dBug User Manual

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Contents

1 Motivation

When testing distributed and multi-threaded systems, their concurrent nature can cause a test to execute in many different ways. For the sake of the argument, let us assume we have a concurrent system with a fixed initial state and a test, which can execute in N possible ways from the initial state. A common technique to address the non-deterministic execution of distributed and multi-threaded systems is *stress testing*. Stress testing repeatedly executes the same test, hoping that eventually all of the possible ways in which the test could have executed (and all of the possible errors the test could have detected) are encountered.

In case there is an error in the system and the test has a chance of $\frac{1}{P}$ to execute in a way that detects the error, stress testing is expected to discover the error in P iterations. In other words, stress testing is good at catching likely errors, but might struggle to discover corner case errors that occur with very low probability. Because the probability distribution of possible ways in which a test executes can be non-uniform and architecture-dependent the value of P can be much higher then N. In such situations, stress testing becomes a very inefficient way of searching for errors.

The dBug tool offers an alternative to stress testing of concurrent systems, which compensates for the aforementioned inefficiency. The key idea behind dBug is to control the order in which concurrent events in a distributed and multi-threaded system happen. The ability to order concurrent events provides dBug with a mechanism to systematically enumerate possible executions of a test, one by one. By doing so, every possible execution becomes equally likely and dBug needs in expectation at most $\frac{N}{2}$ iterations of a test to discover an error (in case it exists).

2 Overview

In order to control the order in which concurrent events happen, dBug uses an interposition layer that sits between the system and the operating system and shared libraries as illustrated in Figure 1. This interposition layer at run-time intercepts calls to select library calls[1] used for coordination and communication between threads of the system. Upon interception of a library call, the interposition layer can delay the execution of the call for an arbitrary amount of time. Optionally, the interposition layer can also decide to inject a fault by simulating an erroneous execution of the library call.

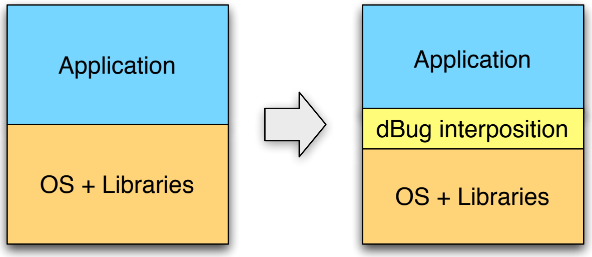

Figure 1: Interposition

Because of the distributed and multi-threaded nature of the system being tested, dBug uses one instance of the interposition layer per process. In order to coordinate the activity of multiple instances of the interposition layer, dBug also runs a process called the *arbiter*, which collects

[1] For the complete list of intercepted calls see Appendix A.

information from each instance of the interposition layer. The different instances of the interposition layer and the arbiter form a simple client-server architecture as illustrated in Figure 2. The arbiter acts as a centralized scheduler of the system and decides in what order the concurrent calls to library routines should execute.

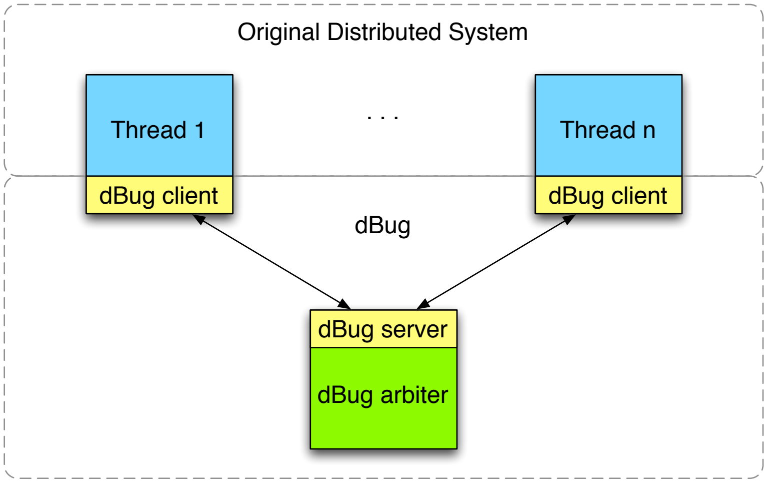

Figure 2: Client-Server Architecture

Finally, in order to systematically explore different executions of a test in a distributed and multi-threaded system, dBug uses a process called the *explorer*, which repeatedly sets up the initial state of the system, starts up the arbiter and provides it with a specific schedule to follow, and runs both the system and the test on top of the interposition layer. When an execution of the test completes, the explorer collects information from the arbiter. This information is used by the explorer to gradually build a *decision tree* of all possible ways in which the arbiter can order concurrent events of the system and the test. The decision tree is in turn used to generate arbiter schedules, which guide future iterations of the test execution towards unexplored orderings of events.

3 Implementation

The interposition layer of dBug is implemented as a shared library `libdbug.so`. The shared library is to be pre-loaded[2] by a dynamic linker during execution of any binary that is to be controlled by dBug. The arbiter is implemented as a binary executable `arbiter`. Finally, the explorer is implemented as a Ruby script `explorer.rb`.

4 Installation

In order to use dBug you need to install:

1. Boost (`http://www.boost.org/`),
2. Ruby (`http://www.ruby-lang.org/en/`),
3. Ruby Gems (`http://rubygems.org/`),

[2] For details see `LD_PRELOAD` in manpage for `ld.so`.

4. the RubyTree gem, and
5. Thrift (`http://thrift.apache.org/`).

Boost, Ruby, and Ruby Gems are available as a package for most distributions. For example, on Ubuntu you can install these using:

```
$ sudo apt-get install libboost-dev libboost-doc ruby-full rubygems
$ sudo gem install rubytree
```

However, Thrift needs to be installed manually and it is best to follow the online tutorial[3].
After you have successfully installed the above run the following commands from the dBug root directory:

```
$ mkdir build; cd build;
$ ./configure --with-boost=$BOOST_PREFIX --with-thrift=$THRIFT_PREFIX
$ make
$ sudo make install
```

where `$BOOST_PREFIX` and `$THRIFT_PREFIX` is the prefix of the Boost and Thrift installation respectively.

5 Examples

In the rest of the section we assume that `$DBUG_DIR` refers to the dBug distribution directory, dBug is installed on your machine and `$DBUG_PREFIX` is the prefix of dBug installation.

5.1 Sequential Example – Interactive Mode

We start with an example which runs the arbiter in the *interactive mode*. In this mode, the user is responsible for guiding the execution of the distributed and multi-threaded program. Conceptually, running the arbiter in the interactive mode corresponds to running each process of the system in `gdb`, which has breakpoints set for select coordination and communication library calls. The program used in this example is listed below and can be found in `$DBUG_DIR/tutorial/example-1.c`.

```
#include <assert.h>
#include <pthread.h>
#include <stdio.h>

int
main(int argc, char *argv[])
{
  pthread_mutex_t mutex;

  assert(pthread_mutex_init(&mutex,NULL) == 0);
  assert(pthread_mutex_lock(&mutex) == 0);
  printf("Critical section.\n");
  assert(pthread_mutex_unlock(&mutex) == 0);
  assert(pthread_mutex_destroy(&mutex) == 0);

  return 0;
}
```

[3] `http://wiki.apache.org/thrift/ThriftInstallation`

First, compile the code above into its binary form `example-1`. Second, start up the arbiter by running ”`arbiter -m 1`”. The option `-m 1` tells the arbiter to run in the interactive mode. Third, open a new terminal window and start the binary `example-1` with the interposition library preloaded by running ”`LD_PRELOAD=$DBUG_PREFIX/lib/libdbug.so ./example-1`”. Fourth, switch back to the terminal window of the arbiter. You should see output similar to:

```
user@user-VirtualBox:~$ arbiter -m 1
[   server.cc]:[...]: Strategy:
[   server.cc]:[...]:   Thread 1 registered.
[   server.cc]:[...]:   Thread 1 updated its process.
[     util.cc]:[...]: Requests:
[     util.cc]:[...]: Requests:
[     util.cc]:[...]:   Request 0:
[     util.cc]:[...]:     id:1
[     util.cc]:[...]:     func:pthread_mutex_init
[     util.cc]:[...]:     status:ENABLED
[     util.cc]:[...]:     command:RESOURCE_CREATE
```

The listing tells us that there is currently one pending call to function `pthread_mutex_init` issued by thread 1. The *status* and *command* are not important for the sake of this example and will be explained later. The interactive mode expects the user to repeatedly input an integer which identifies the thread that the user wishes to proceed next. For instance, you can step through the execution of our example by inputting 1 four times.

5.2 Concurrent Example – Interactive Mode

The next example still uses the interactive mode, but this time our example is concurrent. The program used in this example is listed below and can be found in `$DBUG_DIR/tutorial/example-2.c`.

```
#include <assert.h>
#include <pthread.h>
#include <stdio.h>

pthread_mutex_t mutex;

void *
thread(void *args)
{
  assert(pthread_mutex_lock(&mutex) == 0);
  printf("Critical section slave.\n");
  assert(pthread_mutex_unlock(&mutex) == 0);
  return NULL;
}

int
main(int argc, char *argv[])
{
  pthread_t tid;
  assert(pthread_mutex_init(&mutex,NULL) == 0);
  assert(pthread_create(&tid,NULL,thread,NULL) == 0);
  assert(pthread_mutex_lock(&mutex) == 0);
  printf("Critical section master.\n");
  assert(pthread_mutex_unlock(&mutex) == 0);
  assert(pthread_join(tid, NULL) == 0);
  assert(pthread_mutex_destroy(&mutex) == 0);

  return 0;
}
```

First, compile the code above into its binary form `example-2`. Second, start up the arbiter by running ”`arbiter -m 1`”. Third, open a new terminal window and start the binary `example-2` with the interposition library using ”`LD_PRELOAD=$DBUG_PREFIX/lib/libdbug.so ./example-2`”. Fourth, switch back to the terminal window of the arbiter and input 1 once. You should see output similar to:

```
...
[      util.cc]:[...]: Requests:
[      util.cc]:[...]:   Request 0:
[      util.cc]:[...]:     id:1
[      util.cc]:[...]:     func:pthread_mutex_lock
[      util.cc]:[...]:     status:ENABLED
[      util.cc]:[...]:     command:RESOURCE_ACCESS
[      util.cc]:[...]:   Request 1:
[      util.cc]:[...]:     id:2
[      util.cc]:[...]:     func:pthread_mutex_lock
[      util.cc]:[...]:     status:ENABLED
[      util.cc]:[...]:     command:RESOURCE_ACCESS
```

The listing tells us that there are currently two pending calls to function `pthread_mutex_lock` issued by thread 1 and thread 2. If you input 1, you should see output similar to:

```
...
[      util.cc]:[...]: Requests:
[      util.cc]:[...]:   Request 0:
[      util.cc]:[...]:     id:1
[      util.cc]:[...]:     func:pthread_mutex_unlock
[      util.cc]:[...]:     status:ENABLED
[      util.cc]:[...]:     command:RESOURCE_RELEASE
[      util.cc]:[...]:   Request 1:
[      util.cc]:[...]:     id:2
[      util.cc]:[...]:     func:pthread_mutex_lock
[      util.cc]:[...]:     status:DISABLED
[      util.cc]:[...]:     command:RESOURCE_ACCESS
```

The listing tells us that there are currently two pending calls. The first call is to function `pthread_mutex_unlock` issued by thread 1 and the second call is to function `pthread_mutex_lock` issued by thread 2. Also, notice that the status of the second call is *disabled*. This is because the arbiter keeps track of shared resources that are being accessed and recognizes when a call such as `pthread_mutex_lock` would block. If you try to input 2, the arbiter will warn you that the request of the thread 2 cannot be executed. To step through the rest of the execution, input the sequence $1, 2, 2, 1, 1$. Notice how the arbiter detects that the thread 2 cannot be joined by the thread 1 until the thread 2 returns (or exits).

5.3 Concurrent Example – Batched Mode

In this example, we will reuse the code of the previous example. However, this time instead of stepping through the program interactively, we will use the explorer to automatically explore all possible ways in which the example could have executed. In order to do this, go to the `$DBUG_DIR/tutorial/`

directory and run ”`explorer.rb --prefix $DBUG_PREFIX example-2`”. You should see output similar to:

```
user@user-VirtualBox:~/dbug$ ruby explorer.rb example-2
[EXPLORER] Iteration: 1, Elapsed: 0 s
[EXPLORER] Setting up initial state
[EXPLORER] Selecting a strategy
[EXPLORER] Empty strategy
[EXPLORER] Starting the arbiter
[EXPLORER] Waiting for the arbiter to start up...
[EXPLORER] Starting the test
[EXPLORER] Waiting for the test to finish
Critical section master.
Critical section slave.
[EXPLORER] Waiting for the arbiter to finish
[EXPLORER] Iteration: 2, Elapsed: 1 s
[EXPLORER] Setting up initial state
[EXPLORER] Selecting a strategy
[EXPLORER] Non-empty strategy
[EXPLORER] Starting the arbiter
[EXPLORER] Waiting for the arbiter to start up...
[EXPLORER] Starting the test
[EXPLORER] Waiting for the test to finish
Critical section slave.
Critical section master.
[EXPLORER] Waiting for the arbiter to finish
```

This means that the explorer explored two possible ways in which the binary `example-2` could have executed. When the explorer starts, it creates the `dbug-logs` directory. This directory is gradually populated with information about the different executions of the test. Namely, for each iteration, the `dbug-logs` directory contains the strategy (the `strategy` file) that the arbiter initially followed, the history (the `history-*` file) of the execution the arbiter explored, and detailed logs of the arbiter (the `dbug-server` file) and the interposition layer (divided into the `dbug-interposition` and `dbug-client` files). For example, the strategy file for the second iteration of the above application of the explorer looks as follows:

```
2
1 1
2 2
```

The first line identifies the number n of steps of the execution specified by the strategy. Each of the following n lines then identifies the thread to be proceed and the total number pending calls at that point.
The history file for the first iteration of the above application of explorer looks as follows:

```
1 1 1
1:pthread_mutex_init:RESOURCE_CREATE:1 0 0 0 0 0 0 0 0:1759016536:
1 2 2
1:pthread_mutex_lock:RESOURCE_ACCESS:2 0 0 0 0 0 0 0 0:1759016536:2:
2:pthread_mutex_lock:RESOURCE_ACCESS:1 1 0 0 0 0 0 0 0:1759016536:2:
1 1 2
1:pthread_mutex_unlock:RESOURCE_RELEASE:3 0 0 0 0 0 0 0 0:1759016536:
2:pthread_mutex_lock:RESOURCE_ACCESS:1 1 0 0 0 0 0 0 0:1759016536:2:
2 1 2
2:pthread_mutex_lock:RESOURCE_ACCESS:1 1 0 0 0 0 0 0 0:1759016536:2:
```

```
1:pthread_join:THREAD_JOIN:4 0 0 0 0 0 0 0 0:2:
2 1 2
2:pthread_mutex_unlock:RESOURCE_RELEASE:1 2 0 0 0 0 0 0 0:1759016536:
1:pthread_join:THREAD_JOIN:4 0 0 0 0 0 0 0 0:2:
1 1 1
1:pthread_join:THREAD_JOIN:4 0 0 0 0 0 0 0 0:2:
1 1 1
1:pthread_mutex_destroy:RESOURCE_DELETE:5 2 0 0 0 0 0 0 0:1759016536:
```

The first line identifies 1) the thread whose call was executed, 2) the number m of threads whose call could have been executed, and 3) the number n of threads with a pending call. This line is then followed with n lines – one per each pending call. Each of these lines starts with a thread ID, followed by a name of the function call, and additional information, which will not be explained in this example.

Also, besides the `logs` directory, the explorer creates the `tree.dot` file. This file can be processed by the `dot` tool[4] to produce a visualization of the decision tree that the explorer created; for instance, by running ”`dot -T pdf -o <output_name> tree.dot`”. The decision tree created by the above application of the explorer is depicted in Figure 3. The gray nodes and edges correspond to pending calls that cannot be completed from the current state of the system.

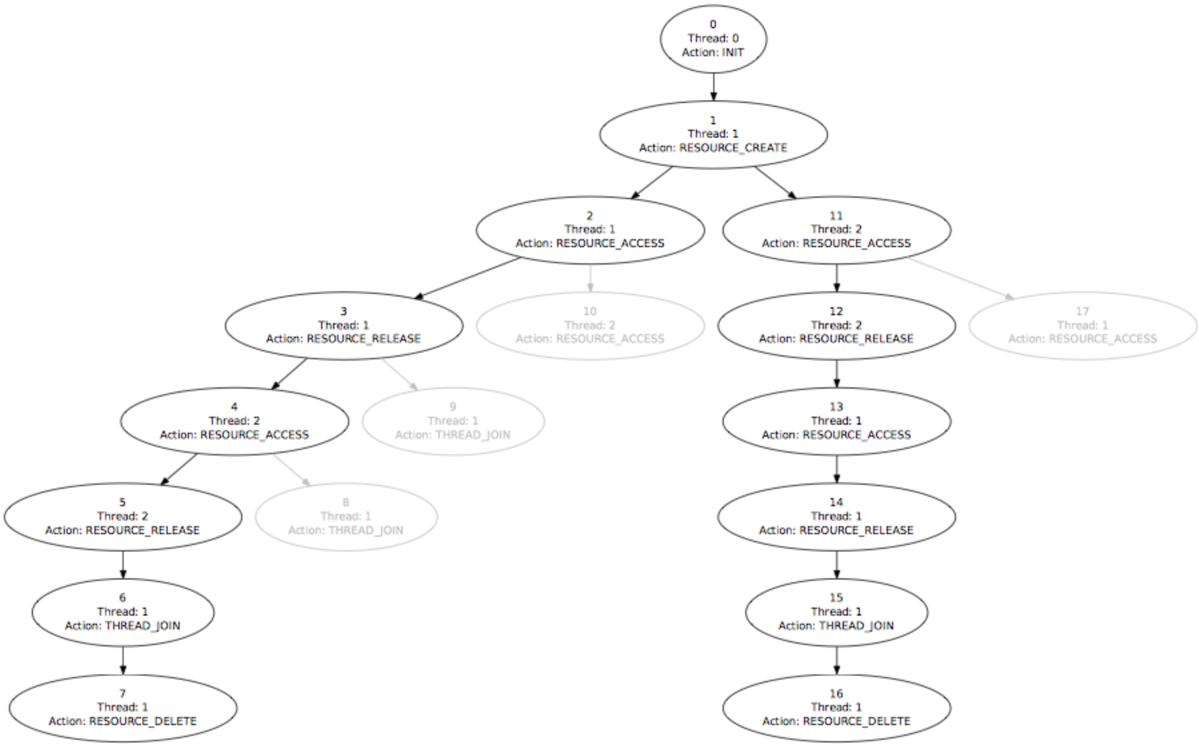

Figure 3: Decision Tree

[4] The `dot` tool is part of the graph visualization suite GraphViz by AT&T.

5.4 Concurrent Example – Deadlock

In this example, we introduce a deadlock into the previous program. We illustrate how the explorer aids us in detecting this error and identifies the sequence of events that leads to the deadlock. The program used in this example is listed below and can be found in `$DBUG_DIR/tutorial/example-3.c`.

```
#include <assert.h>
#include <pthread.h>
#include <stdio.h>

pthread_mutex_t mutex1, mutex2;

void *
thread(void *args)
{
  assert(pthread_mutex_lock(&mutex1) == 0);
  assert(pthread_mutex_lock(&mutex2) == 0);
  printf("Critical section slave.\n");
  assert(pthread_mutex_unlock(&mutex2) == 0);
  assert(pthread_mutex_unlock(&mutex1) == 0);
  return NULL;
}

int
main(int argc, char *argv[])
{
  pthread_t tid;
  assert(pthread_mutex_init(&mutex1,NULL) == 0);
  assert(pthread_mutex_init(&mutex2,NULL) == 0);
  assert(pthread_create(&tid,NULL,thread,NULL) == 0);
  assert(pthread_mutex_lock(&mutex2) == 0);
  assert(pthread_mutex_lock(&mutex1) == 0);
  printf("Critical section master.\n");
  assert(pthread_mutex_unlock(&mutex1) == 0);
  assert(pthread_mutex_unlock(&mutex2) == 0);
  assert(pthread_join(tid, NULL) == 0);
  assert(pthread_mutex_destroy(&mutex2) == 0);
  assert(pthread_mutex_destroy(&mutex2) == 0);

  return 0;
}
```

Similarly to the previous example, let us compile the code above into its binary form `example-3` and run ”`explorer.rb --prefix $DBUG_PREFIX example-3`”. The explorer explores a total of 6 iterations. In order to check whether any iteration encountered an error, one can use the following command ”`grep WARNING dbug-logs/dbug-server*`”. In our case the command outputs a listing similar to:

```
user@user-VirtualBox:~/dbug$ grep WARNING dbug-logs/dbug-server*
logs/dbug-server-3:[...]: [WARNING] Encountered a concurrency error
logs/dbug-server-4:[...]: [WARNING] Encountered a concurrency error
```

The warning messages imply that during two iterations the arbiter encountered an error. In order to investigate the error, one can look at the history file. In our example, the contents of `dbug-logs/history-3` look as follows:

```
1 1 1
1:pthread_mutex_init:RESOURCE_CREATE:1 0 0 0 0 0 0 0 0:2539669330:
1 1 1
1:pthread_mutex_init:RESOURCE_CREATE:2 0 0 0 0 0 0 0 0:2454919772:
2 2 2
2:pthread_mutex_lock:RESOURCE_ACCESS:2 1 0 0 0 0 0 0 0:2539669330:2:
1:pthread_mutex_lock:RESOURCE_ACCESS:3 0 0 0 0 0 0 0 0:2454919772:2:
1 2 2
1:pthread_mutex_lock:RESOURCE_ACCESS:3 0 0 0 0 0 0 0 0:2454919772:2:
2:pthread_mutex_lock:RESOURCE_ACCESS:2 2 0 0 0 0 0 0 0:2454919772:2:
-1 0 2
1:pthread_mutex_lock:RESOURCE_ACCESS:4 0 0 0 0 0 0 0 0:2539669330:2:
2:pthread_mutex_lock:RESOURCE_ACCESS:2 2 0 0 0 0 0 0 0:2454919772:2:
```

The last three lines identify the problem. At that point in the execution, no pending function call can execute. In other words, the execution reached a deadlock. Inspecting the order in which events happened tells us that this is the case when the thread 2 acquires the `mutex1` and then the thread 1 acquires the `mutex2`, creating a circular dependency.

5.5 Concurrent Example – Data Race

In this example, we modify the running example to introduce a data race and we illustrate how the explorer aids us in detecting this error. The program used in this example is listed below and can be found in `$DBUG_DIR/tutorial/example-4.c`.

```
#include <assert.h>
#include <pthread.h>
#include <stdio.h>
#include <string.h>

void *
thread(void *args)
{
  char text[4] = "1:2";
  printf("%s\n", strtok(text,":"));
  printf("%s\n", strtok(NULL,":"));
  return NULL;
}

int
main(int argc, char *argv[])
{
  pthread_t tid;
  char text[4] = "1:2";
  assert(pthread_create(&tid,NULL,thread,NULL) == 0);
  printf("%s\n", strtok(text,":"));
  printf("%s\n", strtok(NULL,":"));
  assert(pthread_join(tid, NULL) == 0);

  return 0;
}
```

Similarly to the previous example, let us compile the code above into its binary form `example-4` and run ”`explorer.rb --prefix $DBUG_PREFIX example-4`”. The explorer explores a total of 2 iterations. In order to check whether any iteration encountered an error, one can again use the command "`grep WARNING dbug-logs/dbug-server*`". In our case the command outputs a listing similar to:

```
user@user-VirtualBox:~/dbug$ grep WARNING logs/dbug-server*
logs/dbug-server-1:[...]: [WARNING] Concurrent non-reentrant function calls
logs/dbug-server-2:[...]: [WARNING] Concurrent non-reentrant function calls
```

The warning messages imply that during two iterations the arbiter encountered an error. In order to investigate the error, one can look at the history file. In our example, the contents of `dbug-logs/history-1` look as follows:

```
-2 2 2
1:strtok:NONREENTRANT_FUNCTION:1 0 0 0 0 0 0 0 0:
2:strtok:NONREENTRANT_FUNCTION:0 1 0 0 0 0 0 0 0:
```

The three lines identify the problem. At that point in the execution, there are two pending function calls to a function that is not guaranteed (by standard or implementation) to be reentrant. In other words, there is a potential data race in the program.

Appendix

A Supported Library Calls

The following is a list of library calls that dBug intercepts. Some of these calls are intercepted only for book-keeping purposes and the order in which they execute is not controlled by the centralized scheduler. For each call we include a short description of the activity that happens upon intercepting the call. Your system and tests are free to use any other library calls. However, the use of unsupported communication, coordination, or blocking primitives can have unexpected consequences. In particular:

- If your system and its tests use unsupported communication and/or coordination primitives, dBug will not explore all possible orders in which concurrent calls to these unsupported primitives could execute. This can result in failing to discover data races that result from ordering events at a finer granularity than that of dBug.

- If your system and its tests use unsupported blocking primitives, the use of dBug could result in false deadlocks. For example, consider the following scenario. There are two threads A and B running in a system. Thread A invokes a call intercepted by dBug, while thread B invokes an unsupported blocking call. In order for the unsupported blocking call to return, the execution of thread A needs to resume. However, this does not happen until the arbiter receives a pending request from every thread of the system. Thus, there is now a circular dependency as the thread A waits for the arbiter, who waits for the thread B, who waits for the thread A.

A.1 POSIX Threads Barriers

Only the default values of barrier attributes are supported.

- **pthread_barrier_init** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter creates an abstract barrier resource. This abstract resource allows arbiter to determine when a call to **pthread_barrier_wait** would return.

- **pthread_barrier_wait** – Controlled by the arbiter. The pending calls to this routine are postponed until the threshold specified in **pthread_barrier_init** is reached.

- **pthread_barrier_destroy** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter deletes the corresponding abstract barrier resource.

A.2 POSIX Threads Conditional Variables

Only the default values of conditional variable attributes are supported.

- **pthread_cond_init** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter creates an abstract conditional variable resource. This abstract resource allows arbiter to determine when a call to **pthread_cond_wait** and **pthread_cond_timedwait** would return.

- **pthread_cond_wait** – Controlled by the arbiter. The pending calls to this routine are postponed until a matching *signal* or*broadcast* event has been received.

- **pthread_cond_timedwait** – Controlled by the arbiter. The pending calls to this routine are postponed until a matching *signal* or*broadcast* event has been received or the arbiter decides to let the call time out.

- **pthread_cond_broadcast**, **pthread_cond_signal** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter records this event with the corresponding abstract conditional variable resource.

- **pthread_cond_destroy** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter deletes the corresponding abstract conditional variable resource.

A.3 POSIX Threads Keys

- **pthread_key_create** – Bookkeeping only. Upon intercepting a call to this routine, the interposition layer creates an abstract key resource. This abstract resource allows the interposition layer to determine if a call to **pthread_getspecific** and **pthread_setspecific** accesses an existing key.

- **pthread_getspecific**, **pthread_setspecific** – Bookkeeping only. Upon intercepting a call to this routine, the interposition layer checks if the corresponding key exists.

- **pthread_key_delete** – Bookkeeping only. Upon intercepting a call to this routine, the interposition layer deletes the corresponding abstract key resource.

A.4 POSIX Threads Management

Only the default values of thread attributes are supported.

- **pthread_create** – Bookkeeping only. The arbiter is notified about the creation of a new thread.

- **pthread_detach**, **pthread_exit** – Bookkeeping only. The arbiter is notified about the thread status change.

- **pthread_join** – Controlled by the arbiter. The pending calls to this routine are postponed until the appropriate thread becomes joinable. To this end, the arbiter collects information about thread status changes by intercepting the above routines.

A.5 POSIX Threads Mutexes

Only the default values of mutex attributes are supported.

- **pthread_mutex_init** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter creates an abstract mutex resource. This abstract resource allows arbiter to keep track of ownership of the mutex.

- **pthread_mutex_lock** – Controlled by the arbiter. The pending calls to this routine are postponed until the mutex becomes available.

- **pthread_mutex_timedlock** – Controlled by the arbiter. The pending calls to this routine are postponed until the mutex becomes available or the arbiter decides to let the call time out.

- **pthread_mutex_trylock** – Controlled by the arbiter. The pending calls to this routine acquire the mutex if it is available or return failure otherwise.
- **pthread_mutex_unlock** – Controlled by the arbiter. The pending calls to this routine give up the ownership of the mutex.
- **pthread_mutex_destroy** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter deletes the corresponding abstract mutex resource.

A.6 POSIX Threads Read/Write Locks

Only the default values of read/write lock attributes are supported.

- **pthread_rwlock_init** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter creates an abstract read/write lock resource. This abstract resource allows arbiter to keep track of ownership of the lock.
- **pthread_rwlock_rdlock** – Controlled by the arbiter. The pending calls to this routine are postponed until the lock can be shared with the calling thread.
- **pthread_rwlock_timedrdlock** – Controlled by the arbiter. The pending calls to this routine are postponed until the lock can be shared with the calling thread or the arbiter decides to let this call time out.
- **pthread_rwlock_tryrdlock** – Controlled by the arbiter. The pending calls to this routine either acquire shared access to this lock if possible or return failure otherwise.
- **pthread_rwlock_wrlock** – Controlled by the arbiter. The pending calls to this routine are postponed until the lock can be held exclusively by the calling thread.
- **pthread_rwlock_timedwrlock** Controlled by the arbiter. The pending calls to this routine are postponed until the lock can be held exclusively by the calling thread or the arbiter decides to let his call time out.
- **pthread_rwlock_trywrlock** – Controlled by the arbiter. The pending calls to this routine either acquire exclusive access to this lock if possible or return failure otherwise.
- **pthread_rwlock_unlock** – Controlled by the arbiter. The pending calls to this routine give up its access rights for the lock.
- **pthread_rwlock_destroy** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter deletes the corresponding abstract read/write lock resource.

A.7 POSIX Threads Spin Locks

Only the default values of spin lock attributes are supported.

- **pthread_spin_init** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter creates an abstract spin lock resource. This abstract resource allows arbiter to keep track of ownership of the lock.
- **pthread_spin_lock** – Controlled by the arbiter. The pending calls to this routine are postponed until the lock becomes available.

- **pthread_spin_trylock** – Controlled by the arbiter. The pending calls to this routine acquire the lock if it is available or return failure otherwise.
- **pthread_spin_unlock** – Controlled by the arbiter. The pending calls to this routine give up the ownership of the mutex.
- **pthread_spin_destroy** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter deletes the corresponding abstract spin lock resource.

A.8 Process Management

- **execl**, **execlp**, **execle**, **execv**, **execvp**, **execve** – Bookkeeping only. Arbiter is notified that all threads running as part of the calling process terminate and a new thread is started.
- **_exit**, **_Exit** – Bookkeeping only. Normally, when a process is terminated, a destructor routine of the interposition layer is called. The destructor routine notifies the arbiter that the calling process terminated. However, a call to this routine bypasses this mechanism. Consequently, upon intercepting a call to this routine, the destructor routine is triggered explicitly.
- **fork** – Bookkeeping only. The arbiter is notified about the creation of a new process.
- **posix_spawn**, **posix_spawnp** – Bookkeeping only. The arbiter is notified about the creation of a new process.
- **setpgid**, **setpgrp**, **setsid** – Bookkeeping only. The arbiter is notified about the change of process group ID.
- **wait** – Controlled by the arbiter. Because the **wait** call is potentially blocking, the arbiter collects information from the running processes that allow the arbiter to determine when the call can complete. This is achieved by having the interposition layer detect changes in process status by intercepting certain function calls and signals and notifying the arbiter about these events.
- **waitpid** – Controlled by the arbiter. On top of the needs of **wait**, the **waitpid** call requires the arbiter to keep track of the process IDs and process group IDs for every process. Again, this is achieved by having the interposition layer detect creation of new processes and changes in process group membership and notifying the arbiter about these events.

A.9 Semaphores

Only the default values of semaphore attributes are supported.

- **sem_init**, **sem_open** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter creates an abstract (un)named semaphore resource. This abstract resource allows arbiter to match wait and post semaphore operations.
- **sem_post** Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter increases the value of the semaphore.
- **sem_wait** Controlled by the arbiter. The pending calls to this routine are postponed until the value of the semaphore is positive. Upon servicing a pending call to this routine, the arbiter decreases the value of the semaphore.

- **sem_close**, **sem_unlink** – Controlled by the arbiter. Upon matching the last close operation with an open operation, a pending unlink operation causes the arbiter deletes the corresponding abstract named semaphore resource.

- **sem_destroy** – Controlled by the arbiter. Upon servicing a pending call to this routine, the arbiter deletes the corresponding abstract unnamed semaphore resource.

A.10 Memory Management

- **calloc**, **free**, **malloc**, **realloc** – Bookkeeping only. The interposition layer keeps track of (re)allocated pointers. This is used to check that each allocated pointer is freed exactly once and no other pointer is attempted to be freed[5].

A.11 Non-reentrant Functions

Certain functions are not required to be reentrant by the POSIX standard. Consequently, the arbiter controls the order in which they execute and issues a warning if multiple threads of the same process try to concurrently execute the same non-reentrant function. The list of non-reentrant functions controlled by the arbiter includes: **gethostbyname**, **gethostbyaddr**, **strtok**, and **inet_ntoa**.

A.12 Miscellaneous

Certain library calls are used by dBug internally. In order to avoid introducing false positives, dBug needs to intercept calls to the following list of functions: **getaddrinfo**, **freeaddrinfo**.

[5] For much more thorough testing of the use of dynamic memory we recommend using the Valgrind tool.