Scope and Motivations

Constraint Solver

Extensions to Prolog

Iteration Constructs

Constraint
Satisfaction

The Interval Constraints Library

Search and Optimization with

Other Constrai

An Introduction to Constraint (Logic) Programming Using ECLⁱPS^e

Stefano Benedettini

DEIS - Dipartimento di Elettronica Informatica e Sistemistica University Bologna, Second Faculty of Engineering

Artificial Intelligence 2010

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Search and Optimization with ECL'PS® 1 Prolog as a Constraint Solver

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Other Constraint

- Constraint Logic Programming (CLP)
- ECLⁱPS^e constraint solver
- Search methods for CLP (hints)

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- Re-discover Prolog as a constraint solver
- Familiarize with ECLⁱPS^e and its extensions to standard Prolog
- Get a grasp of Constraint Logic Programming
 - Learn how to model problems in ECLⁱPS^e
 - Use constraint libraries
- ...have fun with the solver

Re-discover Prolog as a constraint solver

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Search and Optimization with ECL[']PS^o Other Constraint Laboratory lessons will follow a hands-on approach

- During lessons you are supposed to experiment with tools and techniques
 - Few novel theoretical concepts will be introduced
- In order to make the most out of these lessons you should:
 - Have a fair theoretical background (i.e., study stuff you saw during classes)
 - Explore new technologies on your own (documentations, tutorials, websites)
 - Be productive as soon as possible

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 - ...anything else?



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- During lessons you are supposed to experiment with tools and techniques
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- In order to make the most out of these lessons you should:
 - Have a fair theoretical background (i.e., study stuff you saw during classes)
 - Explore new technologies on your own (documentations, tutorials, websites)
 - Be productive as soon as possible
- Ah, of course! You should have fun!

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- During this course a good understanding of Prolog will be assumed
 - You all followed Viroli's course so you'll probably know Prolog better than me anyway...
- We will use fancy stuff like custom operators and structures
- We won't use fancier stuff like metaprogramming
 - Though you're free to explore by yourselves

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Other Cons

- At this point any Prolog implementation will do
- But we will abandon the usual Prolog fairly soon
- You'd better start with ECLⁱPS^e right away

http://eclipse-clp.org/

Resources for ECL¹PS^e

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- ECLⁱPS^e main site http://eclipse-clp.org/
- 2 http://eclipse-clp.org/examples
- Seep your friends close but your documentation closer:
 - http://eclipse-clp.org/doc (we will use that in due time)
- Introductory book on CP using ECLⁱPS^e: Constraint Logic Programming Using ECLⁱPS^e

Resources for Constraint Programming in General

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Search and Optimization with ECL¹PS^o Other Constraint • CS problems and models in various languages:

http://www.csplib.org/

- Gecode: <u>THE</u> C++ library for CP (not for the faint of heart)
- Guido Tack's Ph.D. dissertation (for a challenge)
- Java library: http://jacop.osolpro.com/
- Python library (proprietary): http://www.eveutilities.com/products/emma
- Python library (GPL): http://labix.org/python-constraint

Comet language:

```
http://dynadec.com/support/downloads/(keep
an eye on this)
```

- On-line guide to CP by Roman Bartak
 - ...and much more!
- A blog on CP (serious stuff)

Mapping CSPs in Prolog

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What we would like to do

- Setup variables and domains
- State constraints
- Specify a search strategy

What Prolog has to offer

- Logic variables and closed world assumption
- Predicates can be seen as very basic form of constraint
- Backtracking for free

What Prolog lacks

- Constraint propagation ⇒ Efficiency!
- Constraints and variables are not first-class citizens

Constraints in Prolog

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Optimization wit

Any predicate is really a constraint

```
member(X, [X|_]).
member(X, [\_|T]) :- member(X, T).
p(X, X).
p(X, 3).
:- member(X, [1, 2, 3, 4]), X > 2.
vields X = 3, X = 4, while
:- member(X, [1, 2, 3, 4]), member(Y, [2, 3, 4, 5]),
    p(X, Y).
yields (X, Y) = (1, 3), (2, 2), (2, 3), (3, 3), (3, 3), (4, 3), (4, 4)
```

Do Constraints in Prolog Really Work...?

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Example

How about these?

```
:- X > 3, X < 2. % clearly inconsistent
:- 4 is X + 3. % clearly X = 1
```

Both raise an "Instantiation fault" error

- Non-logical predicates and closed world assumption are Prolog greatest weaknesses
- Variables in arithmetic predicates <u>must be instantiated</u> (else error)
- For which values the second query is satisfied? For none, because you never told Prolog that 1 + 3 is true

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Search and Optimization with ECL¹PS⁰ Consequences

- Constraints can only be tested for satisfiability
 - There is no "constraint propagation" (domain reduction)
- Prolog natively supports only generate and test!

CSP in Prolog

```
solve_problem(Variables) :-
  declare_domains(Variables),
  search(Variables),
  test_constraints(Variables).
```

- First I generate a complete assignment to the decision variables
- Then I test satisfiability

The Simplest Prolog Constraint Solver That Can Possibly Work

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```
% Define domains for a list of variables
domain([], _, []).
domain([H|T], D, [H dom D|Rest]) :- domain(T, D, Rest
    ) .
% Define integral domains for a list of variables
ints(Xs, Min, Max, Vs) :-
 int_range(Min, Max, R),
 domain(Xs, R, Vs).
% Simple labeling
label([]).
label([V dom D|T]) := member(V, D), label(T).
```

Some Constraints

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```
% In constraint
X \text{ in } D :- member(X, D).
% Not in constraint
_ not_in [].
X \text{ not_in } [H|T] := \text{not}(X \text{ in } [H|T]).
% All different
all different([]).
all_different([H|T]) :-
 all different(T),
 H not_in T.
% Ordered
ordered([_]).
ordered([X, Y|Z]) :- X < Y, ordered([Y|Z]).
```

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 $ECL^{i}PS^{e}$ supports a number of extensions that facilitate Prolog programming:

- Structures and arrays
- "Function-like" predicates
- Iteration constructs
- 4 Modules

For more information, please refer to the User Manual ECLⁱPS^e is a mature piece of software. We won't have time to cover everything. You are encouraged to explore by yourselves.

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Search and Optimization with ECL¹PS^a Unofficial name to refer to a syntactic facility that allows you to use custom predicates in expression context

- "Expression Context" is wherever ECLⁱPS^e expects arithmetic operations that are subsequently evaluated
- Usually indicated with metavariable Expr in documentation
- You can use a n-ary predicate $p(X_1, \ldots, X_n)$ as a function that expects X_1, \ldots, X_{n-1} as arguments and returns X_n as result

```
p(_, 3).
summation([], 0).
summation([H|T], S) :- summation(T, S1), S is S1 + H.
:- 10 is 7 + p(ciao).
:- 19 < summation([1, 2, 3]) + 15.</pre>
```

Structure Notation

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Optimization wit

 An easy way to declare and access arguments of a Prolog structure

Declare a structure using:

```
:- local struct(functorName(fieldNames...))
```

- Can refer to fields by name instead of index
- Use fieldName of structName to obtain field index

Example

Declaring and using a structure

```
:- local struct(student(name, surname, exam, mark)).
```

```
:- student{name: john, surname:doe} = student(N, SN, _
, _), N = john, SN = doe.
```

```
:- S = student{name: jane}, arg(4, S, 30), S = student (jane, _, _, M), M = 30.
```

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 ECLⁱPS^e does not support directly enumerations, but they can be emulated via structures

- Encode each value of your enumeration with an integer
- Declare a structure whose field names are the enumeration values
- Use operator of to map a value to an integer
- You should never instantiate a structure of that kind
- The inverse mapping is not as easy

Example

A color example

- :- local struct(colors(black, white, red, green, blue
)).
 - :- X = black of colors, X = 1
- :- X is (white of colors) + (red of colors), X = 5 % useless but still

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- Arrays in ECLⁱPS^e are really a syntactic convenience to indicate structures of structures
- Functor name is irrelevant
 - matrix(row(1, 2, 3), row(4, 5, 6)) is a 2×3 array and so is a(b(1, 2, 3), c(4, 5, 6))
- dim(A, D) unifies a new array A with functor name [] and its dimensions D
- Use subscript/3 to access individual elements or array slices
- Usual C-like subscription operator available in expression context provides same behaviour as subscript/3

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Why Iteration in Prolog?

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Search and Optimization with ECL¹PS^e Although every form of iteration can be expressed by a recursion, this bring some disadvantages:

Code bloat: every iteration requires you to write an additional predicate

Readability: those predicates are coded far away in your code and impact readability

Non-locality: if your iteration has to access many local variables, you have to write a predicate with that many parameters

Iteration in ECLⁱPS^e is as powerful as recursion and often more concise

Iteration Constructs Generalities

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- All iteration constructs have the form (IterationSpecifiers do Body)
- IterationSpecifiers is a comma-separated sequence of iteration specifiers
- Each specifier introduces an iteration variable visible only in *Body*
- Body can access only variables provided by iteration specifiers (but see param)
- Each iteration step, iterations variables in Body are unified with iteration values
- All iteration specifiers step in parallel and the whole loop stops when one of the specifiers completes

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- (foreach(E, List) do Body) executes goal Body iteratively unifying E to each element in list List
- Has invertible semantics: can be used to scan a list or to construct a list

- :- (foreach(E, [1, 2, 3]) do writeln(E)). % prints 1 2 3
- :- (foreach(X, L), foreach(E, [10, 20, 30]) do X **is** E // 10), L = [1, 2, 3].

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Iteration Constructs: param and count

- param(Variables...) makes Variables visible inside iteration body
- count(Index, MinExpr, MaxExpr) unifies Index to each integer in [MinExpr, MaxExpr]

Example

```
multiply(L, K, Out) :-
  (foreach(E, L), foreach(X, Out), param(K) do X is K
   * E).

my_length(L, X) :- % same as length/2 builtin
```

```
:- (count(I, 1, 4) do writeln(I)). % prints 1 2 3 4
```

(foreach(_, L), count(_, 1, X) do true).

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Iteration Constructs: foreacharg and foreachelem

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- foreacharg/2 iterates on a structure/array arguments
 - foreachelem/2 works only for arrays (functor name must be []). Flattens the array and iterate on its elements
- Both support an optional third argument that is unified to element index

```
ECL<sup>j</sup>PS<sup>e</sup> CLP
```

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Libraries

Iteration Constructs: for and multifor

- for(Index, MinExpr, MaxExpr) work like its imperative counterpart
- multifor(IndexList, MinList, MaxList) concisely describes multiply nested fors
- Both constructs support an optional fourth argument to provide an iteration step

```
evens(L) :-
   (for(I, 2, 100, 2), foreach(I, L) do true).

mutliplication_table(T) :-
   dim(T, [10, 10]),
   (multifor([X, Y], [1, 1], [10, 10]), % also multifor
        ([X, Y], 1, 10)
   foreachelem(E, T) do
        E is X * Y
).
```

```
ECL<sup>i</sup>PS<sup>e</sup> CLP
```

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Iteration Constructs: fromto

- Most general construct
- (fromto(Init, In, Out, Last) do Body) introduces local variables In and Out in Body and behaves as follows:
 - 1 First Init = In
 - Executes iteration body
 - 3 After each iteration checks whether Last = Out and breaks if unification succeeds
 - 4 Otherwise unifies a fresh *In* variable with *Out* and repeats from step 2

```
filter_even(L, F) :-
  (foreach(E, L), fromto(L, In, Out, []) do
     (0 is E rem 2 -> In = [E|T], Out = T; In = Out)
  ).

reverse(L, R) :-
  (foreach(E, L), fromto([], In, [E|In], R) do true).
```

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ECLⁱPS^e Modules in a Nutshell

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Advantages

- Group functionally related predicates in the same place
 - Usually one module for each file
- Control naming access
- Modules form a namespace structure

Using modules

- use lib(ModuleName) to compile an ECL^iPS^e library and import exported names
- use use_module(ModuleName) to compile a module and import its exported names
- use : operator to disambiguate a name: ModuleName: (predicate)

ECLⁱPS^e Modules in a Nutshell

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Writing modules

but print row is not.

- use directive module(ModuleName) at the top of a source file to define a module
- export directive states which predicates to export

Example

```
:- module(my_little_module).
:- export print_matrix/1.

print_row(Row) :-
    (foreachelem(E, Row) do write(E), write(" ")),
    nl.

print_matrix(M) :-
    (foreacharg(Row, M), param(M) do print_row(Row)).

print_matrix is available when this module is imported
```

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Overcoming Prolog Limitations

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The Disease

- Variables in arithmetic constraints must be instantiated
- Constraint predicates are mostly used for testing and cannot instantiate variables except the simplest like or, and, etc...
- No constraint propagation

The Cure

- Every goal (i.e., constraint) that is not fully instantiated is suspended and put into the constraint store
- Propagation is applied to variable domains at different strength

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Example

```
ordered_list([_]).
ordered_list([X, Y|T]) :- X < Y, ordered_list([Y|T]).</pre>
```

- :- ordered_list([1, 2, 3, 4, 5]). % works as expected
- :- ordered_list([1, X, 3, Y, 5]). % we suppose X, Y be integral variables

The second goal raises an instantiation error.

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Example

In the first case ECL^{j}PS^{e} enforces variable integrality and correctly propagates the constraints 1 < X < 3 and 3 < Y < 5 thereby inferring X = 2, Y = 4.

In the second case we have a delayed goal, that is a goal that cannot be solved at the moment. $ECL^{i}PS^{e}$ propagates inequalities and infers $X \in 2, 3, Y \in 3, 4$.

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CSP in ECLⁱPS^e

```
solve_problem(Variables) :-
```

```
declare_domains(Variables),
setup_constraints(Variables),
search(Variables).
```

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```
CSP in ECL^iPS^e
```

```
solve_problem(Variables) :-
  declare_domains(Variables),
  setup_constraints(Variables),
  search(Variables).
```

This part comprises model definition.

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Scope and Motivations

Prolog as a Constraint Solver

ECL¹PS^e
Extensions to
Prolog

Syntactic Facilities
Iteration Constructs
Modules

Constraint
Satisfaction
with Ect. 1 pg6

The Interval Constraints Library

Search and Optimization with

Other Const

```
CSP in ECL<sup>i</sup>PS<sup>e</sup>
```

```
solve_problem(Variables) :-
```

```
declare_domains(Variables),
setup_constraints(Variables),
search(Variables).
```

This is the actual search.

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CSP in ECLⁱPS^e

```
solve_problem(Variables) :-
  declare_domains(Variables),
  setup_constraints(Variables),
  search(Variables).
```

Modeling and search are independent phases in the resolution of a problem.

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```
CSP in ECL<sup>i</sup>PS<sup>e</sup>
```

```
solve_problem(Variables) :-
  declare_domains(Variables),
  setup_constraints(Variables),
  search(Variables).
```

Problem model and choice points

- Do not leave choice points during constraint setup!
- If you do, the solver will miss an opportunity do constraint propagation
- You are actually splitting a CSP into multiple CSPs, making choices before propagation, not after
- But it doesn't mean you can't use Prolog non determinism

An Overview of the Libraries

 We'll mostly use only the more recent ic library and briefly touch its derivatives:

```
ic global very useful global constraints
  ic_sets supports set variables
ic symbolic handles (not so) conveniently symbolic
           domains
```

- Don't use old fd libraries: stick with ic!
- Basic searching strategies and B&B optimization
- Many more constraints available (look them up in the documentation):
 - Bin packing
 - Knapsack
 - Scheduling
- Generalized Propagation and Constraint Handling Rules (CHR) will be barely mentioned

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The Interval Constraints Library:

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Constraint Solver

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Syntactic Facilities

Iteration Constructs

Constraint Satisfaction with ECLⁱPS⁶

The Interval Constraints Library:

Search and Optimization with ECL¹PS⁶ Powerful hybrid solver that works on (intervals of) integers and reals

- Variable domains are unions of disjoint intervals
- It enforces bound consistency:
 - Weaker than arc-consistency
 - Iteratively "squeezes" a variable domain: $x, y \in [0, 5] \cap \mathbb{Z}, x < y \Rightarrow x \in [0, 4], y \in [1, 5]$
 - Cannot propagate "holes"
- Handles linear, arithmetic and non-linear constraints
- Issues with real variables:
 - How do we cope with limited precision?
 - How do we represent "holes" in a real domain?
 - Does this make sense: $x \in [0, 1], x \neq 0.5$?

Variable Domains

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- Constrains integer as well real domains with ::, \$:: and #:: operators:
 - ListOfVariables :: RangeSpecification specify either an integer or a real domain depending on the range specification
 - \$:: enforces real domains
 - #:: enforces integer domain
 - I suggest to employ only #:: or \$:: to clearly state variable type
- These operators work also with multidimensional arrays
- See documentation for further details

Example

```
:- Var #:: [1..5, 7, 9..12].
:- [X, Y] #:: 1..5.
:- dim(A, [3, 2]), A :: 0..1.0.
```

Arithmetic Constraints

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- ic support every arithmetic and comparison operator of standard Prolog
 - qualified use: ic:(X op Y) where op is one of >, <, =<, =:=, =\=, +, -, *, ...
 - Prepend \$ to comparison predicates to avoid qualification: \$>, \$<, \$=<, \$=, \$\=, ...
 - Prepend # to comparison predicates to also enforce integrality: #>, #<, #=<, #=, #\=, ...
- New variables spawn into existence as soon they are used

Example

- :- [X, Y] :: 1..5.0, Z #= X + 1, ic:(Z < Y). % 1
- :- length(V, 4), V :: 0..5, (fromto(V, [X, Y|T], [Y|T], [Y|T], [_]) do ic:(X < Y)). % 2

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- ic supports basic boolean operators:
 - or, and, xor, => all infix and neg (for negation)
- \bullet They automatically enforce a boolean domain, that is $\{0,1\}$

Example

How to solve a SAT without really trying

```
:- X and (Y or Z) and (X or neg Y)
:- X and neg X
```

- 2 Infers inconsistency

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• How can we conditionally enforce a constraint?

- How can I express if $x \in [1,3]$ then y < z?
- Remember that we cannot leave choice points so, for instance, operator -> is out of question
- Reified constraints come to the rescue
- Domain, comparison and boolean constraints all have a reified version
 - If the original constraint is op(X, Y), its reified version is op(X, Y, B) where B is a boolean variable
 - If B = 1 the constraint holds, otherwise holds its negation
- Thanks to "function-like predicate" facility we can "chain" reified constraints in expression context

```
:- \#<(X, Y, B1), \#::(X, 1...5, B2), B1  or B2.
```

becomes

:- (X # < Y) or (X # : : 1...5).

The Interval Constraints Library:

- Most of constraints in ic are binary
 - Also alldifferent is nothing more than manually setting pairwise inequalities
- We need a better way to model global constraints than separating them in binary constraints
 - Propagation strength is lower
 - That is we cannot rule out as many values as a we could
- Enter ic_global
 - Lots of high level constraints:
 - Minimum/maximum of a list
 - occurrences
 - a stronger alldifferent
 - ordered (useful for symmetry breaking)
- Also check ac_eqin ic
 - Provides an arc-consistent (and not only bound consistent) version of X #= Y + C (C is an integer constant)

An Example with Global Constraints

```
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```

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```
:- length(V, 100), V #:: 1..99, ic:alldifferent(V).
:- length(V, 100), V #:: 1..99, ic_global:
    alldifferent(V).
:- length(V, 5), V #:: 1..5, ordered(<, V).
:- [X, Y] #:: 1..10, X #\= 7, X #= Y + 2.
:- [X, Y] #:: 1..10, X #\= 7, ac_eq(X, Y, 2).</pre>
```

- Clearly inconsistent but no propagation is performed
- Immediately returns "No" as answer
- 3 Correctly infers, $X_i = i, i = 1, ..., 5$
- **3** $X \in [3,6] \cup [8,10]$ and $Y \in [1,8]$ but cannot propagate the "hole" at X=7
- **5** $X \in [3,6] \cup [8,10]$ and $Y \in [1,4] \cup [6,8]$: now it is arc consistent

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- Propagation is insufficient to prove satisfiability in all but the simplest CSPs
- In ECLⁱPS^e this translate into having delayed goals
- The simples strategy consists in:
 - Recursively considering all unassigned variables in some order
 - 2 Try all values in its domain in ascending order
 - Return a feasible assignment or backtrack and try another value
- this is called labeling

Example

Pythagorean Triplets

```
:- V = [A, B, C], V #:: 1..100, ordered(<, V), A^2 + B^2 #= C^2, findall(V, labeling(V), L).
```

- There are 52 unique Pythagorean triplets of integers in [1,100]
- Note the use of ordered to remove symmetries

Fine Tuning Your Search

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- ECLⁱPS^e provides a general mechanism to customize a search in the form of predicate ic:search
- You must specify:
 - Variable selection strategy
 - Value selection strategy
- Some heuristics are already defined:

Variable selection: input order, (anti) first-fail, most-constra

Value selection: ascending order, starting from max/middle/min value, . . .

Search strategy can have a huge impact on efficiency

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The Interval Constraints Library:

Search and Optimization with ECL¹PS⁰ ECLⁱPS^e comes also with a ready-made B&B implementation to tackle constraint optimization problems

You must also provide an objective function f

 ECLⁱPS^e B&B works as follows (for minimization problems):

- Generates a feasible solution s and impose the constraint f(s') < f(s) for the remainder of the search
- Restarts or continues the search

Example

Which is the largest integer n < 1000 such that the cube of the sum of its digits equals the number itself?

```
:- [X, Y, Z] #:: 0..9,

N #= 100 * X + 10 * Y + Z,

C #= (-N),

(X + Y + Z)^3 #= N,

minimize(labeling([X, Y, Z]), C).
```

The Interval

Search and Optimization with • ECL'PS^e comes also with a ready-made B&B implementation to tackle constraint optimization problems

- You must also provide an objective function f
- ECLⁱPS^e B&B works as follows (for minimization problems):
 - Generates a feasible solution s and impose the constraint f(s') < f(s) for the remainder of the search
 - Restarts or continues the search

Example

Convert a maximization into a minimization problem.

```
:-[X, Y, Z] #:: 0...9,
 N #= 100 * X + 10 * Y + Z,
 C #= (-N),
  (X + Y + Z)^3 #= N,
 minimize(labeling([X, Y, Z]), C).
```

The Interval

Search and Optimization with • ECL¹PS^e comes also with a ready-made B&B implementation to tackle constraint optimization problems

- You must also provide an objective function f
- ECL^IPS^e B&B works as follows (for minimization problems):
 - Generates a feasible solution s and impose the constraint f(s') < f(s) for the remainder of the search
 - Restarts or continues the search

Example

Which is the largest integer n < 1000 such that the cube of the sum of its digits equals the number itself? It's 512.

```
:-[X, Y, Z] #:: 0...9,
 N #= 100 * X + 10 * Y + Z
 C #= (-N),
  (X + Y + Z)^3 #= N,
 minimize(labeling([X, Y, Z]), C).
```

Outline

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Symbolic Domains With ic_symbolic

- Sometimes it's more natural to work with a finite domain other than (an interval of) integers
 - Colors
 - Days of the week
- ic_symbolic permits this kind of symbolic domains
- This library is implemented on top of ic
- Every value in a symbolic domain is mapped to an integer
- Define a new symbolic domain with domain declaration
 local domain(domainName(values...)).

```
Example
```

- :- local domain(weekday(mo, tu, we, th, fr, sa, su)).
- :- X &:: weekday, X & \= tu, X & < fr.

Note the implicit ordering of values.

Set Variables With ic_sets

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Constraints Library

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- This library manipulates integer set variables
- A set is simply a sorted list of integers without repetitions
- Much like ic, it provides bound consistency on set variable domains
- But what is a "range of sets"?
- A set variable σ is a triple: $\langle S_{lb}, S_{ub}, C \rangle$
 - S_{lb} is a set containing all the elements which are certainly in σ
 - S_{ub} is a set containing all the elements that might be in σ (obviously $S_{lb} \subseteq S_{ub}$)
 - C is an integer variable equal to $|\sigma|$
- See also the concept of Lattice

Example

```
:- X :: [1]..[1, 2, 3], insetdomain(X, _, _, _).
```

Finds: $\langle \{1,2,3\}, \{1,2\}, \{1,3\}, \{1\} \rangle$