

- Q: *I do not have any experience with soldering or electronics in general. Will I be able to connect the OSD board to my wireless camera equipment?*
- A: Your video equipment will need to be wired to the OSD board. Although this is a simple task to someone that has some electronics experience, it will probably be a frustrating effort for beginners. All of our documentation is online, so you can see for yourself if your skills are up to the task. If not, then please arrange for hands-on help from someone with electronics experience.
- Q: *I'm not using the RSSI and external voltage inputs. Why does the display show a voltage for them? That is to say, why don't they show 0VDC?*
- A: With nothing connected to the inputs they will display random voltages. If you are not using these fields then it would be best to turn them off. Or better yet, put them to use!
- Q: *I understand that the RSSI input accepts a 0VDC to 5VDC voltage range. However, the voltage I want to use is higher than that. Is there a solution?*
- A: It is important that the RSSI input voltage does not exceed 5.0VDC or damage may occur. For higher voltages a voltage attenuator (divider) must be created using resistors. A typical circuit is shown below. The component values will depend on your application. For example, to divide the signal input voltage by ten, R1 should be 9K and R2 should be 1K. Capacitor C1 is typically .1uF, but its value will depend on your requirements.

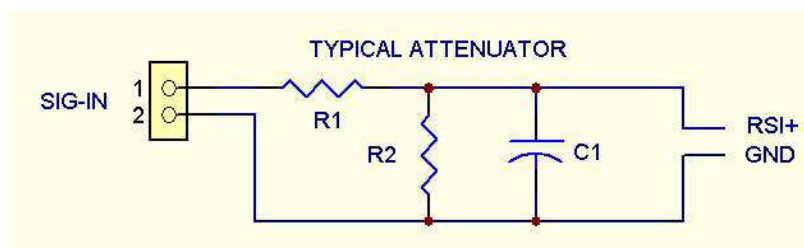


Figure 2, Attenuator Example

- Q: *The tachometer does not seem to work. Also, when I'm in the configuration screen that shows the Magnet Count value, I never see the star (★) character. I understand that it is present when the magnet is near the sensor. What is going on?*
- A: The magnets should be within 1/16" of the sensor for reliable operation. More important, the tach sensor is sensitive to only one pole of the magnet. My advice is to flip the magnet over to the other side (an opposite pole) and try again.

Q: *How many magnets should I use with the tachometer sensor?*

A: Most applications would use two magnets placed 180 degrees apart. By the way, the resolution of the tachometer is dependent on the number of magnets that are sensed per revolution. The resolution is summarized below:

<u>Tach Resolution</u>	
1 Magnets:	60 RPM
2 Magnets:	30 RPM
3 Magnets:	20 RPM
4 Magnets:	15 RPM
5 Magnets:	12 RPM
6 Magnets:	10 RPM

Note: Magnets should be evenly spaced. Above 9999 RPM the displayed resolution is formatted to 100RPM resolution regardless of magnet count.

Q: *My R/C ground range test does not pass when the video gear is used. What should I do?*

A: It is important that your R/C ground range test meet or exceed the manufacturer's recommendations. If your ground range test is not acceptable then the problem must be resolved before using the R/C system. Here are some things to try:

1. Never power the video system with the R/C system's battery. Use a dedicated pack.
2. Keep the video equipment far away from the R/C receiver and all wiring.
3. Keep the GPS cable/antenna far from R/C antenna.
4. Change the routing of your video wiring.
5. Keep all wiring as short as possible.
6. If necessary, disconnect Inspire from the R/C receiver.

Q: *I'm using the micro-GPS module and want a longer cable for it. Do you offer one?*

A: Not at this time. However, if you are skilled at soldering, you can extend the cable up to eight inches. The longer wires may introduce more EMI/RFI; do not allow your extended cable to be routed near your R/C system.

Q: *I'm confused about the fields that show waypoint bearing and distance, as well as the return to home direction arrows. What exactly is a waypoint and what do I need to see all this data?*

A: A waypoint is a specific geographical location. It is identified by its longitude and latitude position. Some GPS receivers allow the user to store one or more waypoints and then use the GPS to direct them to these locations. In addition, the return to home arrow is nothing more than a waypoint to your starting location. To use the waypoint data, Inspire is designed to interface with the popular Garmin Geko 201 GPS receiver. This GPS system allows for easy entry of the waypoint information, including complex routes with several waypoint locations. During use, the Geko sends the real time waypoint status to Inspire, which it then displays to you.

In the example shown in Figure 2, the data outlined in blue says that you must turn 32 degrees to the right in order to head toward arriving waypoint number 08. The waypoint is currently 0.03 miles away.



Figure 3, Waypoints

Q: *The micro-GPS module's data seems to be unstable when it is sitting still on a table. Is it defective?*

A: The GPS receiver is fine. When the GPS is stationary (static operation) the data will often change on its own due to the satellite signal processing. For those applications that are bothered by this, there is a setting in the GPS menu that can be used to reduce the bouncing data. Please see "Motion Filter" on Page 13 of the User Manual.

Q: *I don't get reliable GPS data while testing the system in my workshop. What is wrong?*

A: GPS receivers are designed for outdoor use. For reliable operation you'll need to move outside to an area that has clear view of the sky. Please allow several minutes for the receiver to establish a GPS signal lock with the heavenly satellites.

Q: *Even though I reset the AGL altitude, it does not always return to zero when I go back the exact same location. Sometimes it is off by nearly 50 feet!*

A: The accuracy of GPS altitude is typically fifteen meters. It can be better or worse, depending on the geographical location and satellite fix. If WAAS signals are available in your GPS area, and you have the WAAS/SBAS feature enabled in the setup menus (GPS Hardware, Page 4), then you have the best accuracy possible.

Q: *What is the pin-out of Inspire's 4-pin RS-232 connector? What are the RS-232 voltages?*

A: The pin-out is shown in Figure 3. The voltage levels are standard RS-232 (~±12VDC).

Q: *The current sensor's cables seem very short. Why aren't they much longer so that they can reach all the way to my battery pack?*

A: The provided current sensor wires are deliberately kept short to encourage the end user to choose the best wire gauge for their application. Please add your preferred connector (quality made 4.5mm bullet is typical) to the provided wires and then adapt to the wire size and length that is needed in your installation.

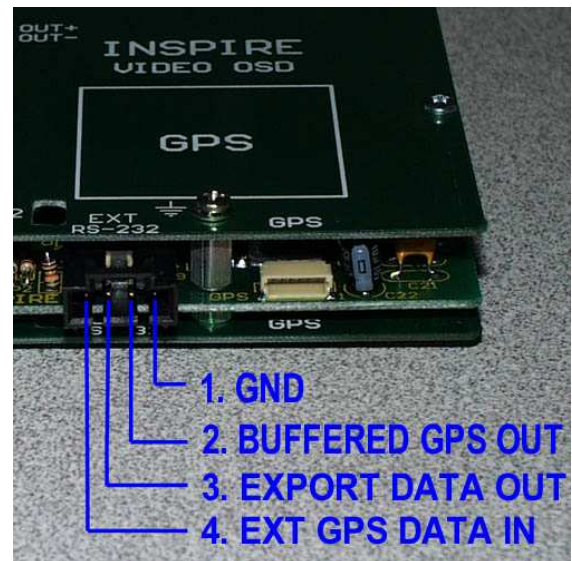


Figure 4, External RS-232 Connector

Q: *I would like to measure slightly more than 75 Amps during the brief periods my propulsion motor is under heavy load. Is this possible?*

A: The stock setup is rated for 75 Amps DC. However, the current sensor IC can accurately measure up to ±100 Amps DC. For safety, the stock heavy gauge wire leads will need to be replaced with a much heavier gauge. Please keep in mind that high currents require very high quality connections to ensure safe and reliable operation.