SPECIFICATIONS -SPECIALTY MODULES

In This Chapter:

| Specialty Module C | Overview | • • • | ••• | ••• | | ••• | ••• | •• | ••• | •• | •• | .7– | 3 |
|--------------------|----------|-------|-----|-----|------|-----|---------|--------|---------|----|-----|---------|---|
| Specialty Modules | | | ••• | ••• | | | •• | •• | ••• | •• | • • | .7- | 5 |

CHAPTER

Notes:

Specialty Modules Overview

There are several Specialty modules available for use in local and remote I/O bases. These modules are listed in the tables below and their specifications are found in this chapter. Each specialty module is identified with a White bar across the front panel as seen below. The module's front panel is also equipped with LED status indicators. Depending on the module, these indicators can show the network health, module health, I/O status or mode of operation the module is currently in.

Specialty Modules

| Module | тв тс | | Specialty Modules | | | | | |
|----------------------|-----------------------------------|--------------------------|---|----------|--|--|--|--|
| Part Number H2-SERIO | Module Type (White: Specialty) | Part Number | Description | See Page | | | | |
| | | H2-CTRIO(2) | High Speed Counter Interface Module | 7-5 | | | | |
| В | | H2-ECOM100 | Ethernet Communications Module | 7-14 | | | | |
| | | H2-ERM(100) H2-EBC100 | Ethernet Remote Master Module Ethernet Base Controller | 7-22 | | | | |
| C | | H2-SERIO(-4) | Serial I/O Module | 7-30 | | | | |
| | | F2-08SIM | 8-point Input Simulator Module | 7-34 | | | | |

Specialty Modules Overview - continued

| Specialty Modules Supported | | | | | | | |
|-----------------------------|---|-------------|-------------------------------------|--|--|--|--|
| Part Number | Description | Part Number | Description | | | | |
| H2-CTRIO | High Speed Counter Interface Module | H2-EBC*** | 10 Base-T Ethernet Base Controller | | | | |
| H2-CTRIO2 | High Speed Counter Interface Module | H2-EBC100 | 100 Base-T Ethernet Base Controller | | | | |
| H2-ECOM*** | 10 Base-T Ethernet Communication Module | H2-EBC-F | 10 Base-FL Ethernet Base Controller | | | | |
| H2-ECOM100 | 100 Base-T Ethernet Communication Module | H2-SERIO | Serial I/O Module | | | | |
| H2-ECOM-F | 10 Base-FL Ethernet Communication Module | H2-SERIO-4 | Serial I/O Module | | | | |
| H2-ERM(100) | 10/100 Base-T Ethernet Remote Master Module | F2-08SIM | 8-point Input Simulator Module | | | | |
| H2-ERM-F | 10 Base-FL Ethernet Remote Master Module | | | | | | |

*** The H2-ECOM and H2-EBC modules are discontinued but are still compatible with the new Do-more H2 Series PLC.

| Specialty Modules NOT Supported | | | | | | | |
|---------------------------------|---------------------------|--------------|---|--|--|--|--|
| Part Number | Description | Part Number | Description | | | | |
| D2-CTRINT | Counter Interface Module | D2-EM | Expansion Base I/F Module | | | | |
| D2-DCM | Data Communication Module | H2-PBC | Profibus Base Controller | | | | |
| D2-RMSM | Remote I/O Master Module | F2-DEVNETS-1 | DeviceNet Base Controller | | | | |
| D2-CM | Expansion Base Controller | F2-SDS-1 | Smart Distributed System Base Controller | | | | |
| F2-CP128 | CoProcessor Module | DV-1000 | DirectVIEW 1000 Timer/Counter access unit | | | | |
| D2-HPP | Handheld Programmer | | • | | | | |

H2-CTRIO(2)

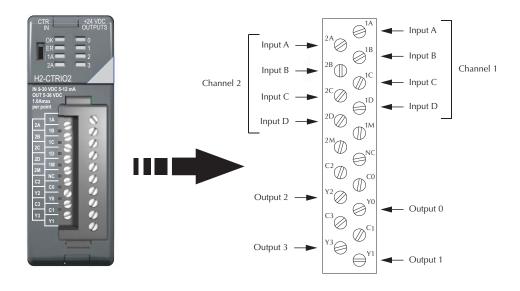
H2-CTRIO(2) Overview

The H2-CTRIO and H2-CTRIO2 Counter I/O (CTRIO) modules are designed to accept high-speed pulse input signals for counting or timing applications. These modules also provide high-speed pulse output signals for servo/stepper motor control, monitoring and alarming as well as other discrete control functions.

The H2-CTRIO(2) modules offer greater flexibility for applications which call for precise counting or timing based on input events or for high-speed control output applications. They can also be used for applications that call for a combination of both high-speed input and high-speed output control functions.

The H2-CTRIO(2) modules have their own internal microprocessor and operate asynchronously with respect to the CPU. Therefore, the response time of the on-board outputs is based on the module's scan time, not the CPU's scan time (unless the CPU is controlling the outputs directly).

H2-CTRIO(2) Terminal Block Layout





NOTE: The H2-CTRIO and H2-CTRIO2 modules have the same terminal block layout.

H2-CTRIO(2) Configuration

The module configuration of the H2-CTRIO(2) is done from within the Edit CTRIO/CTRIO2 Configuration window seen below. The Configure I/O..., Input Filters..., Discrete Tables... and Pulse Profiles... buttons in the lefthand column will allow you to configure the input and output functions of the selected module. Refer to the Do-more Designer Help File for more information on configuration options.

| Nodule Configurati | | | Info: Mo | dule Type: H | x-CTRJO/C | TRIO2 Assig | ned to: D | L205 Local I/O M | Master : DL205 Base : Slot 0 |
|--------------------|----------|------------|----------|--------------|-----------|-------------|-----------|------------------|---|
| Configure I/O | Name: | CTRIO 000 | C1F1 | - | | Name: | CTRIO | 000 Out0 | CONFIGURATION NOTES: |
| conspire your | Ch1/Fn1: | | | | | Out 0 | Unassig | | Select 'Configure I/O' to setup the module's input and output functions. |
| | Name: | CTRIO_000 | _C1F2 | - | | Name: | CTRIO, | _000_Out1 | * Select 'Discrete Tables' to manage preset and PLS tables for |
| | Ch1/Fn2: | Unassigned | | | | Out 1 | Unassig | gned | discrete outputs. # Select 'Pulse Profiles' to |
| | Name: | CTRIO_000 | _C2F1 | - | | Name: | CTRIO | _000_Out2 | manage profiles for pulse output * Each configured resource will automatically generate a device |
| | Ch2/Fn1: | Unassigned | | | | Out 2 | Unassig | phed | object that is available to CTRIO specific instructions. |
| | Names | CTRIO_000 | _C2F2 | | | Name: | CTRIO, | _000_Out3 | * The module name and resource name fields will become Do-more system devices. Choose |
| | Ch2/Fn2: | Unassigned | | | | Out 3 | Unassig | pned | meaningful and unique names for each configured resource. |
| Input Filters | Ch1 A: | 1000 ns | Ch18: | 1000 ns | Ch1C: | 1000 ns | Ch1D: | 1000 ns | * Select 'Input Filters' to configure the input filter times. This is supported by the CTRIO2 |
| | Ch2 A: | 1000 ns | Ch28: | 1000 ns | Ch2 C: | 1000 ns | Ch2D: | 1000 ns | only. |
| Discrete Tables | File # | Name | Table | Туре | | | In | struction | Total Blocks: 256 |
| | | | | | | | | | Blocks Free: 249 |
| | | | | | | | | | Export to CtrioWB File |
| Pulse Profiles | File # | Name | Profi | е Туре | | | In | struction | Import from CtrioWB File |
| | | | | | | | | | |
| | | | | | | | | | OK |

The above window can be accessed once the H2-CTRIO(2) module is added to the I/O configuration either manually or automatically. See the Verify Hardware Configuration section of the Getting Started chapter for more information on setting up the I/O configuration. With the module added, select the Module Configuration(s) entry from the System Configuration page. Then choose the desired module and select Edit Config.

| onfiguration Entries | between the program | rammable by Do-more instruct and the module, eliminating t | tions require a Module Configuration. The Module Configurati he need for Base/Slot addressing in the program. hat is provided through the Module Configuration. | on provides a logical connectio |
|---|---------------------|---|---|---------------------------------|
| Module Configuration(s) Device Configuration | Module Name | Туре | Location | New Config |
| ···· I/O Mappings ···· Memory Configuration | CTRIO_000 | Hx-CTRIO/CTRIO2 | DL205 Local I/O Master->DL205 Base->Slot 0 | Edit Config |
| | | | | Delete Config |
| | | | Select then Edit Config | Assign Config |
| | | ок | Cancel Help | |

| General Specifications | | | | | | |
|--------------------------|---|---|--|--|--|--|
| Specifications | H2-CTRIO | H2-CTRIO2 | | | | |
| Discrete I/O Points Used | None (I/O map directly in H2-DM1/E data structure) | | | | | |
| Base Power Required | 400 mA Max | 275 mA Max | | | | |
| Isolation | 2500V I/O to Logic, 1000V among Input Channels and All Outputs | 1500V I/O to Logic, 1000V among Input Channels and All Outputs | | | | |

| | Input Specifications | | | | | |
|--------------------------|----------------------------|--------------------|--|--|--|--|
| Specifications | H2-CTRIO | H2-CTRI02 | | | | |
| Inputs | 8 pts sink/source | | | | | |
| Maximum Input Frequency | 100 kHz | 250 kHz | | | | |
| Minimum Pulse Width | 5 µsec | 0.5 µsec | | | | |
| Input Voltage Range | 9-30 VDC | 9-30 VDC | | | | |
| Maximum Voltage | 30 VDC | | | | | |
| Input Voltage Protection | Zener Clamped at 33 VDC | | | | | |
| Rated Input Current | 8 mA typical 12 mA maximum | | | | | |
| Minimum ON Voltage | 9.0 VDC | | | | | |
| Maximum OFF Voltage | 2.0 VDC | | | | | |
| Minimum ON Current | 5.0 mA | | | | | |
| Maximum OFF Current | 2.0 mA | | | | | |
| OFF to ON Response | less than 3 µsec | less than 0.5 µsec | | | | |
| ON to OFF Response | less than 3 µsec | less than 0.5 µsec | | | | |

| UFF to UN Response | less than 3 µsec less than 0.5 µsec | | | | |
|-------------------------|--|---|--|--|--|
| ON to OFF Response | less than 3 µsec | less than 0.5 µsec | | | |
| | Output Specifications | | | | |
| Specifications | H2-CTRIO | H2-CTRI02 | | | |
| Outputs | 4 pts (sink/source), independently isolated | | | | |
| Pulse Outputs | 2 channels, 20 Hz to 25 kHz Pulse/Direction or CW/CCW | 2 channels, 20 Hz to 250 kHz Pulse/Direction or CW/CCW | | | |
| Minimum Pulse Width | 5 µsec | 0.5 µsec | | | |
| Output Voltage Range | 5-36 VDC | | | | |
| Maximum Output Voltage | 36 VDC | | | | |
| Maximum Load Current | 1.0 A | 1.0 A at 23°C 0.5 A at 60°C | | | |
| Maximum Leakage Current | 100 |) μA | | | |
| Inrush Current | 5.0 A for 20 ms | 2.0 A for 10 ms | | | |
| ON State V Drop | 0.3 VDC or less | 0.45 VDC or less | | | |
| Overcurrent Protection | Y | es | | | |
| OFF to ON Response | less than 3 µsec | less than 1 µsec | | | |
| ON to OFF Response | less than 3 µsec | less than 1 µsec | | | |





| H2-CTRIO(2) LED Descriptions | | | | |
|------------------------------|--------------------|--|--|--|
| ОК | Module OK | | | |
| ER | User Program Error | | | |
| 1A | Channel 1 Status | | | |
| 2A | Channel 2 Status | | | |
| 0 - 3 | Output Status | | | |

H2-CTRIO(2) LED Indicators

| CTR IN | +24 VDC OUTPUTS |
|----------------|--------------------|
| OK ER 1A | |
| H2-CTRIO | - 3 |

| H2-CTRIO(2) LED Diagnostic Definitions | | | |
|--|---|--|--|
| LED OK | LED ER | Description | |
| Blinking | Blinking | Boot Mode - Used for Field OS Upgrades | |
| Blinking | OFF | Program Mode | |
| OFF | Blinking Module Self-Diagnostic Failure (Blinks may be coded by counts) | | |
| OFF | ON Module Error Due to Watchdog Timeou | | |
| OFF | OFF | No Power to Module | |
| ON | OFF | All is well - RUN Mode | |
| ON | ON | Hardware Failure (H2-CTRIO) | |
| | UN | Not Used (H2-CTRIO2) | |

| | +24 VDC OUTPUTS |
|-----------------|--------------------|
| OK ER 1A | |
| 2A H2-CTRIO2 | -3 |

| H2-CTRIO(2) LED Diagnostic Definition | | | |
|--|--|--|--|
| 1A/2A | | | |
| Blinking 7 times per second | Input is configured as Counter and is changing | | |
| Following state of input | Input is not configured as counter | | |
| 0-3 | | | |
| Follow actual output state: ON = output is passing current | | | |

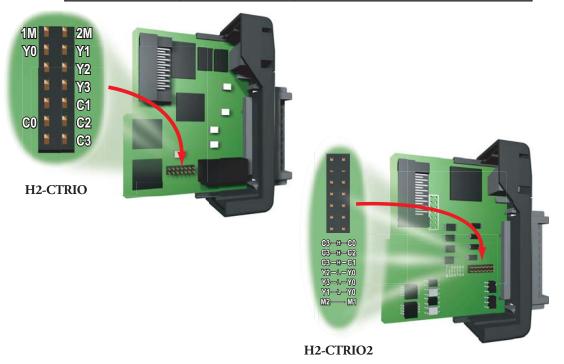
H2-CTRIO(2) Jumper Setup

Jumpers are provided to connect input commons or outputs/output commons. Use of these jumpers is not necessary to set up the CTRIO(2) module. The jumpers are provided solely for convenience in wiring.



NOTE: The location of the jumper board and pin assignments are different between the CTRIO and CTRIO2.

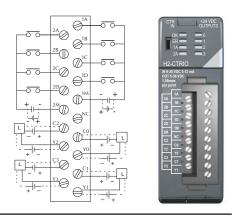
| H2-CTRIO(2) Jumper Functions | | | | |
|------------------------------|--------------|--|--|--|
| H2-CTRIO | H2-CTRI02 | Function | | |
| 1M | l-2M | Install jumper to internally connect the input commons 1M and 2M in order to reduce wiring if appropriate. | | |
| | I-Y1 | Install jumper(s) to internally connect Y0 to other Y terminals in order | | |
| |)-Y2)-Y3 | Install jumper(s) to internally connect Y0 to other Y terminals in orde to reduce wiring if appropriate. Connect wire at Y0 . | | |
| C0-C1 | | | | |
| C0-C2 | | Install jumper(s) to internally connect C0 to other C terminals in order to reduce wiring if appropriate. Connect wire at C0 . | | |
| C0-C3 | | | | |
| | C3-C0 | | | |
| | C3-C1 | Install jumper(s) to internally connect C3 to other C terminals in order to reduce wiring if appropriate. Connect wire at C3 . | | |
| | C3-C2 | | | |



Wiring Information

The H2-CTRIO(2) module has two independent input channels, each consisting of four optically isolated input points (pts. 1A-1D on common 1M and pts. 2A-2D on common 2M). The inputs can be wired to either sink or source current.

The module has four optically isolated output points (Y0-Y3 with isolated commons C0-C3, respectively) that can be wired to either sink or source current. Remember that the internal jumpers can be used to connect the input commons or output commons together.



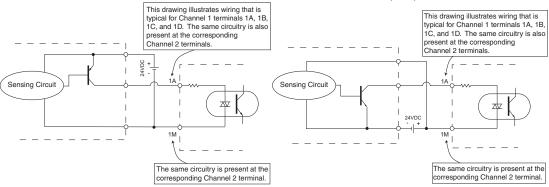


NOTE: Field device wiring must be compatible with the module configuration configured in Do-more Designer

DC type field devices are configured to either sink or source current. This affects the wiring of the device to the CTRIO module as seen below.

PNP Field Device (source)

NPN Field Device (sink)



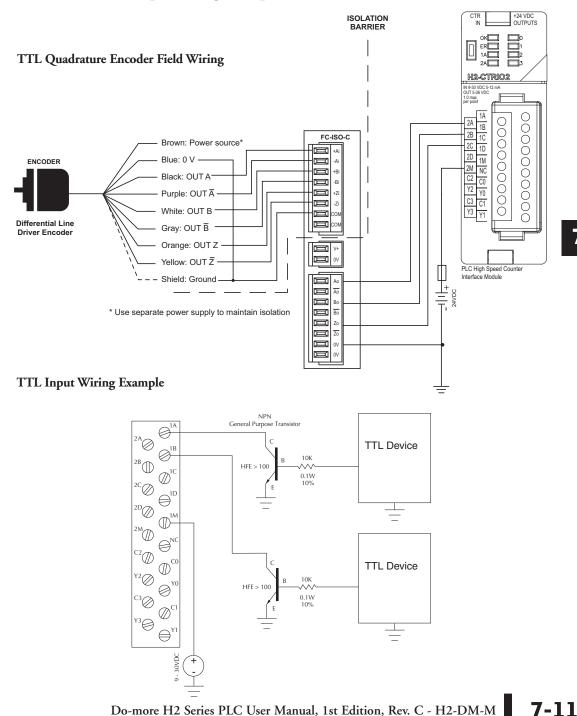
H2-CTRIO(2) Wiring Considerations

When wiring CTRIO modules, please consider the following:

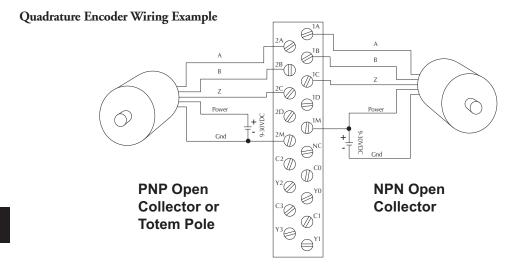
- Keep encoder input wiring as short as possible
- Route wiring to avoid any runs parallel to noisy cables.
- Route wiring to avoid the proximity of noisy devices.
- Use shielded, twisted pair cables, such as:

| Suggested Cabling | | | | | |
|---|------------------------------|-------------|--|--|--|
| Type of Cable Supplier/Part Number Supplier/Part Number | | | | | |
| 3 pair, twisted, overall shield | AutomationDirect/L19853-XXXX | Belden/8103 | | | |
| 1 pair, twisted, overall shield | AutomationDirect/L19827-XXXX | Belden/9841 | | | |

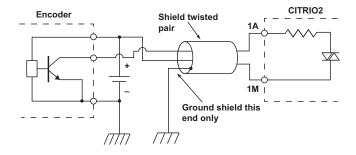
H2-CTRIO(2) Input Wiring Examples



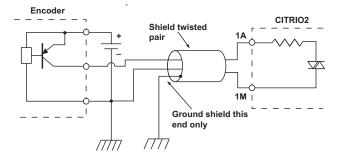
Do-more H2 Series PLC User Manual, 1st Edition, Rev. C - H2-DM-M



NPN Open Collector Device

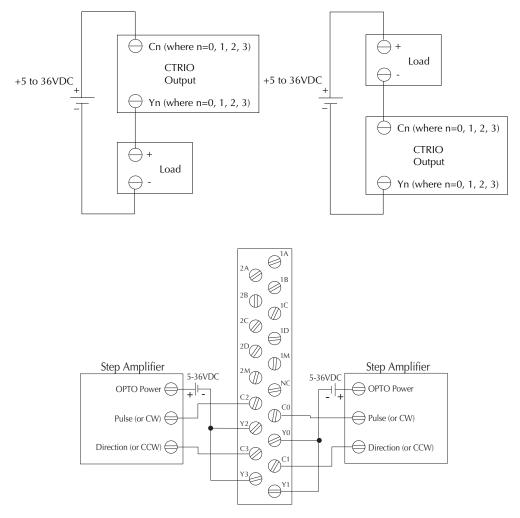


PNP Open Collector Device



H2-CTRIO(2) Output Wiring Examples

The four outputs are individually isolated so each output can be used to break the high or the low side of a DC load seperately



WARNING: The above example assumes that the Step Amplifier interface is made up of optocoupler LEDs (common anodes at the "OPTO Power" terminal) with internal current limiting resistors. This is a standard method, but you must consult your step amplifier documentation to ensure that this method is applicable.

H2-ECOM100

H2-ECOM100 Overview

The H2-ECOM100 Ethernet Communication (ECOM) module provides high-speed Ethernet connections for the Do-more PLC. These modules are easy to set up and install on 10/100BaseT (twisted pair, copper wire) Ethernet networks.

LEDs on the face of each module give vital information about the status of the module and the communications link. The 10/100BaseT modules use standard RJ45 modular connectors.

You can use the ECOM modules to share data between two or more Do-more PLCs or between Do-more PLCs and personal computers. The H2- ECOM100 additionally allows client/server communications with other Ethernet devices using the MODBUS TCP/IP protocol. Communication between PLCs and MODBUS TCP/IP devices is accomplished by using the MRX/MWX instructions.

You can use a personal computer equipped with a 10/100BaseT network adapter card and NetEdit3 software to configure the ECOM module over the network. Once configured, the H2-ECOM100 module allows you to program your Do-more PLC over the Ethernet network using the Do-more Designer programming software. The NetEdit3 utility installs with the Do-more Designer software and can be very useful for troubleshooting certain communication problems.



NOTE: We recommend using a dedicated network for your PLC control applications.

H2-ECOM100 Specifications

| H2-ECOM100 Ethernet Communications Module | | | |
|--|-----------------------|--|--|
| Specifications H2-ECOM100 | | | |
| Communications | 10/100Base-T Ethernet | | |
| Data Transfer Rate 100 Mbps max. | | | |
| Link Distance | 100 meters (328 ft) | | |
| Ethernet Port RJ45 | | | |
| Ethernet Protocols TCP/IP, IPX, Modbus TCP, DHCP, HTML configuration | | | |
| Power Consumption 300 mA @ 5 VDC | | | |



H2-ECOM100 LED Indicators

| H2-ECOM100 LED Descriptions | | | |
|---|--------------------|---|--|
| Indicator | Status Description | | |
| STATUS | ON (Green) | Module is powered up and functional | |
| SIAIUS | OFF | Module powerup failed | |
| LINKGD | ON (Green) | Properly connected to network | |
| LINKGD | OFF | Not connected to network or incorrect configuration | |
| ACTIVE ON or FLASHING (Red) | | Active Network Data | |
| AGTIVE | OFF | Network Idle | |
| CN or FLASHING (Red) A fatal error has occurred | | A fatal error has occurred | |
| OFF No error present | | No error present | |
| 100MBIT | ON | 100Base T Frequency detected | |
| OFF (with ACTIVE LED ON) - | | (with ACTIVE LED ON) - 10Base T Frequency detected | |



H2-ECOM100 Network Identifiers

Each module must be assigned at least one unique identifier to make it possible for other devices to recognize it on the network. There are four identifiers possible with the ECOM modules:

- Module ID
- Name
- IP (Internet Protocol) Address
- Ethernet (MAC) Address

The first three are user selectable but the MAC address is set at the factory. The type of identifier chosen depends on the requirements of your particular application. PC-to-PLC communication typically uses one type of identifier while PLC-to-PLC communication may require another. The following table summarizes Network Identifiers and their uses:

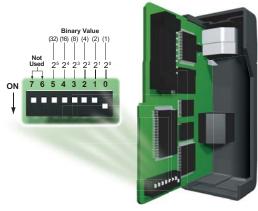
| Network Identifiers | | | | | |
|--|----------------|--|--|--|--|
| Identifier How to Set Format Communication Notes | | | | | |
| | DIP Switch | Number 1-63 | PLC-to-PLC or PC-to-PLC | Disables Module ID in NetEdit3 | |
| Module ID | NetEdit3 | Number 1-90 | PLC-to-PLC or PC-to-PLC | DIP Switch must be set to "0" | |
| | NetEdit3 | Number 1-999,999,999 | PC-to-PLC only | >90 (Not for PLC-to-PLC) | |
| Name | NetEdit3 | 32 Alphanumeric Characters | PC-to-PLC only | HMI software may have restrictions | |
| IP Address | NetEdit3 | 4 sets of numbers, up to three digits each (192.168.76.3) | PC-to-PLC, (PLC-to-PLC Client/Server using TCP/IP or Modbus TCP protocols) | See your Network Administrator for IP addresses | |
| Ethernet (MAC) Address | Set at Factory | 12 Hex digits | PC-to-PLC only | Factory assigned for IPX | |

Module ID

A Module ID is required for PLC-to-PLC communication and it can be set in two ways:

- using the DIP switches on the module
- using the configuration tools in NetEdit3
- HTML configuration (after IP address is assigned to module using NetEdit3)

Use the DIP switches if you want the ability to install or change modules without having to use a PC to set the Module ID. Set the module's DIP switches, install the module in the base and apply power. The Module ID will be accepted on powerup and your ECOM will be ready to communicate.



Name

A Name makes it easy to recognize the PLC by its function. An example of a Name is "PumpStationOne", as seen in the diagram below. The Name can be up to 32 alphanumeric characters in length.

NOTE: Some HMI software products will not accept Names with numbers as the first character, spaces or certain other non-alphanumeric ASCII characters. Also, your HMI product may not accept Names longer than 16 characters. Consult your HMI product documentation about its naming conventions.

IP Address

An IP Address can be assigned to the ECOM module if your network requires one. Usually, the IP Address is required in cases where PLCs are sharing the same network with PCs, and some of the PCs are



carrying out functions unrelated to PLC control. Normally, a network administrator will assign an IP Address to each device on the network. Use NetEdit3 to configure the assigned IP address to the ECOM.



NOTE: You must use an IP address if you are using the UDP/IP or Modbus TCP protocol.

The module ships from the factory with an IP Address of 0.0.0.0. This is not a usable IP Address for normal communication. It only serves as a default setting which can be changed using NetEdit3. The valid setting for each field is 1 through 254. You do not have to change the default IP Address unless you are using the IP Address to link to your ECOM module. The default setting does not cause conflicts with other network communications. If you change the default IP Address for linking to other network devices, you must change all four "0" fields.

Example IP Addresses - If the Client (PC/ECOM) Subnet Mask is 255.255.0.0 and the Client has an IP Address of 192.168.50.2, then the following are valid Server IP Addresses:

- 192.168.55.5 Valid Server ECOM IP Address
- 192.168.70.15 Valid Server ECOM IP Address

The subnet mask determines which fields must match by assigning a 255 to that field. In the example above, the first two fields are masked with a 255, therefore valid Server IP Addresses must match the first two fields of the Client IP or 192.168. The last two fields are allowed to vary because they are masked with a "0".



WARNING: It is extremely important not to have duplicate IP Addresses on your network. If you are using the IP Address to link the ECOM to any network devices (PCs or PLCs), the ECOM must have a unique number.

Ethernet (MAC) Address

A unique Ethernet (MAC) Address is assigned to each module at the factory and will not change. It is printed on a label attached to each ECOM module. The Ethernet (MAC) Address is recognized by NetEdit3. The Ethernet (MAC) Address is a twelve digit number with no deliberate relationship to your network or functional areas of your plant. Typically, the MAC address is not a convenient and easily remembered identifier for your ECOM module.

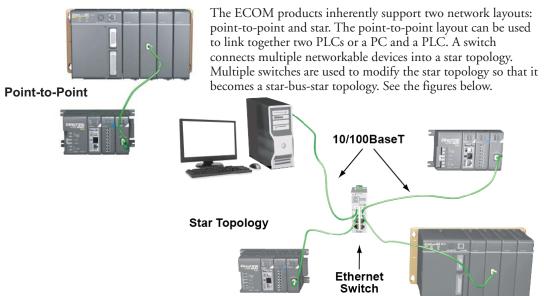


Using Multiple Network Identifiers

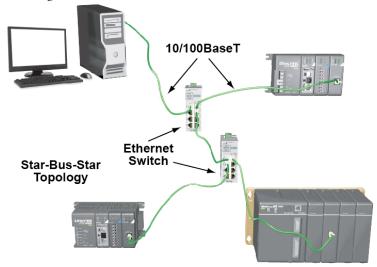
You can use IP Addresses to satisfy network requirements, the Name identifier for PCs running HMI software and Module IDs for PLCs to share data among themselves. Using one type of identifier does not limit your use of the other identifier types.

H2-ECOM100 Network Layouts

The ECOM Ethernet network is a peer-to-peer network. Using Read (RX) or Write (WX) instructions, any PLC on the network can initiate communications with any other PLC on the network. A PC running our KEPDirect software can also initiate communications with any ECOM that is on the same network, but a PLC cannot initiate communication with the PC. An ECOM can sequence through communication connections with each PLC on the network, one at a time.



Switches can connect together to make it possible to connect more devices to the network or to extend the range of the network.



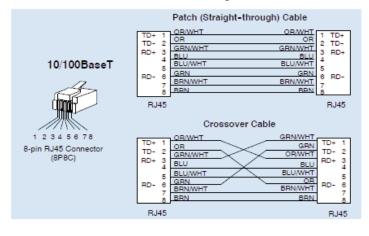
H2-ECOM100 Network Cabling

The H2-ECOM100 module supports 10/100BaseT standard cabling consisting of copper wire twisted pairs.



10/100 BaseT Networks

The cable used to connect a PLC (or PC) to an Ethernet switch is called a patch (straightthrough) cable. The cable used to connect together two PLCs, a PC and a PLC, or two switches is a crossover cable. We recommend that you purchase cables pre-assembled with connectors for convenient and reliable networking.

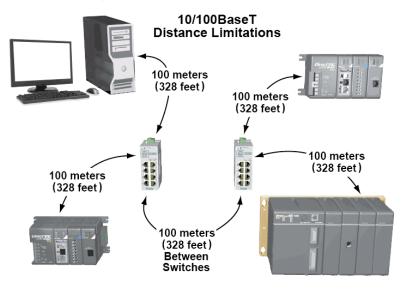




NOTE: The above diagram illustrates the standard wire positions in the RJ45 connector. We recommend all ECOM 10/100BaseT cables to be Category 5, UTP cable.

Cable Lengths

The maximum distance per 10/100BaseT cable segment is 100 meters or 328 feet. Switches allow multiple 100 meter cable segments to be joined together increasing the allowable distance. For example, two switches connected together adds an additional 200 meters to the system, for a total range of 300 meters.



Maximum Number of ECOM Modules on the Network

The maximum number of nodes that can be connected to a 10/100BaseT network is a function of the topology used in constructing the network. Therefore, it is not possible to state an absolute maximum number of nodes that would apply in all cases.

The IEEE 802.3 specification defines the maximum node limit for an Ethernet segment in terms of the ability to detect and avoid data collisions. A "legal" network can have any number of devices provided that they can:

- detect all data collisions that may occur during the communication process and
- respond to these collisions appropriately.

You must take into consideration the network limitations imposed by all cabling and network devices. Consider the limitations imposed on your network if your network uses:

- a combination of cabling standards, such as 10/100 BaseT and 10Base2, or
- intermediate devices, such as switches or routers.

Each ECOM module can be assigned a Module ID ranging from 1 to 999,999,999. Theoretically, you could have this many Ethernet modules coexisting on a single network. Other network limitations would restrict the network size before reaching this limit. For the majority of network PLC applications there is practically no limit to the number of ECOM modules you can access from the NetEdit3 or Do-more Designer software. There is a node limit for PLC-to-PLC communications. The network Read and Write instructions performed by the initiating (master) PLC are only capable of accessing PLCs with Module IDs of 1 through 90. This effectively sets the maximum number of nodes available for PLC-to-PLC communications at 90.



WARNING: We recommend against connecting Ethernet modules to the same network that serves as your primary office network. While Ethernet networks can handle a very large number of data transmissions, and normally handle them very quickly, heavy Ethernet traffic can adversely affect the reliability and speed of the network.

H2-ERM(100)/H2-EBC100

H2-ERM(100) Overview

Expanding I/O beyond the local chassis is useful for a system which has a sufficient number of sensors and other field devices located a relatively long distance from the CPU. The Ethernet Remote Master H2-ERM(100) connects Do-more CPU systems to slave I/O over a high-speed Ethernet link.

Each ERM module can support up to 16 H2-EBC systems, 16 Terminator I/O EBC systems, or 16 fully expanded H4-EBC systems. Of course, combinations are fine, too.



NOTE: Applications requiring an extremely large number of T1H-EBC analog I/O or H4-EBC 16-channel analog I/O, could exceed the buffer capacity of a single H2-ERM(100) module. In these cases, an additional H2-ERM(100) may be required.

The ERM connects to your control network using Category 5 UTP cables for cable runs up to 100 meters (328 ft.). Use Ethernet switches to extend distances and expand the number of nodes.

The PLC, ERM and EBC slave modules work together to update the remote I/O points. These three scan cycles are occurring at the same time, but asynchronously. Critical I/O points that must be monitored every scan are best placed in the CPU base.

It is highly recommended that a dedicated Ethernet remote I/O network be used for the ERM and its slaves. While Ethernet networks can handle a large number of data transactions, and normally handle them very quickly, heavy Ethernet traffic can adversely affect the reliability of the slave I/O and the speed of the I/O network. Ensure ERM networks, multiple ERM networks and ECOM/office networks are isolated from one another.

H2-ERM(100) Ethernet Remote I/O Master Module H2-ERM100 Specifications H2-ERM Ethernet Communications Master Module Module Type 16 Max Slaves per ERM **Communications** 10BaseT Ethernet 10/100BaseT Ethernet 100Mbps Data Transfer Rate 10Mbps RJ45 Ethernet Port 320mA @5VDC 300mA @5VDC Power Consumption 0°C to 60°C (32°F to 140°F), 35% to 95% humidity (non-**Operating Environment** condensing) 100 meters (328 ft) Link Distance TCP/IP, IPX Ethernet Protocols TCP/IP, IPX Modbus TCP/IP, DHCP, HTML configuration



H2-ERM(100) Specifications

| H2-ERM(100) LED Descriptions | | | | |
|---|-------------------|------------------------|--|--|
| Indicator Status Description | | | | |
| LINKGD | ON | Communications Link OK | | |
| ACTIVE | ON Network Active | | | |
| ACTIVE | OFF | Network Idle | | |
| ERROR ON or Flashing Fatal Error Detected | | | | |

H2-ERM(100) LED Indicators



H2-EBC100 Overview

The Ethernet Base Controller (EBC) serves as an interface between the master control system and remote I/O modules. The control function is performed by the master controller, not the EBC slave. The EBC occupies the CPU slot in the base and communicates across the backplane to input and output modules. The function of the EBC is to:

- process analog and digital input signals
- · format the I/O signals to conform to the Ethernet standard
- transmit input signals to the network master
- · receive and translate output signals from the network master
- distribute the output signals to the appropriate output module in the base

The H2-EBC100 module supports industry standard 10/100BaseT Ethernet communications.

NOTE: The RS-232 serial port on the EBC module cannot be used when the EBC module is part of the Domore controller system.

H2-EBC100 Specifications

network master.

| Specifications | H2-EBC100 | |
|--------------------|---|--|
| Communications | 10/100BaseT Ethernet | |
| Data Transfer Rate | 100Mbps max. | |
| Link Distance | 100 meters (328 ft) | |
| Ethernet Port | RJ45 | |
| Ethernet Protocols | TCP/IP, IPX/Modbus TCP/IP, DHCP, HTML configuration | |
| Serial Port* | RJ12 | |
| Serial Protocols | K-Sequence, ASCII IN/OUT, Modbus RTU | |
| Power Consumption | 300mA @ 5VDC | |

* The serial port on the EBC modules cannot be used when the H2-DM1/E is the

12-EBC100 RS 232 ERIAL PORT 10/100 BASE-T ETHERNET PORT

| H2-EBC100 LED Descriptions | | | | |
|----------------------------|----------------------|---|--|--|
| Indicator | Status | Description | | |
| STATUS | ON (Green) | Module is powered up and functional | | |
| 514105 | OFF | Module powerup failed | | |
| LINKGD | ON (Green) | Properly connected to network | | |
| LINKGD | OFF | Not connected to network or incorrect configuration | | |
| ACTIVE | ON or FLASHING (Red) | Active Network Data | | |
| AGTIVE | OFF | Network Idle | | |
| ERROR | ON or FLASHING (Red) | A fatal error has occurred | | |
| OFF | | No error present | | |
| 100MBIT | ON | 100Base T Frequency detected | | |
| TUUMDIT | OFF | (with ACTIVE LED ON) - 10Base T Frequency detected | | |
| TXD | FLASHING (green) | Serial port is transmitting data | | |
| RXD | FLASHING (green) | Serial port is receiving data | | |





H2-ERM(100)/H2-EBC100 Network Identifiers

Each module must be assigned at least one unique identifier to make it possible for other devices to recognize it on the network. There are three identifiers possible with the ERM/EBC modules:

- Module ID
- IP (Internet Protocol) Address
- Ethernet (MAC) Address

The first two are user selectable but the MAC address is set at the factory. The identifiers are used to link the ERM module to its remote EBC slaves. The type of identifier chosen depends on the protocol requirements of your particular application. The following table summarizes Network Identifiers and their uses:

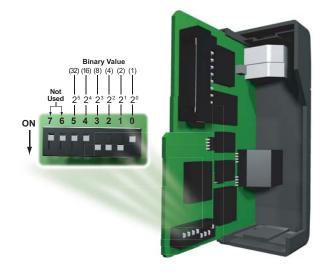
| Network Identifiers | | | | | |
|---|--------|----------------|---|---|--|
| Identifier Protocol How to Set Format Notes | | | | | |
| Module ID | IPX | DIP Switch | Slave Number 1-63, Set ERM to 0 | Module ID can be changed without NetEdit3. When set, disables Module ID selection in NetEdit3 | |
| | | NetEdit3 | Slave Number 1-65535, Set ERM to 0 | DIP Switch must be set to "0" | |
| IP Address | UDP/IP | NetEdit3 | 4 sets of numbers, up to three digits each (192.168.76.3) | See your Network Administrator for IP addresses | |
| Ethernet (MAC) Address | IPX | Set at Factory | 12 Hex digits | Factory assigned for IPX | |

Module ID

Always set the ERM module ID to 0. A slave EBC Module ID can be set in one of two ways:

- Use the DIP switches on the module (1-63).
- Use the configuration tools in NetEdit3 (1-65535).

Set the Module ID using the DIP switches if you wish to be able to install and change slave modules without using a PC. The Module ID equals the *sum* of the binary values of the slide switches set in the ON position. For example, if slide switches 1, 2 and 3 are set to the ON position, the Module ID will be 14. This is found by adding 8+4+2=14. The maximum value which can be set on the DIP switch is 32+16+8+4+2=63. This is achieved by setting switches 0 through 5 to the ON position. The 6 and 7 switch positions are inactive.



H2-ERM(100)/H2-EBC DIP Switch Location

Set the module's DIP switch, insert the module in the base, and connect the network cable. The Module ID is set on powerup, and it is ready to communicate on the network.

The Module IDs can also be set or changed on the network from a single PC by using the tools in NetEdit3.

IP Address

An IP Address can be assigned to the ERM module or its slaves if your network requires one. Normally, a network administrator will assign an IP Address to each device on the network. Since it is recommended to use a separate dedicated network for your ERM, you do not have to use the IP Address, unless you are using the UDP/IP protocol. Use the Module ID or Ethernet Address for each module when using the IPX protocol. You can use NetEdit3 within the ERM Workbench utility to give the ERM or its slave modules an IP Address. Each ERM and slave must have a unique IP Address.

The module ships from the factory with an IP Address of 255.255.255.255. This is not a usable IP Address for normal communications. It only serves as a default setting which can be changed using NetEdit3. The valid settings are 0 through 254. You do not have to change the default IP Address unless you are using IP Address protocol. The default setting does not cause conflicts with other network communications. If you change the default IP Address for linking to other network devices, you must change all four "255" fields. If any field contains the number 255 and other fields have been changed, the module will not be recognized on the network.

Example IP Addresses

- 192.168.55.5 Valid IP Address
- 255.168.55.5 Not Valid



WARNING: It is extremely important not to have duplicate IP Addresses on your network. If you are using the IP Address, all modules must have a unique number.

Ethernet (MAC) Address

A unique Ethernet (MAC) Address is assigned to each module at the factory and will not change. It is printed on a label attached to each ERM/EBC module. The Ethernet (MAC) Address is recognized by NetEdit3. The Ethernet (MAC) Address is a twelve digit number with no deliberate relationship to your network or functional areas of your plant. Typically, the MAC address is not a convenient and easily remembered identifier for your ERM/EBC module.

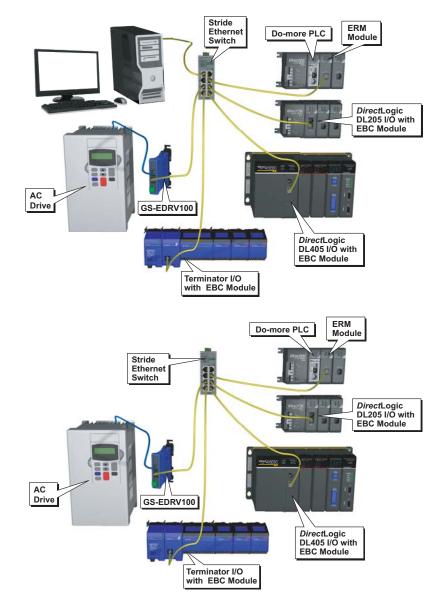


Using Multiple Network Identifiers

You can use IP Addresses to satisfy network requirements and Module IDs for PLCs to share data among themselves. Using one type of identifier does not limit your use of the other identifier types.

H2-ERM(100)/H2-EBC100 Network Layouts

Each ERM module can support up to 16 remote slaves. The slaves supported are the H4–EBC, H2–EBC, T1H–EBC, GS–EDRV100 and HA–EDRV2. Use a PC equipped with a 10/100BaseT network adapter card and the Ethernet Remote Master (ERM) Workbench software configuration utility to configure the ERM module and its slaves over the Ethernet remote I/O network. Once the ERM I/O network is configured and running, the PC can be removed from the network.



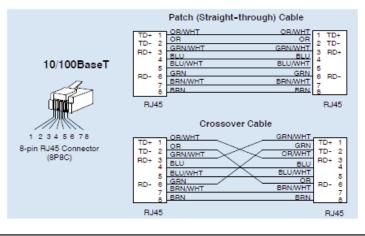
H2-ERM(100)/H2-EBC100 Network Cabling

The ERM/EBC modules support 10/100BaseT standard cabling consisting of copper wire twisted pairs.



10/100 BaseT Networks

The cable used to connect a PLC (or PC) to an Ethernet switch is called a patch (straightthrough) cable. The cable used to connect together two PLCs, a PC and a PLC, or two switches is a crossover cable. We recommend that you purchase cables pre-assembled with connectors for convenient and reliable networking.

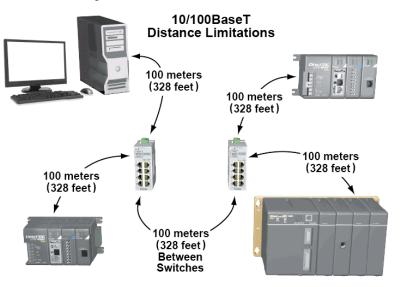




NOTE: The above diagram illustrates the standard wire positions in the RJ45 connector. We recommend all ECOM 10/100BaseT cables to be Category 5, UTP cable.

Cable Lengths

The maximum distance per 10/100BaseT cable segment is 100 meters or 328 feet. Switches allow multiple 100 meter cable segments to be joined together increasing the allowable distance. For example, two switches connected together adds an additional 200 meters to the system, for a total range of 300 meters.



H2-SERIO(-4)

H2-SERIO(-4) Overview

With the H2-SERIO, three additional RS-232 ports can be added to your Do-more system. On the other hand, the H2-SERIO-4 can give you two additional RS-232 ports and one RS-485 or RS-422 port. As many as eight of these modules may be added to the local base, adding up to 24 serial ports (presently, there is no means of using these modules in ethernet remote bases mastered by a Do-more CPU via an ERM module).

The serial ports of the H2-SERIO(-4) support the following functions which can be selected in the Module Configuration of the Do-more software (as seen below):

- Do-more Programming Select this option to setup the port to work with the Do-more Designer programming software.
- K Sequence Select this option to have the port respond to client devices running K Sequence protocol.
- Modbus RTU Server Select this option to have the port respond to client devices running Modbus/RTU protocol.
- Modbus RTU Client Select this option to make the port available for use by the Do-more controller's Modbus Network Read (MRX) and Modbus Network Write (MWX) instructions.
- General Purpose Select this option to make the port available for use by the Do-more controller's Input String from Device (STREAMIN) and Output String to Device (STREAMOUT) instructions.

| figuration Entries | Module Configurations | | | | |
|--|--|-----------------------------|---|--|-------------|
| CPU Configuration I/O Configuration DL205 Local I/O Master | between the program | and the module, eliminating | ctions require a Module Configuration. The the need for Base/Slot addressing in the p that is provided through the Module Conf | | ection |
| Module Configuration(s) | Module Name | Туре | Location | | New Config |
| Device Configuration I/O Mappings | SERIO_000 | Hx-SERIO/SERIO4 | DL205 Local I/O Master->DL205 Base | e->Slot 0 | |
| Memory Configuration | | | | | Edit Config |
| Edit SERIO/4 Configu | | | | | X Config |
| - Module Configuratio | | | | Configuration Notes | D.Confi |
| Name: SERIO Info: Modul Port A Name: SERIO Mode C Do-more Pr C K Sequence C Modbus RT C Modbus RT G General Pu Device Sett | - Type: Hx-SERIO/SERIO4 Port B Nam Ogramming Server U Client pose | e: SERIO_000_B | D Master : DL205 Base : Slot 0 Port C Name: SEPIO_000_C Mode C Do-more Programming C K Sequence Server C Modous RTU Server Modous RTU Server Modous RTU Clent G General Purpose Device Settings | Each port has an associated device that specific to the selected port function. When a different port function is chosen the associated device may be deleted a replaced with a new device. Because port device changes can have significant impact on the system config, they are not applied until OK or 'Apply' are pressed. You will be notified of any potentially important changes and given the option to cancel. When a device change is pending, the system config and re-enable the Device Settings' button. All options except 'General Purpose' are built- protocol clems to arevers. 'General Purpose' configures the port for control by the user program, which can send and receive ASCLI or raw data with the custom protocol instructions. | v ad |

Baud rates, parity and communication bit settings are accessible by selecting the Device Settings... button located below the General Purpose selection or through the Device Configuration section of the System Configuration window. Baud rates up to 115,200 are supported.

| | Module Configurations | | | | | |
|--|---|--|---|--|---|----------|
| PU Configuration /O Configuration ⊟- DL205 Local I/O Master └── DL205 Base | between the program and | d the module, eliminating the | ns require a Module Configuration, need for Base/Slot addressing in th at is provided through the Module Co | | onnection | |
| Iodule Configuration(s) | Module Name | Type | Location | | New | / Confia |
| levice Configuration /O Mappings | SERIO_000 | Hx-SERIO/SERIO4 | DL205 Local I/O Master->DL205 Ba | ase->Slot 0 | | |
| lemory Configuration | | | | | Edit | Config |
| | | | | | Delet | e Confia |
| Edit SERIO/4 Configura | ation | | | | 23 | econny |
| | | | | | | n Config |
| Module Configuration | | | | Configuration Notes | | |
| Info: Module Port A Name: SERIO_00 Mode Co-more Pro K Sequence 1 Modbus RTU Modbus RTU General Purp Device Settin | gramming Server C P Server C P Client C P ose C C | Stopper Control: Stopper Cont | ISSRED.0000/A | Each port has an associated device ti specific to the selected port function. When a different port function is cho the associated device may be deleter replaced with a new device. Because port device changes can has significant impact on the system conf they are not applied until 'OK' or 'App are presed. 'You will be notified of an potentially important changes and giv the option to cancel When a device change is pending, th 'Device Settings' option for that po be disabled. Press 'Apply' to update to system config and re-enable the 'Devis Settings' button. All options except 'General Purpose' a built-in protocol clients or servers. 'General Purpose' configures the port control by the user program, which c | sen, dand ve g, ly' ny ven ven rt will the are t for an | |

These parameters can also be set programmatically using the SETUPSER instruction seen here. See the Do-more Help file for more information on communication instructions.

| Do-more Designer - UNTITLED - [\$Main] | and the second | States Line | Berne Base | | |
|---|-------------------------------|---------------------------------|--------------------------------|---|---|
| 19 17 18 10 17 18 1 | do Cut Copy g Trend Status | Paste Find Find Ne | 1 v2:? | Next Output 100% - | On The Web Tip . Check PID Overview PID View . |
| Project Browser Proje | 3 RTS Co On Suc | Rate ER Its Its Its | - | SETUPSER Device Baud Rate Stop Bits Stop Bits | ol Follows Transmitter s, Set bit C0 |
| Instructions Accept F2 F3 Sh+F2 Sh+F3 F5 F6 Help, press F1 | | PLC Mode Swit Debug | Delta Out g Mode indica S P | -(S)(R)- Set Reset Browse D Offline 00084/6553 | ^w Edit Mode - |

Do-more H2 Series PLC User Manual, 1st Edition, Rev. C - H2-DM-M

7

H2-SERIO(-4) Specifications

| H2-SERIO / H2-SERIO-4 Serial Communications Module | | | | |
|--|--|---|--|--|
| Specifications | H2-SERIO H2-SERIO-4 | | | |
| Module Type | Intelligent | | | |
| Approvals | cUL Listed, file number E185989 | | | |
| Number of Serial Ports per Module | 3 ports: all RS-232 (RJ12 jack) 3 ports: 2 RS-232 ports (RJ12 jack) and 1 RS-422/485 (5 position terminal strip) | | | |
| Signals | RS-232: CTS, RXD, TXD RTS, GND RTS transmission delay times: 5, 50, 250 and 500 ms | RS-232: CTS, RXD, TXD RTS, GND RTS transmission delay times: 5, 50, 250 and 500 ms RS-422 (4 wire) : TX+, TX-, RX-, RX+, GND RS-485 (2 wire): Data+, Data-, GND | | |
| Number of Modules Supported per Do-more PLC | | | | |
| Recommended Cables | RS-232: ZL-RJ12CBL-2 | RS-232: ZL-RJ12CBL-2 RS-422: ADC L19853-x (Belden 8103) RS-485: ADC L19954-x (Belden 9842) | | |
| Protocols Supported | Serial ASCII (full-duplex), K Sequence, Modbus/RTU and Do-more programming | | | |
| Power Consumption | 80 mA @ 5 VDC | | | |
| Baud Rates | 1200, 2400, 4800, 9600, 19200, 38400, 5760 | 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200 | | |
| Parity | None, odd, even | | | |
| Start and Stop Bits | 1, 2 | | | |
| Operating Environment | 0 to 60°C (32°F to 140°F), 5% to 95% RH (n level 2; Vibration: MIL STD 810C 514.2; Shoc | on-condensing); No corrosive gases, Pollution k: MIL STD 810C 516.2 | | |
| Storage Temperature | -20 to 70°C (-4°F to 158°F) | | | |

H2-SERIO(-4) Wiring: RS-232

RS-232

6 pin RJ12 P Type Jack - bot

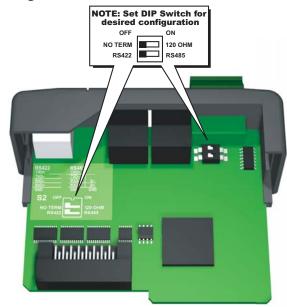
| | Descriptions | | | | | | |
|-----------------|--------------|-----|----------------------------|--|--|--|--|
| hone oth por | 1 | 0V | Power (-) connection (GND) | | | | |
| | 2 | CTS | Clear to Send | | | | |
| | 3 | RXD | Receive data (RS-232) | | | | |
| | 4 | TXD | Transmit data (RS-232) | | | | |
| | 5 | RTS | Request to Send | | | | |
| 1 | 6 | 0V | Signal Ground (GND) | | | | |
| | | | | | | | |

H2-SERIO(-4) RS-232 Pin



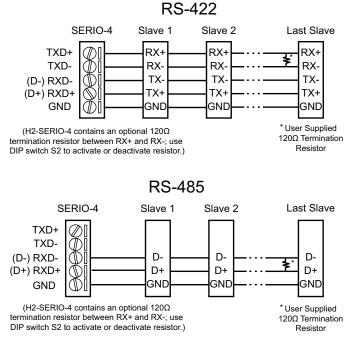
XMT B XMT C

H2-SERIO-4 Wiring: RS-422/485



Set DIP switch S2 on the H2-SERIO-4 to:

- 1. Activate or deactivate the internal 120Ω termination resistor.
- 2. Select RS-422 or RS-485 operation.



Do-more H2 Series PLC User Manual, 1st Edition, Rev. C - H2-DM-M

F2-08SIM, Input Simulator

F2-08SIM Specifications

| F2-08SIM Inpu | t Simulator |
|--------------------------|-----------------|
| Inputs per Module | 8 |
| Base Power Required 5VDC | 50 mA |
| Terminal Type | None |
| Status Indicator | Switch side |
| Weight | 2.65 oz. (75 g) |

