



» Easy to integrate

» Faster machine speed

» High-precision machine operation



Fastest* ever industrial compact vision system

Designed for use in all types of object inspection, position/orientation and measurement operations, this compact camera and controller system is easily integrated into almost any machine or robot. The system is uniquely capable of providing faster, more precise work throughput – to give you more efficiency, less cost, and more competitive advantage. A key feature of the system is its advanced new vision algorithm: Shape Search III. This advanced, intuitive program gives you higher-speed and greater precision measurement even with difficult imaging conditions such as poor lighting, out-of-focus and rotated/ randomly positioned/overlapping target objects. Specifically intended for seamless integration with PLCs, motion controllers, and robotics the FH Vision System meets the diverse needs of builders of highspeed manufacturing machinery. The system also offers the flexibility of a PC-based vision system for easy customization and HMI integration. * Based on Omron investigation in May 2013.



Shorter machine cycle

Faster machine speed

High-speed image processing

A high-speed image bus and 4-core processing increases speed at every step, from image input to data output.

Multiple camera inspections

 $Calculations \ are \ quick \ and \ easy \ for \ four \ parallel \ tasks \ to \ provide \ total \ judgement \ results.$

Fast output to PLC

You can output results to an NJ Series machine automation controller on an EtherCAT communications cycle in just 500µs.

High-precision operation

Measure out-of-focus or rotated images

The new Shape Search III processing item provides superior stability.

Assured calibration accuracy

No worker dependent calibration, vision master calibration is provided.

Easy to integrate

Shared machine interface

Supports Microsoft®.NET

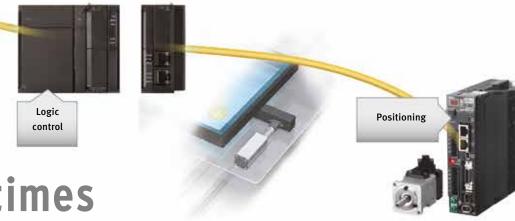
Simplified interface

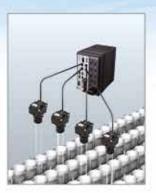
Customizable user interface means only your required menu commands appear on the operation interface.

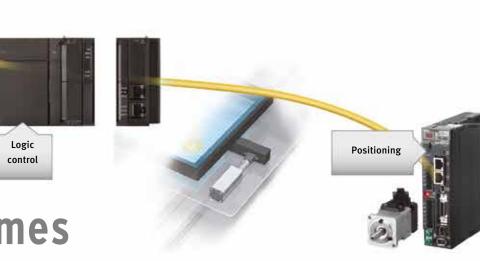
Fast support for additional needs

For additional measurement needs, complete processing item libraries are provided.









Faster machine speed FH

Process higher-resolution images without increasing machine cycle time



Fastest: 3.3 ms

4

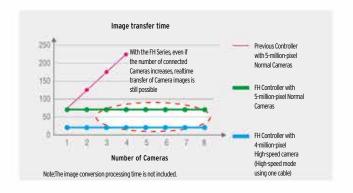
High-speed image input

Camera resolution continues to increase. That's why Omron has greatly reduced the input and transfer times of high-resolution images - to provide high-speed processing that matches the speed of your machine. Even with more cameras and higher resolution, high-speed image input will help increase throughput.

60ms 50ms Previous Camera 7 TIMES FASTER 10ms 5ms FH High-speed Camera 10ms 5ms FH High-speed Camera

Real-time image transfer

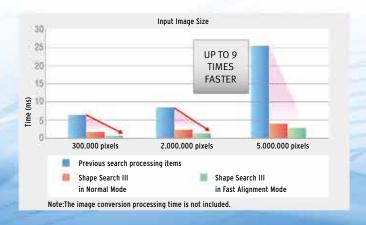
High-resolution cameras capture large amounts of data, which can cause transfer- and input-bottlenecks. That's why the FH Series Controller provides a faster, multi-line image bus to enable real-time transfer of large amounts of image data even for multiple cameras. Now you don't need to sacrifice precision to enable faster machine speed.



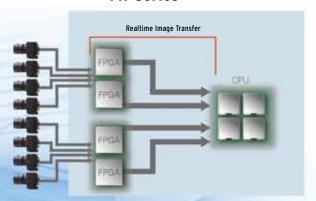
Shape Search III

Ultra-high-speed Searching

New technology makes search algorithms up to nine times faster than before. Even for unstable image conditions (including light interference, overlapping shapes, gloss, and incomplete images), stable searching is now possible without reducing speed.



FH-Series



Four-core CPU* for high-speed demands on different machines

*for high-speed controllers only

Machine cycle time reduced by 75%**

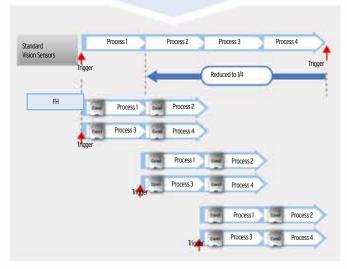
Four core process triggers, so the trigger interval can be 1/4 of previous models (in-house comparison).

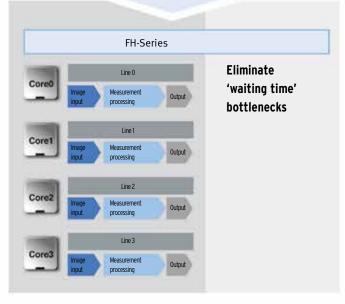
Process multiple lines without waiting

Four controllers are compressed into one without increasing the line cycle time. You can greatly reduce costs for processes that involve many lines.









Multi-input function
Continuous high-speed image capture

Higher speed from advanced image capture and parallel measurements

Each camera has its own image buffer for storing image data. This is separate from the main memory that is used for measurement processing. This allows for up to 256 frames of continuous high-speed image capture even when the main memory is processing measurement data.



**The number of images that can be captured depends on the controller and the camera that is connected to it.

Refer to the user's manual for details.

Faster machine speed FH

Fast output of measurement results reduces machine cycle time

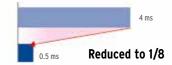
EtherCAT machine control network

EtherCAT is a high-speed open network that is ideal for machine control. You can use it to connect NJ Series machine automation controllers and motion control G5 Series Servomotors and Servo Drives to increase the control speed of everyday communications protocols from workpiece detection to starting axis motion.

Communications cycle

Conventional communications standard

EtherCAT



Features

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- Communications cycle as low as 500 μs
- Motion control that's synchronized with the communications cycle

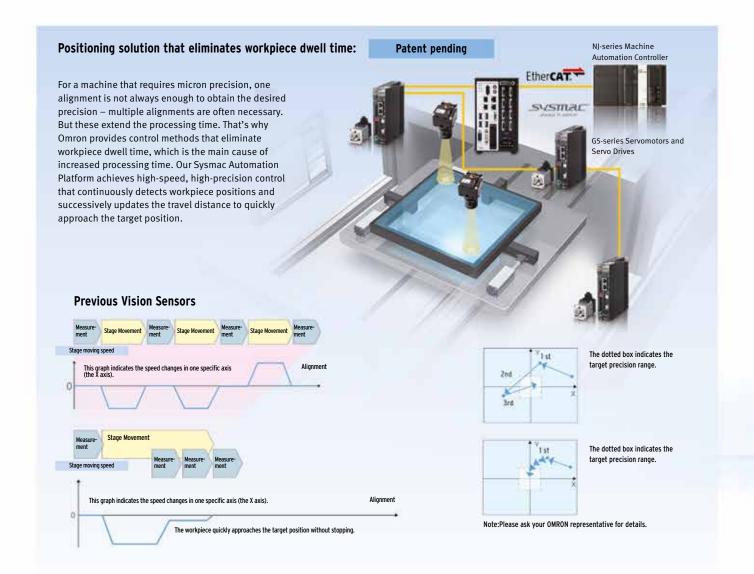
Time from trigger input to producing measurement results

Conventional communications standard

EtherCAT



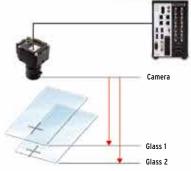
Note:The times given above are typical times. They depend on parameter settings.



FZ5

High-precision image processing required for positioning

Shape Search III

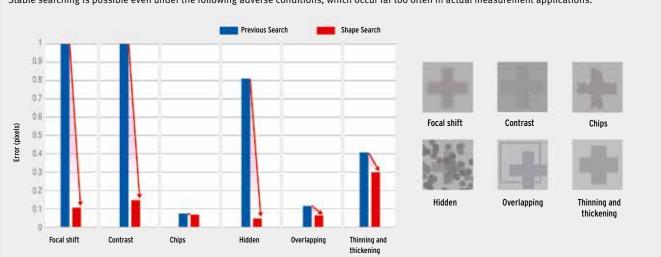


Low-error position detection even with blurry images

Over many years, Omron has perfected techniques to search for and match templates at high speed. This experience and expertise enables us to develop the Shape Search III vision algorithm, which provides advanced robustness and is critical on FA sites. When measuring lamination of glass or other processes where the distance to the workpiece from the camera varies, size differences and focal shifts can occur. Even in cases like this, the new Shape Search III algorithm detects positions with limited error.

Stable searching with limited error even under adverse conditions

Stable searching is possible even under the following adverse conditions, which occur far too often in actual measurement applications.

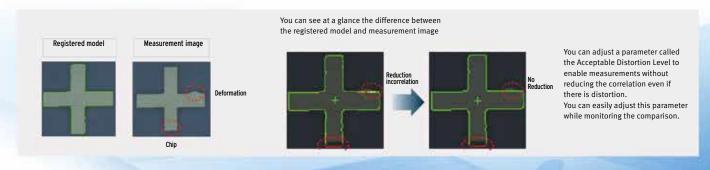


Visualization of comparisons enables easy setup of high-precision searching

Patent pending

Advanced searching is accompanied by many parameters that must be tuned to match the application. However, it is difficult for the person making the settings to see the internal process. Normally, a lot of time and effort is required to maximize tool performance. But with Shape Search III, you can visualize comparisons between the model data and a part of the

measurement object to easily see when comparisons are not optimally matched. Visualization of the comparison level allows for parameters to be adjusted to quickly obtain the best performance.



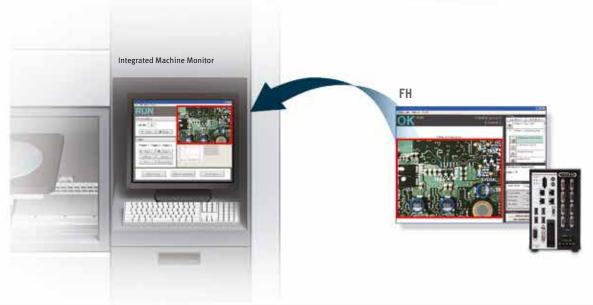
Easy to integrate FH FZ5

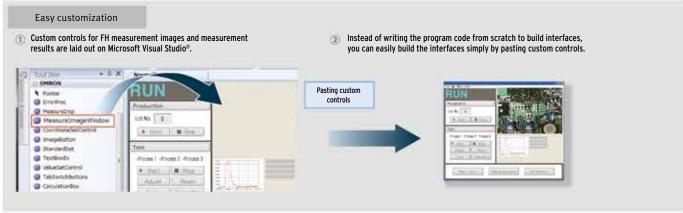
Easily connect the components that configure the machine

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Easy integration into a machine monitor Support for .NET user interface controls

Custom .NET controls are supported so that you can easily display FH Controller measurement images and measurement results on a PC.





Output to HMI or high-resolution monitor



Design components with one software

Develop machine control programs with one software: Sysmac Studio

Use the Automation Software Sysmac Studio to set up all of the slaves connected via EtherCAT. Simulate and debug motion control, logic, drives, and sensing on an integrated platform to reduce the work required for machine design.



One Software



Sysmac Studio version 1.07 or higher supports the FH Series.



FH-series Vision System



G5-series Servomotors and Servo Drives

Minimized commissioning & adjustment

Integrated simulations linked to an NJ Series Machine Automation Controller let you verify the NJ Series program logic. You can directly edit the EtherCAT I/O map to send measurement commands to FH Series Vision Sensors.



Machine Automation Controller

Customize original operation interfaces

Show only the buttons you need

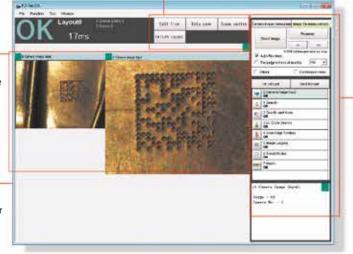
Choose from our library of buttons and position them on screen to best support your daily operation, without "screen clutter".

Arrange the interface elements flexibly

You can flexibly change the image display composition to display entire image, enlarge part of an image, or display images from different cameras.

Eight screen layout

Up to 8 screens can be stored depending on the application or user classification.

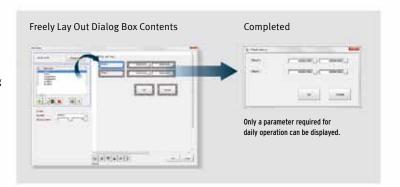


Move windows freely

Drag and drop windows where you want. You can also change the box size and delete.

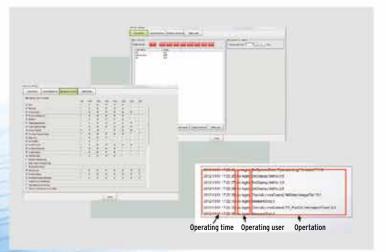
Hide unnecessary adjustment commands

With only menu operations on the controller, you can customize the setting displays in dialog boxes for processing items. For example, you can set up the interface to hide any parameters from the user.



Completely different operation interfaces for designer and operator

Accounts can be used to keep completely different operation interfaces for the designer and operator. You can set up to eight levels of security for up to 50 items for each account. You can record operation logs for each account to enable smoothly isolating problems when troubleshooting.



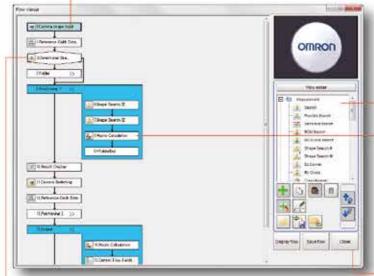
FH FZ5 11

Build measurement process with flowchart programming

Just add any of the large variety of processing items to the measurement flow to build the basic program for image processing. All processing items have menus for easy setup and adjustment. This enables you to easily build the best imaging processing for each application and to smoothly complete testing and adjustments without programming.



Just add processing items from the processing item list to visually edit the flow.



Processing Item List

Folders

You can group processing units into named folders. By managing related processing together and hiding lower levels, you can display even long measurement flows in a way that easily shows the overall flow.

Flowchart Output

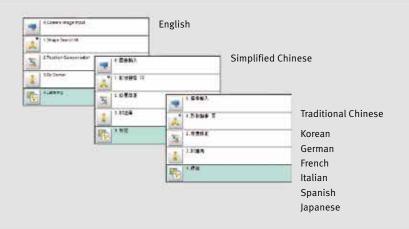
You can save the flowchart as an image file.

Branching

You can use conditional branching to branch according to the execution results of the previous processing units or you can use branching controls with external commands through parallel I/O, PLC Links, or no-protocol communications.

Easy multi-language support: Choose any of nine languages

Display the best language for the user for applications in other countries. You can change display messages between nine different languages: English, Chinese (traditional or simplified), German, French, Italian, Spanish, Korean, and Japanese.



Vision systems line up

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up to 4 cameras



up to $oldsymbol{8}$ cameras

EtherCAT.

SVSTRAC Encoder input

FZ5

High-precision alignment library

Four specialized types of alignment calculations are provided. You can combine these to easily execute alignment calculations on the FH Series Vision System that require complex calculations on previous sensor models or computers.



Movement single position

The axis movement that is required to match the measured position angle to the reference position angle is calculated.

Convert position data

The position angle after the specified axis movement is calculated.

Movement multi points

The axis movements that are required to match the measured position angles to the corresponding reference position angles are calculated.

Position data calculation

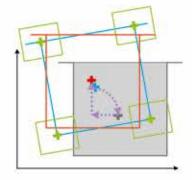
The specified position angle is calculated from the measured position.

Available alignment methods

Position angle alignment

Offsets are suitable for aligning the positions of workpieces with different sizes.

Position angle alignment allows the use of offsets to achieve flexible positioning.



- The Position Data Calculation processing item is used to calculate the position and angle to use in the axis movement based on measurement results (shown in green).
- The rotational movement on the θ axis is calculated as the reference angle minus the measured angle.
- The measurement position is rotated by the rotational movement for the θ axis (grey).
- The reference positions X and Y minus the measured positions X and Y after rotation are used as the X-axis movement and Y-axis movement.

Corresponding point alignment

The axis movements from the measured positions to the reference positions are calculated based on relational position information. This method is suitable for aligning all points within certain distances so that small deviations in the distances do not result in continuity failures, such as they can when aligning electronic substrates.

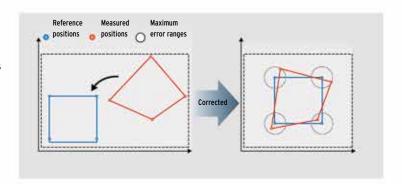


Image filter library

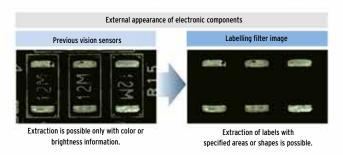
Calculations between images

You can perform arithmetic operations, bit operations, averaging, or maximum/minimum operations between two images.



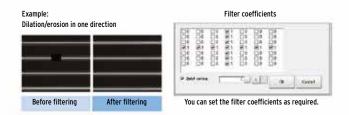
Labelling filter

This filter uses label processing to output an extracted image that contains only the specified characteristic labels.



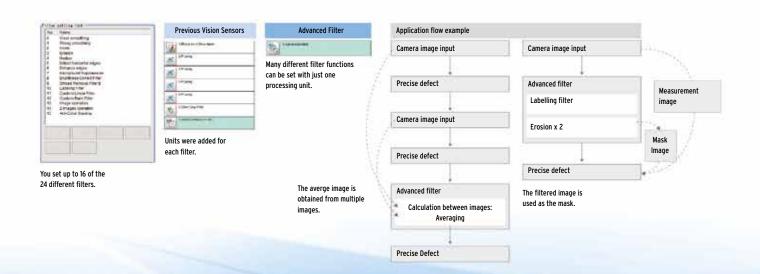
Custom filter

You can set the mask coefficients as required for these filters. The mask size can be up to 21 × 21. You can more flexibly set image smoothing, edge extractions, dilation, and erosion.



Advanced filter

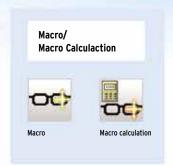
The image filter library has been condensed into one processing item. This allows you to easily set complex filtering as required for external inspections.

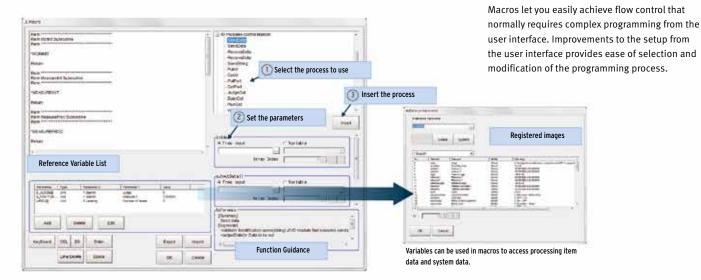


FH

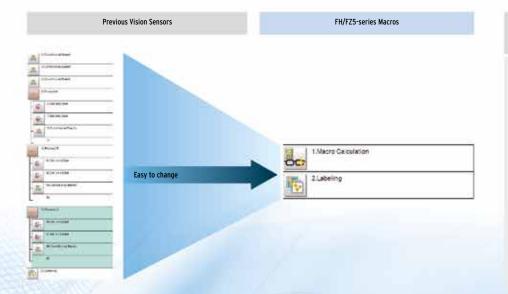
FZ5

Utility library





For example, it would previously have been long and complicated to change the set parameters of a processing item for each product model. With a Macro Calculation processing item, the flow is shorter and setting changes are easy to achieve.



Just enter the values of the variables to update the parameters.

The macros

Branching for each product model
Select INDEX@
Case 0
ExtCond0@ = 1 , Area
ExtParam0@ = 0
ExtParam1@ = 10000
Case 1
ExtCond0@ = 4 , Elliptic major axis
ExtParam0@ = 0
ExtParam1@ = 100
Case 2
ExtCond0@ = 7 , Rectangle width
ExtParam0@ = 0
ExtParam1@ = 200
End Select

Operation and analysis

Optimum operation both online and offline

Connections to a network hard disk drive or network computer enables a wide range of operation possibilities. You can log measurement images long-term, or you can perform verifications and adjustments on a computer without stopping



Ask your OMRON representative about obtaining simulation software.

New Operation Schemes through Network applications

Daily monitoring

You can store NG image in a network HDD to check the NG images every day on a computer without reducing measurement performance. Or you can start simulation software on your computer to remeasure and analyse NG images.

Periodic adjustments and inspection adjustments

The non-stop adjustment function lets you change Controller settings without stopping the production line. With remote operation, you can perform operations without going onsite.

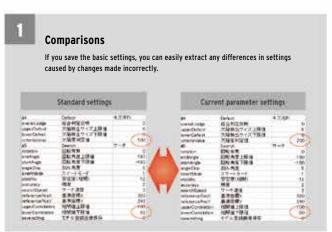
Handling unstable inspections or measurement failure

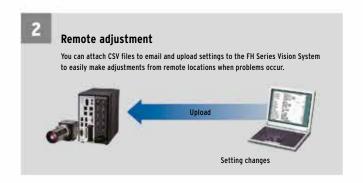
The user sends the programmer the image data, setting data, and parameter settings. The programmer can use the simulation software on the computer to check the process and change the settings with the simulation software. The altered scene data can be returned to the user and loaded to the system to complete the adjustments. This enables modifications without requiring the programmer to be on

Adding inspections or making changes for new models Based on the images to be inspected, settings are made on the simulation software on a PC running simulation software. The scene data is sent to the user to easily add the new settings.

Ideal for history management

CSV files allow you to easily understand the parameter settings. Also, you can easily change any of the settings.





Remote operation centralizes monitoring and adjustment of scattered sensors

You can check the status and adjust the settings of many FH on one computer.

This enables efficient adjustment of Camera images when commissioning a system and application of test adjustment results.



Operating several FHs from one location

Application example

When commissioning a line, from one location you can adjust the camera images from all of the FHs located along the line. There's no need to go to and from remote controllers, and you can compare camera images under various conditions to adjust them.

If setting changes are necessary to add a new model, you can do all the required work at the same time without making trips to all of the controllers.

You can easily balance the thresholds between controllers when increasing inspection stability through testing at the production line.

Displaying images from many FHs on one monitor

Application 1 example 🚄



Space savings with a single monitor installation.

Single location programming for multiple controllers facilitates adjustments and reduces programmer movement.

Note: Ask your Omron representative about obtaining simulation software.

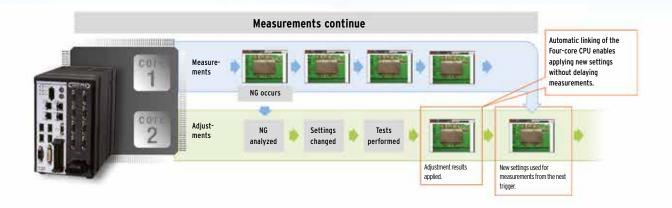
Utilities that don't stop your machines

Making confirmations and adjustments without stopping production

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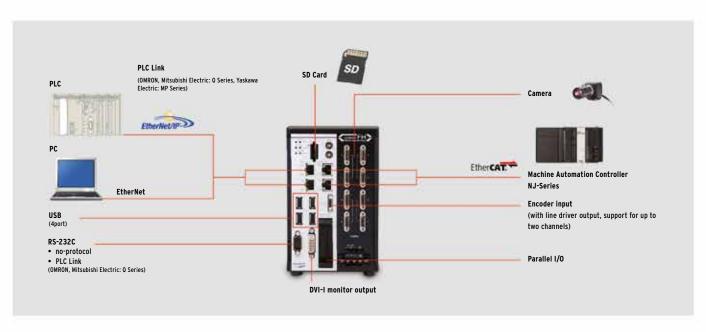
Parallel processing on Four-core CPU not only speeds up measurements, but it enables parallel processing of measurements and adjustments. Automatic distributed processing means that measurements are not delayed when adjustments are applied.

Non-stop adjustment



Seamless communications with peripheral devices

Complete interfaces for all connected devices



Options for more power customization

Application producer development environment to build and simulate applications

The Application Producer provides a development environment that lets you further customize the standard controller features of the FH Series Vision System. It includes custom control units that you can use to develop original interfaces with Microsoft® Visual Studio®, a command reference to help you create original processing items, and more.

Application Producer Main Window



- Create workspaces
- Select and change between workspaces.
- Start the program in the selected workspace.
- Create and add GUI objects.
- Create and add processing items.
- Open Microsoft® Visual Studio® projects.
- Open setup files.
- Create installation files.

Customization Example: GUI Customization



Start Add Panda and select the template that will serve as a base for customization. Selecting an interface template as a base first greatly reduces the work that is required compared with programming interfaces from scratch.



The Application Producer will automatically generate a project file from the selected template so that you can open it in Microsoft® Visual Studio®. You can develop interfaces just by dragging FH Series custom controls and Windows-based controls.



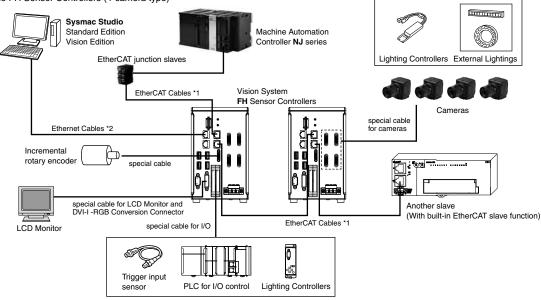
Instead of writing the program code from scratch to build an interface, you can easily build the interface simply by pasting custom controls. You can immediately check and debug the operation of the GUI objects that you add.

FH-Series

System configuration

EtherCAT connections for FH series

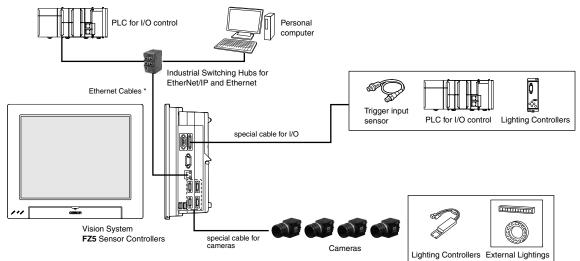
Example of the FH Sensor Controllers (4-camera type)



- *1. To use STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT and RJ45 connector.
 *2. To use STP (shielded twisted-pair) cable of category 5 or higher for Ethernet and RJ45 connector.

EtherNet/IP, No-protocol Ethernet and PLC Link Connections for FZ5 series

Example of the FZ5 Sensor Controllers (4-camera type)



^{*} To use Straight or cross STP (shielded twisted-pair) cable of category 5 or higher for Ethernet and RJ45 connector.

Ordering Information

FH Series Sensor Controllers

Iter	n	CPU	No. of cameras	Output	Model
		High-speed	2	NPN/PNP	FH-3050
18 5 6		Controllers	4	NPN/PNP	FH-3050-10
	Box-type	(4 core)	8	NPN/PNP	FH-3050-20
111	controllers	Standard	2	NPN/PNP	FH-1050
		Controllers	4	NPN/PNP	FH-1050-10
		(2 core)	8	NPN/PNP	FH-1050-20

FZ5 Series Sensor Controllers

Ite	m	CPU	No. of cameras	Output	Model
			2	NPN	FZ5-1100
		High-speed Controllers ontrollers 4 tegrated	2	PNP	FZ5-1105
			4	NPN	FZ5-1100-10
	Controllers		PNP	FZ5-1105-10	
	with LCD			NPN	FZ5-600
WHEE S			2	PNP	FZ5-605
		Controllers		NPN	FZ5-600-10
			4	PNP	FZ5-605-10
a			0	NPN	FZ5-L350
* 10	Box-type	Lite	2	PNP	FZ5-L355
1 11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	controllers	Controllers	4	NPN	FZ5-L350-10
211			4	PNP	FZ5-L355-10

Cameras

	Item	Descriptions	Color / Monochrome	Image read time	Model
		4 million nivele	Color	0.5 ma	FH-SC04
	10.1	4 million pixels	Monochrome	8.5 ms	FH-SM04
	High-speed CMOS Cameras	2 million pixels	Color	4.6 ms	FH-SC02
	(Lens required) - For FH Series only	2 million pixels	Monochrome	4.6 1115	FH-SM02
	- 1 of FIT Series Unity	300,000 pixels	Color	3.3 ms	FH-SC
		300,000 pixels	Monochrome	3.3 1115	FH-SM
		5 million pixels	Color		FZ-SC5M2
D.		(When connecting FZ5-6□ or FZ5-L35□, up to two cameras can be connected.)	Monochrome	62.5 ms	FZ-S5M2
	Digital CCD Cameras	2 million pixels	Color	33.3 ms	FZ-SC2M
	(Lens required)	2 million pixels	Monochrome	33.3 1118	FZ-S2M
		300,000 pixels	Color	12.5 ms	FZ-SC
1.1		300,000 pixeis	Monochrome	12.5 1115	FZ-S
	High-speed	200 200 : 1	Color	4.9 ms	FZ-SHC
	CCD Cameras (Lens required)	300,000 pixels	Monochrome		FZ-SH
		300,000-pixel flat type	Color	12.5 ms	FZ-SFC
1	Small Digital - CCD Cameras	300,000-pixel flat type	Monochrome	12.5 IIIS	FZ-SF
	(Lenses for small camera required)	300,000-pixel pen type	Color	12.5 ms	FZ-SPC
		300,000-pixel peri type	Monochrome	12.5 IIIS	FZ-SP
Helm		Narrow view	Color		FZ-SQ010F
	Intelligent Compact CMOS Cameras (Camera + Manual Focus Lens +	Standard view	Color	16.7 ms	FZ-SQ050F
	High power Lighting)	Wide View (long-distance)	Color	16.7 MS	FZ-SQ100F
		Wide View (short-distance)	Color		FZ-SQ100N
	Intelligent CCD Cameras	Wide View	Color	10.5	FZ-SLC100
	(Camera + Zoom, Autofocus Lens + Intelligent Lighting)	Narrow view	Color	12.5 ms	FZ-SLC15
	Autofocus CCD Cameras	Wide View	Color		FZ-SZC100
	(Camera + Zoom, Autofocus Lens)	Narrow view	Color	12.5 ms	FZ-SZC15

FH-Series

Lenses

C-mount Lens for 1/3-inch image sensor (Recommend: FZ-S□/FZ-SH□/FH-S□)

Model	3Z4S-LE SV-0614V	3Z4S-LE SV-0813V	3Z4S-LE SV-1214V	3Z4S-LE SV-1614V	3Z4S-LE SV-2514V	3Z4S-LE SV-3518V	3Z4S-LE SV-5018V	3Z4S-LE SV-7527V	3Z4S-LE SV-10035V
Appearance/ Dimensions (mm)	29 dia. 30.0	28 dia. 34.0	29 dia. 29.5	29 dia. 24.0	29 dia. 24.5	29 dia. 33.5[WD:∞] to 37.5[WD:300]	32 dia. 37.0[WD:∞] to 39.4[WD:1000]	32 dia. 42.0[WD:∞] to 44.4[WD:1000]	32 dia. 43.9[WD:∞] to 46.3[WD:1000]
Focal length	6 mm	8 mm	12 mm	16 mm	25 mm	35 mm	50 mm	75 mm	100 mm
Brightness	F1.4	F1.3	F1.4	F1.4	F1.4	F1.8	F1.8	F2.7	F3.5
Filter size	M27.0 P0.5	M25.5 P0.5	M27.0 P0.5	M27.0 P0.5	M27.0 P0.5	M27.0 P0.5	M30.5 P0.5	M30.5 P0.5	M30.5 P0.5
Maximum sensor size	1/3 inch	1/3 inch	1/3 inch	1/3 inch					
Mount					(C-mount			<u> </u>

C-mount Lens for 2/3-inch image sensor (Recommend: FZ-S \square 2M/FZ-S \square 5M2/FH-S \square 02) (3Z4S-LE SV-7525H and 3Z4S-LE SV-10028H can also be used for FH-S \square 04)

Model	3Z4S-LE SV-0614H	3Z4S-LE SV-0814H	3Z4S-LE SV-1214H	3Z4S-LE SV-1614H	3Z4S-LE SV-2514H	3Z4S-LE SV-3514H	3Z4S-LE SV-5014H	3Z4S-LE SV-7525H	3Z4S-LE SV-10028H
Appearance/ Dimensions (mm)	42 dia. 57.5	39 dia. 52.5	30 dia. 51.0	30 dia. 47.5	30 dia. 36.0	44 dia. 45.5	44 dia. 57.5	36 dia. 42.0[WD:∞] to 54.6[WD:1200]	39 dia. 66.5[WD:∞] to 71.6[WD:2000]
Focal length	6 mm	8 mm	12 mm	16 mm	25 mm	35 mm	50 mm	75 mm	100 mm
Brightness	F1.4	F2.5	F2.8						
Filter size	M40.5 P0.5	M35.5 P0.5	M27.0 P0.5	M27.0 P0.5	M27.0 P0.5	M35.5 P0.5	M40.5 P0.5	M34.0 P0.5	M37.5 P0.5
Maximum sensor size	2/3 inch	1 inch	1 inch						
Mount					C-moun	t			

Cameras Peripheral Devices

Item		Des	scriptions	Model
_	External Lighting		_	FL Series
7	Lighting Controller (Required to control external lighting from a Controller)	For FL-Series	Lighting Controller	FL-TCC1
	Intelligent Camera Diffusion	an Plato	Wide field of vision	FZ-SLC100-DL
- 4	intelligent Camera Diliusio	on Flate	Narrow field of vision	FZ-SLC15-DL
			Mounting Bracket	FQ-XL
	For Intelligent Compact Camera		Mounting Brackets	FQ-XL2
			Polarizing Filter Attachment	FQ-XF1
	Mounting Bracket for FZ-S	S		FZ-S-XLC
	Mounting Bracket for FZ-S	5□2M		FZ-S2M-XLC
_	Mounting Bracket for FZ-S	55M□2		FZ-S5M-XLC
	Mounting Bracket for FZ-S	SH 🗆		FZ-SH-XLC

Cables

Item	Descriptions	Model
19	Camera Cable Cable length: 2 m, 5 m, or 10 m *2	FZ-VS
/9	Bend resistant Camera Cable Cable length: 2 m, 5 m, or 10 m *2	FZ-VSB
9	Right-angle Camera Cable *1 Cable length: 2 m, 5 m, or 10 m *2	FZ-VSL
/9	Long-distance Camera Cable Cable length: 15 m *2	FZ-VS2
0	Long-distance Right-angle Camera Cable Cable length: 15 m *2	FZ-VSL2
	Cable Extension Unit Up to two Extension Units and three Cables can be connected. (Maximum cable length: 45 m *2)	FZ-VSJ
.9	Monitor Cable Cable length: 2 m or 5 m (When you connect a LCD Monitor FZ-M08 to FH sensor controller, please use it in combination with a DVI-I -RGB Conversion Connector FH-VMRGB.)	FZ-VM
1	DVI-I -RGB Conversion Connector For FH Series only	FH-VMRGB
19	Parallel I/O Cable Cable length: 2 m or 5 m, For FZ Series only	FZ-VP
19	Parallel I/O Cable for Connector-terminal Conversion Unit Cable length: 2 m or 5 m, For FZ Series only Connector-Terminal Block Conversion Units can be connected (Terminal Blocks Recommended Products: OMRON XW2R-J50G-T, XW2R-E50G-T, XW2R-P50G-T)	FZ-VPX
7	Parallel I/O Cable *3 Cable length: 2 m or 5 m, For FH Series only	XW2Z-S013-2/-S013-5
1	Encoder Cable for line-driver Cable length: 1.5 m, For FH Series only	FH-VR

Recommended EtherCAT and EtherNet/IP Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT. Use Straight or cross STP (shielded twisted-pair) cable of category 5 or higher for EtherNet/IP.

Item		Descripti	ions		Model
0		Standard type Cable with Connectors on Wire Gauge and Number of Pairs: AWG2 Cable color: Blue, Yellow, or Green, Cables length: 0.2m, 0.3m, 0.5m, 1m, 1.5	7, 4-pair Cable, Cable	Sheath material: LSZH *2,	XS6W-6LSZH8SS□CM-Y *3
200	For EtherCAT	Rugged type Cable with Connectors on B Wire Gauge and Number of Pairs: AWG2 Cables length: 0.3m, 0.5m, 1m, 2m, 3m, §	2, 2-pair Cable	XS5W-T421-□MD-K *3	
00	- 1	Rugged type Cable with Connectors on B Wire Gauge and Number of Pairs: AWG2 Cables length: 0.3m, 0.5m, 1m, 2m, 3m, 5	2, 2-pair Cable	XS5W-T421-□MC-K *3	
10		Rugged type Cable with Connectors on B Wire Gauge and Number of Pairs: AWG2 Cables length: 0.3m, 0.5m, 1m, 2m, 3m, 5	2, 2-pair Cable		XS5W-T422-□MC-K *3
			Cables	Hitachi Cable, Ltd.	NETSTAR-C5E SAB 0.5 × 4P *4
		Wire Gauge and Number of	Cables	Kuramo Electric Co.	KETH-SB *4
	For EtherCAT *1	Pairs: AWG24, 4-pair Cable		SWCC Showa Cable Systems Co.	FAE-5004 *4
	and EtherNet/IP		RJ45 Connectors	Panduit Corporation	MPS588-C *4
				Kuramo Electric Co.	KETH-PSB-OMR *5
		Wire Gauge and Number of	Cables	Nihon Electric Wire&Cable Co.,Ltd.	PNET/B *5
1		Pairs: AWG22, 2-pair Cable	RJ45 Assem- bly Connector	OMRON	XS6G-T421-1 *5
	For EtherNet/IP	Wire Gauge and Number of	Cables	Fujikura Ltd.	F-LINK-E 0.5mm × 4P *6
	TO LUMEINEVIE	Pairs: 0.5 mm, 4-pair Cable	RJ45 Connectors	Panduit Corporation	MPS588 *6

Note: Please be careful while cable processing, for EtherCAT, connectors on both ends should be shield connected and for EtherNet/IP, connectors on only one end should be shield connected.

The FH series supports the EtherCAT communication. It cannot be used in FZ series.

The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use.

For details, refer to Cat.No.G019.

We recommend you to use above cable for EtherCAT and EtherNet/IP, and RJ45 Connector together.

We recommend you to use above cable for EtherCAT and EtherNet/IP, and RJ45 Assembly Connector together.

We recommend you to use above cable For EtherNet/IP and RJ45 Connectors together.

This Cable has an L-shaped connector on the Camera end.
The maximum cable length depends on the Camera being connected, and the model and length of the Cable being used. For further information, please refer to the "Cameras / Cables" table.
When a high-speed CMOS camera FH-S_02/-S_04 is used in the high speed mode of transmission speed, two camera cables are required.
2 Cables are required for all I/O signals.

Peripheral Devices

Item			Descriptions		Model
	LCD Monitor For Box-type Controlle	ers			FZ-M08
	LIOD Marray		2 GB	2 GB	
H	USB Memory		8 GB		FZ-MEM8G
	SD Card		2 GB		HMC-SD291
2m	For FH Controller on	ly	4 GB		HMC-SD491
	VESA Attachment For installing the LCD		FZ-VESA		
	Desktop Controller Sta For installing the LCD		ontroller		FZ-DS
	Display/USB Switcher				FZ-DU
	Mouse Recommende Driverless wired mous (A mouse that requires	se	er to be installed is not supported.)		-
The state of the s	EtherCAT junction	3 port	Power supply voltage: 20.4 to 28.8 VDC	Current consumption: 0.08 A	GX-JC03
2000	For FH series	6 port	(24 VDC -15 to 20%)	Current consumption: 0.17 A	GX-JC06
1	Industrial Switching	3 port	Failure detection: None	Current consumption:	W4S1-03B
93	Hubs for EtherNet/IP and Ethernet	5 port	Failure detection: None	0.22 A	W4S1-05B
		5 port	Failure detection: Supported		W4S1-05C

Automation Software Sysmac Studio

Please purchase a DVD and licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. The license does not include the DVD.

Product	Specifications	Number of Model Standards licenses	Media	Model
	The Sysmac Studio provides an integrated development	(Media only)	DVD *1	SYSMAC-SE200D
0 0 "	environment to set up, program, debug, and maintain NJ-series	1 license	_	SYSMAC-SE201L
Sysmac Studio Standard Edition	Controllers and other Machine Automation Controllers, as well as EtherCAT slaves.	3 license	_	SYSMAC-SE203L
Ver.1.	Sysmac Studio runs on the following OS.	10 license	_	SYSMAC-SE210L
VCI.1.	Windows XP (Service Pack 3 or higher, 32-bit version) / Vista (32-	30 license	_	SYSMAC-SE230L
	bit version) / 7 (32-bit/64-bit version)	50 license	_	SYSMAC-SE250L
Sysmac Studio Vision Edition Ver.1.□□ *2	Sysmac Studio Vision Edition is a limited license that provides selected functions required for FH-serise/FQ-M-series Vision Sensor settings.	1 license	_	SYSMAC-VE001L

Site licenses are available for users who will run Sysmac Studio on multiple computers. Ask your OMRON sales representative for details.
 Sysmac Studio version 1.07 or higher supports the FH Series. Sysmac Studio does not support the FZ5 Series.

Development Environment

Please purchase a DVD and licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. The license does not include the DVD.

Product	Specifications	Number of Model Standards licenses	Media	Model
Application Developmen	Software components that provide a development environment to further customize the standard controller features of the FH Series. System requirements: • CPU: Intel Pentium Processor (SSE2 or higher) • OS: Windows 7 Professional (32bit) or Enterprise (32bit) or Ultimate (32bit) • .NET Framework: .NET Framework 3.5 or higher	— (Media only)	CD	FH-AP1
Application Producer	Memory: At least 2 GB RAM Available disk space: At least 2 GB Browser: Microsoft® Internet Explorer 6.0 or later Display: XGA (1024 × 768), True Color (32-bit) or higher Optical drive: CD/DVD drive The following software is required to customize the software: Microsoft® Visual Studio® 2010 Professional or Microsoft® Visual Studio® 2008 Professional	1 license	_	FH-AP1L

The same media is used for both the Standard Edition and the Vision Edition. With the Vision Edition, you can use only the setup functions for FH-series/FQ-M-series Vision Sensors.

Ratings and Specifications (Sensor Controllers)

FH Sensor Controllers

Туре				nigii-	speed Controllers	(4 core)	Sia	indard Controllers (2 core)
Model			NPN PNP	FH-3050	FH-3050-10	FH-3050-20	FH-1050	FH-1050-10	FH-1050-2
	Controller typ			Box-type controller	S				
		rocessing items		No					
	No. of Camer			2 4 8 2 4 8 Can be connected to all cameras. (FZ-S series/FH-S series)					
	Connected C	amera		Can be connected	to all cameras. (FZ-	S series/FH-S serie	s)		
		When connected to a intellige	ent compact camera	752 (H) × 480 (V)					
	Processing resolution	When connected to a 300,000	•	640 (H) × 480 (V)					
	(FZ-S)	When connected to a 2 millio	n-pixel camera	1600 (H) × 1200 (V	′)				
		When connected to a 5 million	n-pixel camera	2448 (H) × 2044 (V	')				
	Processing	When connected to a 300,000)-pixel camera	640 (H) × 480 (V)					
	resolution	When connected to a 2 million	n-pixel camera	2040 (H) × 1088 (V	')				
	(FH-S)	When connected to a 4 million	n-pixel camera	2040 (H) × 2048 (V	′)				
	No. of scenes	S		128					
		When connected to a intelligent compact camera			mera(Color): 77, Co mera(Color): 46, Co mera(Color): 33, Co	onnected to 2 camera nnected to 4 camera nnected to 6 camera nnected to 8 camera onnected to 1 came	a(Color): 58 a(Color): 38 a(Color): 29	79	
<i>l</i> lain unctions		When connected to a 300,000	0-pixel camera (FZ-S/FH-S)	Connected to 2 car Connected to 3 car Connected to 4 car Connected to 5 car Connected to 6 car Connected to 7 car	mera(Color): 135, C mera(Color/Monoch mera(Color): 67, Co mera(Color/Monoch mera(Color/Monoch mera(Color/Monoch mera(Color/Monoch	onnected to 2 came rome): 90 nnected to 4 camera rome): 54 rome): 45	ra(Monochrome): 1 a(Monochrome): 68	36	
	Number of logged	When connected to a 2 millio	Connected to 1 car Connected to 3 car	mera(Color/Monoch mera(Color/Monoch		ed to 2 camera(Colo ed to 4 camera(Colo	or/Monochrome): 18 or/Monochrome): 9		
	images *1			Connected to 7 car Connected to 1 car	mera(Color/Monoch mera(Color/Monoch	rome): 5, Connected rome): 43, Connected	d to 8 camera(Color ed to 2 camera(Colo		
		When connected to a 2 millio	on-pixel camera (FZ-S)	Connected to 5 car Connected to 7 car	mera(Color/Monoch mera(Color/Monoch	rome): 8, Connected rome): 6, Connected	d to 6 camera(Color d to 8 camera(Color	/Monochrome): 7	
		When connected to a 4 millio	Connected to 3 car Connected to 5 car Connected to 7 car	mera(Color/Monoch mera(Color/Monoch mera(Color/Monoch	rome): 6, Connected rome): 4, Connected rome): 2, Connected	d to 4 camera(Color d to 6 camera(Color d to 8 camera(Color	r/Monochrome): 5 r/Monochrome): 3 r/Monochrome): 2		
	When connected to a 5 million-pixel camera (FZ-S)			Connected to 1 camera(Color/Monochrome): 16, Connected to 2 camera(Color/Monochrome): 8 Connected to 3 camera(Color/Monochrome): 5, Connected to 4 camera(Color/Monochrome): 4 Connected to 5 camera(Color/Monochrome): 3, Connected to 6 camera(Color/Monochrome): 2 Connected to 7 camera(Color/Monochrome): 2, Connected to 8 camera(Color/Monochrome): 2					
	Operation			Mouse or similar d	evice				
	Settings			Create series of pr	ocessing steps by e	diting the flowchart	(Help messages pro	ovided).	
	Serial commu	unications		RS-232C: 1 CH					
					JDP) 1000BASE-T				
		unications			JDP) 1000BASE-T	2 port	1 port	2port	2port
	EtherNet com			No-protocol (TCP/II			1 port	2port	2port
	EtherNet con	nmunications		No-protocol (TCP/II	2 port rate: 1 Gbps (1000		1 port	2port	2port
cternal terface	EtherNet con	nmunications		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO t	2 port rate: 1 Gbps (1000 (100BASE-TX) mr trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TO 1, STGOUTZ to 10 re random trigger no o 7, DI_LINEO to 2,	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7)	TRIG_A0 to 1, ENCT o 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to	1, DI0 to 7, DI_LI
	EtherNet con EtherNet/IP c EtherCAT con	nmunications communications mmunications		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line randc 17 inputs (STEPO) 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ)	2 port rate: 1 Gbps (1000 (100BASE-TX) In trigger mode) NCTRIG_Z0, STEP1 to 1, READYO to 1, IT1, STGOUT2 to 7 ne random trigger o 7, DI_LINEO to 2, YO to 7, BUSYO to 7	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to, DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, ER	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU	1, DI0 to 7, DI_LI T0/SHTOUT0,
	EtherNet com EtherNet/IP c EtherCAT com	nmunications communications mmunications		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line randc 17 inputs (STEPO) 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ)	2 port rate: 1 Gbps (1000 (100BASE-TX) In trigger mode) NCTRIG_Z0, STEP1 to 1, READYO to 1, IT1, STGOUT2 to 7 ne random trigger o 7, DI_LINEO to 2, YO to 7, BUSYO to 7	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to, DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, ER	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to	1, DI0 to 7, DI_LI T0/SHTOUT0,
	EtherNet con EtherNet/IP c EtherCAT con	nmunications communications mmunications		No-protocol (TCP/II 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO) 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs (STEPO) 34 outputs (READ) RS422-A line drive	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TS TGOUT2 to 7 ner random trigger no 7, DL LINE0 to 2, y0 to 7, BUSY0 to 7 r level. Phase A/B:	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to, DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, ER	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU	1, DI0 to 7, DI_LI T0/SHTOUT0,
	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter	nmunications communications mmunications rface face		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPOI 34 outputs (READ) 75422-A line drive Phase Z: 1MHz DVI-I output IF×1.	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TS TGOUT2 to 7 ner random trigger no 7, DL LINE0 to 2, y0 to 7, BUSY0 to 7 r level. Phase A/B:	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Ef single-phase 4MHz	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU	1, DI0 to 7, DI_LI T0/SHTOUT0,
	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter Monitor inter	nmunications communications mmunications rface face		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUNo STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1 4 channels (suppo	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 2.0, STEP1 to 1, READY0 to 1, TT1, STGOUT2 to 7 or 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B:	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Ef single-phase 4MHz	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU	1, DI0 to 7, DI_LI T0/SHTOUT0,
	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter Monitor inter USB interface	nmunications communications mmunications rface face e face		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUNo STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1 4 channels (suppo	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG _20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Ef single-phase 4MHz	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU	1, DI0 to 7, DI_L T0/SHTOUT0,
	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter Monitor inter USB interface SD card inter	nmunications communications mmunications rface face e face y voltage	Connected to 2 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ') RS422-A line drive Phase Z: 1MHz DVI-I output IF x 1 4 channels (suppo SDHC card of Class	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG _20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Ef single-phase 4MHz	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU	1, DI0 to 7, DI_L T0/SHTOUT0,
	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply	rface face e face y voltage When connected to a intelligent or good and a compact camera, intelligent or good and	Connected to 2 cameras Connected to 4 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ' RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or reandom trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Eli single-phase 4MHz	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase o	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b	1, DI0 to 7, DI_L TO/SHTOUTO, y 4 times),
erface	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter Monitor inter USB interface SD card inter	ommunications communications mmunications rface face e face y voltage When connected to a intelligent		No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ' RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC	2 port rate: 1 Gbps (1000 (100BASE-TX) mt rigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or 1, PILINEO to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 as4 or higher rating	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Eli single-phase 4MHz	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase o	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b	1, DI0 to 7, DI_L T0/SHTOUTO, y 4 times),
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC)	rface face e face y voltage When connected to a intelligent or autofocus camera, intelligent or autofocus camera	Connected to 4 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rando 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ' RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC	2 port rate: 1 Gbps (1000 (100BASE-TX) mt rigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or 1, PILINEO to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 as4 or higher rating	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Eli single-phase 4MHz) s recommended.	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase o	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b	1, DI0 to 7, DI_L T0/SHTOUTO, y 4 times),
erface	EtherNet com EtherNet/IP c EtherCAT com Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption	rface face e face y voltage When connected to a intelligent or good and a compact camera, intelligent or good and	Connected to 4 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1: 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. —	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TT STGOUT2 to 7 ne random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch ts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max.	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Elsingle-phase 4MHz) s recommended.	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, GROR, STGOUT/SI (multiplying phase of the control of the con	FIIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max.	1, DI0 to 7, DI_L T0/SHTOUTO, y 4 times), 5.9 A max. 7.5 A max. 10.9 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC)	rface face e face y voltage When connected to a intelligent or autofocus camera When connected to a 300,000-pixel	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1: 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. —	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TT1, STGOUT2 to 7 or 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch tts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. — 4.2 A max.	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Ef single-phase 4MHz) s recommended.	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, GROR, STGOUT/SI (multiplying phase of the control of the con	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max.	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC)	mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line randc 17 inputs (STEP0/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEP0 i 34 outputs (READ) As outputs (READ) STSP2-A line drive Phase 2: 1MHz DVI-I output IF × 1 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. - 4.1 A max	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max 4.2 A max. 4.8 A max.	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) DI0 to 7, , OR0 to 7, ACK, Ef single-phase 4MHz) s recommended. 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max.	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, 0 RROR, STGOUT/SI (multiplying phase of the control of the c	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max.	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC) *2	nmunications mmunications mmunications rface face face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera sistance	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line randc 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ) RS422-A line drive Phase 2: 1MHz DVI-I output IF × 1: 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. - 4.1 A max Between DC powe	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max 4.2 A max. 4.8 A max.	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7, OR0 to 7, ACK, Efsingle-phase 4MHz Street	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, 0 RROR, STGOUT/SI (multiplying phase of the control of the c	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max.	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) *2 Insulation res	mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera sistance Fast	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line randa 17 inputs (STEP0/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEP0 1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. 4.1 A max Between DC powe Direct infusion: 2 K	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, READY0 to 1, READY0 to 1, READY0 to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 re level. Phase A/B: ch ts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max r supply and contro V Pulse rising: 5 ns	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7, OR0 to 7, ACK, Efsingle-phase 4MHz Street	TRIG_A0 to 1, ENCT 1, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of the content of the co	FRIG_B0 to 1, DSA0 to 2, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max.	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC) *2	nmunications mmunications mmunications rface face face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera sistance	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPOI 34 outputs (READ) 45 outputs (READ) 46 outputs (READ) 50 Area 50 Area 50 Area 50 Area 61 Area 62 Area 63 Area 64 Area 65 Area 66 Area 67 Area 67 Area 68 Area 68 Area 68 Area 68 Area 69 Area 60 Area 61	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 2/0, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or 7, DL LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max.	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7, OR0 to 7, ACK, Ef single-phase 4MHz 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max. 6.8 A max. 10 F GS 20 MΩ or his Pulse width: 50 ns	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, 0 RROR, STGOUT/SI (multiplying phase of the content of the c	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max. - 250 V)	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) *2 Insulation res	nmunications mmunications mmunications rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 200,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera sistance Fast transient	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand t7 inputs (STEPO/E 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ) RS422-A line drive Phase 2: 1MHz DVI-I output IF × 1 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. Between DC powe Direct infusion: 2 K Burst continuation Cramp: 1 KV Pulse Burst continuation	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to , DO0 to 15, ACK) node) Di0 to 7) , OR0 to 7, ACK, Eli single-phase 4MHz 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max. 6.8 A max. let FG: 20 MΩ or hi Pulse width: 50 ns s Period: 300 ms Ap	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, 0 RROR, STGOUT/SI (multiplying phase of the content of the c	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max. - 250 V)	5.9 A max. 10.9 A max. 10.9 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) 12 Insulation res Insulation res Insulation res Insulation res	nmunications mmunications mmunications rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 200,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera sistance Fast transient	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line randa 17 inputs (STEP0/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEP01 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I outputs (FEAD) SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. — 4.1 A max. — Between DC powe Direct infusion: 2 K Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, READY0 to 1, READY0 to 1, READY0 to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 re level. Phase A/B: ch ts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7), OR0 to 7, ACK, Elisingle-phase 4MHz 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max. 6.8 A max. ler FG: 20 MΩ or hiPulse width: 50 ns Seriod: 300 ms Apwidth: 50 ns Period: 300 ms Approved.	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, 0 RROR, STGOUT/SI (multiplying phase of the content of the c	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max. - 250 V)	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC) *2 Insulation res Noise Immunity Ambient tem	rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a million-pixel camera, 4 million-pixel camera or 5 million-pixel camera Fast transient burst	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUN0 STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1. 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. 8etween DC powe Direct infusion: 2 K Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Storage: -20 to 65	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TT1, STGOUT2 to 7 or random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch tts USB 1.1 and 2.0 es4 or higher rating 5.4 A max. 7.0 A max. - 4.2 A max. 4.8 A max r supply and contro V Pulse rising: 5 ns Fulse v time: 15 ms/0.75 m rising: 5 ns Pulse v time: 15 ms/0.75 m °C °C (with no icing or	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Elf single-phase 4MHz 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max. 6.6 A max. 6.68 A max. ler FG: 20 MΩ or hi Pulse width: 50 ns s Period: 300 ms Ap width: 50 ns s Period: 300 ms Ap condensation)	TRIG. A0 to 1, ENCT 11, ERROR0 to 1, 6 RROR, STGOUT/SI (multiplying phase of the control of the	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max. - 250 V)	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) *2 Insulation res Noise Immunity Ambient tem Ambient hum	nmunications mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera of 5 million-pixel camera sistance Fast transient burst perature range nidity range	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUN0) STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO 1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1. 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. Between DC powe Direct infusion: 2 K Burst continuation Cramp: 1 KV Pulse Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Operating and stor	2 port rate: 1 Gbps (1000 (100BASE-TX) mr trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TT1, STGOUT2 to 7 or 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch ts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. - 4.2 A max. 4.8 A max. - 5.0 Type sing: 5 ns time: 15 ms/0.75 m or sing: 5 ns Pulse to time: 15 ms/0.75 m or GC C (with no icing or age: 35% to 85% (w	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7), OR0 to 7, ACK, Elisingle-phase 4MHz 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max. 6.8 A max. ler FG: 20 MΩ or hiPulse width: 50 ns Seriod: 300 ms Apwidth: 50 ns Period: 300 ms Approved.	TRIG. A0 to 1, ENCT 11, ERROR0 to 1, 6 RROR, STGOUT/SI (multiplying phase of the control of the	RIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. - 3.7 A max. 4.3 A max. - 250 V)	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) "2 Insulation res Insulation res Insulation tem Ambient tem Ambient atme	nmunications mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera of 5 million-pixel camera sistance Fast transient burst perature range nidity range	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUNO) STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO 1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1: 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. Between DC powe Direct infusion: 2 k Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Storage: -20 to 65 Operating and stor No corrosive gases	2 port rate: 1 Gbps (1000 (100BASE-TX) mt trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or 7, DUSY0 to 7 r level. Phase A/B: ch tts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. - 4.2 A max. 4.8 A max. - 4.2 B max. 4.8 A max. - 5 supply and contro V Pulse rising: 5 ns time: 15 ms/0.75 m or sing: 5 ns Pulse v time: 15 ms/0.75 m or C (with no icing or age: 35% to 85% (v or STEP)	JANES TO SERVICE TO SE	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of 4.7 A max. 3.6 A max	SOLUTION SOLUTION	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
erface	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) 1 Insulation res Insulation res Insulation tem Ambient tem Ambient atm Grounding	nmunications mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent or autofocus camera, intelligent or autofocus camera a million-pixel camera, 2 million-pixel camera, 4 million-pixel camera isistance Fast transient burst perature range indity range osphere	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO 1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1, 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. — — 4.1 A max. — — Between DC powe Direct infusion: 2 K Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Operating and stor No corrosive gases Type D grounding	2 port rate: 1 Gbps (1000 (100BASE-TX) mt trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or 7, DUSY0 to 7 r level. Phase A/B: ch tts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. - 4.2 A max. 4.8 A max. - 4.2 B max. 4.8 A max. - 5 supply and contro V Pulse rising: 5 ns time: 15 ms/0.75 m or sing: 5 ns Pulse v time: 15 ms/0.75 m or C (with no icing or age: 35% to 85% (v or STEP)	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7) , OR0 to 7, ACK, Elf single-phase 4MHz 6.4 A max. 8.1 A max. 11.5 A max. 5.2 A max. 6.6 A max. 6.68 A max. ler FG: 20 MΩ or hi Pulse width: 50 ns s Period: 300 ms Ap width: 50 ns s Period: 300 ms Ap condensation)	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of 4.7 A max. 3.6 A max	SOLUTION SOLUTION	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
tings	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) "2 Insulation res Insulation res Insulation tem Ambient tem Ambient atme	nmunications mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent or autofocus camera, intelligent or autofocus camera a million-pixel camera, 2 million-pixel camera, 4 million-pixel camera isistance Fast transient burst perature range indity range osphere	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUNO) STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO 1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1: 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. Between DC powe Direct infusion: 2 k Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Storage: -20 to 65 Operating and stor No corrosive gases	2 port rate: 1 Gbps (1000 (100BASE-TX) mt trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 or 7, DUSY0 to 7 r level. Phase A/B: ch tts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. - 4.2 A max. 4.8 A max. - 4.2 B max. 4.8 A max. - 5 supply and contro V Pulse rising: 5 ns time: 15 ms/0.75 m or sing: 5 ns Pulse v time: 15 ms/0.75 m or C (with no icing or age: 35% to 85% (v or STEP)	JANES TO SERVICE TO SE	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of 4.7 A max. 3.6 A max	SOLUTION SOLUTION	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
tings	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) 1 Insulation res Insulation res Insulation tem Ambient tem Ambient atm Grounding	nmunications mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent or autofocus camera, intelligent or autofocus camera a million-pixel camera, 2 million-pixel camera, 4 million-pixel camera isistance Fast transient burst perature range indity range osphere	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO 1 34 outputs (READ) RS422-A line drive Phase Z: 1MHz DVI-I output IF × 1, 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. — — 4.1 A max. — — Between DC powe Direct infusion: 2 K Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Operating and stor No corrosive gases Type D grounding	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max.	JANES TO SERVICE TO SE	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of 4.7 A max. 3.6 A max	SOLUTION SOLUTION	5.9 A max. 7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.
	EtherNet com EtherNet/IP c EtherCAT con Parallel I/O Encoder inter Monitor inter USB interfact SD card inter Power supply Current consumption (at 24.0 VDC) *2 Insulation res Noise Immunity Ambient tem Ambient atm Grounding Degree of pro	nmunications mmunications mmunications mmunications rface face e face y voltage When connected to a intelligent or autofocus camera, intelligent or autofocus camera a million-pixel camera, 2 million-pixel camera, 4 million-pixel camera isistance Fast transient burst perature range indity range osphere	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO I 34 outputs (READ) As outputs (READ) STEPO/E 34 outputs (READ) 4 channels (suppo SDHC card of Clas 20.4 to 26.4 VDC 5.0 A max. Between DC powe Direct infusion: 2 k Burst continuation Cramp: 1 KV Pulse Burst continuation Operating: 0 to 50 Storage: -20 to 65 Operating and stor No corrosive gases Type D grounding IEC60529 IP20	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG 20, STEP1 to 1, READY0 to 1, IT1, STGOUT2 to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 r level. Phase A/B: ch rts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max.	JANES TO SERVICE TO SE	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of 4.7 A max. 3.6 A max	SOLUTION SOLUTION	5.9 A max. 10.9 A max. 10.9 A max. 5.0 A max.
eration	EtherNet com EtherNet/IP c EtherCAT con EtherCAT con EtherCAT con EtherCAT con Parallel I/O Encoder inter Monitor inter USB interface SD card inter Power supply Current consumption (at 24.0 VDC) *2 Insulation res	rface face e face y voltage When connected to a intelligent compact camera, intelligent or autofocus camera When connected to a 300,000-pixel camera, 2 million-pixel camera, 4 million-pixel camera Fast transient burst perature range nidity range osphere	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	No-protocol (TCP/I 1 port Ethernet port baud EtherCAT protocol (In the 2-line rand 17 inputs (STEPO/E 37 outputs (RUNO STGOUT1/SHTOL (In the 5-line to 8-li 19 inputs, STEPO1	2 port rate: 1 Gbps (1000 (100BASE-TX) m trigger mode) NCTRIG_Z0, STEP1 to 1, READY0 to 1, TT STGOUTE to 7 re random trigger no 7, DI_LINE0 to 2, Y0 to 7, BUSY0 to 7 re level. Phase A/B: ch ts USB 1.1 and 2.0 ss4 or higher rating 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max 1.5 ms/0.75 m rising: 5 ns Pulse	/ENCTRIG_Z1, ENC BUSY0 to 1, OR0 to 1, OR0 to 15, ACK) node) DI0 to 7, OR0 to 7, ACK, Ef single-phase 4MHz Single-phase 4MHz	TRIG_A0 to 1, ENCT 11, ERROR0 to 1, (RROR, STGOUT/SI (multiplying phase of 4.7 A max. 3.6 A max.	FRIG_B0 to 1, DSA0 to GATE0 to 1, STGOU HTOUT0 to 7) difference of 1MHz b 5.0 A max. 6.5 A max. 4.3 A max. - 250 V) n	1, DI0 to 7, DI_L TO/SHTOUTO, y 4 times), 5.9 A max. 7.5 A max. 4.5 A max. 5.0 A max. 6.2 A max.

The image logging capacity changes when multiple cameras of different types are connected at the same time.

The current consumption when the maximum number of cameras supported by each controller are connected.

If a strobe controller model is connected to a lamp, the current consumption is as high as when an intelligent camera is connected.

FZ5 Sensor Controllers

Туре			High-speed	Controllers	Standard	Controllers	Lite Cor	ntrollers
		NPN	FZ5-1100	FZ5-1100-10	FZ5-600	FZ5-600-10	FZ5-L350	FZ5-L350-10
Model		PNP	FZ5-1105	FZ5-1105-10	FZ5-605	FZ5-605-10	FZ5-L355	FZ5-L355-10
Controller type			Controllers integrate	ed with LCD			Box-type controllers	3
High-grade Proce	ssing items		No				T	1
No. of Cameras			2	4	2	4	2	4
Connected Camer	ra		Can be connected to (Can not be connected)				not be connected to o two cameras can b	
	When connected to a	intelligent compact camera	,			p		
Processing	When connected to	a 300,000-pixel camera	640 (H) × 480 (V)					
resolution	When connected to	a 2 million-pixel camera	1600 (H) × 1200 (V)	1				
	When connected to	a 5 million-pixel camera	2448 (H) × 2044 (V)	<u> </u>				
No. of scenes		1=	32		1			
	When connected to	Connected to 1 camera Connected to 2 cameras	116		107			
	a intelligent	Connected to 3 cameras	77		71			
	compact camera	Connected to 4 cameras	58		53			
		Connected to 1 camera	Color camera: 270,		Color comoro: 250	Managhrama Cama	ro: 0E0	
		Connected to 1 camera	Monochrome Came	ra: 272	Color camera: 250,	Monochrome Came	ra: 252	
	When connected to	Connected to 2 cameras	Color camera: 135, Monochrome Came	ro: 126	Color camera: 125,	Monochrome Came	ra: 126	
	a 300,000-pixel		Color camera: 90,	100	0.1			
	camera	Connected to 3 cameras	Monochrome Came	ra: 90	Color camera: 83, I	Monochrome Camera	a: 84	
		Connected to 4 cameras	Color camera: 67,	**** CO	Color camera: 62. I	Monochrome Camera	a: 63	·
			Monochrome Came Color camera: 43,	ra: 68				
Number of		Connected to 1 camera	Monochrome Came	ra: 43	Color camera: 40, I	Monochrome Camera	a: 40	
logged images *1	When corrected to	Connected to 2 cameras	Color camera: 21,		Color camera: 20	Monochrome Camera	a· 20	
	When connected to a 2 million-pixel	Connected to 2 cameras	Monochrome Came	ra: 21	50101 Gailleta. 20, 1	Noncomonie Carllen	LU	
	camera	Connected to 3 cameras	Color camera: 14, Monochrome Came	ra: 14	Color camera: 13, I	Monochrome Camera	a: 13	
			Color camera: 10.	14. 14	0.1			
		Connected to 4 cameras	Monochrome Came	ra: 10	Color camera: 10, I	Color camera: 10, Monochrome Camera: 10		
		Connected to 1 camera	Color camera: 16,	10	Color camera: 11, Monochrome Camera: 11			
			Monochrome Camera: 16 Color camera: 8,					
	When connected to	Connected to 2 cameras	Monochrome Camera: 8 Color camera: 5, Monochrome Camera		5			
a 5 million-pixel camera	Connected to 3 cameras	Color camera: 5,			_			
	- Cambra	Connected to 5 cameras	Monochrome Came	ra: 5				
		Connected to 4 cameras	Color camera: 4, Monochrome Came	ra· 4			_	
Operation			Touch pen, mouse,				Mouse or similar de	vice
Settings					liting the flowchart (F	lelp messages provi		
Serial communica	ntions		RS-232C/422A:10	CH			RS-232: 1CH	
EtherNet commun	nications		Ethernet 100BASE-TX/10BASE-T				Ethernet 1000BASE	E-T/100BASE-TX/
					D TV)		10BASE-T	
EtherNet/IP comm	nunications		Ethernet port baud i (When used in Multi-		Base-IX)			
Parallel I/O		mode) 17 inputs (RESET, \$ ENCTRIG_Z0, STE DSA0 to 1, ENCTRI ENCTRIG_B0 to 1, 29 outputs (RUN/BL GATE0 to 1, OR0 to ERROR, STGOUTO (When used in othe 13 inputs (RESET, \$ ENCTRIG_Z0, DSA ENCTRIG_B0, DIO 26 outputs (RUN, B OR0, READYO, ERI 3, DO0 to 15) * STGOUT 2 to 3 o	STEPO/ P1/ENCTRIG_Z1, IG_A0 to 1, DI0 to 7), JSY1, BUSY0, J1, READY0 to 1, to 3, DO0 to 15) r mode) STEPO/ 0, ENCTRIG_A0, to 7, USY0, GATEO,	13 inputs (RESET, STEP0/ ENCTRIG_Z0, DSA0, ENCTRIG_A0, ENCTRIG_B0, DI0 to 7), 26 outputs (RUN, BUSY0, GATE0, OR0, READY0, ERROR, STGOUT0 to 3, DO0 to 15) * STGOUT 2 to 3 only for camera 4 ch type 11 inputs (RESET, STEP, I 0 to 7), 26 outputs (RUN, BUSY, G READY, ERROR, STGOUT DO 0 to 15) * STGOUT 2 to 3 only for camera 4 ch		USY, GATE, OR, TGOUT 0 to 3, and		
Monitor interface			type Integrated Controlle (Resolution: XGA 1,		h TFT color LCD		Analog RGB video output, 1 channel (Resolution: XGA 1,024 × 768 dots)	
USB interface		4 channels (support	s USB 1.1 and 2.0)			2CH (supports USB1.1/2.0)		
Power supply vol			20.4 to 26.4 VDC				<u> </u>	
Current consumption (at 24.0 VDC) *3	When connected to a into When connected to a When connected to a	intelligent compact camera telligent or autofocus camera a 300,000-pixel camera a 2 million-pixel camera	5.0 A max. 3.7 A max.	7.5 A max. 4.9 A max.	5.0 A max.	7.5 A max. 4.9 A max.	4.0 A max. 2.6 A max.	5.5 A max. 2.9 A max.
Ambient temperat		a 5 million-pixel camera	Operating: 0 to 45 °C for low cooling fan speeds, 0 to 50 °C for high cooling fan Speeds (20 to 65 °C, 0 to Storage: -20 to 65 °C (with no icing or condensation)		C			
Ambient humidity	range		Operating and stora	ige: 35% to 85% (w	th no condensation)		·	
Weight				Approx. 3.4 kg	Approx. 3.2 kg	Approx. 3.4 kg	Approx. 1.8 kg	·
Accessories					Instruction Manual,		Instruction Manual	
 The image longer 	ogging capacity cha	nges when multiple cam	eras of different ty	mes are connect	ed at the same tin	ne		

The image logging capacity changes when multiple cameras of different types are connected at the same time.

Do not ground the positive terminal of the 24-VDC power supply to a Lite Controller.

If the positive terminal is grounded, electrical shock may occur when an SG (0-V) part, such as the case of the Controller or Camera, is touched. The current consumption when the maximum number of cameras supported by each controller are connected.

If a strobe controller model is connected to a lamp, the current consumption is as high as when an intelligent camera is connected.

Ratings and Specifications (Cameras)

High-speed CMOS cameras

Model	FH-SM	FH-SC	FH-SM02	FH-SC02	FH-SM04	FH-SC04
Image elements	1/3-inch CMOS image elements		2/3-inch CMOS imag	e elements	1-inch CMOS image	e elements
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color
Effective pixels	640 (H) × 480 (V)		2040 (H) × 1088 (V)		2040 (H) × 2048 (V)	1
Pixel size	$7.4 \; (\mu m) \times 7.4 \; (\mu m)$		5.5 (μm) × 5.5 (μm)		5.5 (μm) × 5.5 (μm)	
Shutter function	Electronic shutter; Shutter speeds can be set from 20 µs to 100 ms.		Electronic shutter; Shutter speeds can be set from 25 μs to 100 ms.			
Partial function	1 to 480 lines	2 to 480 lines	1 to 1088 lines	2 to 1088 lines	1 to 2048 lines	2 to 2048 lines
Frame rate (image read time)	308 fps (3.3 ms)		219 fps (4.6 ms) * 118 fps (8.5		118 fps (8.5 ms) *	
Lens mounting	C-mount	C-mount				
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance					
Ambient temperature range	Operating: 0 to 40 °C	, Storage: -25 to 65 °C	(with no icing or conde	nsation)		
Ambient humidity range	Operating and storage: 35% to 85% (with no		condensation)	·		·
Weight	Approx.105 g		Approx.110 g			
Accessories	Instruction manual					

 $^{^{\}star}~$ For high speed frame rate, 2 pieces of FZ-VS-_M cables are required.

Digital CCD Cameras

Model	FZ-S	FZ-SC	FZ-S2M	FZ-SC2M	FZ-S5M2	FZ-SC5M2
Image elements	Interline transfer reading all pixels, 1/3-inch CCD image elements		Interline transfer readi 1/1.8-inch CCD image		Interline transfer read 2/3-inch CCD image	
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color
Effective pixels	640 (H) × 480 (V)		1600 (H) × 1200 (V)		2448 (H) × 2044 (V)	
Pixel size	$7.4 \; (\mu m) \times 7.4 \; (\mu m)$		$4.4~(\mu\text{m})\times4.4~(\mu\text{m})$		3.45 (μm) × 3.45 (μm))
Shutter function	Electronic shutter; sel	ect shutter speeds from	n 20 μs to 100 ms		•	
Partial function	12 to 480 lines		12 to 1200 lines		12 to 2044 lines	
Frame rate (image read time)	80 fps (12.5 ms)		30 fps (33.3 ms)		16 fps (62.5 ms)	
Lens mounting	C-mount	C-mount C-mount				
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance					
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C (with no icing or conde	ensation)	Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)					
Weight	Approx. 55 g		Approx. 76 g Approx.140 g			
Accessories	Instruction manual	Instruction manual				

Small CCD Digital Cameras

Model	FZ-SF	FZ-SFC	FZ-SP	FZ-SPC		
Image elements	Interline transfer reading all pixels, 1/3-inch CCD image elements					
Color/Monochrome	Monochrome	Color	Monochrome	Color		
Effective pixels	640 (H) × 480 (V)					
Pixel size	$7.4 (\mu m) \times 7.4 (\mu m)$					
Shutter function	Electronic shutter; select shutter	speeds from 20 µm to 100 ms				
Partial function	12 to 480 lines	12 to 480 lines				
Frame rate (image read time)	80 fps (12.5ms)					
Lens mounting	Special mount (M10.5 P0.5)					
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance					
Ambient temperature range	Operating: 0 to 50 °C (camera amp) 0 to 45 °C (camera head) Storage: -25 to 65 °C (with no icing or condensation)					
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)					
Weight	Approx. 150 g					
Accessories	Instruction manual, installation bracket, Four mounting brackets (M2) Instruction manual					

High-speed CCD Cameras

Model	FZ-SH	FZ-SHC		
Image elements	Interline transfer reading all pixels, 1/3-inch CCD image elements			
Color/Monochrome	Monochrome Color			
Effective pixels	640 (H) × 480 (V)			
Pixel size	$7.4 (\mu m) \times 7.4 (\mu m)$			
Shutter function	Electronic shutter; select shutter speeds from 1/10 to 1/50,000 s			
Partial function	12 to 480 lines			
Frame rate (image read time)	204 fps (4.9ms)			
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance			
Ambient temperature range	Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)			
Weight	Approx. 105 g			
Accessories	Instruction manual			

Intelligent Compact CMOS Cameras

Model	FZ-SQ010F	FZ-SQ050F	FZ-SQ100F	FZ-SQ100N		
Image elements	1/3-inch CMOS image elements					
Color/Monochrome	Color					
Effective pixels	752 (H) × 480 (V)					
Pixel size	6.0 (μm) × 6.0 (μm)					
Shutter function	1/250 to 1/32,258					
Partial function	8 to 752 lines					
Frame rate (image read time)	60 fps					
Field of vision	7.5 × 4.7 to 13 × 8.2 mm	13 × 8.2 to 53 × 33 mm	53 × 33 to 240 × 153 mm	29 × 18 to 300 × 191 mm		
Installation distance	38 to 60 mm	56 to 215 mm	220 to 970 mm	32 to 380 mm		
LED class *	Class 2					
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C					
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)					
Weight	Approx. 150 g Approx. 140 g					
Accessories	Mounting bracket (FQ-XL), polari	zing filter attachment (FQ-XF1)	, instruction manual and warning la	bel		

^{*} Applicable standards: IEC62471-2

Intelligent CCD Cameras, Autofocus CCD Cameras

Model	FZ-SLC100	FZ-SLC15	FZ-SZC100	FZ-SZC15			
Image elements	Interline transfer reading all pixels	Interline transfer reading all pixels, 1/3-inch CCD image elements					
Color/Monochrome	Color	Color					
Effective pixels	640 (H) × 480 (V)						
Pixel size	7.4 (μm) × 7.4 (μm)						
Shutter function	Electronic shutter; select shutter	speeds from 1/10 to 1/50,000 s					
Partial function	12 to 480 lines	12 to 480 lines					
Frame rate (image read time)	80 fps (12.5 ms)						
Field of vision *2	13 to 100 mm *1	2.9 to 14.9 mm *1	13 to 100 mm *1	2.9 to 14.9 mm *1			
Installation distance	70 to 190 mm *1	35 to 55 mm *1	77.5 to 197.5 mm *1	47.5 to 67.5 mm			
LED class *3 (lighting)	Class 2		-				
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C (with no icing or condensation)						
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)						
Weight	Approx. 670 g Approx. 700 g Approx. 500 g						
Accessories	Instruction Sheet and hexagonal	wrench					

Tolerance: ±5% max.
The length of the visual field is the lengths along the Y axis.
Applicable standards: IEC62471-2

Ratings and Specifications (LCD Monitor, Cable)

LCD Monitor

Model	FZ-M08
Size	8.4 inches
Туре	Liquid crystal color TFT
Resolution	1,024 × 768 dots
Input signal	Analog RGB video input, 1 channel
Power supply voltage	21.6 to 26.4 VDC
Current consumption	Approx. 0.7 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 1.2 kg
Accessories	Instruction Sheet and 4 mounting brackets

Camera Cables

Model	FZ-VS (2 m) FZ-VSB (2 m) FZ-VSL (2 m)				
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times				
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)				
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)				
Ambient atmosphere	No corrosive gases				
Material	Cable sheath, connector: PVC				
Minimum bending radius	69 mm 69 mm 69 mm				
Weight	Approx. 170 g	Approx. 220 g	Approx. 170 g		

Monitor Cable

Model	FZ-VM
Vibration resistiveness	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -20 to 65 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable sheath: heat-resistant PVC Connector: PVC
Minimum bending radius	75 mm
Weight	Approx. 170 g

Cable Extension Unit

Model	FZ-VSJ
Power supply voltage *1	11.5 to 13.5 VDC
Current con- sumption *2	1.5 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Maximum Units connectable	2 Units per Camera
Weight	Approx. 240 g
Accessories	Instruction Sheet and 4 mounting screws

^{*1} A 12-VDC power supply must be provided to the Cable Extension Unit when connecting the Intelligent Camera, the Autofocus Camera, the Intelligent Compact Camera, the Strobe Controller, or the Lighting Controller.

*2 The current consumption shows when connecting the Cable Extension Unit to an external power supply.

Long-distance Camera Cables

Model	FZ-VS2 (15 m)	FZ-VSL2 (15 m)			
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times				
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)				
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)				
Ambient atmosphere	No corrosive gases				
Material	Cable sheath, connector: PVC				
Minimum bending radius	93 mm				
Weight	Approx. 1600 g				

Parallel Cable

FZ-VP FZ-VPX		
10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times		
Operation: 0 to 50 °C; Storage: -20 to 65 °C (with no icing or condensation)		
Operation and storage: 35 to 85%RH (with no condensation)		
No corrosive gases		
Cable sheath: heat-resistant PVC Connector: resin		
75 mm		
Approx. 160 g Approx. 180 g		
	10 to 150 Hz single amplitude strokes, 4 times Operation: 0 to 50 °C; Storag (with no icing or condensation) Operation and storage: 35 to (with no condensation) No corrosive gases Cable sheath: heat-resistant	

Note: FZ-VP/FZ-VPX is only for the FZ series. The FH series can use XW2Z-S013-2/-S013-5.

Encoder Cable

Model	FH-VR
Vibration resistiveness	10 to 150 Hz single amplitude 0.1 mm 3 directions, 8 strokes, 10 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -10 to 60 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable Jacket: Heat, oil and flame resistant PVC Connector: polycarbonate resin
Minimum bending radius	65 mm
Weight	Approx. 104 g

FH-Series

Cameras / Cables Connection Table

			High-speed CMOS cameras *				
	Model	Cable length	300,000-pixel	2 million-pixel		4 million-pixel	
Type of			FH-SM/SC	FH-SM02/SC02		FH-SM04/SC04	
camera			-	High speed mode of transmission speed select	Standard mode of transmission speed select	High speed mode of transmission speed select	Standard mode of transmission speed select
Camera	FZ-VS FZ-VSL	2 m	Yes	Yes	Yes	Yes	Yes
Cables Right-angle		5 m	Yes	Yes	Yes	Yes	Yes
camera cables		10 m	Yes	No	Yes	No	Yes
Bend resistant	FZ-VSB	2 m	Yes	Yes	Yes	Yes	Yes
camera		5 m	Yes	Yes	Yes	Yes	Yes
cables		10 m	Yes	No	Yes	No	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS2 FZVSL2	15 m	Yes	No	Yes	No	Yes

^{*} High-speed CMOS camera is only for the FH series.

		Cable	Digital CCD cameras		Small digital		Intelligent	Intelligent CCD	
Type of camera			300,000-pixel	2 million-pixel	5 million-pixel	CCD cameras Pen type / flat type	High-speed CCD cameras	compact CMOS cameras	cameras Autofocus CCD cameras
			FZ-S/SC	FZ-S2M/SC2M	FZ-S5M2/ SC5M2	FZ-SF/SFC FZ-SP/SPC	FZ-SH/SHC	FZ-SQ□	FZ-SLC□ FZ-SZC□
Camera Cables		2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Right-angle camera cables	FZ-VS FZ-VSL	5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	Yes	No	Yes	Yes	Yes	No
Bend resistant camera cables	FZ-VSB 5	2 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
		5 m	Yes	Yes	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	Yes	No	Yes	Yes	Yes	No
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS2 FZVSL2	15 m	Yes	Yes	No	Yes	Yes	Yes	No

EtherCAT Communications Specifications

Item		Specifications		
Communications standard		IEC61158 Type 12		
Physical layer		100 BASE-TX (IEEE802.3)		
Modulation		Base band		
Baud rate		100 Mbps		
Topology		Depends on the specifications of the EtherCAT master.		
Transmission Media		Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)		
Transmission Distance		Distance between nodes: 100 m or less		
Node address setting		00 to 9		
External connection terminals		RJ45 × 2 (shielded) IN: EtherCAT input data, OUT: EtherCAT output data		
Send/receive PDO data sizes	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *		
Send/receive PDO data sizes	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *		
Mailbox data size	Input	512 bytes		
IVIAIIDUA UAIA SIZE	Output	512 bytes		
Mailbox		Emergency messages, SDO requests, and SDO information		
Refreshing methods		I/O-synchronized refreshing (DC)		

^{*} This depends on the upper limit of the master.

Version Information

FH Series and Programming Devices

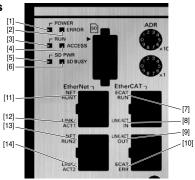
	Required Programming Device			
FH Series	Sysmac Studio Standard Edition/Vision Edition			
	Ver.1.06	Ver.1.07 or higher		
FH-3050 (-□) FH-1050 (-□)	Not supported	Supported		

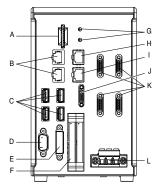
Note: 1. The auto-update to Sysmac Studio version 1.07 will be available soon.

2. Sysmac Studio does not support the FZ5 Series.

Components and Functions

Example of the FH Sensor Controllers
BOX type
(4-camera type)



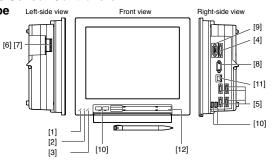


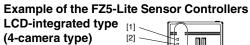
	Name	Description
[1]	POWER LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the controller is in Measurement Mode.
[4]	ACCESS LED	Lit while the memory is accessed.
[5]	SD POWER LED	Lit while power is supplied to the SD card and the card is usable.
[6]	SD BUSY LED	Blinks while the SD memory card is accessed.
[7]	EtherCAT RUN LED	Lit while EtherCAT communications are usable.
[8]	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[9]	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[10]	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.
[11]	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.
[12]	EtherNet NET LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.
[13]	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.
[14]	EtherNet NET LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.

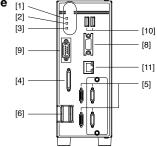
	Name	Description
Α	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.
В	EtherNet connector	Connect an EtherNet device.
С	USB connector	Connect a USB device. Do not plug or unplug it during measurement operation. Otherwise measurement time may be affected or data may be destroyed.
D	RS-232C connector	Connect an external device such as a programmable controller.
Е	DVI-I connector	Connect a monitor.
F	I/O connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.
G	EtherCAT address setup volume	Used to set a node address (00 to 99) as an EtherCAT communication device.
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.
ı	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.
J	Encoder connector	Connect an encoder.
K	Camera connector	Connect cameras.
L	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire the ground line. Be sure to ground the controller alone. Perform wiring using the attached power supply connector.

Example of the FZ5 Sensor Controllers

LCD-integrated type (4-camera type)







	Name	Description
[1]	POWER LED	Lit while power is ON.
[2]	RUN LED	Lit while the controller is in Run Mode.
[3]	ERROR LED	Lit when an error has occurred.
[4]	I/O connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.
[5]	Camera connector	Connect cameras.
[6]	Power	Connect a DC power supply. Wire the power supply unit independently of other devices. After wiring, replace the terminal cover.
[7]	Ground terminal	Connect the ground wire. Make sure that the controller is grounded with a separate ground wire.
[8]	Monitor connector (analog RGB)	Connect a monitor. (Provided with Lite controller type only)
[9]	RS-232C/RS-422 connector	Connect an external device such as a personal computer or PLC.
[10]	USB connector	Connect a track ball, mouse and USB memory. A total of four USB ports are provided and any of them can be used. However, when connecting two or more USB memories, do not connect them to adjacent ports. Doing so may cause the USB memories to come into contact, resulting in malfunction or damage.
[11]	EtherNet connector	Connect the controller to a personal computer.
[12]	Touch pen (holder)	A touch pen is stored. (Provided with the LCD integrated type only)



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