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#### **REVISION LIST:**

Revision	Date	Author	Chapter	Description
1.010	01/12/2011	FI	All	Software changed (v3.201)
1.011	01/02/2012	FI	All	Revision
1.012	08/02/2013	Nt	All	Added new chapters
1.013	30/05/2013	FI	All	Added USB driver link

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# **SECURITY ALERT:**

#### **GENERAL INFORMATION**

To ensure safe operation, the device must be operated according to the instructions in the manual. When using the device are required for each individual application, legal and safety regulation. The same applies also when using accessories.

#### **INTENDED USE**

Machines and systems must be designed so the faulty conditions do not lead to a dangerous situation for the operator (i.e. independent limit switches, mechanical interlocks, etc.).

#### **QUALIFIED PERSONNEL**

The device can be used only by qualified personnel, strictly in accordance with the specifications.

Qualified personnel are persons who are familiar with the installation, assembly, commissioning and operation of this equipment and who have appropriate qualifications for their job.

#### **RESIDUAL RISKS**

The device is state of the art and is safe. The instrument can represent a potential hazard if they are inappropriately installed and operated by personnel untrained. These instructions refer to residual risks with the following symbol:



This symbol indicates that non-observance of the safety instructions is danger for people to serious injury or death and / or the possibility of damage.

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# **INTRODUCTION:**

The CAN Analyzer is a powerful, flexible and economic instrument which develops and verifies system based in CAN-CANopen-DeviceNet-J1939-NMEA 2000.

This product allows the study and configuration of CANopen systems, using a user interface that permits a simple access to devices and their objects.

The instrument is composed of the following: module hardware with a USB/Ethernet interface that connects to a personal computer and a CAN terminal that connects to the line and software for MS Windows.

The driver of USB can be downloaded from here: <u>www.adfweb.com/download/filefold/SW67119.zip</u>.

# THE SOFTWARE:

To obtain software please go to <u>www.adfweb.com/home/download/download.asp</u>.

(*This manual is referenced to the last version of the software present on our web site*). The software works with MSWindows (MS 2000, XP, Vista, Seven, 8; 32/64bit). When launching the SW67411 the below window appears (Fig. 1).

The software is composed of various windows that are controllable from a main window which allows access to the different CAN Analyzer functions (Fig. 1).

ADFweb.com Analyzer_CAN SW67216	[New.Cfg]			<b>×</b>
File Function View Forms Ethernet CAN-BUSLOAD	Trace Help Packet receive: 0 Packet error controller: 0	Packet discarded filter: 0 Filter Ok	Cr Tr	> Ov WI Bo ● ● ● ●
📕 Ready 📕 Trace	Stop			

Figure 1: Main window for SW67216



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## Status Desc indicates:

- ✤ Packet receive: the number of CAN bus packages received from the hardware device;
- Packet discarded Filter: the number of the CAN bus packages discarded from the hardware device;
- ✤ Packet error controller the number of CAN bus packages discarded erroneously from the Controller CANbus;
- Send Filter Bad Filter Filter Ok: the state of the filter configurable from the software.

# Status LED indicates:

- ✤ Cr: Color gray if the CAN Bus network was not activated. Color yellow if the CAN Bus network is active;
- ✤ Tr : Color red if sending data to the Hw CAN Analyzer device. Color gray if there isn't problems;
- ✤ Tp: Color red if the CAN Transmitters are occupied. Color green if there isn't problems;
- Ov : Color red if overwriting is verified within the receive CAN. Color green if there isn't problems;
- ✤ WI : Color red if there are communications errors on the CAN during transmission and reception. Color green if there isn't problems;
- ✤ Bo : Color red if the CAN bus network is always in error. Color green if there isn't problems.

The Bus Load indicates the load level on the line. Normally, a line does not carry a load over 30%. A long period of time with an abnormal load may indicate that the applications are excessively using the BUS.

This could be caused by an incorrect cable connection (use of the terminal resistors) or the presence of device that functions at a different BAUD RATE than the one set in the analyzer.

The "menu" and "tool bar" access a series set-up possibilities such as:

- communication configuration;
- baud rate of the bus;
- turning on and off the hardware.



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# FUNCTION

In this menu it is possible to Start/Stop the analysis of the CAN network, set the parameters of the Analyzer and the parameters of the CAN bus.



# **FUNCTION** → **CAN** START

By selecting the "CAN Start" button under "Function" menu, the analysis is started.

# FUNCTION → CAN STOP

By selecting the "CAN Stop" button under "Function" menu, the analysis is stopped.



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## **FUNCTION** $\rightarrow$ **SETPORT**:

By selecting the "**SetPort**" button under "**Function**" menu it is possible to select the type of hardware in use and define the parameters of communication.

For the "Serial Type (HD67216)" and "USB Type (HD67316-U-D1)" it's only necessary to select to what "**COM port**" the device is connected (Fig. 2).

For the "Ethernet Type (HD67316-E-D1)" it is necessary to insert the "**IP Address**", "**SubNet Mask**", "**Gateway**" and "**Port**" used for the connection to the device (Fig. 3). All these information are set to the device when the update of parameters was performed.

	Set Port Com	municatio	n		
Select the type of Hadrware Serial Type (HD67216) USB Type (HD67316-U-D1) Ethernet Type (HD67316-E-A1)	Select the type of Hadrware Serial Type (HD67216) USB Type (HD67316-U-D1) Ethernet Type (HD67316-E-A1)				
Select the COM Port	Insert th	e IP Add	ress		
COM11	192	. 168	. 2	], [	66
	SubNet N	1ask			
	255	. 255	255		D
	Gateway	65			
	192	168	. 2		1
Figure 2: "Set Port Communication"	Port				
window for Schartype & USB type	2007				

Figure 3: "Set Port Communication" window for "Ethernet Type"



#### **FUNCTION** → **SETUP PROPERTIES:**

By selecting the **"Setup Properties**" button under **"Function**" menu it is possible to set the properties of CAN bus.

In this menu is possible set the Protocol between "**Standard**" (CAN2.0A) or "**Extended**" (CAN2.0B).

By checking the **"Tx Passive**" field the analyzer doesn't reply with the Ack frame to a CAN frame.

In the section "**Baudrate (kBit/s)**" there is the list of Baud that is possible to select for set the CAN baudrate. It is possible to select only one value.

By checking the "**Show only CIA Baudrates**" it is possible to select only the baudrates defined by CIA. Otherwise it is possible to select also no standard baudrates.

Setting Can		<b>X</b>
Controller	Can0 (SJA1000)	🕝 Can1 (SJA1000)
Protocol	🕝 Standard	Extended
Frame Types	Remote	F Error
	Tx Echo	☐ Tx Passive
Boudrate (kBit/s)	BTO	BT1
20000 CIA 50000 CIA 100000 CIA 125000 CIA 250000 CIA 500000 CIA 800000 CIA 1000000 CIA		
Show only CIA Bau	drates	VOK X Cancel

Figure 4: "Setting Can" window



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# VIEW:

In this menu it is possible to select what see in the Main window.



With the "View/Hide Tool bar" button it is possible to show/hide the toolbar with the commands of the menu.

The "**View Form List**" controls the opening of the windows that access the various CAN Analyzer functions.

With the "Hardware Status" button it is possible to show/hide the information of Bus Load, Packet and Status Led.



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# FORMS:

In this menu it is possible to select which forms see.

File Function View	Forms Ethernet Trace	Help
CAN-BUSLOAD	Can Monitor Can Sender Can Open Monitor Network Manager DeviceNet	ket receive: 0 ket error con'e

The "CAN Monitor" is a window that allows the visualization of the BUS data at the package level.

The "CAN Sender" is a window that allows CAN packages to be send into CAN line.

The "CANOpen Monitor" is a window that allows for the visualization of BUS data, interpreting it as CANopen packages.

The "**Network Manager**" is a window that allows for control of the CANopen modules inserted in the line. It can scan the network to find modules and for each one, it reads the object dictionary.

The "**DeviceNet**" is a window that allows the control of a slave DeviceNet.

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#### Forms → CAN Monitor:

This is the window that allows the visualization of the bus data at the package level and its columns mean the following:

- "Time": indicates the time in which data is received;
- "ID (HEX)": indicates the Identifier;
- "Data (HEX)" indicates the data byte of the CAN package ( they can be from 0 to 8 );
- "ASCII" is the representations of the received data in ASCII character.

The buttons on the tool bar allow the following actions:

- "Export Excel" allows the exportation of the entire content of the grid as a text file;
- Figure 5: "CAN Monitor" window
   "CAN Start" and "CAN Stop" is used for activate or stop the writing of the packages in the grid;
- "Clear" eliminates the grid content;
- "Lock Recent Entities" visualizes the last CAN package;
- "Scroll/Overwrite Mode" serves in the choice to write all packages one after another in the grid or to write all of them in the same row;
- "COB-ID List" permits to see the COB that arrives and see the update of their value;
- "Filter" opens the window for filter set-up.

File F	File Function View Option Help					
þ.	🗊 🥑 🍩 🔽 🛨 🛊 👔 🎫 State: Ready					
NR	TIME	ID (HEX)	DATA (HEX)	ASCII		
1	00:00:00.000.0	00000109	00	1		
2	00:04:17.376.8	04000900	01 50 61 72 61 6D 65 74	Paramet		
3	00:04:18.725.6	02FECC00	00 00 00 00 00 00 00 00			
4	00:04:20.202.2	04000801	02 00 00 00 00 00 00 41	A		
5	00:04:24.400.5	0400080F	02 00 00 00 00 00 00 AC	7		
6	00:04:25.502.0	0400083B	02 00 00 00 00 00 00 02			
7	00:04:27.018.2	04000808	02 00 00 00 00 00 00 01			
8	00:05:08.985.0	0400081F	01 00 00 00 00 00 00 00			
9						
10						
11						
12					-	



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## FILTER FOR CAN2.0A (STANDARD)

The filter is an instrument that allows the hardware module to eliminate package that it does not want to be visualized in the CAN Monitor window. (Note: the filter reacts on the Identifier section of the package)

By pressing the "**Filter**" button from the "Can Monitor" window the "Filter" window (if protocol is standard CAN2.0A) appears (Fig. 6). On the set-up windows for the filter, there are two lists:

- ✓ on the right, the list of the Identifiers (\$0-\$7FF) of the packages to be visualized;
- ✤ On the left, those lists to be eliminated.

To modify the lists, use the keys "<<", ">>", "ALL" and "NONE" to move an Identifier from one list to another, bring them to the right (shown) or the left (hidden).

4	>>	0 1 2 3	â
	ALL	- 5 6 7 8	
Hidden IDs;	NONE	] 10 11 Visible IDs: Nar	ne:
DEC		) HEX	

Figure 6: "Filter" window for Standard Protocol



**Electronic Devices** 

# FILTER FOR CAN2.0B (EXTENDED): COB-ID FILTER

When the protocol is extended (CAN2.0B) by pressing the "Filter" button from the "Can Monitor" window the "Filter CAN 2.0B/J1939" window appears (Fig. 7).

In this window there are:

- ✤ A text area on the left for insert the COB-ID in the filter:
- ✤ A big area on the right for display the COB-ID inserted;
- ✤ Two buttons for add or delete the COB-ID;
- ✤ Two options for set the filter to "Type Positive" or "Type Negative".

For insert a COB-ID in the filter you have to digit the COB-ID in the first text area and click on the "ADD" button. Now the COB ID compare on the right box. For delete a COB-ID you have to select the COB-ID to remove and click on the "DELETE" button.

You can choose two type of the filter: positive or negative, by clicking on the relative option:

- **Type Positive**": on the CAN monitor you visualize only the COB-ID added;
- \* "Type Negative": on the CAN monitor you visualize all COB-ID except the COB-ID added.

Filter CAN 2.0B/J1939	
<ul> <li>COB-ID Filter</li> <li>345 ADD</li> <li>DELETE</li> <li>Filter Type</li> <li>Type Positive</li> <li>Type Negative</li> </ul>	Mask Filter
DEC	@ HEX
	V OK X Cancel

Figure 7: "Filter" window for Extended Protocol: COB-ID Filter

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**Electronic Devices** 

## FILTER FOR CAN2.0B (EXTENDED): MASK FILTER

By clicking on "Mask Filter" appears the window in Fig. 8.

This window is for setting "Mask Filter". In the first text area you can write the COB-ID to add to the list. The COB-ID must be in binary code.

When you insert the COB-ID you can insert some variables (x), the variable can be 0 or 1.

Example 1:

COB-ID "10xx11"

On the CAN monitor you can visualize the following COB-ID:

10 <u>00</u> 11
10 <u>01</u> 11
10 <u>10</u> 11
101111

You can insert also the COB-ID without variables, in this way:

Example 2:

COB-ID is 110100 On the CAN monitor you can visualize only the COB-ID 110100

You can add or delete the COB-ID by clicking on the relative buttons.

lter CAN 2.0B/J1939	
🖱 COB-ID Filter	Mask Filter
101110xxx011	
Ex. 111xxx1010 ADD DELETE	00000000000000000000000000000000000000
	✓ OK X Cancel

Figure 8: "Filter" window for Extended Protocol: Mask Filter



#### Forms → CAN Sender:

It allows for data to be send in the network. The package is built by its Identifier and its data.

The window allows a list of packages to be created, then are visualized on the grid.

To add a new package, write the values in the text fields and then choose "Edit New". The new package extends the table at the first available row. Otherwise, to modify a row, select it and choose the option "Edit Modify". "Edit del" eliminates the selected row.

From the "Function Menu", choose "Transmit Current Object" to send the package one single time. Choose "Transmit Cycle" to send it cyclically.

The "Debug" function send only the selected package, if the main checkbox on top is checked. For select the package to be sent you have to check the debug on the end of the line.

File F	unction Optio	ns Edit Help				
þ.	TX OTX	🔐 🖉 📽 📽 🚺 💁 🖗 🗆 🛛	ebug	A	) (В)	
	ID(HEX)	DESCRIPTION	DATA ( HEX)	T		
0	0188	Set Parameters	0102030405060708			
NR	ID(HEX)	DESCRIPTION	DATA (HEX)	CYCLE	INC VALUE	DEBUG
1	01FECA00	Alarms	8966			
	0188	Set Parameters	0102030405060708			
2	0100					and and an

Figure 9: "CAN Sender" window



**Flectronic Devices** 

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For eac	ch defin	ed pack	et it	is	possible	to	define	а	cycle	time	that	it	is	used	for	transmit	of	the
rame o	cyclically	<i>'</i> .																

For assign this time you have to select the desired frame and press the button marked with "A". The right window appears (Fig. 10).

In that it is possible to define the "Timer Tics (mS)" that is the cyclic time used for send the packet and the "Start Byte" from 1 to 8.

Once the package to be sent are set-up: select the row dedicated to the package to be send and click on the transmission:

- "Transmit Current Object": to send one time;
- "Transmit Cyclic": to send cyclically, if the Cycle Options are set-up.

Cycle Options	- 45 X	×
Timer Tics (mS)	1000	
Start Byte	11.	
1	10 10 10 H	8
🗸 ок 🛛 🗶	Cancel	Clear

*Figure 10: "Cycle Option" window* 

🖉 Enable incre	ase value	
Ø Byte	🔘 Word	🖱 DWord
Start Byte	Byte 2	·
🗾 Swap byte	s	

Figure 11: "Increase Option" window

For each defined packet it is possible to increase automatically the value of the data. For do that you have to select the desired frame and press the button marked with "B". The right window appears (Fig. 11).

It is possible to enable the increase of the value by checking the field "Enable increase value"; select the amount of bytes used for the increase ("Byte"=1, "Word"=2, "DWord"=4); select the "Start Byte" and also swap, by checking the "Swap bytes" field it is possible to select which of 2 or 4 bytes used for the increase is increased first.



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#### Forms → CANOPEN MONITOR:

It allows for data to be send in the network. The package is built by its Identifier and its data.

It is a window that allows the BUS data to be visualized, interpreting the data as specified by the CANopen.

The columns mean the following:

- "Time": Indicates the time that data is received;
- "Node": Address of the device associated with the package (1-127);
- "Object": Indicates the type of object;
- "Data": Indicates the data Figure 1. related to the package (the contents depend on the type of package).

The tool bar allows for the following actions:

- \* "Export Excel": allows for the exportation of the entire contents of the grid as a text file;
- "CAN Start" and "CAN Stop": activate or stop the writing of the packages in the grid;
- "Clear" eliminates the grid content;
- "Lock Recent Entities" visualizes the last CAN package;
- "Scroll/Overwrite Mode": serves in the choice to write all the packages one after another in the grid or to write all of them in the same row;
- "Filter" opens the window for filter set-up.

😣 CanC	)pen Monitor [ New.	Cfg ]		and a second second	
File Fun	iction View Options	Help			
þ.	🥩 🚳 🔽 🛫		<b>∄</b> ≠	Ready	
NR	TIME	NODE	OBJECT	DATA	
1	00:00:18.529.5	79	Nodeguard		
2	00:00:55.627.1	31	RPDO 3	00 98 04 F6 07 01 00 00	
3	00:01:01.268.4	31	RPDO 3	00 98 04 F6 07 01 00 00	
4	00:01:01.298.6	67	Nodeguard		
5	00:01:03.059.6	67	Nodeguard		
6	00:01:33.580.6	67	Nodeguard		
7		_			

Figure 11: "CANopen Monitor" window



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The filter is an instrument that allows the hardware module to eliminate package that it does not want to visualized in the CANopen Monitor window.

By pressing the "Filter" button from the "CanOpen Monitor" window the "Filter" window appears (Fig. 12):

The set-up window of the filter allows every type of package to be visualized or not based on a specific address.

It is possible to set the filters on "SDO", "PDO", "EMCY", "NMT", "SYNC", "TIME", "NGNG" frames.

To modify the lists, use the keys "<<", ">>", "ALL" and "NONE" to move an Identifier from one list to another, bring them to the right (shown) or the left (hidden).

The CANopen monitor window is valid only for standard protocol.

Node	ID's	Linei	MAI	orne	TIME	Nono		
				>	1 2 2			
				<	3 4 5			
			A	íLL	6 7 8			
			NC	DNE	9 10		÷	

*Figure 12: "Filter" window* 



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#### Forms → Network Manager

The "Network Manager" window (Fig. 13) allows certain operations, designed for the analysis of CANopen devices.

It is possible to scan the network through this window.

In order to identify the presence of module within the network, it is possible to read the objects of a module's Object Dictionary and send the start package to the network.

Set-up the range of addresses for the scan in order to scan the network.

Press the "Scan" button and wait for this scan. The list of the node is filled in with the found nodes. These can be added to the Index and SubIndex.

The button "Add Node", "Add Index", "Add SubIndex", "Modify" and "Delete" allow for the elaboration of the objects list.

To read the value of an object through SDO, select the object from the list and press the button "Read" and the button "Write" to write it.

With the "**EDS**" button it is possible to add the EDS file for the defined node.

The Network manager window is valid only for standard protocol.

Network Manager	
File Setting View Help	
Status	Sync Object Transmit
Node List	Network          Scan       Start       Stop         Index (hex):       Subindex (hex):       01         1412       01       01         Read       Write       Data         hex 0       0       0         dec 0       0       0
Add Node     Add Teday     Add Cubtred	
Modify Delete EDS	

Figure 13: "Network Manager" window



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By pressing the "**EDS**" button from the "Network Manager" window (Fig. 13) the window "Load EDS file" appears (Fig. 14):

By this window is possible to load an EDS file for CANopen. Can also set as part of EDS you would load by check the field:

- Insert Mandatory object;
- Insert optional object;
- Insert manufacturer object.

When the EDS is loaded on the network manager is possible see the various object of CANopen device (fig. 13).

Choose the El	DS file
Select t	he EDS File
🔽 Insert Man	datory Obiect
Insert Opti	onal Object
✓ Insert Man	ufacturer Obiect

Figure 14: "Load EDS File" window

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#### Liectionic Devices

#### Forms → DeviceNet:

With the button "Device NET", you can access the window for the DeviceNET's Master simulation (Fig. 15).

In the window "Device NET Master Emulator", you must write the device's address only, then push the START button in order to visualize the input and output data.

In the left column you can put the data that DeviceNet's Master must write in DeviceNET's net.

In order to change the data's value, it is enough: to select the data, to write its value in the editbox on the list and to push the SEND button.

In the right column you can view all data of the slave. This column can be only read.

Push the STOP button in order to stop communication with the slave.

3 DeviceNet Master			
Current Slave Address	3	START	STOP
From Master to Slave		From Slave to Master	
\$00			
	<u>^</u>		<u>^</u>
	-		-

*Figure 15: "DeviceNet Master" window* 



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# TRACE

In this menu it is possible to start/stop the saving of data into a trace.

CAN-BUSLOAD Start File Trace Stop File Trace	File Function View Forms Ethernet	Trace	Help
Packet er	CAN-BUSLOAD		Start File Trace
			Packecen

The "Start File Trace" open a window (Fig. 16) that allows to define the settings of the trace.

It is possible to create many small files instead checking the field "Enable MultiFiles" and selec "Change file when arrive to ... x 100000 reco records to be saved into a file.

The "Stop File Trace" stops the trace.

a window (Fig. 16) that allows to	C Trace Definition
small files instead of a big one by ultiFiles" and selecting in the field x 100000 records" how many	Trace File Name C:\Program Files (x86)\ADFweb\CAN_Analyzer_SW67216\Trace\
ne trace.	Enable MultiFiles Change file when arrive to 1 💌 x 100000 records
	Select the fields delimiter Space (' ') Semicolon ( ';') Comma (',') User Select
Figure 16: "Trace Definition" window	Save and Start Trace Save Option Only Cancel



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# **BASIC CONCEPTS ABOUT CAN:**

The CAN Bus is a bus that use simple twisted cable as a physical support. It allows for the communications between several devices at the same time on the same network through an automatic control on the part of the hardware driver, package priority. It is used often in the automotive field and by automated industry.

A CAN package is composed of several parts:

- > 11/ 29 bits of the Identifier;
- > up to 8 bytes of data;
- ➢ and other CRC bits.

The COB-ID serves to define the priority of the BUS package (note: the lower the values, the higher is the bus priority).

The COB-ID bits are, in effect, defined as dominant if zero and recessive if one.

The CAN Hardware Driver and the CAN Controller (generally, the microprocessor) if there is an error during the transmission of the package, they suspend the transmission and recuperate the information automatically. This automation permits a high level of security and therefore is used in critical situations.



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## **BASIC CONCEPTS ABOUT CANOPEN:**

The CANopen is a protocol based on CAN that defines a series of set-up rules for package and interactions in which devices can communicate.

Also, CANopen brings to the generation of profiles made to standardize communication with generic modules such as I/O, Encoder, etc.

Above all, CANopen defines diverse typologies of the package, distinguished base on the COB-ID of the CAN Package (see the table below).

COB-ID	
\$00	Network management
\$80	Sync
\$80+devadd	Emcy
\$180+devadd \$200+devadd	txPDO 1 rxPDO 1
\$280+devadd \$300+devadd	txPDO 2 rxPDO 2
\$380+devadd \$400+devadd	txPDO 3 rxPDO 3
\$480+devadd \$500+devadd	txPDO 4 rxPDO 4
\$700+devadd	Nodeguarding
\$600+devadd \$580+devadd	SDO request SDO response

In the table, for every package "devadd" (the device address), there is a value up to \$7F. A CANopen network can have up to 127 devices ("devadd" begins from 1).



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We add a brief description of the meaning of the 8 bytes of data for each type of package.

Network management (Cob ID 0x00) Byte 1 : Identifies the type of command Byte 2 : Identifies the node that receives the command Byte 3-4-5-6-7-8 :Reserved

Sync Message (Cob ID 0x80) Byte 1-2-3-4-5-6-7-8 : Absent Emergency Object (Cob ID 0x80 - 0xFF) Byte 1 : LSB Error Code Byte 2 : MSB Error Code Byte 3 : Error Register Byte 4-5-6-7-8 : Manufacturer Specific Error Field

Timestamp Message (Cob ID 0x100) Byte 1-2-3-4 : time expressed in milliseconds Byte 5-6 : Number of days Byte 7-8 :Reserved

*Transmit Pdo n° 1* Cob ID 0x180 a 0x1FF Byte 1-2-3-4-5-6-7-8 : databytes

Receive Pdo n° 1 (Cob ID 0x200 a 0x27F) Byte 1-2-3-4-5-6-7-8 : databytes SDO Read Response (Cob ID 0x580 a 0x5FF) Byte1:010X.YY11(0x40) YY Indicates how many byte of the 4 data possibilities do not contain data. Х Indicates a bit which has an indifferent value (don't care) Byte 2 : index byte low Byte 3 : index byte hight Byte 4 : subindex Byte 5,6,7,8 : Data bytes SDO Read Request (Cob ID 0x600 a 0x67F) Byte1: 010X.XXXX (0x40) Х Indicates a bit which has an indifferent value (don't care) Byte 2 index byte low Byte 3 index byte hight Byte 4 subindex Byte 5,6,7,8 Reserved SDO Write Response (Cob ID 0x580 a 0x5FF)

Byte 1 : 011X.XXXX (0x60) Indicates a bit which has an indifferent value (don't care) Byte 2 : index byte low Byte 3 : index byte high Byte 4 : subindex Byte 5,6,7,8 : Data bytes



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#### SDO Write Request (Cob ID 0x600 a 0x67F) Byte1 : 001X.YY11 (0x20)

YY

Indicates how many byte of the 4 data possibilities do not contain data.

# Х

Indicates a bit which has an indifferent value (don't care) Byte 2 : byte index byte low Byte 3 : byte index byte hight Byte 4 : subindex Byte 5,6,7,8 : Reserved

SDO Abort (CobID 580+id) CobID 600+id Byte 1 100X.XXX (0x80) Byte 2 index byte low Byte 3 index byte high Byte 4 subindex Byte 5,6 Additional code Byte 7 Error code Byte 8 Error class

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Codici Error class 00 NO ERROR 05 SDO SERVICE 06 SDO ACCESS 08 SDO OTHER Error code : 01 UNSUPP\_ACCESS 02 NONEXIST\_OBJECT 03 INCONS\_PARA 04 ILLEG\_PARA 06 HARDWARE\_FAULT 07 TYPE\_CONFLICT 09 INCONS\_OBJ\_ATTR 0A RES\_NOT\_AVAIL

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# **ABORT CODE DESCRIPTION:**

0503 0000h Toggle bit not alternated.

0504 0000h SDO protocol timed out.

0504 0001h Client/server command specified not valid or unknown.

0504 0002h Invalid block size (block mode only).

0504 0003h Invalid sequence number (block mode only).

0504 0004h CRC error (block mode only).

0504 0005h Out of memory.

0601 0000h Unsupported access to an object.

0601 0001h Attempt to read a write only object.

0601 0002h Attempt to write a read only object.

0602 0000h Object does not exist in the object dictionary.

0604 0041h Object cannot be mapped to the PDO.

0604 0042h The number and length of the objects to be mapped would exceed PDO length.

0604 0043h General parameter incompatibility reason.

0604 0047h General internal incompatibility in the device.

0606 0000h Access failed due to an hardware error.

0607 0010h Data type does not match, length of service parameter does not match.

0607 0012h Data type does not match, length of service parameter too high.

0607 0013h Data type does not match, length of service parameter too low.

0609 0011h Sub-index does not exist.

0609 0030h Value range of parameter exceeded (only for write access).

0609 0031h Value of parameter written too high.

0609 0032h Value of parameter written too low.

0609 0036h Maximum value is less than minimum value.

0800 0000h general error.

0800 0020h Data cannot be transferred or stored to the application.

0800 0021h Data cannot be transferred or stored to the application because of local control.

0800 0022h Data cannot be transferred or stored to the application because of the present device state.

0800 0023h Object dictionary dynamic generation fails or no object dictionary is present (e.g. object dictionary is generated from file and generation fails because of a file error).



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#### **UPDATE NEW FIRMWARE:**

#### ON HD67316-U-D1:

For update the firmware version of HD67316-U-D1 it is necessary to download from this link <u>www.adfweb.com/download/filefold/USB\_SW67316\_Update.zip</u> the files that are necessary for do the operation.

After extracting the archive you have to launch the executable "USB\_SW67316\_Update.exe" file. The window that appears is shown in Fig. 3.

The steps to do are:

- Connect the device to an USB port and press the "Update COMport List" button;
- ✤ Select the COM port where the device is attached (USB port is virtualized like a serial);
- Press the "Update Device" button and select the file "FW\_USB\_SW67316.sim".

When in the log field appears this "Update made with success" sentence the updating is finished correctly.

If doesn't appears, try to repeat the operations.

Select the COM Port:		Version: 1.00
COM11 💌		
🔁 Update COMport List		
Update Device	Initialized	
Protection		*
Protection OK		^
Protection OK Firmware Write in progress		*
Protection OK Firmware Write in progress Read in progress Update made with succes		*
Protection OK Firmware Write in progress Read in progress Update made with succes		*
Protection OK Firmware Write in progress Read in progress Update made with succes		*
Protection OK Firmware Write in progress Read in progress Update made with succes		*
Protection OK Firmware Write in progress Read in progress Update made with succes		*

*Figure 3: HD67316 CAN Analyzer USB Firmware Update* 





#### ON HD67316-E-A1:

For update the firmware version or changing the Ethernet parameters of HD67316-E-A1 it is necessary to download from this link <u>www.adfweb.com/download/filefold/SW67216.zip</u> the files that are necessary for do the operation.

You have to install the SW67216 program, launch it (Fig.4 appears) and follow these instructions:

- Connect the Ethernet cable to the Analyzer and feed it;
- Go to "Function" → "SetPort", select "Ethernet Type (HD67316-E-A1)" and press the "OK" button;
- Go to "Ethernet" → "Configuration" and select or "By Serial" if you don't know the settings of Ethernet parameters; or "By Ethernet" if you know the IP Address and the Port.

ADFweb.com Analyzer_CAN SW67216 [ New.Cfg ]							×
File Function View Forms Ethernet Trace Help CAN-BUSLOAD 0 Packet receive: 0 Packet error controller: 0	Packet discarded filter: 0 Filter Ok	Cr	Tr	Тр	ov Ov	wi	Bo
Hardware not connected Trace Stop							h

Figure 4: Main window of SW67216

Note:

When you install a new version of the software it is better if the first time you do the update of the Firmware in the HD67316-E-A1 device. And also for the first update you have to use the Serial RS232.



The window (Fig. 5) is divided in two sections, one for the data of Ethernet and the other for the actual update.

The parameters that are necessary to set are: "IP Address", "SubNet Mask", "Default Gateway", "Port".

These operations must be made before starting the update:

- Turn off the Device;
- ✤ Connect the Null Modem Cable form your PC to the Gateway;
- ✤ Insert the Boot Jumper (For more info see Fig. 17);
- Turn on the device;
- ✤ Check the BOOT Led. It must blink quickly (see LEDS section).

Then,	after	selecting	the	correct	COM	port y	you	have	to	select	the	oper	ations	s you	want	to	do.	You	car
select	only '	"Firmwar	<b>e</b> ″, o	nly "Pro	oject	" or bo	oth d	of the	т. <sup>`</sup>	Then p	ress	the	<b>"UPD</b>	ATE″	butto	n.			
When	appea	ars Fig. 6	the u	pdate v	vill be	comp	lete	d with	l su	iccess.	At t	his p	oint y	ou ca	n:				

	Ver 1.00
INIT : OK	ver, 1.00
FIRMWARE : OK	
PROJECT : OK	

Figure 6: "Update Device" window

- ✤ Turn off the device;
- Disconnect the Boot jumper;
- Disconnect the RS232 Cable;
- ✤ Turn on the device.

dress 8 , 2 et Mask 5 , 25	5.	66
8 . 2 let Mask 5 . 25	5.	66
et Mask	5	0
5 25	5	0
		U
lit Gateway		
8 2		1
t connected	I to the H	iD67316-E
🗹 Read F	Project w	hen finish
	t connected	8 , 2 , . t connected to the H ↓ ons ☑ Read Firmware ☑ Read Project w

Figure 5: Update "By Serial" window

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#### USE OF "BY ETHERNET"

It is possible to do the Ethernet update only if you know the actual IP Address, Subnet Mask and Port that are programmed into the device. Otherwise you must use the Serial Update.

It is possible to put the device on Boot Mode (through the Jumper2) and update the device. For use this procedure you have to:

- Turn off the Device;
- ✤ Connect the Null Modem Cable form your PC to the Gateway;
- ✤ Insert the Boot Jumper (For more info see Fig. 17);
- Turn on the device;
- ✤ Check the BOOT Led. It must blink quickly (see LEDS section).

The window (Fig. 7) is divided in two sections, one for the data of Ethernet and the other for the actual update.

The parameters that are necessary to set are: "IP Address", "SubNet Mask", "Default Gateway", "Port".

After inserting the actual "**IP Address**" and the actual "**Port**" you have to select the operations you want to do. You can select only "**Firmware**", only "**Project**" or both of them. Then press the "**UPDATE**" button.

When appears Fig. 8 the update will be completed with success. At this point you can:

🛃 FMai	n		×
INIT	: ок		
FIRM	WARE : OK		
PROJ	ECT: OK		

Figure 8: "Update Device" window

- Turn off the device;
- Disconnect the Boot jumper;
- Disconnect the RS232 Cable;
- Turn on the device.

nsert new da	ta of the And	alyzer Ethe	met
Insert Nev	v IP Address		
192	168	. 2	189
Insert Nev	v SubNet Ma	ask	
255	255	255	. 0
Insert Nev	v Default Ga	teway	
192	168	2	. 1
Insert Nev	v Port		
0007			
2007			
2007 Insert IP Addi 192	ess of the H	D67316-E- . 2	A1
nsert IP Addi 192 nsert Port of	ess of the H 168 the HD6731	D67316-E- 2 6-E-A1	A1 . 66
nsert IP Addi 192 nsert Port of 2007	ress of the H 168 the HD6731	D67316-E- 2 6-E-A1	A1 _ 66
nsert IP Add 192 nsert Port of 2007 Jpdate Devic	the HD 6731	D67316-E- 2 6-E-A1	A1 . 66
Insert IP Add 192 Insert Port of 2007 Update Devic	ress of the H 168 the HD6731 ce Options are <b>v</b> F	D67316-E- 2 6-E-A1 Read Firmv	A1 . 66 ware when finish
2007 Insert IP Addi 192 Insert Port of 2007 Jpdate Devic V Firmw	the HD 6731 ce Options are S F	D67316-E- 2 6-E-A1 Read Firmv Read Proje	A1 66 vare when finish ct when finish

Figure 7: Update "By Ethernet" window



## **CONNECTION SCHEME:**

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Figure 16: Connection scheme for HD67316-U-D1

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Figure 17: Connection scheme for HD67316-E-A1



# **POWER SUPPLY:**

The HD67316-U-D1 device don't need an external power supply for work. The alimentation is given by USB port.

The HD67316-E-A1 can be powered at 8...19V AC and 8...35V DC. For more details see the two tables below.

VAC	$\sim$	VDC			
Vmin	Vmax	Vmin	Vmax		
8V	19V	8V	35V		

Consumption at 24V DC:

Device	W/VA
HD67316-E-A1	3.5

# **Caution:** Not reverse the polarity power



HD67316-E-A1

# USB:

The USB connector (Connector1) of HD67316-U-D1 is a Type-B Female. So the cable must be a Type-B Male.



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# **ETHERNET:**

The Ethernet connection must be made using Connector3 of HD67390-E-A1 with at least a Category 5E cable. The maximum length of the cable should not exceed 100m. The cable has to conform to the T568 norms relative to connections in cat.5 up to 100 Mbps. To connect the device to an Hub/Switch is recommended the use of a straight cable, to connect the device to a PC/PLC/other is recommended the use of a cross cable.

# LEDS:

The device HD67316-U-D1 has got three LEDs that are used to give information of the functioning status. The various meanings of the LEDs are described in the table below.

LED	Normal Mode	Boot Mode
1: Device State (Green)	Blink slowly (~2Hz)	Blink quickly
2: Receiving USB (Blue)	Blink slowly: No frame is received Blink quickly: Frame received on USB	Blink quickly
3: Receiving CAN (Blue)	Blink slowly: No frame is received Blink quickly: Frame received on CAN	Blink quickly



The device HD67316-E-A1 has got four LEDs that are used to give information of the functioning status. The various meanings of the LEDs are described in the table below.

LED	Normal Mode	Boot Mode
1: Receiving CAN (Green)	Blink slowly (~2Hz): No frame is received Blink quickly: A frame is received	Blink quickly
2: Transmitting CAN (Green)	Blink slowly (~2Hz)	Blink quickly
3: Link Ethernet (Green)	ON: Ethernet Cable connected OFF: Ethernet Cable disconnected	<b>ON:</b> Ethernet Cable connected <b>OFF:</b> Ethernet Cable disconnected
4: Device State (Green)	Blink slowly (~2Hz)	Blink quickly



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## CAN:



The termination of CAN line, with a  $120\Omega$  resistor, in the HD67390-U-D1 is made by putting the "Dip2" of "Dip-Switch A" at "ON" position. The termination of CAN line, with a  $120\Omega$  resistor, in the HD67390-E-A1 is made by inserting a jumper like in the figure above.

#### Characteristics of the cable:

DC parameter:	Impedance	70 Ohm/m
AC parameters:	Impedance	120 Ohm/m
	Delay	5 ns/m
Length	Baud Rate [bps]	Length MAX [m]
	10 K	5000
	20 K	2500
	50 K	1000
	100 K	650
	125 K	500
	250 K	250
	500 K	100
	800 K	50
	1000 K	25



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# **MECHANICAL DIMENSIONS:**



*INFO: <u>www.adfweb.com</u> Phone* +39.0438.30.91.31



ADF Web Electronic Devices

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## **ORDERING INFORMATIONS:**

The ordering part number is formed by a valid combination of the following:



#### ACCESSORIES:

- Order Code: **AC34001** Rail DIN Power Supply 220/240V AC 50/60Hz 12 V AC
- Order Code: AC34002 Rail DIN Power Supply 110V AC 50/60Hz 12 V AC



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# **OTHER REGULATIONS AND STANDARDS**

#### WEEE INFORMATION

Disposal of old electrical and electronic equipment (as in the European Union and other European countries with separate collection systems).

This symbol on the product or on its packaging indicates that this product may not be treated as household rubbish. Instead, it should be taken to an applicable collection point for the recycling of electrical and electronic equipment. If the product is disposed correctly, you will help prevent potential negative environmental factors and human health, which could otherwise be caused by inappropriate disposal. The recycling of materials will help to conserve natural resources. For more information about recycling this product, please contact your local city office, your household waste disposal service or the shop where you purchased the product.

## **RESTRICTION OF HAZARDOUS SUBSTANCES DIRECTIVE**

The device respects the 2002/95/EC Directive on the restriction of the use of certain hazardous substances in electrical and electronic equipment (commonly referred to as Restriction of Hazardous Substances Directive or RoHS).

# **CE** MARKING

**C** The product conforms with the essential requirements of the applicable EC directives.





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# WARRANTIES AND TECHNICAL SUPPORT:

For fast and easy technical support for your ADFweb.com SRL products, consult our internet support at <u>www.adfweb.com</u>. Otherwise contact us at the address support@adfweb.com

# **RETURN POLICY:**

If while using your product you have any problem and you wish to exchange or repair it, please do the following:

- 1) Obtain a Product Return Number (PRN) from our internet support at <u>www.adfweb.com</u>. Together with the request, you need to provide detailed information about the problem.
- 2) Send the product to the address provided with the PRN, having prepaid the shipping costs (shipment costs billed to us will not be accepted).

If the product is within the warranty of twelve months, it will be repaired or exchanged and returned within three weeks. If the product is no longer under warranty, you will receive a repair estimate.

## **PRODUCTS AND RELATED DOCUMENTS:**

Part	Description	URL
HD67121	Gateway CANopen / Canopen	www.adfweb.com?product=HD67121
HD67001	Gateway CANopen / Modbus – RTU Master	www.adfweb.com?product=HD67001
HD67004 HD67005	Gateway CANopen / Modbus – Ethernet TCP	www.adfweb.com?product=HD67004
HD67134	Gateway CANopen / DeviceNet	www.adfweb.com?product=HD67134
HD67117	CAN bus Repeater	www.adfweb.com?product=HD67117