

# **FILE MANAGEMENT OF A USB FLASH DRIVE AND MEMORY CARD VIA MICRO SD CARD SLOT OF A MOBILE PHONE**

**By**

**Meryl Filomena B. Coching  
Kristine Doctor  
Francis Mark V. Evangelista  
Lynda Clarissa C. Santos**

A Design Report Submitted to the School of Electrical Engineering,  
Electronics Engineering, and Computer Engineering in Partial  
Fulfilment of the Requirements for the Degree

**Bachelor of Science in Computer Engineering**

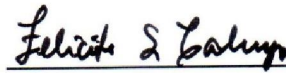
**Mapua Institute of Technology**

October 2011

## Approval Sheet

### Mapua Institute of Technology School of EE-ECE-CoE

This is to certify that we have supervised the preparation of and read the design report prepared by **Meryl Anne Filomena B. Coching, Kristine Doctor, Francis Mark V. Evangelista** and **Lynda Clarissa C. Santos** entitled **File Management of a USB Flash Drive and Memory Card via Micro SD Card Slot of a Mobile Phone** and that the said report has been submitted for final examination by the Oral Examination Committee.

  
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**Felicito S. Caluyo**  
Design Adviser

As members of the Oral Examination Committee, we certify that we have examined this design report presented before the committee on **October 3, 2011**, and hereby recommend that it be accepted as fulfilment of the design requirement for the degree in **Bachelor of Science in Computer Engineering**.

  
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**Ernesto M. Vergara Jr.**  
Panel Member

  
\_\_\_\_\_  
**Ramon G. Garcia**  
Panel Member

  
\_\_\_\_\_  
**Marianne M. Sejera**  
Chairman

This design is hereby approved and accepted by the School of Electrical Engineering, Electronics and Communications Engineering, and Computer Engineering as fulfilment of the design requirement for the degree in **Bachelor of Science in Computer Engineering**.

  
\_\_\_\_\_  
**Felicito S. Caluyo**  
Dean, School of EE-ECE-CoE

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## **ABSTRACT**

Most of modern mobile phones have a micro SD slot that is used for expanded storage. Inspired by the recently released Nokia N8 which has a USB On-the-Go feature that allows a flash drive to be connected via a cable used, the researchers constructed a design wherein the micro SD slot is used as a pathway to incorporate the USB port and the memory card port/s. The purpose of the design is to give the mobile phone additional storage and to access/transfer data using another media, in substitute for desktop PCs particularly. The flash drive to be used should comply with USB 2.0 and the memory card is limited to SD/mini SD with maximums of 2GB and 4GB total space limit respectively. The device is intended for mobile phones with a micro SD slot. The major hardware components of the design consist of SD memory slots, USB to SDIO Bridge Chip Host interface Transfer for the USB flash drive, relay circuits and a microcontroller which is programmed for port switching and a micro SD sniffer for the main output device. The single file copy speed test is conducted to test the functionality of the device. The transfer speeds for each flash memory are also looked upon and was observed that compared to the theoretical data transfer rates for the USB flash drive and SD memory card to the computer, the data transfer rates from the said flash memories with respect to the researchers device are acceptable. After testing the prototype, the researchers satisfied the assumptions that the file management is successful and the file integrity is preserved.

**Keywords:** micro SD, USB 2.0, USB On-the-Go, SD memory card, File Transfer

## Chapter 1

### DESIGN BACKGROUND AND INTRODUCTION

#### Background

Mobile phones have limited capabilities to access storage devices such as thumb drives and other memory cards that do not fit into the phone except card slots installed on the phone. Most of phones today have micro SD memory card slots installed. Almost all people nowadays have mobile phones, and almost all people have the need to transfer files quickly and want to ensure that data are successfully sent. As of now, the available media to send files are via infrared, Bluetooth, and one card slot that depends on what is installed on the phone. But what if the files needed are saved on a USB flash drive, SD memory card or mini SD memory card? Let's say one's phone only accepts a micro SD memory card. One solution is to have a computer to access files to transfer to one's phone. Not all people carry their laptops all the time; or to have access to a PC.

A memory card (sometimes called a flash memory card or a storage card) is a small storage medium used to store data such as text, pictures, audio, and video, for use on small, portable or remote computing devices. Most of the current products use flash memory, although other technologies are being developed. Memory cards offer a number of advantages over the hard disk drive: they're much smaller and lighter, extremely portable, completely silent, allow more immediate access, and are less prone to mechanical damage. A USB flash drive is portable memory storage. It is re-writeable and holds its memory without



a power supply, unlike RAM. USB flash drives will fit into any USB port on a computer. For a USB flash drive to function, it needs a host controller. Just like a PC, all flash drives have a storage device controller for it to read the device. This functionality is lacking in mobile phones since phones do not have a USB host controller.

This design is intended for on the go use. The user can simply insert the storage device and can easily manage files on their phones and the storage device. The phone will read the storage device as a memory card that is inserted in its memory card slot. Only one storage device can be read at a given time. To do this, there is a switch for every device wherein the users can mount the storage device they want to use. The design has a switching capability to choose what device is mounted.

The major components of this design are the SD card slots and USB flash drive slot wherein the user can insert a storage device. The design has a micro SD card sniffer so that the phone can access the storage inserted through this micro SD card sniffer. Switching components are used to access just one USB flash drive or either one of the memory cards at a time, because phones have a limited capability to read simultaneously storage devices.

### **Statement of the Problem**

Being students of Mapua Institute of Technology, the researchers continue to find ways to make life easy by innovating current technology advancements. This study's topic is mainly concerned with portable storage devices and mobile

phones. There is a need for a multi-purpose USB plus memory card reader/writer to host demanding storage applications and on-the-go access of the data.

The design is inspired by the fact that modern mobile phones like smart phones use the general purpose micro SD slot for data storage which limits the capability of the mobile phone to store data on other portable storage media like flash drives or other memory cards. Additionally, USB OTG (on-the-go) which is used by Nokia N8 to access/transfer data using a flash drive is limited only in their platform while other manufacturers of mobile phones do not incorporate such technology in their devices.

### **Objectives of the Design**

The main objective of this study is to design and construct a device that can manage files in a USB flash drive and memory card in a mobile phone via its micro SD card slot". Its specific objectives are as follows:

To construct the main circuitry of the device which will consist of the design's input, process, and output.

To create the prototype that will be able to route the data inside the flash memory for a specific destination.

To create a program that will make the device capable of responding to the user's selection of which flash memory device is to be activated in the mobile phone.

To test if the device is capable of managing files between the mobile phone and the activated flash memory device.

To verify that the data transferred to and from the device is intact with no corruption.

### **Impact of the design**

The significance of this design is to provide people a flexible way of transferring data. Mobile phones are limited to the use of memory cards, although nowadays some mobile phones have a micro USB port that supports USB OTG (on-the-go) that allows USB flash drives including external hard drives to be connected. However, only a few models have this feature and people are forced or enticed to buy them, which are quite expensive. More widespread are mobile phones that have a memory card; however these are restricted to the space they provide and users of these phones need to buy another memory card or delete some files if they need more space. People who need additional storage in different kinds of media will benefit from the proposed device because they will not be limited to the space that their memory card provides; they do not need to buy a new mobile phone and they do not need to worry if they need to access a file.

The design will not be costly to implement. The embedded system only uses a small amount of power to operate, the carbon footprint is minimal and resource utilization is low so no significant harmful effects contribute to the environment. Ethically, people will refrain from using and bringing their PCs just to transfer data because mobile phones are much more portable than PCs. Health and safety concerns will not be likely a problem because the design does

not emit harmful radiation. The design manufacturability is high especially when developed with surface mount technology and finally sustainability will be long-term due to modern mobile phones' heavy reliance on micro SD technology.

### **Design Constraints**

The design covers the USB and memory card slot/s that can be accessed using mobile phones with a micro SD slot.

The design utilizes the PIC microcontroller to manage the selection of which will route the data that will go through.

It is powered by a DC battery or adaptor due to the power requirements of the PIC microcontroller.

There are one USB port and two SD/MMC memory card ports.

The mobile phone can read all files of different types inside the activated flash memory to perform different file management features.

The design will utilize the Nokia C3 as the mobile phone model in the testing part of this study.

The following are the design constraints:

The USB flash drive to be used should be compliant with USB 2.0 standard or lower.

The USB flash drive to be used is limited to 4 GB of total memory space.

Mobile phones with micro SD slots are supported unless the memory card slot is located at the back of the device.

The memory card slot supports a mini SD with an adapter attached and SDs of up to 8GB total memory space.

All files inside the USB flash drive or memory card can be read but cannot be opened or executed unless they are supported by the mobile phone (e.g. mp3 or jpg files )

The size of the files to be transferred from the activated flash memory depends on the internal memory capacity of the mobile phone. Nowadays, mobile phones with micro SD slots have up to 8 GB internal mass memory.

### **Definition of terms**

**Microcontrollers** - are dedicated to one task and run one specific program. The program is stored in ROM (read-only memory) and generally does not change.

**Memory card** - sometimes called a flash memory card or a storage card, is a small storage medium used to store data for use on small, portable or remote computing devices.

**USB Host** - is where the USB host controller is installed and where the client software/device driver runs.

**The USB Host Controller** - is the interface between the host and the USB peripherals. The host is responsible for detecting the insertion and removal of USB devices, managing the control and data flow between the host and the devices, providing power to attached devices, and more.

**PDA**s– acronym for Personal Digital Assistants. It is a mobile device that functions as a personal information manager.

**Flash Memory** - is a non-volatile computer storage chip that can be electrically erased and reprogrammed. Types of flash memory are USB flash drives and SD memory cards.

**EEPROM** - stands for Electrically Erasable Programmable Read-Only Memory and is a type of non-volatile memory used in computers and other electronic devices to store small amounts of data that must be saved when power is removed.

**Voltage Amplifier** - An amplifier designed primarily to build up the voltage of a signal, without supplying it.

**Serial Port** - a serial communication physical interface through which information transfers in or out one bit at a time.

**Biasing** - is the method of establishing predetermined voltages and/or currents at various points of an electronic circuit to set an appropriate operating point.

**Voltage drop** - is the reduction in voltage in the passive elements (not containing sources) of an electrical circuit.

**Saturation** - is the fully conducting state in a semiconductor junction. The term is used especially in applications involving diodes and bipolar transistors

## Chapter 2

### REVIEW OF RELATED DESIGN LITERATURES AND STUDIES

#### **Digital Memory Card Market and Technology**

In recent years, the proliferation of portable consumer electronics such as MP3s, digital cameras, and 3G mobile phones has created a tremendous appetite for digital memory cards that use non-volatile flash memory for information and data storage. There are different card formats and designs such as Secure Digital (SD), mini-SD, MultimediaCards (MMC) and MMCmobile. These cards are assembled by either a chip-on-board (COB) process using bare dice, or surface mount technology (SMT) using packaged flash and controller components. The last step in card assembly is accomplished by using either a pre-mold cover or an injection mold process over a PCA (Printed Circuit board Assembly). (Wei Koh, 2005)

#### ***Flash Memory Types***

The NOR (Not OR) type flash memory was invented by Fujio Masuoka of Toshiba in 1984 and Intel developed it further for initial mass production. In 1987 Masuoka also invented the NAND (Not AND) type flash. Because these two kinds of flash function differently, their applications are suitable for different purposes. The fundamental reason is due to the cell design of the memory—a NAND cell size is smaller hence more density can be packed in an IC chip, whereas the NOR flash requires a larger transistor cell, hence lower density on the same sized

IC. Due to its faster speed and accuracy, NOR is typically used for code execution and NAND, being higher capacity but a little lower, is used more for data storage. The differences between the two types in functionality, however, are becoming smaller as their design and technology are merging together more closely in recent years.(Wei Koh, 2005)

### ***Flash Markets***

In recent years, the growth of NAND is expanding much faster than NOR. The applications in portable data storage, the wide popularity and growth in USB drives and digital still cameras all contribute to the need for more NAND memory. Whereas for NOR, its use in cell phones is now more limited to low-end and mid-range phones. For 3G and higher performance multimedia phones, or so-called smart phones, the trend is now using NAND and DRAM. For low and mid-range phones, the NOR and PSRAM (pseudo static random access memory) combination is used for initial phone registration with the base station and for code executions. For multimedia phones and smart phones, the trend is switching to the use of the SDRAM/NAND combination to increase memory storage capability.(Wei Koh, 2005)

### ***Digital Card Formats***

The following are the card formats using NAND flash memory for data storage: Compact Flash (CF), Multimedia Card (MMC), and Secure Digital (SD). Currently,



CF card market shares are gradually being taken over by thinner and smaller cards such as MMC and SD, as the memory density in these cards go up and increase their storage capacity. In coming years, each card format may come to be specialized in certain applications. For example, CF cards may concentrate on very high capacity (4 GB or higher) for use in high resolution (>6 million pixel) professional, high-end digital still cameras or even camcorders for high volume recording and storage. On the other end of the spectrum, the thin form factor cards are becoming even thinner and smaller for portable devices such as cellphones and multimedia phones or PDAs. The reduction in sizes in MMC—called MMC-*mobile* and the miniSD that is about half the size of a regular SD card—are obviously intended for mobile applications. Most recently, there are microSDs and MMC*micro*. The microSD card is based on SanDisk Transflash cards. Due to their minuscule sizes, initially, their memory densities are typically no more than 50% of their respective “mother” cards, or in the range of 128/256 MB. With use of MCP (multichip package), however, stacked flash die inside the card will enable even the smallest cards to have memory densities in the 512MB and even 1GB range. (Wei Koh, 2005)

### ***MMC versus SD***

When selecting the types of flash cards for application and devices, performance and other factors such as license, royalty, security, and standards are all part of design considerations. Currently MMC and SD cards are the two more dominant

formats of choice. The design and performance difference between the two cards are now nearly equal. One useful factor to note is that, because both MMC and SD cards have the same outer envelope, the MMC cards can be used in the same slot for SD cards and most readers are designed to accept both MMC and SD cards.(Wei Koh, 2005)

### ***Summary***

The growth of NAND and NOR-type flash memory cards has been phenomenal in the past few years with the proliferation of consumer use of portable devices and digital storage. The flash market in 2005 is \$17 billion for both NAND and NOR; however, NAND growth is expected to outpace NOR and will have higher revenue in the years to come. Currently, many different card formats are all growing in popularity, but SD and MMC cards are the leading formats as their memory density increases while CF cards are becoming more specialized in high-end professional digital photography. The fabrication process of MMC and SD cards is moving toward SIP and MCP, due to continued reduction in card size and thickness. Of 1.0mm and lower, the main manufacturing challenges include using a thin die stack, thin substrates and method of forming the final card dimensions by either applying a thin cover or directly over the mold.

## **USB on-the-go interface for portable devices**

Until recently, most portable electronic devices used proprietary wired interfaces for connecting to a PC, accessories or chargers. Such portable electronic devices include cell phones, digital cameras, personal digital assistants and mini-USB plugs. Not only was the mechanical interface different for different models from different vendors, but so also were the electrical and protocol interfaces. Proprietary cables and software packages were often required to connect these devices to PCs and connecting one portable device to another portable device was generally not possible. In recent years, the processing power and data storage capacity of portable devices has increased dramatically. Both manufacturers and consumers desire a standard data interface on portable devices in order to allow data sharing between portable devices, and allow the use of standard cables and accessories. Many of today's portable devices are moving towards the Universal Serial Bus (USB) electrical interface as a way of connecting to a PC, although as desktop interface, it is not well suited for portable devices. The PC acts as host (or master), and all other devices are peripherals (or slaves). Hosts cannot connect to hosts, and to peripherals. (Remple, T.B., 2003)

The mini USB plugs are smaller than the standard USB plugs, and are better suited for portable devices. In standard USB, each cable has a A-plug on one end, and a B-plug on the other end. The A-plug goes to the PC, which acts as the host or master, and the B-plug goes to the peripheral. This cabling

arrangement prevents pc3s (hosts) from being plugged into each other; and also prevents peripherals from being plugged into each other, works cannot connect to peripherals. However, when connecting portable devices together, one of the devices needs to accept a mini.i plug and act as the host, while the other needs to accept a mini-B plug and act as the peripheral. To avoid requiring portable devices to have both connectors are too large for portable devices. The mini AB receptacle accepts either a mini-A plug, or a mini-B plug. A device with a mini-AB receptacle is referred to as an OTG device. When a mini-A plug is inserted into an OTG device, it is referred to as an A-device. When a mini-B plug is inserted into a device, it is referred to as a B-device. The A-device defaults to being the host when the two devices are first connected. The A-device is always responsible for outputting power to the B-device. The following are the features that are required by portable devices, host capability for portable devices smaller connectors low power features in order for cell phones to use the mini-USB connectors instead of existing proprietary connectors, and the OTG interface also has to allow cell phones to connect to analog circuits. (Remple, T.B., 2003)

### ***Host Negotiation Protocol***

In order for an OTG device to act as host, it needs to have a software driver that can recognize and control the peripheral that is connected to it. When two OTG devices are connected, it is possible that the A-device does not have a software driver for the B-device, while the B-device does have a driver for the A-device. If

the A-device continues to act as host, then the two devices would not be able to communicate. To address this issue, the OTG Supplement defines a Host Negotiation Protocol (HNP). HNP allows an A-device and a B-device to swap the role of host automatically, in a way that is transparent to the user.

### ***Low Power Features***

The USB Specification requires that a PC (or A-device) is able to output 500mA. Moreover, the PC must always provide power to the bus, even when a remote device is not connected. These requirements are not practical for portable devices such as cell phones and PDAs. To accommodate portable devices, the OTG supplement requires an OTG device to output 8mA instead of 500 mA. Moreover, the A-device is only required to power the bus when the A-device and B-device are communicating. When the bus is powered down, the B-device requires a way of notifying the A-device that it wants to communicate. For this reason, the OTG Supplement defines a Session Request Protocol (SRP). SRP allows a B-device to request service from the A-device when the bus is powered down. (Remple, T.B., 2003)

### ***Mini-USB AnalogCarkit Interface***

In order for a cell phone to use the mini-USB connector as its primary data connector, the mini-USB connector must provide an interface to an analogcarkit. The interface allows several different signaling modes. In all modes, the VBUS

and GND pins are used for power. The remaining three pins can be used for either USB signaling, UART signaling, or analog signaling. The phone determines which signaling mode it should use by first detecting the state of the ID pin. If the ID pin is floating or grounded, then the phone uses USB signaling. If the ID pin is resistively coupled to ground, then the phone knows it is connected to a carkit. (Remple, T.B., 2003)

### **Dominant design or multiple designs: The Flash Memory Card case**

Any technology currently in use struggled with similar competing products before gaining the dominant design. The famous case of the VHS videotape is the best known example of such a battle. The emergence of a dominant design is very hard to predict and cannot be entirely explained by the economic literature. 'The dominant design is not automatically the technologically superior one, nor will it meet the needs of a particular class to the same extent as a customized design would' (Anderson & Tushman, 1990 and Suárez & Utterback, 1995). The emergence process for dominant designs has typically been viewed as a black box process involving a sophisticated interaction of technological and non-technological factors (Lee et al., 1995). There is even a possibility that no dominant design will emerge, even many years after product introduction. Examples of cases with no dominant design include: Smartphones, PDA phones, Blackberry, regular and advanced cell phones (including clock, photo camera, agenda); HDTV, regular LCD and the plasma screens; Microsoft Xbox, Nintendo

Wii, Playstation 3;DVD-R, DVD-RW, DVD-RAM, DVD-D, DVD+R, DVD+RW, DVD+R DL, HD-DVD and Blu-ray. (deVries, H.J., de Ruijter, J.P.M., & Argam, N., 2007)

### ***Available flash memory cards***

The most common data storage technology is the magnetic disk or hard disk. Beyond these systems, optical systems are recognized as dominant in archival digital data storage. Despite their numerous virtues, these systems also come with several disadvantages. For example, the magnetic and optical data storage systems are not always perfect, especially in small devices with limited power supply. To avoid these disadvantages, flash memory is a good alternative. A flash memory card differs from existing memory storage in that it needs no power supply (nonvolatile) and can be found in a wide range of portable electronic devices. There are a number of industrial standards for memory cards. Different companies produce different types of memory cards, all with different dimensions. In general, these different types are not interchangeable. Currently, roughly six types of flash memory cards exist.

1. *CompactFlash (CF)*. CF was introduced by Sandisk Corporation in 1994. Currently, CF is offered by multiple manufacturers. CF is superior in data transfer rates and capacity, but the large size and (relatively) high power consumption make it less suitable for small electronic devices, such as mobile phones.

2. *SmartMedia (SM)*. SM, owned by Toshiba, was launched in 1996. It was one of the smallest and the thinnest early memory cards, and maintained the most favorable cost ratio. It used to be the favourite card for digital cameras.

3. *Multi-MediaCard (MMC)*. MMC was developed by Siemens (Sandisk as well later on) in 1997. Nowadays, it is offered by multiple manufacturers. MMC micro is the smallest card in the world, (backwards) compatible with other cards, without a write or copyright protection (thinner profiled) and it is available to all developers.

4. *Memory Stick (MS)*. MS was developed and introduced by Sony in 1998. Sony uses this card for a range of different products and licenses it to other companies. MS Duo is the small version for pocket devices.

5. *Secure Digital Card (SD)*. SD was introduced by multiple manufacturers in 2001. The SD card is based on the MMC card but includes a built-in security function and a write protection switch. It is the most common used memory card because of its small size and low power consumption.

6. *Extreme Digital-Picture Card (xD)*. Olympus and Fujifilm introduced xD in 2002 for use in their cameras.

Compact Flash typically uses flash memory in a standardized enclosure. This form was first specified and produced by Sandisk in 1994. Compact Flash lacks the mechanical write protection switch that some other devices have, as seen in a comparison of memory cards. Compact Flash does not have any built in DRM or cryptographic features like on some USB flash drives and other formats such



as Secure Digital. Such features are rarely used on other cards, however, and are therefore mostly superfluous. Toshiba launched Smart Media to compete with MiniCard, CompactFlash, and PC card formats. A Smart Media card consists of a single NAND flash chip embedded in a thin plastic card (though some higher capacity cards contain multiple, linked chips). It was one of the smallest and the thinnest of the early memory cards, and managed to maintain a favorable cost ratio as compared to the others. It lacks a built-in controller, which keeps the cost down. This feature later caused problems, since some older devices would require firmware updates to handle larger capacity cards. The Multi Media Card is based on Toshiba's NAND-based flash memory, and is therefore much smaller than earlier systems based on Intel NOR-based memory such as Compact Flash. MMC originally used a 1-bit serial interface, but newer versions of the specification allow transfers of 4 or sometimes even 8 bits at a time. (deVries, H.J., de Ruijter, J.P.M., & Argam, N., 2007)

Digital cards (SD card) still see significant use because MMC cards can be used in most devices which support SD cards and they are cheaper than SD cards. RS-MMC cards (Reduced-Size Multi Media Cards) are smaller MMC cards; by using a simple mechanical adapter to elongate the card, an RS-MMC card can be used in any MMC slot. The only significant hardware licensors of RS-MMC cards are Nokia and Siemens. Sometimes a memory USB-stick is called a memory stick, but in this study it refers to the brand name of Sony's flash memory card Memory Stick™. Memory Stick is a removable flash memory card format. The Memory

Stick family includes the Memory Stick PRO, a revision that allows greater maximum storage capacity and faster file transfer speeds; Memory Stick Duo, a small-form-factor version of the Memory Stick (including the PRO Duo); and the even smaller Memory Stick Micro (M2). (deVries, H.J., de Ruijter, J.P.M., & Argam, N., 2007)

In summary, there are a host of factors indicating one dominant design to emerge, in particular the network externalities characterizing the market and the need to exchange cards between different products. However, a combination of factors at both the supplier and the consumer side outweigh these factors, instead favoring multiple cards. Some factors at the supplier side make it attractive for companies to introduce or maintain their own cards, to be used in own products or for other products as well. Moreover, the speed of technological development has prompted companies to introduce new cards before a battle could turn into a victory for one of the designs. At the consumer side, a combination of two factors make it easy to live with different cards: consumers buy the host devices and take the related card format for granted rather than consciously choose a certain card format. Furthermore, gateway technologies allow them to do this: the compatibility issues can be solved in a relatively easy way resulting in the advantages related to network externalities to remain. (deVries, H.J., de Ruijter, J.P.M., & Argam, N., 2007)

### ***Memory card address bus design***

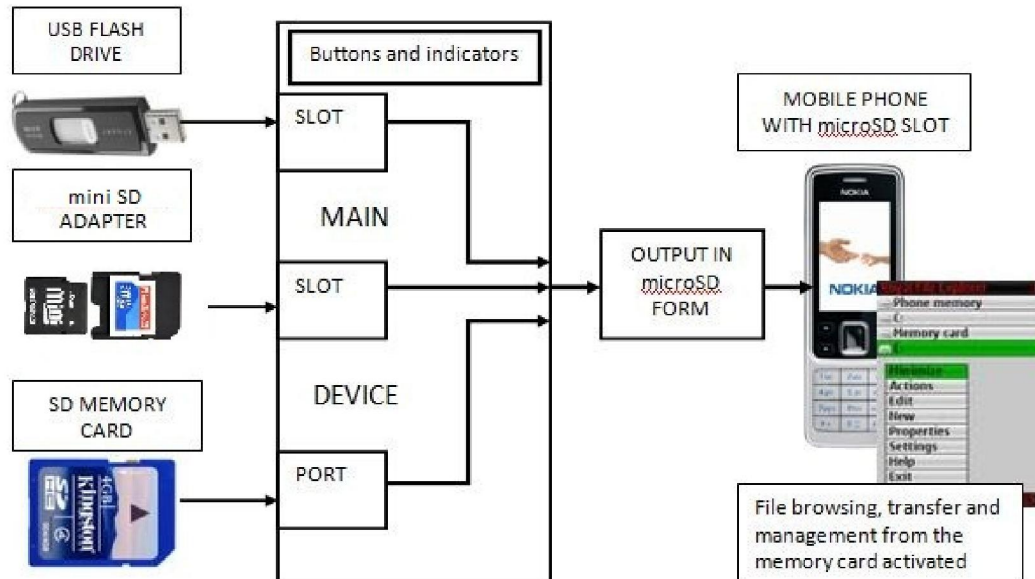
The need to store large quantities of data and information for a certain period of time determines the memory capability of a system. In a typical computer system, the central processing unit (CPU) generates the address of the particular memory location and places it on the address lines that make up an address bus. A memory card has many parallel address lines connected to a number of memory chips. These memory chips may supply program and data to the CPU or hold output data from arithmetic calculations or for printed output or displays. The address bit combination on the address lines determines which word line will be addressed for a particular operation. The designer must fully understand the requirements of the memory operation so the necessary address bit combination occurs at the proper time during the memory cycle. (deVries, H.J., de Ruijter, J.P.M., & Argam, N., 2007)

## Chapter 3

### DESIGN PROCEDURES

#### HARDWARE DEVELOPMENT

##### Conceptual Diagram



**Figure 3.1 – Conceptual Diagram of the Design**

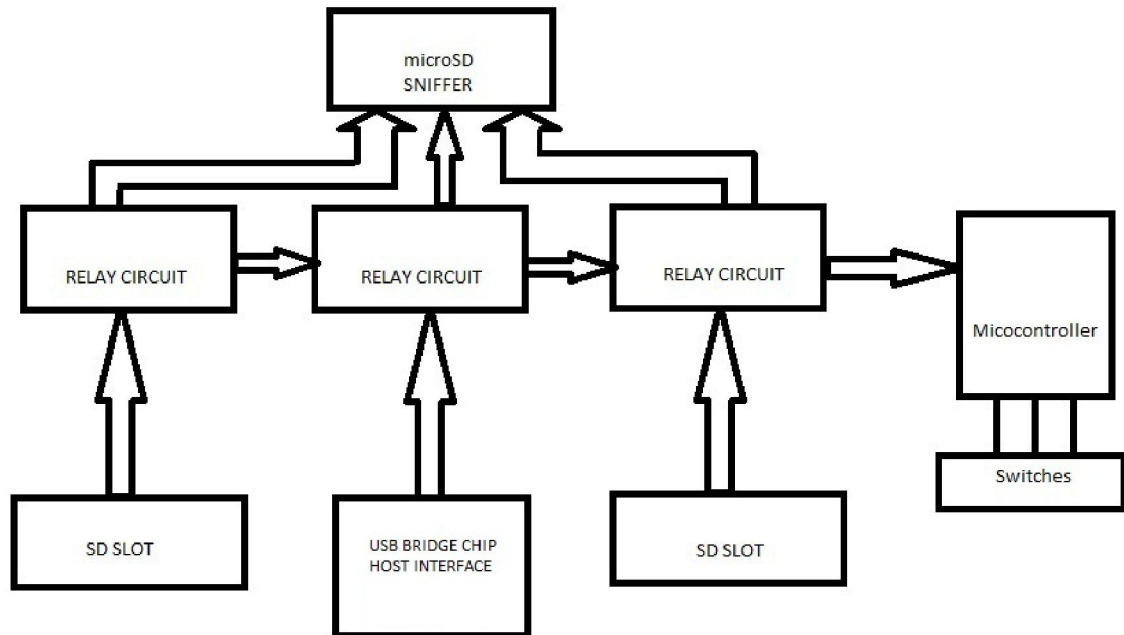
The design paradigm shows the relationship between the components involved in the conceptualization of the file management of a USB flash drive and memory card via the micro SD card slot of a mobile phone. There are three major parts of the conceptualized design: the input, which comprises the memory cards and USB flash drive to be inserted individually into the main device slots; the circuitry of the main device; and lastly, the output, which comprises the device output in micro SD form to be inserted in the mobile phone

for the corresponding application of browsing, transferring and management of files inside the flash memory.

First is the connection of the flash memory to the device. The user inserts the necessary USB flash drive or memory cards to the memory slot of the device. Once the flash memory is plugged in, the user will activate the circuit that corresponds to the slot through the button attached to the device and it will be connected to the micro SD slot of the mobile phone. In case multiple memory devices are connected in the circuit, a program switch inside the main device will be responsible so that the user can view only the specified flash memory that is selected through buttons. An indicator will be visible for the user to know which flash memory is activated and read by the mobile phone. The actual file management is done by the user. The user is able to browse and manage the file/s inside the flash memory inserted.

The functionality of the device depends on its input and is tested for its output. The device should be able to connect to the micro SD card slot of the mobile phone and be recognized as the phone's external memory. Furthermore, the files inside the flash memory can be seen and the phone is ready to initiate file management. Successful file transfer from one memory to another, in this case, flash memory to phone memory or vice versa, is one of the main objectives of this design. The successful file transfer happens when a file has been copied completely, without any error. Therefore, the integrity of the file being transferred must be looked forward to.

## Block Diagram



**Figure 3.2 - Block Diagram of the Design**

The researchers established a block diagram to guide the whole process of designing. The block diagram serves as the backbone of the design. The figure above illustrates the block diagram used by the group.

Three memory slots, particularly two SD/MMC slots and one Universal Serial Bus (USB) Bridge Chip Host Interface, are provided in the circuit for data input. Each of them is then connected to its corresponding relay circuit which will cut and short the lines in the data and power of the memory slots. Each of the slots has eight lines connected to the relay circuit. The relay circuits are then connected to the microcontroller. The microcontroller will be the one to digitally switch the relay circuits in response to the input signal given by the user. The switches will

serve as the main input device from which the user will select the corresponding circuit to be activated. The three relay circuits are then connected independently to the micro SD sniffer, which serves as the output line of the device to be connected to the micro SD slot of the mobile phone. When one of the switches has been activated, it will proceed to the micro SD sniffer and will be accessed through the mobile phone.

## Schematic Diagram



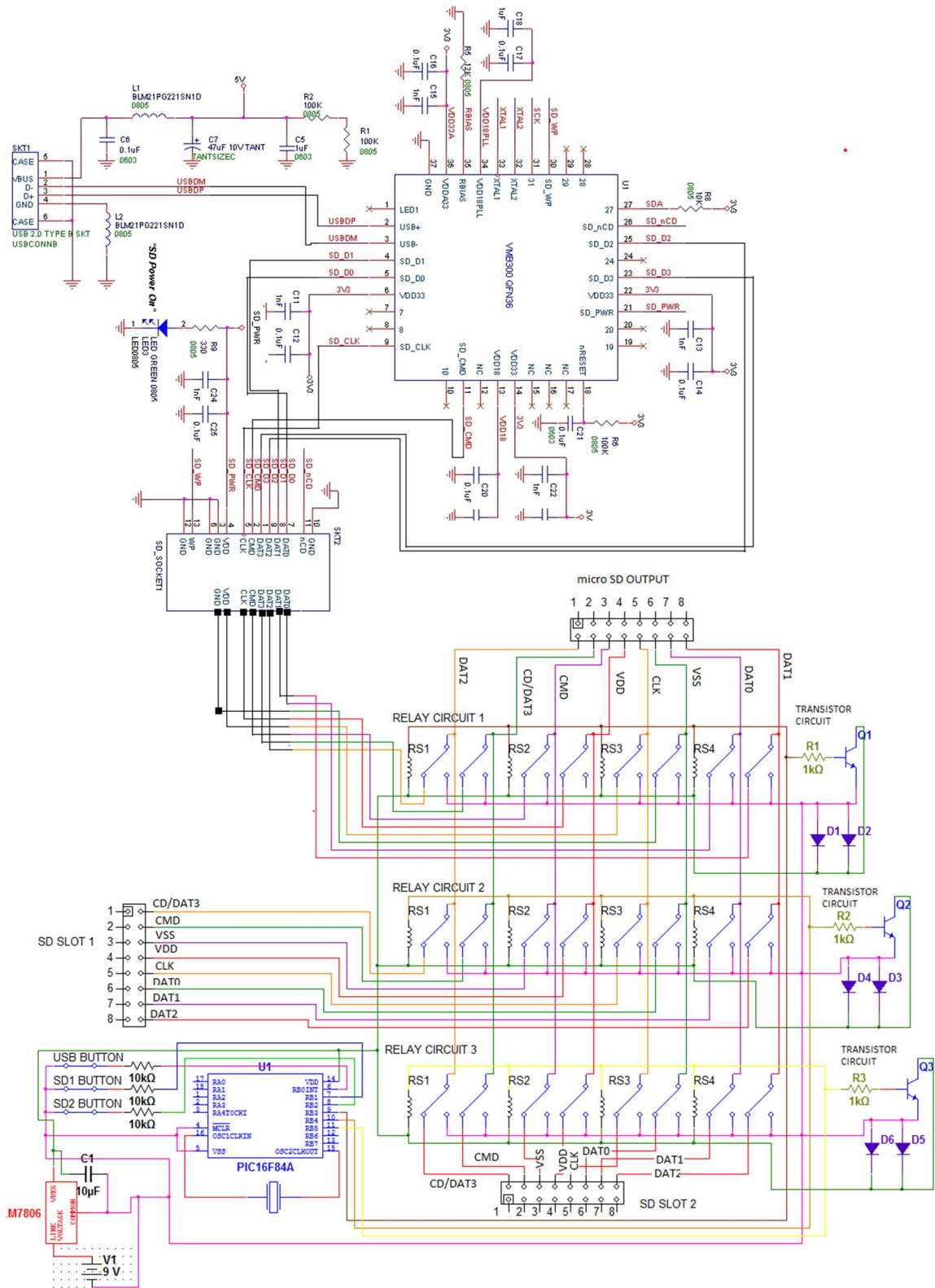


Figure 3.3 Schematic Diagram of the Design

Figure 3.3 shows the schematic/circuit diagram of the whole system. From a 9V DC battery, it will be regulated to 5V to comply with the microcontroller's operating state. A 10 micro-Farad capacitor is connected to the output voltage of the regulator and the ground to filter out the noise coming from the regulator. Each of the switches is then connected to a 10k pull down resistor. The switches are connected to the microcontroller pins for input port assignment. The output line of the each relay circuit is then connected to the output ports of the microcontroller and also to the transistor circuit. The transistor circuit is composed of an NPN Bipolar Junction Transistor (BJT), a 10 kilo-ohms base resistor, and two germanium diodes. The two pins of each relay ICs are connected to every two input lines of the micro SD sniffer. They are connected accordingly to their corresponding pin assignments in order to respond to the operating state of the micro SD output. The output lines of the USB to SDIO bridge chip interface are connected to the corresponding input lines of the relay circuit for it to be processed before going directly to the micro SD output lines. The formula used in getting the value of the capacitor is shown below:

$$C = \frac{5 \times I}{V \times f} = \frac{5 \times 6.2 \times 10^{-4}}{5.8 \times 60} = 10.34 \mu\text{F}$$

Where: C= computed capacitance in farads (F),

I = measured output current from the supply in amps (A),

V = measured supply voltage in volts (V),

f = frequency of the AC supply in hertz (Hz)

When interfacing the switches to the microcontroller, the formula below is used to get the value of the resistor:

$$R = \frac{V}{I} = \frac{5.8}{600 \times 10^{-6}} = 9.67 \times 10^3$$

Where: R = resistance in ohms

V = measured supply voltage in volts (V)

I = measured current flow through resistor in amperes (A)

The base resistor of each transistor circuit is obtained using the formula shown below:

$$Rb = \frac{Vb - Vbe}{Ib} = \frac{5.8 - 0.7}{5 \times 10^{-3}} = 1020$$

Where: Rb = computed base resistor in ohms

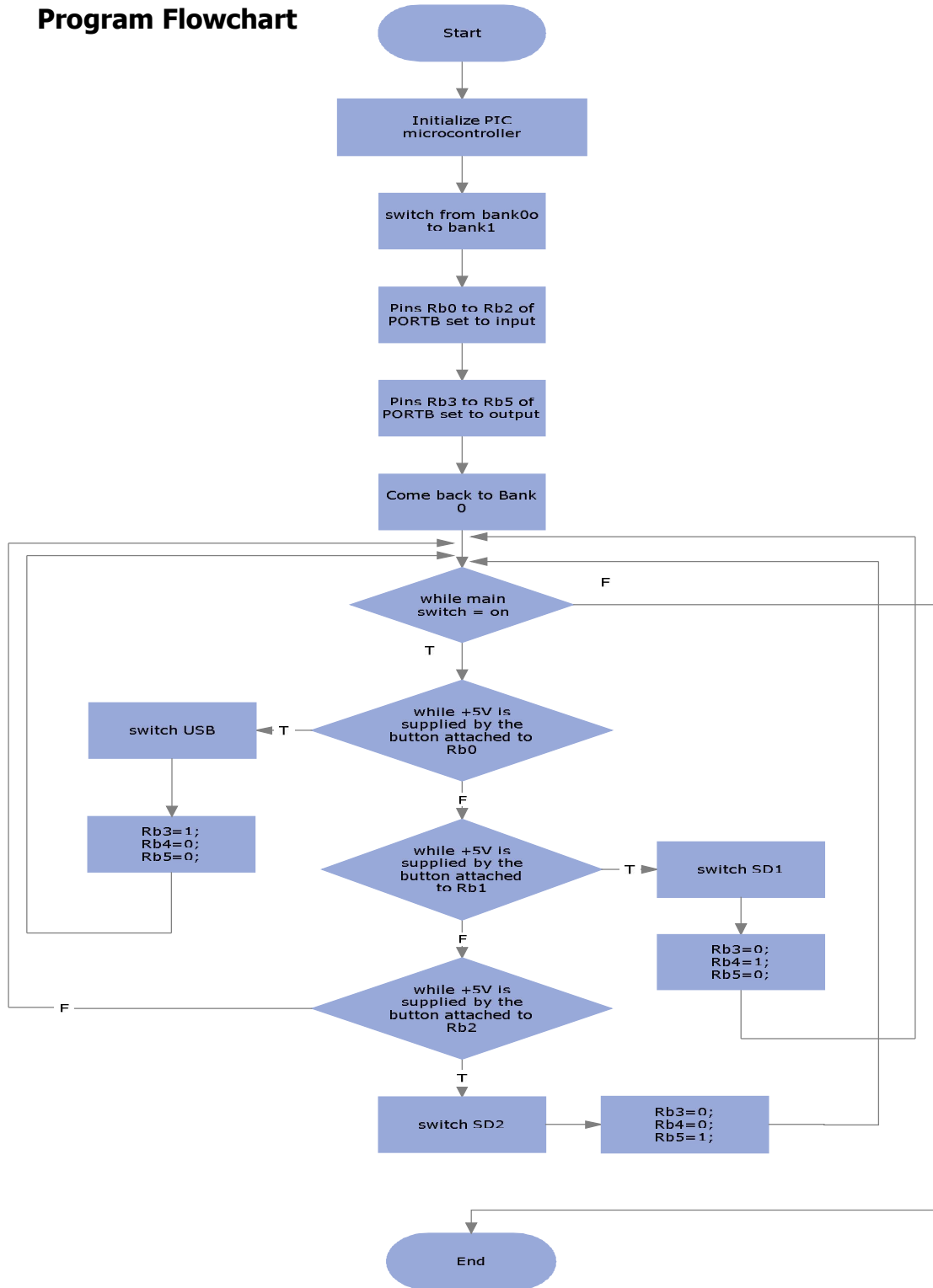
Vb = the base voltage in volts (V)

Vbe = the difference from the base voltage to the base emitter

Ib = measured base current in amperes (A)

# SOFTWARE DEVELOPMENT

## Program Flowchart



### **Figure 3.4 – Program Flowchart**

Figure 3.4 shows how the PIC microcontroller behaves as soon as it is enabled. The first process is the initialization of the PIC microcontroller; this is where it initializes Port B. The initialization process comes in four stages; first is the bank switching from bank 1 to bank 0. Bank 1 is used to control the operation of the PIC, and bank 0 is used to manipulate the data. Initially, the PIC is in bank 0. It is then switched to bank 1 to assign the input and output ports needed. Second, the researchers assign pins 0, 1 and 2 of Port B to be the input data. The researchers then assign all pins 3, 4 and 5 of Port B to be the output data. Lastly, the bank returns to bank 0 for manipulation of data.

After the initialization process, the program for data selection is next. Since there are three memory slots connected in the circuit, it is then programmed for data activation/deactivation. While the circuit is in its operating state, the program will wait for a +5V input from the button associated with pin 0 of port B. While a high signal is received, the program will proceed to the function that will activate SD card slot 1. Else, the function call is skipped and will proceed to the next statement. The same procedure for data selection is done for pins 1 and 2 of port B. When a high signal is received from either of the two ports, then the statement will proceed to the function call that will activate the USB port and SD card slot 2, respectively. If it does not satisfy the condition, it will return to the

selection process. Also, the function call will return to the selection process and will continue to accept and perform the specified operation.

## **PROTOTYPE DEVELOPMENT**

The first step to do is to provide the needed materials and equipment to be used in building the prototype. The researchers discussed both software and hardware specifications separately in the design procedure. The materials and components that were utilized are as follows:

### **Hardware Components**

#### **PIC Microcontroller**

The microcontroller serves as the main processor of the design which has the capability to store the program that must be implemented in the design. The microcontroller used is PIC16F84A, 18-pin enhanced FLASH/EEPROM 8-bit microcontroller. The PIC16F84A has the capability to accept data coming from a serial port directly.

#### **Crystal Oscillator 4MHz**

The microcontroller will need a Crystal Oscillator 4MHz as shown in Figure 3.4. This oscillator will act as a clock feed into the PIC microcontroller; the frequency of the oscillator will affect the instruction per second process of the PIC microcontroller.

#### **Push Button Switches**

Three push button switches are used and will serve as the main input device from which the user will select the corresponding circuit to be activated. The

blue and yellow switches correspond to the activation of the two SD memory slots while the white switch corresponds to the activation of the USB Flash Drive.

### **10K 1/4W Pull-Down Resistor**

The microcontroller also needs to have a pull down resistor, typically a 10k resistor. It is used to limit the current that can flow between Vcc and ground. Since it is a pull-down resistor, one of its legs is connected to the ground.

### **5V Relay Switch**

A relay is used to isolate one electrical circuit from another. The main device consists of 12 relay switches to power up and to electronically switch the corresponding input lines of a memory slot being activated. One relay circuit comprises of four relays in each memory slot, two lines from which are supplied by one relay switch.

### **NPN type Bipolar Junction Transistor (BJT)**

The relay coil's current requirement is usually about 100mA for small relays and the microcontroller cannot supply this much of current to relay by itself. A transistor is used to handle this current requirement. At the same time, it acts as a voltage amplifier to drive the relays in their operating state. One transistor is used for each relay circuit.

### **1/2 Watt 47 Ohms Resistor**

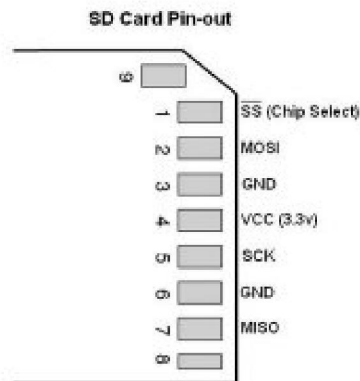
Bipolar transistor amplifiers must be properly biased to operate correctly. Biasing networks consisting of resistors are commonly employed. A series base resistor of 47 ohms is used to set the base current, so that the transistor is driven into

saturation (fully turned on) when the relay is to be energized. That way, the transistor will have minimal voltage drop, and hence dissipate very little power.

### **Germanium Diode**

A power diode is connected across the relay coil, to protect the transistor from damage due to the back-EMF pulse generated in the relay coils inductance when it turns off. Ideally, each of the relays should have its own diode. However, diodes may also consume an amount of current in the circuit. That's why in this particular circuit, having two diodes per relay circuit is enough to protect the transistors from damage.

### **SD Memory Card Slot & Pin-out**



**Figure 3.5 – SD Memory Card Slot & Pin-out**

Two Secure Digital (SD) memory card slots are mounted in the main device. It is where SD memory cards will be inserted to begin with the operation of the device and to enable the file management of the SD memory cards through the mobile phone. The SD card slot has nine interface pins in contact with the SD



memory card inserted which are connected to their corresponding data lines to be processed by the main device circuit.

### **USB to SD IO host controller bridge chip interface**

This chip is used to bridge and process the data lines USB Flash Drive into its corresponding SD input/output lines. It consists of different components and integrated circuits such as the USB chip embedded host controller to access generic USB mass-storage devices; Integrated PCMCIA / CF device designed to bridge chips using serial or parallel-bit streams; USB transceiver to handle connection detection functionality as well as providing the analog electrical signaling required to meet the specification; USB to 16-bit PC Card Interface Device to enable connection of Compact Flash devices via the USB bus; and the Field-programmable Gate Array (FPGA) to configure and translate the USB flash drive into a micro SD-like form.

### **10uF and 0.1uF Capacitors**

A value of 10uF capacitor is used to filter the ripple coming from the regulator so that a smooth form of supply will be delivered to the microcontroller. Since microcontroller circuits are designed as direct current (DC) circuits, variations in the voltages of these circuits can cause problems. If the voltages swing too much, the circuit may operate incorrectly. For most practical purposes, a voltage that fluctuates is considered an AC component. The function of the 0.1uF bypass capacitor is to dampen or isolate the AC, or the electric noise in the circuit.

### **9V Battery Supply and Standard Battery Connector**

The device is operated using a 9V battery supply with its connector to make the device portable.

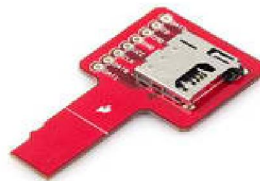
### **6V Voltage Regulator**

The 9V supply of the device will be regulated into 6V to maintain the voltage range of the microcontroller's operating state, which is 5V-6V, and prevent it from being damaged by a power surge.

### **Stranded wires**

Stranded wires are used in this design to connect the data lines from the SD memory card slots and the USB bridge chip host interface transfer to the output data lines which corresponds to the micro SD sniffer. Stranded wires are used over solid wires because they are flexible and the pins of the data lines are thin and small enough for that particular wire to fit in.

### **Micro SD Sniffer**



**Figure 3.6 – micro SD Sniffer**

The output of the main device is called the micro SD sniffer. It is a dummy micro SD card having no memory chip inside and is intended for accessing the output data lines coming from the SD memory cards and USB flash drive inserted in the main device. When the selected flash memory has been processed by the

device, the memory of the sniffer will be that of the selected flash memory device and it will be inserted to the mobile phone for file management.

### **SOFTWARE COMPONENTS**

The program for the device is made using C programming language and MikroC as the program compiler. Pickit2 is utilized to program and debug the microcontroller.

## **Chapter 4**

### **TESTING, PRESENTATION, AND INTERPRETATION OF DATA**

This chapter discusses the testing part of the design; results to those tests can be found in this part so that it can be determined whether the design is effective and accurate or not.

#### **Single File Copy Speed Test**

The purpose of this is to test if the device is capable of responding efficiently with the file management features of the mobile phone, specifically the COPY function of the mobile device. Furthermore, the accuracy of a file when being transferred from all of the three flash memory devices to the corresponding memory of the phone is being tested. As indicated in the scope of this study, the mobile phone model to be used for this purpose is the Nokia C3. The sizes of the SD Memory Card, mini SD Memory Card and USB Flash Drive are tested based on the memory size supported by most mobile phone switch is 4 GB of memory. Another purpose of this test is to determine the causes of errors and data loss in transferring a file, if there are any. After this test, the functionality of the device and how successful a single file is transferred without data loss can be determined. The transfer speed of each file is also measured and observed after this test.

These are the procedures to be followed in conducting the test:

The COPY function of the mobile phone will be used to duplicate a file from the given SD memory cards and USB flash drive or vice versa.

For each memory type, the maximum memory capacities of the three flash memories in accordance with the design's delimitation will be used. For both SD memory card and mini SD memory card, 4 GB memory size will be used; and for USB flash drive, 8 GB memory size will also be used.

The file sizes that will be used for testing are 1 MB and 10 MB whose file types/extensions to be used are .jpg (picture file) and .mp4 (video file) respectively. Note that these files are supported by the test phone. Separate tables will be provided for each file size.

Thirty trials will be made to test and observe the consistency of the file transfer speed.

To make sure that the data transferred is correct and is the same file from the source, a prompt should be displayed on the mobile phone indicating that the file has been successfully transmitted. Moreover, the file that has been transferred should be similar to the source file being copied from in terms of their size in bytes. If the mobile phone supports the file format of the file being transferred (e.g., music, documents, pictures), then it should be opened successfully in the mobile phone. On the other hand, a corrupted icon or image is displayed by the mobile phone if it is not successful at all.

The results to be displayed in the tables are the transfer speed of the file in seconds out of 30 trials made. A timer is used to measure the transfer speed of the file copied from the flash memory to the phone memory in seconds. The

average transfer speed computed from the results of the 30 trials is displayed at another table.

The REMARKS column is intended for the instance of having successful or unsuccessful file transfers during the actual process, and if the files are successfully copied only from the external memory to the mobile phone, the other way around, or both.

**Tables of data collected:**

**Table 4.1. File Copy Speed Test Results using Phone Model Nokia C3 at file size of 1 MB**

<b>TRIAL</b>	<b>Transfer Speed of File Copied from SD Memory (sec)</b>	<b>Transfer Speed of File Copied from Mini SD Memory (sec)</b>	<b>Transfer Speed of File Copied from USB Flash Drive (sec)</b>	<b>REMARKS</b>
1	3.2 s	4.3 s	5.2 s	File copied to and from both devices
2	3.2 s	4.3 s	5.3 s	File copied to and from both devices
3	3.1 s	4.3 s	5.2 s	File copied to and from both devices
4	3.2 s	4.3 s	5.4 s	File copied to and from both devices
5	3.2 s	4.5 s	5.4 s	File copied to and from both devices
6	3.3 s	4.5 s	5.4 s	File copied to and from both devices
7	3.2 s	4.5 s	5.4 s	File copied to and from both devices
8	3.2 s	4.5 s	5.4 s	File copied to and from both devices
9	3.1 s	4.5 s	5.4 s	File copied to and from both devices

10	3.2 s	4.5 s	5.4 s	File copied to and from both devices
11	3.3 s	4.5 s	5.4 s	File copied to and from both devices
12	3.3 s	4.5 s	5.4 s	File copied to and from both devices
13	3.3 s	4.3 s	5.4 s	File copied to and from both devices
14	3.3 s	4.3 s	5.4 s	File copied to and from both devices
15	3.3 s	4.4 s	5.4 s	File copied to and from both devices
16	3.2 s	4.5 s	5.4 s	File copied to and from both devices
17	3.3 s	4.5 s	5.4 s	File copied to and from both devices
18	3.2 s	4.3 s	5.4 s	File copied to and from both devices
19	3.2 s	4.4 s	5.4 s	File copied to and from both devices
20	3.2 s	4.5 s	5.4 s	File copied to and from both devices
21	3.3 s	4.5 s	5.3 s	File copied to and from both devices
22	3.3 s	4.4 s	5.4 s	File copied to and from both devices
23	3.1 s	4.4 s	5.4 s	File copied to and from both devices
24	3.3 s	4.5 s	5.4 s	File copied to and from both devices
25	3.2 s	4.4 s	5.3 s	File copied to and from both devices
26	3.3 s	4.4 s	5.4 s	File copied to and from both devices
27	3.2 s	4.4 s	5.3 s	File copied to and from both devices
28	3.3 s	4.4 s	5.4 s	File copied to and from both devices
20	3.2 s	4.5 s	5.4 s	File copied to and from both devices
30	3.2 s	4.5 s	5.4 s	File copied to and from both devices

**Table 4.2. File Copy Speed Test Results using Phone Model Nokia C3 at  
file size of 10 MB**

<b>TRIAL</b>	<b>Transfer Speed of File Copied from SD Memory (sec)</b>	<b>Transfer Speed of File Copied from Mini SD Memory (sec)</b>	<b>Transfer Speed of File Copied from USB Flash Drive (sec)</b>	<b>REMARKS</b>
1	13.2 s	13.6	16.5 s	File copied to and from both devices
2	13.2 s	13.8	16.6 s	File copied to and from both devices
3	13.2 s	13.8	16.5 s	File copied to and from both devices
4	13.2 s	13.6	16.5 s	File copied to and from both devices
5	13.2 s	13.6	16.5 s	File copied to and from both devices
6	13.2 s	13.6	16.5 s	File copied to and from both devices
7	13.2 s	13.6	16.5 s	File copied to and from both devices
8	13.2 s	13.8	16.6 s	File copied to and from both devices
9	13.2 s	13.8	16.5 s	File copied to and from both devices
10	13.1 s	13.9	16.5 s	File copied to and from both devices
11	13.2 s	13.8	16.6 s	File copied to and from both devices
12	13.2 s	13.5	16.5 s	File copied to and from both devices
13	13.2 s	13.6	16.5 s	File copied to and from both devices
14	13.2 s	13.5	16.5 s	File copied to and from both devices



15	13.1 s	13.8	16.6 s	File copied to and from both devices
16	13.2 s	13.4	16.5 s	File copied to and from both devices
17	13.2 s	13.5	16.6 s	File copied to and from both devices
18	13.3 s	13.8	16.5 s	File copied to and from both devices
19	13.2 s	13.8	16.5 s	File copied to and from both devices
20	13.1 s	13.7	16.7 s	File copied to and from both devices
21	13.2 s	13.8	16.6 s	File copied to and from both devices
22	13.2 s	13.8	16.5 s	File copied to and from both devices
23	13.2 s	13.6	16.6 s	File copied to and from both devices
24	13.3 s	13.6	16.6 s	File copied to and from both devices
25	13.2 s	13.8	16.7 s	File copied to and from both devices
26	13.2 s	13.7	16.7 s	File copied to and from both devices
27	13.2 s	13.8	16.7 s	File copied to and from both devices
28	13.2 s	13.8	16.6 s	File copied to and from both devices
20	13.2 s	13.7	16.7 s	File copied to and from both devices
30	13.3 s	13.7	16.5 s	File copied to and from both devices

The average file transfer speed for each flash memory device is computed using the formula:

$$\frac{\text{RESULT IN TRIAL 1} + \text{TRIAL 2} + \text{TRIAL 3} \dots\dots\dots + \text{TRIAL 30}}{30}$$

**Table 4.3 Average Transfer Speed at 1 MB and 10 MB**

<b>File Size</b>	<b>Average Transfer Speed in SD Memory Card</b>	<b>Average Transfer Speed In mini SD Memory Card</b>	<b>Average Transfer Speed in USB Flash Drive</b>
<b>1 MB</b>	3.2 s	4.4 s	5.4 s
<b>10 MB</b>	13.2 s	13.7 s	16.6 s

The formula below is used to get the standard deviation for each proportion. This will determine how much variation or "dispersion" there is from the average transfer speed of each flash memory with respect to our device.

$$s^2 = \frac{\sum (X - M)^2}{N}$$

Where  $s^2$  is the variance, X is the speed value per n trial, and N is the number of trials which is 30. The standard deviation S is simply the square root of variance.

Table 4.4 summarizes the variance and standard deviation of the results in Tables 4.1 and 4.2.

**Table 4.4 Variance and Standard Deviation at 1 MB and 10 MB**

	<b>Transfer Speed in SD Memory Card</b>	<b>Transfer Speed In mini SD Memory Card</b>	<b>Transfer Speed in USB Flash Drive</b>
<b>Variance</b>	0.004241379	0.006850575	0.003402299
<b>Standard Deviation</b>	0.065125873	0.082768199	0.058329228

Based on the results gathered in Tables 4.1 and 4.2, the file copy test is successful for the mobile phone model Nokia C3 to and from SD memory cards and USB flash drives. It can be implied that the device is capable of copying files

of different types and sizes such as 1 MB and 10 MB. The transfer speed is also measured and was observed to be close to each other.

With regards to the transfer speed of the files copied from the USB flash drive or SD memory card to the mobile phone, it was observed that the average transfer rate of the flash memories with respect to the prototype. The actual transfer speed of the Mini SD Card was lower than the SD Memory card because the Mini SD card is connected to another adaptor which implies an additional data rate going to the destination. Nevertheless, since the standard deviation was smaller than half of the average for all the three flash memories, the results are said to be consistent which makes device functional and reliable with regards to the file transfer speed value.

The transfer speed for the USB flash drive to the mobile phone is lower than the transfer speed of SD memory card and Mini SD memory card. This is due to the technology of the USB flash drive compared to memory cards which has larger power dissipation for data transfer.

During the testing process, other file management features of the mobile phone such as the delete and move options were tested. Therefore it can also be implied that the file management is successfully operated with the device.

### **Impact Analysis**

The design solution can help in the country's economic growth when the device is given a chance to develop further and to become a product which is manufactured, thus aiding in employing people. The device is also environment-

friendly because no harmful components are used in the hardware implementation process, which in turn yields to good health and a safe environment. Although the device has a little problem with its manufacturing capability because some of the major components are not yet available in the country, its sustainability is not questionable and it can be offered in the future where technology is much advanced. The device can have a big impact on social welfare as it is intended not just for a single person but to all who need it.

## Chapter 5

### CONCLUSION AND RECOMMENDATION

#### Conclusion

Based on the objectives of the design and the results of test performed the following observations and conclusions can be made.

The general conclusion is that file integrity is preserved upon copying/moving between the mobile phone and the device, which hosts the Secure Digital (SD) card, miniSD card and the USB flash disk.

The following are the specific conclusions:

Developing a design that can transfer data on a variety of media affords a lot of convenience and flexibility.

Specific lines of circuit are activated for each switch selected, thereby saving power.

The mobile phone provides the power for the USB flash drive and memory card slots while the relays are for the selection of lines in the circuit to be activated.

## **Recommendations**

The following are recommended ways to improve the design:

While a PIC microcontroller was used in this design, other microcontrollers can be used as well as long as the requirements for proper operation are satisfied.

The overall power of the circuit can be reduced when using surface mount components.

Adding another memory card slot can be considered since not all memory cards can be hosted on the SD card adapter.

Other USB host adapter can be used to support large capacity USB flash drives.

When planning to use the original design, extending its memory card support can be done by reprogramming the PIC microcontroller.

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**APPENDICES**  
**APPENDIX A**  
**OPERATION'S MANUAL**

**System Requirements**

Intel Pentium IV or greater

Windows XP, Vista, or Windows 7

MPLAB, ePICKIT2

Mobile phone with Micro SD Slot

**Installation Procedure**

**1. ePICKIT2 installation**

Open the PICKit2 v2.61 installer and click "Next".

Enter the installation directory and click "Next".

Choose "I agree" and click next until the progress bar appears

Wait for it until the PICKit2 has been successfully installed.

Click "Close" when it finishes.

**2. MPLAB installation**

Open the MPLAB v8.56 setup installer and click "Next".

Choose "I accept" and click "Next".

Select the complete installation then click "Next".

Enter the installation directory and click "Next".

Click "Install" and wait until it finishes.

Close the installer when it is successfully installed.

### **III. User's Manual**

#### **How to Setup the Device for File Management of a USB Flash Drive and SD Memory Card using the Micro SD slot of a Mobile Phone:**

Insert the necessary USB flash drive and/or SD memory card in the memory slot/s of the device. Be sure that the flash memories to be used conform to the system's requirements.

Once inserted, the user may now select through push buttons the flash memory to be read and accessed by the mobile phone with the micro SD slot. The yellow and blue switches correspond to the activation of SD memory 1 and 2 respectively, while the white switch corresponds to the activation of the USB flash drive.

If multiple flash memories are inserted, the user may select the order of which flash memory is to be read first, next and/or last. Multiple switching is allowed in this case.

Once the selected flash memory is activated, insert the micro SD output sniffer to the memory slot of the mobile phone.

Go the File Manager section of the mobile phone. If the device is successfully inserted, the file manager can read and identify the name and free size in bytes of the corresponding flash memory, aside from its phone memory. For other phone models, the flash memory should be visible to the Gallery section of the mobile phone.

Open the contents of the flash memory. The user can now browse and manage the files inside by selecting the specific file and then the Options menu that is subsequent to the chosen file.

When copying or moving a file from the flash memory to the phone memory or vice versa, an indication is seen if the file was successfully moved or copied.

When the user is done browsing and accessing the flash memory in the mobile phone, simply unplug the micro SD sniffer output cable from the phone and turn off the switch button which corresponds to the flash memory that was read earlier.

In case the user configured another flash memory to be read by the mobile phone, just select the button that corresponds to that flash memory and repeat the above procedures 4 to 8.

#### **IV. Troubleshooting Guides and Procedures**

If the device is not responding or operating, check first the battery supply if it is still operating at a minimum voltage of 5-6 V. If not, change the battery pack into 9 V.

If the switch indicators are the problem, the LED must just be busted. Replace it with a new one.

Check the wirings and cables inside and outside the device container if they are still connected with each other.

If the device output is now connected to the micro SD memory slot of the mobile phone and the flash memory being activated is not visible or is corrupted in the

File Manager or Gallery section of the phone, reinsert the micro SD sniffer onto the memory slot and try again.

If the flash memory to be read is still not visible or is corrupted, reboot first the device, reinsert the flash memory onto the memory slot of the device, reinsert the micro SD sniffer and then try again.

If the file transfer between the flash memory and phone memory is not successful, reinsert the micro SD sniffer and try again. The pin/s of the micro SD output may have just not been properly connected to the memory slot of the mobile phone.

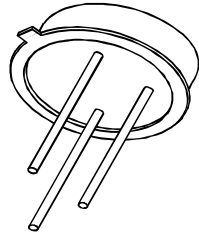
The mobile phone may not be able to read immediately another flash memory immediately after the preceding flash memory. The user will have to reinsert the micro SD output sniffer on to the memory slot to refresh the file manager and to be able to read the current flash memory that is activated.

## **V. Error Definitions**

The light indicators are off when the button is pressed – the power supply is off or insufficient.

The file management is not successful – the micro SD sniffer is not properly connected to the mobile phone slot.

**APPENDIX B**  
**SET OF DATA SHEETS**



**2N2222; 2N2222A**  
**NPN switching transistors**

Product specification  
Supersedes data of September 1994  
File under Discrete Semiconductors, SC04

1997 May 29

**Philips**  
**Semiconductors**

## NPN switching transistors

## 2N2222; 2N2222A

### FEATURES

High current (max. 800 mA)

Low voltage (max. 40 V).

### APPLICATIONS

Linear amplification and switching.

### DESCRIPTION

PNP complement: 2N2907A.

### PINNING

PIN	DESCRIPTION
1	emitter
2	base
3	collector, connected to case

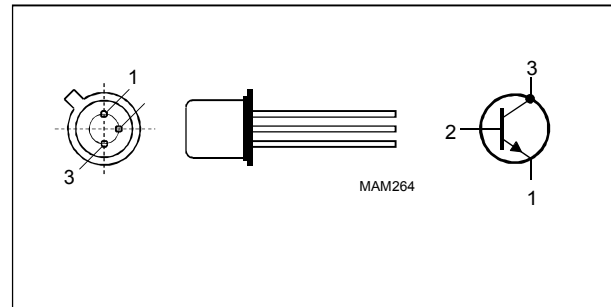


Fig. 1 Simplified outline (TO-18) and symbol.

### QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
$V_{CBO}$	collector-base voltage 2N2222 2N2222A	open emitter		60 75	V V
$V_{CEO}$	collector-emitter voltage 2N2222 2N2222A	open base		30 40	V V
$I_C$	collector current (DC)			800	mA
$P_{tot}$	total power dissipation	$T_{amb} = 25\text{ }^{\circ}\text{C}$		500	mW
$h_{FE}$	DC current gain	$I_C = 10\text{ mA}; V_{CE} = 10\text{ V}$	75		
$f_T$	transition frequency 2N2222 2N2222A	$I_C = 20\text{ mA}; V_{CE} = 20\text{ V}; f = 100\text{ MHz}$	250 300		MHz MHz
$t_{off}$	turn-off time	$I_{Con} = 150\text{ mA}; I_{Bon} = 15\text{ mA}; I_{Boff} = 15\text{ mA}$		250	ns

**LIMITING VALUES**

In accordance with the Absolute Maximum Rating System (IEC 134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V <sub>CBO</sub>	collector-base voltage 2N2222 2N2222A	open emitter		60	V
				75	V
V <sub>CEO</sub>	collector-emitter voltage 2N2222 2N2222A	open base		30	V
				40	V
V <sub>EBO</sub>	emitter-base voltage 2N2222 2N2222A	open collector		5	V
				6	V
I <sub>C</sub>	collector current (DC)			800	mA
I <sub>CM</sub>	peak collector current			800	mA
I <sub>BM</sub>	peak base current			200	mA
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> 25 C		500	mW
		T <sub>case</sub> 25 C		1.2	W
T <sub>stg</sub>	storage temperature		65	+150	C
T <sub>j</sub>	junction temperature			200	C
T <sub>amb</sub>	operating ambient temperature		65	+150	C

**THERMAL CHARACTERISTICS**

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
R <sub>th j-a</sub>	thermal resistance from junction to ambient	in free air	350	K/W
R <sub>th j-c</sub>	thermal resistance from junction to case		146	K/W

NPN switching transistors

2N2222; 2N2222A

**CHARACTERISTICS**

$T_j = 25\text{ }^\circ\text{C}$  unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
$I_{CBO}$	collector cut-off current 2N2222	$I_E = 0; V_{CB} = 50\text{ V}$		10	nA
		$I_E = 0; V_{CB} = 50\text{ V}; T_{amb} = 150\text{ }^\circ\text{C}$		10	A
$I_{CBO}$	collector cut-off current 2N2222A	$I_E = 0; V_{CB} = 60\text{ V}$		10	nA
		$I_E = 0; V_{CB} = 60\text{ V}; T_{amb} = 150\text{ }^\circ\text{C}$		10	A
$I_{EBO}$	emitter cut-off current	$I_C = 0; V_{EB} = 3\text{ V}$		10	nA
$h_{FE}$	DC current gain	$I_C = 0.1\text{ mA}; V_{CE} = 10\text{ V}$	35		
		$I_C = 1\text{ mA}; V_{CE} = 10\text{ V}$	50		
		$I_C = 10\text{ mA}; V_{CE} = 10\text{ V}$	75		
		$I_C = 150\text{ mA}; V_{CE} = 1\text{ V}; \text{note 1}$	50		
		$I_C = 150\text{ mA}; V_{CE} = 10\text{ V}; \text{note 1}$	100	300	
$h_{FE}$	DC current gain 2N2222A	$I_C = 10\text{ mA}; V_{CE} = 10\text{ V}; T_{amb} = 55\text{ }^\circ\text{C}$	35		
$h_{FE}$	DC current gain 2N2222 2N2222A	$I_C = 500\text{ mA}; V_{CE} = 10\text{ V}; \text{note 1}$	30		
			40		
$V_{CEsat}$	collector-emitter saturation voltage 2N2222	$I_C = 150\text{ mA}; I_B = 15\text{ mA}; \text{note 1}$		400	mV
		$I_C = 500\text{ mA}; I_B = 50\text{ mA}; \text{note 1}$		1.6	V
$V_{CEsat}$	collector-emitter saturation voltage 2N2222A	$I_C = 150\text{ mA}; I_B = 15\text{ mA}; \text{note 1}$		300	mV
		$I_C = 500\text{ mA}; I_B = 50\text{ mA}; \text{note 1}$		1	V
$V_{BEsat}$	base-emitter saturation voltage 2N2222	$I_C = 150\text{ mA}; I_B = 15\text{ mA}; \text{note 1}$		1.3	V
		$I_C = 500\text{ mA}; I_B = 50\text{ mA}; \text{note 1}$		2.6	V
$V_{BEsat}$	base-emitter saturation voltage 2N2222A	$I_C = 150\text{ mA}; I_B = 15\text{ mA}; \text{note 1}$	0.6	1.2	V
		$I_C = 500\text{ mA}; I_B = 50\text{ mA}; \text{note 1}$		2	V
$C_c$	collector capacitance	$I_E = i_e = 0; V_{CB} = 10\text{ V}; f = 1\text{ MHz}$		8	pF
$C_e$	emitter capacitance 2N2222A	$I_C = i_c = 0; V_{EB} = 500\text{ mV}; f = 1\text{ MHz}$		25	pF
$f_T$	transition frequency 2N2222 2N2222A	$I_C = 20\text{ mA}; V_{CE} = 20\text{ V}; f = 100\text{ MHz}$	250		MHz
			300		MHz
F	noise figure 2N2222A	$I_C = 200\text{ }^\circ\text{A}; V_{CE} = 5\text{ V}; R_S = 2\text{ k }^\circ; f = 1\text{ kHz}; B = 200\text{ Hz}$		4	dB



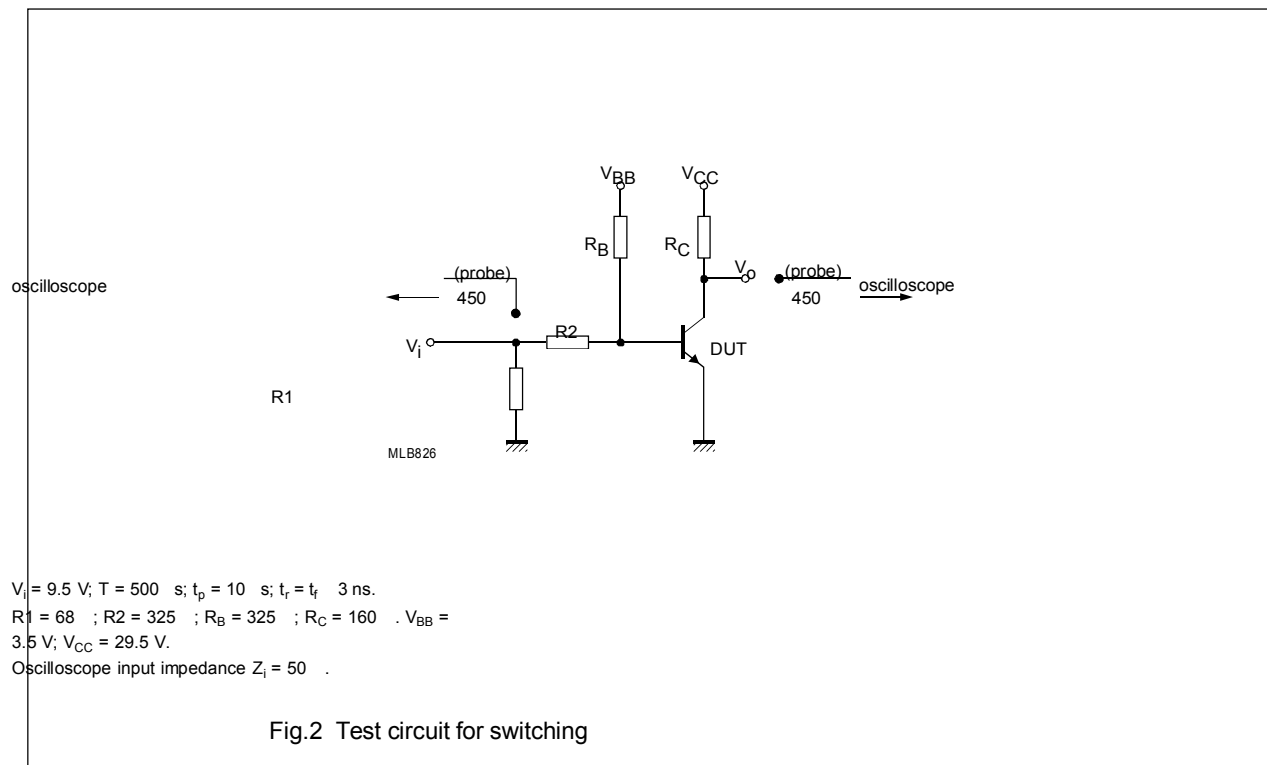
# NPN switching transistors

2N2222; 2N2222A

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
<b>Switching times (between 10% and 90% levels); see Fig.2</b>					
$t_{on}$	turn-on time	$I_{Con} = 150 \text{ mA}; I_{Bon} = 15 \text{ mA}; I_{Boff} = 15 \text{ mA}$		35	ns
$t_d$	delay time			10	ns
$t_r$	rise time			25	ns
$t_{off}$	turn-off time			250	ns
$t_s$	storage time			200	ns
$t_f$	fall time			60	ns

### Note

1. Pulse test:  $t_p = 300 \text{ } \mu\text{s}; 0.02$ .





# PIC16F84A

## 18-pin Enhanced FLASH/EEPROM 8-Bit Microcontroller

### High Performance RISC CPU Features:

- Only 35 single word instructions to learn
- All instructions single-cycle except for program branches which are two-cycle
- Operating speed: DC - 20 MHz clock input  
DC - 200 ns instruction cycle
- 1024 words of program memory
- 68 bytes of Data RAM
- 64 bytes of Data EEPROM
- 14-bit wide instruction words
- 8-bit wide data bytes
- 15 Special Function Hardware registers
- Eight-level deep hardware stack
- Direct, indirect and relative addressing modes
- Four interrupt sources:
  - External RB0/INT pin
  - TMR0 timer overflow
  - PORTB<7:4> interrupt-on-change
  - Data EEPROM write complete

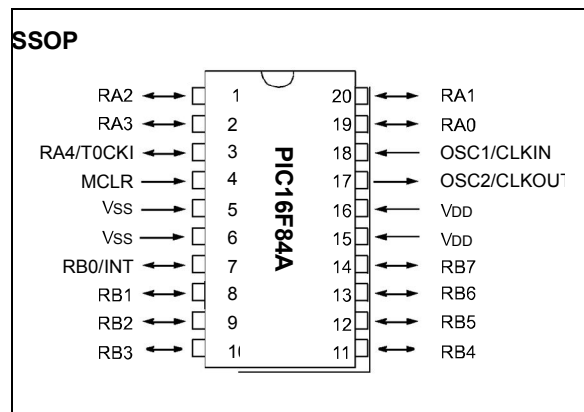
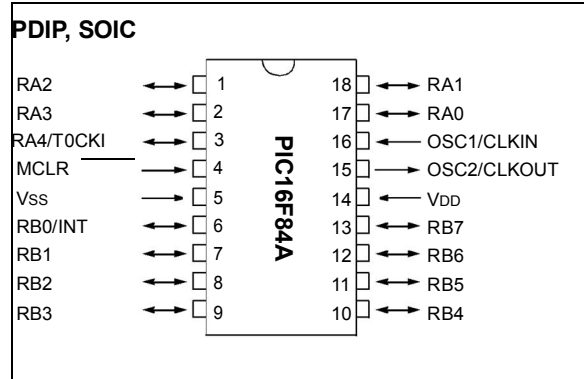
### Peripheral Features:

- 13 I/O pins with individual direction control
- High current sink/source for direct LED drive
  - 25 mA sink max. per pin
  - 25 mA source max. per pin
- TMR0: 8-bit timer/counter with 8-bit programmable prescaler

### Special Microcontroller Features:

- 10,000 erase/write cycles Enhanced FLASH Program memory typical
- 10,000,000 typical erase/write cycles EEPROM Data memory typical
- EEPROM Data Retention > 40 years
- In-Circuit Serial Programming™ (ICSP™) - via two pins
- Power-on Reset (POR), Power-up Timer (PWRT), Oscillator Start-up Timer (OST)
- Watchdog Timer (WDT) with its own On-Chip RC Oscillator for reliable operation
- Code protection
- Power saving SLEEP mode
- Selectable oscillator options

### Pin Diagrams



### CMOS Enhanced FLASH/EEPROM Technology:

- Low power, high speed technology
- Fully static design
- Wide operating voltage range:
  - Commercial: 2.0V to 5.5V
  - Industrial: 2.0V to 5.5V
- Low power consumption:
  - < 2 mA typical @ 5V, 4 MHz
  - 15 A typical @ 2V, 32 kHz
  - < 0.5 A typical standby current @ 2V

## 1.0 DEVICE OVERVIEW

This document contains device specific information for the operation of the PIC16F84A device. Additional information may be found in the PICmicro™ Mid-Range Reference Manual, (DS33023), which may be downloaded from the Microchip website. The Reference Manual should be considered a complementary document to this data sheet, and is highly recommended reading for a better understanding of the device architecture and operation of the peripheral modules.

The PIC16F84A belongs to the mid-range family of the PICmicro® microcontroller devices. A block diagram of the device is shown in Figure 1-1.

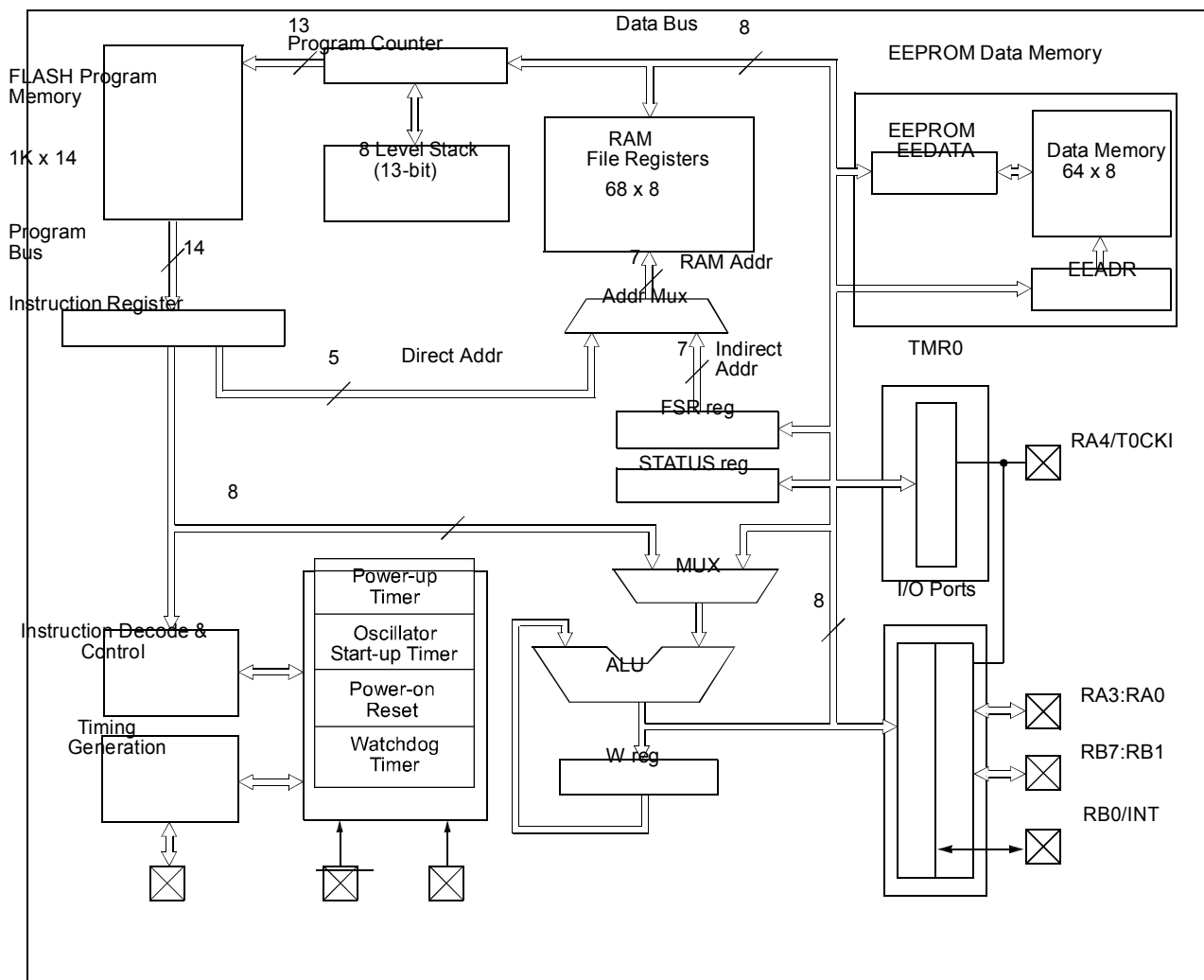
The program memory contains 1K words, which translates to 1024 instructions, since each 14-bit program memory word is the same width as each device instruction. The data memory (RAM) contains 68 bytes. Data EEPROM is 64 bytes.

There are also 13 I/O pins that are user-configured on a pin-to-pin basis. Some pins are multiplexed with other device functions. These functions include:

- External interrupt
- Change on PORTB interrupt
- Timer0 clock input

Table 1-1 details the pinout of the device with descriptions and details for each pin.

**FIGURE 1-1: PIC16F84A BLOCK DIAGRAM**



## 2.0 MEMORY ORGANIZATION

There are two memory blocks in the PIC16F84A. These are the program memory and the data memory. Each block has its own bus, so that access to each block can occur during the same oscillator cycle.

The data memory can further be broken down into the general purpose RAM and the Special Function Registers (SFRs). The operation of the SFRs that control the “core” are described here. The SFRs used to control the peripheral modules are described in the section discussing each individual peripheral module.

The data memory area also contains the data EEPROM memory. This memory is not directly mapped into the data memory, but is indirectly mapped. That is, an indirect address pointer specifies the address of the data EEPROM memory to read/write. The 64 bytes of data EEPROM memory have the address range 0h-3Fh. More details on the EEPROM memory can be found in Section 3.0.

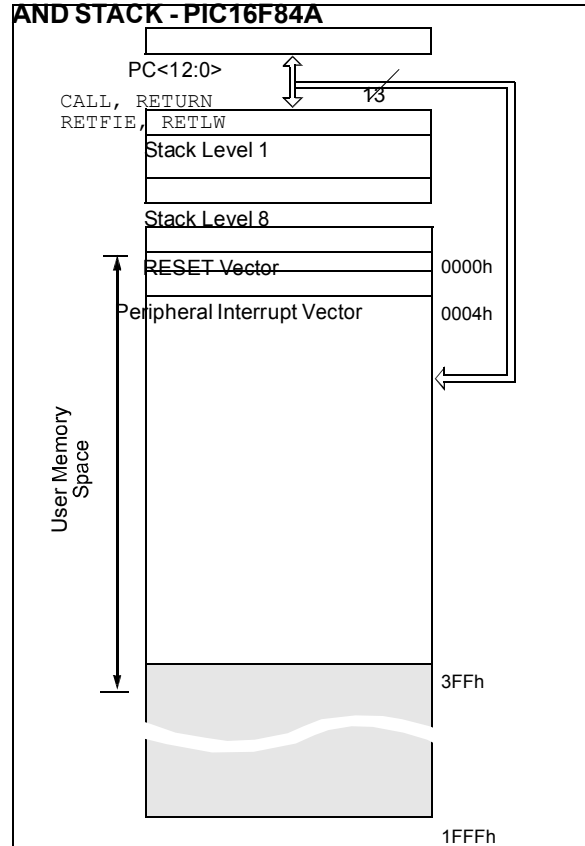
Additional information on device memory may be found in the PICmicro™ Mid-Range Reference Manual, (DS33023).

### 2.1 Program Memory Organization

The PIC16FXX has a 13-bit program counter capable of addressing an 8K x 14 program memory space. For the PIC16F84A, the first 1K x 14 (0000h-03FFh) are physically implemented (Figure 2-1). Accessing a location above the physically implemented address will cause a wraparound. For example, for locations 20h, 420h, 820h, C20h, 1020h, 1420h, 1820h, and 1C20h, the instruction will be the same.

The RESET vector is at 0000h and the interrupt vector is at 0004h.

**FIGURE 2-1: PROGRAM MEMORY MAP AND STACK - PIC16F84A**



## 2.2 Data Memory Organization

The data memory is partitioned into two areas. The first is the Special Function Registers (SFR) area, while the second is the General Purpose Registers (GPR) area. The SFRs control the operation of the device.

Portions of data memory are banked. This is for both the SFR area and the GPR area. The GPR area is banked to allow greater than 116 bytes of general purpose RAM. The banked areas of the SFR are for the registers that control the peripheral functions. Banking requires the use of control bits for bank selection. These control bits are located in the STATUS Register. Figure 2-2 shows the data memory map organization.

Instructions `MOVWF` and `MOVF` can move values from the W register to any location in the register file ("F"), and vice-versa.

The entire data memory can be accessed either directly using the absolute address of each register file or indirectly through the File Select Register (FSR) (Section 2.5). Indirect addressing uses the present value of the RP0 bit for access into the banked areas of data memory.

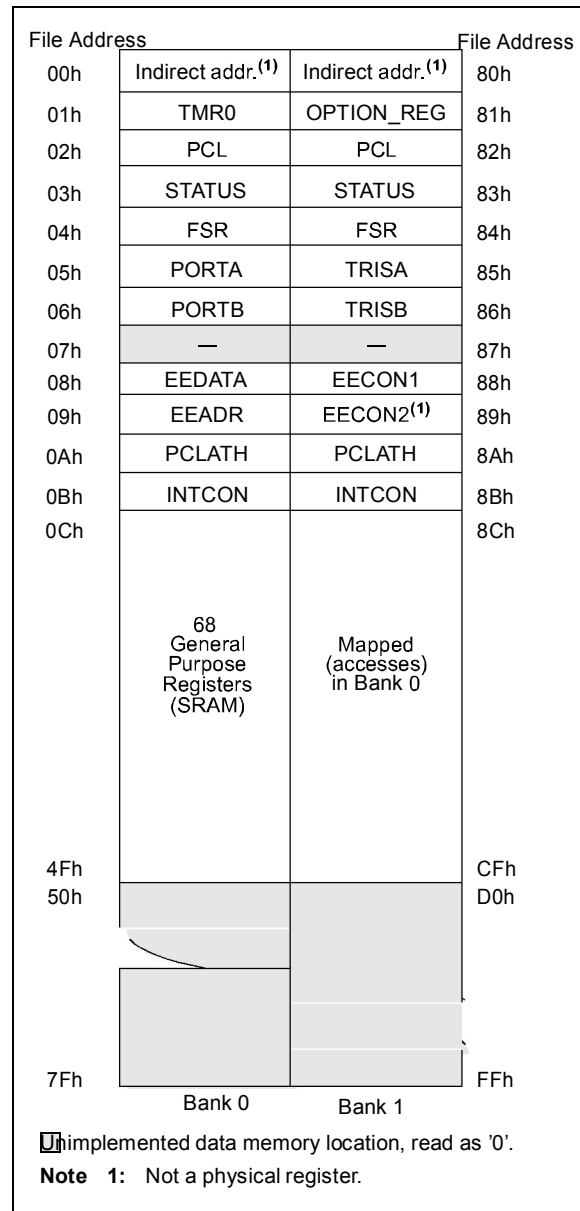
Data memory is partitioned into two banks which contain the general purpose registers and the special function registers. Bank 0 is selected by clearing the RP0 bit (STATUS<5>). Setting the RP0 bit selects Bank 1. Each Bank extends up to 7Fh (128 bytes). The first twelve locations of each Bank are reserved for the Special Function Registers. The remainder are General Purpose Registers, implemented as static RAM.

### 2.2.1 GENERAL PURPOSE REGISTER FILE

Each General Purpose Register (GPR) is 8-bits wide and is accessed either directly or indirectly through the FSR (Section 2.5).

The GPR addresses in Bank 1 are mapped to addresses in Bank 0. As an example, addressing location 0Ch or 8Ch will access the same GPR.

**FIGURE 2-2: REGISTER FILE MAP - PIC16F84A**



## 2.3 Special Function Registers

The Special Function Registers (Figure 2-2 and Table 2-1) are used by the CPU and Peripheral functions to control the device operation. These registers are static RAM.

The special function registers can be classified into two sets, core and peripheral. Those associated with the core functions are described in this section. Those related to the operation of the peripheral features are described in the section for that specific feature.

**TABLE 2-1: SPECIAL FUNCTION REGISTER FILE SUMMARY**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-on RESET	Details on page
<b>Bank 0</b>											
00h	INDF	Uses contents of FSR to address Data Memory (not a physical register)								---- ----	11
01h	TMR0	8-bit Real-Time Clock/Counter								xxxx xxxx	20
02h	PCL	Low Order 8 bits of the Program Counter (PC)								0000 0000	11
03h	STATUS <sup>(2)</sup>	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	8
04h	FSR	Indirect Data Memory Address Pointer 0								xxxx xxxx	11
05h	PORTA <sup>(4)</sup>	—	—	—	RA4/T0CKI	RA3	RA2	RA1	RA0	---x xxxx	16
06h	PORTB <sup>(5)</sup>	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0/INT	xxxx xxxx	18
07h	—	Unimplemented location, read as '0'								—	—
08h	EEDATA	EEPROM Data Register								xxxx xxxx	13,14
09h	EEADR	EEPROM Address Register								xxxx xxxx	13,14
0Ah	PCLATH	—	—	—	Write Buffer for upper 5 bits of the PC <sup>(1)</sup>					---0 0000	11
0Bh	INTCON	GIE	EEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF	0000 000x	10
<b>Bank 1</b>											
80h	INDF	Uses Contents of FSR to address Data Memory (not a physical register)								---- ----	11
81h	OPTION_REG	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	9
82h	PCL	Low order 8 bits of Program Counter (PC)								0000 0000	11
83h	STATUS <sup>(2)</sup>	IRP	RP1	RP0	TO	PD	Z	DC	C	0001 1xxx	8
84h	FSR	Indirect data memory address pointer 0								xxxx xxxx	11
85h	TRISA	—	—	—	PORTA Data Direction Register					---1 1111	16
86h	TRISB	PORTB Data Direction Register								1111 1111	18
87h	—	Unimplemented location, read as '0'								—	—
88h	EECON1	—	—	—	EEIF	WRERR	WREN	WR	RD	---0 x000	13
89h	EECON2	EEPROM Control Register 2 (not a physical register)								---- ----	14
0Ah	PCLATH	—	—	—	Write buffer for upper 5 bits of the PC <sup>(1)</sup>					---0 0000	11
0Bh	INTCON	GIE	EEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF	0000 000x	10

Legend: x = unknown, u = unchanged, - = unimplemented, read as '0', q = value depends on condition

**Note 1:** The upper byte of the program counter is not directly accessible. PCLATH is a slave register for PC<12:8>. The contents of PCLATH can be transferred to the upper byte of the program counter, but the contents of PC<12:8> are never transferred to PCLATH.

**2:** The TO and PD status bits in the STATUS register are not affected by a MCLR Reset.

**3:** Other (non power-up) RESETS include: external RESET through MCLR and the Watchdog Timer Reset.

**4:** On any device RESET, these pins are configured as inputs.

**5:** This is the value that will be in the port output latch.

## 2.3.1 STATUS REGISTER

The STATUS register contains the arithmetic status of the ALU, the RESET status and the bank select bit for data memory.

As with any register, the STATUS register can be the destination for any instruction. If the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. These bits are set or cleared according to device logic. Furthermore, the  $\overline{TO}$  and  $\overline{PD}$  bits are not writable. Therefore, the result of an instruction with the STATUS register as destination may be different than intended.

For example, `CLRF STATUS` will clear the upper three bits and set the Z bit. This leaves the STATUS register as `000u u1uu` (where u = unchanged).

Only the `BCF`, `BSF`, `SWAPF` and `MOVWF` instructions should be used to alter the STATUS register (Table 7-2), because these instructions do not affect any status bit.

**Note 1:** The IRP and RP1 bits (STATUS<7:6>) are not used by the PIC16F84A and should be programmed as cleared. Use of these bits as general purpose R/W bits is NOT recommended, since this may affect upward compatibility with future products.

**2:** The C and DC bits operate as a borrow and digit borrow out bit, respectively, in subtraction. See the `SUBLW` and `SUBWF` instructions for examples.

**3:** When the STATUS register is the destination for an instruction that affects the Z, DC or C bits, then the write to these three bits is disabled. The specified bit(s) will be updated according to device logic

### REGISTER 2-1: STATUS REGISTER (ADDRESS 03h, 83h)

R/W-0		R/W-0	R/W-0	R-1	R-1	R/W-x	R/W-x	R/W-x
	IRP	RP1	RP0	TO	PD	Z	DC	C
bit 7								bit 0

bit 7-6 **Unimplemented:** Maintain as '0'

bit 5 **RP0:** Register Bank Select bits (used for direct addressing)

01 = Bank 1 (80h - FFh)

00 = Bank 0 (00h - 7Fh)

bit 4  **$\overline{TO}$ :** Time-out bit

1 = After power-up, `CLRWDT` instruction, or `SLEEP` instruction

0 = A WDT time-out occurred

bit 3  **$\overline{PD}$ :** Power-down bit

1 = After power-up or by the `CLRWDT` instruction

0 = By execution of the `SLEEP` instruction

bit 2 **Z:** Zero bit

1 = The result of an arithmetic or logic operation is zero

0 = The result of an arithmetic or logic operation is not zero

bit 1 **DC:** Digit carry/borrow bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions) (for  $\overline{\text{borrow}}$ , the polarity is reversed)

1 = A carry-out from the 4th low order bit of the result occurred

0 = No carry-out from the 4th low order bit of the result

bit 0 **C:** Carry/borrow bit (`ADDWF`, `ADDLW`, `SUBLW`, `SUBWF` instructions) (for  $\overline{\text{borrow}}$ , the polarity is reversed)

1 = A carry-out from the Most Significant bit of the result occurred

0 = No carry-out from the Most Significant bit of the result occurred

**Note:** A subtraction is executed by adding the two's complement of the second operand. For rotate (`RRF`, `RLF`) instructions, this bit is loaded with either the high or low order bit of the source register.

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

- n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

## 2.3.3 INTCON REGISTER

The INTCON register is a readable and writable register that contains the various enable bits for all interrupt sources.

**Note:** Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the global enable bit, GIE (INTCON<7>).

### REGISTER 2-3: INTCON REGISTER (ADDRESS 0Bh, 8Bh)

	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-x
GIE	EEIE	TOIE	INTE	RBIE	TOIF	INTF	RBIF	
bit 7								bit 0

- bit 7                   **GIE:** Global Interrupt Enable bit  
1 = Enables all unmasked interrupts  
0 = Disables all interrupts
- bit 6                   **EEIE:** EE Write Complete Interrupt Enable bit  
1 = Enables the EE Write Complete interrupts  
0 = Disables the EE Write Complete interrupt
- bit 5                   **TOIE:** TMR0 Overflow Interrupt Enable bit  
1 = Enables the TMR0 interrupt  
0 = Disables the TMR0 interrupt
- bit 4                   **INTE:** RB0/INT External Interrupt Enable bit  
1 = Enables the RB0/INT external interrupt  
0 = Disables the RB0/INT external interrupt
- bit 3                   **RBIE:** RB Port Change Interrupt Enable bit  
1 = Enables the RB port change interrupt  
0 = Disables the RB port change interrupt
- bit 2                   **TOIF:** TMR0 Overflow Interrupt Flag bit  
1 = TMR0 register has overflowed (must be cleared in software)  
0 = TMR0 register did not overflow
- bit 1                   **INTF:** RB0/INT External Interrupt Flag bit  
1 = The RB0/INT external interrupt occurred (must be cleared in software)  
0 = The RB0/INT external interrupt did not occur
- bit 0                   **RBIF:** RB Port Change Interrupt Flag bit  
1 = At least one of the RB7:RB4 pins changed state (must be cleared in software)  
0 = None of the RB7:RB4 pins have changed state

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
- n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown



## 2.4 PCL and PCLATH

The program counter (PC) specifies the address of the instruction to fetch for execution. The PC is 13 bits wide. The low byte is called the PCL register. This register is readable and writable. The high byte is called the PCH register. This register contains the PC<12:8> bits and is not directly readable or writable. If the program counter (PC) is modified or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a NOP. All updates to the PCH register go through the PCLATH register.

### 2.4.1 STACK

The stack allows a combination of up to 8 program calls and interrupts to occur. The stack contains the return address from this branch in program execution.

Mid-range devices have an 8 level deep x 13-bit wide hardware stack. The stack space is not part of either program or data space and the stack pointer is not readable or writable. The PC is PUSHed onto the stack when a CALL instruction is executed or an interrupt causes a branch. The stack is POPed in the event of a RETURN, RETLW or a RETFIE instruction execution. PCLATH is not modified when the stack is PUSHed or POPed.

After the stack has been PUSHed eight times, the ninth push overwrites the value that was stored from the first push. The tenth push overwrites the second push (and so on).

CONTINUE

:

An effective 9-bit address is obtained by concatenating the 8-bit FSR register and the IRP bit (STATUS<7>), as shown in Figure 2-3. However, IRP is not used in the PIC16F84A.

## 2.5 Indirect Addressing; INDF and FSR Registers

The INDF register is not a physical register. Addressing INDF actually addresses the register whose address is contained in the FSR register (FSR is a pointer). This is indirect addressing.

### EXAMPLE 2-1: INDIRECT ADDRESSING

- Register file 05 contains the value 10h
- Register file 06 contains the value 0Ah
- Load the value 05 into the FSR register
- A read of the INDF register will return the value of 10h
- Increment the value of the FSR register by one (FSR = 06)
- A read of the INDF register now will return the value of 0Ah.

Reading INDF itself indirectly (FSR = 0) will produce 00h. Writing to the INDF register indirectly results in a no-operation (although STATUS bits may be affected).

A simple program to clear RAM locations 20h-2Fh using indirect addressing is shown in Example 2-2.

### EXAMPLE 2-2: HOW TO CLEAR RAM USING INDIRECT ADDRESSING

```

movlw 0x20 ;initialize pointer
movwf FSR ;to RAM
NEXT  clrf INDF ;clear INDF register
      incf FSR ;inc pointer
      btfss FSR,4 ;all done?
      goto NEXT ;NO, clear next
                                           ;YES, continue

```

**TABLE 6-2: CAPACITOR SELECTION FOR CRYSTAL OSCILLATOR**

Mode	Freq	OSC1/C1	OSC2/C2
LP	32 kHz	68 - 100 pF	68 - 100 pF
	200 kHz	15 - 33 pF	15 - 33 pF
XT	100 kHz	100 - 150 pF	100 - 150 pF
	2 MHz	15 - 33 pF	15 - 33 pF
	4 MHz	15 - 33 pF	15 - 33 pF
HS	4 MHz	15 - 33 pF	15 - 33 pF
	20 MHz	15 - 33 pF	15 - 33 pF

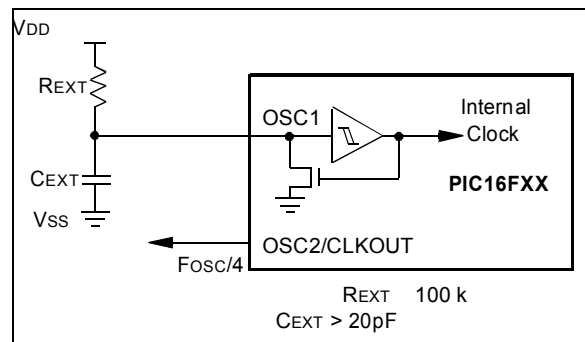
**Note:** Higher capacitance increases the stability of the oscillator, but also increases the start-up time. These values are for design guidance only. Rs may be required in HS mode, as well as XT mode, to avoid over-driving crystals with low drive level specification. Since each crystal has its own characteristics, the user should consult the crystal manufacturer for appropriate values of external components. For  $V_{DD} > 4.5V$ ,  $C1 = C2 = 30\text{ pF}$  is recommended.

Recommended values: 5 k

## 6.2.3 RC OSCILLATOR

For timing insensitive applications, the RC device option offers additional cost savings. The RC oscillator frequency is a function of the supply voltage, the resistor ( $R_{EXT}$ ) values, capacitor ( $C_{EXT}$ ) values, and the operating temperature. In addition to this, the oscillator frequency will vary from unit to unit due to normal process parameter variation. Furthermore, the difference in lead frame capacitance between package types also affects the oscillation frequency, especially for low  $C_{EXT}$  values. The user needs to take into account variation, due to tolerance of the external R and C components. Figure 6-3 shows how an R/C combination is connected to the PIC16F84A.

**FIGURE 6-3: RC OSCILLATOR MODE**



## 6.3 RESET

The PIC16F84A differentiates between various kinds of RESET:

- Power-on Reset (POR)
- $\overline{\text{MCLR}}$  during normal operation
- $\overline{\text{MCLR}}$  during SLEEP
- WDT Reset (during normal operation)
- WDT Wake-up (during SLEEP)

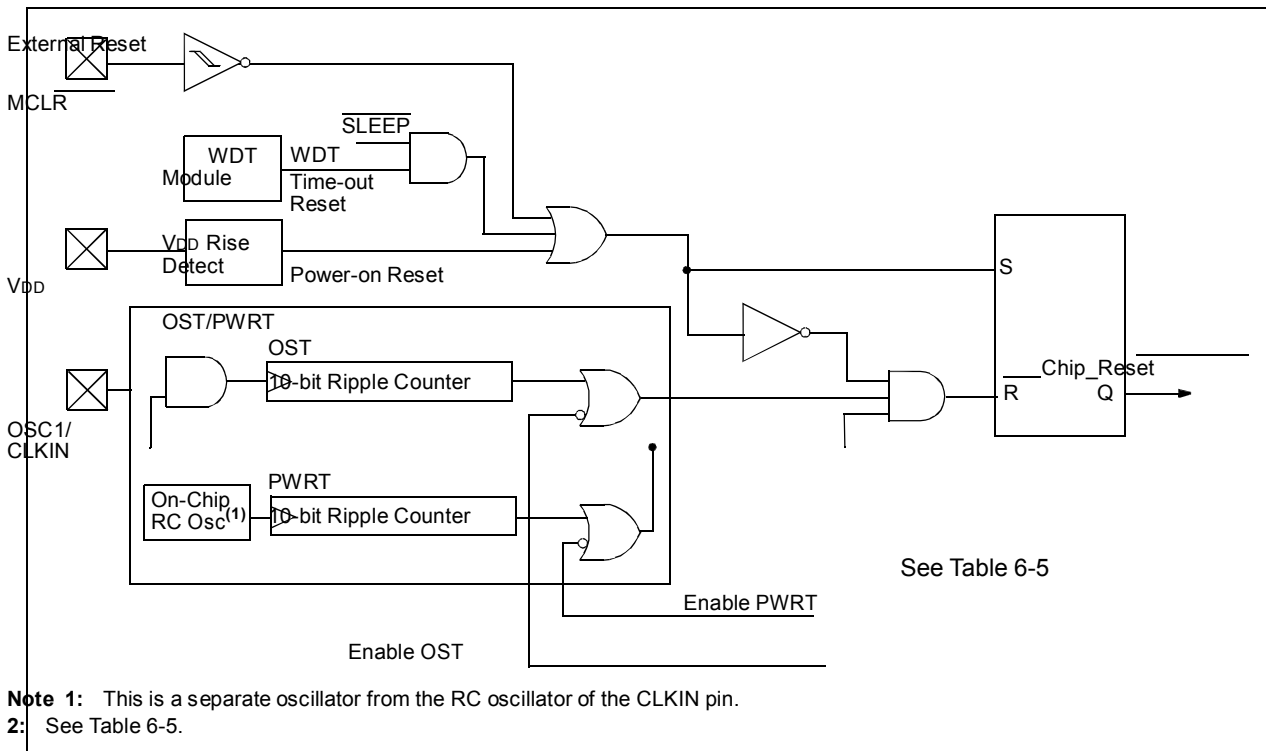
Figure 6-4 shows a simplified block diagram of the On-Chip RESET Circuit. The  $\overline{\text{MCLR}}$  Reset path has a noise filter to ignore small pulses. The electrical specifications state the pulse width requirements for the  $\overline{\text{MCLR}}$  pin.

Some registers are not affected in any RESET condition; their status is unknown on a POR and unchanged in any other RESET. Most other registers are reset to a "RESET state" on POR,  $\overline{\text{MCLR}}$  or WDT Reset during normal operation and on  $\overline{\text{MCLR}}$  during SLEEP. They are not affected by a WDT Reset during SLEEP, since this RESET is viewed as the resumption of normal operation.

Table 6-3 gives a description of RESET conditions for the program counter (PC) and the STATUS register. Table 6-4 gives a full description of RESET states for all registers.

The  $\overline{\text{TO}}$  and  $\overline{\text{PD}}$  bits are set or cleared differently in different RESET situations (Section 6.7). These bits are used in software to determine the nature of the RESET.

**FIGURE 6-4: SIMPLIFIED BLOCK DIAGRAM OF ON-CHIP RESET CIRCUIT**



**TABLE 6-3: RESET CONDITION FOR PROGRAM COUNTER AND THE STATUS REGISTER**

Condition	Program Counter	STATUS Register
Power-on Reset	000h	0001 1xxx
$\overline{\text{MCLR}}$ during normal operation	000h	000u uuuu
$\overline{\text{MCLR}}$ during SLEEP	000h	0001 0uuu
WDT Reset (during normal operation)	000h	0000 1uuu
WDT Wake-up	PC + 1	uuu0 0uuu
Interrupt wake-up from SLEEP	PC + 1 <sup>(1)</sup>	uuu1 0uuu

Legend: u = unchanged, x = unknown

**Note 1:** When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

**TABLE 6-4: RESET CONDITIONS FOR ALL REGISTERS**

Register	Address	Power-on Reset	MCLR during: – normal operation – SLEEP WDT Reset during normal operation	Wake-up from SLEEP: – through interrupt – through WDT Time-out
W	—	xxxx xxxx	uuuu uuuu	uuuu uuuu
INDF	00h	---- ----	---- ----	---- ----
TMR0	01h	xxxx xxxx	uuuu uuuu	uuuu uuuu
PCL	02h	0000 0000	0000 0000	PC + 1 <sup>(2)</sup>
STATUS	03h	0001 1xxx	000q quuu <sup>(3)</sup>	uuuq quuu <sup>(3)</sup>
FSR	04h	xxxx xxxx	uuuu uuuu	uuuu uuuu
PORTA <sup>(4)</sup>	05h	---x xxxx	---u uuuu	---u uuuu
PORTB <sup>(5)</sup>	06h	xxxx xxxx	uuuu uuuu	uuuu uuuu
EEDATA	08h	xxxx xxxx	uuuu uuuu	uuuu uuuu
EEADR	09h	xxxx xxxx	uuuu uuuu	uuuu uuuu
PCLATH	0Ah	---0 0000	---0 0000	---u uuuu
INTCON	0Bh	0000 000x	0000 000u	uuuu uuuu <sup>(1)</sup>
INDF	80h	---- ----	---- ----	---- ----
OPTION_REG	81h	1111 1111	1111 1111	uuuu uuuu
PCL	82h	0000 0000	0000 0000	PC + 1 <sup>(2)</sup>
STATUS	83h	0001 1xxx	000q quuu <sup>(3)</sup>	uuuq quuu <sup>(3)</sup>
FSR	84h	xxxx xxxx	uuuu uuuu	uuuu uuuu
TRISA	85h	---1 1111	---1 1111	---u uuuu
TRISB	86h	1111 1111	1111 1111	uuuu uuuu
EECON1	88h	---0 x000	---0 q000	---0 uuuu
EECON2	89h	---- ----	---- ----	---- ----
PCLATH	8Ah	---0 0000	---0 0000	---u uuuu
INTCON	8Bh	0000 000x	0000 000u	uuuu uuuu <sup>(1)</sup>

Legend: u = unchanged, x = unknown, - = unimplemented bit, read as '0', q = value depends on condition

**Note 1:** One or more bits in INTCON will be affected (to cause wake-up).

**2:** When the wake-up is due to an interrupt and the GIE bit is set, the PC is loaded with the interrupt vector (0004h).

**3:** Table 6-3 lists the RESET value for each specific condition.

**4:** On any device RESET, these pins are configured as inputs.

**5:** This is the value that will be in the port output latch.

## 6.4 Power-on Reset (POR)

A Power-on Reset pulse is generated on-chip when  $V_{DD}$  rise is detected (in the range of 1.2V - 1.7V). To take advantage of the POR, just tie the MCLR pin directly (or through a resistor) to  $V_{DD}$ . This will eliminate external RC components usually needed to create Power-on Reset. A minimum rise time for  $V_{DD}$  must be met for this to operate properly. See Electrical Specifications for details.

When the device starts normal operation (exits the RESET condition), device operating parameters (voltage, frequency, temperature, etc.) must be met to ensure operation. If these conditions are not met, the device must be held in RESET until the operating conditions are met.

For additional information, refer to Application Note AN607, "Power-up Trouble Shooting."

The POR circuit does not produce an internal RESET when  $V_{DD}$  declines.

## 6.5 Power-up Timer (PWRT)

The Power-up Timer (PWRT) provides a fixed 72 ms nominal time-out ( $T_{PWRT}$ ) from POR (Figures 6-6 through 6-9). The Power-up Timer operates on an internal RC oscillator. The chip is kept in RESET as long as the PWRT is active. The PWRT delay allows the  $V_{DD}$  to rise to an acceptable level (possible exception shown in Figure 6-9).

A configuration bit,  $\overline{PWRTE}$ , can enable/disable the PWRT. See Register 6-1 for the operation of the  $\overline{PWRTE}$  bit for a particular device.

The power-up time delay  $T_{PWRT}$  will vary from chip to chip due to  $V_{DD}$ , temperature, and process variation. See DC parameters for details.

XT, HS, LP	72 ms + $1024T_{OSC}$	$1024T_{OSC}$	$1024T_{OSC}$
RC	72 ms	—	—

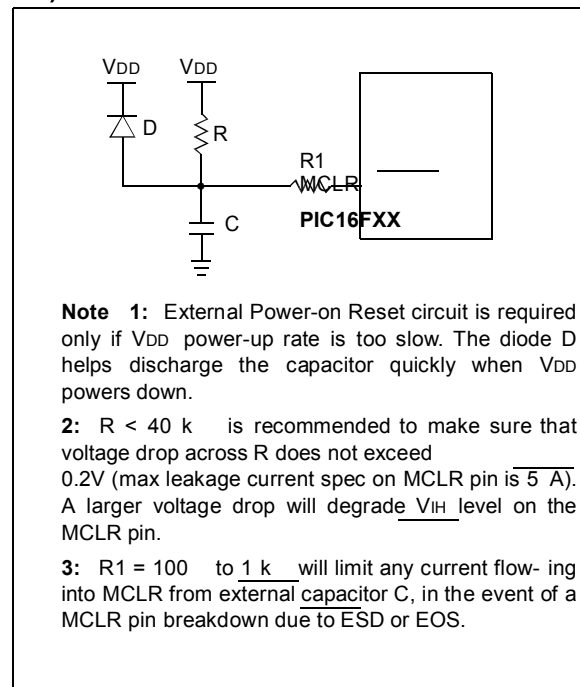
## 6.6 Oscillator Start-up Timer (OST)

The Oscillator Start-up Timer (OST) provides a 1024 oscillator cycle delay (from OSC1 input) after the PWRT delay ends (Figure 6-6, Figure 6-7, Figure 6-8 and Figure 6-9). This ensures the crystal oscillator or resonator has started and stabilized.

The OST time-out ( $T_{OST}$ ) is invoked only for XT, LP and HS modes and only on Power-on Reset or wake-up from SLEEP.

When  $V_{DD}$  rises very slowly, it is possible that the  $T_{PWRT}$  time-out and  $T_{OST}$  time-out will expire before  $V_{DD}$  has reached its final value. In this case (Figure 6-9), an external Power-on Reset circuit may be necessary (Figure 6-5).

**FIGURE 6-5: EXTERNAL POWER-ON RESET CIRCUIT (FOR SLOW  $V_{DD}$  POWER-UP)**



## 6.8 Interrupts

The PIC16F84A has 4 sources of interrupt:

- External interrupt RB0/INT pin
- TMR0 overflow interrupt
- PORTB change interrupts (pins RB7:RB4)
- Data EEPROM write complete interrupt

The interrupt control register (INTCON) records individual interrupt requests in flag bits. It also contains the individual and global interrupt enable bits.

The global interrupt enable bit, GIE (INTCON<7>), enables (if set) all unmasked interrupts or disables (if cleared) all interrupts. Individual interrupts can be disabled through their corresponding enable bits in INTCON register. Bit GIE is cleared on RESET.

The “return from interrupt” instruction, `RETFIE`, exits interrupt routine as well as sets the GIE bit, which re-enables interrupts.

The RB0/INT pin interrupt, the RB port change interrupt and the TMR0 overflow interrupt flags are contained in the INTCON register.

When an interrupt is responded to, the GIE bit is cleared to disable any further interrupt, the return address is pushed onto the stack and the PC is loaded with 0004h. For external interrupt events, such as the RB0/INT pin or PORTB change interrupt, the interrupt latency will be three to four instruction cycles. The exact latency depends when the interrupt event occurs. The latency is the same for both one and two cycle instructions. Once in the Interrupt Service Routine, the source(s) of the interrupt can be determined by polling the interrupt flag bits. The interrupt flag bit(s) must be cleared in software before re-enabling interrupts to avoid infinite interrupt requests.

**Note:** Individual interrupt flag bits are set regardless of the status of their corresponding mask bit or the GIE bit.

### 6.8.1 INT INTERRUPT

External interrupt on RB0/INT pin is edge triggered: either rising if INTEDG bit (OPTION\_REG<6>) is set, or falling if INTEDG bit is clear. When a valid edge appears on the RB0/INT pin, the INTF bit (INTCON<1>) is set. This interrupt can be disabled by clearing control bit INTE (INTCON<4>). Flag bit INTF must be cleared in software via the Interrupt Service Routine before re-enabling this interrupt. The INT interrupt can wake the processor from SLEEP (Section 6.11) only if the INTE bit was set prior to going into SLEEP. The status of the GIE bit decides whether the processor branches to the interrupt vector following wake-up.

### 6.8.2 TMR0 INTERRUPT

An overflow (FFh 00h) in TMR0 will set flag bit T0IF (INTCON<2>). The interrupt can be enabled/disabled by setting/clearing enable bit T0IE (INTCON<5>) (Section 5.0).

### 6.8.3 PORTB INTERRUPT

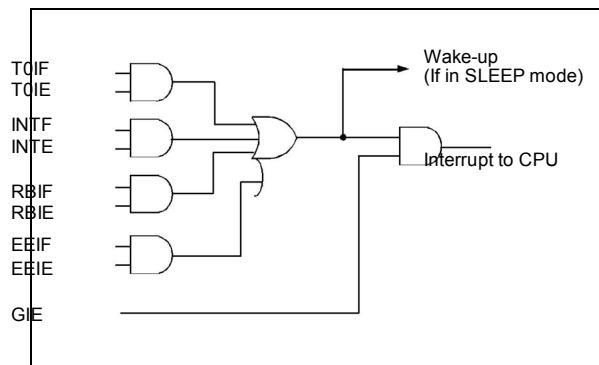
An input change on PORTB<7:4> sets flag bit RBIF (INTCON<0>). The interrupt can be enabled/disabled by setting/clearing enable bit RBIE (INTCON<3>) (Section 4.2).

**Note:** For a change on the I/O pin to be recognized, the pulse width must be at least  $T_{cy}$  wide.

### 6.8.4 DATA EEPROM INTERRUPT

At the completion of a data EEPROM write cycle, flag bit EEIF (EECON1<4>) will be set. The interrupt can be enabled/disabled by setting/clearing enable bit EEIE (INTCON<6>) (Section 3.0).

**FIGURE 6-10: INTERRUPT LOGIC**



## 6.9 Context Saving During Interrupts

During an interrupt, only the return PC value is saved on the stack. Typically, users wish to save key register values during an interrupt (e.g., W register and STATUS register). This is implemented in software.

The code in Example 6-1 stores and restores the STATUS and W register's values. The user defined registers, W\_TEMP and STATUS\_TEMP are the temporary storage locations for the W and STATUS registers values.

Example 6-1 does the following:

- a) Stores the W register.
- b) Stores the STATUS register in STATUS\_TEMP.
- c) Executes the Interrupt Service Routine code.
- d) Restores the STATUS (and bank select bit) register.
- e) Restores the W register.

### EXAMPLE 6-1: SAVING STATUS AND W REGISTERS IN RAM

```

PUSH  MOVWF  W_TEMP      ; Copy W to TEMP register,
      SWAPF  STATUS,    W      ; Swap status to be saved into W
      MOVWF  STATUS_TEMP ; Save status to STATUS_TEMP register
ISR   :
      :                    ; Interrupt Service Routine
      :                    ; should configure Bank as required
      :
POP   SWAPF  STATUS_TEMP,W    ; Swap nibbles in STATUS_TEMP register
      ; and place result into W
MOVWF STATUS            ; Move W into STATUS register
      ; (sets bank to original state)
SWAPF  W_TEMP,    F      ; Swap nibbles in W_TEMP and place result in W_TEMP
SWAPF  W_TEMP,    W      ; Swap nibbles in W_TEMP and place result into W
    
```

## 6.10 Watchdog Timer (WDT)

The Watchdog Timer is a free running On-Chip RC Oscillator which does not require any external components. This RC oscillator is separate from the RC oscillator of the OSC1/CLKIN pin. That means that the WDT will run even if the clock on the OSC1/CLKIN and OSC2/CLKOUT pins of the device has been stopped, for example, by execution of a SLEEP instruction. During normal operation, a WDT time-out generates a device RESET. If the device is in SLEEP mode, a WDT wake-up causes the device to wake-up and continue with normal operation. The WDT can be permanently disabled by programming configuration bit WDTE as a '0' (Section 6.1).

### 6.10.1 WDT PERIOD

The WDT has a nominal time-out period of 18 ms, (with no prescaler). The time-out periods vary with temperature, V<sub>DD</sub> and process variations from part to part (see DC specs). If longer time-out periods are desired, a prescaler with a division ratio of up to 1:128 can be assigned to the WDT under software control by writing to the OPTION\_REG register. Thus, time-out periods up to 2.3 seconds can be realized.

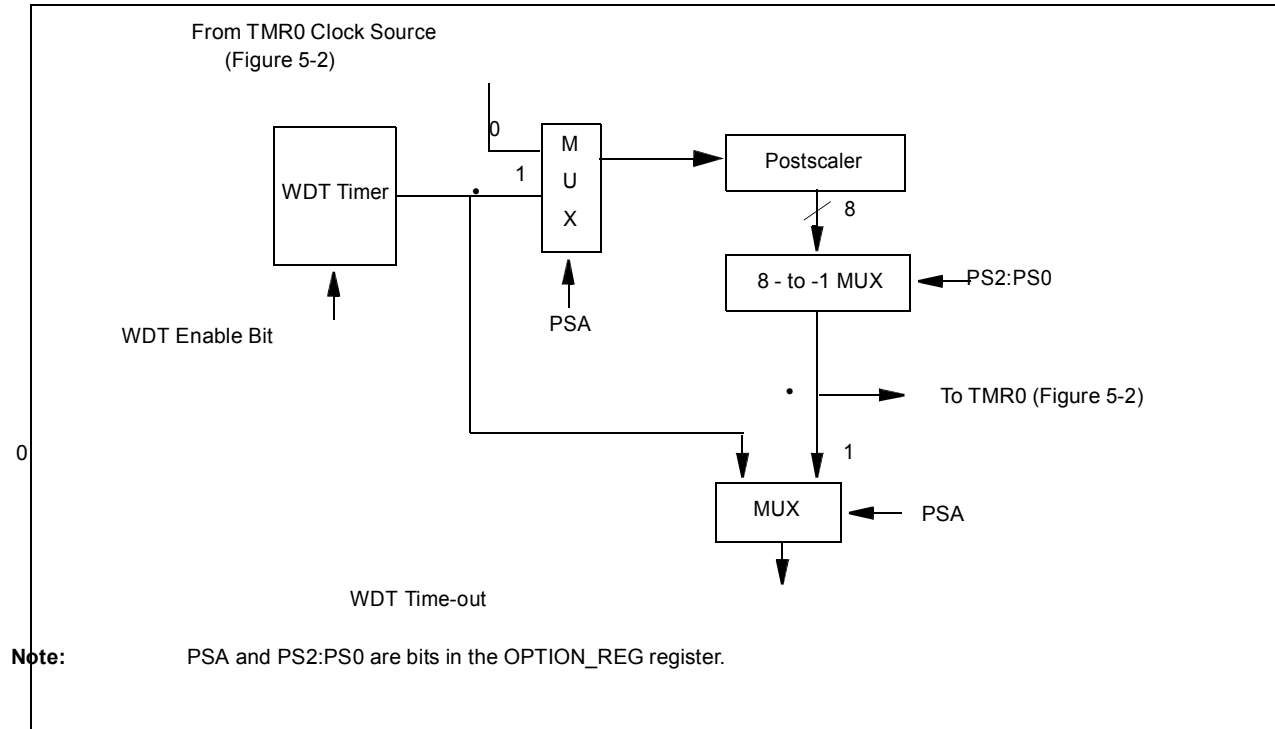
The CLRWDT and SLEEP instructions clear the WDT and the postscaler (if assigned to the WDT) and prevent it from timing out and generating a device RESET condition.

The  $\overline{TO}$  bit in the STATUS register will be cleared upon a WDT time-out.

## 6.10.2 WDT PROGRAMMING CONSIDERATIONS

It should also be taken into account that under worst case conditions ( $V_{DD} = \text{Min.}$ , Temperature = Max., Max. WDT Prescaler), it may take several seconds before a WDT time-out occurs.

**FIGURE 6-11: WATCHDOG TIMER BLOCK DIAGRAM**



**TABLE 6-7: SUMMARY OF REGISTERS ASSOCIATED WITH THE WATCHDOG TIMER**

Addr	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Value on Power-on Reset	Value on all other RESETS
2007h	Config. bits	(2)	(2)	(2)	(2)	PWRTE <sup>(1)</sup>	WDTE	FOSC1	FOSC0	(2)	
81h	OPTION_REG	RBPU	INTEDG	T0CS	T0SE	PSA	PS2	PS1	PS0	1111 1111	1111 1111

Legend: x = unknown. Shaded cells are not used by the WDT.

**Note 1:** See Register 6-1 for operation of the PWRTE bit.

**2:** See Register 6-1 and Section 6.12 for operation of the code and data protection bits.



## 6.11 Power-down Mode (SLEEP)

A device may be powered down (SLEEP) and later powered up (wake-up from SLEEP).

### 6.11.1 SLEEP

The Power-down mode is entered by executing the SLEEP instruction.

If enabled, the Watchdog Timer is cleared (but keeps running), the PD bit (STATUS<3>) is cleared, the TO bit (STATUS<4>) is set, and the oscillator driver is turned off. The I/O ports maintain the status they had before the SLEEP instruction was executed (driving high, low, or hi-impedance).

For the lowest current consumption in SLEEP mode, place all I/O pins at either VDD or VSS, with no external circuitry drawing current from the I/O pins, and disable external clocks. I/O pins that are hi-impedance inputs should be pulled high or low externally to avoid switching currents caused by floating inputs. The TOCK1 input should also be at VDD or VSS. The contribution from on-chip pull-ups on PORTB should be considered.

The MCLR pin must be at a logic high level (VIHMC).

It should be noted that a RESET generated by a WDT time-out does not drive the MCLR pin low.

### 6.11.2 WAKE-UP FROM SLEEP

The device can wake-up from SLEEP through one of the following events:

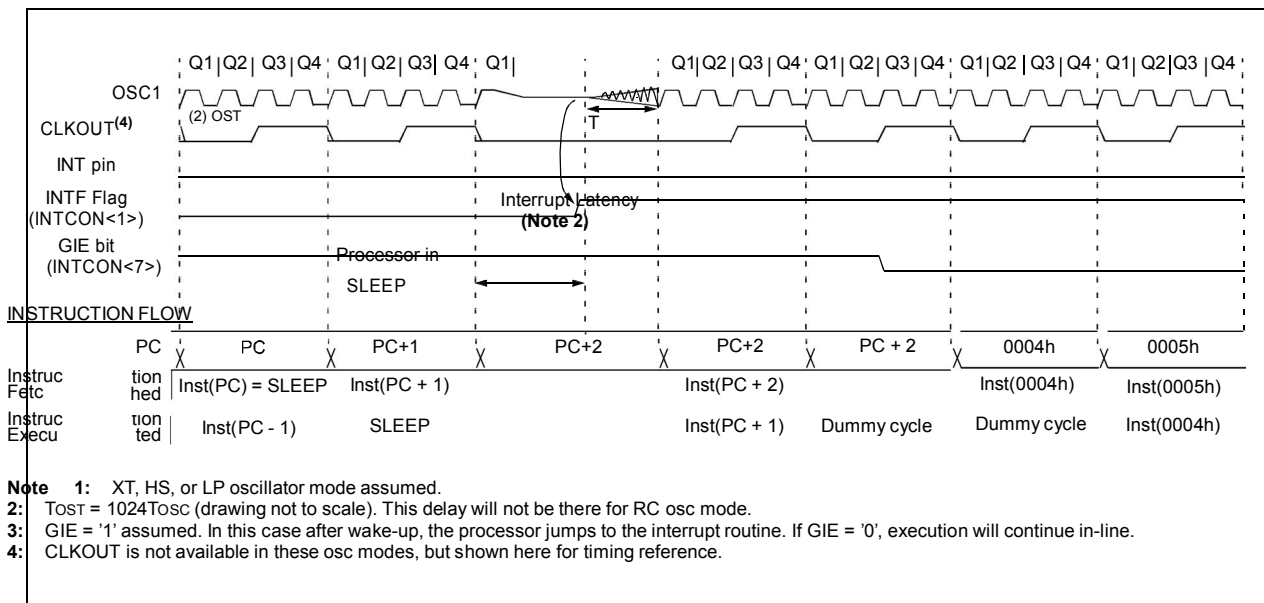
1. External RESET input on  $\overline{\text{MCLR}}$  pin.
2. WDT wake-up (if WDT was enabled).
3. Interrupt from RB0/INT pin, RB port change, or data EEPROM write complete.

Peripherals cannot generate interrupts during SLEEP, since no on-chip Q clocks are present.

The first event ( $\overline{\text{MCLR}}$  Reset) will cause a device RESET. The two latter events are considered a continuation of program execution. The  $\overline{\text{TO}}$  and PD bits can be used to determine the cause of a device RESET. The PD bit, which is set on power-up, is cleared when SLEEP is invoked. The  $\overline{\text{TO}}$  bit is cleared if a WDT time-out occurred (and caused wake-up).

While the SLEEP instruction is being executed, the next instruction (PC + 1) is pre-fetched. For the device to wake-up through an interrupt event, the corresponding interrupt enable bit must be set (enabled). Wake-up occurs regardless of the state of the GIE bit. If the GIE bit is clear (disabled), the device continues execution at the instruction after the SLEEP instruction. If the GIE bit is set (enabled), the device executes the instruction after the SLEEP instruction and then branches to the interrupt address (0004h). In cases where the execution of the instruction following SLEEP is not desirable, the user should have a NOP after the SLEEP instruction.

**FIGURE 6-12: WAKE-UP FROM SLEEP THROUGH INTERRUPT**



**BTFSK**                    **Bit Test, Skip if Clear**

---

Syntax:                    [label] BTFSK f,b

Operands:                0 f 127  
                              0 b 7

Operation:                skip if (f<b>) = 0

Status Affected:        None

Description:              If bit 'b' in register 'f' is '1', the next instruction is executed.  
If bit 'b' in register 'f' is '0', the next instruction is discarded, and a NOP is executed instead, making this a 2Tcy instruction.

**CALL**                    **Call Subroutine**

---

Syntax:                    [label] CALL k

Operands:                0 k 2047

Operation:                (PC)+1 TOS,  
k                            PC<10:0>,  
(PCLATH<4:3>)            PC<12:11>

Status Affected:        None

Description:              Call Subroutine. First, return address (PC+1) is pushed onto the stack. The eleven-bit immediate address is loaded into PC bits <10:0>. The upper bits of the PC are loaded from PCLATH. CALL is a two-cycle instruction.

**CLRF**                    **Clear f**

---

Syntax:                    [label] CLRF f

Operands:                0 f 127

Operation:                00h (f)  
1                            Z

Status Affected:        Z

Description:              The contents of register 'f' are cleared and the Z bit is set.

**CLRW**                    **Clear W**

---

Syntax:                    [label] CLRW

Operands:                None

Operation:                00h (W)  
1                            Z

Status Affected:        Z

Description:              W register is cleared. Zero bit (Z) is set.

**CLRWD**                   **Clear Watchdog Timer**

---

Syntax:                    [label] CLRWD

Operands:                None

Operation:                00h WDT  
0                            WDT prescaler,  
1                             $\overline{TO}$   
1                            PD

Status Affected:         $\overline{TO}$ ,  $\overline{PD}$

Description:              CLRWD instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits  $\overline{TO}$  and  $\overline{PD}$  are set.

**COMF**                    **Complement f**

---

Syntax:                    [label] COMF f,d

Operands:                0 f 127  
d                            [0,1]

Operation:                ( $\bar{f}$ ) (destination)

Status Affected:        Z

Description:              The contents of register 'f' are complemented. If 'd' is 0, the result is stored in W. If 'd' is 1, the result is stored back in register 'f'.

**DECF**                    **Decrement f**

---

Syntax:                    [label] DECF f,d

Operands:                0 f 127  
d                            [0,1]

Operation:                (f) - 1 (destination)

Status Affected:        Z

Description:              Decrement register 'f'. If 'd' is 0, the result is stored in the W register. If 'd' is 1, the result is stored back in register 'f'.

## DECFSZ      Decrement f, Skip if 0

**Syntax:**            [ label ] DECFSZ f,d

**Operands:**        0 f 127  
d                    [0,1]

**Operation:**        (f) - 1    (destination);  
skip if result = 0

**Status Affected:**    None

**Description:**        The contents of register 'f' are decremented. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'. If the result is 1, the next instruction is executed. If the result is 0, then a NOP is executed instead, making it a 2TCY instruction.

## INCFSZ      Increment f, Skip if 0

**Syntax:**            [ label ] INCFSZ f,d

**Operands:**        0 f 127  
d                    [0,1]

**Operation:**        (f) + 1    (destination),  
skip if result = 0

**Status Affected:**    None

**Description:**        The contents of register 'f' are incremented. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'. If the result is 1, the next instruction is executed. If the result is 0, a NOP is executed instead, making it a 2TCY instruction.

## GOTO        Unconditional Branch

**Syntax:**            [ label ] GOTO k

**Operands:**        0 k 2047

**Operation:**        k    PC<10:0>  
PCLATH<4:3>    PC<12:11>    Status Affected:

                          None

**Description:**        GOTO is an unconditional branch. The eleven-bit immediate value is loaded into PC bits <10:0>. The upper bits of PC are loaded from PCLATH<4:3>. GOTO is a two-cycle instruction.

## IORLW      Inclusive OR Literal with W

**Syntax:**            [ label ] IORLW k

**Operands:**        0 k 255

**Operation:**        (W) .OR. k    (W)

**Status Affected:**    Z

**Description:**        The contents of the W register are OR'ed with the eight-bit literal 'k'. The result is placed in the W register.

## INCF        Increment f

**Syntax:**            [ label ] INCF f,d

**Operands:**        0 f 127  
d                    [0,1]

**Operation:**        (f) + 1    (destination)

**Status Affected:**    Z

**Description:**        The contents of register 'f' are incremented. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.

## IORWF      Inclusive OR W with f

**Syntax:**            [ label ] IORWF f,d

**Operands:**        0 f 127  
d                    [0,1]

**Operation:**        (W) .OR. (f)    (destination)

**Status Affected:**    Z

**Description:**        Inclusive OR the W register with register 'f'. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.

---

**MOVF**            **Move f**

---

Syntax:            [ label ] MOVF f,d

Operands:        0 f 127

d                   [0,1]

Operation:        (f) (destination)

Status Affected: Z

Description:        The contents of register f are moved to a destination dependant upon the status of d. If d = 0, destination is W register. If d = 1, the destination is file register f itself. d = 1 is useful to test a file register, since status flag Z is affected.

---

**RETFIE**          **Return from Interrupt**

---

Syntax:            [ label ] RETFIE

Operands:        None

Operation:        TOS PC,  
1                   GIE

Status Affected: None

---

**MOVLW**          **Move Literal to W**

---

Syntax:            [ label ] MOVLW k

Operands:        0 k 255

Operation:        k (W)

Status Affected: None

Description:        The eight-bit literal 'k' is loaded into W register. The don't cares will assemble as 0's.

---

**RETLW**          **Return with Literal in W**

---

Syntax:            [ label ] RETLW k

Operands:        0 k 255

Operation:        k (W);  
TOS                PC Status

Affected:         None

Description:        The W register is loaded with the eight-bit literal 'k'. The program counter is loaded from the top of the stack (the return address). This is a two-cycle instruction.

---

**MOVWF**          **Move W to f**

---

Syntax:            [ label ] MOVWF f

Operands:        0 f 127

Operation:        (W) (f)

Status Affected: None

Description:        Move data from W register to register 'f'.

---

**RETURN**          **Return from Subroutine**

---

Syntax:            [ label ] RETURN

Operands:        None

Operation:        TOS PC

Status Affected: None

Description:        Return from subroutine. The stack is POPed and the top of the stack (TOS) is loaded into the program counter. This is a two-cycle instruction.

---

**NOP**             **No Operation**

---

Syntax:            [ label ] NOP

Operands:        None

Operation:        No operation

Status Affected: None

Description:        No operation.

**RLF**                      **Rotate Left f through Carry**

---

Syntax:                    [label] RLF f,d

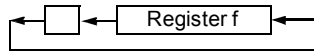
Operands:                0 f 127  
d [0,1]

Operation:                See description below

Status Affected:        C

Description:              The contents of register 'f' are rotated one bit to the left through the Carry Flag. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is stored back in register 'f'.

C



**SUBLW**                    **Subtract W from Literal**

---

Syntax:                    [label] SUBLW k

Operands:                0 k 255

Operation:                k - (W)    W

Status Affected:        C, DC, Z

Description:              The W register is subtracted (2's complement method) from the eight-bit literal 'k'. The result is placed in the W register.

**RRF**                      **Rotate Right f through Carry**

---

Syntax:                    [label] RRF f,d

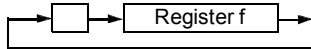
Operands:                0 f 127  
d [0,1]

Operation:                See description below

Status Affected:        C

Description:              The contents of register 'f' are rotated one bit to the right through the Carry Flag. If 'd' is 0, the result is placed in the W register. If 'd' is 1, the result is placed back in register 'f'.

C



**SUBWF**                    **Subtract W from f**

---

Syntax:                    [label] SUBWF f,d

Operands:                0 f 127  
d [0,1]

Operation:                (f) - (W)    destination)

Status Affected:        C, DC, Z

Description:              Subtract (2's complement method) W register from register 'f'. If 'd' is 0, the result is stored in the W register. If 'd' is 1, the result is stored back in register 'f'.

**SLEEP**

---

Syntax:                    [label] SLEEP

Operands:                None

Operation:                00h    WDT,  
0                            WDT prescaler,  
1                             $\overline{TO}$ ,  
0                            PD

Status Affected:         $\overline{TO}$ ,  $\overline{PD}$

Description:              The power-down status bit,  $\overline{PD}$  is cleared. Time-out status bit,  $\overline{TO}$  is set. Watchdog Timer and its prescaler are cleared.

The processor is put into SLEEP mode with the oscillator stopped.

**SWAPF**                    **Swap Nibbles in f**

---

Syntax:                    [label] SWAPF f,d

Operands:                0 f 127  
d [0,1]

Operation:                (f<3:0>)    (destination<7:4>),  
(f<7:4>)    (destination<3:0>)

Status Affected:        None

Description:              The upper and lower nibbles of register 'f' are exchanged. If 'd' is 0, the result is placed in W register. If 'd' is 1, the result is placed in register 'f'.

## **XORLW**                      **Exclusive OR Literal with W**

---

Syntax:                      [label] XORLW k  
Operands:                   0 k 255  
Operation:                   (W) .XOR. k      W)  
Status Affected:           Z  
Description:                The contents of the W register are XOR'ed with the eight-bit literal 'k'. The result is placed in the W register.

## **XORWF**                      **Exclusive OR W with f**

---

Syntax:                      [label] XORWF f,d  
Operands:                   0 f 127  
                                  d                      [0,1]  
Operation:                   (W) .XOR. (f)      destination)  
Status Affected:           Z  
Description:                Exclusive OR the contents of the W register with register 'f'. If 'd' is 0, the result is stored in the W register. If 'd' is 1, the result is stored back in register 'f'.

## Features

- Optimised for high speed transfer of data.
- USB 2.0 Hi-Speed connection.
- up to 480 Mbps data rate
- Backward compatibility with Full-Speed USB 2.0 and USB 1.1.
- Integrated USB 2.0 Hi-Speed PHY.
- USB suspend/resume supported
- 3.3V supply.
- Low power < 600mW operating, <900uA suspend.
- Suitable for bus powered applications.
- 16 kB USB buffer memory.
- SDIO interface supports
- 1bit or 4bit SDIO
- SD Interrupt.
- Card detection.
- VUB300 live on power up.
- SD Specifications Part 1 Physical Layer Specification Version 2.00.
- SD Specifications Part E1 SDIO Specification Version 2.00.
- Single chip solution
- Development / Demonstration board available same functionality with multi chip solution.
- Package : 36-pin QFN 6x6mm
- Fully 'green', lead-free and RoHS compliant.
- >120Mbps "Real World" block read/write performance\*



\* Read/write performance based on CMD18/25/53 multi-block transfers

## Introduction

Extending the capabilities of SD and SDIO devices into the world of USB, and also allowing expansion of Laptop and Desktop PC's into the world of SD and SDIO devices, the VUB300 is a USB to SDIO host controller bridge chip interface that allows SDIO and SD compliant devices to be connected to any host PC via the Universal Serial Bus (USB). It is a USB 2.0 compliant device operating at Hi-Speed (480 Mbps). The SDIO Host function conforms to the SDIO Host specification with a generic USB "wrapped" interface to extend SDIO host controller support to the USB bus.



## Device Support

The VUB300 conforms to the SD Specifications Part 1 Physical Layer Specification Version 2.00 and SD Specifications Part E1 SDIO Specification Version 2.00. The VUB300 supports any SD or SDIO device that conforms to the SD/SDIO specifications.

## Host Support

The VUB300 conforms to the USB 2.0 Specification; it is a Hi-Speed device and will work on any host that supports USB 2.0 or 1.1 host ports. Please note that maximum data throughput is only available with USB 2.0 Hi-Speed hosts.



## Operating System Support

The VUB300 SDIO host controller drivers are supported on the following operating systems:

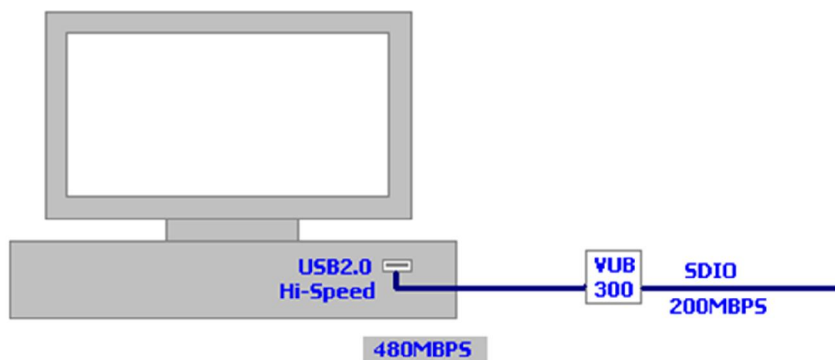
- Linux
- Windows 2000
- Windows XP
- Windows Vista 32
- Windows Vista 64
- Windows Mobile/PocketPC/CE\*
- Apple MAC OSX\*

The drivers integrate with the generic SDIO host stack providing seamless functionality with existing SD and SDIO device drivers.

\*Planned

## Functionality and Design

VUB300 offers a unique USB to SDIO host controller interface link with this single chip bridge solution in the form of an ASIC.



VUB300 offers capability and intelligence to handle both USB and SDIO protocol, creating the connection between the two and seemingly translating the data between the two formats.

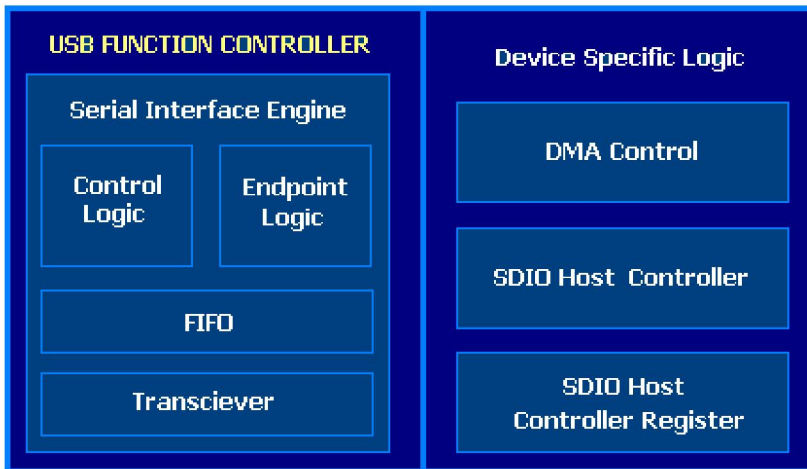


Diagram 3: VUB300 Block Diagram

## **USB**

### **Integrated USB 2.0 Hi-Speed Transceiver / PHY**

VUB300 ASIC has integrated USB 2.0 compliant Hi-Speed Transceiver.

## **SDIO**

SDIO Host Controller, SDIO Host Controller Register and DMA Control, all make up the SDIO Function Controller section within VUB300, see Diagram 3.

### **DMA Control**

By implementing DMA control VUB300 is able to achieve high performance data transfers between an SD/SDIO data path and the USB bulk data interface. SD/SDIO blocks transfers in DMA mode of 256, 512, 1024 and 2048 are supported. Tested and recommended are 256 or 512 block transfers.

### **SDIO Host Controller**

SDIO Function Controller is designed according to the SD Association's SD host controller specification.

## **SDIO Host Controller Interface**

All the access to the SD/SDIO bus are made via the SDIO host transaction processor accessing the internal SDIO Host controller registers. DMA, burst access, CRC error detection, SD interrupt, timing, etc. are supported by the transaction processor core. SD command and data transfers are initiated by the host side driver as USB transactions, these are translated into SD bus commands and data transfers. The complete responses are returned to the host side driver.

## ***VUB300 Bridging Logic***

VUB300 has IP core with device specific logic that is adapting, organising and translating data between USB and SDIO interface. This device specific logic design has been improved by the Elan development team for superior and fast performance.

## Pin Descriptions

### SECURE DIGITAL INTERFACE

Pin #	Name	Type	Description
23 25 4 5	SD_D[3:0]	SD Data	This is a bi-directional bus that connects to the DAT bus of SD device
9	SD_CLK	SD Clock	This is an output clock signal to SD/SDIO device
11	SD_CMD	SD Command	This is a bi-directional signal that connects to the CMD signal of SD device
30	SD_WP	SD Write Protect	This is an IO pin designated as the Secure Digital card mechanical write protect pin
26	SD_nCD	SD Card Detect	This is an IO pin designated as the Secure Digital card detection pin

### USB INTERFACE

Pin #	Name	Type	Description
2 3	USB+ USB-	USB Bus Data	These pins connect to the USB data bus signals
35	RBIAS	USB Transceiver Bias	A 12.0k, 1.0% resistor is attached from VSS to this pin in order to set the transceiver's internal bias currents
33	XTAL1 (CLKIN)	24MHz Crystal or external clock input	This pin can be connected to one terminal of the crystal or it can be connected to an external 24 clock when a crystal is not used
32	XTAL2	24MHz Crystal	This is the other terminal of the crystal, or it is left open when an external clock source is used to drive XTAL1(CLKIN). It may not be used to drive any external circuitry other than the crystal circuit
36	VDDA33	3.3V Analog Power	3.3V Analog Power
34	VDD18PLL	1.8V PLL Power	This pin in the 1.8V Power for the PLL +1.8V Filtered analog power for internal PLL. This pin must have a 1.0 $\mu$ F (or greater) $\pm$ 20% (ESR <0.1 $\Omega$ ) capacitor to VSS

<b>MISC</b>			
<b>Pin #</b>	<b>Name</b>	<b>Type</b>	<b>Description</b>
1	LED1	General Purpose IO	This pin may be used to drive an activity LED
21	CRD_PWR	General Purpose I/O	Card Power drive of 3.3V at either 100mA or 200mA
18	nRESET	RESET Input	This active low signal is used by the system to reset the chip. The active low pulse should be at least 1 $\mu$ s wide
<b>DIGITAL / POWER</b>			
<b>Pin #</b>	<b>Name</b>	<b>Type</b>	<b>Description</b>
13	VDD18	+1.8V Core power	+1.8V core power. This pin must have a +1.0 $\mu$ F (or greater) $\pm$ 20% (ESR <0.1 $\Omega$ ) capacitor to VSS
6 13 22	VDD33	3.3V Power & Regulator Input	3.3V power supply input
28	TEST	Input	This signal is used for testing the chip. When unused tie to VSS
SLUG	VSS		Ground reference

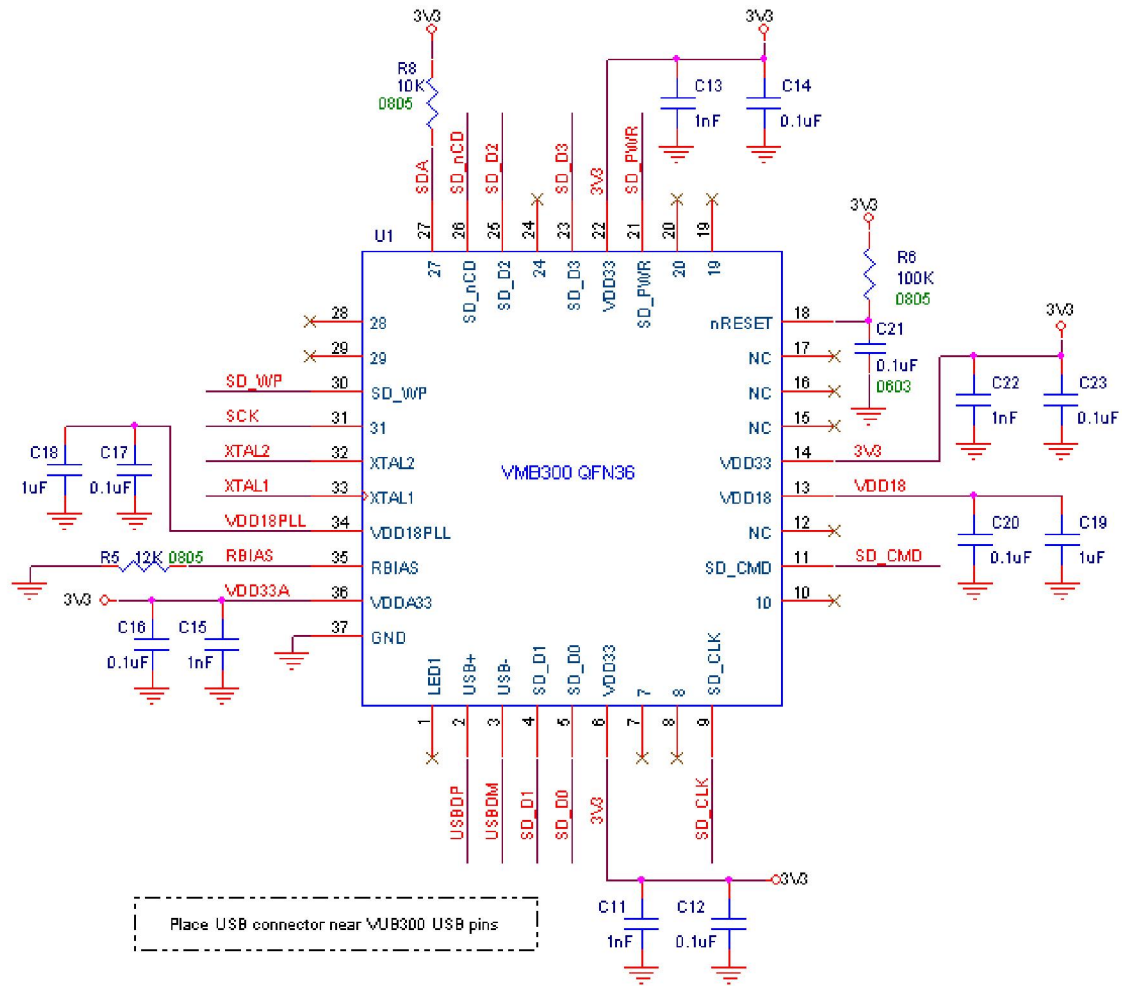
## **SDIO Socket Pin Definitions**

<b>Pin</b>	<b>Name</b>	<b>Description</b>
1	SD_DAT[3]/CD	Data line 3 / Card detect
2	SD_CMD	Command line
3	VSS1	Ground
4	SD_PWR	Supply voltage, should be connected to CRD_PWR
5	SD_CLK	Clock
6	VSS2	Ground
7	SD_DAT[0]	Data line 0
8	SD_DAT[1]/IRQ	Data line 1 / SDIO Interrupt
9	SD_DAT[2]/WAIT	Data line 2 / SDIO Read Wait
10	SD_nCD	SD/SDIO card detect switch, active LOW
11	SD_WP	SD card write protect switch, active HIGH

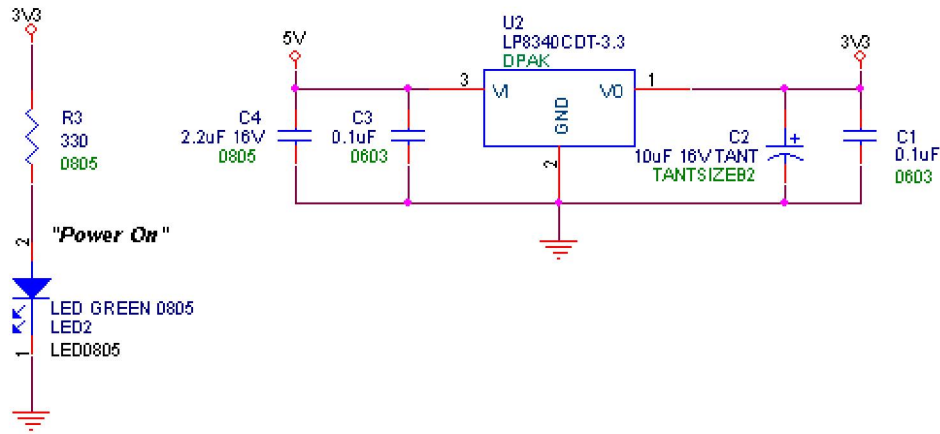
## Reference Design

The following schematic provides USB SD/SDIO card reader reference design.

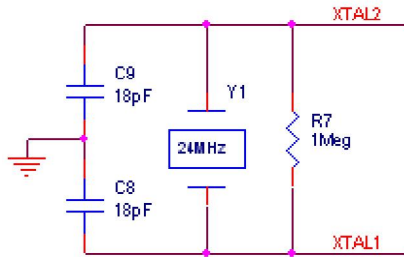
### VUB300 main block



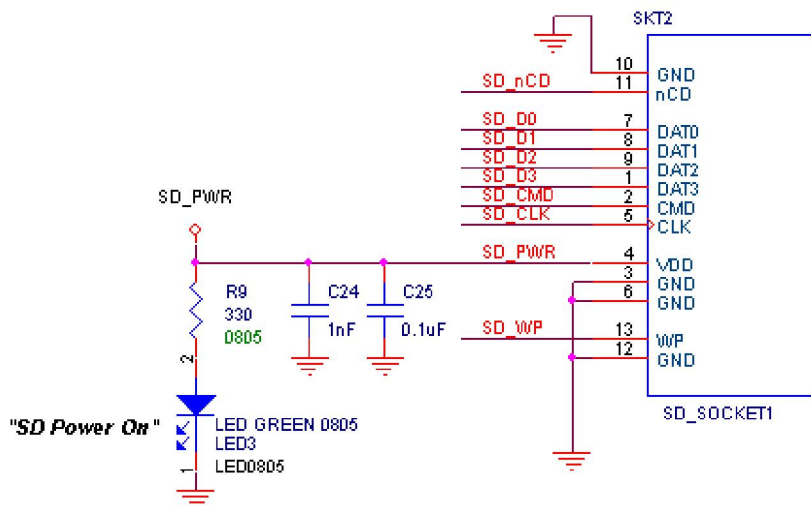
## Power supply block



## Clock reference block

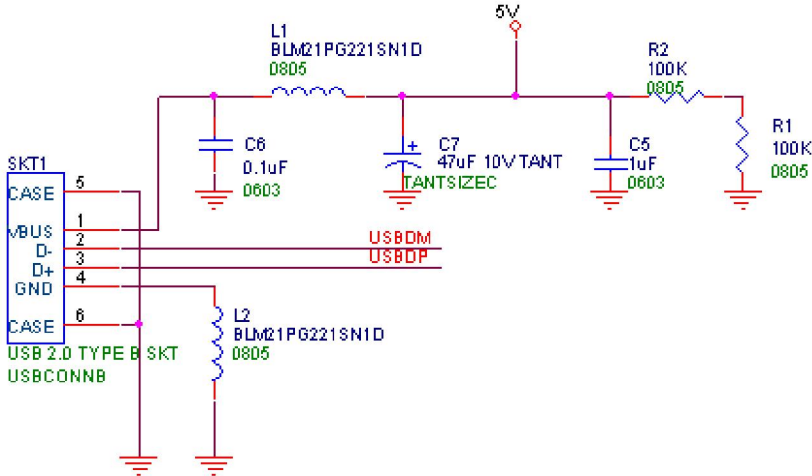


## SD/SDIO socket block





# USB socket block



<b>Symbol</b>	<b>Min</b>	<b>Nom</b>	<b>Max</b>	<b>Notes</b>
A	'0.80		'1.00	Overall package height
A1	0	0.02	0.05	Standoff
A2	'0.60		'0.80	Mold cap thickness
A3	0.20 REF			Leadframe thickness
D/E	5.85	'6.00	'6.15	X/Y body size
D1/E1	5.55		5.95	X/Y mold cap size
D2/E2	'4.00	'4.10	'4.20	X/Y exposed pad size
L	'0.50	'0.60	'0.75	Terminal length
b	0.18	0.25	'0.30	Terminal width
e	0.50 BSC			Terminal pitch
x	4 X 0° - 12°			

## Electrical Specifications

Parameter	Conditions	Min	Typ	Max	Units
Supply Voltage (VDD)		3.0	3.3	3.6	V
Operating Temperature Range	Industrial	-40		+85	°C
Full Speed I <sub>DD</sub>			110	140	mA
High Speed I <sub>DD</sub>			135	165	mA
Supply current USB suspend			350	900	uA

## Recommended Operating Conditions

Parameter	Min	Max	Units
Operating Temperature	-40	85	°C
3.3V Supply Voltage (V <sub>DD33</sub> , V <sub>DDA33</sub> )	3.0	3.6	°C
3.3V Supply rise time	0	400	°C
Voltage on USB+ and USB- pins	-0.3	5.5	V
Voltage on any signal pin	-0.3	V <sub>DD33</sub>	V
Voltage on XTAL1	-0.3	V <sub>DDA33</sub>	V
Voltage on XTAL2	-0.3	V <sub>DD18</sub>	V

## Absolute Maximum Ratings\*

Parameter	Min	Max	Units
Ambient temperature under bias	-55	125	°C
Storage Temperature	-65	150	°C
Lead Temperature		325 (soldering < 10 seconds)	°C
3.3V supply voltage ( $V_{DD33}$ , $V_{DDA33}$ )	-0.5	4.0	V
Voltage on USB+ and USB- pins	-0.5	$(3.3V \text{ supply voltage} + 2) \leq 6$	V
Voltage on CRD_PWR	-0.5	$V_{DD33} + 0.3$	V
Voltage on any signal pin	-0.5	$V_{DD33} + 0.3$	V
Voltage on XTAL1	-0.5	4.0	V
Voltage on XTAL2	-0.5	$V_{DD18} + 0.3$	V

\*Note: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the devices at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

**APPENDIX C**  
**PROGRAM LISTING**

```
void main()
{
TRISB = 0x07;
PORTB = 0;
    while(1){
        while(PORTB.F0 == 1){
            PORTB.F3 = 1;

            PORTB.F4 = 0;
            PORTB.F5 = 0;
        }

        while(PORTB.F1 == 1){
            PORTB.F4 = 1;

            PORTB.F5 = 0;
            PORTB.F3 = 0;
        }

        while(PORTB.F2 == 1)
```

```
{  
  
    PORTB.F5 = 1;  
  
    PORTB.F3 = 0;  
  
    PORTB.F4 = 0;  
  
}
```

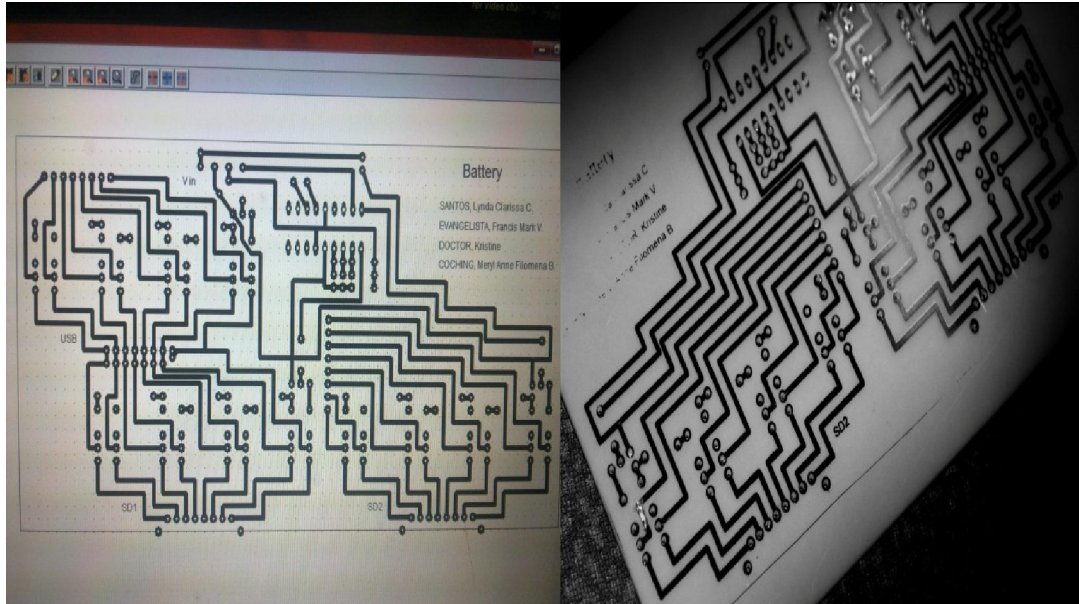
```
    PORTB.F3 = 0;  
  
    PORTB.F4 = 0;  
  
    PORTB.F5 = 0;
```

```
}
```

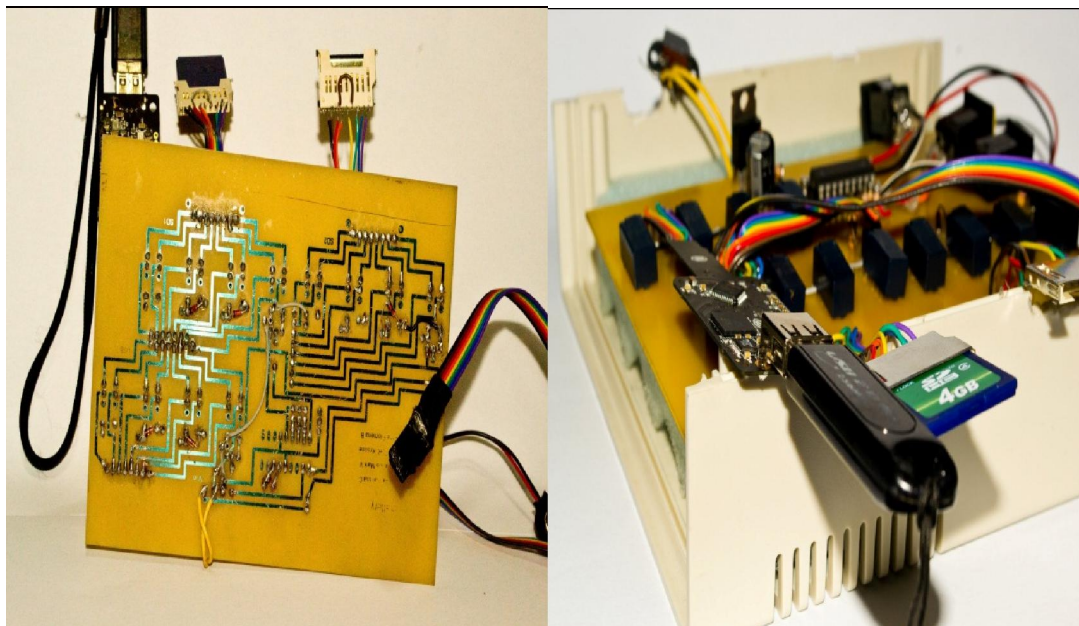
```
}
```

## APPENDIX D

### PICTURES OF PROTOTYPE



**PCB Layout**



**Final Circuit Design of the Device**



**Prototype Testing**



**Prototype with Case**



# File Management of a USB Flash Drive and Memory Card via Micro SD Card Slot of a Mobile Phone

Meryl Anne Filomena B. Coching<sup>#1</sup>, Kristine Doctor<sup>\*2</sup>, Francis Mark V. Evangelista<sup>#3</sup>,

Lynda Clarissa C. Santos<sup>#4</sup>

<sup>#</sup>*School of EECE, Mapúa Institute of Technology  
Muralla St., Intramuros, Manila, Philippines*

<sup>1</sup>meryl\_082791@yahoo.com

<sup>2</sup>sirk\_dr10@yahoo.com

<sup>3</sup>fmvevangelista@mymail.mapua.edu.ph

<sup>4</sup>lccsantos@mymail.mapua.edu.ph

**Abstract**— Most of the modern mobile phones have a micro SD slot that is used for expanded storage. Inspired by the recently released Nokia N8 which used USB On-the-Go feature that allows a flash drive to be connected via cable used, the researchers construct a design wherein the micro SD slot will be used as a pathway to incorporate the USB port and the memory card port/s. The purpose of the design is to give the mobile phone additional storage and to access/transfer data using another media, in substitute for desktop PCs particularly. The flash drive to be used should comply with USB 2.0 and the memory card is limited to SD/mini SD with maximum of with 2GB and 4GB total space limit respectively. The device is intended for mobile phones with micro SD slot. The major hardware components of the design consist of SD memory slots, USB to SDIO Bridge Chip Host interface Transfer for the USB flash drive, relay circuits and microcontroller which is programmed for port switching and micro SD sniffer for the main output device. The single file copy speed test is conducted for five mobile phone models to test the functionality of the device. The transfer speeds for each flash memory are also looked upon and was observed that comparing to the theoretical data transfer rates for the USB flash drive and SD memory card to the computer, the data transfer rates from the said flash memories with respect to our device are acceptable. After testing the prototype, the researchers satisfied the assumptions that the file management is successful and the file integrity is preserved.

**Keywords**— micro SD, USB 2.0, USB On-the-Go, SD memory card, File Transfer

## I. INTRODUCTION

Mobile phones have limited capabilities to access storage devices such as thumb drives and other memory cards that do not fit into the phone except card slots installed on the phone. Most of phones today have micro SD memory card slots installed. Almost all people nowadays have mobile phones, and almost all people have the need to transfer files quickly and want to ensure that data are successfully sent. As of now, the available media to send files are via infrared, Bluetooth, and one card slot that depends on what is installed on the phone. But what if the files needed are saved on a USB flash

drive, SD memory card or mini SD memory card? Let's say one's phone only accepts a micro SD memory card. One solution is to have a computer to access files to transfer to one's phone. Not all people carry their laptops all the time; or to have access to a PC.

A memory card (sometimes called a flash memory card or a storage card) is a small storage medium used to store data such as text, pictures, audio, and video, for use on small, portable or remote computing devices. Most of the current products use flash memory, although other technologies are being developed. Memory cards offer a number of advantages over the hard disk drive: they're much smaller and lighter, extremely portable, completely silent, allow more immediate access, and are less prone to mechanical damage. A USB flash drive is portable memory storage. It is re-writeable and holds its memory without a power supply, unlike RAM. USB flash drives will fit into any USB port on a computer. For a USB flash drive to function, it needs a host controller. Just like a PC, all flash drives have a storage device controller for it to read the device. This functionality is lacking in mobile phones since phones do not have a USB host controller.

This design is intended for on the go use. The user can simply insert the storage device and can easily manage files on their phones and the storage device. The phone will read the storage device as a memory card that is inserted in its memory card slot. Only one storage device can be read at a given time. To do this, there is a switch for every device wherein the users can mount the storage device they want to use. The design has a switching capability to choose what device is mounted.

The major components of this design are the SD card slots and USB flash drive slot wherein the user can insert a storage device. The design has a micro SD card sniffer so that the phone can access the storage inserted through this micro SD card sniffer. Switching components are used to access just one USB flash drive or either one of the memory cards at a time, because phones have a limited capability to read simultaneously storage devices.



## II. SINGLE FILE COPY SPEED TEST

The purpose of this is to test if the device is capable of responding efficiently with the file management features of the mobile phone, specifically the COPY function of the mobile device. Furthermore, the accuracy of a file when being transferred from all of the three flash memory devices to the corresponding memory of the phone is being tested. As indicated in the scope of this study, the mobile phone model to be used for this purpose is the Nokia C3. The sizes of the SD Memory Card, mini SD Memory Card and USB Flash Drive are tested based on the memory size supported by most mobile phone switch is 4 GB of memory. Another purpose of this test is to determine the causes of errors and data loss in transferring a file, if there are any. After this test, the functionality of the device and how successful a single file is transferred without data loss can be determined. The transfer speed of each file is also measured and observed after this test.

These are the procedures to be followed in conducting the test:

1. The COPY function of the mobile phone will be used to duplicate a file from the given SD memory cards and USB flash drive or vice versa.

2. For each memory type, the maximum memory capacities of the three flash memories in accordance with the design's delimitation will be used. For both SD memory card and mini SD memory card, 4 GB memory size will be used; and for USB flash drive, 8 GB memory size will also be used.

3. The file sizes that will be used for testing are 1 MB and 10 MB whose file types/extensions to be used are .jpg (picture file) and .mp4 (video file) respectively. Note that these files are supported by the test phone. Separate tables will be provided for each file size.

4. Thirty trials will be made to test and observe the consistency of the file transfer speed.

5. To make sure that the data transferred is correct and is the same file from the source, a prompt should be displayed on the mobile phone indicating that the file has been successfully transmitted. Moreover, the file that has been transferred should be similar to the source file being copied from in terms of their size in bytes. If the mobile phone supports the file format of the file being transferred (e.g., music, documents, pictures), then it should be opened successfully in the mobile phone. On the other hand, a corrupted icon or image is displayed by the mobile phone if it is not successful at all.

6. The results to be displayed in the tables are the transfer speed of the file in seconds out of 30 trials made. A timer is used to measure the transfer speed of the file copied from the flash memory to the phone memory in seconds. The average transfer speed computed from the results of the 30 trials is displayed at another table.

7. The REMARKS column is intended for the instance of having successful or unsuccessful file transfers during the actual process, and if the files are successfully copied only from the external memory to the mobile phone, the other way around, or both.

Based on the results gathered in Tables 4.1 and 4.2, the file copy test is successful for the mobile phone model Nokia C3 to and from SD memory cards and USB flash drives. It can be implied that the device is capable of copying files of different types and sizes such as 1 MB and 10 MB. The transfer speed is also measured and was observed to be close to each other.

With regards to the transfer speed of the files copied from the USB flash drive or SD memory card to the mobile phone, it was observed that the average transfer rate of the flash memories with respect to the prototype. The actual transfer speed of the Mini SD Card was lower than the SD Memory card because the Mini SD card is connected to another adaptor which implies an additional data rate going to the destination. Nevertheless, since the standard deviation was smaller than half of the average for all the three flash memories, the results are said to be consistent which makes device functional and reliable with regards to the file transfer speed value.

The transfer speed for the USB flash drive to the mobile phone is lower than the transfer speed of SD memory card and Mini SD memory card. This is due to the technology of the USB flash drive compared to memory cards which has larger power dissipation for data transfer.

During the testing process, other file management features of the mobile phone such as the delete and move options were tested. Therefore it can also be implied that the file management is successfully operated with the device.

## III. CONCLUSIONS

The design solution can be able to help in the economic growth when given a chance to develop more about the device and become a product wherein the manufacturing section can aid employment to the people. The device is also environmental-friendly because no harmful components were used in the hardware implementation process, which in turn yields to a good health and safety environment and people. Although the device has a little problem with its manufacturing capability because some of the major components are not yet available in the vicinity, its sustainability is not questionable and it can be offered in the future where technology is much advance. The device has a big impact on the social welfare as it is intended not just to a single person but to all who need it.

Based on the objectives of the design and the results of test performed the following observations and conclusions can be made.

The general conclusion is that file integrity is preserved upon copying/moving between the mobile phone and the device, which hosts the Secure Digital (SD) card, miniSD card and the USB flash disk.

The following are the specific conclusions:

1. Developing a design that can transfer data on variety of media affords a lot of convenience and flexibility.
2. Specific lines of circuit are activated for each switch selected, thereby saving power.

3. The mobile phone provides the power for the USB flash drive and memory card slots while the relays are for the selection of lines in the circuit to be activated.

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