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# HC67Q2

**PICMG 1.3 Full-size SBC**

## **User's Manual**

**Version 1.0**

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# Chapter 1

# Introduction

## 1.1 Copyright Notice

All Rights Reserved.

The information in this document is subject to change without prior notice in order to improve the reliability, design and function. It does not represent a commitment on the part of the manufacturer.

Under no circumstances will the manufacturer be liable for any direct, indirect, special, incidental, or consequential damages arising from the use or inability to use the product or documentation, even if advised of the possibility of such damages.

This document contains proprietary information protected by copyright. All rights are reserved. No part of this manual may be reproduced by any mechanical, electronic, or other means in any form without prior written permission of the manufacturer.

## 1.2 Declaration of Conformity

### CE

This product has passed the CE test for environmental specifications when shielded cables are used for external wiring. This kind of cable is available from ICI. Please contact your local supplier for ordering information.

Test conditions for passing included the equipment being operated within an industrial enclosure. In order to protect the product from being damaged by ESD (Electrostatic Discharge) and EMI leakage, we strongly recommend the use of CE-compliant industrial enclosure products.

### FCC Class A

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions : (1) this device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

### ROHS

Industrial Computers Inc. certifies that all components in its products are in compliance and conform to the European Union's Restriction of Use of Hazardous Substances in Electrical and Electronic Equipment (RoHS) Directive 2002/95/EC.

The above mentioned directive was published on 2/13/2003. The main purpose of the directive is to prohibit the use of lead, mercury, cadmium, hexavalent chromium, polybrominated biphenyls (PBB), and polybrominated

the EU are to enforce by 7/1/2006.

Industrial Computers Inc. hereby states that the listed products do not contain unintentional additions of lead, mercury, hex chrome, PBB or PBDB that exceed a maximum concentration value of 0.1% by weight or for cadmium exceed 0.01% by weight, per homogenous material. Homogenous material is defined as a substance or mixture of substances with uniform composition (such as solders, resins, plating, etc.). Lead-free solder is used for all terminations (Sn(96-96.5%), Ag(3.0-3.5%) and Cu(0.5%)).

### **SVHC / REACH**

To minimize the environmental impact and take more responsibility to the earth we live, Arbor hereby confirms all products comply with the restriction of SVHC (Substances of Very High Concern) in (EC) 1907/2006 (REACH --Registration, Evaluation, Authorization, and Restriction of Chemicals) regulated by the European Union.

All substances listed in SVHC < 0.1 % by weight (1000 ppm)

### **1.3 About This User's Manual**

This user's manual provides general information and installation instructions about the product. This User's Manual is intended for experienced users and integrators with hardware knowledge of personal computers. If you are not sure about any description in this booklet. Please consult your vendor before further handling.

### **1.4 Warning**

Single Board Computers and their components contain very delicate Integrated Circuits (IC). To protect the Single Board Computer and its components against damage from static electricity, you should always follow the following precautions when handling it :

1. Disconnect your Single Board Computer from the power source when you want to work on the inside.
2. Hold the board by the edges and try not to touch the IC chips, leads or circuitry.
3. Use a grounded wrist strap when handling computer components.
4. Place components on a grounded antistatic pad or on the bag that comes with the Single Board Computer, whenever components are separated from the system.

## 1.5 Replacing the Lithium Battery

Incorrect replacement of the lithium battery may lead to a risk of explosion.

The lithium battery must be replaced with an identical battery or a battery type recommended by the manufacturer.

Do not throw lithium batteries into the trash-can. It must be disposed of in accordance with local regulations concerning special waste.

## 1.6 Technical Support

If you have any technical difficulties, please do not hesitate to call or e-mail our customer service.

<http://www.eindustrialcomputers.com>

email: [support@eindustrialcomputers.com](mailto:support@eindustrialcomputers.com)

## 1.7 Warranty

This product is warranted to be in good working order for a period of two years from the date of purchase. Should this product fail to be in good working order at any time during this period, we will, at our option, replace or repair it at no additional charge except as set forth in the following terms. This warranty does not apply to products damaged by misuse, modifications, accident or disaster.

Vendor assumes no liability for any damages, lost profits, lost savings or any other incidental or consequential damage resulting from the use, misuse of, or inability to use this product. Vendor will not be liable for any claim made by any other related party.

Vendors disclaim all other warranties, either expressed or implied, including but not limited to implied warranties of merchantability and fitness for a particular purpose, with respect to the hardware, the accompanying product's manual(s) and written materials, and any accompanying hardware. This limited warranty gives you specific legal rights.

Return authorization must be obtained from the vendor before returned merchandise will be accepted. Authorization can be obtained by calling or faxing the vendor and requesting a Return Merchandise Authorization (RMA) number. Returned goods should always be accompanied by a clear problem description.

## 1.8 Packing List

### Packing List

Before you begin installing your single board, please make sure that the following materials have been shipped:



1 x HC67Q2 PICMG 1.3 Full-size SBC



1 x Driver CD  
1 x Quick Installation Guide

CBK-06-67Q1-00

#### Cable Kit

1 x RS-232 cable  
1 x RS-232/422/485 cable  
1 x SATA cable  
1 x USB cable w/ bracket  
1 x Keyboard & Mouse cable  
1 x AUDIO cable

If any of the above items is damaged or missing, contact your vendor immediately.

## 1.9 Ordering Information

**Note:**

HC67Q2 supports 4 x PCIe x1 Slots. Another version is available that supports 1 x x4 PCIe x4 slot. PCIe x4 slot and PCIe x1 slot can't work at the same time with the same BIOS version. Therefore, 2 BIOS versions are required to be applied as following configurations. If you want to change the BIOS setting for PCIe support, please contact our tech support at [support@eindustrialcomputers.com](mailto:support@eindustrialcomputers.com)

Update BIOS in DOS:

- PCIe1.bat: BIOS set as PCIe x1 enabled.
- PCIe4.bat: BIOS set as PCIe x4 enabled.

## 1.10 Specifications

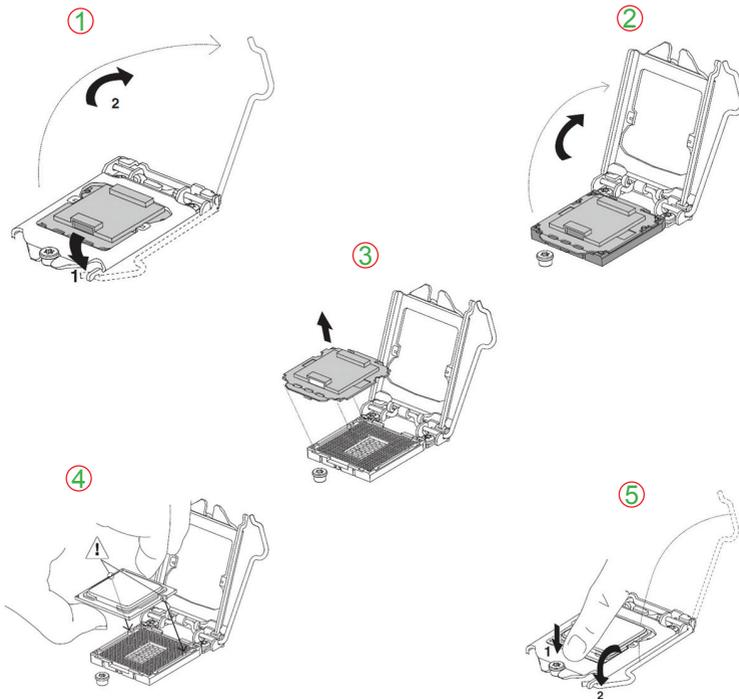
Form Factor	PICMG 1.3 Full-size SBC
Processor	Socket LGA1155 for Intel 32nm Sandy Bridge processors (i7-2600 at 3.4GHz, i5-2400 at 3.1GHz, i3-2120 at 3.3GHz, or Pentium G850 at 2.9GHz)
Chipset	Intel® PCH Q67
System Memory	2 x 240-pin Long-DIMM sockets, supporting DDR3 1066/1333MHz, up to 8GB
Graphics	Integrated Intel HD Graphics 200
Display	1 x Analog RGB supported, up to 2048 x 1536 @60Hz
Super I/O	Fintek F71869ED
BIOS	AMI BIOS
Serial ATA	2 x SATA 600MB/s ports, 4 x SATA 300MB/s ports (2 x SATA ports on SBC, 2 x SATA ports through GF to Backplane) Support RAID 0, 1, 5, 10
Ethernet	2 x Intel 82583V PCIe GbE controllers
USB 2.0	14 x USB 2.0 ports: 10 x ports by pin-header, 4 x ports to GF
Serial Port	2 x COM ports: COM1 RS-232, COM2 RS-232/422/485 selectable
Parallel Port	SPP/EPP/ECP mode
Digital I/O	8-bit programmable digital I/O
Keyboard/ Mouse	One 6-pin Mini-DIN connector for keyboard and mouse (PS/2 standard via Y-cable)
Audio	HD Audio Codec ALC886, Line-in/ Line-out/MIC
Expansion Bus	Standard SHB Express
Power Connector	4-pin ATX 12V type and ATX feature
Certification	CE/FCC
Operation Temp.	0°C ~ 60°C (32°F ~ 140°F)
Humidity	0% ~ 95% non-condensing
Dimension (L x W)	338 x 126 mm (13.3" x 4.96")



## 1.12 Installing the CPU

The LGA1155 processor socket comes with a lever to secure the processor. Please refer to the pictures step by step as below.

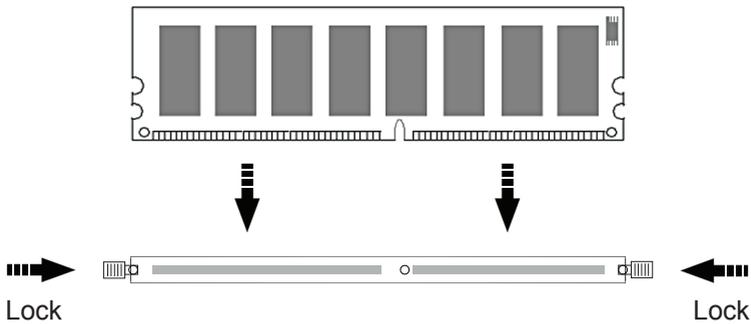
1. Push the lever down to unclip it and lift it.
2. Open the load plate.
3. Remove the protective cover from the load plate. Do not discard the protective cover. Always replace the socket cover if the processor is removed from the socket.
4. Hold processor with your thumb and index fingers, oriented as shown. Ensure your fingers align to the socket cutouts. Align the notches with the socket. Lower the processor straight down without tilting or sliding the processor in the socket.
5. Close the load plate. Pressing down on the load plate, close and engage the socket lever.



### 1.13 Installing the Memory

To install the Memory module, locate the Memory DIMM slot on the board and perform as below:

1. Hold the Memory module so that the key of the Memory module align with those on the Memory DIMM slot.
2. Gently push the Memory module in an upright position and a right way until the clips of the DIMM slot close to lock the Memory module in place, when the Memory module touches the bottom of the DIMM slot.
3. To remove the Memory module, just pressing the clips of DIMM slot with both hands.

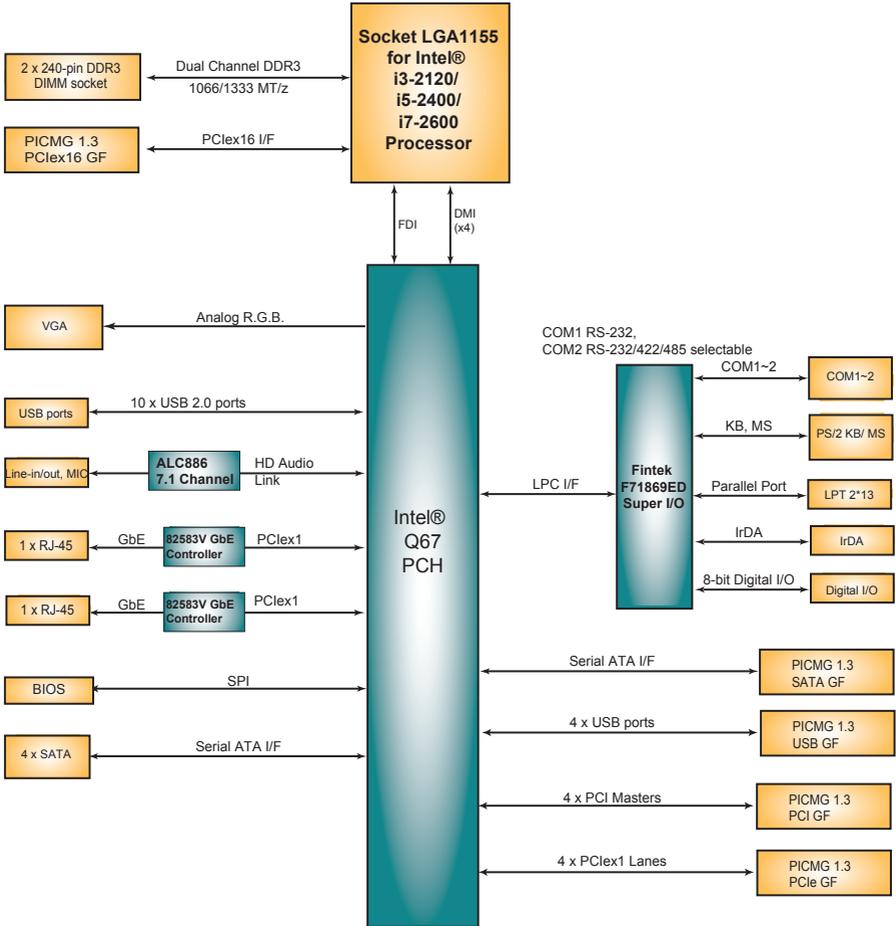




**Chapter 2**

**Installation**

## 2.1 Block Diagram



## 2.2 Jumpers and Connectors

### Jumpers/ Connectors Quick Reference

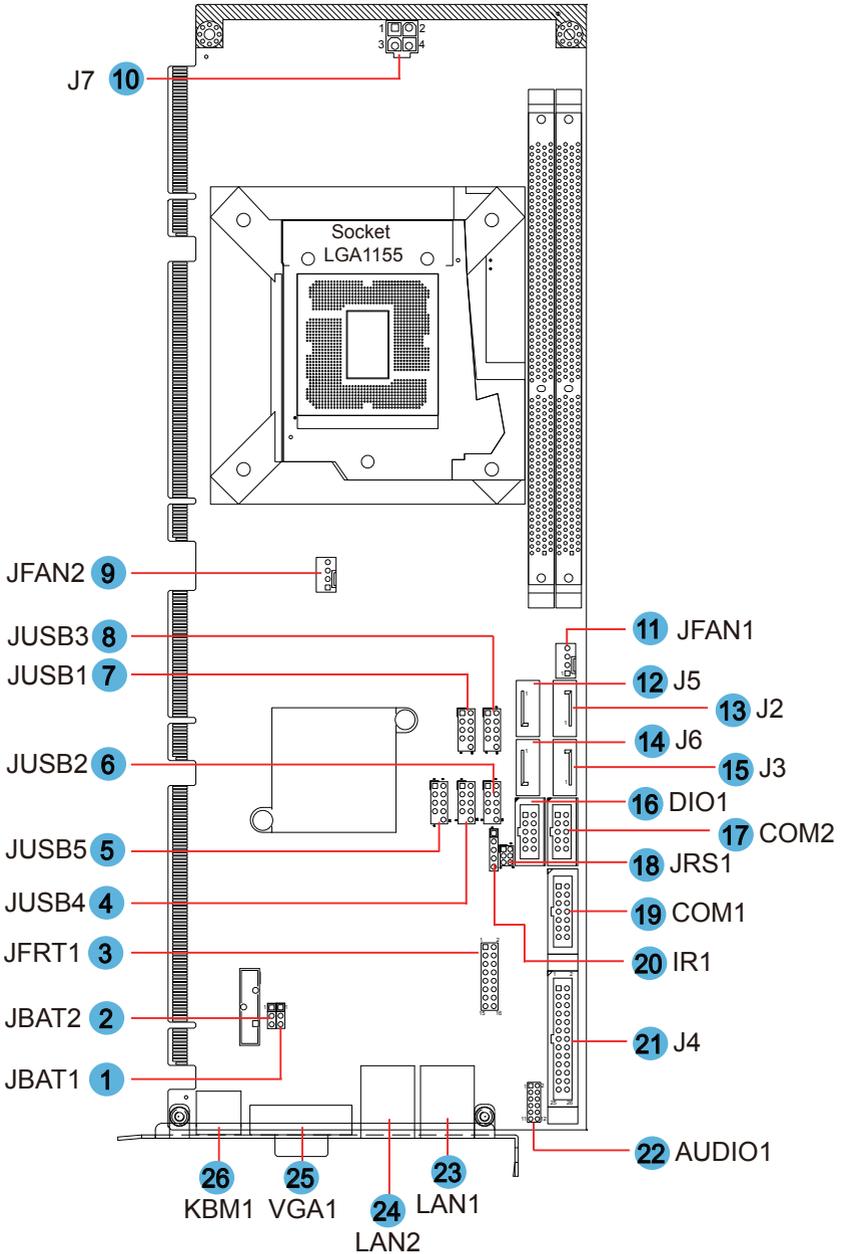
#### Jumpers

Label	Description
JBAT1	Protected RTC Setting
JBAT2	Clear CMOS Setting
JRS1	COM2 RS-232/422/485 Selection

#### Connectors

Label	Description
AUDIO1	AUDIO Connector
COM1	RS-232 Connector
COM2	RS-232/422/485 Connector
DIO1	Digital I/O Connector
IR1	Infrared Connector
J2, J3, J5, J6	SATA Connectors
J4	LPT Connector
J7	ATX1 2V power Connector
JFAN1~2	Fan Connectors
JFRT1	Switches and Indicators
JUSB1~5	USB Port Connectors
KBM1	Keyboard and Mouse Connector
LAN1~2	Ethernet Connectors
VGA1	Analog RGB Connector

### 2.3 Jumpers & Connectors Location



## 2.4 Jumpers

### JBAT1: Protected RTS Setting (1)

If the board refuses to boot due to inappropriate CMOS settings here is how to proceed to clear (reset) the CMOS to its default values.

Connector type: 2.54mm pitch 1x3-pin headers

Pin	Mode	
1-2	Keep Protected (Default)	
2-3	Clear CMOS	

### JBAT2: Clear CMOS Setting (2)

If the board refuses to boot due to inappropriate CMOS settings here is how to proceed to clear (reset) the CMOS to its default values.

Connector type: 2.54mm pitch 1x3-pin headers

Pin	Mode	
1-2	Keep CMOS (Default)	
2-3	Clear CMOS	

You may need to clear the CMOS if your system cannot boot up because you forgot your password, the CPU clock setup is incorrect, or the CMOS settings need to be reset to default values after the system BIOS has been updated.

Refer to the following solutions to reset your CMOS setting:

#### **Solution A:**

1. Power off the system and disconnect the power cable.
2. Place a shunt to short pin 2 and pin 3 of JBAT1 for five seconds.
3. Place the shunt back to pin 1 and pin 2 of JBAT1.
4. Power on the system.

#### **Solution B:**

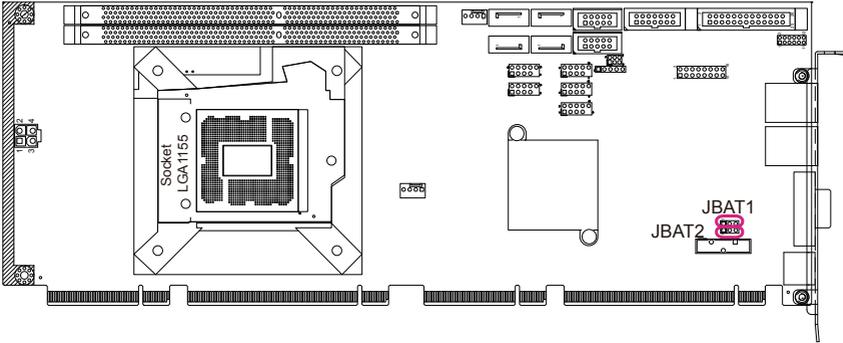
If the CPU Clock setup is incorrect, you may not be able to boot up. In this case, follow these instructions:

Turn the system off, then on again. The CPU will automatically boot up using standard parameters.

As the system boots, enter BIOS and set up the CPU clock.

**Note:**

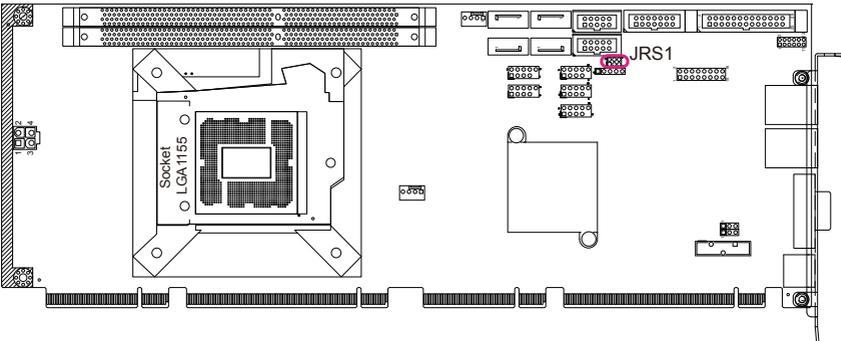
If you are unable to enter BIOS setup, turn the system on and off a few times.



**JRS1: COM2 RS-232 / 422 / 485 Selection (18)**

Connector type: 2.00mm pitch 2x3-pin headers.

Mode	RS-232 (Default)	RS-422	RS-485
1-2	Short	Open	Open
3-4	Open	Short	Open
5-6	Open	Open	Short



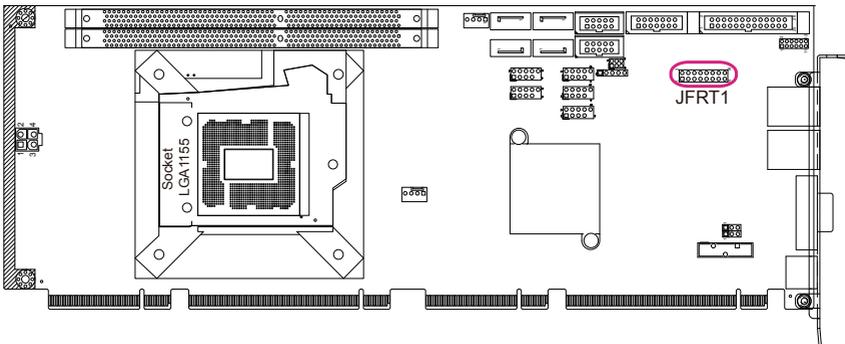
## 2.5 Connectors

### JFRT1: Switches and Indicators (3)

It provides connectors for system indicators that provides light indication of the computer activities and switches to change the computer status.

Connector type: 2.54mm pitch 2x8-pin headers.

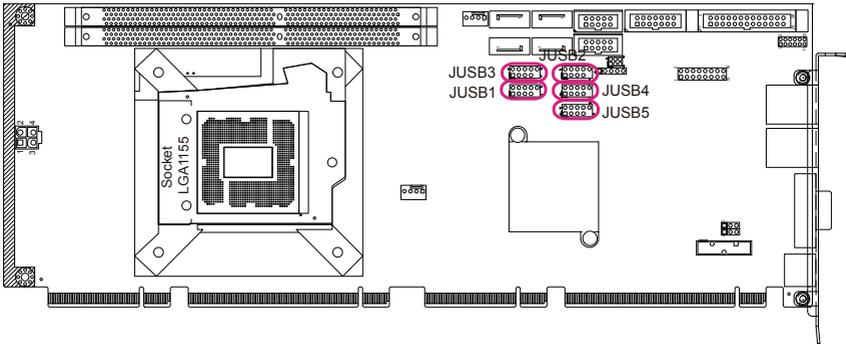
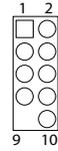
Pin	Description	Pin	Description
1	Power LED+	2	PWRBTN+
3	Power LED-	4	PWRBTN-
5	Power LED-	6	RESET+
7	HD LED+	8	RESET-
9	HD LED-	10	SPEAKER+
11	SMB CLK	12	SPEAKER+
13	SMB DAT	14	SPEAKER-
15	SMB GND	16	SPEAKER-



### JUSB1~5: USB Ports (4, 5, 6, 7, 8)

Connector type: 2.54mm pitch 2x5 pin-header, pin-10 is eliminated.

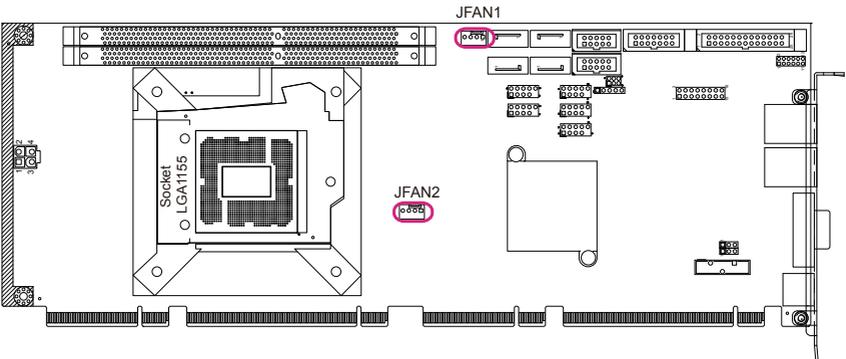
Pin	Description.	Pin	Description.
1	+5V	2	+5V
3	USBD1-	4	USBD2-
5	USBD+	6	USBD2+
7	GND	8	GND
9	N/C (Key)	10	N/C



### JFAN1, 2: Fan Connectors (9), (11)

Connector type: 2.54mm pitch 1x4-pin wafer connector.

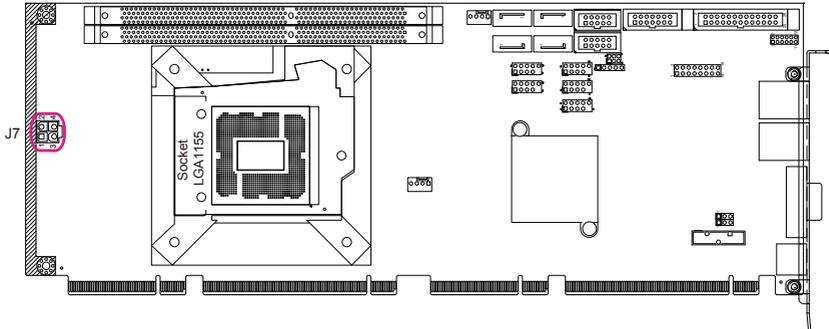
Pin	Description
1	GND
2	+12V
3	RPM
4	FAN_CTL



### J7: ATX +12V Connector (10)

J7 supplies the CPU operation ATX +12V (Vcore).

Pin	Description	Pin	Description
1	GND	2	GND
3	+12V	4	+12V

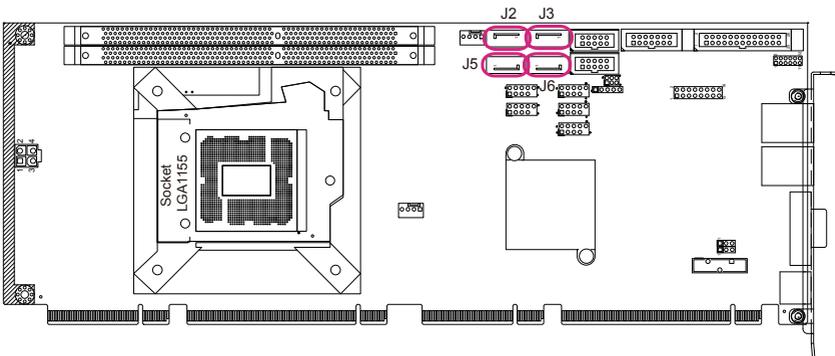
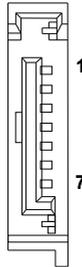


### J2, J3, J5, J6: Serial ATA Connectors (12, 13, 14, 15)

Connector type: SATA connectors.

#### Pin Description

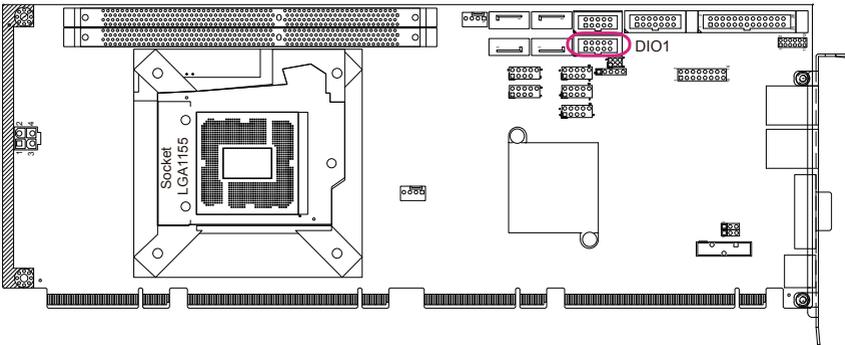
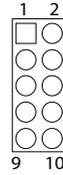
1	GND
2	TX+
3	TX-
4	GND
5	RX-
6	RX+
7	GND



### DIO1: Digital I/O Connector (16)

Connector type: 2.54mm pitch 2x5-pin headers.

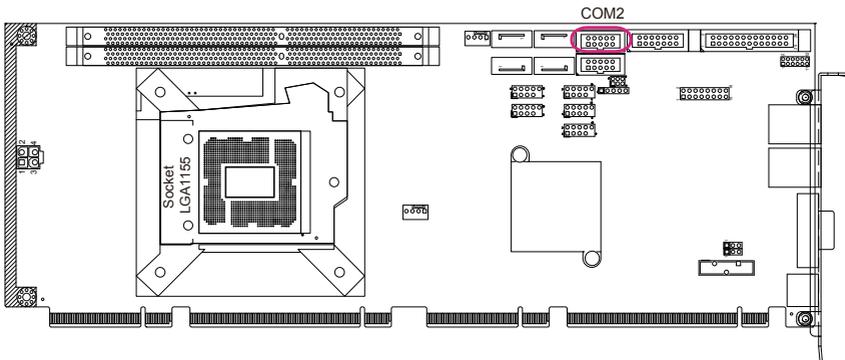
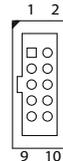
Pin	Description	Pin	Description
1	DIO0	2	DIO1
3	DIO2	4	DIO3
5	DIO4	6	DIO5
7	DIO6	8	DIO7
9	+5V	10	GND



### COM2: RS-232 Port (17)

Connector type: 2.54mm pitch 2x5-pin box headers.

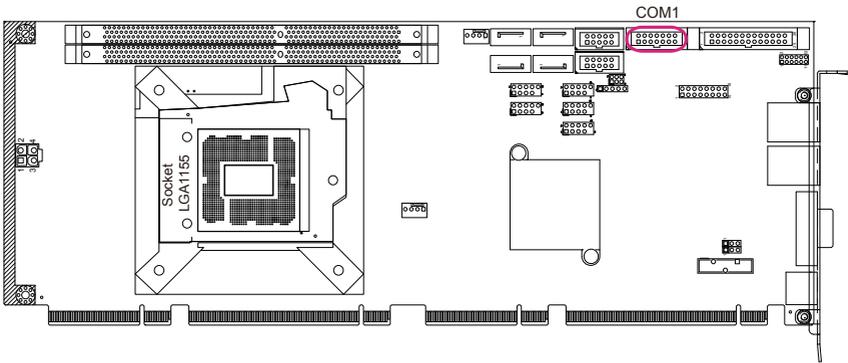
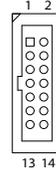
Pin	Description	Pin	Description
1	DCD#	2	DSR#
3	RXD	4	RTS#
5	TXD	6	CTS#
7	DTR#	8	RI#
9	GND	10	N/C



## COM1: RS-232/422/485 Port (19)

Connector type: 2.54mm pitch 2x7-pin box headers.

Pin	Description	Pin	Description
1	DCD#	2	DSR#
3	RXD	4	RTS#
5	TXD	6	CTS#
7	DTR#	8	RI#
9	GND	10	GND
11	442TX+/ 485+	12	422TX-/ 485-
13	422RX+	14	422RX-

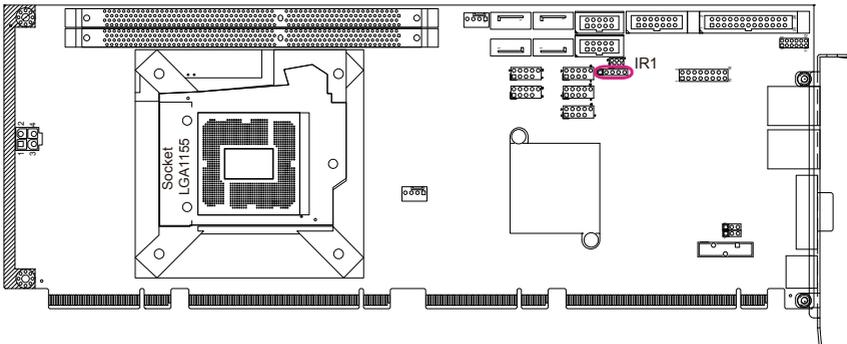
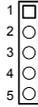


## IR1: Infrared Connector (20)

Connector type: 2.54mm pitch 1x5-pin headers.

Pin	Description
-----	-------------

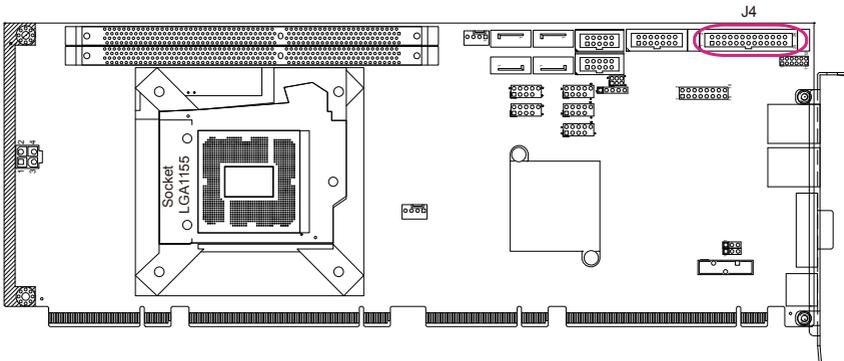
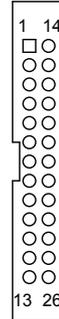
1	+5V
2	N/C
3	IRRX
4	GND
5	IRTX



### J4: Parallel Port Connector (21)

Connector type: 2.54mm pitch 2x13 box headers.

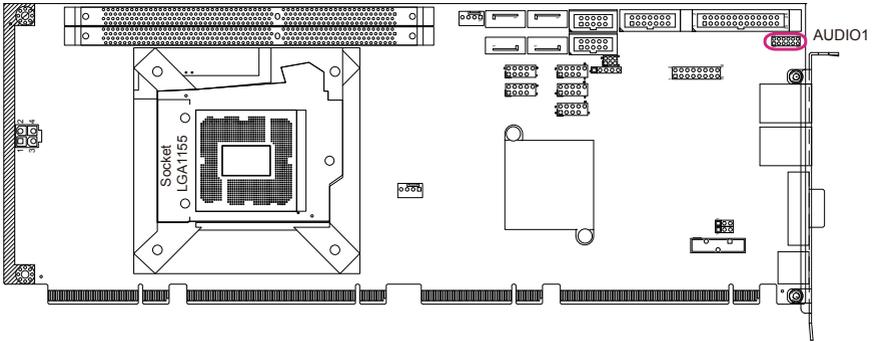
Pin	Description	Pin	Description
1	STB#	14	AFD#
2	PTD0	15	ERROR#
3	PTD1	16	INIT#
4	PTD2	17	SLIN#
5	PTD3	18	GND
6	PTD4	19	GND
7	PTD5	20	GND
8	PTD6	21	GND
9	PTD7	22	GND
10	ACK#	23	GND
11	BUSY	24	GND
12	PE	25	GND
13	SELECT	26	N/C



### AUDIO1: AUDIO Connector (22)

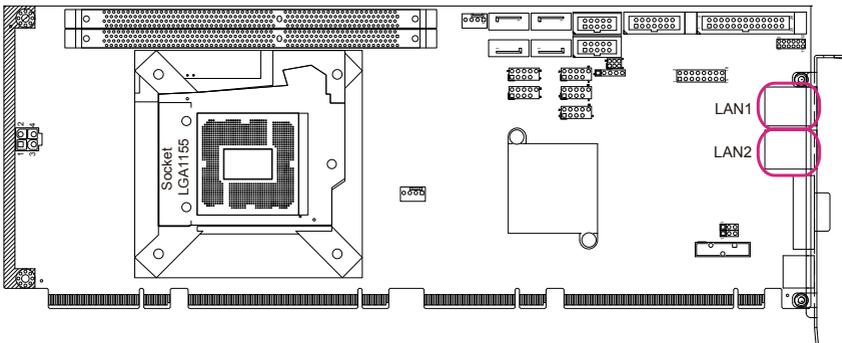
Connector type: 2.00mm pitch 2x6-pin headers.

Pin	Description	Pin	Description
1	LIN-L	2	LIN-R
3	LINE-JD	4	GND_AU
5	MICL	6	MICR
7	MIC-JD	8	GND_AU
9	LOUT-L	10	LOUT-R
11	FRONT-JD	12	GND_AU



### LAN1, 2: GbE Connectors (23), (24)

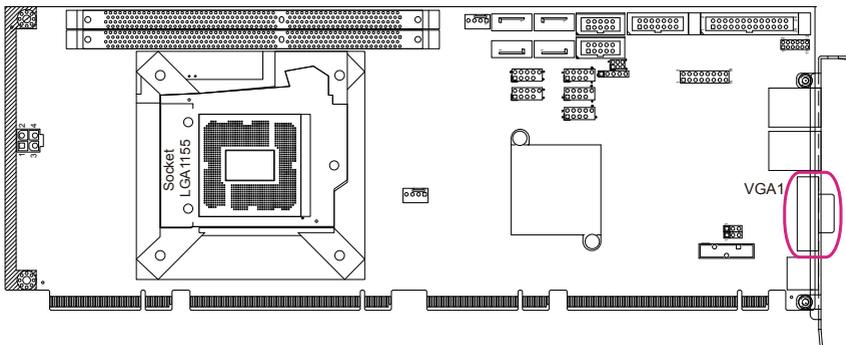
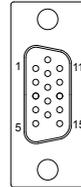
Connector type: RJ-45 with LED indicators.



## VGA1: Analog RGB Connector (25)

Connector type: D-Sub 15-pin female.

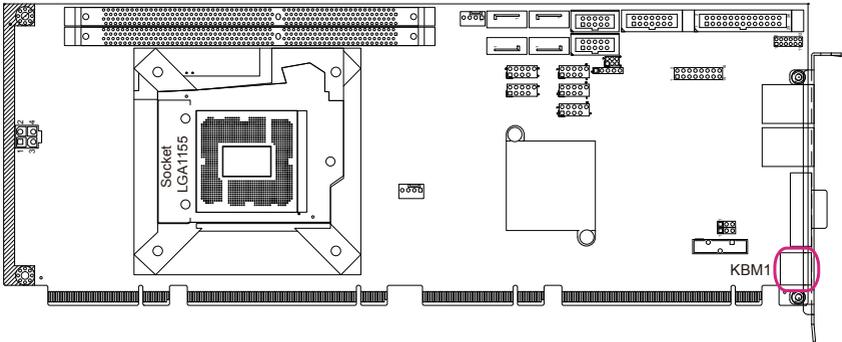
Pin	Description	Pin	Description
1	RED	9	VCC
2	GREEN	10	GND
3	BLUE	11	N/C
4	N/C	12	DDC_DATA
5	GND	13	HSYNC
6	GND	14	VSYNC
7	GND	15	DDC-CLK
8	GND		



## KBM1: Keyboard & Mouse Connector (26)

Connector type: 6-pin Mini-DIN connector.

Pin	Description
1	KB Data
2	MS Data
3	GND
4	VCC PS2
5	KB Clock
6	MS Clock



## 2.6 The Installation Paths of CD Driver

### Windows XP

Chipset	\\CHIPSET\\INF 9.2.0.1021
NET Framework	\\NET Framework
LAN	\\ETHERNET\\INTEL\\82583\\32 \\ETHERNET\\INTEL\\82583\\64
Graphics	\\GRAPHICS\\INTEL_2K_XP_32\\5313 \\GRAPHICS\\INTEL_2K_XP_64\\5313
AHCI	\\RAID\\INTEL\\6-series 10.1.0.1008
AUDIO	\\AUDIO\\REALTEK_HD\\WIN2K_XP_x86x64_R257

### Windows 7

Chipset	\\CHIPSET\\INF 9.2.0.1021
NET Framework	\\NET Framework
LAN	\\ETHERNET\\INTEL\\82583\\32 \\ETHERNET\\INTEL\\82583\\64
Graphics	\\GRAPHICS\\INTEL_WIN7_32\\2291 \\GRAPHICS\\INTEL_WIN7_64\\2291
AHCI	\\RAID\\INTEL\\6-series 10.1.0.1008
AUDIO	\\AUDIO\\REALTEK_HD\\Win7_R257

### Management Engine Driver

Please download the driver at:

[ftp://ftp.arbor.com.tw/pub/driver/01slot\\_computing/HiCORE-i67Q1/ME/](ftp://ftp.arbor.com.tw/pub/driver/01slot_computing/HiCORE-i67Q1/ME/)

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# Chapter 3

# BIOS

### 3.1 BIOS Introduction

The AMI BIOS provides a Setup utility program for specifying the system configurations and settings. The BIOS ROM of the system stores the Setup utility and configurations.

When you turn on the computer, the AMI BIOS is immediately activated. To enter the BIOS SETUP UTILITY, press “Delete” once the power is turned on. When the computer is shut down, the battery on the motherboard supplies the power for BIOS RAM.

The Main Setup screen lists the following information

BIOS Information

BIOS Vendor: displays the vendor name

Core Version: displays the current version information of the core

Project Version

Build Date: the date when the project was made/updated

Memory Information: displays the total memory

Access Level: shows user’s access level



## Key Commands

BIOS Setup Utility is mainly a key-based navigation interface. Please refer to the following key command instructions for navigation process.

“←”“→”	Move to highlight a particular configuration screen from the top menu bar / Move to highlight items on the screen
“↓”“↑”	Move to highlight previous/next item
<b>Enter</b>	Select and access a setup item/field
<b>Esc</b>	On the Main Menu – Quit the setup and discard changes saved into CMOS (a message screen will display and ask you to select “OK” or “Cancel” for exiting and discarding changes. Use “←” and “→” to select and press “Enter” to confirm) On the Sub Menu – Exit current page and return to main menu
<b>Page Up / +</b>	Increase the numeric value on a selected setup item / make change
<b>Page Down -</b>	Decrease the numeric value on a selected setup item / make change
<b>F2</b>	Recover to previous values in setup
<b>F3</b>	Recover to optimized defaults automatically
<b>F1</b>	Activate “General Help” screen
<b>F10</b>	Save the changes that have been made in the setup and exit. (a message screen will display and ask you to select “OK” or “Cancel” for exiting and saving changes. Use “←” and “→” to select and press “Enter” to confirm)

## System Date

Set the system date. Note that the “Day” automatically changes when you set the date.

The date format is:

- Day** : Sun to Sat
- Month** : 1 to 12
- Date** : 1 to 31
- Year** : 1999 to 2099

## System Time

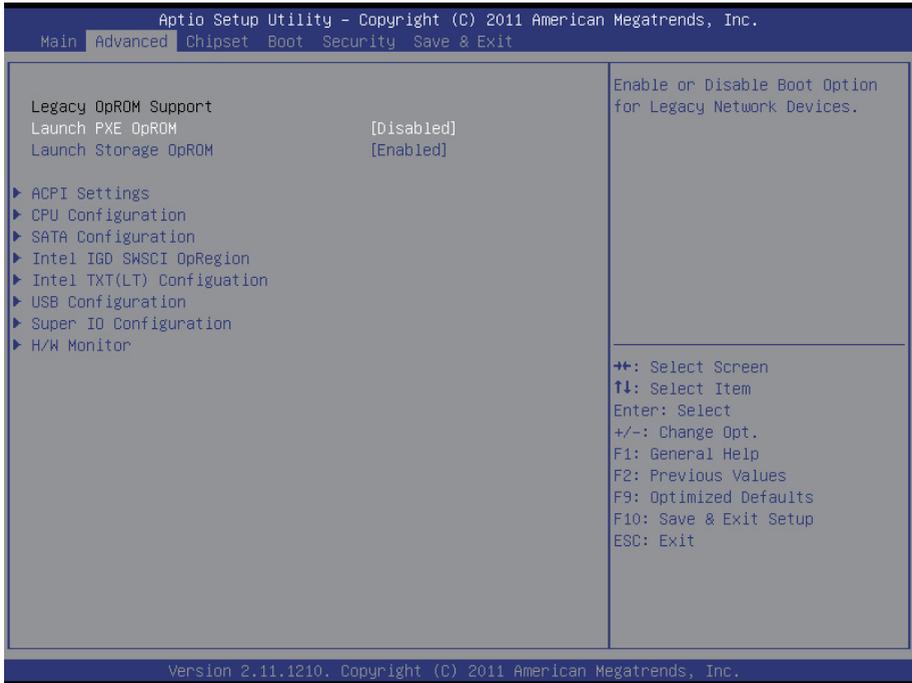
Set the system time.

The time format is:

- Hour** : 00 to 23
- Minute** : 00 to 59
- Second** : 00 to 59

### 3.2 Advanced Settings

The “Advanced” screen provides setting options to configure ACPI, CPU, SATA, USB, Super IO and other peripherals. You can use “←” and “→” keys to select “Advanced” and use the “↓” and “↑” to select a setup item.

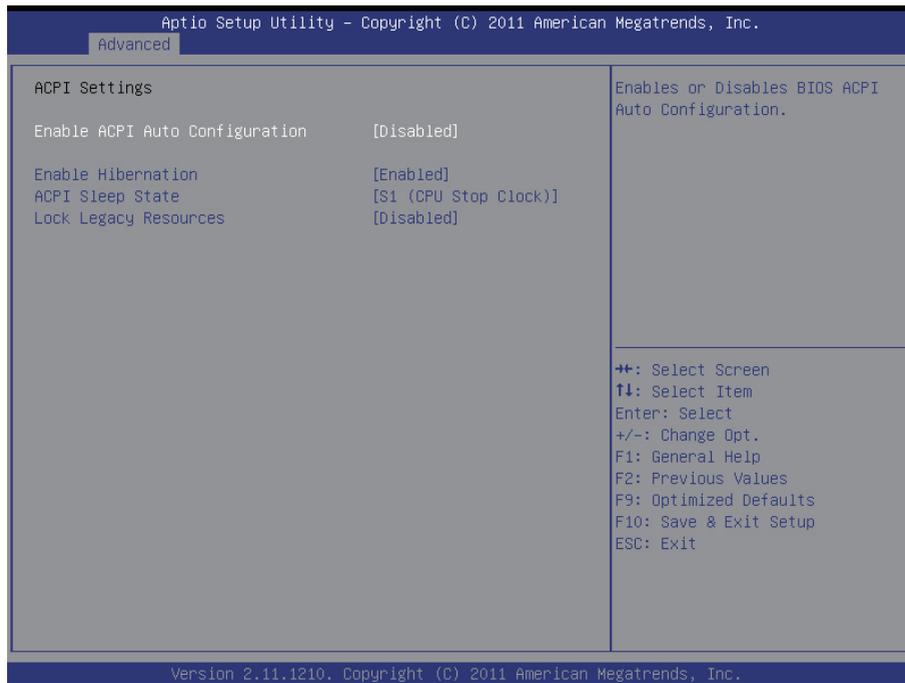


**Note:**

Please pay attention to the instructions at the upper-right frame before you decide to configure any setting of an item.

### 3.2.1 ACPI Settings

Press “Enter” on “ACPI Settings” and you will be able to set up ACPI configuration.



#### Enable ACPI Auto Configuration

Allow you to enable or disable BIOS ACPI Auto Configuration.

#### Enable Hibernation

Allow you to enable or disable system hibernation (OS/S4 Sleep State). This option may not be effective in some OSeS.

#### ACPI Sleep State

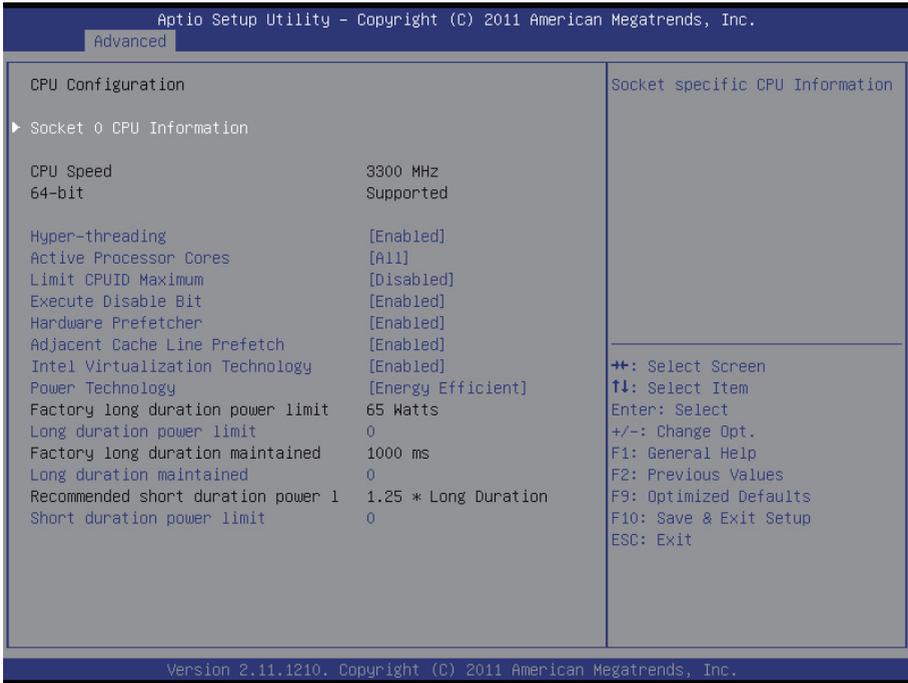
Provide 3 options, Suspend Disable, S1 (CUP Stop Clock), and S3 (Suspend to RAM) in order. Suspend ranks the highest ACPI sleep state.

#### Lock Legacy Resources

Allow you to enable or disable Lock Legacy Resources.

### 3.2.2 CPU Configuration

Press “Enter” on “CPU Configuration” to configure the CPU on the “CPU Configuration” screen.



#### CPU Details

Detail information including CPU manufacturer name, Processor Speed, Processor Stepping, Microcode Revision, Processor Core number, etc.

#### Hyper-Threading Technology

Enabled: activates the Hyper-Threading Technology for higher CPU threading speed. (Recommended)

Disabled: deactivates the Hyper-Threading Technology.

---

### **Active Processor Cores**

Number of cores to enable in each processor package.

The choice: All, 1, 2

### **Limit CPUID Maximum**

Disable for Windows XP.

The choice: Disabled, Enabled

### **Execute Disable Bit**

Enable/Disable the Execute disable bit function.

### **Hardware Prefetcher**

To turn on/off the MLC streamer prefetcher.

The choice: Disabled, Enabled

### **Adjacent Cache Line Prefetch**

To turn on/off prefetching of adjacent cache lines.

The choice: Disabled, Enabled

### **Intel® Virtualization Technology**

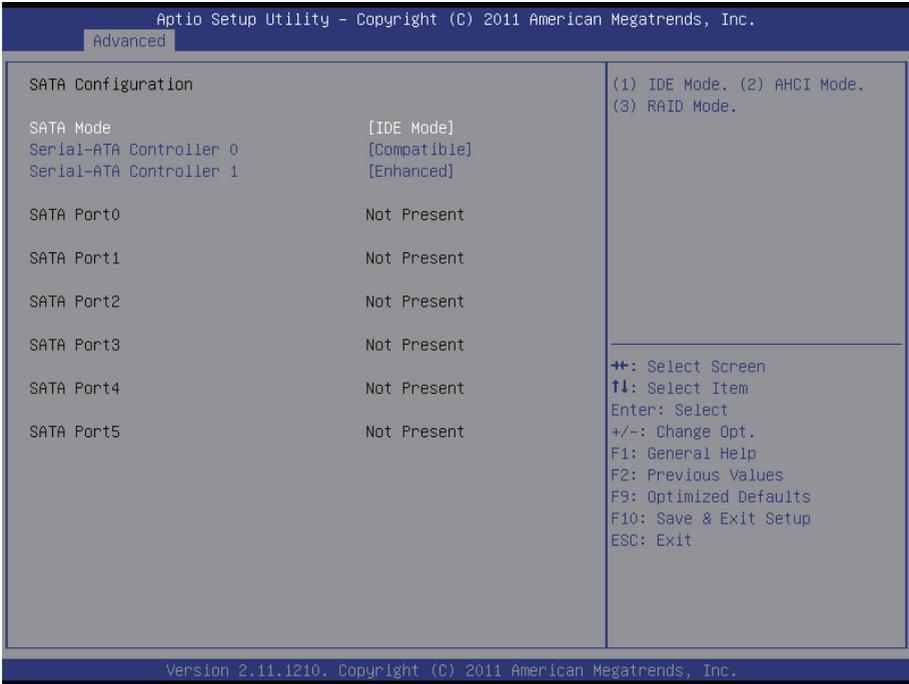
Enable/Disable the Intel® Virtualization Technology feature.

### **Power Technology**

Enable the power management features.

The choice: Disabled, Energy Efficient, Custom

### 3.2.3 SATA Configuration



#### SATA Mode

It allows you to select the operation mode for SATA controller.

#### Serial-ATA Controller 0

Enable/ Disable Serial ATA Controller 0.

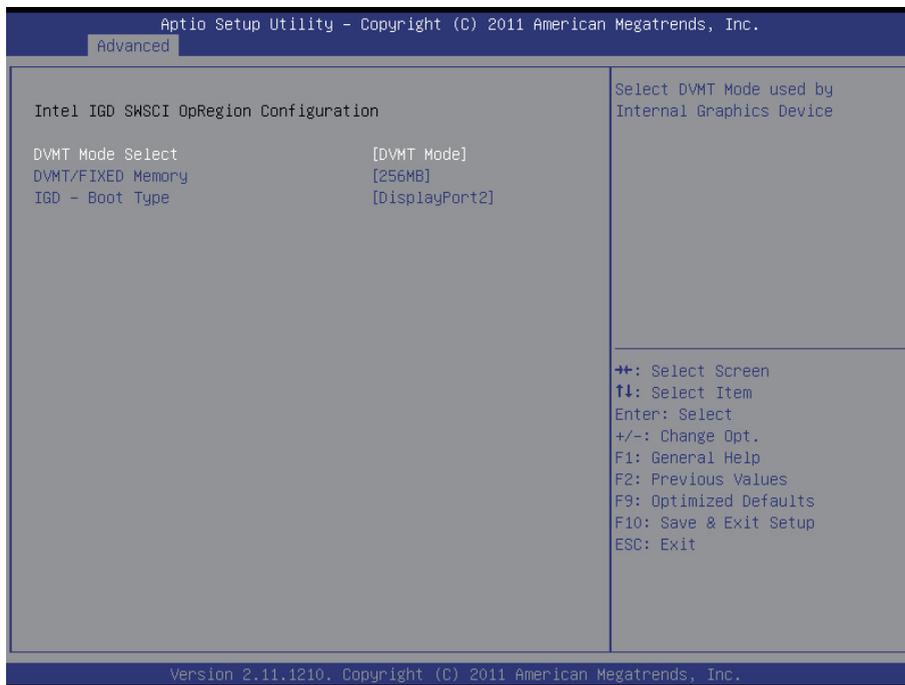
The choice: Disable, Enhanced, Compatible

#### Serial-ATA Controller 1

Enable/ Disable Serial ATA Controller 0.

The choice: Disable, Enhanced

### 3.2.4 Intel® IGD SWSCI OpRegion



#### DVMT/ Fixed Memory

This feature allows you to select the memory size of DVMT/BOTH operating mode.

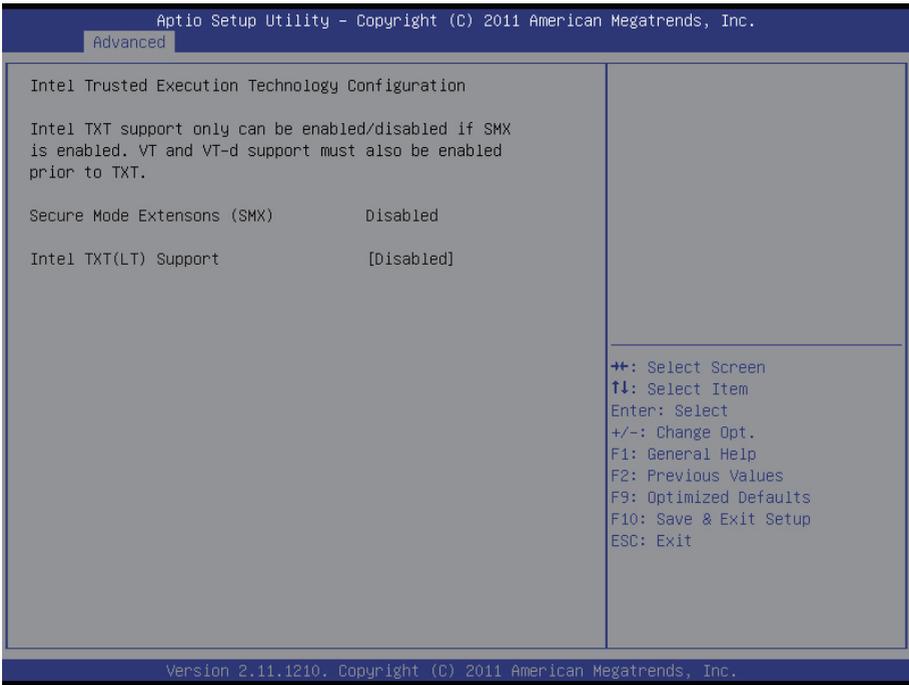
The choice: 256MB, 128MB, Maximum

#### IGD – Boot Type

This feature allows you to select the display device when you boot up the system.

### 3.2.5 Intel® Trusted Execution Technology Configuration

The menu is used to read USB configuration information and configure the USB setting.

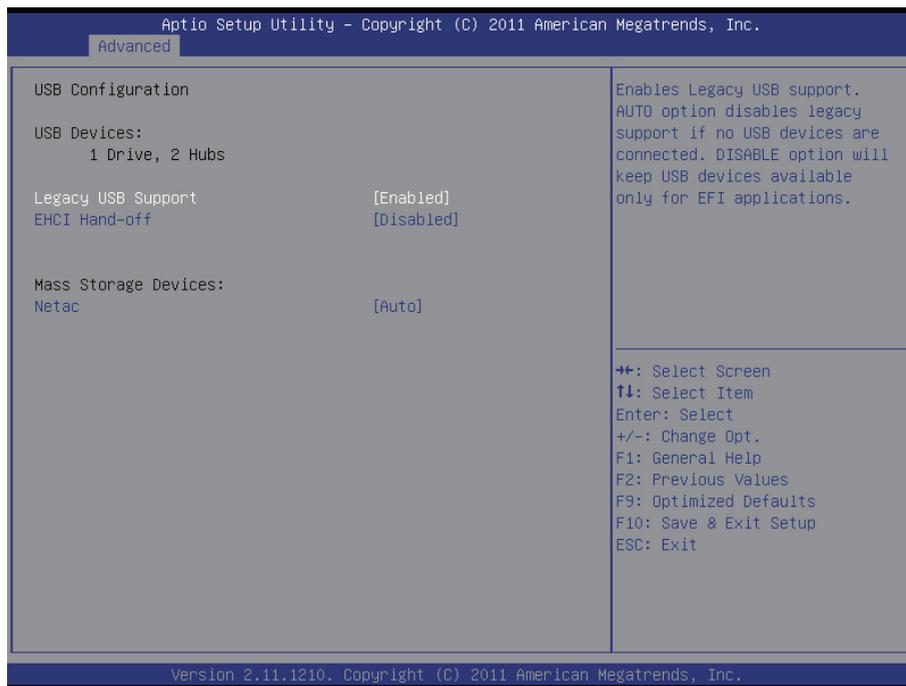


#### Intel® TXT(LT) Support

This item allows you to enable/disable the Intel TXT (LT) support.

## 3.2.6 USB Configuration

The menu is used to read USB configuration information and configure the USB setting.



### Legacy USB Support

Enable support for legacy USB. Normally if this option is not enabled, any attached USB mouse or USB keyboard won't be accessible until a USB compatible operating system is fully booted with all loaded USB drivers. When this option is enabled, any attached USB mouse or USB keyboard can control the system even when there is no USB driver loaded onto the system.

The choice: Enabled, Disabled, Auto (AUTO option disables legacy support if no USB devices are connected.)

### EHCI Hand-Off

This option allows you to enable EHCI Hand-Off function by BIOS if your computer operating system does not support it. EHCI is the abbreviation for Enhanced Host Controller Interface, which is necessary for high speed USB operation.

The choice: Enabled, Disabled

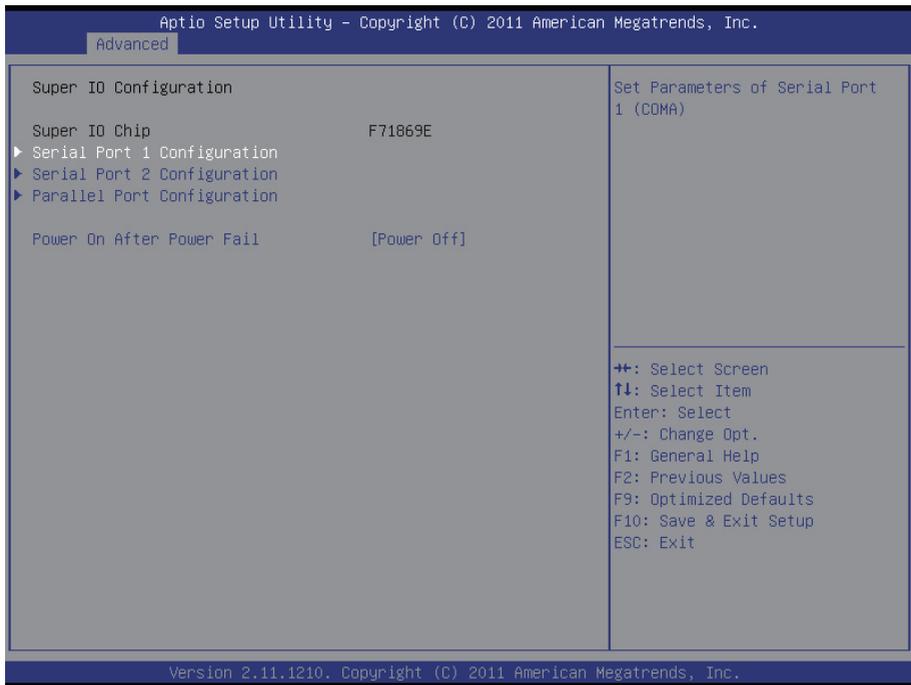
## Mass Storage Devices

This item allows you to set up mass storage devices.

The choice: Auto, Floppy, Forced FDD, Hard-Disk, CD-ROM

### 3.2.7 Super IO Configuration

You can use this item to set up or change the Super IO configuration for FDD controllers, parallel ports and serial ports.



## Serial Port 1 Configuration

Aptio Setup Utility - Copyright (C) 2011 American Megatrends, Inc.	
Advanced	
Serial Port 1 Configuration	Enable or Disable Serial Port (COM)
Serial Port	[Enabled]
Device Settings	IO=3F8h; IRQ=4;
Change Settings	[Auto]
++: Select Screen ↑↓: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F9: Optimized Defaults F10: Save & Exit Setup ESC: Exit	
Version 2.11.1210. Copyright (C) 2011 American Megatrends, Inc.	

### Serial Port

This item allows you to enable/disable Serial Port (COM).

## Serial Port 2 Configuration



### Serial Port

This item allows you to enable/disable Serial Port (COM).

### Change Settings

This item allows you to change the serial port IO port address and interrupt address.

### COMB RS-485 Autoflow

This item allows you to enable serial port 2 auto flow control function. Auto flow control is used in RS-485 to control the signal transmitter automatically. When RS-485 auto flow is disabled, the RS-485 auto flow will not work. RS-422/485 is available after modifying the COMB RS-485 Autoflow in BIOS setting to enabled.

The choice: Enabled, Disabled (default)

## Parallel Port Configuration

Aptio Setup Utility - Copyright (C) 2011 American Megatrends, Inc.

Advanced

Parallel Port Configuration		Enable or Disable Parallel Port (LPT/LPTE)
Parallel Port	[Enabled]	
Device Settings	ID=378h; IRQ=7;	
Change Settings	[Auto]	
Device Mode	[STD Printer Mode]	

++: Select Screen  
↑↓: Select Item  
Enter: Select  
+/-: Change Opt.  
F1: General Help  
F2: Previous Values  
F9: Optimized Defaults  
F10: Save & Exit Setup  
ESC: Exit

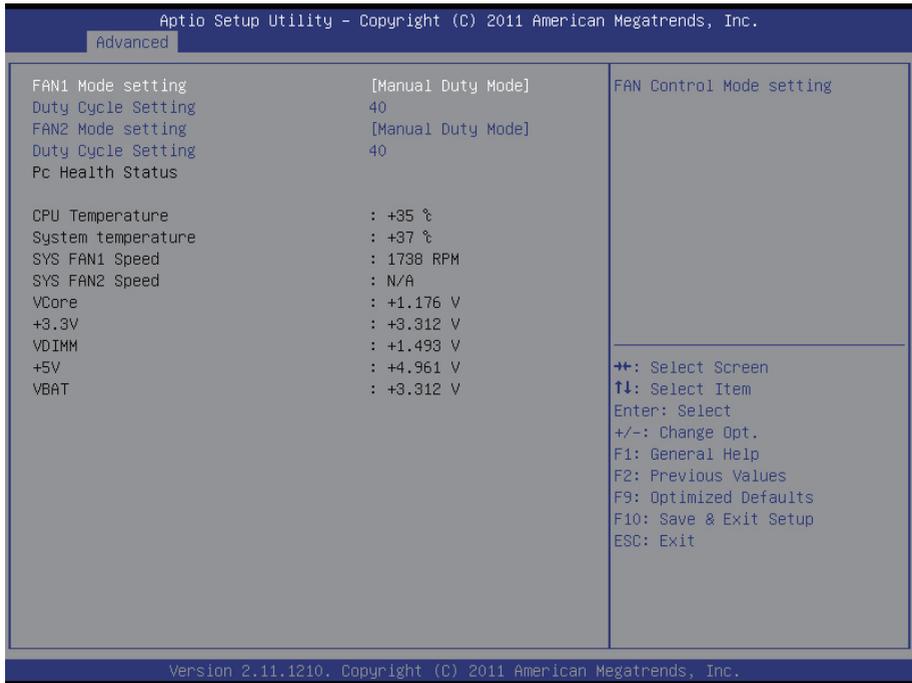
Version 2.11.1210. Copyright (C) 2011 American Megatrends, Inc.

### Parallel Port Configuration

This item allows you to enable/disable Parallel Port (LPT/LPTE).

### 3.2.8 H/W Monitor

The H/W Monitor lists out the temperature, fan speeds and system voltages that is being monitored.



#### FAN1 Mode Setting

Allow you to select the FAN control mode.

#### FAN2 Mode Setting

Allow you to select the FAN control mode.

#### CPU/System Temperature

Show you the current CPU/System fan temperature.

#### System FAN1/2 Speed

Show you the current system Fan operating speed.

#### Vcore

Show you the voltage level of CPU (Vcore).

### +3.3V / +5V / VBAT

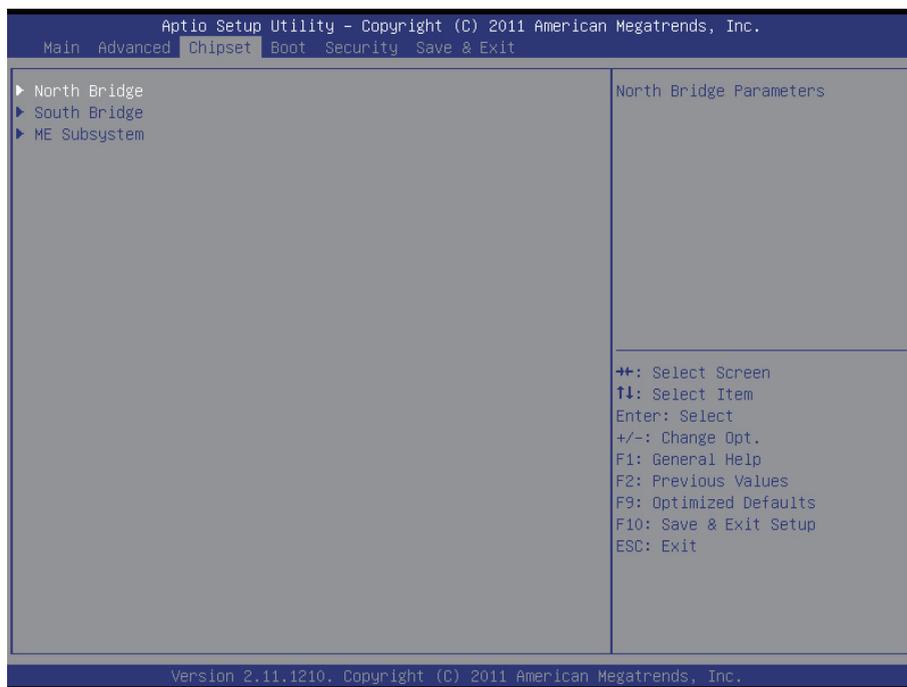
Show you the voltage level of the +3.3V, +5V standby and battery.

### VDIMM

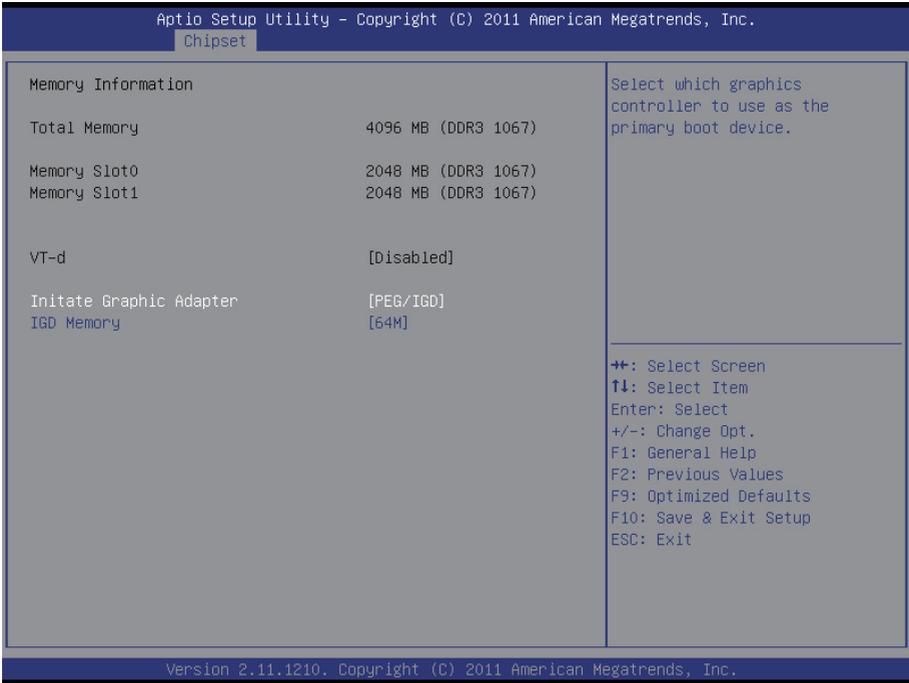
Show you the current VDIMM voltage.

## 3.3 Advanced Chipset Settings

Select “Chipset” to enable CRID, access “North Bridge,” “South Bridge” and “ME Subsystem.”



### 3.3.1 North Bridge



#### Vt-d

Enable/Disable the Vt-d function.

#### Initiate Graphic Adapter

This item allows you to select which graphics controller to use and set it as the primary boot device.

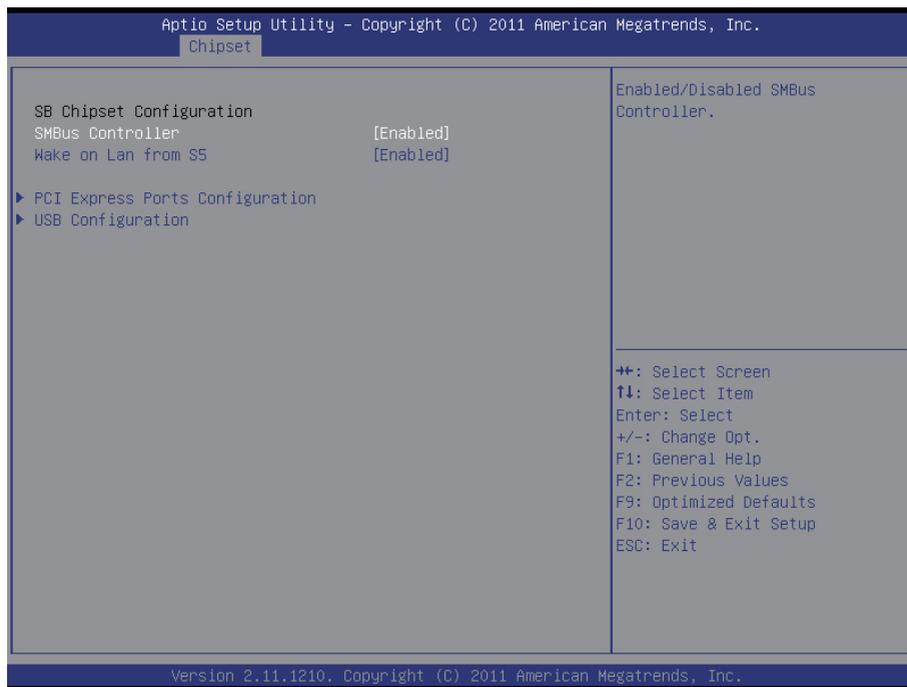
The choice: IGD, PCI/IGD, PCI/PEG, PEG/IGD, PEG/PCI

#### IGD Memory

This item shows the information of the IGD (Internal Graphics Device) memory.

### 3.3.2 South Bridge

Normally, the south bridge controls the basic I/O functions, such as USB and audio. This screen allows you to access the configurations of I/Os.



#### SMBus Controller

SMBus Controller help

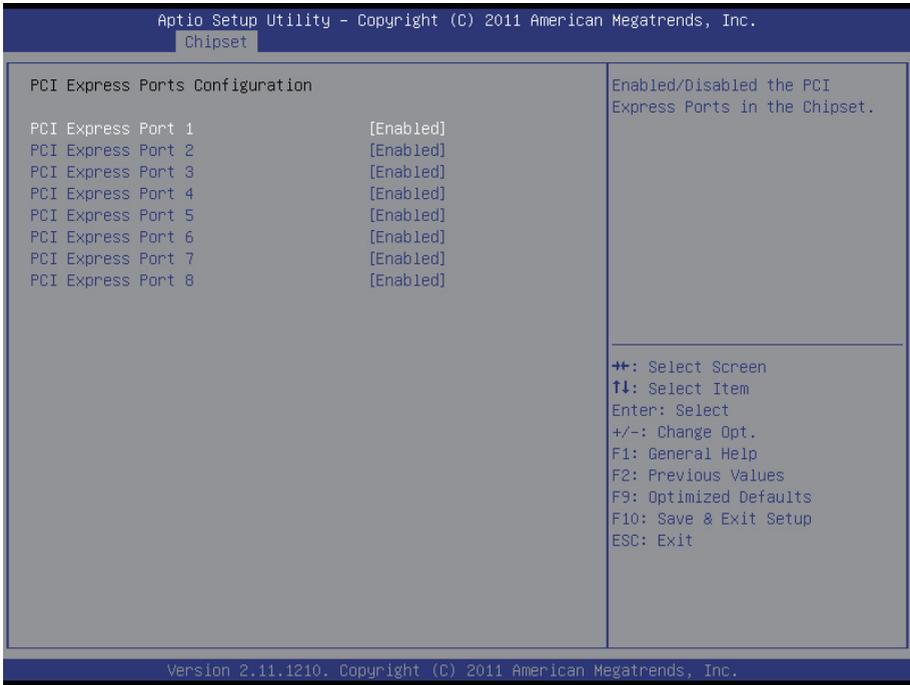
The choice: Enabled, Disabled

#### Wake on Lan from S5

Wake on Lan from S5 help

The choice: Enabled, Disabled

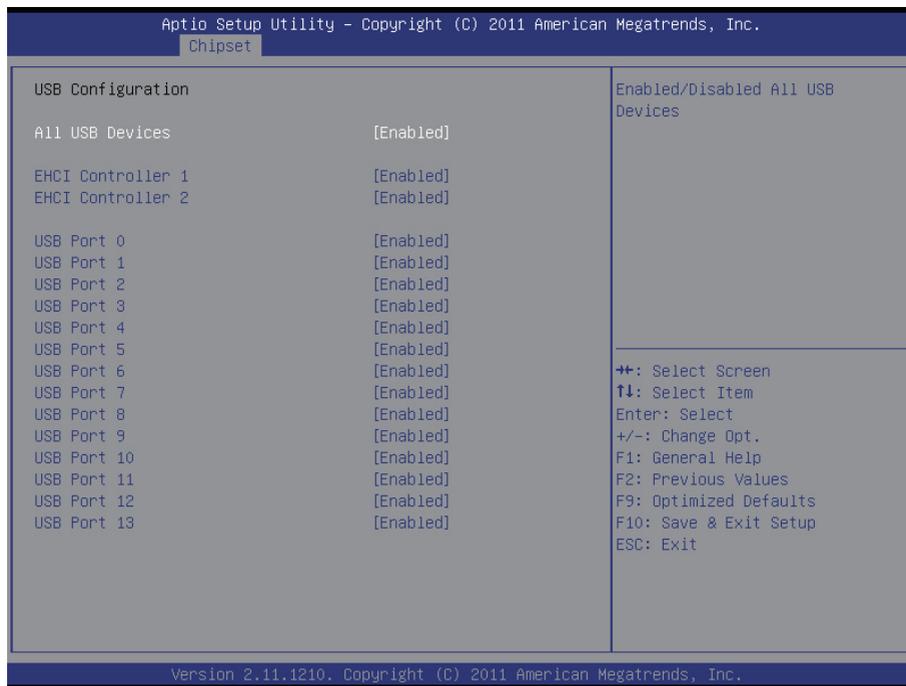
## PCI Express Ports Configuration



### PCI Express Port 1/2/3/4/5/6/7/8

Enable/Disable the PCI Express Ports in the chipset.

## USB Configuration



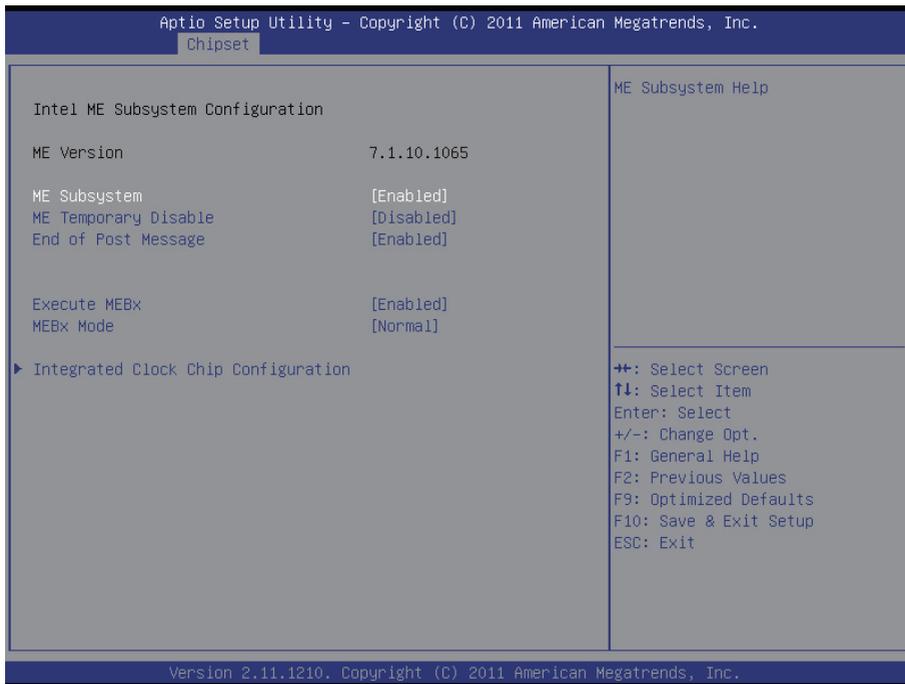
The USB Configuration menu is used to read USB configuration information and configure the USB settings.

### All USB Devices

Use this item to enable or disable all USB devices.

### 3.3.3 ME Subsystem

Use the ME Subsystem menu to configure the Intel® Management Engine (ME) configuration options.



#### ME Subsystem

Use the ME Subsystem option to enable or disable the Intel® ME subsystem. The choice: Enabled, Disabled

#### End of Post Message

Use the End of Post Message option to enable or disable the end of post message of the ME Subsystem.

The choice: Enabled, Disabled

#### Execute MEBx

Use the Execute MEBx option to enable or disable the Intel® Management Engine BIOS extension (MEBx).

The choice: Enabled, Disabled

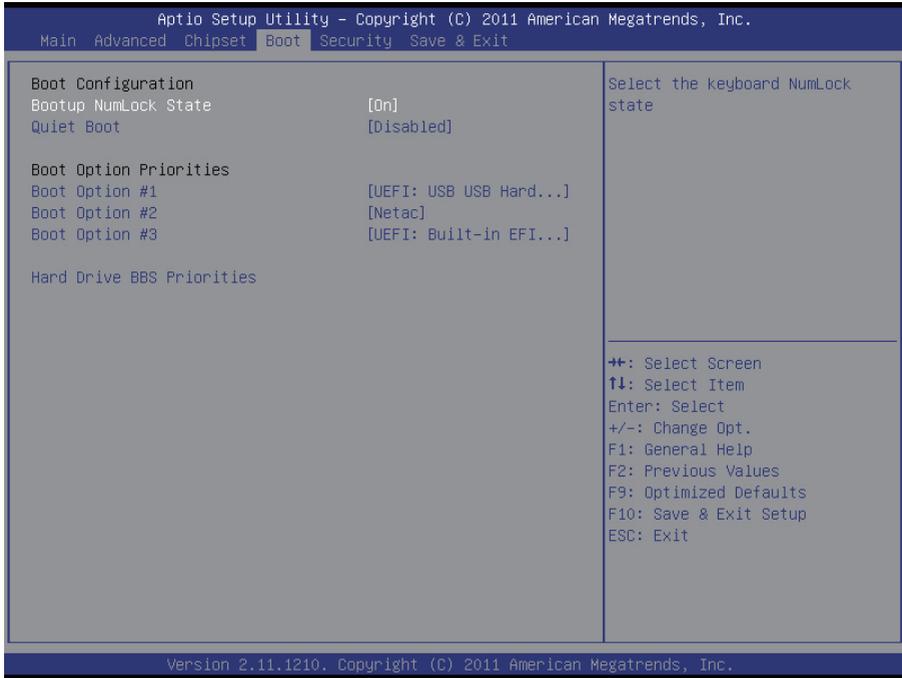
## Integrated Clock Chip Configuration



### ICC Enable

This item allows you to enable or disable the current ICC.

### 3.4 Boot Settings



#### Bootup Numlock State

This item determines if the Numlock key is active or inactive at system start-up time.

#### Quiet Boot

This item can help to select screen display when the system boots. The choice: Enabled, Disabled

#### Boot Option Priorities

This item allows you to select boot priorities for all boot devices.



## Boot Option #1

This item allows you to set the system boot priorities.

### 3.5 Security

You can set administrator password by Security menu.

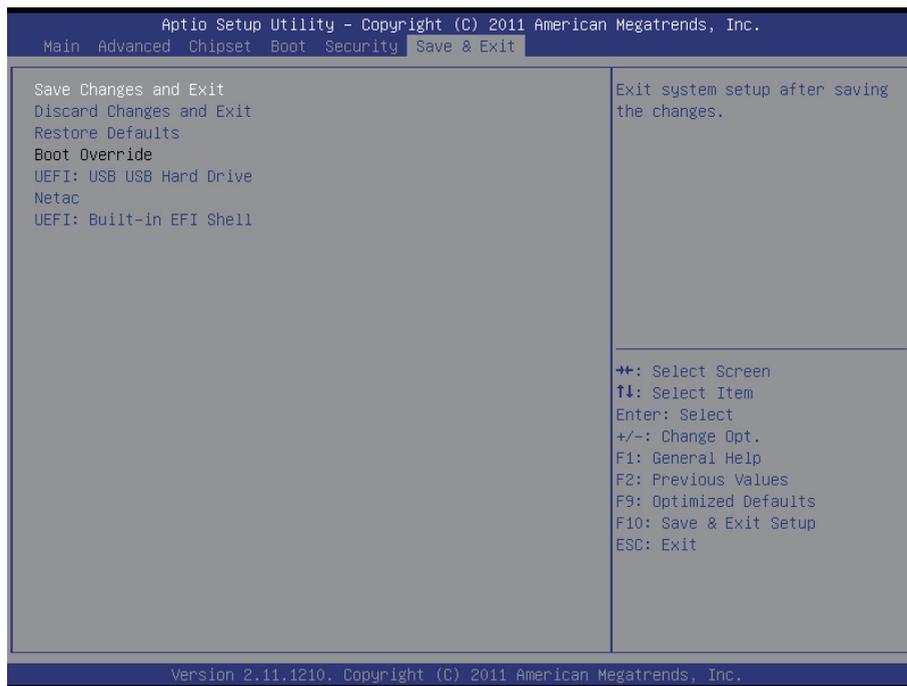
Aptio Setup Utility - Copyright (C) 2011 American Megatrends, Inc.  
Main Advanced Chipset Boot Security Save & Exit

Password Description	Set Administrator Password
If ONLY the Administrator's password is set, then this only limits access to Setup and is only asked for when entering Setup. If ONLY the User's password is set, then this is a power on password and must be entered to boot or enter Setup. In Setup the User will have Administrator rights. The password must be 3 to 20 characters long.	
Administrator Password	++: Select Screen ↑↓: Select Item Enter: Select +/-: Change Opt. F1: General Help F2: Previous Values F9: Optimized Defaults F10: Save & Exit Setup ESC: Exit

Version 2.11.1210. Copyright (C) 2011 American Megatrends, Inc.

## 3.6 Exit Options

Use the option to exit BIOS settings, and save/discard any changes you made.



### Save Changes and Exit

Exit system setup after saving the changes.

### Discard Changes and Exit

Exit system setup without saving any changes.

### Discard Changes

Discard changes done so far to any of the setup questions.

### 3.7 Beep Sound codes list

#### 3.7.1 Boot Block Beep Codes

Number of Beeps	Description
1	Insert diskette in floppy drive A:
2	'AMIBOOT.ROM' file not found in root directory of diskette in A:
4	Flash Programming successful
5	Floppy read error
6	Keyboard controller BAT command failed
7	No Flash EPROM detected
8	Floppy controller failure
9	Boot Block BIOS checksum error
10	Flash Erase error
11	Flash Program error
12	'AMIBOOT.ROM' file size error
13	BIOS ROM image mismatch (file layout does not match image present in flash device)

#### 3.7.2 POST BIOS Beep Codes

Number of Beeps	Description
1	Memory refresh timer error.
2	Parity error in base memory (first 64KB block)
4	Motherboard timer not operational
5	Processor error
6	8042 Gate A20 test error (cannot switch to protected mode)
7	General exception error (processor exception interrupt error)
8	Display memory error (system video adapter)
9	AMIBIOS ROM checksum error
10	CMOS shutdown register read/write error
11	Cache memory test failed

### 3.7.3 Troubleshooting POST BIOS Beep Codes

Number of Beeps	Description
1, 2 or 3	Reseat the memory, or replace with known good modules.
4-7, 9-11	<p>Fatal error indicating a serious problem with the system. Consult your system manufacturer. Before declaring the motherboard beyond all hope, eliminate the possibility of interference by a malfunctioning add-in card. Remove all expansion cards except the video adapter.</p> <ul style="list-style-type: none"><li>• If beep codes are generated when all other expansion cards are absent, consult your system manufacturer's technical support.</li><li>• If beep codes are not generated when all other expansion cards are absent, one of the add-in cards is causing the malfunction. Insert the cards back into the system one at a time until the problem</li></ul>
8	If the system video adapter is an add-in card, replace or reset the video adapter. If the video adapter is an integrated part of the system board, the board may be faulty.

### 3.8 AMI BIOS Checkpoints

#### 3.8.1 Bootblock Initialization Code Checkpoints

The Bootblock initialization code sets up the chipset, memory and other components before system memory is available. The following table describes the type of checkpoints that may occur during the bootblock initialization portion of the BIOS *(Note)*:

Checkpoint	Description
Before D0	If boot block debugger is enabled, CPU cache-as-RAM functionality is enabled at this point. Stack will be enabled from this point.
D0	Early Boot Strap Processo (BSP) initialization like microcode update, frequency and other CPU critical initialization. Early chipset initialization is done.
D1	Early super I/O initialization is done including RTC and keyboard controller. Serial port is enabled at this point if needed for debugging. NMI is disabled. Perform keyboard controller BAT test. Save power-on CPUID value in scratch CMOS. Go to flat mode with 4GB limit and GA20 enabled.
D2	Verify the boot block checksum. System will hang here if checksum is bad.
D3	Disable CACHE before memory detection. Execute full memory sizing module. If memory sizing module is not executed, start memory refresh and do memory sizing in Boot block code. Do additional chipset initialization. Re-enable CACHE. Verify that flat mode is enabled.
D4	Test base 512KB memory. Adjust policies and cache first 8MB. Set stack.
D5	Bootblock code is copied from ROM to lower system memory and control is given to it. BIOS now executes out of RAM. Copy compressed boot block code to memory in right segments. Copy BIOS from ROM to RAM for faster access. Perform main BIOS checksum and update recovery status accordingly.

---

D6	Both key sequence and OEM specific method are checked to determine if BIOS recovery is forced. If BIOS recovery is necessary, control flows to checkpoint E0. See <i>Bootblock Recovery Code Checkpoints</i> section of document for more information.
D7	Restore CPUID value back into register. The Bootblock-Runtime interface module is moved to system memory and control is given to it. Determine whether to execute serial flash.
D8	The Runtime module is uncompressed into memory. CPUID information is stored in memory.
D9	Store the Uncompressed pointer for future use in PMM. Copying Main BIOS into memory. Leaves all RAM below 1MB Read-Write including E000 and F000 shadow areas but closing SMRAM.
DA	Restore CPUID value back into register. Give control to BIOS POST (ExecutePOSTKernel). See POST Code Checkpoints section of document for more information.
DC	System is waking from ACPI S3 state
E1 - E8 EC - EE	OEM memory detection/configuration error. This range is reserved for chipset vendors & system manufacturers. The error associated with this value may be different from one platform to the next.

---

### 3.8.2 Bootblock Recovery Code Checkpoints

The Bootblock recovery code gets control when the BIOS determines that a BIOS recovery needs to occur because the user has forced the update or the BIOS checksum is corrupt. The following table describes the type of checkpoints that may occur during the Bootblock recovery portion of the BIOS (Note):

Checkpoint	Description
E0	Initialize the floppy controller in the super I/O. Some interrupt vectors are initialized. DMA controller is initialized. 8259 interrupt controller is initialized. L1 cache is enabled.
E9	Set up floppy controller and data. Attempt to read from floppy.
EA	Enable ATAPI hardware. Attempt to read from ARMD and ATAPI CDROM.
EB	Disable ATAPI hardware. Jump back to checkpoint E9.
EF	Read error occurred on media. Jump back to checkpoint EB.
F0	Search for pre-defined recovery file name in root directory.
F1	Recovery file not found.
F2	Start reading FAT table and analyze FAT to find the clusters occupied by the recovery file.
F3	Start reading the recovery file cluster by cluster.
F5	Disable L1 cache.
FA	Check the validity of the recovery file configuration to the current configuration of the flash part.
FB	Make flash write enabled through chipset and OEM specific method. Detect proper flash part. Verify that the found flash part size equals the recovery file size.
F4	The recovery file size does not equal the found flash part size.

---

FC	Erase the flash part.
----	-----------------------

---

FD	Program the flash part.
----	-------------------------

---

FF	The flash has been updated successfully. Make flash write disabled. Disable ATAPI hardware. Restore CPUID value back into register. Give control to F000 ROM at F000:FFF0h.
----	-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------

### 3.8.3 POST Code Checkpoints

The POST code checkpoints are the largest set of checkpoints during the BIOS pre-boot process. The following table describes the type of checkpoints that may occur during the POST portion of the BIOS <sup>(Note)</sup>:

Checkpoint	Description
03	Disable NMI, Parity, video for EGA, and DMA controllers. Initialize BIOS, POST, Runtime data area. Also initialize BIOS modules on POST entry and GPNV area. Initialize CMOS as mentioned in the Kernel Variable "wCMOSFlags."
04	Check CMOS diagnostic byte to determine if battery power is OK and CMOS checksum is OK. Verify CMOS checksum manually by reading storage area. If the CMOS checksum is bad, update CMOS with power-on default values and clear passwords. Initialize status register A. Initialize data variables that are based on CMOS setup questions. Initializes both the 8259 compatible PICs in the system
05	Initializes the interrupt controlling hardware (generally PIC) and interrupt vector table.
06	Do R/W test to CH-2 count reg. Initialize CH-0 as system timer. Install the POSTINT1Ch handler. Enable IRQ-0 in PIC for system timer interrupt. Traps INT1Ch vector to "POSTINT1ChHandlerBlock."
07	Fixes CPU POST interface calling pointer.
08	Initializes the CPU. The BAT test is being done on KBC. Program the keyboard controller command byte is being done after Auto detection of KB/MS using AMI KB-5.
C0	Early CPU Init Start -- Disable Cache – Init Local APIC
C1	Set up boot strap processor Information
C2	Set up boot strap processor for POST
C5	Enumerate and set up application processors
C6	Re-enable cache for boot strap processor

---

C7	Early CPU Init Exit
0A	Initializes the 8042 compatible Key Board Controller.
0B	Detects the presence of PS/2 mouse.
0C	Detects the presence of Keyboard in KBC port.
0E	Testing and initialization of different Input Devices. Also, update the Kernel Variables. Traps the INT09h vector, so that the POST INT09h handler gets control for IRQ1. Uncompress all available language, BIOS logo, and Silent logo modules.
13	Early POST initialization of chipset registers.
20	Relocate System Management Interrupt vector for all CPU in the system.
24	Uncompress and initialize any platform specific BIOS modules. GPNV is initialized at this checkpoint.
2A	Initializes different devices through DIM. See DIM Code Checkpoints section of document for more information.
2C	Initializes different devices. Detects and initializes the video adapter installed in the system that have optional ROMs.
2E	Initializes all the output devices.
31	Allocate memory for ADM module and uncompress it. Give control to ADM module for initialization. Initialize language and font modules for ADM. Activate ADM module.
33	Initializes the silent boot module. Set the window for displaying text information.
37	Displaying sign-on message, CPU information, setup key message, and any OEM specific information.

---

38	Initializes different devices through DIM. See DIM Code Checkpoints section of document for more information. USB controllers are initialized at this point.
39	Initializes DMAC-1 & DMAC-2.
3A	Initialize RTC date/time.
3B	Test for total memory installed in the system. Also, Check for DEL or ESC keys to limit memory test. Display total memory in the system.
3C	Mid POST initialization of chipset registers.
40	Detect different devices (Parallel ports, serial ports, and coprocessor in CPU, ... etc.) successfully installed in the system and update the BDA, EBDA...etc.
52	Updates CMOS memory size from memory found in memory test. Allocates memory for Extended BIOS Data Area from base memory. Programming the memory hole or any kind of implementation that needs an adjustment in system RAM size if needed.
60	Initializes NUM-LOCK status and programs the KBD typematic rate.
75	Initialize Int-13 and prepare for IPL detection.
78	Initializes IPL devices controlled by BIOS and option ROMs.
7C	Generate and write contents of ESCD in NVRam.
84	Log errors encountered during POST.
85	Display errors to the user and gets the user response for error.
87	Execute BIOS setup if needed / requested. Check boot password if installed.
8C	Late POST initialization of chipset registers.
8D	Build ACPI tables (if ACPI is supported)
8E	Program the peripheral parameters. Enable/Disable NMI as selected
90	Initialization of system management interrupt by invoking all handlers. Please note this checkpoint comes right after checkpoint 20h
A1	Clean-up work needed before booting to OS.

---

A2	Takes care of runtime image preparation for different BIOS modules. Fill the free area in F000h segment with 0FFh. Initializes the Microsoft IRQ Routing Table. Prepares the runtime language module. Disables the system configuration display if needed.
A4	Initialize runtime language module. Display boot option popup menu.
A7	Displays the system configuration screen if enabled. Initialize the CPU's before boot, which includes the programming of the MTRR's.
A9	Wait for user input at config display if needed.
AA	Uninstall POST INT1Ch vector and INT09h vector.
AB	Prepare BBS for Int 19 boot. Init MP tables.
AC	End of POST initialization of chipset registers. De-initializes the ADM module.
B1	Save system context for ACPI. Prepare CPU for OS boot including final MTRR values.
00	Passes control to OS Loader (typically INT19h).

---

### 3.8.4 DIM Code Checkpoints

The Device Initialization Manager (DIM) gets control at various times during BIOS POST to initialize different system busses. The following table describes the main checkpoints where the DIM module is accessed *(Note)*:

Checkpoint	Description
2A	Initialize different buses and perform the following functions: Reset, Detect, and Disable (function 0); Static Device Initialization (function 1); Boot Output Device Initialization (function 2). Function 0 disables all device nodes, PCI devices, and PnP ISA cards. It also assigns PCI bus numbers. Function 1 initializes all static devices that include manual configured onboard peripherals, memory and I/O decode windows in PCI-PCI bridges, and noncompliant PCI devices. Static resources are also reserved. Function 2 searches for and initializes any PnP, PCI, or AGP video devices.
38	Initialize different buses and perform the following functions: Boot Input Device Initialization (function 3); IPL Device Initialization (function 4); General Device Initialization (function 5). Function 3 searches for and configures PCI input devices and detects if system has standard keyboard controller. Function 4 searches for and configures all PnP and PCI boot devices. Function 5 configures all onboard peripherals that are set to an automatic configuration and configures all remaining PnP and PCI devices.

While control is in the different functions, additional checkpoints are output to port 80h as a word value to identify the routines under execution. The low byte value indicates the main POST Code Checkpoint. The high byte is divided into two nibbles and contains two fields. The details of the high byte of these checkpoints are as follows:

HIGH BYTE XY

The upper nibble “X” indicates the function number that is being executed. “X” can be from 0 to 7.

- 0 = func#0, disable all devices on the BUS concerned.
- 2 = func#2, output device initialization on the BUS concerned.
- 3 = func#3, input device initialization on the BUS concerned.
- 4 = func#4, IPL device initialization on the BUS concerned.
- 5 = func#5, general device initialization on the BUS concerned.
- 6 = func#6, error reporting for the BUS concerned.
- 7 = func#7, add-on ROM initialization for all BUSES.
- 8 = func#8, BBS ROM initialization for all BUSES.

The lower nibble 'Y' indicates the BUS on which the different routines are being executed. 'Y' can be from 0 to 5.

- 0 = Generic DIM (Device Initialization Manager).
- 1 = On-board System devices.
- 2 = ISA devices.
- 3 = EISA devices.
- 4 = ISA PnP devices.
- 5 = PCI devices.

### 3.8.5 ACPI Runtime Checkpoints

ACPI checkpoints are displayed when an ACPI capable operating system either enters or leaves a sleep state. The following table describes the type of checkpoints that may occur during ACPI sleep or wake events <sup>(Note)</sup>:

Checkpoint	Description
AC	First ASL check point. Indicates the system is running in ACPI mode.
AA	System is running in APIC mode.
01, 02, 03, 04, 05	Entering sleep state S1, S2, S3, S4, or S5.
10, 20, 30, 40, 50	Waking from sleep state S1, S2, S3, S4, or S5.

**Note:**

*Please note that checkpoints may differ between different platforms based on system configuration. Checkpoints may change due to vendor requirements, system chipset or option ROMs from add-in PCI devices.*

---

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---



# Appendix

## Appendix A: I/O Port Address Map

Each peripheral device in the system is assigned a set of I/O port addresses which also becomes the identity of the device.

The following table lists the I/O port addresses used.

Address	Device Description
0x00000000-0x0000000F	Direct memory access controller
0x00000000-0x0000000F	PCI bus
0x00000010-0x0000001F	Motherboard resources
0x00000020-0x00000021	Programmable interrupt controller
0x00000022-0x0000003F	Motherboard resources
0x00000040-0x00000043	System timer
0x00000044-0x0000005F	Motherboard resources
0x00000060-0x00000060	Standard 101/102-Key or Microsoft Natural PS/2 Keyboard
0x00000061-0x00000061	System speaker
0x00000062-0x00000063	Motherboard resources
0x00000064-0x00000064	Standard 101/102-Key or Microsoft Natural PS/2 Keyboard
0x00000065-0x0000006F	Motherboard resources
0x00000070-0x00000071	System CMOS/real time clock
0x00000072-0x0000007F	Motherboard resources
0x00000080-0x00000080	Motherboard resources
0x00000081-0x00000083	Direct memory access controller
0x00000084-0x00000086	Motherboard resources
0x00000087-0x00000087	Direct memory access controller
0x00000088-0x00000088	Motherboard resources
0x00000089-0x0000008B	Direct memory access controller
0x0000008C-0x0000008E	Motherboard resources
0x0000008F-0x0000008F	Direct memory access controller
0x00000090-0x0000009F	Motherboard resources
0x000000A0-0x000000A1	Programmable interrupt controller
0x000000A2-0x000000BF	Motherboard resources

0x000000C0-0x000000DF	Direct memory access controller
0x000000E0-0x000000EF	Motherboard resources
0x000000F0-0x000000FF	Numeric data processor
0x000001F0-0x00000177	ATA Channel 1
0x000001F0-0x000001F7	ATA Channel 0
0x000002F8-0x0000029F	Motherboard resources
0x000002F8-0x000002FF	Communications Port (COM2)
0x00000378-0x00000376	ATA Channel 1
0x00000378-0x0000037F	Printer Port (LPT1)
0x000003B0-0x000003BB	Intel(R) HD Graphics Family
0x000003B0-0x000003BB	PCI bus
0x000003C0-0x000003DF	Intel(R) HD Graphics Family
0x000003E0-0x00000CF7	PCI bus
0x000003F6-0x000003F6	ATA Channel 0
0x000003F8-0x000003FF	Communications Port (COM1)
0x00000400-0x00000453	System board
0x00000454-0x00000457	Motherboard resources
0x00000458-0x0000047F	System board
0x000004D0-0x000004D1	Motherboard resources
0x00000500-0x0000057F	System board
0x0000D000-0x0000FFFF	PCI bus
0x00001180-0x0000119F	System board
0x0000D000-0x0000DFFF	Intel(R) 6 Series/C200 Series Chipset Family PCI Express Root Port 3 - 1C14
0x0000E000-0x0000EFFF	Intel(R) 6 Series/C200 Series Chipset Family PCI Express Root Port 2 - 1C12
0x0000F000-0x0000F03F	Intel(R) HD Graphics Family
0x0000F040-0x0000F05F	Intel(R) 6 Series/C200 Series Chipset Family SMBus Controller - 1C22
0x0000F060-0x0000F06F	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08

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0x0000F070-0x0000F07F	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08
0x0000F080-0x0000F083	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08
0x0000F090-0x0000F097	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08
0x0000F0A0-0x0000F0A3	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08
0x0000F0B0-0x0000F0B7	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08
0x0000F0C0-0x0000F0CF	Intel(R) 6 Series/C200 Series Chipset Family 4 port Serial ATA Storage Controller - 1C00
0x0000F0D0-0x0000F0DF	Intel(R) 6 Series/C200 Series Chipset Family 4 port Serial ATA Storage Controller - 1C00
0x0000F120-0x0000F127	Intel(R) Active Management Technology - SOL (COM3)
0x0000F130-0x0000F13F	Standard Dual Channel PCI IDE Controller
0x0000F140-0x0000F143	Standard Dual Channel PCI IDE Controller
0x0000F150-0x0000F157	Standard Dual Channel PCI IDE Controller
0x0000F160-0x0000F163	Standard Dual Channel PCI IDE Controller
0x0000F170-0x0000F177	Standard Dual Channel PCI IDE Controller

## Appendix B: BIOS Memory Map

Address	Device Description
0xFED10000-0xFED19FFF	System board
0xE0000000-0xEFFFFFFF	System board
0xFED90000-0xFED93FFF	System board
0xFED20000-0xFED3FFFF	System board
0xFEE00000-0xFEE0FFFF	System board
0xFB400000-0xFB7FFFFF	Intel(R) HD Graphics Family
0xD0000000-0xDFFFFFFF	Intel(R) HD Graphics Family
0xFBC07000-0xFBC07FFF	Intel(R) Active Management Technology - SOL (COM3)

0xFBC00000-0xFBC03FFF	High Definition Audio Controller
0xFBC04000-0xFBC040FF	Intel(R) 6 Series/C200 Series Chipset Family SMBus Controller - 1C2
0xFED00000-0xFED003FF	High Precision Event Timer
0xFBC05000-0xFBC053FF	Intel(R) 6 Series/C200 Series Chipset Family USB Enhanced Host Controller - 1C26
0xFBB40000-0xFBB5FFFF	Intel(R) 82583V Gigabit Network Connection #7
0xFBA00000-0xFBAFFFFFF	Intel(R) 82583V Gigabit Network Connection #7
0xFBA00000-0xFBAFFFFFF	Intel(R) 6 Series/C200 Series Chipset Family PCI Express Root Port 2 - 1C12
0xFBB60000-0xFBB63FFF	Intel(R) 82583V Gigabit Network Connection #7
0xFBC06000-0xFBC063FF	Intel(R) 6 Series/C200 Series Chipset Family USB Enhanced Host Controller - 1C2D
0xFB940000-0xFB95FFFF	Intel(R) 82583V Gigabit Network Connection #8
0xFB800000-0xFB8FFFFFF	Intel(R) 82583V Gigabit Network Connection #8
0xFB800000-0xFB8FFFFFF	Intel(R) 6 Series/C200 Series Chipset Family PCI Express Root Port 3 - 1C14
0xFB960000-0xFB963FFF	Intel(R) 82583V Gigabit Network Connection #8
0xFBC08000-0xFBC0800F	Intel(R) Management Engine Interface
0xBFA00000-0xFFFFFFFF	PCI bus
0xFED1C000-0xFED1FFFF	System board
0xFEC00000-0xFECFFFFFF	System board
0xFED08000-0xFED08FFF	System board
0xFF000000-0xFFFFFFFF	System board
0xA0000-0xBFFFF	Intel(R) HD Graphics Family
0xA0000-0xBFFFF	PCI bus
0xC0000-0xDFFFF	PCI bus

## Appendix C: Interrupt Request Lines (IRQ)

Peripheral devices use interrupt request lines to notify CPU for the service required. The following table shows the IRQ used by the devices on board.

Level	Function
IRQ 0	System timer
IRQ 1	Standard 101/102-Key or Microsoft Natural PS/2 Keyboard
IRQ 3	Communications Port (COM2)
IRQ 4	Communications Port (COM1)
IRQ 8	System CMOS/real time clock
IRQ 10	Intel(R) 6 Series/C200 Series Chipset Family SMBus Controller - 1C22
IRQ 12	Microsoft PS/2 Mouse
IRQ 13	Numeric data processor
IRQ 14	ATA Channel 0
IRQ 15	ATA Channel 1
IRQ 16	Intel(R) 6 Series/C200 Series Chipset Family USB Enhanced Host Controller - 1C2D
IRQ 16	Intel(R) Management Engine Interface
IRQ 17	Intel(R) Active Management Technology - SOL (COM3)
IRQ 18	
IRQ 19	Intel(R) 6 Series/C200 Series Chipset Family 2 port Serial ATA Storage Controller - 1C08
IRQ 22	High Definition Audio Connector
IRQ 23	Intel(R) 6 Series/C200 Series Chipset Family USB Enhanced Host Controller - 1C26
IRQ 81 ~IRQ190	Microsoft ACPI-Compliant System

## Appendix D: Digital I/O Setting

Below are the source codes written in C, please take them for Digital I/O application examples. The default I/O address is 6Eh.

```
#include <stdio.h>
#include <dos.h>
#include <conio.h>
```

```
char APName[]=          "\t\tHicore-i67Q1 DIO Testing Program\n"
                        "\t=====\\
n";
```

```
char APHelp[]= "\n - Pass 'A' key for inver state of DIO GPIO"
               "\n - Pass 'Esc' key for Exit"
               "\n";
```

```
void main(void){
    char getkey = 0;
    // char DIOSTS=0;
    // char tempJ=0;
    // char tempA=0;
    unsigned char GP2xVal,GP3xVal,GP1xVal;

    clrscr(); //clear screen
    printf(APName);
    printf(APHelp);

    outportb(0x2e, 0x87);          /* entry key*/
    outportb(0x2e, 0x87);        /* enable configuration */

    outportb(0x2e, 0x07);        /* point to logical device */
    outportb(0x2e+1, 0x06);     /* select logical device 6 */
```

```

//pg DIO as output
//0:input 1:Output
/* Index c0, GPIO3x Output pin control */
outportb(0x2e, 0xc0); /* select offset c0h */
outportb(0x2e+1, 0xff);
delay(10);

//pg DIO default LOW
/* Index c1, GPIO3x Output Data value */
outportb(0x2e, 0xc1); /* select offset c1h */
outportb(0x2e+1, 0x00);
GP3xVal = 0;
delay(10);

gotoxy(1,9);
//printf("DIO Status: Low \n");

do{
    if (getkey != 27){
        while (!kbhit());
        getkey = getch();
        switch (getkey){
            case 'A':
            case 'a':
                if (GP3xVal == 0)
                {
                    GP3xVal = 1; //DIO

                    //pg DIO high
                    outportb(0x2e,
                    outportb(0x2e+1,

                    gotoxy(1,8);
                    printf("GP3x Status:
                    High\n");

                }
            else
            {

```

```

GP3xVal = 0; //DIO
all low
//pg DIO LOW
outportb(0x2e,
0xc1);      /* select offset c1h */
outportb(0x2e+1,
0x00);

gotoxy(1,8);
printf("GP3x Status:
Low \n");
}
break;
default:
break;
};
//printf( "Input: [%c]      ", getkey);      //DEBUG
};
}while (getkey != 27); //ESC ascii==27
//pg all DIO as Input
outportb(0x2e, 0xaa);      /* exit key / disable configuration */
}

```

```

unsigned long Process_686C_Command_Write(unsigned long m_ECCMD,
unsigned long m_ECDDATA)
{
//-----
int i,temp;
unsigned long m_OutBuf;
//-----
m_OutBuf=inportb(0x6C);
if ( ( m_OutBuf&0x00000003) > 0 )
{
// temp=inportb(0x68);
return 0xFFFFFFFF;
}

outport(0x6C,m_ECCMD);
for ( i=0; i<=4000; i++ )

```

```

{
    m_OutBuf=inportb(0x6C);
    if ( ( m_OutBuf&0x00000002) == 0 ) break;
}
if ( i < 3999 )
    {
        output(0x68,m_ECADATA);
        for ( i=0; i<=4000; i++ )
            {
                m_OutBuf=inportb(0x6C);
                if ( ( m_OutBuf&0x00000002) == 0 )
                    { return 0x00000000; }
            }
    }

if ( i > 3999 ) m_OutBuf=inportb(0x68);
return 0xFFFFFFFF;
}
//-----
unsigned long Process_686C_Command_Read(unsigned long m_ECCMD )
{
int i,temp;
unsigned long m_OutBuf,m_InBuf;
m_OutBuf=inportb(0x6C);
if ( ( m_OutBuf&0x00000003) > 0 )
    {
        temp=inportb(0x68);
        return 0xFFFFFFFF;

    }
m_InBuf = m_ECCMD;
output(0x6C,m_InBuf);
for ( i=0; i<=3500; i++ )
    {
        m_OutBuf=inportb(0x6C);
        if ( ( m_OutBuf&0x00000001) > 0 )
            {
                temp=inportb(0x68);
                temp= (temp & 0x000000FF) ;
                return temp;
            }
    }
}

```

```

    // break;
    }
}
if ( i > 3499 )
{
    temp=inportb(0x68);
    return 0xFFFFFFFF;
}
return 0xFFFFFFFF;
}

//-----
unsigned long ECU_Read_686C_RAM_BYTE( unsigned long ECUMemAddr )
{
    unsigned long uDATA1,uDATA2,ECRamAddrH,ECRamAddrL;
    ECRamAddrL=ECUMemAddr%256; ECRamAddrH=ECUMemAddr/256;
    //
    uDATA1=Process_686C_Command_Write(0x000000A3, ECRamAddrH );
    if ( uDATA1==0xFFFFFFFF ) { return 0xFFFFFFFF; }
    //
    uDATA1=Process_686C_Command_Write(0x000000A2, ECRamAddrL );
    if ( uDATA1==0xFFFFFFFF ) { return 0xFFFFFFFF; }
    //
    uDATA1=Process_686C_Command_Read( 0x000000A4 );
    if ( uDATA1 > 0x000000FF ) { return 0xFFFFFFFF; }
    uDATA2=Process_686C_Command_Read( 0x000000A4 );
    if ( uDATA2 > 0x000000FF ) { return 0xFFFFFFFF; }
    if (uDATA1==uDATA2) return uDATA1;
    else return 0xFFFFFFFF;
}
//-----
unsigned long ECU_Write_686C_RAM_BYTE( unsigned long ECUMemAddr,unsigned long ECUMemData )
{
    unsigned long uDATA, RD_DATA, ECRamAddrH, ECRamAddrL;
    ECRamAddrL=ECUMemAddr%256; ECRamAddrH=ECUMemAddr/256;
    //
    uDATA=Process_686C_Command_Write(0x000000A3, ECRamAddrH );
    if ( uDATA==0xFFFFFFFF ) { return 0xFFFFFFFF; }
}

```

## Appendix

---

```
//
uDATA=Process_686C_Command_Write(0x000000A2, ECRamAddrL );
if ( uDATA==0xFFFFFFFF ) { return 0xFFFFFFFF; }
//
uDATA=Process_686C_Command_Write(0x000000A5, ECUMemData );
if ( uDATA==0xFFFFFFFF ) { return 0xFFFFFFFF; }
//
return 0x00000000;
}
//-----
```

```
unsigned char SMB_Byte_READ(int SMPORT, int DeviceID, int REG_IN-
DEX)
```

```
{
    unsigned char SMB_R;
    outportb(SMPORT+02, 0x00);          /* clear */
    outportb(SMPORT+00, 0xff);         /* clear */
    delay(10);
    outportb(SMPORT+04, DeviceID+1);   /* clear */
    outportb(SMPORT+03, REG_INDEX);    /* clear */
    outportb(SMPORT+02, 0x48);         /* read_byte */
    delay(10);
    //printf(" %02x ",inportb(SMPORT+05));
    SMB_R= inportb(SMPORT+05);
    return SMB_R;
}
```

```
void SMB_Byte_WRITE(int SMPORT, int DeviceID, int REG_INDEX, int
REG_DATA)
```

```
{
    outportb(SMPORT+02, 0x00);          /* clear */
    outportb(SMPORT+00, 0xff);         /* clear */
    delay(10);
    outportb(SMPORT+04, DeviceID);     /* clear */
    outportb(SMPORT+03, REG_INDEX);    /* clear */
    outportb(SMPORT+05, REG_DATA);     /* read_byte */
    outportb(SMPORT+02, 0x48);         /* read_byte */
    /*
    delay(10);
    printf(" %02x ",inportb(SMPORT+05)); */
}
```

## Appendix E: Watchdog Timer (WDT) Setting

WDT is widely used for industry application to monitor the activity of CPU. Application software depends on its own requirement to trigger WDT with adequate timer setting. Before WDT time-out, the functional normal system will reload the WDT. The WDT never times out for a normal system. Then, WDT will time out and reset the system automatically to avoid abnormal operation.

This board supports 255-level watchdog timer by software programming. Below are the source codes written in assembly & C, please take them as WDT application examples.

### C Language Code

```

/*----- Include Header Area -----*/
#include "math.h"
#include "stdio.h"
#include "dos.h"

/*----- routing, sub-routing -----*/

void main()
{
/*----- index port 0x4e -----*/
    outportb(0x4e, 0x87);    /* initial IO port */
    outportb(0x4e, 0x87);    /* twice, */

    outportb(0x4e, 0x07);    /* point to logical device */
    outportb(0x4e+1, 0x07);  /* select logical device 7 */
    outportb(0x4e, 0xf5);    /* select offset f5h */
    outportb(0x4e+1, 0x40);  /* set bit5 = 1 to clear bit5 */
    outportb(0x4e, 0xf0);    /* select offset f0h */
    outportb(0x4e+1, 0x81);  /* set bit7 = 1 to enable WDTRST# */
    outportb(0x4e, 0xf6);    /* select offset f6h */
    outportb(0x4e+1, 0x05);  /* update offset f6h to 0ah :10sec */
    outportb(0x4e, 0xf5);    /* select offset f5h */
    outportb(0x4e+1, 0x20);  /* set bit5 = 1 enable watch dog time */

    outportb(0x4e, 0xAA);    /* stop program F71869E, Exit */
}

```