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# FORTHdsPIC User Manual

## Contents

FORTHdsPIC User Manual .....	1
1. Introduction .....	2
2. System Requirements .....	2
2.1. MicroStick II Development Board .....	2
2.2. Custom Development Board .....	2
3. Installing FORTHdsPIC .....	3
3.1. MicroStick II Development Board .....	3
3.2. Custom Development Board .....	3
4. Running FORTHdsPIC .....	4
4.1. MicroStick II Development Board .....	4
4.2. Custom Development Board .....	4
5. Running FORTH in Interpreter Mode .....	5
5.1. Simple Command Line .....	5
6. Running FORTH Programs .....	6
6.1. Creating New Words with the Compiler .....	6
6.2. FORTH Programming .....	7
6.3. How Forth programs are stored & run in FORTHdsPIC .....	8
7. Moving the Forth code to non-volatile (Flash) memory .....	10
7.1. Compiling code for the Flash memory .....	11
7.2. Running an Embedded Application .....	12
Appendix 1. FORTHdsPIC Basic Instruction Set .....	13
Appendix 2. Sample Forth programs .....	18

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# 1. Introduction

Two versions of FORTHdsPIC are available as Microchip MPLAB IDE 8.92 projects. Both are designed to run on a 28-pin DIP package of the dsPIC33FJ digital signal controller series. At least 64KBytes of Flash memory and 16KBytes of RAM need to be available. One version is set up for the MicroStick 2 development board from Microchip and the other for a third-party Arduino® format board. The main difference is the clock source; internal on the MicroStick and 8MHz external crystal on the other. In either case, the processor clock speed delivers a processor performance of 40MIPS. This can be increased to 70MIPS by using the 'EP' version of the chip. The other difference is the need for a PICkit 3 programmer/debug tool for the Arduino board: the MicroStick has this functionality built-in.

## 2. System Requirements

Both these versions can run code in a stand-alone or embedded mode once the user's Forth code has been compiled and 'Flashed' into program memory. But first FORTHdsPIC must be installed on the dsPIC chip via a host PC.

### 2.1. MicroStick II Development Board

PC with two spare USB sockets loaded with MPLAB IDE and a terminal emulator such as TeraTerm  
Microchip MicroStick II Part No. DM330013-2 RS Part No. 749-6445  
FTDI UART - USB converter cable Part No. TTL-232R-RPi RS Part No. 767-6200  
MiniUSB - USB-A cable



Fig.1 Microchip MicroStick II Development Board

### 2.2. Custom Development Board

PC with two spare USB sockets loaded with MPLAB IDE and a terminal emulator such as TeraTerm  
Development board with ICSP header pins  
Microchip PICkit 3 programmer/debug tool  
FTDI UART - USB converter cable (If no USB port available) P/N TTL-232R-RPi RS P/N 767-6200

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## 3. Installing FORTHdsPIC

### 3.1. MicroStick II Development Board

All that's needed for the one-time Flashing of the FORTHdsPIC firmware is the PC with MPLAB, the MicroStick and a USB cable. The MicroStick has on-board programmer/debug hardware so no additional equipment is required. The firmware uses the dsPIC internal clock oscillator.

1. Connect the MicroStick to the PC with the USB cable and run MPLAB. There may be some upheaval as Windows locates a USB driver the first time.
2. Run MPLAB and click on **Open...** in the **Project** menu. Select FORTHdsPIC\_Microstick\_xx.
3. MPLAB might complain it can't find some files where it expects to find them. It should offer a link to the correct location and all you have to do is accept.
4. Generate the object code by clicking on the **Build All** button.
5. Click on the **Program** button to Flash the dsPIC program memory with the firmware.

### 3.2. Custom Development Board

For other types of board including new designs, an external programmer/debug tool will be required. A standard Microchip ICSP header should be provided to which the PICkit 3 programmer may be connected. The firmware assumes an external 8MHz crystal is connected.

1. Plug the PICkit 3 into the development board using the ICSP header. Connect the PICkit 3 to the PC with the USB cable and run MPLAB. There may be some upheaval as Windows locates a USB driver the first time.
2. Run MPLAB and click on **Open...** in the **Project** menu. Select FORTHdsPIC\_DIP.
3. MPLAB might complain it can't find some files where it expects to find them. It should offer a link to the correct location and all you have to do is accept.
4. Generate the object code by clicking on the **Build All** button.
5. Click on the **Program** button to Flash the dsPIC program memory with the firmware.

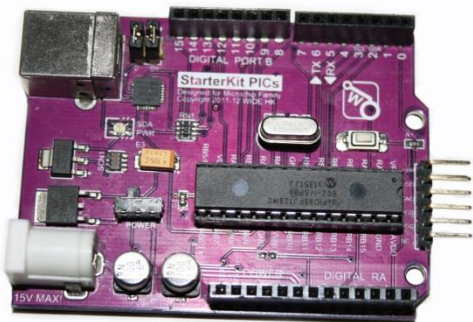


Fig.2 Arduino-format development board for PIC24/dsPIC from WIDE.HK. Features ICSP header for debug/programmer and a USB-UART bridge chip.

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## 4. Running FORTHdsPIC

### 4.1. MicroStick II Development Board

Once programmed with the FORTHdsPIC firmware, MPLAB is no longer needed but the USB connection is still required to power the board. In order to edit, compile and run FORTH code you will need the PC running a terminal emulator, USB cable and a UART-USB bridge cable.

1. Connect the bridge cable to UART Tx, Rx and Gnd pins of the header on the MicroStick.  
Pin 1 : Black  
Pin 4 : Orange  
Pin 5 : Yellow
2. Plug the other end of the cable into the PC. Again there should be a one-time search for and loading of a driver.
3. Run the terminal emulator, in my case I use TeraTerm, and make sure it links to the correct serial COM port with settings 19200baud, 8bits, No Parity and Transmit Delay 200ms. Save the template so it's selected whenever the MicroStick is plugged in.
4. The board is powered from the USB link so with the slide-switch set to A, press the RST button and a title message with FORTH prompt should appear in the emulator window:

```
FORTHdsPIC Vsn. X.X (C) W.G.Marshall  
10 >
```

### 4.2. Custom Development Board

Once programmed with the FORTHdsPIC firmware, MPLAB is no longer needed but the board will still need to be powered. Power supply and connection to the PC terminal emulator will depend on the particular board design. In order to edit, compile and run FORTH code you will need a host PC running a terminal emulator and a USB or UART-USB bridge cable.

1. Either connect the bridge cable to Tx, Rx and Gnd pins of a UART1 header on the board. These are the pin numbers for a 28-pin DIP package dsPIC33. These pins will be assigned to UART1 by FORTHdsPIC when it boots up.  
Gnd Pin 19 : Black  
Rx Pin 21 : Orange  
Tx Pin 22 : Yellow  
or connect a USB cable to the target board if it has a UART-USB bridge chip fitted.
2. Plug the other end of the cable into the PC. Again there may be a one-time search for and loading of a driver for the bridge chip.
3. Run the terminal emulator, in my case I use TeraTerm, and make sure it links to the correct serial COM port with settings 19200baud, 8bits, No Parity and Transmit Delay 200ms. Save the

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template so it's selected whenever the MicroStick is plugged in.

4. The board is powered from the USB link so with the slide-switch set to A, press the RST button and a title message with FORTH prompt should appear in the emulator window:

```
FORTHdsPIC Vsn. X.X (C) W.G.Marshall
10 >
```

## 5. Running FORTH in Interpreter Mode

From now on operation of FORTHdsPIC is largely independent of the hardware platform. Fig.3 below shows a minimal system for program development based on the MicroStick II fitted with a dsPIC33 device.

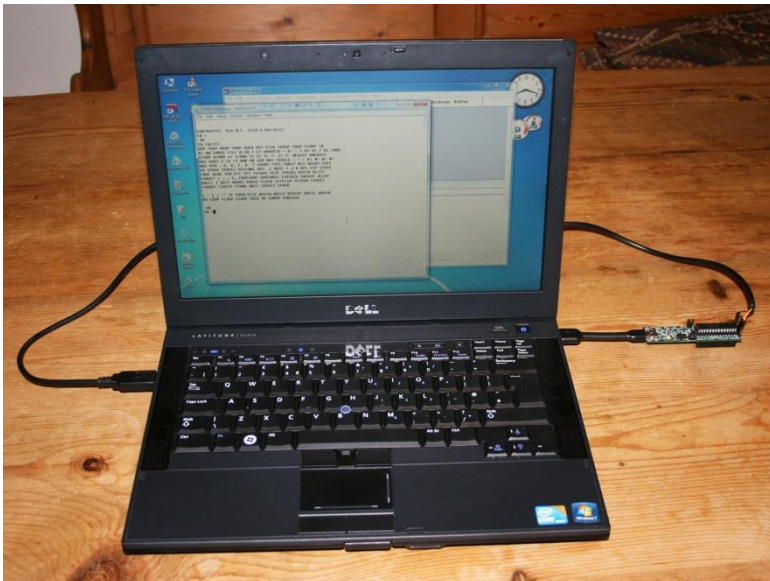


Fig.3 FORTHdsPIC running on a MicroStick. Communication is via the TeraTerm window. MPLAB IDE is open in the background.

### 5.1. Simple Command Line

Basic calculations can be performed immediately by typing Forth commands and numbers separated by spaces after the command prompt, followed by Return. Max length = 80 characters.

#### 5.1.1 Command Prompt

The Command prompt (>) is preceded by a number indicating the number base in use. The default is decimal (10) and its value is held in the system variable **BASE**. Typing **HEX** at the prompt will change the base to hexadecimal (16); **DECIMAL** will change it back.

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### 5.1.2 Command Line Interpreter

At the command prompt (>) type: **6 4 \* 3 / .** not forgetting the spaces, and press Return. The '.' means Print the result on the console.

```
10 > 6 4 * 3 / .  
8 OK  
10 >
```

This simple calculation is equivalent to Print (6 x 4) / 3 but using Reverse Polish notation instead. This format is very efficient on computers which feature temporary data storage in the form of push-down or LIFO stacks.

## 6. Running FORTH Programs

### 6.1. Creating New Words with the Compiler

The Command Line Interpreter is great for testing small pieces of Forth code, but for a full program incorporating structures such as **DO...LOOP**, a compiler is necessary.

#### 6.1.1 Generate a Forth source code file

Use a basic text editor such as Microsoft Notepad to create a Forth source code or 'program' file. Save it on the PC hard-disk. A Forth program consists of at least one new word definition enclosed by ':' and ';'. The simple code example above can be compiled as a new word definition called **CALC** like this:

```
( Program 1: Calculator )  
: CALC * SWAP / ;
```

Note that the numbers are not included. When the compiled word CALC is executed it will take the top three items off the parameter stack to work on.

#### 6.1.2 Running the Compiler

Send the source text file to the FORTHdsPIC compiler. Use the appropriate function on the terminal emulator to do this. For TeraTerm click on **Send file...** from the **File** menu and select your file to send. FORTHdsPIC just sees the text file as a very long keyboard input: any 'colon' definitions are compiled and code saved in the code area of RAM. Any other words are executed immediately.

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### 6.1.3 Running the compiled program

The vocabulary entry and the run-time code for the new word definition **CALC** is stored in RAM memory and will be lost if the power to the board is switched off or the processor RST (Reset) button pressed. To run **CALC** with the same numbers as before, type **3 4 6 CALC .** at the command prompt:

```
10 > 3 4 6 CALC .
8 OK
10 >
```

The Interpreter reads the command line from left to right and ‘pushes’ the three numbers onto the Last-In First-Out Parameter Stack in order. When **CALC** is executed, the top two, 4 and 6 are ‘popped’ off the stack, multiplied together and the result pushed on the stack. The top two parameters, now 24 and 3 are **SWAP**ped, popped off, the division performed and the result, 8 pushed back on the stack. Finally the print number command (.) pops the result and displays it.

Note:

1. Now that **CALC** is a defined word, it can be used to operate on any three numbers.
2. **CALC** can be used inside new definitions alongside the standard words.

## 6.2. FORTH Programming

It is possible to create one very large colon-definition using just the standard words of the FORTHdsPIC instruction set. From the debugging point of view and of someone else trying to understand your work, this is very definitely the worst way to program in Forth. The drawback of using a push-down stack for storing intermediate results is keeping track, ensuring that each Forth word begins execution with its operands on top of the stack in the correct order. Following a piece of source code involves keeping an image of the stack in your mind at every stage. This becomes difficult with more than three stacked items so annotating a source listing with stack ‘snapshots’ is essential.

The table below shows the data on the stack during execution of the **CALC** example.

TOS = Top of Stack

Parameter Stack	Before *	After *	After SWAP	After /
TOS	6	24	3	8
TOS-1	4	3	24	
TOS-2	3			

Fig.4 State of Parameter Stack as CALC executes

## 6.3. How Forth programs are stored & run in FORTHdsPIC

### 6.3.1 Format & Storage

A compiled Forth program consists of a list of 16-bit address links each pointing to the code for that word. That code could be the start of another list of addresses or actual executable machine code. There is a problem though. The dsPIC has what is called a modified Harvard architecture where data and program memories are separated. This means that executable code is stored in Program memory, but Forth address links are treated as data and stored in Data memory. Early versions of Forth ran on microprocessors with a single memory space for both Data and Program. Fortunately there is a way of 'fooling' the dsPIC chip into believing that an area of Program Flash memory is actually Data RAM. Those familiar with PIC chips will be aware of the TBLRD and TBLWT instructions which allow data to be read from and written to program memory. The PIC24/dsPIC devices also have an operating mode called Program Space Visibility (PSV).

### 6.3.2 Program Space Visibility

In FORTHdsPIC a 32Kbyte section of program (Flash) space is mapped into data memory (RAM) beginning at address 8000h. This is why the compiled Forth links all have Bit 15 = 1. The PSV system is enabled from startup so every time the processor reads data from an address with Bit 15 set, it gets it from Flash memory not RAM. Here are the Vocabulary and Code entries for the compiled **CALC** example:

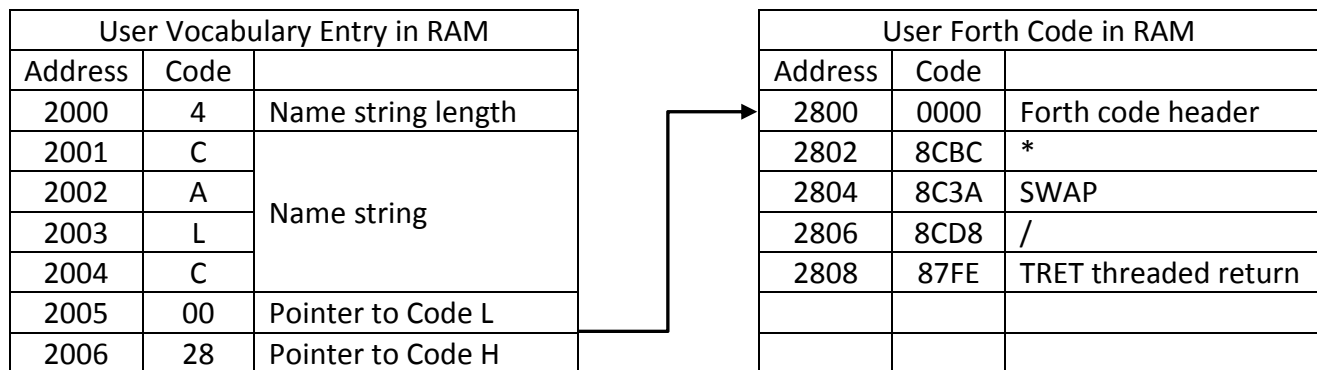


Fig.5 Vocabulary entry and Forth linked code for example **CALC** program

### 6.3.3 How FORTHdsPIC runs the **CALC** example compiled code

Two pieces of code are produced by the Compiler for each 'colon-definition'. (**Fig.5**) When **CALC** is subsequently typed at the command prompt, the Interpreter scans the vocabulary and when it finds the correct entry it picks up the Code Pointer and runs EXECUTE. This routine checks the item at the Code Pointer address, in this case 2800h, to see if it is zero as here, indicating a Forth linked list follows. The Forth Program Counter (PC) is saved on the Return Stack and moved on to point to the next item in the list (\*) at address 2802h. The contents of



---

this address 2802h is now loaded as a pointer and the data at *this* address, 8CBCh, checked to see if it's zero. If it is, then the whole process from saving and incrementing the PC onwards is repeated until a non-zero value is found. In our example **CALC**, 8CBCh is the address of the multiply (\*) machine code routine, which can now be executed. Now the actual address of the routine in Program memory is 0CBCh so Bit 15 is masked off to enable a 'computed goto' to take place. Remember Bit 15 is set to trigger the PSV system so the contents of Program memory location 0CBCh can be read as *Data*. Once it has been established that it contains executable machine code, Bit 15 is cleared and the code at 0CBCh executed instead.

The code starting at address 0CBCh is for the single-precision multiply (\*) and terminates like all the machine code routines with a jump to the threaded linker, NEXT. This tiny machine code routine is the heart of the system, transferring program execution from one link address to the next. After the divide (/) the linked Forth code **CALC** ends with TRET which pops the last PC off the Return stack before jumping to NEXT. As this is the end of the program, control returns to the Interpreter and the command prompt.

The important point to notice is the difference between executing **CALC** as a command line and executing the compiled version.

When you type in a series of commands and data at the prompt (Section 5.1.2) the Interpreter searches for each one in the Interpreter vocabulary, locates its code and executes it until the end of the line is reached.

When **CALC** is compiled (Section 6.1.1) and then run at the command prompt, the Interpreter pushes the three parameters on the stack before searching all the vocabularies for the **CALC** entry. Once the **CALC** word begins executing the vocabularies are no longer referenced because the compiled code now contains all the pointers in a list. Hence compiled code will always run much faster than interpreted code.

Note that the Pointer to Code in the User Vocabulary (Fig.5) does not have Bit 15 set because the newly compiled code is in RAM. This will change if user code is moved to Flash memory. (See Section 7)

Take a look at the listing for FORTHdsPIC itself: all the speed sensitive word definitions are in machine code while those printing to the terminal say, are composed of Forth linked lists.

#### 6.3.4 How FORTHdsPIC runs more complex compiled code

This example serves to show the code generated (Fig.6) when two new user word definitions, **CALC** and **PRINT** are incorporated in the definition of a third, **MAIN**.

```
( Program 2: Print results of simple calculation )
: CALC * SWAP / ;      ( Perform calculation with top 3 stack items )
: PRINT . CR ;        ( Print TOS item followed by NewLine )
: MAIN CALC PRINT ;   ( Combine CALC and PRINT into a new word – MAIN )
```

Fig.6 below illustrates the program flow of the new word MAIN. As before, the command interpreter searches for **MAIN** in the vocabulary, and begins execution when it finds the entry and its code pointer value of 2812. This time however, the pointer links through to a new definition, **CALC** which also resides in RAM. Hence the absence of the PSV bit on the link address of 2800. Note again that the vocabulary entries for **CALC** and **PRINT** are not required for **MAIN** to run.

Vocabulary		Forth Code		
Address	Code	Address	Code	Function
2000	4	2800	0000	<i>CALC</i>
	C		8CBC	*
	A		8C3A	SWAP
	L		8CD8	/
	C		87FE	TRET
	00	280A	0000	<i>PRINT</i>
	28		8A52	.
2007	05		8900	CR
	P		87FE	TRET
	R	2812	0000	<i>MAIN</i>
	I		2800	CALC
	N		280A	PRINT
	T		87FE	TRET
	0A			End
	28			
200F	4			
	M			
	A			
	I			
	N			
	12			
	28			

Fig.6 Vocabulary entry and Forth linked code for example **MAIN** program

## 7. Moving the Forth code to non-volatile (Flash) memory

Once the Forth code has been debugged while stored in RAM, it can be moved to the dsPIC's Flash memory so that it won't disappear when the device power is removed. It will also 'auto-boot' from power-up or Reset.

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## 7.1. Compiling code for the Flash memory

The only difference between code generated to run in RAM and that for Flash memory is in the memory address references for the compiled code which will usually need Bit 15 to be set. After testing your code in RAM and making sure it is bug-free the following operations should be performed to transfer it to Flash memory.

1. Ensure the name of the top-level word in the source code text file (the one that runs the whole program) is **MAIN**.
2. Clear the RAM by pressing the Reset button on the processor board, or by typing **ABORT** <return> at the command prompt.
3. Type **SETFLSH** <return> at the command prompt. This sets a flag so that the compiler knows to create code for Flash memory.
4. Send the source code file from the host PC to the FORTHdsPIC host. The code is initially loaded into RAM, but cannot be run here.
5. If no errors appeared on the screen as the program compiled, type **FLASH** <return> at the command prompt. **FLASH** has copied the RAM vocabulary and code space to the corresponding Flash memory locations.
6. To run the program:  
*Either* type **MAIN** at the prompt to run the program  
*or*  
Press Reset on the Microstick. If you use this method, the RAM is cleared and typing **MAIN** to re-run the program will result in an 'Undefined' error message. The user program will now only run from Reset or Power-on (auto-boot). This is the stand-alone or embedded mode.

Here is a code example that shows how different programs can be loaded and run in RAM and Flash. It also shows that commands can be run by the interpreter in between colon definitions.

### ( Program 3: RAM versus Flash memory Benchmark Test )

**SETFLSH**

**: FHEADING CR ." Flash Benchmark" CR ;**

**: MAIN FHEADING**

**TIMSET TIMSRT 10001 1 DO SP! LOOP**

**TIMSTP TIMRD 40 M/MOD ." BM1: " 8 F. ." usecs" DROP ;**

**FLASH**

**SETRAM**

**: RHEADING CR ." RAM Benchmark" CR ;**

**: BENCH RHEADING**

**TIMSET TIMSRT 10001 1 DO SP! LOOP**

**TIMSTP TIMRD 40 M/MOD ." BM1: " 8 F. ." usecs" DROP ;**

---

**SETFLSH** sets the Flash memory flag and the next two colon definitions **FHEADING** and **MAIN** are compiled into RAM accordingly.

**FLASH** copies the code into Flash memory.

**SETRAM** clears the Flash flag so subsequent compilation will yield code that will execute in RAM. The vocabulary and code entries of **RHEADING** and **BENCH** are appended to those of the other two in RAM.

Type **BENCH** at the prompt and the benchmark program for RAM based programs produces:

```
RAM Benchmark  
BM1: 7501 usecs OK  
10 >
```

Type **MAIN** at the prompt and the benchmark program for Flash based programs produces:

```
Flash Benchmark  
BM1: 8251 usecs OK  
10 >
```

Both versions will run from the keyboard input because the **MAIN** vocabulary entry remains in the RAM and so it can be found by the Interpreter search. Type **VLIST** to confirm this.

Notice that the Flash-based program takes longer to run than the RAM-based code. This is because of the increased number of PSV fetches which makes the Flash code about 10% slower.

When either Flash or RAM-based code ends, control returns to the command prompt.

## 7.2. Running an Embedded Application in Flash memory

An embedded program must auto-start from power-up and never return to the command prompt. However when testing, an exit should be provided otherwise the only way to regain control is to connect up MPLAB IDE and force a chip erase. FORTHdsPIC will then have to be re-Flashed.

```
( Program 4: Walks until a key is pressed )  
: MAIN BEGIN WALK INKEY 0= WHILE REPEAT ;
```

This code fragment from a robot control program keeps WALK running in a loop until it detects a terminal key has been pressed.

```
( Program 5: Walks for ever )  
: MAIN BEGIN WALK AGAIN ;
```

This code replaces Program 4 only when the complete program is fully debugged! The terminal can now be disconnected.

## Appendix 1. FORTHdsPIC Basic Instruction Set

Typing **VLIST** at the command prompt provides a list of FORTH words in two vocabularies, Interpreter and Compiler. New word definitions will appear in a third, User vocabulary.

10 >VLIST

DUP ?DUP DROP SWAP OVER ROT PICK 2DROP 2DUP 2SWAP >R  
 R> R@ CMOVE FILL @ C@ ! C! ARRAY1D + D+ - \* M\* U\* / M/ /MOD  
 U/MOD M/MOD \*/ \*/MOD 2\* 2/ 1+ 1- 2+ 2- NEGATE DNEGATE  
 ABS DABS S->D +! AND OR XOR NOT TOGGLE = > < U< 0= 0> 0<  
 MAX MIN . U. D. F. R. ? COUNT TYPE INKEY KEY QUERY EMIT  
 CR SPACE SPACES DECIMAL HEX .( BASE I J K DPL CODE HERE  
 SP! DEPTH VLIST FORGET ( : , C, CONSTANT VARIABLE EXECUTE  
 CREATE ALLOT DOES> ] QUIT ABORT ERASE FLASH SETFLSH  
 SETRAM TIMSET TIMSRT TIMSTP TIMRD WAIT SVOSET SERVO

(' [ ; ." IF THEN ELSE BEGIN WHILE REPEAT UNTIL AGAIN  
 DO LOOP +LOOP LEAVE CASE OF ENDOF ENDCASE

Stack Manipulation																																																																																												
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action																																																																																					
DUP	n	n	Duplicate TOS	2DROP	nh		Drop Double-Precision number																																																																																					
		n			nl			?DUP	n	n	Duplicate TOS if TOS not equal to zero	2DUP	nh	nh	Duplicate Double-Precision number		n if n<>0	nl	nl	DROP	n		Drop TOS	2SWAP	n1h	n2h	Exchange Double-Precision numbers			n1l	n2l	SWAP	n1	n2	Exchange TOS and TOS-1	>R	n		Move TOS to Return stack	n2	n1	n1h	n2h			n2h	n1h	OVER	n1	n2	Copy TOS-1 to TOS	R>	n1l	n1l	Move Top of Return stack to TOS	n2	n1	n2l	n1l		n2			ROT	n1	n3	Rotate TOS-2 to TOS	R@		n	Copy Top of Return stack to TOS	n2	n1			n3	n2			PICK	n	n2	Copy TOS-n to TOS n = 2 shown				n1	n1			n2	n2
?DUP	n	n	Duplicate TOS if TOS not equal to zero		2DUP	nh			nh	Duplicate Double-Precision number																																																																																		
		n if n<>0				nl		nl	DROP		n			Drop TOS		2SWAP	n1h	n2h	Exchange Double-Precision numbers			n1l	n2l		SWAP	n1		n2	Exchange TOS and TOS-1	>R	n			Move TOS to Return stack			n2	n1		n1h	n2h			n2h	n1h	OVER	n1		n2	Copy TOS-1 to TOS			R>	n1l		n1l	Move Top of Return stack to TOS	n2	n1	n2l	n1l		n2						ROT	n1		n3	Rotate TOS-2 to TOS	R@		n	Copy Top of Return stack to TOS	n2	n1					n3	n2			PICK	n	n2	Copy TOS-n to TOS n = 2 shown	
DROP	n		Drop TOS	2SWAP		n1h	n2h	Exchange Double-Precision numbers																																																																																				
						n1l	n2l		SWAP		n1	n2	Exchange TOS and TOS-1	>R	n			Move TOS to Return stack		n2	n1	n1h	n2h				n2h	n1h			OVER	n1	n2		Copy TOS-1 to TOS	R>	n1l	n1l	Move Top of Return stack to TOS	n2	n1	n2l	n1l		n2				ROT		n1	n3		Rotate TOS-2 to TOS	R@			n	Copy Top of Return stack to TOS	n2	n1			n3	n2			PICK		n	n2	Copy TOS-n to TOS n = 2 shown							n1	n1			n2	n2								
SWAP	n1	n2	Exchange TOS and TOS-1		>R	n				Move TOS to Return stack																																																																																		
	n2	n1				n1h	n2h																																																																																					
				n2h		n1h																																																																																						
OVER	n1	n2	Copy TOS-1 to TOS	R>		n1l	n1l	Move Top of Return stack to TOS																																																																																				
	n2	n1			n2l	n1l																																																																																						
		n2																																																																																										
ROT	n1	n3	Rotate TOS-2 to TOS		R@		n		Copy Top of Return stack to TOS																																																																																			
	n2	n1																																																																																										
	n3	n2																																																																																										
PICK	n	n2	Copy TOS-n to TOS n = 2 shown																																																																																									
	n1	n1																																																																																										
	n2	n2																																																																																										

Memory							
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
CMOVE	n		Copy n bytes from RAM start address S to destination D	!	RAM address		Write 16-bit number n to RAM address
	RAM address S				n		
	RAM address D						
FILL	n1		Fill n1 bytes with character n2 starting at RAM address	C!	RAM address		Write byte n to RAM address
	n2				n		
	RAM address						
@	RAM address	n	Read 16-bit number n at RAM address to TOS	ARRAY1D	n		Creates 1D array <name> size n words
C@	RAM address	n	Read byte n at RAM address to TOS	ALLOT	n		Moves Code pointer in RAM up by n bytes

Arithmetic				SP = Single Precision (16-bit) DP = Double Precision (32-bit)			
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
+	n1	r	SP to SP signed addition $n1 + n2 \rightarrow r$	2*	n	r	SP to SP signed multiply by 2 $n \times 2 \rightarrow r$
	n2						
-	n1	r	SP to SP signed subtract $n2 - n1 \rightarrow r$	2/	n	r	SP to SP signed divide by 2 $n / 2 \rightarrow r$
	n2						
*	n1	r	SP to SP signed multiply $n1 \times n2 \rightarrow r$	1+	n	r	SP to SP signed increment $n + 1 \rightarrow r$
	n2						
/	n1	r	SP to SP signed division $n2 / n1 \rightarrow r$	1-	n	r	SP to SP signed decrement $n - 1 \rightarrow r$
	n2						
M*	n1	rh	SP to DP signed multiply $n1 \times n2 \rightarrow rh,rl$	2+	n	r	SP to SP signed increment by 2 $n + 2 \rightarrow r$
	n2	rl					
U*	n1	rh	SP to DP unsigned multiply $n1 \times n2 \rightarrow rh,rl$	2-	n	r	SP to SP signed decrement by 2 $n - 2 \rightarrow r$
	n2	rl					
M/	n	r	DP to SP signed division $(nh,nl) / n \rightarrow r$	ABS	n	r	SP to SP absolute (Make positive) $ n  \rightarrow r$
	nh						
/MOD	n1	r	SP to SP signed division & remainder $n2 / n1 \rightarrow r,rem$	DABS	nh	rh	DP to DP absolute (Make positive) $ nh,nl  \rightarrow rh,rl$
	n2	rem			nl	rl	
U/MOD	n1	r	SP to SP unsigned division & remainder $n2 / n1 \rightarrow r,rem$	+!	RAM address		SP addition to data in RAM $[addr] + n \rightarrow [addr]$
	n2	rem			n		
M/MOD	n	rh	DP to DP unsigned division & remainder $(nh,nl) / n \rightarrow rh,rl,rem$	S->D	n	rh	Sign extend SP to DP number $n \rightarrow rh,rl$
	nh	rl					
	nl	rem					
NEGATE	n	r	SP to SP negate $-n \rightarrow r$	*/	n	r	SP to SP signed multiply then divide $(n1 \times n2) / n \rightarrow r$
					n1		
DNEGATE	nh	rh	DP to DP negate $-(nh,nl) \rightarrow rh,rl$	*/MOD	n	r	SP to SP signed multiply then divide $(n1 \times n2) / n \rightarrow r,rem$
	nl	rl			n1	rem	
					n2		
DADD	n1h	rh	DP to DP addition $(n1h,n1l) + (n2h,n2l) \rightarrow rh,rl$				
	n1l	rl					
	n2h						
	n2l						

Logic							
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
AND	n1	r	Logical AND of TOS and TOS-1	NOT	n	n	Bit inversion of TOS (1's Compliment)
	n2						
OR	n1	r	Logical Inclusive OR of TOS and TOS-1	TOGGLE	pattern		Exclusive OR of data byte pattern at RAM address
	n2				RAM address		
XOR	n1	r	Logical Exclusive OR of TOS and TOS-1				
	n2						

Comparison				Flag state: 0 = False -1 = True			
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
=	n1	flag	TOS = True if n2 = n1 False if n2 <> n1	0>	n	flag	TOS = True if n > 0
	n2						
>	n1	flag	TOS = True if n2 > n1 False if n2 <= n1	0<	n	flag	TOS = True if n < 0
	n2						
<	n1	flag	TOS = True if n2 < n1 False if n2 => n1	MAX	n1	r	Larger of TOS and TOS-1 left on TOS
	n2				n2		
U<	n1	flag	TOS = True if n2 < n1 unsigned False if n2 => n1	MIN	n1	r	Smaller of TOS and TOS-1 left on TOS
	n2				n2		
0=	n	flag	TOS = True if n = 0				

Terminal I/O							
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
.	n		Print signed SP number n with trailing space	INKEY		Character / 0	TOS = keyboard character or 0 if none available
U.	n		Print unsigned SP number n with trailing space			character	
D.	nh		Print signed DP number with trailing space	QUERY			Read line of keyboard input to buffer
	nl						
F.	n		Print formatted signed DP number in field width n	EMIT	character		Print ASCII character
	nh						
R.	n		Print formatted signed SP number n1 in field width n	CR			Print Carriage Return and Line Feed
	n1						
?	RAM address		Print SP number stored at RAM address	SPACE			Print Space character
COUNT	Pointer	character	Get string character from pointer then increment pointer	SPACES	n		Print n Spaces
		Pointer+1					
TYPE	String length n		Print n characters from pointer. Used with COUNT	.(			Print string up to ) Command line only
	Pointer						

System Variables and Stack							
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
CODE		RAM address	TOS = address of User Code pointer	I		n	TOS = value of first level DO...LOOP index
HERE		RAM address	TOS = address of User Vocabulary pointer	J		n	TOS = value of second level DO...LOOP index
BASE		RAM address	TOS = address of number BASE variable	K		n	TOS = value of third level DO...LOOP index
DECIMAL			Set number BASE = 10	SP!			Reset Parameter stack pointer to TOS
HEX			Set number BASE = 16	DEPTH		n	TOS = number of items on Parameter stack
CONSTANT	n		Define CONSTANT <name> value n	VARIABLE			Define VARIABLE <name>

System Commands							
Word	Stack Before	Stack After	Action	Word	Stack Before	Stack After	Action
VLIST			List all ForthdsPIC & new User words in RAM	ABORT			Force system reset
FORGET			Erase all user words in RAM from <name> onwards	FLASH			Copy user RAM area to user Flash memory area
EXECUTE	Pointer		Execute code at address located at [pointer]	ERASE			Erase user Flash memory area
QUIT			Exit program & clear all stacks	SETFLSH			Set Flash status flag
CREATE.. ..DOES>			Create new definition with <name> and action code	SETRAM			Clear Flash status flag

Loop Structures			
Word	Stack Before	Stack After	Action
n2 n1 DO...[LEAVE]...LOOP	n1		Execute words between DO and LOOP n2 – n1 times. n1 is the loop index incremented by 1 each time round the loop. Accessed within the loop by using I which leaves the index on TOS. Optional LEAVE forces early exit.
	n2		
n2 n1 DO..[LEAVE]..n3 +LOOP	n1		As for DO...LOOP but index increment set by n3.
	n2		
BEGIN....WHILE....REPEAT			Execute a loop WHILE TOS = True
BEGIN....UNTIL			Execute a loop UNTIL TOS = True
BEGIN....AGAIN			Execute a continuous loop



<b>Conditional Structures</b>			
Word	Stack Before	Stack After	Action
<b>IF....ELSE....THEN</b>	Flag		If flag = True, words following IF executed and words after ELSE skipped. If flag = False, words between IF and ELSE skipped and words after ELSE executed.
<b>CASE...OF...ENDOF...ENDCASE</b>	n		CASE begins list of conditional actions. If n = number before OF then words between OF and ENDOF executed and execution skips to ENDCASE. If not equal, skip to next OF.... ENDOF line.

<b>Embedded Functions</b>			
Word	Stack Before	Stack After	Action
<b>WAIT</b>	n		Wait for n milliseconds
<b>TIMSET TIMSRT TIMSTP TIMRD</b>		rh	TIMSET sets up 32-bit user timer. TIMSRT starts timer. TIMSTP stops timer. TIMRD reads timer and pushes on stack. Timer clocked at 40MHz.
		rl	
<b>SVOSET SERVO</b>	Servo No		SVOSET initialises OC1 to OC4 as PWM outputs. SERVO moves Servo No (1-4) to Angle (0-180 degrees)
	Angle		

---

## Appendix 2. Sample Forth programs

Walking robot program with four servomotors

The DO...LOOPS rotate each servo by one degree followed by a 10ms delay each time round the loop. This slows the joint movement down to a realistic level.

```
( Program 6: Servo test for walking robot )
( STEP performs one leg movement cycle )
( Servo 1 = right ankle, Servo 2 = left ankle )
( Servo 3 = right hip, Servo 4 = left hip )

: HOME      ( Starting position: Left foot forward, right back )
  90 1 SERVO 90 2 SERVO 120 3 SERVO 120 4 SERVO ;

: LEANLEFT  ( Balance on left leg )
  121 90 DO I 2 SERVO 10 WAIT LOOP
  141 90 DO I 1 SERVO 10 WAIT LOOP
  129 140 DO I 1 SERVO 10 WAIT -1 +LOOP ;

: ROTATELEFT ( Rotate on left leg )
  59 120 DO I 3 SERVO I 4 SERVO 10 WAIT -1 +LOOP ;

: LEANLEFTBACK ( Return right leg to floor )
  89 120 DO I 2 SERVO 10 WAIT -1 +LOOP
  89 130 DO I 1 SERVO 10 WAIT -1 +LOOP ;

: LEANRIGHT ( Balance on right leg )
  59 90 DO I 1 SERVO 10 WAIT -1 +LOOP
  39 90 DO I 2 SERVO 10 WAIT -1 +LOOP
  51 40 DO I 2 SERVO 10 WAIT LOOP ;

: ROTATERIGHT ( Rotate on right leg )
  121 60 DO I 3 SERVO I 4 SERVO 10 WAIT LOOP ;

: LEANRIGHTBACK ( Return left leg to floor )
  91 60 DO I 1 SERVO 10 WAIT LOOP
  91 50 DO I 2 SERVO 10 WAIT LOOP ;

: STEPRIGHT ( Move right leg forward )
  LEANLEFT ROTATELEFT LEANLEFTBACK ;

: STEPLEFT ( Move left leg forward )
  LEANRIGHT ROTATERIGHT LEANRIGHTBACK ;

: STEP      ( Full step forward )
  STEPRIGHT STEPLEFT ;

: WALK      ( Walks until a key is pressed )
  SVOSET HOME BEGIN
  STEP INKEY
  0= WHILE REPEAT ;
```

## Forth Timing Benchmark Program

```
( Program 7. FORTH Benchmarks adapted for FORTHdsPIC 40MHz clock )

: HEADINGR CR ." RAM Benchmarks" CR ;

: BM1 TIMSET TMSRT 10001 1 DO SP! LOOP TIMSTP
  CR TIMRD 40 M/MOD ." BM1: " 8 F. ." usecs" DROP ;          ( Multiplier )

: BM2 TIMSET TMSRT 10001 1 DO 11 1 DO LOOP SP! LOOP TIMSTP   ( DO LOOP )
  CR TIMRD 40 M/MOD ." BM2: " 8 F. ." usecs" DROP ;

: BM3 TIMSET TMSRT 10001 1 DO 11 1 DO 9 LOOP SP! LOOP TIMSTP ( Literal )
  CR TIMRD 40 M/MOD ." BM3: " 8 F. ." usecs" DROP ;

VARIABLE V
: BM4 TIMSET TMSRT 10001 1 DO 11 1 DO V LOOP SP! LOOP TIMSTP ( Variable )
  CR TIMRD 40 M/MOD ." BM4: " 8 F. ." usecs" DROP ;

: BM5 TIMSET TMSRT 10001 1 DO 11 1 DO 9 V ! LOOP SP! LOOP TIMSTP ( Save variable )
  CR TIMRD 40 M/MOD ." BM5: " 8 F. ." usecs" DROP ;

: BM6 TIMSET TMSRT 10001 1 DO 11 1 DO V @ LOOP SP! LOOP TIMSTP ( Read variable )
  CR TIMRD 40 M/MOD ." BM6: " 8 F. ." usecs" DROP ;

9 CONSTANT C
: BM7 TIMSET TMSRT 10001 1 DO 11 1 DO C LOOP SP! LOOP TIMSTP ( Read constant )
  CR TIMRD 40 M/MOD ." BM7: " 8 F. ." usecs" DROP ;

: BM8 TIMSET TMSRT 10001 1 DO 11 1 DO 9 DUP LOOP SP! LOOP TIMSTP ( DUP ToS )
  CR TIMRD 40 M/MOD ." BM8: " 8 F. ." usecs" DROP ;

: BM9 TIMSET TMSRT 10001 1 DO 11 1 DO 9 1+ LOOP SP! LOOP TIMSTP ( Increment ToS )
  CR TIMRD 40 M/MOD ." BM9: " 8 F. ." usecs" DROP ;

: BM10 TIMSET TMSRT 10001 1 DO 11 1 DO 9 9 > LOOP SP! LOOP TIMSTP ( Greater than )
  CR TIMRD 40 M/MOD ." BM10: " 8 F. ." usecs" DROP ;

: BM11 TIMSET TMSRT 10001 1 DO 11 1 DO 9 9 < LOOP SP! LOOP TIMSTP ( Less than )
  CR TIMRD 40 M/MOD ." BM11: " 8 F. ." usecs" DROP ;

: BM12 TIMSET TMSRT 10001 1 DO 1 BEGIN 1+ DUP 11 < WHILE REPEAT ( BEGIN WHILE )
  SP! LOOP TIMSTP
  CR TIMRD 40 M/MOD ." BM12: " 8 F. ." usecs" DROP ;

: BM13 TIMSET TMSRT 10001 1 DO 20 BEGIN 1- DUP 11 < UNTIL      ( BEGIN UNTIL )
  SP! LOOP TIMSTP
  CR TIMRD 40 M/MOD ." BM13: " 8 F. ." usecs" DROP ;

: TEN ; : NINE TEN ; : EIGHT NINE ; : SEVEN EIGHT ; : SIX SEVEN ; : FIVE SIX ;
: FOUR FIVE ; : THREE FOUR ; : TWO THREE ; : ONE TWO ;

: BM14 TIMSET TMSRT 10001 1 DO ONE SP! LOOP TIMSTP           ( Compile )
  CR TIMRD 40 M/MOD ." BM14: " 8 F. ." usecs" DROP ;

: BM15 TIMSET TMSRT 10001 1 DO 9 2 / 3 * 4 + 5 - SP! LOOP TIMSTP ( SP Maths )
  CR TIMRD 40 M/MOD ." BM15: " 8 F. ." usecs" DROP ;

: BM16 TIMSET TMSRT 10001 1 DO 900 900 M* 9 M/ 90000.        ( DP Maths )
  DNEGATE D+ SP! LOOP TIMSTP
  CR TIMRD 40 M/MOD ." BM16: " 8 F. ." usecs" DROP ;

: BENCH HEADINGR BM1 BM2 BM3 BM4 BM5 BM6 BM7 BM8 BM9 BM10 BM11 ( Full Test )
  BM12 BM13 BM14 BM15 BM16 ;
```

---

## Fast Fourier Transform program

```
( Program 8. Fast Fourier Transform )
( 256-point 16-bit signed complex )
( W.G Marshall 2014 )

257 ARRAY1D REAL
257 ARRAY1D IMAG
256 ARRAY1D C/S
257 ARRAY1D POWER
VARIABLE J1
VARIABLE K1
VARIABLE L1
VARIABLE M1
VARIABLE M2
VARIABLE M3
VARIABLE U1
VARIABLE U2
VARIABLE SFACT

: REORDER 1 J1 !      ( Decimation in time )
256 1 DO
  I J1 @ <
  IF J1 @ REAL DUP @ I REAL DUP @
  ROT ROT ! SWAP !
  THEN 128 K1 !
  BEGIN
  K1 @ DUP J1 @ <
  WHILE
  J1 @ OVER - J1 ! 2/ K1 !
  REPEAT
  J1 +!
LOOP ;

: SCALE 0 257 1 DO      ( Automatic scaling )
I REAL @ DUP 13312 >
IF DROP NOT LEAVE
ELSE -13312 <
IF DROP NOT LEAVE THEN THEN
  I IMAG @ DUP 13312 >
  IF DROP NOT LEAVE
  ELSE -13312 <
  IF DROP NOT LEAVE THEN THEN
LOOP
IF 257 1 DO I REAL DUP @ 2/ SWAP !
I IMAG DUP @ 2/ SWAP !
LOOP SFACT DUP @ 2* SWAP C! THEN ;

: FFT 1 DUP M1 ! SFACT ! 256 M2 ! 9 1 DO      ( 256-point FFT )
SCALE M2 DUP @ 2/ SWAP C! 0 M3 !
M1 @ DUP 2* M1 ! DUP K1 C! 1+ 1 DO
  M3 @ DUP C/S @ U2 ! 192 + 255 AND C/S @ U1 !
  256 I DO
    I K1 @ + L1 !
    L1 @ REAL @ DUP U1 @ 32767 */
    L1 @ IMAG @ DUP U2 @ 32767 */
    ROT SWAP - SWAP U1 @ 32767 */
    ROT U2 @ 32767 */ +
    DUP I IMAG @ SWAP - L1 @ IMAG ! I IMAG +!
    DUP I REAL @ SWAP - L1 @ REAL ! I REAL +! M1 @
  +LOOP
M3 @ M2 @ + M3 C!
LOOP
LOOP ;
```

```

: POW 257 1 DO      ( Calculate frequency power data )
  I REAL @ DUP 16384 */
  I IMAG @ DUP 16384 */ +
  I POWER !
LOOP ;

: FMAX 0 U1 !      ( Calculate maximum power )
257 1 DO
  I POWER @ U1 @ MAX U1 !
LOOP ;

: PULSE 17 1 DO    ( Create pulse data for TEST )
  DUP I REAL ! 0 I IMAG !
LOOP
DROP 257 17 DO
  0 I REAL ! 0 I IMAG !
LOOP ;

: S1 0 804 1608 2410 3212 4011 4808 5602 6393 7179 7962 8739 9512 10278 11039 11793      ( Create Sine table )
12539 13279 14010 14732 15446 16151 16846 17530 18204 18867 19519 20159 20787 21403 22005 22594
23170 23731 24279 24811 25329 25832 26319 26790 27245 27683 28105 28510 28898 29268 29621 29956
30273 30571 30852 31113 31356 31580 31785 31971 32137 32285 32412 32521 32609 32678 32728 32757 32767
127 192 DO I C/S ! -1 +LOOP ;

: S2 1 256 193 DO
  DUP 192 SWAP - C/S @ I C/S ! 1+
  LOOP
DROP ;

: S3 256 128 DO
  I C/S @ NEGATE I 128 - C/S !
  LOOP ;

: SIN S1 S2 S3 ;    ( Create -Sine/Cosine table )

: VIEW 128 1 DO     ( Print Real frequency data in a table )
  I 8 + I DO
  I REAL @ 7 R.
  LOOP
  CR
  8 +LOOP ;

: TEST              ( Perform FFT on a single rectangular pulse )
SIN
16000 PULSE
TIMSET TIMSRT REORDER FFT TIMSTP    ( Time reorder and FFT )
VIEW
20 SPACES ." Scaling Factor = " SFACT ?
TIMRD 40 M/MOD CR 24 SPACES D. ." usecs" DROP ;

: GRAPH POW FMAX U1 @ 22 / U1 ! ( Print power graph )
CR ." Power |" CR
0 22 DO
  6 SPACES ." | "
  41 1 DO
    I POWER @ U1 @ / J < IF
    SPACE
  ELSE
    ." #"
  THEN
  LOOP
  CR
  -1 +LOOP
6 SPACES 42 1 DO ." -" LOOP SPACE ." Frequency" CR ;

```