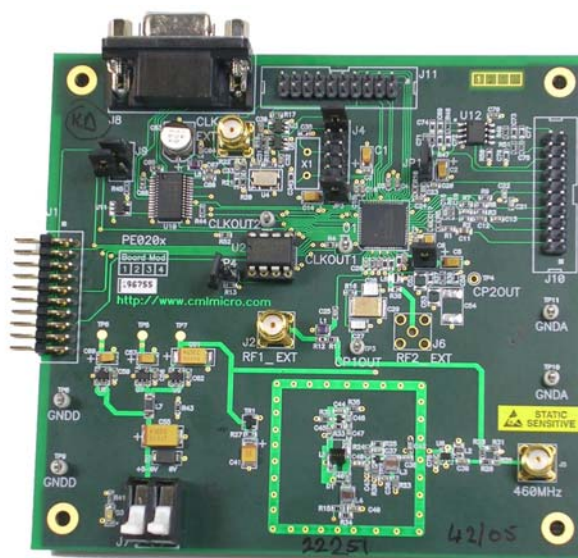


UM0201/5 February 2006

Features

- CMX703x *FirmASIC™* product range evaluation
- Evaluate both RF and baseband capabilities
- On-board 460MHz VCO
- On-board supply regulators operate from a single 5 volt supply
- Command and control by PC via the PE0001 interface card or user's μ C development application or emulator
- Socketed EEPROM option for Function Image™
- On-board access to all CMX703x signals, commands and data



1. Brief Description

The PE0201 Platform Evaluation Kit is designed to assist in the evaluation and application development of the CMX703x range of *FirmASIC™* products. The kit is in the form of a populated PCB comprising a CMX703x IC and appropriate supporting components and circuitry, including a 460MHz VCO operating in conjunction with one of the IC's on-chip synthesizers.

The board also incorporates all the necessary power-supply regulation facilities for operation from a single 5 volt supply, together with a number of board jumpers to enable various circuit arrangements to be effected.

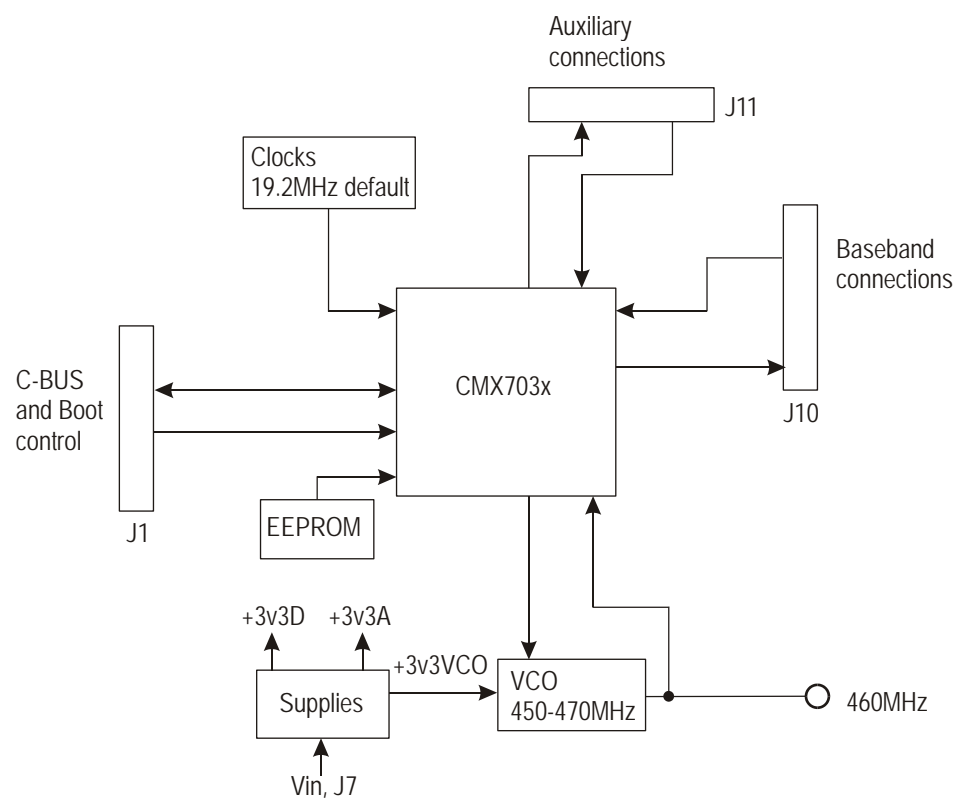
The board is fitted with connectors allowing the PE0201 to be operated with a CML PE0001 Interface Card and associated PC GUI software, or by direct connection between the CMX703x C-BUS serial port and the user's μ C development application or emulation system.

The CMX703x Function Image™ (FI) can be loaded, on power-up, directly into the on-board target CMX703x IC using the PE0001 interface or the user's system. Alternatively, it can be pre-loaded,

separately, into the on-board EEPROM for automatic operation on power-up. Function images can be downloaded from the CML website.

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It is always recommended that you check for the latest product datasheet version from the Datasheets page of the CML website: [www.cmlmicro.com].

**Figure 1 Block Diagram**

2. Preliminary Information

The CMX703x device fitted to the PE0201 has very little inherent functionality. The functionality must come from a Function Image™ which is downloaded from the CML website. The PE0201 is designed to support a range of CMX703x *FirmASIC*™ devices with their respective function images. Not all features of the PE0201 will be available with a given Function Image™.

2.1 Laboratory Equipment

The following laboratory equipment is needed to use this evaluation kit:

A 5 Volt dc regulated power supply.

If being used with the PE0001 Interface Card the following items will also be required.

1. An IBM compatible PC equipped with a serial port and with one of the following Microsoft operating systems installed - 98, NT, 2000sp4 or XP.
2. Software application ES000110.exe, or later version, installed on the PC.
3. RS232, 9-way DTE <-> DCE cable.

2.2 Precautions

Like most evaluation kits, this product is designed for use in office and laboratory environments. The following practices will help ensure its proper operation:

2.2.1 Static Protection

This product uses low power CMOS circuits which can be damaged by electrostatic discharge. Partially damaged circuits can function erroneously, leading to misleading results. Observe ESD precautions at all times when handling this product.

2.2.2 Contents - Unpacking

Please ensure that you have received all of the items listed on the separate information sheet (EK0201) and notify CML within 7 working days if the delivery is incomplete.

2.3 Approvals

This product is not approved to any EMC or other regulatory standard. Users are advised to observe local statutory requirements, which may apply to this product and the radio frequency signals that may emanate from it.

3. Quick Start

This section is divided into two sub-sections. The first is for those users who are using the PE0201 with a PE0001 controller card and its Windows PC application. The second is for users who are using the PE0201 by itself, without the PE0001.

3.1 With PE0001

Note that the C-BUS connector J1, a right angle header, of the PE0201 is designed to plug directly into socket J1 of the PE0001.

3.1.1 Setting-Up

- Ensure that all pins of header, J9, are open circuit.
- Refer to the PE0001 user manual, and follow the instructions given in the quick start section.

The basic arrangement, when used with the PE0001 is shown below.

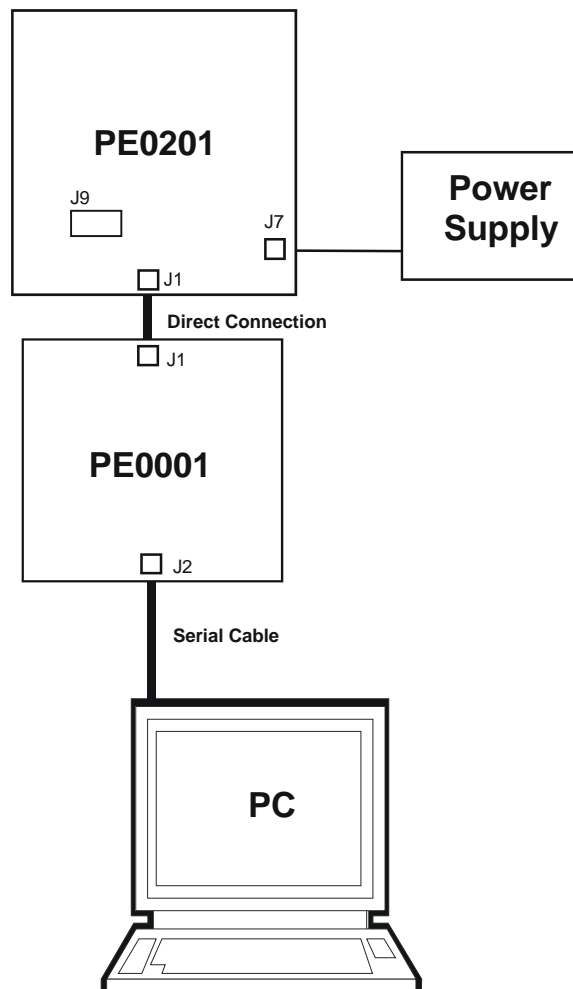


Figure 2 PE0201 used with PE0001

3.1.2 Operation

The Function Image™ (FI) must now be downloaded to the CMX703x device. Use the 'Function Image Download' tab of the PE0001 windows application. Two methods are available for downloading the FI:

- Directly from a file on the PE0001 host PC to the CMX703x.
- From the PE0201 EEPROM. To use this method the EEPROM must first be programmed with the FI using a user-supplied proprietary programmer. The EEPROM is socketed so that it can be removed for this purpose.

Function images are available as a 'C' type header file and must be obtained from the CML website.

The PE0201 should now be ready for evaluation of the CMX703x with the loaded FI.

3.2 Without PE0001

As an alternative to using the PE0001 controller kit, users may control the CMX703x target device with a user-supplied host controller card. C-BUS serial interface connections are made via connector J1.

The power-up, or boot state of the CMX703x may be set using jumpers on header, J9. Consult the relevant CMX703x documentation for valid modes. A jumper in-circuit on header, J9, corresponds to a '1' state on the boot pins.

A FI for the CMX703x device must be either, included in the customers host system and downloaded to the CMX703x device on power-up, or, programmed into the EEPROM using a user-supplied proprietary programmer. The EEPROM is socketed so that it can be removed for this purpose.

4. Signal Lists

CONNECTOR PINOUT				
Connector Ref.	Connector Pin No.	Signal Name	Signal Type	Description
J1	1	N/C	-	
	2	CSN	I/P	Chip select. Connects to host μ C.
	3	N/C	-	
	4	CDATA	I/P	Serial Data input. Connects to host μ C.
	5	N/C	-	
	6	SCLK	I/P	Serial clock input. Connects to host μ C.
	7	N/C	-	
	8	RDATA	O/P	Serial data output. Connects to host μ C.
	9	N/C	-	
	10	IRQN	O/P	Interrupt request. Connects to host μ C.
	11, 12	GNDD	PWR	Digital supply ground.
	13	BOOTEN1	O/P	CMX703x Hardware Boot Control.
	14	BOOTEN2	O/P	CMX703x Hardware Boot Control.
	15	RS232/CBUS N	O/P	CMX703x Hardware Boot Control.
	16, 17, 18	N/C	-	Do not connect these pins.
	19, 20	+3V3D	PWR	3.3V dc digital supply rail.
J2		RF1_EXT	I/P	External input option to RF synthesiser 1.
J3		CLK EXT	I/P	External input option for CMX703x clock.
J5		460MHz	O/P	Output from 460MHz VCO.
J6		RF2_EXT	I/P	External input to RF synthesiser 2 (not fitted).
J7		+V	PWR	External supply voltage.
		GNDD	PWR	External supply ground.

CONNECTOR PINOUT				
Connector Ref.	Connector Pin No.	Signal Name	Signal Type	Description
J8	1	N/C	-	
	2	TXD	O/P	9-pin D Type connector – PC TXD.
	3	RXD	I/P	9-pin D Type connector – PC RXD.
	4	N/C	-	
	5	GNDD	Power	9-pin D Type connector – PC GND.
	6	N/C	-	
	7	RTS	I/P	9-pin D Type connector – PC RTS.
	8	CTS	O/P	9-pin D Type connector - PC CTS.
	9	N/C	-	
J10	1	IP1	I/P	Channel 1 inverting input.
	3	IP2	I/P	Channel 2 inverting input.
	5	IP3	I/P	Channel 3 inverting input.
	7	MOD1	O/P	Channel 1 output.
	9	MOD2	O/P	Channel 2 output.
	11	AUDIO	O/P	Channel 3 output.
	13	BUF1IN	I/P	High impedance buffered input.
	15	BUF1OUT	O/P	Buffered output.
	17	BUF2IN	I/P	High impedance buffered input.
	19	BUF2OUT	O/P	Buffered output.
	2, 4, 6, 8, 10, 12, 14, 16, 18, 20	GNDA	PWR	Analogue supply ground.
J11	1	AUXADC4	I/P	Auxiliary ADC input.
	2	AUXDAC1	O/P	Auxiliary DAC output.
	3	AUXADC3	I/P	Auxiliary ADC input.
	4	AUXDAC2	O/P	Auxiliary DAC output.
	5	AUXADC2	I/P	Auxiliary ADC input.
	6	AUXDAC3	O/P	Auxiliary DAC output.
	7	AUXADC1	I/P	Auxiliary ADC input.
	8	AUXDAC4	O/P	Auxiliary DAC output.

CONNECTOR PINOUT				
Connector Ref.	Connector Pin No.	Signal Name	Signal Type	Description
	9, 10	GNDA	PWR	Analogue supply ground.
	11, 12	N/C		
	13, 14	GNDD	PWR	Digital supply ground.
	15, 16, 17, 18	N/C	-	Do not connect these pins.
	19	GPIO2	BI	General purpose I/O pin.
	20	GPIO1	BI	General purpose I/O pin.

TEST POINTS		
Test Point Ref.	Default Measurement	Description
TP1	-	CMX703x system clock 1 output.
TP2	-	CMX703x system clock 2 output.
TP3	-	CP1OUT, charge pump output for RF synthesiser 1.
TP4	-	CP2OUT, charge pump output for RF synthesiser 2 (not fitted).
TP5	3.3V	Output from on-board regulator. DC supply voltage for analogue rail.
TP6	3.3V	Output from on-board regulator. DC supply voltage for digital rail.
TP7	3.3V	Output from on-board regulator. DC supply voltage for RF Charge Pump and 460MHz VCO.
TP8	0V	GNDD, digital ground.
TP9	0V	GNDD, digital ground.
TP10	0V	GNDA, analogue ground.
TP11	0V	GNDA, analogue ground.

JUMPERS/LINKS			
Link Ref.	Positions	Default Position	Description
JP1	1-2	short	Isolates analogue supply rail from CMX703x.
JP2	1-2	short	Isolates charge pump supply rail from CMX703x.
JP3	1-2	short	Isolates digital supply rail from CMX703x.
JP4	1-2	open	Write protects EEPROM (when shorted).
J4	1-2	short	19.2MHz TXCO clock source.
	3-4	open	External clock source.
	5-6	open	Crystal clock source – if components fitted by customer.
	7-8	short	Ground external clock input.
	9-10	open	Crystal clock source – if components fitted by customer.
J9	1-2	open	Manual C-BUS (open) or RS232 selection (short).
	3-4	open	Manual BootEn1 control (short = HI).
	5-6	open	Manual BootEn2 control (short = HI).
J10	13-14	short	Ground input to uncommitted buffer1.
	17-18	short	Ground input to uncommitted buffer2.

LEDs	
LED Ref.	Description
D16	Indicates that digital supply voltage is present.

Notes: I/P = Input
 O/P = Output
 BI = Bidirectional
 N/C = Not connected
 PWR = Power supply connection

5. Circuit Schematics and Board Layouts

For clarity, circuit schematics are available as a separate high resolution pdf file. This can be found on the CML website.

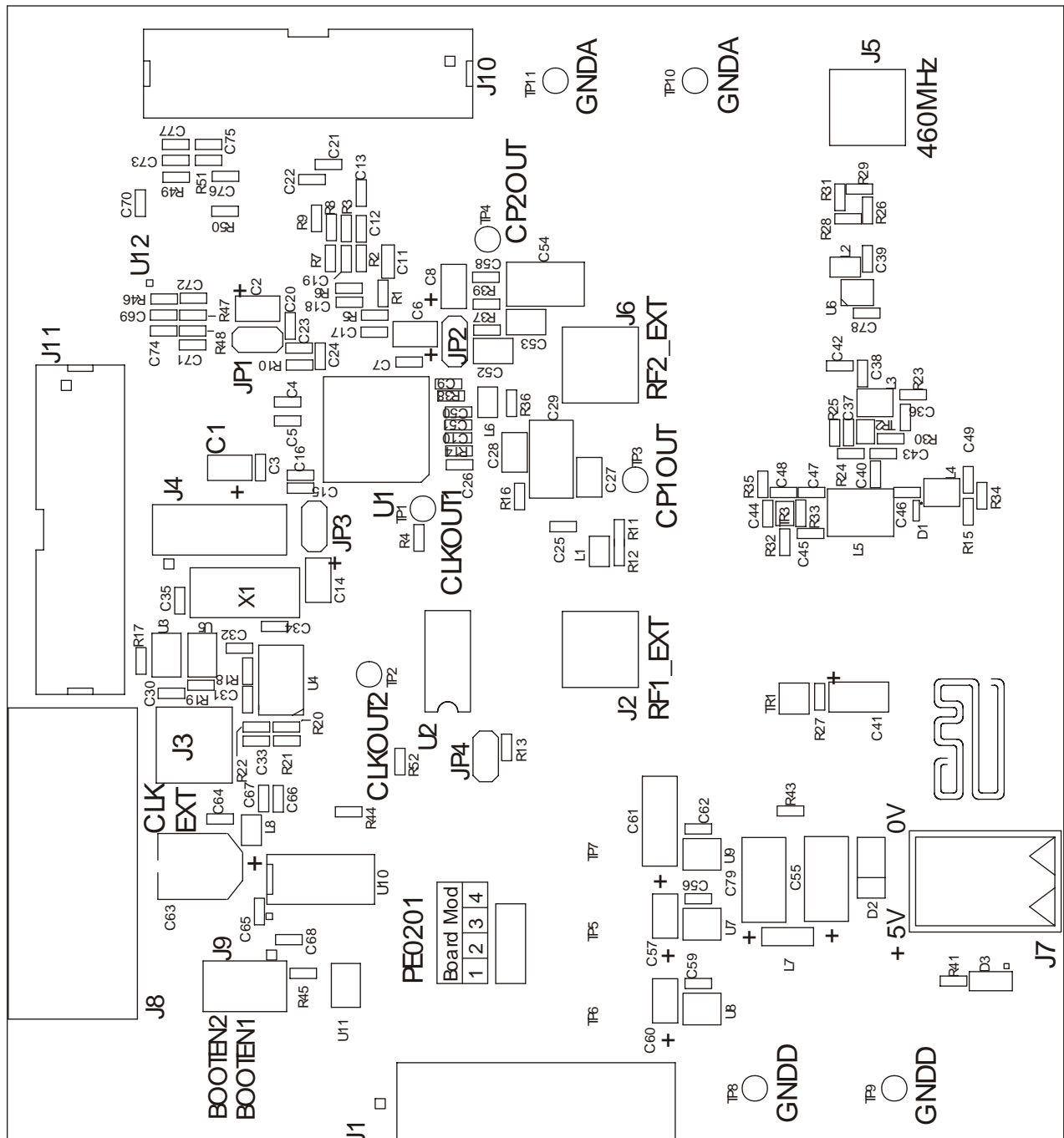


Figure 3 Evaluation Board - Layout

6. Detailed Description

6.1 Hardware Description

6.1.1 Power supplies

The board is fitted with three voltage regulators. U7, U8 and U9 provide the analogue, digital and RF Charge Pump supply rails respectively. The input to these three regulators is provided by an external 5V dc regulated power supply, which is connected to the board via connector J7, a snap type connector.

The Analogue, Digital and RF Charge Pump supply voltage levels can be monitored on test points TP5, TP6 and TP7 respectively.

LED illumination confirms the on-board presence of the +3.3V dc digital voltage supply.

6.1.2 Clock Options

The PCB is designed to provide three CMX703x device clock options. The board is supplied with a 19.2MHz oscillator module fitted. This option allows convenient RF synthesiser configuration to typical channel spacings. If a FI providing an auxiliary DAC at AuxDAC4 is used, then fine tuning of the output frequency is possible. A 3.9k Ω resistor should be fitted in position R21 for this purpose.

Other options are an external clock source at J3 and PCB footprints for assembly of a quartz crystal oscillator circuit (C34, C35 and X1).

Header J4 is used with jumper sockets to select the required option as shown in the table below. Shaded cells illustrate locations where a jumper socket should be fitted.

J4 Jumper position	Clock option		
	19.2MHz TCXO (default)	External	Quartz crystal
1->2			
3->4			
5->6			
7->8			
9->10			

Table 1 Clock Select Jumper Positions.

6.1.3 Control Interface

The C-BUS and CMX703x boot control signals are brought out on connector J1. This is a right angle male header designed to plug directly into the PE0001 controller card which has a matching female header. Additionally this connector carries the +3.3V digital supply rail, which can be used to power the PE0001 card.

Alternatively, if not using the PE0001, the CMX703x boot control signals can be manually set with jumpers on header J9.

It is possible that a future CMX703x device will have an RS232 interface instead of a C-BUS interface. In such cases, the PE0201 will not operate with the PE0001 controller kit; the RS232 interface provided on the PE0201 PCB should be used instead.

6.1.4 Baseband Interfacing

Connector J11 provides access to Auxiliary ADCs 1 to 4, Auxiliary DACs 1 to 4, and the general purpose I/O lines of the CMX703x device.

The CMX703x device baseband input amplifiers for IP1, IP2 and IP3 are configured as AC coupled, unity gain, inverting amplifiers. The inputs to these circuits are fed from connector J10.

The CMX703x device baseband outputs, MOD1, MOD2 and AUDIO, are fed through an RC network to connector J10.

A dual op amp IC is fitted to the board, with both amplifiers configured as unity-gain buffers. It is possible to set up other op amp based configurations with the addition of passive components to the PCB footprints provided. It is recommended that 0603 sized surface mount components are used. Access to the input and output of each of these uncommitted amplifiers is also from connector J10.

6.1.5 RF Circuits

The board is fitted with a Voltage Controlled Oscillator (VCO). Using RF synthesiser 1 of the CMX703x device, the VCO is tuneable across a range of 450 to 470MHz, with a nominal frequency of 460MHz. The output of the VCO is fed to connector J5, which is a straight SMA type. The charge pump settings for CMX703x (RF channel control register, \$B3), when using this VCO should be:

Positive slope - \$B3;b4=0.

High gain - \$B;b3=1;

For further information, refer to relevant CMX703x data sheet.

Alternatively, RF synthesiser 1 can be used with an external VCO, with the following circuit changes:

- Remove R11 and R28 - Disconnect VCO output from CMX703x.
- Remove R32 – Stops the on-board VCO oscillating.
- Remove R15 – Disconnect CMX703x charge pump output from on-board VCO.

The charge pump output of RF synthesiser 1 can now be picked up from TP3, labelled CP1OUT, and the users VCO output connected to the SMA connector J2, labelled RF1_EXT. Note that the loop filter for RF synthesiser 1 is still in circuit.

RF synthesiser 2 can also be used with a user-supplied external VCO. A loop filter can be constructed using the PCB footprints provided. Also, the ISET resistor, R38, must be fitted. The user-supplied VCO can be fitted across the following connectors that are not fitted:

- J6, SMA socket, labelled RF2_EXT – RF input to RF synthesiser 2.
- TP4, test loop, labelled CP2OUT – Charge pump output.

6.2 Adjustments and Controls

The boot state of the CMX703x device can be set manually, using jumpers on header, J9. If using with the PE0001.

6.3 Function Image™

The PE0201 is shipped with a blank EEPROM, U2. The EEPROM is socketed, allowing it to be removed and externally programmed with a FI. Instead of using the EEPROM, FIs may be downloaded into the CMX703x device via the C-BUS interface.

Whenever power is removed from the PE0201 the FI will be erased from the CMX703x device. Therefore, whenever power is applied a FI must be loaded, either from the EEPROM or via the C-BUS interface.

6.4 Evaluation Tests

Before a FI is loaded into the CMX703x device, there is a limited functionality which can be demonstrated directly by programming the C-BUS. The first group of examples can be used to verify control of the CMX703x via the C-BUS serial interface.

All of the following examples are available as PE0001 compatible script files from the CML website.

6.4.1 Write to and Read from a Register

- Write any 16-bit number to register \$C0.
The data transferred to the device on the Command Data pin looks like this:

```
{ C0 } { <ms byte> } { <ls byte> } ..... Command Data
```
- The value written to this register (the Powerdown Control register) can be read back from register \$C4 by issuing a single command byte, then reading two data bytes from the Reply Data pin, as follows:

```
{ C4 } ..... Command Data
{ <ms byte> } { <ls byte> } ..... Reply Data
```

Note that the power consumption of the device will increase once this register has been written to, since some parts of the device will no longer be powersaved.

6.4.2 Check Analogue Path and Set Input Gain

Write 0x4061 to \$C0 (Powerdown Control)
 Write 0x0C30 to \$B1 (Input Gain and Signal Routing)
 Write 0x0008 to \$CF (Test Mode)

Apply a 1kHz, audio signal to the input, IP3 (J10 pin 5), at a level of -10dBm (the maximum signal level before distortion is about +1dBm).

Check the audio signal coming out of the AUDIO OUT pin (J10, pin 11). The level should be 5.5dB, below the level of the input signal.

The MOD1 and MOD2 outputs should have no signal on them. All three outputs should have a dc bias level of approximately 1.65 volts.

6.4.3 Check Analogue Path and Set Output Gain

Write 0x03E1 to \$C0 (Powerdown Control)
Write 0x410C to \$B0 (Analogue Gain)
Write 0x0001 to \$CF (Test Mode)

Apply a differential 1kHz, audio signal across the inputs, IP1 (J10, pin 1) and IP2 (J10, pin 2), at a level of 0dBm between them.

Check the audio signal coming out of the AUDIO OUT pin (J10, pin 11). The level should be -9.6dBm.

Check the audio signal coming out of the MOD1 pin (J10, pin 7). The level should be -6.0dBm.

Check the audio signal coming out of the MOD2 pin (J10, pin 9). The level should be -12.0dBm.

All three outputs should have a DC bias level of approximately 1.65 volts.

6.4.4 Generate Two External Digital Clocks

Write 0x0021 to \$C0 (Powerdown Control)
Write 0x2577 to \$AB (System Clock 1 PLL Configuration)
Write 0xE0C8 to \$AC (System Clock 1 Reference and Source Configuration)
Write 0x09A0 to \$AD (System Clock 2 PLL Configuration)
Write 0xE0C8 to \$AE (System Clock 2 Reference and Source Configuration)

With the default 19.2MHz clock input, a digital clock frequency of 4.0MHz should be observed at the AUX/SYS CLOCK 1 output, labelled CLKOUT1 (TP1), and a frequency of 19.968MHz should be observed at the AUX/SYS CLOCK 2 output, labelled CLKOUT2 (TP2).

Now write 0xA0C8 to either \$AC or \$AE registers, to turn off the CLKOUT1 or CLKOUT2 outputs, respectively.

6.4.5 Set RF Synthesiser 1

These settings will enable the on-board VCO to switch between two frequencies of 455MHz and 465MHz. The VCO output is monitored at SMA socket, J5, labelled 460MHz.

Each synthesiser has an N and an R value for the Rx frequency and the same again for the Tx frequency. Once programmed, the synthesiser can easily be switched between Rx and Tx. An Application Note is available separately, to help calculate the N and R values. The RF Channel Data register (\$B2) is used to program both RF synthesisers and this is done by 16 contiguous writes to this register. This can be reduced to 8 contiguous writes if only one of the synthesisers is to be programmed. There is no indication of the completion of these writes, except that the synthesiser which has been written to will indicate lock in the RF Channel Status register (\$B4), once it has been enabled, and providing the correct external components have been used for the programmed frequency. For this example, it is assumed that the RF frequency is derived from the default clock frequency of 19.2MHz.

To select an Rx frequency of 465MHz and a Tx frequency of 455MHz on Channel 1 Synthesiser, with a loop comparison frequency of 25kHz, the following values of N and R are required:

For 455MHz, using the Tx divider registers:
Tx N = 18,200 = 0x4718
Tx R = 768 = 0x0300

For 465MHz, using the Rx divider registers:

Rx N = 18,600 = 0x48A8
Rx R = 768 = 0x0300

Write 0x8000 to \$B3 (RF Channel Control) to select XTAL clock input as reference.

Write 0x0021 to \$C0 (Powerdown Control)

Write 0x4318 to \$B2 (RF Channel Data, Tx N b9:0)

Write 0x4411 to \$B2 (RF Channel Data, Tx N b19:10)

Write 0x4B00 to \$B2 (RF Channel Data, Tx R b9:0)

Write 0x4C00 to \$B2 (RF Channel Data, Tx R b19:10)

Write 0x50A8 to \$B2 (RF Channel Data, Rx N b9:0)

Write 0x5412 to \$B2 (RF Channel Data, Rx N b19:10)

Write 0x5B00 to \$B2 (RF Channel Data, Rx R b9:0)

Write 0x5C00 to \$B2 (RF Channel Data, Rx R b19:10)

Then:

Write 0x802D to \$B3 (RF Channel Control) to select the Rx frequency or ...

Write 0x802B to \$B3 (RF Channel Control) to select the Tx frequency or ...

Write 0x8028 to \$B3 (RF Channel Control) to disable both Rx and Tx frequencies

When RF Synthesiser 1 is in lock, it will return the value 0x01 in the RF Channel Status register (\$B4). When not in lock, this value will be 0x00. Depending on the setting of the IRQ mask in the IRQ Mask register (\$CE), an interrupt will be generated and the interrupt will be reported in the Status 1 register (\$C6) as the value 0x8002.

7. Performance Specification

7.1 Electrical Performance

7.1.1 Absolute Maximum Ratings

Exceeding these maximum ratings can result in damage to the Evaluation Kit.

	Min.	Max.	Units
Supply ($V_{IN} - V_{SS}$)	-0.3	9.0	V
Voltage on any connector pin to V_{SS}	-0.3	3.6	V
Current into or out of V_{IN} and V_{SS} pins	0	+0.45	A
Current into or out of any other connector pin	-20	+20	mA

7.1.2 Operating Limits

Correct operation of the Evaluation Kit outside these limits is not implied.

	Notes	Min.	Max.	Units
Supply (+V - V_{GND})		4.5	5.5	V
External Clock Frequency		4.0	24.576	MHz

7.1.3 Operating Characteristics

For the following conditions unless otherwise specified:

Evaluation Device Clock Frequency = 19.2MHz, $V_{IN} = 5.0V$, $T_{amb} = +25^{\circ}C$.

For CMX703x parameters, see relevant CMX703x data sheet.

	Notes	Min.	Typ.	Max.	Units
DC Parameters					
I_{DD}	1	60	75	100	mA
+3V3A		3.15	3.3	3.45	V
+3V3D		3.15	3.3	3.45	V
+3V3_VCO		3.15	3.3	3.45	V
Baseband Parameters					
Output Impedances					
Mod1, Mod2 and Audio	2	-	100	-	k Ω
Buf1out and Buf2out	4	-	0.1	-	Ω
Input Impedances					
IP1, IP2 and IP3		-	50	-	k Ω
Buf1in and Buf2in	4	1	-	-	M Ω
External Clock Input					
'High' pulse width	3	21	-	-	ns
'Low' pulse width	3	21	-	-	ns
Input impedance		10	-	-	M Ω
VCO output					
Frequency range		450	-	470	MHz
Power		-	6.5	-	dBm
Output Impedance		-	50	-	Ω

- Notes:**
1. Not including any current drawn from pins by external circuitry.
 2. Small signal impedance.
 3. Timing for an external input to the CLOCK/XTAL pin.
 4. When configured, as supplied, as unity gain buffers.

7.1.3 Operating Characteristics - Timing Diagrams

See relevant CMX703x documentation for C-BUS signal timing information.



About FirmASICTM

CML's proprietary FirmASICTM component technology reduces cost, time to market and development risk, with increased flexibility for the designer and end application. FirmASICTM combines Analogue, Digital, Firmware and Memory technologies in a single silicon platform that can be focused to deliver the right feature mix, performance and price for a target application family. Specific functions of a FirmASICTM device are determined by uploading its Function ImageTM during device initialization. New Function ImagesTM may be later provided to supplement and enhance device functions, expanding or modifying end-product features without the need for expensive and time-consuming design changes. FirmASICTM devices provide significant time to market and commercial benefits over Custom ASIC, Structured ASIC, FPGA and DSP solutions. They may also be exclusively customised where security or intellectual property issues prevent the use of Application Specific Standard Products (ASSP's).





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For a full data sheet listing see: www.cmlmicro.com/products/datasheets/download.htm

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Oval Park, Langford, Maldon, Essex, CM9 6WG - England. Tel: +44 (0)1621 875500 Fax: +44 (0)1621 875600 Sales: sales@cmlmicro.com Technical Support: techsupport@cmlmicro.com	4800 Bethania Station Road, Winston-Salem, NC 27105 - USA. Tel: +1 336 744 5050, 800 638 5577 Fax: +1 336 744 5054 Sales: us.sales@cmlmicro.com Technical Support: us.techsupport@cmlmicro.com	No 2 Kallang Pudding Road, #09 - 05/06 Mactech Industrial Building, Singapore 349307 Tel: +65 6745 0426 Fax: +65 6745 2917 Sales: sg.sales@cmlmicro.com Technical Support: sg.techsupport@cmlmicro.com	No. 218, Tian Mu Road West, Tower 1, Unit 1008, Shanghai Kerry Everbright City, Zhabei, Shanghai 200070, China. Tel: +86 21 6317 4107 +86 21 6317 8916 Fax: +86 21 6317 0243 Sales: cn.sales@cmlmicro.com.cn Technical Support: sg.techsupport@cmlmicro.com