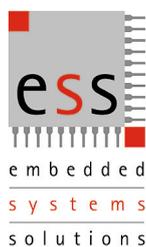


User Manual Addendum

CAN*gine*

No. 1

Bluetooth® Option



CANgine No. 1 Bluetooth Option User Manual

May 2006
Page 2 of 13



Edition 3
May 2006

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| 3 | May 2006 | Blink Code not connected |
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1 Introduction

Thank you for choosing a product of our CANgine product family. The CANgine family is based on high performance 8 bit microcontrollers with integrated full CAN interface and flash memory. With these products you are able to build extremely small but powerful CAN units.

With the option BT of CANgine-No.1 communication with the host uses the bluetooth SSP (serial port profile) instead of a RS232 serial link. As any standard CANgine CANgineBT is powered via the CAN connector according to the recommendations of CiA (CAN in Automation).

In it's standard case, CANgineBT-No.1 only measures 85 x 36 x 20 mm³ (3.32 x 1.4 x 0.79 inch³). If this does not fit for some applications CANgineBT-No.1 can be delivered in other cases or without case in customer specific variants. Due to the modular concept of the CANgine products in hardware and software this is possible even at lower production volumes. Email or call our sales department if you have special requirements.

This manual only describes specific functions of the bluetooth option. For the normal behaviour of CANgine-No.1 please refer to the CANgine-No.1 manual.

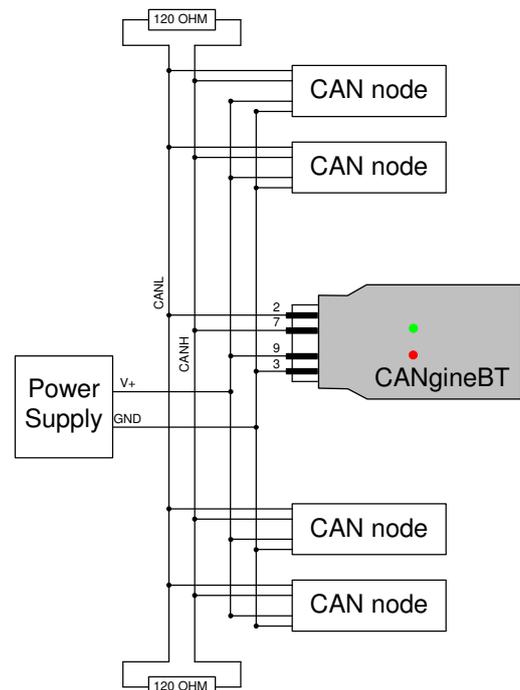


2 Installation

The picture shows how to connect CANgine to a CAN network. Power supply is connected via pin 9 (+) and pin 3 (GND) of the CAN connector as proposed by CiA. The maximum supply voltage is 30 V. Applying higher voltages will lead to damages. Pay attention to the terminating resistors (120 Ohm) at both ends of the CAN bus.

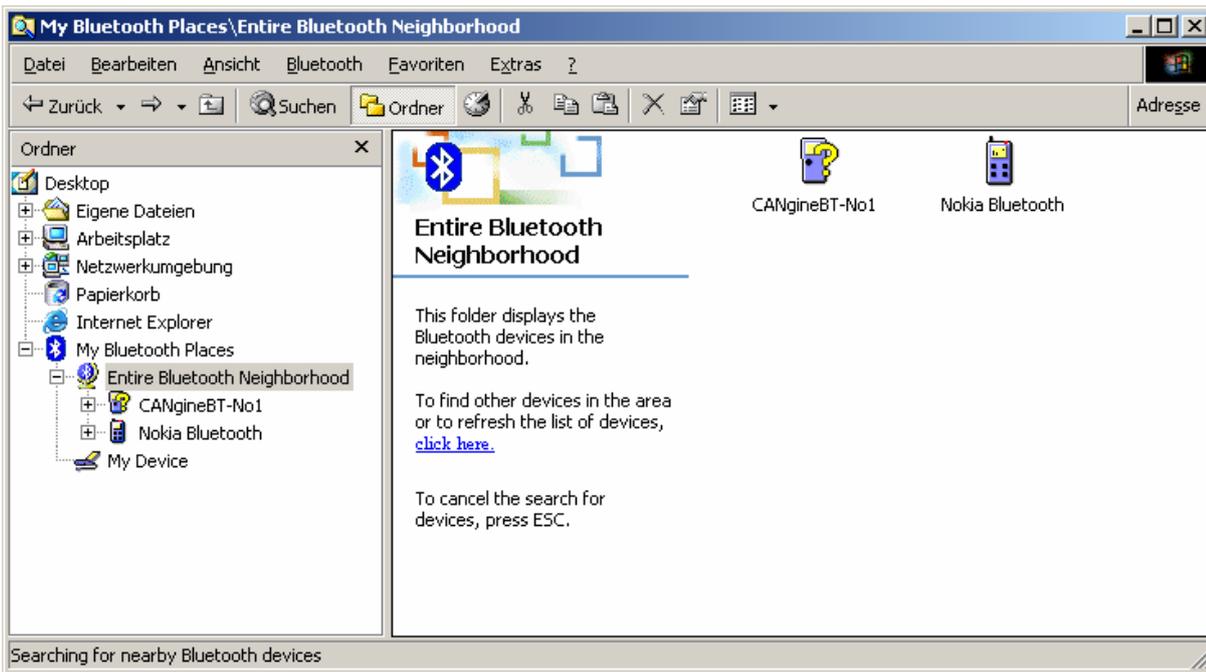
After applying power CANgineBT-No.1 is ready for operation and waits for a connection request from a Bluetooth device. If the Bluetooth area is scanned the modul reports "CANgineBT-No.1" with SPP service. Also the Bluetooth address is reported. With the help of this address a connection is possible without previous scan.

When waiting for a Bluetooth connection CANgineBT-No. 1's error LED flashes five times to signal "no Bluetooth connection". When a connection is established successfully the red LED switches off.



3 Establishing Communication

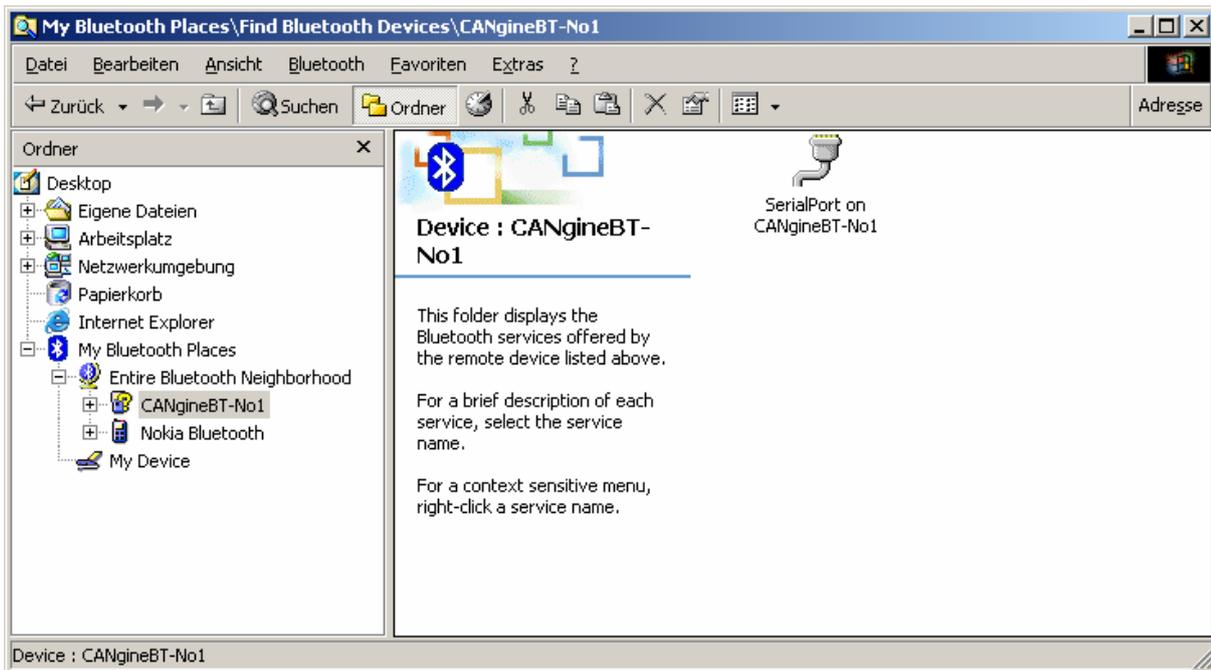
Establishing a Bluetooth connection is exemplified in the next chapters using a standard USB Bluetooth adapter. After scanning the CANgineBT-No.1 is reported as shown in the screenshot.



Clicking with the right mouse button on the CANgine symbol and selecting properties shows the Bluetooth address of the CANgineBT-No.1.

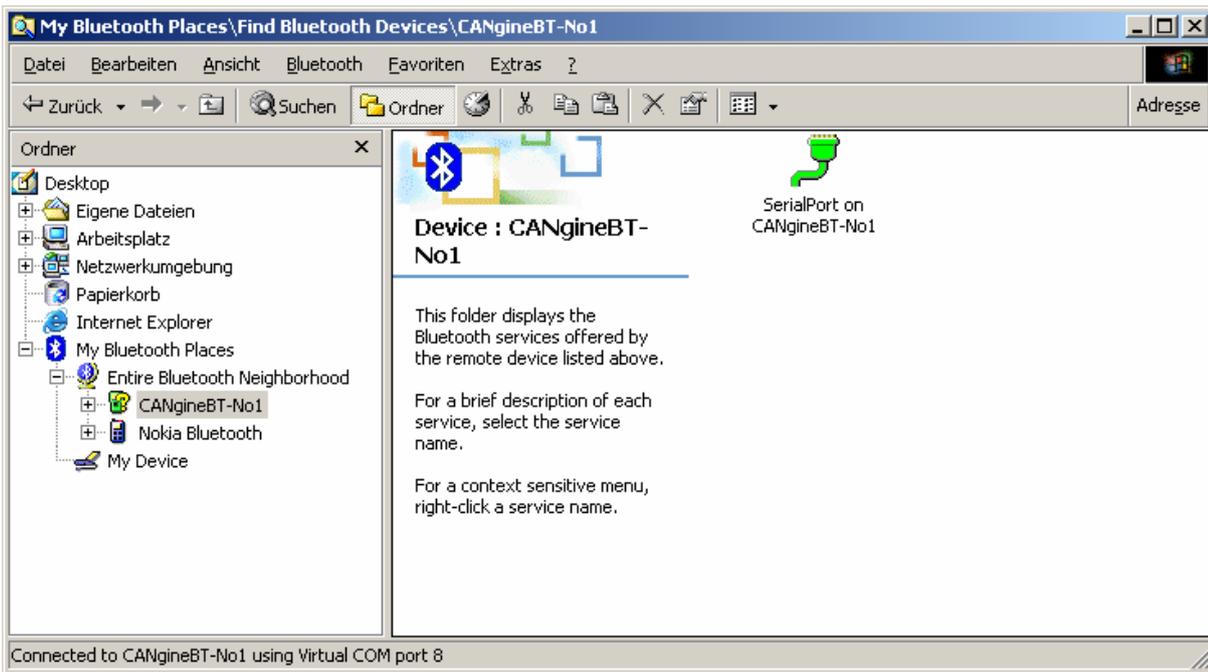


Double clicking on the CANgine symbol in the neighbourhood screen shows the services offered by the CANgineBT. This is only the SPP (serial port profile) service.

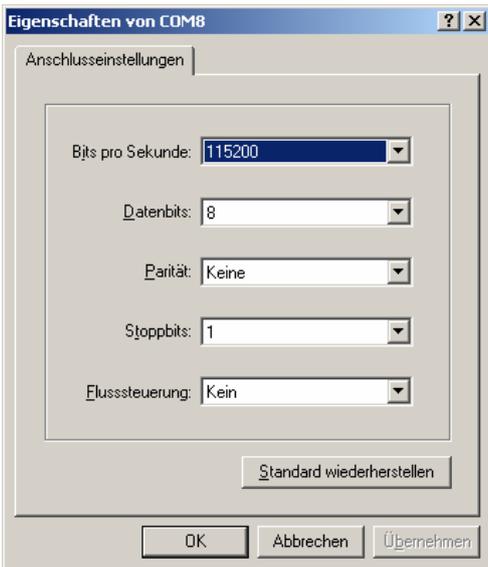


Double clicking the Serial port icon in the device screen establishes a connection between a virtual serial port on the PC and the CANgineBT-No.1. If the software asks for a PIN enter 0000. In the software used in this example the connected device is marked in green to signal the successful connection. If you don't know the COM port number (in this example it is shown by an own window) try to explore the properties of the connected device (right mouse click).

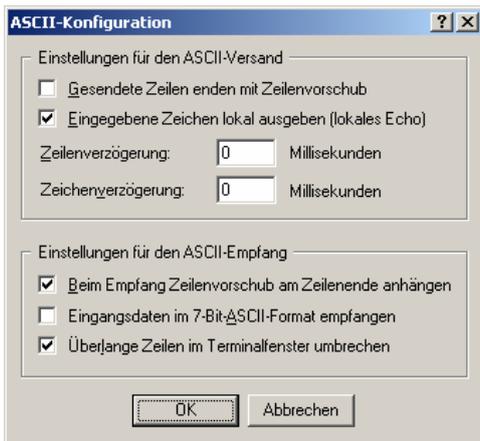




To communicate with CANgineBT-No.1 start a terminal program like Hyperterminal and set the parameters to 115.200 bps, 8 data bits, no parity, 1 stop bit and no flow control.



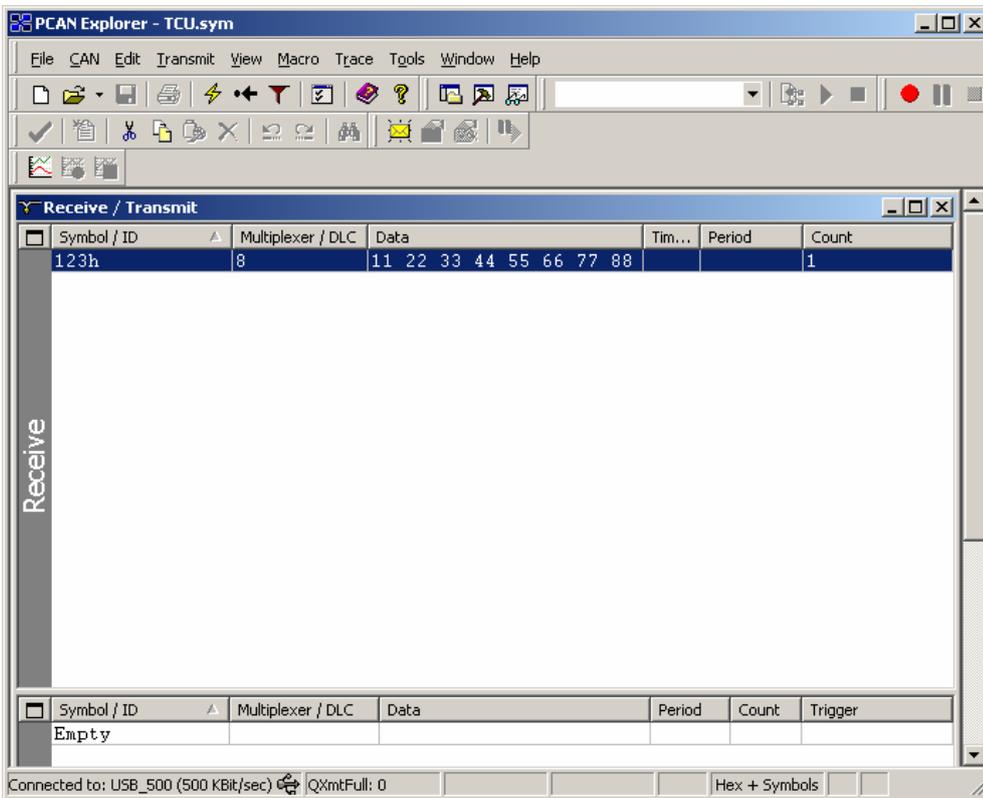
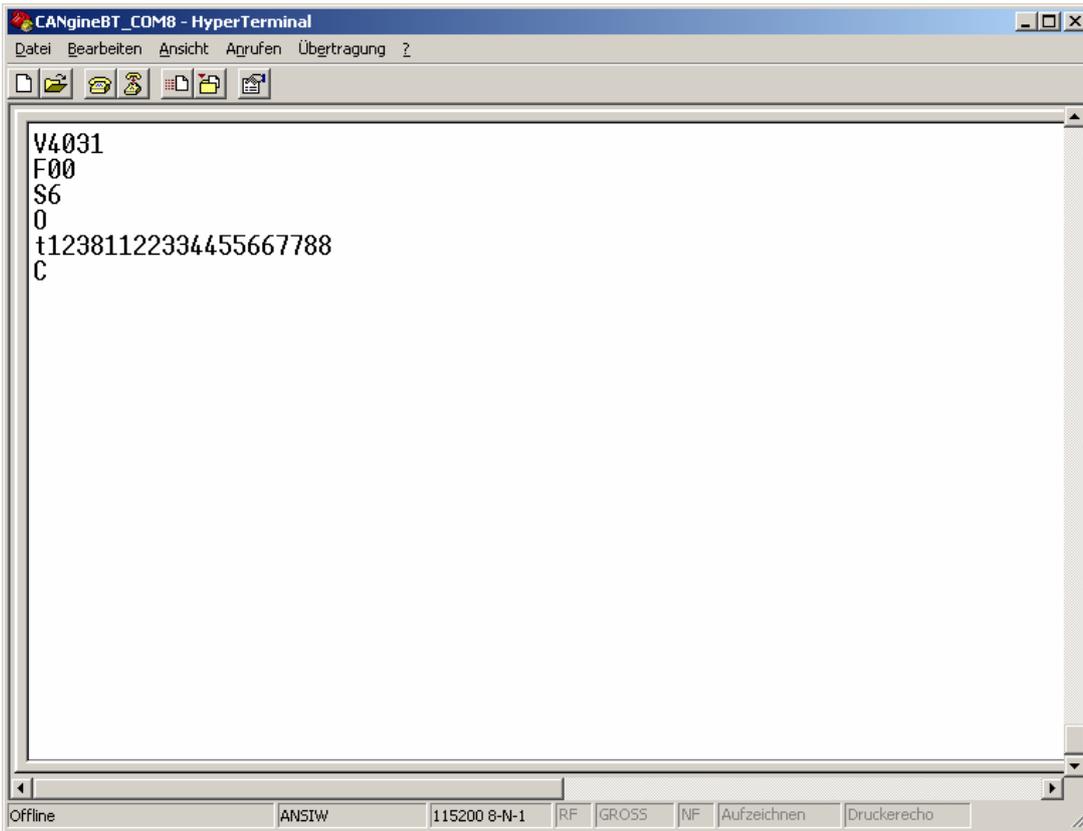
Due to better performance CANgineBT-No.1 like CANgine-No.1 sends no echo characters. For your convenience while testing set the communication parameters in your terminal program to local echo on sending and adding a linefeed character on receiving.



If you change the communication parameters of hyperterminal you have to disconnect the COM8 device. This may also disconnect the Bluetooth connection (the red LED on CANgineBT flashes 5 times). If you re-connect in hyperterminal your Bluetooth software should also re-connect the Bluetooth connection (the red LED on CANgineBT switches off).

After having established the connection with the right communication parameters enter the following commands:

| Command | Meaning | Answer from CANgine |
|----------|---------------------------------------|--|
| [CR] | Initialize communication with CANgine | [CR] |
| V[CR] | Ask for version number | V4031[CR] |
| F[CR] | Ask for error information | F00[CR] |
| S6[CR] | Set CAN Baudrate to 500 kbit/s | [CR] |
| O[CR] | Open CAN channel | [CR] |
| t...[CR] | Send a standard CAN Frame | [CR]; Your CAN monitor should show a received message. If no CAN is connected the CANgine enters CAN error mode. |
| C[CR] | Close CAN channel | [CR] |



4 Pinning of CAN Connector

| Pin | Signal | Pin | Signal |
|-----|--------|-----|--------|
| 1 | nc | 6 | GND |
| 2 | CANL | 7 | CANH |
| 3 | GND | 8 | nc |
| 4 | nc | 9 | +Vcc |
| 5 | nc | | |

5 Technical Data

| | | |
|---------------------------|--------------------------------------|-----------------|
| Power supply | 7 .. 30 | VDC |
| Supply current | 100 (typ.) | mA |
| Internal micro controller | Clock: 40 Full CAN 2.0B Interface | MHz |
| CAN Transceiver | 82C251 | |
| CAN connector | Sub-D 9 pin male | |
| CAN baud rate | 10 .. 1.000 | kBit |
| Display | RUN and ERROR LEDs | |
| Size | 84 x 35.6 x 20.2 | mm ³ |
| Weight | 43 | g |
| Temperature range | 0 .. +55 | °C |



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