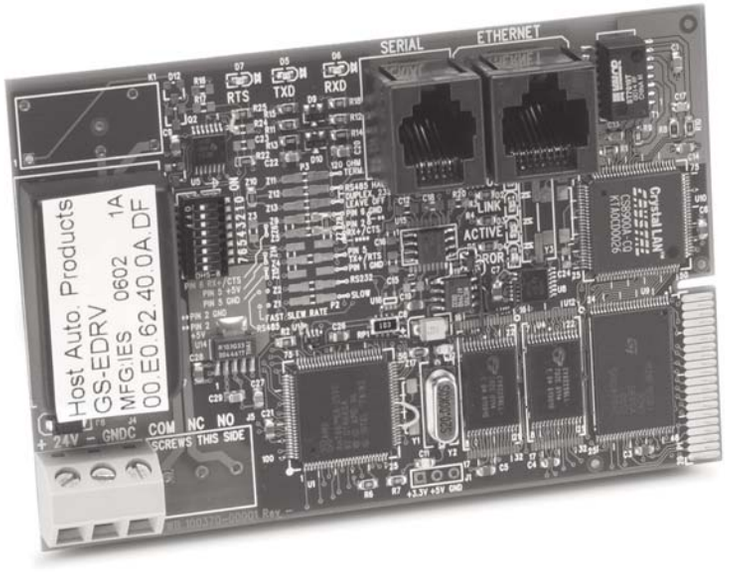
GS Accessories

GS Series AC Drive Ethernet Interface

User Manual



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GS Series AC Drive
Ethernet Interface
USER MANUAL

Please include the Manual Number and the Manual Issue, both shown below, when communicating with Technical Support regarding this publication.

Manual Number: **GS-EDRV-M**

Issue: **Third Edition**

Issue Date: **05/2011**

Publication History		
Issue	**Date**	**Description of Changes**
First Edition	8/02/02	Original
1st Edition, Revision A	3/14/03	Added Input WORD functions
1st Edition, Revision B	8/12/05	Website publication only; Corrected Output Word Map & Warnings
Second Edition	02/2010	Revised “Reading/Writing From/To the Drive” & “Input/Output Word Map” sections
Third Edition	05/2011	Added GS-EDRV100 product information and specifications.

TABLE OF CONTENTS

Manual Overview

Overview of this Publication

The GS AC Drive Ethernet Interface User Manual describes the installation, configuration, and operation of GS AC Drive Ethernet Interface cards.

Who Should Read This Manual

This manual contains important information for those who will install, maintain, and/or operate any GS Series AC Drive Ethernet Interface card.

Supplemental Publications

The **Ethernet Remote Master Module Manual** (H24-ERM-M) is available from **AutomationDirect** and may be useful for your application.

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When you see the "notepad" icon in the left-hand margin, the paragraph to its immediate right will be a special note.

When you see the "exclamation mark" icon in the left-hand margin, the paragraph to its immediate right will be a WARNING. This information could prevent injury, loss of property, or even death (in extreme cases).

GS-EDRV Overview

The GS-EDRV provides a low-cost, high-performance 10BaseT Ethernet link between a control system and a GS Series AC Drive. The control system can be any of the following:

- DL205 CPU, DL405 CPU, or a WinPLC, with the appropriate Ethernet Remote Master module (H2-ERM or H4-ERM).
- A Productivity3000 CPU using the onboard Ethernet port.
- A PC running Entivity's ThinknDo software, a PC using a custom device driver that was developed using our Ethernet SDK, or a PC running KEP***Direct*** EBC or OPC Server.
- Any independent I/O controller with a Modbus TCP/IP driver.

The GS-EDRV mounts on DIN rail and utilizes cable connections and, if needed, Ethernet switches or hubs to communicate to the AC drive.

The functions of the interface are as follows:

- process input signals from the AC drive.
- format these signals to conform to the Ethernet standard.
- transmit converted signals to the control system.
- receive and translate output signals from the control system.
- sends the output signals to the drive.

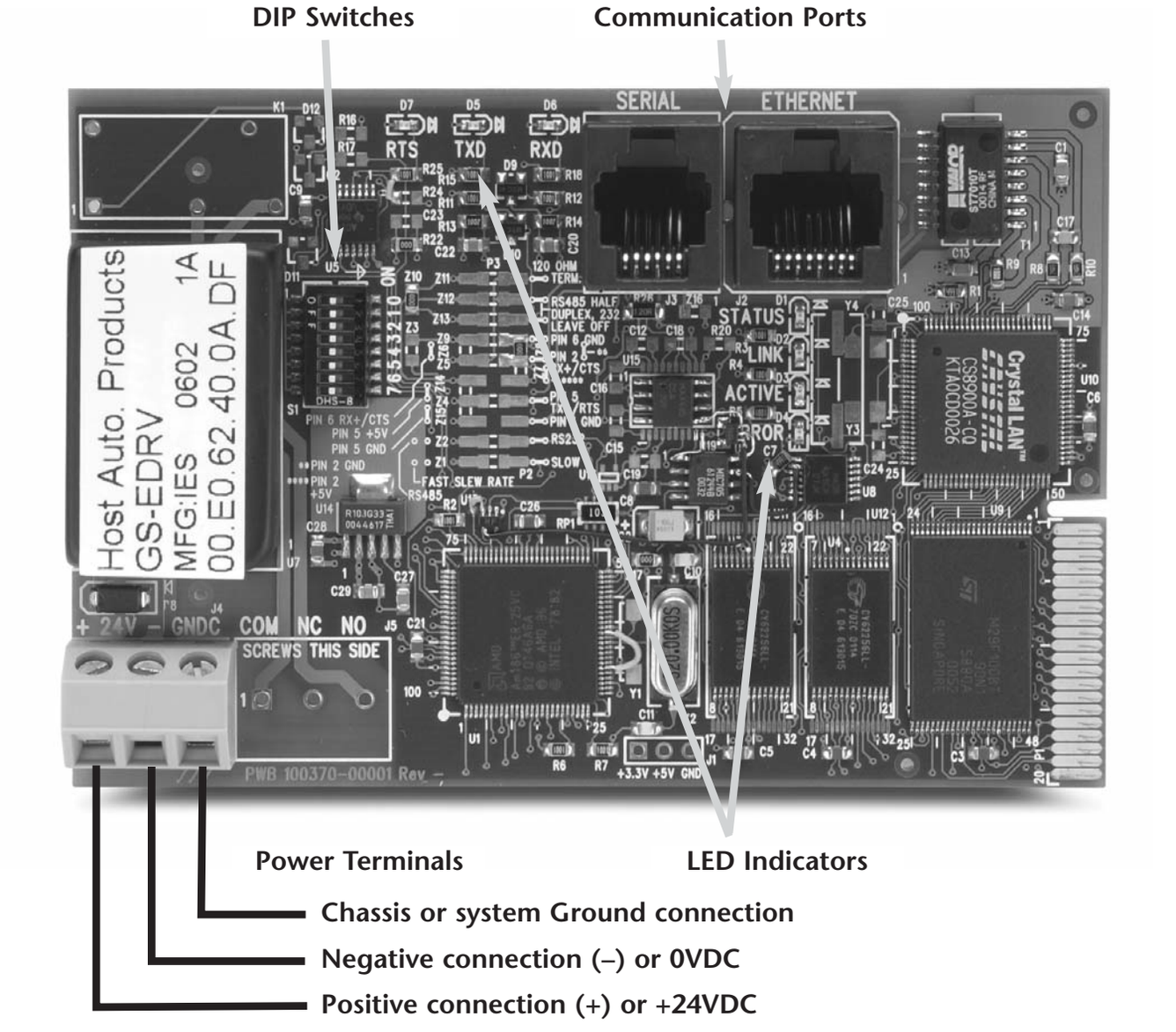
The control function is NOT performed by the interface. The control function is performed by one of the control systems mentioned above. The I/O mapping function is performed by an H2(4)-ERM module (purchased separately). The H2(4)-ERM module is configured with the ERM Workbench Utility which is part of the ***Direct***SOFT PLC programming software.

Package Contents

After receiving the GS-EDRV, please check for the following:

- Make sure that the part number indicated on the package corresponds with the part number of your order.
- Make sure that the package includes a GS AC Drive Ethernet Interface card (GS-EDRV), one piece of **SNAP**TRACK™, two DIN mounting clips, and one serial connection cable.
- Inspect the contents to insure they were not damaged during shipment.

GS-EDRV Board Layout



Power Terminals

Power for the GS-EDRV is connected directly to the card using a nominal 24VDC supply (+24VDC, –0VDC). The GNDC terminal is for a chassis or system Ground.

Input Voltage

18–33 VDC with a 24VDC nominal supply

Input Current

90–135 mA

Communication Ports

Two comm ports are provided to make the connection from a GS Series AC drive (Serial port) to an Ethernet device or network (Ethernet port).

DIP Switches

The DIP Switches are used to set the Module ID for the GS-EDRV card.

LED Indicators

STATUS Indicator

The green STATUS LED is steady ON when the GS-EDRV is connected to a GS Series AC drive and communication has been established.

LINK

The green LINK LED is steady ON when the GS-EDRV is correctly connected to an active device on the network. The LINK LED verifies that the proper cables are connected, and the card is functioning correctly. If a mismatch with the 10BaseT connections occurs this LED will not be illuminated.

ACTIVE

The green ACTIVE LED flashes to indicate that the card sees data travelling on the network. If any network device is sending or receiving data, the ACTIVE LED will be illuminated. In idle mode (no network traffic) this LED is OFF. During heavy communication loads this LED will be steady ON.

ERROR Indicator

If the GS-EDRV's red Error (ERROR) indicator is flashing or steady ON, a fatal error has occurred. The error may be in the card itself, or a network problem may be causing this symptom. The ERROR indication can be caused by a faulty ground, an electrical spike or other types of electrical disturbances. Cycle power to the system to attempt clearing the error.

RTS

The green RTS LED indicates the GS-EDRV is ready to send information to the AC drive.

TXD

The green TXD LED flashes to indicate that the card sees data traveling to the AC drive. During heavy communication loads, this LED will be steady ON.

RXD

The green RXD LED flashes to indicate that the card sees data traveling from the AC drive. During heavy communication loads this LED will be steady ON.

Setting the GS-EDRV Address

Each GS-EDRV must have an identification (ID) or address in order to be recognized on the network, and each ID must be unique.

WARNING: Duplicate IDs on the same network will cause unpredictable results and must be avoided.

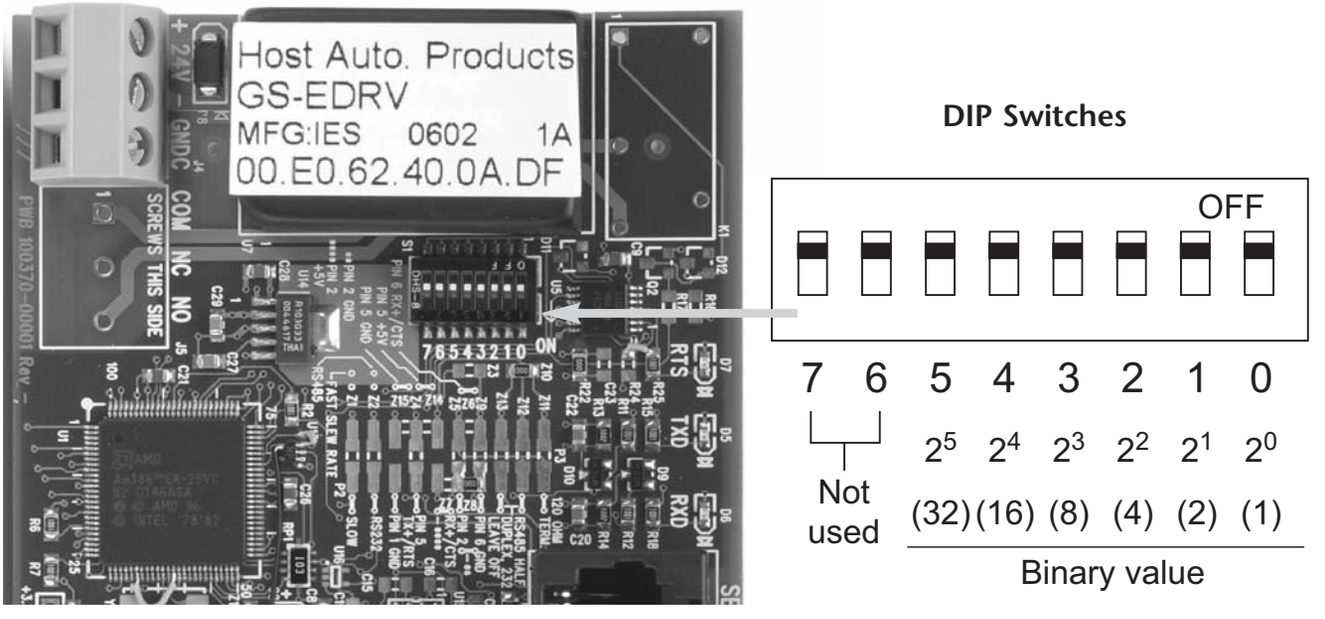
Setting Module ID with DIP Switches

You can use the DIP switch to set the ID to a number from one to sixty-three. Do not use ID "0" for communication.

If the DIP switch is set to a number greater than 0, the software tools are disabled from setting the ID. Again, the software tools will only allow changes to the ID if the DIP switch setting is 0 (zero, all switches OFF).

The DIP switch settings are read only at power-up. You must cycle power if you change the DIP switches.

The GS-EDRV contains eight individual DIP switches, but only six of these are active. You will find that the switches on the printed circuit board are labeled 0 (zero) through 7. The numbers on the printed circuit board indicate the power of 2 represented by each individual switch. For example, switch 0 represents 2^0 (or 1), switch 1 is 2^1 (or 2), switch 2 is 2^2 (or 4), and so on.

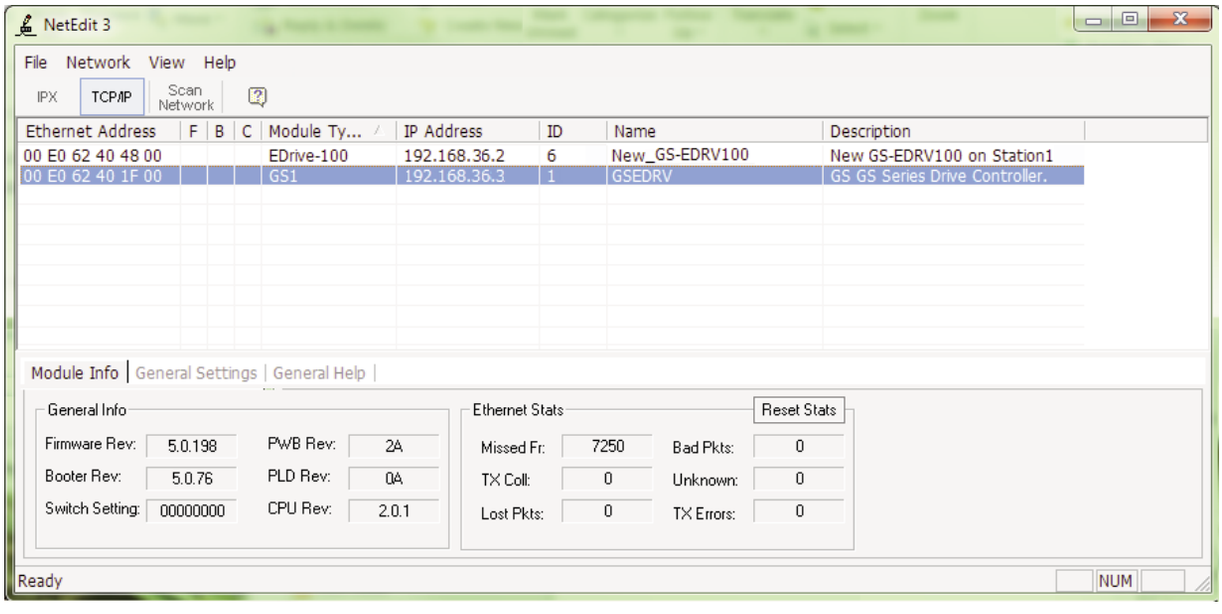


The ID equals the sum of the binary values of the slide switches set in the ON position. For example, if you set slide switches 1, 2, and 3 to the ON position, the ID will be 14. This is found by adding 8+4+2=14. The maximum value you can set on the DIP switch is 32+16+8+4+2+1=63. This is achieved by setting switches 0 through 5 to the ON position.

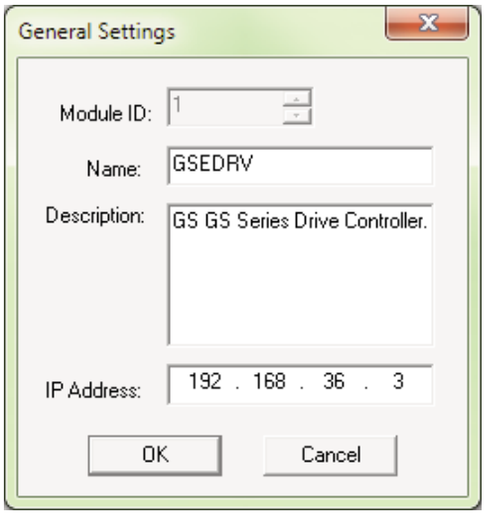
Setting TCP/IP Address with NetEdit

NetEdit is a free utility that can be used to configure the GS-EDRV's IP address. This utility is included with the DirectSOFT software or it can be downloaded from http://support.automationdirect.com/downloads.html.

Connect your PC to the Ethernet network that the GS-EDRV is currently on and open the NetEdit utility. If it is not already selected, select the TCP/IP tab as seen below.

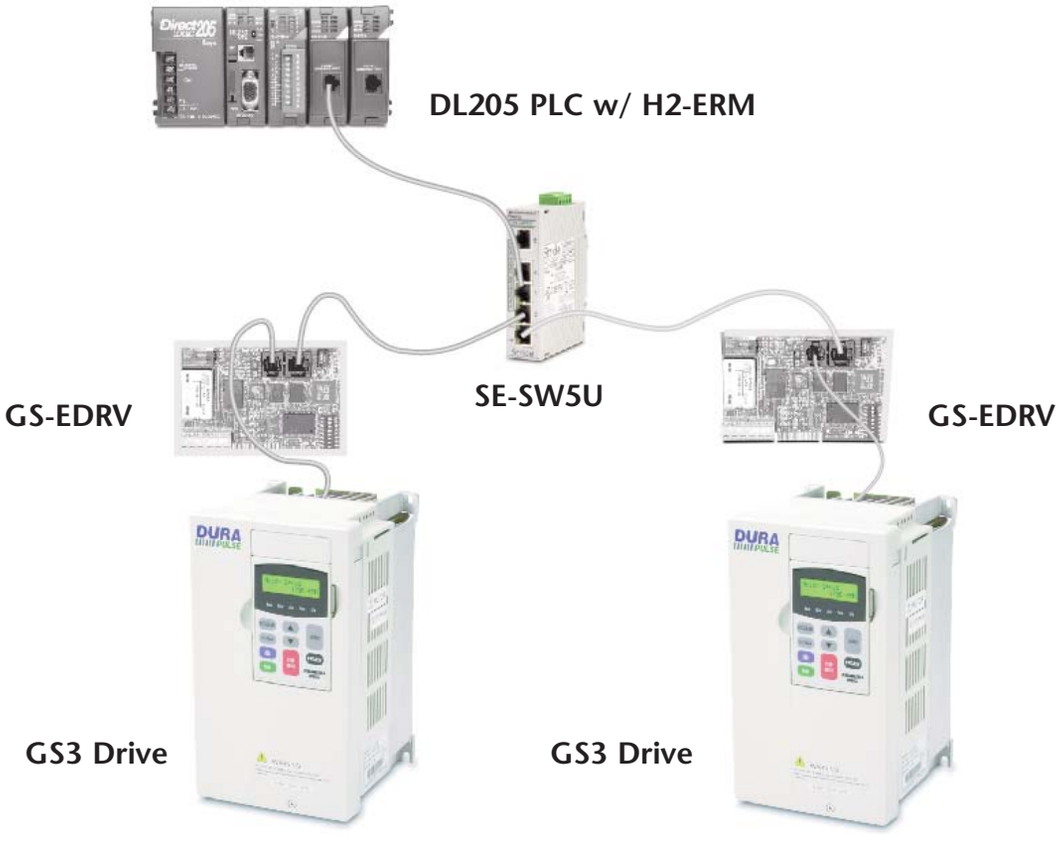


Double click on the desired GS-EDRV. A "General Settings" popup will display allowing you to configure the IP address of the module you have selected.



Press the OK button to write the new configuration to the GS-EDRV.

Network Connections



10Base-T Connections

The GS-EDRV Ethernet port has an eight-pin modular jack that accepts RJ45 connector plugs. UTP (Unshielded Twisted-Pair) cable is rated according to its data-carrying ability (bandwidth) and is given a "category" number. We strongly recommend using a category 5 cable for all Ethernet 10Base-T connections. For convenient and reliable networking, we recommend that you purchase commercially manufactured cables (cables with connectors already attached).

To connect an GS-EDRV (or PC) to a hub, switch, or repeater, use a patch cable (sometimes called a straight-through cable). The cable used to connect a PC or an H2(4)-ERM directly to an GS-EDRV or to connect two hubs is referred to as a crossover cable.

Patch (Straight-through) Cable

EDRV			HUB
TD+ 1	OR/WHT	OR/WHT	1 RD+
TD- 2	OR	OR	2 RD-
RD+ 3	GRN/WHT	GRN/WHT	3 TD+
4	BLU	BLU	4
5	BLU/WHT	BLU/WHT	5
RD- 6	GRN	GRN	6 TD-
7	BRN/WHT	BRN/WHT	7
8	BRN	BRN	8
RJ45			RJ45

Crossover Cable

EDRV			PC
TD+ 1	OR/WHT	GRN/WHT	1 TD+
TD- 2	OR	GRN	2 TD-
RD+ 3	GRN/WHT	OR/WHT	3 RD+
4	BLU	BLU	4
5	BLU/WHT	BLU/WHT	5
RD- 6	GRN	OR	6 RD-
7	BRN/WHT	BRN/WHT	7
8	BRN	BRN	8
RJ45			RJ45

This diagram illustrates the standard wire positions in the RJ45 connector. We recommend all Ethernet 10BaseT cables to be Category 5, UTP cable.

GS-EDRV100 Overview

The GS-EDRV100 provides a low cost, high-performance 10/100Mbps Ethernet link between a control system and a GS Series AC Drive. The control system can be any of the following:

- DL205 CPU, DL405 CPU, or a WinPLC, with the appropriate Ethernet Remote Master module (H2-ERM or H4-ERM).
- A Productivity3000 CPU using the onboard Ethernet port.
- A PC running Entivity's ThinknDo software, a PC using a custom device driver that was developed using our Ethernet SDK, or a PC running KEP***Direct*** EBC or OPC Server.
- Any independent I/O controller with a Modbus TCP/IP driver.

The GS-EDRV100 has an encapsulated compact DIN rail mounted design allowing for minimal space requirements. With the appropriate cable connections and, if needed, Ethernet switches or hubs, the GS-EDRV100 will allow you to communicate with your AC drive over qualified Ethernet networks.

The functions of the interface are as follows:

- process input signals from the AC drive.
- format these signals to conform to the Ethernet standard.
- transmit converted signals to the control system.
- receive and translate output signals from the control system.
- sends the output signals to the drive.

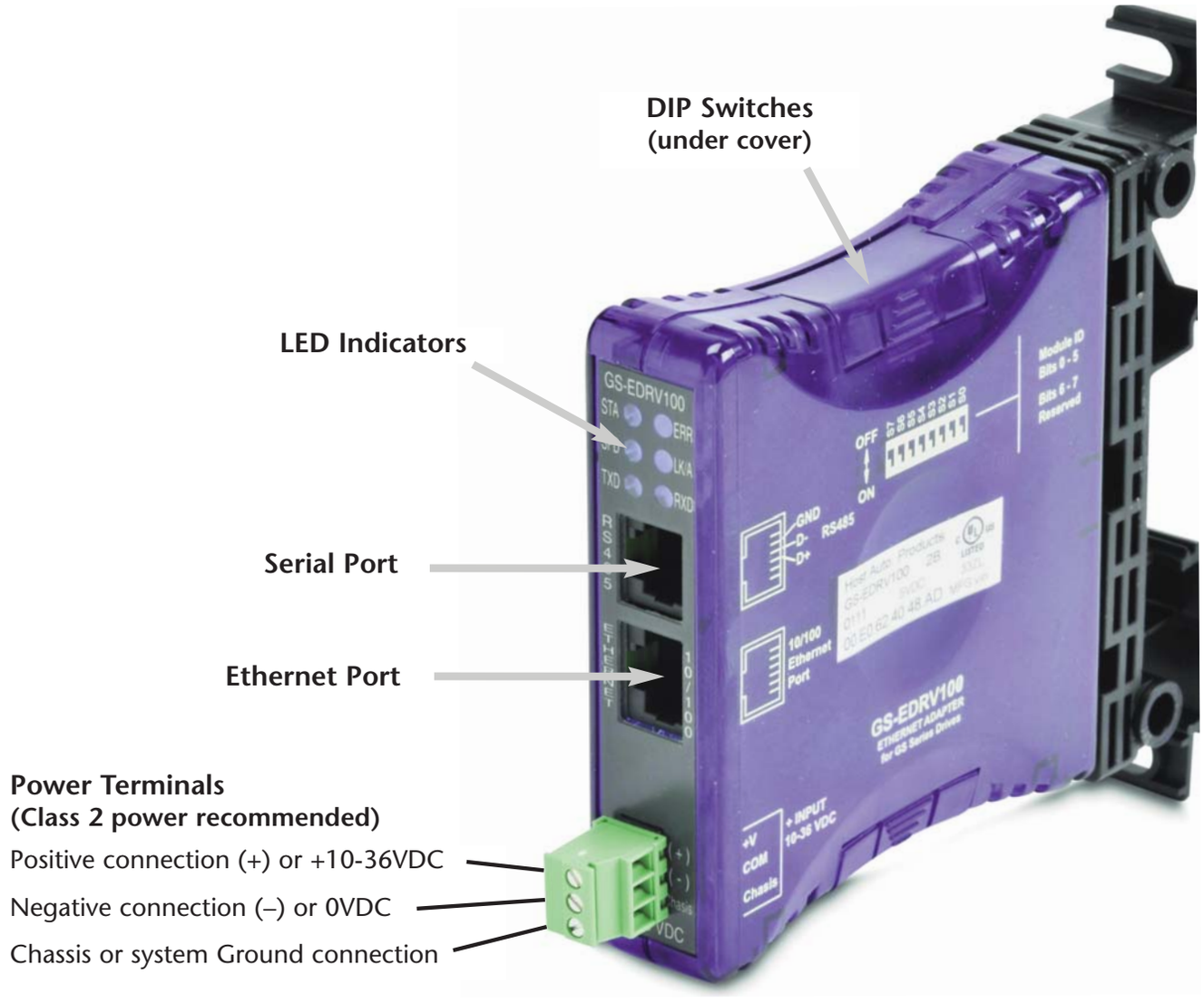
The control function is NOT performed by the interface. The control function is performed by one of the control systems mentioned above. The I/O mapping function is performed by an H2(4)-ERM module (purchased separately). The H2(4)-ERM module is configured with the ERM Workbench Utility which is part of the ***Direct***SOFT PLC programming software.

Package Contents

After receiving the GS-EDRV100, please check for the following:

- Make sure that the part number indicated on the package corresponds with the part number of your order.
- Make sure that the package includes a GS AC Drive Ethernet Interface card (GS-EDRV100), one DIN rail mounting clip, one 3-wire terminal block, and one serial connection cable (2ft in length).
- Inspect the contents to insure they were not damaged during shipment.

GS-EDRV100 Layout



Power Terminals

Power for the GS-EDRV100 is connected directly to the card using a 10-36VDC power supply (a Class 2 power supply is recommended). The Chassis terminal is for a chassis or system Ground.

Input Current and Voltage Ratings

220mA@10VDC, 70mA@24VDC, or 50mA@36VDC.

Communication Ports

Two comm ports are provided to make the connection from a GS Series AC drive (Serial port) to an Ethernet device or network (Ethernet port).

DIP Switches

The DIP Switches are used to set the Module ID for the GS-EDRV100 card.

LED Indicators

STA

The STA or STATUS LED is steady ON when the GS-EDRV100 is connected to a GS Series AC drive and communication has been established.

SPD

The SPD or SPEED LED is used to represent the Ethernet speed. The LED will be ON when the Ethernet speed is 100Mbps and OFF when the speed is 10Mbps.

TXD

The TXD or TRANSMIT DATA LED flashes to indicate that the GS-EDRV100 is sending data through the serial port to the AC drive.

ERR

If the GS-EDRV100's ERR (ERROR) indicator is ON, a critical error has occurred. The error may be in the card itself, or a network problem may be causing this symptom. The ERROR indication can be caused by a faulty ground, an electrical spike or other types of electrical disturbances. Cycle power to the system to attempt clearing the error. The ERROR LED will also flash (once per second) when a firmware update is in progress.

LK/A

The LK/A or LINK GOOD/ACTIVITY LED flashes to indicate that the card sees data traveling on the Ethernet network. If any network device is sending or receiving data, the LK/A LED will be flashing. During heavy communication loads, this indicator will be steady ON. If the LED is OFF, then a problem with the Ethernet connection has been detected.

RXD

The RXD or RECEIVE DATA LED flashes to indicate that the GS-EDRV100 is receiving data through the serial port from the AC drive.

Setting the GS-EDRV100 Address

Each GS-EDRV100 must have an identification (ID) or address in order to be recognized on the network, and each ID must be unique.

WARNING: Duplicate IDs on the same network will cause unpredictable results and must be avoided.

Setting Module ID with DIP Switches

You can use the DIP switch to set the ID to a number from one to sixty-three. Do not use ID "0" for communication.

If the DIP switch is set to a number greater than 0, the software tools are disabled from setting the ID. Again, the software tools will only allow changes to the ID if the DIP switch setting is 0 (zero, all switches OFF).

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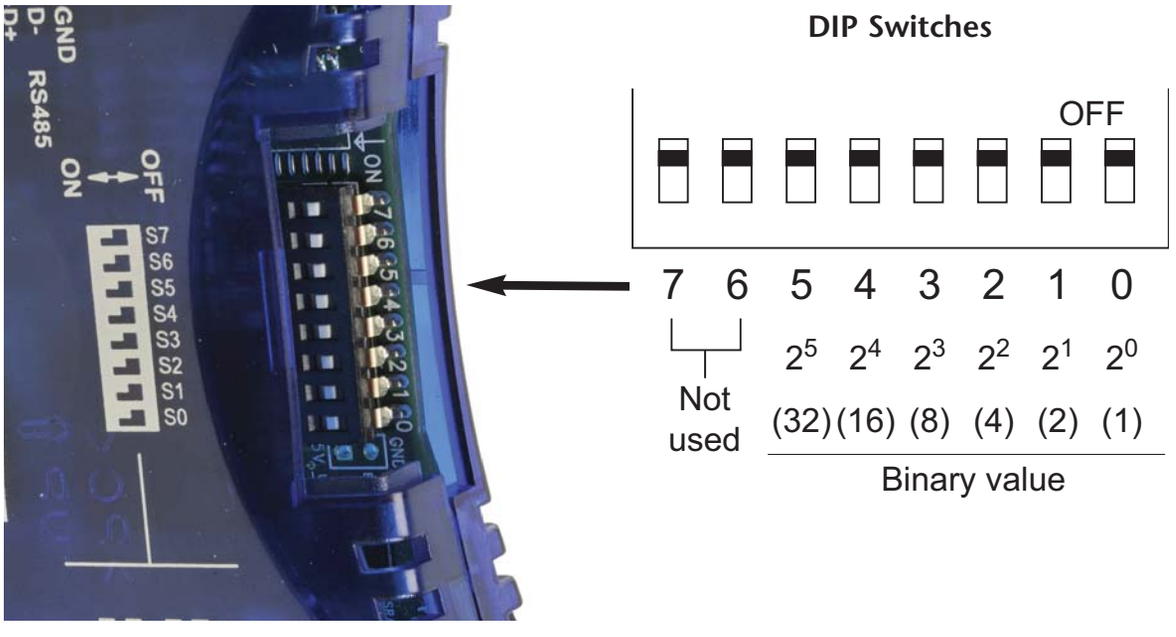
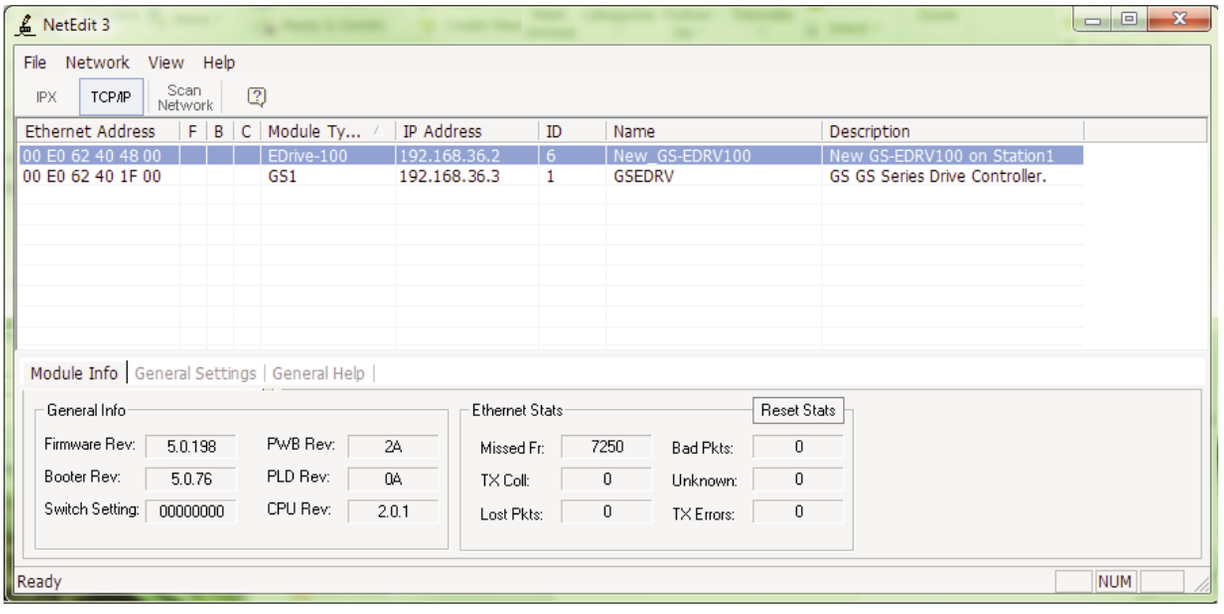


The ID equals the sum of the binary values of the slide switches set in the ON position. For example, if you set slide switches 1, 2, and 3 to the ON position, the ID will be 14. This is found by adding 8+4+2=14. The maximum value you can set on the DIP switch is 32+16+8+4+2+1=63. This is achieved by setting switches 0 through 5 to the ON position.

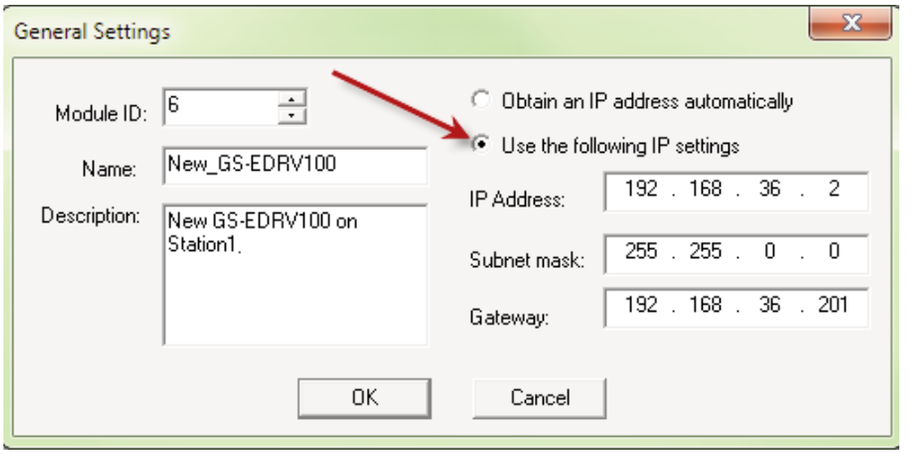
Setting TCP/IP Address with NetEdit

NetEdit is a free utility that can be used to configure the GS-EDRV100's IP address. This utility is included with the DirectSOFT software or it can be downloaded from http://support.automationdirect.com/downloads.html.

Connect your PC to the Ethernet network that the GS-EDRV100 is currently on and open the NetEdit utility. If it is not already selected, select the TCP/IP tab as seen below.

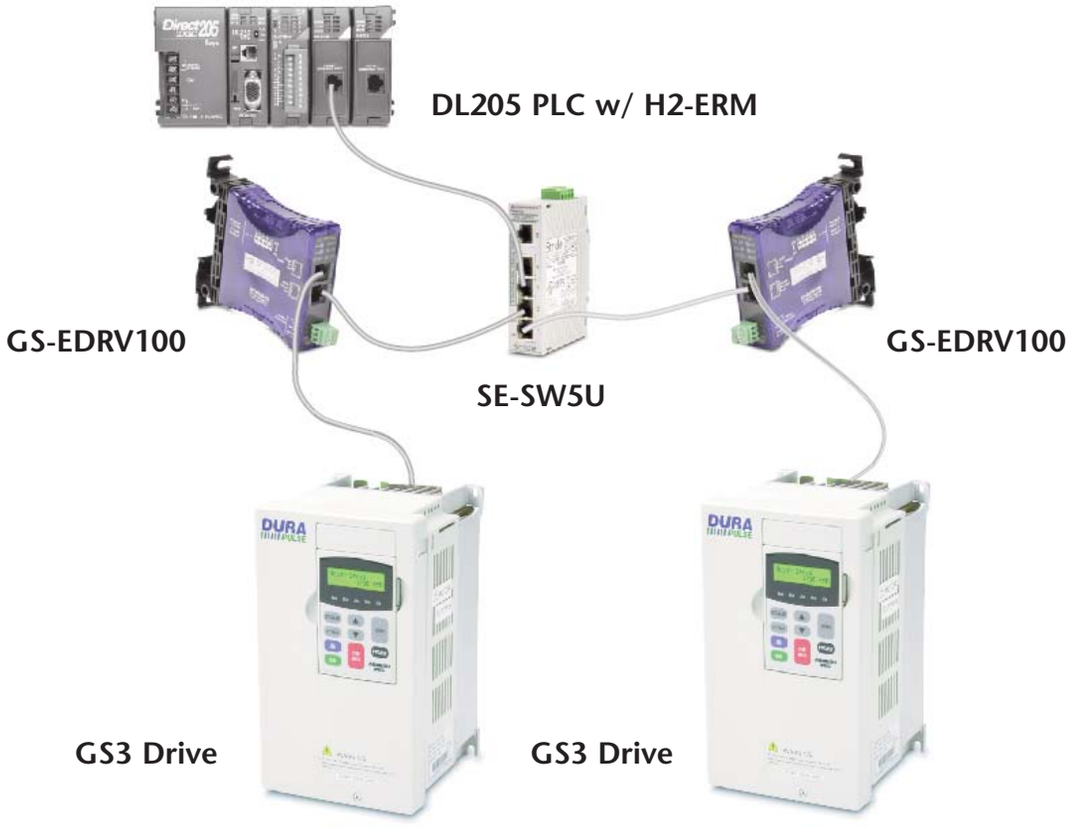


Double click on the desired GS-EDRV100. A "General Settings" popup will display allowing you to configure the IP address of the module you have selected.



Press the OK button to write the new configuration to the GS-EDRV100.

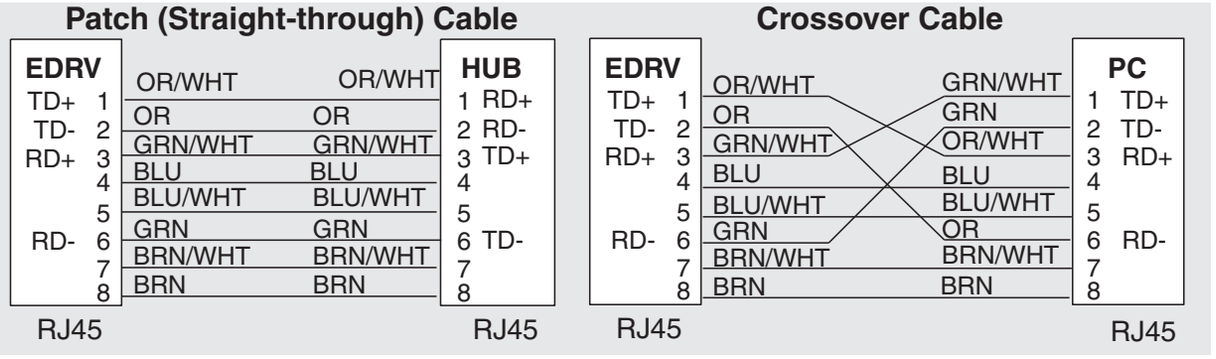
Network Connections



10/100Mbps Connections

The GS-EDRV100 Ethernet port has an eight-pin modular jack that accepts RJ45 connector plugs. UTP (Unshielded Twisted-Pair) cable is rated according to its data-carrying ability (bandwidth) and is given a "category" number. We strongly recommend using a category 5 cable for all Ethernet 10/100Mbps connections. For convenient and reliable networking, we recommend that you purchase commercially manufactured cables (cables with connectors already attached).

To connect an GS-EDRV100 (or PC) to a hub, switch, or repeater, use a patch cable (sometimes called a straight-through cable). The cable used to connect a PC or an H2(4)-ERM directly to an GS-EDRV100 or to connect two hubs is referred to as a crossover cable.



This diagram illustrates the standard wire positions in the RJ45 connector.
We recommend all Ethernet 10/100Mbps cables to be Category 5, UTP cable.

GS-EDRV(100) to GS Series AC Drive Connection

A serial connection cable (2ft. in length) is provided with the GS-EDRV(100) to make an RS-485 connection with a GS Series AC Drive.

*When using the **GS2** Series AC Drive , DIP Switch 2 and 3 (SW2 and SW3) on the drive must be set to RS485.*

Switches SW2 and SW3 on the drive must be set to RS485 for an RS-485 connection (GS2 Series Only).

Setting the GS Series AC Drive Parameters

The following parameters need to be set in the GS Series AC Drive in order to operate properly with the GS-EDRV(100) interface card.

P3.00: 03 or 04 – Operation Determined by RS232C/RS485 interface. Keypad STOP is enabled (03) or disabled (04).

P4.00: 05 – Frequency determined by RS232/RS485 communication interface

P9.00: xx – Communication address 01-254 (unique for each device)

P9.01: 01 – 9600 baud data transmission speed

P9.02: 05 – MODBUS RTU mode <8 data bits, odd parity, 1 stop bit>

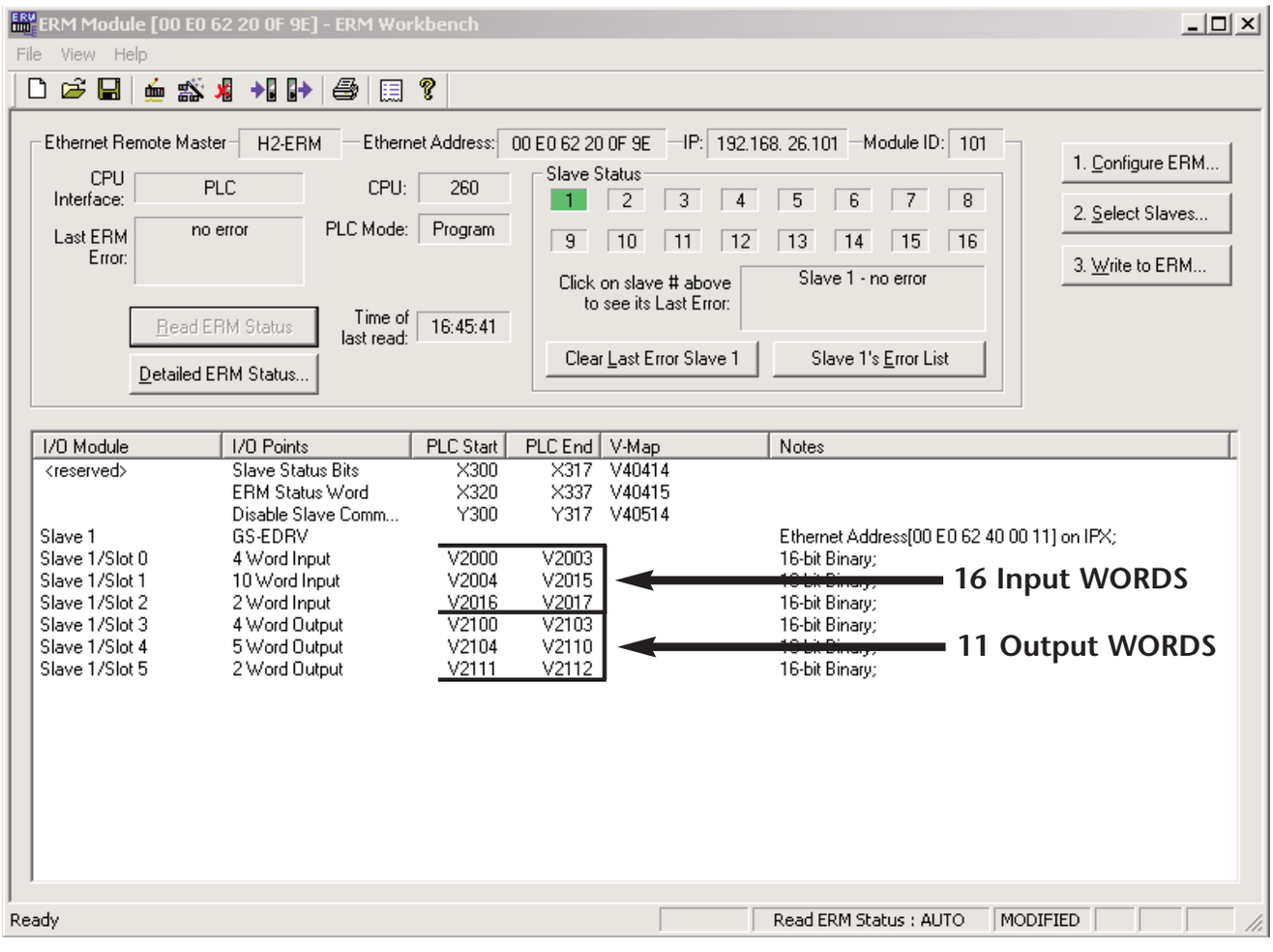
The previous list of parameter settings is the minimum required to communicate with a GS Series AC Drive through a GS-EDRV(100) interface card. There may be other parameters that need to be set to meet the needs of your application.

GS-EDRV(100) to ERM Module Connection

The GS-EDRV(100) interface card can be added to any H2(4)-ERM module using the ERM Workbench Utility. For more details on selecting and configuring slaves for the ERM module, see CHAPTER 4 of the H24-ERM-M.

Reserved PLC Memory for the GS-EDRV(100)

Once the GS-EDRV(100) is added the ERM module, 16 WORD inputs and 11 WORD outputs are mapped back to the PLC. The assigned PLC addresses are shown in the ERM Workbench Utility.



Reading/Writing From/To the Drive

The control function is NOT performed by the interface. The control function is performed by the control system. The I/O mapping function is performed by an H2(4)-ERM module (purchased separately). The H2(4)-ERM module is configured with the ERM Workbench Utility which is part of the DirectSOFT PLC programming software.

Input/Output Word Map

The Input and Output WORDS for the GS-EDRV(100) are mapped to specific parameters and functions in the GS Series AC Drives. The Word Map tables on the following pages show the Input and Output WORDS and their functions.

Using the Input/Output Words

Output Words 10 and 11 are used in conjunction with Input Words 15 and 16 to Read/Write AC drive parameters that are not mapped to other Input and Output Words. By using Output Words 10 and 11 with Input Words 14 and 15, you have the ability to read/write most AC drive parameters.

P9.29 is the only Communication Parameter (P9.xx range) that can be written to using the Read/Write Input/Output Words (IW 15 & 16; OW 10 & 11). However, these Input/Output Words can be used to read values from all of the drive Communication Parameters (P9.xx range).

Input Word Map

Input WORD Map		
Input Word	**Parameter Reference**	**Function**
1	N/A	Present Output Frequency
2	N/A	Present Output Current
3	Drive P9.29 & EDRV Comm Fault Bit	Bit 0 = Drive Serial Comm External Fault bit (P9.29) Bit 1 = EDRV internal EDRV-to-Drive Comm Fault bit 00 = 0: no EDRV-to-drive comm fault; no manual comm ext fault 01 = 1: no EDRV-to-drive comm fault; manual comm ext fault triggered 10 = 2: EDRV-to-drive comm fault; no manual comm ext fault 11 = 3: EDRV-to-drive comm fault; manual comm ext fault triggered
4	P6.31	P6.31 = Status Monitor 1 – Error Codes from AC Drive. 00: No fault occurred 01: Over-current(oc) 02: Over-voltage(ov) 03: Overheat (oH) 04: Overload (oL) 05: Overload 1 (oL1) 06: Overload 2 (oL2) 07: External Fault (EF) 08: CPU failure 1 (CF1) 09: CPU failure 2 (CF2) 10: CPU failure 3 (CF3) 11: Hardware Protection Failure (HPF) 12: Over-current during accel (OCA) 13: Over-current during decel (Ocd) 14: Over-current during steady state (Ocd) 15: Ground fault or fuse failure (GFF) 16: Low voltage (Lv) 17: Input power 3-phase loss 18: External Base-Block (bb) 19: Auto adjust accel/decel failure (cFA) 20: Software protection code (codE)
5	P9.16	Block Transfer Parameter 6 – User defined read value
6	P9.17	Block Transfer Parameter 7 – User defined read value
7	P9.18	Block Transfer Parameter 8 – User defined read value
8	P9.19	Block Transfer Parameter 9 – User defined read value
9	P9.20	Block Transfer Parameter 10 – User defined read value
10	P9.21	Block Transfer Parameter 11 – User defined read value
11	P9.22	Block Transfer Parameter 12 – User defined read value
12	P9.23	Block Transfer Parameter 13 – User defined read value
13	P9.24	Block Transfer Parameter 14 – User defined read value
14	P9.25	Block Transfer Parameter 15 – User defined read value

Table continued next page.

Input Word Map (continued)

Input WORD Map (continued)		
Input Word	**Parameter Reference**	**Function**
15	Read/Write Response	Response to a read/write request (Output Word 10) Bit: 00-07 = Memory Reference 08-11 = Memory type number (i.e. 0 to A for P0 to P10) 12-13 = Operation (works in conjunction with bit 15): 0=NOP, 9=Read accomplished, A=Write accomplished Bit 12 set indicates a read operation. Bit 13 set indicates a write operation. Bit 15 set indicates the read or write op was accomplished. Check bit 14 and Input Word 16 to see if an error occurred. 14 = Error status: If set, an error has occurred. Error Code is stored in Word 16. 15 = Read/Write Status: If set, the read or write operation was successful.
16	Read Request Value	If Input Word 15 is a Read response, the value is stored here. If Input Word 15 is an Error response, the error code is stored here. Error Codes: 0x8010 HEIE_INVALID_REQUEST 0x8090 HEIE_NOT_INITIALIZED 0x8096 HEIE_INVALID_OPERATION 0x006F HEIE_INVALID_TYPE 0x0091 HEIE_INVALID_MODE 0x008C HEIE_INVALID_ADDRESS 0x0085 HEIE_RANGE_ERROR 0x006D HEIE_SIZE_ERROR

Output Word Map

Output WORD Map		
Output Word	**Parameter Reference**	**Function**
1	P9.27	RUN Command
2	P9.26	RS-485 Speed Reference
3	P9.28	Direction Command (0 = Forward; 1 = Reverse)
4	P9.30	Serial Comm Fault Reset (0 = no action; 1 = Reset Fault)
5	P9.11	Block Transfer Parameter 1 – user defined write value
6	P9.12	Block Transfer Parameter 2 – user defined write value
7	P9.13	Block Transfer Parameter 3 – user defined write value
8	P9.14	Block Transfer Parameter 4 – user defined write value
9	P9.15	Block Transfer Parameter 5 – user defined write value
10	Read/Write Request	Bit: 00-07 = Memory Reference 08-11 = Memory type number (i.e. 0 to A for P0 to P10) 12-13 = Operation: 00=NOP, 01=Read, 10=Write, 11=Undefined 14 = Undefined for request
11	Write Request Value	If Output Word 10 is a Write request, the value to be written is placed here.

Examples – I/O Word Mapping

1) Read P9.29 (Serial Comm External Fault):
Write value 0x191D into Output Word 10, and the parameter address 0x991D will come back into Input Word 15. The value read from P9.29 will be stored in Input Word 16.

OW 10: Read Request: Read from drive parameter 9.29																
		n/a	operation		parameter group #				parameter memory reference #							
Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary #	0	n/a	0	1	1	0	0	1	0	0	0	1	1	1	0	1
Hex #	0	n/a	1		9				1				D			
Decimal #	0	n/a	1		9				29							
Meaning	n/a	n/a	read		parameter 9.29											

IW 15: Read Response: Read from drive parameter 9.29																
	status	error	operation		parameter group #				parameter memory reference #							
Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary #	1	0	0	1	1	0	0	1	0	0	0	1	1	1	0	1
Hex #	9				9				1				D			
Decimal #	9				9				29							
Meaning	successful		read		parameter 9.29											

2) Write to P9.29 (Serial Comm External Fault):
Write value 0x291D into Output Word 10, and the parameter address 0xA91D will come back into Input Word 15. The value in Output Word 11 will be written to drive P9.29.

OW 10: Write Request: Write to drive parameter 9.29																
		n/a	operation		parameter group #				parameter memory reference #							
Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary #	0	n/a	1	0	1	0	0	1	0	0	0	1	1	1	0	1
Hex #	0	n/a	2		9				1				D			
Decimal #	0	n/a	2		9				29							
Meaning	n/a	n/a	write		parameter 9.29											

IW 15: Write Response: Write to drive parameter 9.29																
	status	error	operation		parameter group #				parameter memory reference #							
Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary #	1	0	1	0	1	0	0	1	0	0	0	1	1	1	0	1
Hex #	A				9				1				D			
Decimal #	10				9				29							
Meaning	successful		write		parameter 9.29											

Examples – I/O Word Mapping (continued)

3) Read P0.00 (Motor Nameplate Voltage):
Write value 0x1000 into Output Word 10, and the parameter address 0x9000 will come back into Input Word 15. The value read from P0.00 will be stored in Input Word 16.

OW 10: Read Request: Read from drive parameter 0.00																
		n/a	operation		parameter group #				parameter memory reference #							
Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary #	0	n/a	0	1	0	0	0	0	0	0	0	0	0	0	0	0
Hex #	0	n/a	1		0				0				0			
Decimal #	0	n/a	1		0				0							
Meaning	n/a	n/a	read		parameter 0.00											

IW 15: Read Response: Read from drive parameter 0.00																
	status	error	operation		parameter group #				parameter memory reference #							
Bit #	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Binary #	1	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0
Hex #	9				0				0				0			
Decimal #	9				0				0							
Meaning	successful		read		parameter 0.00											

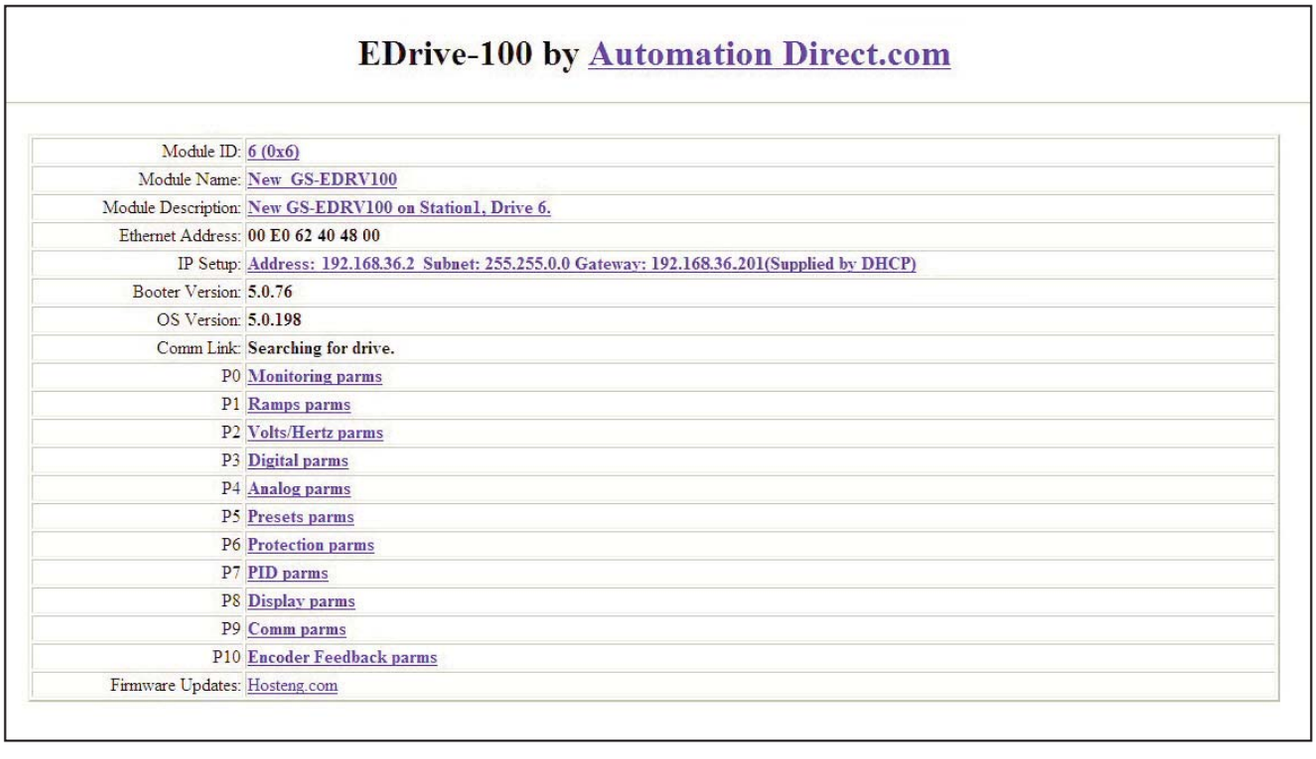
Built-in Web Server

The GS-EDRV(100) interface card has a built-in Web Server that allows you to access AC drive data with your favorite Web browser. In order to access the internal Web Server, you must first assign an IP address to the GS-EDRV(100) card. The IP address can be assigned by using the NetEdit utility. You can then access the GS-EDRV(100) card by typing the IP address into your Web browser.

Example

If the IP address of your GS-EDRV100 is 192.168.36.2, just enter **http://192.168.36.2** into the address field of your browser and press the **Enter** key.

The browser will then access the built-in Web Server as seen below. The available parameter groups are shown with links to the parameter options.



EDrive-100 by Automation Direct.com

Module ID:	6 (0x6)
Module Name:	New_GS-EDRV100
Module Description:	New GS-EDRV100 on Station1, Drive 6.
Ethernet Address:	00 E0 62 40 48 00
IP Setup:	Address: 192.168.36.2 Subnet: 255.255.0.0 Gateway: 192.168.36.201(Supplied by DHCP)
Booter Version:	5.0.76
OS Version:	5.0.198
Comm Link:	Searching for drive.
P0	Monitoring parms
P1	Ramps parms
P2	Volts/Hertz parms
P3	Digital parms
P4	Analog parms
P5	Presets parms
P6	Protection parms
P7	PID parms
P8	Display parms
P9	Comm parms
P10	Encoder Feedback parms
Firmware Updates:	Hosteng.com

Troubleshooting – H24-ERM-M

Refer to Ethernet Remote Master User Manual H24-ERM-M

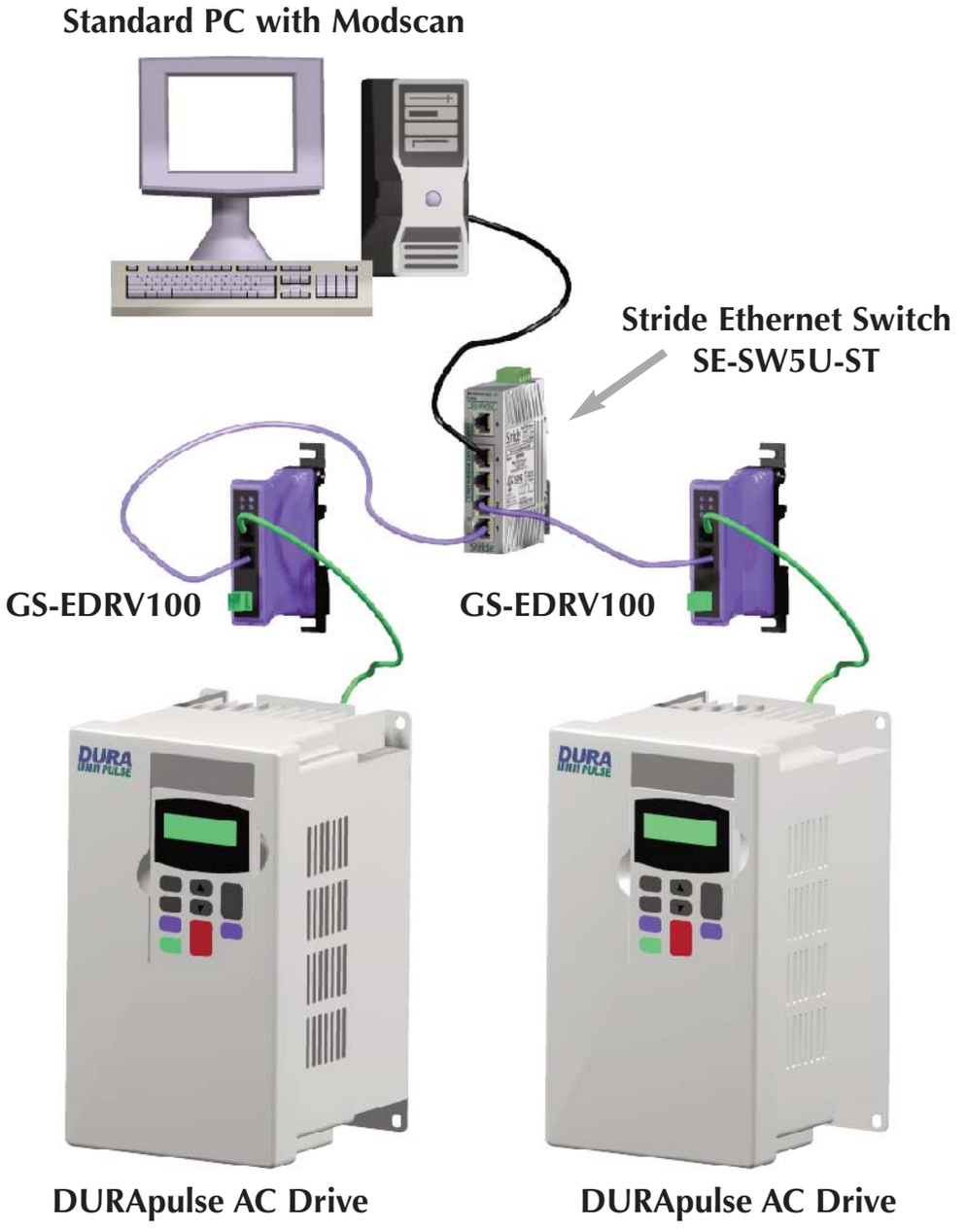
Troubleshooting help for the ERM module and its slaves is available in CHAPTER 6 of the Ethernet Remote Master User Manual (H24-ERM-M).

Application Example: Modbus TCP/IP

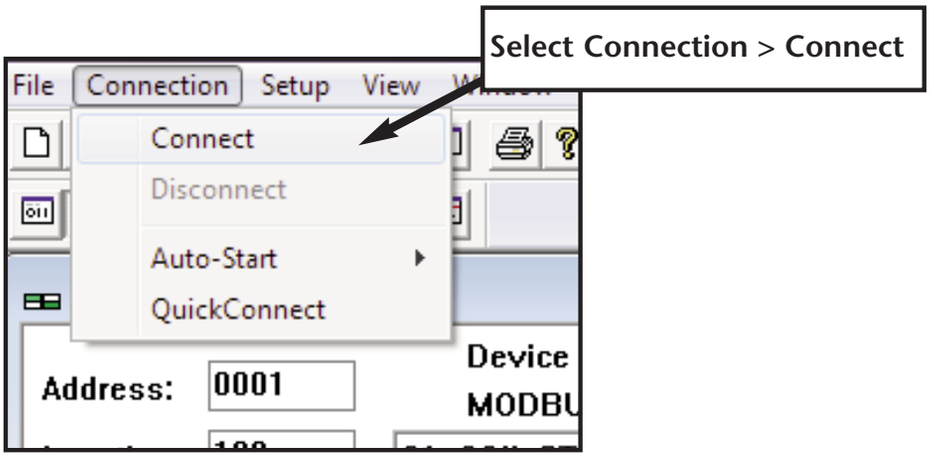
This application example shows how to use a GS-EDRV(100) to access a GS1, GS2 or a DURApulse drive's parameters for monitoring and control via the Modbus TCP/IP protocol.

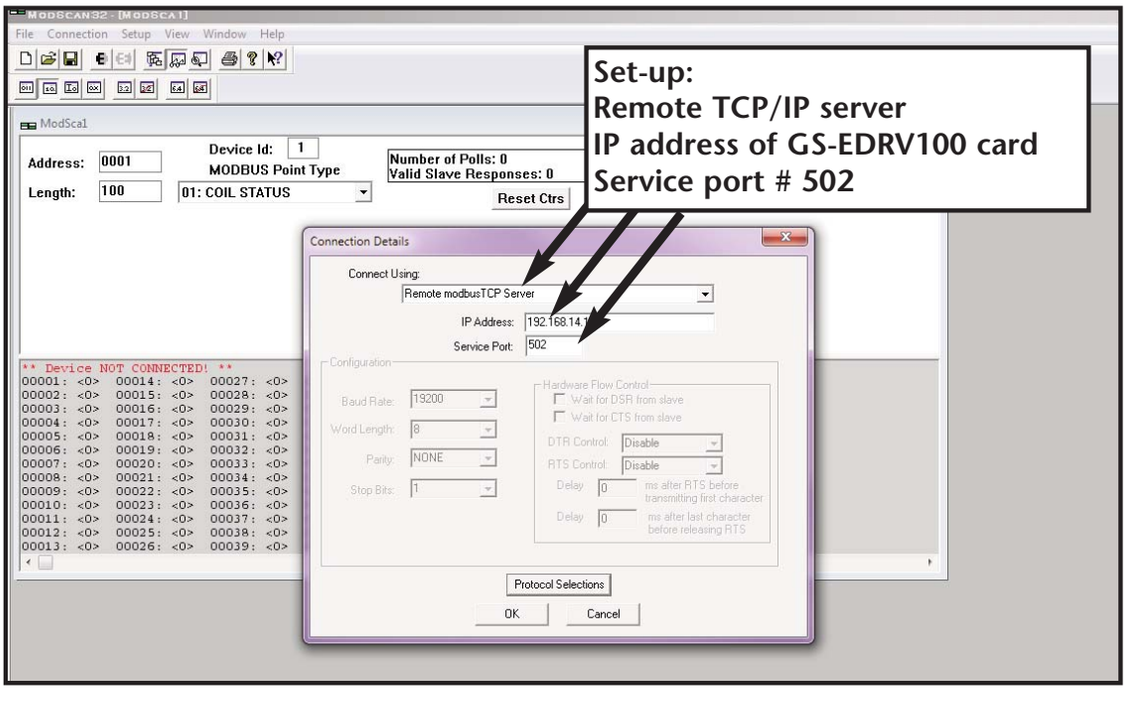
Equipment and software used in example:

- Two DURApulse Drives
- Two GS-EDRV100 Ethernet interface modules
- A Stride Ethernet switch (SE-SW5U-ST)
- A standard network PC with a Modbus TCP/IP driver installed
- ModScan software (available for download from Win-Tech at http://www.win-tech.com/html/demos.htm). or any other Modbus TCP/IP interfacing software

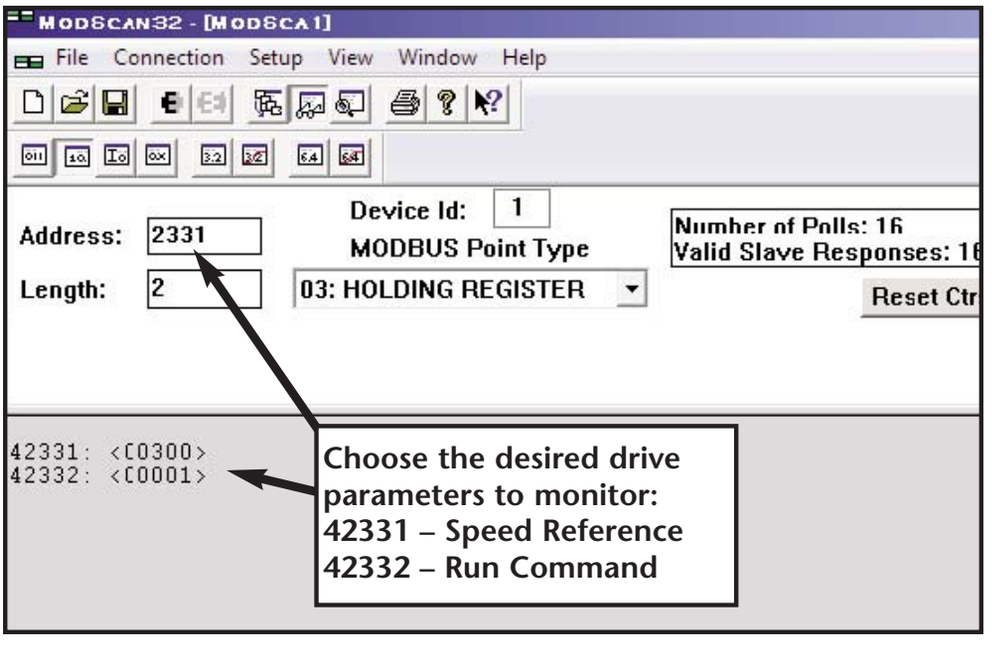


To monitor drive parameters using ModScan, set up the connection parameters as follows:





Once a connection to the interface has been established, select the drive parameters that you wish to monitor. See the table below for drive parameters and their modbus addresses.



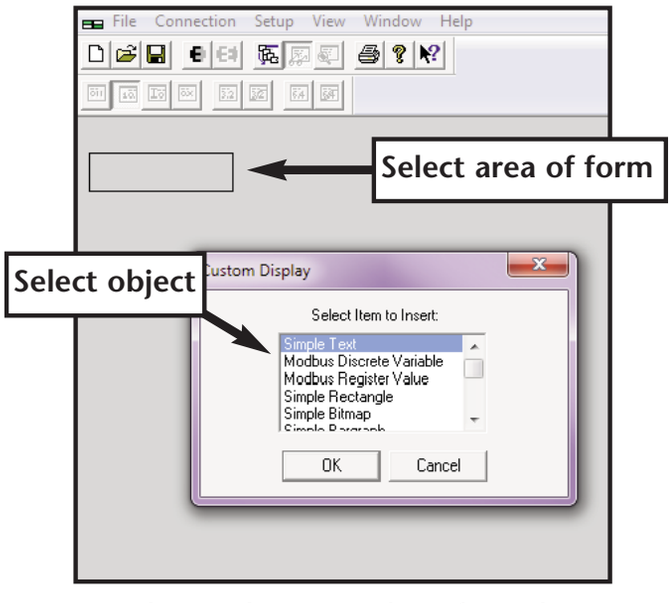
If you wish to write a value to the drive from this page, double click the address you wish to change and a Write Register window will appear. Enter the new value and select Update.

Modbus Addresses		
Read/Write	**Hex**	**Modbus**
Speed reference	091AH	42331
Run command	091BH	42332
Direction	091CH	42333
External fault	091DH	42334
Fault reset	091EH	42335
Jog	091FH	42336
Status	2101H	48450
Frequency command	2102H	48451
Output frequency	2103H	48452
Output current	2104H	48453
DC bus voltage	2105H	48454
Output voltage	1206H	48455
Motor RPM	2107H	48456
Scale frequency (low)	2108H	48457
Scale frequency (high)	2109H	48458
Percent load	210BH	48460
Firmware version	2110H	48465

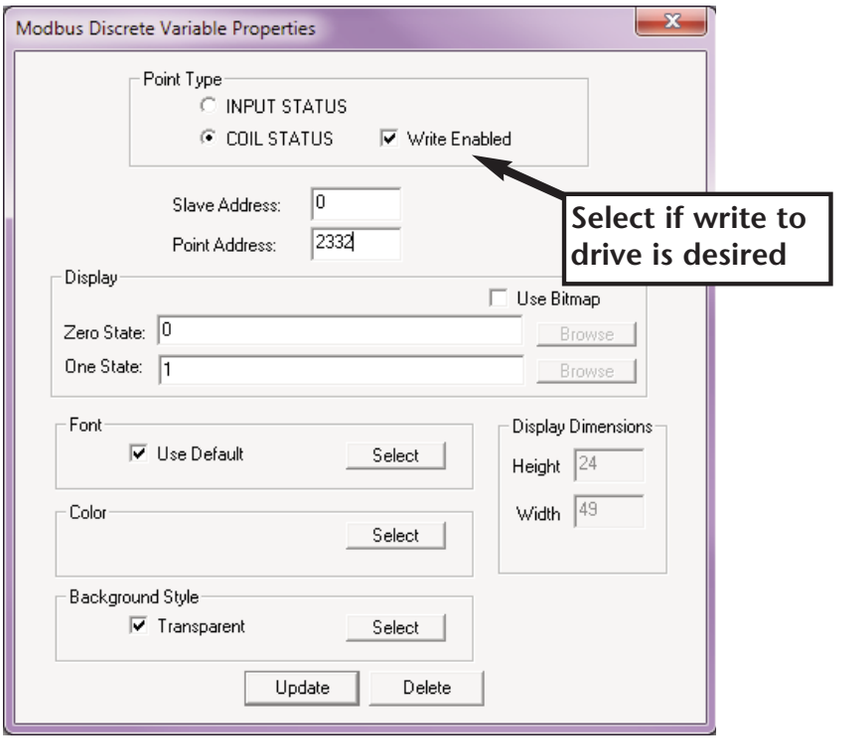
ModScan gives you the ability to build custom interface forms (like the one below) that can be used to display and control GS/DURApulse drive parameters.

Custom Form			
GS3-43PO	**Default**	**New**	**Comments**
P0.00	480	460	Motor nameplate voltage setting
P0.01	5	4.8	Motor nameplate amps setting
P0.02	60	60	Motor base frequency
P0.03	1750	1725	Motor base RPM
P0.04	1750	1725	Motor maximum RPM
P1.00	0	1	Coast to stop
P1.01	10	20	Acceleration time
P2.00	0	2	Volts/hertz set to fans and pumps
P3.00	0	3	RS485 operation control enabled
P4.00	0	5	RS485 speed reference control
P8.00	0	3	RPM display
P9.00	1	X (1)	Communication address (dependent on drive 1-8)
P9.01	1	1	9600 baud rate
P9.02	0	5	Modbus RTU 8 data bits, odd parity, 1 stop bit

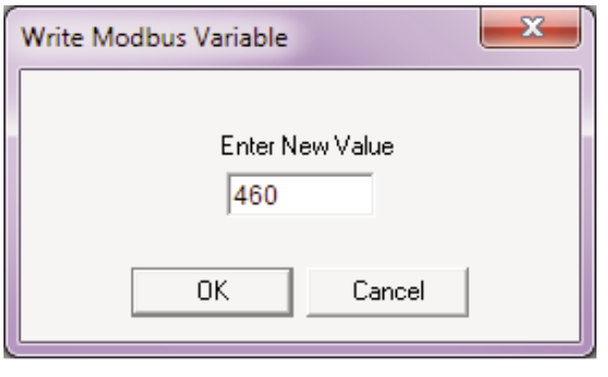
To build a new form, select **File>Custom Form>Create** and a blank form will open. With your mouse, select an area of the form and a Custom Display menu will appear as seen below.



Select an object (text, charts, shapes or data) from the menu and ModScan will load the selection into the form. When creating data objects, such as Register and Discrete variables, selecting the Write Enabled checkbox (as seen on following page) will allow the user to write values out to the drive from this form.



Once a read/write data object is created, double click on the object and a Write Modbus Variable popup will appear allowing the user to enter a new value for the selected parameter.



Enter the new value and select OK to write the new value to the drive.