

AutomationDirect

1/16 DIN Series

Operator's Manual

PM24

Microprocessor - Based Process/Temperature Limit Controller

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General Safety Information

Electrical Hazards and Warnings

Prior to connecting the controller, read the user's manual for proper connection and operating information.

Follow National Electrical Code (NEC) safety requirements when wiring and connecting a power source and sensors or other devices to the controller. Failure to do so could result in injury, death or damage to equipment and property.

Make sure the proper input voltage is applied to the controller. Improper voltage will result in damage to the unit.

Use caution when removing the controller from its case, there may be live voltage present at the terminals. This should only be done by a qualified technician.

All terminal screws must be tightened securely. Terminal screws not properly secured can cause an electrical short that may damage property, equipment or cause injury or death. Terminal screws improperly secured may fall into equipment causing possible damage to property or equipment.

This instrument is not intended for use in life safety applications.

Important: For applications where physical injury or equipment damage might occur in the event our product fails, we recommend the installation of independent safety equipment with its own independent sensor that will shut down the process.

Important: Firmware version of controller must match the version indicated on the bottom front cover of this manual.

PM 24 Limit Controller

1/16 DIN Series
PM24 Operator's Manual
Manual Rev. 2.2
Firmware Version 1.50

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PM24

1/16 DIN Microprocessor-Based Temperature/Process Limit Controller

1. MAIN FEATURES

- Process/Temperature multi-sensor input, without hardware change.
- Accepts 7 thermocouples, RTD-Pt100, DC mA, mV and Volts. All inputs are factory calibrated.
- Programmable Scaling: -1999 to 9999 with selectable decimal point for: mA, mV and Volts input.
- Selectable °F/°C temperature.
- RTD-Pt100 with 1° temperature resolution: -326 to 986°F (-199 to 530°C), and 0.1° temperature resolution: -199.9 to 986.0°F (-199.9 to 530.0°C).
- Input sample rate: 10 reading per second (100 ms).
- Output Alarms: Dual stationary SPST Alarm Relays, with individual hysteresis adjustment.
- Sensor break protection in any condition.
- Easy-to-set programming menu.
- Firmware version displayed during power up.
- High impact ABS enclosure.
- Dimensions: 48x48x106mm.
- Power: 90 to 260Vac.

2. SPECIFICATIONS

- Dimensions: 48 x 48 x 106mm (1/16 DIN) Approximate weight: 200g max.
- Panel cut-out: 45.5 x 45.5mm (± 0.3mm)
- Terminal connection: screws, accepting 16 – 24 AWG or 6.3 mm fork lugs.
- Power: 90 to 260Vac, 50/60Hz, Consumption: 7VA max.
- Operating environment: 0 to 50°C (32 to 122°F, humidity: 10 to 90% RH, non-condensing).
- Flame-Retardant ABS Plastic Case.
- Warm-up time: 15 minutes max.

INPUT

- Keypad selection of input type (refer to table 1)
- Display resolution : 0.1°F/C or 1°F/C (RTD-Pt100),
-1999 to 9999 fully scalable for mA, mV and Volts input
- Input sample rate: 10 per second (100 ms)
- Accuracy : Thermocouples J, K, T, E, N: 0.2% of span, ±1°C, ±1 digit
Thermocouples R, S: 0.25% of span, ±3°C, ±1 digit
Pt100, mA, mV and Volts: 0.2% of span, ±1 digit
- Input impedance: 0-50mV and thermocouples: >10MΩ
0-10 Volts DC: >1MΩ
4-20 mA DC: 100 Ω
- Pt100 measurement: DIN 43760 standard ($\alpha=0.00385$).
3-wire circuit, cable resistance compensation.
Excitation current: 170μA.

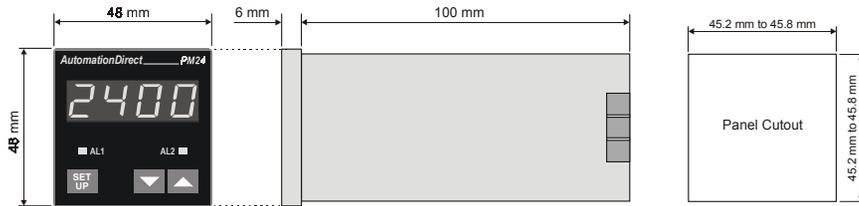
SENSOR WIRE INPUT:

- Thermocouples** are connected to terminals 2(+) and 3(-), with positive on terminal 2.
- Voltage signals up to 50 mV** should be connected to terminals 2(+) and 3(-).
- Pt100 sensors** are connected to terminals 1, 2 and 3, as indicated in this manual. For full compensation of cable resistance only cables with equal wire electrical resistance should be used.
- Voltage signals up to 10 Vdc** should be connected to terminals 5(+) and 3(-)
- Current 4 to 20mA** signals should be connected to terminals 4 (+) and 3 (-).

OUTPUT:

- Two SPST Relays (without contact suppression):
Resistive: 3A @ 250VAC / 3A @ 125VAC / 3A @ 30VDC
Inductive: 2A @ 250VAC / 2A @ 30VDC
Dielectric Strength: 750Vrms between open contacts (at sea level for 1 min.)

2.1 MAIN DIMENSIONS AND CUTOUT:

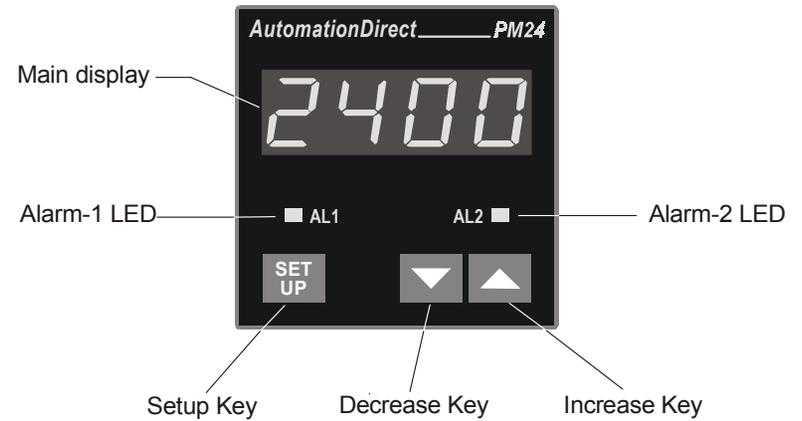


(not to scale)

(Figure 1)

3. OPERATION

Operator Interface



(Figure 2)

Main display - PV: Displays the PV (Process Variable) value, and used when configuring the parameters of the controller.

Alarm 1 - AL1 LED: status of the alarms, (LED On = alarm active).

Alarm 2 - AL2 LED: status of the alarms, (LED On = alarm active).

SETUP key: used to set up the menu cycles.

DECREASE key: used to change parameter values.

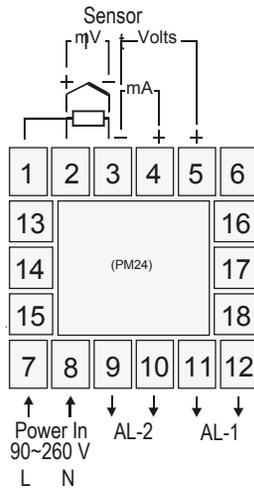
INCREASE key: used to change parameter values.

IMPORTANT:

When the controller is turned on, the firmware version is displayed for approximately 4 seconds, after which the controller starts normal operation. The value of PV is displayed and the outputs are enabled after 6 seconds.

Prior to first operation, the controller should be fully configured. The user must set basic parameters such as input type ("TYPE"), alarm set points ("RISP" and "R2SP"), etc.

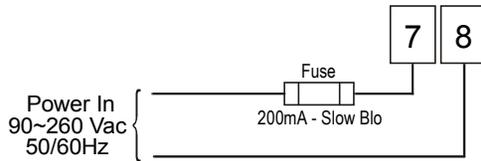
3.1 ELECTRICAL CONNECTIONS:



(Figure 3)

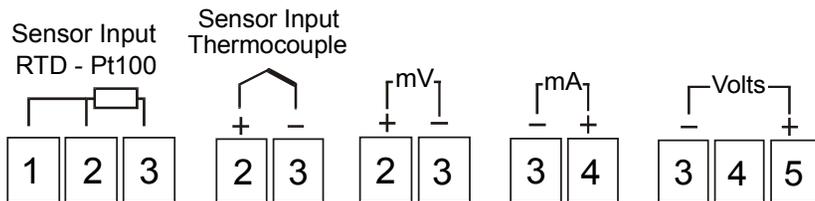
3.2 POWER WIRING:

AC Voltage Power Wiring



Note: The installation of fuse is optional, depending on level of protection required.

3.3 INPUT SIGNAL WIRING:

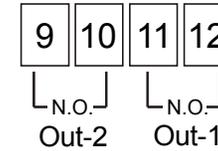


(Figure 4)

NOTE: Use copper conductors rated for at least 75 °C. For Thermocouple sensors use appropriate compensated thermocouple wires.

3.4 OUTPUT ALARM WIRING:

Dual SPST Relay Output Alarms



(Figure 5)

3.5 PANEL ASSEMBLY:

First remove the mounting clamp and insert the controller into the panel cut out. Place the unit into the panel cutout and slide the mounting clamp from the rear to a firm grip at the panel.

The internal circuitry can be fully removed from the housing without disconnecting any wiring. By using the thumb, just press the tab in the lower part of the front panel, grab the front panel firmly and pull the front face and circuitry from the housing.

Warning: Use caution when removing the controller from its case, there may be live voltage present at the terminals. This should only be done by a qualified technician. It is recommended that power to the controller be disconnected prior to removing the controller from the case.

3.6 ERROR MESSAGES:

The connection and configuration errors for most of the problems encountered when using the controller are shown below.

Error messages are displayed to help the user to identify possible problems.

- : Process temperature is below the selected sensor range.
- : Process temperature is above the selected sensor range
- : Controller or sensor error.

Example: - Broken (open) thermocouple, mA, mV or Volts open loop.
- Pt100 badly connected, short-circuited, open, or high cable resistance.

4. MENU SYSTEM:

The Parameter Menu System is organized into four basic cycles. This is shown in the chart below.

| Cycle |
|-------------------|
| 1 – Indication |
| 2 – Alarms |
| 3 – Configuration |
| 4 – Calibration |

4.1 INITIAL STARTUP

When the controller is initially energized the Firmware version is displayed for approximately 4 seconds after which the controller reverts to the normal operation mode in the **Indication** cycle. The value of the process variable (**PV**) is displayed and the outputs are enabled after 6 seconds.

Important: The Firmware version of the controller must match the version indicated on the bottom front cover of this manual.

4.2 SETUP CYCLE PARAMETER ACCESS:

The Indication cycle is the default cycle for the controller and only shows the PV. All other cycles have parameters that can be accessed and changed to configure the controller as needed.

The cycles need only to be accessed when a change of parameters is necessary. To reach the other parameters the user must keep the **SETUP** key pressed for approximately 4 seconds. After this time the controller will display the first parameter of the next cycle. By keeping the **SETUP** key pressed for another 3 seconds the next cycle will be accessed.

Release the **SETUP** key when the desired cycle is reached. Press the **SETUP** key once to access the next parameter in the same cycle or quickly press the **SETUP** key to move through the parameters in the cycle. After the last parameter in a cycle is reached, pressing the **SETUP** key one last time will bring the controller back to the **Indication** cycle (**Cycle-1**). The display will also revert to the **Indication** cycle after 20 seconds if the parameters in a cycle are not changed.

Once in a desired parameter the display will alternate the name and value. The value can then be changed by pressing the  or  key.

The following page shows the Cycle Parameter Menu.

Cycle Parameter Menu

| Cycle-1 | Cycle-2 | Cycle-3 | Cycle-4 |
|-------------------------|-----------------------------|---------------------------------------|---|
| INDICATION | ALARMS | CONFIGURATION | CALIBRATION |
| PV Indication | RISP Alarm 1 | TYPE Input Type | InLC Input Low Calibration |
| | R2SP Alarm 2 | dPPo Decimal Point Position | InHC Input High Calibration |
| | ALrE Differential | unIt Unit | CLL Cold Junction Low Calibration |
| | | InLL Input Low Limit | |
| | | InHL Input High Limit | |
| | | OFFS Offset Signal Input | |
| | | RIFu Alarm 1 Function | |
| | | R2Fu Alarm 2 Function | |
| | | R1H3 Alarm 1 Hysteresis | |
| | | R2H3 Alarm 2 Hysteresis | |
| | | Prot Security Protection | |

NOTE: Any changed parameter is saved into non-volatile memory when scrolling to the next parameter or 20 seconds after the new parameter is changed.

4.3 DIGITAL SERIAL NUMBER ACCESS:

To read the controller's serial number (8 digits), hold down the  key for a few seconds and the first four digits will appear on the display. To read the second four digits, hold down the  key for a few seconds and the second four digits will appear on the display, completing the 8 digits serial number.

The serial number is recorded in the factory and cannot be changed.

5. CONTROLLER CONFIGURATION

The Configuration section gives information on parameter settings in each Cycle which will help to configure the controller for the desired operation. **However, the first parameter that needs to be programmed is the Input Type (TYPE) in the Configuration cycle, Cycle-3 (see section 5.3 page 11, and Table 1 page 12).** This will determine the scale for all other parameter values, i.e.: a J thermocouple has different temperature range than a K thermocouple and will have a different setpoint range.

5.1 CYCLE 1 – OPERATION:

| | |
|----------------------|---|
| PV INDICATION | After power up the display indicates the measured value proportional to the input signal. |
|----------------------|---|

5.2 CYCLE 2 – ALARM SETPOINTS:

Low and high alarms are used to signal minimum and maximum temperature values as programmed in the “**R ISP**” and “**R2SP**” prompts

| | |
|---|--|
| R ISP Alarm 1 | SETPOINT for Alarm 1: Tripping point for alarm 1 (see Table 2, page 13). |
| R2SP Alarm 2 | SETPOINT for Alarm 2: Tripping point for alarm 2 (see Table 2, page 13). |
| RLRE Alarm Reference (Diferential) | REFERENCE VALUE FOR DIFFERENTIAL ALARM: a value in respect to which the differential, differential low, and differential high alarms will be set. Valid for alarms type 2, 3, 4, 8, 9, and 10 (see Table 2, page 13). |

5.3 CYCLE 3 – INPUT TYPE, AND ALARMS CONFIGURATION:

| | |
|-----------------------------------|--|
| TYPE Type | INPUT TYPE: Selects the input sensor type to be connected to the indicator. Default: 1 (T/C Type K) “This is the first parameter to be set” (Refer to Table 1, page 12). |
| dpp0 Decimal Point | DECIMAL POINT POSITION: Available only for input types 18, 19 or 20. Defines the number of digits to be shown after the decimal point. Programmable from 0 to 3. Default: 0 |
| unit unit | TEMPERATURE UNIT: Selects display indication for degrees Celsius or Fahrenheit. Default: 0 0 - degrees Celsius (°C) 1 - degrees Fahrenheit (°F) |
| inLL Input Low Limit | INPUT LOW LIMIT: Available for input types from 9 to 20. Defines the lowest value to be displayed when the input signal is at its lower value. For input types from 0 to 8 it defines the lowest alarm set point value. Default: - 150 |
| inHL Input High Limit | INPUT HIGH LIMIT: Available for input types from 9 to 20. Defines the highest value to be displayed when the input signal is at its upper value. For input types from 0 to 8 it defines the highest alarm set point value. Default: 1370 |
| OFFS Offset Input | OFFSET SIGNAL INPUT: Offset value to be added to the PV to compensate sensor error. Default: 0 |
| R1Fu Alarm 1 Function | FUNCTION OF ALARM 1: Refer to Table 2, page 13, for function description and respective codes to set at this prompt. Default: 0 |
| R2Fu Alarm 2 Function | FUNCTION OF ALARM 2: Refer to Table 2, page 13, for function description and respective codes to set at this prompt. Default: 0 |
| R1HY Alarm 1 Hysteresys | ALARM 1 HYSTERESIS: Defines the differential range between the PV value at which the alarm is turned on and the value at which it is turned off (in engineering units). Default: 1 |
| R2HY Alarm 2 Hysteresys | ALARM 2 HYSTERESIS: Defines the differential range between the PV value at which the alarm is turned on and the value at which it is turned off (in engineering units). Default: 1. |
| Prot Protection | FUNCTION PROTECTION: See description and Figure 8 on page 15, and Figure 9 on page 16. Default: 1 0 = No protection, all cycles can be accessed. 1 = No access to cycle 4 2 = No access to cycle 3, and cycle 4. 3 = No access to cycle 2, cycle 3, and cycle 4. |

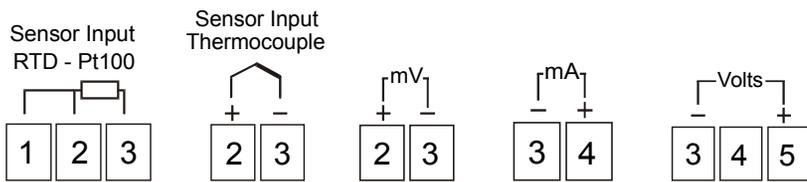
Input Type:

Table 1 – Input Type:

| INPUT TYPE | CODE | RANGE |
|-------------------------|-----------|---|
| Thermocouple J | 0 | -166 to 1400°F (-110 to 760°C) |
| Thermocouple K | 1 | -238 to 2498°F (-150 to 1370°C) |
| Thermocouple T | 2 | -256 to 752°F (-160 to 400 °C) |
| Thermocouple E | 3 | -130 to 1328°F (-90 to 720°C) |
| Thermocouple N | 4 | -238 to 2372°F (-150 to 1300°C) |
| Thermocouple R | 5 | 32 to 3200°F (0 to 1760°C) |
| Thermocouple S | 6 | 32 to 3200°F (0 to 1760°C) |
| Pt100 (Resolution 0.1°) | 7 | -199.9 to 986.0°F (-199.9 to 530.0°C) |
| Pt100 (Resolution 1°) | 8 | -326 to 986°F (-199 to 530°C) |
| 4 to 20mA | 9 | Linearized J: -166 to 1400°F (-110 to 760°C) |
| 4 to 20mA | 10 | Linearized K: -238 to 2498°F (-150 to 1370°C) |
| 4 to 20mA | 11 | Linearized T: -256 to 752°F (-160 to 400 °C) |
| 4 to 20mA | 12 | Linearized E: -130 to 1328°F (-90 to 720°C) |
| 4 to 20mA | 13 | Linearized N: -238 to 2372°F (-150 to 1300°C) |
| 4 to 20mA | 14 | Linearized R: 32 to 3200°F (0 to 1760°C) |
| 4 to 20mA | 15 | Linearized S: 32 to 3200°F (0 to 1760°C) |
| 4 to 20mA | 16 | Linearized Pt100: -199.9 to 986.0°F (-199.9 to 530.0°C) |
| 4 to 20mA | 17 | Linearized Pt100: -326 to 986°F (-199 to 530°C) |
| 0 to 50mV | 18 | Linear. Programmable range from -1999 to 9999 |
| 4 to 20mA | 19 | Linear. Programmable range from -1999 to 9999 |
| 0 to 10V | 20 | Linear. Programmable range from -1999 to 9999 |

NOTE: In case of sensor break or failure an error " **Erra**" message is displayed.

Wires Sensor Input



(Figure 6)

Notes: 1) For Thermocouple Sensors use appropriate compensated thermocouple wires.

2) Use copper conductors rated for at least 75 °C (except on T/C).

Alarm Type:

Table 2 – Alarm Type

| TYPE | CODE | ACTION |
|--|-----------|--|
| Low Alarm (Low Process Alarm) | 0 | Low SPAL |
| High Alarm (High Process Alarm) | 1 | High SPAL |
| Differential Low (Deviation Low) | 2 | Dif-Low SPAL+ |
| | | Dif-Low SPAL- |
| Differential High (Deviation High) | 3 | Dif-High SPAL+ |
| | | Dif-High SPAL- |
| Differential (Band Alarm) | 4 | Dif-SPAL+ |
| | | Dif-SPAL- |
| Input Sensor Error | 5 | Alarm is ON whenever: <ul style="list-style-type: none"> • Process is below selected range. • Process is above selected range. • Thermocouple or Pt100 is broken (open). • Pt100 is shorted, badly connected or wire impedance is too high. |
| (Alarm Functions) Alarm with inhibition at power-up | 6 | Low alarm disabled at power-up |
| | 7 | High alarm disabled at power-up |
| | 8 | Differential low limit alarm disabled at power-up |
| | 9 | Differential high limit alarm disabled at power-up |
| | 10 | Differential alarm disabled at power-up |

(where SPAn means: **R ISP** and **R2SP**)

Alarm Functions:

Low Alarm: Activates at present value, independent of main setpoint. Low process-alarm activates at and below alarm setting.

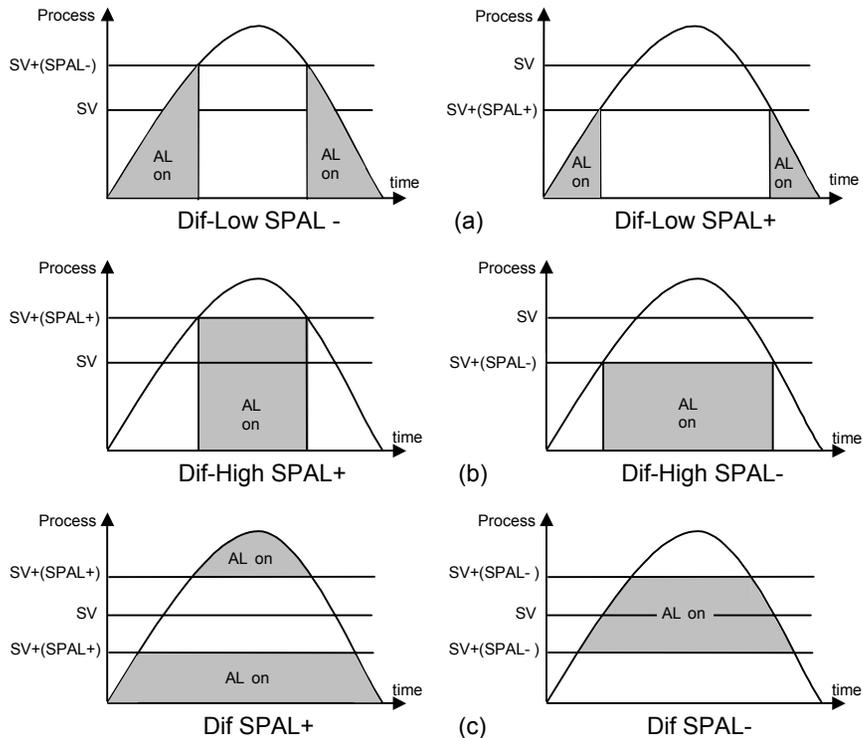
High Alarm: Activates at present value, independent of main setpoint. High process-alarm activates at and above alarm setting.

Differential Low: Activates at present deviation (negative or positive) value from Alarm Reference ($ALrE$). Low deviation-alarm activates below alarm setting. Figure 7(a) gives a graphical description of this.

Differential High: Activates at present deviation (negative or positive) value from Alarm Reference ($ALrE$). High deviation-alarm activates above alarm setting. This is represented in figure 7(b).

Differential: Activates when the process exceeds a specified band-alarm centered around the Alarm Reference ($ALrE$). See Figure 7(c).

Inhibition at power-up: Alarm blocking at power-up inhibits the relay alarm from activating when the unit is first energized. The alarm will only trip after the process variable reaches a new alarm situation.



(Figure 7)

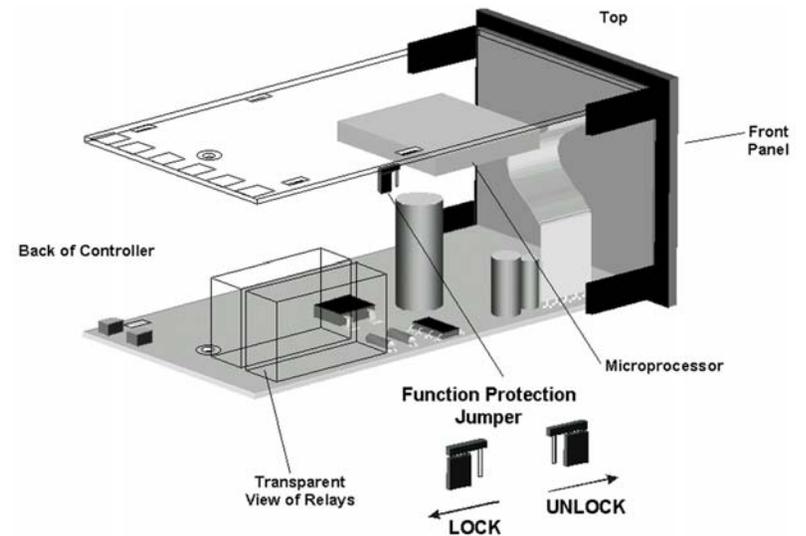
Function Protection (Prot):

The controller is shipped with full accessibility. If you want to use the "Function Protection" to disable access to cycles 2, 3 and 4, follow the steps below:

- After programming the controller for the desired operation select the level of cycle access desired in Cycle-3 at the **prot** parameter using the ∇ or \blacktriangle keys.
- Remove the controller circuitry from the housing by using the thumb to press the tab in the lower front face of the controller, then, while firmly grabbing the front face at the top and bottom pull it and the circuitry from the case.

Warning: Use caution when removing the controller from its case, there may be live voltage present at the terminals. This should only be done by a qualified technician. It is recommended that power to the controller be disconnected prior to removing the controller from the case.

- View the controller in the position shown in Figure 8 and note the Protection Jumper on the top main board.
- **Enable Function Protection** (locks the **Prot** parameter) by placing the jumper over both jumper prongs as shown in figure below. Needle nose pliers are recommended for changing jumper position.
- **Disable Function Protection** (unlocks the **Prot** parameter) by placing the jumper over both jumper prongs as shown in figure below.
- Once the desired protection is obtained slide the controller back in the case making sure that the main board and power supply board stay in the circuit board channels at the top and bottom side walls of the case. Use the palm of the hand to press the front panel flush into the controller housing.



(Figure 8)

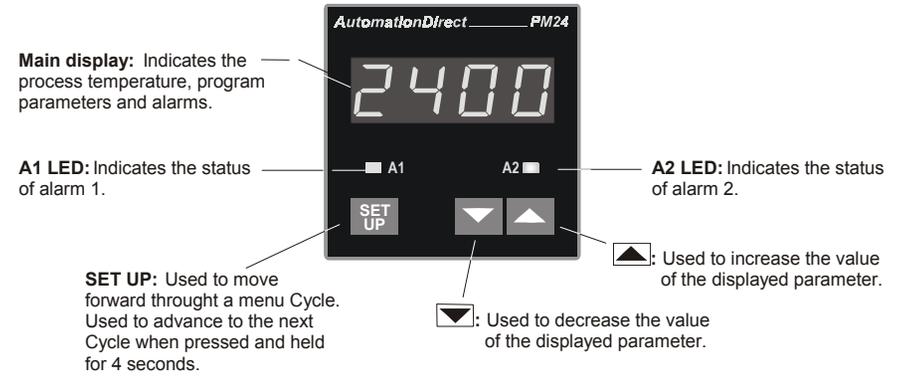
CYCLE 4 - CALIBRATION LEVEL:

NOTE: All input and output types are factory calibrated. This cycle should only be accessed by experienced personnel. If in doubt do not press the  or  keys in this cycle.

| | |
|---|---|
| <p>InLE</p> <p>Input Low Calibration</p> | <p>SENSOR OFFSET CALIBRATION. Sets the temperature sensor low calibration (offset). The display shows only the corrected temperature and not the offset added. A signal simulator should be used to inject a low value signal to properly adjust the offset.</p> |
| <p>InHE</p> <p>Input High Calibration</p> | <p>INPUT HIGH CALIBRATION. Sets the sensor input circuit gain or high calibration. A signal simulator should be used to inject a high value signal to properly adjust the offset.</p> |
| <p>[JL]</p> <p>Cold Junction Low Calibration</p> | <p>COLD JUNCTION OFFSET CALIBRATION: Sets the cold junction °C offset calibration. A good thermometer or a temperature simulator should be used to properly adjust this parameter.</p> |

PM24 Quick Setup Reference

Key and Display Functions



Set Up Cycle Parameters

| Cycle-1 | Cycle-2 | Cycle-3 | Cycle-4 |
|-------------------------|-----------------------------|---------------------------------------|--|
| INDICATION | ALARMS | CONFIGURATION | CALIBRATION |
| PV Indication | A1SP Alarm 1 | TYPE Input Type | InLE Input Low Calibration |
| | A2SP Alarm 2 | dPPo Decimal Point Position | InHE Input High Calibration |
| | ALrE Differential | unit Unit | [JL] Cold Junction Low Calibration |
| | | InLL Input Low Limit | |
| | | InHL Input High Limit | |
| | | OFFS Offset Signal Input | |
| | | A1Fu Alarm 1 Function | |
| | | A2Fu Alarm 2 Function | |
| | | A1Hy Alarm 1 Hysteresis | |
| | | A2Hy Alarm 2 Hysteresis | |
| | | Prot Security Protection | |

PM24

Configuration Sheet

Name: _____ Date: _____

Part#: _____

Project: _____

| Process Setpoint: | | | |
|-----------------------|---------|------------|----------------------------|
| Cycle 3 CONFIGURATION | Default | CODE/VALUE | CHARACTERISTICS / FUNCTION |
| <i>tYPE</i> | 1 | | |
| <i>dPPo</i> | 0 | | |
| <i>Un lt</i> | 0 | | |
| <i>l nLL</i> | - 150 | | |
| <i>l nHL</i> | 1370 | | |
| <i>R 1FU</i> | 0 | | |
| <i>R2FU</i> | 0 | | |
| <i>R 1HY</i> | 1 | | |
| <i>R2HY</i> | 1 | | |
| <i>Prot</i> | 1 | | |
| Cycle 2 ALARMS | Default | CODE/VALUE | CHARACTERISTICS / FUNCTION |
| <i>R 1SP</i> | 6 10 | | |
| <i>R2SP</i> | 6 10 | | |
| <i>ALrE</i> | - 150 | | |

Error Codes Table for Temperature/Process Controllers

Document # C0504

The connection and configuration errors for most of the problems encountered in using the controller are shown below. A final revision of the connections and parameters will save time and further losses.

Error messages are displayed to help the user to identify possible problems.

Error Codes Table

| Display Shows | Cause |
|---------------|---|
| ---- | Process or temperature is below the selected sensor range. |
| ---- | Process or temperature is above the selected sensor range. |
| <i>Err 0</i> | Sensor error. Example: 1. No connections on the sensor input terminals. 2. Broken thermocouple (open wire) or broken RTD-Pt100. 3. RTD-Pt100 badly connected, short-circuited or high cable resistance. |
| <i>Err 1</i> | RTD-Pt100 badly connected, short-circuited or high cable resistance. |
| <i>Err 6</i> | This kind of error is caused when, for instance, a 4-20mA signal goes through the mV or Thermocouples input and can introduce signals of up to 30VDC at the input point and force the Auto/Zero and Auto/Span to work outside the limits that guarantee the precision of the controller. This error goes away when the signal is removed from the input and the connection is fixed (normally, input signals of up to 30VDC do not damage the controller's hardware). |
| <i>Err 2</i> | Auto/Zero Problem: This error is caused by a wrong connection and indicates that a voltage greater than 30VDC was input into the sensor and the Auto/Zero circuit was damaged. It is necessary to revise the controller. |
| <i>Err 4</i> | Auto/Span Problem: This error is caused by a wrong connection and indicates that a voltage greater than 30VDC was input into the sensor and the Auto/Span circuit was damaged. It is necessary to revise the controller. |

NOTE: The controllers do not accept AC-Voltage or AC-Current in the sensor input. This type of signal can damage the controller.