



Matrics API Programmer's Manual

Version 2.3

Published: September 14, 2004
Part Number: 110009-001

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Section 1. Introduction

Purpose

Matrics provides high performance industry standard UHF RFID products and a broad suite of RFID enabling equipments and solutions. To best serve our customer, and to help to promote the RFID application in the real world, engineers at Matrics have always been striving to provide the best solution with the best technology and methodology available.

This document explains the model, design concepts, and software Application Programming Interfaces (API) offered by Matrics for the purposes of integrating these products into a scalable infrastructure and enabling RFID in an enterprise environment.

Audience

The intended audience of this document is software/network engineers who are interested in evaluating and applying Matrics technology and products in their RFID applications.

It is assumed that the audience is familiar with XML, TCP/IP Socket and/or serial port communication protocol programming and troubleshooting and fundamental concepts of RFID. No further discussion and information is provided in this document regarding basic concepts and techniques in these areas.

Scope

This document describes in detail the software communication interfaces, protocol definitions, and formats for documents exchanged with these products:

1. AR-400 Series RFID Reader
2. SR-400 Series RFID Reader
3. Matrics Visibility Manager (MVM)
4. PR-100 Series RFID Reader Module
5. MR-100 Series RFID Reader Module
6. RR Series (Rugged) RFID Readers (FCC Part 90)

Matrics has strived to have a uniform API across these product lines and unless otherwise noted, information would apply to all of the available platforms. Specific limitations (e.g. if commands or sections apply to subset of above products) are noted where applicable.

For RF characteristics, RF air protocols, hardware interface and other product specifications, please refer to the product's data sheet or user manual.

Acronyms and Abbreviations

The following acronyms and abbreviations are used in this document:

| ACRONYM | DEFINITION |
|---------|-----------------------------------|
| API | Application Programming Interface |
| bin | value in binary notation |
| CRC | Cyclic Redundancy Check |
| DTD | Document Type Definition |
| hex | value in hexadecimal notation |
| IT | Information Technology |
| LSbit | Least Significant bit |
| LSByte | Least Significant Byte |
| MIB | Management Information Base |
| MSbit | Most Significant bit |
| MSByte | Most Significant Byte |
| RFID | Radio Frequency Identification |
| SOF | Start Of Frame |
| TBD | To Be Determined |
| URL | Uniform Resource Locator |
| XML | Extensible Markup Language |

References

For additional information, refer to the following documentation:

- *SR 400 Reader User's Manual* (PN: 110001-001)
- *AR 400 Reader User's Manual* (PN: 110003-001)
- *Matrics Visibility Manager (MVM) User's Manual* (PN: 110005-001)

Disclaimer

While Matrics has committed its best efforts to providing accurate information and timely updates to this document, we assume no responsibility for any inaccuracies that may be contained herein, and we reserve the right to make changes to this document without notice.

Section 2. Overview

This section provides a conceptual overview of the standard methodology and tools recommended for enabling communication of tag data between Matrics equipments and back-end enterprise system (referred to as a “Host”).

Physical Interfaces

At physical layer, there are two kinds of interfaces for command and data communication:

- RS485 serial port
- Ethernet

Different equipment supports different set of physical interfaces:

| | SR 400 | AR 400 | MVM |
|-----------------|---------------|---------------|------------|
| RS485 | Support | Support | |
| Ethernet | | Support | Support |

Logical Software Interfaces

On top of RS485 and TCP/IP socket interfaces, Matrics provides a byte stream communication protocol (referred to as a “byte stream protocol”).

Additionally, an HTTP over TCP/IP interface is available to provide a Web-based administration console (using HTML), and well as a service interface allowing for machine to machine interaction (using XML). In both cases, the actions are initiated in the form of an HTTP request.

The default port for HTTP requests is port 80, and the default port for the socket interface is port 3000.

RFID Application Scenarios

1. Reader Network Environment

A collection of RFID readers compose a logical network. Readers are not only responsible for collecting tag data, but monitoring the RFID network devices.

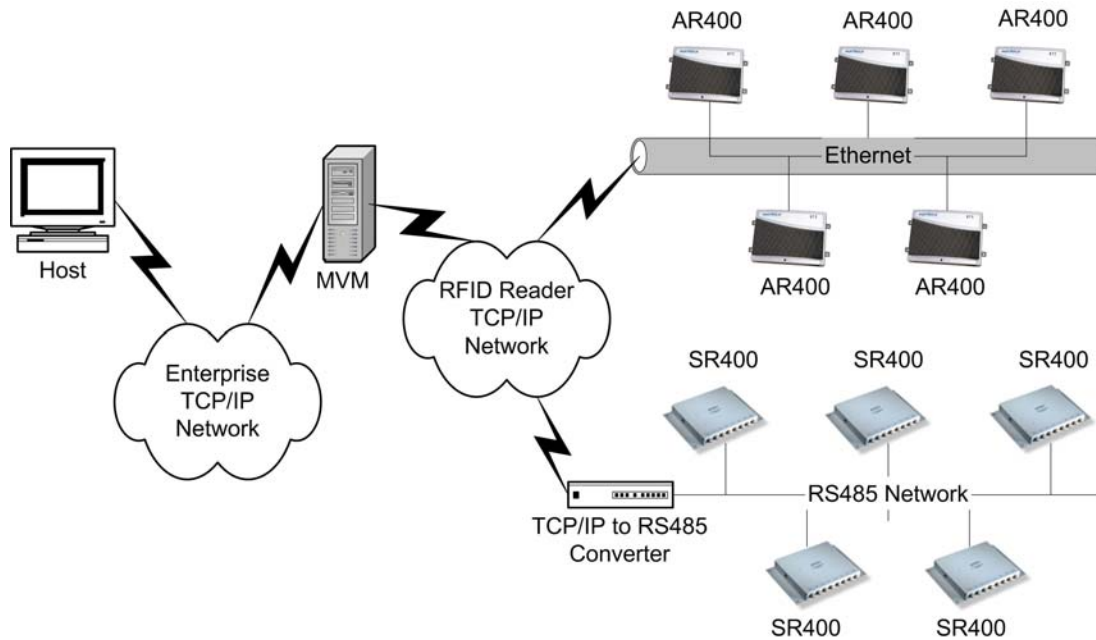


Figure 1 Reader Network with Matrics Visibility Manager

The nature of a Reader Network implies some issues:

a. Data consolidation

A large number of RFID readers can generate significant amount of data. When readers are acting as passive units, they need to be driven by Host and simply report whatever is currently visible within its read range in one or several read cycles. The Host needs to manage to coordinate all the readers and collect, process, consolidate, and reconcile the data and then distill meaningful information out of them. When the number of readers increase, so does the effort to achieve and maintain optimal or even adequate performance, reliability and scalability.

b. Network management and monitoring.

As RFID are used to facilitate critical business processes, it is important to be able to promptly detect and report any errors to maintain the integrity and stability of the RFID network.

c. Readers' configuration and maintenance

RFID readers for different locations and applications may have different personalities. To achieve the effectiveness and efficiency for RFID devices' maintenance, their configuration should be carefully tracked and maintained. Appropriate methods are also needed to accommodate automation of these procedures and processes.

To overcome these problems and help expedite the development of Host applications, Matrics designed and implemented the Matrics Visibility Manager, as known as the MVM. It acts as a central control unit bearing the duty of configuring and managing readers, collecting and consolidating tag data, and acts as a bridge between the RFID reader network and the enterprise

network to logically/physically isolate two network segments to reduce the potential impact to enterprise network. The MVM also acts as the only software interface access point for the enterprise Host application, so that the host does not need to worry about the low-level interaction with the reader devices.

The MVM is architected as a plug-and-play network appliance with minimum maintenance requirement. It talks to readers and provides a simple HTTP/ XML interface for host side applications.

Some of the MVM features, such as consolidation of tag data and event generation, HTTP and XML data communication interfaces are also available on the AR 400 platform, so that it can work in autonomous mode and greatly reduce the data traffic to the Host application. The mechanism and interface for configuration and command/data communication are also kept the same for an AR 400 and the MVM so the Host application can easily scale up and down with minimum modification.

The MVM is optional. Users could choose to interact with RFID readers directly. And since an AR 400 also provides the similar interface over HTTP and XML and is capable to work in self polling mode (autonomous mode), the Host side can use the same programming model as working with the MVM. In this case, each AR 400 is analogous to one mini-MVM controlling a single reader.

2. Real-time Application

Sometimes a real-time response is important or the Host application may want to have direct control of the read cycle and/or change some parameters on the fly. In these kinds of situation, the byte stream protocol over either RS485 or Ethernet TCP socket communication would be a better choice.

Section 3. XML over HTTP Host Interface

This section provides a conceptual overview of the standard methodology and model applied in the XML over HTTP messaging mechanism. The goal of this mechanism is to provide an easy and flexible integration programming interface, to hide complexity and hardware variations, and to make the Host system less sensitive to changes imposed by firmware changes.

This interface is available on an MVM and an AR 400 reader. In the following discussion in this section, we will use generic notion of device to refer to either the MVM or an AR 400 reader.

Typically, when this mode is utilized, one or more of the read points are configured using an autonomous polling method, such as polled or periodic. As such, the collected data can be retrieved by the host system independent of the low-level operations of the reader(s).

By default, the HTTP port on MVM and AR 400 is 80. On AR 400, this port value can be changed through Web-based and serial administration console.

RFID Tag Information

The knowledge of an RFID tag includes: RFID Tag ID value, optional user assignable ID and threshold rule, current RFID tag state, last RFID tag state transition (tag event), time stamp and read point list. A Matrics device can acquire the knowledge of a RFID tag through two methods. The conventional one is to read through a read point (antenna). The second one is through the import tag list.

RFID Tag ID

Each RFID tag has a unique ID, which could be encoded with different standards. In the HTTP/ XML based interface protocol, Matrics provides two different presentation formats for the same ID data:

Matrics Hexadecimal Raw Format

This format presents the raw RFID tag value in a hex decimal string. This string is a strict presentation of the original RFID tag value without any bits being omitted. For example, a 64 bit tag always has a length of 16 hexadecimal characters, and a 96 bit tag always has a length of 24 hexadecimal characters, no matter if leading or trailing bits are actually zeros.

This strict length requirement is mandatory for both the output tag list as in a query result, and the input tag list as used in import tag list or purge tag list.

To get the query result in this format, the optional parameter “&raw=1” must be added to the query string. For example:

```
http://192.168.0.1/cgi-bin/dataProxy?oper=queryTags&raw=1
```

```
http://192.168.0.1/cgi-bin/dataProxy?oper=queryEvents&raw=1
```

Matrics Type-Id Fields Format

Rather than use the ‘native’ encoding scheme, Matrics also provides one presentation format that is able to handle Matrics and other EPC tag encoding schemes in one simple format.

There are two pieces of information that make a tag unique in the world: “ID” and “type.” ID can contain up to 64 bits of information. Type is also a 64-bit value; however, the amount of information contained within the 64 bits varies by tag type (Matrics or EPC.). Both fields are represented in hex, minimizing the data transfer.

This is the default presentation format in the result tag list of HTTP query commands.

Optional User Assignable ID

As an optional feature, in addition to the native tag ID value, you may choose to use a more meaningful user defined ID to identify a tag or the item a tag represents. This user defined ID is called UID (uid). It is a plain text string with a limit length of 32 characters. For example: “Small Shoe Box”, “SKU001”, “Part ABC”, etc.

Another advantage of the user defined ID is that it is not necessary a one-to-one relationship between a native tag ID and a user defined ID, it may be a one-to-many relationship. In other words, for each UID, there could be multiple native tag IDs associated with it.

For example, if you have ten computer monitors, each with a unique RFID, you can assign one UID as “Big Brand Monitor” to all of these ten units. At the same time, you can specify a threshold value and rule for this specific UID. So whenever the number of the items with this same UID falling below or rising above this threshold value, a threshold tag event would be generated for this UID. This ensures that you are notified when changes in the amount of assets occur, instead of, or in addition to, when assets move.

The only way to specify a UID and its rule is through the import tag list, as optional attributes to the <Tag/> XML tag. Because of the running state, the UID and its threshold rule for a group of RFID tags can be specified only once at the first record, and all others are implied.

RFID Tag State and State Transition

As a tag is moving in and out of reading range, a RFID tag state changes accordingly. Figure 4 shows different RFID states in a Matrics device and the state transitions.

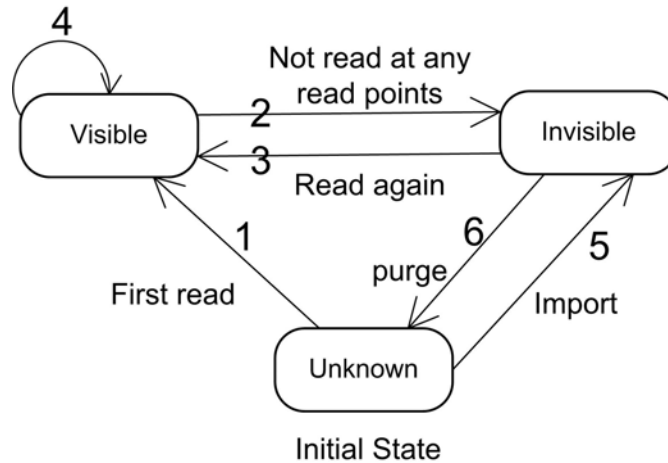


Figure 2 RFID Tag State Transition

Transition 1: After being read for the first time, the tag changes to visible state and stays there as long as it still can be read through any of the subordinate read points. This transition could generate New Tag Event. If New Tag Event is disabled, then this event could be promoted to more general Visibility Change Event.

Transition 2: After being read before, when it can not be read by any of the read points anymore, it changes to invisible state. This transition could generate Tag Invisible Event. If Tag Invisible Event is disabled, then this event could be promoted to more general Visibility Change Event.

Transition 3: If an already known, but not currently visible tag is read by any read points again, its state changes to visible state again. This transition could generate Visibility Change Event. Because the tag has already been known by the system, the New Tag Event is not applicable here.

Transition 4: A currently visible tag can be read by a different set of read points in different read cycle. Its state remains as visible. But this change could generate Visibility Change Event.

Transition 5: sometimes, tag information can be pushed into a Matrics device through an import tag list. This essentially injects the knowledge of RFID tags into the device before they are read for this first time. The tags are known to the system after that, but they are still not visible to any read points yet. This transition would not generate any tag events.

Transition 6: When a tag is removed from either by a purge tag list or through reboot cycle, its information disappears from the device. It will start its state transition just as if it starts from the initial state.

Time Stamp

The RFID tag state transition could generate tag events. And each tag has a time stamp associated with it. This time stamp records the time of the last state transition that could generate a tag event. Non event generating state transitions do not update the time stamp.

Read Point List

Read Point List is a comma delimited list of Read Point Ids indicating which read point(s) the RFID tag is currently visible at. Read Point Id is the internal automatically generated unique identifier for a read point (antenna). The Read Point Map tells the association of the Read Point Id to the read point's name and other attributes.

Events

A Matrics device generates several types of events: **Visibility** and **Threshold** Events that report tag activity; and **Network Status** and **Exception** Events that report device/system activity.

Visibility Events

There are three types of Visibility Events that are generated when changes in tag visibility occur:

- **New Tag Event**—A New Tag Event is a special case event that is generated when a new tag appears for the first time. A new tag is one that has never been seen before, and has not previously been known to the Reader. You can then commission the tag (or associate a User ID and a threshold rule to the tag.)

This event should be processed in a timely fashion to get meaningful results. The default Notify option is set to Immediate for this event. If you don't want to be notified when this type of event occurs, set the Notify option to Never, in which case the event is promoted to a generic Visibility Changed Event.

- **Tag Not Visible Event**—A Tag Not Visible Event is a special case event that is generated when a visible tag disappears from all Read Points. For example, if a tagged item is removed from a shelf and is out of RF range (not being seen by any Read Point), then a Tag Not Visible Event would apply. The Event reports where the tag was located when last visible to the system.

In the normal operation, there may be cases that a tag has transient periods when it can not be read reliably at all time in the system. To smooth out temporary conditions, the Notify option for this event could be set to Moderated. The system then would generate an event only when the tag has not been read for a period of time longer than the specified moderate timeout. (The system still knows about the tag, but it is not visible to any Read Point.) If you don't want to be notified when this type of event occurs, set the Notify option to Never, in which case the event is promoted to a generic Visibility Changed Event.

- **Visibility Changed Event**—A Visibility Changed Event is a generic event (not as specific as a New Tag or Tag Not Visible Event) generated any time that the visibility of a tag changes. The visibility change may be due to the change of the set, or the number of Read Points that the RFID tag is visible at. For example, if a tagged item moves from a shelf on aisle 2 to another shelf on aisle 4 (visibility changes from one Read Point to another), then a Visibility Changed Event would apply.

Note: If the Tag Not Visible Event is enabled, a disappeared tag (previously visible, but currently not visible to any read points any more) will generate the more specific Tag Not Visible Event

instead. Likewise, a New Tag Event will be generated for the first visibility change when applicable.

This event should be processed in a timely fashion to get meaningful results. The default Notify option is set to Immediate.

Threshold Events

A Threshold Event is generated when the number of visible tags satisfies the threshold rule for this group of tags. By default, this event's notify option is set to Never.

To activate the threshold condition, user defined IDs and relevant threshold rules must be specified through an import tag list. The notify option also needs to be enabled to generate event notification for this event.

In the normal operation, a tag may have transient periods when it is changing visibility in the system, set the notify option to Moderated to smooth out temporary conditions, and generate an event only when the tag is not experiencing a temporary moment of invisibility.

Network Status Events

Network Status Events alert you the status change of device's managed resources. For example, if a problem is detected, an event is generated by the device and sent without a server request.

If you want to receive Network Status Event notifications, you must subscribe to them by setting the SNMP configuration on the Event Notifications page. If the SNMP host is not set (or is not valid), no Network Status Events will be sent.

Network Status Events are divided into two categories, 'device' and 'program.' A Device Event notes the change in a device's status. A Device Event is further divided into two categories, 'user' and 'system.' Both categories have an addition specification as to whether the status change is being reported for itself or in association with a 'parent' device.

For example, if the 'user' disabled a Reader, several events would be generated. The Reader would get a 'user/disable' status notification. The Read Point(s) below the Reader would get a 'user/disable/parent' notification. If the system detected a problem with the Reader, it would automatically disable the device, and the matching events would be generated. These classifications allow you to not only see the overall effect on the Reader Network, but also allow the likely offending component to be identified. When the fault is fixed, you can 'enable' the device. Any device below it that was 'parent disabled' is automatically brought back online.

Exception Events

Exception Events provide the same type of information available via SNMP, except via XML. An Exception Event gives you information when a device goes off-line, polling is turned off, etc.. You may choose this option if you don't support SNMP, but still want to receive feedback if the device/program changes state. XML is enabled by setting the Notify option for Exception Events to 'Immediate' in the Notify column on the Event Notifications page.

Event Notification Preferences

If you want to be notified when particular events occur, you can choose (subscribe to) the events via the Notifications screen. You may also choose whether or not you want to receive any event notifications at all. If the Host Notification Link is not set (or is not valid), no notifications will be sent. If you want to receive event notifications, simply supply a valid link. The system will test the validity by using the Test option.

To specify the event notifications that you want to receive, select the appropriate Notify option of each event type:

- **Never**—The system never generates notifications for this event type.
- **Immediate**—The system generates notifications for this event type as soon as they are detected, assuming they are not ‘filtered’ out.
- **Moderated**—The system retests this condition every minute up to the timeout value. If the condition still exists and an intervening event has not happened since, the system generates notifications for this event type, assuming they are not ‘filtered’ out.

The type of event filters available include:

- **None**—No filter. Allows all events to pass through.
- **Zone Inclusive**—Only allow events that occur in a specific Read Point Zone to pass through.
- **Class Inclusive**—Only allow events that occur in a specific Read Point Class to pass through.
- **Read Point Inclusive**—Only allow events that occur in a specific Read Point to pass through.
- **Zone Exclusive**—Only allow events that do NOT occur in a specific Read Point Zone to pass through.
- **Class Exclusive**—Only allow events that do NOT occur in a specific Read Point Class to pass through.
- **Read Point Exclusive**—Only allow events that do NOT occur in a specific Read Point to pass through.

If the SNMP host is not set (or is not valid), no Network Status Events will be sent. You also have the option of selecting either version 1 or version 2c SNMP messages.

Communication Models

On top of HTTP protocol, there are several approaches for getting information from a device:

Query Model

A pure query model allows a device to run as an independent, isolated system in passive mode, and does not initiate communication to the Host. The Host system can initiate HTTP queries at any time to the device to gather runtime information. From HTTP protocol’s perspective, the Host system is only a client, and the device is only a server.

Assuming the device’s IP address is 192.168.0.100, the following is an example of what the URL might look like:

```
http://192.168.0.100/cgi-bin/dataProxy?oper=queryTags
```


The result of a 'queryTags' operation is an XML tag list document. As described in the definition of tag list, there could be a ReadPointMap in the response. For efficiency, the host system should only request the ReadPointMap once, when it first comes online. Adding '&map=1' to the URL forces the map to be sent with the query. Without this option, the map is only sent when it has been changed. Thus, for subsequent queries, it is not necessary or efficient to explicitly request the map every time.

Two kinds of information can be reported by a Matrics device: a snapshot view of the world and a delta view of accumulated changes.

The snapshot view can be acquired by the "queryTags" command. By default, this is a snapshot of all the tags currently visible by any subordinate read points. Any tags that are not visible by any read points at the moment of the query are not included in the report. So this is a partial view of the whole world.

The complete snapshot view can also be got by the "queryTags" command, but must be with the optional parameter "&invis=1" in the query string. This returns a tag list including all the tags this device has ever had knowledge of, except those that have been purged. All visible tags have a non-empty Read Point List; this may be implied by the running state.

The delta view is a tag event list as the result of the "queryEvents" command. It accumulates all the events and associated tag information since last time this command has been run. It tells all the delta changes, instead of snapshot since then. The Host system can apply these changes to its original snapshot to get an updated view.

Subscribe/Notify Model

This model allows a device to notify the Host system as event occurs, in the form of an HTTP query request. In this case, the Host system is an HTTP server, and the Matrics device is an HTTP client. Upon notification, the Host should come back to query the device. The result is an event list XML document that contains all the 'events' that have occurred since last event query. In this case, the Host is an HTTP client, and the device is an HTTP server.

The Host system can also specify (subscribe) for the type of event, and the conditions under which it wants to receive notification. This allows the Host to see changes as they happen, and only the 'changes' are communicated.

When the subscribe/Notify model is used (or a hybrid), communication is typically initiated by the Reader. In order to use this model, you must supply a host IP address (and port, if it is not the default 80) where the host system can be contacted (via HTTP query) and notified of pending events. There are two options you must support: *test* and *notify*. The following are examples of what the host URL might look like:

```
http://192.168.0.127/?oper=test  
http://192.168.0.127/?oper=notify
```

The Reader uses the 'test' option to validate the link to the host system. The host system should reply with a simple XML acknowledgement described in the XML section of this document.

The Reader uses the 'notify' option to notify the host system that one or more events are available for query (i.e., something has changed since the last query.) The host system should reply with a simple

XML acknowledgement described in the XML section of this document. Additionally, the host system can send Tag List data (Import Tag List or Purge List) as part of the reply. A Tag List reply is purely optional.

The user can 'import' tags, optionally along with the uid and rule, into the system, at any time, as part of a notify reply. Note that tags that are 'imported' prior to their first physical visibility (being seen by the Reader at a Read Point) will never report a New Tag Event, but will simply report a Visibility Changed Event when the physical tag appears at a Read Point.

After the host system receives the notification and acknowledges it, it should follow up with a 'queryEvents.' The following is an example of what the URL might look like:

```
http://192.168.0.100/cgi-bin/dataProxy?oper=queryEvents&map=1
```

The result of a 'queryEvents' operation is an XML document containing information about the events that have occurred since the last query. This allows you to keep a running view of the changes in asset visibility.

Note: For efficiency, the ReadPointMap (the 'map' which associates Read Point IDs, Read Point Names, Class and Zone information for your Read Point locations) should only be requested once, when the host system first comes online. Adding 'map=1' to the URL forces the map to be sent with the query. When it is not added, the map is only sent when it has possibly changed. Thus, for subsequent queries, it is not necessary or efficient to request the map each time.

Hybrid Model

The typical (and most efficient) approach is a hybrid of the two. For example, you query the 'tags' of the system to get a snapshot of what is visible, and then subsequently wait for notifications. Upon notification, you can query the 'events' of the system, which is essentially delta information, and then update your view by applying the delta to the original one.

HTTP Protocol Support

HTTP URL and Query String

The "http" scheme is used to locate network resources via the HTTP protocol. This is the scheme-specific syntax and semantics for http URLs:

```
http_URL = "http:" "/" host [ ":" port ] [abs_path [ "?" query ] ]
```

If the port is empty or not given, port 80 is assumed. The semantics are that the identified resource is located at the server listening for TCP connections on that port of that host, and the Request-URI for the resource is abs_path. If the abs_path is not present in the URL, a "/" is placed as the Request-URI in the HTTP request start-line.

The URL scheme allows you to include a query string that is to be passed to the designated URL. This is indicated by placing a question mark at the end of the URL, followed by the desired query string. For example:

```
http://www.host.com/cgi-bin/proxyProgram?query_string
```

And the query_string could be:

```
name=value&name=value&name=value
```

The query string consists of multiple name/value parameter pairs with an "&" in between each pair. The designated URL, usually a CGI or proxy program, then could parse and interpret this query string and take appropriate actions.

Web browsers, such as MS Internet Explorer, Netscape Navigator, Mozilla, etc. are typical HTTP clients. http_URL is used as internet address, and displayed in the address bar in these programs. Web browsers parse the http_URL, convert it into a HTTP GET request message and send to the server, then receive and handle (display) the response. Basically, a web browser can readily be used as a test tool to send simple query to an HTTP server, simply by attaching the query string at the end of the internet address.

Matrics HTTP Service Interfaces

Matrics platform provides four logical service interfaces in the form of HTTP Request-URI, and serve as command proxies.

- /cgi-bin/loginProxy
This serves as the user login command proxy for the Web-based administration console
- /cgi-bin/coreProxy
This serves as the command proxy for the back-end core server
- /cgi-bin/dataProxy
This serves as the main data communication interface interacting with the Host

Commands and their respective parameters are passed to these interfaces as a query string in the http URL. we call these as HTTP query commands in the context of this discussion. The general format of these commands looks like:

```
http://192.168.0.1/cgi-bin/dataProxy?oper=<command>&param1=val1&param2=val2...
```

In the query string, a special name("oper")/value pair is used to tell the name of the command. Parameters for this specific command are defined by the following name/value pairs.

You can always try these command samples via a Web browser. Simply copy the URL into a Web browser's address bar, and replace the IP address as appropriate.

Matrics HTTP Query Commands

Following provides the definition of HTTP query commands and their parameters:

login

This command is only accepted by the loginProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|--------|---------|--|
| name | string | N/A | The user name used to login the Web-based administration console |
| pswd | string | N/A | The password for this user name |

For example:

```
http://192.168.0.1/cgi-bin/loginProxy?oper=login&name=user&pswd=password
```

The response for this command is a HTML <META> element with a redirection.

1. If the command succeeds, the response is:

```
<META HTTP-EQUIV="Refresh" CONTENT="0; URL=/cgi-bin/mainPage">
```

2. If either the user name or the password is wrong, the response is:

```
<META HTTP-EQUIV="Refresh" CONTENT="0; URL=/cgi-bin/loginPage?err=17">
```

3. If there is already another user currently logged in, the response is:

```
<META HTTP-EQUIV="Refresh" CONTENT="0; URL=/cgi-bin/loginPage?err=62">
```

4. If the password for this user has not been changed from the reset password, the response is:

```
<META HTTP-EQUIV="Refresh" CONTENT="0; URL=/cgi-bin/passwordPage?user=user&reset=1">
```

queryEvents

This command is only accepted by the dataProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|------|---------|---|
| map | int | 0 | =1, send read point map in the query result |
| raw | int | 0 | =1, send tag data in raw format |

For example:

```
http://192.168.0.1/cgi-bin/dataProxy?oper=queryEvents
```

This returns a list of current tag events.

queryTags

This command is only accepted by the dataProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|------|---------|---------|
|----------------|------|---------|---------|

| | | | |
|------------|-----|---|--|
| map | int | 0 | =1, send read point map in the query result |
| invis | int | 0 | =1, send currently invisible tags too |
| raw | int | 0 | =1, send tag data in raw format |
| uidOnly | int | 0 | =1, send only those tags which have user ids |
| since | hex | 0 | >0, send only tags whose visibility has been changed since the time specified. The time is the number of seconds since |
| showLastRP | int | 0 | =1, show the last read point this tag has been seen |
| ascTime | int | 0 | =1, show text timestamp in ANSI C's asctime() format ("Thu Jan 01 00:12:40 1970") |
| sendRule | int | 0 | =1, send the rule associated with one user id |

For example:

`http://192.168.0.1/cgi-bin/dataProxy?oper=queryTags`

The response for the example is a list of currently visible tags.

startPolling

This command is only accepted by the coreProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|------|---------|---|
| onOff | int | 0 | =1, enable polling =0, disable polling |

For example:

`http://192.168.0.1/cgi-bin/coreProxy?oper=startPolling&onOff=1`

This temporarily starts autonomous polling. This command only turns on/off polling temporarily. The reader will restore its operation as defined in its configuration after reboot. To make sure the reader can automatically start polling after reboot, polling needs to be enabled and the configuration needs to be committed (saved).

getVersion

This command is only accepted by the coreProxy. It does not have any parameters.

For example:

`http://192.168.0.1/cgi-bin/coreProxy?oper=getVersion`

The response is a plain text string as "3.4.5" for the current software/firmware version.

setDateTime

This command is only accepted by the coreProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|--------|---------|---|
| input | string | N/A | In the form of "MMDDHHmmCCYY.SS", where MM is the month, DD is the day, HH is the hour, mm is the minute, CC is the century, YY is the year, and SS is the seconds. |

The following command synchronizes the device's clock to 12/04/2002 16:17:10:

`http://192.168.0.100/cgi-bin/dataProxy?oper=setDateTime&input=120416172002.10`

If the command is properly formatted and accepted, the reply may look like:

```
<Metrics>
<Error code='0' msg='Wed Dec 4 16:17:10 EST 2002' />
</Metrics>
```

If not properly formatted or accepted, the error code and message will reflect the nature of the problem.

processTagList

This command is only accepted by the dataProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|--------|-----------|-------------------------|
| url | string | Host link | The URL of the tag list |

The following command can be used to initiate an RFID tag list import or purge (even when not using the event model):

```
http://192.168.0.100/cgi-bin/dataProxy?oper=processTagList&url=http://129.168.0.101/
hostTagList.xml
```

The URL argument is optional. If not present, the command will attempt to use the host notification link. If successful, the reply may look like:

```
<Metrics>
<Error code='3008' msg='Operation was successful' />
</Metrics>
```

This means that the system has successfully enqueued an operation to access the host (system pointed at by the URL) to process a tag list for import and/or purge list. When contacting the host system, we will include the following on the URL:

?oper=process

The host system should return the XML described in the *XML File Descriptions* section of this manual.

If not properly formatted or accepted, the error code and message will reflect the nature of the problem.

setLightIndicator

This is command is only accepted by the dataProxy.

| Parameter Name | Type | Default | Meaning |
|----------------|--------|---------|---|
| rred | string | N/A | Right Red Light. “on”/“off” turns on/off the red light on the right side |
| rrto | int | 0 | Right Red Light Timeout, a 16 bit integer that represents a decimal number in 100s of milliseconds for which the light will be on. If parameter is omitted or set to zero, light is turned on indefinitely. |
| rgreen | string | N/A | Right Green Light. “on”/“off” turns on/off the green light on the right side |

| | | | |
|--------|--------|-----|--|
| rgto | int | 0 | Right Green Light Timeout, same definition as the “rrto”above |
| lred | string | N/A | Left Red Light. “on”/“off” turns on/off the red light on the left side |
| lrto | int | 0 | Left Red Light Timeout, same definition as the “rrto”above |
| lgreen | string | N/A | Left Green Light. “on”/“off” turns on/off the green light on the left side |
| lgto | int | 0 | Left Green Light Timeout, same definition as the “rrto”above |

For example:

To turn the right red light on indefinitely and the left green light on for 1 second

```
http://192.168.0.100/cgi-bin/dataProxy?oper=setLightIndicator&rred=on&rrto=0&lgreen=on&lgto=10
```

The same can be accomplished with (no rrto needed):

```
http:// 192.168.0.100/cgi-bin/dataProxy?oper=setLightIndicator&rred=on&lgreen=on&lgto=10
```

To turn off the right red light:

```
http:// 192.168.0.100/cgi-bin/dataProxy?oper=setLightIndicator&rred=off
```

Event notification

These are HTTP query commands sent by device to the Host as event notification.

1. test

For example:

```
http://192.168.0.127/?oper=test
```

This is the test command sent by the device to verify the host notification link specified is alive and working. This command is used whenever the host notification link is changed. The Host should respond with a minimum host acknowledgement to honor this test. Otherwise, the host notification link will not be accepted.

2. notify

For example:

```
http://192.168.0.127/?oper=notify
```

This is the real event notification command the Host will receive at runtime. As for the notify command, the Host needs to respond with a minimum host acknowledgement. The host can also embed other information such as import tag list in the acknowledgement, so it does not need to initiate another separate transaction to pass this information through.

HTTP Support on the Host Side

The HTTP technology of choice is up to the user discretion. It can range from a full feature server to a simple HTTP listener.

XML Document Descriptions

This section describes the definition of the fields in the XML documents. All items are mandatory unless otherwise stated. Any extra field that may appear now or in the future should be ignored.

All well-formed Matrics XML documents have the following basic structure:

```

1 <?xml version=' 1.0' ?>
2 <Matrics> <!-- start-tag of Matrics XML document -->
3 <!-- other document elements -->
4 </Matrics> <!-- end-tag of Matrics XML document -->

```

The start tag <Matrics> and end tag </Matrics> must be present to form the root element of a Matrics XML document. All following element tags must reside inside the content of this element.

All comments in the XML document samples are for explanatory purpose in this document only. They are not present in the real runtime communication documents.

Running State

Information for certain attribute fields in the XML files is communicated in ‘running state.’ This is a method whereby an attribute only needs to be sent when it is different from the preceding value of that field. The result is a significant reduction in file size and network bandwidth use.

Example:

```

1 <?xml version=' 1.0' ?>
2 <Matrics> <!-- start-tag of Matrics XML document -->
3 <TagList> <!-- start-tag of a tag list -->
4 <Tag raw=' 8900640246000000' uid=' SKU789' />
5 <Tag raw=' 8900640246000001' />
6 <Tag raw=' 8900640246000002' uid=' ' />
7 <Tag raw=' 8900640246000003' />
8 <Tag raw=' 8900640246000004' uid=' SKU980' />
9 <Tag raw=' 8900640246000005' />
10 </tagList> <!-- end-tag of a tag list -->
11 </Matrics> <!-- end-tag of Matrics XML document -->

```

The following table illustrates the information carried by the above example:

| No. | RFID Tag Value | Uid | Comment |
|-----|------------------|--------|--|
| 1 | 8900640246000000 | SKU789 | uid is explicitly specified as SKU789 |
| 2 | 8900640246000001 | SKU789 | uid is implied as SKU789 because of running state |
| 3 | 8900640246000002 | | No uid because it is explicitly cleared |
| 4 | 8900640246000003 | | No uid because of running state |
| 5 | 8900640246000004 | SKU980 | uid is explicitly specified as a new value of SKU980 |
| 6 | 8900640246000005 | SKU980 | uid is implied as SKU980 because of running state |

Minimal Host Acknowledgement

<HostAck/> is an empty-element tag denoting Host’s acknowledgement of test or notification. This tag is mandatory if there is no tag list embedded in the acknowledgement response, is optional if a tag list is present.

For example, this is the minimum Host acknowledgement:

```

1 <?xml version=' 1.0' ?>
2 <Matrics> <!-- start-tag of Matrics XML document -->
3 <HostAck /> <!-- minimum Host acknowledgement tag -->
4 </Matrics> <!-- end-tag of Matrics XML document -->

```

RFID Tag List

A tag list is a logical container holding a list of RFID tags. Each RFID tag is uniquely identified by its tag value, and may have some other attributes associated with it. A tag list could be the result in the response of a query for tags command, or as a source for the Host to inject the knowledge for some tags into a

device. The Host can use a purge list to remove the knowledge of tags from a device. A tag list as an import list has different semantics than a tag list as the result of a query command, hence they have different set of attributes for the <tag/> XML tag.

<TagList> is start XML tag for a tag list.

</TagList> is end XML tag for a tag list.

<PurgeList> is start XML tag for a purge list.

</PurgeList> is end XML tag for a purge list.

<Tag/> is empty-element tag for a single tag entry in the content of a tag list or purge list. It has following attributes when it is used in an import tag list:

| Attribute name | Type | Default | Meaning | | | | | | | | | |
|----------------|--------------|------------------------------|---|-----------|---------|---------|--------------|-----------|------------------------------|----|--------------|--------|
| id | Hex | N/A | The id field of the RFID tag value | | | | | | | | | |
| type | Hex | Running state | The type field of the RFID tag value | | | | | | | | | |
| raw | Hex | N/A | Raw tag id value. Always a 16 character hexadecimal value for a 64 bit tag; a 24 character hexadecimal value for a 96 bit tag. | | | | | | | | | |
| uid | String | Running state | Optional user assignable ID value | | | | | | | | | |
| rule | String | Running state | This optional rule describes a threshold event rule for a specific uid. Only one rule should be present for a given uid, otherwise last one wins. The format of the rule is a string consisting of two operation characters as operators and a 32 bit binary value other than 0 in decimal format. The definition of these operators are: <table border="1" data-bbox="597 1077 1406 1180"> <thead> <tr> <th>Operators</th> <th>Meaning</th> <th>Example</th> </tr> </thead> <tbody> <tr> <td>LT (default)</td> <td>Less Than</td> <td>“100” is the same as “LT100”</td> </tr> <tr> <td>GT</td> <td>Greater Than</td> <td>“GT50”</td> </tr> </tbody> </table> | Operators | Meaning | Example | LT (default) | Less Than | “100” is the same as “LT100” | GT | Greater Than | “GT50” |
| Operators | Meaning | Example | | | | | | | | | | |
| LT (default) | Less Than | “100” is the same as “LT100” | | | | | | | | | | |
| GT | Greater Than | “GT50” | | | | | | | | | | |

When <tag/> is used in a purge list, only the attributes ‘id’ and ‘type’ or ‘raw’ is used; attributes uid and rule are not applicable and will be ignored.

In this example, the <HostAck/> tag is omitted because of the presence of an import tag list:

```

1 <?xml version=' 1.0' ?>
2 <Matrics> <!-- start-tag of Matrics XML document -->
3 <TagList> <!-- start tag for tag list -->
4 <tag raw=' 206980C00021260459800000' uid=' 34 inch digital TV' rule=' 100' />
5 <tag raw=' 8900640246000000' uid=' stereo system' rule=' 30' />
6 </TagList> <!-- end tag for tag list -->
7 </Matrics> <!-- end-tag of Matrics XML document -->

```

In this example, the <HostAck/> tag is omitted because of the presence of a purge tag list:

```

1 <?xml version=' 1.0' ?>
2 <Matrics> <!-- start-tag of Matrics XML document -->
3 <PurgeList> <!-- start tag for purge list -->
4 <tag raw=' 206980C00021260459800000' /> <!-- a 96 bit RFID tag -->
5 <tag raw=' 8900640246000000' /> <!-- a 64 bit RFID tag -->
6 </PurgeList> <!-- end tag for purge list -->
7 </Matrics> <!-- end-tag of Matrics XML document -->

```


RFID Tag List Query Result

A tag list can be returned as the result of a queryTags command. The same <tag/> XML tag is used to describe an entry in this tag list, but it has some additional attributes for this specific situation:

| Attribute name | Type | Default | Meaning |
|----------------|--------|---------------|---|
| time | Hex | Running state | The time stamp indicating when this tag has been seen. It is a hexadecimal value representing the number of seconds since the Epoch (Jan. 1, 1970.) |
| RPL | string | Running state | Read Point List. This is a comma delimited list of ReadPointIds (from the map) indicating which read point(s) the RFID tag is currently visible at. |

Read Point Map

Logically, each antenna is called a Read Point, and identified internally by an automatically generated unique Read Point ID. Through the Web-based administration console, a user can configure a read point with name, read point class, read point zone, and other attributes. Please refer to the user manual for detail instruction.

To be efficient, only the Read Point ID, instead of the name, is used to identify an antenna in a tag list or event list. The Read Point Map is where you can find out its associated information. It is a logical container holding the association of a Read Point ID to its name, and the Read Point Class and Read Point Zone it uses.

Read Point Map can be sent as part of the response of a query, but does not need to be sent every time. It is always sent automatically in the response of the very first query after power on or reboot, or whenever the read point configuration has been changed. All other time, it is only sent when it is explicitly asked in the query.

If the Host system needs to know the detail configuration of each read point, it should explicitly ask for the Read Point Map at its very first query to make sure it has the correct association information. In order to keep its record consistent with the information in the device, it still needs to monitor and detect the Read Point Map in the response of each query, even it has not explicitly asked for it, and update its own record promptly.

<ReadPointMap> is start XML tag for a ReadPointMap list.

</ReadPointMap> is end XML tag for a ReadPointMap list.

<Pair/> is empty-element tag for a single entry in the content of a Read Point Map list. It has following attributes:

| Attribute name | Type | Default | Meaning |
|----------------|---------|---------------|--|
| name | String | N/A | The name of the read point |
| id | Decimal | N/A | The unique id of the read point |
| zone | String | Running state | The name of the Read Point Zone used by this read point |
| class | String | Running state | The name of the Read Point Class used by this read point |

For example:

```

1  <?xml version=' 1.0' ?>
2  <Metrics> <!-- start-tag of Metrics XML document -->
3  <EventGroup> <!-- start-tag of an event group -->
4      <ReadPointMap> <!-- start tag for a Read Point Map -->
5          <pair name=' Read Point #1' id=' 231' zone=' First Door' class=' Portal' />
6          <pair name=' Read Point #2' id=' 16' />
7              <!-- running state determines the zone and class -->
8          <pair name=' Read Point #3' id=' 790' zone=' Second Door' />
9              <!-- a new zone, running state determines the class -->
10         <pair name=' Read Point #4' id=' 68' />
11             <!-- running state determines the zone and class -->
12         </ReadPointMap> <!-- end tag for a Read Point Map -->
13         <tagList> <!-- start tag for purge list -->
14             <tag row=' 206980C00021260459800000' time=' 111111111' RPL=' 1, 2, 3' />
15             <tag row=' 8900640246000000' /> <!-- running state -->
16         </tagList> <!-- end tag for purge list -->
17     </EventGroup> <!-- end-tag of an event group -->
18 </Metrics> <!-- end-tag of Metrics XML document -->

```

The Read Point Map in the above example carries the following information:

| Read Point name | Read Point ID | Read Point Zone | Read Point Class |
|-----------------|---------------|-----------------|------------------|
| Read Point #1 | 231 | First Door | Portal |
| Read Point #2 | 16 | First Door | Portal |
| Read Point #3 | 790 | Second Door | Portal |
| Read Point #4 | 68 | Second Door | Portal |

Event Query Result

Similar to a tag list, an event list is returned as a response for the query for events.

<EventList> is start XML tag for a list of events.

</EventList> is end XML tag for a list of events.

Every entry in the event list is also described by the **<Tag/>** XML tag with one extra attribute:

| Attribute name | Type | Default | Meaning | | | | | | | | |
|----------------|------------------------|---------------|--|---|---------|---|-----------------|---|------------------------|---|-----------------|
| event | Decimal | Running state | The type number of event associated with this RFID tag. Legitimate event values are: <table border="1" data-bbox="597 1360 948 1537"> <tbody> <tr> <td>0</td> <td>New Tag</td> </tr> <tr> <td>1</td> <td>Tag Not Visible</td> </tr> <tr> <td>2</td> <td>Tag Visibility Changed</td> </tr> <tr> <td>3</td> <td>Threshold Event</td> </tr> </tbody> </table> | 0 | New Tag | 1 | Tag Not Visible | 2 | Tag Visibility Changed | 3 | Threshold Event |
| 0 | New Tag | | | | | | | | | | |
| 1 | Tag Not Visible | | | | | | | | | | |
| 2 | Tag Visibility Changed | | | | | | | | | | |
| 3 | Threshold Event | | | | | | | | | | |

If the Exception event is enabled, an exception list is also returned as a response for the query for events.

<ExceptionList> is start XML tag for a list of exception events.

</ExceptionList> is end XML tag for a list of exception events.

<Exception/> is the empty-element tag for a single entry in the content of an exception list. It has following attributes:

| Attribute name | Type | Default | Meaning |
|----------------|------|---------|---------|
|----------------|------|---------|---------|

| | | | |
|--------|---------|---------------|--|
| time | Hex | Running state | The time stamp indicating when this exception occurred. It is a hexadecimal value representing the number of seconds since the Epoch (Jan. 1, 1970.) |
| name | String | Running state | The name of the device generating this event |
| state | Decimal | Running state | The current status of the device |
| type | Decimal | Running state | The type of the device |
| reason | String | N/A | The reason for the exception |

These attributes are actually the same as defined for SNMP events. Please refer to the SNMP description for details.

Sample event list:

```

1  <?xml version='1.0'?>
2  <Metrics> <!-- start-tag of Metrics XML document -->
3  <EventGroup> <!-- start-tag of an event group -->
4    <ReadPointMap> <!-- start tag for a Read Point Map -->
5      <pair name=' Read Point #1' id=' 231' zone=' First Door' class=' Portal' />
6      <pair name=' Read Point #2' id=' 16' />
7      <pair name=' Read Point #3' id=' 790' zone=' Second Door' />
8      <pair name=' Read Point #4' id=' 68' />
9    </ReadPointMap> <!-- end tag for a Read Point Map -->
10   <EventList> <!-- start tag for purge list -->
11     <tag event=' 0' raw=' 206980C00021260459800000' time=' 4104fec8' RPL=' 1, 2, 3' />
12     <tag raw=' 8900640246000000' /> <!-- running state -->
13     <tag event=' 1' raw=' 206980C00021260459800001' time=' 4104feba' RPL=' ' />
14     <tag event=' 2' raw=' 206980C00021260459800002' time=' 4104febF' RPL=' 2, 3' />
15   </EventList> <!-- end tag for purge list -->
16   <ExceptionList>
17     <Exception time=' 4104fb58' name=' Read Point 1-1-1-2-1' state=' 0' type=' 0' reason=' Enable
18     all' />
19     <Exception state=' 1' reason=' No antenna' />
20     <Exception time=' 4104fb94' state=' 0' reason=' Enable all' />
21     <Exception state=' 1' reason=' No antenna' />
22     <Exception time=' 4104fbd0' state=' 0' reason=' Enable all' />
23     <Exception state=' 1' reason=' No antenna' />
24     <Exception time=' 4104fc0c' state=' 0' reason=' Enable all' />
25     <Exception state=' 1' reason=' No antenna' />
26     <Exception time=' 4104fc23' name=' Core Server Polling' state=' 0' type=' 1' reason=' Metrics
27     MVM Core Server starts polling' />
28   </ExceptionList>
29 </EventGroup> <!-- end-tag of an event group -->
30 </Metrics> <!-- end-tag of Metrics XML document -->

```

Error Result

<Error /> is empty-element XML tag denoting a system error.

It has following attributes:

| Attribute name | Type | Default | Meaning |
|----------------|---------|---------|---|
| Code | decimal | N/A | System error code |
| Msg | string | N/A | human readable description of the error |

For example:

```

1  <?xml version='1.0'?>
2  <Metrics> <!-- start-tag of Metrics XML document -->
3    <Error code=' 99' msg=' An error description goes here' />
4  </Metrics> <!-- end-tag of Metrics XML document -->

```

Sample DTD

Below is a sample DTD that you can use to describe the XML elements in XML Declaration Syntax. This just serves as a reference.

It is not required for either the Host system or the Matrics platform to input or output a DTD. However, if you use an XML parser that desires a DTD, you can use the description below (make sure you insert the DOCTYPE entry into the input stream.)

Validating parsers read the DTD before they read your document so that they can identify where every element type ought to be and how they relate to each other, so that applications that need to know this information in advance (most editors, search engines, databases, etc.) can set themselves up properly.

```

1  <!--
2     Typical usage:
3     <?xml version='1.0' ?>
4     <!DOCTYPE Matrics SYSTEM 'MatricsXML.dtd' >
5     <Matrics>
6     ...
7     </Matrics>
8     DTD for Matrics User XML
9  -->
10
11 <!-- Top Level -->
12 <!ELEMENT Matrics (EventGroup|HostAck|Error)*>
13
14 <!-- EventGroup -->
15 <!ELEMENT EventGroup (ReadPointMap|TagList|EventList|ExceptionList)*>
16 <!ELEMENT ReadPointMap (Pair)*>
17 <!ELEMENT Pair EMPTY>
18 <!ATTLIST Pair
19     name CDATA #REQUIRED
20     id CDATA #REQUIRED
21     zone CDATA #IMPLIED
22     class CDATA #IMPLIED
23 >
24 <!ELEMENT EventList (Tag)*>
25 <!ELEMENT TagList (Tag)*>
26 <!ELEMENT Tag EMPTY>
27 <!ATTLIST Tag
28     raw CDATA #REQUIRED
29     id CDATA #IMPLIED
30     uid CDATA #IMPLIED
31     type CDATA #IMPLIED
32     event CDATA #IMPLIED
33     time CDATA #IMPLIED
34     RPL CDATA #IMPLIED
35     rule CDATA #IMPLIED
36 >
37 <!ELEMENT ExceptionList (Exception)*>
38 <!ELEMENT Exception EMPTY>
39 <!ATTLIST Exception
40     reason CDATA #REQUIRED
41     time CDATA #IMPLIED
42     name CDATA #IMPLIED
43     type CDATA #IMPLIED
44     state CDATA #IMPLIED
45 >
46
47 <!-- HostAck -->
48 <!ELEMENT HostAck (TagList|PurgeList)*>
49
50 <!-- PurgeList -->
51 <!ELEMENT PurgeList (Tag)*>
52
53 <!-- Error -->
54 <!ELEMENT Error EMPTY>
55 <!ATTLIST Error
56     code CDATA #REQUIRED

```

| | | |
|----|-----|------------------|
| 57 | msg | CDATA #REQUI RED |
| 58 | > | |

Section 4. SNMP Trap

A Matrics device's Statistics and Traps Management Information Base (MIB) is defined in the "Matrics-snmp.mib" file. These objects are part of the enterprise MIB for Matrics.

Enterprise Identifier

The enterprise identifier for "Matrics Inc." is 12405.

| | |
|----------------|---|
| matrics | OBJECT IDENTIFIER ::= { enterprises 12405 } |
| matricsMvm | OBJECT IDENTIFIER ::= { matrics 1 } |
| matricsMvmTrap | OBJECT IDENTIFIER ::= { matricsMvm 1 } |

devEvent trap

The "devEvent" trap is defined in the MIB. This trap is generated to indicate that a device event has occurred.

The trap's Object ID:

(.iso.org.dod.internet.snmpV2.snmpModules.snmpMIB.snmpMIBObjects.
snmpTrap.snmpTrapOID.0) = OID: enterprises.12405.1.1.0.1

This trap has 4 variable bindings:

- Name: trapDevName
 OID: enterprises.12405.1.1.1 { matricsMvmTrap 1 }
 Syntax: DisplayString
 Access: read-only
 Status: current
 Description: Name of the device that causes the trap.
- Name: trapDevStatus
 OID: enterprises.12405.1.1.2 { matricsMvmTrap 2 }
 Syntax: INTEGER
 Access: read-only
 Status: current
 Description: Current status of the device.
 It could be: enabled(0),
 sysDisabled(1),
 userEnabled(2),
 userDisabled(3),
 parentSysEnabled(4)
 parentSysDisabled(5)
 parentUserEnabled(6)
 parentUserDisabled(7)

3. Name: trapDevType
 OID: enterprises.12405.1.1.3 { matrixsMvmTrap 3 }
 Syntax: INTEGER
 Access: read-only
 Status: current
 Description: Type of module that causes the trap.
 It could be: device(0),
 program(1)
4. Name: trapDevReason
 OID: enterprises.12405.1.1.4 { matrixsMvmTrap 4 }
 Syntax: Display String
 Description: Reason for the trap.

Example trap (SNMP Version 1):

```
2002-05-15 15:55:28 Agent [192.168.0.181] (via localhost [127.0.0.1]) TRAP, SNMP v1, community public
enterprises.matrics Enterprise Specific Trap (0) Uptime: 2 days, 6:15:59.47
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevName = "Converter #3"
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevStatus = userDisabled(3)
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevType = device(0)
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevReason = "User disabled"
```

Example trap (SNMP Version 2c):

```
2002-05-15 15:58:18 Agent [127.0.0.1]:
system.sysUpTime.0 = Timeticks: (19552896) 2 days, 6:18:48.96
.iso.org.dod.internet.6.3.1.1.4.1.0 = OID: enterprises.matrics.matricsMvm.matricsMvmTrap.
matrixsMvmTrap#.devEvent
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevName.0 = "Converter #3"
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevStatus.0 = userEnabled(2)
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevType.0 = device(0)
enterprises.matrics.matricsMvm.matricsMvmTrap.trapDevReason.0 = "User enabled"
```

Heartbeat SNMP Event

The Reader sends a "heartbeat" once a minute via SNMP (if SNMP is enabled.) This message has the following values:

Name: Core Server
 Type: Program
 Status: enable
 Description: Heartbeat

SNMP Traps

Below is a list of traps that you might receive from a Matrics Reader (and the name, status and type of device where the trap originated), and their possible causes.

1. Message: "Bad/missing reply from hostlink"
Device name: "HostProxy"
Device status: enabled (0)
Device type: program (1)
Cause: Bad reply is detected when you try to access the host link.
2. Message: Alert error message "A-xxxxx"
Device name: "Logger"
Device status: enabled (0)
Device type: program (1)
Cause: Possible reasons for alert are:
"Invalid rule operator xxxx": Incorrect operator is detected in the rule when importing a tag to the database (imported by tagList.)
"Invalid rule xxxx": Invalid rule is detected when importing a tag to the database (imported by tagList.)
"No host link set": The host link has not been specified yet when trying to notify the host.
"Invalid XML config file in initReaderNetwork": The XML config file is not valid when the core server initiates the Reader network.
3. Message: Critical error message "C-xxxxx"
Device name: "Logger"
Device status: enabled (0)
Device type: program (1)
Cause: Possible reasons for critical error message are:
"Failed to connect": Cgi proxy cannot connect to the appropriate server.
"Open failed errno=xx": Server cannot open the network port to listen to.
"Accept failed": Server cannot correctly accept data from the network port to which it's listening.
"Bind failed": Server cannot find the right command and parameter combination specified in the incoming command string.
"Server transmit failed": Server cannot send response back to cgi proxy.
"xxxx not open": Failed to open the database xxxx.
"Can't open pipe in notifyHost": Core server cannot communicate with the host link.
"No local hosts access": Cannot add local host to trusted hosts database.
"Socket failed": Network operation failed to open a socket.
"Listener socket failed to set SO_LINGER": Network operation cannot set the SO_LINGER attribute to the listener socket.
"Listener socket failed to set SO_REUSEADDR": Network operation cannot set the SO_REUSEADDR attribute to the listener socket.
"Giving up socket binding": Network operation cannot bind the socket.
"Listen failed": Network operation cannot listen to a socket.

- “Can not open pipe”: Server can’t open communication pipe to cgi proxy.
 “map db open failed”: Can’t open the map database.
 “useridx db open failed”: Can’t open the useridx database.
 “TAG.DB not open”: Can’t open the TAG.DB database.
4. Message: “Failed to read configuration file”
 Device name: “Console Server”/ “Core Server”
 Device status: enabled (0)
 Device type: program (1)
 Cause: Notification about Matrics Server failed to read in configuration file.
 5. Message: “Matrics Console Server starts running”
 Device name: “Console Server”
 Device status: enabled (0)
 Device type: program (1)
 Cause: Notification about Matrics Console Server starts running.
 6. Message: “Matrics Console Server quits running”
 Device name: “Console Server”
 Device status: userDisabled (3)
 Device type: program (1)
 Cause: Notification about Matrics Console Server quits running.
 7. Message: “Matrics Core Server starts running”
 Device name: “Core Server”
 Device status: enabled (0)
 Device type: program (1)
 Cause: Notification about Matrics Core Server starts running.
 8. Message: “Matrics Core Server quits running”
 Device name: “Core Server”
 Device status: userDisabled (3)
 Device type: program (1)
 Cause: Notification about Matrics Core Server quits running.
 9. Message: “Matrics Core Server starts polling”
 Device name: “Core Server Polling”
 Device status: enabled (0)
 Device type: program (1)
 Cause: Notification about Matrics Core Server starts polling.
 10. Message: “Matrics Core Server stops polling”
 Device name: “Core Server Polling”
 Device status: userDisabled (3)
 Device type: program (1)
 Cause: Notification about Matrics Core Server stops polling.

11. Message: Reader network device's status has been changed
- Device name: The name of the device (converter/converter port reader/reader/reader port)
- Device status: enabled (0) / sysDisabled (1) / userEnabled (2) / userDisabled (3) / parentSysEnabled (4) / parentSysDisabled (5) / parentUserEnabled (6) / parentUserDisabled (7)
- Device type: device (0)
- Cause: Detailed reason for device's status change:
"Initial state": The device's initial status is not enabled when initializing a Reader network.
"Enable All": The device is enabled by the "enable all" user command.
"User enabled": The device is enabled by user.
"User disabled": The device is disabled by user.
"Can't establish connection to port": The converter is disabled by error because the server cannot establish connection to the port.
"Failed receive from reader (xxx)": The Reader is disabled by error because the server cannot receive from the Reader.

Section 5. Byte Stream Protocol

Overview

This section provides the definition of fields and behavior of the Byte Stream protocol. This protocol can be carried on both a 4-wire RS485 link (for AR 400 and SR400) and a TCP/IP socket connection (for AR 400 only). The default configuration for the RS485 serial link is at 230400 baud rate, with 8 data bits, 1 start bit, 1 stop bit and no parity. The default TCP/IP port AR 400 listens to is 3000.

A Matrics reader is always waiting in passive mode for this protocol. The Host system should initiate all communication sequences. The packet sent from the Host system is as a “request” and the reply from a reader is a “response”. It is a synchronous protocol, which means that the Host must wait to receive the response for last request before issuing a new request. The maximum length of a request packet’s data section is 64 bytes; the maximum length of a response packet’s buffer space is 256 bytes.

Some commands are specific to a particular reader model, and not available on others. These commands are clearly marked in their definition.

Packet Format

Figure 5 shows the protocol packet format. The following table provides the definition of each field.

| Field | Size(Byte) | Value | Description |
|---------------|------------|-----------|--|
| SOF | 1 | 0x01 | Start of Frame |
| Node Address | 1 | 0~0x1F | RS485 network node address of the recipient or responding reader. |
| Packet Length | 1 | Dependent | The length of the packet including CRC, but excluding SOF |
| Command | 1 | Various | The action to be taken by a reader |
| Cmd Mirror | 1 | Dependent | Mirror the original command in the response packet |
| Status | 1 | Various | The result or status of a command execution |
| Data | Various | Dependent | The parameters or data for the command or response |
| CRC | 2 | Dependent | Bitwise inversion of the 16-bit CCITT-CRC of the packet excluding SOF, with the LSB (Least Significant Byte) first |

For TCP/IP connection, the node address in the request packet is also required to match the reader’s configuration to keep consistent.

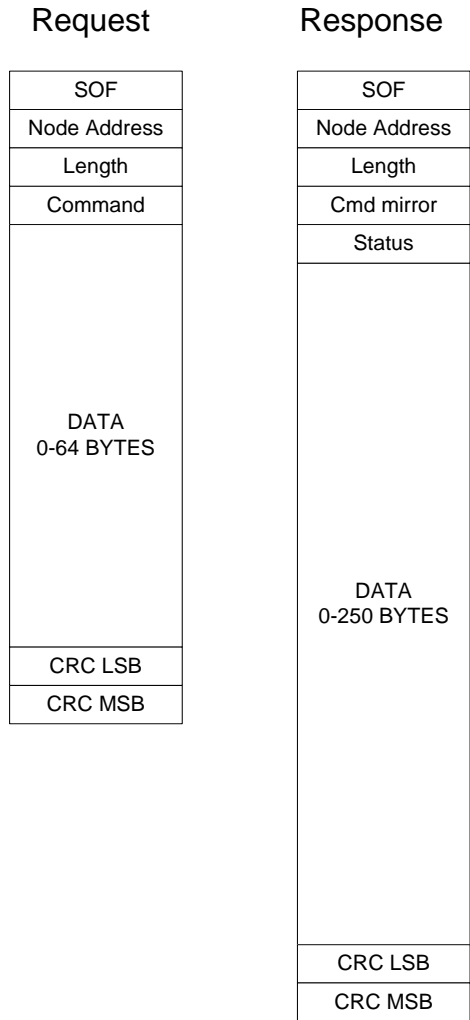


Figure 3 Byte Stream Protocol Packet Format

Status

The status field in the response packet indicates the execution result or status. The bit definition is:

| Bit order | Name | Value | Description |
|-----------|---------------|----------|---|
| 0 | Progress bit | 0 | Command execution has finished |
| | | 1 | Command execution is still in progress |
| 1 | | Reserved | |
| 2 | | Reserved | |
| 3 | | Reserved | |
| 4 | | Reserved | |
| 5 | | Reserved | |
| 6 | Parameter bit | 0 | Reader parameter has been set |
| | | 1 | Reader is working with default parameters |
| 7 | Error bit | 0 | Normal status |

| | | | |
|--|--|---|--------------------|
| | | 1 | Error has occurred |
|--|--|---|--------------------|

These status bits are defined and should be interpreted independently. For example, the error bit set to one does not necessarily imply this is the last response packet. The progress bit should always be checked instead.

A Matrics reader operates with a set of default parameters after reboot, and set the parameter bit to one to indicate this situation. The Host system should monitor this bit in all response packets and set the reader parameters accordingly. This bit is reset to zero after the first time the Host system sets the parameters.

Error Codes

Error Code is present in the first data byte whenever the Error bit is set.

| Error Code | Description |
|------------|--|
| F0hex | Invalid command parameter(s) |
| F1hex | Insufficient data |
| F2hex | Command not supported |
| F3hex | Antenna Fault (not present or shorted) |
| F4hex | DSP Timeout |
| F5hex | DSP Error |
| F6hex | DSP Idle |
| F7hex | Zero Power |
| FFhex | Undefined error |

CRC

A Cyclic Redundancy Check is used for error detection and is positioned at the end of the packet. The 16-bit CRC is calculated on all the bytes of the packet following the SOF. The CRC uses the CCITT polynomial ($X^{16} + X^{12} + X^5 + 1$) with a seed or preload value of 0xBEEF. The bitwise inversion of the calculated value is appended to the end of the data section of the packet, with the LSB first.

Example Code:

```

1  /*
2  * This is the table used to by the table lookup method of generating CCITT CRC values.
3  * The CCITT polynomial is x^16 + x^12 + x^5 + 1 reverse direction table - i.e. LSB first
4  */
5  static const uint16 crcTable[256] =
6  {
7      0x0000, 0x1189, 0x2312, 0x329b, 0x4624, 0x57ad, 0x6536, 0x74bf,
8      0x8c48, 0x9dc1, 0xaf5a, 0xbed3, 0xca6c, 0xdbed, 0xe97e, 0xf8f7,
9      0x1081, 0x0108, 0x3393, 0x221a, 0x56a5, 0x472c, 0x75b7, 0x643e,
10     0x9cc9, 0x8d40, 0xbfdb, 0xae52, 0xdaed, 0xcb64, 0xf9ff, 0xe876,
11     0x2102, 0x308b, 0x0210, 0x1399, 0x6726, 0x76af, 0x4434, 0x55bd,
12     0xad4a, 0xbcc3, 0x8e58, 0x9fd1, 0xeb6e, 0xfae7, 0xc87c, 0xd9f5,
13     0x3183, 0x200a, 0x1291, 0x0318, 0x77a7, 0x662e, 0x54b5, 0x453c,
14     0xbdcb, 0xac42, 0x9ed9, 0x8f50, 0xfbef, 0xea66, 0xd8fd, 0xc974,
15     0x4204, 0x538d, 0x6116, 0x709f, 0x0420, 0x15a9, 0x2732, 0x36bb,
16     0xce4c, 0xdfc5, 0xed5e, 0xfcd7, 0x8868, 0x99e1, 0xab7a, 0xbaf3,
17     0x5285, 0x430c, 0x7197, 0x601e, 0x14a1, 0x0528, 0x37b3, 0x263a,
18     0xdccd, 0xcf44, 0xfddf, 0xec56, 0x98e9, 0x8960, 0xbbfb, 0xaa72,
19     0x6306, 0x728f, 0x4014, 0x5122, 0x2522, 0x34ab, 0x0630, 0x17b9,
20     0xef4e, 0xfec7, 0xcc5c, 0xdd5, 0xa96a, 0xb8e3, 0x8a78, 0x9bf1,

```

```

21 0x7387, 0x620e, 0x5095, 0x411c, 0x35a3, 0x242a, 0x16b1, 0x0738,
22 0xffcf, 0xee46, 0xdcdd, 0xcd54, 0xb9eb, 0xa862, 0x9af9, 0x8b70,
23 0x8408, 0x9581, 0xa71a, 0xb693, 0xc22c, 0xd3a5, 0xe13e, 0xf0b7,
24 0x0840, 0x19c9, 0x2b52, 0x3adb, 0x4e64, 0x5fed, 0x6d76, 0x7cff,
25 0x9489, 0x8500, 0xb79b, 0xa612, 0xd2ad, 0xc324, 0xf1bf, 0xe036,
26 0x18c1, 0x0948, 0x3bd3, 0x2a5a, 0x5ee5, 0x4f6c, 0x7df7, 0x6c7e,
27 0xa50a, 0xb483, 0x8618, 0x9791, 0xe32e, 0xf2a7, 0xc03c, 0xd1b5,
28 0x2942, 0x38cb, 0x0a50, 0x1bd9, 0x6f66, 0x7eef, 0x4c74, 0x5dfd,
29 0xb58b, 0xa402, 0x9699, 0x8710, 0xf3af, 0xe226, 0xd0bd, 0xc134,
30 0x39c3, 0x284a, 0x1ad1, 0x0b58, 0x7fe7, 0x6e6e, 0x5cf5, 0x4d7c,
31 0xc60c, 0xd785, 0xe51e, 0xf497, 0x8028, 0x91a1, 0xa33a, 0xb2b3,
32 0x4a44, 0x5bcd, 0x6956, 0x78df, 0x0c60, 0x1de9, 0x2f72, 0x3efb,
33 0xd68d, 0xc704, 0xf59f, 0xe416, 0x90a9, 0x8120, 0xb3bb, 0xa232,
34 0x5ac5, 0x4b4c, 0x79d7, 0x685e, 0x1ce1, 0x0d68, 0x3ff3, 0x2e7a,
35 0xe70e, 0xf687, 0xc41c, 0xd595, 0xa12a, 0xb0a3, 0x8238, 0x93b1,
36 0x6b46, 0x7acf, 0x4854, 0x59dd, 0x2d62, 0x3ceb, 0x0e70, 0x1ff9,
37 0xf78f, 0xe606, 0xd49d, 0xc514, 0xb1ab, 0xa022, 0x92b9, 0x8330,
38 0x7bc7, 0x6a4e, 0x58d5, 0x495c, 0x3de3, 0x2c6a, 0x1ef1, 0x0f78
39 };
40
41 /*
42  * uint16 calcBlockCRC(size_t count, uint16 crc, void *buffer)
43  *
44  * ARGUMENTS
45  *   size_t count :   Number of bytes in the buffer
46  *   uint16 crc   :   Preload value of the CRC
47  *   void *buffer :   Buffer whose CRC is to be calculated
48  *
49  * DESCRIPTION
50  *   This routine is called to calculate the CCITT CRC value of a block of data.
51  *
52  * RETURNS
53  *   CRC value.
54  */
55
56 uint16 calcBlockCRC(size_t count, uint16 crc, void *buffer)
57 {
58     const uint8 *pBuf = (const uint8*)buffer;
59
60     while (count--)
61         crc = (uint16)((crc >> 8) ^ crcTable[(uint8)(crc ^ *pBuf++)]);
62     return (crc ^ ((uint16)0xFFFF));
63 }

```

Note: 'uint16' represents unsigned 16bit value like 'unsigned short' and 'uint8' represents unsigned 8bit value like 'unsigned char'

General Communication Sequence

Figure 6 shows the general communication sequence for the byte stream protocol.

For a TCP/IP socket connection, the Host system needs to establish connection to the reader before any message exchange. An established TCP/IP socket connection will be kept open until the Host system closes it or error occurs. For a RS-485 serial connection, the Host system can start sending command at any time as long as the physical layer is connected.

For each request sent by the Host system to a reader, there could be multiple response packets back. The progress bit in a response packet's status field serves as an indicator. Being zero means this is the last packet; otherwise, it means the command execution is still in progress and more packets are going to come until the last one with this bit set to zero.

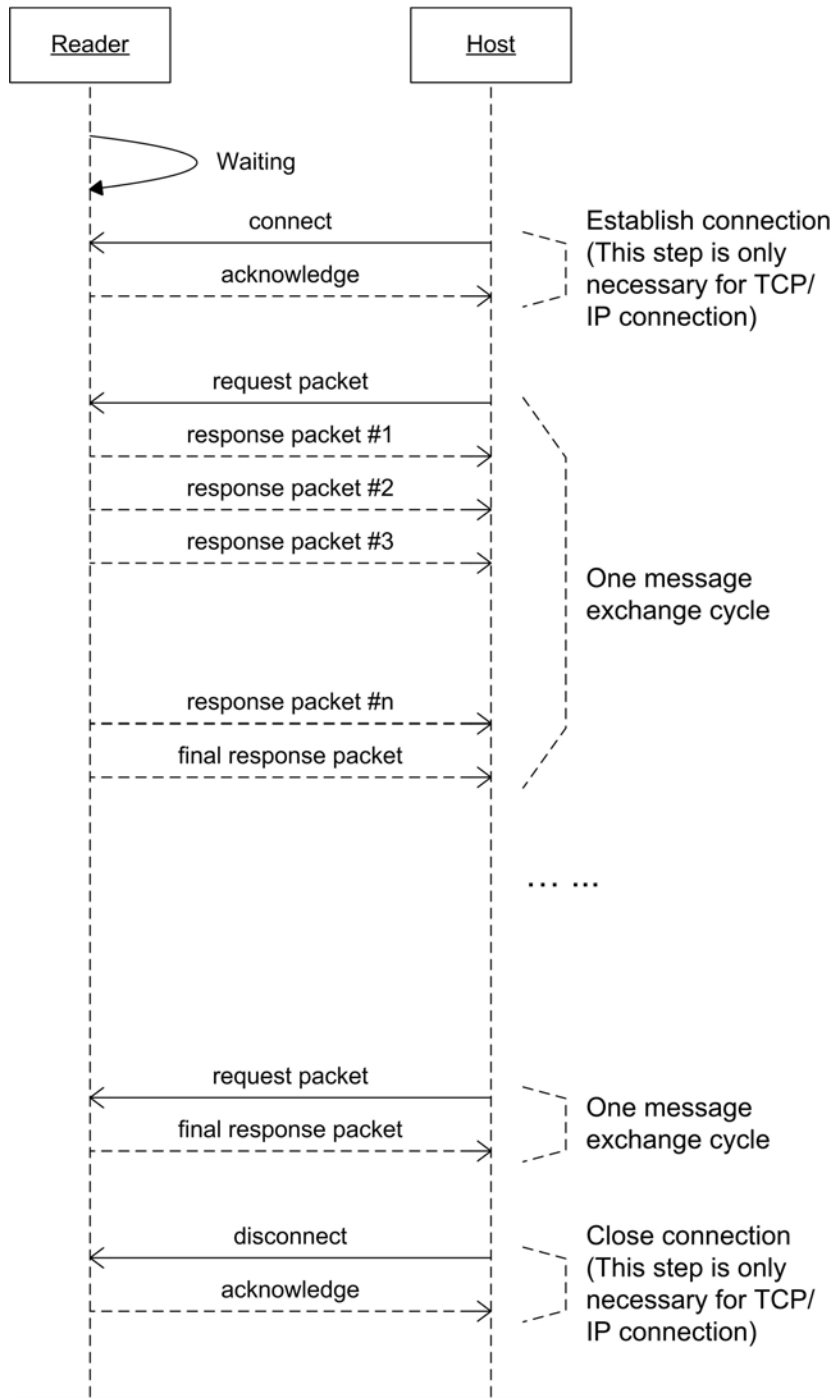


Figure 4: General byte stream protocol communication sequence

General Use Tips

Reserved Fields

All reserved fields or bits are subject to change in the future and their value should not be presumed. Defined bit field should be checked independently for the information it carries.

RS485 Node Address

For a RS485 serial connection network, each reader is uniquely identified by its serial number, which is not changeable by users. Normally, knowing each reader's serial number, the Host system should be able to initialize and maintain the RS485 network by dynamically assigning a RS485 node address to each reader. The Host system should at least go through this initialization process each time it starts running.

Set Parameter Block

Generally, reader's parameters set by the byte stream protocol are not persisted. When a reader boots up, it may start with a default or persisted set of system configuration, which may not be what the Host system expects. When using the byte stream protocol, the Host system should always set the reader's parameters by using the Set Parameter Block command before starts reading tags. At runtime, the Host system also needs to monitor the "Parameter Bit" in the response packet's status byte, and re-initialize the reader whenever this bit is set. On the other hand, these parameters can also be changed at anytime by issuing a new command.

By default, AR400 reader's web administration console starts with another set of default configuration and initializes itself by this, thus always clear the "Parameter Bit". The side effect of this is that the host application may miss the chance to detect the reader's reboot if the reader is always driven by the byte stream protocol. This self initialization can be disabled by manually disabling the reader. After logging into the web administration console, select the "Configuration" menu item, click the reader's link to go to the "Reader Configuration" page, check "disable" option and commit the change. Then the reader will skip this initialization and always set the "Parameter Bit" after reboot.

General Initialization Sequence

When there are more than one reader on one RS485 network, it is recommended to suspend (a broadcast message) all readers at the beginning, then the host can dynamically assign node addresses to its known readers and starts working with them. The advantage of this sequence is to make sure any new readers that are unknown to the host would keep silent and not cause node address conflict.

After assignment of node address, the host could set the parameters for all antennas to a set of default value (for example, without any combined group). Then the host could get status of a reader and find out which antennas are connected and configure them accordingly. This sequence could keep the configuration of the reader and antennas to a known state whenever the host application starts.

The reader should be able to read or write after this initialization sequence.

Section 6. Byte Stream Command Definitions

Unless noted, the following commands are available for all Matrics Readers. Commands that are specific to a particular Reader model (and not available on other Readers) or firmware version, are noted as such in *italicized red text*.

Read Full Field Command (22_{hex})

Read all RFID tags using one antenna port of the addressed reader.

Command Example:

To command reader with node address of 0x04 to read all RFID tags under antenna port #1.

| Byte order | Value | Description | |
|------------|-------|--|------|
| 0 | 0x01 | SOF, Start of Frame | |
| 1 | 0x04 | RS485 network node address (0x00 ~ 0x1F) | |
| 2 | 0x06 | Packet length excludes SOF, but includes the CRC | |
| 3 | 0x22 | Command | |
| 4 | 0xA0 | Logical antenna indicator, defined as: | |
| | | Antenna port #1 | 0xA0 |
| | | Antenna port #2 | 0xB0 |
| | | Antenna port #3 | 0xC0 |
| | | Antenna port #4 | 0xD0 |
| 5 | CRC | LSB of the CRC-16 | |
| 6 | CRC | MSB of the CRC-16 | |

Response Example:

There are two kinds of response packet for this command:

1. RFID tag data packet

This packet can carry up to ten RFID tag IDs. For each RFID tag ID, there is one extra byte at the beginning as type indicator. The definition of the tag indicator is:

| Bit order | Name | Value | Description |
|-----------|------------|----------|---------------------|
| 0 | Type bit | 0 | EPC type tag ID |
| | | 1 | Matrics type tag ID |
| 1 | | Reserved | |
| 2 | | Reserved | |
| 3 | | Reserved | |
| 4 | Length bit | 0 | 8 bytes tag ID |

| | | | |
|---|--|----------|-----------------|
| | | 1 | 12 bytes tag ID |
| 5 | | Reserved | |
| 6 | | Reserved | |
| 7 | | Reserved | |

For example, if two RFID tags are read, their tags IDs in hexadecimal are:

0x89,00,64,02,46,00,00,00

0x20,69,80,C0,00,21,26,04,59,80,00,00

Then the response packet carrying these two tag IDs is:

| Byte order | Value | Description | | | |
|------------|-------|---|---|------------------------|-------------------------|
| 0 | 0x01 | SOF, Start of Frame | | Response packet header | |
| 1 | 0x04 | RS485 network node address | | | |
| 2 | 0x1E | Packet length except SOF | | | |
| 3 | 0x22 | Mirror of the Command | | | |
| 4 | 0x01 | Status, could be 0x41 is parameter has not been set | | | |
| 5 | 0xA0 | Mirror of the Logical antenna indicator | | Data field | |
| 6 | 0x02 | Number of tags in this packet | | | |
| 7 | 0x00 | 8 bytes EPC tag | Type indicator | | The 1 st Tag |
| 8 | 0x00 | LSB | Tag ID in hexadecimal, with the LSB first | | |
| 9 | 0x00 | | | | |
| 10 | 0x00 | | | | |
| 11 | 0x46 | | | | |
| 12 | 0x02 | | | | |
| 13 | 0x64 | | | | |
| 14 | 0x00 | | | | |
| 15 | 0x89 | MSB | | | |
| 16 | 0x10 | 12 bytes EPC tag | Type indicator | | The 2 nd Tag |
| 17 | 0x00 | LSB | Tag ID in hexadecimal, with the LSB first | | |
| 18 | 0x00 | | | | |
| 19 | 0x80 | | | | |
| 20 | 0x59 | | | | |
| 21 | 0x04 | | | | |
| 22 | 0x26 | | | | |
| 23 | 0x21 | | | | |
| 24 | 0x00 | | | | |
| 25 | 0xC0 | | | | |
| 26 | 0x80 | | | | |
| 27 | 0x69 | | | | |
| 28 | 0x20 | MSB | | | |
| 29 | CRC | LSB of the CRC-16 | | | CRC |
| 30 | CRC | MSB of the CRC-16 | | | |

2. Final packet

| Byte order | Value | Description | | |
|------------|-------|---|------------------------|--|
| 0 | 0x01 | SOF, Start of Frame | Response packet header | |
| 1 | 0x04 | RS485 network node address | | |
| 2 | 0x0C | Packet length except SOF | | |
| 3 | 0x22 | Mirror of the Command | | |
| 4 | 0x00 | Status, could be 0x40 is parameter has not been set | | |
| 5 | 0x02 | LSB | Data field | |
| 6 | 0x00 | MSB | | Total number of tags read |
| 7 | 0x00 | LSB | | The number of detected under-run errors (Reserved for test purpose) |
| 8 | 0x00 | MSB | | |
| 9 | 0x00 | LSB | | The number of detected CRC errors (Reserved for test purpose) |
| 10 | 0x00 | MSB | | |
| 11 | CRC | LSB of the CRC-16 | CRC | |
| 12 | CRC | MSB of the CRC-16 | | |

Note:

- If no tag is read, only the final packet is returned.
- If RF power level for the specified antenna is set to zero when the Read Full Field Command is issued, a Zero Power error is returned.
- In the case that response packages indicate Reader parameter not set, the Set Parameter Block command has to be used to setup the Reader.
- When a combined group is used, only the lowest antenna indicator should be used to address all antennas in this specific group. The read command sent by the lowest antenna indicator of a combined group actually triggers read at all antennas in the group.

Set Parameter Block Command (23_{hex})

Set parameters related to one antenna port. It is possible to set the same block of parameters for more than one antenna at the same time

Data Block:

| Byte order | Value | Description |
|------------|-----------|--|
| 0 | 0x00~0x01 | 0x01 – configure antenna port #1; 0x00 -- do not |
| 1 | 0x00~0x01 | 0x01 – configure antenna port #2; 0x00 -- do not |
| 2 | 0x00~0x01 | 0x01 – configure antenna port #3; 0x00 -- do not |
| 3 | 0x00~0x01 | 0x01 – configure antenna port #4; 0x00 -- do not |
| 4 | 0x01~0xFF | Power level for tag reading (0x01=minimum, 0xFF=maximum) |
| 5 | 0x00~0x08 | Environment variable |
| 6 | 0x00~0x02 | Combined antenna 0x00 – not combined, independently addressed port 0x01 – combined logical group #1 0x02 – combined logical group #2 |
| 7 | | Reserved |
| 8 | 0x00~0x3F | Tag filter pattern length 0x00 – filter disabled 0x01~0x3F – number of bits in filter |
| 9 | 0x00 | Tag type the filter applies. Always 0x00 – EPC tag |
| 10 | 0x00~0x02 | Select the air protocol class to use for reading tag 0x00 – default value for reading all classes Bit 1– set to 1 means to read EPC 1.1 Class 0 Bit 2– set to 1 means to read EPC 1.1 Class 1 |
| 11 | 0x01~0xFF | Power level for tag writing (0x01=minimum, 0xFF=maximum) |
| 12~19 | | Tag filter pattern, with LSB first |
| 20~35 | | Reserved |

Note:

- Power level

The ‘Power level’ for both reading and writing tags is logarithmic with the maximum power about 30dBm. This table describes the different values for different power levels.

| Output Power | | % Full Power | Power Level Value (decimal) | | |
|--------------|------|--------------|-----------------------------|-----|-------|
| dBm | Walt | | AR 400 | | SR400 |
| | | | From | To | |
| 30 | 1.00 | 100 | 248 | 255 | 236 |
| 29.5 | 0.89 | 89 | 240 | 247 | 224 |
| 29 | 0.79 | 79 | 232 | 239 | 213 |

| | | | | | |
|------|------|----|-----|-----|-----|
| 28.5 | 0.71 | 71 | 224 | 231 | 203 |
| 28 | 0.63 | 63 | 216 | 223 | 194 |
| 27.5 | 0.56 | 56 | 208 | 215 | 186 |
| 27 | 0.50 | 50 | 200 | 207 | 178 |
| 26.5 | 0.45 | 45 | 192 | 199 | 171 |
| 26 | 0.40 | 40 | 184 | 191 | 164 |
| 25.5 | 0.35 | 35 | 176 | 183 | 157 |
| 25 | 0.32 | 32 | 168 | 175 | 150 |
| 24.5 | 0.28 | 28 | 160 | 167 | 143 |
| 24 | 0.25 | 25 | 152 | 159 | 136 |
| 23.5 | 0.22 | 22 | 144 | 151 | 129 |
| 23 | 0.20 | 20 | 136 | 143 | 122 |
| 22.5 | 0.18 | 18 | 128 | 135 | 116 |
| 22 | 0.16 | 16 | 120 | 127 | 111 |
| 21.5 | 0.14 | 14 | 112 | 119 | 108 |
| 21 | 0.13 | 13 | 104 | 111 | 105 |
| 20.5 | 0.11 | 11 | 96 | 103 | 102 |
| 20 | 0.10 | 10 | 88 | 95 | 99 |
| 19.5 | 0.09 | 9 | 80 | 87 | 96 |
| 19 | 0.08 | 8 | 72 | 79 | 93 |
| 18.5 | 0.07 | 7 | 64 | 71 | 90 |
| 18 | 0.06 | 6 | 56 | 63 | 87 |
| 17.5 | 0.06 | 6 | 48 | 55 | 84 |
| 17 | 0.05 | 5 | 40 | 47 | 81 |
| 16.5 | 0.04 | 4 | 32 | 39 | 78 |
| 16 | 0.04 | 4 | 0 | 31 | 75 |

- Environment variable

The ‘Environment variable’ determines how hard the reader tries to read tags during a ‘Read All’ command. A bigger number means longer and more intense reading (more frequencies are used for a FCC part 15 reader), thus is better for situations where tagged items are not moving (stationary), like in a shelf application, to overcome issues like RF interference and RF-Null’s on a fixed pool of tags. In the situation where tags constantly moving in and out of the read field, it is important to read as fast as possible to be able to start negotiating with new tags coming into the read field, thus in this kind of dynamic environments this variable is usually set to a small number. The exact value chosen for this ‘Environment variable’ also depends on the location of, and RF environment around the system. Generally, it is safe to start with the smallest value (00 for dynamic, 04 for static), then adjust it according to the read performance.

- Combined antenna

Antennas can be logically grouped together by using the ‘Combined antenna’ parameter. For one antenna group, a host only needs to address the antenna with the smallest index to get reads from all combined antennas. For example, if antenna 1, 3 and 4 are combined, then the Host only needs to execute ‘Read Full’ for antenna 1 to actually get reads from all of antenna 1, 3 and 4. For a four port Matrics reader, there can be up to two logical groups. Antenna ports with the same ‘Combined antenna’ parameter value, except 0x00, belong to one group.

Only AR 400 readers support more than one combined group. SR400 can have only one combined group.

- Tag filter

Read performance could be improved by selectively reading tags with specified beginning portion of the tag ID. Tag filter specifies a bit pattern, which is always 64 bit long, and how many meaningful bits, starting from the left hand (Most Significant bit) side, this pattern has. Every tag read needs to match the specified meaningful bits to qualify as a successful read. In the parameter block, this bit pattern is stored as the LSB first.

- Air protocol selection

Air protocol selection applies to both reading and writing tags.

Command Example:

For example, we want to configure antenna port #1 and #3 at the same time. They all belong to the 2nd combined group, with maximum reading power, setup for dynamic environment application, only read Class 0 and EPC 1.1 SGTIN-96 encoded tags (with the first 8 bits as 00110000_{binary}).

| Byte order | Value | Description | | |
|------------|-------|---|-----------------------|--------------------|
| 0 | 0x01 | SOF, Start of Frame | Request packet header | |
| 1 | 0x04 | RS485 network node address (0x00 ~ 0x1F) | | |
| 2 | 0x29 | Packet length excludes SOF, but includes the CRC | | |
| 3 | 0x23 | Command | | |
| 4 | 0x01 | Configure antenna port #1 | Data field | |
| 5 | 0x00 | Do not configure antenna port #2 | | |
| 6 | 0x01 | Configure antenna port #3 | | |
| 7 | 0x00 | Do not configure antenna port #4 | | |
| 8 | 0xFF | Maximum power for reading tag | | |
| 9 | 0x00 | Setup for dynamic environment | | |
| 10 | 0x02 | They belong to the 2 nd combined group | | |
| 11 | 0x00 | Reserved | | |
| 12 | 0x08 | Tag filter has 8 meaningful bit | | |
| 13 | 0x00 | Tag filter is always for EPC tag | | |
| 14 | 0x01 | Only read EPC 1.1 Class 0 tags | | |
| 15 | 0x00 | No power for writing RFID tag | | |
| 16 | 0x00 | LSB | | Tag filter pattern |
| 17 | 0x00 | | | |
| 18 | 0x00 | | | |
| 19 | 0x00 | | | |
| 20 | 0x00 | | | |
| 21 | 0x00 | | | |
| 22 | 0x00 | | | |
| 23 | 0x30 | MSB | | |
| 24~39 | 0x00 | Reserved | | |
| 40 | CRC | LSB of the CRC-16 | CRC | |

| | | | |
|----|-----|-------------------|--|
| 41 | CRC | MSB of the CRC-16 | |
|----|-----|-------------------|--|

Response Example:

The response packet indicates completion or error, and does not have data field.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x23 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Get Parameter Block Command (24_{hex})

Get parameters for one specific antenna port.

Command Example:

Get the parameters for the first antenna port from the reader with node address of 04_{hex}.

| Byte order | Value | Description | |
|------------|-------|--|------|
| 0 | 0x01 | SOF, Start of Frame | |
| 1 | 0x04 | RS485 network node address (0x00 ~ 0x1F) | |
| 2 | 0x06 | Packet length excludes SOF, but includes the CRC | |
| 3 | 0x24 | Command | |
| 4 | 0xA0 | Logical antenna indicator, defined as: | |
| | | Antenna port #1 | 0xA0 |
| | | Antenna port #2 | 0xB0 |
| | | Antenna port #3 | 0xC0 |
| | | Antenna port #4 | 0xD0 |
| 5 | CRC | LSB of the CRC-16 | |
| 6 | CRC | MSB of the CRC-16 | |

Response Data Block:

| Byte order | Value | Description |
|------------|-----------|--|
| 0 | 0x01~0xFF | Power level for tag reading (0x01=minimum, 0xFF=maximum) |
| 1 | 0x00~0x08 | Environment variable |
| 2 | 0x00~0x02 | Combined antenna |
| 3 | | Reserved |
| 4 | 0x00~0x3F | Tag filter pattern length |
| 5 | 0x00 | Tag type the filter applies. Always 0x00 – EPC tag |
| 6 | 0x00~0x02 | Select the air protocol class to use for reading tag |
| 7 | 0x01~0xFF | Power level for tag writing (0x01=minimum, 0xFF=maximum) |
| 8~15 | | Tag filter pattern, with LSB first |
| 16~31 | | Reserved |

These fields have the same definitions as in the Set Parameter Block Command.

Response Example:

| Byte order | Value | Description | |
|------------|-------|-------------|--|
| | | | |

| | | | |
|------|------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x26 | Packet length except SOF | |
| 3 | 0x24 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5~36 | | Response data block as defined above | Data field |
| 37 | CRC | LSB of the CRC-16 | CRC |
| 38 | CRC | MSB of the CRC-16 | |

Set Node Address Command (12_{hex})

The Host system could either broadcast a message by using node address 0xFF, or use the known address to set a reader's RS485 node address. The data section consists of one byte for the new node address, followed by the reader's serial number (8 bytes, LSByte first).

There is no response if the broadcast address 0xFF is used. Otherwise, the response packet indicates completion or error.

Command Example:

Set the node address for the reader with serial number of 0123456789ABCDEF_{hex} to 04_{hex}.

| Byte order | Value | Description | |
|------------|-------|--|---------------|
| 0 | 0x01 | SOF, Start of Frame | |
| 1 | 0xFF | RS485 network broadcast address | |
| 2 | 0x0E | Packet length excludes SOF, but includes the CRC | |
| 3 | 0x12 | Command | |
| 4 | 0x04 | New RS485 node address for this reader | |
| 5 | 0xEF | LSB | Serial Number |
| 6 | 0xCD | | |
| 7 | 0xAB | | |
| 8 | 0x89 | | |
| 9 | 0x67 | | |
| 10 | 0x45 | | |
| 11 | 0x23 | | |
| 12 | 0x01 | MSB | |
| 13 | CRC | LSB of the CRC-16 | |
| 14 | CRC | MSB of the CRC-16 | |

Response Example:

Response packet for Set Node Address command sent to node address of 04_{hex}.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x12 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | CRC |
| 5 | CRC | LSB of the CRC-16 | |
| 6 | CRC | MSB of the CRC-16 | |

Get Reader Status Command (14_{hex})

Get a 32 byte data block about a reader's system status.

Command Example:

Get the status from the READER with node address of 04_{hex}.

| Byte order | Value | Description |
|------------|-------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address (0x00 ~ 0x1F) |
| 2 | 0x05 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x14 | Command |
| 4 | CRC | LSB of the CRC-16 |
| 5 | CRC | MSB of the CRC-16 |

Response Data Block:

| Byte order | Value | Description | |
|------------|---------------------|--|-----------------------------|
| 0~7 | | Reader's serial number, with LSB first | |
| 8 | | Version number (major) | |
| 9 | | Version number (minor) | |
| 10 | | Version number (build) | |
| 11 | 0x00~0x01 | Reset flag, 0x01—has been reset, needs parameter | |
| 12 | | Combined antenna bit mask for port #1 | |
| 13 | | Combined antenna bit mask for port #2 | |
| 14 | | Combined antenna bit mask for port #3 | |
| 15 | | Combined antenna bit mask for port #4 | |
| 16 | | Antenna status bit mask for port #1 | |
| 17 | | Antenna status bit mask for port #2 | |
| 18 | | Antenna status bit mask for port #3 | |
| 19 | | Antenna status bit mask for port #4 | |
| 20 | 0x00~0x05 | Error of the last command packet | |
| | | 0x00 | No error |
| | | 0x01 | No SOF |
| | | 0x02 | Timed out |
| | | 0x03 | Bad CRC |
| | | 0x04 | Insufficient number of data |
| 0x05 | State Machine error | | |
| 21~31 | | Reserved | |

Each antenna port could connect to up to eight antennas when a multiplexer is used. So one byte is dedicated to each antenna port to represent the status of each antenna. In each byte, the least significant bit (bit 0) represents the lowest indexed antenna (antenna #1) on that port; the second bit (bit 1) represents the second antenna (antenna #2), and so on.

Response Example:

Response packet for Get Reader Status command sent to node address of 04_{hex}.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x26 | Packet length except SOF | |
| 3 | 0x14 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5~36 | | Response data block as defined above | Data field |
| 37 | CRC | LSB of the CRC-16 | CRC |
| 38 | CRC | MSB of the CRC-16 | |

Set Suspend Mode Command (18_{hex})

This command set all or a specifically addressed reader in Suspend Mode. A suspended reader only responds to a ‘Set Node Address Command’ (SR400 needs firmware version 1.0.3 or higher.)

Command Example:

Set all readers in suspend mode.

| Byte order | Value | Description |
|------------|-------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0xFF | RS485 network broadcast address |
| 2 | 0x05 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x18 | Command |
| 4 | CRC | LSB of the CRC-16 |
| 5 | CRC | MSB of the CRC-16 |

Set the reader with node address of 0x04 in suspend mode.

| Byte order | Value | Description |
|------------|-------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | 0x05 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x18 | Command |
| 4 | CRC | LSB of the CRC-16 |
| 5 | CRC | MSB of the CRC-16 |

Response Example:

There is no response if the broadcast address 0xFF is used. Otherwise, the response packet indicates completion or error.

Response packet for Set Suspend Mode command sent to node address of 04_{hex}.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x18 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Get Node Address Command (19_{hex})

Given its serial number, get a reader's RS485 node address. The data section consists of the serial number (8 bytes, LSByte first) of the READER whose address is to be retrieved (needs READER firmware version 1.0.4 or higher.)

Command Example:

Ask for the RS485 node address for a reader with serial number of 0x0123456789ABCDEF:

| Byte order | Value | Description | |
|------------|-------|--|---------------|
| 0 | 0x01 | SOF, Start of Frame | |
| 1 | 0xFF | RS485 network broadcast address | |
| 2 | 0x0D | Packet length excludes SOF, but includes the CRC | |
| 3 | 0x19 | Command | |
| 4 | 0xEF | LSB | Serial number |
| 5 | 0xCD | | |
| 6 | 0xAB | | |
| 7 | 0x89 | | |
| 8 | 0x67 | | |
| 9 | 0x45 | | |
| 10 | 0x23 | | |
| 11 | 0x01 | MSB | |
| 12 | CRC | LSB of the CRC-16 | |
| 13 | CRC | MSB of the CRC-16 | |

Response Example:

The reader with the specified serial number must response even though the request is a broadcast message. The response packet shows that the reader has the node address of 0x04.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x19 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | CRC |
| 5 | CRC | LSB of the CRC-16 | |
| 6 | CRC | MSB of the CRC-16 | |

Set Frequency Channel Command (1C_{hex})

[This command applies to Matrics FCC Part 90 Readers ONLY.]

Set the frequency channel that the reader is going to use to read tags.

Command Example:

| Byte order | Value | Description |
|------------|-----------|---|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | 0x06 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x1C | Command |
| 4 | 0x00~0x0D | The step index of the frequency channel. There are 14 steps between 914.25Mhz ~ 917.25Mhz, with each step of 500kHz |
| 5 | CRC | LSB of the CRC-16 |
| 6 | CRC | MSB of the CRC-16 |

Response Example:

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x1C | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Set Baud Rate Command (1D_{hex})

Set the baud rate for the RS485 link.

Command Example:

Set the reader with address 0x04 to use the specified baud rate.

| Byte order | Value | Description |
|---------------|-----------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | 0x06 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x1D | Command |
| 4 | 0x00~0x05 | The step index of the Baud Rate. |
| | | 0x00 230400 bps |
| | | 0x01 115200 bps |
| | | 0x02 57600 bps |
| | | 0x03 38400 bps |
| | | 0x04 19200 bps |
| 0x05 9600 bps | | |
| 5 | CRC | LSB of the CRC-16 |
| 6 | CRC | MSB of the CRC-16 |

Response Example:

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x1D | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Note: The reader needs to reboot after successful execution of this command. The Host system also needs to use the new baud rate to talk to the reader again.

Start Constant Read Command (25_{hex})

[This command applies to Matrics SR 400 Readers ONLY.]

Let a reader start to read constantly until it is told to stop by the ‘Stop Constant Read’ command.

This command should be used only if the host is capable of handling the constant amount of data returned from the reader (1 packet per time slot), and the tag population being read consists of one tag.

In this mode, the reader has four time slots and reads one tag per time slot. The dwell time parameter specifies how long a time slot is. The antenna indicator tells which antenna is used in that time slot. Antenna could be reused in different time slots. A time slot could be disabled by specifying the antenna indicator as 0x00, which means the reader will keep silent in that time slot.

If this command is used, only one Reader can be active on a RS-485 link. There is no need to set the reader parameter in advance, because all necessary parameters for this mode are included in the command to speed up this mode.

Command Example:

Every reader will be set in ‘Constant Read’ mode (B4 is special address to address every Reader). It will read up to one tag per time slot. ‘Dwell Time’ determines how long the reader will stay in each time slot.

| Byte order | Value | Description |
|------------|-----------|---|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0xB4 | Special RS485 network node address that addresses every Reader (for point-to-point applications only) |
| 2 | 0x19 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x25 | Command |
| 4 | 0xA0 | Antenna port indicator for the time slot #1 |
| 5 | 0xB0 | Antenna port indicator for the time slot #2 |
| 6 | 0xA0 | Antenna port indicator for the time slot #3 |
| 7 | 0xB0 | Antenna port indicator for the time slot #4 |
| 8 | 0x00~0xFF | Power level for antenna port #1 |
| 9 | 0x00~0xFF | Power level for antenna port #2 |
| 10 | 0x00~0xFF | Power level for antenna port #3 |
| 11 | 0x00~0xFF | Power level for antenna port #4 |
| 12 | 0x06~0x96 | DWT: Dwell time in milliseconds (10~150ms) |
| 13 | 0x00~0x10 | FCH: Frequency channel 0~16 (0–lowest frequency) |
| 14 | 0x00~0x40 | TFL: Tag filter length in bits |
| 15 | 0x00 | TFT: Tag filter type, always 0x00 – EPC type tags |
| 16 | | LSB |
| 17 | | Tag filter pattern |
| 18 | | |
| 19 | | |
| 20 | | |

| | | | |
|----|-----|-------------------|--|
| 21 | | | |
| 22 | | | |
| 23 | | MSB | |
| 24 | CRC | LSB of the CRC-16 | |
| 25 | CRC | MSB of the CRC-16 | |

Note: 'Frequency Channel' is applicable only to FCC Part 90 regulation readers.

Response Example:

There is no special response for this command. After this command is sent, the reader responds with regular data packages including Tag ID data. For example, response packet for one RFID tag read by antenna with index of 0xA0.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x11 | Packet length except SOF | |
| 3 | 0x25 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | 0xA0 | Antenna indicator | Data field |
| 6 | 0x01 | Number of tags in this packet | |
| 7 | 0x10 | 12 bytes EPC tag | |
| 8~19 | | 12 bytes hexadecimal tag ID with LSB first | |
| 20 | CRC | LSB of the CRC-16 | CRC |
| 21 | CRC | MSB of the CRC-16 | |

Stop Constant Read Command (26_{hex})

[This command applies to Matrics SR 400 Readers ONLY.]

This command stops the constant read initiated by the above command.

Command Example:

Every reader's 'Constant Read' mode will be stopped.

| Byte order | Value | Description |
|------------|-------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0xB4 | Special RS485 network node address |
| 2 | 0x05 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x26 | Command |
| 4 | CRC | LSB of the CRC-16 |
| 5 | CRC | MSB of the CRC-16 |

Response Example:

The Host system should wait for the final packet with the status indicating the complete of the command execution.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address (returns the internal address of the reader, even if the command was issued with B4 address) | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x25 | Mirror of the Start Const Read Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Set System Parameter Command (27_{hex})

There are some system specific configurable parameters. They can be identified by its index, and their values can be changed accordingly. The parameter value is always a two byte field, and with the LSB first in the packet. ($VAL = (VAL_{MSB} \ll 8) + VAL_{LSB}$).

These are currently supported parameter index and values:

| Parameter Index | Description | Parameter Values |
|-----------------|--|-------------------------|
| 0x01 | Light indicator box <i>[SR 400 ONLY]</i> | 0—disabled 1—enabled |
| 0x03 | Reflected power threshold (VSWR) <i>[RDR-IP-0xx ONLY]</i> | 0x00~0x3E8 |
| All others | Reserved | |

Command Example:

| Byte order | Value | Description |
|------------|-----------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | 0x08 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x27 | Command |
| 4 | 0x01/0x03 | Parameter index |
| 5 | | Parameter Value LSB |
| 6 | | Parameter Value MSB |
| 7 | CRC | LSB of the CRC-16 |
| 8 | CRC | MSB of the CRC-16 |

Response Example:

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x27 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Read With Payload Command (31_{hex})

SR400 Reader needs firmware versions 2.2.1 and above.

This command is designed for getting the user data field from Class 0+ tags. It has similar formation to the 'Read Full Field' command (22_{hex}), but with some extras:

- Fields in the request packet specifying an optional bit pattern tag filter

The request command can specify a bit pattern tag filter to selectively read tags. Following fields carry this information:

| Field Name | Size (Bytes) | Description |
|------------|-----------------------|---|
| IDLEN | 1 | The number of significant bits in the tag filter bit pattern. IDLEN=0 means no pattern is provided in this command, so all tags in the field will be read and returned. |
| IDTYPE | 1 | Optional, only exists when IDLEN is not zero, and the value should always be 0x00. |
| IDBYTES | $N = ((IDLEN-1)/8)+1$ | Variable length field with N bytes indicating the tag filter bit pattern, with the MSB first. These bytes only exist, and N is calculated when IDLEN is not zero. |

- Fields in the request packet specifying how many user data bits are requested

Class 0+ tags could have up to 104 bits extra user data. Following fields specify where the requested data starts, and how many bits in this 104 bits data should be returned:

| Field Name | Size (Bytes) | Description |
|--------------------|--------------|--|
| Start bit position | 1 | The start bit position in this 104 bits user data (0x00~0x67) |
| Bit length | 1 | The number of bits should be returned from the start bit (0x00~0x68). Entire field is read and validated, but only requested portion is returned |

- Fields in the response packet specifying the extra user data bits in the tag.

Following fields carry the returned user data bits:

| Field Name | Size (Bytes) | Description |
|------------------|------------------------------------|--|
| Data bits length | 1 | The number of significant bits in the returned user data field. |
| DataBytes | $N = ((Data\ bits\ length-1)/8)+1$ | Variable length field with N bytes indicating the user data field in the tag, with the LSB first. These user data bits are LSbit justified. These bytes only exist, and N is calculated when 'Data bits length' is not zero. |

Command Example:

Let reader with node address of 0x04 and using antenna 0xA0 return Tag ID and user data bits from all of the RFID tags in its field.

| Byte order | Value | Description |
|------------|-------|---|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | 0x0A | Packet length excludes SOF, but includes the CRC |
| 3 | 0x31 | Command |
| 4 | 0xA0 | Antenna port indicator |
| 5 | 0x00 | IDLEN=0, tag filter is not used, so read all tags |
| 6 | 0x00 | IDTYPE, always=0 |
| 7 | 0x00 | The user data starts from the first bit |
| 8 | 0x68 | The user data has 104(0x68) bits |
| 9 | CRC | LSB of the CRC-16 |
| 10 | CRC | MSB of the CRC-16 |

Response Example:

The data response to this command is similar to that for the command 0x22, except the extra fields for each tag's user data value. The user data field is right justified in a variable number of bytes, with LSB first. The final status response is the same as for the command 0x22.

For example, if two RFID tags are read, their tags IDs in hexadecimal are:

| No. | Tag ID | Tag user data |
|-----|---------------------------------------|------------------------------|
| 1 | 0x89,00,64,02,46,00,00,00 | 0x00112233445566778899AABBCC |
| 2 | 0x20,69,80,C0,00,21,26,04,59,80,00,00 | 0xFFEEDD33445566778899AABBCC |

Then the response packet carrying these two tag IDs is:

| Byte order | Value | Description | | | |
|------------|-------|---|---|------------------------|-------------------------|
| 0 | 0x01 | SOF, Start of Frame | | Response packet header | |
| 1 | 0x04 | RS485 network node address | | | |
| 2 | 0x3A | Packet length except SOF | | | |
| 3 | 0x31 | Mirror of the Command | | | |
| 4 | 0x01 | Status, could be 0x41 is parameter has not been set | | | |
| 5 | 0xA0 | Mirror of the Logical antenna indicator | | Data field | |
| 6 | 0x02 | Number of tags in this packet | | | |
| 7 | 0x00 | 8 bytes EPC tag | Type indicator | | The 1 st Tag |
| 8 | 0x00 | LSB | Tag ID in hexadecimal, with the LSB first | | |
| 9 | 0x00 | | | | |
| 10 | 0x00 | | | | |
| 11 | 0x46 | | | | |
| 12 | 0x02 | | | | |
| 13 | 0x64 | | | | |
| 14 | 0x00 | | | | |

| | | | | | |
|----|------|-------------------|----------------|--|--|
| 15 | 0x89 | MSB | | Tag user data, right justified, in hexadecimal, with the LSB first | |
| 16 | 0x68 | Data bits length | | | |
| 17 | 0xCC | LSB | | | |
| 18 | 0xBB | | | | |
| 19 | 0xAA | | | | |
| 20 | 0x99 | | | | |
| 21 | 0x88 | | | | |
| 22 | 0x77 | | | | |
| 23 | 0x66 | | | | |
| 24 | 0x55 | | | | |
| 25 | 0x44 | | | | |
| 26 | 0x33 | | | | |
| 27 | 0x22 | | | | |
| 28 | 0x11 | | | | |
| 29 | 0x00 | MSB | | The 2 nd Tag | |
| 30 | 0x10 | 12 bytes EPC tag | Type indicator | | |
| 31 | 0x00 | LSB | | | |
| 32 | 0x00 | | | | |
| 33 | 0x80 | | | | |
| 34 | 0x59 | | | | |
| 35 | 0x04 | | | | |
| 36 | 0x26 | | | | |
| 37 | 0x21 | | | | |
| 38 | 0x00 | | | | |
| 39 | 0xC0 | | | | |
| 40 | 0x80 | | | | |
| 41 | 0x69 | | | | |
| 42 | 0x20 | MSB | | | |
| 43 | 0x68 | Data bits length | | Tag user data, right justified, in hexadecimal, with the LSB first | |
| 44 | 0xCC | LSB | | | |
| 45 | 0xBB | | | | |
| 46 | 0xAA | | | | |
| 47 | 0x99 | | | | |
| 48 | 0x88 | | | | |
| 49 | 0x77 | | | | |
| 50 | 0x66 | | | | |
| 51 | 0x55 | | | | |
| 52 | 0x44 | | | | |
| 53 | 0x33 | | | | |
| 54 | 0xDD | | | | |
| 55 | 0xEE | | | | |
| 56 | 0xFF | MSB | | | |
| 57 | CRC | LSB of the CRC-16 | | CRC | |
| 58 | CRC | MSB of the CRC-16 | | | |

Please see the definition of command 0x22 for the sample of the final status packet.

Kill Specific (32 hex)

Kills and optionally erase fields of a specific RFID tag in the field of the addressed READER.

Command Example:

Reader with node address 0x04 and using antenna 0xA0 is to kill a specific RFID tag in its field.

| Byte order | Value | Description |
|------------|-----------|---|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | 0x13/0x17 | Packet length excludes SOF, but includes the CRC |
| 3 | 0x32 | Command |
| 4 | 0xA0 | Antenna port indicator |
| 5 | 0x00/0x10 | The type of the tag: 0x00 – 8 bytes EPC tag 0x10 – 12 bytes EPC tag |
| +8/+12 | | Tag ID value (8 or 12 bytes long), with LSB first |
| +3 | | 3 bytes kill code, with MSB first. (class 1 kill code is positioned in the LSB) |
| +1 | 0x00~0x02 | Specifies if any fields are to be erased before the tag is killed. Specified by: Bit 0: =1 – erase tag ID Bit 1: =1 – erase user data |
| +1 | CRC | LSB of the CRC-16 |
| +1 | CRC | MSB of the CRC-16 |

Response Example:

Response packets for when the RFID tag was killed by antenna with index 0xA0.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x32 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | | Error code for the kill operation | CRC |
| 6 | CRC | LSB of the CRC-16 | |
| 7 | CRC | MSB of the CRC-16 | |

Write Tag (33_{hex})

SR400 Reader needs firmware versions 2.2.1 or higher.

Writes (or rewrites) any or all fields (tag ID, user data and kill code) of a specific RFID tag. Options are selected via parameter flags providing a wide variety of useful combinations.

The options are:

| Options | Description | | | | | | | | | | | | | | | |
|----------------|---|-------------------------|------------|-------------|---|----------|------------------|---|------------|-------------------------|------------|------------|---------------------|------------|--|---------------------|
| IDTYPE | <p>This specifies the encoding scheme. The reader will correctly position, size, and CRC protect the ID field appropriately based on the encoding scheme and the 'current' class mode (class 0 or class 1) of operation. An unknown encoding type will cause the command to fail.</p> <p>0x00 -- 8 bytes (64 bits) EPC Tag ID 0x10 -- 12 bytes (96 bits) EPC Tag ID</p> | | | | | | | | | | | | | | | |
| ERASEOPTIONS | <p>Its bits specify which, if any, fields to be erased before the tag is killed.</p> <table border="1"> <thead> <tr> <th>Bit order</th> <th>Field name</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>ERASE_ID</td> <td>=1, erase tag ID</td> </tr> <tr> <td>1</td> <td>ERASE_DATA</td> <td>=1, erase tag user data</td> </tr> <tr> <td>All others</td> <td></td> <td>Reserved, always =0</td> </tr> </tbody> </table> <p>Previously written or locked fields can not be erased.</p> | Bit order | Field name | Description | 0 | ERASE_ID | =1, erase tag ID | 1 | ERASE_DATA | =1, erase tag user data | All others | | Reserved, always =0 | | | |
| Bit order | Field name | Description | | | | | | | | | | | | | | |
| 0 | ERASE_ID | =1, erase tag ID | | | | | | | | | | | | | | |
| 1 | ERASE_DATA | =1, erase tag user data | | | | | | | | | | | | | | |
| All others | | Reserved, always =0 | | | | | | | | | | | | | | |
| WRITEOPTIONS | <p>Specifies which, if any, fields to be written during this operation.</p> <table border="1"> <thead> <tr> <th>Bit order</th> <th>Field name</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>WRITE_ID</td> <td>=1, write tag ID</td> </tr> <tr> <td>1</td> <td>WRITE_DATA</td> <td>=1, write tag user data</td> </tr> <tr> <td>2</td> <td>WRITE_KILL</td> <td>=1, write kill</td> </tr> <tr> <td>All others</td> <td></td> <td>Reserved, always =0</td> </tr> </tbody> </table> | Bit order | Field name | Description | 0 | WRITE_ID | =1, write tag ID | 1 | WRITE_DATA | =1, write tag user data | 2 | WRITE_KILL | =1, write kill | All others | | Reserved, always =0 |
| Bit order | Field name | Description | | | | | | | | | | | | | | |
| 0 | WRITE_ID | =1, write tag ID | | | | | | | | | | | | | | |
| 1 | WRITE_DATA | =1, write tag user data | | | | | | | | | | | | | | |
| 2 | WRITE_KILL | =1, write kill | | | | | | | | | | | | | | |
| All others | | Reserved, always =0 | | | | | | | | | | | | | | |
| DATAWRITEMODES | <p>Specifies how the Data Write is performed. (Currently not used – set to 0 if WRITE_DATA is used.</p> | | | | | | | | | | | | | | | |
| LOCKOPTIONS | <p>Specifies which, if any, fields to be locked in this operation.</p> <table border="1"> <thead> <tr> <th>Bit order</th> <th>Field name</th> <th>Description</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>LOCK_ID</td> <td>=1, lock tag ID</td> </tr> <tr> <td>1</td> <td>LOCK_DATA</td> <td>=1, lock tag user data</td> </tr> <tr> <td>2</td> <td>LOCK_KILL</td> <td>=1, lock kill</td> </tr> <tr> <td>All others</td> <td></td> <td>Reserved, always =0</td> </tr> </tbody> </table> <p>NOTE: ONCE A FIELD IS LOCKED IT CAN NOT BE ERASED OR WRITTEN FURTHER.</p> | Bit order | Field name | Description | 0 | LOCK_ID | =1, lock tag ID | 1 | LOCK_DATA | =1, lock tag user data | 2 | LOCK_KILL | =1, lock kill | All others | | Reserved, always =0 |
| Bit order | Field name | Description | | | | | | | | | | | | | | |
| 0 | LOCK_ID | =1, lock tag ID | | | | | | | | | | | | | | |
| 1 | LOCK_DATA | =1, lock tag user data | | | | | | | | | | | | | | |
| 2 | LOCK_KILL | =1, lock kill | | | | | | | | | | | | | | |
| All others | | Reserved, always =0 | | | | | | | | | | | | | | |

Note:

- Currently only the WRITEOPTIONS of WRITE_ID and WRITE_DATA are supported. And none of the LOCKOPTIONS are supported.
- The Air protocol class (EPC 1.1 Class 0/Class 1) is determined by the set parameter block command.

Command Example:

READER with node address of 04_{hex} and using antenna A0_{hex} is to perform a write oriented operation on a specific RFID tag in its field.

| Byte order | Value | Description |
|------------|-----------|--|
| 0 | 0x01 | SOF, Start of Frame |
| 1 | 0x04 | RS485 network node address |
| 2 | | Packet length excludes SOF, but includes the CRC |
| 3 | 0x33 | Command |
| 4 | 0xA0 | Antenna port indicator |
| 5 | 0x10 | IDTYPE, 12 bytes EPC tag |
| 6 | 0x00~0x68 | IDLEN, the number of significant bits to match in the pattern. 0 means no pattern is provided, so ALL tags in field will be addressed. |
| 7~18 | | IDBITS(byte length determined by IDTYPE): The ID to be written into a tag or the tag ID used to singulate a tag when writing user data or kill fields. |
| 19 | | ERASEOPTIONS |
| 20 | | WRITEOPTIONS |
| [+3] | | [KILLCODE] Optional. 3 bytes MSB...LSB (class 1 kill code is positioned in the LSB), Only present when WRITE_KILL has been specified |
| [+1] | | [DATAWRITEMODES] Optional. 1 byte, only present when WRITE_DATA is specified |
| [+1] | | [DATABITLEN] Optional. 1 byte, only present when WRITE_DATA is specified |
| [+0~13] | | [DATABYTES] 0~13 bytes of data based on DATABITLEN ((DATABITLEN-1)/8)+1 (data is padded with zeros as appropriate on tag) |
| [+1] | 0x00~0x68 | [DATABITPOS] representing the bit offset within the data field to start the write, only present when WRITE_DATA is specified |
| +1 | | LOCKOPTIONS: 1 byte |
| +1 | CRC | LSB of the CRC-16 |
| +1 | CRC | MSB of the CRC-16 |

Response Example:

Response packets for when the RFID tag was written by antenna with index 0xA0.

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x33 | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | | ErrCode0: global error code | Data field |
| 6 | | ErrCode1: write page 0 error code | |
| 7 | | ErrCode2: write page 2 error code | |
| 8 | | ErrCode3: write page 3 error code | |

| | | | |
|----|-----|-----------------------------------|-----|
| 9 | | ErrCode4: erase page 0 error code | |
| 10 | | ErrCode5: erase page 2 error code | |
| 11 | | ErrCode6: erase page 3 error code | |
| 12 | | ErrCode7: lock page 0 error code | |
| 13 | | ErrCode8: lock page 2 error code | |
| 14 | | ErrCode9: lock page 3 error code | |
| 15 | CRC | LSB of the CRC-16 | CRC |
| 16 | CRC | MSB of the CRC-16 | |

Here is the description of all error codes:

| Error code | Description |
|------------|-------------------------|
| 0xE8 | Page 3 verify error |
| 0xE9 | Page 2 verify error |
| 0xEB | Read user data error |
| 0xEC | Bit read error |
| 0xED | Bit write inhibit error |
| 0xEE | Bit write error |
| 0xEF | Skip bit error |
| 0xF0 | Page 3 write error |
| 0xF1 | Page 2 write error |
| 0xF2 | Page 0 write error |
| 0xF3 | Page 3 erase error |
| 0xF4 | Page 2 erase error |
| 0xF5 | Page 0 erase error |
| 0xF6 | Page 3 lock error |
| 0xF7 | Page 2 lock error |
| 0xF8 | Page 0 lock error |
| 0xF9 | No tag response error |
| 0xFA | Command error |
| 0xFB | CRC error |
| 0xFC | Traversal error |
| 0xFD | Invalid page error |
| 0xFE | No page to program |
| 0xFF | Wrong ID type |
| 0 | No error |
| 1 | Function not executed |

Set Light Indicator (3A_{hex})

Only supported by AR400 Reader with firmware version 3.7.3 or higher.

The DC-400 Light Indicator Box has four lights (red and green lights on both right and left sides) can be turned on or off by this command.

Command Example:

For the reader with node address of 04_{hex},

- turn on the left green light for one second
- turn on the right green light indefinitely, until it is explicitly turned off by another command
- turn off the left red light

| Byte order | Value | Description | | | | | | | | | | | | | | | | | | |
|------------|-----------------------|---|------------------------|------------|---|----------|---|----------------------|---|----------|---|------------------------|---|---------------------|---|----------|---|-----------------------|---|----------|
| 0 | 0x01 | SOF, Start of Frame | | | | | | | | | | | | | | | | | | |
| 1 | 0x04 | RS485 network node address | | | | | | | | | | | | | | | | | | |
| 2 | 0x0A | Packet length excludes SOF, but includes the CRC | | | | | | | | | | | | | | | | | | |
| 3 | 0x3A | Command | | | | | | | | | | | | | | | | | | |
| 4 | 0x58 | Light selection mask, its bits determines which light(s) will be affected by this command. Set the bit value to “1” to select the light. All reserved bits should always set as “0”. | | | | | | | | | | | | | | | | | | |
| | | <table border="1"> <thead> <tr> <th>Bit order</th> <th>Definition</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>Reserved</td> </tr> <tr> <td>1</td> <td>Right side red light</td> </tr> <tr> <td>2</td> <td>Reserved</td> </tr> <tr> <td>3</td> <td>Right side green light</td> </tr> <tr> <td>4</td> <td>Left side red light</td> </tr> <tr> <td>5</td> <td>Reserved</td> </tr> <tr> <td>6</td> <td>Left side green light</td> </tr> <tr> <td>7</td> <td>Reserved</td> </tr> </tbody> </table> | Bit order | Definition | 0 | Reserved | 1 | Right side red light | 2 | Reserved | 3 | Right side green light | 4 | Left side red light | 5 | Reserved | 6 | Left side green light | 7 | Reserved |
| | | Bit order | Definition | | | | | | | | | | | | | | | | | |
| | | 0 | Reserved | | | | | | | | | | | | | | | | | |
| | | 1 | Right side red light | | | | | | | | | | | | | | | | | |
| | | 2 | Reserved | | | | | | | | | | | | | | | | | |
| | | 3 | Right side green light | | | | | | | | | | | | | | | | | |
| | | 4 | Left side red light | | | | | | | | | | | | | | | | | |
| | | 5 | Reserved | | | | | | | | | | | | | | | | | |
| 6 | Left side green light | | | | | | | | | | | | | | | | | | | |
| 7 | Reserved | | | | | | | | | | | | | | | | | | | |
| 5 | 0x48 | Light action mask, with the same bit definition as the above Light selection mask. Set the bit value to “1” to turn it on, and “0” to turn it off. All reserved bits should always set as “0”. | | | | | | | | | | | | | | | | | | |
| 6 | 0x00 | Two optional time out fields. <ul style="list-style-type: none"> • For each bit set in the above action mask, there is a corresponding time out field which is two byte long, with MSB first. • The first time out field corresponds to the least significant bit that is set to “1” in the action mask. • The number in this field is in the unit of one hundred of millisecond, indicating how long the light will stay on. | | | | | | | | | | | | | | | | | | |
| 7 | 0x00 | | | | | | | | | | | | | | | | | | | |
| 8 | 0x00 | | | | | | | | | | | | | | | | | | | |
| 9 | 0x0A | | | | | | | | | | | | | | | | | | | |
| 10 | CRC | LSB of the CRC-16 | | | | | | | | | | | | | | | | | | |
| 11 | CRC | MSB of the CRC-16 | | | | | | | | | | | | | | | | | | |

Response Example:

| Byte order | Value | Description | |
|------------|-------|---|------------------------|
| 0 | 0x01 | SOF, Start of Frame | Response packet header |
| 1 | 0x04 | RS485 network node address | |
| 2 | 0x06 | Packet length except SOF | |
| 3 | 0x3A | Mirror of the Command | |
| 4 | 0x00 | Status: complete, =0x40 if parameter has not been set | |
| 5 | CRC | LSB of the CRC-16 | CRC |
| 6 | CRC | MSB of the CRC-16 | |

Appendix A. XML Error Messages and Resolutions

User Messages

Access Denied - Non-trusted Host

Cause: The machine that is attempting access is not set up as a Trusted Host in the system.

Resolution: Add the IP address to the Trusted Host list, or disable Trusted Host check.

Operation failed.

Cause: A user operation did not complete, typically due to invalid input.

Resolution: Validate all of your inputs, and then retry the operation. If it is not successful, contact Matrics Customer Support at 410-872-0300.

You have entered an invalid User Name and/or Password - Try again.

Cause: The User Name and/or password that you typed are not found in the system, or do not match the current user registry.

Resolution: Retype your login information to ensure its accuracy. If it is not successful, contact your site's System Administrator to add/edit your user account.

Your session has Timed-out - Log in again.

Cause: The current session was inactive beyond the timeout period, so the system automatically logged you out.

Resolution: Log in again. As a security precaution to protect against unauthorized system access, you should always log out of the system when you are done using it.

Invalid Name.

The User Name is not correct.

Cause: The User Name that you typed does not match the current user registry (may be illegal characters, too long, too short, unknown or duplicate.)

Resolution: Retype your User Name to ensure its accuracy.

The user name has already been used.

Cause: The User Name is a duplicate (when adding a new user to the user registry.)

Resolution: Retype a new User Name.

Not a legal IP address (1.0.0.0 - 255.255.255.255).**The Host Link is not valid.****Cannot reach the specified IP Address.****The SNMP Host Link is not valid.**

Cause: The IP address that you entered is either formatted inaccurately or cannot be accessed (pinged.)

Resolution: Correct any typos in the IP address, and make sure your Host device is connected and online.

Invalid network mask.

Cause: The network mask that you entered is formatted inaccurately.

Resolution: Make sure you get the correct network mask from the network administrator and type it in correctly.

Invalid SNMP version number.

Cause: The version number for SNMP protocol is not a supported version.

Resolution: Use version number 1 for SNMP version 1, and 2 for SNMP version 2c.

Invalid Serial Number (0000-0000-0000-0000).

Cause: The serial number that you entered is formatted inaccurately.

Resolution: Correct any typos in the serial number.

Invalid Description.

Cause: The description you entered contains invalid characters (<, >, or ').

Resolution: Remove the invalid characters to correct the description.

Invalid Password.

Cause: The password that you typed does not match the current user registry (may be illegal characters, too long, or too short.)

Resolution: Retype your password to ensure its accuracy.

Cannot delete the admin user account.

Cause: You may have tried to delete the “admin” user account.

Resolution: No action. The operation is ignored because the system will not allow deletion of this user account.

Cannot delete local Host Address.

Cause: You may have tried to delete the 127.0.0.1 IP address.

Resolution: No action. The operation is ignored because the system will not allow deletion of this IP address.

Cannot delete the IP address of the active session host.

- Cause:** You may have tried to delete the IP address of the host that has the current active session.
- Resolution:** No action. The operation is ignored because the system will not allow deletion of this IP address.

The IP address is still used in ReaderNetwork configuration.

- Cause:** You may have tried to delete the IP address that has been automatically added in the trusted hosts database for a reader network device.
- Resolution:** No action. The operation is ignored because the system will not allow deletion of this IP address.

Cannot modify Default zone.

- Cause:** The Default read point zone cannot be modified.
- Resolution:** No action. The operation is ignored because the system will not allow modification of the Default zone.

Cannot modify the default tag filter ALL.

- Cause:** The default tag filter “ALL” cannot be modified.
- Resolution:** No action. The operation is ignored because the system will not allow modification of the tag filter “ALL”.

This Name has already been used. This Serial Number has already been used. This IP Address has already been used.

- Cause:** The Name, Serial Number, or IP Address that you entered already exists in the system.
- Resolution:** Type a unique value for the new Name, Serial Number, or IP Address.

You must select an item from the list.

- Cause:** The system requires that you select an item from the list box before continuing.
- Resolution:** Select an item from the list box, and then continue.

Last command is still pending. Try again later.

- Cause:** The system has not completed processing the previous command.
- Resolution:** Wait a few moments for the previous command to complete, before sending another command.

Another Administrator is currently logged in. Try again later.

- Cause:** The system will not allow more than one Administrator to log in at a time.
- Resolution:** Wait until the other Administrator logs out (or times-out) before you log in.

Backup configuration file does not exist.

Cause: The system cannot revert to a backup of the current configuration unless a backup file exists.

Resolution: Commit the new configuration to create a backup file.

Failed to confirm the new Password.

Cause: The system requires that you type your password identically two times.

Resolution: Retype your password twice to ensure its accuracy.

Reader Network configuration change(s) have not been saved.

Cause: The user has requested to log out prior to committing/reverting the changes made during their session.

Resolution: Select one of the Commit/Revert options.

The new Password is the same as the old one.

Cause: The system requires that you type a new password (that is different from your existing password) during the Change Password operation.

Resolution: Type a new password that is different from your existing password.

The old Password is not correct.

Cause: The system requires that you correctly type your existing password during the Change Password operation.

Resolution: Retype your existing password to ensure its accuracy.

Commit Accepted - Configuration Changes are queued for action.

Discard Accepted - Configuration reverted to last committed version.

Revert Accepted - Configuration reverted to backup version.

Command Accepted - All 'On Demand' scans queued.

Command Accepted - Polling is Enabled.

Command Accepted - Polling is Disabled.

Operation was Successful.

Cause: You asked the system to perform a function.

Resolution: No action required. The system is reporting that your request was accepted.

Unspecified error occurred - code: ####

Cause: A specific error message is missing for the given status code.

Resolution: Note the code number, and contact Matrics Customer Support at 410-872-0300.

The page that you requested was not found.

Internal Web Server Error.

Cause: The system experienced an internal web server error.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Internal Messages

Request method was NULL. No query string was provided.

Cause: The system does not permit a proxy program to be executed from the command line rather than the web server.

Resolution: No action required. The system is reporting that this action is not permitted.

Content length is unknown.

Cause: The system cannot accept an incorrectly formatted HTTP POST request (from an unsupported Browser application.)

Resolution: Use a GET request instead, or update your software.

Couldn't read complete post message.

Cause: The system stopped a POST operation before completion.

Resolution: Retry the operation, and allow it to complete.

Unhandled reply type.

Cause: The system generated an unexpected value.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Failed to open port.

Failed to connect.

Failed to transmit.

Failed to receive.

Error during Receive of Command.

Cause: The system experienced an internal network failure.

Resolution: Contact Matrics Customer Support at 410-872-0300.

DB open failed.

DB put failed.

DB get failed.

DB delete failed.

Cause: The system experienced internal database errors. If you have recently installed the system, this error may be a configuration problem (open permissions.) If the system has been operational for a while, this error may be due to a full or corrupt database. This error may also be caused by disk failure.

Resolution: Contact Matrics Customer Support at 410-872-0300.

FIFO open failed.

Cause: The system experienced an internal communication failure.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Invalid Read Point Type.

Invalid Read Point Scan Period.

Invalid tag category.

Invalid value for the header field of EPC tag.

Invalid value for the manager field of EPC tag.

Invalid value for the class field of EPC tag.

Invalid User Access value.

The option is not valid.

Cause: The system does not recognize the value that you entered, or requires you to make a menu selection.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Invalid Device Address.

Cause: The device address info (parent) is invalid, missing, or formatted inaccurately.

Resolution: Retry the operation. If it is not successful, contact Matrics Customer Support at 410-872-0300.

The size of command over limit.

The size of value over limit.

Too many command/value pairs.

Cause: The command input has exceeded some internal limit.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Command parsing state error.

Missing argument for the command.

Command internal type case error.

Missing operator.

Unknown operator.

Cause: A command has been formatted inaccurately.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Failed to register the Read Point.

Failed to unregister the Read Point.

Failed to unregister the Reader.

Cause: The system could not process the item as intended.

Resolution: Contact Matrics Customer Support at 410-872-0300.

Cannot find Read Point Class.
Cannot find Reader.
Cannot find Read Point Zone.
Converter was not found.
Cannot find the Event.
Cannot find the Read Point.
Cannot find the specified Reader Port.
Cannot find the specified Host Address.
Cannot find the specified Tag Filter.
Cannot find the specified Read Point Zone.

Cause: The system could not find (or process) the item as intended.

Resolution: Retry the operation. If it is not successful, contact Matrics Customer Support at 410-872-0300.

The reader is not empty.

Cause: The device cannot be deleted if it is not empty.

Resolution: Delete all children devices at first.

The action must be confirmed.

Cause: The user must confirm the requested action before it is executed.

Resolution: Select the confirmation option.