TECICE- HC05

USER'S MANUAL

68HC05 In Circuit Emulator



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1. INTRODUCTION

Thank you for choosing the TECICE-HC05 emulator development tool. We think that as you become familiar with the product you will feel that you have made a sound investment, one that will pay for itself over and over again on a wide variety of development projects. Please keep in mind that we welcome your feedback regarding your experiences using the product and your suggestions for improvements. Please keep in touch and let us know what your doing with the TECICE-HC05.

1.1 IMPORTANT NOTICES

- ?? Make sure that you have read the warranty, liability and software license statements on page 2 of this manual. Any use of this product constitutes acceptance of the terms and conditions of those statements. If you do not agree with these terms and conditions return the product at once. The purchase price will be refunded.
- ?? FOLLOW THE INSTRUCTIONS IN SECTION 2. GETTING STARTED. This will take only a few minutes, but it will save you a tremendous amount of time and trouble later on.

?? USE A COMMON POWER STRIP FOR BOTH THE TECICE AND YOUR TARGET SYSTEM.

Care must be taken to insure that both the TECICE and your target system are powered on/off together to prevent CMOS latch up, a condition that causes a CMOS chip to draw a large amount of current and possibly damage the chip or other chips connected to it. CMOS latch up occurs when a CMOS chip gets an input voltage that exceeds the power pin voltage of the chip. When either the TECICE or your target system is powered on and the other is off, <u>CMOS latch up can occur</u>.

THIS CAN BURN OUT CHIPS INSIDE THE EMULATOR OR ON YOUR TARGET SYSTEM!!!

Follow this procedure to get the best results. Use a common power strip for both the TECICE and your target system. Turn the power on/off using the switch on the power strip so as to turn everything on/off at once.

IF CMOS LATCH UP OCCURS, TURN ALL POWER OFF IMMEDIATELY!!!

?? The TECICE-HC05 monitor program has no provisions to update the COP watchdog timer. Therefore, if you enable the watchdog timer, the system will reset and lock up. TO GET OUT OF THIS LOCK UP, PRESS THE MASTER RESET.

1.2 TECI BUG POLICY

TECI will <u>NOT</u> ship a product that has a known bug that prevents the product from performing its intended function! However, sometimes there are bugs in a product that may be a nuisance to the user, but do not prevent the product from performing its intended function. Furthermore, the risk of introducing new, more serious and unknown bugs into the product by performing a <u>quick</u> <u>fix</u> may not justify an immediate and untested fix. TECI will sometimes ship a product that has these so called "nuisance bugs" if we feel that an acceptable workaround exists and we feel that the benefit to the user far outweighs the nuisance.

1.3 GENERAL DESCRIPTION

TECICE-HC05 is a real time in circuit emulator designed to emulate most members of the Motorola 68HC05 family of single chip microcontrollers. TECICE-HC05 is an acronym made up from the letters "TECI", "ICE" and "HC05". TECI stands for The Engineers Collaborative, Inc., ICE stands for in circuit emulator and HC05 stands for the Motorola MC68HC05 family of microcontrollers.

TECICE-HC05 can be used with any host computer running terminal emulation software with the ability to download files over a directly connected RS-232 interface at 9600 baud. TECICE-HC05 is controlled by standard ASCII commands and could be used with just a dumb terminal if it weren't for the fact that some means of downloading object code files generated from compilers/assemblers is required by real applications.

The emulator can be configured by the user to emulate most members of the 68HC05 family of microcontrollers. To change the configuration of the emulator the user must install the proper emulation processor and emulation probe, and choose the proper internal jumper options for his/her application.

For those users that will be using the emulator with IBM PCs or compatibles, a cross assembler program and a special terminal emulation program is provided. The cross assembler program is called WASM05.EXE and the terminal emulation program is called WTT05.EXE. These programs are fully described in the "WASM05 & WTT05 Manual". WASM05 is a Windows hosted Text Editor / 68HC05 Macro Cross Assembler. WTT05 is a Windows hosted Emulator Control Program with Source Level Debugging. Both of these programs are part of an integrated set of software and hardware tools provided by TECI to facilitate the development of 68HC05 single chip microcontroller applications.

The example/demo programs assembled in the "WASM05 & WTT05" and the "GETTING STARTED" sections of this manual assume use of the WTT05 program.

1.4 TECICE-HC05 EMULATOR SPECIFICATIONS

- ?? Dimensions: 7.3" Wide X 9.5" Deep X 1.5" High
- ?? Weight: 4 pounds

- ?? Power Requirements: 12 Volts AC 50/60 Hz at 1 AMP.
- ?? Interface: RS-232 9600 Baud, 8 data bits, 1 start bit, 1 or 2 stop bits, no parity.

1.5 EQUIPMENT REQUIRED

?? IBM PC BASED SYSTEMS

System Requirements: At least a 486 class PC running Windows NT, Windows 95 or Windows 3.1 with at least 8MB ram, 4 MB of free hard disk space, a 3.5" floppy disk drive and one serial port configured as COM1 or COM2. An SVGA monitor is recommended. Also required is a serial port cable that connects from your COM1 or COM2 serial port and has a male DB-25 connector for mating with the TECICE-HC05. Standard modem cables will work with the TECICE-HC05.

?? OTHER HOST COMPUTER SYSTEMS

Other host computers must have an RS-232 serial port and terminal emulation software that is capable of making a direct connection to the RS-232 serial port at 9600 baud, 8 data bits, one or two stop bits, one stop bit and no parity. This software must send characters that are typed at the keyboard out the serial port and display incoming characters from the emulator on the video screen. The software must also be capable of downloading standard text object code files to the emulator. Most standard modem communication programs will work. Also required is a serial port cable that connects from the serial port and has a male DB-25 connector for mating with the TECICE-HC05. Standard modem cables will work with the TECICE-HC05. Instead of connecting the cable to a modem, it is connected to the emulator.

You may use the WASM05 Editor/Macro Cross Assembler Program or another text editor and 68HC05 cross assembler program. The text editor program is used for entering and editing programs in 68HC05 assembly language. The 68HC05 cross assembler program must create object code files in Motorola S record or Intel HEX format.

2. GETTING STARTED

Please read and follow the directions in this section before you go any further!

Before you do anything else, please take just a few moments to familiarize yourself with this section, the WASM05 and WTT05 software and your new emulator. We specifically designed this section to give you a lot of information in a very brief period of time. Working through the installation and tutorial now will give you a big advantage in understanding how these programs work together to make your emulator a powerful tool!

2.1 SOFTWARE PREPARATION

2.1.1 Installing WASM05 And WTT05

The software is supplied on a 3 1/2 inch floppy diskette. The file supplied on this diskette is named SETUP.EXE. This is a self-installing, Windows executable file that will install all of the necessary files when invoked.

To install the software, place the distribution diskette in a floppy drive and run the program A:SETUP.EXE or B:SETUP.EXE from within Windows and follow the on-screen instructions.

*** Important Notice ***

If you have trouble running SETUP.EXE, try running the program with the /M command line switch as follows: >A:SETUP.EXE /M<enter> This is the manual installation mode which will prompt you for the location of needed directories, etc.

After running SETUP.EXE you should find the following files in the installation directory(C:\WASM05 is the default).

WASM05.EXE - Editor/Macro Assembler executable file.
WASM05.HLP - Editor/Macro Assembler on-line help file.
WASM05.INI - Editor/Macro Assembler initialization file.
WTTDEMO.05P - Demo 68HC05 project file.
WTTDEMO.ASM - Demo 68HC05 project source code file.
WTTDEMO.LST - Demo 68HC05 project include file.
ITEST.INC - Demo 68HC05 project include file.
D68HC05.05P - Project file for showing WASM05 source code examples.
D68HC05.ASM - File showing WASM05 source code examples.
UNWISE.EXE - Uninstall executable.
INSTALL.LOG - Installation log file - required by the uninstall program.
WTT05.EXE - Emulator control program executable file.



WTT05.HLP - Emulator control program online help file. WTT05.INI - Emulator control program initialization file.

*** Important Notice ***

FONT SIZE: If the text is not displayed as desired, the font size may be changed from within WASM05 by clicking Options|Font and changing the font size.

2.1.2 Uninstalling WASM05 & WTT05

To uninstall the software, double click on the UNWISE.EXE program in the installation directory. This program will read the INSTALL.LOG file and remove all files that were installed with the SETUP.EXE program.

2.2 HARDWARE PREPARATION

After unpacking the emulator, inspect the emulation probe to make sure none of the pins are bent or shorted together. Make sure that there are no loose components rattling around inside the emulator which would indicate mishandling during shipping. Then, plug the power connector from the wall mounted transformer into the back of the emulator where it is marked 12 VAC, and plug the transformer into a 120 VAC outlet. The Ready lamp on the front panel should come on. If it does not, you should open the emulator housing and make a closer visual inspection for components that may have shaken loose during shipping. The Ready lamp should go off when the Master Reset switch is pressed and come back on when the Master Reset switch is released. Connect the emulator to the host computer via an RS-232 serial cable, the same type of cable used for external modems will work.

For the example session it will not be necessary to connect the emulation probe to any target system.

2.3 WASM05 & WTT05 TUTORIAL

2.3.1 Using WASM05

First, invoke the WASM05 editor/assembler program by clicking on its chip icon. The first time you use the program, it should come up with the WTTDEMO.05P project already loaded into the editor. This is an example project for use with this tutorial. The project name and active editor file name are shown in the title bar of the main program window. If the program doesn't come up with the WTTDEMO.05P project loaded, you can load it with the File|Open Project menu item. At this time the project consists of two files, the WTTDEMO.ASM main source file and one include file named ITEST.INC . You can switch the editor back and forth between these files by clicking on the file tabs. Try It!

To see what each of the speed buttons on the button bar do, move your mouse pointer over each button and hold it there for about a second. A yellow help hint box should appear near the mouse pointer describing the button function. A little more detailed description appears on the status bar at the bottom of the screen. Once you get used to what the speed button functions are, you can turn the help hints and status line help hints off by unchecking the appropriate Option menu items. The operation of the text editor portion of WASM05 is similar to most Windows text editors; so we won't go into how to edit text here. You can use the online help for this purpose or, better yet, just experiment on your own. If you always click on the "Save Project" speed button before exiting the program, WASM05 will come up configured exactly as it was when you last used it.

Before we get too far into the tutorial we need to check something. We are going to run the WTTDEMO program on your emulator during this tutorial by calling the emulator control program WTT05 from WASM05. To make sure that this works properly, we <u>may need to change the program</u> depending on your emulator configuration. So please read the

*** IMPORTANT NOTICE ***

message that appears in the header at the beginning of the WTTDEMO.ASM file and follow the instructions there.

It is now assumed that, if your emulator is configured for a 68HC05 chip that has a 16K byte memory map, you have set the "target_has_16k" equate to 1 in the WTTDEMO.ASM file as instructed above. If you haven't, your emulator will not run the WTTDEMO program properly!

WASM05 source code files use standard Motorola 6805 op-code mnemonics and source file syntax with a few industry standard enhancements. See the online help for complete documentation. Also, a project named D68HC05.05P was included in the distribution files. This is a project that shows the proper usage of all 68HC05 mnemonics, pseudo ops and source file syntax.

Now let's assemble the WTTDEMO project. To do this click the large "£6805" speed button on the button bar. Two errors were intentionally left in the project files to show what happens when

errors are encountered by the assembler. Note that an error window opened that has a list of the errors. The first error is an "unrecognized opcode mnemonic" error in line 40 of file WTTDEMO.ASM . Also note that the cursor in the WTTDEMO.ASM file was placed at the beginning of line 40, the line that contains the first error. If you click on the "GoTo Next Error" button, the editor cursor goes to the next error, which is in line 7 of the include file ITEST.INC . When errors are encountered, you can find and fix them easily by using the "GoTo Next Error" button and the information in the error window.

Now lets fix the errors and reassemble the project. Click on the "GoTo Next Error" button until the editor cursor is at the line containing the first error: line 40 of file WTTDEMO.ASM . Note that the op code mnemonic in that line is "staaa", an improper 6805 mnemonic. Obviously, the proper 6805 mnemonic is "sta"; so change "staa" to "sta". Click on the "GoTo Next Error" button. This is another "unrecognized opcode mnemonic" error in line 7 of ITEST.INC . Here, the opcode mnemonic reads ".rts" instead of "rts". Change ".rts" to "rts" and click on the "GoTo Next Error" button. This error just informs the user that the assembler could not complete its second pass because of errors encountered during pass one. We do not have any corrections to make associated with this error.

Click the " \ll 6805" speed button to reassemble the project. Note that this time no error window appears, so no errors were encountered and the project assembled correctly. To view the files created by the assembler, click on the Options menu, then on the Project Options submenu. The Project Options dialog box opens. Check the "Auto Load Output Files" checkbox; then click OK. Click the " \ll 6805" button again and note that after assembly there are now four files loaded into the editor. The two new files were the files created by the assembler and are WTTDEMO.LST, the listing file, and WTTDEMO.S19, the object code file in Motorola S-record format. Click on their tabs to view these files. The WTTDEMO.LST file is used by the WTT05 program to control the emulator and the WTTDEMO.S19 file is used to program 68HC05 chips when the program is debugged.

We are now ready to use the WTT05 program and the TECICE-HC05 emulator to run and test the WTTDEMO program.

2.3.2 Using WTT05

To invoke WTT05 from WASM05, click on the "D", run debugger, speed button. The "Debugger Command Line" under Options|Project Options menu in WASM05 determines which program runs when this button is pressed. If you installed these programs in the default directories, the Debugger Command Line entry should be "c:\teci\wtt05.exe c:\teci\wttdemo.lst

*** Important Notice ***

FONT SIZE: If the text is not displayed as desired, the font size may be changed from within either program by clicking Options|Font and changing the font size.

Connect the emulator to your PC with a standard serial cable such as would be used with an external modem or serial printer. The emulation probe should <u>NOT</u> be plugged into a target system for this tutorial!

The first time you run WTT05 you must configure a serial port for WTT05 to use to communicate with the emulator. You do this by entering the "Com Setup" dialog box under the Communications menu. Select a com port and click OK.

To check communications with the emulator, plug the wall transformer that powers the emulator into a power strip with an ON/OFF switch and power the emulator on. Each time the emulator is powered on the following message should appear in the WTT05 Communications Window:

TECICE-HC05 Version x.x Checking Emulator Memory...Memory is functioning.

The "Checking Emulator Memory..." self test is only done on a cold start up. So you will have to leave the emulator off for several seconds to get this message. If you get this message, at least one way communications is established. Press the "Download" speed button; if two way communication is working, you should see activity in the communications window as the object code file is downloaded to the emulator. (You can find the "Download" button by moving the cursor over each button until the help hint box appears.)

Under the WTT05 Options menu, make sure the WASM05, Yellow Hint Boxes, and Status Line Help Hints options are checked.

Click on the "Download" button to download the WTTDEMO program to the emulator. Click on the "Reset & Run" button to run the WTTDEMO program. Note that the emulator "Ready" light goes OFF, the "Running" light goes ON and the all of the WTT05 speed buttons are disabled except for "STOP". This indicates that the emulator is running a user program. A "Running user program..." message appears in the communication window.

Click on the "STOP" button and note that the emulator "Running" light goes OFF, the "Ready" light goes ON and the WTT05 speed buttons become active again. This indicates that the emulator and the WTT05 program are ready for commands.

Click the "Run" button, then the "STOP" button several times and note that each time the "STOP" button is pressed the Code Window is updated to show where the program stopped. The blue PC arrow graphic points to the next program instruction that will be executed when the program is again allowed to run. Also note that the register display on the left side of the button bar is updated to show the current value of all the CPU registers.

Press the "STEP" button. This sends a single step command to the emulator. Note that WTT05 executes a single program instruction and then updates the screen. Press the "STEP" button several times to step the program through its main loop and one subroutine call.

Press the "ANIMATE" button to see an animation of the program. Animate is a continuous sequence of single steps. Press the "STOP" button.

Highlight the "power_on_reset" line in the code window by clicking on it. Then press the "Reset and Run to Highlighted Line" button. This performs a user reset of the CPU to put all internal registers and I/O ports in a known state and sets a breakpoint at address \$800. After execution, the PC arrow should go to this line, indicating that the operation was successful.

Now highlight the "main_loop" line by clicking on it; then press the "Run to Highlighted Line" button. This runs the program from where the PC was (\$800) to the highlighted line (\$80A) without resetting the CPU.

Now highlight the "bra main_loop" at address \$810; then press the "Set PC to highlighted value" button. Note that this sets the PC value to \$810. There are other ways to change the PC value. You can just edit its value in the register display area at the left side of the button bar. If you have entered a valid PC value, the code window will be updated to show the code at the new PC value. You can change all CPU register values by editing their values in the register display edit boxes.

If you want to change one of the condition code flags, the "Z" flag for example, just click on its present value and the value will toggle.

The "Manual Commands" window is for entering emulator commands that don't have a corresponding speed button. For example, to send a display memory(dm) command to the emulator, click inside the Manual Command window and type "dm 0 20 <enter>". A memory dump from address 0 to address \$20 will appear in the communication window. A complete list of emulator commands is in the Help File.

Click in the "code" window in the margin to the left of any code-generating line of code; for example, click on the "power_on_reset" line at address \$800. Note that a STOP sign graphic appears in the margin. A breakpoint is now set on this line of code. Set additional breakpoint at addresses \$810 and \$814. Press the "Reset & Run" button and note that program execution stops at the first breakpoint. Press the "Run" button and note that the program stops at address \$810 breakpoint. Press the "Run" button again to have the program stop at the address \$810 breakpoint. If one or more of the breakpoints are not shown on the screen, you can cycle through them by pressing the "STOP" button. The "STOP" button stops program execution of the user program if the user program is running, and cycles through the breakpoints if the user program is not running. Up to 5 breakpoints may be set this way. To remove breakpoints just click on the stop signs. Remove all breakpoints now.

WTT05 has a neat feature called the "Watch Wizard". The Watch Wizard is an intelligent watch point that is used to display the present value of program variables. The Watch Wizard data appears on the status line at the bottom of the screen. However, status line help hints overwrite the Watch Wizard data; so to make sure that the data is in view, you must not position the cursor



over a control that activates a status line help hint. Or, you may disable status line hints by unchecking it in the Options manu.

The Watch Wizard shows the variable address, its name and its present value in hex, decimal and binary. The variable that is displayed depends on which line of code is highlighted in the code window. To change the present value of the Watch Wizard variable, simply edit its value in one of the value edit boxes.

Click on the "inc count_up" line at address \$80C to highlight that line of code. Note that the Watch Wizard now displays the value of the count_up variable at address \$50. Now, click on the "dec count_down" line at address \$812 to highlight that line of code. Note that the Watch Wizard now displays the value of the count_down variable at address \$51. When you highlight a line of code that references a variable, the current value of that variable is shown by the Watch Wizard.

Click on the "inc count_up" line at address \$80C again to highlight that line of code and press the "Reset and Run to Highlighted Line" button. The Watch Wizard should show the current value of "count_up" to be zero. Now, repeatedly press the "Run to Highlighted Line" button and note that the value of "count_up" increases by one after each press of the button. At each button press, the program starts running at address \$80C and runs completely around the main_loop, stopping back at the "inc count_up" line at address \$80C where the Watch Wizard displays the changed value of count_up.

If you want to look at more than one Watch Point at a time, use the Watch Window speed button on button bar instead of the Watch Wizard at the bottom of the screen.

You have now completed the WASM05 & WTT05 Tutorial. From this point on, you should be able to utilize both programs successfully with the assistance of the online Help program.

*** Important Notice ***

If you are using the C6805 C-Compiler with WTT05, you must select the compiler listing file option that places both C and the generated assembly code in the listing file. You must also check the C6805 option under the WTT05 Options menu.

2.3.3 Converting Tasm05 Projects To Wasm05 Projects

Before going any further in this section, it is very important that you complete the Tutorial and become familiar with the basics about WASM05. Having accomplished this, if you have developed project(s) in TECI's TASM05 Cross Assembler Program, you may follow these steps to convert each project to WASM05.

- 1) Invoke WASM05 and open a New Project (File|New Project).
- 2) Click on the "Add File to Project" speed button. Find the directory your TASM05 files are in and add each file, one at a time.
- 3) Once you have added all of your files, use File|Save Project As to save the project.

Remember, (a) projects <u>must</u> be saved with the .05P file extension; and (b) the main source code file of the project <u>must</u> have the same file name as the project file with an extension of .ASM. This is how the assembler knows which file to assemble first.

Example: If the project file name is **DEMO.05P**, then the main source code file must be named **DEMO.ASM**. All other project files may have any name/extension.



3. TECICE-HC05 USER'S GUIDE

3.1 GENERAL CIRCUIT DESCRIPTION

3.1.1 Physical Description

The circuitry of the TECICE-HC05 is contained on two 7" X 9" double sided printed circuit boards mounted one on top of the other inside the emulator housing. These pcb's are called the top and bottom boards. The bottom board contains the I/O ports, power supply, RS-232 serial port circuits, clock generator, reset circuit and operator control switches and indicators. The top board contains the control processor, emulation processor, memory, address decoder, breakpoint logic, map switch logic, configuration jumpers and emulation probe connections. In normal use the user does not need access to the bottom board. All user configurable options are accessible on the top board.

3.1.2 Electrical Description

Schematic diagrams of the two emulator circuit boards are included in Appendix A. The emulator consists of two 68HC05 control processors, the control processor and the emulation processor.

Control Processor - Schematic Sheet 2 of 8

The control processor (U5) is a 68HC705C8 single chip microcontroller that controls the emulator by performing all communications with the host computer via the RS-232 port, communicating with the emulation processor via U20 and U21, controlling the breakpoint circuits and interfacing with the front panel controls and indicators. The control processor receives commands from the host computer, checks the commands for errors, executes commands by passing instructions and data to and from the emulation processor or other circuits, and reports the results of the commands back to the host computer.

Emulation Processor - Schematic Sheet 3 of 8

The emulation processor has two functions to perform and two memory maps, one memory map for each function. 1) The emulation processor runs user programs from the user memory map. 2) The emulation processor executes commands issued to it from the control processor. It performs this function from the monitor memory map. The emulator has map switch logic to switch between the two memory maps.

There are two sockets on the top board for the emulation processors. U29 is a 40 pin dip socket for the C series processors and U30 is a 52 pin PLCC socket for the B series processors. **Only on of these sockets may be occupied at a time.** Configuring the TECICE-HC05 to emulate a specific processor consists, in part, of populating the correct emulation processor socket.

Instead of using the emulation processor in its normal single chip mode of operation, TECICE-HC05 forces the emulation processor into a special mode which allows the address, data and control busses to come outside the chip. This allows the address and data busses, and memory to be accessed by the emulator for program debugging purposes. The address, data, and control busses come out of the emulation processor on what would normally be I/O ports A, B and C. These I/O ports are reconstructed by the I/O port circuitry on the bottom board of the emulator.

Emulator Memory - Schematic Sheet 5 of 8

U25 is an 8K X 8 eprom that contains the emulation processors' control program. This eprom is located in the monitor memory map. The emulation processor runs this program when it is in the monitor mode (when the emulator is performing commands issued by the host computer).

U26 is a 32K X 8 static ram memory chip. Part of this chip is used for user ram memory and user pseudo rom. This is where the users' program resides during emulation. The other part of this chip is used for scratch pad ram and stack space for the monitor program. Also on this schematic sheet the stack capture register (U19) is used by the emulator to find the value of the stack pointer during debugging. The SWI jammer (U22) is used by the breakpoint circuits to force a software interrupt which causes a map switch from the user map to monitor map for debugging purposes. The option register (U24) is used to emulate the dynamic ram/rom memory switching capability of the 68HC05C8 chips. The A-B buffer (U20), the B-A register(21), the A-B and B-A flags are used for communications between the control and emulation processors.

Breakpoint Circuits - Schematic Sheet 6 of 8

The breakpoint control circuit of the emulator consists of a 16 bit address comparator (U17 & U18), a 16 bit pass counter (U3 & U4), an SWI detector (U10) and programmable logic device (U9). This circuit allows the emulator, for example, to break on the 65000th pass around a loop.

Map Switch - Top Board Schematic Sheet 7 of 8

There are two map switches, a temporary map switch (U13) and a permanent map switch (U12). When a user program is running the memory map is "permanently" switched to the user map. When a breakpoint is reached in the user program the memory map is "permanently" switched to the monitor map. During the execution of commands from the host computer it is sometimes necessary for the emulation processor to switch memory maps for only a few cpu cycles. This is called a temporary map switch. A temporary map switch would occur, for example, during the modify memory command. Temporary map switches occur when the emulation processor fetches an instruction from the monitor map, executes the instruction in the user map then returns to the monitor map for the next instruction.

Clock Circuit - Bottom Board Schematic Sheet 2 of 6

The emulation processor clock must be a TTL level signal. Therefore it can not come from the target system if the target system uses the crystal clock or RC clock options. If clock frequency is critical to proper target system operation then the emulation processor clock must be the same as the target system clock would be when there is an actual 68HC05 in the target system instead of the emulation probe. TECICE-HC05 provides four ways to generate the clock signal. 1) The clock can be derived from the emulator's 8MHZ oscillator and divider (X1 on the top board and U6 & U7 on the bottom board). The divider value can be selected by the Clock Freq. rotary switch on the rear panel of the

emulator. Using this method, 8Mhz, 4Mhz, 2Mhz, 1Mhz, .5Mhz, .25Mhz and .125Mhz clock frequencies can be selected. 2) The clock source can be from the External Clock input on the rear panel of the emulator. 3) The clock source can be from the target system provided that this clock is a TTL level signal. 4) The emulators clock oscillator (X1) can be replaced by the user to match his specific requirements.

3.2 TARGET SYSTEM CONNECTION

Connection from the TECICE-HC05 emulator to the user target system is made via the emulation probe. The emulation probe replaces the 68HC05 microcontroller chip in the target system. Four types of emulation probes work with TECICE-HC05. 1) 40 pin DIP, 2) 44 pin PLCC, 3) 52 pin PLCC and 4) 48 pin DIP.

See the CONFIGURING THE EMULATOR section for more information on this subject.



3.3 LIMITATIONS

In some ways the emulator will not behave exactly like the 68HC05 microcontroller chip that is being emulated. The user must be aware of these differences and allow for them.

No memory limitation checking is done to assure that the user program will fit in the amount of RAM/ROM space available in the device being emulated. The user must know the memory map of the device being emulated and make sure that only valid RAM/ROM memory locations are used.

The emulator uses 74HC126 and 74HC244 CMOS TTL type logic devices to reconstruct I/O ports A, B and C as shown on bottom board schematic diagram sheets 3, 4 and 5. These devices present a different amount of loading to the I/O pins and have different drive capability than the actual 68HC05 chip. Also, the emulator I/O ports are wired differently than an actual 68HC05 chip in such a way that, during a read operation of an I/O port pin that has been set up as an output, the emulator will read a logic one or zero depending on the actual voltage level on the I/O pin and the threshold of the 74HC244 device. This differs from actual chip performance in that the result of a read operation, under this circumstance, in the actual chip is not dependant on I/O pin loading as it is in the emulator. The following is a comparison of the I/O pin characteristics of a typical 68HC05 chip and the emulator.

Output Low Voltage Output High Voltage	-	<u>TYPICAL 68HC05 CHIP</u> 0.4 v max @ 1.6ma 4.2 v min @ -0.8ma	<u>EMJLATOR</u> 0.33 v max @ 6ma 4.6 v min @ -6ma
Input Low Voltage	-	1.0 v max	1.5 v max
Input High Voltage		3.2 v min	3.2 v min

Breakpoints are implemented by forcing an SWI to occur. This puts five bytes on the user's stack. This leaves only 59 bytes of usable stack space instead of 64.

The emulator does not use power from the target system. Therefore the power consumption of the target system will differ under emulation than it is when an actual microcontroller chip is used.

The emulator does not use the target system clock source when the target system uses the crystal or RC clock modes. Therefore, if the emulator's clock frequency has not been configured to match that of the target system, program timing may be different when emulating.

3.4 CONTROLS, INDICATORS AND EXTERNAL CONNECTIONS

3.4.1 Front Panel



FIGURE 1 - TECICE-HC05 FRONT PANEL

Figure 1 shows the front panel emulator; each of the controls and indicators are described below.

MASTER RESET SWITCH

This is a momentary action pushbutton switch that, when pressed, resets the control and emulation processors, the target system, and user I/O, places the emulator in the monitor mode and sends the monitor prompt to the host computer.

USER RESET SWITCH

This is a momentary action pushbutton switch that, when pressed and released, resets the emulation processor, the target system, and user I/O and forces a map switch to the user memory map, the emulation processor fetches the reset vector from the user map and begins execution of the user's program.

ABORT SWITCH

This is a momentary action pushbutton switch that, when pressed and released, forces a return to the monitor mode from the user mode provided proper operation of user code. The abort switch works like a manual breakpoint. The abort switch does nothing when the emulator is in the monitor mode.

RUNNING LAMP

This is an LED that is ON when the emulator is in the user mode and OFF when the emulator is in the monitor mode. It indicates when the users' program is running.

READY LAMP

This is an LED that is ON when the emulator is in the monitor mode and the control processor is ready to receive a command from the host computer. The READY lamp is OFF when a user program is running or when the control processor is executing a command from the host computer.

3.4.2 Rear Panel



FIGURE 2 - EMULATOR REAR PANEL

CLOCK FREQUENCY SELECTOR SWITCH

The clock frequency selector switch is a ten position rotary switch which selects the emulation processor clock rate. For instructions on how to select a given clock rate, please see Section 3.5.6 (Changing the Clock Frequency) later in this manual.

EXTERNAL CLOCK

The external clock input provides the clock input connection when the clock frequency selector switch is in the external position(switch position 7).

CLOCK TP

This is a clock test point. It provides a convenient place to attach an oscilloscope or frequency counter in case the user needs to verify what clock rate has been selected.

RS-232

This is a DB-25 female connector that connects the serial port of the host computer to the emulator. The bottom board schematic diagram Sheet 2 of 6 shows how this connector is wired. For IBM PCs, the same serial cable that is used with external moderns can be used. Also, 25 conductor flat ribbon cables with no cross overs or loopbacks work. The cable should have a connector that mates with the serial port of the host computer on one end and a DB-25 male connector on the other end for mating with the emulator.

EXTERNAL BP

This is the external breakpoint input. The user can have external circuitry cause a breakpoint when emulating by pulling this TTL input low. The breakpoint will occur on the first LIR (load instruction register) cpu cycle after the external bp input goes low. This input must remain low until the LIR cycle (about 26 clock cycles worst case) and must go back high before the emulator reenters the user mode after the breakpoint has occurred.

12 VAC

This is the power input. It normally has 12 volts AC at 60/50 cycles from the wall mounted transformer supplied with the emulator. The connector inside the emulator is a 2.5mm mono phone jack that accepts standard 2.5mm mono phone plugs.

3.5 CONFIGURING THE EMULATOR

3.5.1 Factory Default Configuration

TECICE-HC05 is shipped from the factory in one of the following configurations depending on the emulation processor ordered.

CONFIGURATION OPTION	68HC705C8A EMUL PROC	68HC805B6 EMUL PROC	68HC705C9A EMUL ROC	68HC805B16 EMUL ROC
Emulation Probe	40 PIN DIP	52 PIN PLCC	40 PIN DIP	52 PIN PLCC
Clock Frequency	4.0 Mhz	4.0 Mhz	4.0 Mhz	4.0 Mhz
J1 Jumper Position	C8 OR C9	NOT C8 OR C9	C8 OR C9	NOT C8 or C9
J2 Jumper Position	NOT EXTAL	NOT EXTAL	NOT XTAL	NOT EXTAL
J3 Jumper Position	C8 Position	C8 Position	C9 Position	C9 Position
J4 Jumper Position	NOT B6	B6 Position	NOT B6	B6 Position
J5 Jumper Position	INSTALLED	INSTALLED	REMOVED	REMOVED
J6 Jumper Position	NOT B6 TYPE	B6 TYPE	NOT B6 TYPE	B6 TYPE
J7 Jumper Position	NOT EDGE	NOT EDGE	NOT EDGE	NOT EDGE

3.5.2 Changing The Configuration

Changing some of the configuration options requires removal of the housing cover to provide access to the top board of the emulator. To do this, remove the two screws from the rear panel, remove the rear panel and bezel; then slide the housing cover toward the rear until it can be detached from the extruded aluminum base. Figure 3 shows component placement on the top board with important configuration components noted.



3.5.3 Changing Emulation Processors

There are two sockets for emulation processors. Only one of them can be populated at a time. Damage to the emulator might occur if both sockets are populated and power is applied. U29 is the socket for 40 pin dip emulation processors and U30 is the socket for 52 pin plcc processors. To change emulation processors, 1) remove the present processor and install the new one in the appropriate socket, 2) make sure that the appropriate emulation probe is installed, 3) check the option jumpers described below to insure that they are in the correct position, and 4) make sure that the clock speed setting and clock source are correct.

3.5.4 Changing Emulator Probes

Currently four types of emulation probes are supported by TECICE-HC05. They are 1) 40 PIN DIP, 2) 44 PIN PLCC, 3) 52 PIN PLCC and 4) 48 PIN DIP. To change an emulation probe:

- 1) Remove the two screws that hold the front panel of the emulator in place, remove the aluminum front panel and set it aside.
- 2) Slide the housing cover toward the front until it is free of the aluminum base of the housing and set the housing cover aside.
- 3) Disconnect the old emulation cable/s from the top board by unplugging it/them from top board connectors P2 and P3 or P4.
- 4) Slide the old emulation cable/s through the opening in the bezel and set the old cable/s aside.
- 5) Thread the new emulation probe cable/s through the opening in the bezel and attach the connector/s to the appropriate top board connectors as described below.
- 6) Replace the housing cover. Replace the bezel and aluminum front panel with the front panel screws.

?? 40 PIN DIP EMULATION PROBE

This probe has a 40 conductor ribbon cable with a 40 pin dip connector on one end for plugging into the target system processor socket. On the other end, it has a connector that attaches to P4 on the emulator top board.

?? 44 PIN PLCC EMULATION PROBE

This probe consists of an adapter that attaches to the target system end of the 40 PIN DIP EMULATION PROBE and converts from 40 pin dip to 44 pin plcc. This adapter just plugs onto the 40 pin dip probe; there is no need to open the emulator housing to install this adapter.

?? 52 PIN PLCC EMULATION PROBE

This probe consists of two 26 conductor ribbon cables with connectors on one end that attaches to P2 (the longer cable) and P3 (the shorter cable) on the emulator board. On the target system end of these cables there are connectors that attach to a 52 PIN PLCC EMULATION PROBE adapter that, in turn, plugs into a 52 pin plcc socket on the target system.

?? 48 PIN DIP EMULATION PROBE

You can change from a 52 pin plcc probe to a 48 pin dip probe by changing the adapter on the target system end of the two 26 conductor ribbon cables without opening the emulator housing. The 48 pin dip probe consists of the same two 26 conductor ribbon cables as the 52 pin plcc probe and they attach to the emulator board at the same points. Only the adapter is different.

3.5.5 Changing The Clock Frequency

Changing the clock frequency usually consists of setting the clock freq. selector switch to the desired divider value. The TECICE-HC05 is shipped from the factory with an 8 Mhz oscillator installed in the X1 socket on the top board. X1 may be changed by the user to obtain other clock rates as shown in the chart below.



FIGURE 4 - CLOCK FREQUENCY SELECTOR SWITCH

The clock frequency selector switch is a ten position rotary switch which selects the emulation processor clock rate. To select a given clock rate, find the desired rate in the chart below and rotate the switch until the desired number is next to the alignment dot. Note that X1 is the clock oscillator that is located in the upper right hand corner of the top board. As shipped from the TECI factory, X1 is an 8.0 Mhz oscillator from which the clock rates shown in the second column of the chart are derived. X1 is a standard type of clock oscillator that can be obtained in many frequencies. If the standard frequencies do not meet user requirements, X1 can be replaced with a version that has a more appropriate frequency. Alternately, switch position 7 can be selected and the correct clock rate applied to the external clock input on the rear panel.

	AS SHIPPED	
CLOCK FREQ.	X1 FREQ.	X1 FREQ.
SWITCH NUM	8.0 Mhz	USER X1
0	8.0 Mhz	USER X1
1	4.0 Mhz	USER X1 / 2
2	2.0 Mhz	USER X1 / 4
3	1.0 Mhz	USER X1 / 8
4	0.5 Mhz	USER X1 / 16
5	0.25 Mhz	USER X1 / 32
6	0.125 Mhz	USER X1 / 64
7	EXTERNAL	EXTERNAL
8	UNUSED	UNUSED
9	UNUSED	UNUSED

3.5.6 Setting The Option Jumpers

?? C8 OR C9 JUMPER (J1)

The C8 or C9 jumper (J1) determines whether or not the option register (U24) can be written to for the purpose of controlling the RAM0 and RAM1 dynamic ram/rom memory mapping features of the 68HC05C8 and 68HC05C9 chips. This jumper is shown on top board schematic diagram sheet 5 of 8. This jumper should be in the "C8 OR C9"j position when emulating a C8 or a C9 chip and in the other position when emulating all other devices. The diagram below shows J1 in the "C8 OR C9" position.



?? EXTAL JUMPER (J2)

The EXTAL jumper (J2) determines whether the emulation clock source is from the emulators internal clock generator or from the target system via the emulation probe. This jumper is shown on top board schematic diagram sheet 3 of 8. If the clock comes from the target system it must be a square wave at TTL signal levels. The diagram below shows the jumper in the position that selects the emulator's internal clock generator.



?? C8, C9 JUMPER (J3)

This jumper determines where the emulator will look for the processor's reset and interrupt vectors in the memory map. The C8 position assumes vectors at \$1FFF. The C9 position assumes vectors at #3FFF. This jumper is shown on top board schematic diagram sheet 4 of 8. The jumper should be placed in the C9 position only when emulating the 68HC05C9 chip and in the C8 position for all other chips. The diagram below shows the jumper in the C8 position.



?? B6 JUMPER (J4)

The B6 jumper J4 allows reading and writing to the emulation processor's internal eeprom memory. This jumper is shown on top board schematic diagram sheet 4 of 8. If you are emulating B6 devices and want to enable the internal eeprom1, then this jumper should be placed in the B6 position. The diagram below shows the jumper in the normal (not B6) position.



?? J5 JUMPER

This jumper should be in place for emulation processors with an 8K byte memory map and should be removed for emulation processors with a 16K byte memory map. The jumper should be in place unless the emulation processor is a C9 or B16 device. When removed, the A13 address line is enabled. This jumper is shown on top board schematic diagram sheet 3 of 8.

?? B6 TYPE JUMPER (J6)

This jumper is used to enable the feature of the B6 chip that allows the E clock to appear on PORT C bit 2 by writing to the ECLK control register at address \$07. This jumper is shown on top board schematic diagram sheet 2 of 8. To enable this feature place the jumper in the B6 TYPE position. The diagram below shows the jumper in the position that disables this feature.



?? IRQ SENSITIVITY JUMPER (J7)

The IRQ sensitivity jumper (J7) converts an emulation processor that has edge and level IRQ sensitivity to negative edge sensitivity only. This jumper should be left in the position shown when emulating the 68HC805C4, 68HC705C8, 68HC805B6 processors because the IRQ sensitivity is determined by the user through use of the option register. The jumper should be placed in the EDGE position only when the emulation processor has fixed edge and level sensitivity and the user application calls for negative edge only.





3.6 EMULATOR SELF TESTS

The TECICE-HC05 has a memory test and a port test. In addition to these two tests, the emulator maintains checksums on communications with the host computer and between its two processors. The test and the checksums are provided to give the user means to determine if the emulator is functioning properly and isolate any malfunction so it can be repaired.

The memory test is performed whenever the emulator is powered up, and when the TeST command is used. The memory test only tests the parts of the memory that are used by the TECICE-HC05.

The port test first tests the internal operation of ports A, B, and C. This is done by setting each port in turn as outputs, writing a pattern to it and reading it back. If the emulation pod is connected to something or pins are shorted together, the test will fail even if the chips inside the emulator are all good. Afterwards, writes and reads between ports are made. The port test is only done with the TeST command is used.

See Error Messages section for an explanation of test errors.

?? Special Test Programs

In Appendix B there are two test program listings, C8TEST (for C8 chips) and B6TEST (for B6 chips).. These test programs give the input/output circuits of the emulator a good workout. They are to be run with the emulation probe connected to a test board shown on the Test Board schematic. The test board is designed to be general purpose. It can be useful anytime viewing the contents of the ports and providing inputs in real time as desired.

When the board is used with test programs: C8TEST.MIK or B6TEST.MIK, JP1 and JP2 should be shorted, although, not to each other. See the program listings and schematics for more details.

?? Warnings

Only one of the two processors on the Test Board schematics may be in place at one time.

A switch on D port MUST be opened when using that pin as an output; otherwise a high output may be shorted to ground. In the test program this means all but switch 1 (Port D bit 0) must be open. Switch one will control what is displayed on the other three ports.

4. WASM05 & WTT05 USER'S GUIDE

4.1 INSTALLING WASM05 & WTT05

The software is supplied on a 3 1/2 inch floppy diskette. The file supplied on this diskette is named SETUP.EXE. This is a self-installing, Windows executable file that will install all of the necessary files when invoked.

To install the software, place the distribution diskette in a floppy drive and run the program A:SETUP.EXE or B:SETUP.EXE from within Windows and follow the on-screen instructions.

*** Important Notice ***

If you have trouble running SETUP.EXE , try running the program with the /M command line switch as follows: >A:SETUP.EXE /M < enter> This is the manual installation mode which will prompt you for the location of needed directories, etc.

After running SETUP.EXE you should find the following files in the installation directory(C:\WASM05 is the default).

WASM05.EXE - Editor/Macro Assembler executable file.
WASM05.HLP - Editor/Macro Assembler on-line help file.
WASM05.INI - Editor/Macro Assembler initialization file.
WTTDEMO.05P - Demo 68HC05 project file.
WTTDEMO.ASM - Demo 68HC05 project source code file.
WTTDEMO.LST - Demo 68HC05 project include file.
ITEST.INC - Demo 68HC05 project include file.
D68HC05.05P - Project file for showing WASM05 source code examples.
D68HC05.ASM - File showing WASM05 source code examples.
UNWISE.EXE - Uninstall executable.
INSTALL.LOG - Installation log file - required by the uninstall program.
WTT05.EXE - Emulator control program executable file.
WTT05.INI - Emulator control program initialization file.

*** Important Notice ***

FONT SIZE: If the text is not displayed as desired, the font size may be changed from within WASM05 by clicking Options|Font and changing the font size.

4.2 UNINSTALLING WASM05 & WTT05

To uninstall the software, double click on the UNWISE.EXE program in the installation directory. This program will read the INSTALL.LOG file and remove all files that were installed with the SETUP.EXE program.

4.3 WASM05 PROGRAM OVERVIEW

WASM05 is a windows hosted text editor and 68HC05 macro cross assembler. The program is a general purpose text editor that has special enhancements for managing assembly language programming projects. WASM05 can edit 255 files simultaneously in a tabbed editor environment. To switch between files just click on the tab with the name of the file that you want to edit. Each of the 255 files can be up to 16MB in size and several files can be grouped together and associated with one another. Thus all of the files required for a programming project can be loaded and/or saved with a single command.

WASM05 is a project oriented program. Each project is specified by a unique project file name. Project files have an extension of .05P which stands for HC05Project. When a project file is opened, all of the files that comprise that project are loaded into the editor at once. Each file is assigned its own unique editor tab and the name of the file appears on that tab. A file is selected for editing by clicking on its tab. When a project is saved, all of the files that are open in the editor are saved as part of the project. Among others, the program has speed buttons for opening and saving projects, and adding or removing files from the current project so that managing projects is very easy and natural. However...

*** Important Notice ***

There are two project management details that the <u>user is responsible</u> for getting correct: (1) Projects <u>must</u> be saved with the .05P file extension; and (2) the main source code file of the project <u>must</u> have the same file name as the project file with an extension of .ASM. This is how the assembler knows which file to assemble first.

Example: If the project file name is **DEMO.05P**, then the main source code file must be named **DEMO.ASM**. All other project files may have any name/extension.

The figure below shows some of the more commonly used controls and features of the WASM05 program. Most of the speed buttons perform normal text editing functions. Refer to the online help file for complete descriptions of these speed buttons. Three of the speed buttons are specifically for program development work. The " ≤ 6805" speed button assembles the project files and creates an object code file, a listing file and a map file. The "D" speed button calls your favorite debugging program. We recommend the WTT05.EXE emulator control program, another TECI 68HC05 development tool. The "P" speed button calls your programmer software. Which programs the "D" and "P" buttons invoke depends on what you specify under the Options/Project Options dialog box. You can set up these buttons to call any program you like by entering the command line parameters for your program in the edit box provided.

WASM05 MAIN SCREEN



4.4 WTT05 PROGRAM OVERVIEW

WTT05 is a Windows emulator control program for TECI's TECICE-HC05 in circuit emulators. It takes the place of the older DOS TT program. The graphic below shows several of the most salient features of WTT05. Some major enhancements over the older emulator control program are as follows:

- 1) A dynamic listing file window that follows code execution.
- 2) The ability to set or remove breakpoints simply by clicking on a listing file line.
- 3) The ability to change register or memory values in the emulator simply by changing them in Windows style edit boxes.
- 4) A Watch Wizard to quickly show you the current value of any program variable.
- 5) Speed buttons to automate common tasks.
- 6) Much closer integration with the editor/assembler.
- 7) and more.

*** Important Notice ***

FONT SIZE: If the text is not displayed as desired, the font size may be changed from within either program by clicking Options|Font and changing the font size.

WTT05 MAIN SCREEN



Watch Wizzard - Just click on any line of code and the current value of the variable referred to in that line is displayed in hex, decimal and binary.

5. APPENDIX

5.1 TUTORIAL LISTING FILE

•*******	******	* * * * * * * * * * * * * * * * * * * *	******	****
;**		WTTDEMO.ASM	4/30/97 RBJ	**
;**				**
;** A WASM11 cr	oss ass	sembler and WTT11 e	emulator demonstration program.	**
;**		TOT The Engineers	Colleborative Inc	**
;**	11	CI - The Engineers	s collaborative, inc.	**
; " " • * *	RI D-	X#3 BOX 6C		**
•**	Do Di	(802)525-3458 F=	(802)525-3451	**
, •**		ail bobi@tec-i.com	n (002)525 5451	**
;***************	******	****	 ***********************************	****
; irq_vectors	equ	\$ffc0		
;	-	-		
;				
ram	equ	\$0	;start of ram area	
program	equ	\$F800	;start of program area	
;				
registers	equ	\$1000		
port_c	equ	registers + 3	;	
port_c_ddr	equ	registers + 7	;	
;				
	org	ram	;ram variables	
count_up	rmb	1	;	
count_down	rind	T	;	
,	ora	program	start of program memory	
power on reset	lds	#\$ff	:load stack pointer	
power_on_resec	ldaa	#\$** #%1111111	program starts here afte	r reset
	staaa	port c	initialize port A with 1	's
	staa	port c ddr	set port A to an output	port
	clr	count up	clear	
	clr	count down	the ram variables	
main_loop	com	port_c	;compliment port A	
	inc	count_up	; increment count up	
	bsr	decrement_byte	; increment a word	
	inca		;	
	decb		;	
	bra	main_loop	;loop forever	
;				
	includ	le itest.inc	;an include file	
;				
dummy_isr ;	rts		;should never be called	
	org	irq_vectors	; interrupt service routin	e vectors
	dw d	lummy_isr	;reserved	
	dw c	lummy_isr	;reserved 1	
	dw o	lummy_isr	;reserved 2	
	dw o	lummy_isr	;reserved 3	
	dw o	lummy_isr	;reserved 4	
	dw c	lummy_isr	;reserved 5	
	dw c	lummy_isr	;reserved 6	
	dw c	lummy_isr	;reserved 7	
	dw c	lummy_isr	;reserved 8	
	dw o	lummy_isr	;reserved 9	
	dw d	ummy_isr	;reserved 10	
	dw d	ummy_isr	;sci serial system	
	dw d	lummy_1sr	;spi serial transfer complete	
	dw d	ummy_isr	;pulse accumulator input edge	
	aw a	lununy_1sr	;puise accumulator overilow	
	aw a	lummy_lsr	; timer overiiow	
	dw (lummy_isr	timer output compare 5	
	uw c	TOTUNITY_IST	, cimer output compare 4	

dw	dummy_isr	;timer output compare 3
dw	dummy_isr	;timer output compare 2
dw	dummy_isr	;timer output compare 1
dw	dummy_isr	;timer input capture 3
dw	dummy_isr	;timer input capture 2
dw	dummy_isr	;timer input capture 1
dw	dummy_isr	;real time interrupt
dw	dummy_isr	;!IRQ (external pin or parallel I/O)
dw	dummy_isr	;!xirq pin
dw	dummy_isr	;SWI
dw	dummy_isr	;illegal opcode trap
dw	dummy_isr	;COP failure (reset)
dw	dummy_isr	;COP clock monitor fail



TECICE-HC05 SCHEMATICS