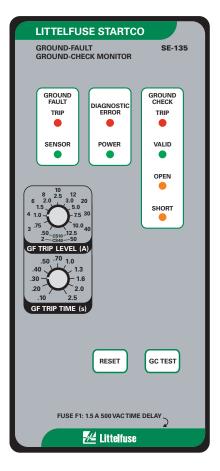


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SE-135 MANUAL

GROUND-FAULT GROUND-CHECK MONITOR

REVISION 3-C-100314



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SE-135 Ground-Fault Ground-Check Monitor

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1. GENERAL

The SE-135 is a microprocessor-based, combination ground-fault and ground-wire monitor for resistancegrounded systems. It has a switching power supply that accepts a wide range of ac and dc voltages, and its specifications apply over an industrial temperature range at high humidity. The SE-135 meets the IEEE surgewithstand-capability tests (oscillatory and fast transient) for protective relays and relay systems. Isolated, normally open and normally closed contacts are provided for contactor control or for shunt or undervoltage operation in a breaker-trip circuit. All operating conditions are clearly annunciated and two Form C contacts are provided for remote indication. The SE-135 is housed in an anodized extruded-aluminum enclosure, and all connections are made with plug-in, wire-clamping terminal blocks. Provision is made for both panel and surface mounting.

The ground-fault circuit detects fundamentalfrequency, zero-sequence current with a window-type current sensor and it verifies that the current sensor is connected and not shorted. A definite-time characteristic with 11 trip levels and 11 trip times allows coordination in virtually any resistance-grounded system. Although other current sensors may satisfy the verification circuit, only SE-CS10-series and SE-CS40-series sensors have characteristics that meet system specifications. Currentsensor verification can be disabled for a ground-checkonly application.

The ground-check circuit has an open-circuit voltage of 30 Vdc, which is not a hazard to personnel, and it has an output drive current above 100 mA for optimum performance in slip-ring, commutated-load, and highinduced-ac applications. Features include an externally accessible ground-check fuse, a resistance-insertion test, 3-kV isolation between the ground-check loop and the monitor electronics, and a PPI-600V accessory for parallel-ground-path rejection. A PPI-600V will also eliminate intermachine arcing and prevent stray ac and dc currents from flowing in the monitored ground wire. Unlike ground-check circuits using other termination devices, and especially those with phase-reversal switches, a ground-check circuit using a termination device with a Zener characteristic is capable of loop measurements that are independent of current in the phase conductors. The SE-135 ground-check circuit recognizes the SE-TA12A-series 12-volt Zener characteristic as a valid end-of-line completion. This is the only passive characteristic that will satisfy the ground-check circuit's multi-level drive, allow induced currents to circulate in the ground-check loop, survive a phase-to-ground-check fault, and clamp the ground-check voltage during the fault. Although a standard 12-volt Zener diode may engage the SE-135's ground-check circuit, only an

SE-TA12A-series termination assembly has the compensation required to meet system specifications.

2. OPERATION

2.1 GROUND-FAULT CIRCUIT

2.1.1 GF TRIP TIME SETTING

The ground-fault circuit has a definite-time characteristic with 11 settings from 0.1 to 2.5 seconds. Time-coordinated ground-fault protection requires the trip time to be longer than the trip time of downstream ground-fault devices.

2.1.2 GF TRIP LEVEL SETTING

The trip level of the ground-fault circuit is switch selectable with 11 settings from 0.5 to 12.5 A for the SE-CS10-series CT and from 2 to 50 A for the SE-CS40-series CT. A minimum tripping ratio of five is recommended to achieve at least 80% winding protection, and this requires the trip level to be no more than 20% of the grounding-resistor let-through current. A ground-fault trip is latched, requiring a reset. A current-sensor failure will also cause a ground-fault trip. See Section 3.1.

If the SE-135 is operated in a ground-check-only application and an SE-CS10 is not connected, connect terminals 17 and 18 to disable sensor verification. See Fig. 1.

2.2 GROUND-CHECK CIRCUIT

The ground-check loop consists of the outgoing ground-check conductor, quick-coupler connections, the SE-TA12A-series termination assembly, the SE-TA12A connection to equipment frame or ground bus, the ground-return path, and the SE-135 cable-ground-terminal connection to substation ground.

The SE-135 detects a valid ground-check loop when an SE-TA12A-series termination assembly is detected in the loop and loop resistance is less than 28 ohms (45 ohms for XGC option). The loop is not valid if open (or high resistance), or if the ground-check conductor is shorted to ground.

When the ground-check loop is valid, the SE-135 ground-check circuit can be tested by pressing the GC TEST button or by shorting GC TEST terminals 11 and 12. This test invalidates the loop by inserting 47 ohms (75 ohms for XGC option) in the ground-check loop and a trip should occur in less than 250 ms.

The ground-check circuit is usually operated in the non-latching mode; however, it can be operated in the latching mode by connecting terminals 14 and 15.

The ground-check circuit is protected by a 1.5-A timedelay fuse (F1).

If the SE-135 is used in a ground-fault-only application, an SE-TA12A must be connected to the

ground-check and cable-ground terminals to validate the ground-check circuit. See Fig. 1.

The typical maximum distance of a trailing cable is 5.0 km (3.1 miles) for the standard model and up to 10 km (6.3 miles) for the XGC option. Several factors may limit the maximum distance of the cable, including the ground-check wire gauge, and induced ac current in the ground-check loop.

2.3 RESET

All ground-fault trips are latching and ground-check trips can be latching or non-latching. To reset ground-fault trips or latching ground-check trips, press the RESET button or connect the RESET terminals 9 and 10. See Fig. 1.

Cycling the supply voltage will also reset ground-fault trips; however, if the ground-check circuit is configured for latching fail-safe operation, the ground-check circuit will trip when supply voltage is applied.

The single-shot reset circuit responds only to a momentary closure; a jammed or shorted button will not maintain a reset signal. The front-panel RESET button is inoperative when remote-reset terminals 9 and 10 are connected. See Section 4.5.

2.4 TRIP RELAY

Isolated, normally open (Trip A, terminals 24 and 25) and normally closed (Trip B, terminals 22 and 23) contacts are provided for use in a contactor- or breaker-control circuit. With no connection between terminals 12 and 13, the SE-135 trip relay operates in the fail-safe mode. This mode is used with undervoltage devices where the trip relay energizes and its normally open contact closes if the ground-fault and ground-check circuits are not tripped. This mode is recommended because:

- Undervoltage devices release if supply voltage fails.
- Undervoltage ground-check circuits do not allow the power circuit and open cable couplers to be energized until the ground-check loop is verified.

The fail-safe mode of operation of the SE-135 trip relay can be used for shunt-trip circuits with a storedenergy trip source. In this case, the normally closed trip contact is used—the contact opens when the SE-135 is energized and the ground-fault and ground-check circuits are not tripped. Care must be taken to ensure safe and correct operation during power up and power down.

Connect terminals 12 and 13 for non-fail-safe trip relay operation with shunt-trip devices. In this mode, the normally open trip contact is used—the trip contact is closed when a ground-fault or ground-check trip occurs.

Shunt-trip circuits are not fail-safe and are not recommended because:

• Shunt-trip devices do not operate if supply voltage fails.

• Shunt-trip ground-check circuits allow the power circuit and open cable couplers to be energized for a short interval after supply voltage is applied.

CAUTION: The SE-135 is not a lock-out device. Follow lock-out procedures for maintenance.

2.5 NETWORK COMMUNICATIONS

An IEEE 802.3 port with Modbus[®] TCP Ethernet protocol is available.

The SE-135 default IP address is 10.0.0.1. Use SE-MON-GFGC to change the IP address, monitor connected SE-135 units, and to issue remote commands. SE-MON-GFGC can be downloaded from www.littelfuse.com/relayscontrols.

If the computer running SE-MON-GFGC has more than one active network connection, SE-MON-GFGC may not detect the SE-135. Ensure SE-MON-GFGC is not blocked by Windows Firewall by adding it to the Firewall Exceptions list in the Windows Control Panel.

On start-up SE-MON-GFGC scans the network for SE-135 units and displays them in a list. Select one from the list and click "Edit" to change the IP address, subnet mask, or description. When selecting an IP address, ensure it is not already in use. Click "Apply" to save the changes. SE-MON-GFGC will pause for five seconds and scan the network again.

To view the status of an SE-135, select the unit and click "Monitor". If a warning appears, the SE-135 may have been set to an IP address that is not accessible by the network.

Table 1 shows the SE-135 coil addresses. Table 2 provides the holding registers in 16-bit format.

A remote reset can be generated by writing DO1 high for one second and then writing it back to low.

TABLE 1. COIL ADDRESS

COIL	DESCRIPTION	NAME	ATTRIBUTE
ADDRESS			
00001	GC Status	DI0	Read
00002	GF Status	DI1	Read
00003	Trip Relay	DI2	Read
00018	Remote Reset	DO1	Read/Write

TABLE 2. HOLDING REGISTER ADDRESS

TIMBLE 2. HOLDING REGISTER ADDRESS			
REGISTER	DESCRIPTION	ATTRIBUTE	
Address			
40301	DI0 – DI11	Read	
40303	DO0 - DO5	Read/Write	

3. INDICATION

3.1 GROUND FAULT

A red TRIP LED indicates a ground-fault trip and the remote-indication relay GF is energized when the ground-fault circuit is not tripped (fail-safe indication-contact operation). A green SENSOR LED indicates a current sensor is correctly connected. If the SE-CS10- or SE-CS40-series current sensor is disconnected or shorted, the green LED will go out and the ground-fault circuit will trip. If the sensor fault is intermittent, the ground-fault circuit will trip and the green LED will flash to indicate that the trip was initiated by a sensor fault.

NOTE: The SE-CS10- and SE-CS40-series current sensors are 600-V-rated current transformers. When system voltage is above 600 V, ensure conductors passed through the sensor window are insulated to system voltage.

3.2 POWER

The green POWER LED indicates that the internal power supply is on.

3.3 DIAGNOSTIC ERROR

The red DIAGNOSTIC ERROR LED indicates that an internal error caused the SE-135 to trip. Return the SE-135 to the factory if a reset does not clear the trip.

Induced ac current in the ground-check loop can cause the LED to flicker. This is a normal condition and does not indicate a diagnostic error; the ground-check monitoring circuit is not affected.

3.4 GROUND CHECK

A red TRIP LED indicates a ground-check trip. A green VALID LED indicates a valid ground-check loop and the remote-indication relay GC is energized when the ground-check loop is valid (fail-safe indication-contact operation). Two yellow LED's indicate the status of an invalid ground-check loop. OPEN indicates the loop resistance exceeds the trip resistance and SHORT indicates the ground-check conductor is shorted to the ground conductor. A flashing yellow LED indicates the corrected cause of a latched ground-check trip.

4. INSTALLATION

4.1 GENERAL

This ground-fault ground-check monitoring system consists of an SE-135 Monitor, an SE-CS10- or SE-CS40-series Current Sensor, and an SE-TA12A-series Termination Assembly connected as shown in Fig. 1. If required, remote indication and reset can be implemented with standard pilot devices, or with an RK-132 Remote-Indication-and-Reset Kit.

4.2 MONITOR

Each SE-135 is packaged with both panel- and surfacemounting hardware.

Outline and panel-cutout dimensions for the SE-135 are shown in Fig. 2. To panel mount the SE-135, insert it through the panel cutout and secure it with the four supplied 8-32 locknuts and flat washers.

If an optional SE-IP65CVR-G is used, follow the included installation instructions. See Figs. 4 and 5.

All connections to the SE-135 are made through plugin, wire-clamping terminal blocks for 24 to 12 AWG (0.2 to 2.5 mm^2) conductors. Each plug-in terminal block can be secured to the monitor by two captive screws for reliable connections in high-vibration applications.

Outline dimensions and mounting details for surface mounting an SE-135 are shown in Fig. 3. Fasten the SE-134-SMA Surface-Mount Adapter to the mounting surface and make connections to the adapter terminal blocks. Follow the instructions in Fig. 3 to install or remove the SE-135.

Use terminal 1 (L1) as the line terminal on ac systems or the positive terminal on dc systems. Use terminal 2 (L2/N) as the neutral terminal on ac systems or the negative terminal on dc systems.

NOTE: On revision 4 and newer units, terminal 3 (SPG) is internally connected to terminal 4. For these units an external terminal-3-to-terminal-4 connection is not required, nor is it necessary to remove the terminal-3 connection for dielectric-strength testing.

4.3 CURRENT SENSORS

Outline dimensions and mounting details for the SE-CS10- and SE-CS40-series current sensors are shown in Fig. 6. Pass only phase conductors through the sensor window as shown in Fig. 1. If a shield, ground, or ground-check conductor enters the sensor window, it must be returned through the window before it is terminated. Connect the current sensor to terminals 16 and 17. Ground terminal 17. Current-sensor primary and secondary connections are not polarity sensitive. See Section 4.7.

4.4 **TERMINATION ASSEMBLY**

Outline dimensions and mounting details for the SE-TA12A, SE-TA12A-WL, and SE-TA12ASF-WL are shown in Figs. 7 and 8. Install the SE-TA12A at the load to complete the ground-check loop as shown in Fig. 1. Connect terminal G of the SE-TA12A to the equipment frame so that the ground-conductor-to-equipment-frame connection will be included in the monitored loop.

4.5 REMOTE OPERATION

Remote indication contacts and a reset input are provided as shown in Fig. 1.

The optional RK-132 Remote Kit is shown in Fig. 9. Connect terminals of the green ground-check indicator to SE-135 terminals 26 and 27 and the red ground-fault indicator to terminals 19 and 21. For remote reset, connect the normally open push-button switch across terminals 9 and 10.

4.6 PARALLEL-PATH ISOLATION

A PPI-600V can be used for parallel-path rejection. A PPI-600V will also eliminate inter-machine arcing and prevent stray ac and dc currents from flowing in

the monitored ground wire. See Figs. 10 and 11. See Technical Note GC-10 "Parallel Path Isolator" at www.littelfuse.com/relayscontrols, or contact Littelfuse Startco for application details.

4.7 FERRITE PLACEMENT

A ferrite kit is included with CE-compliant options only. Where CE compliance is desired, install each ferrite as shown in Fig. 12. If a current sensor is used, connect the shield wire as shown in Fig. 13.

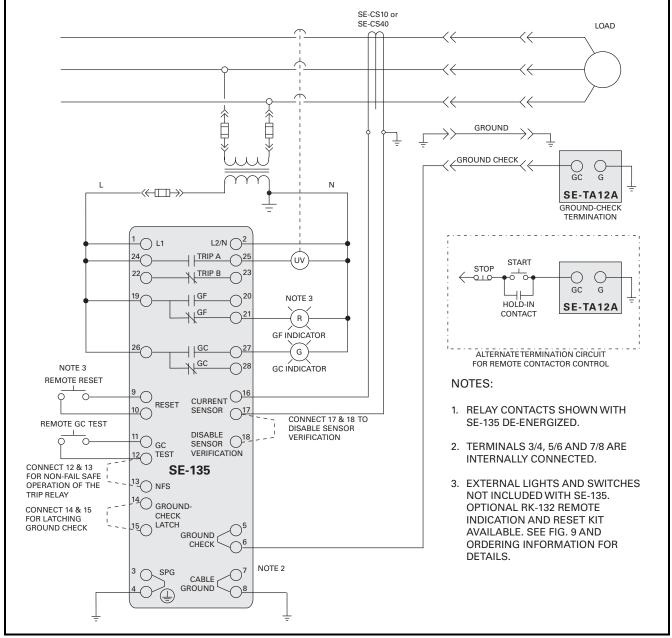


FIGURE 1. SE-135 Typical Application.



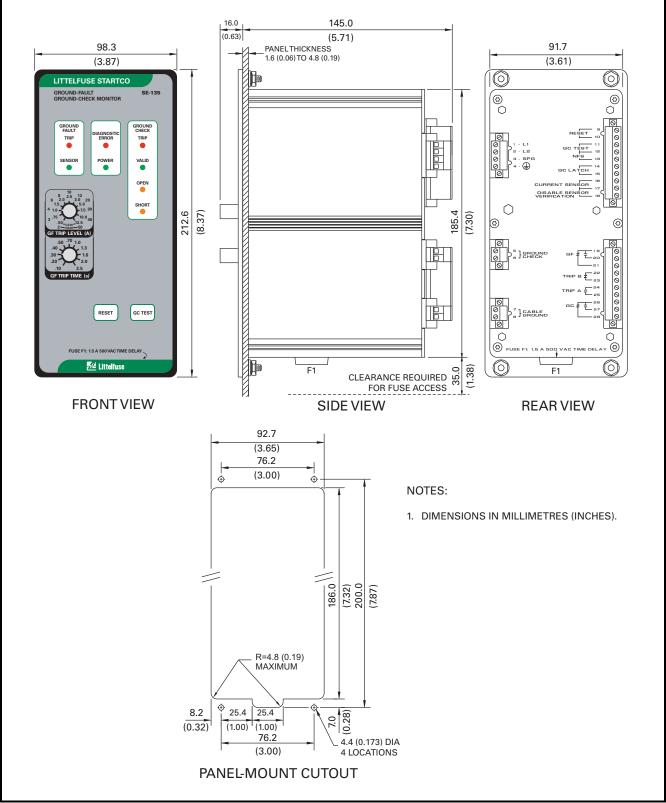


FIGURE 2. SE-135 Outline and Panel-Mounting Details.



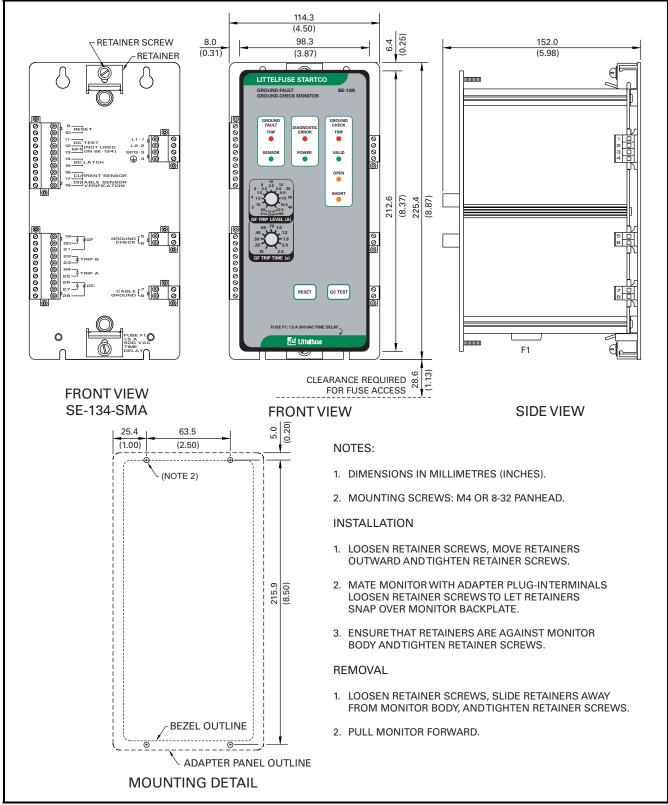


FIGURE 3. SE-134-SMA Surface Mount Adapter and SE-135 Surface-Mounting Details.



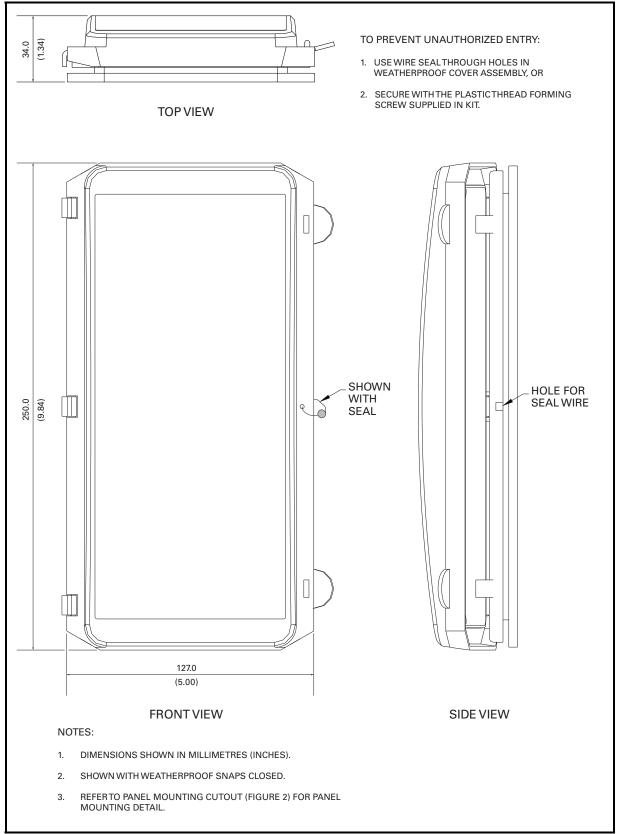


FIGURE 4. SE-IP65CVR-G Weatherproof Cover Outline.



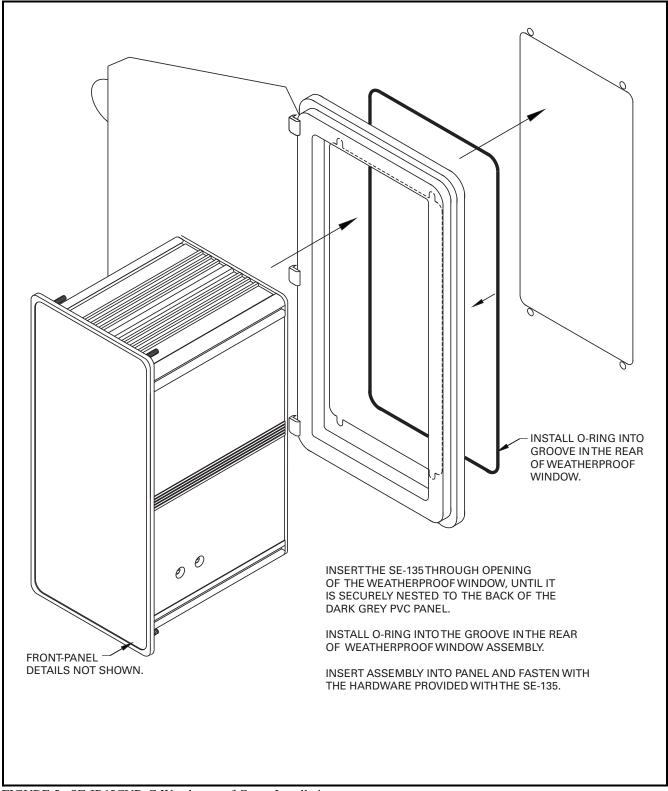


FIGURE 5. SE-IP65CVR-G Weatherproof Cover Installation.



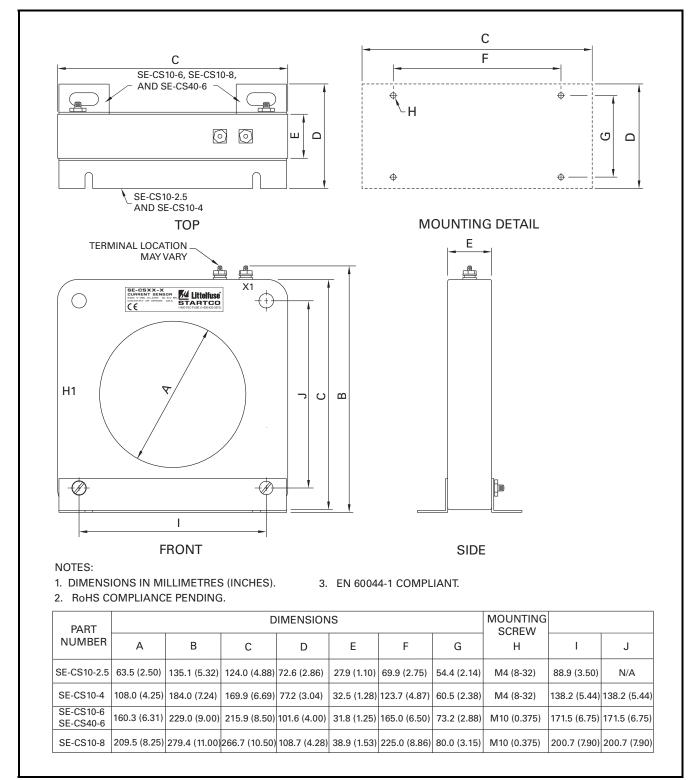


FIGURE 6. SE-CS10 and SE-CS40 Current Sensors.



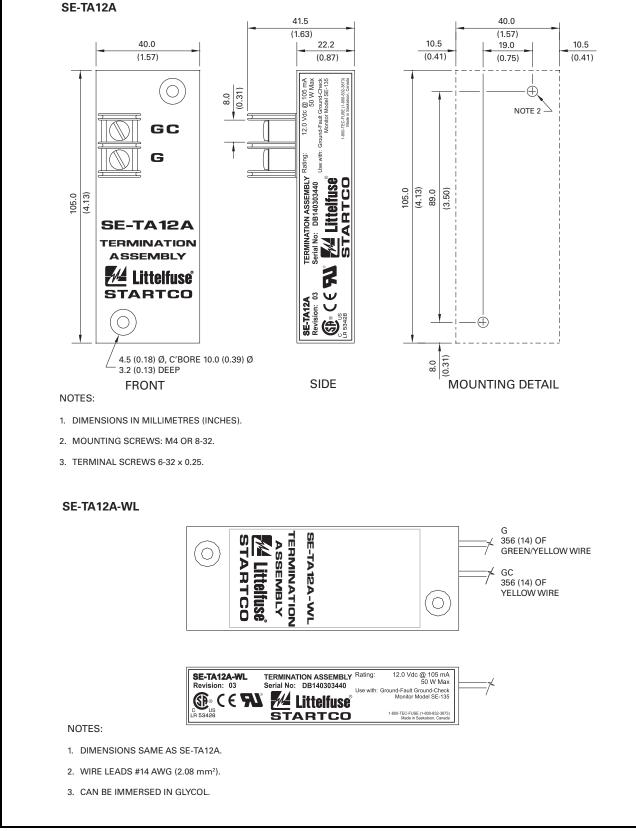
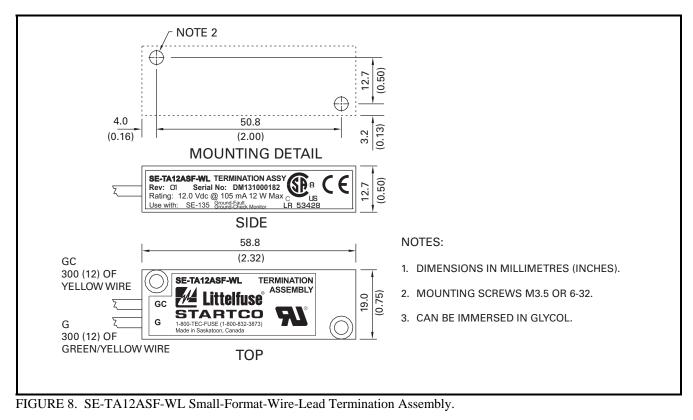


FIGURE 7. SE-TA12A and SE-TA12A-WL Termination Assemblies.





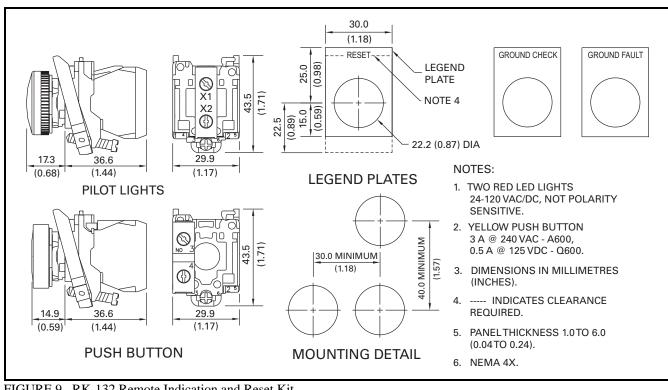


FIGURE 9. RK-132 Remote Indication and Reset Kit.



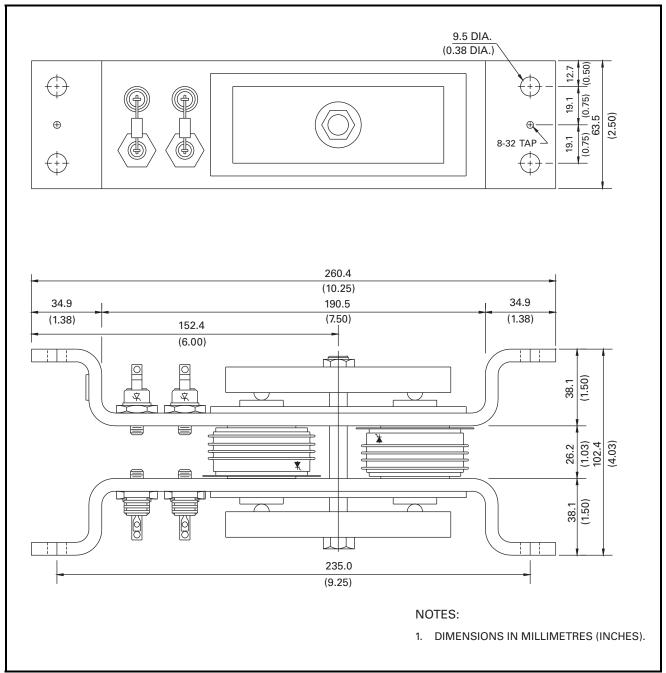
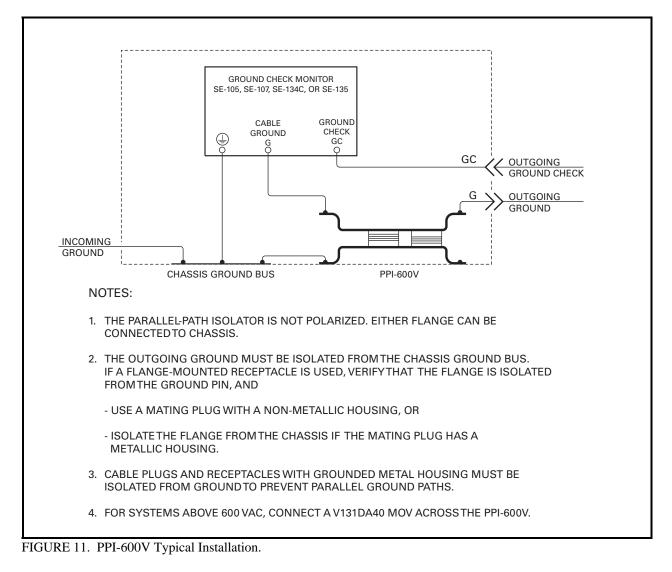


FIGURE 10. PPI-600V Parallel-Path Isolator.







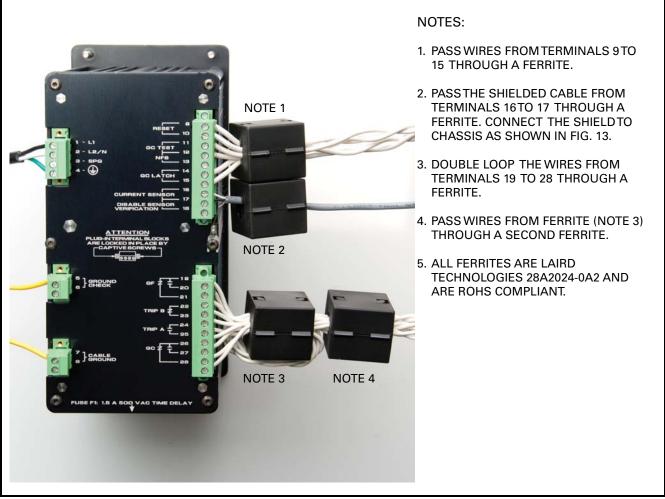


FIGURE 12. SE-135 with Ferrites Installed.

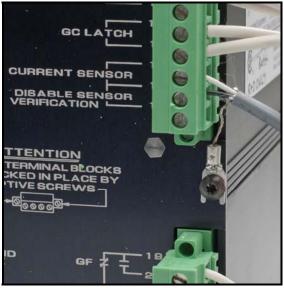


FIGURE 13. Current Sensor Shield Connection.

5. TECHNICAL SPECIFICATIONS

5.1 SE-135

Supply: Option 0
(+10, -45%), 50-400 Hz; 15 W, 110-250 Vdc (+10, -25%) Option 1 15 W, 24-48 Vdc (+50, -25%); 20 VA, 48 Vac (+10, -55%), 50-100 Hz Ground-Fault Circuit: Digital Filter
15 W, 110-250 Vdc (+10, -25%) Option 1
(+10, -25%) Option 1
Option 1 15 W, 24-48 Vdc (+50, -25%); 20 VA, 48 Vac (+10, -55%), 50-100 Hz Ground-Fault Circuit: Digital Filter 50 to 60 Hz, Bandpass 3 dB Frequency Response 30 to 90 Hz Trip-Level Settings: SE-CS10-x
(+50, -25%); 20 VA, 48 Vac (+10, -55%), 50-100 Hz Ground-Fault Circuit: Digital Filter
20 VA, 48 Vac (+10, -55%), 50-100 Hz Ground-Fault Circuit: Digital Filter
(+10, -55%), 50-100 Hz Ground-Fault Circuit: Digital Filter
Ground-Fault Circuit: Digital Filter
Digital Filter
3 dB Frequency Response 30 to 90 Hz Trip-Level Settings: SE-CS10-x
Trip-Level Settings: SE-CS10-x50, .75, 1.0, 1.5, 2.0, 2.5
SE-CS10-x50, .75, 1.0, 1.5, 2.0, 2.5
SE-CS10-x50, .75, 1.0, 1.5, 2.0, 2.5
12.5 A
SE-CS40-x2, 3, 4, 6, 8, 10, 12, 20, 3
40, and 50 A
Trip-Time Settings
1.0, 1.3, 1.6, 2.0, and
2.5 s
Thermal Withstand:
SE-CS10-x
1,000 A for 2.5 s
(Ground-Fault Current)
SE-CS40-x600 A Continuous
4,000 A for 2.5 s
(Ground-Fault Current)
Sensor Lead Resistance 2Ω maximum
Trip-Level Accuracy:
SE-CS10-x 5% or 0.1 A
SE-CS10-x
SE-CS40-x
$\begin{array}{c} \text{SE-CS40-x} &$
SE-CS40-x
$\begin{array}{llllllllllllllllllllllllllllllllllll$
$\begin{array}{c} \text{SE-CS40-x} &$
$\begin{array}{c} \text{SE-CS40-x} & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \text{Open and Short} \\ \text{Trip Mode} & \text{Latching} \\ \hline \\ \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & 30 \text{ Vdc} \\ \text{Output Impedance.} & 136 \Omega \\ \text{Loop Current} & 105 \text{ mA} \\ \text{Induced-ac Withstand} & 60 \text{ Vac Continuous,} \\ 120 \text{ Vac for } 10 \text{ s,} \\ 250 \text{ Vac for } 0.25 \text{ s} \\ \hline \\ \text{Pull-in Time} & \leq 1.5 \text{ s} \\ \hline \\ \text{Trip Resistance:} \\ \text{Standard} & 28 \Omega \pm 10\% \\ \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \ \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \ \Omega \pm 10\% \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \Omega \pm 10\% \\ \text{Trip Time:} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \ \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \ \Omega \pm 10\% \\ \text{Trip Time:} \\ \text{Standard at } 50 \ \Omega & \dots & 220 \pm 30 \text{ ms} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \ \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \ \Omega \pm 10\% \\ \text{Trip Time:} \\ \text{Standard at } 50 \ \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \ \Omega & \dots & 220 \pm 30 \text{ ms} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \ \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \ \Omega \pm 10\% \\ \text{Trip Time:} \\ \text{Standard at } 50 \ \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \ \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{Short Detection} & \dots & \text{Yes} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \ \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \ \Omega \pm 10\% \\ \text{Trip Time:} \\ \text{Standard at } 50 \ \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \ \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{Short Detection} & \dots & 3 \text{ kV, } 60 \text{ Hz, 1 s} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 136 \Omega \\ \text{Loop Current} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \Omega \pm 10\% \\ \text{XGC Option at } 75 \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{Short Detection} & \dots & \text{Yes} \\ \text{Isolation} & \dots & 3 \text{ kV, } 60 \text{ Hz, } 1 \text{ s} \\ \text{Test} & \dots & \text{Front-Panel Button and} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 136 \Omega \\ \text{Loop Current} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \Omega \pm 10\% \\ \text{XGC Option at } 75 \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{Short Detection} & \dots & \text{Yes} \\ \text{Isolation} & \dots & 3 \text{ kV, } 60 \text{ Hz, } 1 \text{ s} \\ \text{Test} & \dots & \text{Front-Panel Button and} \\ \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 136 \Omega \\ \text{Loop Current} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \text{Pull-in Time} & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & 28 \Omega \pm 10\% \\ \text{XGC Option} & 45 \Omega \pm 10\% \\ \text{Trip Time:} \\ \text{Standard at } 50 \Omega & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \Omega & 220 \pm 30 \text{ ms} \\ \text{Short Detection} & \qquad Yes \\ \text{Isolation} & \dots & 3 \text{ kV, } 60 \text{ Hz, } 1 \text{ s} \\ \text{Test} & \qquad & \text{Front-Panel Button and} \\ \text{Remote, N.O. Contact} \\ \text{Fuse Rating (F1)} & \dots & 1.5 \text{ A, } 500 \text{ Vac,} \end{array}$
$\begin{array}{c} \text{SE-CS40-x} & \dots & 5\% \text{ or } 0.4 \text{ A} \\ \text{Trip-Time Accuracy} & \dots & +50, -15 \text{ ms} \\ \text{Sensor Verification} & \dots & \text{Enabled or Disabled} \\ \text{Sensor-Fault Detection} & \dots & \text{Open and Short} \\ \text{Trip Mode} & \dots & \text{Latching} \\ \end{array}$ $\begin{array}{c} \text{Ground-Check Circuit:} \\ \text{Open-Circuit Voltage} & \dots & 30 \text{ Vdc} \\ \text{Output Impedance} & \dots & 136 \Omega \\ \text{Loop Current} & \dots & 105 \text{ mA} \\ \text{Induced-ac Withstand} & \dots & 60 \text{ Vac Continuous,} \\ & 120 \text{ Vac for } 10 \text{ s,} \\ & 250 \text{ Vac for } 0.25 \text{ s} \\ \end{array}$ $\begin{array}{c} \text{Pull-in Time} & \dots & \leq 1.5 \text{ s} \\ \text{Trip Resistance:} \\ \text{Standard} & \dots & 28 \Omega \pm 10\% \\ \text{XGC Option} & \dots & 45 \Omega \pm 10\% \\ \text{XGC Option at } 75 \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{XGC Option at } 75 \Omega & \dots & 220 \pm 30 \text{ ms} \\ \text{Short Detection} & \dots & \text{Yes} \\ \text{Isolation} & \dots & 3 \text{ kV, } 60 \text{ Hz, } 1 \text{ s} \\ \text{Test} & \dots & \text{Front-Panel Button and} \\ \end{array}$

Trip Mode	. Latching or Non-Latching
Trip Relay:	
CSA/UL Contact Rating	
	5 A 30 Vdc,
	0.25 HP, B300 Pilot Duty
Supplemental Contact Rati	
Make/Carry (0.2 s)	
Break dc	
Develope	35 W Inductive (L/R < 0.04)
Break ac	1,500 VA Resistive, 1,500 VA Inductive
	(PF > 0.4)
Subject to maximums of 8	A and 250 V (ac or dc)
Contact Configuration	
Operating Mode	Contacts
Operating Mode	Non-Fail-Safe
Remote-Indication Relays:	
CSA/UL Contact Rating	. 8 A Resistive 250 Vac,
	8 A 30 Vdc
Supplemental Contact Rati	
Make/Carry (0.2 s)	
Break dc	25 W Inductive (L/R < 0.04)
Break ac	
Dieux ue	1,500 VA Inductive
	(PF > 0.4)
Subject to maximums of 8	
Contact Configuration	
Operating Mode	. Fail-Safe
Trip Reset	Front-Panel Button and
	Remote, N.O. Contact
	· · · · · · · · · · · · · · · · · · ·
Terminal Block Rating	
	12 AWG (2.5 mm ²)
DWD Conformal Coating	MIL 1 46059 analified
PWB Conformal Coating	UL QMJU2 recognized
	OL QWIJOZ ICCOgnizcu
Mounting Configuration	. Panel Mount and
	Surface Mount
Dimensions:	
Height	
Width	
Depth	152 11111 (5.2)
Shipping Weight	2.3 kg (5.1 lb)
Environment:	
	40 to 60°C (-40 to 140°F)
Storage Temperature	55 to 80°C (-67 to 176°F)
Humidity	. 85% Non-Condensing



Surge Withstand	(Oscillatory and Fast	CertificationCSA Canada and USA
	Transient)	UL Listed
EMC Tests:		Listed Ground Fault Sensing and Relaying Equipment 4FX9 E340889 A usetra liso
Verification tested in accor	dance with EN 60255-26:2009.	and Relaying Equipment 4FX9 E340889
Dell'states 1 Conducted		Australia
Radiated and Conducted Emissions	CISPR 22:2008-09	N11659
Liiiissioiis	Class A	CE, European Union
		CE
Current Harmonics and		FCC
Voltage Fluctuations	IEC 61000-3-2 and IEC 61000-3-3	FC
	Class A	
		To: CSA C22.2 No. 14 Industrial Control Equipment UL 508 Industrial Control Equipment
Electrostatic Discharge	IEC 61000-4-2	UL 1053 Ground Fault Sensing and Relaying
	\pm 6 kV contact discharge	Equipment
	(direct and indirect)	CE Low Voltage Directive
	\pm 8 kV air discharge	IEC 61010-1:2010 (3 rd Edition)
Radiated RF Immunity	IEC 61000-4-3	FCC CFR47, Part 15, Subpart B, Class A – Unintentional Radiators
j	10 V/m, 80-1,000 MHz,	Class A – Onintentional Radiators
	80% AM (1 kHz)	Compliance RoHS Pending
	10 V/m, 1.0 to 2.7 GHz,	
	80% AM (1 kHz)	5.2 CURRENT SENSORS
Fast Transient	IEC 61000-4-4	Environment: Operating Temperature40 to 60°C (-40 to 140°F)
	Class A: ± 4 kV (on AC	Storage Temperature40 to 80°C (-40 to 140°F)
	mains and I/O lines)	
Sugar Immunity	IEC 61000 4 5	SE-CS10-2.5:
Surge Immunity	Zone B	Current Ratio 1,000:5 A
	\pm 1 kV differential mode	Insulation
	$\pm 2 \text{ kV}$ common mode	Shipping Weight
~		
Conducted RF Immunity		SE-CS10-4:
	10 V, 0.15-80 MHz, 80% AM (1 kHz)	Current Ratio 1,000:5 A
		Insulation
Magnetic Field		Shipping Weight 1.9 kg (4.3 lb)
Immunity		
	50 Hz and 60 Hz 30 A/m and 300 A/m	SE-CS10-6:
	50 A/III and 500 A/III	Current Ratio 1,000:5 A
Power Frequency	IEC 60255-22-7	Insulation
	Zone A: differential mode	Shipping Weight
	150 Vrms	
	Zone A: common mode 300 Vrms	
	500 11115	
1 MHz Burst		
	\pm 1 kV differential mode	
	(line-to-line) ± 2.5 kV common mode	



SE-CS10-8:

Current Ratio	1,000:5 A
Insulation	600-V Class
Window Diameter	
Shipping Weight	

SE-CS40-6:

Current Ratio	800:1 A
Insulation	600-V Class
Window Diameter	160 mm (6.3")
Shipping Weight	1.8 kg (4.0 lb)

Certification......CE⁽¹⁾, European Union CE

Compliance	IEC 60044-1
	RoHS Pending

NOTES:

⁽¹⁾ When connected to an SE-135.

5.3 TERMINATION ASSEMBLIES

SE-TA12A:

Characteristic	.12-V Zener, Temperature
	Compensated
Circuit Type	. High-Current Shunt
	Regulator
Reverse Voltage	.12 ±0.03 Vdc @ 100 mA
Forward Voltage	.0.5 ±0.1 Vdc @ 100 mA
Operating Temperature	
Current Range	. 2 mA to 25 A
Maximum Clamping	
Voltage	.55 V @ 250 A,
	5x20 µs Pulse
Power Rating	.50 W
Screw Terminal	.6-32 x 0.25
Dimensions	. 105 x 40 x 41.5 mm
	(4.13 x 1.57 x 1.63")
Shipping Weight	. 300 g (0.7 lb)

SE-TA12A-WL:

Characteristic 12	2-V Zener, Temperature
C	ompensated
Circuit TypeH	igh-Current Shunt
Re	egulator
Reverse Voltage12	2 ±0.03 Vdc @ 100 mA
Forward Voltage0.	5 ±0.1 Vdc @ 100 mA
Operating Temperature4	$0 \text{ to } 60^{\circ}\text{C} (-40 \text{ to } 140^{\circ}\text{F})$
Current Range21	mA to 25 A
Maximum Clamping	
Voltage55	5 V @ 250 A,
5x	x20 μs Pulse
Power Rating50) W

Wire Leads	. 14 AWG (2.08 mm ²),
	356 mm (14")
Dimensions	. 105 x 40 x 22.2 mm
	(4.13 x 1.57 x 0.87")
Shipping Weight	. 300 g (0.7 lb)

SE-TA12ASF-WL:

Characteristic	12-V Zener, Temperature
	Compensated
Circuit Type	High-Current Shunt Regulator
Reverse Voltage	12 ±0.03 Vdc @ 100 mA
Forward Voltage	0.5 ±0.1 Vdc @ 100 mA
Operating Temperature	40 to 60°C (-40 to 140°F)
Current Range	2 mA to 15 A
Maximum Clamping	
Voltage	55 V @ 250 A, 5x20 µs Pulse
Power Rating	12 W
Wire Leads	18 AWG (0.82 mm ²),
	300 mm (11.8")
Dimensions	58.8 x 19 x 12.7 mm
	(2.32 x 0.75 x 0.5")
Shipping Weight	45 g (0.1 lb)
	-

Certification CSA Canada and USA

UL Listed Uster Guide Lister Ground Fault Sensing and Relaying Equipment 4FX9 E340889 CE⁽¹⁾, European Union

NOTES: ⁽¹⁾ When connected to an SE-135.

6. ORDERING INFORMATION⁽¹⁾

SE	-135-	<u>—</u> - <u></u> ,]
			-Network Communications:
			0 None
			3 Ethernet ⁽²⁾
	Power Supply:		
	0 Universal ac/dc Supply		
	1 24- to 48-Vdc Supply ⁽²⁾⁽³⁾		
Ground Check Options:			
Blank Standard			
			XGC Extended-GC-Trip Resistance
(1)	All	options	include CE/C-Tick unless otherwise

- stated. CE/C-Tick models include a ferrite kit.
- ⁽²⁾ CE/C-Tick not available.
- ⁽³⁾ Not available with Ethernet network communications option.

Ground-Check Termination:

SE-TA12A	50-W Termination
	Assembly with Screw
	Terminals
SE-TA12A-WL	50-W Termination
	Assembly with Wire
	Leads
SE-TA12ASF-WL	12-W Small-Format
	Termination Assembly
	with Wire Leads

Current Sensors:

SE-CS10-2.5	Current Sensor,
	63 mm (2.5") window
SE-CS10-4	Current Sensor,
	108 mm (4.2") window
SE-CS10-6	Current Sensor,
	160 mm (6.3") window
SE-CS10-8	Current Sensor,
	209 mm (8.2") window
SE-CS40-6	Current Sensor,
	160 mm (6.3") window

Parallel Path Isolator

PPI-600V	For system voltages up to
	600 Vac

Accessories:	
RK-132	Remote Indication and
	Reset, includes two 24- 120-V pilot lights, a reset push button, and legend plates
SE-IP65CVR-G	Hinged transparent cover, IP65
SE-134-SMA	Surface-Mount Adapter, included with SE-135
SE-134-HDWR	Hardware Kit (excludes ferrites and SE-134-SMA), included with SE-135

7. WARRANTY

The SE-135 Ground-Fault Ground-Check Monitor is warranted to be free from defects in material and workmanship for a period of five years from the date of purchase.

Littelfuse Startco will (at Littelfuse Startco's option) repair, replace, or refund the original purchase price of an SE-135 that is determined by Littelfuse Startco to be defective if it is returned to the factory, freight prepaid, within the warranty period. This warranty does not apply to repairs required as a result of misuse, negligence, an accident, improper installation, tampering, or insufficient care. Littelfuse Startco does not warrant products repaired or modified by non-Littelfuse Startco personnel.

8. TEST PROCEDURES

8.1 GROUND-CHECK TRIP TESTS

8.1.1 LATCHING GROUND-CHECK TRIP TEST

Connect the monitor, current sensor and termination assembly as shown in Fig 14. Connect terminals 14 and 15 for latching operation. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.

Open the ground-check loop by removing either the GC or G connection between the monitor and the termination assembly (pressing the faceplate GC TEST button will also perform an open-ground-check test). The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the OPEN LED's will be on.

Reconnect the ground-check loop. The VALID and TRIP LED's will be on and the OPEN LED will be flashing. The TRIP contacts (terminals 22-23 and 24-25) will remain latched and ground-check indication contacts (terminals 26-27 and 26-28) will change state.

Reset the monitor.

Short the ground-check loop by connecting G to GC. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the SHORT LED's will be on.

Remove the short from G to GC. The VALID and TRIP LED's will be on and the SHORT LED will be flashing. The TRIP contacts (terminals 22-23 and 24-25) will remain latched and ground-check indication contacts (terminals 26-27 and 26-28) will change state.

Reset the monitor.

8.1.2 NON-LATCHING GROUND-CHECK TRIP TEST

Connect the monitor, current sensor and termination device as shown in Fig. 14. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.

Open the ground-check loop by removing either the GC or G connection between the monitor and the termination assembly (pressing the faceplate GC Test button will also perform an open circuit test). The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the OPEN LED's will be on.

Reconnect the ground-check loop. The monitor will reset.

Short the ground-check loop by connecting G to GC. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-check indication contacts (terminals 26-27 and 26-28) will change state. The VALID LED will be off, and both the GROUND CHECK TRIP and the SHORT LED's will be on.

Remove the short from G to GC. The monitor will reset.

8.2 TRIP RELAY FAIL-SAFE MODE TEST

Connect the monitor, current sensor and termination device as shown in Fig. 14. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on. The output contacts between terminals 22 and 23 will be open and between 24 and 25 will be closed.

Remove the supply voltage. The output contacts between terminals 22 and 23 will close and the output contacts between terminals 24 and 25 will open.

8.3 CURRENT-SENSOR-VERIFICATION TEST

Connect the monitor, current sensor and termination device as shown in Fig. 14. With supply voltage applied, the POWER, SENSOR, and VALID LED's will be on.

Open the current-sensor circuit by disconnecting one of the sensor leads. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-fault indication contacts (terminals 19-20 and 19-21) will change state. The GROUND FAULT TRIP LED will be on and the SENSOR LED will be off.

Reconnect the current sensor. The GROUND FAULT TRIP LED will stay on and the SENSOR LED will flash. The output contacts will remain latched.

Reset the monitor.

Short the current sensor by connecting terminals 16 and 17. The monitor will trip. The trip contacts (terminals 22-23 and 24-25) and the ground-fault indication contacts (terminals 19-20 and 19-21) will change state. The GROUND FAULT TRIP LED will be on and the SENSOR LED will be off.

Remove the short from terminals 16 and 17. The GROUND FAULT TRIP LED will stay on and the SENSOR LED will flash. The output contacts will remain latched.

Reset the monitor.

8.4 SE-TA12A-SERIES TERMINATION ASSEMBLY TESTS

Apply 24 Vdc across the series combination of a $100-\Omega$, 5-W current-limiting resistor and the termination assembly, as shown in Fig. 15. In the reverse biased test, the voltage should be 12 V across the termination assembly terminals. In the forward biased test, the voltage across the termination assembly terminals should be between 0.3 and 0.9 V.

8.5 GROUND-FAULT PERFORMANCE TEST

To meet the requirements of the National Electrical Code (NEC), as applicable, the overall ground-fault protection system requires a performance test when first installed. A written record of the performance test is to be retained by those in charge of the electrical installation in order to make it available to the authority having jurisdiction. A test-record form is provided for recording the date and the final results of the performance tests.

The following ground-fault system tests are to be conducted by qualified personnel:

- a) Evaluate the interconnected system in accordance with the overall equipment manufacturer's detailed instructions.
- b) Verify proper location of the ground-fault current sensor. Ensure the cables pass through the groundfault-current-sensor window. This check can be done visually with knowledge of the circuit. The connection of the current-sensor secondary to the SE-135 is not polarity sensitive.
- c) Verify that the system is correctly grounded and that alternate ground paths do not exist that bypass the current sensor. High-voltage testers and resistance bridges can be used to determine the existence of alternate ground paths.
- d) Verify proper reaction of the circuit-interrupting device in response to a simulated or controlled ground-fault current. To simulate ground-fault current, use CT-primary current injection. Fig. 14 shows a test circuit using Littelfuse Startco Ground-Fault-Relay Test Units. The SE-400 has a programmable output of 0.5 to 9.9 A for a duration of 0.1 to 9.9 seconds. Set the test current to 120% of GF TRIP LEVEL. The SE-100T provides a test current of 0.65 or 2.75 A for testing 0.5- and 2.0-A trip levels. Inject the test current through the current-sensor window for at least 2.5 seconds. Verify that the circuit under test has reacted properly. Correct any problems and re-test until the proper reaction is verified.
- e) Record the date and the results of the test on the attached test-record form.

DATE	GROUND-FAULT-TEST RECORD TEST RESULTS
DAIE	ILSI KESULIS

TABLE 3. GROUND-FAULT-TEST RECORD

Retain this record for the authority having jurisdiction.



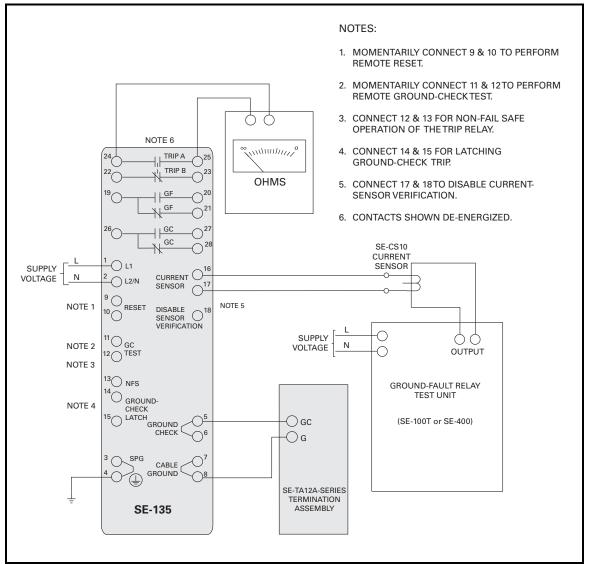


FIGURE 14. Ground-Fault-Test Circuit.

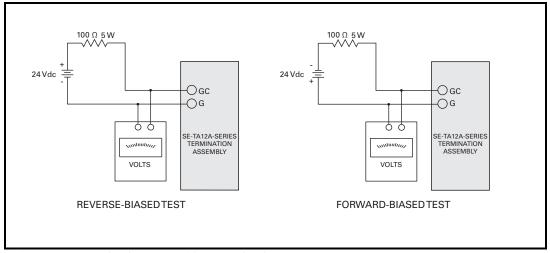


FIGURE 15. Termination-Assembly-Test Circuits.



APPENDIX A SE-135 REVISION HISTORY

MANUAL RELEASE DATE	MANUAL REVISION	PRODUCT REVISION (REVISION NUMBER ON PRODUCT LABEL)
October 3, 2014	3-C-100314	
November 12, 2013	3-B-111213	04D
May 14, 2013	3-A-050613	

MANUAL REVISION HISTORY

REVISION 3-C-100314

SECTION 4

Figs. 7, 8, and 11 updated.

APPENDIX A

Revision history updated.

REVISION 3-B-111213

SECTION 2

Maximum trailing cable length added.

SECTION 5

Additional termination assembly and compliance specifications added.

APPENDIX A

Revision history updated.

REVISION 3-A-050613

SECTION 2

Network communications added.

SECTION 4

Ferrite placement instructions added.

SECTION 5

CE specifications, XGC option, SE-CS40-6 specifications and dimensions added.

SECTION 6

Ordering information updated.

APPENDIX A

Revision history added.

PRODUCT REVISION HISTORY

REVISION 04D

Ferrite kit added.