# Max31.Saw

## Full Automatic Saw Controller





(MAX31SawV10UMR1EN.CDR - 0916 rev 1.0)

2-Axis Control (Encoder feedback), 2 speed positioning, Manual ve Auto positioning, 3 quick program buttons, Analog output (0-10V) for sawing speed, LCD graphic display 128x64 dot, Help button, Service display, Real time clock, User friendly, Removable memory module

### **1.1 - FRONT VIEW**



#### 1.2 - KEYPAD



## 2.1 - MANUAL (ANGLE)

M	Press M ( when the display shows main screen )
	Press ++ to move forward fast
2	Press + to move forward slow
4	Press to move backward fast
5	Press to move backward slow
$\bigcirc$	Press STOP to exit



### 2.2 - AUTO (ANGLE)



#### 3 - SAW SPEED



## 4.1 - SET HEAD HEIGHT



Press H ( when the display shows main screen )

Enter the height set value

#### Press START

<sup>[Not.1]</sup> Output relay (H-LMT) contacts closes if the head position passes over this soft limit value

<sup>[Not.2]</sup> If the entered limit value is greater than the existing head pos., Output (H-OUT) relay contacts closes 1 sec. to bring the head to this new position.

#### 4.2 - SAW HEAD POSITION TEACH



Press sH ( when the display shows main screen )

The existing height of the saw head is teached to the controller and shown on the display.



200

Set Height?

10:30

mm

## 5.1 - PROGRAM SELECT ( 3 programs )



Press P1 (or P2 or P3) ( when the display shows main screen

The recalled programs contains the stored set values for angle, height and sawing speed.



## 5.2 - PROGRAM TEACH



Press  $P_1$  (or  $P_2\,\text{or}\,P_3)$  for 3 sec. ( when the display shows main screen ) ( till its led is off )

Angle, Height and speed writes to memory

## 6 - PARAMETERS



## 7.1 - ANGLE CALIBRATION ( POSITION CORRECTION )



## 7.2 - HEAD HEIGHT CALIBRATION



## 7.3 - AUTO CALIBRATION

By switch-on, cal.mode is asked. For auto cal. mode, just press START to activate RUN output (contact close) signals PLC to rise the saw head to the top switch. Then saw head movement stops and PLC send READY signal (closes) to saw controller to start angle positioning toward A-RST siwtch. Angle positioning outputs continue to be active for 1 sec after A-RST switch is closed, then positioning stops, just at this moment calibration values (pr.8 and pr.11 respectively) are transferred as actual value and angle, height positions are displayed on the screen.

## 8 - SERVİCE MENU



### **CONNECTIONS and PANEL CUT-OUT DIMENSION**



_		Supply
1	PE	Protective Earth
2	Ν	24V AC/DC +/-%15 @50Hz
3	L	24V AC/DC +/-%15 @50Hz

		Digital Inputs
4	+COM	+12V Common
5	STOP	Stop Input, NC, PNP
6	READY	Ready Input, NO, PNP
7	A-RST	Angle Reset Input, NO, PNP
8	H-RST	Height Reset Input, NO, PNP
9	NEXT	Next Angle / Count Input

		A-Encoder (Angle)
11	PE	Protective Earth
12	+12V	Encoder Supply +12VDC
13	А	Encoder A
14	В	Encoder B
15	0V	Encoder Supply 0V

		Angle Axis Outputs	
16	BACK	Angle Forward	
17	FORW	Angle Backward	_+∕-+
18	COM	Common	
19	SF	Slow/Fast	Close=Fast
20	SF	Slow/Fast	_
21	RUN	RUN out	
22	RUN	RUN out	•

_		Com Port
23	GND	RS232 - 0V
24	RX	RS232 - Receive
25	ТΧ	RS232 - Transmit

		Analog Output
26	AOUT	0-10Vdc Analog Out (sawing speed)
27	0V	GND

		H-Encoder (Head Height)
11	PE	Protective Earth
12	+12V	Encoder Supply +12VDC
13	А	Encoder A
14	В	Encoder B
15	0V	Encoder Supply OV

		Other Outputs		
33	H-LMT	Height Limit (NO)		
34	ZONE	Clamp Pos (Close=Negative)		
35	СОМ	Common		
36	H-OUT	Height change out (NO)		
37	H-OUT	Height change out (NO)		

NOTE : STOP input must be shorted to common if it is not used.