
Delay25

A 4 channel 1/2 ns programmable delay line

[H. Correia](#), [A. Marchioro](#), [P. Moreira](#)
and
[J. Schrader](#)

CERN - EP/MIC, Geneva Switzerland

2005-05-13

Version 1.1

Technical inquires: Alessandro.Marchioro@cern.ch, Paulo.Moreira@cern.ch

Preliminary

Introduction _____ **4**
 Features:4

OPERATION _____ **4**

Operating the ASIC _____ **6**
 IO mode6
 I2C register access6
 Control registers6
 Channel control registers CR0, CR1, CR2, CR3 and CR47
 General control register GCR7
 Timing.....8

pinout _____ **8**

References _____ **9**

Summary of Changes

Version 1.1:

- General control register bit assignments corrected 2005-05-13

Version 1.0:

- First release of the Delay25 manual 2004-12-15

INTRODUCTION

The Delay25 is a 5 channel CMOS programmable delay line featuring 4 channels that allow to phase delay periodic or non-periodic digital signals and a master channel that can be used to phase delay a clock signal. The master channel serves as a calibration reference. The phase of each channel can be independently programmed with a resolution of 0.5 ns through an I2C interface [1]. The reference clock frequency can be any of the following: 32, 40, 64 or 80 MHz.

The ASIC is manufactured in a 0.25 μm CMOS radiation tolerant technology.

Features:

- 0.25 μm CMOS technology
- Radiation tolerant
- Self calibrating
- Reference clock frequencies: 32, 40, 64 or 80 MHz
- Phase resolution: 0.5 ns
- Output jitter: < xxxxxx ps
- Programmable I/O:
 - CMOS 2.5V
 - LVDS
- Supply voltage: 2.5 V
- Package: TQFP32

OPERATION

A block diagram of the delay25 ASIC is shown in Figure 1. The ASIC contains a master Delay Locked Loop (DLL), four Replica Delay Lines (RDL), an I2C interface and double standard I/O input and output buffers.

In the circuit, the DLL serves as a control element for the replica delay lines. In short, a delay locked loop is a control loop that regulates the total propagation delay of a clock signal across a voltage controlled delay line. The control loop assures that the total propagation delay is exactly equal to a clock period (or a multiple of it). By taping the signal along the delay line at regular intervals it is possible to obtain precisely calibrated delays which are a fraction of the clock period. Since the DLL uses a reference clock to calibrate the total propagation delay its operation is rendered independent of the fabrication process parameters, temperature and power supply voltage (within the operation ranges). The four replica delay lines are physically made as exact copies of the voltage controlled delay line that is part of the DLL. Under these conditions, and due to the good matching that is possible to obtain in integrated circuits, when the control voltage produced by the DLL is applied to the replica delay lines, their total propagation delay will be identical to that of the master delay line. Again, by taping these replica delay lines at periodic intervals it is possible to obtain calibrated delays which are a fraction of the reference clock period. There are two main differences between the master and the replica delay lines: first, the master delay line is part of a control loop, that is, its total delay is constantly monitored and corrected, while the replica delay lines are working open loop. Second,

the master delay line requires a periodic (clock) signal for correct operation of the control loop while the replica delay lines can be used with non-periodic signals (pulses) since they are working open loop. As said before calibration of the replica delay lines depends on matching, which for integrated circuits is normally quite good but not exactly perfect. This means that the total delay of the replica delay lines is not going to be exactly equal to that of the master and so there will be some small errors introduced. However, these errors should be well with the system requirements and specifications.

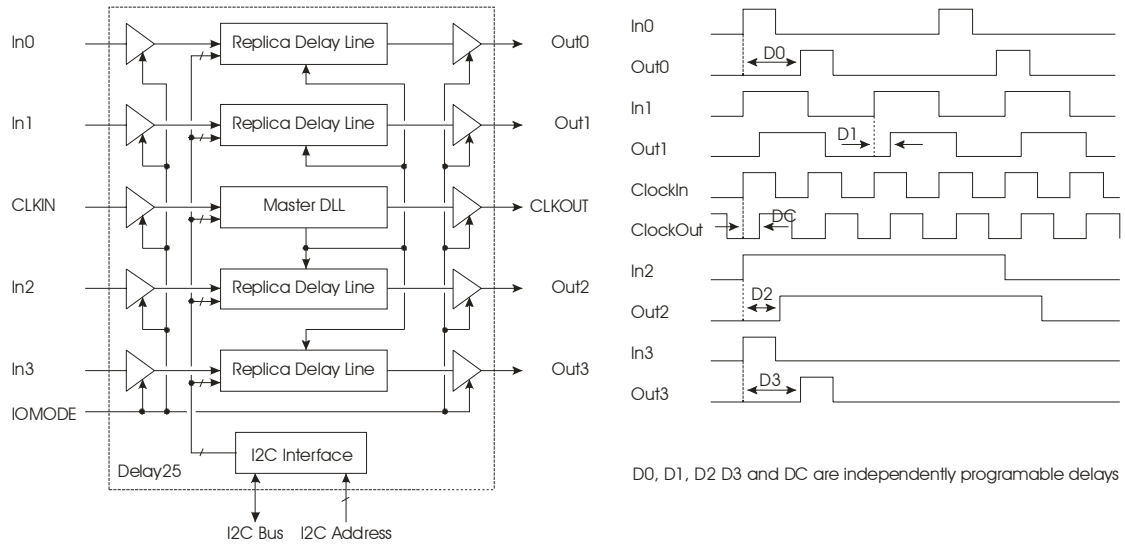


Figure 1 Block diagram of the delay25 (left) and hypothetical use of the ASIC illustrating the meaning of the phase delay for each channel (right)

Figure 1 (right) illustrates a possible use of the delay25 chip and the meaning of phase delay for each channel. As mentioned before, please note that the master channel can be only used with a clock signal having clock frequencies of 32, 40, 64 or 80 MHz.

The IOMODE configuration pin allows the ASIC to operate with either CMOS (2.5V) or LVDS [2] levels. The reset and I2C related pins are not affected by the IOMODE signal.

OPERATING THE ASIC

The ASIC operation is controlled by the IOMODE pin and by means of four internal registers, which can be accessed through an I2C bus.

IO mode

The IO signal levels are controlled by the pin IOMODE (IO mode) as is indicated in Table 1. As represented in Figure 1 the IO mode pin affects only the input and output buffers of the replica and master delay lines. When the IO mode is set to CMOS (0) all the channels inputs and outputs work single ended being all the negative inputs and outputs disabled. When IO mode is set to LVDS (1) all the channels inputs and outputs are differential.

Table 1 IO modes

IOMODE	Function
0	CMOS 2.5 V
1	LVDS

I2C register access

The ASIC registers are accessed through the I2C bus which is composed of the following signals: SCL (serial clock), SDA (serial data) and the address pins I2CA<6:3> which correspond to the four most significant bits of the I2C address (these act a chip select address). The three least significant bits of the I2C address are internally decoded and map into the ASIC internal register as shown in Table 2.

Table 2 Internal I2C register map

I2C Address	Name	Function
0	CR0	Control register for channel 0
1	CR1	Control register for channel 1
2	CR2	Control register for channel 2
3	CR3	Control register for channel 3
4	CR4	Control register for clock channel
5	GCR	General control register
6	Unused	-
7	Unused	-

Control registers

Five register control the operation of the Delay25 ASIC. Each channel is individually controlled by its control register (CR0 to CR4). A general control register (GCR) controls global parameters for all the five channels, the DLL and the logic.

Channel control registers CR0, CR1, CR2, CR3 and CR4

The bit allocation of each channel control register is as given in Table 3. Bits Del<5:0> control the delay for each channel and the Enable bit enables the channel output. Upon a reset, bit Enable and bits Del<5:0> are cleared.

Table 3 Control registers (CR0 to CR4) bit allocation

B7	B6	B5	B4	B3	B2	B1	B0	
n.u.	Enable	Del<5>	Del<4>	Del<3>	Del<2>	Del<1>	Del<0>	Function
n.u.	0	0	0	0	0	0	0	Reset State

General control register GCR

The general control register GCR controls the operation of the Delay-Locked Loop (DLL) and allows to reset the DLL or the ASIC via the I2C interface. The bit allocation for this register is given in Table 4

Table 4 General Control Register (GCR) bit allocation

B7	B6	B5	B4	B3	B2	B1	B0	
reserved	IDLL	n.u.	n.u.	n.u.	n.u.	M<1>	M<0>	Function
0	0	-	-	-	-	Not cleared	Not cleared	Reset State

The ASIC can operate with for different clock frequencies (32, 40, 64 and 80 MHz). Correct operation of the ASIC requires bits M<1:0> of the control register to be set to the appropriate mode. The settings of these bits should be made according to Table 5. Bits M<1:0> are not affected by a reset.

Table 5 Clock modes

M<1>	M<0>	Clock Frequency [MHz]
0	0	40
0	1	80
1	0	32
1	1	64

IDLL: bit IDLL is used to force the resynchronization of the DLL without resetting the chip. Writing a “1” to this bit forces the resynchronization of the DLL. This bit always reads as a “0”

Timing

Data in preparation

PINOUT

The ASIC is package in a 32 pin TQFP package. Pins are assigned as indicated in Table 6.

Table 6 Pins assignments

Pin number	Pin name	IO levels	Function
1	Vdd	+2.5 V	Power
2	SCL	CMOS	I2C serial clock
3	SDA	CMOS – open drain	I2C serial data
4	I2CA6	CMOS	I2C Address
5	I2CA5	CMOS	I2C Address
6	I2CA4	CMOS	I2C Address
7	I2CA3	CMOS	I2C Address
8	GND	0 V	Ground
9	OUT0+	LVDS/CMOS	Channel 0 +output
10	OUT0-	LVDS	Channel 0 -output
11	OUT1+	LVDS/CMOS	Channel 1 +output
12	OUT1-	LVDS	Channel 1 -output
13	OUT2+	LVDS/CMOS	Channel 2 +output
14	OUT2-	LVDS	Channel 2 -output
15	OUT3+	LVDS/CMOS	Channel 3 +output
16	OUT3-	LVDS	Channel 3 -output
17	Vdd	2.5 V	Power
18	IOMODE	CMOS	IO mode select
19	ResetZ	CMOS	Reset – active low
20	CLKOUT-	LVDS	Clock channel 4 -output
21	CLKOUT+	LVDS/CMOS	Clock channel 4 +output
22	CLKIN-	LVDS	Clock channel 4 -input
23	CLKIN+	LVDS/CMOS	Clock channel 4 +input
24	GND	0 V	Ground
25	IN3-	LVDS	Channel 3 -input
26	IN3+	LVDS/CMOS	Channel 3 +input

27	IN2-	LVDS	Channel 2 -input
28	IN2+	LVDS/CMOS	Channel 2 +input
29	IN1-	LVDS	Channel 1 -input
30	IN1+	LVDS/CMOS	Channel 1 +input
31	IN0-	LVDS	Channel 0 -input
32	IN0+	LVDS/CMOS	Channel 0 +input

REFERENCES

[1] The I2C-BUS Specification:

http://www.semiconductors.philips.com/acrobat_download/literature/9398/39340011.pdf

[2] See for example: <http://www.national.com/an/AN/AN-971.pdf>