

Digital Controller Model: PXH

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Thank you for purchasing the Fuji Digital Controller.

Once you have confirmed that this is the product you ordered, please use it in accordance with the following instructions.

INP-TN1PXH-E

For detailed information on operating this equipment, please refer to the separate operations manual (User's manual) in the supplied CD-ROM.

In addition, please keep this instruction manual within easy reach of the actual person using this equipment.

CAUTION

The content of this manual is subject to change without notice.

The greatest care has been taken with the content of this manual to ensure accuracy; however, Fuji Electric Systems and Fuji Electric Instruments shall not be held liable for damages, including indirect damages, caused by typographical errors, absence of information or use of information in this manual.

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Confirming Specifications and Accessories

Before using the product, confirm that it matches the type ordered.

(For model code, please refer to page 39.)

Confirm that all of the following accessories are included.

| Digital Controller 1 unit Instruction Manual 1 copy | • CD-ROM1 pc (Contents) |
|---|--|
| Mounting fixture2 pcs | Instruction Manual |
| Watertight packing1 pc | User's Manual |
| Unit nameplate 1 pc | Communication Functions |
| • Terminating resistance*1 | Instruction Manual (Modbus) |
| 1 pc | Communication Sample Program |
| | Parameter Loader |
| | Instruction Manual |
| | Parameter Loader Software |
| | Digital Controller 1 unit Instruction Manual 1 copy Mounting fixture 2 pcs Watertight packing 1 pc Unit nameplate 1 pc Terminating resistance*1 1 pc |

*1) Supplied only when the communications function (RS485) is selected with this model.

Option

| Name | Order No. |
|-------------------------------|------------------|
| PC loader communication cable | ZZPPXH1*TK4H4563 |
| Terminal covers *2 | ZZPPXR1-B230 |

*2) Two covers are required per unit.

Related Information

Refer to the following reference materials for details about the items described in this manual.

| Content | Document | Reference Number |
|----------------------------|---|------------------|
| Specifications | Catalogue | ECNO: 1152 |
| Operation Method | User's Manual for Digital Controller (type: PXH) | INP-TN514206-E |
| Communication Functions | munication Communication Functions Instruction Manual (Modbus) for Inctions Digital Controller (type: PXH) | |
| Loader Functions | Parameter Loader Instruction Manual for Digital Controller (type: PXH) | INP-TN514208-E |

The latest materials can also be downloaded at the following URL: http://www.fic-net.co.jp/eng

Please read the section "Safety Warnings" thoroughly before using.

Please observe the warnings stated here as they contain important safety details. The safety warning items are divided into "WARNING" and "CAUTION" categories.

| Warning | Mishandling may lead to death or serious injury. |
|---------|--|
| Caution | Mishandling may cause injury to the user or property damage. |



1.1 Limitations in Use

This product was developed, designed and manufactured on the premise that it would be used for general machinery.

In particular, if this product is to be used for applications that require the utmost safety as described below, please take into consideration the safety of the entire system and the machine by adopting such means as a fail-safe design, a redundancy design as well as the conducting of periodical inspections.

- Safety devices for the purpose of protecting the human body
- Direct control of transportation equipment
- Airplanes
- Space equipment
- Atomic equipment, etc

Please do not use this product for applications which directly concern human lives.

1.2 Installation and Wiring

• This equipment is intended to be used under the following conditions.

| Ambient temperature | –10°C to 50°C | | |
|-----------------------|---------------|-----------------------------------|--|
| Ambient humidity | 90% RH | l or below (with no condensation) | |
| Installation category | | by IEC1010 1 | |
| Pollution level | 2 | by lectoro-1 | |

 Between the temperature sensor and the location where the voltage reaches the values described below, secure clearance space and creepage distance as shown in the table below.
 If such space cannot be secured, the EN61010 safety compliance may become invalid.

| Voltage used or generated | Clearance Space | Creepage Space | | |
|---------------------------|--------------------------------|----------------|---|-----------|
| by any assemblies | [mm] | [mm] | \ | I |
| Up to 50 Vrms or Vdc | 0.2 | 1.2 | 1 | |
| Up to 100 Vrms or Vdc | 0.2 | 1.4 | | hazardous |
| Up to 150 Vrms or Vdc | 0.5 | 1.6 | | voltage |
| Up to 300 Vrms or Vdc | 1.5 | 3.0 | | |
| Above 300 Vrms or Vdc | Please consult our distributor | | | , , |

 For the above, if voltage exceeds 50Vdc (called danger voltage), grounding and basic insulation for all terminals of the equipment and auxiliary insulation for warning outputs is required. Note that the insulation class for this equipment is as follows. Before installing, please confirm that the insulation class for equipment meets usage requirements.

| Power source | Internal Circuit |
|-----------------------------|---------------------------------|
| Digital output 1, 2 | PC Loader interface |
| | Measurement value input 1 (PV1) |
| Digital output 3 | Measurement value input 2 (PV2) |
| Digital output 4 | Auxiliary analog Input 1 (Ai1) |
| Digital output 11 to 15 | Output 1 (Current / SSR driver) |
| | Output 2 (Current) |
| Basic insulation (1500\/AC) | Digital input 1 to 4 |
| | Digital input 11 to 15 |
| | Transmitter power supply |
| No insulation | RS485 |

- In cases where damage or problems with this equipment may lead to serious accidents, install appropriate external protective circuits.
- As this equipment does not have a power switch or fuses, install them separately as necessary. (Main power switch: 2point Breaker, fuse rating: 250V 1A)
- For power supply wiring, use wire equal to 600V vinyl insulation or above.
- To prevent damage and failure of the equipment, provide the rated power voltage.
- To prevent shock and equipment failure, do not turn the power ON until all wiring is complete.
- Before feeding power, confirm that clearance space has been secured to prevent shock and fire with the equipment.
- Do not touch the terminal while the machine is on. Doing so risks shock or equipment errors.
- Never disassemble, convert, modify or repair this equipment. Doing so carries the risk of abnormal operation, shock and fire.

1.3 Maintenance

- When installing and removing the equipment, turn the power OFF. Failing to do so may cause shock operational errors or failures.
- Periodic maintenance is recommended for continuous and safe use of this equipment. Some components used on this equipment have a limited life and/or may deteriorate with age.
- The warranty period for this unit (including accessories) is one year, if the product is used properly.



2.1 Cautions when Installing

Please avoid installing in the following locations.

- Locations in which the ambient temperature falls outside the range of -10 to 50°C when equipment is in use. (If the power supply is AC200V, the recommended maximum ambient temperature is 45°C.)
- Locations in which the ambient humidity falls outside the range of 0 to 90% RH when equipment is in use
- Locations with rapid temperature changes, leading to dew condensation
- Locations with corrosive gases (especially sulfide gas, ammonia, etc.) or flammable gases
- Locations in contact with water, oil, chemicals, steam or hot water (If the equipment gets wet, there is a risk of electric shock or fire, so have it inspected by the distributor.)
- Locations with high concentrations of atmospheric dust, salt or iron particles
- Locations with large inductive interference, resulting in static electricity, magnetic fields or noise
- Locations in direct sunlight.
- Locations that build up heat from radiant heat sources, etc.

2.2 Cautions when Attaching the Panels

• Please attach the PXH with the included Fixtures (2 pieces) to the top and bottom, and tighten with a screwdriver.

The clamp torque is approximately 0.15 N·m (1.5 kg·cm)

It is designed such that overtightening will cause left/right cracking to the central area of the Fixtures and hence reduce the torque.

Cracking to the central area will not cause any problems in terms of usability of the equipment as is. (However, do exercise caution in not applying too much torque because the casing is made of plastic.)

- The front of this equipment is wateproof in compliance with NEMA-4X standards (IP66-equivalent). However, regarding waterproofing between the equipment and the panel, use the included packing to ensure waterproofing and attach it according to the guidelines below. (Incorrect attachment may cause the equipment to lose its waterproof capabilities.)
 - 1 As shown in Fig. 1, insert the panel after attaching the packing to the equipment case.
 - (2) As shown in Fig. 2, tighten the fixture screws so that no gaps can remain between the equipment face, the packing and the panels. Once finished, confirm that there are no changes in shape such as displaced or improperly-fitted packing, etc. as shown in Fig. 3.
- Please exercise caution if the panel strength is weak and gaps develop between the packing and the panel, as this will result in the loss of its waterproofing capabilities.

Mounting method



Standard: vertical attachment (horizontal position fixtures)

If attached at an angle, the maximum gradient is a 30° downslope.

(Caution)

- In order not to hamper heat dissipation, do not block the sides of the equipment.
- Do not block the air vents on the upper part of the terminal.
- For the PXH9, please attach the Fixtures to the attachment holes in the center of the main unit.

2.3 Cautions for Wire Connections

- Perform wiring beginning from the left-side terminals (No. 1 to No. 12).
- Do not connect anyting to the unused terminals. (Do not use them as relay terminals.)
- For thermocouple input, use the designated compensation lead; for resistance temperature sensors, use wires with small lead wire resistance and without any resistance difference among the three wires.
- To avoid noise conductor effects, do not use input signal wires in close proximity with electric power lines or load lines.
- Use input signal lines and output signal lines that are separated from each other and are shielded.
- If there is a lot of noise from the power source, adding an insulation transducer and using a noise filter is recommended.

(Example: TDK ZMB22R5-11 noise filter)

Always attach a noise filter to a panel that is grounded securely, and keep the wiring between the noise filter output side and the measuring equipment power terminal wiring to a minimum length. Please do not attach fuses and switches, etc. to the noise filter output wiring since doing so will decrease the filter's effectiveness.

- Twisting the measuring instrument wiring is effective when connecting the wires. (The shorter the pitch of the twist, the more effective the connection is against noise.)
- Operation preparation time is required for the contact output when power is turned on. If using it as a signal to an external interlock circuit, please couple it with a delayed relay.
- Concerning the output relay, connecting the maximum rated load will shorten the product's life; so please attach an auxiliary relay. If the output operation frequency is high, selecting a SSR/SSC drive output type is recommended.

[Proportionate cycles] Relay output: 30 seconds or more,

SSR/SSC drive output: 1 second or more

• When inductive loads such as magnetic opening/closing equipment, etc. as relay output equipment are connected, use of "Zetrap," manufactured by Fuji Device Technology, Co. Ltd., is recommended in order to protect the connection points against opening/closing surges and to ensure long-term use.

Model names : ENC241D-05A (For 100V power voltage)

ENC471D-05A (For 200V power voltage)

Attachment position : Please connect between the relay control output connection points. (Refer to Fig. 5.)

- If using a thermocouple input, make sure that an RCJ module is connected as shown in the diagram below. (If an RCJ module is not connected, the temperature measurement cannot function.) To use resistance bulb input instead of thermocouple input, remove RCJ module. Keep the removed RCJ module, and do not forget to mount it back when input is changed again.
- Take wiring resistance into consideration when using a Zener barrier.
- In applying mV voltage, do not remove the RCJ module.
- It is dangerous to make an SSR connection when the output is set at 4-20mA, because the output will be kept "ON" even when the MV display shows –5%. Make sure to confirm the setting and the wiring before making the SSR connection.
- When the transmitter power supply model is selected, the external wiring will be connected as Fig. 6.



2.4 Key Operation Cautions/Operations during Abnormality

- The alarm function does not work properly when an abnormality takes place unless the settings are made correctly. Always verify its setting before operation.
- If the input wiring breaks, the display will read UUUU. When replacing the sensor, always turn the power OFF.
- The PV display will read UUUU or LLLL when over range or under range during input. However, if the display limit is smaller than the over-range/under-range, the fixed number -19999 or 99999 will be displayed.

2.5 Others

- Please do not wipe the equipment with organic solvents such as alcohol or benzene, etc. If wiping is necessary, do so with a neutral cleaning agent.
- Do not use mobile phones near this instrument (within 50 cm). Otherwise a malfunction may result.
- Trouble may occur if the instrument is used near a radio, TV, or wireless device.

For Proper Usage

| <reference item=""></reference> | | <details></details> | |
|---------------------------------|---------------------------------------|--|--|
| | Model Designation Confirmation | • Please confirm that the model delivered matches your order. | |
| 1 | ↓ Installation / Mounting ↓ | External dimensions Panel cut dimensions How to install on the panel | |
| 2 | Wire Connection | Terminal connection diagram | |
| | \downarrow | 1 | |
| | Turn Power On | | |
| | | | |
| 3 | Usage (Read before using) | How to change the temperature setting values | |
| 4 | Display and Operation Methods | Basic method of operation | |
| 5 | Switching Parameters | List of parameters Table of input/output/alarm | |
| 6 | Digital Controller Function | codes | |
| | \downarrow | Set up input sensor and input | |
| 7 | Controller Set-up Procedure | range Control method selection | |
| | \downarrow | Control via auto-tuning | |
| | Operation | Automatic settings of parameters | |
| | | - | |
| 8 | When the display does not make sense. | Displays during abnormalities. | |
| | | - | |

Since about 15 minutes is needed until the unit becomes thermally stable, wait for 15 minutes or more after turning the power on before making measurements, etc.

* It takes about 7 seconds from power ON to establish a stable output.

1

Installation/mounting

External/Panel Cut Dimensions

(Unit: mm)



- Depending on the models, some terminals will remain unused (terminals 37 to 60). A terminal block should not be installed onto these unused terminals.
 (A dummy cover will be installed.)
- * Use a PC loader interface when using the parameter loader. An optional PC loader communication cable is required to use the parameter loader.
- Use wires and solderless terminals of the size shown below for connections.

|--|

| Parts | Size | |
|--|--------------------------------|--|
| Thermocouple (Compensating lead wire) | 1.25mm ² or smaller | |
| Wire | 1.25mm ² or smaller | |

Solderless terminal size

| Compatible wire size | Fastening torque |
|-----------------------------|------------------|
| 0.25 to 1.25mm ² | 0.8N•m |





Round solderless terminal

Y-type solderless terminal

Connection using terminal cover

• Connect 2 wires of 1.25mm² or smaller in size together to the same terminal as shown below.



Wiring Connection

Terminal Connection Diagram

2



3 Usage (Read before using)

Operating parts and their functions



Operation Part

| Name | Function |
|--|--|
| ① F1 key | Assignable by the user. |
| ② F2 key | Assignable by the user. |
| ③ F3 key | Assignable by the user. |
| ④ A/M key (AUTO/MANUAL switch key) | Switches between AUTO mode and MANUAL mode |
| (5) DISP key (switch display key) | Switches display between the set value (SV) / control output (MV). |
| | Press the key to return from the setting mode to the operation mode (operation screen). |
| 6 SEL key | For parameter block selection, parameter selection, and |
| (Select key) | parameter setting change. |
| ⑦ ▶ key (Digit selection key) | Select a digit of data value for a desired setting change. |
| ⑧ ▲ key | Increases the data value of a desired setting change. |
| (Up key) | Changes the value of a set value (SV) when in operation. Used to select channels and parameters and change parameter settings in the setting mode. |
| ⑨ ▼ key (Down key) | Decreases the data value of a desired setting change. Changes the value of a set value (SV) when in operation. Used to select channels and parameters and change the parameter setting in the setting mode. |

* During the electrical current output, the lamp will not light.



Display

| Name | Function |
|---|---|
| STBY Lamp | Lamp lights when in standby mode. |
| 1 R Lamp | Lamp lights when in REMOTE mode. |
| 1 A Lamp | Lamp lights when in AUTO mode. |
| 13 M Lamp | Lamp lights when in MANUAL mode. |
| 🕼 C1 Lamp | Lamp lights when control output 1 is ON. * |
| 🚯 C2 Lamp | Lamp lights when control output 2 is ON. * |
| 16 DO1 Lamp | Lamp lights when digital output 1 to output 4 (DO1 to |
| DO2 Lamp | DO4) is on. |
| DO3 Lamp | The lamp functions are assignable by the user. |
| DO4 Lamp | |
| DO5 Lamp | Do5: None |
| 1 ALM Lamp | Lamp lights when alarm is activated. |
| (19) SV / MV Lamp | Indicates the status shown in the sub-segment display. SV : Set value |
| | MV : Control output value |
| (9) Measurement value (PV) display (red) | Displays the measurement value (PV) during operation. Also displays the parameter name when setting parameters. |
| ② Set value (SV) | Displays the set values (SV) or control output value (MV) |
| display (orange) or | during operation. |
| Output value (MV) | |
| display (orange) | During exerction $(M/har TD) T (abs. 02) is set at 10, 12$ |
| display | burning operation : when TPLT (cn8-92) is set at 10, 13, |
| uispiay | When TPLT ($ch8_02$) is set at 11, 14 |
| | the SV number is displayed |
| 2 Bar graph display | Setting parameters · Parameter number is displayed |
| | Displays a bar graph of control output (MV) during operation. |

Displays and Operation Methods

4



5

Switching parameters



Ch1 oPE (Operation parameter)

| | | Parameter | | Content Explanation | Factory | Parameter | Notes |
|-----|---------------|-----------|----------------------------------|---|---------|-----------|---|
| No. | Display | Symbol | Name | | default | mask | 10103 |
| 1 | <i>-</i> 2111 | rEM1 | Remote mode | Switches setting between remote/auto mode operation. REM: Remote mode AUT: Auto mode | AUT | 01-1 | |
| 5 | SF63 | STbY | Standby command | Switches controller to RUN/Standby. ON: Control standby (output OFF, alarm OFF) OFF: Control RUN | OFF | 01-5 | Refer to Table 7. |
| 7 | Rſ | AT | Auto-tuning command | Sets auto-tuning. OFF: non action ON1: start auto-tuning. | OFF | 01-7 | |
| 8 | L8Ch | LACh | Alarm latch cancel command | Disables alarm 1 - 8 latch. OFF: Stopped CLR: Latch clear | OFF | 01-8 | |
| 9 | PLſn | PLTn | Palette selection | Selects a PID palette to be used to control (Setting range: 0 to 7) | 0 | 01-10 | |
| 10 | AL I | AL1 | Alarm settings 1 | Alarm 1 operation value setting. Setting possible within the input range | 10%FS | 02-1 | Displayed when alarm operation type 1TP (chA-1) is set to 1 to 11. (See table 1.) |
| 11 | R I-L | A1-L | Alarm lower limit settings 1 | Alarm 1 lower limit operation value setting. Setting possible within the input range | 10%FS | 02-1 | Displayed when alarm operation type 1TP (chA-1) is set to 16 to 31. (See table 1.) |
| 12 | R I-h | A1-h | Alarm upper limit settings 1 | Alarm 1 upper limit operation value setting. Setting possible within the input range | 10%FS | 02-1 | Displayed when alarm operation type 1TP (chA-1) is set to 16 to 31. (See table 1.) |
| S | | | | | | | |
| 31 | AL 8 | AL8 | Alarm settings 8 | Alarm 8 operation value setting. Setting possible within the input range | 10%FS | 02-8 | Displayed when alarm operation type 8TP (chA-36) is set to 1 to 11. (See table 1.) |
| 32 | 88-L | A8-L | Alarm lower limit settings 8 | Alarm 8 lower limit operation value setting. Setting possible within the input range | 10%FS | 02-8 | Displayed when alarm operation type 8TP (chA-36) is set to 16 to 31. (See table 1.) |
| 33 | 88-h | A8-h | Alarm upper limit settings 8 | Alarm 8 upper limit operation value setting. Setting possible within the input range | 10%FS | 02-8 | Displayed when alarm operation type 8TP (chA-36) is set to 16 to 31. (See table 1.) |
| 34 | Loĺ | LoC | Keylock | Selects parameter lock type (Setting range: 0 to 5) | 0 | 01-11 | |
| | | | | Key operation Communication | | | |
| | | | | No. All Parm. SV/MV All Parm. SV/MV | | | |
| | | | | | | | |
| | | | | 2 X 0 0 0 | | | |
| | | | | 3 O O X X | | | |
| | | | | | | | |
| | | | | O: Can be set X: Cannot be set | | | |

Ch2 P_d (Control parameter)

| | Parameter | | | Orantant Fundametian | Factory | Parameter | Natas |
|-----|-----------------|--------|--|--|---|-----------|---|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 1 | P | P1 | Proportional band | Setting range: 0.0 to 999.9% ON/OFF control at setting = 0. | 5.0 | 03-1 | |
| 2 | <u> </u> | i1 | Integral time | Setting range: 0.0 to 3200.0 seconds Integral control OFF at setting = 0. | 240.0 | 03-1 | |
| 3 | d / | d1 | Derivative time | Setting range: 0.0 to 999.9 seconds Derivative control OFF at setting = 0. | 60.0 | 03-1 | |
| 5 | 8rh 1 | Arh1 | Anti - reset windup Upper limit setting value | Integration cut point upper limit setting value (Setting range: 0 to 100%FS) | 100%FS | 03-3 | Sets by devia- tion from SV. |
| 6 | 8-L I | ArL1 | Anti - reset windup Lower limit setting value | Integration cut point lower limit setting value (Setting range: 0 to 100%FS) | 100%FS | 03-3 | Sets by devia- tion from SV. |
| 7 | 551 | Sh1 | SV value upper limit | Sets upper limit SV (Setting range: -25 to 125%FS) | 100%FS | 03-4 | |
| 8 | SL I | SL1 | SV value lower limit | Sets lower limit SV (Setting range: -25 to 125%FS) | 0%FS | 03-4 | |
| 9 | ពភ្នក រ | Mvh1 | MV value upper limit | Sets upper limit MV (Setting range: -25.0 to 125.0%FS) | 105.0 | 03-5 | |
| 10 | nal i | MvL1 | MV value lower limit | Sets lower limit MV (Setting range: -25.0 to 125.0%FS) | -5.0 | 03-5 | |
| 13 | - 4N <u>0</u> 1 | dMv1 | MV change ratio limit | Sets the limit value of deviation of MV (DMV) in one control cycle (50ms.) (Setting range: 0.0 to 150.0%) 0.0: No limit | 0.0% | 03-7 | Limit is not applied to the deviation of MV by EX-MV operation. |
| 14 | ብር I | dT1 | Sampling cycle | Sets sampling cycle for PID operation. (Setting range: 5 to 1000) | 5 | 03-8 | The actual cycle is (Set value \times 10) ms. |
| 15 | h5 / | hS1 | Hysteresis setting | Hysteresis value during ON/OFF control time. (Setting range: 0 to 50%FS) | 0.3%FS | 03-9 | |
| 18 | 6AL 1 | bAL1 | Operation output convergence value | Sets output convergence value (Setting range: -100.0 to 100.0%) | 0.0% | 03-12 | |
| 19 | ΓΕΙ | TC1 | Cycle time of Control output (MV1) | Sets proportional cycle for control output. (Setting range: 1 to 150 sec) | By designation at the time of ordering | 03-13 | Effective only for RY output and SSR drive output |
| 20 | rEūl | rE∨1 | Control operation setting | Sets a control operation method. NRML: Normal operation REV: Reverse operation | REV | 03-14 | |
| 22 | ו החפ | PMv1 | Preset value for control output | Sets MV for stanby. (Setting range: -25.0 to 125.0%) | 0.0 | 03-16 | Refer to Table 7. |
| 23 | ALP I | ALP1 | Alpha | Sets 2 degrees of freedom coefficient α . (Setting range: -300.0 to 300.0%) | 100.0 | 40-1 | |
| 24 | ьег і | bET1 | Beta | Sets 2 degrees of freedom coefficient β . (Setting range: 0.0 to 999.9%) | 0.0 | 40-1 | |
| 97 | <u> </u> | EXM1 | External control amount | Sets external output value. (Setting range: -25.0 to 125.0%) | 0.0 | 07-1 | |
| 99 | 2F / | kF1 | FF gain | Sets Feed Forward gain and bias 1, bias 2. | 0.0 | 40-2 | |
| A0 | Ь IF I | b1F1 | FF bias1 | [FF = KF1 × (Input – B1F) + B2F] (Setting range: –1000.0 to 1000.0) | 0.0 | 40-2 | |
| A1 | 62F I | b2F1 | FF bias2 | | 0.0 | 40-2 | |

Ch3 PLF (Control palette)

| | Parameter | | | | Factory | Parameter | Notos |
|-----|----------------|--------|---|--|---------|-----------|-------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 1 | Sũ I | Sv1 | Setting value 1 | palette 1 SV (Setting range: SV lower limit value to SV upper limit value) | 0%FS | 08-1 | |
| 2 | P- (| P-1 | Proportional band 1 | palette 1 proportional band (Setting range: 0.0 to 999.9%) ON/OFF control at setting = 0. | 5.0 | 08-1 | |
| 3 | [- | i-1 | Integral time 1 | palette 1 integral time (Setting range: 0.0 to 3200.0 sec) Integral control OFF at setting = 0. | 240.0 | 08-1 | |
| 4 | d- | d-1 | Derivative time 1 | palette 1 derivative time (Setting range: 0.0 to 999.9 sec) Derivative control OFF at setting = 0. | 60.0 | 08-1 | |
| 6 | 8rh | Arh1 | Anti - reset windup upper limit value 1 | palette 1 Anti - reset windup upper limit value setting. (Setting range: 0 to 100%FS) | 100%FS | 08-1 | |
| 7 | Rrt I | ArL1 | Anti - reset windup lower limit value 1 | palette 1 Anti - reset windup lower limit value setting. (Setting range: 0 to 100%FS) | 100%FS | 08-1 | |
| 8 | 445 I | hYS1 | Hysteresis setting 1 | palette 1 hysteresis setting (Setting range: 0 to 50%FS) | 0.3%FS | 08-1 | |
| 11 | 6L - 1 | bL-1 | Output conver- gence value 1 | palette 1 Output convergence value (Setting range: -100.0 to 100.0%) | 0.0% | 08-1 | |
| S | | | | | | | |
| 67 | 557 | Sv7 | Setting value 7 | palette 7 SV (Setting range: SV lower limit value to SV upper limit value) | 0%FS | 14-1 | |
| 68 | ר-9 | P-7 | Proportional band 7 | palette 7 proportional band (Setting range: 0.0 to 999.9%) ON/OFF control at setting = 0. | 5.0 | 14-1 | |
| 69 | [-7 | i-7 | Integral time 7 | palette 7 integral time (Setting range: 0.0 to 3200.0 sec) Integral control OFF at setting = 0. | 240.0 | 14-1 | |
| 70 | d-7 | d-7 | Derivative time 7 | palette 7 derivative time (Setting range: 0.0 to 999.9 sec) Derivative control OFF at setting = 0. | 60.0 | 14-1 | |
| 72 | 8-67 | Arh7 | Anti - reset windup upper limit value 7 | palette 7 Anti - reset windup upper limit value setting. (Setting range: 0 to 100%FS) | 100%FS | 14-1 | |
| 73 | Rrl7 | ArL7 | Anti - reset windup lower limit value 7 | palette 7 Anti - reset windup lower limit value setting. (Setting range: 0 to 100%FS) | 100%FS | 14-1 | |
| 74 | hy57 | hYS7 | Hysteresis setting 7 | palette 7 hysteresis setting (Setting range: 0 to 50%FS) | 0.3%FS | 14-1 | |
| 77 | <i>Б</i> Г - 7 | bL-7 | Output conver- gence value 7 | palette 7 Output convergence value (Setting range: -100.0 to 100.0%) | 0.0% | 14-1 | |
| 78 | rEF I | rEF1 | PID switch point 1 | palette 1 PID switch point (Setting range: -25 to 125%FS) | 0%FS | 08-1 | |
| S | | | | | | | |
| 84 | r 8 F 7 | rEF7 | PID switch point 7 | palette 7 PID switch point (Setting range: -25 to 125%FS) | 0%FS | 14-1 | |

Ch7 fign (Monitor)

| | _ | Parameter | | | Factory | Parameter | Nutri |
|-----|---------------|-----------|-------------------------------|---|---------|-----------|---|
| No. | Display | Symbol | Name | Content Explanation | default | mask | INOTES |
| 1 | ا ت٩ | Pv1 | PV1 monitor | Displays Process value 1 input. | - | 17-1 | Reading of the signal input to |
| 2 | P52 | Pv2 | PV2 monitor | Displays Process value 2 input. | - | 17-2 | the terminal |
| 4 | 821 | Ai1 | AI1 monitor | Displays Analog input 1 input. | - | 17-5 | (before input correction) |
| 6 | r Sū I | rSv1 | RSV1 monitor | Displays REMOTE set value 1 temperature. | - | 17-9 | Control RSV value (after input correction) |
| 10 | LSū I | LSV1 | Local SV1 monitor | Display Local set value 1 | - | 17-9 | |
| 14 | r[]l | RCJ1 | RCJ1 monitor | Displays RCJ1 input. | - | 17-1 | |
| 15 | r []2 | RCJ2 | RCJ2 monitor | Displays RCJ2 input. | - | 17-2 | |
| 17 | Ro I | Ao1 | AO1 monitor | Displays Analog output 1 output value. | - | 18-1 | |
| 18 | 802 | Ao2 | AO2 monitor | Displays Analog output 2 output value. | - | 18-1 | |
| 21 | d <u>:</u> 01 | Di01 | DI monitor 1 | Displays DI1 to 4 status. | - | 19-1 | |
| 22 | dī | Di11 | DI monitor 2 | Displays DI11 to 15 status. DI15 DI15 DI14 DI13 DI12 DI11 | _ | 19-1 | |
| 24 | do0 | DO01 | DO monitor 1 | Displays DO1 to 4 status. | - | 19-1 | |
| 25 | do 11 | DO11 | DO monitor 2 | Displays DO11 to 15 status. DO15 DO14 DO13 DO12 DO11 DO11 | - | 19-1 | |
| 27 | 820 | AiM | Calculation result monitor | Displays user's calculation result. | - | 19-3 | |
| 28 | רח | TM1 | | | | 34-1 | |
| 29 | רחצ | TM2 | | | | 34-2 | |
| 30 | רח3 | TM3 | | | | 34-3 | The alterna |
| 31 | רחץ | TM4 | Alarm delay | Displays the remaining time for the alarm | - | 34-4 | i ne aiarm |
| 32 | rns | TM5 | remaining time | delay of ALM1 to ALM8. | | 34-5 | select the unit. |
| 33 | กกรี | TM6 | monitor | | | 34-6 | |
| 34 | רחז | TM7 | | | | 34-7 | |
| 35 | rna | TM8 | | | | 34-8 | |
| 36 | 80 | AMV1 | EXMV value | Displays the value to be output as EXMV. | - | 17-9 | |
| 40 | FFJI | FFV1 | Feed Forward | Displays the value of Feed Forward | - | 17-9 | |
| | | | value | element. | | | |

Ch8 5E7 (Input/output definition)

| | | Parameter | | | Factory | Parameter | Natas |
|-----|---------------|-----------|--------------------------------------|--|------------|-----------|-----------------------------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 1 | Pũ IF | Pv1F | PV1 full-scale | Sets the full-side scale of PV1 input. (Setting range: –19999 to 99999) | As ordered | 20-1 | For details see Table 3. |
| 2 | Р <i></i> 16 | Pv1b | PV1 base scale | Sets the base-side scale of PV1 input. (Setting range: –19999 to 99999) | As ordered | 20-1 | For details see Table 3. |
| 3 | Pū Id | Pv1d | PV1 decimal point position | Specifies the decimal point position of PV1 input. (Setting range: 0 to 3) | 1 | 20-1 | |
| | | | | 3 : A 2 : 1 : 0 : No decimal point | | | |
| 4 | ٢٥ ا | Pv1T | PV1 input type | Sets the type of PV1 input. (Setting range: 0 to 27) | As ordered | 20-1 | For details see Table 2. |
| 5 | PJ IU | Pv1U | Unit | Sets the measurement unit. non : No unit °F : °F unit °C : °C unit | As ordered | 20-2 | |
| 6 | רי הר | Pv1Z | PV1 input zero point adjustment | Sets the correction value of a zero point for PV1 input. (Setting range: -50 to 50%FS) | 0%FS | 20-3 | |
| 7 | <i>P</i> ت ا5 | Pv1S | PV1 input span point adjustment | Sets the correction value of a span point for PV1 input. (Setting range: -50 to 50%FS) | 0%FS | 20-3 | |
| 11 | P I[U | P1CU | PV1 input rooter cut point | Sets the cut point of square-root extraction calculation for PV1 input. In case of OFF, the square-root extraction is not calculated. (Setting range: OFF, 0.0 to 125.0%) | OFF | 20-7 | |
| 12 | ף ורר | P1TF | Time constant of PV1 input filter | Sets the constant during filter for PV1 input. (Setting range: 0.0 to 900.0 sec) | 0.0 | 20-8 | |
| 14 | PJ2F | Pv2F | PV2 full-scale | Sets the full-side scale of PV2 input. (Setting range: –19999 to 99999) | As ordered | 20-1 | For details see Table 3. |
| 15 | PJ26 | Pv2b | PV2 base scale | Sets the base-side scale of PV2 input. (Setting range: –19999 to 99999) | As ordered | 20-1 | For details see Table 3. |
| 16 | <i>P</i> ū2d | Pv2d | PV2 decimal point position | Specifies the decimal point position of PV2 input. (Setting range: 0 to 3) | 1 | 20-1 | |
| | | | | 1 : 0 : No decimal point | | | |
| 17 | PG2F | Pv2T | PV2 input type | Sets the type of PV2 input. (Setting range: 0 to 27) | 3 | 20-1 | For details see Table 2. |
| 18 | <i>Pū</i> 2U | Pv2U | Unit | Sets the measurement unit for PV2 input. non : No unit °F : °F unit °C : °C unit | °C | 20-2 | |
| 19 | P522 | Pv2Z | PV2 input zero point adjustment | Sets the correction value of a zero point for PV2 input. (Setting range: -50 to 50%FS) | 0%FS | 20-3 | |
| 20 | <i>Pū2</i> S | Pv2S | PV2 input span point adjustment | Sets the correction value of a span point for PV2 input. (Setting range: -50 to 50%FS) | 0%FS | 20-3 | |
| 24 | P2CU | P2CU | PV2 input rooter cut point | Sets the cut point of square-root extraction calculation for PV2 input. In case of OFF, the square-root extraction is not calculated. (Setting range: OFF, 0.0 to 125.0%) | OFF | 20-7 | |
| 25 | <i>P2</i> FF | P2TF | Time constant of PV2 input filter | Sets the constant during filter for PV2 input. (Setting range: 0.0 to 900.0 sec) | 0.0 | 20-8 | |

Ch8 5EF (Input/output definition)

| | | Parameter | | Content Explanation | Factory | Parameter | Notes |
|-----|---|-----------|--------------------------------------|--|------------|-----------|--|
| No. | Display | Symbol | Name | | default | mask | |
| 40 | | Ai1F | Ai1 full scale | Sets the full-side scale of analog (Ai1) input. (Setting range: –19999 to 99999) | As ordered | 23-1 | |
| 41 | RE 16 | Ai1b | Ai1 base scale | Sets the scale of base-side analog (Ai1) input. (Setting range: -19999 to 99999) | As ordered | 23-1 | |
| 42 | AC 19 | Ai1d | Ai1 decimal point position | Specifies the decimal point position for analog (Ai1) input. (Setting range: 0 to 3) 3: 2: 1: 0: No decimal point | 1 | 23-1 | |
| 43 | 80 IF | Ai1T | Ai1 input type | Sets the type of Ai1 input. (Setting range: 16 to 18) | 16 | 23-1 | For details see Table 2. |
| 45 | אנ וצ | Ai1Z | Ai1 input zero point adjustment | Sets the correction value of a zero point for Ai1 input. (Setting range: -50 to 50%FS) | 0%FS | 23-3 | |
| 46 | 8C IS | Ai1S | Ai1 input span point adjustment | Sets the correction value of a span point for Ai1 input. (Setting range: -50 to 50%FS) | 0%FS | 23-3 | |
| 49 | R ICU | A1CU | Ai1 input rooter cut point | Sets the cut point of the square-root extraction calculation for Ai1 input. In case of OFF, the square-root extraction is not calculated. (Setting range: OFF, 0.0 to 125.0%) | OFF | 23-7 | |
| 50 | 8 IF F | A1TF | Time constant of Ai1 input filter | Sets the constant during filter for Ai1 input. (Setting range: 0.0 to 900.0sec) | 0.0 | 23-8 | |
| 64 | Ro IF | Ao1T | AO1 output type | Switches the AO1 (re-transmission output) signal. Setting range: PV, SV, MV, DV, AiM, S1, S2, S3 | PV | 25-1 | It is invalid when the control output is chosen. |
| 66 | Ro Ih | Ao1h | AO1 output scale upper limit | Sets the scale upper limit value of the AO1 output. (Setting range: -130.0 to 130.0%) | 100.0% | 25-1 | |
| 67 | Ro IL | Ao1L | AO1 output scale lower limit | Sets the scale lower limit value of the AO1 output. (Setting range: -130.0 to 130.0%) | 0.0% | 25-1 | |
| 68 | <i>ន </i> | A1Lh | AO1 output limit upper limit | Sets the upper limt value of the AO1 output limit. (Setting range: -25.0 to 105.0%) | 105.0% | 25-1 | |
| 69 | A ILL | A1LL | AO1 output limit lower limit | Sets the lower limt value of the AO1 output limit. (Setting range: -25.0 to 105.0%) | -5.0% | 25-1 | |
| 70 | 802C | Ao2T | AO2 output type | Switches the AO2 (re-transmission output) signal. Setting range: PV, SV, MV, DV, AiM, S1, S2, S3 | PV | 25-2 | It is invalid when the XPS is attached. |
| 72 | RoZh | Ao2h | AO2 output scale upper limit | Sets the scale upper limit value of the AO2 output. (Setting range: -130.0 to 130.0%) | 100.0% | 25-2 | |
| 73 | 8021 | Ao2L | AO2 output scale lower limit | Sets the scale lower limit value of the AO2 output. (Setting range: -130.0 to 130.0%) | 0.0% | 25-2 | |
| 74 | 8217 | A2Lh | AO2 output limit upper limit | Sets the upper limt value of the AO2 output limit. (Setting range: -25.0 to 105.0%) | 105.0% | 25-2 | |
| 75 | 8211 | A2LL | AO2 output limit lower limit | Sets the lower limt value of the AO2 output limit. (Setting range: -25.0 to 105.0%) | -5.0% | 25-2 | |

Ch8 5EF (Input/output definition)

| | | Parameter | - | Operational Eventeen atting | Factory | Parameter | Natas |
|---------------|---------------------|-------------------|-----------------------------------|---|------------|-----------|-----------------------------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 88 | CALC | CALC | Calculation | Selects the calculation type. (Setting range: 0 to 11) | 0 | 25-9 | For details see Table 9. |
| 89 | UCFI | UCF1 | UCAL full scale | Sets the scale on the full side which is utilized for mathematical calculations. (Setting range: –19999 to 99999) | As ordered | 25-9 | |
| 90 | ИСЬ І | UCb1 | UCAL base scale | Sets the scale on the base side which is utilized for mathematical calculations. (Setting range: –19999 to 99999) | As ordered | 25-9 | |
| 91 | 1631 | UCD1 | UCAL decimal point position | Sets the decimal point position for mathematical calculations. (Setting range: 0 to 3) | 1 | 25-9 | |
| 92 | <i>FPLF</i> | TPLT | Template | Specifies the template. The range of effective setting. 10 : Single-loop basic PID control (with Math function) 11 : Single-loop SV selection PID control (with Math function) 13 : Single-loop basic PID control 14 : Single-loop SV selection PID control 16 : Single-loop input selection PID control (with Math function) Setup other than the above is forbidden. | 13 | 25-10 | |
| 93 | оГ УР | oTYP | Output type | Selects the control output selector type. (Setting range: 10 to 13) | As ordered | 25-11 | For details see Table 4. |
| 98 { b3 | En0 s En 16 | CN01 { CN16 | Constant 1 Constant 16 | Sets a constant value used for templates. The meaning of the value varies depending on template. Make the setting after checking the description of each template. (Setting range: -19999 to 99999) | 0 | 25-15 | |

Ch9 535 (Sysytem definition)

| | | Parameter | | Content Explanation | Factory | Parameter | Notes |
|---------------|--------------------|-------------------|---|---|--|-----------|-----------------------------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | notes |
| 1 | PRS (| PAS1 | Security setting 1 | Sets security (passwords). (Setting range: 0000 to FFFF) | 0000 | 26-1 | |
| 2 | PRS2 | PAS2 | Security setting 2 | Sets security (password). (Setting range: 0000 to FFFF) | 0000 | 26-2 | |
| 3 | P853 | PAS3 | Security setting 3 | Sets security (password). (Setting range: 0000 to FFFF) | 0000 | 26-3 | |
| 7 | rīh l | rih1 | Remote mode setting prevention | Prevents switching to the REMOTE mode. (Setting range: ON/OFF) | OFF | 27-1 | |
| 11 | r8[| rAC1 | R_ACK use selection | Selects use or non-use of R_ACK. (Setting range: INH, ENA) | INH | 27-5 | |
| 15 | 8-01 | A-M1 | A/M mode | Selects the A/M mode. (Setting range: A-M, A) | A-M | 27-9 | |
| 19 | [nd | Cnd1 | Mode settings when the power turns ON. | Sets the mode when the power turns ON. (Setting range: A, R, M) | A | 28-1 | |
| 23 | רדו | Trk1 | Tracking method selection (SV) | Selects ON or OFF for tracking the local set value (SV) | ON | 28-9 | |
| 30 | Srbo | STBo | Operation settings when in standby mode | Sets the front display operation in the standby mode. (Setting range: 0: lighting, 1: extinction) | 0 | 29-4 | For details see Table 7. |
| 31 | PLIS | PLTS | palette switching method selection | Selects a palette switching factor. (Setting range: PLTn, SV, PV) | PLTn | 29-6 | |
| 32 | F | F1 | User designation key-1 (F1) | | 0 | 29-7 | |
| 33 | 53 | F2 | User designation key-2 (F2) | Sets user assignments for function keys. [F1] - [F3]. (Setting range: 0 - 27) | 0 | 29-8 | For details see Table 8. |
| 34 | F3 | F3 | User designation key-3 (F3) | | 0 | 29-9 | |
| 35 | brd¦ | brd1 | Burn out direction specification (MV1) | Specifies the direction of the control output during a burnout. (Setting range: HOLD, LO, UP, EXMV) | Lo | 30-1 | |
| 39 5 42 | асо I , асоч | di01 〈 di04 | Assignment for digital input 1 S Assignment for digital input 4 | Sets assignments for DI1-DI4, DI11-DI15. | di01 : 60 di02 : 70 di03 : 0 di04 : 103 | 31-1 | For details see |
| 43 | dī | di11 | Assignment for digital input 11 | (Setting range: 0 - 255) | 0 | 31-2 | Table 5. |
| \ 47 | ہ میں 15 ایک | ر di15 | ک Assignment for digital input 15 | | | | |
| 53 | do l | do1 | Assignment for digital output 1 | | do1 : 1 do2 : 2 | 31-9 | |
| ∫ 56 | ् do4 | ہ do4 | ک Assignment for digital output 4 | Sets assignments for DO1-DO4, DO11-DO15. | do3 : 3 do4 : 4 | | For details see |
| 57 | do | do11 | Assignment for digital output 11 | (Setting range: 0 - 255) | 0 | 31-10 | I able 6. |
| { 61 | ر مە 15 | { do15 | ک Assignment for digital output 15 | | | | |

Ch9 535 (Sysytem definition)

| | | Parameter | | Content Evalenation | Factory | Parameter | Notoo |
|--------|---------|-----------|-----------------------|--|----------------------|--------------|-----------------------------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 67 | E / | C1 | LED C1 assignment | | 21 | 32-1 | |
| 68 | 53 | C2 | LED C2 assignment | | 22 | 32-2 | |
| 69 | Ldo I | Ldo1 | LED DO1 assignment | Allocates indicator LEDs. (Setting range: 0 to 255) | Ldo1 : 1 Ldo2 : 2 | 32-3 32-4 | For details see Table 6. |
| S | S | S | ہ LED DO5 | | Ldo3 : 3 Ldo4 : 4 | 32-5 32-6 | |
| 73 | LdoS | Ldo5 | assignment | | Ldo5 : 0 | 32-7 | |
| 74 | LALU | LALM | LED ALM assignment | | 17 | 32-8 | |
| 80 | d 5,00 | dS00 | Parameter | Skips (not display) unnecessary | | 0-1 | |
| \int | 2543 | { dS43 | mask setting | parameters. | - | { 0-15 | |
| E3 | r E S | rES | Reset command | Resets the main unit. ON : Reset OFF : Normal | OFF | 33-1 | |

ChA RL II (Alarm setting)

| | | Parameter | | Content Explanation | Factory | Parameter | Notes |
|-----|-------------|-----------|----------------------------------|---|---------|-----------|-----------------------------|
| No. | Display | Symbol | Name | | default | mask | 10103 |
| 1 | <i></i> | 1TP | Alarm 1 type setting | Sets the alarm type for alarm 1. (Setting range: 0 to 38) | 0 | 34-1 | For details see Table 1. |
| 2 | 10P | 10P | Alarm 1 option setting | Sets alarm options for alarm 1. (Setting range: 0000 to 1111) Switching unit time 0: OFF 0: seconds 1:minutes non-excitation output Unit abnormal Latch | 0000 | 34-1 | |
| 3 | IHYS | 1hYS | Alarm 1 hysteresis setting | Sets alarm hysteresis for alarm 1. (Setting range: 0.00 to 50.00%FS) | 0.3%FS | 34-1 | |
| 4 | IGT R | 1dLY | Alarm 1 delay time setting | Sets delay time for alarm 1. (Setting range: 0 to 9999) * Sets alarm options for time units. The unit of time is selected by alarm options. | 0 | 34-1 | |
| S | | | | | | | |
| 36 | 8r <i>P</i> | 8TP | Alarm 8 type setting | Sets the alarm type for alarm 8. (Setting range: 0 to 38) | 0 | 34-8 | |
| 37 | 8°b | 80P | Alarm 8 option setting | Sets alarm options for alarm 8. (Setting range: 0000 to 1111) Switching time unit 0: OFF 0: seconds 1:minutes non-excitation output Abnormal input Latch | 0000 | 34-8 | |
| 38 | 8772 | 8hYS | Alarm 8 hysteresis setting | Sets alarm hysteresis for alarm 8. (Setting range: 0.00 to 50.00%FS) | 0.3%FS | 34-8 | |
| 39 | 8 <i>4L</i> | 8dLY | Alarm 8 delay time setting | Sets delay time for alarm 8. (Setting range: 0 to 9999) * Sets alarm options for time units. The unit of time is selected by alarm options. | 0 | 34-8 | |

ChB [of (Communication)

| Parameter | | | | | Factory | Parameter | |
|-----------|---------|--------|-------------------------------------|--|---------|-----------|-------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 2 | 5ՐոႷ | STn4 | RS485 station No. | Specifies the RS485 communication station No. (Setting range: 0 to 255) * does not operate with STn4=0. | 1 | 36-2 | |
| 3 | SPd4 | SPd4 | RS485 communication speed | Selects the communication speed for RS485 communication. (Setting range) 96 : 9600 bps 192 : 19200 bps 384 : 38400 bps | 384 | 36-3 | |
| 4 | ЪСГЧ | biT4 | RS485 bit format | Selects the bit format for RS485 communication.(Setting range)Data lengthParity8n8None8o8Odd8E8Even | 80 | 36-4 | |
| 7 | SPd2 | SPd2 | PC Loader communication speed | Selects the communication speed for PC Loader communication. (Setting range) 96 : 9600 bps 192 : 19200 bps 384 : 38400 bps | 384 | 36-9 | |
| 8 | 6272 | biT2 | PC Loader bit format | Selects the bit format for PC Loadercommunication.Data lengthParity(Setting range)8n8None808Odd8E8Even | 80 | 36-10 | |

Note) Be sure to reset or turn on the power after the parameter setting is changed.

ChD [L[(Mathematical Calculation)

| Parameter | | | | | Factory | Parameter | N. / |
|--------------|-------------------|-----------------|---|---|---------|-------------------|------------------------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 1 5 16 | ٤0 / ک ٤ /6 | K01 { K16 | Constant for mathematical calculation | Sets the constant used for mathematical calculation | 0.0000 | 38-1 〈 38-4 | Floating-point setting |

ChE 8. (Tuning)

| Parameter | | | | | Factory | Parameter | Neter |
|-----------|---------|--------|---------------------|---|---------|-----------|-------|
| No. | Display | Symbol | Name | Content Explanation | default | mask | Notes |
| 1 | 869 1 | ATP1 | Auto tuning type | Specifies the auto-tuning method. (Setting range) NRML : Standard type AT LPV : Low PV type AT | NRML | 39-1 | |

Digital Controller Functions

Alarm functions 6-1

1) Alarm Types

6

• The alarm types are an absolute value alarm, a deviation alarm, an upper/lower limit alarm and a range alarm. (For details see [Table 1 Alarm Operation Type Codes])

2) Alarm function

| No. | Function Name | Function | Parameter set |
|-----|-------------------------------|--|--|
| 1 | Hysteresis function | Alarm operation can be set for operation dead band (hysteresis). | alarm 1: 1hYS (chA-3) 〈 alarm 8: 8hYS (chA-38) |
| 2 | ON delay function | After alarm ON conditions are established, the alarm is ON after the ON delay setting time. | alarm 1: 1dLY (chA-4) ر alarm 8: 8dLY (chA-39) |
| 3 | Alarm latch function | Alarm goes ON once, and alarm ON function status is maintained. To release the alarm latch, the following methods are used. | alarm 1: 1oP (chA-2) { alarm 8: 8oP (chA-37) |
| | | I) Turns power ON again on the controller. | |
| | | II) Turns alarm latch settings OFF once. | |
| | | III) Releases latch on the alarm latch release screen. | LACH (ch1-8) |
| | | IV) Executes release with DI input. | di01 (ch9-39) to di04 (ch9-42) |
| | | V) Executes release with communication. | |
| 4 | Abnormal alarm function | Sets alarm relay to ON when abnormality occurs in equipment. (For unit abnormalities, see the page on "Troubleshooting".) | alarm 1: 1oP (chA-2) { alarm 8: 8oP (chA-37) |
| 5 | De-energizing function | Transmits to the alarm relay by excitation/non-excitation of an alarm output. (When function is ON, output will be by non-excitation.) | alarm 1: 10P (chA-2) { alarm 8: 80P (chA-37) |

ON delay function



Caution When the power is off, even when the non-excitation function is ON, there will be no output during standby. (Function will be OFF.)

[Table 1] Alarm Operation Type Codes Parameter: 1TP (chA-1) to 8TP (chA-36)

| | 1TP to 8TP | Alarm Type | Operation Diagram | | | |
|-----------------------------------|------------|---|--------------------|--|--|--|
| | 0 | No alarm | PV | | | |
| Absolute value Alarm | 1 | Upper limit absolute | ALn PV | | | |
| | 2 | Lower limit absolute | ALn PV | | | |
| | 3 | Upper limit absolute (w/hold) | ALn PV | | | |
| | 4 | Lower limit absolute (w/hold) | ALn PV | | | |
| Deviation Alarm | 5 | Upper limit deviation | ALn SV | | | |
| | 6 | Lower limit deviation | ALn SV PV | | | |
| | 7 | Upper/lower limit deviation | ALn ALn | | | |
| | 8 | Upper limit deviation (w/hold) | ALn SV | | | |
| | 9 | Lower limit deviation (w/hold) | ALn SV PV | | | |
| | 10 | Upper/lower limit deviation (w/hold) | ALn ALn | | | |
| Range Alarm | 11 | Range upper/lower limit deviation | ALn ALn SV | | | |
| Upper/ lower limit Alarm | 16 | Upper/lower limit absolute | An-L An-H PV | | | |
| | 17 | Upper/lower limit deviation | An-L An-H SV | | | |
| | 18 | Upper limit absolute Lower limit deviation | An-L SV An-H | | | |
| | 19 | Lower limit absolute Upper limit deviation | An-H An-L SV | | | |
| | 20 | Upper/lower limit absolute (w/hold) | An-L An-H PV | | | |
| | 21 | Upper/lower limit deviation (w/hold) | An-L An-H | | | |
| | 22 | Upper limit absolute Lower limit deviation (w/hold) | An-L SV An-H | | | |
| | 23 | Upper limit deviation Lower limit absolute (w/hold) | An-H An-L SV | | | |

| | 1TP to 8TP | Alarm Type | Operation Diagram |
|-------------------|------------|--|--|
| Range Alarm | 24 | Range upper/lower limit absolute | An-L An-H PV |
| | 25 | Range upper limit/lower limit deviation | An-L An-H |
| | 26 | Range upper limit absolute Lower limit deviation | SV An-H PV |
| | 27 | Range upper limit deviation Lower limit absolute | An-H An-L SV |
| Range Alarm | 28 | Range upper limit/lower limit absolute (w/hold) | An-L An-H PV |
| | 29 | Range upper limit/lower limit deviation (w/hold) | An-L An-H SV PV |
| | 30 | Range upper limit absolute Lower limit deviation (w/hold) | SV An-H PV |
| | 31 | Range upper limit deviation Lower limit absolute (w/hold) | An-H An-L SV |
| Limit | 32 | SV upper/lower limit | An-L An-H SV |
| Rate of change | 35 | PV rate of change Upper/lower limit | 0% ALn 100 PV change ratio among 5 cycles |
| Timer | 36 | ON delay timer | |
| | 37 | OFF delay timer | |
| | 38 | ON/OFF delay timer | |

Caution The Hold Function:

This is an alarm for a situation when the alarm does not turn ON immediately, and the value shifts to outside the range once and then reenters within the range, even when the measured value is within the range of the alarm at the time the power is turned on.

Notes)
After changing the alarm type, confirm the alarm setting values.

Alarm setting values may change by this change of the alarm type, but this is normal.

- Caution: The alarm latch function cannot be used when using the OFF delay timer.
- ALn : Indicates the AL1 (ch1-10) to AL8 (ch1-31) alarm setting values.
- An-H : Indicates the A1-H (ch1-12) to A8-H (ch1-33) alarm setting values.
- An-L : Indicates the A1-L (ch1-11) to A8-L (ch1-32) alarm setting values.
- dLYn : Indicates the 1dLY (chA-4) to 8dLY (chA-39) alarm ON delay setting values.

Setup Procedures of the Controller

7

| | ① Does the input sensor type match the sensor in use? |
|-----------------------------|--|
| I I Input settings | Select the sensor in use from Table 2 and set to PV1T (ch8-4). |
| * Not necessary if input | (Example) Set Pv1T (ch8-4) to "7" in the case of a T thermocouple. |
| was specified when ordered. | Ļ |
| | ② Are the input range settings in the appropriate range for the sensor in use? |
| | The standard ranges for each sensor are shown in Table 2. |
| | Select the appropriate temperature range for the equipment in |
| | use and set the upper and lower limit values. Lower limit $ ightarrow$ |
| | Pv1b (ch8-2), Upper limit \rightarrow Pv1F (ch8-1). |
| | (Example) If the temperature range is 0 to 800 [°C]: Set $0 \rightarrow$ |
| | Pv1b (ch8-2), 800 → Pv1F (ch8-1) |
| | (Note) While it is possible to set outside the standard range, |
| | the standard range settings are recommended. |
| | (Note) There are no standard ranges for DC Volt (and DC |
| | Current) input. Set the upper and lower limits as |
| | you wish. (within the range -19999 to 99999, lower |
| | limit < upper limit) |

Note 1) Set input sensor type PV1T (ch8-4) and input range settings (Pv1b (ch8-2), Pv1F (ch8-1), and Pv1U (ch8-5)) in advance of all the other settings, and then reset the instrument without fail.

Other parameters may change when these parameters are changed, but this is normal.

Confirm all parameter values. Be sure to reset the instrument after setting the input range. Otherwise improper values may be displayed. Be sure to check the setting after the reset.

2 Control Settings

 Please read if controls are not responding as you expect.

① What is the control purpose? (To heat? To cool?)

| Objective | Operation Method | Explanation | | Method |
|-----------|---------------------|--|---------------|-------------------------------|
| To heat | Reverse operation | Raising the measurement value will reduce operation output. | \rightarrow | Set rEv1 (ch2-20) to REV. |
| To cool | Direct operation | Raising the measurement value will increase opera- tion output. | | Set rEv1 (ch2-20) to NRML. |
| | | | | |

| ② What kind of control is it? (PID, ON/OFF) | | | | | | | |
|---|---|-------------|--|--|--|--|--|
| Control Type | Explanation | | Method | | | | |
| PID control | The output signal changes within the range of 0 to 100% according to PID calculation. A stable control without a control offset can be achieved. | \bigwedge | Please execute auto-tuning manually. The optimal P.I.D will be calculated automatically. (The PID value may also be set manually.) | | | | |
| ON/OFF control (2-position control) | Output is either ON (100%) or OFF (0%). (Suitable when frequent output switching is inconvenient.) | | Set ch2 P1 (ch2-1) to "0.0". | | | | |

[Table 2] Input Codes

Parameter: PV1T, PV2T, AI1T

| Input Type | Code | Input Type | С | Code |
|---|-----------------------|---|---|----------------------------|
| Resistance bulb • Pt100Ω (IEC) | 1 | • N • PL-II • WRe5-26 | | 12 13 14 |
| For thermocouple • J • K • R • B • S | 2 3 4 5 6 | DC voltage • 1 to 5V DC • 0 to 5V DC • 0 to 10V DC • 0 to 10mV DC • 0 to 50mV DC | | 16 17 18 19 20 |
| • T • E • PR40/20 | 7 8 9 | DC current • 4 to 20mA DC • 0 to 20mA DC | | 26 27 |

Note 2) For Ai1, only DC voltage (code 16 to 18) settings are possible.

[Table 3] Input Range Table (Standard Range) Parameter: PV1F/PV1B, PV2F/PV2B, AI1F/AI1B

| Input Type | | Measurement Range (°C) | Measurement Range (°F) | Input | Input Type | | Measurement Range (°F) |
|--|------------------------|---------------------------|---------------------------|--------------|-----------------|-------------|---------------------------|
| | Pt100Ω | 0 to 150 | 32 to 302 | | J | 0 to 400 | 32 to 752 |
| | | 0 to 300 | 32 to 572 | | J | 0 to 1000 | 32 to 1832 |
| | | 0 to 500 | 32 to 932 | | к | 0 to 400 | 32 to 752 |
| Resistance | | 0 to 600 | 32 to 1112 | | К | 0 to 800 | 32 to 1472 |
| IFC | | -50 to 100 | -58 to 212 | | К | 0 to 1200 | 32 to 2192 |
| | | -100 to 200 | -148 to 392 | | R | 0 to 1600 | 32 to 2912 |
| | | -150 to 600 | -238 to 1112 | | В | 0 to 1800 | 32 to 3272 |
| | | -150 to 850 | -238 to 1562 | Thermocouple | S | 0 to 1600 | 32 to 2912 |
| | | | | | Т | -200 to 200 | -328 to 392 |
| | | | | | Т | -200 to 400 | -328 to 752 |
| | | | | | E | 0 to 800 | 32 to 1472 |
| • To use the Zen | er barrier for a F | PT input, user | | | E | -200 to 800 | -328 to 1472 |
| adjustment is re | equired. | | | | PR40/20 | 0 to 1800 | 32 to 3272 |
| Note 1) | | | | | N | 0 to 1300 | 32 to 2372 |
| R thermocouple | e 0 to 500°C | roper values may | not | | PL-II | 0 to 1300 | 32 to 2372 |
| B thermocouple | 0 to 400°C ∫ b | e displayed within | | | WRe5-26 | 0 to 2300 | 32 to 4172 |
| | th | nese ranges due t | o the | | 1 to 5V DC | | |
| | S | ensor's characteri | STICS. | | 0 to 5V DC | | |
| Note 2) When using at the setting below the minimum range stated in the table above, the input accuracy is not guaranteed. | | | DC voltage | 0 to 10V DC | -19999 to 99999 | | |
| | | | | 0 to 10mV DC | / Scaling is | | |
| | | | | 0 to 50mV DC | possible | | |
| Note 3) In the -50%FS to +50%FS display, values under -199.99 | | | | | 4 to 20mA DC | | |
| will not l | will not be displayed. | | | | 0 to 20mA DC | | |

[Table 4] Output Type Code Table

Parameter: OTYP



[Table 5] Di Input Assignments (Di1 to Di15)

| | | Operating Conditions | | | | |
|------------------------|---|----------------------|-------------|-------------|------------|--|
| Di1 to Di15 Setting | Function | Stat | us | Edge | | |
| Value | | ON | OFF | _ | | |
| 0 | None | - | - | - | - | |
| 1 | STBY (standby) | Standby | Normal | - | - | |
| 30 | AT (Auto tuning) | - | - | AT start | AT stop | |
| 40 | Alarm latch reset (Alarm1) to (Alarm 8) Release all | ch reset | | Release all | Latch hold | |
| 50 to 57 | Timer operating (Alarm1) to (Alarm 8) | ON | OFF | _ | _ | |
| 60 | R-ACK (Remote acknowledgement) | Remote | Local | _ | _ | |
| 70 | SMV (Manual command) | Manual mode | Auto mode | _ | _ | |
| 80 | PV-TRK command (PV tracking) | ON | OFF | _ | _ | |
| 103 | EX-MV (External control amount) | EX-MV | MV | _ | _ | |
| 200 to 249 | Binary data setting to constant parameter CN01 to CN05 1st digit : Bit position 10th digit : Parameter No. | 1 (1bit) | 0 (1bit) | _ | - | |

[Table 6] DO and LED display Assignments

| DO output | LED display | Туре |
|------------------------------|------------------------|-----------------------------|
| DO01 to DO04 DO11 to DO15 | C1, C2 LDO1 to LDO5 | |
| 0 | 0 | No setting |
| 1 | 1 | ALM1 |
| 2 | 2 | ALM2 |
| 3 | 3 | ALM3 |
| 4 | 4 | ALM4 |
| 5 | 5 | ALM5 |
| 6 | 6 | ALM6 |
| 7 | 7 | ALM7 |
| 8 | 8 | ALM8 |
| 17 | 17 | OR ALM (OR of all the ALMs) |
| _ | 21 | Output (MV) 1 |
| | 22 | Output (MV) 2 |
| 29 | 29 | System fault |
| 80 | 80 | Manual MV |
| 81 | 81 | EX-MV command |
| 82 | 82 | Remote SV |
| 83 | 83 | Local SV |
| 84 | 84 | PV tracking |
| 85 | 85 | NORMAL operating |
| 86 | 86 | Auto tuning (AT) |
| 87 | 87 | Remote request |
| 88 | 88 | Remote ACK (R-Ack) |
| 89 | 89 | NOT-A |

[Table 7] Standby Operation

| STBY | STBO | Operation during Standby | | | | |
|-------|-------|---------------------------------|----------------------|---------|--|--|
| value | value | MV output | Output other than MV | Display | | |
| ON | 0 | Value of PMv1 (-25% to 125%) | OFF or -25% | ON | | |
| | 1 | Value of PMv1 (-25% to 125%) | OFF or -25% | OFF | | |
| OFF | - | Normal | Normal | ON | | |

[Table 8] User Assignable Function Keys

| F1 to F3 setting value | Key operation | | | | |
|------------------------|---|--|--|--|--|
| 0 | No function | | | | |
| 1 | DSV display Switches Remote/Auto. (Press for 2 seconds.) Note 1 | | | | |
| 2 | Standby switching (1 second) | | | | |
| 3 | Alarm latch clear | | | | |
| 10 | AT (Auto tuning) START/STOP | | | | |
| 20 | Alarm timer start/stop (ALM1) | | | | |
| 21 | Alarm timer start/stop (ALM2) | | | | |
| 22 | Alarm timer start/stop (ALM3) | | | | |
| 23 | Alarm timer start/stop (ALM4) | | | | |
| 24 | Alarm timer start/stop (ALM5) | | | | |
| 25 | Alarm timer start/stop (ALM6) | | | | |
| 26 | Alarm timer start/stop (ALM7) | | | | |
| 27 | Alarm timer start/stop (ALM8) | | | | |

Note 1) Do not use this when TPLT=11,14 (SV select template) is in use, because it shifts to the remote-mode for a moment.

[Table 9] Type of Math function

| CALC set value | Name of operation | Math function |
|-------------------|------------------------------|--|
| 0 | No operation | PV1 |
| 1 | Expression 1 | $M1 = k01 \times \sqrt[*1]{PV1} \times \sqrt[*2]{\frac{Ai1+k02}{k03} \times \frac{k04}{PV2+k05}}$ |
| 2 | Expression 2 | $M1 = k01 \times PV1 \times \sqrt[*1]{\frac{Ai1+k02}{k03} \times \frac{k04}{PV2+k05}}$ |
| 3 | Expression 3 | $M1 = k01 \times PV1 \times \frac{Ai1+k02}{k03} \times \frac{k04}{PV2+k05}$ |
| 4 | Expression 4 | M1= (k01×(k02×PV1+k03×PV2+k04×Ai1)+k05) (k06×(k07×PV1+k08×PV2+k09×Ai1)+k10) |
| 5 | Expression 5 | $M1 = \frac{(k01 \times ((k02 \times PV1 + k03) \times (k04 \times PV2 + k05) \times (k06 \times Ai1 + k07)) + k08)}{(k09 \times ((k10 \times PV1 + k11) \times (k12 \times PV2 + k13) \times (k14 \times Ai1 + k15)) + k16)}$ |
| 6 | Expression 6 | M1= k01×PV1×(k02×PV2+k03×Ai1)+k04×Ai1+k05 |
| 7 | H selector, 2 points | Max (PV1, PV2) |
| 8 | L selector, 2 points | Min (PV1, PV2) |
| 9 | H selector, 3 points | Max (PV1, PV2, Ai1) |
| 10 | L selector, 3 points | Min (PV1, PV2, Ai1) |
| 11 | Input switching, 2 points | PV1 when PV1<= k01, PV2 when PV1>k01 |

*1 Square root extraction cut point can be set at k06.

*2 Square root extraction cut point can be set at k07.

[Table 10] Controller Templates

FPLF = 10 Single-loop basic PID control (with Math function)

Contents of input conditioner

- User adjustment
- Square root extractions
- Input filter

1 The value obtained by calculating the input value for PV1, PV2, and Ai1 can be controlled as PV.

<Operations allowed>

- Flow rate/temperature/pressure corrections
- Averaging (Weighting allowed)
- Maximum/minimum selector
- Input signal switching

(See table 9 for details of mathematical expressions.)

2 The same as Template No.13 except for Math function.

Note) A scale setting [UCF1, UCB1, UCD1 (ch8: 89-91)] must be made in accordance with the range resulting from the Math function.



FPLF = 11 Single-loop SV selection PID control (with Math function)

- The template is used to perform Math function with PV1, PV2, and Ai1 in SV selection type control. (See item 1 in template No.10 for Math function.)
- 2 The same as template No.14 except for the Math function.
- Note) Scale setting [UCF1, UCB1, UCD1 (ch8: 89-91)] must be made in accordance with the range resulting from the Math function.

| Selection | SV selection SV selection | | SV selection |
|-----------|---------------------------|----------|--------------|
| SV No. | Signal 1 | Signal 2 | Signal 3 |
| Local SV | OFF | OFF | OFF |
| SV1 | ON | OFF | OFF |
| SV2 | OFF | ON | OFF |
| SV3 | ON | ON | OFF |
| SV4 | OFF | OFF | ON |
| SV5 | ON | OFF | ON |
| SV6 | OFF | ON | ON |
| SV7 | ON | ON | ON |

SV selection signal and SV number to be selected



FPLF = 13 Single-loop basic PID control **1** This is the most basic control template.

- 2 Control is allowed in an auto/manual/remote operation mode and by digital input.
- **3** Set the control output and transfer output with a parameter [OTYP]. (See Table 4 for details.)
- By changing the digital input (Di) allocations, a standby operation, etc. can be performed.
 (See Table 5 for details.)
- 5 Digital output (Do) and LED lamp allocations can be changed. (See Table 6 for details.)



Image: Setting value (SV) can be selected by digital input. The SV can be selected from the local (front panel) setting value and 7 pairs of palette setting values (SV of ch3), 8 points in total. PID parameters can be switched according to the SV. (Set PLTS (ch9-31) at SV.) Set control output and transfer output by parameters [OTYP]. (See Table 4 for details.)

- By changing the allocation of the digital input (Di), a standby operation, etc. can be performed.
 (See Table 5 for details.)
- 5 Digital output (Do) and LED lamp allocations can be changed. (See Table 6 for details.)
- SV selection signals and selected SV Nos. are the same as those of template No.11.



8

Troubleshooting

[Please read when the display does not make sense]

Error indications

This Controller has a display function to notify when the equipment is not functioning properly. When a problem occurs, remove the cause immediately.

Once the cause has been removed, turn the power OFF then ON again.

| Display | Cause | Control Output |
|--------------------------------|--|---|
| טטטט | Thermocouple sensor wire broken RTD wiring broken PV value above upper limit +5%FS or more RCJ sensor not attached (thermocouple input) | The value of brd1 (CH9-35) is to be the control output (MV). (Kind of output) |
| LLLL | \bigcirc RTD sensor (between A-B) short circuited \bigcirc The PV value is at the lower limit of –5%FS or lower. | HOLD, (2) LO (OFF or lower limit value of the AO) UP (ON or upper limit value of the AO), (4) EXMV |
| LLLL | When PV value is under –199.99. Note) When a resistance bulb is used, "LLLL" is not displayed even if under –150°C. | Control continues Note) Control continues until below –5%FS. Burnout occurs at below –5%FS. |
| PV not displaying | Standby mode (STbo (ch9-30) = 1) | The value of PMv1 (CH2-22) is to be the control output (MV). |
| -19999 or 99999 | Display limit is smaller than over range or under range value. | Control continues Note) Control continues until under –5%FS or 105%FS. |
| Correct PV not displayed | The main unit was not reset or the power was not turned on after the scale setting was changed. | |

When the key operation is not functioning properly.

Key operation may not be performed in the following cases.

| Status | Remedy | | | | |
|---|--|--|--|--|--|
| LoC setting does not allow the parameter the display. | Set LoC (ch1-34) at "0." | | | | |
| Forgot password. | Set the parameter of PS1 at "F1C3." ${\times}$ Set parameters PAS1 and PAS2 (ch9:1-2) at 0000 to reset the password. | | | | |

* Setting the paremater to "F1C3" displays all parameters.

Please do not change the parameters unnecessarily. It may cause a failure of this main unit.

Model Specification

PXH Model Code

| | | Digit · | ►12 | 34 | 5 | 6 7 | 78 | | 91 | 011 | 1213 |
|-------|--|---------|-----|-----|---|--------|--------|-----|-----------------------|--------|-------------|
| | | • | ΡX | Н 9 | А | | 1 |]-[| ١ | / | 0 |
| Digit | Description | Notes | | | | | | | | | |
| 4 | <dimension face="" front="" h="" of="" w="" x=""> 96 x 96 mm</dimension> | | | 9 | | | | | | | |
| 5 | <number control="" function="" loops="" of=""> 1 loop, PID controller</number> | | | | A | | | | | | |
| 6 | <measurement input="" value=""> Universal input: 1 point Universal input: 2 points</measurement> | *1 | | | | 1 2 | | | | | |
| 7 | <auxiliary input=""> Without DC voltage: 1 point</auxiliary> | | | | | (| D 1 | | | | |
| 8 | <version no.=""></version> | | | | | | 1 | | | | |
| 9 | <output> OUT1 OUT2</output> | | | | | | | | | | |
| | CurrentNot fittedCurrentCurrentCurrentTransmitter supplySSR/SSC driverNot fittedSSR/SSC driverCurrent | | | | | | | | 1 2 5 A B | | |
| 10 | <power supply=""> 100 to 240 V AC</power> | | | | | | | | , | / | |
| 11 | <communication interface=""> Without RS-485</communication> | | | | | | | | | 0 R | |
| 12 | <digital input="" output=""> Digital input Digital output (Includes control output (Relay))</digital> | *1 | | | | | | | | | |
| | 4 points (Di1-4) 2 points (Do3, Do4) 4 points (Di1-4) 4 points (Do1-4) 9 points (Di1-4, Di11-15) 9 points (Do1-4, Do11-15) | | | | | | | | | | 0 A B |
| 13 | <additional specifications=""> Not fitted.</additional> | | | | | | | | | | 0 |

*1: "2" at the 6th digit and "B" at the 12th digit cannot be assigned simultaneously.

Specificaitons

| (1) Power voltage | 100 (-15%) to 240V AC (+ | 10%) 50/60Hz |
|---------------------------------|---------------------------------|--|
| (2) Power consumption | 100V AC | : 15VA or less |
| | 220V AC | : 20VA or less |
| (3) Normal operation conditions | Ambient temperature | : −10°C to 50°C |
| | Ambient humidity | : 90%RH or less (no dew condensation) |
| | Storage temperature | : -20°C to 60°C |
| | Warm-up time | : 15 min. or longer |
| (4) Input | Input signal | : RTD, thermocouple, DC voltage, DC current |
| | 1 0 | (multi input) |
| | | Refer to Table 3. |
| | Input indication accuracy | |
| | Thermocouple | : $\pm 0.1\%$ of FS ± 1 digit $\pm 1^{\circ}$ C or $\pm 1.5^{\circ}$ C whichever |
| | • | is higher. |
| | | however. |
| | | Thermocouple B : |
| | | 0 to 400°C, ±5% of FS ±1digit ±1°C |
| | | Thermocouple R : |
| | | 0 to 500°C. \pm 1% of FS \pm 1diait \pm 1°C |
| | Resistance bulb | : ±0.1% of FS ±1digit or ±0.25 °C whichever is |
| | | higher |
| | DC voltage, DC current | : ±0.1% of FS 1digit |
| | Input sampling cycle | : 50ms |
| | Input impedance | |
| | Thermocouple/voltage (m | V) : $1M\Omega$ or more |
| | Voltage | · :1MΩ |
| | Current | : 250Ω |
| | Allowance input voltage | |
| | Voltage (V) | : +35V/-10V DC |
| | Current | : ±25mA DC |
| | Thermocouple/resistance | bulb/voltage (mV) : ±5V |
| | Noise reduction ratio | |
| | Normal mode | : 40dB (50/60Hz) or more |
| | Common mode | : 120dB (50/60Hz) or more |
| | Input value correction | |
| | User adjustment | : $\pm 50\%$ of FS each at zero, span |
| | Square-root extraction | : 0.0 to 125.0 at OFF or cut point |
| | First-order lag filter | : 0.0 to 900.0 seconds |
| | Effect of source resistance | /permissible wiring resistance |
| | Thermocouple, voltage input (m) | V) : 0.1% FS per 100Ω |
| | Power supply input (V) | : 0.1%FS per 500Ω |
| | Resistance bulb input | : 10Ω or less (per cable) |
| (5) Relay contact output | Contact capacity | : 220V AC / 30V DC, 3A (resistance load) |
| • | | 220V AC / 30V DC, 1A (induction load) |
| (6) SSR/SSC drive output | ON | : 12V DC (10 to 15V DC) |
| (voltage pulse output) | OFF | : 0.5V DC or less |
| , | Max. current | : 20mA DC |
| | Load resistance | : 600Ω or over |
| | | |

| (7) DC output (4 to 20mA DC) | No. of points | : Max. 2 points (with re-transmission output) |
|--------------------------------------|-------------------------|--|
| | Accuracy | : ±0.2%FS |
| | Linearity | : ±0.2%FS |
| | Load resistance | : under 600Ω |
| (8) Digital input | No. of Input | : Max. 9 points |
| | Specifications | : Non-voltage contact or transistor input |
| | Contact capacity | : 12V DC, 2mA |
| | Input pulse width | : 200ms or more |
| (9) Digital output | Digital output1 to 3 | : 1a (SPST) contact, 220V AC / 30V DC, 1A (resistance load) |
| | Digital output 4 | : 1c (SPDT) contact, 220V AC / 30V DC, 1A (resistance load) |
| | Digital output 11 to 15 | : 1a (SPST) contact, 220V AC / 30V DC, 1A (resistance load) |
| (10) Auxiliary analog input | No. of Input | : 1 point |
| | Input signal | : 1 to 5V DC / 0 to 5V DC / 0 to 10V DC |
| | Input accuracy | : ±0.2%FS |
| (11) Analog re-transmission output | No. of output | : 2 point at max. |
| | Output signal | : Current output (4 to 20mA DC) |
| | Accuracy | : ±0.2%FS |
| | Linearity | : ±0.2%FS |
| | Load resistance | : under 600Ω |
| | Output contents | : PV, SV, DV, MV re-transmssion |
| | Scaling function | : Provided |
| (12) Transmitter power supply output | No. of output | : 1 point |
| | Rating | : 24V DC (17 to 30V DC), max. current 23mA |
| | | (short circuit protection) |
| (13) Communications functions *1 | RS-485 Interface | |
| | Protocol | : Modbus-RTU standard |
| | Transmission speed | : 9600bps, 19200bps, 38400bps |
| | Transmission distance | : Max. 500m (total connected length) |
| | Transmission method | : Asynchronous (Half-duplex bit serial) |
| | Data format | : Data length: 8 bits odd/even/none |

*1 Recommended converter

| RC-77 (insulted) from RA Systems Corp. | http://www.ras.co.jp |
|--|------------------------|
| K3SC-10 (insulted) from Omron Corp. | http://www.omron.co.jp |
| Modbus RTU is a trademark of Modicom. | |