



User Manual S.USV pi solutions

Compatible with S.USV pi basic and S.USV pi advanced

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1 Functions

The S.USV pi solutions is an advanced power supply additional module for Raspberry Pi, with the main focus on the uninterruptible power supply of the single-board computer.

The module also provides additional functions in order to optimize the operation of the Raspberry Pi by the user.

The S.USV pi solutions is a fully functional plug & play solution. The power supply occurs directly through the J8 connector on the Raspberry Pi and therefore uses a common voltage source, thus no additional cabling or power supply needed. In addition, the module is equipped with a LiPo battery. An integrated boost switching power converter covers the necessary voltage range, thereby the Raspberry Pi shut down safely in case of misconduct and prevent data loss.

The “advanced” version also provides a power input for the extended voltage range of 7 – 24 volts (solar cells, automotive applications, etc.).

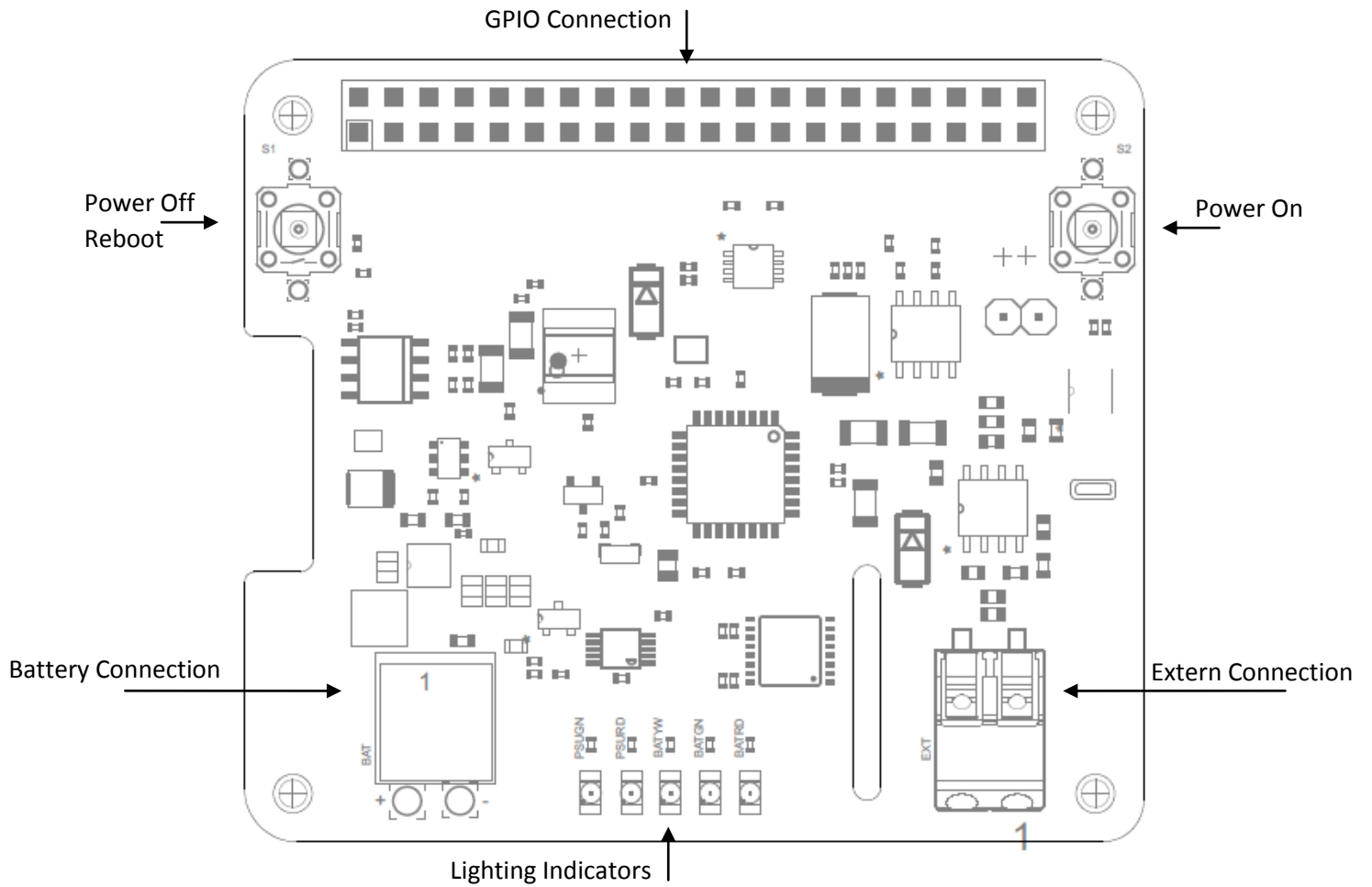
- HAT compliant UPS Module
- Compatible with Pi 2 B, Pi A+, Pi B+
- Adapter solution for Pi Model A and B
- Uninterruptible power supply
- Plug & Play (Power via Raspberry Pi)
- Monitoring – System
- Intelligent software solution including mobile application
- Built-in LiPo battery (300mAh) with intelligent charging function
- Battery Management Controller
- Battery Monitoring System
- Software simulated Real Time Clock with Battery Back-Up
- Time-controlled on and off switching of the Raspberry Pi
- Raspberry Pi
- Supply Switch (Power on and off buttons / File safe shutdown)
- LED – Status display
- Bootloader for Live – Firmware updates
- Power input with extended voltage range of 7-24 volts

2 Technical Specification

| | <i>S.USV pi basic</i> | <i>S.USV pi advanced</i> |
|----------------------------|----------------------------|----------------------------|
| Plug & Play | √ | √ |
| Power Supply | 5 Volts/2000 mA | 5 Volts/2000 mA |
| Extended Voltage Range | x | 7-24 Volts/2000 mA |
| Interfaces | I ² C | I ² C |
| ID EEPROM | √ | √ |
| Monitoring - System | √ | √ |
| Mobile Application | √ | √ |
| LiPo - Battery | √ | √ |
| Battery Management | √ | √ |
| Battery Monitoring | √ | √ |
| Real Time Clock | √ | √ |
| Raspberry Pi Supply Switch | √ | √ |
| Compatibility | Pi 2 Model B, Pi A+, Pi B+ | Pi 2 Model B, Pi A+, Pi B+ |
| Dimensions | 65x56,5 mm | 65x56,5 mm |

| | 300 mAh | 3000 mAh |
|----------------------------|--|--|
| Normal Voltage | 3.7V | 3.7V |
| Working Voltage | 3.0 - 4.2 V | 3.0 - 4.2 V |
| Capacity | 300mAh | 3000mAh |
| Internal Impedance | ≤130mΩ | ≤45mΩ |
| Constant Discharge Current | 0.2C(Standard) 1C(Max) | 0.2C(Standard) 1C(Max) |
| Working Temperature | charge: 0-45°C; discharge: -20-60°C | charge: 0-45°C; discharge: -20-60°C |
| Connector | JST-XH-2P | JST-XH-2P |
| Leadwire | UL1571#28 / 50mm | UL1571#28 / 50mm |
| Wrapping Way | blue PVC | blue PVC |
| Line Drawn Out Direction | Center | Center |
| Dimensions | 30.5 x 20.5 x 6.0 mm | 60.5 x 48,5 x 9.0 mm |

2.1 Overview



2.2 Performance

- **Battery Connection:** Connector for connecting the supplied LiPo battery.
Battery Connector: (Würth Elektronik 620 002 113 322)
- **Extern Connection:** Connector for connecting extended voltage range (7-24V).
- **GPIO PORT:** GPIO Connection to the Raspberry Pi.
- **Power Off / Reboot:** Press for reboot or hold at least 3 seconds for shutdown.
- **Power On:** Press for booting the Raspberry Pi.
- **Lighting Indicators:** LED status indicator for the S.USV / Raspberry Pi.

2.3 Lighting Indicators

| LED | Indication |
|----------------------|--|
| PSU GREEN (Blinking) | Startup - initialization of the S.USV firmware |
| PSU GREEN | RPi Power Supply Unit is online (Voltage present) |
| PSU RED | RPi Power Supply Unit is offline (Voltage loss) – Battery Powering is online |
| BAT YELLOW | Charging Circuit Online – Battery is charging |
| BAT GREEN | Charging Circuit Online – Battery is fully charged |
| BAT RED | Charging Circuit Offline – Battery is missing or corrupt |
| BAT RED (Blinking) | Charging Circuit Offline – Remaining battery capacity in the critical area |

3 Installation Guide

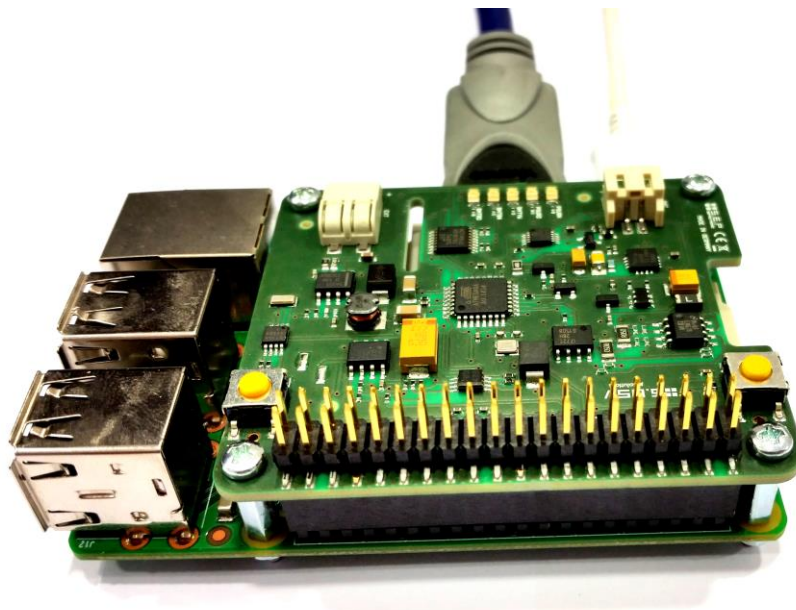
3.1 Hardware

In initial operation we recommend to fully charge the supplied battery to ensure full functionality. Furthermore, we recommend a PSU with at least 2 amps to operate the Raspberry Pi.

In the following steps the commissioning of the S.USV will be described again in detail:

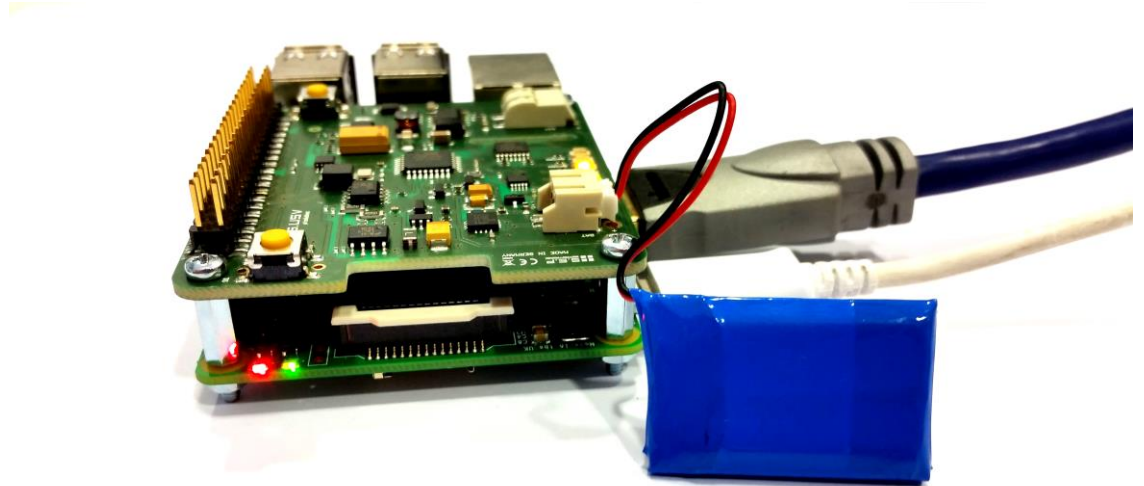
3.1.1 Commissioning S.USV

- The primary power supply of the S.USV occurs via the GPIO port - Pin 2 (+5V) of the Raspberry Pi. Please now connect the board as shown on the RPi to establish the necessary connection and secure it with the included mounting kit.



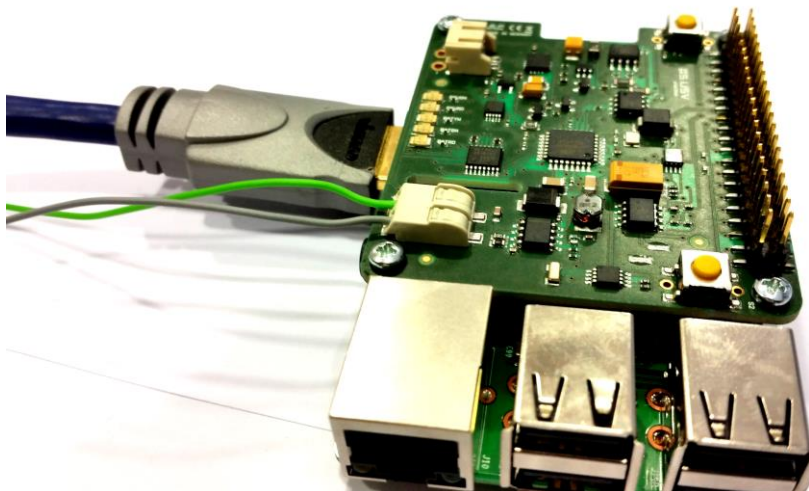
3.1.2 Connecting the battery

- For initial operation please make sure that the included LiPo-battery is plugged into the provided JST connector on the front side of the board.



3.1.3 Connecting the external power supply

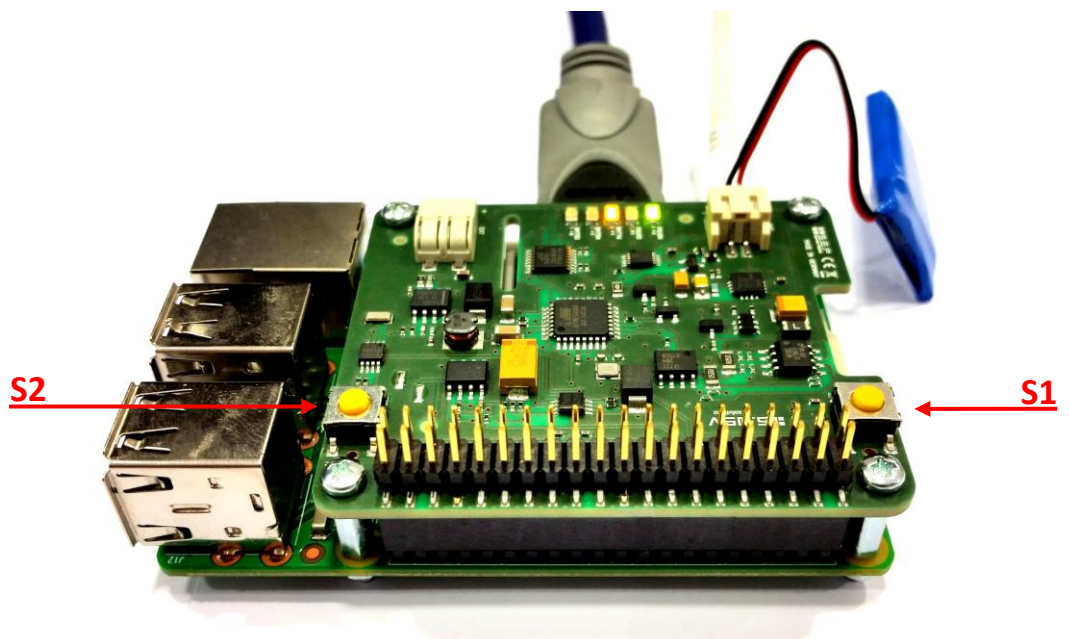
- For usage of the wide-range input the shown terminal block is located on the front side of the board. Please note here the +/- marking on the board in order to avoid a short circuit.



3.1.4 Using the buttons

- For Power on, Power off and restart of the Raspberry Pi, the following buttons are available:
 - **S1** : Power Off / Reboot
 - **S2** : Power On

Both buttons have corresponding vias, thus they can be performed at any point of a housing.



3.1.5 GPIO – Port

- For the power supply and data transmission of the S.USV following GPIO - Pins in use:
 - **Pin #02:** DC Power +5V – Power supply
 - **Pin #03:** GPIO 02 (SDA1, I²C) – I²C data line
 - **Pin #05:** GPIO 03 (SCL1, I²C) – I²C clock line
 - **Pin #13:** GPIO 27 (GPIO_GEN2) – Monitoring S.USV
 - **Pin #27:** ID_SD (I²C ID EEPROM) – ID data line
 - **Pin #28:** ID_SC (I²C ID EEPROM) – ID clock line

3.2 Software

(Note: The current software has been optimized specifically for Raspbian. In the next few weeks further versions for all common operating systems will be available.)

3.2.1 Raspbian

- To install and configure the Raspberry Pi, we recommend the Quick Start Guide of Raspberry Pi directly:

<https://www.raspberrypi.org/help/quick-start-guide/>

- To install the operating system, we recommend the Image Installation Guides of Raspberry Pi:

<https://www.raspberrypi.org/documentation/installation/installing-images/>

- The Image of Raspbian operating system can be found on the following page:

<https://www.raspberrypi.org/downloads/>

3.2.2 I2C

The ID EEPROM contains data that identifies the board, tells the Raspberry Pi how the GPIOs need to be set up and what hardware is on the board. This allows the S.USV *pi solutions* to be automatically identified and set up by the Pi software at boot time including loading all the necessary drivers.

Users of previous models A and B please follow the manual instructions:

- The communication between the S.USV and the Raspberry Pi happens via the I2C - interface, please activate and configure this first using the following steps:

1. First you have to install the relevant I2C-Tools to be able to see which devices are connected to your Raspberry Pi. To do this, you have to enter the following commands in the Terminal to install the i2c-tools utility:

sudo apt-get install python-smbus

```
pi@raspberrypi ~ $ sudo apt-get install python-smbus
Reading package lists... Done
Building dependency tree
Reading state information... Done
```

sudo apt-get install i2c-tools

```
pi@raspberrypi ~ $ sudo apt-get install i2c-tools
Reading package lists... Done
Building dependency tree
Reading state information... Done
```

2. Next you will need to open LXTerminal or console or SSH and enter the following command:

sudo nano /etc/modules

and add these two lines to the end of the file

i2c-bcm2708

i2c-dev

```
GNU nano 2.2.6 File: /etc/modules
# /etc/modules: kernel modules to load at boot time.
#
# This file contains the names of kernel modules that should be loaded
# at boot time, one per line. Lines beginning with "#" are ignored.
# Parameters can be specified after the module name.
snd-bcm2835
i2c-dev
i2c-bcm2708
rtc-ds1307
```

Then save the file with **Control-X Y <return>**

3. Depending on your Distribution, you may also have a file called ***/etc/modprobe.d/raspi-blacklist.conf***

If you do not have this file, then there is nothing to do, however, if you have this file, you have to edit and comment out the lines below by putting a # in front of them:

blacklist spi-bcm2708

blacklist i2c-bcm2708

Open an Editor on the file by typing:

sudo nano /etc/modprobe.d/raspi-blacklist.conf

```
GNU nano 2.2.6 File: /etc/modprobe.d/raspi-blacklist.conf
#blacklist spi-bcm2708
#blacklist i2c-bcm2708
```

then edit the file as described above and then save and exit the file using **Control-X Y <return>**

4. If you are running a recent Raspberry Pi (3.18 kernel or higher) you will also need to update the ***/boot/config.txt*** file. Edit it with ***sudo nano /boot/config.txt*** and add the following lines to the bottom of the file:

dtparam=i2c1=on
dtparam=i2c_arm=on

```
GNU nano 2.2.6 File: /boot/config.txt
# uncomment if hdmi display is not detected and composite is being output
#hdmi_force_hotplug=1
# uncomment to force a specific HDMI mode (this will force VGA)
#hdmi_group=1
#hdmi_mode=1
# uncomment to force a HDMI mode rather than DVI. This can make audio work
# DMT (computer monitor) modes
#hdmi_drive=2
# uncomment to increase signal to HDMI, if you have interference, blanking,
# no display
#config_hdmi_boost=4
# uncomment for composite PAL
#sdtv_mode=2
#uncomment to overclock the arm. 700 MHz is the default.
#arm_freq=800
# Uncomment some or all of these to enable the optional hardware interfaces
#dtparam=i2c_arm=on
#dtparam=i2s=on
#dtparam=spi=on
# Uncomment this to enable the lirc-rpi module
#dtoverlay=lirc-rpi
# Additional overlays and parameters are documented /boot/overlays/README
dtparam=i2c1=on
dtparam=i2c_arm=on
```

5. Once, the steps above are done, reboot the system by using the command ***sudo reboot***

- Now, when you log in, you can use the following command to see all the connected devices:

sudo i2cdetect -y 1

```
pi@raspberrypi ~ $ sudo i2cdetect -y 1
   0  1  2  3  4  5  6  7  8  9  a  b  c  d  e  f
00:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
10:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
20:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
30:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
40:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
50:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
60:  --  --  --  --  --  --  --  --  UU  --  --  --  --  --  --  --
70:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
```

This shows, that two I2C-Addresses are in use – 0x0F for the S.USV and 0x68 for the Real Time Clock located on the S.USV.

Note, that if you are using one of the first Raspberry Pis, you will have to change the command to ***sudo i2cdetect -y 0***

3.2.3 S.USV

- Please download the provided debian package from our download section and save it to any local memory address on your Raspberry Pi.
- To install the Debian package on your Raspberry Pi switch to directory in which the debian package is located and perform the following commands in the command line.

sudo tar -xvzf susvd-en-x.x-all.tar.gz (to unzip the tar file)

sudo dpkg -i susvd-en-x.x-all.deb (to install the debian package)

```
pi@raspberrypi ~ $ cd /home/pi/S.USV-Install/
pi@raspberrypi ~/S.USV-Install $ ls
susvd-en-1.1-all.deb
pi@raspberrypi ~/S.USV-Install $ sudo dpkg -i susvd-en-1.1-all.deb
```

- The S.USV Client and Daemon are now fully installed and ready for use. (The installed files are located in the following path: ***/opt/susvd***)

- In case of a successful installation, change to the directory **/opt/susvd** and run the following command as superuser to start the daemon and ensure proper work of the S.USV (Refer to section 4 for a description of all the commands):

sudo ./susvd -start

```
pi@raspberrypi ~ $ cd /opt/susvd
pi@raspberrypi /opt/susvd $ sudo ./susvd -start
S.USV Daemon started..
pi@raspberrypi /opt/susvd $ █
```

The correct start of the Daemon will be shown in the console output.

- If everything is done, you can use the full functionality of the S.USV.

3.2.4 RTC – Real Time Clock

The integrated real-time clock is a useful addition to the Raspberry Pi. For existing Ethernet connection the current time synchronizes via the NTP (Network Time Protocol) service. In various scenarios the connection to a network is not possible. This may be the case in the car, at a solar or wind turbine or even when using the RPi in the control cabinet. With the use of the real time clock, the system time is kept up to date even when there is no network connection.

The ID EEPROM on the board configures the RTC module automatically.

(Note: Refer to point 2 to set up the current time.)

Users of previous models A and B please follow the manual instructions:

- Please verify that the chip module is seen by running ***sudo i2cdetect -y 1*** (*i2cdetect -y 0* for old Rev. 1 Pi) at the command line. The DS1307 Real Time Clock should be located at the I2C address ID #68.

- Load the RTC module by running ***sudo modprobe rtc-ds1307*** in the kernel. The following commands should be running as super user.

For a Rev. 2 Pi or later:

```
echo ds1307 0x68 > /sys/class/i2c-adapter/i2c-1/new_device
```

For the older Rev.1 Pi:

```
echo ds1307 0x68 > /sys/class/i2c-adapter/i2c-0/new_device
```

- Now check the time on the RTC device using:

sudo hwclock -r

```
pi@raspberrypi ~ $ sudo hwclock -r
Mon 19 Oct 2015 13:33:23 CEST -0.885224 seconds
```

If this is the first use of the RTC, it will report back Jan 1 2000.

Please configure now the current time and then conform with:

sudo hwclock -w

to write the system time to the RTC module.

- To set up the Raspberry Pi using the Real Time Clock, you will need to add the RTC module chip to the file ***/etc/modules***.

- Go into the terminal window and run:

sudo nano /etc/modules

Then add ***rtc-ds1307*** at the end of the file.

```
GNU nano 2.2.6 File: /etc/modules
# /etc/modules: kernel modules to load at boot time.
#
# This file contains the names of kernel modules that should be loaded
# at boot time, one per line. Lines beginning with "#" are ignored.
# Parameters can be specified after the module name.
snd-bcm2835
i2c-dev
i2c-bcm2708
rtc-ds1307
```

- Next step is to add the DS1307 device creation at boot by editing the file ***/etc/rc.local***

Run ***sudo nano /etc/rc.local***

and add the following lines to the end of the file:

```
echo ds1307 0x68 > /sys/class/i2c-adapter/i2c-1/new_device
sudo hwclock -s
date
```

```
GNU nano 2.2.6 File: /etc/rc.local
#!/bin/sh -e
#
# rc.local
#
# This script is executed at the end of each multiuser runlevel.
# Make sure that the script will "exit 0" on success or any other
# value on error.
#
# In order to enable or disable this script just change the execution
# bits.
#
# By default this script does nothing.
#
# Print the IP address
_IP=$(hostname -I) || true
if [ "$_IP" ]; then
    printf "My IP address is %s\n" "$_IP"
fi
echo ds1307 0x68 > /sys/class/i2c-adapter/i2c-1/new_device
sudo hwclock -s
date
exit 0
```

To save the file, press Ctrl+X, Y then return.

4. The next time you reboot your Raspberry Pi it will read the current time from the Real Time Clock on the S.USV.

4 Client Software

Communication between S.USV and the Raspberry Pi via the I2C interface at the address 0x0F. In principle the software package of the S.USV consist of two tools:

1. The S.USV Daemon (susvd), which monitors and controls the S.USV by constantly reading the S.USV status and reacting on several events. The S.USV Daemon will be started once and is running in the background.
2. The S.USV Client (susv), which gives the user the possibility to get and see the actual status of the S.USV as well as to control the S.USV, e.g. activating or deactivating the charging circuit. The S.USV-Client is also responsible for editing the config-variables of the S.USV Daemon, eg. Shutdown timer.

4.1 S.USV – Daemon

The S.USV daemon is responsible for monitoring and controlling the S.USV in conjunction with the Raspberry Pi.

The S.USV daemon creates a log in the file: ***/var/log/susvd.log***

The following sections will be shown the individual options.

4.1.1 Daemon Configuration

To configure the S.USV Daemon change to the directory ***/opt/susvd*** and execute the following commands as superuser:

sudo ./susv -timer <time in seconds>

(Default Wert = 10)

This value indicates how long the system continues to run before the filesafe shutdown will be initiated by the S.USV after the voltage supply is switched to battery.

Values “>=0” are possible.

```

pi@raspberrypi ~$ sudo ./susv -timer 60
*****
*                               *
* S.USV pi solutions           *
* www.s-usv.de                 *
*                               *
* Model: Advanced              *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:40:26 2015     *
*                               *
*****
* Shutdown timer set to: 60    *
*                               *
* Please restart S.USV Daemon *
*                               *
*****

```

This function can be disabled by the value “-1”.

In this case, the Raspberry Pi remains running, until the Battery Capacity reaches 10%. From that point on, the S.USV will automatically perform a filesafe shutdown in order to prevent the battery from getting damaged.

sudo ./susv -auto <0/1>

(Default Wert = 1)

This value determines the starting behavior of the S.USV Daemon. The value "1" activates the autostart, the value "0" disables the autostart.

```
pi@raspberrypi ~ $ sudo ./susv -auto 1
*****
*
* S.USV pi solutions *
* www.s-usv.de *
*
* Model: Advanced *
* Firmware Version: 1.1 *
* Software Version: 1.1 *
*
* Charging current: 300 mA *
*
* Mon Oct 19 13:41:08 2015 *
*
*****
* Autostart enabled *
*
* Please restart S.USV Daemon *
*
*****
```

If the autostart is disabled, please notice that you have to start the S.USV-Daemon manually in order for the S.USV to work correctly.

sudo ./susv -sleep <time in seconds>

(Default Wert = 1)

This value determines the repetition in which the S.USV Daemon monitors and controls the voltage output of the S.USV. Values ">=0" are possible.

```
pi@raspberrypi ~ $ sudo ./susv -sleep 1
*****
*
* S.USV pi solutions *
* www.s-usv.de *
*
* Model: Advanced *
* Firmware Version: 1.1 *
* Software Version: 1.1 *
*
* Charging current: 300 mA *
*
* Mon Oct 19 13:42:33 2015 *
*
*****
* Sleep timer set to: 1 *
*
* Please restart S.USV Daemon *
*
*****
```

4.1.2 Daemon Controlling

To control the S.USV Daemon change to the directory ***/opt/susvd*** and execute the following commands as superuser:

sudo ./susvd -start

Starts the S.USV Daemon Service and its configuration.

sudo ./susvd -stop

Stops the S.USV Daemon Service.

sudo ./susvd -restart

Restarts the S.USV Daemon Service.

4.2 S.USV – Client

The S.USV Client allows the user state monitoring and function control of the S.USV.

The following sections will be shown the individual options.

4.2.1 Client Options

To control the S.USV Client change to the directory ***/opt/susvd*** and execute the following commands:

./susv -help

This command shows all possible options.

./susv -chrgon

Switch charging circuit on.

Allows the manual switching of the battery's charging circuit.

```
pi@raspberrypi ~ $ ./susv -chrgon
*****
*                               *
* S.USV pi solutions            *
* www.s-usv.de                 *
*                               *
* Model: Advanced              *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:47:10 2015     *
*                               *
*****
*                               *
* Charging circuit: Online     *
*                               *
*****
```

(Note: The configuration of the charging circuit is stored in EEPROM and reloaded at system startup.)

./susv -chrgoff

Switch charging circuit off.

Allows the manual shutdown of the battery's charging circuit.

```
pi@raspberrypi ~ $ ./susv -chrgoff
*****
*                               *
* S.USV pi solutions            *
* www.s-usv.de                 *
*                               *
* Model: Advanced              *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:47:58 2015     *
*                               *
*****
*                               *
* Charging circuit: Offline    *
*                               *
*****
```

(Note: The configuration of the charging circuit is stored in EEPROM and reloaded at system startup.)

./susv -vin

Read input voltage.

With this command it is possible to check the current input voltage.

```
pi@raspberrypi ~ $ ./susv -vin
*****
*                               *
* S.USV pi solutions           *
* www.s-usv.de                 *
*                               *
* Model: Advanced              *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:48:16 2015     *
*                               *
*****
*                               *
* Voltage in: 4.91 V           *
*                               *
*****
```

./susv -pwrext

Read the external power consumption.

With supply via the external voltage input, the current external power consumption can be checked by this command.

```
pi@raspberrypi ~ $ ./susv -pwrext
*****
*                               *
* S.USV pi solutions           *
* www.s-usv.de                 *
*                               *
* Model: Advanced              *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:48:40 2015     *
*                               *
*****
*                               *
* Power Extern: 492.05 mA      *
*                               *
*****
```

./susv -pwrbat

Read the battery power consumption.

With supply via battery, the current battery power consumption can be checked by this command.

```
pi@raspberrypi ~ $ ./susv -pwrbat
*****
*                               *
* S.USV pi solutions           *
* www.s-usv.de                 *
*                               *
* Model: Advanced               *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:49:55 2015     *
*                               *
*****
*                               *
* Power Battery: 492.05 mA     *
*                               *
*****
```

./susv -capbat

Read battery capacity.

This command allows to read the current battery voltage and the remaining battery capacity.

```
pi@raspberrypi ~ $ ./susv -capbat
*****
*                               *
* S.USV pi solutions           *
* www.s-usv.de                 *
*                               *
* Model: Advanced               *
* Firmware Version: 1.1        *
* Software Version: 1.1        *
*                               *
* Charging current: 300 mA     *
*                               *
* Mon Oct 19 13:50:48 2015     *
*                               *
*****
*                               *
* Battery capacity: 100.00%    *
* Battery voltage: 4.20V      *
*                               *
*****
```

(Note: A remaining capacity of <25% is indicated by the LED BATRD. At a remaining capacity of <10% the Raspberry Pi will automatically shut down.)

sudo ./susv -chrgpwr <300/500/1000>

(Please use this command as superuser)

Change the charge current for the battery.

Use this command to change the active charge current for the battery. In order to minimize the charging time following current strengths are available.

- 300mA
- 500mA
- 1000mA

```

pi@raspberrypi ~ $ sudo ./susv -chrgpwr 1000
*****
* S.USV pi solutions *
* www.s-usv.de *
* *
* Model: Advanced *
* Firmware Version: 1.1 *
* Software Version: 1.1 *
* *
* Charging current: 1000 mA *
* *
* Mon Oct 19 13:51:33 2015 *
* *
*****
* Charging current: 1000 mA *
* *
*****

```

(Note: The configured charging current is stored in EEPROM and reloaded at startup.)

./susv -flash <path to HEX file>

Upgrade the firmware.

Use this command to upgrade the actual firmware.

```

pi@raspberrypi ~ $ ./susv -flash /home/pi/S.USV-Install/susv_fw_11.hex
device      : /dev/i2c-1 (address: 0x30)
version     : TWIBOOT m8v2.1 (sig: 0x1e 0x93 0x07 => AVR Mega 8)
flash size  : 0x1c00 / 7168 (0x40 bytes/page)
eeprom size : 0x0200 / 512
writing flash : [*****] (4228)
pi@raspberrypi ~ $

```

sudo ./susv -chgadd <0x.>

(Default Adresse = 0x0f)

(Please use this command as superuser)

Change the I2C address of the S.USV.

To avoid potential compatibility issues, use this command to change the I2C address of the S.USV. Verify the address by typing ***i2cdetect -y 1*** in the terminal.

```
pi@raspberrypi ~ $ sudo ./susv -chgadd 0x32
*****
*
* S.USV pi solutions
* www.s-usv.de
*
* Model: Advanced
* Firmware Version: 1.1
* Software Version: 1.1
*
* Charging current: 300 mA
*
* Mon Oct 19 13:53:49 2015
*
*****
*
* I2C-Address set to: 0x32
*
* Please restart S.USV Daemon
*
*****
pi@raspberrypi ~ $ cd /opt/susvd/
pi@raspberrypi /opt/susvd $ sudo ./susvd -restart
S.USV Daemon stopped!
S.USV Daemon started..
pi@raspberrypi /opt/susvd $ i2cdetect -y 1
   0  1  2  3  4  5  6  7  8  9  a  b  c  d  e  f
00:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
10:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
20:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
30:  --  --  32  --  --  --  --  --  --  --  --  --  --  --  --
40:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
50:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
60:  --  --  --  --  --  --  --  UU  --  --  --  --  --  --  --
70:  --  --  --  --  --  --  --  --  --  --  --  --  --  --  --
```

(Note: The configured I2C address is stored in EEPROM and reloaded at startup.)

./susv -status

Read S.USV status.

This command allows to read the S.USV status. Here of all available modes are indicated as well as the current powering source and its power consumption.

```
pi@raspberrypi ~ $ ./susv -status
*****
*                                     *
* S.USV pi solutions                 *
* www.s-usv.de                       *
*                                     *
* Model: Advanced                    *
* Firmware Version: 1.1              *
* Software Version: 1.1              *
*                                     *
* Charging current: 300 mA           *
*                                     *
* Mon Oct 19 13:59:07 2015          *
*                                     *
*****
*                                     *
* Powering Source: Battery           *
* Charging circuit: OFFLINE          *
*                                     *
* Voltage in: 4.95 V                 *
* Battery capacity: 57.94%           *
* Battery voltage: 3.95V             *
* Power Battery: 501.81 mA           *
* Power Extern: n/a                  *
*                                     *
* Shutdown timer: -1                 *
* Autostart: enabled                 *
* Sleep timer: 1                     *
*                                     *
*****
```

