MVP-Cxx-(D1)

Proportional Valve Controller

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Contents

Welcome

Welcome to **High Country Tek** Inc. HCT is North America's foremost independent designer and producer of modular, ruggedized digital and analog electronic controllers for the fluid power industry.

From our factory in California, we manufacture 'specialty' controllers for specific functions and the user programmable 'DVC family' to enable large area networked system solutions.

The modules are used in mobile, industrial and marine applications. They are also applied successfully in other industry segments.

HCT products are encapsulated in solid flame resistant material for maximum durability, electrical integrity and complete environmental security.

HCT is a market leader in many application arenas, including hydraulic generator, *e-Fan* and hydraulic fan system controls. These controllers facilitate significant fuel, emission and operational savings.

HCT's market neutrality offers integration with any hydraulic OEM valves, pumps, sub-systems or systems.

For more information, please visit us at: **www.hctcontrols.com**.

Cautions

Changing setup values or operating modes while a machine is running may cause unintended machine movement. It could lead to possible **injury** or **death**. Any moving parts should be disabled prior to changing setup values or operating modes. In every case, exercise caution and work should be completed only by qualified personnel.

Product Application Guidelines

ALWAYS do the following

- FULLY read this manual and accompanying data sheets BEFORE starting.

- Isolate this unit from all other equipment BEFORE any form of welding.

- Isolate the controller from ANY form of battery charging or battery boosting.

- Be aware of the electrical & mechanical connections, and the expected reactions of the equipment.

- Operate the units within the temperature range.

- Use the correct tools to do the job (i.e. P.C., software) etc.

- Separate High Voltage AC cables from Low Voltage DC signal and supply cables.

- Make sure power supply is CORRECT, ELECTRICALLY CLEAN, STABLE, and rated for the full load.

- Make sure the controller output voltage & current is compatible with the equipment.

- All unused wires / terminals should be terminated safely.

- Ensure ALL connectors have no unintended SHORT or OPEN circuits.

- Ensure ALL connectors are wired correctly, secure, locked in place and fully connected.

- Disconnect or connect wires to or from this unit only when the power supply is disconnected.

- Use adequate screening in areas of intense Radio Frequency fields.

- Ensure ALL work areas are clear of personnel before operating the controller.

- Follow and abide by local and country health & safety standards.

MVP-Cxx-(D1) Controller

The MVP-Cxx-(D1) controller drives proportional solenoid valves. The output current is proportional to the command input.

Once configured, the settings are permanently stored in the controller memory.

MVP-C Features

- Easily configured using HCT Graphical User Interface (GUI) or HCT Hand Held Interface (HHI)
- LED indication of power, output current and fault status
- Permanently sealed, standard DIN 43650 Form A connector body with pre-wired 18AWG PVC cable
- Multiple modes for proportional or 2-speed control
- Single coil applications, programmable enable input
- All input and output limits are independently adjustable
- Adjustable output with short circuit protection, adjustable ramp up and ramp down rates

Operating Specifications

	MVP-C (Standard)	MVP-Cxx-xxxD1
Supply Voltage	9 to 28VDC	
Supply Current	Valve current + 20mA (Quiescent Max)	
Output Current	**-06A:** 600mA MAX **-12A:** 1.2A MAX **-25A:** 2.5A MAX	**-06A:** 600mA MAX **-25A:** 2.5A MAX
Coil Resistance	2Ω MIN.	
Reference Voltages	+5V @ 2mA	
Dither Frequency	30, 33, 38, 43, 50, 60, 75, 100, 150, 300Hz (Select OFF for 1000Hz)	80, 100, 120, 140, 160, 180, 200, 220, 240, 260, 80, 300Hz (Select OFF for 1000Hz)
Analog Input Range	**-C1V:** 0 to 10V; **-C2A:** 4 to 20mA	
Analog Input Impedance	**-C1V:** 12KΩ; **-C2A:** 250Ω	
Operating Temperature Range	-20º to 70º C (operating); -40º to 85º C (storage)	
Enclosure	Glass filled Nylon	
Dimensions	Inch: 2.4 L x 1.2 W x 0.75 H; Mm: 60 L x 30 W x 19 H	

Physical Description

There are two indicator LEDs: STATUS and OUTPUT. The STATUS LED is green when the applied voltage is within the operating range.

The OUTPUT LED is yellow and the brightness will vary with the output current.

In the case of a fault the STATUS LED will flash red with a flash code. It will continue to flash until clearing faults by moving the command signal out of active range or cycling the power. See Fault Status for details.

The MVP communicates with the Graphical User Interface through an infrared interface port to RS232. The infrared adapter clips onto the MVPC/D1 aligning with the notches in the sides. It must be powered when configuring the settings.

User Interface

The MVP has a number of internal settings.

Users can open the Graphical User Interface to view, make changes and save the settings in a data file which can be uploaded to any MVP controller.

The Hand Held Interface can also be used to view and make changes, but this device does not have the capability to save the settings in a data file. The programmer, cable and adapter are self-contained which makes the HHI a viable alternative for field work.

Configuration

The GUI has 4 buttons (ran from a PC): Lock, Unlock, Up, and Down. There are short-cut keys: '/'(lock), '*'(unlock), '+'(up), and '-'(down).

The HCT Hand Held Interface has the same 4 buttons and 2-line LCD.

Use the up and down arrows to navigate through the parameter list. The display will show the next parameter in the list when pressed. The parameter name is on the first line and the value is on the second line. The list is in circular, stepping down from the last parameter to the first and vice-versa.

There are three types of parameters: **fixed; monitor; and variable**. **Fixed** parameters show the module's firmware version, etc. **Monitor** parameters display output current and system voltage. Use **variable** parameters to configure the controller, such as maximum output current, operating mode, etc. Some parameters combine variable and monitor in one line. Use it to set a variable according to the current monitor value.
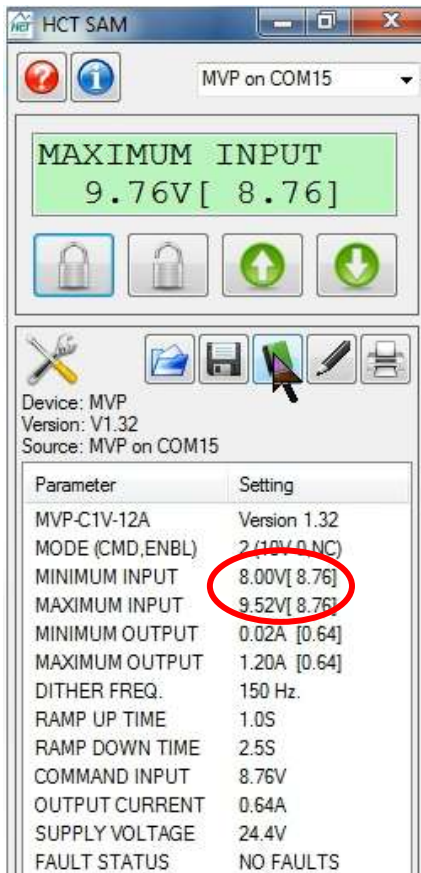
Press the unlock button to enter the edit mode. An asterisk (*) will appear at the beginning of the second line. Use the up and down buttons to change the value. For parameters containing both variable and monitor, the monitor data is in square brackets.

Press the lock button to save the parameters and end edit mode.

When the lock button is pressed, the changes take effect immediately. Change values only when the machine is **NOT** running.

"Read settings from controller" displays a static table of values from non-volatile memory. The changes made to the settings by selecting "lock" are not updated in the table unless "read settings from controller" is selected again.
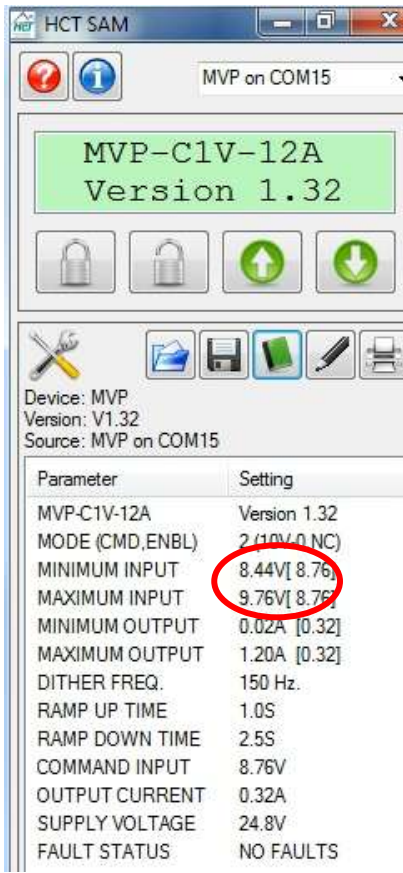
To save the settings into a file for future use, click "read settings from controller" before clicking "save settings to file".

When uploading settings from a data file, the static table shows the settings from the data file, but they are not in the controller yet.

Click "write settings to controller" before clicking "read settings from controller". After this step, the static table will display the MVP settings from the data file.

Parameter List

The following table outlines the MVP-F parameters as well as the limits and units of measure for each parameter.

Parameter	Limits	Units
MVP-Cxx-xxx-(D1)		Version #
Mode	See Mode Description	Mode #
Minimum input	0 to 10.0	V
	4 to 20.0	mA
Maximum input	0 to 10.0	V
	4 to 20.0	mA
Minimum output	0 to 600*	mA
Maximum output	0 to 600*	mA
Ramp up	0.0 to 120.0	Seconds
Ramp down	0.0 to 120.0	Seconds
Dither frequency (MVP-C)	30 to 300, (select OFF for 1000Hz)	Hz.
Dither frequency (MVP-Cxx-xxx-D1)	80 to 300, (select OFF for 1000Hz)	Hz
Output current		mA
Supply voltage		Volts
Fault status		Fault

*0 to 1.2A for **–12A** version, 0 to 2.5A for **–25A** version for MVP-C

*0 to 2.5A for **–25A** version for MVP-Cxx-xxx-D1

MVP-Cxx - The title parameter is fixed. It displays the model number and the firmware version.

MODE - Six modes of operation.

1. Output is proportional to the command input with Enable not used.
2. Output is inversely proportional to the command input with Enable not used.
3. Output is proportional to the command input with Enable used.
4. Output is inversely proportional to the command input with Enable used.
5. 2-speed where Enable provides output at the level set in Minimum Output and Command provides output at the level set in Maximum Output.
6. 2-speed where Enable provides output at the level set in Maximum Output and Command provides output at the level set in Minimum Output.

MIN INPUT - Sets the minimum command input. The input can be inverted. The value in the brackets is the present command input. This parameter is a combination variable/monitor type.

MAX INPUT - Sets the maximum command input. The input can be inverted. The value in the brackets is the present command input. This parameter is a combination variable/monitor type.

MIN OUTPUT - Sets the minimum output current (milliamps for -06A, amps for -12A, -25A). It cannot be inverted. The value in the square brackets is the present output current. This parameter is a combination variable/monitor type.

MAX OUTPUT - Sets the maximum output current (milliamps for -06A, amps for -12A, -25A). It cannot be inverted. The value in the square brackets is the present output current. This parameter is a combination variable/monitor type.

RAMP UP/DOWN - Sets the time for Output current to ramp **UP** or **Down** through the full input range. These parameters are variable.

DITHER FREQ. – Set the PWM or dither frequency according to the valve specifications. This parameter is variable.

Options: 30, 33, 38, 43, 50, 60, 75, 100, 150, 300, (Select OFF for 1000Hz) for MVP-C.

Options: 80, 100, 120, 140, 160, 180, 200, 220, 240, 260, 280, 300, (Select OFF for 1000Hz) for MVP-Cxx-xxx-D1.

OUTPUT CURRENT - Displays the present output current. This parameter is a monitor type.

SUPPLY VOLTAGE - Displays the module's power supply voltage. It is helpful for troubleshooting. This parameter is a monitor type.

FAULT STATUS - The STATUS LED will flash red 2 times for Coil Open and 3 times for Coil Short.

Dual-coil valve control:
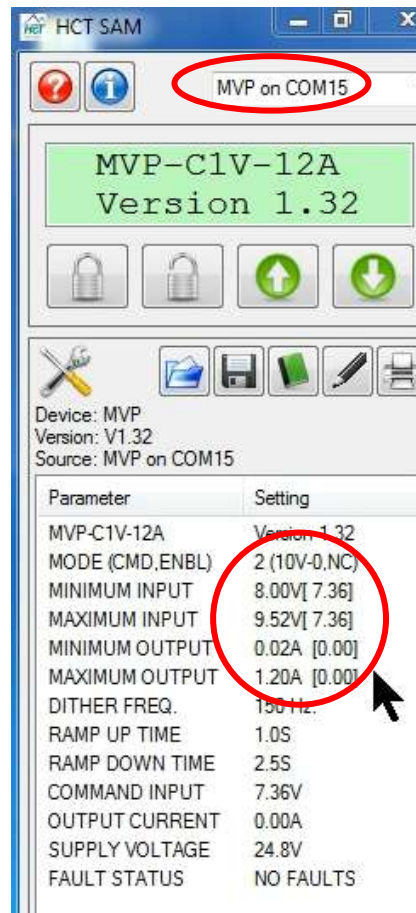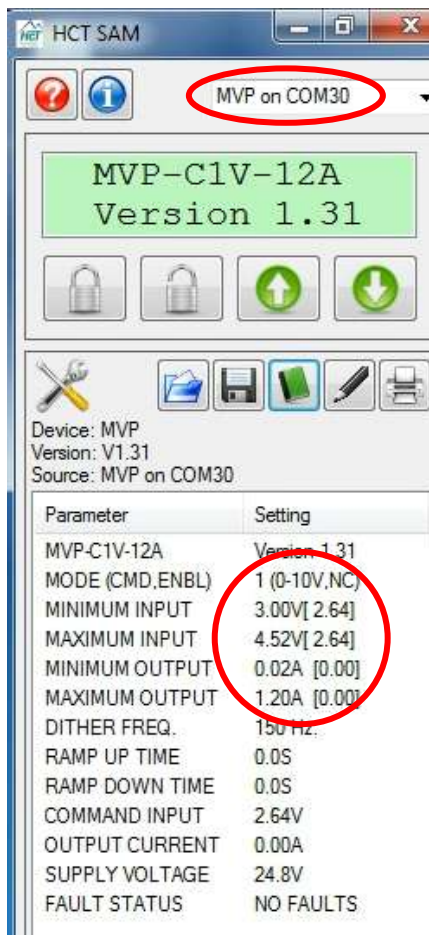
1st MVP drives coil A. It is in mode 1.

The input range is 3-4.52V.

The present input is 2.64V, out of the input range. That is why coil A current is 0.
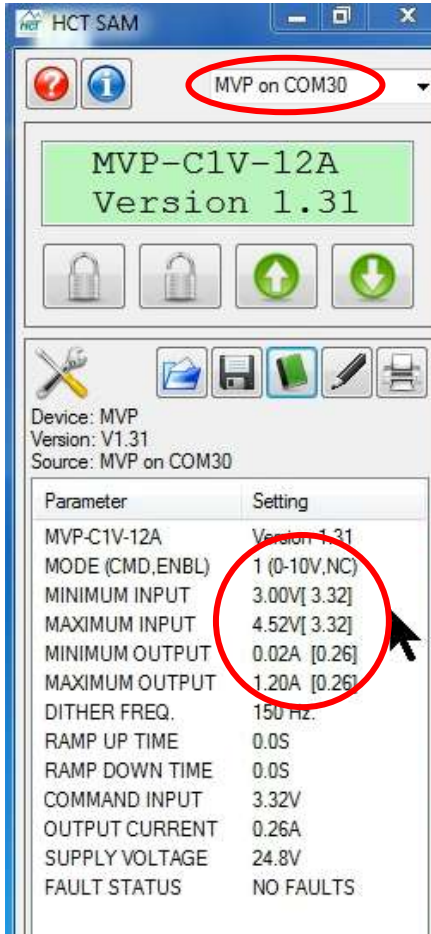
2nd MVP drives coil B. It is in mode 2

The input range is 8-9.52V which is equivalent to 2-0.48V. The present input 7.36V is equivalent to 2.64V for coil A.

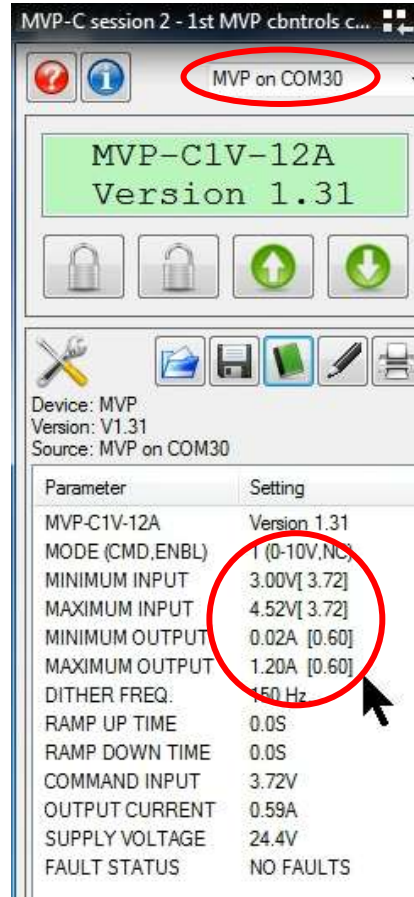Coil B output is 0A.

Input is 3.32V, coil A current is 0.26A.

Input is 3.72V, coil A current is 0.6A because the current is limited by the coil resistance.

Input is 3.32V, coil A current is 0.26A.

Input is 3.72V, coil A current is 0.6A because the current is limited by the coil resistance.
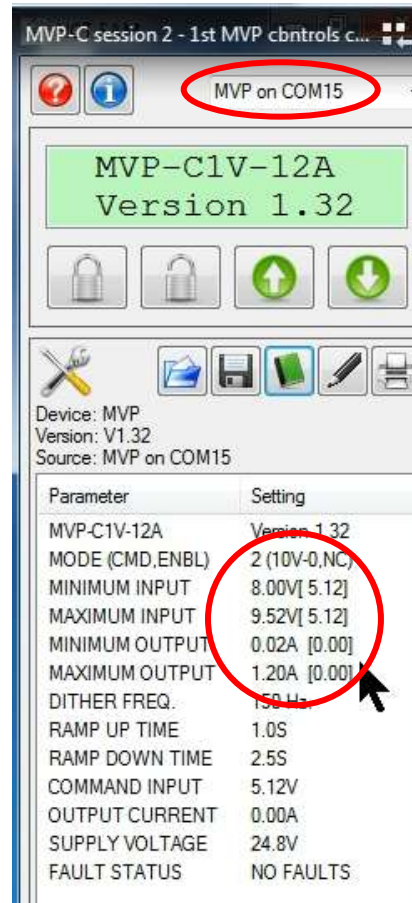
Input is 4.84V, coil A current is 0.79A because the current is limited by the coil resistance.

Input 4.84V is equivalent to 5.16V for coil B. Coil B current is 0A because the input is in deadband.

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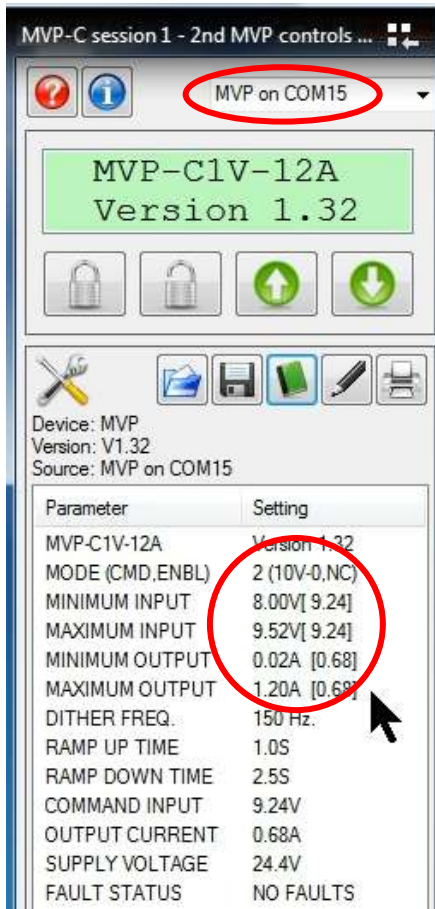
Input is 9.24V, coil B current is 0.68A because the current is limited by the coil resistance.

10V input for coil B is equivalent to 0V for coil A.

Notes: when using two MVPs to drive a dual-coil valve, sudden power loss will cause unintended high speed movement in one direction.
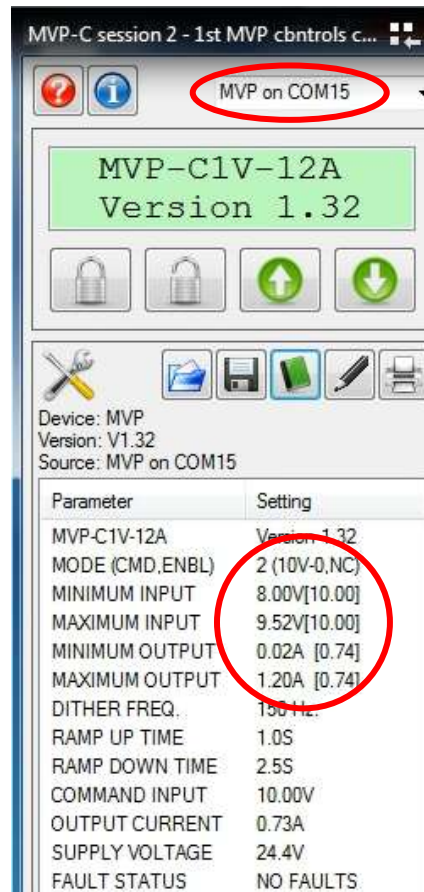
Wiring

Terminal	Function
Brown	+PWR
Blue	PWR GND
Black	Command Input
White	Enable Input
Red	+5V Reference
GRN/YEL	Connector GND

Order Information

The following is a break-down of the MVP part numbering system:

M V P - C 1 V - 0 6 A - 1 0 F

10F = 10ft cable
20F & 30F standards

06A = 600mA output
12A = 1200mA output
25A = 2500mA output

C1V = 0-10V input
C2A = 4-20mA

M V P - C 1 V - 0 6 A - 1 0 F - D 1

10F = 10ft cable
20F & 30F standards

06A = 600mA output
25A = 2500mA output

C1V = 0-10V input
C2A = 4-20mA
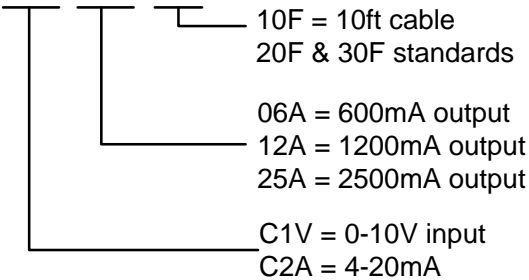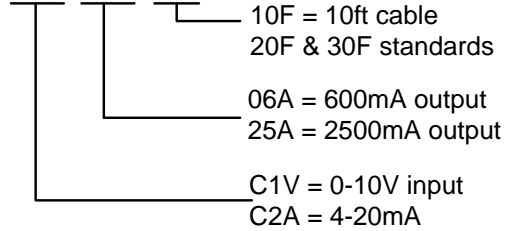
Required Communication Cables:

For the Hand Held Interface Device: P/N: CBL-IRA

For the PC software SAM: PN: CBL-IRMU

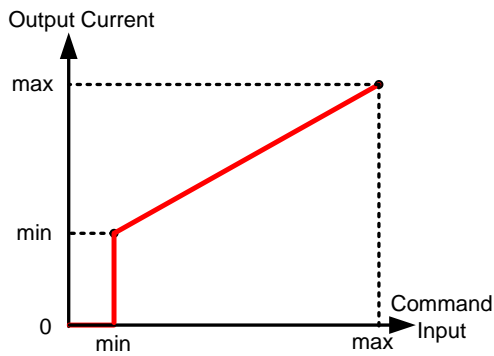P/N: CBL-IRA   P/N: CBL-IRMU
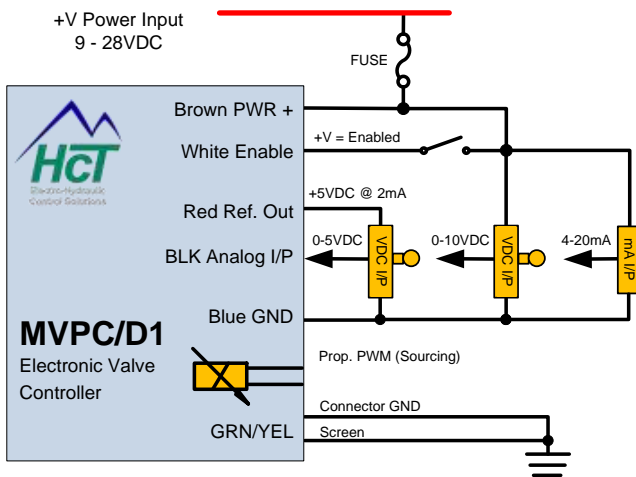
Application Examples

Single Solenoid Control

The MVP can drive a single solenoid with a signal of 0-5VDC, or 0-10VDC, or 4-20mA.

Mode 1 is used when the enable switch is not used. Mode 3 is used when the enable switch is used.

Set the dither and output settings according to the valve specifications.
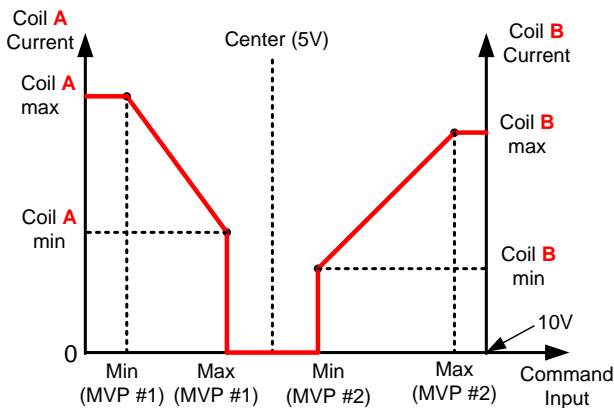
Dual-coil Valve Control

Two MVPs can drive a dual-coil valve with a signal of 0-5VDC, or 0-10VDC, or 4-20mA.

If enable switch is not used, set MVP #1 to be Mode 1, MVP #2 to be Mode 2.

If enable switch is used, set MVP #1 to be Mode 3, MVP #2 to be Mode 4.

Set 2.5-5VDC for MVP #1, 7.5-10VDC for MVP #2 when there is no deadband in the command input. Normally we leave deadband in the middle and both ends.

Set the dither and output settings according to the valve specifications.
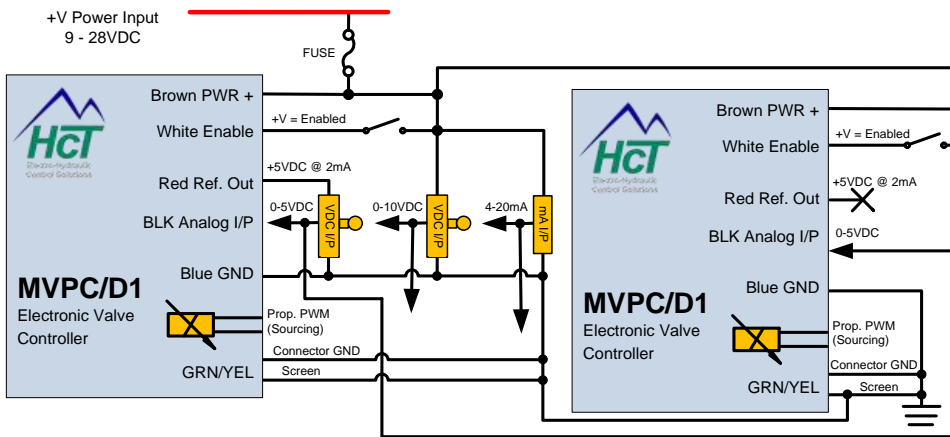
Double Solenoid Control

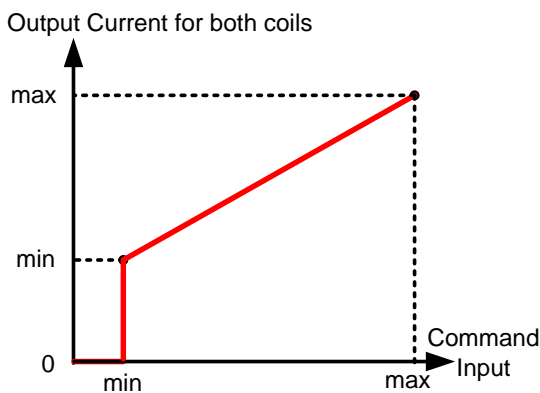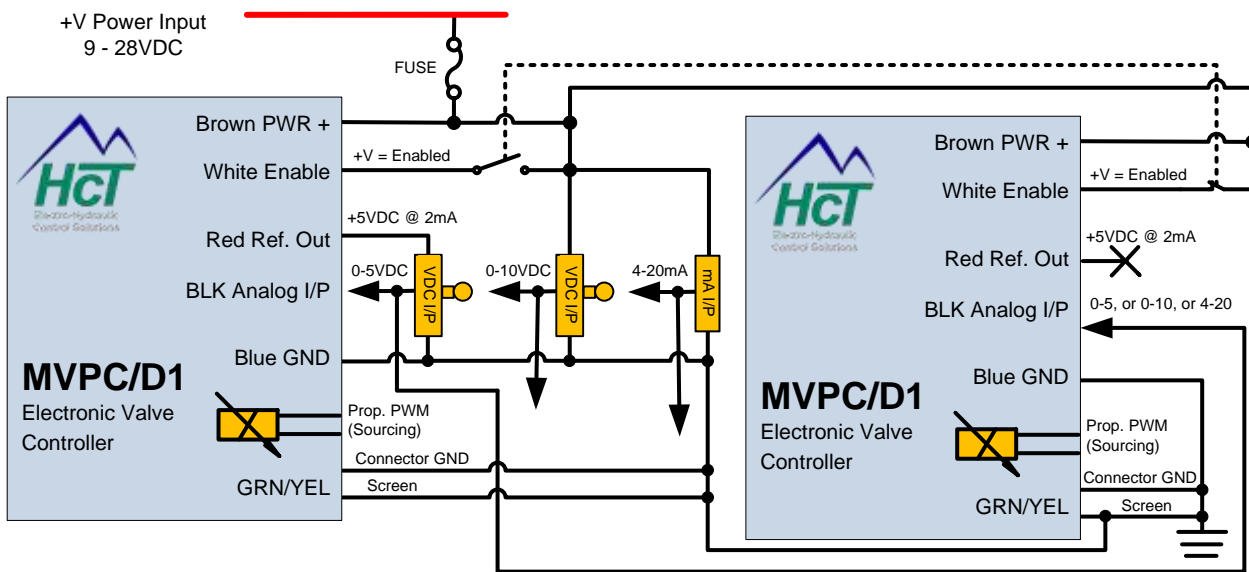Two MVPs can drive a double solenoid valve with a signal of 0-5VDC, or 0-10VDC, or 4-20mA.

A selector switch determines which solenoid is activated. If enable switch is not used, set MVP #1 to be Mode 1, MVP #2 to be Mode 1. If enable switch is used, set MVP #1 to be Mode 3, MVP #2 to be Mode 3.

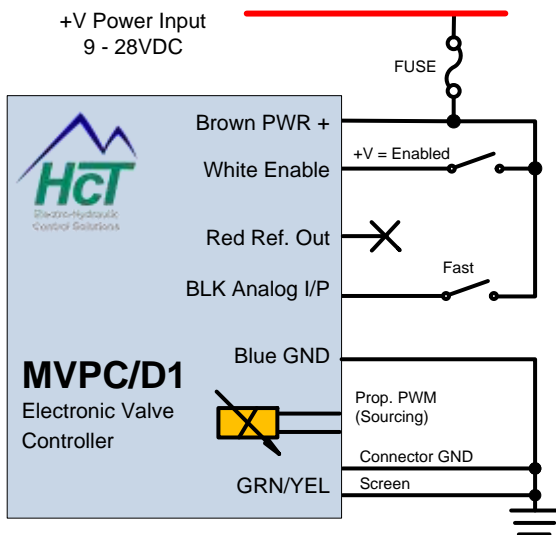Set the dither and output settings according to the valve specifications.

Single Solenoid 2-speed Control

The MVP can be configured for 2-speed control.

When selecting mode 5, the Enable signal allows minimum output.

The Command signal allows maximum output.

Single Solenoid 2-speed Control

The MVP can be configured for 2-speed control.

When selecting mode 6, the Enable signal allows maximum output.

The Command signal allows minimum output.

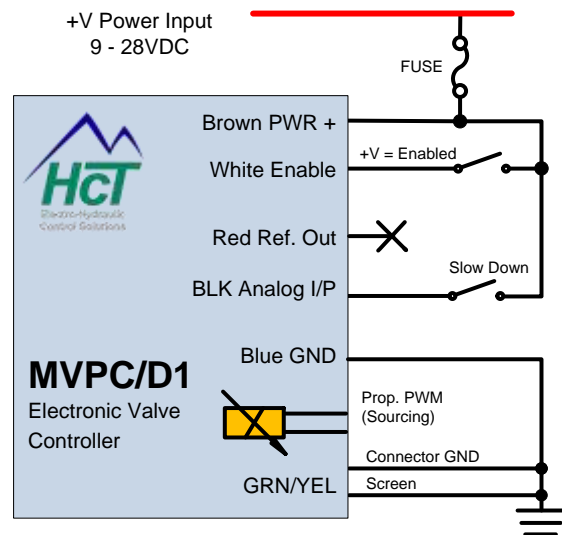| Output Current	Enable Switch	Command Switch
Minimum Setting	On	Off
Maximum Setting	On	On

Output Current	Enable Switch	Command Switch
Maximum Setting	On	Off
Minimum Setting	On	On

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- ❖ **Agriculture**
- ❖ **Cranes & lifts**
- ❖ **Refuse & Re-cycling**
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