PIC Microcontroller Universal Board

Rathod Raju Ambadas, R. P. Chaudhari

Abstract- A Microcontroller is a device which integrates a number of the components of a microprocessor system onto a single microchip and optimized to interact with the outside world through on-board interfaces; i.e. it is a little gadget that houses a microprocessor, ROM (Read Only Memory), RAM (Random Access Memory), I/O (Input Output functions), and various other specialized circuits all in one package.

Microcontrollers are used in automatically controlled products and devices, such as automobile engine control systems, implantable medical devices, remote controls, office machines, appliances, power tools, toys and other embedded systems. By reducing the size and cost compared to a design that uses a separate microprocessor, memory, and input/output devices, microcontrollers make it economical to digitally control even more devices and processes. Mixed signal microcontrollers are common, integrating analog components needed to control nondigital electronic systems.

Keywords- ROM, RAM, I/O.

I. INTRODUCTION

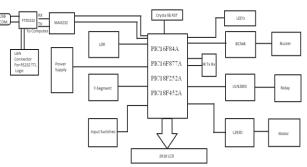
Based on the experiences with the IPS Board I present here a design for a multi purpose prototyping board for PIC 18F's. Microchip offers a broad range of microcontrollers (PIC's) for various applications. If you use such microcontrollers to develop and prototype solutions it can become cumbersome to design different prototyping boards over and over again depending on the controller used. So made the effort to design a Universal PIC Board UPB where a broad range of different controllers (mostly of the 18F series) can be used. The board offers RS232 (RX,TX including RTS,CTS), USB, a switch, a LED, ICSP, a reset and power monitoring, I2C, external / USB power, power stabilization, connector for alternate power (battery) and power switch and an expansion bus.

Design and programming of embedded systems require skills that need training and practice. Usually these activities are performed using a development board equipped with a specific microcontroller and a software environment for firmware development. The main problem of such approach is its focus on only one device type - other microcontroller families require other development boards. This aspect becomes important in a university laboratory, where students have to work with different types of embedded systems

Universal Development Tools enable you to develop applications with different types of microcontrollers. These tools provide the same development environment while the microcontroller can be changed easily. The Boards were designed to allow students or engineers to easily exercise and explore the capabilities of the various microcontrollers with peripheral devices such as: ADC, DAC, CAN, Ethernet, IrDA, MP3, RS485 and many more.

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Block Diagram Description

PIC microcontroller universal Board is a powerful development platform based on PIC18F452, PIC18F252, PIC16F877A and PIC16F84 microcontroller. USB based data logging, real time data monitoring and control, interactive control panels etc. The on-chip USB controller provides direct high speed interface to a PC/ laptop with speeds up to 12Mb/s. The UART boot loader eliminates need of an additional programmer and allows you to program using serial port.

The on board peripherals include USB interface, ULN2003 current sinking driver, L293D DC motor controller, 16 X 2 character LCD and many more. The onchip peripherals and the external hardware on the development board are interconnected using pin headers and jumpers. The I/O pins on the microcontroller can be accessed. The board is made from double sided PTH PCB board to provide extra strength to the connector joints for increased reliability. It supports the operating supply voltage between 5V dc and 12 Vac and has built-in reverse polarity protection.

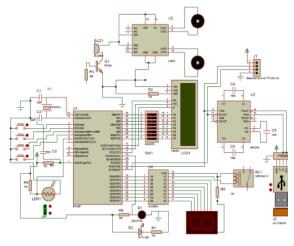


Figure: Circuit Diagram of PIC Microcontroller Universal Board

II. MAIN THEME

PIC microcontroller universal Board is a powerful development platform based on PIC18F452, PIC18F252, PIC16F877A and PIC16F84 PIC microcontroller. This board is ideal for developing embedded applications



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involving high speed wireless communication, USB based data logging, real time data monitoring and control, interactive control panels etc

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Figure: Developed Universal Board System

III. STEP OF EXECUTION PROCESS

- 1. By PIC Multi programmer burn the code of DC Motor in to the IC by MPLAB Software
- 2. We have given Ac power supply to transformer, we get step down AC
- 3. After that we given AC (12V) to Bridge we get 12 V DC
- 4. We convert that 12 DC Into 5v DC by using IC 7805
- 5. That DC 5 v supply is given to the Microcontroller.
- 6. At port B (RB0 to RB3) we have connected DC motor
- The positive & negative terminal of motor is connected to VCC & GND (Pin no.32, 31) of microcontroller 18 F452/16F877A
- 8. After giving power supply to microcontroller DC motor rotates clockwise

Comparison of the System with PIC16F87XA Device Features

17	DIC	DIC	DIC	DIC	
Key	PIC	PIC	PIC	PIC	Developed
Features	16F873A	16F874	16F87	16F87	System
	56.00	A	6A	7A	5.6.00
Operating	DC – 20	DC –	DC –	DC –	DC - 20
Frequency	MHz	20 MHz	20	20	MHz
			MHz	MHz	
Resets	POR,	POR,	POR,	POR,	POR,BOR
(and	BOR	BOR	BOR	BOR	(PWRT,O
Delays)	(PWRT,	(PWRT	(PWR	(PWR	ST)
	OST)	, OST)	Τ,	Τ,	
			OST)	OST)	
Flash	4K	4K	8K	8K	1024 bytes
Program					
Memory					
(14-bit					
words)					
Data	192	192	368	368	68 bytes
Memory					
(bytes)					
EEPROM	128	128	256	256	64 bytes
Data					2
Memory					
(bytes)					
Interrupts	14	15	14	15	1
I/O Ports	Ports A,	Ports A,	Ports	Ports	Ports A,B
201010	B, C	B, C, D,	A, B,	A, B,	1 0110 11,2
	2, 0	Е, С, Е, Е	C, 2,	C, D,	
		Ľ	C	Е, Д,	
Timers	3	3	3	3	3
Capture/Co	2	2	2	2	2
mpare					
/PWM					
modules					
Serial	MSSP,	MSSP,	MSSP,	MSSP,	MSSP,
Communic	USART	USART	USAR	USAR	USART
ations	Corner	Corner	T	Т	Conner
Parallel	_	PSP	_	PSP	-
Communic		151		1.51	
ations					
10-bit	5 input	8 input	5 input	8 input	8 input
Analog-to-	channels	channel	channe	channe	channels
Digital	chambers	s	ls	ls	chumine 15
Module		3	15	10	
Analog	2	2	2	2	2
Comparator	~	~	-	4	2
s					
Instruction	35	35	35	35	49
Set	Instructio	Instruct	Instruc	Instruc	49 Instruction
Bet	ns	ions	tions	tions	msuucuon
Dackages	28-pin	40-pin	28-pin	40-pin	PDIP,
Packages	PDIP	PDIP	28-pm PDIP	PDIP	SOIC,
	28-pin	44-pin	28-pin	44-pin	SSOP
	SOIC	PLCC	SOIC	PLCC	
	28-pin	44-pin	28-pin	44-pin	
	SSOP	TQFP	SSOP	TQFP	
		/// min	28-pin	44-pin	
	28-pin OFN	44-pin OFN	OFN	OFN	

As technology advances rapidly comes in modernisation and in an effort to keep the up to date, we developed a PICbased microcontroller design. We believe that this low-cost and reliable laboratory constitutes, for, a smooth transition to the co-design of universal boards.

A device, which in testing program phase, can simulate any environment, is called a development system. Apart from the programmer, the power supply unit and the microcontroller socket, the development system contains elements for input pin activation and output pin monitoring. A high quality version has LED displays, LCD displays, temperature sensors and all other elements which the target device can be supplied with. These peripherals could be connected to the MCU. In this way, the whole program may



be tested in practice, during its development stage, because the microcontroller does not know, or care, whether its input is activated by a push-button or a sensor built in a real machine.

The universal boards result for various applications as follows

- A. Countdown Timer 7-segment display
- B. Character Generator Display LCD
- C. Speed Measurement of the DC Motor
- D. LED Glows as per the programming

As per the above results is taken through universal board for controlling the application as per decoding the codes and excecuted the same.

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