XYRectify tip sheet

This tip sheet was prepared for users with a working knowledge of the iWitness[™] close-range photogrammetry software system

The purpose of this tip sheet is to provide the basic understanding of using XYRectify and to present an accurate means of scaling the XYRectify (rectified JPEG image) using a CAD diagramming software.

For this procedure, it is assumed the user has basic familiarity with the **XYRectify** software. If not, please refer to the XYRectify User Manual. We will also use the CAD Zone *Quick Scene* diagramming software in combination with an originally shot oblique image that was later rectified using the XYRectify software.

Background

Rectification is the image processing technique whereby an image taken obliquely to a plane is converted to an equivalent 'normal' image of that same plane. An easy way to picture the rectification process is to consider the conversion of an oblique aerial image of the ground to a corresponding vertical image. This process, which requires the establishment of a minimum of four control points of known XY coordinates in the object plane, along with the marking of the four corresponding image points, is carried out using **XYRectify**. Following rectification, XY coordinates can be measured within XYRectify, or with the scale-homogeneous rectified image and a CAD diagramming program.

1. If it is at all possible, it is best to pre-calibrate the camera in *iWitness*, and use the focal length & other camera parameters as the calibration settings for *XYRectify*.

If the camera is NOT in the *XYRectify* Global Camera Database (see Figure 1), upon importing the image, Figure 2 is presented.

XYRect		
♪	This camera is not in the database. Camera details must be completed manually	
	(ОК	Figure 1

Camera parameters	\mathbf{X}
Timage dimensions are: 2304 pixels wide & 3456 pixels high	
The following three fields must have valid entry data	
Camera name for default	
Enter focal length in mm 26.000	
Enter the following data if known, otherwise leave as it is	
Size of image pixel (mm)	Camera Image
Principal point coordinates (mm) xp 0.0	
ур 0.0	
Radial lens distortion coefficients K1 0.0 K2 0.0	КЗ 0.0
Decentring distortion coefficients P1 0.000e+000 P2 0.000e+000	1
<u>C</u> ancel <u>O</u> K	Figu

2. In this instance, the focal length of 26mm is simply read in *XYRectify* from an image's EXIF header tag. If the Pixel size is not correct, the user should go to www.dpreview.com and select the Canon EOS 350D camera: http://www.dpreview.com/reviews/CanonEOS350D/page2.asp and determine the pixel size: In this case being: Sensor width 22.2mm / Max.Image width 3456 pixels = **.0064mm.**

In Figure 2, type **.0064** in the "Size of image pixel" field.

3. In Figure 3, note that **the camera was not calibrated**, so there's no correction for the DISTORTION Parameters (specifically K1). For most rectified measurements, K1 is important, but K2 and K3, as well as P1 and P2, are not absolutely necessary. If the camera has been calibrated, then it is best to click the "Apply corrections" box. The pixel size (mm) should be correct relative to the c(mm) focal length (as noted in Figure 2.) NOTE: it is always better to work with a camera that's been calibrated using *iWitness* to optimize accuracy for use in *XYRectify*.

Camera par	ameter	s			×			
Information Model: Ca	Model: Canon EOS DIGITAL REBEL XT							
Sensor spec	Sensor specifics Wide High							
Resolution (pixels):	2304		3456				
Pixel size (m	Pixel size (mm): 0.0064 0.0064							
-Focal length	and prin	icipal po	int -					
c (mm):	26.000)		·····				
xp (mm):	0.0000			<u>O</u> K				
yp (mm):	0.0000							
Distortions -								
K1: 0.000	0e+000	P1:	0.00	000e+000				
K2: 0.000	0e+000	P2:	0.00	000e+000				
K3: 0.000	0e+000	E A	pply	corrections				
						Figure 3		

4. At this stage the camera parameters are set up and the image will be imported. Double-click the image thumbnail to display it.

5. Control Points:

XYRectify requires a minimum of **4 control points** on a fairly planar surface and spread out (in this example a roadway intersection.) The control points are XY coordinates that need to be accurate. In this instance a total station was used to measure a quantity six XY coordinates; *but a total station is not the only means* of obtaining these XY coordinates, they could come from many different sources.

Create a Control Point file using MS Notepad. Type in the name of the control point, and then its X, and Y coordinates, separated by TABS. See Figure 4. Save the file in your working folder.

	- · · · · ·				
	D control - Not	epad			In our example "I wr BF" means
	File Edit Format	View Help			" <i>Lower Bulls-Eve</i> " as defined by
	Lwr_BE Center_BE Upper_BE Left_CL	22.9 26.8 31.25 -4.09	-122.55 -19.98 79.26 -30.03	•	the white X and the white circle in the rectified image.
	Right_CL Last_pt	57.66 266.68	-32.22 -41.28		Left_CL is the end of the double centerline on the left side (<i>note</i> :
Figure	2 4				the image is actually illustrated
					appears on the right side in the image marking process noted in Figure 7.)

6. Click on the **File + Import Control**... and open the newly created control points file.

P •						
A	XYRecti	i <mark>y - Untit</mark> le	e d			
File	Window	Help				
N	ew		Ctrl+	N		
0	pen		Ctrl+	0		
C	lose					
S	ave		Ctrl+	s		
S	ave As					
Ir	nport Imag	es				
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2 sample1						
3	result app	lied correctio	ins 4 cps			
4	result app	lied correctio	ins 4 cps			
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7. A "Control Points" thumbnail is presented in the thumbnails located to the left side of the screen (see Figure 10). Double-click it and the control points dialog will be presented, as in Figure 6.

Control Points					\mathbf{X}
Label	X	Y	VX	٧Y	<u>^</u>
LWR_BE	22.900	-122.550			
CENTER_BE	26.800	-19.980			
• UPPER_BE	31.250	79.260			
LEFT_CL	-4.090	-30.030			
RIGHT_CL	57.660	-32.220			
Projective Transform Transformation performation performation performation performation performation performance for the second p	nation prmed? N I CPs	IO RMS 0 (minir	num of 4)	
Full image Bounded by con	trol points + 10%	6	Create ; <u>C</u> los	Image se	J Figur

Click in the Label field with the "red plus" and it becomes a "yellow plus".

Mark the corresponding location of the control point in the image and it becomes a "green plus". See Figure 7.



Do this same action for the remaining (minimum of 4) control points.

Note in Figure 7 that the "**Rectified Image**" in the lower left of the dialog box displays two options, "Full Image" and "Bounded by control points". The default is "Full Image". The operator can choose to rectify either the entire original image (*full image*), or a portion of the original image (*bounded by control points* ...) equal to the area encompassed by the control points, plus a border area of approximately 10%. In this example, we are going to leave the tick mark on the default "**Full Image**".

Figure 8 illustrates all **6 Control Points Marked**, from the Control Points Dialog Box:



5. CIICK LITE	Create .	inaye in	rigure	9.	
Control Points					×
Label	X	Y	VX	٧Y	^
CENTER_BE	26.800	-19.980	-0.404	0.354	
UPPER_BE	31.250	79.260	-0.549	-0.080	
• LEFT_CL	-4.090	-30.030	0.663	-0.129	≣
RIGHT_CL	57.660	-32.220	1.051	-0.088	
LAST_PT	266.680	-41.280	-0.051	-0.051 -0.005	
Projective Transl	formation				
Transformation p	erformed?	YES	RMS	0.472	
Number of measu	ured CPs	(minimum	of 4)		
Rectified Image		Cre	ate <u>I</u> mage	\mathcal{D}	
bounded by	control points	Ŧ 10%			

8. Click the "Create Image" in Figure 9.

The **Save As** dialog will now be presented. Give the resulting *Projective Transformation Image* a new name; (we'll call it "crash".) Save it to your working folder.

The newly created rectified image we named "crash.jpg" is now planar rectified and an *image thumbnail* of it is presented above the Control thumbnail in Figure 10. Note: the rectified image "crash.jpg" is also saved to your working folder.



9. Output File from XYRectify:

The saved JPEG is accompanied by a 'tfw' or 'World file' which defines the XY reference coordinate system for the rectified image. The TFW (ASCII text file) is named the same name as your image; in this example case "crash.twf" located in your working folder.

The image can now be imported into your favorite CAD package.

The TFW File created during the XYRectify Process

After marking the control points in XYRectify, a TFW "world" file is automatically created and saved in the working folder. There are 6 lines of numbers that represent the TFW file. The TFW six line numbers look similar to this:

0.3190419410

0.000000000 0.000000000 -0.3190419410 -115.3208527345 204.8477400810

Explanation of the TFW line numbers

- LINE 1: The first line value represents the scale of any pixel in X.

- LINE 2: The second value represents the rotation in X.
- LINE 3: The third value represents the rotation in Y.

- LINE 4: The fourth value represents the scale of any pixel in Y (negative, because Y is 'flipped').

- LINE 5: The fifth value represents the X value of the top-left pixel.
- LINE 6: The sixth value represents the Y value of the top-left pixel.

Using this tip sheet all that is necessary for the reader to understand is that the <u>first</u> line of the TFW file represents the size of the pixel in the *Measured Units* of the 4+ Control Points measured within *XYRectify*.

Therefore, if one knows the size of the image format, one can simply calculate the UNIT size of the image format in width (X) or height (Y).

To acquire the **XYRectify JPEG image format in pixels**, simply right clicking on the JPEG image ("Summary" tab.) See Figure 11 below:

Figure 11	Properties	? 🗙
General Sumr	nary	
Property	Value	
Image		
🗋 Width	1232 pixels	
🗋 Height	1798 pixels 🚽	
🗋 🗋 Horizont	al Resolutio <mark>n i dpi</mark>	
🗋 Vertical I	Resolution 1 dpi	
Bit Depti	h 24	
	ount 1	
Descript	ion	
📝 Title		
Subject		
🛛 📝 Keyword	ts	
Commen	its	
Origin		
Author		
	<<	Simple
	OK Cancel	Apply

In our example, the pixel size reported in the TFW file is **0.3190419410**. The numbers of pixels in the image **width** is **1232** (Figure 11). Therefore, .3190419410 x 1232 (pixels) is 393.06. If the Units of Measurement from the Control Points was Feet, then the calculation means the *XYRectify* image is **393.06 feet in the overall width** of the image's format.

NOTE: Pixels are dimensionally square generated as part of the XYRectify process. For accurate CAD scaling, all that is required at this point, is to calculate either **the width of the pixels relative to the image format's width**, or conversely the pixels height relative to the image format height.

Using the Calculation for CAD Scaling

As previously noted, we are using Quick Scene by CAD Zone as the CAD diagramming program for this tip sheet. The Crash Zone as well as other CAD diagramming programs offer "image scaling" functionality.

Figure 12

In Quick Scene, use the File Pull down Menu and select "Import Images".

Fig	jure	12													
	6	Quic	k Sce	ene 4.	1 - [L	Inti	t le d	1]-	[E	valua	ating:	0 R	emai	ning	31
		File	Edit	Draw	View	Dra	wing	Aids	Wir	ndow	Help				
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Figure 13 illustrates the XYRectify (rectified image.)



Quick Scene: Click on the "Bitmap scale" icon (see Figure 14.)

Figure 15 Quick Scene will prompt you to select (i.e., click) on the image, followed by *carefully* clicking on the bottom left **and** right corners of the image (see figure 16). Note: this is the **image width** as described earlier.





In Figure 16, notice how after clicking on the corner of the image (see left arrow), Quick Scene places a **turquoise** color "marker" for the first Scale point. The cursor on the right is illustrated as 'pre-selecting' the second scale distance. Notice on the right, how the crosshair is perfectly indexed to the corner of the image. **Click it** to add the second **Scale Point**.

Figu	ure 17			
	Bitmap	Scale		\mathbf{X}
	Distance	Between Points:	257' 6.44''	
	Enter /	Actual Distance:	393.06	
		Adjust Bit	map Now	Close

In Figure 1	.7, type in t	he proper	image	width	distance	(in our	case it is
393.06'),	followed by	clicking "	Adjust	Bitmap	o Now".		

The *XYRectify* planar rectified image is now accurately scaled and ready to be "traced" and/or any of the planar surface entities can now be measured in the image within Quick Scene.