or more	
A950/951/953GOT	130 (5.12) or more	
A956GOT	130 (5.12)or more (165mm (6.50inch) or more for use of optical fiber cable in	
	MELSECNET connection)	

Unit : mm(inch)

B-area dimension

To use the memory card or voice output device, 100mm (3.94inch) or more space is needed in consideration of cable pulling-out or memory card loading/unloading. (50mm (1.97inch) or more when they are not used.)

C-area dimension

To ensure good ventilation, provide 80mm(3.15inch) or more distance from structure or other devices at top of the unit.

D-area dimension

When a device which generates radiated noise, etc. (such as a contactor) and/or a device which generates heat is placed around the GOT, leave a

100mm(3.94inch) or more clearance at the back and 50mm(1.97inch) or more clearances on the right- and left-hand sides to avoid the influence of noise and heat.

* The ambient temperature of the unit should not be higher than 55° C.

6. APPENDICES

1. SAFETY REQUIREMENTS	
Safety Precautions6-2	
2. LOADING AND INSTALLATION	
Loading and Installation6-3	
3. COMPATIBILITY WITH THE Y2K PROBLEM	
Compatibility of MELSEC Q Series CPU Modules with	
the Y2K Problem6-10	
4 INTRODUCTION TO MELFANSweb	
• MELFANSweb6-11	
5 MODEL LIST	
• Q Mode Model List6-12	
• A Mode Model List6-14	
• Q/A Mode Common Model List6-15	
Accessories Shared Among Q/AnS Series I/O6-18	
CC-Link Remote Devices6-19	
Software, Peripheral Devices6-21	
Personal Computer Network Boards6-23	
GOT-A900 Graphic Operation Terminal6-24	
• ID Systems	
6 SERVICE NETWORK	
Service Network	

SAFETY REQUIREMENTS

Safety Precautions

Safety Precautions (Always read these precautions)

When using the Q series products, thoroughly read the manuals packed with the individual products and the associated manuals introduced in the manuals packed with the products, and also pay careful attention to safety and handle the equipment properly.

The precautions given in this section are concerned with all Q series products and describe only the items to be noted in the design stage. For the precautions for individual products and the precautions for installation, wiring, starting, maintenance, usage and disposal of the products, always refer to the QCPU (Q Mode) User's Manual (Hardware Design/Maintenance and Inspection) and the user's manuals of the individual products. These [Safety Precautions] classify the safety precautions into two categories: "DANGER" and "CAUTION".

DANGER	Procedures which may lead to a dangerous condition and cause death or serious injury if not carried out properly.
ACAUTION	Procedures which may lead to a dangerous condition and cause superficial to medium injury, or physical damage only, if not carried out properly.

Depending on circumstances, procedures indicated by CAUTION may also be linked to serious consequences. In any case, it is important to follow the instructions.

DESIGN PRECAUTIONS

- Install a safety circuit external to the PLC that keeps the entire system safe if an external power supply fault or PLC failure occurs. Otherwise, accidents could result from false output or malfunction.
 - (1) Outside the PLC, construct mechanical damage preventing interlock circuits such as emergency stop, protective circuits, forward/reverse or other opposed-motion interlocking circuits, and positioning upper and lower limits switches.
 - (2) When the PLC detects either of the following faulty conditions, it may stop operation and turn off all outputs.
 - The overcurrent protection or overvoltage protection of the power supply module is activated.
 - The PLC CPU detected a fault, such as the watchdog timer error, with its self-diagnostic function.

In addition, all outputs may be turned on when there is a fault that the PLC CPU cannot detect, such as in the I/O controller. Build a fail-safe circuit or provide a proper mechanism outside the PLC that will make sure the machine will operate safely at such times.

For fail-safe circuit examples, refer to "Loading and Installation" on the next page.

- IMPORTANT: Whether outputs are turned off or not depends on the Hold/Clear selection preset per output module. When Hold is selected, outputs are not turned off if a faulty condition is detected. Therefore, always make up a necessary external safety circuit.
- (3) Outputs could be left on or off when there is a problem in the output module relay or transistor. Build an external monitoring circuit that will monitor any output signal that could cause serious accidents.
- When overcurrent which exceeds the rating or caused by short-circuited load flows in the output module for a long time, it may cause smoke or fire. To prevent this, configure an external safety circuit, such as a fuse.
- Build a circuit that turns on the external power supply when the PLC power supply is turned on. If the external power supply is turned on first, it could result in false output or malfunction.
- When a communications fault occurs in the data link, the faulty station is placed in the following states. Using communications status information, configure an interlock circuit in the sequence program so that the system operates safely. Not doing so could result in false output or malfunction.
 - (1) The data link data prior to the communications fault is held intact.
 - (2) All outputs turn off in the remote I/O stations of MELSECNET(II, /B, /10) and CC-Link.
 - (3) In the remote I/O stations of MELSECNET/MINI-S3, outputs are held or all outputs turn off in accordance with E.C. mode setting.

For checking a faulty communications station or the operating status at a communications fault, refer to the corresponding data link manual.

Do not bundle the control and communication cables with the main circuit and power cables, or install them close to each other. They should be installed 100 mm (3.94inch) or more away from each other. Not doing so could result in noise that would cause malfunction.

MOUNTING PRECAUTIONS

Use the PLC in the environment that meets the general specifications given in this manual. Using this PLC in any environment outside the range of the general specifications could result in electric shock, fire, malfunction, or damage to or deterioration of the product.

WIRING PRECAUTIONS

- Be sure to ground the FG terminals and LG terminals to the protective earth conductor. Not doing so could result in electric shock or malfunction.
- Use the PLC at the rated voltage of each module. Using it at any different voltage can cause a fire or failure.
- Do not connect the outputs of multiple power supply modules in parallel. Doing so can heat the power supply modules, causing a fire or failure.

Loading and Installation

Safety Considerations

When the PLC power supply is switched $ON \rightarrow OFF$, proper process output may not be provided temporarily due to differences in delay time and starting time between the PLC power supply and PLC output load power supply (especially DC).

For example, if the output load power supply is switched on in a DC output module and the PLC power supply is then switched on, the DC output module may provide false output instantaneously at power-on of the PLC. Therefore, it is necessary to make a circuit which can switch on the PLC power supply first.

Also, an abnormal operation may be performed if an external power supply fault or PLC failure takes place. To prevent any of these abnormal operations from leading to the abnormal operation of the whole system, areas which can result in machine breakdown and accidents due to abnormal operations (e.g. emergency stop, protective and interlock circuits) should be constructed outside the PLC.

Examples of system design circuits in the above viewpoint are given below.

- System design circuit example 1 (when not using ERR contact of power supply module)
- When using Q mode



- When PLC power supply and output power supply are both AC
- (1) Switch power ON.
- (2) Set CPU to RUN.
- (3) Turn ON the start switch.
- (4) When the magnetic contactor (MC) comes on, the output equipment is powered and driven by the program.
- When PLC power supply is AC and output power supply is DC
- (1) Switch power ON.
- (2) Set CPU to RUN.

- (3) When DC power is established, RA2 goes ON.
- (4) Timer (TM) times out after the DC power reaches 100%. (The TM set value should be the period of time from when RA2 goes ON to the establishment of 100% DC voltage. Set this value to approximately 0.5 seconds.)
- (5) Turn ON the start switch.
- (6) When the magnetic contactor (MC) comes on, the output equipment is powered and driven by the program. (If a voltage relay is used at RA2, no timer (TM) is required in the program.)

Appendices

LOADING AND INSTALLATION

Loading and Installation

System design circuit example 2 (when using ERR contact of Q61P-A1/Q61P-A2 power supply module)



- When PLC power supply is AC and output power supply is DC
- (1) Switch power ON.
- (2) Set CPU to RUN. ERR contact turns ON.
- (3) When DC power is established, RA2 goes ON.
- (4) Timer (TM) times out after the DC power reaches 100%. (The TM set value should be the period of time from when RA2 goes ON to the establishment of 100% DC voltage. Set this value to approximately 0.5 seconds.)
- (5) Turn ON the start switch.

(6) When the magnetic contactor (MC) comes on, the output equipment is powered and may be driven by the program. (If a voltage relay is used at RA2, no timer (TM) is required in the program.)

The power-ON procedure is as follows:

Note: Only the $\overline{\text{ERR}}$ contact of the power supply module loaded in the main base is valid. The $\overline{\text{ERR}}$ contact of the power supply module loaded in the extension base cannot be used.
LOADING AND

Loading and Installation

When using A mode



- (1) Switch power ON.
- (2) Set CPU to RUN.
- (3) Turn ON the start switch.
- (4) When the magnetic contactor (MC) comes on, the output equipment is powered and may be driven by the program.
- When PLC power supply is AC and output power supply is DC
- (1) Switch power ON.
- (2) Set CPU to RUN.
- (3) When DC power is established, RA2 goes ON.

- (4) Timer (TM) times out after the DC power reaches 100%. (The TM set value should be the period of time from when RA2 goes ON to the establishment of 100% DC voltage. Set this value to approximately 0.5 seconds.)
- (5) Turn ON the start switch.
- (6) When the magnetic contactor (MC) comes on, the output equipment is powered and may be driven by the program. (If a voltage relay is used at RA2, no timer (TM) is required in the program.)

LOADING AND INSTALLATION

Loading and Installation

Fail-safe measures against failure of the PLC

Failure of a PLC CPU or memory can be detected by the self diagnosis function. However, failure of I/O control area may not be detected by the CPU.

In such a case, all I/O points turn ON or OFF depending on a condition of a failure, and normal operation and safety may not be maintained.

Though Mitsubishi PLCs are manufactured under strict quality control, configure an external fail-safe circuit so that a PLC failure occurring for some reason would not lead to machine damage or accidents.



*1: Y00 alternates between ON and OFF at 0.5 second intervals.

Use a no-contact output module (transistor in the example shown above).

PLC Generated Heat Calculation

The temperature inside an enclosure containing the PLC must be kept below the operating ambient temperature given in the general specifications. Hence, heat in the panel must be calculated from the average power consumption of the equipment contained therein. This section explains how to find the average power consumption of the Q series system. Calculate an in-panel temperature rise from the power consumption.

Calculation of average power consumption

Power is consumed by the following PLC areas.



• Power consumption of power supply module Approximately 70% of the power supply module current is converted into power, with the remaining 30% dissipated as heat, i.e. 3/7 of the output current is used by the power supply module. Therefore, the calculation expression is as follows.

$$Wpw = \frac{3}{7} \times (I_{5\vee} \times 5) (W)$$

Isv: 5VDC current consumption of each module

Total 5VDC circuit power consumption of modules

The 5VDC output circuit power of the power supply module is the total power consumption of the modules.

$$W_{5V} = I_{5V} \times 5$$

 Total 24VDC average power consumption of output module (power consumption of points switched on simultaneously)

The average power of the external 24VDC power supply is the total current consumption of the modules.

 $W_{24V} = I_{24V} \times 24(W)$



Loading and Installation

 Average current consumption due to output section drop voltage of output module (power consumption of points switched on simultaneously)

 $\label{eq:Wout} \begin{array}{l} \text{Wout} = \text{Iout} \times \text{Vdrop} \times \text{number of output points} \times \\ \text{simultaneous ON ratio (W)} \end{array}$

IOUT : Output current (actual operating current) (A)

 $\label{eq:Vdrop} Vdrop \ : Drop \ voltage \ of \ each \ output \ module \ (V)$

- Input section average power consumption of input module (power consumption of points switched on simultaneously)
 - $$\label{eq:Win} \begin{split} \text{Win} = \text{Iin} \times \text{E} \times \text{number of input points} \times \\ \text{simultaneous ON ratio (W)} \end{split}$$
 - IN : Input current (effective value for AC) (A)
 - E : Input voltage (actual operating voltage) (V)
- Power consumption of intelligent function module power supply section when Q mode is used

```
Ws = I5v \times 5 \times I24v \times 24 \times I100v \times 100 (W)
```

• Power consumption of whole PLC system The sum of the above values is the power consumption of the entire PLC system.

 $W = W_{PW} + W_{5V} + W_{24V} + W_{OUT} + W_{IN} + W_{S} (W)$

Further calculations are necessary to work out the heat generated and a temperature rise in the panel. Generally a temperature rise in the panel is expressed as follows.

- T = <u>W</u>[°C]
- W : Power consumption of the entire PLC system (obtained as above)
- A : Panel inside surface area [m²]
- U : if the panel temperature is uniform....6 if the panel air is not circulated.......4

POINT

If the temperature rise in the enclosure exceeds the specified range, it is recommended to install a heat exchanger to lower the temperature in the panel. If an ordinary fan is used, it will suck not only external air but also dust, etc. Note that conductive dust, etc. may affect the PLC.

Base Module Mounting

Mounting instructions

Note the following when mounting the PLC in an enclosure, etc.

- Leave a minimum of 30mm(1.18inch) clearance above the PLC to ensure proper ventilation and ease of module replacement.
- (2) The PLC must not be installed on its side, horizontally or to a ceiling to ensure proper ventilation.
- (3) Ensure that the surface on which the base is to be mounted is flat to prevent possible flexing of the printed circuit boards.
- (4) Do not mount the PLC close to sources of vibration like large magnetic contactors or no-fuse breakers.
- (5) Use wiring conduits where appropriate.

For installations with conduit running closer to the PLC than the clearances shown on the next page, note the following.

1) When used above the PLC, the conduit should be less than 50mm(1.97inch) deep to allow proper ventilation.

Leave an adequate clearance above the PLC to tighten or remove the mounting screws in the module top. Module replacement cannot be made if the mounting screws cannot be accessed.

- When used below the PLC, ensure that there is an adequate clearance for the 100/200VAC input cable of the power supply module and the I/O and 12/24VDC cables of the I/O modules.
- (6) Equipment fitted before the PLC (fitted at the back of the panel door) should be installed at least 100mm (3.94 inch) away from the PLC to protect it from radiated noise and heat.

Also, any equipment on either side of the base module should be at least 50mm (1.97 inch) away from the base module.



Loading and Installation

Mounting

(1) When using Q6 B extension base

(2) When using QA1S6 B extension base Indicates the panel top, wiring duct or any assembly. **30mm**(1.18inch) 30mm(1.18inch) B) Main base (Q3) Main base (Q3 B) or more or more -30mm(1.18inch) -30mm(1.18inch) ŧ or more 7 or more _30mm(1.18inch) or more Extension base (Q6 B) Extension base (QA1S6 В or more Duct (Height 50mm (1.97inch) max.) **3**0mm(1.18inch) or more 1 **30mm**(1.18inch) / or more Series mounting Panel, etc. PLC Door Contactor, relay, etc. 100mm (3.94inch) or more PLC front clearance Vertical mounting Horizontal mounting from equipment (Not allowed) (Not allowed)

LOADING AND INSTALLATION

Loading and Installation

Wiring

Wiring instructions

This section gives the instructions for wiring the power supply and I/O cables.

Power supply wiring

(1) Wire the PLC power supply, I/O equipment and other equipment in separate lines as shown below.

Connect an insulating transformer if there is noise. Main PLC Insulating supply supply supply in transformer 200VAC - PLC Insulating L/O power T1_-

(2) The 100VAC, 200VAC and 24VDC cables should be twisted as tightly as possible in the shortest possible

length. Use the largest possible gauge (max. 2mm²) to minimize any voltage drop.

Main circuit

(3) As a measure against surges due to lightning, use a surge absorber as shown below.



POINTS

- (1) Ground the surge absorber (E1) and PLC (E2) separately.
- (2) When selecting a surge absorber, make due
- allowance for increases in the power supply voltage.

- I/O equipment wiring
- (1) Run the input and output lines separately.
- (2) When the I/O signal cables cannot be separated from the main circuit and power lines, use a batch-shielded cable grounded at the PLC end, or in some cases, at the opposite end.



- (3) Where wiring runs through piping, securely ground the piping.
- (4) Run the 24VDC I/O cables separately from 100VAC and 200VAC cables.
- (5) Wiring over 200m (656.17ft.) or further may give rise to leakage currents due to the line capacity, causing false inputs. This must be corrected by taking proper measures.
- Grounding

The way of grounding indicates below ((1), (2) and (3)).

- (1) Where possible, independently ground the PLC to the protective earth conductor. (Grounding resistance 100 Ω max.)
- (2) When independent grounding is impossible, use the shared grounding method shown in 2).



(3) Use 2mm² or larger grounding wire. The grounding points should be as near as possible to the PLC to minimize the grounding cable length.

COMPATIBILITY WITH THE Y2K PROBLEM

Compatibility of MELSEC Q Series CPU Modules with the Y2K Problem

Both the Q and A mode CPUs of the Q series will operate properly in and after the year 2000. Compatibility with the year 2000 (Y2K) problem will be described below. It should be noted that there are differences in compatibility between the Q and A mode CPUs.

Q mode CPU	Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU,
	Q25HCPU
A mode CPU	Q02CPU-A, Q02HCPU-A, Q06HCPU-A

Q Mode CPU

Clock timing range

The timing range of the Q mode CPU clock function is from January 1, 1980 to December 31, 2079.

Leap year date compensation

The Q mode CPU automatically compensates for a leap day within the above timing range.

Recognition of years in and after 2000

The Q mode CPU has four-digit year data. It will not mistake the year 2000 for 1900 if you create a sequence program which will handle the year data in four digits.

A Mode CPU

Clock timing range

The A mode CPU clock function has only two-digit year data. Namely, it times from January 1, 00 to December 31, 99 in every century and cannot recognize differences between 1900, 2000 and 2100.

Leap year date compensation

The A mode CPU makes automatic leap year compensation correctly until February 28, 2100. Though there is no leap day of February 29, 2100, the CPU times as if there is a leap day, so the clock data must be re-set on March 1, 2100.

Recognition of years in and after 2000

As described above, the A mode CPU has only two-lowerdigit year data. When the year data is handled in a sequence program, proper processing may not be performed depending on the way of handling. For example, when years are compared to know whether one is greater or less than the other, comparison in the two lower digits will lead to the judgment that 2000 is older than 1999. In a system where a personal computer or similar external device reads the A mode CPU devices via the computer link module, MELSECNET(II)/10 module or the like to perform result management, the data in and after 2000 will be handled as older than the data prior to 2000 if the clock data of the A mode CPU has also been rearranged into the reading time series.

INTRODUCTION TO MELFANSweb

MELFANSweb

MELFANSweb: Information retrieval and communication on the Internet



Product lineup

Introduces the outlines of our products per series. This is useful to get the entire picture, e.g. product types.

New products

Introduces products released recently or to be released soon.

Standard-compliant products

Introduces products which comply with various standards, such as explosion-proof and shipborne products, and with foreign standards, such as UL and EN.

Product details

Provides detailed information on individual products such as specifications, functions, features, wiring examples and outline dimensional drawings. These can be exported as images.

Manual guidance

Offers information on the manuals packed with the products and optional manuals, e.g. updated version and new product-compatible manual lists.

What's New

Notice of items recently added or changed. Use this when you want to know only the newest information.

Announcement

Notice of expansion plans, etc. from the MELFANSweb. View this from time to time.

Contact

Introduces the locations and handling models of the Japanese domestic and overseas sales sites (branches, etc.) and service sites.

URL http://www.nagoya.melco.co.jp/english/

Q Mode Model List

CPU Modules (Q Mode)

Pr	oduct	Туре	Outline
CPU modu	ule	Q02CPU	I/O points: 4096 Program capacity: 28K steps Basic instruction 79ns
		Q02HCPU	I/O points: 4096 Program capacity: 28K steps Basic instruction 34ns
		Q06HCPU	I/O points: 4096 Program capacity: 60K steps Basic instruction 34ns
		Q12HCPU	I/O points: 4096 Program capacity: 124K steps Basic instruction 34ns
		Q25HCPU	I/O points: 4096 Program capacity: 252K steps Basic instruction 34ns
		13JL97	QCPU (Q mode) Hardware Design/Maintenance and Inspection Manual (optional)
		13JL98	QCPU (Q mode) User's Manual (Function Explanation Program Fundamentals) (optional)
		13JF58	QCPU (Q mode)/QnACPU Programming Manual (Common Instructions) (optional)
		13JF60	QCPU (Q mode)/QnACPU Programming Manual (SFC) (optional)
		13JF61	QCPU (Q mode) Programming Manual (MELSAP-L) (optional)
		13JF59	QCPU (Q mode)/QnACPU Programming Manual (PID Control Instructions) (optional)
		13JL96	QCPU (Q mode) User's Manual: Hardware (packed with Q3□B)
Battery		Q6BAT	Replacement battery
IC memory	v card	Q2MEM-1MBS	Small SRAM card Capacity: 1M bytes
	, ,	Q2MEM-2MBF	Small linear flash memory card Capacity: 2M bytes
		Q2MEM-4MBF	Small linear flash memory card Capacity: 4M bytes
		Q2MEM-8MBA	Small ATA card Capacity: 8M bytes
		Q2MEM-16MBA	Small ATA card Capacity: 16M bytes
		Q2MEM-32MBA	
SRAM car	d batterv	Q2MEM-BAT	Replacement battery, for Q2MEM-1MBS
Base	Main	Q35B	Power supply + CPU + 5 slots for Q series I/O
module	ividin	Q38B	Power supply + CPU + 8 slots for Q series I/O
		Q312B	Power supply + CPU + 12 slots for Q series I/O
	Extension	Q65B	Power supply + 5 - I/O slots, for Q series module loading
	Exteriorer	Q68B	Power supply + 8 - I/O slots, for Q series module loading
		Q612B	Power supply + 12 - I/O slots, for Q series module loading
	Adapter	Q6DIN1	DIN rail mounting adapter, for Q38B/Q312B/Q68B/Q612B
	/ laupici	Q6DIN2	DIN rail mounting adapter, for Q35B/Q65B
Extension	cable	QC06B	0.6m (19.69ft.) cable for Q65B/Q68B/Q612B connection
Extension	ouble	QC12B	1.2m (3.98ft.) cable for Q65B/Q68B/Q612B connection
		QC30B	3m (9.84ft.) cable for Q65B/Q68B/Q612B connection
		QC50B	5m (16.4ft.) cable for Q65B/Q68B/Q612B connection
		QC100B	10m (32.81ft.) cable for Q65B/Q68B/Q612B connection
Power sur	ply module	Q61P-A1	100-120VAC input/5VDC 6A output
i ower sup	ply module	Q61P-A2	200-240VAC input/5VDC 6A output
AC input n	nodule	QX10	100-120VAC, input 16 points, input time constant: 20ms, terminal block
DC input n		QX40	24VDC positive common input, 16 points, input time constant 1/5/10/20/70ms, terminal block
	liouuic	QX41	24VDC positive common input, 32 points, input time constant 1/5/10/20/70ms, connector
		QX42	24VDC positive common input, 64 points, input time constant 1/5/10/20/70ms, connector
		QX80	24VDC negative common input, 16 points, input time constant 1/5/10/20/70ms, terminal block
		QX81	24VDC negative common input, 32 points, input time constant 1/5/10/20/70ms, connector
Contact of	utput module	QY10	240VAC/24VDC 2A, 16 points, without fuse, terminal block
Transistor		QY40P	12/24VDC 0.1A sink, 16 points, with short-circuit protection function, terminal block
module	output	QY41P	
mouule			12/24VDC 0.1A sink, 32 points, with short-circuit protection function, connector
		QY42P	12/24VDC 0.1A sink, 64 points, with short-circuit protection function, connector
		QY50	12/24VDC 0.5A sink, 16 points, with fuse, terminal block
		QY80	12/24VDC 0.5A source, 16 points, with fuse, terminal block
Dissi	L.I.	QY81P	12/24VDC 0.1A source, 32 points, with short-circuit protection function, connector
Blank mod		QG60	— D. Osnica I/O. Mashda Harada Maraval (anticast)
I/O module	÷	13JL99	Q Series I/O Module User's Manual (optional)

Note 1: The purchase order number is indicated in the manual's Type field.

Q Mode Model List

Product	Туре	Outline
Analog module	Q64AD	4 channels, analog-to-digital conversion: voltage/current input
0	Q68ADV	8 channels, analog-to-digital conversion: voltage input
	Q68ADI	8 channels, analog-to-digital conversion: current input
	SW0D5C-QADU-E	Analog-to-digital converter module utility software
	13JR03	Q64AD, Q68ADV, A68ADI User's Manual (Details) (optional) (Note 1)
	13JQ51	Q64AD, Q68ADV, A68ADI User's Manual: Hardware (packed with product)
	Q62DA	2 channels, digital-to-analog conversion: voltage/current output
	Q64DA	4 channels, digital-to-analog conversion: voltage/current output
	SW0D5C-QDAU-E	Digital-to-analog converter module utility software
	13JR02	Q62DA, Q64DA User's Manual (Details) (optional) (Note 1)
	13JQ49	Q62DA, Q64DA User's Manual: Hardware (packed with product)
High-speed counter	QD62	2 channels, 200kpps, 5/12/24VDC input, sink transistor output
module	QD62D	2 channels, 500kpps, differential input, sink transistor output
	QD62E	2 channels, 200kpps, 5/12/24VDC input, source transistor output
		High-speed counter utility software
	13JL95	QD62, QD62D, QD62E User's Manual (Details) (optional) (Note 1)
	13JQ69	QD62, QD62D, QD62E User's Manual: Hardware (packed with product)
Positioning module	QD75P1	1 axis, open collector output
r contorning modulo	QD75P2	2 axes, open collector output
	QD75P4	4 axes, open collector output
	QD75D1	1 axis, differential output
	QD75D2	2 axes, differential output
	QD75D4	4 axes, differential output
	SW0D5C-QD75P-E	
	13JR09	QD75P/QD75D User's Manual (Details) (optional)
	13J973	QD75P/QD75D User's Manual: Hardware (packed with product)
	13JN62	SW0D5C-QD75P-E Operating Manual (optional) (Note 3)
MELSECNET/10H	QJ71LP21	SI/QSI optical cable, dual loop
module		
module	QJ71BR11	Coaxial 75 Ω cable, single bus
	13JF92	MELSECNET/10H Reference Manual (optional)
00111	13JQ48	QJ71LP21, QJ71BR11 User's Manual (packed with product)
CC-Link module	QJ61BT11	For master/local
	13JL91	QJ61BT11 User's Manual: Details (optional)
	13JQ41	QJ61BT11 User's Manual: Hardware (packed with product)
Ethernet module	QJ71E71	For 10BASE-5/10BASE-T
	QJ71E71-B2	For 10BASE-2
	13JL88	Ethernet Module User's Manual: Basic (optional)
	13JL89	Ethernet Module User's Manual: Applications (optional)
	13JF89	MC Protocol Reference Manual (optional)
	13JQ35	QJ71E71, QJ71E71-B2 User's Manual: Hardware (packed with product)
Serial communication	QJ71C24	RS-232 1ch, RS-422/485 1ch
module	QJ71C24-R2	RS-232 2ch
		Serial communication module utility software
	13JL86	Serial Communication Module User's Manual: Basic (optional) (Note 1)
	13JL87	Serial Communication Module User's Manual: Applications (optional)
	13JF89	MC Protocol Reference Manual (optional)
	13JQ31	QJ71C24, QJ71C241-R2 User's Manual: Hardware (packed with product)
Extension base module	QA1S65B	Power supply + 5 - I/O slots, for AnS series module loading
	QA1S68B	Power supply + 8 - I/O slots, for AnS series module loading
Extension cable	QC06B	0.6m(1.97ft.) cable for QA1S65B/QA1S68B connection
	QC12B	1.2m(3.93ft.) cable for QA1S65B/QA1S68B connection
	QC30B	3m(9.84ft.) cable for QA1S65B/QA1S68B connection
	QC50B	5m(16.39ft.) cable for QA1S65B/QA1S68B connection
	QC100B	10m(32.79ft.) cable for QA1S65B/QA1S68B connection
AnS series module	In addition to the	above modules, the AnS series modules can be loaded and used in the QA1S65B/QA1S68B.
	Refer to the AnS	series module model list.

Note 1: User's manual includes explanations of the corresponding utility software. Also, the user's manual (details) is included the corresponding utility software in the PDF format. Note 2: The purchase order number is indicated in the manual's Type field. Note 3: The PDF format manual is included in the software product.



A Mode Model List

Pro	oduct	Туре	Outline			
CPU modu	le for A	Q02CPU-A	I/O points: 4096 Program capacity: 28K steps Basic instruction 79ns			
mode		Q02HCPU-A	I/O points: 4096 Program capacity: 28K steps Basic instruction 34ns			
Q06HCPU-A			I/O points: 4096 Program capacity: 30K steps $ imes$ 2 Basic instruction 34ns			
13JR10			QCPU (A mode) User's Manual: Details			
		13J740	ACPU Programming Manual (Fundamentals)			
		13J741	ACPU Programming Manual (Common Instructions)			
		13J742	AnSHCPU/AnACPU/AnUCPU Programming Manual (Dedicated Instructions)			
		13J743	AnA/AnUCPU Programming Manual (AD57 Instructions)			
		13J744	AnA/AnUCPU Programming Manual (PID Control Instructions)			
		13JF40	MELSAP-2 Programming Manual			
	13JL96		QCPU (A mode) User's Manual: Hardware (packed with QA1S3⊟B)			
Battery		Q6BAT	Replacement battery			
IC memory	card	Q2MEM-1MBS	Small SRAM card Capacity: 1M bytes			
SRAM card	battery	Q2MEM-BAT	Replacement battery, for Q2MEM-1MBS			
Base	Main	QA1S35B	Power supply + CPU + 5-I/O slots for AnS series module loading			
module		QA1S38B	Power supply + CPU + 8-I/O slots for AnS series module loading			
	Extension	QA1S65B	Power supply + 5 I/O slots for AnS series module loading			
		QA1S68B	Power supply + 8 I/O slots for AnS series module loading			
Extension of	cable	QC06B	0.6m(1.97ft.) cable for QA1S65B/QA1S68B connection			
		QC12B	1.2m(3.93ft.) cable for QA1S65B/QA1S68B connection			
QC30B		QC30B	3m(9.84ft.) cable for QA1S65B/QA1S68B connection			
	QC50B		5m(16.39ft.) cable for QA1S65B/QA1S68B connection			
		QC100B	10m(32.79ft.) cable for QA1S65B/QA1S68B connection			
AnS series	module		above modules, the AnS series modules can be loaded and used in the QA1S65B/QA1S68B.			
		Refer to the AnS	series module model list.			

Note 1: The purchase order number is indicated in the manual's Type field.

Q/A Mode Common Model List

Product	Туре	Outline		oatible ode
			A	Q
	A1S61PN	100-240VAC input, 5VDC 5A output	0	0
base	A1S62PN	100-240VAC input, 5VDC 3A/24VDC 0.6A output	0	0
	A1S63P	24VDC input, 5VDC 5A output	0	0
AC input module	A1SX10	100-120VAC, 16 points, terminal block	0	0
	A1SX10EU	100-120VAC, 16 points, terminal block	0	0
	A1SX20	200-240VAC, 16 points, terminal block	0	0
	A1SX20EU	200-240VAC, 16 points, terminal block	0	0
	A1SX30	12/24VAC, 12/24VDC, 16 points, terminal block	0	0
DC input module	A1SX40	12/24VDC, 16 points, terminal block (sink)	0	0
	A1SX40-S1	24VDC, 16 points, terminal block, for high-speed input (sink)	0	0
	A1SX40-S2	24VDC, 16 points, terminal block, for high leakage current sensor (sink)	0	0
	A1SX41	12/24VDC, 32 points, connector (sink)	0	0
	A1SX41-S1	24VDC, 32 points, connector, for high-speed input (sink)	0	0
	A1SX41-S2 A1SX42	24VDC, 32 points, connector, for high leakage current sensor (sink)	0	0
	A15X42 A1SX42-S1	12/24VDC, 64 points, connector (sink) 24VDC, 64 points, connector, for high-speed input (sink)		0
or main/extension ase C input module C input module C/DC input module C input module odule ontact output module iac output module iac output module ransistor output odule TL-CMOS output odule TL-CMOS output odule	A15X42-51 A1SX42-S2	24VDC, 64 points, connector, for high leakage current sensor (sink)	0	
	A15742-52 A1S42X		0	0
	A1542A	24VDC dynamic, 64 points, connector (sink)	0	0
module .	A1SX71	5/12VDC, 32 points, connector (sink/source)		
DC input module	A1SX80	12/24VDC, 16 points, terminal block for high-speed input (sink/source)	0	0
	A1SX80-S1	24VDC, 16 points, terminal block, for high-speed input (sink/source)	0	0
	A1SX80-S2	24VDC, 16 points, terminal block, for high leakage current sensor (sink/source)	0	0
	A1SX81	12/24VDC, 32 points, connector (sink/source)	0	0
	A1SX81-S2	24VDC, 32 points, connector, for high leakage current sensor (sink/source)	0	0
	A1SX82-S1	24VDC, 64 points, connector (sink/source)	0	0
Contact output module	A1SY10	240VAC/24VDC 2A, 16 points, terminal block	0	0
	A1SY10EU	240VAC/24VDC 2A, 16 points, terminal block	0	0
	A1SY14EU	240VAC/24VDC 2A, 12 points, terminal block	0	0
	A1SY18A	240VAC/24VDC 2A, 8 independent contact output points, terminal block	0	0
	A1SY18AEU	240VAC/24VDC 2A, 8 points, terminal block	0	0
Triac output module	A1SY22	100-240VAC 0.6A, 16 points, terminal block, with fuse	0	0
	A1SY28A	100-240VAC 1A, 8 points, all points independent	0	0
	A1SY28EU	100-240VAC 0.6A, 8 points, 4 points/common	0	0
	A1SY40	12/24VDC 0.1A, 16 points, terminal block, with fuse (sink)	0	0
module	A1SY41	12/24VDC 0.1A, 32 points, connector, with fuse (sink)	0	0
	A1SY42	12/24VDC 0.1A, 64 points, connector, with fuse (sink)	0	0
	A1S42Y	12/24VDC 0.1A dynamic, 64 points, connector, with fuse (sink)	0	0
	A1SY50	12/24VDC 0.5A, 16 points, terminal block, with fuse (sink)	0	0
	A1SY60	24VDC 2A, 16 points, terminal block, with fuse (sink)	0	0
	A1SY68A	5/12/24/48VDC 2A, 8 points, terminal block, all points independent	0	0
TTL-CMOS output module	A1SY71	5/12VDC, 32 points, transistor 16mA, connector, with fuse (sink)	0	0
Transistor output	A1SY80	12/24VDC 0.8A, 16 points, terminal block, with fuse (source)	0	0
module	A1SY81	12/24VDC 0.1A, 32 points, connector, with fuse (source)	Õ	Ō
	A1SY81EP	12/24VDC 0.1A, 32 points, short-circuit protection (source)	Ŏ	Õ
	A1SY82	12/24VDC 0.1A, 64 points, connector, with fuse	Õ	Ō
	A1S60E	5/12/24VDC 2A, 16 points, terminal block, with fuse (source)	Ŏ	Õ
DC input transistor	A1SH42	12/24VDC, 32 input points, 32 output points 0.1A, connector, with fuse (source)	Ŏ	Ŏ
output module	A1SH42-S1	24VDC, 32 high-speed input points, 32 output points 0.1A, connector, with fuse	Ŏ	Õ
	A1SX48Y58	24VDC, 8 input points, transistor 0.5A, 8 output points, terminal block	Ŏ	Õ
DC input, contact output module	A1SX48Y18	24VDC, 8 input points, 2A contact, 8 output points, terminal block	0	0

Note 1: Compatible mode \bigcirc : Usable, \triangle : Usable with restriction, \times : Unusable, —: External accessory

Q/A Mode Common Model List

Product	Туре			Outline		patible ode
					Α	Q
High-speed counter	A1SD61	DC input, 50kpps,			0	0
	A1SD62	DC input, 100kpps			0	0
	A1SD62D			input), 200kpps, 2 channels	0	0
	A1SD62D-S1			erential input), 200kpps, 2 channels	0	\bigcirc
	A1SD62E			, 100kpps, 2 channels		0
Analog-to-digital	A1S64AD	Analog input, 4 cha			0	\circ
converter module	A1S68AD	Analog input, 8 cha				0
Digital-to-analog	A1S62DA	Analog output, 2 cł				0
converter module	A1S68DAV	0 to ±10V, analog				0
	A1S68DAI	4-20mA, analog ou				0
Temperature-digital	A1S62RD3	Pt100 (3 wire type)				0
converter module	A1S62RD4	Pt100 (4 wire type), 2 channels				0
	A1S68TD	Thermocouple inpu				0
Analog I/O module	A1S63ADA			alog output 1 channel		0
-	A1S66ADA Analog input 4 channels, analog output 2 channels emperature control A1S64TCTT-S1 Thermocouple input/transistor output, 4 channels					0
Temperature control	A1S64TCTT-S1					0
module	A1S64TCTTBW-S1	detection function		or output, 4 channels, with heater wire breakage	_	0
	A1S64TCRT-S1		Pt100 input/transistor output, 4 channels			0
	A1S64TCRTBW-S1	Pt100 input/transis function	Pt100 input/transistor output, 4 channels, with heater wire breakage detection function			0
Temperature control	A1S62TCTT-S2	Thermocouple input/transistor output (heating/cooling), 2 channels			0	0
module	A1S62TCTTBW-S2	Thermocouple input/transistor output (heating/cooling), 2 channels, with heater wire breakage detection function			0	0
	A1S62TCRT-S2			(heating/cooling), 2 channels	0	0
	A1S62TCRTBW-S2	Pt100 input/transistor output (heating/cooling), 2 channels, with heater wire breakage detection function				0
Pulse catch module	A1SP60	Pulse catch functio		nt input	0	0
Analog timer module	A1ST60	8 timer points	, - 1 -			Õ
Interrupt module	A1SI61	Interrupt input, 16 p	ooints			Õ
Computer link module	A1SJ71UC24-R2	RS-232, 1 channel				×
•	A1SJ71UC24-R4	RS-422/RS-485, 1 channel		Ō	×	
	A1SJ71UC24-PRF	Computer link/printer function, RS-232C, 1 channel		0	×	
Positioning module	A1SD70	Analog output, 1 axis		0	0	
	A1SD71-S2	Pulse train output,	2 axes		0	0
	A1SD71-S7	Pulse train output,	2 axes, m	anual pulse generator usable		
	A1SD75M1	SSC network	1 axis	2 axes (linear/circular interpolation)		
	A1SD75M2	compatible	2 axes	Absolute system/incremental system/speed-positio	า	
	A1SD75M3	companio	3 axes	switching control		
	A1SD75P1-S3		1 axis	2 axes (linear/circular interpolation)		
	A1SD75P2-S3	Pulse train output	2 axes	-2147483648 to 2147483647 pulses		
	A1SD75P3-S3		3 axes			
	A1SD774M	4 axes, motion con			0	0
A1SD75 cable	A1SD75-C01HA			b conversion adapter cable		-
Teaching module	AD75TU	For AD75/A1SD75				<u> </u>
Positioning module- AD75C20SH A1SD75PD-Mitsubishi MR-HDA			-	+		
servo amplifier connection cable	AD75C20SJ			A connection cable (2m (6.56 ft.))		+-
	AD75C20SJ2			$2\square A$ connection cable (2m (6.56 ft.))	+-	+-
	AD75C20SC			C A connection cable (2m (6.56 ft.))		_
MELSECNET/MINI-S3 A1SJ71PT32-S3 Master module A1SJ71T32-S3 Master module					0	\triangle
MELSECNET(II)	A1SJ71132-33 A1SJ71AP21	Master module for		cal cable, duplex loop	0	\land
	A1SJ71AP21 A1SJ71AR21			cal cable, duplex loop	0	×
MELSECNET/B	A1SJ71AR21 A1SJ71AT21B				0	×
		For master/local module, twisted pair Remote I/O module, twisted pair				

Note 1: Compatible mode \bigcirc : Usable, \triangle : Usable with restriction, \times : Unusable, —: External accessory

Q/A Mode Common Model List

Product	Туре	Outline		atible de
			Α	Q
MELSECNET/10	A1SJ71LP21	SI/QSI optical cable, duplex loop, for control/ordinary/master station	0	×
	A1SJ71BR11	Coaxial 75 Ω cable, simplex bus, for control/ordinary/master station	Ō	×
	A1SJ72QLP25	SI/QSI optical cable, duplex loop, for remote I/O station	0	\times
	A1SJ72QBR15	Coaxial 75 Ω cable, simplex bus, for remote I/O station	0	\times
	A6BR10	Repeater for coaxial bus, 100-240VAC power supply		
	A6BR10-DC	Repeater for coaxial bus, 240VDC power supply		—
	A6RCON-R75	75 Ω termination resistor for coaxial bus	_	_
Ethernet module	A1SJ71E71-B2-S3	Coaxial 75 Ω cable, simplex bus, for control/ordinary/master station SI/QSI optical cable, duplex loop, for remote I/O station Coaxial 75 Ω cable, simplex bus, for remote I/O station Repeater for coaxial bus, 100-240VAC power supply Repeater for coaxial bus, 240VDC power supply Repeater for coaxial bus, 240VDC power supply 75 Ω termination resistor for coaxial bus Ethernet interface module (10BASE2) Ethernet interface module (10BASE5) Master/local module, for twisted pair Master/local module, twisted pair JPCN-1 master module, twisted pair JPCN-1 master module, twisted pair Power distribution control equipment transmission signal unit interface module for B/NET Max. 128 control I/O points, S-LINK master module Intelligent communication module Modbus ASCII/RTU slave, RS-232 × 1ch Modbus ASCII/RTU slave, RS-422/485 × 1ch Profibus-FMS, Client or Server Profibus-DP, Master DeviceNet, Master Absolute position detection by dedicated sensor PLC simple monitoring module Memory card interface module Memory card interface module Memory card module		
	A1SJ71E71-B5-S3	Ethernet interface module (10BASE5)	0	××
CC-Link module	A1SJ61BT11	Master/local module, for twisted pair	0	\times
I/O Link master module	A1SJ51T64	Master module, twisted pair/ cabtire cable	0	0
JEMANET	A1SJ71J92-S3	JPCN-1 master module, twisted pair	0	\triangle
	A1SJ72J95	JPCN-1 slave module, twisted pair	0	0
B/NET module	A1SJ71B62-S3	Power distribution control equipment transmission signal unit interface module for B/NET	0	Δ
S-LINK master module	A1SJ71SL92	Max. 128 control I/O points, S-LINK master module	0	0
telligent A1SD51S Intelligent communication module		0	Δ	
Modbus	odbus A1SJ71UC24-R2-S2 Modbus ASCII/RTU slave, RS-232 × 1ch		0	\triangle
	A1SJ71UC24-R4-S2	Modbus ASCII/RTU slave, RS-422/485 × 1ch	0	\triangle
Profibus	A1SJ71PB96F	Profibus-FMS, Client or Server	0	\triangle
	A1SJ71PB92D	Profibus-DP, Master	0	0
DeviceNet	A1SJ71DN91	DeviceNet, Master	0	0
Position detection module	A1S62LS	Absolute position detection by dedicated sensor	0	0
PLC simple monitoring module	A1SS91	PLC simple monitoring module	0	0
Memory card interface	A1SD59J-S2	Memory card interface module	0	0
module	A1SD59J-MIF	Memory card module		
	AC20MIF-L	Connection cable 2m (6.56ft.)		
ID interface module	A1SJ71ID1-R4	ID reader/writer interface module, 1 channel	0	Δ
(Note 2)	A1SJ71ID2-R4	ID reader/writer interface module, 2 channels	0	\triangle
	A1SD32ID1	ID reader/writer interface module, 1 channel	0	0
	A1SD32ID2	ID reader/writer interface module, 2 channels	0	0
Blank cover	A1SG60	Blank cover for I/O slot	0	0
	A1SG62	16/32/64 point dummy module	Ō	Ō
AnS conversion adapter	A1S-TA32	32-point crimp-contact terminal block adapter 0.5mm ² (AWG20)	—	—
adaptor	A1S-TA32-3	32-point crimp-contact terminal block adapter 0.3mm ² (AWG22)		
	A1S-TA32-7	32-point crimp-contact terminal block adapter 0.75mm ² (AWG18)	_	—
	A1S-TB32	32-point screw terminal block adapter 0.14mm ² to 0.75mm ² (AWG26 to 18)	—	—

Note 1: Compatible mode \bigcirc : Usable, \triangle : Usable with restriction, \times : Unusable, —: External accessory Note 2: Please confirm compliance of the ID products to local laws and regurations for radio transmitting devices.

Accessories Shared Among Q/AnS Series I/O

		Product	Туре		Outline			
Cor	nnect	tor/terminal	A6TBXY36	Sink type input module, s	ink type output module (stand	dard type)		
bloo	ck co	onverter module	A6TBXY54	Sink type input module, sink type output module (2-wire type)				
			A6TBX70	For sink type input module (3-wire type)				
			A6TBX36-E	For source type input mod	dule (standard type)			
			A6TBY36-E	For source type output me	odule (standard type)			
			A6TBY54-E	Source module input mod	lule (2-wire type)			
		tor/terminal	A6TBX54-E	Source module output mo	dule (2-wire type)			
_		onverter module		Source module input mod	lule (3-wire type)			
Cab	ble		AC05TB	For 0.5m (1.64ft.) sink mo	odule			
			AC10TB For 1m (3.28ft.) sink module					
			AC20TB	For 2m (6.56ft.) sink mod				
			AC30TB	For 3m (9.84ft.) sink mod	ule			
			AC50TB	For 5m (16.40ft.) sink mo	dule			
			AC80TB	For 8m (26.25ft.) sink mo	dule (common current 0.5A r	nax.)		
			AC100TB	For 10m (32.80ft.) sink m	odule (common current 0.5A	max.)		
			AC05TB-E	For 0.5m (1.64ft.) sink module				
			AC10TB-E	For 1m (3.28ft.) sink module				
			AC20TB-E	For 2m (6.56ft.) sink module				
			AC30TB-E	For 3m (9.84ft.) sink module				
			AC50TB-E	For 5m (16.40ft.) sink module				
Rela	-		A6TE2-16SRN	Relay terminal module				
	Cab	ble	AC06TE	Cable for relay terminal	Cable length 0.6m (1.97ft.)			
			AC10TE	module connection	Cable length 1m (3.28ft.)	Application to AY42, AY42-S1,		
			AC30TE		Cable length 3m (9.84ft.)	AY42-S4, AH42, A1SY41, A1SY42,		
			AC50TE		Cable length 5m (16.40ft.)	A1SH42		
			AC100TE		Cable length 10m (32.80ft.)			
		Soldering	A6CON1	Soldering 32-point connect				
ž	r sink	For crimp contact	A6CON2	Crimp-contact connection	32-point connector	40-pin connector		
necto	G G Soldering		A6CON3	Flat cable pressure-displa	cement 32-point connector			
Ŋ			A6CON1E	Soldering 32-point connect	ctor			
0/1			A6CON2E	Crimp-contact connection		31-pin D-sub connector		
	For	For pressure displacement	A6CON3E	Flat cable pressure-displa	cement 32-point connector			

CC-Link Remote Devices

Product	Туре	Outline
Input module	AJ65BTB1-16D	16 points, 24VDC (7mA), 1-wire type, terminal block type
•	AJ65BTB2-16D	16 points, 24VDC (7mA), 2-wire type, terminal block type
	AJ65BTC1-32D	32 points, 24VDC (7mA), 1-wire type, connector type
Output module	AJ65BTB1-16T	16 points, 24VDC (0.5A), transistor output, 1-wire type, terminal block type
	AJ65BTB2-16T	16 points, 24VDC (0.5A), transistor output, 2-wire type, terminal block type
	AJ65BTC1-32T	32 points, 24VDC (0.5A), transistor output, 1-wire type, connector type
	AJ65BTB2-16DR	16 points, 24VDC/240VAC (2A), relay contact output, 2-wire type, terminal block type
I/O composite module		8 input points, 24VDC (7mA), 8 output points, 24VDC (0.5A), transistor output, 1-wire type,
	AJ65BTB1-16DT	terminal block
	AJ65BTB2-16DT	8 input points, 24VDC (7mA), 8 output points, 24VDC (0.5A), transistor output, 2-wire type, terminal block
	AJ65BTB2-16DR	8 input points, 24VDC (7mA), 8 output points, 24VDC/240VAC (2A), relay contact output, 2- wire type, terminal block
Small input module	AJ65SBTB1-8D	8 points, 24VDC (7mA), 1-wire type, response time 1.5ms, terminal block type
	AJ65SBT1-16D	16 points, 24VDC (7mA), 1-wire type, response time 1.5ms, terminal block type
	AJ65SBTB1-16D1	16 points, 24VDC (5mA), 1-wire type, response time 0.2ms, terminal block type
	AJ65SBTB1-32D	32 points, 24VDC (7mA), 1-wire type, response time 1.5ms, terminal block type
		32 points, 24VDC (5mA), 1-wire type, response time 0.2ms, terminal block type
	AJ65SBTC1-32D	32 points, 24VDC (5mA), 1-wire type, response time 1.5ms, one-touch connector type (plug optional)
	AJ65SBTC1-32D1	32 points, 24VDC (5mA), 1-wire type, response time 0.2ms, one-touch connector type (plug optional)
	AJ65SBTC4-16D	16 points, 24VDC (5mA), 2-, 3-, 4-wire type, response time 1.5ms, one-touch connector type (for 8 sensors) (shared between sink and source: selected by switch) (plug: optional)
	AJ65SBTCF1-32D	32 points, 24VDC (5mA), 1-wire type, response time 1.5ms, FCN connector type
	AJ65SBTW4-16D	16 points, 24VDC (5mA), response time 1.5ms, waterproof 4-wire type (for 8 sensors)
<u> </u>		(shared between sink and source: selected by switch) (cap: optional) (waterproof type)
		8 points, 12/24VDC (0.5A), transistor output, 1-wire type, terminal block type
		16 points, 12/24VDC (0.5A), transistor output, 1-wire type, terminal block type
		32 points, 12/24VDC (0.5A), transistor output, 1-wire type, terminal block type
	AJ65SBTCF1-32T	32 points, 12/24VDC (0.1A), 1-wire type, transistor output, FCN connector type
	AJ65SBTC1-32T	32 points, 12/24VDC (0.1A), transistor output, 1-wire type, one-touch connector type (plug: optional)
	AJ65SBTB1-16T1	16 points, 12/24VDC (0.5A), 1-wire type, transistor output (OFF-time leakage current 0.1mA), terminal block type
	AJ65SBTB1-32T1	32 points, 12/24VDC (0.5A), 1-wire type, transistor output (OFF-time leakage current 0.1mA), terminal block type
	AJ65SBTB1-8TE	8 points, 12/24VDC (0.1A), 1-wire type, transistor output (source), terminal block type
	AJ65SBTB1-16TE	16 points, 12/24VDC (0.1A), 1-wire type, transistor output (source), terminal block type
		8 points, 2-wire type 100VAC input, terminal block type
		16 points, 2-wire type 100VAC input, terminal block type
		8 points, 24VDC, 100 to 240VAC, 2-wire type relay output, terminal block type
	AJ65SBTB2-16R	16 points, 24VDC, 100 to 240VAC, 2-wire type relay output, terminal block type
Small I/O composite module	AJ65SBTB1-32DT	16 points, 24VDC (7mA), 1-wire type, response time 1.5ms 16 points, 24VDC (0.5A), 1-wire type, transistor output, terminal block type
modulo	AJ65SBTC1-32DT	16 input points, 24VDC (5mA), 1-wire type, response time 1.5ms (plug: optional) 16 output points, 24VDC (0.1A), transistor output, 1-wire type, one-touch connector type
	AJ65SBTC1-32DT1	16 input points, 24VDC (5mA), 1-wire type, response time 0.2ms (plug: optional) 16 output points, 24VDC (0.1A), transistor output, 1-wire type, one-touch connector type
	AJ65SBTC4-16DT	8 input points, 24VDC (5mA), 2-, 3-, 4-wire type, response time 1.5ms (for 8 sensors) (plug:
	AJ65SBTCF1-32DT	16 points, 12/24VDC (5mA), 1-wire type, response time 1.5ms 16 points, 12/24VDC (0.1A), 1-wire type, transistor output, FCN connector type
	AJ65SBTW4-16DT	8 input points, 24VDC (5mA), response time 1.5ms (for 8 sensors) 8 output points, 24VDC (0.5A), transistor output (cap: optional), (waterproof type)
Analog-to-digital		4 channel input, analog input: -10V to +10V, -20mA to +20mA
conversion module	AJ65BT-64AD	Digital output: -2000 to +2000, 0 to +4000

CC-Link Remote Devices

Product	Туре		Outli	ne				
Digital-to-analog	AJ65BT-64DAV	4 channel vol	tage output, digital input: -2000 to -	+2000				
conversion module	AJ03B1-04DAV		t: -10V to +10V					
	AJ65BT-64DAI		rrent output, digital input: -2000 to +	-2000				
	AJ03B1-04DAI	Analog outpu	t: 4mA to 20mA					
High-speed counter	AJ65BT-D62		set DC input, counting range: 0 to 1					
module	AJ65BT-D62D	Differential in	put, preset DC input, counting range	e: 0 to 16777215 (24-bit binary)				
	AJ65BT-D62D-S1	Differential in	put, preset differential input, countin	g range: 0 to 16777215 (24-bit binary)				
Positioning	AJ65BT-D75P2-S3	2 axes (indep	axes (independent, with linear/circular interpolation simultaneous)					
Temperature input	AJ65BT-68TD	8-channel the	3-channel thermocouple input					
Temperature input	AJ65BT-64RD3	4-channel Pt	4-channel Pt100 (3-wire type) input					
	AJ65BT-64RD4	4-channel Pt100 (4-wire type) input						
RS-232C	AJ65BT-R2	RS-232C, 1 channel, with 2 DC input points/2 transistor output points						
GPP connection	AJ65BT-G4	PLC read/wri	te/monitor/test for master station, lo	Accessible to A mode CPU only				
	AJ03B1-04	station and other stations on MELSECNET						
ID module	AJ65BT-D32ID2	Reader/writer	2-channel connection					
Plug for one-touch		Plug color	Applicable cable core size (mm ²)	Applicable cable outline size (mm ²)				
connector (20-piece	A6CON-P214	Transparent	0.14 to 0.2	Ø 1.0 to 1.4				
set)	A6CON-P220	Yellow	(AWG#26 to 24)	Ø 1.4 to 2.0				
	A6CON-P514	Red	0.3 to 0.5	Ø1.0 to 1.4				
	A6CON-P520	Blue	(AWG#22 to 20)	ϕ 1.4 to 2.0				
Protective cover	A6CVR-8	Applies to AJ	65SBTB1-8D, AJ65SBTB1-8T (10-	piece set)				
		Applies to AJ	65SBTB1-16D, AJ65SBTB1-16D1,	AJ65SBTB1-16T, AJ65SBTC1-32D,				
	A6CVR-16	AJ65SBTC1-32D1, AJ65SBTC1-32T, AJ65SBTC1-32DT, AJ65SBTC1-32DT1, AJ65SBTC4-						
		16D, AJ65SBTC4-16DT (10-piece set)						
	A6CVR-32	Applies to AJ	65SBTB1-32D, AJ65SBTB1-32D1,	AJ65SBTB1-32T (10-piece set)				
Dustproof cap	A6CAP-DC1	Unused conn	ector protection cap, dustproof only	(not compliant with IP67) (20-piece set)				
Waterproof cap	A6CAP-WP1	Unused conn	ector protection cap, waterproof stru	ucture: IP67-compliant (20-piece set)				

Software, Peripheral Devices

Product	Туре	Outline		oatible ode	Com- patible
			А	Q	OS
System software	SW1D5C-QSET-E	Ladder/list/SFC programming, simulation tool, SW0D5C- QADU/QDAU/QSCU/QCTU (CD-ROM)	0	0	5/8/N
	SW5D5C-GPPLLT-E	Ladder/list/SFC programming, simulation tool (CD-ROM)	0	0	5/8/N
	SW5D5C-GPPW-E	Ladder/list/SFC programming (CD-ROM)	0	Ō	5/8/N
	SW5D5C-GPPW-E5	Ladder/list/SFC programming (CD-ROM), license product (for 5 licenses)	0	0	5/8/N
	SW5D5C-GPPW-E10	Ladder/list/SFC programming (CD-ROM), license product (for 10 licenses)	0	0	5/8/N
	13J966	Starting GPPW (optional)	—	—	
	13J974	GPPW Operating Manual: Startup (packed with product)	—	_	
	13J975	GPPW Operating Manual (optional) (Note 1)	—	_	-
	13J976	GPPW Operating Manual: SFC (optional) (Note 1)	—	—	
	13J980	GPPW Operating Manual (MELSAP-L) (optional) (Note 1)	—	—	
Simulation software	SW5D5C-LLT-E	Simulation tool (CD-ROM)	0	0	5/8/N
	SW5D5C-LLT-E5	Simulation tool (CD-ROM), license product (for 5 licenses)	0	0	5/8/N
	SW5D5C-LLT-E10	Simulation tool (CD-ROM), license product (for 10 licenses)	0	0	5/8/N
	13J977	LLT Operating Manual (optional) (Note 1)	—	_	-
Data conversion	SW0D5C-CNVW-E	CSV file, TXT file data conversion (CD-ROM)	0	0	5/8/N
software	SW0D5C-CNVW-E5	CSV file, TXT file data conversion (CD-ROM),	0	0	5/8/N
	SWUD5C-CINVW-E5	license product (for 5 licenses) CSV file, TXT file data conversion (CD-ROM),		0	5/8/N
	SW0D5C-CNVW-E10	license product (for 10 licenses)	0	0	N1/0/C
	13J949	CNVW Operating Manual (packed with product)	—	_	
Intelligent function	SW0D5C-QADU-E	Analog-to-digital converter module utility (CD-ROM) (Note 2)	×	0	5/8/N
module software	SW0D5C-QDAU-E	Digital-to-analog converter module utility (CD-ROM) (Note 2)	\times	0	5/8/N
	SW0D5C-QSCU-E	Serial communication module utility (CD-ROM) (Note 2)	\times	0	5/8/N
	SW0D5C-QCTU-E	High-speed counter module utility (CD-ROM) (Note 2)	×	0	5/8/N
Monitoring control	SW3D5F-CSKP-E	Basic communication support software tool (FD)	0	0	5/8/N
system software tool	SW3D5F-CSKP-E5	Basic communication support software tool (FD), license product (for 5 licenses)	0	0	5/8/N
	SW3D5F-CSKP-E10	Basic communication support software tool (FD), license product (for 10 licenses)	0	0	5/8/N
	SW3D5F-CSKP-E20	Basic communication support software tool (FD), license product (for 20 licenses)	0	0	5/8/N
	13J954	CSKP Operating Manual (packed with product)	_	—	_
	13JF57	CSKP Programming Manual (packed with product)	—	_	
	SW3D5F-OLEX-E	EXCEL communication support software tool (FD)	0	0	5/8/N
	SW3D5F-CSOLEX-E	CSKP, EXCEL communication support software tool set product (FD)	0	0	5/8/N
	SW3D5F-OLEX-E5	EXCEL communication support software tool (FD), license product (for 5 licenses)	0	0	5/8/N
	SW3D5F-OLEX-E10	EXCEL communication support software tool (FD), license product (for 10 licenses)	0	0	5/8/N
	13J955	OLEX Operating Manual (packed with product)		_	<u> </u>
	SW3D5F-XMOP-E	Monitoring OCX software tool (FD)	0	0	5/8/N
	SW3D5F-CSXMOP-E	CSKP, monitoring OCX software tool set product (FD)	0	Õ	5/8/N
	SW3D5F-XMOP-E5	Monitoring OCX software tool (FD),	0	0	5/8/N
		license product (for 5 licenses) Monitoring OCX software tool (FD),	0	0	5/8/N
	SW3D5F-XMOP-E10	license product (for 10 licenses)			0,0,11
		XMOP Operating Manual (packed with product)		—	
	SW0D5C-PIC-B	Graphic data package	0	0	5/8/N

Note 1: Manual in PDF format is included in corresponding software.

Note 2: Operation manual of the software and user's manual of corresponding modules in PDF format are included.

Note 3: Compatible mode $: \bigcirc$: Usable, \times : Not usable

Note 4: Compatible OS : 5: Windows 95, 8: Windows 98, N: Windows NT 4.0

Note 5: Please contact local Mitsubishi office for availability of Japanese, Chinese and German version software.

Software, Peripheral Devices

Product	Туре	Outline		oatible ode Q	Com- patible OS
Special module data	SW0IVD-MINIP-E	MELSECNET/MINI-S3 data setting software	0	0	V
setting software	13JF37	MINIP Operating Manual (packed with product)	—	_	-
	SW0IVD-ROMA-E	Intel HEX format ROM write-compatible data transfer software	0	0	V
	13JF34	ROMA Operating Manual (packed with product)	—	—	_
	SW1IX-AD51HPE	A1SD51S BASIC programming software	0	0	V
	13J733	AD51HP Operating Manual (packed with product)	—	—	_
	SW1IVD-AD71P	AD71, AD72 positioning data setting software	0	0	V
	13J916	AD71P Operating Manual (packed with product)	_	—	
	SW0D5C-AD75P-E	AD75 positioning data setting software (CD-ROM)	0	0	5/8/N
	13J948	AD75P-E Operating Manual (packed with product)	_	_	_
	SW0D5C-QD75P-E	QD75 positioning data setting software (CD-ROM)	0	0	5/8/N
	13J973	QD75P-E Operating Manual (packed with product)	_		_
Connection cable	QC30R2	RS-232 cable for personal computer-CPU connection, 3m(9.84ft.) (mini- DIN6P)-(Dsub9P)	0	0	—
PC card adapter	Q2MEM-ADP	Adapter for standard PCMCIA slot of Q2MEM memory card	0	0	_

Note 1: Compatible mode : (): Usable Note 2: Compatible OS : 5: Windows 95, 8: Windows 98, N: Windows NT 4.0, V: MS-DOS (DOS/V)

Personal Computer Network Boards

Product	Туре	Outline		atible de	Com- patible
			Α	Q	OS
MELSECNET/10 interface board		MELSECNET/10 interface for ISA bus, optical SI/QSI-200/250 (driver type: SW3DNF-MNET10)	0	\bigtriangleup	5/8/N/V
		MELSECNET/10 interface for ISA bus, optical GI-500/125 (driver type: SW3DNF-MNET10)	0	\triangle	5/8/N/V
		MELSECNET/10 interface for ISA bus, coaxial bus (driver type: SW3DNF-MNET10)	0	Δ	5/8/N/V
		MELSECNET/10 Interface Board User's Manual (packed with product)	—		
CC-Link interface board	A80BDE-J61BT13	CC-Link interface for PCI bus, local station, twisted pair (driver type: SW3DNF-CCLINK)	0	0	5/8/N
	13JL82	A80BD-J61BT13 User's Manual (packed with product)	-	_	_

Note 1: Compatible OS: 5: Windows 95, 8: Windows 98, N: Windows NT 4.0, V: MS-DOS (DOS/V) Note 2: MELSECNET/10 board is compatible with MELSECNET/10 mode and is not compatible with MELSECNET/10H mode.

Note 3: Compatible mode: \bigcirc : Usable, \triangle : Usable with restriction, \times : Unusable

GOT-A900 Graphic Operation Terminal

Product	Туре	Outline				
A985GOT	A985GOT-TBA	800×600 pixels, 256-color TFT color LCD, screen size: 12 (100-240VAC power supply built in), high intensity				
	A985GOT-TBD	800×600 pixels, 256-color TFT color LCD, screen size: 12 (24VDC power supply built in), high intensity				
	A985GOT-TBA-EU	800×600 pixels, 256-color TFT color LCD, screen size: 12 (100-240VAC power supply built in), high intensity, CE/UL/cUL compliance				
A975GOT	A975GOT-TBA	640×480 pixels, 256-color TFT color LCD, screen size: 10 (100-240VAC power supply built in), wide-angle vision				
	A975GOT-TBA-B	640×480 pixels, 256-color TFT color LCD, screen size: 10 (100-240VAC power supply built in), high intensity				
	A975GOT-TBD-B	640×480 pixels, 256-color TFT color LCD, screen size: 10 (24VDC power supply built in), high intensity				
	A975GOT-TBD	640 × 480 pixels, 256-color TFT color LCD, screen size: 10 (24VDC power supply built in), wide-angle vision				
	A975GOT-TBA-EU	640 × 480 pixels, 256-color TFT color LCD, screen size: 10 (100-240VAC power supply built in), high intensity, CE/UL/cUL compliance				
A970GOT	A970GOT-TBA	640 × 480 pixels, 16-color TFT color LCD, screen size: 10 (100-240VAC power supply built in), wide-angle vision				
	A970GOT-TBD	640 × 480 pixels, 16-color TFT color LCD, screen size: 10 (24VDC power supply built in), wide-angle vision				
	A970GOT-TBA-B	640 × 480 pixels, 16-color TFT color LCD, screen size: 10 (100-240VAC power supply built in), high intensity				
	A970GOT-TBD-B	640 × 480 pixels, 16-color TFT color LCD, screen size: 10 (24VDC power supply built in), high intensity				
	A970GOT-TBA-EU	640 × 480 pixels, 16-color TFT color LCD, screen size: 10 (100-240VAC power supply built in), high intensity, CE/UL/cUL compliance				
	A970GOT-SBA	640 × 480 pixels, 8-color STN color LCD, screen size: 10 (100-240VAC power supply built in)				
	A970GOT-SBD	640 × 480 pixels, 8-color STN color LCD, screen size: 10 24VDC power supply built in)				
	A970GOT-SBA-EU	640 × 480 pixels, 8-color STN color LCD, screen size: 10 (100-240VAC power supply built in), CE/UL/cUL compliance				
	A970GOT-LBA	640×480 pixels, STN monochrome LCD, screen size: 10 (100-240VAC power supply built in)				
	A970GOT-LBD	640×480 pixels, STN monochrome LCD, screen size: 10 (24VDC power supply built in)				
	A970GOT-LBA-EU	640×480 pixels, STN monochrome LCD, screen size: 10 (100-240VAC power supply built in), CE/UL/cUL compliance				
A960GOT	A960GOT-EBA	600 × 400 pixels, monochrome EL, screen size: 9 (100-240VAC power supply built in)				
	A960GOT-EBD	600 imes 400 pixels, monochrome EL, screen size: 9 (24VDC power supply built in)				
	A960GOT-EBA-EU	640×400 pixels, monochrome EL, screen size: 9 (100-240VAC power supply built in), CE/UL/cUL compliance				
A950GOT	A950GOT-SBD	320×240 pixels, 8-color STN color LCD, RS422 interface, 1MB built-in memory, 24VDC power supply				
	A950GOT-LBD	320×240 pixels, monochrome LCD, RS422 interface, 1MB built-in memory, 24VDC power supply				
	A951GOT-QSBD	320×240 pixels, 8-color STN color LCD, Q series bus interface, 1MB built-in memory, 24VDC power supply				
	A951GOT-QLBD	220×240 pixels, monochrome LCD, Q series bus interface. 1MR built in moment				
	A953GOT-SBD	320×240 pixels, 8-color STN color LCD, RS232C interface, 1MB built-in memory, 24VDC power supply				
	A953GOT-LBD	220 × 240 pixels, monochrome LCD, RS232C interface, 1MB built-in memory, 24VDC power supply				
	A956GOT-SBD	320 × 240 pixels, 8-color STN color LCD, external communication interface required, 1MB built- in memory, 24VDC power supply				
	A956GOT-LBD	320 × 240 pixels, monochrome LCD, external communication interface required, 1MB built-in memory, 24VDC power supply				
	A950GOT-SBD-M3	320 × 240 pixels, 8-color STN color LCD, RS422 interface, 3MB built-in memory, 24VDC power supply				
	A950GOT-LBD-M3	320 × 240 pixels, monochrome LCD, RS422 interface, 3MB built-in memory, 24VDC power supply				

GOT-A900 Graphic Operation Terminal

Product	Туре	Outline				
A950GOT	A951GOT-QSBD-M3	$320{\times}240$ pixels, 8-color STN color LCD, Q series bus interface, 3MB built-in memory, 24VDC power supply				
	A951GOT-QLBD-M3	320 × 240 pixels, monochrome LCD, Q series bus interface, 3MB built-in memory, 24VDC power supply				
	A953GOT-SBD-M3	320 \times 240 pixels, 8-color STN color LCD, RS232C interface, 3MB built-in memory, 24VDC power supply				
	A953GOT-LBD-M3	$^{320\times240}$ pixels, monochrome LCD, RS232C interface, 3MB built-in memory, 24VDC power supply				
	A956GOT-SBD-M3	320×240 pixels, 8-color STN color LCD, external communication interface required, 3MB built- n memory, 24VDC power supply				
	A956GOT-LBD-M3	320×240 pixels, monochrome LCD, external communication interfamemory, 24VDC power supply	•			
Bus connection board	A9GT-QBUSS	For bus connection to Q mode PLC, for connection of one A960/970/975/985GOT or for last GOT when multiple GOTs are connected				
	A9GT-QBUS2S	For bus connection to Q mode PLC, for connection of multiple A960.				
	A9GT-QBUS2SU	For bus connection to Q mode PLC, for connection of multiple A956				
	A9GT-QCNB	For bus connection to Q mode PLC, needed when distance to first C (43.28ft.)				
Serial communication board	A9GT-RS4	For CPU direct connection/computer link connection/microcomputer connection				
	A9GT-RS2	For CPU direct connection/computer link connection/microcomputer connection	connection and RS-232			
Network concettor	A9GT-RS2T	Clock function built-in serial communication board				
Network connection module		MELSECNET/10 inter-PLC optical loop				
		MELSECNET/10 inter-PLC coaxial bus				
Data link connection module		MELSECNET/II optical loop				
module	A7GT-J71AR23 A7GT-J71AT23B	MELSECNET/II coaxial loop MELSECNET/B twisted pair bus				
CC-Link connection	A/G1-J/1A123B A8GT-J61BT13	CC-Link (intelligent device station) twisted pair				
module	A8GT-J61BT15	CC-Link (intelligent device station) twisted pair CC-Link (remote device station) twisted pair				
Backlight	A9GT-80LTT	A985GOT TFT color LCD display section replacement backlight (1 p				
Dacklight	A9GT-70LTT	A975/975GOT TFT color LCD display replacement backlight (1 pc.)				
	A9GT-70LTT-B	A975/975GOT-B TFT color LCD display replacement backlight (1 pc.)				
	A9GT-70LTS	A975/975GOT STN color LCD display replacement backlight (2-piec				
	A9GT-50LT	A95⊡GOT STN color/monochrome LCD display replacement backlight				
Extension memory	A9GT-FNB	For optional OS				
board	A9GT-FNB1M	For optional OS + extension memory 1MB				
		For optional OS + extension memory 2MB				
	A9GT-FNB4M	For optional OS + extension memory 4MB				
	A9GT-QFNB	For optional OS (for MELSEC-QnA/A/FX ladder monitoring)				
		For optional OS + extension memory 4MB (for MELSEC-QnA/A/FX I	adder monitoring)			
Protective sheet	A9GT-80PSC		Any of these needed			
		Protective sheet (for A985GOT, logo removable) 5-piece set	,			
	A9GT-70PSC	Protective sheet (for A975/970GOT, without logo) 5-piece set				
	A9GT-70PSCL	Protective sheet (for A975/970GOT, logo removable) 5-piece set				
		Protective sheet (for A960GOT, without logo) 5-piece set				
	A9GT-60PSCL	Protective sheet (for A960GOT, logo removable) 5-piece set				
	A9GT-50PSC	Protective sheet (for A95 GOT, logo removable) 5-piece set				
Attachment		Conventionally used model	Replaceable model			
	A77GT-96ATT	A77GOT-L/L-S3/L-S5/CL/CL-S3/CL-S5	A960GOT			
	A85GT-95ATT	A85⊡GOT	A95□GOT			
	A87GT-96ATT	A77GOT-EL/EL-S3/EL-S5, A870GOT-EWS, A8GT-70GOT-EW/EB A960GOT				
	A87GT-97ATT	A870GOT-SWS/TWS, A8GT-70GOT-SW/SB/TW/LB	A97 GOT			
Stand	A9GT-80STAND	Debugging stand for A985GOT				
	A9GT-70STAND	Debugging stand for A975/970/960GOT				
	A9GT-50STAND	Debugging stand for A95□GOT				
Memory card	Q1MEM-64S	Memory capacity 64k bytes, for QnACPU, SRAM, (PCMCIA 2.1 com	pliant)			
		Memory capacity 128k bytes, for QnACPU, SRAM, (PCMCIA 2.1 compliant)				
	Q1MEM-256S	Memory capacity 256k bytes, for QnACPU, SRAM, (PCMCIA 2.1 compliant)				
	Q1MEM-512S	Memory capacity 512k bytes, for QnACPU, SRAM, (PCMCIA 2.1 compliant)				
		Memory capacity 1M bytes, for QnACPU, SRAM, (PCMCIA 2.1 compliant)				
	Q1MEM-2MS	Memory capacity 2M bytes, for QnACPU, SRAM, (PCMCIA 2.1 com				

GOT-A900 Graphic Operation Terminal

Product	Туре	Outline			
Flash PC card	A9GTMEM-10MF				
	A9GTMEM-20MF	GOT memory capacit	GOT memory capacity 20M bytes, flash PC card formatted		
	A9GTMEM-40MF	GOT memory capacity 40M bytes, flash PC card formatted			
Printer module	A9GT-50PRF	For connection of par	allel printer for A95 GOT, 1 channel		
Printer/memory module	A9GT-50MIF.PRF	Memory card interfac	e with parallel printer for A95□GOT, 1	I channel each	
External I/O interface	A9GT-70KBF		for A960/A97∐/A985GOT bints/64 keyboard input points, 16 trar	nsistor output points)	
	A8GT-50KBF	External I/O interface			
Drawing software	SW3D5C- GOTRE-PACK	CD-ROM for Windows	s 98/95/NT 4.0		
Q series bus cable	QC06B	0.6m(1.97ft.) cable	Q mode PLC bus connection cable		
	QC12B	1.2m(3.93ft.) cable	Q mode PLC bus connection cable		
	QC30B	3m(9.84ft.) cable	Q mode PLC bus connection cable		
	QC50B	5m(16.40ft.) cable	Q mode PLC bus connection cable		
	QC100B	10m(32.79ft.) cable	Q mode PLC bus connection cable		
	A9GT-QC200BS	20m(65.57ft.) cable	Q mode PLC bus connection cable	For purchasing, contact Mitsubishi	
		30m(98.36ft.) cable	Q mode PLC bus connection cable	Electric System Service Co., Ltd.	
	A9GT-QC350BS	35m(114.75ft.) cable	Q mode PLC bus connection cable		
RS-422 cable	AC30R4-25P	3m(9.84ft.) cable	CPU connection RS-422 cable		
	AC100R4-25P	10m(32.79ft.) cable	CPU connection RS-422 cable		
	AC300R4-25P	30m(98.36ft.) cable	CPU connection RS-422 cable		
Personal computer connection RS-232C	AC30N2A	3m(9.84ft.) cable	For personal computer connection (b 25-9 pin converter is needed for GO		
cable	AC30R2	3m(9.84ft.) cable	For personal computer connection (both sides: D-sub 25-pin), 25-9 pin converter is needed for GOT side.		
	AC30R2-9P	3m(9.84ft.) cable	For personal computer connection (c	one side: D-sub 9-pin, D-sub 25-pin)	
	AC30R2-9SS	3m(9.84ft.) cable	For personal computer connection (b	ooth sides: D-sub 9-pin)	
	FX-232CAB-1	3m(9.84ft.) cable	For personal computer connection (both sides: D-sub 9-pin)		
	FX-232CAB-2	3m(9.84ft.) cable	For personal computer connection (one side: D-sub 9-pin, half-pitch)		
CPU connection RS-232 cable	QC30R2	3m(9.84ft.) cable	CPU connection RS-232 cable		
Parallel cable (Centronics compliant)	AC30PIO-20P	3m(9.84ft.) cable	For parallel printer connection		

ID Systems

F	Product	Туре	Outline
D-NS series	Battery-less data	D-NS03PS	Plate type, memory capacity 320k bytes, compact
	carrier	D-NS03PM	Plate type, memory capacity 320k bytes, metal mounting
		D-NS03P	Plate type, memory capacity 320k bytes, oil-resistant/metal mounting
	Reader/writer	D-NS422RW	Standard, max. communications distance 25mm(0.99inch)
		D-NS422RWS	Compact, max. communications distance 15mm(0.59inch)
	ID controller	D-NS232IF2	For personal computer RS-232C, reader/writer 2 channels
	Cable	D-NS422CAB10	10m(32.79ft.) for reader/writer D-NS422RW, D-422RWS extension
		D-NS422CAB20	20m(65.57ft.) for reader/writer D-NS422RW, D-422RWS extension
		D-NS422CAB40	40m(131.15ft.) for reader/writer D-NS422RW, D-422RWS extension
		D-NS422CAB100	100m(327.87ft.) for reader/writer D-NS422RW, D-422RWS extension
D series	Battery-built-in	D-8PS	Plate type, memory capacity 8k bytes, compact
	data carrier	D-8PX	Plate type, memory capacity 8k bytes, battery replacement
		D-8P	Plate type, memory capacity 8k bytes, long distance
		D-03P	Plate type, memory capacity 320k bytes, compact
		D-03CS	Card type, memory capacity 320k bytes, compact card
	Holder	D-03CS-HLD	For D-03CS screwing
	Reader/writer	D-422RWL	Long distance, max. communications distance 260mm(10.24inch)
		D-422RW	Standard, max. communications distance 90mm(3.55inch)
	Handy controller	D-20HC	Handy controller, Japanese display
		D-20HC-E	Handy controller, English display
		D-20HC-RW	Reader/writer for D-20HC
	For general-	D-232RW	Reader/writer for RS-232, combination with SW1IVW-AIDP and D-20HC
	purpose personal computer	D-232IF	RS-232 signal conversion module, combination with SW1IVW-AIDP and D-422RWL or D422RW
		D-20HC-PS	Power supply adapter for D232 interface
	Cable	D-422CAB10	10m(32.79ft.) for reader/writer D-422RW, D-422RWL extension
		D-422CAB30	30m(65.57ft.) for reader/writer D-422RW, D-422RWL extension
		D-422CAB50	50m(131.15ft.) for reader/writer D-422RW, D-422RWL extension
		D-422CAB100	100m(327.87ft.) for reader/writer D-422RW, D-422RWL extension
		D-422CAB200	200m(655.74ft.) for reader/writer D-422RW, D-422RWL extension
		D-232CAB10	10m(32.79ft.) for reader/writer D-232RW extension
		FX2N-CNV-IF	Cable for FX-1DIF, conversion cable for connection with FX2N/A1FX

Note 1: Please confirm complience of the ID products to local laws and regulations for radio transmitting devices.



Service Network

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	Ohio-South Office	7566 Paragon Road, Centerville, OH 45459	Tel: 1-937-291-4600 Fax: 1-937-291-4606
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Belgium	Getronics NV/SA	Pontbeeklaan 43 1730 Zellik	Tel: 32-2-4671711 Fax: 32-2-4671745
Sweden	G & L Beijer Electronics AB.	Krangatan 4 S-20123 Malmo	Tel: 46-40-358600 Fax: 46-40-932301
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			Fax: 43-2252-48860
Spain	Mecco Medicion Control S.A	Gran via Deles Corts Catalanes	Tel: 34-3-4227700
		133, 4 E-08014 Barcelona	Fax: 34-3-4322847
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		Bldg., 660-11, Deungchon-dong,	Fax: 82-2-3665-4965
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		Instrumentation Plaza 103 Cao	Fax: 86-21-6484-6996
		Bao Rd.Shanghai 200233, China	
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