GRT HORIZON

Models HX, HS & WS

Set Up & Configuration Guide

Rev. A February 2009

Grand Rapids Technologies, Inc.
3133 Madison Avenue SE
Wyoming MI 49548
616-245-7700
www.grtavionics.com

INTENTIONALLY BLANK

FORWARD

Welcome to Grand Rapids Technologies' GRT Horizon! We are pleased that you have chosen our product to meet your flying needs.

Visit the Grand Rapids Technologies (GRT) website (www.grtavionics.com) for the latest updates and supplemental information concerning the operation of this and other GRT products.

This manual describes the operation of GRT Horizon EFIS using the software version shown in the Record of Revisions. Some differences may be observed when comparing the information in this manual to other software versions. Every effort has been made to ensure that the information in this manual is accurate and complete. GRT is not responsible for unintentional errors or omissions in the manual or their consequences.

Copyright © 2001 - 2009 Grand Rapids Technologies or its subsidiaries. All rights reserved.

Information in the document is subject to change without notice. Grand Rapids Technologies reserves the right to change or improve their products and to make changes in the content of this material without obligation to notify any person or organization of such changes or improvements.

CAUTIONS

WARNING: Obstacle clearance is not assured in Synthetic Approach Mode.

WARNING: Various functions of this system may be incomplete or untested. Please exercise caution when using the EFIS until a software update and a user manual corresponding to the software version are provided.

CAUTION: If any display unit is inoperable, the display units will not be able to swap information. The pilot must account for this down-graded mode of operation and not expect data will transfer between displays.

CAUTION: If GPS position data is lost for more than 30 seconds, the EFIS Horizon issues a **No GPS Position** warning and automatically reverts to dead-reckoning using the AHRS heading, true airspeed, last known winds and time. This data is used to estimate changes in position, which are applied to the last known GPS position to give an approximate navigation solution. The accuracy of the dead-reckoning function will degrade with time depending on the accuracy of this data and changes in the winds.

CAUTION: When the ground track indicator is hollow, indicating it is display limited, the ground track indicated is necessarily inaccurate. This means the aircraft's track over

the ground is not as indicated and regard to obstacle and terrain clearar	the pilot	should	be a	aware	of t	his	inaccuracy	with
GRT Horizon Set Up Guide A	ŗ	og. iv					F	Rev

RECORD OF REVISIONS

Rev	Date	SW Rev	Change(s)
Α	Feb 2009	32a	Initial Release

LIST OF EFFECTIVE PAGES

| Page Rev |
|----------|----------|----------|----------|----------|----------|----------|
| iA | iiA | iiiA | ivA | vA | viA | |
| 1-1A | 1-2A | | | | | |
| 2-1A | 2-2A | 2-3A | 2-4A | 2-5A | 2-6A | 2-7A |
| 2-8A | 2-9A | 2-10 A | 2-11 A | | | |
| 3-1A | 3-2A | 3-3A | 3-4A | 3-5A | 3-6A | 3-7A |
| 4-1A | 4-2A | | | | | |
| 5-1A | 5-2 A | 5-3A | 5-4A | 5-5A | 5-6A | 5-7A |
| 5-8A | | | | | | |
| 6-1A | 6-2A | 6-3A | 6-4A | 6-5A | 6-6A | 6-7A |
| 7-1A | 7-2A | | | | | |
| 8-1A | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |
| | | | | | | |

Chapter 1 INTRODUCTION	1-1
Chapter 2 GENERAL SETUP	2-1
Serial Port Settings	2-9
Adjusting Autopilot Response	2-9
Chapter 3 PRIMARY FLIGHT DISPLAY	3-1
Chapter 4 MOVING MAP SETUP	4-1
Chapter 5 GRAPHICAL ENGINE DISPLAY SETUP	5-1
Chapter 6 ENGINE LIMITS	6-1
Chapter 7 DISPLAY UNIT MAINTENANCE	7-1
Load EFIS Software	7-1
Chapter 8 AHRS MAINTENANCE	8-1
AHRS Software Version	8-1
Load AHRS Software	8-1
True Airspeed Corrections	8-1
Altimeter Calibration	8-1
Angle of Attack Calibration	8-1

Chapter 1 INTRODUCTION

The Settings Menu is provided to configure your GRT Horizon EFIS for your preferences and to setup interfaces to other equipment in your aircraft. This manual is intended to assist you in using the Settings Menu.

When you have completed configuring your GRT Horizon, you may want to backup the settings to a USB flash drive (memory stick). This is done on the Display Unit Maintenance page and must be done for each Display Unit.

The pages in the Settings Menu are:

General Setup
Primary Flight Display
Moving Map
Graphical Engine Display
Engine Limits
Display Unit Maintenance
AHRS Maintenance
Altimeter Calibration

They are to be setup on each unit.

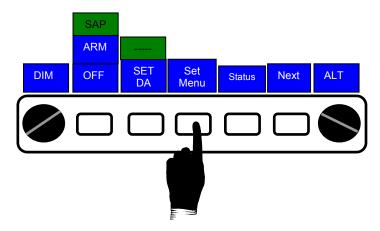
All user settings are stored in non-volatile memory, and thus are not lost when power is removed from the DU. The data is stored with error detection algorithms to detect loss or changes to the data caused by memory failure. All user settings are retained when software is upgraded. When software upgrades result in new user settings becoming available, these settings will default to the values described in the revised Users Guide issued with the software upgrade.

How to Access the Settings Menus

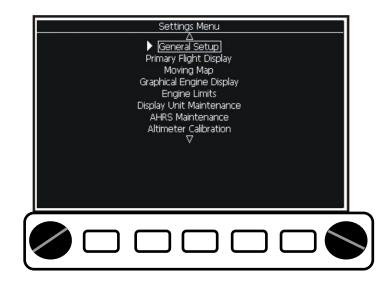
To access Settings Menu:

1. Press any button

- 2. Press button labeled **NEXT** (more than once may be required)
- 3. Press button labeled **SET MENU**
- 4. Scroll (either knob) to desired menu
- 5. Press knob to select



Press Set MENU



Scroll to desired menu Press knob to select

To change a setting. Note that the box around the setting is dim. Push either knob. The box will become bright to indicate you are in change mode. Rotate either knob to view the choices.

GRT Horizon Set Up Guide

pg. 1-1 Rev A

When the desired choice is in the box will return to dim. window, push either knob to select. The

Chapter 2 GENERAL SETUP

General Setup configures the serial ports which are used to communicate between display units and other installed equipment; units of measure and other interface items. **General Setup must be configured on each DU**. Usually there are differences between DUs.

This table shows suggested values and gives explanation for each parameter:

Setting	Selection	Suggested Value
Inter-Display Link	Auto/Primary/2/3/4	Set one display unit to "Primary", all others to "AUTO". The numeric entries force the display unit to a particular "address", and may be useful for troubleshooting, but should otherwise not be used.
Valid Frames Received	None	Will be continuously changing when the inter-display unit link is operating correctly. (Not a user setting.)
Compare Limits	Yes/No	"Yes" allows the display units to compare limits, and prompt you to correct mis-matching limits between display units. Normally limits are automatically transmitted between display units when updated by the pilot.
Send EIS Data	Yes/No	Select "Yes" only if a other display units do not have EIS wired to them.
Send Analog Inputs	Yes/No	Select "Yes" only if a display unit has analog inputs wired to it that other display units do not have.
Send SL30-1 Data	Yes/No	Select "No" unless another display unit is not provided with SL30-1 serial data. Normally all display units should be wired to the SL30-1 serial data output.
Send SL30-1 Commands	Yes/No	Select "Yes" if an SL30 is used as nav/com radio 1, and a different display unit is providing the serial output to the radio.
Send SL30-2 Data	Yes/No	Select "No" unless another display unit is not provided with SL30-2 serial data. Normally all display units should be wired to the SL30-2 serial data output.
Send SL30-2 Commands	Yes/No	Select "Yes" if an SL30 is used as nav/com radio 2, and a different display unit is providing the serial output to the radio.
Send SL40 Commands	Yes/No	Select "Yes" if an SL40 is used

Setting	Selection	Suggested Value
		as a com radio, and a different display unit is providing the serial output to this radio.
Send GPS Data	Yes/No	Select "No" unless another display unit is not provided with GPS serial data. Normally all display units should be wired to the GPS serial data output.
Send ARINC Data	Yes/No	Set to "Yes" only if this display unit includes an ARINC 429 module, and other display units do not include this module.
Send Zaon & GTX330 Data	Yes/No	Set to "Yes" only if this display unit is wired to Zaon or GTX330 and other display units are not.
Send DEMO Data	Yes/No	"Yes" is preferred, as it allows all display units to show the demo data being re-played from any other display unit.
ARINC Module Connected	Yes/No	This setting is required to be YES if the EFIS Horizon has an ARINC-429 Module installed. This setting will also show the autopilot gains at the bottom of this page when selected. If YES, the Receive and Transmit setting must be set to the same setting as the radio unit installed, ie. GNS 430, etc. The ARINC Input Counter counts
Serial Port 1, 2, 3, 4, 5, 6 Rate	110 / 300 / 600 / 1200 / 2400 / 4800 / 9600 / 14400 / 19200 / 38400 / 56000 / 57600 / 115200 / 128000 / 256000	packets received from the ARINC module and is useful for troubleshooting. Depends on use All serial ports can be configured for any of the functions listed below. The function of the port, and the baud rate, must be set to correspond to the equipment wired to the port.
		Note that the baud rate selection sets both input and output of each Serial Port. On a given Serial Port, the In and Out cannot have different baud rates. On HS & WS DUs. Only Serial Port
Serial Port 1, 2, 3, 4, 5, 6 Input	Off / AHRS 1 or 2 / EIS / GPS 1 or 2 NMEA 0183 Global Positioning / GPS 1 or 2 Aviation Map Com / SL30 1 or 2 / SL40 / Display Unit Interlink / XM Weather / Zaon Traffic / CO Guardian / GTX330 Traffic	1 & 2 are high speed. On HX DUs, all Serial Ports are high speed. Used to assign functions to specific Serial Ports Off Unused ports should be set to Off. AHRS 1 or 2 Used to communicate to the AHRS via RS232 format (19200 baud)

Setting	Selection	Suggested Value
		EIS (Engine Monitor)
		Used to accept data from EIS via RS232 format (9600 baud)
		NMEA 0183 GPS 1 or 2 Used to accept GPS data via NMEA0183 data format. Used to interface to internal GRT or hand held GPS if equipped. (4800 or 9600 baud – depends on GPS receiver)
		GPS 1 or 2 Aviation/MapCom Used to accept GPS data via RS232 Aviation format from panel mount GPS (9600 baud)
		SL-30/SL-40 1 or 2 Used to accept data from a SL-30 / SL-40 via RS232 format (9600 baud)
		Display-Unit Link Used to connect to other display units via RS232 format (19200 baud)
		Weather (must be Serial Port 1 or 2 HS & WS DUs) Used to accept XM Weather data via RS232 format (115200 baud)
		Zaon PCAS XRX Used to accept traffic data via RS232 format (57600 baud)
		CO Guardian Used to accept CO warning data via RS232 format (9600 baud)
		GTX 330 Used to accept traffic data via RS232 format from GTX330 or Zaon(9600 baud)
Serial Port 1, 2,3, 4 Output	Off / Autopilot NMEA 0183 / Autopilot Aviation / AHRS 1 or 2 / Fuel/Air Data	Used to assign functions to specific Serial Ports
	(Z Format) / Fuel/ Air Data (S Format) / Fuel/Air Data (D Format) / Alt Encoder 1 or 2 / SL30 1 or 2 / SL40 / GPS 1 or 2 NMEA 0183 /	Off Unused ports should be set to Off.
	Display Unit Interlink / XM Weather / CO Guardian	Autopilot NMEA 0183 format For controlling autopilots that accept NMEA 0183 data. If Autopilot
		accepts both RS 232 Aviation/MapCom and NMEA 0183 format, this format is preferred.(4800 or 9600 buad GPS dependent)
		Autopilot RS232 Aviation/MapCom format For controlling autopilots that accept RS232 Aviation data, typically those designed to interface to panel mount GPS (9600 baud)

Setting	Selection	Suggested Value
		AHRS 1 or 2 Used to communicate to the AHRS via RS232 format (19200 baud)
		Fuel/Air Data (Z Format) Provides fuel flow, fuel totalizer airspeed and altitude data output. If the equipment receiving this data does not accept it, try the "S" and "D" formats. (9600 baud)
		Fuel/Air Data (S Format)
		Fuel/Air Data (D Format)
		Altitude Encoder 1 or 2 Configures output format of altitude encoding data. Format is determined by Altitude Encoder Setting (see below)
		SL-30 1 or 2 Provides tuning and frequency present for communication and navigation radio functions to SL-30 1 or 2. (9600 baud)
		SL40 Provides tuning and frequency present for communication radio functions to SL-40 (9600 baud)
		GPS NMEA 0183 1 or 2 Used to interface to internal GRT GPS, if equipped.
		Display-Unit Link Used to connect to other display units via RS232 format (19200 baud)
		Weather (must be Serial Port 1 or 2 on HS & WS DUs)) Used to interface to XM Weather data via RS232 format (115200 baud)
		CO Guardian Used to reset CO warning data via RS232 format (9600 baud)
Serial Port 1, 2, 3, 4, 5, 6 Input Counter	None	Will be continuously changing when the serial port is operating correctly.
Analog 1, 2, 3, 4, 5, 6, 7, 8 Function	Off / ILS Tuned 1 or 2 / GPS Deviations Active 1 or 2 / VOR/ILS Deviations Active 1 or 2 / Ext A/P HDG Mode Select (direct or cycle) / Hold / Sequence (Active/Hold) / Aux (EIS compatible) / Flap Position / Aileron Trim / Elevator Trim / Page Flip / Sync Selected Heading /	(Not a user setting.) Used to assign functions to specific analog ports

Setting	Selection	Suggested Value
	Dimmer	
Discrete 1, 2, 3, 4, 5, 6, 7, 8 Active Voltage	Low / High	Depends on use
EIS Model	4000/6000/9000	As installed
EIS Temperature Units	Deg F / Deg C / Deg C except CHT / Deg F except OAT / Deg C except FADEC	Deg F
EIS Fuel Flow Units	Gallons / Liters / Liters with extra conversion	Gallons
EIS Baroset Units	In Hg / millibars	Inches Hg
AltEnc1 Serial Format	#AL+12345T+25CK / ALT 12345 with 99900flag / ALT 12345 with -2500 flag / \$MGL+12345T+25CK /	For transponders that do not accept fuel/air data from the GRT Horizon EFIS for altitude encoding, this setting defines the format of the serial altitude output. The required format should be specified in the transponder installation manual. Note that the GRT Horizon EFIS can simultaneously provide two different altitude encoding outputs to drive two different transponders.
AltEnc2 Serial Format	Same as above	
Page Change	Single / Double Click	Double Click This setting controls how page views change. One click (press) of a button or knob will change the view. Two clicks will show the labels then another click is required to change the view.
Initial Menu Timeout (sec)	3.0 / 120	5.0 These selections determine how long menu boxes remain on the screen.
Used Menu Timeout (sec)	3.0 / 120	5.0
Default Page	PFD / MAP / ENG / (PFD/MAP) / (PFD/HSI) / (PFD/ENG) / (MAP/ENG) / MAP Circle View / (MAP/HSI) / MAP North Up	PFD for MFD1, MAP for MFD 2 This setting sets the default page after the start up screen is acknowledged.
Page Selection	Numerous	All ON This setting enables or disables the various available page views. For example if you want to be able to view a split page of PFD left, MAP right, you must enable it here.
Speed/Distance Units	Knots, Nautical Miles / MPH, Statute Miles / KMH, Kilometers /	Knots, nautical miles This selection defines the units used for all displays, except those specifically labeled otherwise. The selection changes both speed and distance units.
Temperature Units	Deg F / Deg C /	Deg F Used for all temperature data unless otherwise specified.
Fuel Units	Gallons / Liters	Gallons Defines units used for fuel flow totalizer function and flow rate. This selection does not alter the data received from EIS.
Tachometer Units	RPM / Percent RPM	RPM
Manifold Pressure Units	In Hg / 100mm Hg /	In Hg
Pressure Units Outside Air Temp Source	Psi / atm (kg/cm2) Auto / AHRS / EIS	Psi Auto An OAT sensor may be
Outside All Terrip Source	AUIO / AI INO / EIO	attached to EIS or EFIS or both.

Auto Will use the data from EIS if it is valid or the Horizon EIFS AHRS if it valid or North Horizon EIFS AHRS if it valid of North Horizon EIFS AHRS if it valid or North Hor	Setting	Selection	Suggested Value
Analog VOR/ILS Inputs Off / NAV 1 or 2 Defines the source of Analog VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS and GPS data in both ARINC and Analog format. In dual DU systems, for redundancy, DU1 may receive VOR/ILS data via ARINC and DU2 would receive it via Analog. This selection allows you to define to the DU receiving Analog data the source of the Analog data. In this example, DU1 would be set to Nav 1. EXT NAV MODE Off / NAV 1 or 2 Off / NAV 1 or 2 Off / ORV 1 or 2 Orly applicable when two GNS430, 530, or 480 receivers are in use. GNS430, 530 & 480 have two modes, GPS or VOR/ILS. The mode is selected by the CDI button Since switching the mode on the receiver may also change the mode on the DU, this GPS receiver is connected to that DU ARINC VOR/ILS Inputs Off / NAV 1 or 2 Defines the source of ARINC VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS data to DU. This selection allows you to define to the DU receiving ARINC data the source of the ARINC data. In this example, DU1 would be set to Nav 1 and DU2 would be set to OFF.			valid or the Horizon EFIS AHRS if it is valid. Valid OAT data must be greater than -40 deg F. The AHRS/EIS selections force the specified source to be used. OAT is used for true airspeed calculations which affect wind calculation and
Since switching the mode on the receiver may also change the mode on the Puthich GPS receiver is connected to that DU. ARINC VOR/ILS Inputs Off / NAV 1 or 2 Off / NAV 1 or 2 Defines the source of ARINC VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS and GPS data in both ARINC and Analog format. In dual DU systems, for redundancy, DU1 may receive VOR/ILS data via ARINC and DU2 would receive it via Analog. This selection allows you to define to the DU receiving ARINC data the source of the ARINC data. In this example, DU1 would be set to Nav 1 and DU2 would be set to Nav 1 and DU2 would be set to OFF			Defines the source of Analog VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS and GPS data in both ARINC and Analog format. In dual DU systems, for redundancy, DU1 may receive VOR/ILS data via ARINC and DU2 would receive it via Analog. This selection allows you to define to the DU receiving Analog data the source of the Analog data. In this example, DU1 would be set to OFF and DU2 would be set to Nav 1.
VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS and GPS data in both ARINC and Analog format. In dual DU systems, for redundancy, DU1 may receive VOR/ILS data via ARINC and DU2 would receive it via Analog. This selection allows you to define to the DU receiving ARINC data the source of the ARINC data. In this example, DU1 would be set to Nav 1 and DU2 would be set to OFF	EXT NAV MODE	Off / NAV 1 or 2	530, or 480 receivers are in use. GNS430, 530 & 480 have two modes, GPS or VOR/ILS. The mode is selected by the CDI button Since switching the mode on the receiver may also change the mode on the DU, this selection defines to the DU which GPS receiver is
	ARINC VOR/ILS Inputs	Off / NAV 1 or 2	VOR/ILS data to DU. Many GPS (GNS430, 530, 480) output VOR/ILS and GPS data in both ARINC and Analog format. In dual DU systems, for redundancy, DU1 may receive VOR/ILS data via ARINC and DU2 would receive it via Analog. This selection allows you to define to the DU receiving ARINC data the source of the ARINC data. In this example, DU1 would be set to Nav 1 and DU2 would be set to
	ARINC GPS Input	Off / GPS 1 or 2	Defines the source of ARINC GPS

Setting	Selection	Suggested Value
		data to DU.
		Many GPS (GNS430, 530, 480) output VOR/ILS and GPS data in both ARINC and Analog format.
		In dual DU systems, for redundancy, DU1 may receive GPS data via ARINC and DU2 would receive it via Analog.
		This selection allows you to define to the DU receiving ARINC data the source of the ARINC data.
		In this example, DU1 would be set to GPS 1 and DU2 would be set to OFF
SL30 OBS Source	SL30 NAV Head / EFIS Course Knob	EFIS Course Knob This selection allows the SL-30's external navigation head to provide the selected course (OBS) data to the EFIS permitting the external Nav head and EFIS to show the same course at all times. If no course data is provided by the SL-30, the EFIS automatically reverts to the EFIS course knob for course selections.
NAV Mode Source	Internal / External	External GNS430, 530 & 480 have two modes, GPS or VOR/ILS. On the receiver, the mode is selected by the CDI button. External uses the CDI button to switch the mode of both the 430 and the DU. Internal switches the mode of the DU but the 430 mode must also be changed via the CDI button.
NAV EXT1 Label	EXT1 / G430-1 / G480-1 / G530-1	As connected
NAV EXT2 Label	EXT2 / G430-2 / G480-2 / G530-2	As connected
NAV1 Label	VOR / TACAN	VOR
NAV2 Label	VOR / TACAN	VOR
GPS 1 Flight Plan Source	Internal / External	This selection specifies if the internal EFIS flight planning function is active or if the external GPS flight plan is to be used for GPS receiver 1. Select External if an external GPS is configured as GPS 1. Select Internal if the EFIS is equipped with internal GPS and it is configured as GPS 1.
GPS 2 Flight Plan Source	Internal / External	See above
Virtual GPS 2	Off / On	When On , a second GPS 2 navigation mode is provided, whose flight plan is entered via the internal GPS flight plan selection. The position data for this virtual GPS is provided by the GPS1 source. This allows the pilot to enter one flight plan into the external GPS, and a second flight plan into the EFIS

Setting	Selection	Suggested Value
		internal flight plan. The desired flight plan can be selected by setting the navigation mode to GPS1 or GPS2. Requires only one GPS.
Flaps & Trim Calibration	Table	If Flap and or Trim position sensors have been fitted, this page provides for calibration of the on-screen indicators. GRT Horizon assumes that sensors are connected to analog inputs. The specific analog input is defined earlier in this set up page.
External dimmer Scale	Table	If an external voltage is being supplied one of the analog inputs to control dimming, this page provides for calibration of that control.
Clock	Off / On	On Turns on clock
Set Mode	Manual / Auto	Auto Auto uses GPS NMEA0183 or weather data to set time. (Clock power must be provided to retain local time settings.)
Local Time Offset		Used to set clock to local time – enter hours difference from Zulu time. If left 0, clock will display Zulu time.
		You can display Zulu time on the PFD and local time on the MFD if you set the Offset on the PFD DU to 0 and the Offset on the MFD to local time.
Lateral Autopilot Functions	Off / On	On This setting turns on page view labels for LAT A/P and enables Lateral Autopilot.
Vertical Autopilot Functions	Off / On	On This setting turns on page view labels for VERT A/P and enables the Vertical Autopilot. Note that vertical autopilot functions are only available when ARINC interface is used. Autopilot must accept GPSS and GPSV commands.
Turn Anticipation Range	0.0 – 5.0	1.0 This setting determines the distance in miles the autopilot needs to be from the navaid or waypoint before it will start a turn. This setting only effects GPSS steering commands.
Autopilot Serial Output	Normal / GPS Coupler	Normal This setting configures the data sent to the autopilot. Normal should be used by most modern autopilots. The GPS Coupler selection formats the data for use with older autopilots that use a GPS couplers, such as some Navaid Devices or S-Tec autopilots.
Autopilot Gains		See Text Below

Serial Port Settings

If you're using more than one radio or GPS use the 1 or 2 settings. For example, a 430 and SL30, the 430 will be the number 1 radio and the SL30 will be the number 2 radio, set accordingly, GPS Aviation/Mapcom 1 for the 430 and SL-30 2 for the SL30.

NOTE: When both the analog, and serial outputs from a navigation receiver are wired to the EFIS, the EFIS will use, in order of priority:

- 1. ARINC 429 serial data
- 2. RS-232 serial data
- 3. Analog data

Adjusting Autopilot Response

Gain adjustments are provided to allow the user to optimize the commands provided to the autopilot. If "ARINC Module Connected" is YES, the Gain Adjustments apply to GPSS steering sent to the autopilot via ARINC. If "Autopilot Serial Output" is "GPS Coupler" the Gain Adjustments apply to steering commands sent to the autopilot via the GPS Coupler. If neither ARINC or GPS Coupler are selected, steering commands are sent to the autopilot via RS232 Serial link and no Gain Adjustments are required, the autopilot handling all functions

To access Gain Adjustments:

- 1. Press a button
- 2. Press **NEXT** button (more than once may be required)
- 3. Press **SET MENU** button
- 4. Select **General Setup**, press knob
- 5. Scroll to Autopilot Serial Output
- 6. Highlight by pressing knob (setting will have a white box around it)
- 7. Change setting to GPS Coupler
- 8. Press knob to CHANGE

The adjustment of these gains allows the user to account for variations in the response of the autopilot, airplane and pilot's preferences for the aggressiveness of autopilot tracking.

The following guidelines are provided to assist the pilot with adjustments to these gains.

Start with all gains at 1.0 When adjusting gain, change by factor of 2 (change to .5 from 1.0 to decrease gain or to 2.0 from 1.0 in increase gain). Note that the autopilot may limit some responses, for example the amount of bank angle used to intercept a course.

Cross Track Gain (XTGain) - Normally this gain should not be altered, as it currently affects GPS, Synthetic Approach, Localizer and Glideslope. With the Roll Gain adjusted as desired, airplane on course with minimal cross-track error, change to heading mode, select a heading 20 degrees different from the current heading. When the airplane is 500-1000' off course, and heading 20 degrees away from the course, change back to NAV mode for the lateral autopilot mode. Adjust the XTGain so that the airplane recaptures the GPS course with a small overshoot. If XTGain is too low, the intercept angle will be at shallow angles, and will be sluggish. If too high, overshoot will be observed.

Roll Gain - Put the airplane on the course; with zero cross-track error (use the GPS on a 500' range scale to see when very close to being on track.) Note how much activity there is in the ailerons in smooth air while on course. Set the roll gain as high as possible, but not so high that it results in any noticeable roll activity in smooth air. Note that Roll Gain affects all modes except Heading.

Heading Gain - Slow the airplane to the minimum speed at which you will use the heading select function. Adjust the Heading gain as high as possible without excessive roll or heading oscillations

Localizer Gain - Adjust the gain so that it is as high as possible without oscillations back and forth across the localizer until 100-200 feet above the ground.

VOR Gain - Adjust the gain as high as possible so that oscillations begin when close to the VOR. If tracking of the VOR causes an uncomfortable ride (due to noise on the VOR data), reduce the gains as desired.

Altitude Hold Gain – Adjust the gain to hold altitude without oscillations in turbulence.

Vertical Speed Gain – Adjust the gain to hold vertical speed without oscillations in turbulence.

Glideslope Gain – Adjust the gain to stay on the glideslope without oscillations in turbulence.

Α

NOTE: Depending on the intercept angle when the approach is captured, the turn rate available through the autopilot, and other factors, pilot intervention may be required to capture the approach without overshoot.

The recommended procedure for intercepting the synthetic approach is to do so at a distance of 8 nm or more from runway, at an intercept angle of 45 degrees or less.

The accuracy of the autopilot to track the synthetic approach will be maximized when the intercept occurs in this manner.

Chapter 3 PRIMARY FLIGHT DISPLAY
The Primary Flight Display Setup Menu allows you to set your preferences on the PFD.

Detailed information on each choice follows this table which shows suggested values

Setting	Selection	Suggested Value
Up Reference	Heading / Track	Heading Selects whether the yaw
		axis reference for the PFD screen is
		heading or ground track. Heading is
		the recommended setting, as this
		allows the EFIS to provide an
		artificial view that matches the view
		out the window. This makes the
		position of runways, obstacles and
		other traffic appear on the screen in
		the same relative position that they
		appear out the window and is
		especially useful when strong cross
		winds exist, as the difference
		between ground track and heading
		can be significant.
Stall Speed Vs1		POH Value Stall speed is the lower
•		end of the airspeed tape at the
		bottom of the green and white
		sections. Use the speed from your
		Aircraft Pilot Operating Handbook
		(POH) for this and the following
		settings.
Max Flap Ext Speed Vfe		POH Value This setting is the top of
' '		the white section on the airspeed
		tape.
Max Struct Cruise Speed Vno		POH Value This setting is the top of
•		the green and the bottom of the
		yellow section of the airspeed tape.
Never Exceed Speed Vne		POH Value Never Exceed speed.
·		This setting is the bottom of the red
		and the top of the yellow section of
		the airspeed tape.
Speed Bug 1 (X)		These are user selectable speed
		bugs that can be used to indicate Vx,
		Vy, Vg. They display as magenta
		triangles beside the airspeed tape
		Setting them to 0 disables them.
Speed Bug 2 (Y)		See above
Speed Bug 3 (G)		See above
Below Stall	None / Red	Red This allows user selectable
		color of the airspeed tape for speeds
		below stall speed.
HITS Frame Color	Magenta / Green / White	Magenta Sets the color of the HITS
		boxes and is user selectable.
Attitude Reference Index	Bars / Nose	Nose Selects whether the pitch
		reference on the PFD are traditional
		pitch reference bars, or a non-
		traditional nose reference cyan
		colored circle. The traditional bars
		are bolder but tend to clutter the PFD
		screen a little more than may be
		desired, especially near the center of
		the screen where the depiction of the

Setting	Selection	Suggested Value
		runway, flight path marker and HITS
		occurs. Since the PFD includes a flight path marker, the need for
		traditional bars is reduced. Nose is
		recommended, but try both to chose
000 001	0.10%	your preference. On Enables or disables the GPS CDI
GPS CDI	On / Off	on the PFD page.
Slip Indicator	On / Off	On Controls the display of the slip indicator.
Turn Rate Indicator	On / Off	On Controls the display of small greet triangles on the roll scale that
		indicate the bank angle required to
		achieve a standard rate (2 minute)
		turn.
Wind Indicator Mode	Off / Vector & Digital Speed / Vector	Vector & Digital Speed & Direction
	& Digital Speed & Direction	OFF – No display of wind data. Vector and Digital Speed – The
		vector (arrow) points to the wind
		direction relative to the aircraft's
		heading. Speed is displayed. Vector and Digital Speed/Direction
		Same as previous except a digital
		value of direction is also displayed.
		Digital value is relative to magnetic
Digital Hood / Cross Wind Diaples	05/05	north.
Digital Head / Cross Wind Display	On / Off	On Controls display of head and cross wind components in the lower
		left portion of the PFD screen.
		Head/Tailwinds are shown with H/T
		and cross winds are shown with L/R for left/right.
Baroset units	Inches Hg / millibars	Inches Hg Defines the units used for
		setting barometric pressure in the
		altimeter. Inches of Hg is used in the US; millibars are used in many
		places outside the US.
Artificial Runways	On / Off	On When ON, an artificial view of
		runways at airports within 10 miles of the aircraft is depicted on the PFD.
Flight Path Marker	On / Off	On The Flight Path Marker (FPM) is
		the projected flight path the aircraft will take with current flight/wind
		conditions. It shows where the
		aircraft will be if the present
Aires and displayed	Named / Lang	flight/wind conditions continue.
Airspeed display size Altimeter display Size	Normal / Large Normal / Large	Normal Normal
Track/Heading display size	Normal / Large	Normal
Airspeed Resolution	Fine / Coarse	Fine Fine shows graduations of 5
		mph on the airspeed tape, compared
May indicator vertical anged	1000 / 2000 / 2000 / 5000	to 10 mph in Coarse.
Max indicator vertical speed	1000 / 2000 / 3000 / 5000	1000 Selects the maximum range for the vertical bar graph display. With
		the 1000 or 2000 fpm scale, the bar
		graph represents vertical speed in a
		linear manner, that is a speed of 750
		fpm is represented by a bar ¾ of full scale. With the 3000 or 5000 fpm
		scales, 0 to +/- 1000 fpm is linear

Setting	Selection	Suggested Value
		and the remainder of the scale is
		compressed.
Pitch ladder offset		Like a traditional attitude indicator,
		this allows the pitch indicator to be
		set for zero pitch during normal
		cruise. A positive setting causes the
		pitch ladder to be displayed above
		the actual zero point. Note that the
		PFD includes a flight path marker
		(FPM) that shows the aircraft's path
		relative to the horizon, and unlike the
		pitch ladder, the FPM shows climb or
		descent (above or below the horizon)
Flight level altitude		independent of airspeed. 18000 This setting automatically sets
I light level attitude		the baroset to standard pressure
		(29.92 in Hg) when at or above this
		preset altitude
Altitude Alerting	On / Off	On Enables/disables alarms to warn
		of deviation from desired altitude.
Max Altitude Deviation		200 Altitude deviation which will
011 1 1 1 0 5 1 1 1 1		trigger the above mentioned alarm
Climb IAS Preset #1	40 - 600	May also be set from Autopilot pages.
Climb IAS Preset #2	40 – 600	
Climb VS Preset #1	0 – 9999	
Climb VS Preset #2	0 - 9999	
Descent IAS Preset #1	40 – 600	
Descent IAS Preset #2	40 – 600	
Descent VS Preset #1	0 – 9999	
Descent VS Preset #2	0 – 9999	
Upper Left Corner Box	Ground speed / True Airspeed	Ground speed Select the data to be
		displayed in the upper left corner of the PFD. Groundspeed is
		the PFD. Groundspeed is recommended . If two display units
		are installed, Groundspeed is
		displayed on the map page of the
		MFD, so display TAS here.
Data Boxes	On / Off	This setting turns on data boxes at
		the bottom of the PFD page. Two
		boxes are provided and each can
		display four user definable items.
		The items can either be data
		(distance to waypoint, engine RPM
		etc) or a labels ("RNG"," RPM" etc)
		that can be used to identify the data
		above or below the label. If no entry
		is selected for these boxes, they are
Loft Day Hanard of Cata		not displayed See text following
Left Box, Upper Left Entry Left Box, Upper Right Entry		Data: Dest Waypoint ID Data: Dest Waypoint Est Time
Leit Box, Opper Right Elliny		Enroute
Left Box, Lower Left Entry		Data: Dest Waypoint Range
Left Box, Lower Right Entry		Data: Dest Waypoint Bearing
Right Box Upper Left Entry		Data: RPM
Right Box, Upper Right Entry		Data: MAP
Right Box, Lower Left Entry		Label: RPM
Right Box, Lower Right Entry		Label: MAP
Approach Glideslope Angle		3.0 Defines glideslope angle used for
		the synthetic approach when no ILS

Setting	Selection	Suggested Value
		glideslope is associated with the
		selected runway
Approach Height Intercept	Reserved for Future Use	N/A
ILS Type	Off / Needles / Scales	Scales OFF – Glideslope and Localizer deviation is not shown at any time. Needles – "Needles" and scales are overlaid on the center of the PFD. Format is similar to traditional navigation heads. Scales are depicted as "dots" of deviation. Scales will be displayed when an ILS is tuned. Scales replace the attitude reference "bars" or "nose" indicator and thus function both as scale for
		localizer deviation and as reference for attitude display. "Needles" will be displayed only when localizer or glideslope is valid and ILS is active. If "VOR Deviation on Loc Display" is enabled, and VOR data is valid, only the localizer scale and needle will be displayed (no glideslope scale or needle will be displayed). Scales – Deviation scales are overlaid on the bottom center of the screen (localizer) and right side (glideslope). Scales are displayed when ILS is tuned. Deviation indicators will display when localizer or glideslope is valid and ILS is active. When ILS is active but localizer or glideslope is invalid, deviation indicator is not displayed. If ILS data is provided to the Horizon EFIS via serial input and this input is not providing data to the EFIS, or is reporting the nav receiver failed, a line will be drawn through the scales
Show VOR CDI on Localizer	Yes / No	to indicate the failure. Yes Yes displays VOR deviation data on the PFD in place of localizer deviation when the Horizon EFIS
		navigation mode is VOR. "VOR" will appear just to the left of the scale on the PFD. To/From is provided to the right of the scale if available
Show GPS CDI on Loc/GS	Yes / No	Yes. This setting displays the GPS CDI when localizer and glideslope is active.
ILS Inhibit of HITS	Inhibit / No Inhibit	No Inhibit When inhibited, the HITS that is displayed during Synthetic Approach is removed when the navigation mode is LOC or ILS and the localizer is valid. The height above touchdown zone will still appear below the Flight Path Marker.
Default Decision Height		200 When the height above the runway touchdown zone is lower

Setting	Selection	Suggested Value
		than this entry, the height above touchdown that is displayed below the Flight Path Marker will flash between Red and Green
G-Meter Mode	Off / Auto / On / On with Min Max	On with Min Max OFF – G-Meter does not display Auto – G-Meter displays when High or Low threshold is exceeded. ON – G-Meter is displayed. ON with Min/Max – G-Meter displays inside a yellow box when Caution Min or Max is exceeded.
G-Meter Maximum		Sets the scaling of the analog portion of the G-Meter. Set at or slightly greater than max allowable positive G loading.
G-Meter Minimum		Sets the scaling of the analog portion of the G-Meter. Set at or slightly greater than max allowable negative G loading.
G-Meter Caution Max		Sets value where G-Meter displays when On with Min/Max is selected.
G-Meter Caution Min		Sets value where G-Meter displays when On with Min/Max is selected.
Auto G-Meter High Threshold		Sets value where G-Meter displays when Auto is selected.
Auto G-Meter Low Threshold		Sets value where G-Meter displays when Auto is selected.

Data Boxes (On/ Off)

This setting turns on data boxes at the bottom of the PFD page. Two boxes are provided and each can display four user definable items. The items can either be data (distance to waypoint, engine RPM etc) or a labels ("RNG"," RPM" etc) that can be used to identify the data above or below the label. If no entry is selected for these boxes, they are not displayed. If entries for the top two positions are not used, the height of the box is reduced to half normal size.

Available choices for these boxes are:

OFF

DATA: Dest Waypoint ID

DATA: Dest Wpt Est Time Enroute

DATA: Dest Waypoint Range DATA: Dest Waypoint Bearing

DATA: RPM DATA: RPM2 DATA: N1 DATA: N2

DATA: Oil Temperature DATA: Oil Pressure

DATA: Coolant Temperature

DATA: Carb Temperature

DATA: Highest EGT (Exhaust Gas Temperature)
DATA: Highest CHT (Cylinder Head Temperature)
DATA: Highest TIT (Turbine Inlet Temperature)

DATA: Aux 1-6 (from EIS Engine Monitor)

DATA: Outside Air Temperature

DATA: Density Altitude DATA: Volts (from EIS)

DATA: Fuel Flow

DATA: Fuel Remaining (from Fuel Flow)
DATA: Fuel Range (from Fuel Flow)

DATA: Groundspeed DATA: True Airspeed DATA: Percent Power

DATA: Power Bus 1Voltage DATA: Power Bus 2 Voltage DATA: Power Bus 3 Voltage

Label: ETE (Estimated Time Enroute)

Label: RNG (Range)
Label: BEAR (Bearing)
Label: DEST (Destination)

Label: RPM (Revolutions per minute)
Label: RPM2 (Revolutions per minute)

Label: N1 Label: N2

Label: OilT (Oil Temperature)
Label: OilP (Oil Pressure)

Label: Cool (Coolant Temperature)
Label: Carb (Carburetor Temperature

Label: Hi EGT Label: Hi CHT Label: Hi TIT

Label: MAP (Manifold Pressure)
Label: FPrs (Fuel Pressure)
Label: L Fuel (Left Fuel tank)
Label: R Fuel (Right Fuel tank)

Label: AMP (Amps)

Label: Volts Label: Volt1 Label: Volt2 Label: Volt3 Label: D Alt

Label: OAT (Outside Air Temperature)

Label: GS (Groundspeed)
Label: TAS (True Airspeed)

Label: Power

Suggestion: Many have found that setting the left four Databoxes to show Dest Waypoint ID, Dest Wpt Est Time Enroute, Dest Waypoint Range and Dest Waypoint Bearing and the right four databoxes to show engine information such as RPM and Manifold Pressure is convenient. This is the factory default.

Chapter 4 MOVING MAP SETUP

This set up page allows the user to configure the Moving Map to suit individual preferences.

Detailed information on each choice follows this table which shows suggested values

Setting	Selection	Suggested Value
Up Reference	Heading / Track	Track Heading Selects whether the yaw axis reference for the PFD screen is heading or ground track. Heading is the recommended setting, as this allows the EFIS to provide an artificial view that matches the view out the window. This makes the position of runways, obstacles and other traffic appear on the screen in the same relative position that they appear out the window and is especially useful when strong cross winds exist, as the difference between ground track and heading can be significant.
Airport Symbol Size	Small / Large	Small
Label Font Size	Small / Large	Small
HSI Plane Symbol	Conventional / Canard	To match your aircraft
Connect Bearing Pointers	Yes / No	No The bearing pointer(s) on the HSI page may be shown with the tails connected to the pointers (heads) or with the tail and pointer (head) as separate pieces. YES shows bearing pointer as it is typically shown on an RMI with tail and pointer (head) connected. NO shows the bearing pointer with the tail and pointer (head) not connected and provides some level of declutter that may be preferred.
Max map range:	Off / 1 / 2 / 5 / 10 / 15 / 20 / 35 / 50 / 100 / 150 / 300 / 500 / 1000	Max map range at which each of the following symbols are displayed. The symbol will appear on the map when the map's range is set to a range equal to or lower than this entry. The available selections are the map ranges with the addition of OFF, which disables the item so it will not be displayed at any time. These selections serve to declutter the map display.
Small airports		20 Airports with runways less than 5000 feet
Medium airports		100 Airports with runways 5000 feet or longer or a control tower
Large airports		300 Airports with runways longer than 8100 feet.
VOR		300 Includes VORs, VOR/DME, VOR/Tacan (VORTAC)
NDB		50
Airspaces		50 Includes Class B, C, and D

Setting	Selection	Suggested Value
•		airspace boundaries.
Max obstructions distance		10
Obstacle alarm	On / Off	On Enables/disables alarms that
		warn of nearby obstacles. When
		enabled, an obstacle alarm will be
		provided when an obstacle is
		projected to be within 250 feet of the
		aircraft's flight path within 60
		seconds time and 25 degrees of
		ground track. Since flight path is
		used, an alarm will be generated if
		the aircraft is above the obstacle but
		descending at a rate that will allow it
		to collide with it. Likewise, if the
		aircraft is below an obstacle but
		climbing at a sufficient rate to miss it,
		an alarm will not be generated.
Terrain	On / Off	On Enables the Moving Map Soft
		Key "SHOW" selection that allows
		terrain to be displayed.
Terrain Alarm	On / Off	On Enables or disables a warning
		when terrain is with 500 feet of the
		aircraft's altitude and within 2
		minutes.
Auto Declutter	On / Off	On When enabled, this function
		limits the number of items displayed
		on the map to 50, by limiting the
Ob a 12 bit at a	No Control March 100 all	number of small airports displayed
Show Lightning	No / On North up Map only / On all	Selects which map pages are to
Requires XM Weather	MAP pages	display lightning data. Showing on
		North UP Only can increase update
Show AIRMET	No / On North up Man anh/ / On all	rate of the other map pages. Selects which map pages are to
	No / On North up Map only / On all	display IFR AIRMETS. Showing on
Requires XM Weather	MAP pages	North UP Only can increase update
		rate of the other map pages.
Color airports using METARS	No / On North up Map only / On all	Airports may be colored depending
Requires XM Weather	MAP pages	on their weather conditions (VFR,
requires xivi vveatrici	WAI pages	MVFR, IFR). This Selects which
		map pages are to display airports in
		weather colors. Showing on North
		UP Only can increase update rate of
		the other map pages.
METAR Text	Raw / Translated	Translated Controls the formal of
Requires XM Weather		the METAR shown for each airport.
- 4		Translated selection shows the
		METAR in plain English.
TAF Text	Raw / Translated	Translated Controls the formal of
Requires XM Weather		the TAF shown for each airport.
		Translated selection shows the TAF
		in plain English.

.

Chapter 5 GRAPHICAL ENGINE DISPLAY SETUP

There are a six engine display pages. This menu allows the user to select which parameters are displayed and in what manner they are displayed.

The following table is an example of a typical setup for a RV with an O 360 engine. It reflects the example pages shown in Section 4, Engine Monitor.

Setting	Selection	Suggested Value
Dial Settings Up to four engine parameters may be displayed as conventional dials. The dials display includes the capability to display red lines, green and yellow arcs, a numeric display of the current value and up to 6 "Bugs". Dial 1 is the top left dial, 2 is the top right dial, 3 is the bottom left dial and 4 is the bottom right dial. Dials 1 and 2 are visible on all engine monitor pages. Each dial is configured in the same manner. Dial #1 Source	Dial Source (Off, RPM, Aux 1-6, Fuel Flow, Percent Power, N1, N2, Fuel Pressure, CHT 1-2, EGT 1-2, TIT 1-2, Highest CHT, EGT or TIT, Oil Temp, Oil Press, Torque, Fuel Qty, Fuel Remaining, EIS and EFIS Volts, Amps, Coolant Temp, Carb Temp, Gear Box Temp, Hyd Press, Water Press, Air Press, Aux 1-6)	MAP
Dial #1 Scale	.01, .1, 1, 10, 100	0.1 This is what determines the available resolution of the dial and also the numeric display. It should correspond to the resolution set in EIS. For example, 0.1 would be appropriate for MAP, 100 would be appropriate for RPM, 1 would be appropriate for oil pressure etc.
Dial #1 Units Label		in Hg This selects the displayed label. Dial Source above will select the name label (RPM, MAP, Pwr, Flow etc), this field selects the displayed units label (x100, in Hg, %,blank).
Dial #1 Start		10.0 Each dial presentation is 270 degrees (¾ of a circle). Using these two fields, you specify what value the dial starts at and what value it ends at. For example, you want to have a tachometer dial and the maximum RPM is 3000. If you start the dial at 0 and end at
		3000, each 90 degrees (¼ of a circle) will represent 1000 RPM. If you start the dial at 1200 and end at 3000, each 90 degrees (¼ of a circle) will represent 600 RPM, making the dial easier to read. If you are concerned about clear, easy to read indications in a specific operating region, you may set the

Setting	Selection	Suggested Value
		dial that way. For example, the tach dial could be set 1700 start and 2600 end, making each 90 degrees represent 300 RPM. This is perfectly safe since EIS and/or EFIS is monitoring for Min Max limits, so the dial presentation doesn't need to include Min or Max values.
		Since this is an easy display to change, you can change it depending on parameters you wish to observe or tests you are performing. In early flight you might want to monitor Oil Temp closely, so set up one of the dials to do that.
Dial #1 End		32.0 See above.
Dial #1 Label Increment		5.0 All dials have major (long) and minor (short) graduations or tick marks. Dial Tick Increment defines what values have graduations or tick marks and Dial Label Increment defines which tick marks have labels, making them major tick marks.
		For example, MAP dial might have Dial Tick Increment set to 1 and Dial Label Increment set to 5 resulting in lines every 1 inHg and labels (and longer lines) every 5.
		Another example, a tach dial, might have Dial Tick Increment set to 100 and Dial Label Increment set to 500 resulting in lines every 100 RPM and labels (and longer lines) every 500.
Dial #1 Tick Increment		1.0 See above.
Dial #1 Green Start		0 These allow the setting of the desired start and end points of the colored arcs.
Dial #1 Green End		0
Dial #1 Yellow Start		0
Dial #1 Yellow End Dial #1 Red Start		0
Dial #1 Red End		0
Dial #1 Bug #1 Position		0 These allow the setting of user defined "bugs" to indentify pertinent values. For example, by setting the same color bugs on MAP and RPM dials, one can easily set a particular power setting.
Dial #1 Bug #2 Position		0
Dial #1 Bug #3 Position		0
Dial #1 Bug #4 Position		0
Dial #1 Bug #5 Position		0
Dial #1 Bug #6 Position		0
Dial #2 Source Dial #2 Scale		RPM
Dial #2 Scale Dial #2 Units Label		100 x100
DISTRE OTTIO LODGE		A 144

Setting	Selection	Suggested Value
Dial #2 Start		1000
Dial #2 End		2700
Dial #2 Label Increment		200
Dial #2 Tick Increment		100
Dial #2 Green Start		1000
Dial #2 Green End		2400
Dial #2 Yellow Start		0
Dial #2 Yellow Start		0
Dial #2 Red Start		2600
Dial #2 Red End		2700
Dial #2 Bug #1 Position		2200
Dial #2 Bug #1 Color		Magenta
Dial #2 Bug #2 Position		0
Dial #2 Bug #3 Position		0
Dial #2 Bug #4 Position		0
Dial #2 Bug #5 Position		0
Dial #2 Bug #6 Position		0
Dial #3 Source		Percent Power
Dial #3 Scale		1
Dial #3 Units Label		%
Dial #3 Start		0
Dial #3 End		100
Dial #3 Label Increment		10
Dial #3 Tick Increment		5
Dial #3 Green Start		0
Dial #3 Green End		0
Dial #3 Yellow Start		0
Dial #3 Yellow End		0
Dial #3 Red Start		0
Dial #3 Red End		0
Dial #3 Bug #1 Position		75
Dial #3 Bug #1 Color		Magenta
Dial #3 Bug #2 Position		0
Dial #3 Bug #3 Position		0
Dial #3 Bug #4 Position		0
Dial #3 Bug #4 Position		0
Dial #3 Bug #6 Position		0
Dial #4 Source		Fuel Flow
Dial #4 Scale		0.1
Dial #4 Units Label		No Label
Dial #4 Start		0.0
Dial #4 End		20.0
Dial #4 Label Increment		5.0
Dial #4 Tick Increment		1.0
Dial #4 Green Start		0
Dial #4 Green End		0
Dial #4 Yellow Start		0
Dial #4 Yellow End		0
Dial #4 Red Start		0
Dial #4 Red End		0
Dial #4 Bug #1 Position		0
Dial #4 Bug #2 Position		0
Dial #4 Bug #3 Position		0
Dial #4 Bug #4 Position		0
Dial #4 Bug #5 Position		0
Dial #4 Bug #6 Position		0
Performance/Fuel Box 2	Off, Carb temp, TAS, MPG/KPL	Carb The display in the upper left
1 S.I.O.IIIIGIIOO/I GOI DOX Z	on, ours tomp, the, in one i	corner of the Engine Monitor displays

Setting	Selection	Suggested Value
		fuel related information. The
		second field on the left side is user
		selectable from the above choices.
Fuel Flow Data	Off / On	On Fuel Flow information may be
		displayed in the upper left corner
		also.
Number of Cylinders	2,4,6,9	4 Sets how many EGT/CHT graphs
		are to be displayed. This setting
		should correspond to the number of
		EGTs that are measured by the
		model of EIS that is being used.
EGT Vertical Graph Min		900 One of the engine display
		pages shows EGT and CHT as
		graphs. These settings define the
		appearance of those graphs.
		Cimilar to other displays it is not
		Similar to other displays, it is not
CCT Vertical Craph May		necessary to start these at 0. 1600
EGT Vertical Graph Max		200
EGT Vertical Graph Increment		100
EGT Vertical Graph Ticks		
CHT Vertical Graph Min		100
CHT Vertical Graph Max		500
CHT Vertical Graph Increment		100
CHT Vertical Graph Ticks		100
EGT Time History Temp Min		900 Used to set the Min Max temps
		displayed when EGT Time History
		display is selected. The narrower
		the band (higher Min, lower Max) the
		more resolution and ability to
EGT Time History Temp Max		observe change.
Min Max (EIS Volts, EFIS Volts 1-3,		10 The GRT Horizon EFIS displays
Aux 1-6)		a number of parameters as vertical
EIS Volt Graph Min		bar graphs. There are a number of
Lie vok Graph Niiii		parameters for which the Min and
		Max display values are user
		selectable.
		Note that these are display values,
		not Min Max limits. Usually the
		display value range will be greater
		that limit range. For example, you
		might display voltage from 10 to 16
		volts, but the Min Max limits might be
		set at 12.8 and 15.6 volts.
EIS Volt Graph Max		20
EFIS Volt 1 Graph Min		0
EFIS Volt 1 Graph Max		0
EFIS Volt 2 Graph May		0
EFIS Volt 2 Graph Min		0 0
EFIS Volt 3 Graph Min EFIS Volt 3 Graph Max		0
Fuel Flow MAX FUEL		0 This is the value EFIS will use
I UEL FIUW WIAA FUEL		when you reset the fuel computer
		after refueling. You may also leave
		this number blank and input the fuel
		quantity from EIS. The EIS will
		override this entry.
Flow Rate Bar Graph Max		9.1 This entry sets the maximum
1 1011 Mate Dai Grapit Max		U.I This chury sets the maximum

Setting	Selection	Suggested Value
		fuel flow rate that will be displayed on the bar graph. Higher flow rates will indicate the same as this flow rate (top of bar graph). Measured flow rate is shown adjacent to the bar graph in numeric form. This parameter sets display value, not Max limit.
Prompt for Fuel Added	Yes / No	No On Power up, YES / NO enables or disables an on screen message prompting you to enter the amount of fuel added which is used to compute
Aux (1-6) Function		fuel usage and endurance. EIS Auxiliary Inputs are scaled and labeled appropriately via user settings on the EIS Engine Monitor. This information is NOT transmitted to the Horizon EFIS, and thus must be entered into the Horizon EFIS. For each Auxiliary Input used on the EIS, the name or label of each and whether it is Integer or Decimal data must be entered. Each Aux input is shown on this setup page and each is programmed in a similar manner. For example, scroll to Aux 1 Function. A number of preprogrammed labels are displayed (None, Aux, Volt Bus, Left Right Center Fuel, Gear Box Temp, Amp, TIT, Hyd Press, Torque, Flaps, Aileron & Elevator Trim, etc) If any of these is the correct label for the Aux 1 Input, select it. To make a custom label, select AUX. This will cause a new Setting line to appear, "Aux 1 Name" and its Value is "EIS Aux 1". Scroll to "EIS Aux 1" and press either knob. A new screen, "Aux Name Editor" will appear. The current value, "EIS Aux 1" is displayed at the top and there is a box around "E", indicating that first field, which contains "E" may be edited. To create a custom label, edit each field in turn. To edit "E", use the button under the appropriate column of characters to select the desired
		character. Then press the right knob to move to the next field and edit it. Repeat for all fields. For example, to change "EIS Aux 1" to "MAP", with the box around "E",

Setting	Selection	Suggested Value
		Note that over the right knob there is a list and NEXT has a white outline
		box. Press the knob and the box at
		the top moves to "I". Press the first
		button to select "A" Repeat to select "P" in the third position. Note
		that there is a "blank" in the fifth
		column. Insert blanks to "erase "Aux
		1".
		Select CASE over the right knob to
		change to lower case characters if desired.
		desiled.
		When complete, select SAVE which
		will return to Setting/Value screen.
		The next line on the Setting / Value
		screen is now "MAP Integer / Decimal". Select the same setting as
		set in EIS.
		Repeat for all Auxiliary Inputs.
		All Auxiliary inputs that are not in use
		should be set to NONE .
Aux 1 Function		MAP
Aux i Function		WAF
Aux 1-6 Integer/Decimal		Each of the Aux inputs must be
		defined as Integer or Decimal. These settings should correspond to
		the settings in EIS.
MAP Integer/Decimal		Decimal
Aux 1-6 Graph Min Max Level		These inputs will be displayed as
-		vertical bar graphs. These settings
		define the parameter values for the bottom and top of the bar graphs
		bottom and top of the bar graphs
MAP Graph Min Level		10.0
MAP Graph Max Level		32.0
Aux 2 Function		Left Fuel
Left Fuel Integer/Decimal Left Fuel Graph Min Level		Decimal 0
Left Fuel Graph Max Level		15
Aux 3 Function		Right Fuel
Right Fuel Integer/Decimal		Decimal
Right Fuel Graph Min Level		0
Right Fuel Graph Max Level		15
Aux 4 Function		Amp
Amp Integer/Decimal Amp Graph Min Level		Integer -100
Amp Graph Max Level	+	+100
Aux 5 Function		
Aux 5 Function Fuel Pressure Integer / Decimal Fuel Pressure Graph Min Level		Fuel Pressure Decimal

Setting	Selection	Suggested Value
Fuel Pressure Graph Max Level		0
Aux 6 Function		Off
Typical Cruise Fuel Flow		9 Expressed in Gallons per Hour
"		(GPH). This value is used to
		compute Endurance.
Reserve Fuel Display at Airports		(Future use)
Bar Graph A1-A6		Six bar graphs are displayed in the
		lower left corner of every Engine
		page. Here is where the selection of
		these six parameters is made. A1 is
		the left most display. Off causes that
		bar not to display.
Bar Graph A1		Oil Pressure
Bar Graph A2		Oil Temperature
Bar Graph A3		EIS Volt
Bar Graph A4	1	Amp
Bar Graph A5		Off
Bar Graph A6		Off
Bar Graph B1-B11		There are provisions for an additional
		eleven bar graphs to the right of A6.
		Here is when the selection of these
		parameters is made. B1 is the left
		most display. Off causes that bar not
		to display. These are displayed only
		on the BARS Engine page.
Bar Graph B1		Off
Par Craph P2		Off
Bar Graph B2 Bar Graph B3	+	Off
Bar Graph B4		Off
Bar Graph B5		Off
Bar Graph B6		Off
Bar Graph B7		Off
Bar Graph B8		Off
Bar Graph B9		Off
Bar Graph B10		Off
Bar Graph B11		Off
Split: Box 1-11		On the ENG/MAP split page, there
		are provisions to display11
		parameters. Box 1 and 2 display at
		the top of the page and Box 3-11
		display in a 3x3 grid beneath them.
		B3, B4 and B5 are the top row, B6,
		B7 and B8, the second and B9, B10
		and B11 the third.
Split: Box 1		RPM
Calife Day 0		MAD
Split: Box 2		MAP Oil Tomporature
Split: Box 4		Oil Temperature
Split: Box 4	_	Off
Split: Box 5	_	Off
Split: Box 6	_	Oil Pressure
Split: Box 7	_	Off
Split: Box 8 Split: Box 9		Off Off
Spiil. Dux 9		UII

Setting	Selection	Suggested Value
Split: Box 10		Off
Split: Box 11		Off
Reset Oil Hours on next SAVE	Yes / No	Yes The STATS Engine page has a field that keeps track of engine hours since last oil change. Selecting Yes, resets that field if you select SAVE at the prompt

Chapter 6 ENGINE LIMITS

This set up page configures the Min Max limits that are used to annunciate alarms on the PFD for inputs to the GRT Horizon EFIS.

The GRT Horizon EFIS uses the GRT EIS Engine Information System to interface to all external inputs. A feature of EIS is the capability to continuously compare each input to user set Min Max limits. If an input exceeds its limits, the error is annunciated by a flashing warning lamp and flashing EIS display. In EIS if a limit is set to 0, then that input is not monitored and will not trigger an alarm.

The GRT Horizon EFIS can have Min Max limits set similar to EIS. If this is done, out of limit inputs will trigger an alarm on the display as well as in EIS. Like EIS, setting an EFIS limit to 0 causes it not to be monitored.

How alarms are annunciated is a user preference. The options are:

EIS only – EIS should be mounted in the panel so the pilot can acknowledge alarm. Set all desired engine limits in EIS and set all engine limits in EFIS to 0.

EFIS only – works well if EIS is mounted remotely, such as for rear engine aircraft. Set all engine limits in EIS to 0 and set all desired engine limits in EFIS.

EIS and EFIS – alarms will have to be acknowledged in both units. Gives some backup in case of EFIS failure, EIS is still capable of generating alarms. Set desired engine limits in both EIS and EFIS.

Definition of Engine Limits and suggested settings are in the table below (this table is identical to the table in the EIS User's Manual).

Setting	Use	Recommended Setting		
Max Time	Alerts pilot when flight time exceeds this limit. Useful as a warning to check fuel. Limit is entered in minutes, so 2 hours is entered as 120, etc. Range is 0-500 minutes.	30-45 minutes less than airplane's endurance.		
Interval	Provides a warning that repeats at the interval entered in minutes. Useful as a reminder to perform periodic tasks such as switching fuel tanks. Acknowledging this alarm cancels the warning completely, therefore the warning light will not remain on after acknowledging this alarm. Range is 0-500 minutes.	As required. Typically 30-60 minutes is used for changing fuel tank selection.		

Setting	Use	Recommended Setting
Max Flow	Maximum Fuel Flow – Generates a warning when the fuel flow (rate of fuel burn) exceeds this limit. Useful for detecting badly leaking fuel lines, loose connections to fuel injectors, etc. Very useful safety feature for all engines, but especially fuel injected engines. Be sure to use it! Range of Max Fuel Flow Limit is 0-500 gph, in	Set about 10-20% above max fuel flow rate at full takeoff power. Applicable only if the fuel flow option is installed.
	increments of 1 gallon/hour.	
Max OilP	Maximum Oil Pressure. Useful as a reminder to reduce RPM when warming a cold engine, especially in winter conditions, to avoid excessive oil pressure.	98 or less. Max oil pressure displayed by the instrument is 99 psi.
Min OilP	Range is 0-99 psi Minimum Oil Pressure – Essential! Be sure to use this one! Warns of loss of oil pressure. As this is the most serious alarm, some pilots may take drastic action when seeing this alarm. Consider you situation carefully if you get this alarm. An instrumentation failure (sensor failure) is possible, as is complete engine stoppage or anything in between. Use your judgment!	As recommended by the engine manufacturer, or 20 psi.
	Range is 0-99 psi	
Min Crz_OP	Minimum Cruise Oil Pressure - Generates a warning when the oil pressure is below this limit. This limit is active only when the engine RPM is above the min Lim-RPM setting. This allows setting a low oil pressure limit that apply only at higher engine. RPM.	As recommended by engine manufacturer, if available. If not provided, set based on experience.
Max OilT	Maximum Oil Temperature Range 0-300 deg F.	As recommended by engine manufacturer.
Min OilT	Minimum Oil Temperature – Intended for troubleshooting engine problems. Also useful as an "engine not warmed up yet" reminder. Range is 0-300 F.	Set limit based on experience.
Max RPM	Warns when engine exceeds maximum RPM. Range of Max RPM Limit is 0-9990.	Set according to engine manufacturer's recommendation.
Min RPM	Warns when engine RPM falls below this entry. Useful for troubleshooting engine problems. May also be used as a warning that the engine RPM is dropping too low on the landing rollout which could result in engine stall. No warning is generated when the engine RPM is zero. Range is 0-9990.	Set limit based on experience.

Setting	Use	Recommended Setting	
Min Fuel	Minimum Fuel Quantity – Generates a warning when the fuel flow function's fuel quantity drops below this limit.	Set to at least enough useable fuel to provide 30-60 minutes of fuel at cruise power. Applicable	
	Range is 0-500 gallons.	only if the fuel flow option is installed.	
Min Aux (1-6) Max Aux (1-6)	Minimum & Maximum for Aux input. (ideally these limits would use the name the user selected for this input. The displayed value must be either an integer or a decimal number with 1 digit after the decimal, according to the user selections below.) Range is 0-999, or 0-99.9	Set limit as needed depending on the use of the auxiliary input. Some uses of the auxiliary inputs do not require limits (such as manifold pressure) and some do, such as fuel pressure.	
Max H2O	Maximum water temperature limit	Set limit as recommended by engine manufacturer	
Min H2O	Range is 0-300 deg F. Minimum water temperature limit. Intended for troubleshooting engine problems. Also useful as an "engine not warmed up yet" reminder. Range is 0-300 deg F.	Set limit based on experience.	
Max Volt	Maximum Voltage Limit – Allows for detection of failed regulator. Loss of correct voltage regulation resulting in over-charging (and subsequent high voltage) will greatly shorten the life of the battery, and could be dangerous. Range is 0-35.0 volts (increments of 0.1 volts)	Start with 15.6 volts. Lower as much as possible without getting false alarms. Typical limit should be 14.6 Volts.	
Min Volt	Minimum Voltage Limit – Allows for detection of loss of charging. Range is 0-35.0 volts (increments of 0.1 volts)	of Set limit to about 12.8 volts to get immediate alerting of loss of charging, although this will cause low voltage alarm whenever instrument is on while engine is not running. Set to 12.4 volts or less to avoid alarm when engine not running, but still gives alarm shortly after battery discharging has begun.	
Max Carb	Carb temp warning is generated when the carb temp falls between the Max Carb and Min Carb Limit. Range is –30 to +120 deg F	40-60 deg F	
Min Carb	See Max Carb Range is –30 to +120 deg F	0-20 deg F	
Max EGT	Maximum EGT – Not all engines have published limits, nor do all engines require a maximum EGT limit. This alarm can be useful for troubleshooting engine problems also.	Set limit according to engine manufacturer recommendation, or based on experience.	
	Range is 0-1900 deg F		

Setting	Use	Recommended Setting
Min EGT	Minimum EGT – This alarm is active only when the engine RPM is above the entry for EGT-RPM. This alarm is useful to detecting the loss of a cylinder, or for troubleshooting engine problems. Range is 0-1900 deg F	800-1200 deg F, depending on sensitivity desired. If false alarms are consistently generated, reduce the limit to less than 800 deg F, or set to 0.
Lim-RPM	Defines the RPM at which the following RPM dependant limits become active. These are: Min EGT and Min Crz_OP Range is 0-9990 RPM.	Set limit to an RPM slightly less than the RPM used for the MAG check. This allows the Min Volt test to become active during the MAG test to automatically test for charging.
Max EgtSpan	Maximum difference between the highest and lowest EGT. This limit can be used to help detect changes in normal engine operation. It is also useful when leaning using the digital leaning pages, as it is possible to not notice a EGT that is abnormally low when using these pages to lean the engine. (Its more obvious on the bar graph pages.) Range is 0-1900 deg F.	Set this limit based on experience. It may take some trial and error to arrive at a good limit. After establishing a limit that rarely generates alarms, activation of this alarm may indicate developing engine problem.
Max EGT- Inc	Maximum Increase in EGT from the Lean Point. This alarm is active while lean point is active. This alarm will often generate a false alarm when the load on the engine significantly reduced during descent. To avoid this false alarm, reset the Lean Point. (Selecting "Set Lean Page" and "Yes" activates alarm; "Reset" de-activates alarm.) This limit also sets the Horizon red line on the vertical bar graph. Range is 0-1900 deg F.	Set limit based on experience. A small value will allow sensitive detection of EGT increases, which is useful for detection of intermittent problems. Normal operation may require a larger setting to prevent false alarms due to normal EGT fluctuation caused by turbulence or other small power/load fluctuations.
Max EGT- Dec	Maximum Decrease in EGT from the Lean Point. See also Max EGT-Inc description. Range is 0-1900 deg F.	Set limit based on experience. You may find that this limit is significantly different from the Max EGT-Inc. See also Max EGT-Inc description.
Max Crate	Maximum Cooling Rate for CHT – The alarm is provided in degrees/minute, and corresponds to the maximum rate of decrease in CHT. No limit applies to the maximum rate of increase. All cylinders are checked for this limit. Range is 0-255 deg F/minute.	Set limit based on engine manufacturer's recommendation. If no limit is provided, establish a limit based on experience.

Setting	Use	Recommended Setting	
Max CHT	Maximum Cylinder Head Temperature. Often engines will normally operate significantly lower than the engine manufacturer's limit. Consider setting this limit lower than the maximum to get early warning of abnormal CHTs. This limit also sets the Horizontal red line on the vertical bar graph. Range is 0-700 deg F	Set according to engine manufacturer's recommendation.	
Min CHT	Minimum Cylinder Head Temperature. Intended for engine troubleshooting problems. Also useful as an "engine not warmed up yet" reminder. Range is 0-700 deg F	Set limit based on experience.	

Other Limits

Min EFIS Voltage Bus 1 Max EFIS Voltage Bus 1 Min EFIS Voltage Bus 2 Max EFIS Voltage Bus 2 Min EFIS Voltage Bus 3 Max EFIS Voltage Bus 3

As discussed in the GRT Horizon EFIS Install Manual, there may be up to three independent sources of power for the EFIS. These settings allow monitoring of each power source.

Notice that completion of the labels on the Engine Information System Setup page has transferred the names for the EIS Auxiliary inputs to this page.

Engine Performance (requires EIS Manifold Pressure Option)

The GRT Horizon EFIS uses the information in this table to calculate the percent power being produced by your engine based on RPM, manifold pressure, altitude and outside air temperature.

The table is completed using performance data from the engine manufacturer or the aircraft Pilot Operating Handbook (POH).

If power tables are not available from the engine manufacturer,

- 1. Kitplanes magazine March 2007 issue has an article which may be useful or
- 2. power tables may be found on the internet. Be sure to use with caution

The left three columns are used to calculate power based on RPM and MAP

Rated Horsepower Enter the maximum sea level rated horsepower of your engine.

RPM To be valid, at least two RPM entries must be defined and the values must be increasing as you move down the table.

55% MAP Use your engine operating manual to determine the manifold pressure which results in 55% power at the RPM entered on this row, for a standard day at sea level.

75% MAP Use your engine operating manual to determine the manifold pressure which results in 75% power at the RPM entered on this row, for a standard day at sea level.

Note that engine manuals are often written in terms of brake horsepower (bhp), not percent power. To convert bhp to percent power, divide bhp by rated horsepower (for example, for a 160 rated hp engine, 120 bhp is 75 percent power (120/160=.75)).

The right two columns compensate for altitude.

Altitude Enter a list of altitudes. Use altitudes that are roughly evenly spaced from some level above sea level (2000 ft is good) up to some altitude that is above any altitude you expect to fly. Only 1000 ft increments are allowed and they must be increasing as you move down the table.

The entry **Delta HP**Is how much horsepower increases for a given engine condition (RPM and MAP) between sea level and the altitude in the table. To calculate, the horsepower is determined from the performance data for a particular RPM and MAP at sea level **and** at a particular altitude in the table. The difference is entered into the table. Try to use a RPM, MAP that would be typical cruise setting for your aircraft.

The Delta HP entry for 14000 ft in the example table was calculated like this.

From the Lycoming manual, the altitude performance chart indicates that at 14000 ft with RPM of 2300 and MAP of 17 inHg produces 88 hp. At sea level, the same 2300 RPM, 17 inHg produces 65 hp. The difference (88-65=23) is entered into the table for 14000 ft entry.

An example of a filled in table for a Lycoming O-320 is:

O-320 160 HP

RPM	55% MAP	75% MAP	Altitude	Delta HP
2000	22.7	27.6	2000	6.0
2100	21.9	26.8	4000	8.0
2200	21.2	26.0	6000	12.0
2300	20.5	25.1	8000	15.0
2400	19.7	24.2	10000	22.0
2500	19.1	23.6	12000	29.0

RPM	55% MAP	75% MAP	1	Altitude	Delta HP
2600	18.6	23.0	•	14000	23.0
2700	18.3	22.5			

If you do not data for this table, leave it blank. All that happens is percent power is not calculated.

Fuel Data Scale

The Fuel Data Scale provides a way to calibrate irregular shaped fuel tanks. Fuel level senders are often linear devices; their output or resistance changes linearly as the level of fuel changes. If the shape of the fuel tank is uniform, the volume of fuel will increase linearly with the height of fuel. For example, a 20 gallon tank which is 10 inches tall, every inch of fuel is 2 gallons.

If the tank is irregularly shaped, this is not the case. Perhaps the fuel tank is a wet wing so the tank is the shape of the wing. Obviously in this case as the height of fuel changes the quantity of fuel does not change in a uniform manner. The Fuel Data Scale provides a way to correct for this.

Fuel quantity is one of the Aux Inputs on EIS. Since the sender is likely a linear device, it is convenient to configure the EIS Aux Input to show 0-100 (roughly corresponding to 100%) or 0 to H where H is the height of the tank. The entries in this table are then used to correlate the reading from EIS (Probe on the Fuel Data Scale Tables) to the actual fuel (Actual on the Fuel Data Scale Tables). The actual amount must be accurately measured. One method is to drain the tank and incrementally add known quantities of fuel.

There are tables for Left, Center and Right Fuel Tanks and up to 10 entries allowed.

The more entries you have in the table, the more accurate the display. For best results, try to have multiple entries where the shape changes, to get better resolution. For example, if the tank is uniform for the first 5 inches, a couple of entries will suffice for that. If it then changes a lot in the next inch, three or four entries would be good there. If the shape is uniform above that point, just a few entries will work for that portion.

Keep in mind that if this table is used, the fuel levels displayed on EIS may not match those shown on the EFIS.

It is a good practice to provide for an independent fuel quantity measurement, such as a sight gauge or calibrated dipstick.

Note also that fuel quantity discussed here is measurement of the actual fluid. If the EIS Fuel Flow option has been selected, fuel quantity is calculated by the fuel flow transducer. The initial fuel quantity is input either to EIS or EFIS and as fuel is consumed, the fuel remaining is calculated based on fuel flo

Chapter 7 DISPLAY UNIT MAINTENANCE

This set up page is used to install GRT Horizon EFIS software and database updates and other system maintenance tasks. Most fields are for factory use.

EFIS Settings Backup

This feature allows all user settings to be stored or recalled from a file on a USB flash drive. The Backup Directory function will name a directory on the flash drive for easy identification. **Backup All Settings** selection will backup the settings for the display unit you are saving from.

To restore the settings previously saved, select the directory that was named during backup and select **Restore All Settings**.

Load EFIS Software

This feature allows the user to load updated GRT software and databases. This data is available on the GRT website (www.grtavionics.com). The latest Instructions for updating data are also there. Download the data and transfer it to a USB flash drive (memory stick).

The USB flash drive must be installed in the display unit and the unit powered. In multiple display systems the software version must match on each display unit.

To Load EFIS Software:

- 1. Press any button
- 2. Press **NEXT** knob (more than once may be required)
- 3. Press SET MENU knob
- 4. Scroll to **Display Unit Maintenance**, press knob
- 5. Scroll to Load EFIS Software, press knob and turn to start

Copy Terrain (HS/WS only)

This feature allows you to load terrain data, again from the USB flash drive.

To copy terrain data:

Press any knob

- 1. Press **NEXT** knob (more than once may be required)
- 2. Press **SET MENU** knob
- 3. Scroll to **Display Unit Maintenance**, press knob
- 4. Scroll to Copy Terrain Data, press knob and turn to start

To view the terrain data on the MAP page make sure **TERRAIN** is selected with the **SHOW** knob.

Weather Status

To activate the weather module you must have XM Weather service established and the Horizon set to receive incoming signals.

To activate the weather module (assuming activation has been requested from XM):

- 1. Press any button
- 2. Press **NEXT** knob (more than once may be required)
- 3. Press **SET MENU** knob
- 4. Scroll to **Display Unit Maintenance**, press knob
- 5. Scroll to **Weather Status**, change to activate menu
- 6. Scroll to **Activation Mode**, turn to **ON** within 4 hours of XM subscription activation

If the activation is successful the **Service Level** will show the subscribed level and the **Signal Status** should be at least **Marginal** or better for good reception.

7. Turn **Activation Mode** to **OFF**. If left **ON** weather data will not show on **MAP** pages.

To find the unit serial number, select the PIC Calibration Data to find Serial Number.

Chapter 8 AHRS MAINTENANCE

This page is primarily for factory use. The fields of interest to the user are:

AHRS Software Version

Should correspond to the latest stable version as listed on the GRT website.

Load AHRS Software

To load updated AHRS software,

- 1. Press any button
- 2. Press **NEXT** knob (more than once may be required)
- 3. Press **SET MENU** knob
- 4. Scroll to AHRS Maintenance, press knob
- 5. Scroll to Load AHRS Software, press knob and turn to start

True Airspeed Corrections

The GRT Horizon EFIS does not provide any means to correct the indicated airspeed, as this would result in the GRT Horizon EFIS showing a different indicated airspeed than other indicators that may be installed in the airplane.

However, the GRT Horizon EFIS does provide a means of correcting the true airspeed that it displays in the PFD data box, and which is used in the wind calculation. Since the wind calculation is based on the difference between GPS groundspeed, and true airspeed, it is quite sensitive to true airspeed errors, and a significant improvement in the accuracy of the winds can be achieved by performing this calibration for some airplanes. The correction is made using **True Airspeed Corrections** selection. The instructions are in the Calibration section of the GRT Horizon EFIS Users Guide.

Altimeter Calibration

This Settings page is used to recalibrate the altimeter. Instructions are in the GRT Horizon EFIS User Guide.

Angle of Attack Calibration

The Settings page (Primary Flight Display) is used to calibrate the Angle of Attack. Instructions are in the GRT EFIS User Guide.