

OD4 Conditioning Module



user manual

CE

1.0: Index _____

Section	Title Page
1.0	Index
2.0	Safety Information
3.0	Introduction
3.1	OD4 Mk2 Enhancements 4
4.0	Installation 5
4.1	Mounting 5
4.2	Operational Environment 6
4.2.1	Residential, Commercial & Light Industrial
	Environments 6
4.2.2	Industrial Environments 6
4.3	Electrical Connections
4.4	Connecting the Transducer 9
4.5	Connecting the Power Supply 10
4.6	Connecting the Signal Out 10
1.0 Index	<

1

Section	Title I	Page
4.6.1	Voltage Connections	10
4.6.2	Current Connections	. 11
4.7	Using an EMC Cable Gland	. 12
5.0	Setting up the Transducer and OD4	. 13
5.1	Links Explained	. 14
5.2	Basic Procedure	15
5.3	Sensitivity and the X2, X4, DIV2 Links	19
6.0	Half-Bridge Version	. 20
7.0	Specifications	. 20
7.1	Electrical	20
7.2	Mechanical and Connections	22
7.3	Environmental	. 22
7.4	Notes	23
Return Of	Goods	
Solartron S	Sales Offices	

Part No. 502621 Issue 8

2.0: Safety Information

Terms in this Manual

WARNING statements identify conditions or practices that could result in personal injury or loss of life.

CAUTION statements identify conditions or practices that could result in damage to the equipment or other property.

Symbols in this manual

This symbol indicates where applicable cautionary or other information is to be found.

WARNINGS:

Do not operate in explosive atmosphere

To avoid explosion, do not operate this equipment in an explosive atmosphere.

Safety Critical Environments

This equipment is not intended for use in a safety critical environment.

CAUTION:

Low Voltage

This equipment operates at below the SELV and is therefore outside the scope of the Low Voltage Directive.

This equipment is designed to work from a low voltage DC supply. Do not operate this equipment outside of specification.

2.0: Safety Information

CAUTION:

Electrostatic Discharge

This equipment is susceptible to **ESD** (Electrostatic Discharge) when being installed or adjusted, or whenever the case cover is removed. To prevent ESD related damage, handle the conditioning electronics by its case and do not touch the connector pins. During installation, follow the guidelines below.

- Ensure all power supplies are turned off.
- If possible, wear an ESD strap connected to ground. If this is not possible, discharge yourself by touching a metal part of the equipment into which the conditioning electronics is being installed.
- Connect the transducer and power supplies with the power switched off.
- Ensure any tools used are discharged by contacting them against a metal part of the equipment into which the conditioning electronics is being installed.
- During setting up of the conditioning electronics, make link configuration changes with the power supply turned off. Avoid touching any other components.
- Make the final gain and offset potentiometer adjustments, with power applied, using an appropriate potentiometer adjustment tool or a small insulated screwdriver.

3

3.0: Introduction ____

The OD4 MK2 is a development of the original OD4. It is a compact conditioning module powered from a single DC supply. Adjustable gain and zero controls are provided for use with the complete range of Solartron LVDT and half-bridge transducers.* The unit is of robust construction, housed in a die cast aluminium box providing a substantial degree of mechanical protection.

The OD4 MK2 incorporates its own voltage regulation for operation from 10-30 VDC and can provide outputs of up to ± 10 V together with ± 20 mA.

3.1: OD4 MK2 Enhancements

The OD4 MK2 has been designed as a form, fit and function replacement for the original OD4, but with several enhancements.

- Wider gain range, allowing ALL Solartron transducers to be connected without the need for attenuation resistors.

4

- Up to ±10 V dc and ±20 mA are available for all gain settings.
- Fixed and variable offsets make setting of uni-polar output easier.
- Gain and offset adjustment are fully independent.
- Selectable transducer excitation frequency.
- Selectable transducer load resistances.
- Selection between forward and reverse connection.
- Fully CE Compliant.
- Half-Bridge transducers can now be accommodated with simple plug wiring changes.*
- * For half-bridge only variant see section 6.0.

3.0: Introduction

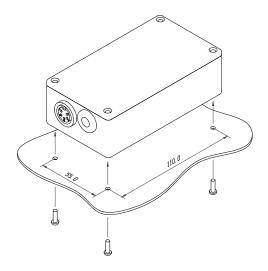
4.0: Installation_

4.1: Mounting

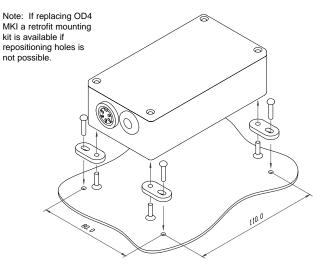
The OD4 may be mounted in a variety of ways and in any attitude. Ensure that there is enough space for the cover to be removed to allow for internal adjustments. Space should also be allowed for the transducer connector, EMC glands (if fitted) and cabling. It is recommended that the OD4 case be connected to earth or chassis. This earth connection is not a safety earth, but is part of the overall electrical screening scheme.

5

Underside Mounting



Top-Side Mounting



4.0: Installation _

Part No. 502621 Issue 8

4.2: Operational Environment

This section discusses the type of installation required depending on the electrical environment.

4.2.1: Residential, Commercial and Light Industrial Environments

Typically, this will be an office, laboratory or industrial environment where there is no equipment likely to produce high levels of electrical interference, such as welders or machine tools.

Connections may be made using twisted, unscreened wire. This is a cost effective option and will give good performance in this environment.

Standard equipment wire such as 7/0.2 (24AWG) can be twisted together as required. Standard data cable such as generic CAT5 UTP will also give good performance.

4.2.2: Industrial Environments

Typically, this will be an industrial environment where there is equipment likely to produce high levels of electrical interference, such as welders, machine tools, cutting and stamping machines.

Connections should be made using screened cable. Braided or foil screened cables may be used. The cable screen should be connected to the OD4 case at cable entry point. The case of the OD4 should be connected to a local ground. An EMC cable gland is recommended. This is supplied with the OD4.

6

When selecting the type of wire or cable to be used, consider the following parameters:

- Screening.
- Conductor size (resistance).
- Mechanical aspects such as flexibility and robustness.

This is not a complete list. Installations may require other special cable characteristics.

4.0: Installation

4.3: Electrical Connections

The OD4 requires three connections.

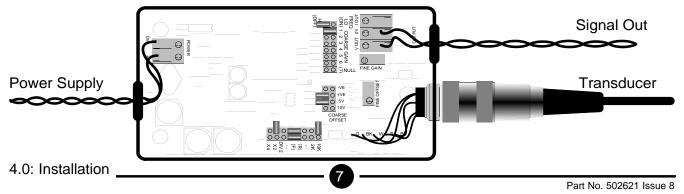
- 1. Transducer.
- 2. Power Supply.
- 3. Output Signal, Voltage or Current.

A small hole should be made in the grommet prior to passing the wires through. If a screened cable is to be used, an EMC cable gland is recommended (see section 4.7).

For best performance in electrically noisy environments, the case of the OD4 should be connected to a local earth. This can be achieved via the mounting bracket. This earth connection is not a safety earth, but is part of the overall electrical screening scheme.

The wiring layout arrangements are similar for OD4 fitted with EMC glands and screened cable.

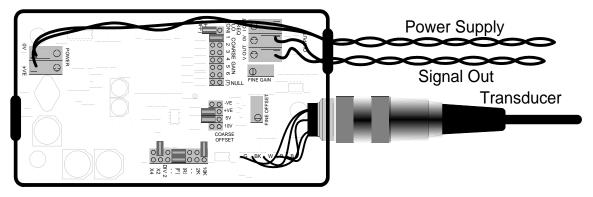
Separate Power Supply and Signal Out wires



4.3: Electrical Connections

Power Supply and Signal Out wires from one end only

Connections to the power supply should be routed to one side as shown. This helps to reduce interference between power supply wires and the more sensitive parts of the circuitry.



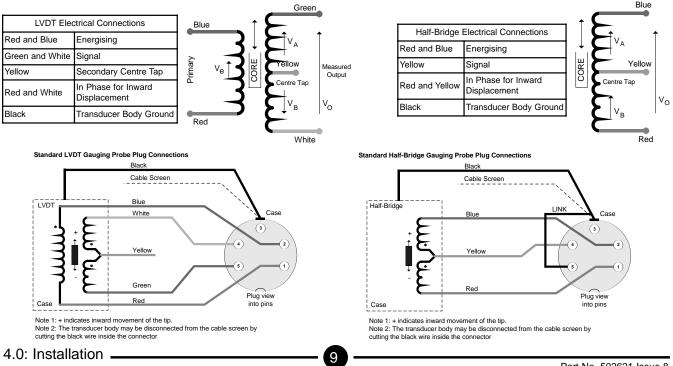
A technical note explaining good practice for cable installation and routing can be downloaded from <u>www.solartronmetrology.com</u>.

8

4.0: Installation

4.4: Connecting the Transducer

Transducers fitted with a 5-pin DIN plug are simply screwed into the case mounted socket. Transducers not fitted with a plug should be wired to the plug supplied. For the half-bridge only variant see section 6.0.



Part No. 502621 Issue 8

4.5: Connecting the Power Supply

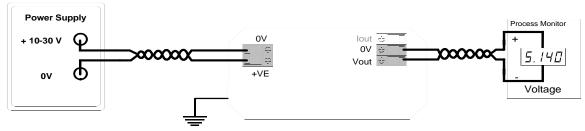
The OD4 requires a dc power supply in the range 10-30 V. A fully regulated supply is not required, but the voltage at the input to the OD4 must remain within specification. Ideally, the 0 V at the power supply should not be connected to earth or the chassis, as this would result in ground loops being formed. The 0 V supply, 0 V signal and case are all internally connected together at the OD4.

4.6: Connecting the Signal Out

The output signal may be voltage or current.

4.6.1: Voltage Connections

Voltage can easily be monitored using a variety of instrumentation such as voltmeters. Voltage drops along wires contribute to measurement errors, so care must be taken when using long cable lengths (100 m for example). High impedance instruments are more prone to interference.

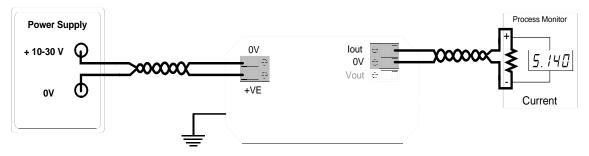


The signal 0 V should always be used as reference. If power supply 0 V is used, then error voltages may be introduced.

4.0: Installation

4.6.2: Current Connections

Current output requires the use of purposely designed current input instrumentation. Current output is more suitable for transmitting over longer distances because current is not lost due to wiring resistance. Additionally, with a low impedance, a current loop is less likely to pick up noise.



The total loop resistance (resistance of measuring equipment and wiring) must not exceed specification.

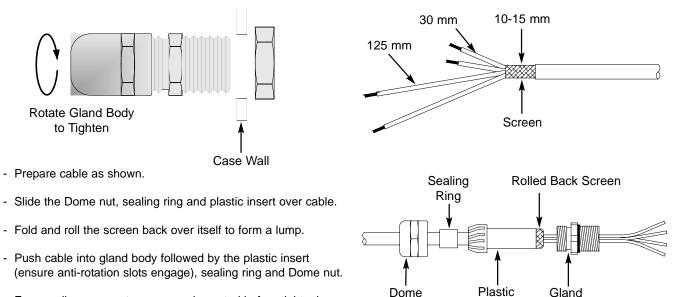
Note: The OD4 is not loop-powered, so a power supply must not be used in-line with the current output.

4.0: Installation

Part No. 502621 Issue 8

4.7: Using an EMC Cable Gland

To ensure the cable screen is properly connected to the OD4 case, an EMC cable gland should be used. This is supplied as an optional extra. The diagrams below assume a single 4-way cable is being used. Remove the grommet and fit the cable gland as shown below.



12

Nut

Insert

- Ensure all components are properly seated before tightening the dome nut.

4.0: Installation

Body

5.0: Setting up the Transducer and OD4_

The OD4 may be set-up with output signals anywhere within a ± 10 VDC or ± 20 mA range. Typical outputs are ± 10 VDC, ± 5 VDC, 0-10 VDC and 4-20 mA. These procedures apply to voltage and current output.

Voltage and current output are available at the same time, although they cannot be individually adjusted. Either voltage or current should be chosen as the calibration reference.

All outputs use 0 V signal as the signal reference.

A list of standard link settings is available, see section 5.2.



During installation and adjustment, the top of the enclosure has to be removed for access to user adjustments. At this time, standard ESD handling precautions for electronic equipment should be followed.

13

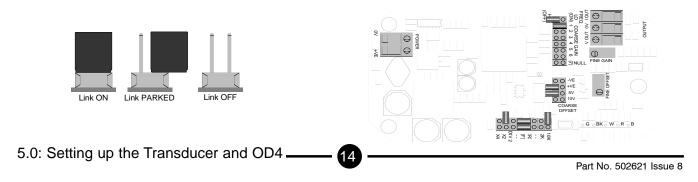
5.0: Setting up the Transducer and OD4 _____

5.0: Setting up the Transducer and OD4 (continued)_

5.1: Option Links - Explained

The table below and subsequent diagrams explain the link functions and show the factory setting.

Link	Description	Options	Standard Setting
Course Gain	Sets the basic gain	1 link on Positron 1 to 6	Link ON Position 1
Fine Gain	Adjustment between course gain ranges	Potentiometer Adjustment	Mid Position
Course Offset	Shifts the output by a fixed amount	Link ON -VE or +VE and Link ON 5V or 10V No offset - Link Parked	No offset - Links Parked
Fine Offset	Fine trim around any fixed offset	Potentiometer Adjustment	Mid Position
(7) Null	Used during set-up to null output	ON, OFF	OFF
Freq.	Selects transducer primary frequency	Lo - ON, Hi - Parked	Hi Freq Link Parked
Input Resistance	Sets transducer secondary load	100kΩ Parked, 10kΩ - ON, 2kΩ - ON	100KΩ - Link Parked
Polarity (FR)	Enables output signal direction change	2 Links across Forward or Reverse	F Position - 2 Link ON
Input Gain	Input Gain of x1, x2, x4 or divide 2	X1 - Parked, X2 - ON, X4 - ON, DIV2 - ON	Link parked on X2

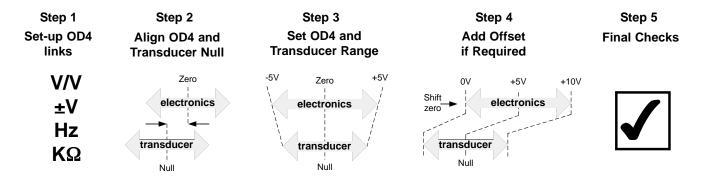


5.0: Setting up the Transducer and OD4 (continued).

5.2: Basic Procedure

To set-up the OD4, some basic steps should be followed.

The following steps describe a typical setting procedure and applies to most applications. Other procedures may be used as appropriate.



15

For a bi-polar output i.e. ± 10 VDC or ± 20 mA, follow steps 1 to 3. For a uni-polar output i.e. 0-10 V, 0-20 mA or 4-20 mA, follow steps 1 to 4.

In either case, step 5 (final checks) should be followed on the completion of the set-up.

5.0: Setting up the Transducer and OD4 _

5.0: Setting up the Transducer and OD4 (continued).

5.2: Basic Procedure

STEP 1 - Set-up OD4 Links

If the transducer characteristics are known, set the frequency and input resistance links as required. A list of standard settings for all Solartron transducers is available from <u>www.solartronmetrology.com</u>. If the transducer characteristics are not known, the standard link settings should be used.

If your transducer is known to be outside of the standard sensitivity range, the X2 or DIV2 links will have to be used. See section 5.3.

STEP 2 - Align OD4 Null and Transducer Null

Any electrical offset in the OD4 is removed. The transducer position is adjusted so that transducer and OD4 nulls are aligned.

Null the OD4.

- 1. Put the Gain link on position (7) as shown. This allows any electronics offset in the output stage to be removed.
- 2. Adjust the Fine Offset control to give as near to zero output as practical.

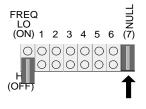
Null the transducer.

- 1. Replace the Gain link to the original position.
- 2. Adjust the position of the transducer to give as near to zero output as practical. This is the centre of the mechanical range.

If the transducer cannot be centered for practical reasons an offset will remain within the system. There may be noticeable interaction between Gain and Offset adjustment. This does not prevent the OD4 being set-up. However several iterations may be required when adjusting Gain and Offset. Please contact your supplier if guidance is required.

16

5.0: Setting up the Transducer and OD4 -



Part No. 502621 Issue 8

5.0: Setting up the Transducer and OD4 (continued)_

5.2: Basic Procedure

STEP 3 - Setting Bi-Polar Full-scale Output

- 1. Move the transducer to the position where maximum OD4 output is required.
- 2. If the polarity of the output is wrong, move the Polarity (FR) links to the R position (see link diagram). Move the transducer back and re-check the zero position. Adjust transducer position as required.

Normal Output Polarity



Reverse Output Polarity



- 3. Move the RANGE link between 1 and 6 until the OD4 output is near the required value.
- 4. Adjust the Fine Gain control to give the required output.
- 5. A bi-polar output has now been set, proceed to step 5. If a uni-polar output is required, proceed to step 4.

Example: ±10 VDC is required from a ±1 mm transducer. Set the transducer to +1 mm and set the output to 10 V.

If your transducer is known to be outside of the standard sensitivity range, the X2 or DIV2 links will have to be used. See section 5.3.

5.0: Setting up the Transducer and OD4 (continued)

5.2: Basic Procedure

STEP 4 - Setting Uni-polar Full-Scale Output (adding an offset)

- 1. Move the transducer to the null position. OD4 output will be 0 V or 0 mA.
- 2. Apply offset using the +VE, -VE, 5 V and 10 V links and then adjust the Fine Offset control to set the offset precisely.
- 3. Perform final checks, step 5.

Example: 0-10 V is required for a ± 1 mm transducer. Set the transducer to give ± 5 V over the full range and then, with the transducer at null, add ± 5 V offset. Adjust the Fine Offset control to give 5 V. When the transducer is moved to the ± 1 mm position, the output will be ± 10 V.

Example: 4-20 mA is required for a ± 1 mm transducer. Set the transducer to give ± 8 mA over the full range and then, with the transducer at null, add +5 V (approx. 10 mA) offset. Adjust the Fine Offset control to give +12 mA. When the transducer is moved to the +1 mm position, the output will be +20 mA.

STEP 5 - Final Checks

Ensure that the calibration is correct by moving the transducer across the required mechanical range, checking calibration points. Fine adjustment can be made if required.

It may only be possible to set the output accurately at the two calibration points. This is due to non-linearity within the transducer.

18

5.0: Setting up the Transducer and OD4 (continued)_

5.3: Transducer Sensitivity and the X2, X4, DIV2 Link

The OD4 compensates for changes in primary signal amplitude by producing an internal error signal that is the ratio between the primary and secondary signals. If the transducer output signal is too high or too low, errors may occur that can degrade the performance of the OD4 / transducer combination. For these transducers, the X2, X4 or DIV2 input gain link must be used.

For Solartron transducers, consult the list of standard settings available from the downloads section of <u>www.solartronmetrology.com</u>.

Transducer Full Range Output

In general, transducer sensitivity is quoted as **mV/V/mm** Where: **mV** is the output of the transducer **V** is the primary voltage **mm** is the mechanical position of the transducer from null (usually mid mechanical range).

To get the transducer Full Range Output, multiply all three together.

Example: AX/1.0 sensitivity is 210 mV/V/mm AX/1.0 range is ±1 mm OD4 primary voltage 3 V

Transducer Full Range Output = 210 x 3 x 1 = 630 mV (0.63 V)

Set the X2, X4, DIV2 link as shown in the table below.

Transducer Full Range Output	Input Gain Link Setting
400 mV FR to 2500 mV FR	Standard Range - Link Parked on X2
2500 mV FR to 5000 mV FR	High Transducer Output - Link ON DIV2
150 mV FR to 400 mV FR	Low Transducer Output - Link ON X2
55 mV FR to 150 mV FR	Very Low Transducer Output - Link ON X4

19

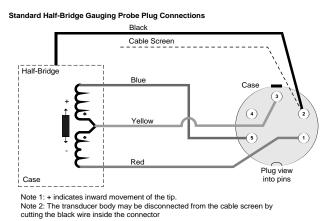
5.0: Setting up the Transducer and OD4 _____

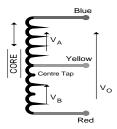
6.0: Half-Bridge only Variant

This is a half-bridge optimised variant of the standard product. The excitation frequency is higher (see specification) and the transducer input connector is wired to accept half-bridge transducers with standard connections.

6.1: Connecting the transducer

The 5-pin DIN plug is screwed into the case mounted socket. Transducers not fitted with a plug should be wired to the plug supplied. LVDT transducers cannot be connected to this input.





Half-Bridge Electrical Connections

Red and BlueEnergisingYellowSignalRed and YellowIn Phase for Inward DisplacementBlackTransducer Body Ground

6.2: Setting up the Half-Bridge Transducer

The setting up procedure is the same as LVDT transducers. See section 5. The sensitivity of half-bridge transducers is generally lower than for LVDT types, the x2 and x4 gain position may have to be used. A list of standard link settings for all Solartron Transducers is available from the downloads section of <u>www.solartronmetrology.com</u>.

20

6.0: Half-Bridge only Variant

7.0: Specifications _____

7.1: Electrical

Parameter		Value	Comments
Power Supply			
Typical Voltage / Curren	t	24 VDC at 55 mA	
Voltage Range		10 to 30 VDC	
Current Range		140 mA at 10 V to 50 mA at 30 V	
Transducer Excitation			
Energising Voltage		3 Vrms nominal	see note 1
Energising Frequency		2.5 kHz (Lo) or 5 kHz (Hi) nominal 10 kHz (Lo) or 13 kHz (Hi)	link selectable Half-Bridge version only
Energising Current		30 mA max.	
Transducer Signal Inpu	ut		
Input Signal Range	Standard	400 to 2500 mV FR	6 gain ranges (applies to LVDT only)
	Special	DIV2 2500 to 500 mV FR x2 150 to 400 mV FR x4 55 to 150 mV FR	see note 2
Input Load Resistance		2, 10, 10 kΩ	link selectable
Options		Forward and Reverse LVDT Input Half-Bridge Input	link selectable standard special plug wiring or half-bridge version only

21

7.0: Specifications

7.0: Specifications (continued)

7.1: Electrical

Parameter		Value	Comments
Signal Output			
Output Voltage Range		up to ±10 VDC into 1 kΩ	see notes 3 and 4
Output Residual Noise)	<1 mVrms	
Output Current		up to ±20 mA into 150 Ω load	see note 5
Output Offset	Coarse	±5 VDC (approx 10 mA) fixed	link selectable
		±10 VDC (approx 20 mA) fixed	link selectable
	Fine	±2.8 VDC (approx 5.6 mA)	Variable (adds to fixed offsets)
Temperature Coefficie	nt Gain	<0.01% FRO/°C	
Temperature Coefficier	nt Offset	<0.01% FRO/°C	
Warm-Up		15 minutes recommended	
Linearity		<0.1% FRO	
Bandwidth (-3dB)		500 Hz typical	
Protection (see note	6)		
Power Supply		Reverse connection protected	
Inputs and Outputs		Short circuit protected Transient and ESD Protected	
Certification (see not	e 7)		
Immunity		BS EN61000-6-2:2001	Immunity for Industrial Environments
Emissions		BS EN61000-6-3:2001	Emission for Residential, commercial and light-industrial environments

7.0: Specifications (continued)

7.2: Mechanical and Connections

Parameter	Value	Comments
Transducer	5-pin circular DIN	
Power Supply	Internal Terminal Block	
Output Signal	Internal Terminal Block	
Enclosure - Size	120 x 65 x 40 mm	Excluding connectors
Weight	300 g (0.66 lbs) approx.	
Material of Case	Die-Cast Zinc Alloy (painted)	

7.3: Environmental

Parameter	Value	Comments
Operating Temperature Range	0 - 60°C	
Storage Temperature Range	-20 - 85°C	
IP Rating	IP40	

23

7.0: Specifications (continued)

7.4: Notes

- 1. Primary voltage absolute value and drift is not specified. The OD4 uses ratiometric techniques to compensate for primary voltage drift.
- 2. The way in which the OD4 functions means a special configuration must be used for transducers outside of the standard range. This is selectable by links. The majority of Solartron LVDT transducers are within the standard range. See section 5.
- 3. OD4 can drive into a 1 k Ω load but this offers no advantage. 10-100 k Ω is recommended.
- 4. Output voltage range can be adjusted as required anywhere within this range by using a combination of gain and offset, for example. ±10 VDC, ±5 VDC, 0-5 VDC, 0-10 VDC, 4-20 mA.
- 5. Current output may be used at the same time as voltage output. Calibration of voltage and current cannot be individually adjusted.
- 6. Protection applies to the product when fully installed according to the user manual. During installation the top of the enclosure has to be removed for access to user adjustments. At this time standard ESD handling precautions for electronic equipment should be followed.
- 7. The OD4 complies with the toughest electrical emissions and immunity regulations. Compliance requires installation according to the user manual. Compliance does not guarantee performance as the installation environment may be outside of test specification limits. The flexibility of OD4 means it can be installed in a variety of ways according to user requirements. Simple installations with short non-screened cables will meet the lesser light-industrial immunity regulations. Heavy industrial installations, especially with longer cables, will need more careful installation with screened cables.

7.0: Specifications

Return of Goods

Devices returned for service/repair/calibration should be shipped prepaid to your distributor or, if purchased directly from Solartron Metrology, to the relevant Sales Office (see below).

The shipping container should be marked: "For the Attention of the Returns Department"

The following information should accompany the device(s):

- 1. Contact details of company/person returning device, including return shipping instructions.
- 2. A statement of service required and purchase order.
- 3. Description of the device fault and the circumstances of the failure, including application environment and length of time in service.
- 4. Original purchase order number and date of purchase, if known.

Please note: A standard assessment charge is applicable on all non-warranty devices returned for

repair. Customer damage and any device found, upon inspection, to have no fault will be considered nonwarranty.

Please contact the Sales Office or Distributor for warranty terms, service options and standard charges.

Adherence to these procedures will expedite handling of the returned device and will prevent unnecessary additional charges for inspection and testing to determine the condition.

Solartron Metrology reserves the right to repair or replace goods returned under warranty.

All repairs are guaranteed for 3 months (unless otherwise stated).

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