

# AR-B5432 Board

**EPIC SBC supports Intel ATOM N270 Processor  
with Dual Gigabit LANs / LCD / TV out / DVI**

## User Manual

**Manual Rev.:** 1.0

**Book Number:** AR-B5432-2009.08.06

## Revision

Version	Date	Author	Description
1.0	2009.08.06	Xavier	Initial release.

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Manual's first edition:

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# Table of Contents

<b>1 Introduction .....</b>	<b>5</b>
1.1 Specifications .....	6
1.2 Package Contents .....	7
1.3 Block Diagram .....	8
<b>2 H/W Information .....</b>	<b>9</b>
2.1 Locations (Top Side).....	9
2.2 Locations (Bottom Side).....	10
2.3 Connector and Jumper Setting.....	11
<b>3 Bios Setting .....</b>	<b>16</b>
3.1 Main Setup .....	17
3.2 Advanced Setup .....	18
3.3 Power Setup .....	19
3.4 PnP/PCI Setup .....	20
3.5 Peripherals Setup.....	21
3.6 PC Health Setup .....	22
3.7 Boot Setup .....	23
3.8 Exit Setup.....	24
<b>4 BIOS Refreshing, WatchDog and GPIO Programming .....</b>	<b>26</b>
4.1 BIOS Refreshing.....	26
4.2 WatchDog Programming .....	27
4.3 GPIO Programming .....	31
<b>5 Electrical Characteristics .....</b>	<b>36</b>
5.1 Basic Electrical Characteristics Table.....	36

# 1 INTRODUCTION

Welcome to the AR-B5432 Computer. The AR-B5432 is a Intel 945GSE chipset based platform designed for low power consumption and wide operating temperature. It supports the Atom N270 processor, while coming with a 533MHz Front Side Bus.

## 1.1 Specifications

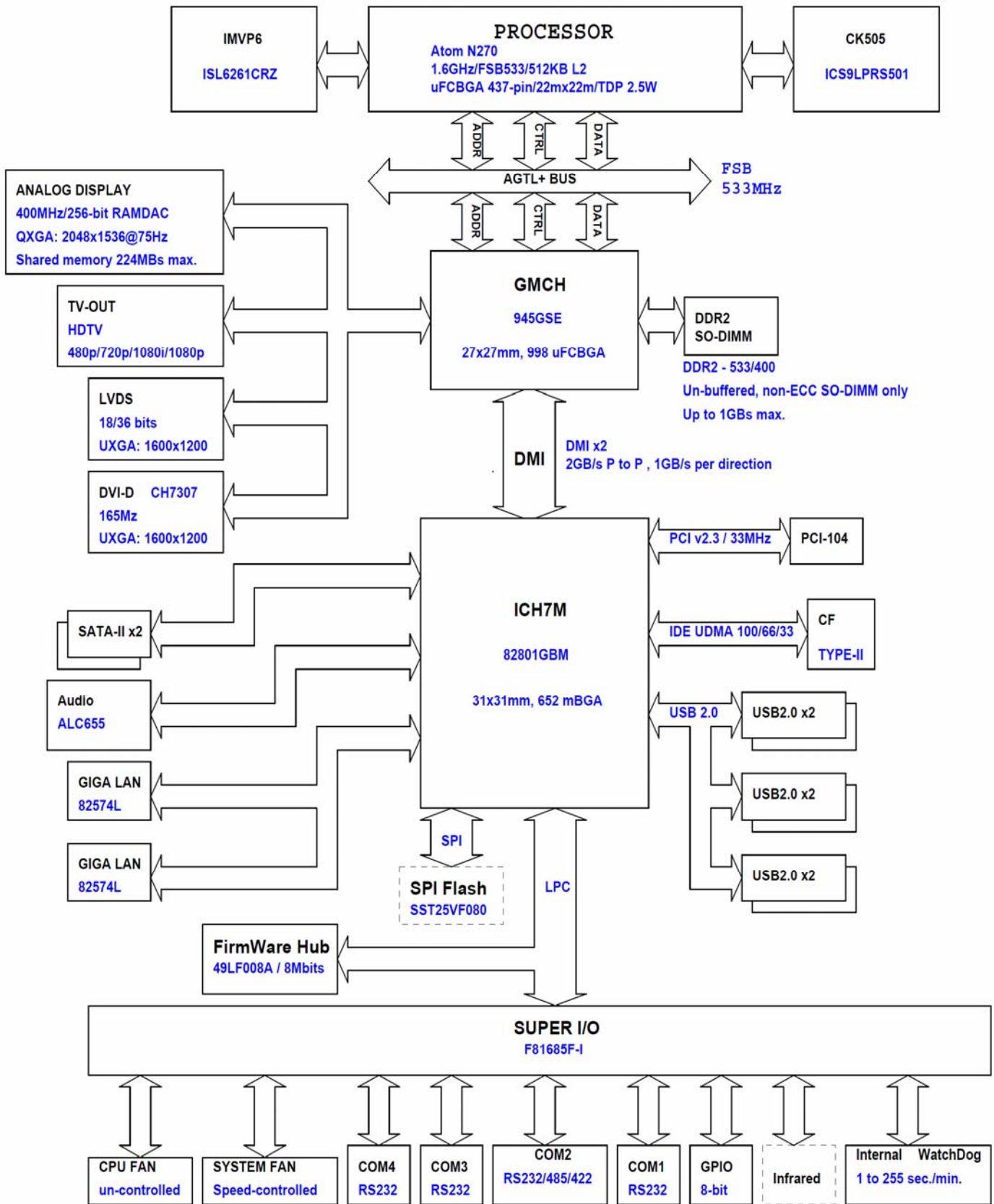
- **Processor: on-board Intel Atom N270**
  - Single core and supports 2-Threads.
  - 1.6GHz core frequency.
  - 533MHz FSB.
  - 512KBs L2 cache.
  - 2.5W low TDP.
- **Chipset-North Bridge: Intel 945GSE**
  - One SODIMM socket supports DDR II 533/400 SODIMM and capacity up to 1GBs max.
  - DVMT 3.0 supports 224MBs graphics memory max. (shared with system memory).
  - Analog display supports 400MHz/256-bit RAMDAC, resolution QXGA (2048x1536@75Hz).
  - 18-bit/36-bit LVDS supports Single/Dual channel LCD, resolution UXGA (1600x1200).
  - DVI-D supports 165MHz pixel rate max., resolution UXGA (1600x1200).
- **Chipset-South Bridge: Intel 82801GM**
  - Two SATA II connectors.
  - AC'97 Codec ALC655 supports 5.1 CH. audio output.
  - Two PCI-e GbE controllers - Intel 82574L - support 1000/100/10 Mbps LANs.
  - Six USB2.0 ports.
  - Supports +3.3V CompactFlash Type II card with Ultra-DMA mode 2/1/0.
  - PCI-104 supports four PCI devices with PCI Bus Master mode.
- **Super I/O: F81865F-I**
  - Internal WatchDog, programmable 1~255 second(s)/minute(s).
  - 8 bits programmable bi-direction GPIOs, TTL-3.3V.
  - Four serial ports, one supports RS232/485/422.
  - One Serial Infrared (SIR), baud rate 115.2K bps max. **(optional)**.
  - Two DC fan connectors, one supports ON/OFF control by system temperature.
  - Hardware monitor for voltage, fan speed and temperature.
- **Others**
  - Power requirement: +12Vdc input only **(+12V@2.1A typically)**.
  - Operating temperature: -40~75°C (-40~167°F). **[cold-start @ -20~75°C (-4~167°F)]**.
  - Storage temperature: -40~85°C (-40~185°F).
  - Relative humidity: 0~90%@40°C (104°F), non-condensing.
  - Dimension: 165 mm x 115 mm.

## 1.2 Package Contents

Check if the following items are included in the package.

- AR-B5432 EPIC SBC board
- Quick Manual
- Software Utility CD

### 1.3 Block Diagram

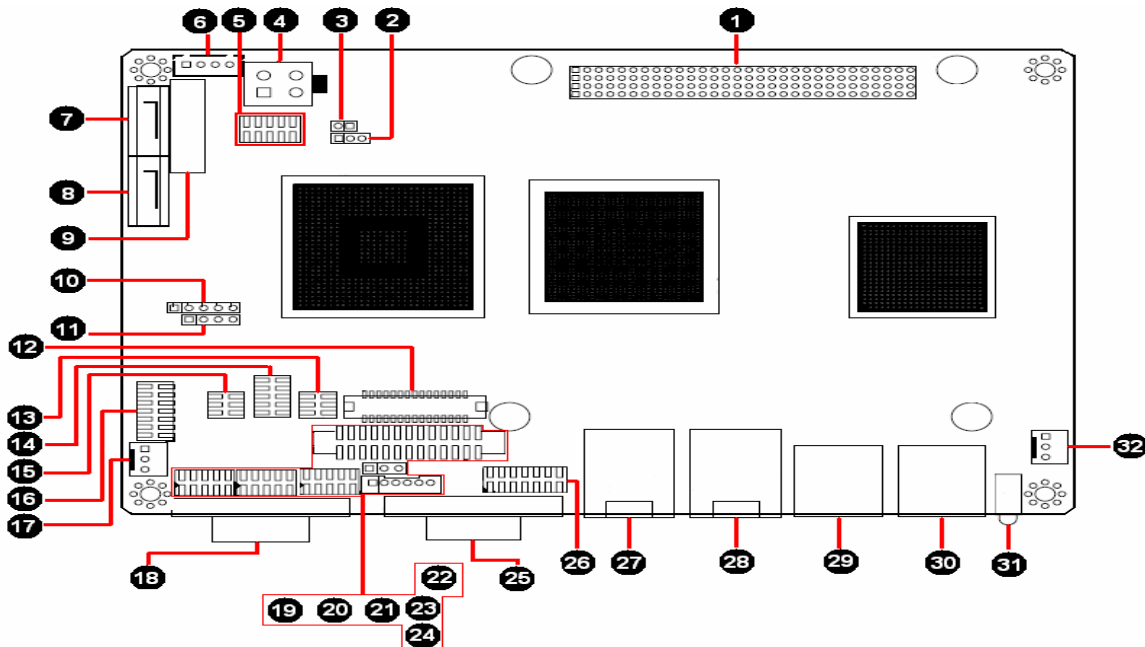




# 2 H/W INFORMATION

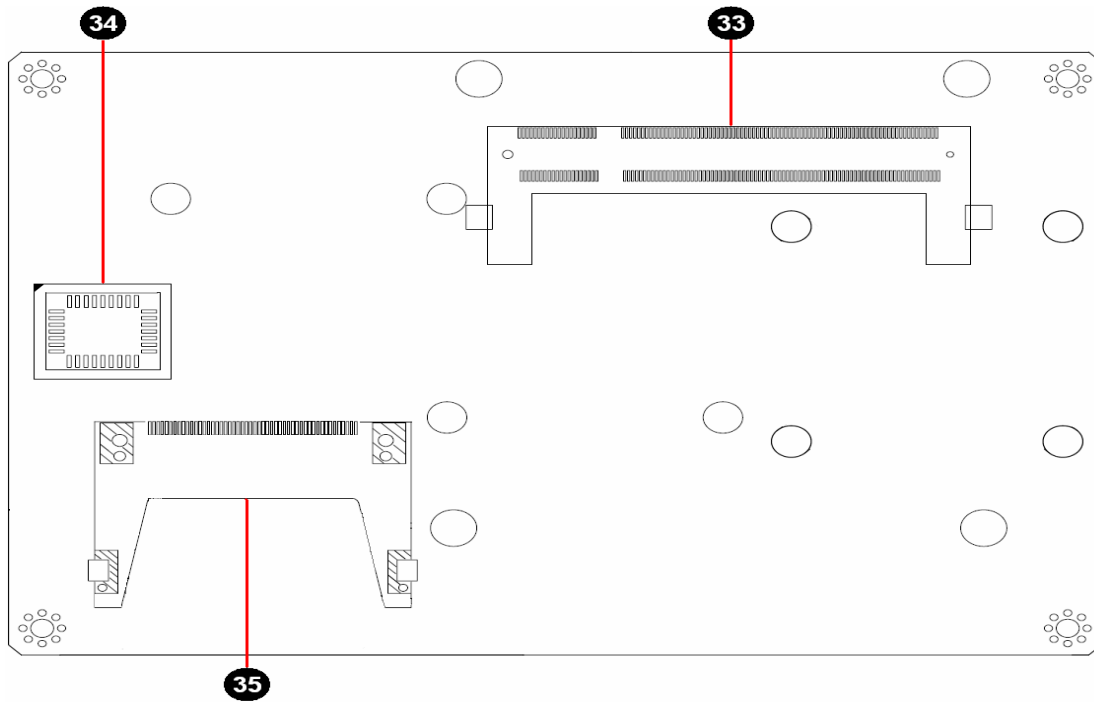
This chapter describes the installation of AR-B5432. First, it shows the function diagram and the layout of AR-B5432. Then describes the unpacking information which you should read carefully, as well as the jumper/switch settings for the AR-B5432 configuration.

## 2.1 Locations (Top Side)



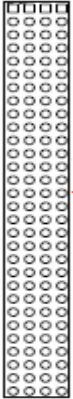





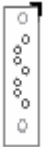

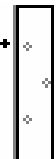
① CN2	⑫ LVDS1	⑳ PWR2
② JP2	⑬ CN7	㉑ PWR1
③ JP3	⑭ GPIO1	㉒ VGA1
④ PWR5	⑮ JP5	㉓ CN1
⑤ CN4	⑯ AUDIO1	㉔ LAN1
⑥ PWR3	⑰ SYSFAN1	㉕ LAN2
⑦ SATA1	⑱ COM1	㉖ CN3
⑧ SATA2	⑲ COM4	㉗ CN8
⑨ BAT1	㉘ COM3	㉙ LED1
⑩ IR1	㉚ COM2	㉛ CPUFAN1
⑪ CN6	㉜ DVI-D1	

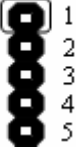
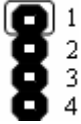
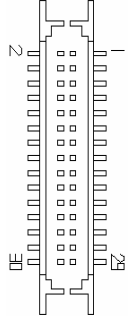



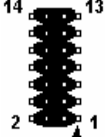

## 2.2 Locations (Bottom Side)







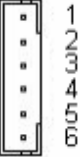
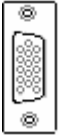
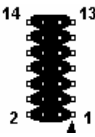







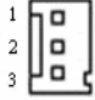
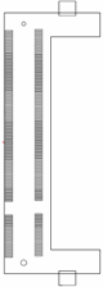
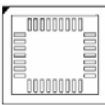
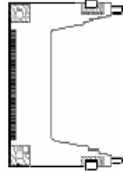
<b>33</b>	<b>SODIMM1</b>
<b>34</b>	<b>SKT1</b>
<b>35</b>	<b>CF1</b>

## 2.3 Connector and Jumper Setting

<b>1. CN2: PCI-104 connector.</b>		<b>2. JP2: CMOS data retention/clear.</b>		<b>3. JP3: Signal SERIRQ connects to PCI-104 pin #B1 selection.</b>																																										
 <p>PCI-104 connector.</p>		<table border="1"> <thead> <tr> <th>STATUS</th> <th>SETTING</th> </tr> </thead> <tbody> <tr> <td>1-2</td> <td>CMOS data retention. (Default).</td> </tr> <tr> <td>2-3</td> <td>CMOS data reset.</td> </tr> </tbody> </table>	STATUS	SETTING	1-2	CMOS data retention. (Default).	2-3	CMOS data reset.		<table border="1"> <thead> <tr> <th>STATUS</th> <th>SETTING</th> </tr> </thead> <tbody> <tr> <td>Open</td> <td>Disconnected. (Default)</td> </tr> <tr> <td>Short</td> <td>Connected.</td> </tr> </tbody> </table>	STATUS	SETTING	Open	Disconnected. (Default)	Short	Connected.																														
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<b>4. PWR5: External +12V DC power input connector.</b>		<b>5. CN4: Internal USB2.0 connector for USB2.0 port #3, port #4.</b>		<b>6. PWR3: Extra +12V and +5V DC power output connector (for SATA device).</b>																																										
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<b>7. SATA1: SATA device connector #1.</b>		<b>8. SATA2: SATA device connector #2.</b>		<b>9. BAT1: CMOS battery holder.</b>																																										
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<b>10. IR1: Infrared device connector. (Optional)</b>		<b>11. CN6: RS422/RS485 signal connector.</b>		<b>12. LVDS1: LCD panel (LVDS, 18-bit/36-bit) connector.</b>																																																																																							
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<b>13. CN7: Front panel connector. (NOTE 1)</b>		<b>14. GPIO1: 8-bit TTL-3.3V GPIO connector.</b>																																																																																									
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<b>18. COM1: D-SUB-9 male connector for RS232 port #1.</b>		<b>19. COM4: RS232 signal connector for port #4.</b>		<b>20. COM3: RS232 signal connector for port #3.</b>																																																																																							
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27. LAN1: RJ45 connector for Gigabit Ethernet port #1.		28. LAN2: RJ45 connector for Gigabit Ethernet port #2.		29. CN3: USB A-type stack connector for USB2.0 port #1, port #2.									
	RJ45 connector for Gigabit Ethernet port #1. Wake-On-LAN supported.		RJ45 connector for Gigabit Ethernet port #2.		Upper: Port #2. Lower: Port #1.								
30. CN8: USB A-type stack connector for USB2.0 port #5, port #6.		31. LED1: System standby power and HDD access indicators.		32. CPUFAN1: CPU DC fan connector.									
	Upper: Port #6. Lower: Port #5.		Green: Standby power indicator. Yellow: HDD access indicator.		<table border="1" style="width: 100%; border-collapse: collapse;"> <thead> <tr style="background-color: #cccccc;"> <th style="text-align: center;">PIN</th> <th style="text-align: center;">SETTING</th> </tr> </thead> <tbody> <tr> <td style="text-align: center;">1</td> <td style="text-align: center;">GND</td> </tr> <tr> <td style="text-align: center;">2</td> <td style="text-align: center;">+12V</td> </tr> <tr> <td style="text-align: center;">3</td> <td style="text-align: center;">Fan speed data</td> </tr> </tbody> </table>	PIN	SETTING	1	GND	2	+12V	3	Fan speed data
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33. SODIMM1: 200-pin un-buffered DDR II SODIMM socket.		34. SKT1: 32-PLCC socket for flash EEPROM (system BIOS access).		35. CF1: Type II compact flash card socket.									
	Supports DDR II 533/400MHz un-buffered and non-ECC SODIMM. Capacity is 2GBs max.		32-PLCC socket for flash EEPROM.		+3.3V CF card only and UDMA mode supported.								

**NOTE 1:**

**CN7: Front panel connector.**



STATUS	SETTING
1	External buzzer.
2	1: Buzz + 2: Buzz -
3-4	Hardware reset
5-6	Power button for ATX mode; jumper shorted for AT mode.

When using **AT mode** in the system, the pin5-6 of header **CN7** must be shorted. If using **ATX mode** in the system, the pin5-6 of header **CN7** should connect to a **Push-Button-Switch**.

**NOTE: When using AT mode, the monitor will not display any message and the system will not auto-shut down after soft-off. In this case, please cut the PSU's power off or remove PSU's power to cut the system power off.**

## 3 BIOS SETTING

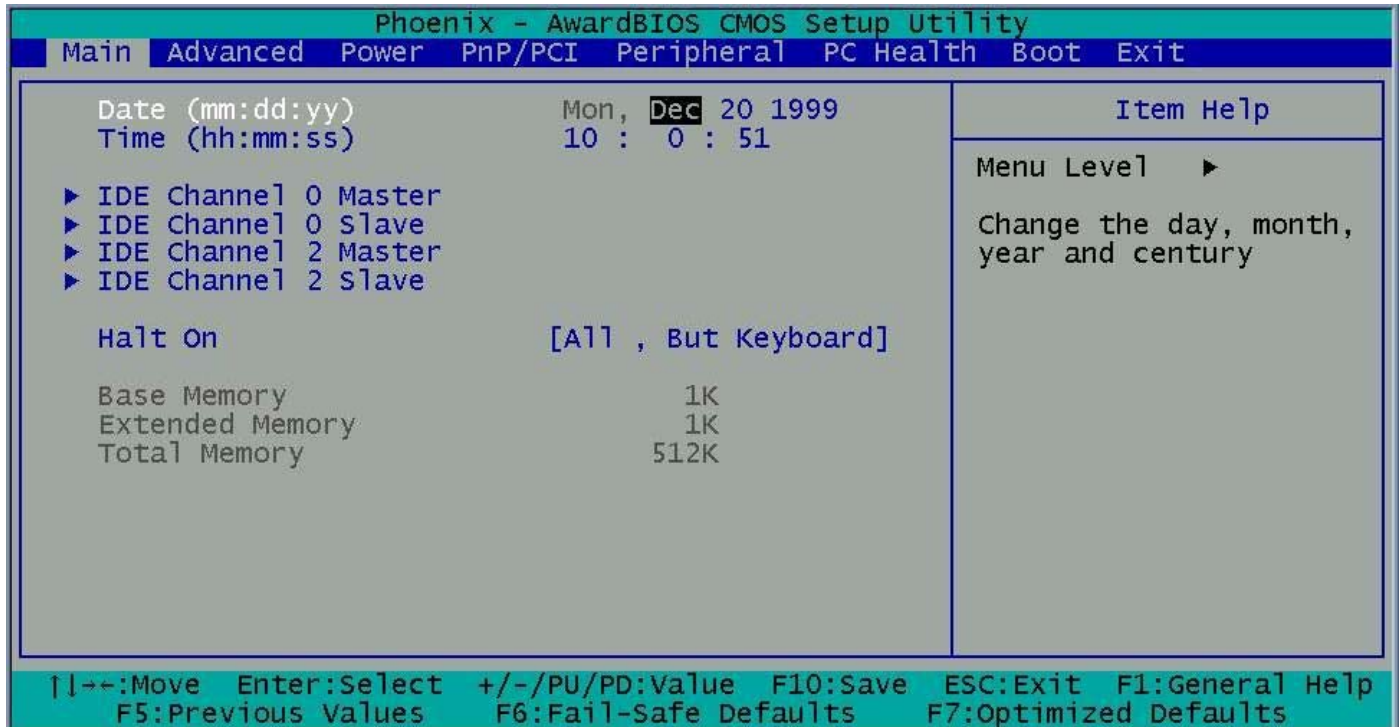
This chapter describes the BIOS menu displays and explains how to perform common tasks needed to get the system up and running. It also gives detailed explanation of the elements found in each of the BIOS menu displays. The following topics are covered:

- Main Setup
- Advanced Setup
- Power Setup
- PnP/PCI Setup
- Peripherals Setup
- PC Health Setup
- Boot Setup
- Exit Setup

Once you enter the BIOS CMOS setup utility, you can use the control keys that listed at the bottom of the menu to select the desired value in each item.

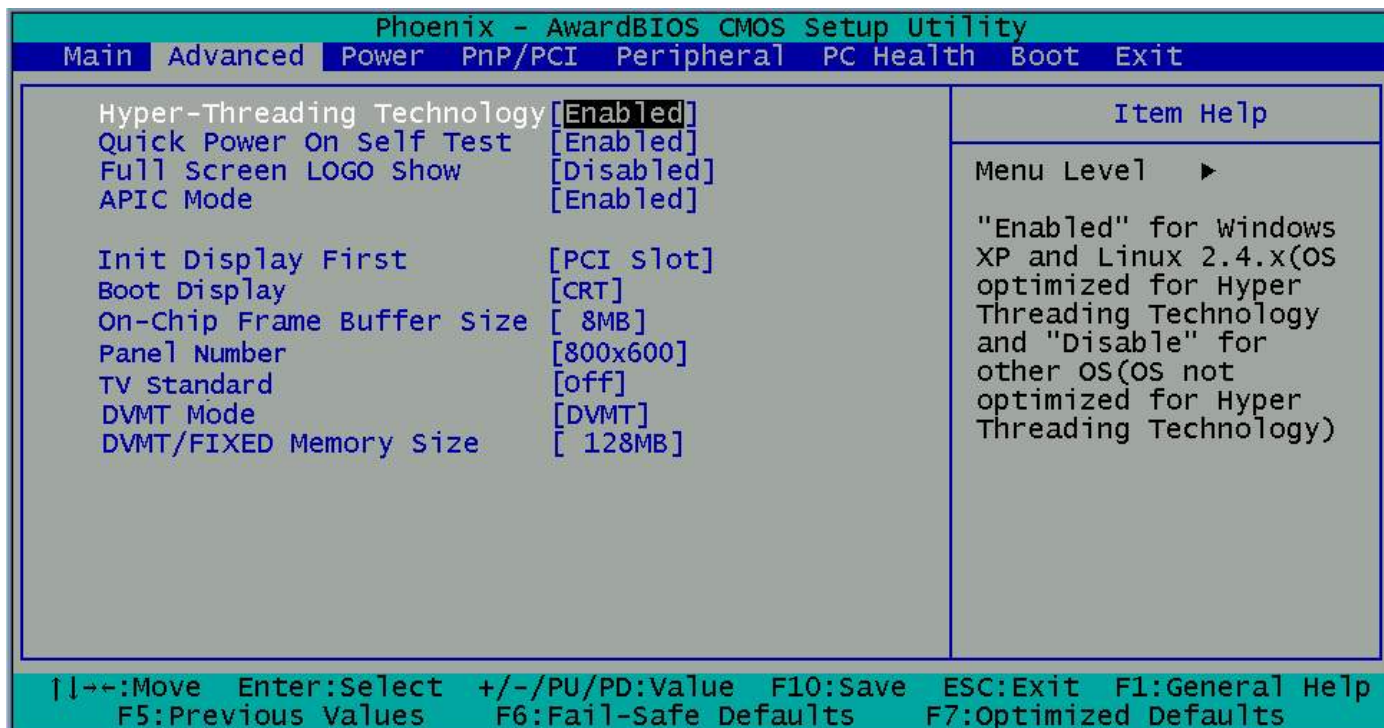


### 3.1 Main Setup



Option	Choice	Description
Date Setup	N/A	To set the system date. Note that the 'Day' automatically changes when you set the date.
Time Setup	N/A	To set the system time.
IDE Channel 0 Master/Slave IDE Channel 2 Master/Slave	N/A	Press <Enter> to view the IDE device's information and related parameters.
Halt On	All Errors, No Errors, All, But keyboard.	To select the situation in which you want the BIOS to stop the POST process and notify you.

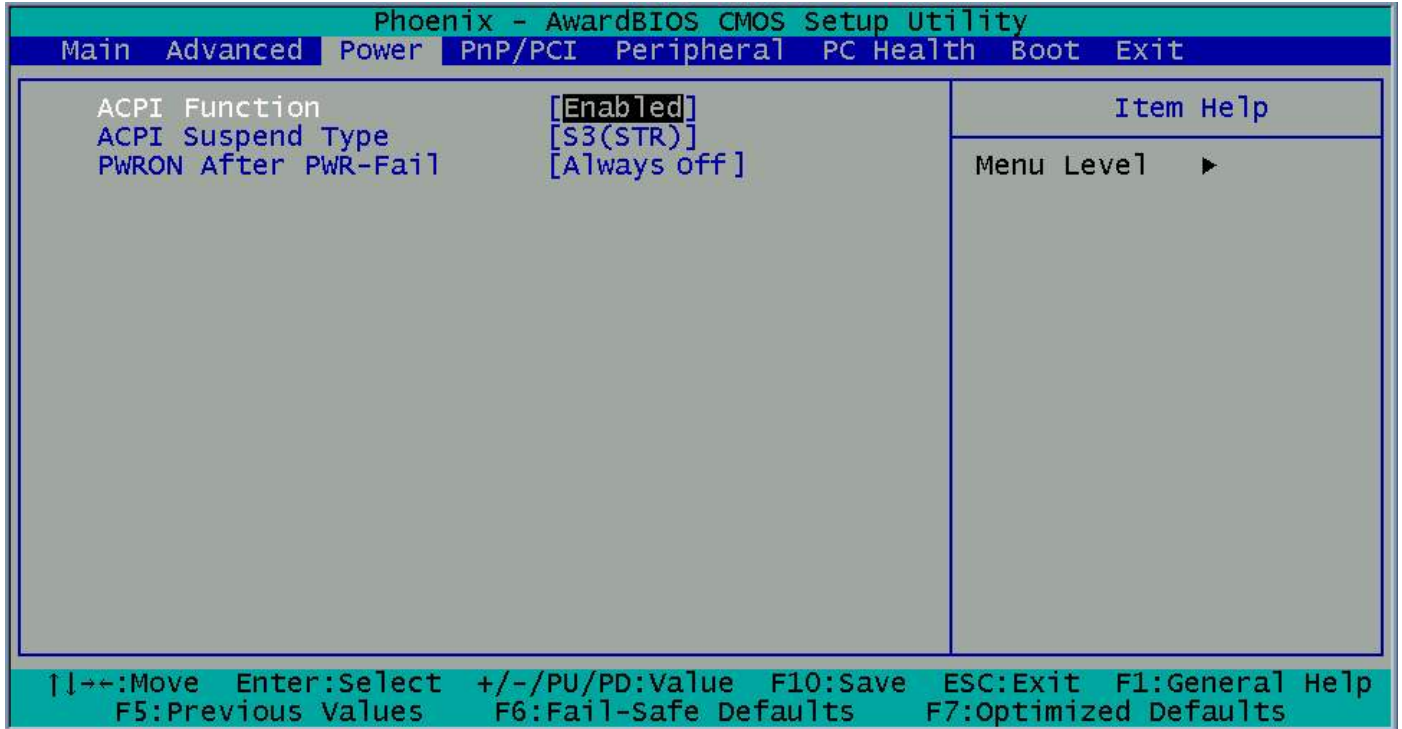
### 3.2 Advanced Setup



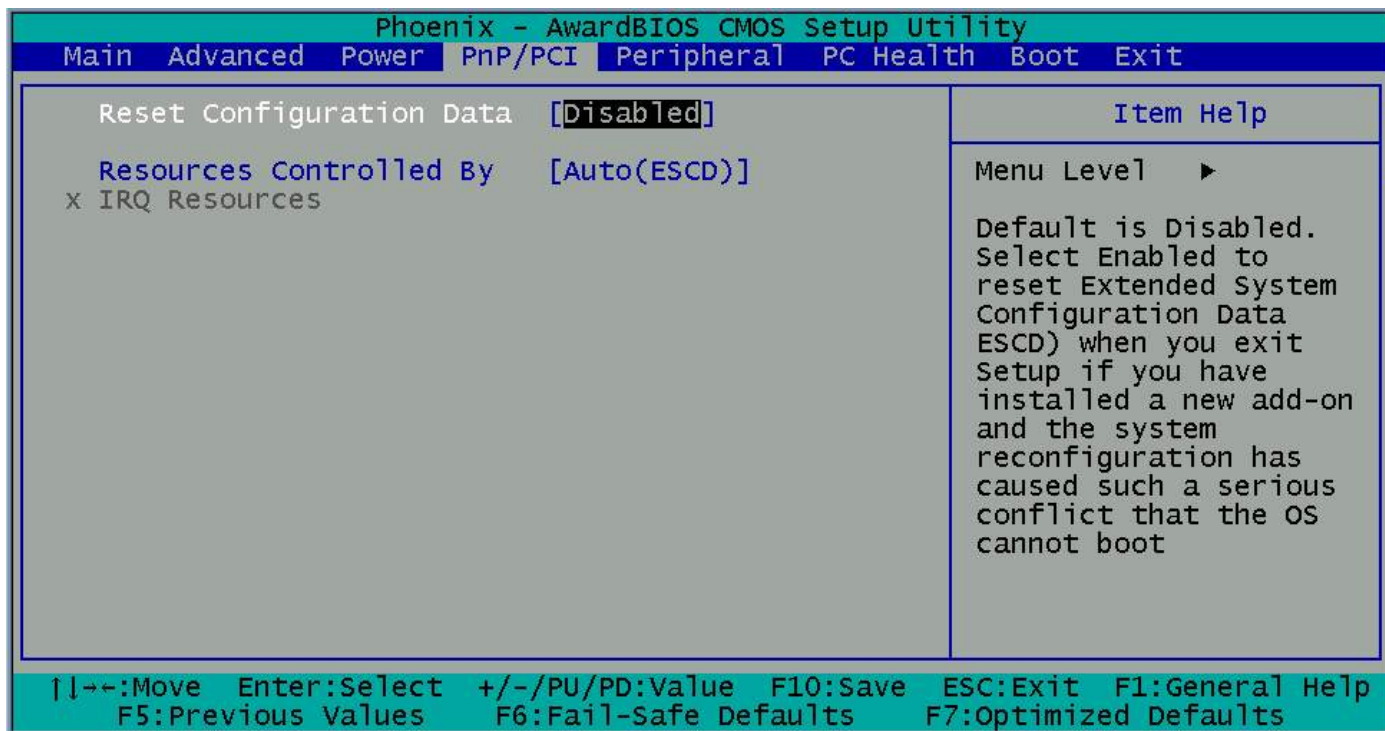
Option	Choice	Description
<b>Quick Power On Self Test</b>	Enabled Disabled	This category speeds up Power On Self Test (POST) after you have powered up the computer. If it is set to <i>Enabled</i> , BIOS will shorten or skip some check items during POST.
<b>Full Screen Logo Show</b>	Enabled Disabled	Select <i>Enabled</i> to show the OEM full screen logo if you have add-in BIOS.
<b>Boot Display</b>	CRT LVDS CRT+LVDS DVI TV CRT+DVI	To set the display device.
<b>Panel Type</b>	800x600 1024x768	To set the LVDS panel resolution that you want.
<b>DVMT mode</b>	FIXED DVMT Both	To set the mode of Dynamic Video Memory Technology (DVMT).

DVMT/FIXED Memory Size	64MB	To set the shared memory size for DVMT.
	128MB	
	224MB	

### 3.3 Power Setup

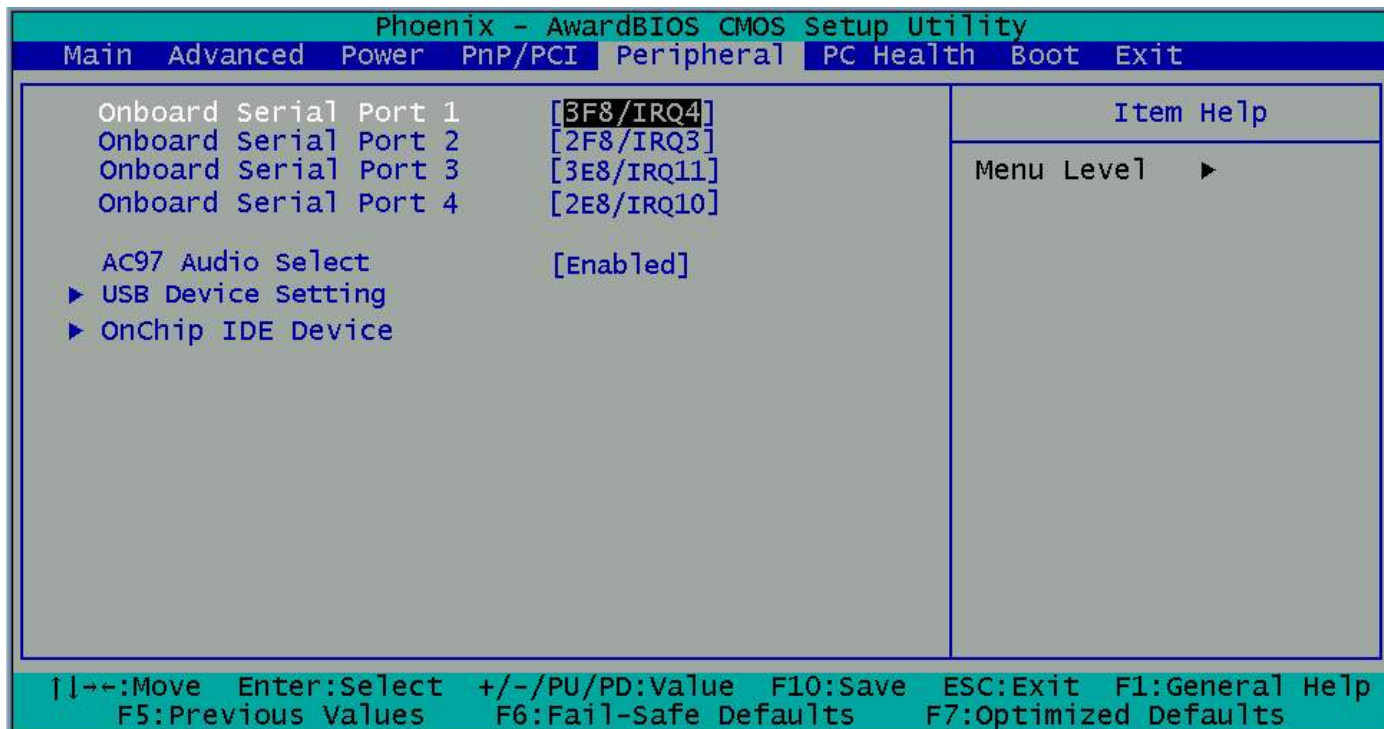


### 3.4 PnP/PCI Setup



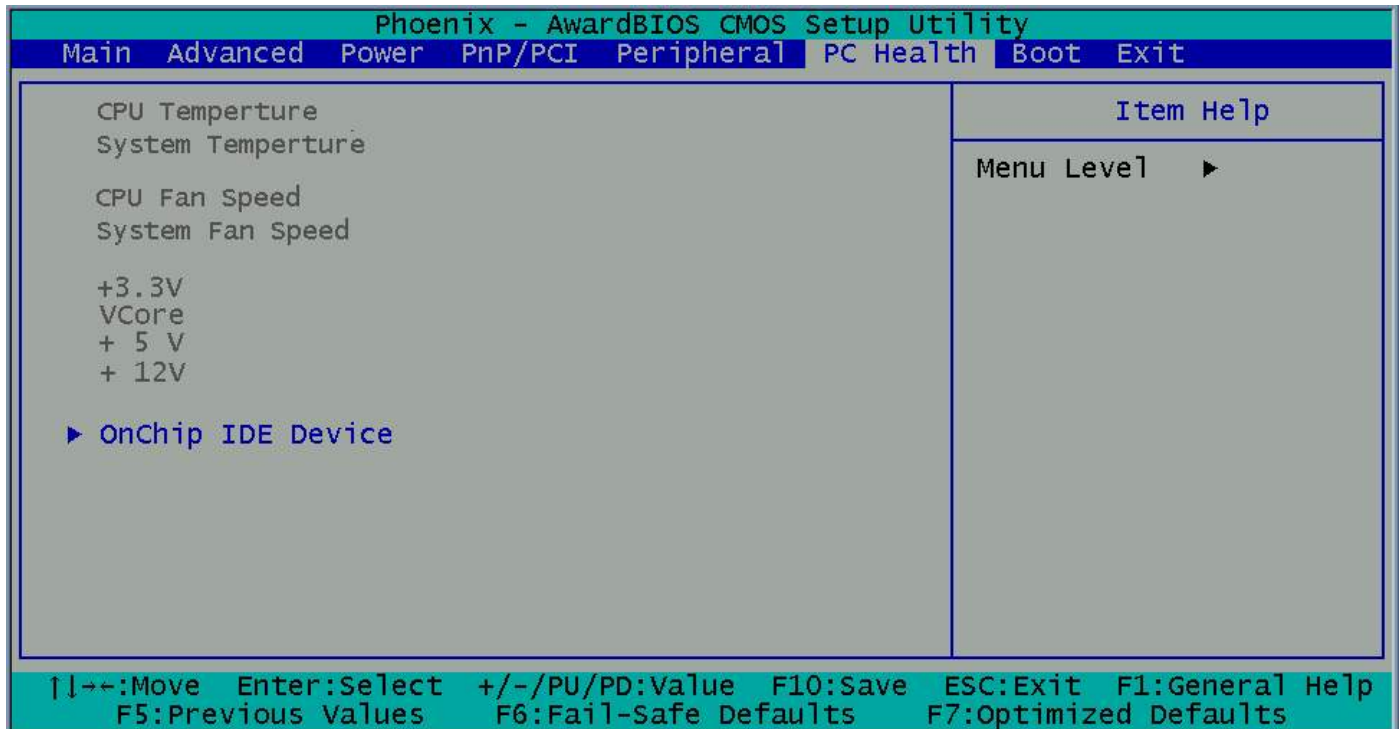
Option	Choice	Description
<b>Reset Configuration Data</b>	Enabled Disabled	Normally, you leave this field <i>Disabled</i> . Select <i>Enabled</i> to reset Extended System Configuration Data (ESCD) when you exit setup. If you have installed a new add-on and the system reconfiguration has caused such a serious conflict, then the operating system can not boot.
<b>Resources Controlled By</b>	Auto(ESCD) Manual	The Award Plug and Play BIOS has the capacity to automatically configure all of the boot and Plug and Play compatible devices. However, this capability means absolutely nothing unless you are using a Plug and Play operating system such as Windows 95. If you set this field to "manual," then you may choose specific resources by going into each of the submenus.
<b>IRQ Resources</b>	N/A	When resources are controlled manually, assign a type to each system interrupt, depending on the type of the device that uses the interrupt.

### 3.5 Peripherals Setup

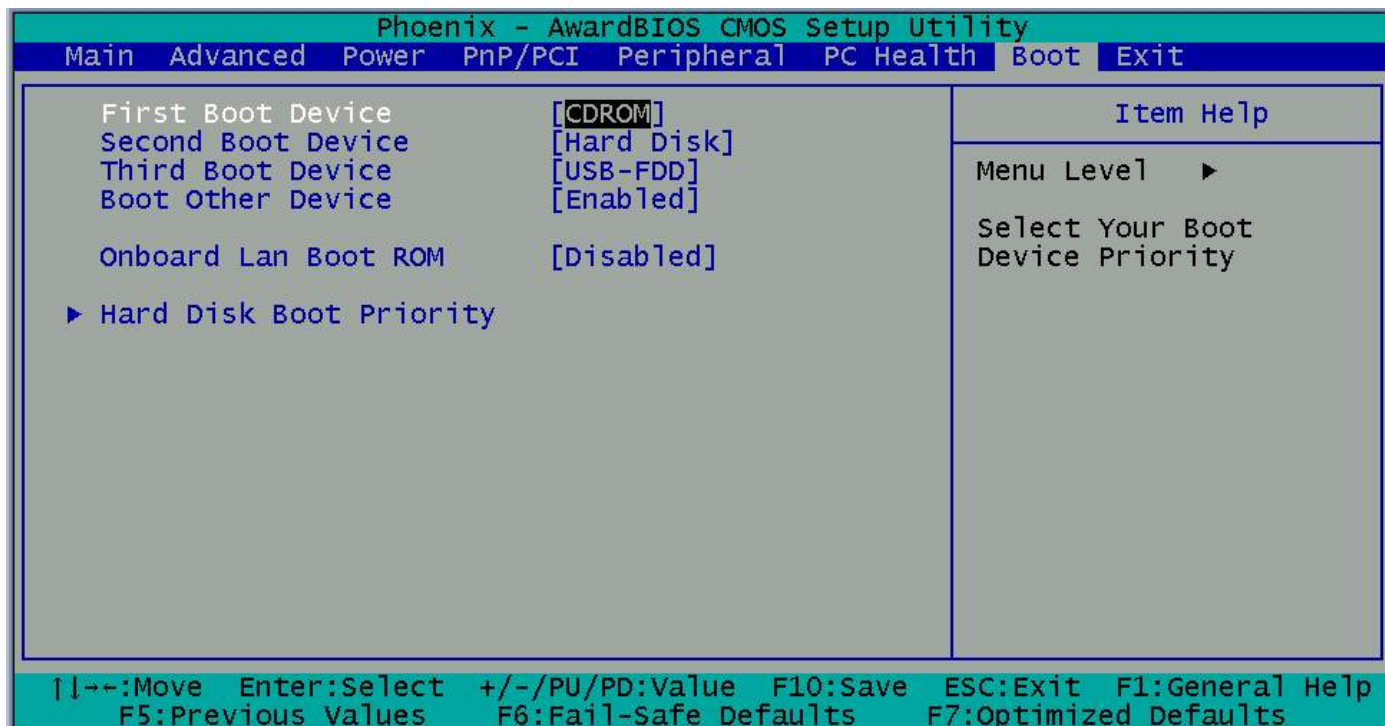


Option	Choice	Description
Onboard Serial Port 1	Serial Port 1: 3F8 / IRQ4	Select an address and the corresponding interrupt for each serial port.
Onboard Serial Port 2	Serial Port 2: 2F8 / IRQ3	
Onboard Serial Port 3	Serial Port 3: 3E8 / IRQ11	
Onboard Serial Port 4	Serial Port 4: 2E8 / IRQ10	
AC97 Audio Select	Enabled Disabled	This item allows you to decide to enable/disable AC97 Audio.
USB Device setting	Press Enter	Press <Enter> to Enabled/Disabled USB controllers and view device's information.
OnChip IDE Device	N/A	Press <Enter> to Enabled/Disabled IDE/SATA controllers or set parameters.

## 3.6 PC Health Setup

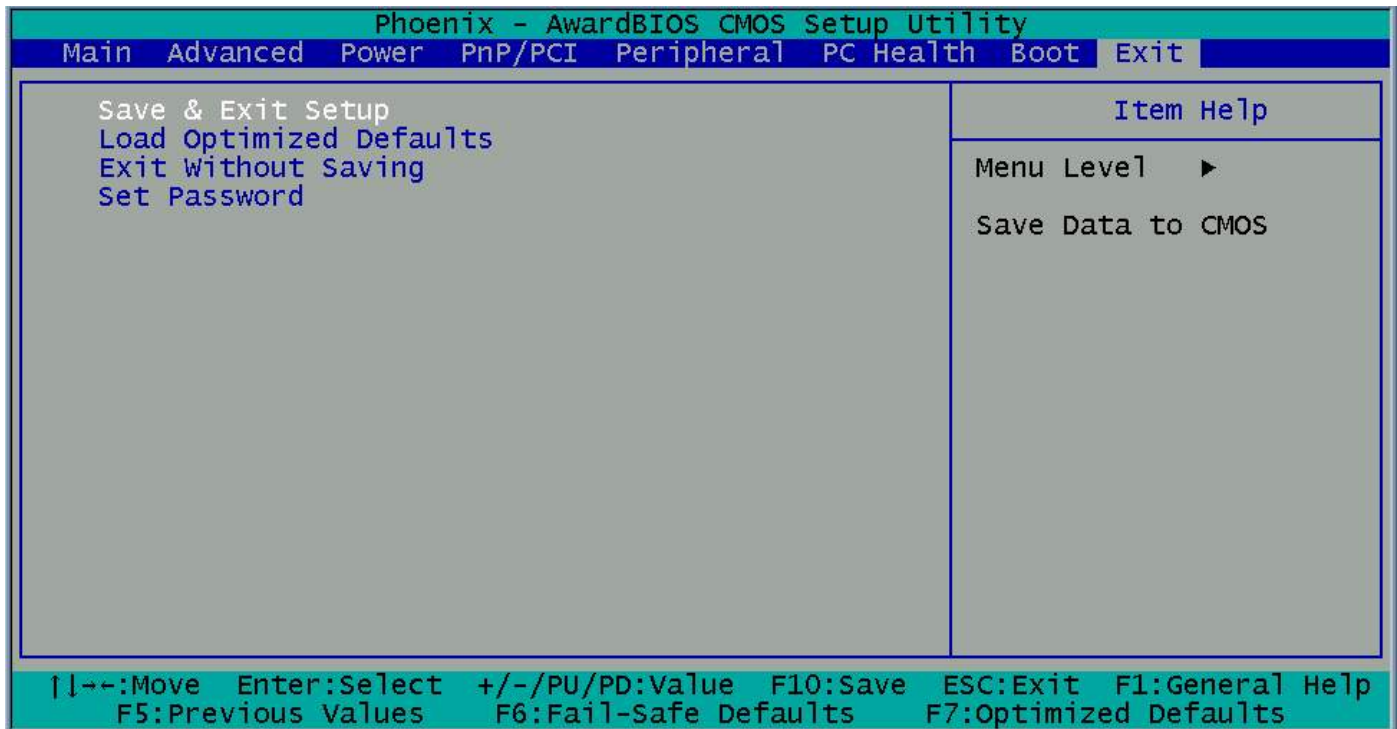


### 3.7 Boot Setup



Option	Choice	Description
<b>First / Second / Third Boot Device/Other Boot Device</b>	Hard Disk CDROM USB-FDD USB-CDROM LAN Disabled	The BIOS attempts to load the operating system from the devices in the sequence selected in these items.
<b>Lan Boot Select</b>	Disabled Lan-1 Lan-2	These fields allow the system to search for an OS from LAN.
<b>Hard Disk Boot Priority</b>	N/A	Press <Enter> to set the boot priority for each bootable device.

### 3.8 Exit Setup



Option	Choice	Description
<b>Save &amp; Exit Setup</b>	Pressing <Enter> on this item for confirmation:  Save to CMOS and EXIT (Y/N)? Y	Press “Y” to store the selections made in the menus in CMOS – a special section of memory that stays on after you turn your system off. The next time you boot your computer, the BIOS configures your system according to the Setup selections stored in CMOS. After saving the values the system is restarted again.
<b>Load Optimized Defaults</b>	When you press <Enter> on this item you get a confirmation dialog box with a message like this:  Load Optimized Defaults (Y/N)? N	Press ‘Y’ to load the default values that are factory-set for optimal-performance system operations.



<p><b>Exit Without Saving</b></p>	<p>Pressing &lt;Enter&gt; on this item for confirmation: Quit without saving (Y/N)? Y</p>	<p>This allows you to exit Setup without storing any changes in CMOS. The previous selections remain in effect. This shall exit the Setup utility and restart your computer.</p>
<p><b>Set Password</b></p>	<p>Pressing &lt;Enter&gt; on this item for confirmation:  ENTER PASSWORD:</p>	<p>When a password has been enabled, you will be prompted to enter your password every time you try to enter setup. This prevents unauthorized persons from changing any part of your system configuration.</p> <p>Type the password, up to eight characters in length, and press &lt;Enter&gt;. The password typed now will clear any previous password from the CMOS memory. You will be asked to confirm the password. Type the password again and press &lt;Enter&gt;. You may also press &lt;Esc&gt; to abort the selection and not enter a password.</p> <p>To disable a password, just press &lt;Enter&gt; when you are prompted to enter the password. A message will confirm that the password will be disabled. Once the password is disabled, the system will boot and you can enter Setup freely.</p>

**4****BIOS REFRESHING, WATCHDOG AND  
GPIO PROGRAMMING****4.1 BIOS Refreshing**

The BIOS program instructions are contained within computer chips called FLASH ROMs that are located on your system board. The chips can be electronically reprogrammed, allowing you to update your BIOS firmware without removing and installing chips.

The AR-B5432 provides the FLASH BIOS update function for you to easily to update BIOS. Please follow these operating steps to update BIOS:

Step 1:	You must boot up system into MS-DOS first and please don't detect files CONFIG.SYS and AUTOEXEC.BAT.
Step 2:	In the MS-DOS mode, you should execute the AWDFLASH program to update BIOS.
Step 3:	Follow all messages then you could update BIOS smoothly.

## 4.2 WatchDog Programming

This section describes the usage of WatchDog. AR-B5432 integrated the WatchDog that enable user to reset the system after a time-out event. User can use a program to enable the WatchDog and program the timer in range of 1~255 second(s)/minute(s). Once user enables the WatchDog, the timer will start to count down to zero except trigger the timer by user's program continuously. After zeroize the timer (stop triggering), the WatchDog will generate a signal to reset the system. It can be used to prevent system crash or hang up. The WatchDog is disabled after reset and should be enabled by user's program.

Please refer to the following table to program WatchDog properly, and user could test WatchDog under 'Debug' program.

Address port: 2E and Data port: 2F	
C:>debug	To enter debug mode.
-o 2E 87	To enter configuration.
-o 2E 87	
-o 2E 07	To point to Logical Device Number Reg.
-o 2F 07	To select logical device 7 (WatchDog)
-o 2E 30	To activate WatchDog.
-o 2F 01	
-o 2E F5	Preparing to select the unit of timer equals minute or second.
-l 2F	To read the value of index "2F".
-o 2F xx	The value "xx" equals [(value of index "2F") OR (F7) or (FF)]. OR (F7): unit is second. OR (FF): unit is minute.
-o 2E F6	Preparing to set the WatchDog timer value.
-o 2F ##	The value "##" ranges between 01 ~ FF (1 ~ 255). 00: To disable WatchDog.
-o 2E FA	Preparing to set the WatchDog output signal.
-l 2F	To read the value of index "2F".
-o 2F xx	The value "xx" equals [(value of index "2F") OR (01)]. To issue signal WDTRST to reset system.
-o 2E F5	Preparing to start the WatchDog timer counting.
-l 2F	To read the value of index "2F".
-o 2F xx	The value "xx" equals [(value of index "2F") OR (20)]. To start timer counting.
-q	To quit debug mode

WatchDog demo program in Turbo C++ as following:

```
//=====
// Turbo C++ Version 3.0 Copyright(c) 1990, 1992 by Borland International,Inc.
//=====
// Describe : F81865 WatchDog timer test
//=====

//=====
// Language include files
//=====
#include <conio.h>
#include <stdlib.h>
#include <stdio.h>
#include <dos.h>

//=====
// Normal procedure
//=====
void Show_Help();

//=====
// Main procedure
//=====
int main(int argc, char *argv[])
{
unsigned char IO_Port_Address=0x2E;
unsigned char Time;
int Temp;

if ( argc != 2 )
{ Show_Help(); return 1; }

clrscr();

Time=atoi(argv[1]);

// Set Watchdog
```

```
outportb(IO_Port_Address,0x87);    // Enter Configuration
outportb(IO_Port_Address,0x87);

outportb(IO_Port_Address,0x07);    // Point to Logical Device Number Reg.
outportb(IO_Port_Address+1,0x07);  // Select logical device 7, (Watchdog Function)

outportb(IO_Port_Address,0x30);    // Device Active register
outportb(IO_Port_Address+1,0x01);

outportb(IO_Port_Address,0xF5);    // Select Watchdog count mode seconds or minutes
outportb(IO_Port_Address+1,inportb(IO_Port_Address+1)&0xF7);    // Default is second, bit3=0

outportb(IO_Port_Address,0xF5);    // Select Watchdog output mode
outportb(IO_Port_Address+1,inportb(IO_Port_Address+1)|0x10);    // Set to Pulse mode, bit4=1

outportb(IO_Port_Address,0xF6);    // Set Watchdog Timer Value
outportb(IO_Port_Address+1,Time);  // 0x00 to disable, max 0xFF

outportb(IO_Port_Address,0xFA);    // Set Watchdog Time out output via WDTRST
outportb(IO_Port_Address+1,inportb(IO_Port_Address+1)|0x01); // bit0=1

outportb(IO_Port_Address,0xF5);    // Start Watchdog Time counting
outportb(IO_Port_Address+1,inportb(IO_Port_Address+1)|0x20); // bit5=1

textcolor(YELLOW);
for(Temp=Time;Temp>0;Temp--)
{
outportb(IO_Port_Address,0xF6);    // Read Watchdog Timer Value
Time=inportb(IO_Port_Address+1);

gotoxy(20,10);
printf(">>> After %3d Second will reset the system. <<<",Time);

delay(1000);
}

textcolor(LIGHTRED);
gotoxy(18,10);
```

```
cprintf("If you can see this message, Reset system is Fail",Time);
```

```
return 1;
```

```
}
```

```
//=====
```

```
// Function : Show_Help()
```

```
// Input   : -
```

```
// Change  : -
```

```
// Return  : -
```

```
// Description : Show Title string.
```

```
//=====
```

```
void Show_Help()
```

```
{
```

```
clrscr();
```

```
printf("WatchDog Test for F81865   \n\n");
```

```
printf("Sample:                   \n");
```

```
printf("      WDT.EXE 10           \n");
```

```
printf("( For 10 seconds to reset. )\n");
```

```
}
```

## 4.3 GPIO Programming

This section describes the usage of GPIOs. AR-B5432 integrated eight bits, TTL-3.3V, bidirectional, and software programmable GPIOs for user's application.

Address port: 2E and Data port: 2F								
GP##	GP57	GP56	GP55	GP54	GP53	GP52	GP51	GP50
Bit #	Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)

GPIO demo program in Turbo C++ as following:

```

=====
// Turbo C++ Version 3.0 Copyright(c) 1990, 1992 by Borland International, Inc.
=====
// Describe : GPIO50~GPIO57 Test utility for F81865.
=====

//=====
// Language include files
//=====
#include <conio.h>
#include <stdio.h>

//=====
// Normal procedure
//=====
void Show_Help();
void Show_Fail();
void Show_Pass();

//=====
// Main procedure
//=====
int main(int argc)
{

```

```
char *Model_Name="AR-B5432";
unsigned char    IO_PORT_BASE=0x2E; // DATA_PORT = IO_PORT_BASE + 1;
unsigned char data;
int result=0;

if ( argc > 1 )
    { Show_Help();    return 1;  }

clrscr();
textcolor(WHITE);
gotoxy(1, 1);
printf("<>=====  
gotoxy(1, 2);  printf("|| F81865 GPIO Test Utility v1.0 Acrosser Technology Co., Ltd.          ||");
gotoxy(1, 3);
printf("<>=====  
gotoxy(1, 4);
printf("<>=====  
gotoxy(1, 5);  printf("|| Model Name   :                               ||");
gotoxy(1, 6);  printf("|| SIO IO Base :                               ||");
gotoxy(1, 7);
printf("<>====="

// Show Got Parameter Informat
textcolor(LIGHTGRAY);
gotoxy(18,5);  printf("%s",Model_Name);
gotoxy(18,6);  printf("%X",IO_PORT_BASE);

// Enter F81865 Config
outportb(IO_PORT_BASE,0x87);
outportb(IO_PORT_BASE,0x87);

// Set Multi-function Pins to GPIO
outportb(IO_PORT_BASE,0x2A);
outportb(IO_PORT_BASE+1,(inportb(IO_PORT_BASE+1) | 0x08));

// Select GPIO Port device
outportb(IO_PORT_BASE,0x07);
outportb(IO_PORT_BASE+1,0x06);
```



```
// Set GPIO Port Active
outportb(IO_PORT_BASE,0x30);
outportb(IO_PORT_BASE+1,0x01);

// Set F81865 GPIO50~53 to Output, GPIO54~GPIO57 to Input
outportb(IO_PORT_BASE,0xA0);
outportb(IO_PORT_BASE+1,0x0F);

// Set F81865 GPIO50~53 to High
outportb(IO_PORT_BASE,0xA1);
outportb(IO_PORT_BASE+1,0x0F);
// Read F81865 GPIO54~57 Status, if not High error.
outportb(IO_PORT_BASE,0xA2);
data=inportb(IO_PORT_BASE+1)&0xF0;
if(data!=0xF0)
    result=1;
// Set F81865 GPIO50~53 to Low
outportb(IO_PORT_BASE,0xA1);
outportb(IO_PORT_BASE+1,0x00);
// Read F81865 GPIO54~57 Status, if not Low error.
outportb(IO_PORT_BASE,0xA2);
data=inportb(IO_PORT_BASE+1)&0xF0;
if(data!=0x00)
    result=1;

// Set F81865 GPIO50~53 to input, GPIO54~GPIO57 to Output
outportb(IO_PORT_BASE,0xA0);
outportb(IO_PORT_BASE+1,0xF0);

// Set F81865 GPIO54~57 to High
outportb(IO_PORT_BASE,0xA1);
outportb(IO_PORT_BASE+1,0xF0);
// Read F81865 GPIO50~53 Status, if not High error.
outportb(IO_PORT_BASE,0xA2);
data=inportb(IO_PORT_BASE+1)&0x0F;
if(data!=0x0F)
    result=1;
```

```
// Set F81865 GPIO54~57 to Low
outportb(IO_PORT_BASE,0xA1);
outportb(IO_PORT_BASE+1,0x00);
// Read F81865 GPIO50~53 Status, if not Low error.
outportb(IO_PORT_BASE,0xA2);
data=inportb(IO_PORT_BASE+1)&0x0F;
if(data!=0x00)
    result=1;

// Exit F81865 Config
outportb(IO_PORT_BASE,0xAA);

if(result)
    Show_Fail();
else
    Show_Pass();

return result;
}

//=====
// Function : Show_Help()
// Input    : -
// Change   : -
// Return   : -
// Description : Show Title string.
//=====
void Show_Help()
{
    clrscr();
    printf("GPIO Test utility for F81865\n\n");
    printf("VCC    ✂          ✂ GND  \n");
    printf("GPIO50 ✂ ◀-----+ ✂ GPIO54\n");
    printf("GPIO51 ✂ ◀-----+ ✂ GPIO55\n");
    printf("GPIO52 ✂ ◀-----+ ✂ GPIO56\n");
    printf("GPIO53 ✂ ◀-----+ ✂ GPIO57\n");
}
```

```

//=====
// Function : Show_Fail()
// Input   : -
// Change  : -
// Return  : -
// Description : Show Fail Message.
//=====

void Show_Fail()
{
    textcolor(LIGHTRED);
    gotoxy(20,10);  cprintf("  請 請 請 請 請 請 請 請 請 請 ");
    gotoxy(20,11);  cprintf("  請 請 請 請 請 請 ");
    gotoxy(20,12);  cprintf("  請 請 請 請 請 請 請 請 ");
    gotoxy(20,13);  cprintf("  請 請 請 請 請 請 ");
    gotoxy(20,14);  cprintf("  請 請 請 請 請 請 請 請 請 請 ");
}

//=====
// Function : Show_Pass()
// Input   : -
// Change  : -
// Return  : -
// Description : Show Pass Message.
//=====

void Show_Pass()
{
    textcolor(LIGHTGREEN);
    gotoxy(20,10);  cprintf("  請 請 請 請 請 請 請 請 請 請 ");
    gotoxy(20,11);  cprintf("  請 請 請 請 請 請 ");
    gotoxy(20,12);  cprintf("  請 請 請 請 請 請 請 請 請 請 ");
    gotoxy(20,13);  cprintf("  請 請 請 請 請 請 ");
    gotoxy(20,14);  cprintf("  請 請 請 請 請 請 請 請 請 請 ");
}

```

# 5 ELECTRICAL CHARACTERISTICS

## 5.1 Basic Electrical Characteristics Table

Electrical Characteristics						
	Parameter / Condition	Value			Unit	
		Min.	Typ.	Max.		
+12V	External power input for system or +12Vdc power output (for SATA, LCD inverter, ... etc.)	11.4	12.0	12.6	V	
+5V	+5Vdc power output (for SATA, USB, DVI, ... etc.)	4.75	5.0	5.25	V	
+3.3V	+3.3Vdc power output (for LVDS, PCI-104, ... etc.)	3.14	3.30	3.46	V	
GPIO $V_{IL}$	GPIO's maximum Input LOW voltage	-	-	0.8	V	
GPIO $V_{IH}$	GPIO's minimum input HIGH voltage	2.0	-	-	V	
GPIO $V_{OL}$	GPIO's typical output LOW voltage	-	0	-	V	
GPIO $V_{OH}$	GPIO's typical output HIGH voltage	-	3.3	-	V	