

# Piranha4

**P4-CM-08K070-00-R**

**Monochrome Camera User's Manual**



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# 1. System Precautions and Cleaning

## Precautions

Read these precautions and this manual carefully before using the camera.

Confirm that the camera's packaging is undamaged before opening it. If the packaging is damaged please contact the related logistics personnel.

Do not open the housing of the camera. The warranty is voided if the housing is opened.

Keep the camera housing temperature in a range of 0 °C to 50 °C during operation.

Do not operate the camera in the vicinity of strong electromagnetic fields. In addition, avoid electrostatic charging, violent vibration, and excess moisture.

To clean the device, avoid electrostatic charging by using a dry, clean absorbent cotton cloth dampened with a small quantity of pure alcohol. Do not use methylated alcohol. To clean the surface of the camera housing, use a soft, dry cloth. To remove severe stains use a soft cloth dampened with a small quantity of neutral detergent and then wipe dry. Do not use volatile solvents such as benzene and thinners, as they can damage the surface finish. Further cleaning instructions are below.

Though this camera supports hot plugging, it is recommended that you power down and disconnect power to the camera before you add or replace system components.

## Electrostatic Discharge and the CMOS Sensor

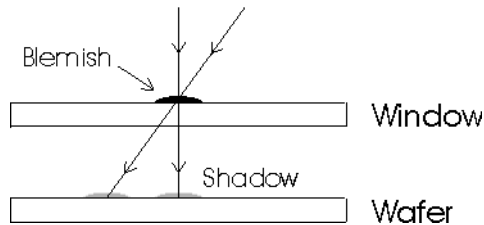
Image sensors and the camera bodies housing are susceptible to damage from electrostatic discharge (ESD). Electrostatic charge introduced to the sensor window surface can induce charge buildup on the underside of the window that cannot be readily dissipated by the dry nitrogen gas in the sensor package cavity. The charge normally dissipates within 24 hours and the sensor returns to normal operation.

## Protecting Against Dust, Oil, and Scratches

The sensor window is part of the optical path and should be handled like other optical components, with extreme care. Dust can obscure pixels, producing dark patches on the sensor response. Dust is most visible when the illumination is collimated. The dark patches shift position as the angle of illumination changes. Dust is normally not visible when the sensor is positioned at the exit port of an integrating sphere, where the illumination is diffuse. Dust can normally be removed by blowing the window surface using an ionized air gun. Oil is usually introduced during handling. Touching the surface of the window barehanded will leave oily residues. Using rubber fingercots and rubber gloves can prevent contamination. However, the friction between rubber and the window may produce electrostatic charge that may damage the sensor. To avoid ESD damage and to avoid introducing oily residues, avoid touching the sensor. Scratches diffract incident illumination. When exposed to uniform illumination, a sensor with a scratched window will normally have brighter pixels adjacent to darker pixels. The location of these pixels will change with the angle of illumination.

**An important note on window blemishes:**

When flat field correction is performed, window cleanliness is paramount. The figure below shows an example of what can happen if a blemish is present on the sensor window when flat field correction is performed. The blemish will cast a shadow on the wafer. FFC will compensate for this shadow by increasing the gain. Essentially FFC will create a white spot to compensate for the dark spot (shadow). As long as the angle of the incident light remains unchanged then FFC works well. However when the angle of incidence changes significantly (i.e. when a lens is added) then the shadow will shift and FFC will make things worse by not correcting the new shadow (dark spot) and overcorrecting where the shadow used to be (white spot). While the dark spot can be potentially cleaned, the white spot is an FFC artifact that can only be corrected by another FFC calibration.



## Cleaning the Sensor Window

### Recommended Equipment

- Glass cleaning station with microscope within clean room.
- 3M ionized air gun 980  
([http://solutions.3mcanada.ca/wps/portal/3M/en\\_CA/WW2/Country/](http://solutions.3mcanada.ca/wps/portal/3M/en_CA/WW2/Country/))
- Ionized air flood system, foot operated.
- Swab (HUBY-340CA-003)  
(<http://www.cleancross.net/modules/xfsection/article.php?articleid=24>)
- Single drop bottle (FD-2-ESD)
- E2 (Eclipse optic cleaning system ([www.photosol.com](http://www.photosol.com)))

### Procedure

- Use localized ionized air flow on to the glass during sensor cleaning.
- Blow off mobile contamination using an ionized air gun.
- Place the sensor under the microscope at a magnification of 5x to determine the location of any remaining contamination.
- Clean the contamination on the sensor using one drop of E2 on a swab.
- Wipe the swab from left to right (or right to left but only in one direction). Do this in an overlapping pattern, turning the swab after the first wipe and with each subsequent wipe. Avoid swiping back and forth with the same swab in order to ensure that particles are removed and not simply transferred to a new location on the sensor window. This procedure requires you to use multiple swabs.
- Discard the swab after both sides of the swab have been used once.
- Repeat until there is no visible contamination present.

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# 2. The Piranha4 Camera

## Camera Highlights

Based on Teledyne DALSA's unique line scan CMOS sensor architecture, the new Piranha4 8k dual line scan camera provides outstanding signal-to-noise for high speed imaging.

The P4-8k has 8k resolution with a  $7\text{ }\mu\text{m} \times 7\text{ }\mu\text{m}$  pixel size for optimized optical design. The camera delivers a max line rate of 70 kHz.

Precise sensor alignment simplifies multiple camera calibration at the system level. The camera delivers a throughput of 573 MPix/ s using the Camera Link™ interface. An advanced GenICam™ compliant interface makes the camera easier to setup, control, and integrate. Programmability includes exposure control, flat field correction, and gain settings.

The Piranha4 8k camera is ideal for flat panel display, printed circuit board, solar cell, film, and large format web inspection.

### Key Features

- 8192 x 2 pixels,  $7.04\text{ }\mu\text{m} \times 7.04\text{ }\mu\text{m}$  pixel pitch, 100% fill factor
- 70 KHz line rates
- 276 DN / (nJ / cm<sup>2</sup>) broadband @ 1x gain, 12 bit (dual line)
- 62 dB dynamic range

### Programmability

- Adjustable digital gain and offset
- 8, 10 or 12 bit selectable output
- Adjustable integration time and line rate
- Test patterns and camera diagnostics
- Flat field calibration

### Applications

- Flat-panel display inspection
- Printed circuit board inspection
- Parcel sorting
- High performance document scanning
- High throughput applications

## Models

The camera is available in the following configurations:

**Table 1: Camera Models Overview**

Model Number	Description
P4-CM-8K070-00-R	8k resolution, 70 kHz line rate, 573 Mpix/ s throughput, Camera Link interface.

**Table 2: Software**

Software	Product Number / Version Number
Camera firm ware	Embedded within camera
GenICam™ support (XML camera description file)	Embedded within camera
Sapera LT, including CamExpert GUI application and GenICam for Camera Link imaging driver	Version 7.20 or later

# Camera Performance Specifications

**Table 3: Camera Performance Specifications**

Specifications	Performance
Imager Format	CMOS dual line scan
Resolution	8192 x 2 pixels
Pixel Size	7.04 $\mu\text{m}$ x 7.04 $\mu\text{m}$
Pixel Fill Factor	100 %
Throughput	573 Mpix/ s
Line Rate	0 kHz minimum to 70 kHz maximum (Full), 41 kHz maximum (Medium), 20 kHz maximum (Base)
Exposure Time	7 $\mu\text{s}$ minimum to 3,000 $\mu\text{s}$ maximum
Bit Depth	8 bits, 10 bits, or 12 bits selectable
<b>Connectors and Mechanicals</b>	
Control & Data Interface	2 Camera Link MDR26 connectors, used to transmit Base, Medium, or Full Camera Link configurations
Power Connector	Hirose 6-pin circular
Power Supply	+ 12 V to + 24 V DC (+11.4 V to +25.2 V maximum limits)
Power Dissipation	17 W
Size	80 mm (W) x 130 mm (H) x 57 mm (D)
Mass	< 700 g, including heat sinks (< 530 g without heat sinks)
Operating Temp	0 °C to 50 °C, front plate temperature
<b>Optical Interface</b>	
Lens Mount	M72 x 0.75
Sensor to Camera Front Distance	12 mm
Sensor Alignment (aligned to sides of camera)	
Flatness	50 $\mu\text{m}$
$\Theta$ y (parallelism)	0.08° or 81 $\mu\text{m}$
x	$\pm$ 50 $\mu\text{m}$
y	$\pm$ 50 $\mu\text{m}$
z	$\pm$ 250 $\mu\text{m}$
$\Theta$ z	$\pm$ 0.2°



Compliance	
Regulatory Compliance	CE and RoHS; GenICam

Operating Ranges	Performance		Notes
	Single Line	Dual Line	
Dynamic Range	62 dB	63.3 dB	
Random Noise	3.42 DN *rms	2.8 DN rms	FFC enabled
Broadband Responsivity	198 DN/ (nJ/ cm <sup>2</sup> )	276 DN/ (nJ/ cm <sup>2</sup> )	
Gain	1x to 10x Nominal range	1x to 10x Nominal range	
DC Offset	16 DN	16 DN	FFC enabled
PRNU	<1% @50% Sat	<1% @50% Sat	
FPN	< 5 DN	< 5 DN	
SEE	20.2 nJ/ cm <sup>2</sup>	14.49 nJ/ cm <sup>2</sup>	
NEE	11.16 pJ/ cm <sup>2</sup>	12.39 pJ/ cm <sup>2</sup>	
Antiblooming	> 100 x Saturation		
Integral non-linearity	< 2% DN		

\*DN = digital number

Test Conditions:

- Values measured using 12-bit, 1x gain.
- 10 kHz line rate
- Light source: broadband, quartz halogen, 3250 K with 700 nm IR cutoff filter.
- Front plate temperature: 45° C

## Certifications and Compliance

Compliance
EN 55011, FCC Part 15, CISPR 11, and ICES-003 Class A Radiated Emissions Requirements
EN 55024 and EN 61326-1 Immunity to Disturbance
RoHS per EU Directive 2002/ 95/ EC and WEEE per EU Directive 2002/ 96/ EC and China Electronic Industry Standard SJ/ T11364-2006
GenICam XML Description File, Superset of the GenICam™ Standard Features Naming Convention specification V1.5, Camera Link Serial Communication: GenICam™ Generic Control Protocol (GenCP V1.0)

## Supported Industry Standards

### GenICam™

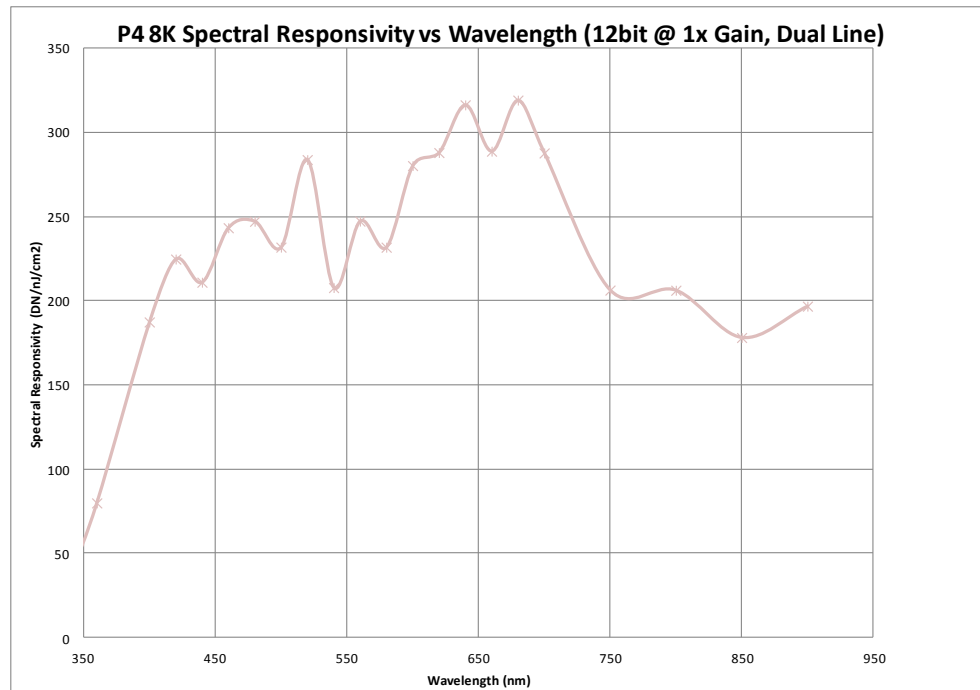
Piranha4 cameras are GenICam compliant. They implement a superset of the GenICam™ Standard Features Naming Convention specification V1.5.

This description takes the form of an XML device description file respecting the syntax defined by the GenApi module of the GenICam™ specification. The camera uses the GenICam™ Generic Control Protocol (GenCP V1.0) to communicate over the Camera Link serial port.

For more information see [www.genicam.org](http://www.genicam.org).

# Responsivity

The responsivity graph describes the sensor response to different wavelengths of light (excluding lens and light source characteristics).



**Figure 1: Spectral Responsivity vs. Wavelength (Dual Line)**

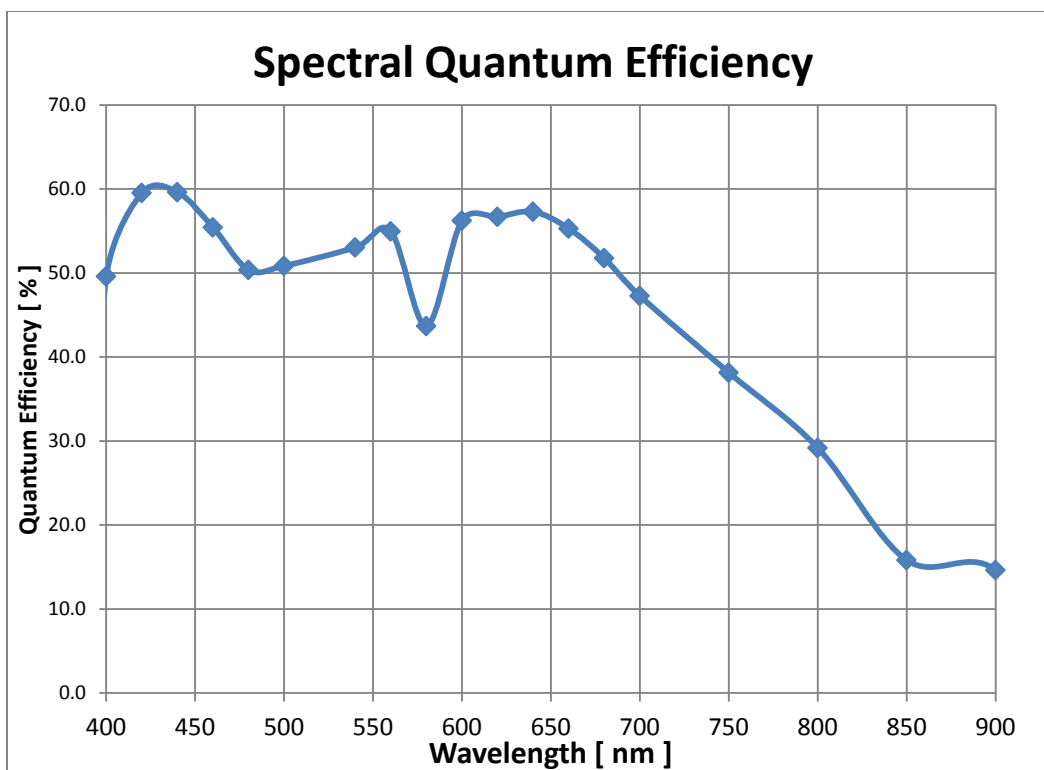


Figure 2: Spectral Quantum Efficiency

## FPN Characteristics with Temperature

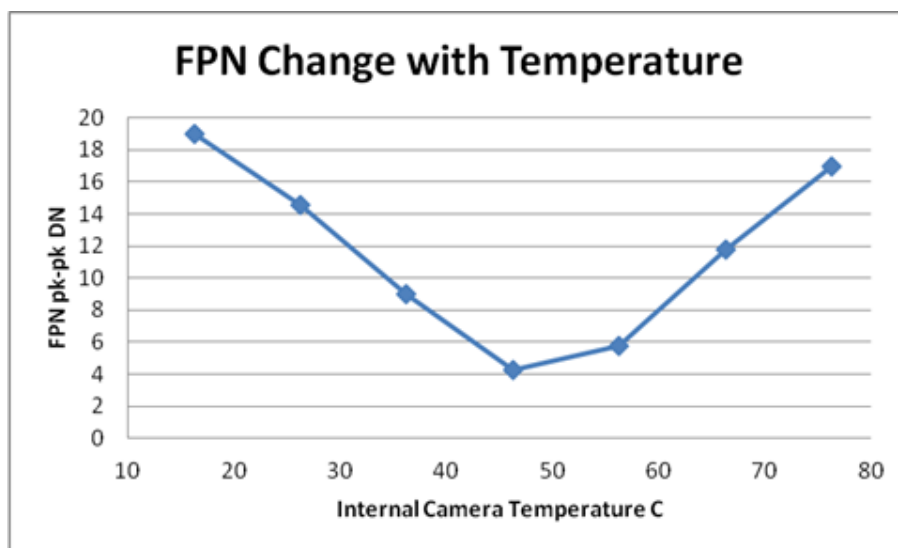


Figure 3: FPN Derating Chart

# Mechanicals

**Figure 4: Camera Mechanical**

**Figure 5: Camera Mechanical with External Heat Sink**

## **Camera Mounting and Heat Sink Considerations**

The Piranha4 cameras ship with two heat sinks installed and ideally positioned to allow close spacing of the cameras. These heat sinks are designed to provide adequate convection cooling when not obstructed by enclosures or mounting assemblies.

Teledyne DALSA recognises that each customer's application can be unique. In consideration, the P4 camera heat sinks have been designed in such a way that they can be repositioned on the different faces of the camera or removed entirely, depending on the mounting configuration and its heat sinking potential.

Repositioning or removal of the heat sinks must be performed with care in order to avoid temperature issues. The camera has the ability to measure its internal temperature. Use this feature to record the internal temperature of the camera when it is mounted in your system and operating under the worst case conditions. The camera will stop outputting data if its internal temperature reaches 75 °C.

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# 3. Software and Hardware Setup

## Recommended System Requirements

To achieve best system performance, the following minimum requirements are recommended:

- High bandwidth frame grabber recommended, e.g. Xcelera-CL PX4 Full Camera Link frame grabber (Part # OR-X4CO-XPFO0).
- Operating system: Windows XP 32-bit.

## Setup Steps: Overview

Take the following steps in order to setup and run your camera system. They are described briefly below and in more detail in the sections that follow.

### 1. Install and Configure Frame Grabber and GUI

If your host computer does not have a PX4 full Camera link frame grabber then you need to install one.

We recommend the Xcelera-CL PX4 Full frame grabber or equivalent, described in detail on the [teledynedalsa.com](http://teledynedalsa.com) site [here](#). Follow the manufacturer's installation instructions.

A GenICam™ compliant XML device description file is embedded within the camera firmware allowing GenICam™ compliant application to know the camera's capabilities immediately after connection. Installing SperaLT gives you access to the CamExpert GUI, a GenICam™ compliant application.

### 2. Connect Camera Link and Power Cables

- Connect the Camera Link cables from the camera to the computer.
- Connect a power cable from the camera to a +12 VDC to +24 VDC power supply.

### 3. Establish communicating with the camera

Start the GUI and establish communication with the camera. Refer to page 15 for a description on communicating with the camera.

#### ASCII Commands

As an alternative to the CamExpert (or equivalent) GUI, you can communicate with this camera using ASCII-based commands. A complete list of the commands and a description of how to access them can be found in the appendix: [Appendix B: ASCII Commands](#).

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## 4. Operate the Camera

At this point you will be ready to start operating the camera in order to acquire images, set camera functions, and save settings.

# Step 1. Install and configure the frame grabber, graphics card and GUI

## Install Frame Grabber

Install a Full configuration Camera Link frame grabber according to the manufacturer's description.

We recommend the Xcelera-CL PX4 frame grabber or equivalent, described in detail on the [teledynedalsa.com](http://teledynedalsa.com) site [here](#).

## Install Sopera LT and CamExpert

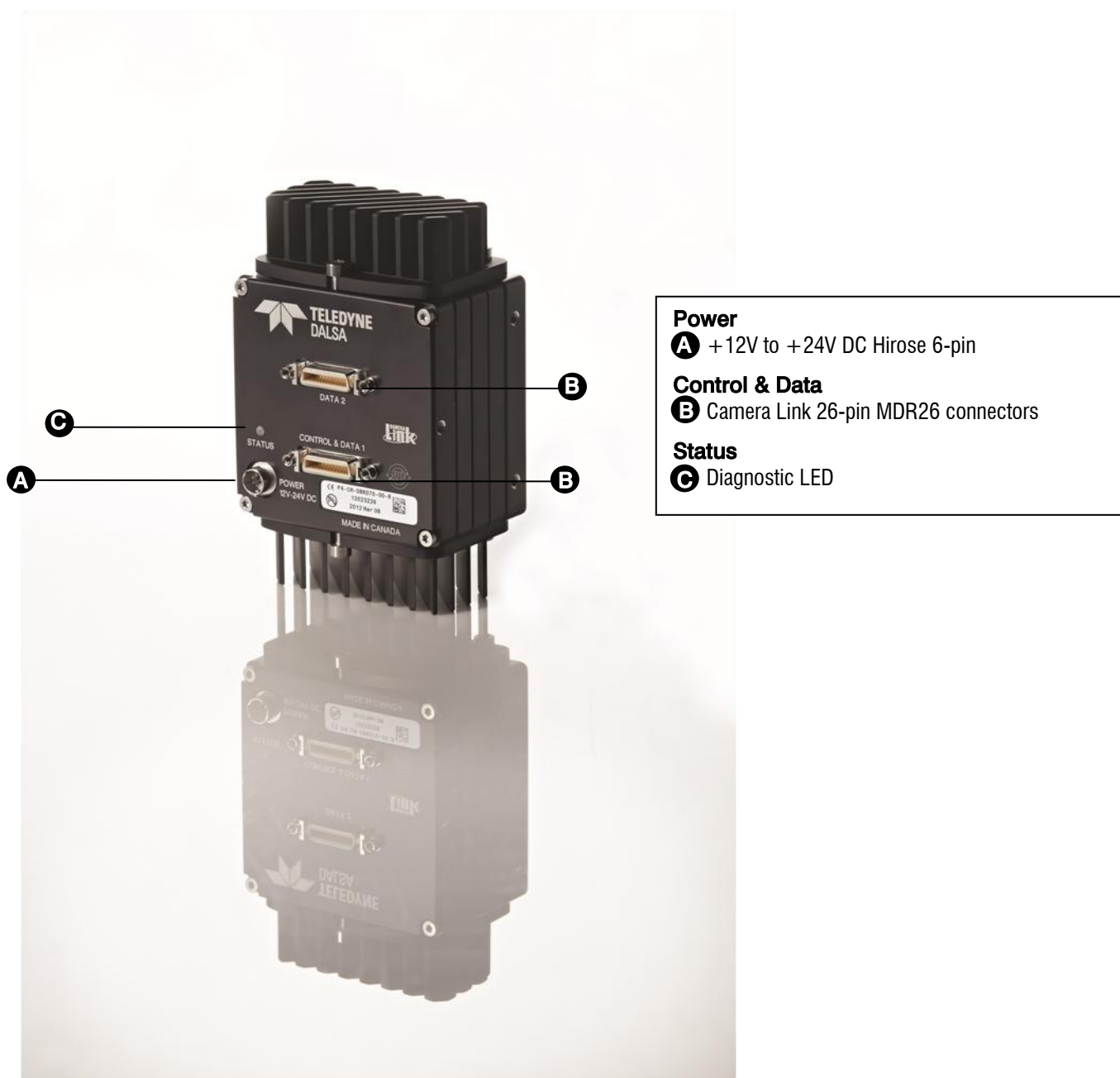
Communicate with the camera using a Camera Link-compliant interface. We recommend you use CamExpert. CamExpert is the camera interfacing tool supported by the Sopera library and comes bundled with SoperaLT. Using CamExpert is the simplest and quickest way to send commands to and receive information from the camera.

### Camera Link Control Communications

The P4 family of cameras are GenICam™ compliant. Sopera uses the GenICam™ Generic Control Protocol (GenCP V1.0) to communicate with the camera over the Camera Link serial port. When communications are first established Sopera will when connecting for the first time download the GenICam™ XML Description file. This file details how to access and control the camera.

# Step 2. Connect Data, Trigger, and Power Cables

Note: the use of cables types and lengths other than those specified may result in increased emission or decreased immunity and performance of the camera.



**Figure 6: Input and Output, Trigger, and Power Connectors**



**WARNING! Grounding Instructions**

Static electricity can damage electronic components. It's critical that you discharge any static electrical charge by touching a grounded surface, such as the metal computer chassis, before handling the camera hardware.



## Data Connector: Camera Link

The camera uses two Camera Link MDR26 cables transmitting the Camera Link Base, Medium, or Full configuration. The figure below shows the MDR26 Camera Link Connector and the tables that follow list the Camera Link Base, Medium, and Full configurations.

For detailed information on Camera Link please refer to the Camera Link Road Map available from the Knowledge Center on the Teledyne DALSA Web site:

(<http://www.teledynedalsa.com/mv/knowledge/appnotes.aspx>).

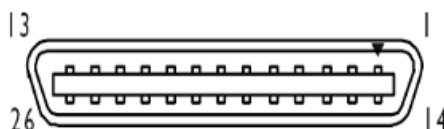


Figure 7. MDR26 Camera Link Connector

Data 2			Control / Data 1		
Camera Connector	Right Angle Frame Grabber Connector	Channel Link Signal	Camera Connector	Right Angle Frame Grabber Connector	Channel Link Signal
1	1	inner shield	1	1	inner shield
14	14	inner shield	14	14	inner shield
2	25	Y0-	2	25	X0-
15	12	Y0+	15	12	X0+
3	24	Y1-	3	24	X1-
16	11	Y1+	16	11	X1+
4	23	Y2-	4	23	X2-
17	10	Y2+	17	10	X2+
5	22	Yclk-	5	22	Xclk-
18	9	Yclk+	18	9	Xclk+
6	21	Y3-	6	21	X3-
19	8	Y3+	19	8	X3+
7	20	100 ohm	7	20	SerTC+
20	7	terminated	20	7	SerTC-
8	19	Z0-	8	19	SerTFG-
21	6	Z0+	21	6	SerTFG+
9	18	Z1-	9	18	CC1-
22	5	Z1+	22	5	CC1+
10	17	Z2-	10	17	CC2+
23	4	Z2+	23	4	CC2-
11	16	Zclk-	11	16	CC3-
24	3	Zclk+	24	3	CC3+
12	15	Z3-	12	15	CC4+
25	2	Z3+	25	2	CC4-
13	13	inner shield	13	13	inner shield

26	26	inner shield	26	26	inner shield
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\*Exterior Overshield is connected to the shells of the connectors on both ends. Unused pairs should be terminated in 100 ohms at both ends of the cable. Inner shield is connected to signal ground inside camera

## Full Configuration

### 8 bits Camera Link Full Configuration

Connector 1: Channel link X		Connector 2: Channel link Y		Connector 3: Channel link Z	
Camera/Frame Grabber Pin	Bit Name	Camera/Frame Grabber Pin	Bit Name	Camera/Frame Grabber Pin	Bit Name
Tx0/Rx0	D0(0)	Tx0/Rx0	D3(0)	Tx0/Rx0	D6(0)
Tx1/Rx1	D0(1)	Tx1/Rx1	D3(1)	Tx1/Rx1	D6(1)
Tx2/Rx2	D0(2)	Tx2/Rx2	D3(2)	Tx2/Rx2	D6(2)
Tx3/Rx3	D0(3)	Tx3/Rx3	D3(3)	Tx3/Rx3	D6(3)
Tx4/Rx4	D0(4)	Tx4/Rx4	D3(4)	Tx4/Rx4	D6(4)
Tx5/Rx5	D0(7)	Tx5/Rx5	D3(7)	Tx5/Rx5	D6(7)
Tx6/Rx6	D0(5)	Tx6/Rx6	D3(5)	Tx6/Rx6	D6(5)
Tx7/Rx7	D1(0)	Tx7/Rx7	D4(0)	Tx7/Rx7	D7(0)
Tx8/Rx8	D1(1)	Tx8/Rx8	D4(1)	Tx8/Rx8	D7(1)
Tx9/Rx9	D1(2)	Tx9/Rx9	D4(2)	Tx9/Rx9	D7(2)
Tx10/Rx10	D1(6)	Tx10/Rx10	D4(6)	Tx10/Rx10	D7(6)
Tx11/Rx11	D1(7)	Tx11/Rx11	D4(7)	Tx11/Rx11	D7(7)
Tx12/Rx12	D1(3)	Tx12/Rx12	D4(3)	Tx12/Rx12	D7(3)
Tx13/Rx13	D1(4)	Tx13/Rx13	D4(4)	Tx13/Rx13	D7(4)
Tx14/Rx14	D1(5)	Tx14/Rx14	D4(5)	Tx14/Rx14	D7(5)
Tx15/Rx15	D2(0)	Tx15/Rx15	D5(0)	Tx15/Rx15	Not Used
Tx16/Rx16	D2(6)	Tx16/Rx16	D5(6)	Tx16/Rx16	Not Used
Tx17/Rx17	D2(7)	Tx17/Rx17	D5(7)	Tx17/Rx17	Not Used
Tx18/Rx18	D2(1)	Tx18/Rx18	D5(1)	Tx18/Rx18	Not Used
Tx19/Rx19	D2(2)	Tx19/Rx19	D5(2)	Tx19/Rx19	Not Used
Tx20/Rx20	D2(3)	Tx20/Rx20	D5(3)	Tx20/Rx20	Not Used
Tx21/Rx21	D2(4)	Tx21/Rx21	D5(4)	Tx21/Rx21	Not Used
Tx22/Rx22	D2(5)	Tx22/Rx22	D5(5)	Tx22/Rx22	Not Used
Tx23/Rx23	Not Used	Tx23/Rx23	Not Used	Tx23/Rx23	Not Used
Tx24/Rx24	LVAL	Tx24/Rx24	LVAL	Tx24/Rx24	LVAL
Tx25/Rx25	FVAL	Tx25/Rx25	FVAL	Tx25/Rx25	FVAL
Tx26/Rx26	Not Used	Tx26/Rx26	Not Used	Tx26/Rx26	Not Used
Tx27/Rx27	D0(6)	Tx27/Rx27	D3(6)	Tx27/Rx27	D6(6)

Tap 1 bits are D0(x)...Tap 8 bits are D7(x)

## Camera Link Bit Definitions

BASE Configuration	T0							
Pixel Format	Port A Bits 0 thru 7		Port B Bits 0 thru 7		Port C Bits 0 thru 7			
Mono 8	Tap 1 LSB..Bit 7 Pixels (1, 3, 5, ... 8189, 8191)		Tap 2 LSB..Bit7 Pixels (2, 4, 6, ... 8190, 8192)		xxxxxxx			
Mono 12	Tap 1 LSB.. Bit 7 Pixels (1, 3, 5, ... 8189, 8191)		Tap 1 Bits 8,9,10,11 Pixels (1, 3, 5, ... 8189,8191) Tap 2 Bits 8,9,10,11 Pixels (2,4,6, ... 8190, 8192)		Tap 2 LSB..Bit 7 Pixels (2,4,6, ... 8190, 8192)			
Medium Configuration	T0							
Pixel Format	Port A Bits 0 thru 7	Port B Bits 0 thru 7	Port C Bits 0 thru 7	Port D Bits 0 thru 7	Port E Bits 0 thru 7	Port F Bits 0 thru 7		
Mono 8	Tap 1 LSB..Bit 7 Pixels (1, 5, 9, ... 8185, 8189)	Tap 2 LSB..Bit 7 Pixels (2, 6, 10, ... 8186, 8190)	Tap 3 LSB..Bit 7 Pixels (3, 7, 11, ... 8187, 8191)	Tap 4 LSB...Bit 7 Pixels (4, 8, 12, ... 8188, 8192)	xxxxxxxx	Xxxxxxxxx		
Mono 10 / Mono 12	Tap 1 LSB.. Bit 7 Pixels (1, 5, 9, ... 8187, 8191)	Tap 1 Bits 8,9,10,11 Pixels (1, 5, 9, ... 8187, 8191)  Tap 2 Bits 8,9,10,11 Pixels (2, 6, 10, ... 8188, 8192)	Tap 2 LSB..Bit 7 Pixels (2, 6, 10, ... 8188, 8192)	Tap 4 LSB...Bit 7 Pixels (4, 8, 12, ... 8186, 8190)	Tap 3 LSB...Bit 7 Pixels (3, 7, 11, ... 8185, 8189)	Tap 3 Bit 8,9,10,11 Pixels (3, 7, 11, ... 8185, 8189)  Tap 4 Bits 8,9,10,11 Pixels (4, 8, 12, ... 8186, 8190)		
Full Configuration	T0							
Pixel Format	Port A LSB...Bit 7	Port B LSB...Bit 8	Port C LSB...Bit 8	Port D LSB...Bit 8	Port E LSB...Bit 8	Port F LSB...Bit 8	Port G LSB...Bit 8	Port H LSB...Bit 8
Mono 8	Tap 1 LSB... Bit 7 Pixels (1, 9, 17, ... 8177, 8185)	Tap 2 LSB... Bit 7 Pixels (2, 10, 18, ... 8178, 8186)	Tap 3 LSB... Bit 7 Pixels (3, 11, 19, ... 8179, 8187)	Tap 4 LSB... Bit 7 Pixels (4, 12, 20, ... 8180, 8188)	Tap 5 LSB... Bit 7 Pixels (5, 13, 21, ... 8181, 8189)	Tap 6 LSB... Bit 7 Pixels (6, 14, 22, ... 8182, 8190)	Tap 7 LSB...Bit 7 Pixels (7, 15, 23, ... 8183, 8191)	Tap 8 LSB... Bit 7 Pixels (8, 16, 24, ... 8184, 8192)

Table 4: Camera Link Bit Definitions

Signal	Configuration
CC1	EXSYNC
CC2	Spare
CC3	Direction
CC4	Spare

**Table 5: Camera Control Configuration**

For additional Camera Link documentation refer to the Knowledge Center on Teledyne DALSA Web site:  
[http:// www.teledynedalsa.com/ imaging/ knowledge-center/](http://www.teledynedalsa.com/imaging/knowledge-center/).

## Camera Link cable quality and length

The maximum allowable Camera Link cable length depends on the quality of the cable used and the Camera Link strobe frequency. Cable quality degrades over time as the cable is flexed. In addition, as the Camera Link strobe frequency is increased the maximum allowable cable length will decrease.

The Piranha4 cameras are capable of driving cables 10 metres or less in length. We do not guarantee good imaging performance with low quality cables of *any* length. In general, we recommend the use of high quality cables for any cable length.

## Input Signals, Camera Link

The camera accepts control inputs through the Camera Link MDR26F connector. The camera ships in internal sync, and internally programmed integration.

### EXSYNC (Line Readout Trigger)

Line rate can be set internally using the GenICam features. The external control signal EXSYNC is optional and enabled through the user interface. This camera uses the falling edge of EXSYNC to trigger pixel readout.

The EXSYNC signal tells the camera when to integrate and readout the image. It can be either an internally generated signal by the camera, or it can be supplied externally via the serial interface. Depending upon the mode of operation the high time of the EXSYNC signal can represent the integration period.

**Note:** The EXSYNC signal is measured at CC1 and will give a “true” measurement (i.e. within the measurement resolution of 25 ns) even though the camera will only trigger at a maximum of 70 KHz.

## Output Signals, Camera Link Clocking Signals

These signals indicate when data is valid, allowing you to clock the data from the camera to your acquisition system. These signals are part of the Camera Link configuration and you should refer to the Camera Link Implementation Road Map, available at our [Knowledge Center](#), for the standard location of these signals.

Clocking Signal	Indicates
LVAL (high)	Outputting valid line
DVAL	Not used
STROBE (rising edge)	Valid data
FVAL	Tied to LVAL

## Power Connector



**WARNING:** It is extremely important that you apply the appropriate voltages to your camera. Incorrect voltages may damage the camera. Input voltage requirement: +12 VDC to +24 VDC, 2 Amps. Before connecting power to the camera, test all power supplies.

Hirose 6-pin Circular Male



Mating Part: HIROSE  
HR10A-7P-6S

**Figure 8: 6-pin Hirose Circular Male Power Plug—Power Connector**

**Table 6. Power Plug Pinout**

Pin	Description	Pin	Description
1	+12 V to +24 V DC	4	GND
2	+12 V to +24 V DC	5	GND
3	+12 V to +24 V DC	6	GND

The camera requires a single voltage input +12 VDC to +24 VDC. The camera meets all performance specifications using standard switching power supplies, although well-regulated linear supplies provide optimum performance.

### **WARNING: When setting up the camera's power supplies follow these guidelines:**



- Apply the appropriate voltages.
- Protect the camera with a 2 amp slow-blow fuse between the power supply and the camera.
- Do not use the shield on a multi-conductor cable for ground.
- Keep leads as short as possible in order to reduce voltage drop.
- Use high-quality supplies in order to minimize noise.

**Note:** If your power supply does not meet these requirements, then the camera performance specifications are not guaranteed.

## LEDs

The camera is equipped with an LED on the back to display the operational status of the camera. The table below summarizes the operating states of the camera and the corresponding LED states. When more than one condition is active, the LED indicates the condition with the highest priority.

Color of Status LED	Meaning
Off	No power, or hardware malfunction.
Dark Blue	In boot-loader. Completing firmware upgrade.
Light Blue	Busy. For example, powering up or performing a calibration.
Green	Ready.
Red	Error. Check BiST register for the specific error.

## Step 3. Establish Communication with the Camera

### Power on the camera

Turn on the camera's power supply. You may have to wait while the camera readies itself for operation. The camera must boot fully before it will be recognized by the GUI—the LED shines green once the camera is ready.

### Connect to the frame grabber

1. Start Sapera CamExpert (or equivalent Camera Link compliant interface) by double clicking the desktop icon created during the software installation.
2. CamExpert will search for installed Sapera devices. In the Devices list area on the left side, the connected frame grabber will be shown.
3. Select the frame grabber device by clicking on the name.

### Connect to the camera

1. Start a new Sapera CamExpert application (or equivalent Camera Link compliant interface) by double clicking the desktop icon created during the software installation.
2. In the Devices list area on the left side, select the COM port below the CamerLink label.



Figure 9. CamExpert Icon, created during software installation

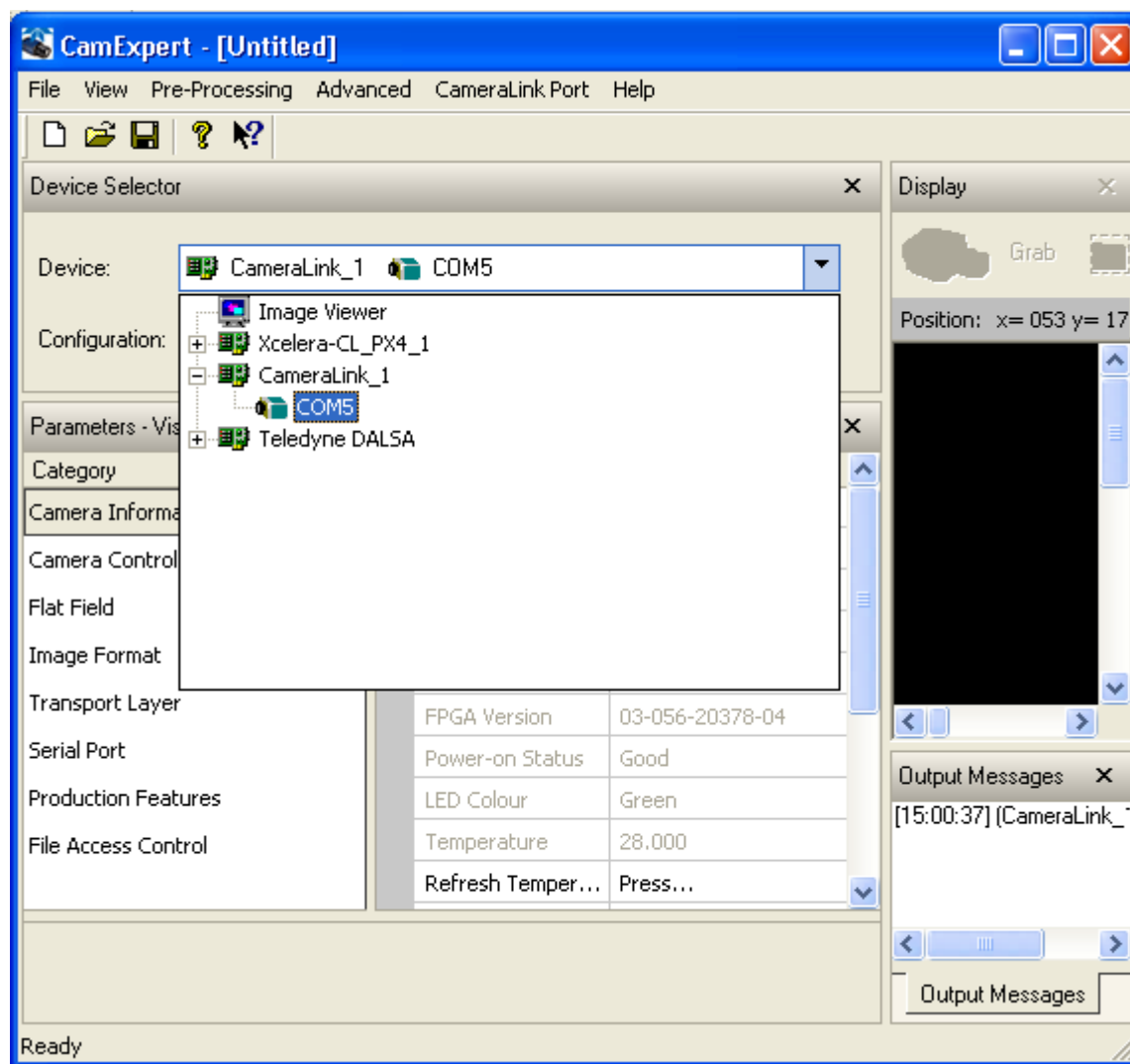


Figure 10. CamExpert GUI showing connected camera

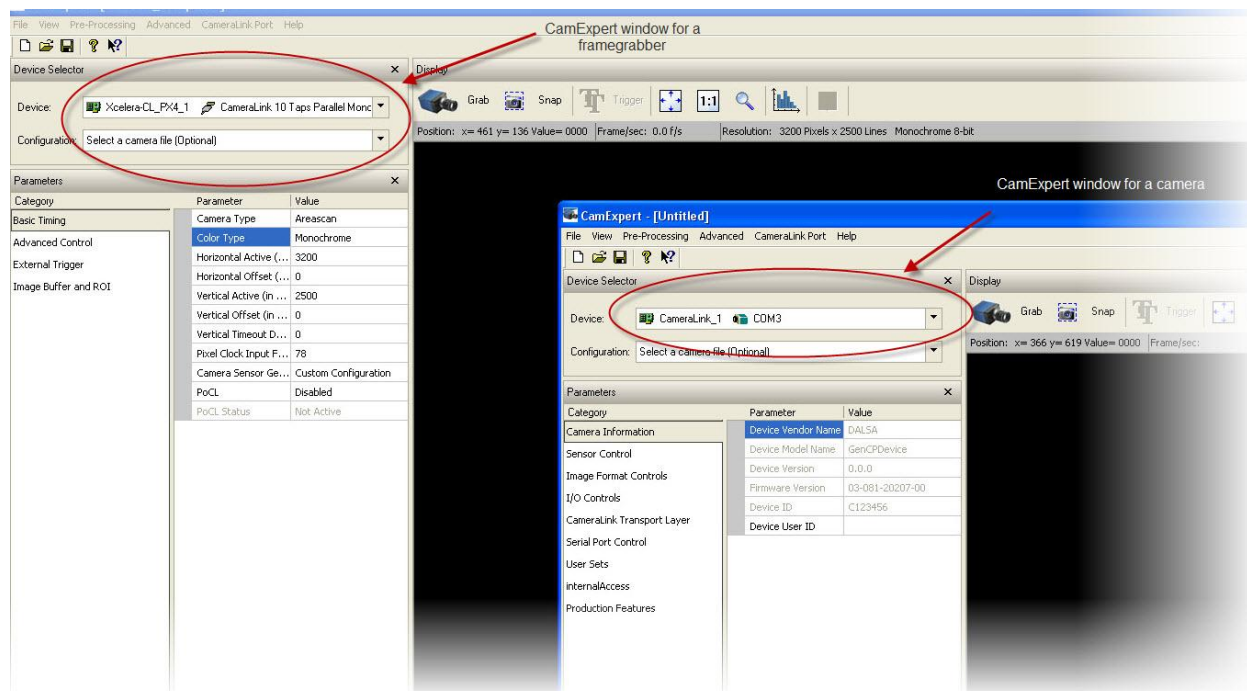
## Check LED Status

If the camera is operating correctly at this point, the diagnostic LED will shine green.

## Software Interface

All the camera features can be controlled through the CamExpert interface. For example, under the Camera Control menu in the camera window you can control the line rate and exposure times.

Note: the camera uses two CamExpert windows to send commands and display the results. One window controls the camera and the other is used for image acquisition and display.



**Figure 11. Two CamExpert window shown. One connected to the frame grabber and one to the camera.**



At this point your host and camera system should be setup and you can verify the camera's operation by retrieving a test pattern and setting the camera's trigger and exposure time.

Note that within the CamExpert window that controls the camera, the image display and associated buttons such as Grab and Snap are inactive and have no function.

## Using Sapera CamExpert with Piranha4 Cameras

CamExpert is the camera interfacing tool supported by the Sapera library. When used with a Piranha4 camera, CamExpert allows a user to test all camera operating modes. Additionally CamExpert saves the camera user settings configuration to the camera or saves multiple configurations as individual camera parameter files on the host system (\*.ccf). CamExpert can also be used to upgrade the camera's software.

An important component of CamExpert is its live acquisition display window which allows immediate verification of timing or control parameters without the need to run a separate acquisition program.

For context sensitive help, click on the  button then click on a camera configuration parameter. A short description of the configuration parameter will be shown in a popup. Click on the  button to open the help file for more descriptive information on CamExpert.

The central section of CamExpert provides access to the camera features and parameters. Note: The availability of the features is dependent on the CamExpert user setting.



## CamExpert Panes

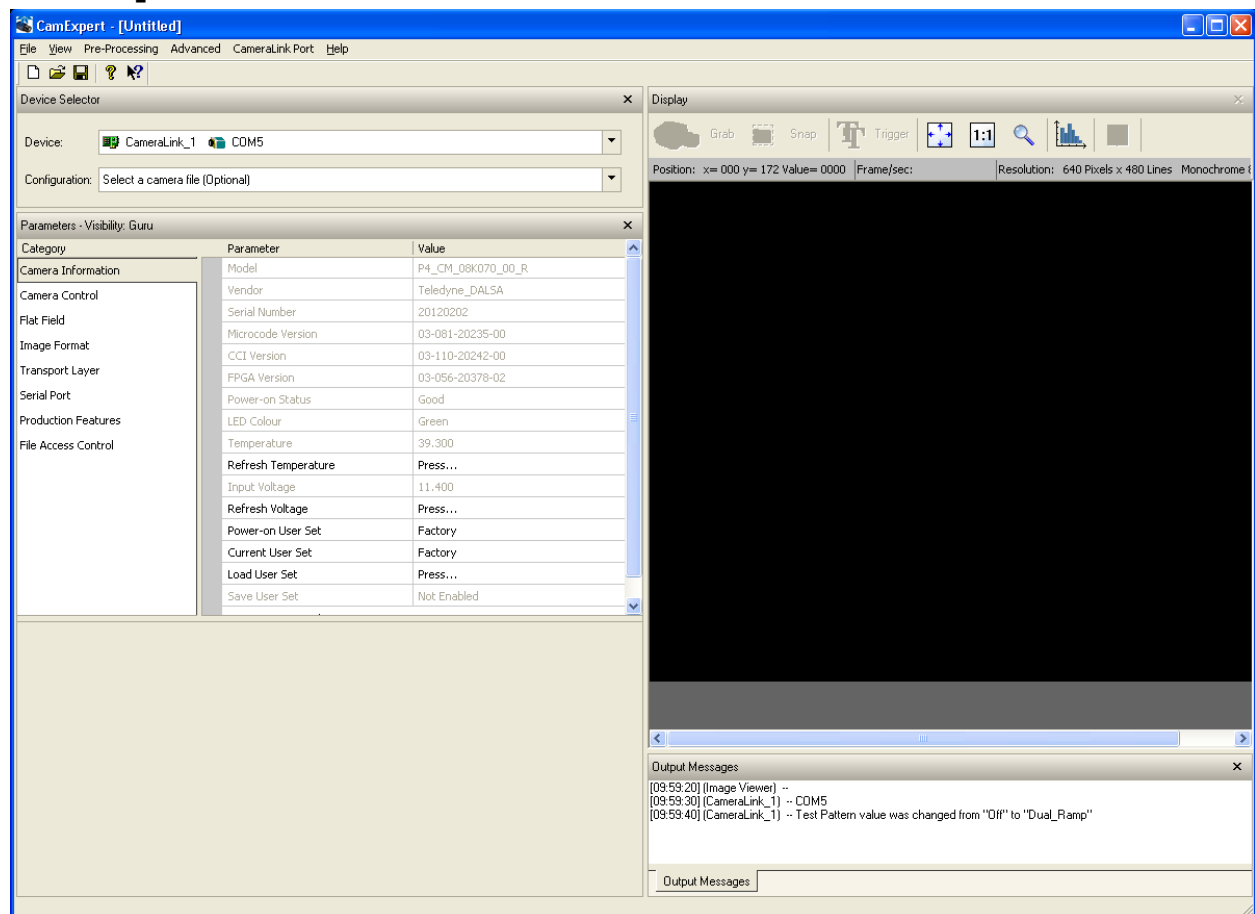


Figure 12. CamExpert's Camera Control Window

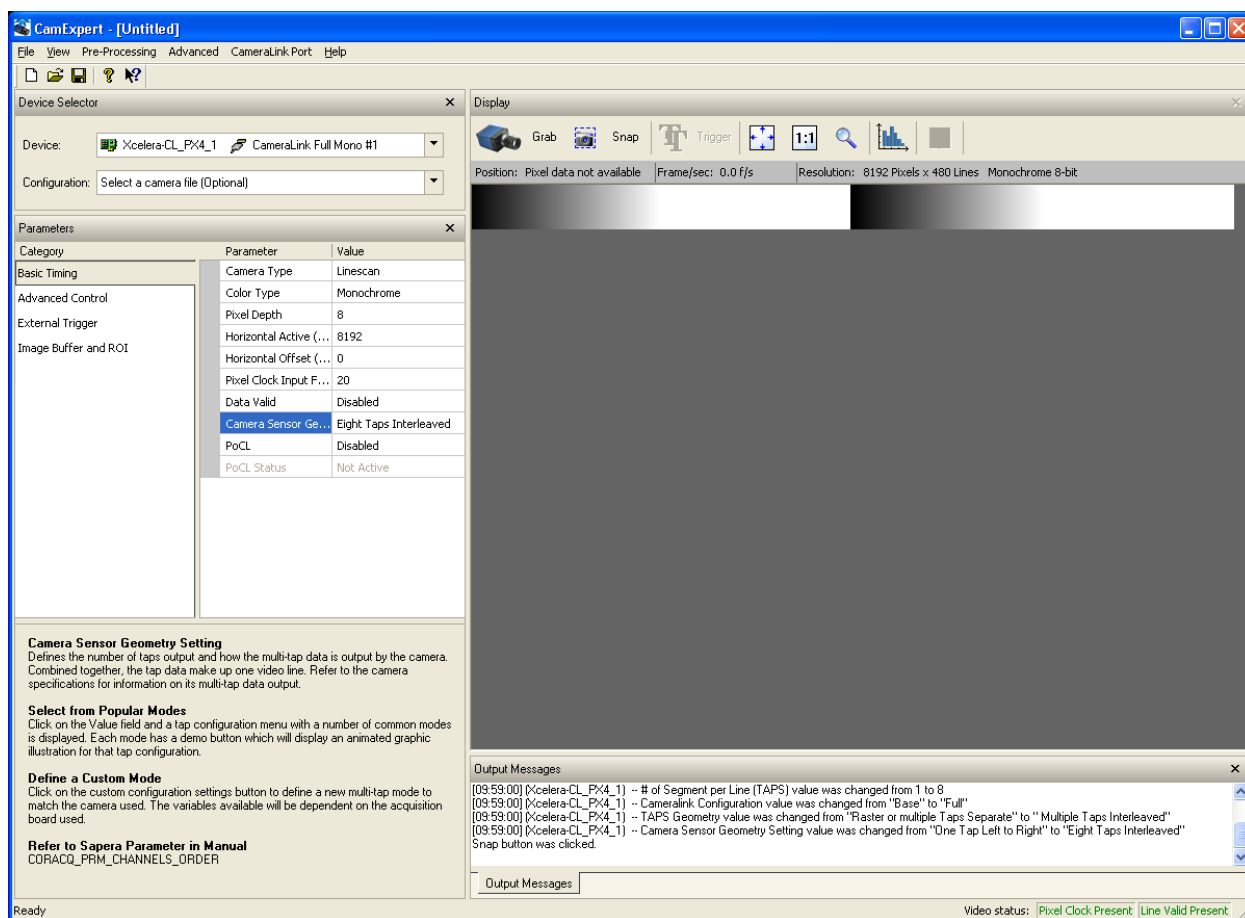




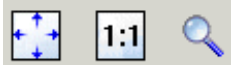



Figure 13. CamExpert's Image Acquisition Window

The CamExpert application uses panes to simplify choosing and configuring camera files or acquisition parameters for the installed device.

- **Device Selector pane:** View and select from any installed Sapera acquisition device. Once a device is selected CamExpert will only present acquisition parameters applicable to that device. Optionally select a camera file included with the Sapera installation or saved by the user.
- **Parameters pane:** Allows viewing or changing all acquisition parameters supported by the acquisition device. CamExpert displays parameters only if those parameters are supported by the installed device. This avoids confusion by eliminating parameter choices when they do not apply to the hardware in use.
- **Display pane:** Provides a live or single frame acquisition display. Frame buffer parameters are shown in an information bar above the image window.
- **Control Buttons:** The Display pane includes CamExpert control buttons. These are:

 Grab  Freeze	<b>Acquisition control button:</b> Click once to start live grab, click again to stop.
 Snap	<b>Single frame grab:</b> Click to acquire one frame from device.
 Trigger	<b>Trigger button:</b> With the I/ O control parameters set to Trigger Enabled, click to send a single trigger command.
	<b>CamExpert display controls:</b> (these do not modify the frame buffer data) Stretch image to fit, set image display to original size, or zoom the image to any size and ratio.
	<b>Histogram / Profile tool:</b> Select to view a histogram or line/ column profile during live acquisition or in a still image.

- **Output Message pane:** Displays messages from CamExpert or the device driver.

## Review a Test Image

The camera is now ready to retrieve a test pattern. Select **Image Format Control > Test Pattern** and choose one of the following available test images.

0. Off: Sensor Video

1. Ramp



2. A5: 4 pixels repeating\*



3. Each Tap Fixed\*



4. All\_1365\*



5. All\_1\*



\*12-bit, single line. low sensitivity.

At this point you are ready to start operating the camera in order to acquire images, set camera functions, and save settings.

## 4. Camera Operation

### Factory Settings

The camera ships and powers up for the first time with the following factory settings:

- Camera Link Full, 8 bit pixels
- Internal trigger, line rate 10 kHz
- Internal exposure control, exposure time 50  $\mu$ s
- 2 stage TDI
- 1x horizontal and vertical binning
- Flat field enabled, all pixel coefficients set to 1x
- Offset 0, Gain 1x

### Check Camera and Sensor Information

Camera and sensor information can be retrieved via a controlling application—for example, the CamExpert GUI shown in the following examples. Parameters such as camera model, firmware version, sensor characteristics, etc. are read to uniquely identify the connected device.

The camera information parameters are grouped together as members of the Camera Information set.

Category	Parameter	Value
Camera Information	Model	P4_CM_08K070_00_R
Camera Control	Vendor	Teledyne_DALSA
Flat Field	Serial Number	15005465
Image Format	Microcode Version	03-081-20235-03
Transport Layer	CCI Version	03-110-20242-03
Serial Port	FPGA Version	03-056-20378-04
Production Features	Power-on Status	Good
File Access Control	LED Colour	Green
	Temperature	28.000
	Refresh Temperature	Press...
	Input Voltage	11.600
	Refresh Voltage	Press...
	Power-on User Set	UserSet1
	Current User Set	UserSet1
	Load User Set	Press...
	Save User Set	Press...

# Verify Temperature and Voltage

To determine the voltage and temperature at the camera, use the **Refresh Voltage and Refresh Temperature** features found in the **Camera Information** set.

The temperature returned is the internal temperature in degrees Celsius. For proper operation, this value should not exceed 75 °C. If the camera exceeds the designated temperature it will stop imaging and the LED will turn red. Once you have diagnosed and remedied the issue use the **reset camera** function.

The voltage displayed is the camera's input voltage. Note that the voltage measurement feature of the camera provides only approximate results (typically within 10% and dependent on the voltage drop in the cable). The measurement should not be used to set the applied voltage to the camera, but only used as a test to isolate gross problems with the supply voltage.

# Saving and Restoring Camera Settings

The parameters used to select, load and save user sets are grouped together under the Camera Information set of features. There are 8 user sets available and one factory set.

Camera Information	
Parameter	Choices
User Set Default Selector	Select the camera parameters to load when the camera is reset or powered up as the Factory set, or as User Set 1 to 8.  Selecting the set from the list automatically saves it as the default set.
User Set Selector	Select the Factory or User set to Save or Load. -Factory Set -User Set 1 to 8.
User Set Load	Load the set specified by User Set Selector to the camera and make it the active / current set.
User Set Save	Save the current set as selected user set.

## Description of the Camera Settings

The camera operates in one of three settings:

1. Current session.
2. User setting.
3. Factory setting (read-only).
4. Default setting.

The current settings can be saved (thereby becoming the user setting) using the User Set Save parameter. A previously saved user setting (User Set 1 to 8) or the factory settings can be restored using the User Set Selector and User Set Load parameters.

Either the Factory or one of the User settings can be saved as the Default Setting by selecting the set in the User Set Default Selector. The chosen set automatically saves as the default setting and is the set loaded when the camera is reset or powered up.

The relationship between these three settings is illustrated in Figure 14. Relationship between the Camera Settings:

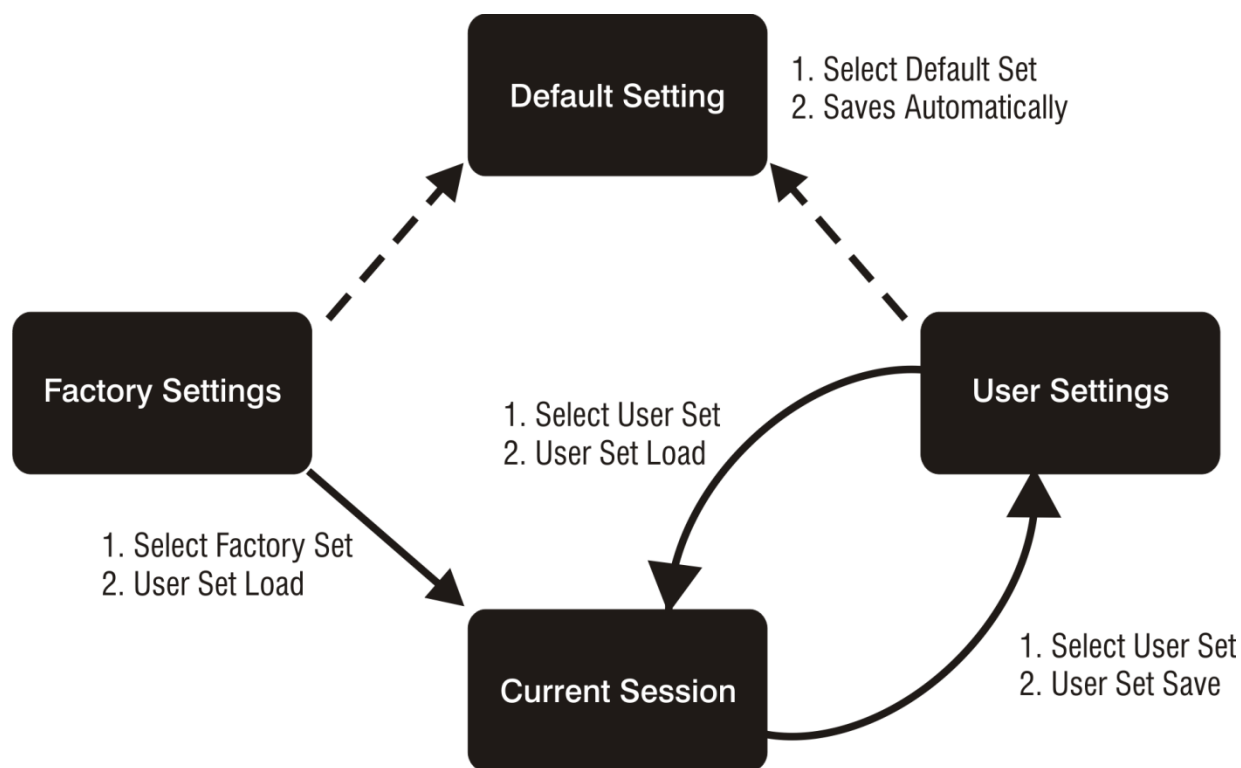


Figure 14. Relationship between the Camera Settings

### Active Settings for Current Session

The active setting for the current session is the set of configurations that are operating while the camera is currently running, including all unsaved changes you have made to the settings before saving them.

These active settings are stored in the camera's *volatile* memory and will be lost and cannot be restored if the camera resets or if the camera is powered down or loses power.

To save these settings for reuse the next time you power up or reset the camera, or to protect against losing them in the case of power loss, you must save the current settings using the **User Set Save** parameter. Once saved, the current settings become the selected **User Set**.

### User Setting

The user setting is the saved set of camera configurations that you can customize, resave, and restore. By default the user settings are shipped with the same settings as the factory set.

The command **User Set Save** saves the current settings to non-volatile memory as a **User Set**. The camera automatically restores the last saved user settings when it powers up.

To restore the last saved user settings, select the **User Set** parameter you want to restore and then select the **User Set Load** parameter.

## Factory Settings

The factory setting is the camera settings that were shipped with the camera and which loaded during the camera's first power-up. To load or restore the original factory settings, at any time, select the **Factory Setting** parameter and then select the **User Set Load** parameter.

Note: By default, the user settings are set to the factory settings.

## Default Setting

Either the Factory or one of the User settings can be used as the Default Setting by selecting the set in the User Set Default Selector. The chosen set automatically becomes the default setting and is the set loaded when the camera is reset or powered up.

# Camera Link Configuration

Name	Taps	SPF*	Cables
Base	2	8, 10, 12	1
Medium	4	8, 10, 12	2
Full	8	8	2

\*Set Pixel Format (number of bits per pixel)

## TDI Stages

You have the option to set the TDI stages as either a single line (1) or as the sum of a pair of lines (2).

### TDI Stages and Direction Control

If the camera's direction is set to reverse, then the TDI stage is locked to TDI stage 2. While operating in TDI stage 1 the direction control is not available and will be greyed out, the camera must be operating with internal direction control.

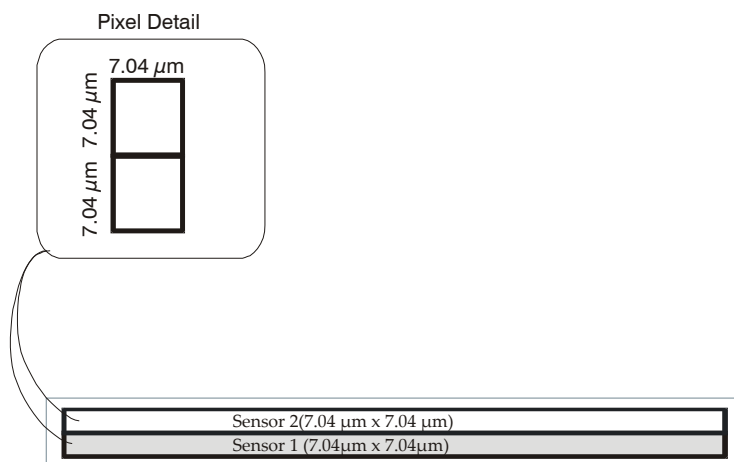
### TDI Stage 2 Vs. Vertical Binning 2

TDI mode delays one line before summing so that each row images the same area. In the case of vertical binning equal to 2, the rows image adjacent areas and are summed without separation delay. This action, combined with horizontal binning equal to 2, results in a big pixel that has half the resolution but four times the response compared to TDI stages = 1.

## Sensitivity Mode and Pixel Readout

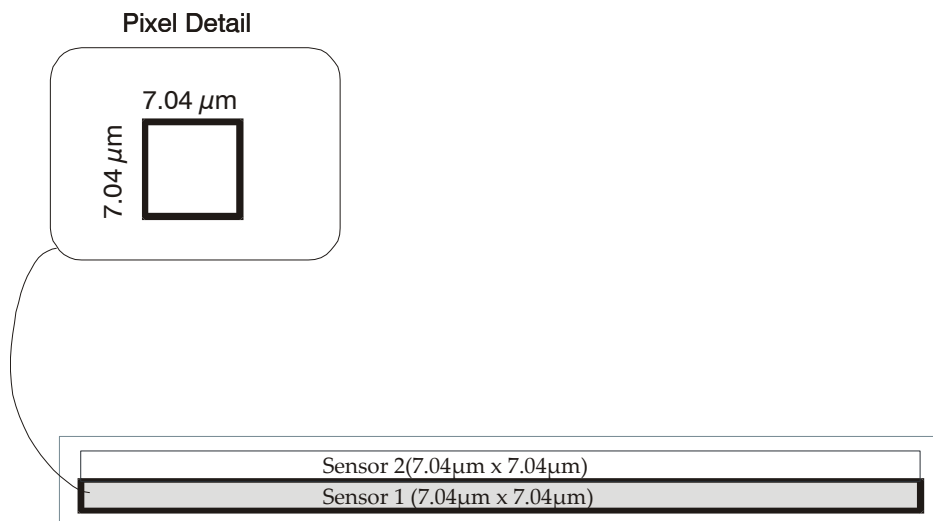
The camera has the option to operate in either high sensitivity (dual line) or low sensitivity (single line) modes.

When in high sensitivity mode, the camera uses both line scan sensors and as a result the responsivity increases (40%). When in TDI stages = 1, the camera uses the bottom sensor only. The internal gain is 1.4x greater for TDI stages = 1 vs. TDI stages = 2.



**Figure 15: High Sensitivity Mode**

In TDI stages = 2, the camera uses a 7.04  $\mu\text{m}$  x 7.04  $\mu\text{m}$  pixel and captures the same image twice, resulting in a brighter image.



**Figure 16: Low Sensitivity Mode**

In TDI stages = 1, the camera uses a 7.04  $\mu\text{m}$  x 7.04  $\mu\text{m}$  pixel and captures the image using one sensor (Sensor 1).



# Trigger Modes

The camera's image exposures are initiated by a trigger event. The trigger event is either a programmable internal signal used in free running mode, an external input used for synchronizing exposures to external triggers, or a programmed function call message by the controlling computer. These triggering modes are described below.

- **Internal trigger (trigger disabled):** The camera free-running mode has a programmable internal timer for line rate and a programmable exposure period.
- **External trigger (trigger enabled):** Exposures are controlled by an external trigger signal. The external trigger signal is the Camera Link control line CC1.

# Exposure Controls

The Exposure Control modes define how and when the camera will capture an image—the integration period. The integration period is the amount of time the camera's sensor is exposed to incoming light before the captured image is transmitted to the controlling computer.

- Exposure control is defined as the start of exposure and exposure duration.
- The start of exposure can be an internal timer signal (free-running mode) or an external trigger signal.
- The exposure duration can be programmable (such as the case of an internal timer) or controlled by the external trigger pulse width.

The camera can grab images in one of three ways. You determine the three imaging modes using a combination of the Exposure Mode parameters (including I/ O parameters), Exposure Time and Line Rate parameters.

Description	Line Rate	Exposure Time	Trigger Source (Sync)
Internal line rate and exposure time	Internal, programmable	Internal programmable	Internal
External line rate and exposure time	Controlled by EXSYNC pulse	External (EXSYNC)	External
EXSYNC pulse controlling the line rate. Programmed exposure time.	Controlled by EXSYNC pulse	Internal programmable	External

**Figure 17. Exposure controls**

The parameters used to select the imaging modes—trigger sources (sync), exposure time, and line rate—are grouped together as the Camera Controls.

Camera Controls	
Parameter	Description
Line Rate (in Hz)	Camera line rate in Hz. Only available when the start line trigger parameter is disabled (Trigger Mode off).
Exposure Mode	Set the operation mode for the camera's exposure. Trigger Width or Timed. Trigger Width is only available when Trigger Mode is enabled.
	<b>Trigger Width</b> Uses the width of the current line trigger signal pulse to control the exposure duration.

	<b>Timed</b> The exposure duration time is set using the Exposure Time feature and the exposure starts with the Line Start event.
Exposure Time	Sets the exposure time (in microseconds). Exposure Mode feature must be set to Timed

## Exposure Modes in Detail

### 1. Internally Programmable Line rate and Internally Programmable Exposure Time (Default)

Line rate is the dominant factor when adjusting the line rate or exposure time. When setting the line rate, exposure time will decrease, if necessary, to accommodate the new line rate. When adjusting the exposure time the range is limited by the line rate.

**Note:** The camera will not set line periods shorter than the readout period.

**GenICam parameters to set:**

**I / O Controls > Trigger Mode > Off**

### 2. External Line Rate and External Exposure Time (Trigger Width)

In this mode, EXSYNC sets both the line period and the exposure time. The rising edge of EXSYNC marks the beginning of the exposure and the falling edge initiates readout. Note:

$$\text{maximum line rate} = \frac{1}{(\text{exposure time} + \text{low time}^*)}$$

\*Exposure time must be greater than 6  $\mu$ s and low time greater than 1,500 ns

**GenICam parameters to set:**

- **I / O Controls > Trigger Mode > On**
- **Camera Control > Exposure Mode > Trigger Width**

**Warning!** When running external line rate and external exposure time, the line rate must not exceed 1 / (exposure time + 1,500 ns). Under these conditions the exposure time will become indeterminate and result in image artefacts. This is not the case when running internal exposure control.

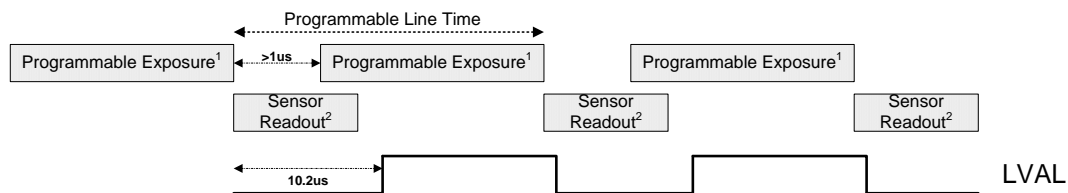
### 3. External Line Rate, Programmable Exposure Time

In this mode, the line rate is set externally with the falling edge of EXSYNC generating the rising edge of a programmable exposure time.

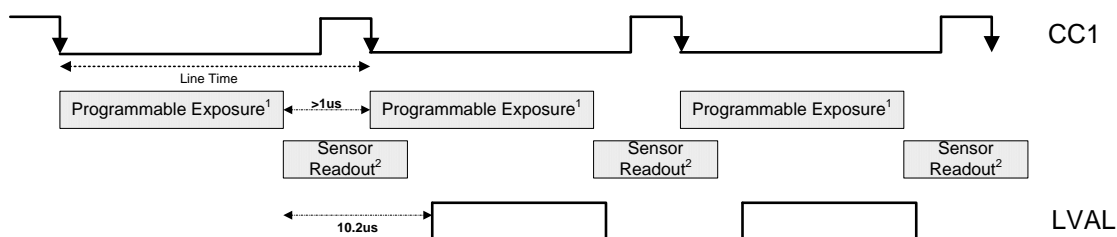
**GenICam parameters to set:**

- **I / O Controls > Trigger Mode > On**
- **Camera Control > Exposure Mode > Timed**

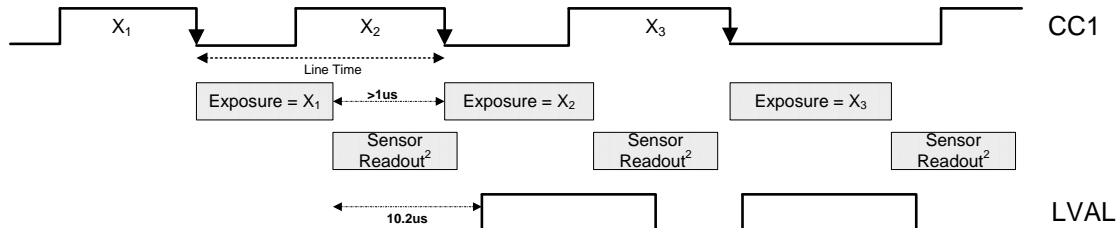
1. External Trigger Off, Internal Exposure Control  
Free running, not synchronized to an external signal



2. External Trigger On, Internal Exposure Control  
CC1 Falling edge triggers start of internal exposure³



3. External Trigger On, External Exposure Control  
CC1 Falling edge triggers start of exposure  
CC1 high duration sets the exposure time



Notes:

1. Exposure time > 4 micro-seconds
2. Sensor Readout time = 9.5 micro-seconds
3. One additional falling edge during exposure is latched

Figure 18. Exposure Modes

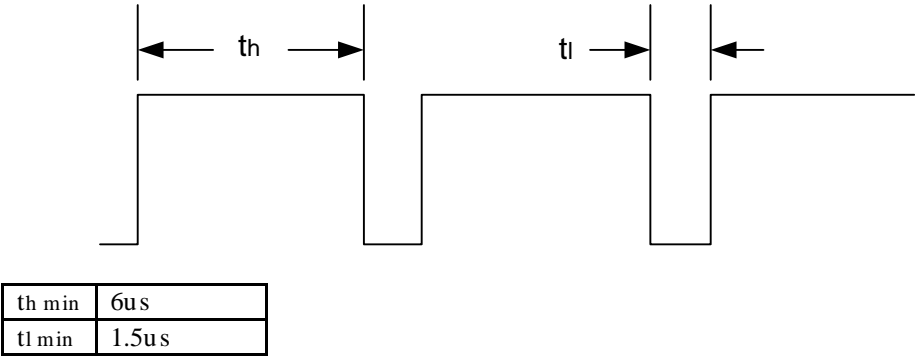


Figure 19. External Trigger Minimum High and Low Times

# Set Line Rate

To set the camera’s line rate use the line rate parameter, part of the Camera Controls set. This feature can only be used when the camera is in Internal mode—that is, when the start line trigger is disabled (Trigger Mode Off).

$$\text{maximum line rate} = \frac{1}{(\text{exposure time} + \text{low time}^*)}$$

\*Exposure time must be greater than  $6\mu\text{s}$  and low time greater than  $1,500\text{ ns}$

Note: A line rate  $< 1 / (\text{Exposure time} + 1,500\text{ ns})$  will return an error (“Invalid Parameter”) if this condition is not met. You must adjust these two parameters in the correct sequence to maintain this condition.

If the external line rate exceeds 70 kHz the camera will continue to output data at its maximum line rate of 70 kHz. Though no image artefacts associated with over-speed will occur, you may notice that under over-speed conditions the image will appear compressed and the apparent distance travelled will be reduced.

Camera Control	
Parameter	Description
Line Rate (in Hz)	Camera line rate in a range from 1 Hz to 70 KHz.  This feature is only available when the camera is in Internal Mode—line trigger is disabled (Trigger Mode off).

Line Rates	
Camera Link Configuration	Maximum Line Rate
Base	20 kHz (Up to 41 kHz with the use of horizontal binning at 2x)

Medium	41 kHz
Full	70 kHz

CL Clock Rate	Number of AOI	CL Configuration	Line Rate Formula (Hz)
85 MHz	1	Base	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1}{2}\right) + 15}$
		Medium	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1}{4}\right) + 15}$
		Full	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1}{8}\right) + 15}$
85 MHz	2	Base	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2}{2}\right) + 15}$
		Medium	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2}{4}\right) + 15}$
		Full	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2}{8}\right) + 15}$
85 MHz	3	Base	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3}{2}\right) + 15}$
		Medium	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3}{4}\right) + 15}$
		Full	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3}{8}\right) + 15}$

CL Clock Rate	Number of AOI	CL Configuration	Line Rate Formula (Hz)
85 MHz	4	Base	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3 + AOIwidth4}{2}\right) + 15}$
		Medium	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3 + AOIwidth4}{4}\right) + 15}$
		Full	Max: 70KHz $\frac{85000000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3 + AOIwidth4}{8}\right) + 15}$

CL Clock Rate	Number of AOI	CL Configuration	Line Rate Formula (Hz)
42.5 MHz	1	Base	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1}{2}\right) + 15}$
		Medium	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1}{4}\right) + 15}$
		Full	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1}{8}\right) + 15}$
42.5 MHz	2	Base	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2}{2}\right) + 15}$
		Medium	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2}{4}\right) + 15}$
		Full	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2}{8}\right) + 15}$

CL Clock Rate	Number of AOI	CL Configuration	Line Rate Formula (Hz)
42.5 MHz	3	Base	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3}{2}\right) + 15}$
		Medium	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3}{4}\right) + 15}$
		Full	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3}{8}\right) + 15}$
42.5 MHz	4	Base	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3 + AOIwidth4}{2}\right) + 15}$
		Medium	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3 + AOIwidth4}{4}\right) + 15}$
		Full	Max: 70KHz $Rate = \frac{42500000}{\left(\frac{AOIwidth1 + AOIwidth2 + AOIwidth3 + AOIwidth4}{8}\right) + 15}$

## Set Exposure Time

To set the camera's exposure time, use the **Exposure Time** parameter—a member of the Camera Controls set. This feature is only available when the **Exposure Mode** parameter is set to **Timed**. The allowable exposure range is from 7 µs to 3,000 µs, dependent on the value of the internal line rate.

### GenICam parameters:

Camera Controls > Exposure Time (Timed Exposure Mode) > 7 µs to 3,000 µs.

## Control Gain and Black Level

The cameras provide gain and black level adjustments in the digital domain for the CMOS sensor. The gain and black level controls can make small compensations to the acquisition in situations where lighting varies and the lens iris cannot be easily adjusted. The user can evaluate gain and black level by using CamExpert.

The parameters that control gain and black level are grouped together in the Camera Controls set.

Camera Controls	
Black Level	Apply a digital addition after an FPN correction: $\pm 1/8$ of available range. For example in 12-bit mode the available range is -512 to +511.
Gain	Set the gain as an amplification factor applied to the video signal across all pixels: 1x to 10x.

## Set Image Size

To set the height of the image, and therefore the number of lines to scan, use the parameters grouped under the Image Format Control set.

Image Format Control	
Control the size of the transmitted image	
Width	Width of the image. Read only.
Height	Height of the image in lines. Read only.
Pixel Format	Mono 8, Mono 10, or Mono 12 bit depth to Camera Link.
Test Image Selector	Select an internal test image: Off Ramp A5 Each Tap Fixed All 1365 All 1

## Set Baud Rate

The baud rate sets the speed (in bits per second—bps) of the serial communication port and is available as part of the Serial Port Control parameters.

Serial Port Control		
Action	Parameter	Options
Control the baud rate used by the camera's serial port	Baud Rate	9600 (factory default) 19200 57600 115200 230400* 460800* 921600*  Note: During connection CamExpert automatically sets the camera to maximum allowable baud.  *Your system requires a Px8 frame grabber to achieve these baud rates.



Number of bits per character used in the serial port	Data Size	8
Parity of the serial port	Parity	None
Number of stop bits per character used in the serial port	Number of Stop Bits	1

## Pixel Format

Use the Pixel Format feature, found in the **Image Format Control** set, to select the format of the pixel to use during image acquisition, as Mono 8, Mono 10, or Mono 12 bit depth.

Image Format Control	
Parameter	Description
Pixel Format	Mono 8* Mono 10 Mono 12  *Only available format for Full CameraLink configuration.

## Camera Direction Control

Found in the **Camera Control > Direction Control** set of features. Note: This feature is only available when in high sensitivity mode only (TDI stage 2).

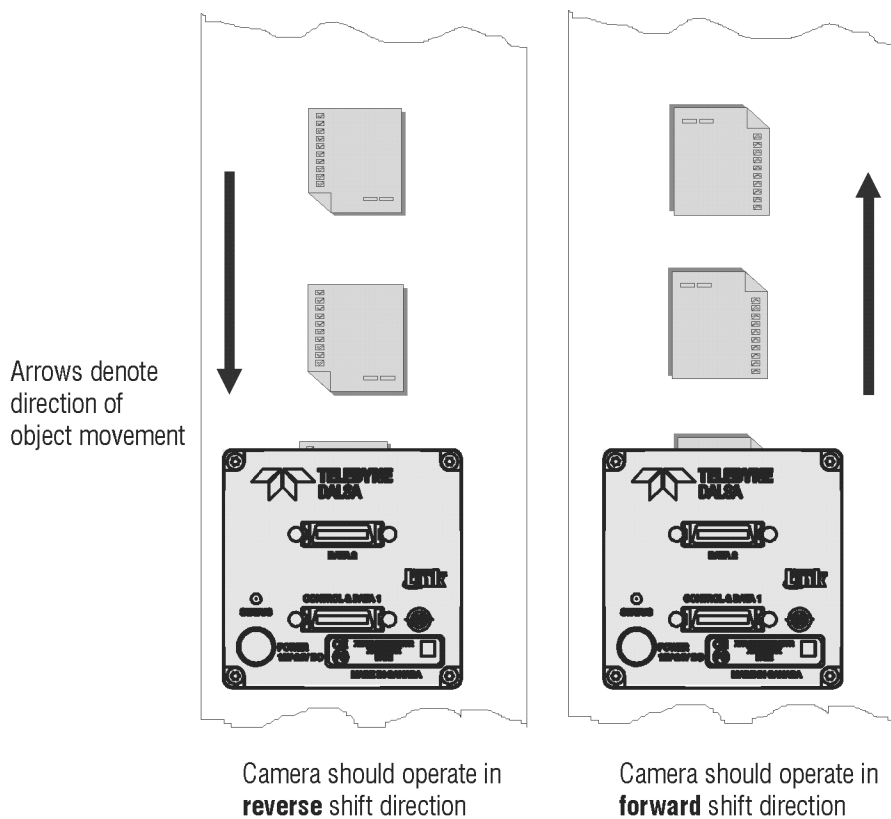
Note: the **Sensor Shift** features are not available when the camera is in low or tall pixel sensitivity modes.

Camera Control > Direction Control	
Parameter	Description
Scan Direction Source	When in TDI stages 2, this command lets you select the <b>Internal</b> or <b>external direction control</b> . Use this feature to accommodate object direction change on a web and to mount the camera "upside down."
Scan Direction	Read the current direction.

## Sensor Shift Direction Example

When in high sensitivity mode, you can select either forward or reverse sensor shift direction. Selectable direction accommodates object direction change on a web and allows you to mount the camera “upside down”.

Note that the example here assumes the use of a lens (which inverts the image).



**Figure 20: Object Movement and Camera Direction Example Using a Lens**

# Pixel Readout Direction (Mirroring Mode)

Set the tap readout from left to right or from right to left. This feature is especially useful if you want to mount the camera “upside down.”

Image Format Control	
Parameter	Description
ReverseX	Off: All pixels are read out from left to right. On: All pixels are read out from right to left.

## Binning

Binning is the combining of two or more image sensor pixels to form a new combined pixel. A binned image using the same exposure settings as a non-binned image will show an improved signal-to-noise ratio, reduced scanning times (due to lower spatial resolution) and save as a smaller image file size compared with a non-binned image, at the expense of lower image resolution.

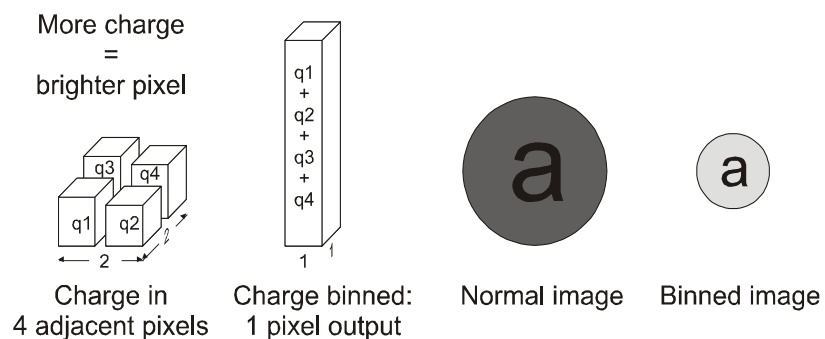
In 2 x 2 binning, 4 physical pixels on the sensor are combined into one image pixel. This operating mode is ideal for applications that require faster acquisition and processing times and require greater signal collection.

For this camera, the default binning value is 1 x 1,

The **Binning Vertical** and **Binning Horizontal** features in the **Image Format Control** set represents the number of horizontal pixels that will be combined (added) together.

Note: Compared to running the camera in TDI stages = 2, running the camera in 2 x 2 binning mode will result in 4x responsivity, not 2x. All increases in output due to binning is relative to a single sensor line (TDI stage = 1).

Image Format Control	
Parameter	Description
Binning Vertical	This feature represents the number of vertical photo-sensitive cells that must be combined (added) together: 2.  Note: TDI stages must be set to 1 before vertical binning can be changed to 2x.
Binning Horizontal	This feature represents the number of horizontal photo-sensitive cells that must be combined (added) together.



**Figure 21: 2x2 Binning in Area Mode**

## Resetting the Camera

The feature **Camera Reset**, part of the **Transport Layer** set, resets the camera. The camera resets with the default settings, including a baud rate of 9600.

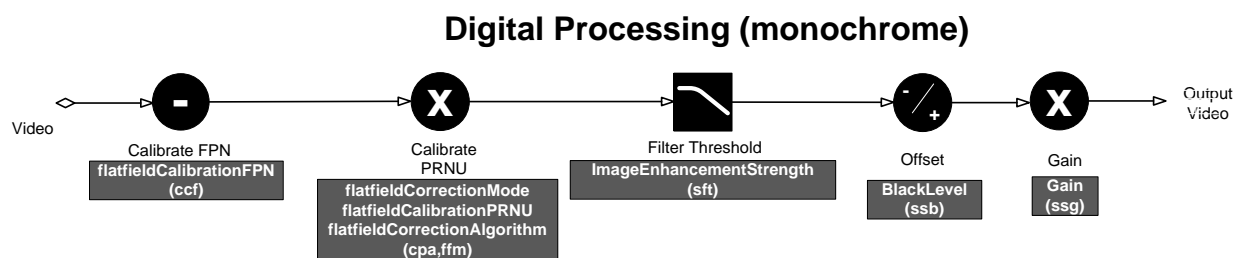
Transport Layer	
Parameter	Description
Camera Reset	Resets the camera and puts in the default settings, including a 9600 baud rate.

## Calibrating the Camera

**Important Note:** to ensure best results, the conditions under which you calibrate the camera (e.g. temperature and illumination) should be as close to the actual operating conditions as possible. .

Category	Parameter	Value
Camera Information	Mode	On
Camera Control	Calibration Algorithm	Basic
Flat Field	Calibration Target	200
Image Format	Calibration Sample Size	Lines_1
Transport Layer	Calibrate	Press...

**Figure 22: Flat Field Calibration in CamExpert**



**Figure 23: Camera Calibration Process.**

## 1. Flat Field

This Flat Field set contains a number of features that are used to correct image distortion due to lens vignetting and uneven illumination. .

Note:

1. Flat field coefficients consist of an offset and gain for each pixel.
2. These are the first user corrections applied to the image.
3. The flat field coefficients are saved and loaded with the user set.

Parameter	Description
flatfieldCorrectionMode	<ol style="list-style-type: none"> <li>1. Off – Flat field correction coefficients are not applied.</li> <li>2. On – Flat field correction coefficients are applied.</li> <li>3. Initialize – Sending this value will reset all current coefficients (offsets to 0 and gains to 1x).</li> </ol>
flatfieldCorrectionAlgorithm	<ol style="list-style-type: none"> <li>1. Basic – Direct calculation of coefficients based on current average line values and target.</li> <li>2. LowPass – A low pass filter is first applied to the current average line values before calculating the coefficients. Use this algorithm if the calibration target is not uniform white or it is not possible to defocus the image. Because of the low pass filter this algorithm is not able to correct pixel-to-pixel variations and so it is preferable to use the “Basic” algorithm if possible.</li> </ol>
flatfieldCalibrationTarget	<ol style="list-style-type: none"> <li>1. After calibration all pixels will be scaled to output this level</li> <li>2. Range depends on pixel format: <ul style="list-style-type: none"> <li>• 8 bit: 0 to 255 DN</li> <li>• 10 bit: 0 to 1023 DN</li> <li>• 12 bit: 0 to 4095 DN</li> </ul> </li> </ol>
flatfieldCalibrationSampleSize	<ol style="list-style-type: none"> <li>1. Number of lines to average when calibrating</li> <li>2. 2048 or 4096</li> </ol>
flatfieldCalibrationROIOffsetX	<ol style="list-style-type: none"> <li>1. Together with “flatfieldCalibrationROIWidth” specifies the range of pixels to be calibrated. Pixel coefficients outside this range are not changed. It is possible to calibrate different regions sequentially.</li> </ol>
flatfieldCalibrationROIWidth	
flatfieldCalibrationFPN	<ol style="list-style-type: none"> <li>1. Save average line (of “flatfieldCalibrationSampleSize” rows). This is the first user correction applied – it is subtracted from each line.</li> </ol>

	<ol style="list-style-type: none"> <li>2. This feature may not be of use to many users as the camera already subtracts true “dark current”, but it may be useful for some to provide a per pixel offset correction.</li> <li>3. Range 0 to 511 DN, 12 bit</li> <li>4. Default value is 0 DN for each pixel</li> </ol>
flatfieldCalibrationPRNU	<ol style="list-style-type: none"> <li>1. Use “flatfieldCorrectionAlgorithm” to calculate the per pixel gain to achieve the specified target output.</li> <li>2. Range 0 to 15.9998x</li> <li>3. Default 1x</li> </ol>

## 2. Contrast Enhancement

Two features to maximize the use of the output dynamic range (especially when pixel format is less than 12 bits). Typical use is to subtract minimum pixel value expected and then gain up maximum pixel value to approach full scale.

### Offset

1. Single value added to each pixel
2. Range -512 to 511 DN, scaled down according to pixel format
3. Positive values may be used to measure dark noise

### Gain

1. Floating point digital multiplier applied to each pixel
2. Range 1x to 10x

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# Appendix A: GenICam Commands

This appendix lists the available GenICam camera features. Access these features using the CamExpert interface.

Features listed in the description table but tagged as *Invisible* are typically reserved for Teledyne DALSA Support or third party software usage, and not typically required by end user applications.

**A note on the CamExpert examples shown here: The examples shown for illustrative purposes and may not entirely reflect the features and parameters available from the camera model used in your application.**

## Camera Information Category

Camera information can be retrieved via a controlling application. Parameters such as camera model, firmware version, etc. are read to uniquely identify the connected P4 device. These features are typically read-only.

The Camera Information Category groups information specific to the individual camera. In this category the number of features shown is identical whether the view is Beginner, Expert, or Guru.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.

Category	Parameter	Value
Camera Information	Model	P4_CM_08K070_00_R
Camera Control	Vendor	Teledyne_DALSA
I/O Controls	Serial Number	14013771
Flat Field	Device User ID	6565657
Image Format	Microcode Version	03-081-20235-03
Transport Layer	CCI Version	03-110-20242-04
Serial Port	FPGA Version	03-056-20378-07
File Access Control	Power-on Status	Good
	LED Colour	Green
	Temperature	29
	Refresh Temperature	Press...
	Input Voltage	10.200
	Refresh Voltage	Press...
	Power-up Configuration	Setting...
<< Less		More >>

## Camera Information Feature Descriptions

The following table describes these parameters along with their view attributes and in which version of the device the feature was introduced. Additionally the Device Version column will indicate which parameter is a member of the DALSA Features Naming Convention (using the tag **DFNC**), versus the GenICam Standard Features Naming Convention (SFNC not shown).

The Device Version number represents the camera software functional group, not a firm ware revision number.

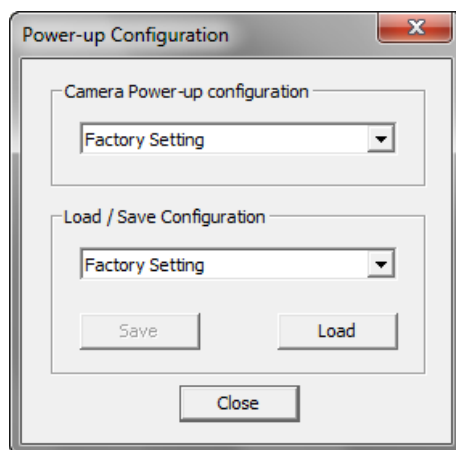
Display Name	Feature	Description	Device Version & View
Model Name	DeviceModelName	Displays the device model name. (RO)	1.00 Beginner
Vendor Name	DeviceVendorName	Displays the device vendor name. (RO)	1.00 Beginner
Device Version	DeviceVersion	Displays the device version. This tag will also highlight if the firmware is a beta or custom design. (RO)	1.00 Beginner
Manufacturer Info	DeviceManufacturerInfo	This feature provides extended manufacturer information about the device. (RO)	1.00 Beginner
Firmware Version	DeviceFirmwareVersion	Displays the currently loaded firmware version number. Firmware files have a unique number and have the .cbf file extension. (RO)	1.00 Beginner
Serial Number	DeviceID	Displays the device's factory set camera serial number. (RO)	1.00 Beginner



Display Name	Feature	Description	Device Version & View
Device User ID	DeviceUserID	Feature to store user-programmable identifier of up to 15 characters. The default factory setting is the camera serial number. (RW)	1.00 Beginner
Power-up Configuration Selector	UserSetDefaultSelector	Selects the camera configuration set to load and make active on camera power-up or reset. The camera configuration sets are stored in camera non-volatile memory. (RW)	1.00 Beginner
<b>Factory Setting</b>	<b>Default</b>	<b>Load factory default feature settings</b>	
UserSet1	UserSet1	Select the user defined configuration UserSet 1 as the Power-up Configuration.	
UserSet2	UserSet2	Select the user defined configuration UserSet 2 as the Power-up Configuration	
UserSet3	UserSet3	Select the user defined configuration UserSet 3 as the Power-up Configuration	
UserSet4	UserSet4	Select the user defined configuration UserSet 4 as the Power-up Configuration.	
UserSet5	UserSet5	Select the user defined configuration UserSet 5 as the Power-up Configuration.	
UserSet6	UserSet6	Select the user defined configuration UserSet 6 as the Power-up Configuration.	
UserSet7	UserSet7	Select the user defined configuration UserSet 7 as the Power-up Configuration.	
UserSet8	UserSet8	Select the user defined configuration UserSet 8 as the Power-up Configuration.	
User Set Selector	UserSetSelector	Selects the camera configuration set to load feature settings from or save current feature settings to. The Factory set contains default camera feature settings. (RW)	1.00 Beginner
<b>Factory Setting</b>	<b>Default</b>	<b>Select the default camera feature settings saved by the factory</b>	
UserSet 1	UserSet1	Select the User-defined Configuration space UserSet1 to save to or load from features settings previously saved by the user.	
UserSet 2	UserSet2	Select the User-defined Configuration space UserSet2 to save to or load from features settings previously saved by the user.	
UserSet3	UserSet3	Select the User-defined Configuration space UserSet3 to save to or load from features settings previously saved by the user.	
UserSet4	UserSet4	Select the User-defined Configuration space UserSet4 to save to or load from features settings previously saved by the user.	
UserSet5	UserSet5	Select the User-defined Configuration space UserSet5 to save to or load from features settings previously saved by the user.	

Display Name	Feature	Description	Device Version & View
UserSet6	UserSet6	Select the User-defined Configuration space UserSet6 to save to or load from features settings previously saved by the user. Select the User-defined Configuration space UserSet7 to save to or load from features settings previously saved by the user. Select the User-defined Configuration space UserSet8 to save to or load from features settings previously saved by the user.	
UserSet7	UserSet7		
UserSet8	UserSet8		
Power-on User Set	UserSetDefaultSelector	Allows the user to select between the factory set and 1 to 8 user sets to be loaded at power up	1.00 Beginner
Current User Set	UserSetSelector	Points to which user set (1-8) or factory set that is loaded or saved when the UserSetLoad or UserSetSave command is used	1.00 Beginner
Load Configuration	UserSetLoad	Loads the camera configuration set specified by the User Set Selector feature, to the camera and makes it active. (W)	1.00 Beginner
Save Configuration	UserSetSave	Saves the current camera configuration to the user set specified by the User Set Selector feature. The user sets are located on the camera in non-volatile memory. (W)	1.00 Beginner
Device Built-In Self Test Status	deviceBISTStatus	Determine the status of the device using the 'Built-In Self Test'. Possible return values are device-specific. (RO)	1.00 DFNC Beginner
LED Color	deviceLEDColorControl	Displays the status of the LED on the back of the camera. (RO)	1.00 DFNC Beginner
Temperature	DeviceTemperature	Displays the internal operating temperature of the camera. (RO)	1.00 DFNC Beginner
Refresh Temperature	refreshTemperature	Press to display the current internal operating temperature of the camera.	1.00 DFNC Beginner
Input Voltage	deviceInputVoltage	Displays the input voltage to the camera at the power connector (RO)	1.00 DFNC Beginner
Refresh Voltage	refreshVoltage	Press to display the current input voltage of the camera at the power connector	1.00 DFNC Beginner
License Key	securityUpgrade		1.00 DFNC Guru

## Camera Configuration Selection Dialog



CamExpert provides a dialog box which combines the features to select the camera power up state and for the user to save or load a camera state from Genie memory.

### Camera Power-up Configuration

The first drop list selects the camera configuration state to load on power-up (see feature *UserSetDefaultSelector*). The user chooses from one factory data set or one of two possible user saved states.

### User Set Configuration Management

The second drop list allows the user to change the camera configuration anytime after a power-up (see feature *UserSetSelector*). To reset the camera to the factory configuration, select *Factory Setting* and click Load. To save a current camera configuration, select User Set 1 to 8 and click Save. Select a saved user set and click Load to restore a saved configuration.

# Camera Control Category

The P4 camera controls, as shown by CamExpert, groups sensor specific parameters. This group includes controls for line rate, exposure time, scan direction, and gain. Parameters in gray are read only, either always or due to another parameter being disabled. Parameters in black are user set in CamExpert or programmable via an imaging application.

Category	Parameter	Value
Camera Information	Sensor ColorType	Monochrome
Camera Control	Internal Line Rate	10000
I/O Controls	Measured Line Rate	10003
Flat Field	Refresh Measured Line Rate	Press...
Image Format	Exposure Time Source	Timed
Transport Layer	Exposure Time	50
Serial Port	Measured Exposure Time	49993
File Access Control	Refresh Measured Exposure Time	Press...
	TDI Stages	2
	Direction Source	Internal
	Internal Direction	Forward
	Offset	0
	Gain	1
	<< Less	

## Camera Control Feature Descriptions

The following table describes these parameters along with their view attribute and minimum camera firmware version required. Additionally the firmware column will indicate which parameter is a member of the DALSA Features Naming Convention (DFNC), versus the GenICam Standard Features Naming Convention (SFNC not shown).

The Device Version number represents the camera software functional group, not a firmware revision number.

Display Name	Feature	Description	Device Version & View
Internal Line Rate	AcquisitionLineRate	Specifies the camera internal line rate, in Hz when Trigger mode set to internal. Note that any user entered value is automatically adjusted to a valid camera value.	1.00 Beginner
Measured Line Rate	measureLineRate	Specifies the line rate provided to the camera by either internal or external source (RO)	1.00 Beginner
Refresh measured line rate	refreshMeasureLineRate	Press to show the current line rate provided to the camera by either internal or external sources	1.00 Beginner
Exposure Time Source Timed	ExposureMode Timed	Sets the operation mode for the camera's exposure (or shutter). (RO) The exposure duration time is set using the Exposure Time feature and the exposure starts with a LineStart event.	1.00 Beginner
Trigger Width	TriggerWidth	Uses the width of the trigger signal pulse to control the exposure duration.	
Exposure Time	ExposureTime	Sets the exposure time (in microseconds) when the Exposure Mode feature is set to Timed.	1.00 Beginner
Measured Exposure Time	measureExposureTime	Specifies the exposure time provided to the camera by either internal or external source (RO)	1.00 Beginner
Refreshed measured exposure time	refreshMeasureExposureTime	Press to display the current exposure time provided to the camera.	1.00 Beginner
TDI Stages 1 2	sensorTDIStageSelection 1 2	Selects the number of lines to be imaged Single Line Dual Line	1.00 Beginner DFNC
Direction Source	sensorScanDirectionSource Internal External	Direction determined by value of SensorScanDirection  Direction control determined by value on CC3	1.00 Beginner
Internal Direction	sensorScanDirection Forward Reverse	When ScanDirectionSource set to Internal, determines the direction of the scan	1.00 Beginner
Gain	Gain	Sets the selected gain as an amplification factor applied to the image.	1.00 Beginner

Display Name	Feature	Description	Device Version & View
Offset	BlackLevel	Controls the black level as an absolute physical value. This represents a DC offset applied to the video signal, in DN (digital number) units.	1.00 Beginner

## Digital I/O Control Feature Descriptions

The P4 Digital I/ O controls, as shown by CamExpert, groups sensor specific parameters. This group includes controls for line rate, exposure time, scan direction, and gain. Parameters in gray are read only, either always or due to another parameter being disabled. Parameters in black are user set in CamExpert or programmable via an imaging application.

Category	Parameter	Value
Camera Information	Trigger Source	CC1
Camera Control	Trigger Selector	LineStart
I/O Controls	Trigger Mode	Off
Flat Field	<< Less	
Image Format		
Transport Layer		
Serial Port		
File Access Control		

## Digital I/O Feature Descriptions

The following table describes these parameters along with their view attribute and minimum camera firmware version required. Additionally the firmware column will indicate which parameter is a member of the DALSA Features Naming Convention (DFNC), versus the GenICam Standard Features Naming Convention (SFNC not shown).

The Device Version number represents the camera software functional group, not a firmware revision number.

Display Name	Feature	Description	Device Version & View
Trigger Source	Trigger Source	Defines the source of external trigger (RO)	1.00 DFNC Beginner
Trigger Selector	Trigger Selector	Defines what the trigger initiates (RO)	1.00 DFNC Beginner
Trigger Mode	Trigger Mode	Determines the source of trigger to the camera, internal or external (CC1)	1.00 DFNC Beginner

## Flat Field Category

The P4 Flat Field controls, as shown by CamExpert, group parameters used to configure camera pixel format, and image cropping. Additionally a feature control to select and output an internal test image simplifies the process of setting up a camera without a lens.

Parameters in gray are read only, either always or due to another parameter being disabled. Parameters in black are user set in CamExpert or programmable via an imaging application.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.

Category	Parameter	Value
Camera Information	Mode	On
<a href="#">Camera Control</a>	Scan Direction Reverse Set	Not Enabled
I/O Controls	Calibration Algorithm	Basic
Flat Field	Calibration Target	150
	Calibration Sample Size	4096
Image Format	ROI Offset X	1
Transport Layer	ROI Width	8192
Serial Port	Calibrate FPN	Press...
File Access Control	Calibrate PRNU	Press...
	Filter Threshold	0
	<< Less	

## Flat Field Control Feature Description

The following table describes these parameters along with their view attribute and minimum camera firmware version required. Additionally the firmware column will indicate which parameter is a member of the DALSA Features Naming Convention (DFNC), verses the GenICam Standard Features Naming Convention (SFNC not shown).

The Device Version number represents the camera software functional group, not a firmware revision number.

Display Name	Feature	Description	Device Version & View
Mode	flatfieldCorrectionMode		1.00
Off	Off	FPN and flat field coefficients disabled.	Beginner
On	On	FPN and flat field coefficients enabled.	DFNC



Display Name	Feature	Description	Device Version & View
Initialize	Initialize	Reset all FPN to 0 and all flat field coefficients to 1.	
ScanDirectionControlled	ScanDirectionControlled	Different user set loaded depending on direction.	
Select flatfield Correction Scan Direction Reverse Set	flatfieldScanDirectionReverseSet	When flatfieldCorrectionMode is set to ScanDirectionControlled this feature selects the UserSet (1 to 8) which will be used for the reverse scan direction.	1.00 Beginner DFNC
Calibration Algorithm	flatfieldCorrectionAlgorithm	Selection between two different flat field algorithms.	1.00 Beginner DFNC
Basic	Basic	Direct calculation of coefficients based on average line values and target. First each color is flat fielded to its peak value and then the color gains are used to achieve the target.	
LowPass	LowPass	A low pass filter is first applied to the average line values before calculating the coefficients. Use this algorithm if the calibration target is not uniformly white or it is not possible to defocus the image. Because of the low pass filter this algorithm is not able to correct pixel-to-pixel variations and so it is preferable to use the "Basic" algorithm.	
Calibration Target	flatfieldCalibrationTarget	Set a value between 0 and 255 to which the flat field algorithm will target the image to.	1.00 Beginner DFNC
Calibration Sample Size	flatfieldCalibrationSampleSize	Sets the number of lines to be averaged during a flat field calibration	1.00 Beginner DFNC
Lines_2048 Lines_4096	Lines_2048 Lines_4096		
ROI Offset X	flatfieldCalibrationROIOffsetX	Set the starting point of a region of interest where a flat field calibration will be performed	1.00 Beginner DFNC
ROI Width	flatfieldCalibrationROIWidth	Sets the width of the region of interest where a flat field calibration will be performed	1.00 Beginner DFNC
Calibrate FPN	flatfieldCalibrationFPN	Initiates the FPN calibration process	1.00 Beginner DFNC

Display Name	Feature	Description	Device Version & View
Calibrate PRNU	flatfieldCalibrationPRNU	Initiates the PRNU or Flatfield process	1.00 Beginner DFNC
Filter Threshold 0 -16	ImageEnhancementStrength 0-16	Set the threshold at which the filter will be enabled. Contrast between pixels greater than this threshold will not be filtered	1.00 Beginner DFNC

## Region of Interest (ROI)

The ROI feature is related to flat field calibration. It is important to specify an ROI when the object being imaged has areas that have black, non illuminated areas such as beyond the edge of a film that is front illuminated, or is saturated, again beyond the edge of a film but in this case bright field back illuminated. The ROI feature allows from one to four specific regions of the pixel line to be specified where flat field calibration will take place. Pixel data outside the ROI will not be used when performing flat field calibration.

## Image Format Control Category

The P4 Image Format controls, as shown by CamExpert, groups parameters used to configure camera pixel format, image cropping, and the test pattern.

Parameters in gray are read only, either always or due to another parameter being disabled. Parameters in black are user set in CamExpert or programmable via an imaging application.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.

Category	Parameter	Value
Camera Information	Pixel Color Filter	None
Camera Control	Pixel Coding	Mono
I/O Controls	Test Pattern	Off
Flat Field	Vertical Binning	1
	Horizontal Binning	1
Image Format	Line Mirroring	Off
Transport Layer	Pixel Format	Mono8
Serial Port	Width	8192
File Access Control	MaxWidth	8192
	Height	1
	Multiple AOI Mode	Off
	AOI Count	0
	AOI Selector	1
	AOI Offset X	0
	AOI Width	0
	<< Less	

## Image Format Control Feature Description

The following table describes these parameters along with their view attribute and minimum camera firmware version required. Additionally the firmware column will indicate which parameter is a member of the DALSA Features Naming Convention (DFNC), versus the GenICam Standard Features Naming Convention (SFNC not shown).

The Device Version number represents the camera software functional group, not a firmware revision number.

Display Name	Feature	Description	Device Version & View
Test Pattern	TestImageSelector	Selects the type of test image that is sent by the camera. Choices are either as defined by SNFC and/ or as provided by the device manufacturer.	1.00 Beginner DFNC
Off	Off	Selects sensor video to be output from sensor	
Ramp	Ramp	Selects a grey scale	
Vertical Binning	BinningVertical	Selects between a single line or 2x vertically binned image	1.00 Beginner DFNC
1	1		
2	2		
Horizontal Binning	BinningHorizontal	Selects between 1x or 2x horizontally binned image	1.00 Beginner DFNC
1	1		
2	2		
Line Mirroring	ReverseX		1.00 Beginner DFNC
Off	Off	Video output in normal order	
On	On	Video output in a reverse order	
Pixel Format	Pixel Format	Output image pixel coding format of the sensor. Mono8, Mono10, or Mono12	1.00 Beginner DFNC
Width	Width	Width of the Image provided by the device (in pixels).(RO)	1.00 Beginner
Max Width	WidthMax	The maximum image horizontal dimension of the image. (RO)	1.00 Beginner
Height	Height	Height of the Image provided by the device (in lines). (RO)	1.00 Beginner
Multiple AOI Mode	multipleAOIMode	Turns on an output Area of Interest	1.00 Beginner DFNC
Off	Off	Area of interest is off	
Active	Active	Area of interest is on	
Multiple AOI Count	multipleAOICount	Set the number of output area of interest 1-4	1.00 Beginner DFNC
Multiple AOI Selector	multipleAOISelector	Selects the area of interest to be setup	1.00 Beginner DFNC

AOI Offset X	multipleAOIOffsetX	Set the start of area of interest (pixels)	1.00 Beginner
AOI Width	multipleAOIWidth	Set the width of area of interest (pixels)	1.00 Beginner DFNC

# Binning

Binning is the combining of two or more image sensor pixels to form a new combined pixel. A binned image using the same exposure settings as a non-binned image will show an improved signal-to-noise ratio, reduced scanning times (due to lower spatial resolution) and save as a smaller image file size compared with a non-binned image, at the expense of lower image resolution.

In 2 x 2 binning, 4 physical pixels on the sensor are combined into one image pixel. This operating mode is ideal for applications that require faster acquisition and processing times and require greater signal collection. For this camera, the default binning value is 1 x 1,

The **Binning Vertical** and **Binning Horizontal** features in the **Image Format Control** set represents the number of horizontal pixels that will be combined (added) together.

Note: Compared to running the camera in high-sensitivity mode, running the camera in 2 x 2 binning mode will result in 4x responsivity, not 2x.

Image Format Control	
Parameter	Description
Binning Vertical	This feature represents the number of vertical photo-sensitive cells that must be combined (added) together: 2.  Note: TDI stages must be set to 1 before vertical binning can be changed to 2x.
Binning Horizontal	This feature represents the number of horizontal photo-sensitive cells that must be combined (added) together.

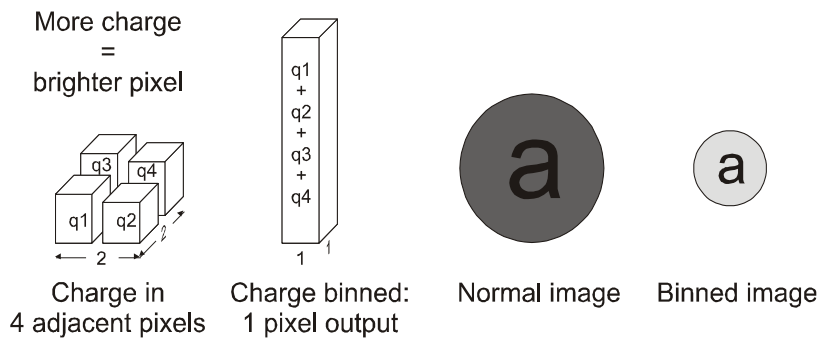


Figure 24: 2x2 Binning in Area Mode

# Area of Interest (AOI) Setup

The Area of Interest (AOI) feature can be used to reduce the amount of image-data output from the camera. Use this feature when there are areas in the image that contain unneeded information.

An example where you would use this feature is in an application that is inspecting several separated lanes of objects with one camera and the image between the lanes can be ignored.

The AOI feature allows from one to four specific areas of the pixel line to be specified where image data will be output. Since the AOI feature reduces the amount of data output, this has the additional benefit of allowing the cameras to operate at higher EXSYNC rates when using base or medium camera link modes.

For example, if the total number of pixels for the specified AOI's is less than 1 K when using base Camera Link mode at 85 MHz, the maximum EXSYNC rate can be 100 KHz; versus 20 KHz if all 8K pixels were output.

**Note:** The setup of AOI is always with respect to the sensor. Therefore, if you are using the mirroring mode with AOI, be aware that pixel one will be on the right side of the displayed image.

## In order to set up an AOI for the camera:

1. The AOI mode must first be in the off position.
2. Use the AOI Count to select the total number of AOIs desired to a max of 4.
3. To set up each AOI individually use the AOI Selector to point to the AOI to be set up.
4. AOI Offset X is used indicate the starting pixel of the AOI.
5. AOI Width is used to indicate the width of the AOI.

Category	Parameter	Value
Camera Information	Pixel Color Filter	None
Camera Control	Pixel Coding	Mono
I/O Controls	Test Pattern	Off
Flat Field	Vertical Binning	1
Image Format	Horizontal Binning	1
Transport Layer	Line Mirroring	Off
Serial Port	Pixel Format	Mono8
File Access Control	Height	8192
	Multiple AOI Mode	Off
	AOI Count	1
	AOI Selector	1
	AOI Offset X	0
	AOI Width	8191
	Less	

1. Must be off to set up the AOI.

2. Set up the number of AOI desired to max of 4.

3. Select area to set up.

4. Select beginning of selected area

5. Set up width of selected area

### In order to initiate operation of the AOI once setup:

1. The AOI mode must be changed to Active.
2. Be sure to set the frame grabber image width to the sum of all AOI widths set up in the camera.

Category	Parameter	Value
Camera Information	Pixel Color Filter	None
Camera Control	Pixel Coding	Mono
I/O Controls	Test Pattern	Off
Flat Field	Vertical Binning	1
	Horizontal Binning	1
Image Format	Line Mirroring	Off
Transport Layer	Pixel Format	Mono8
Serial Port	Width	8192
File Access Control	MaxWidth	8192
	Height	1
	Multiple AOI Mode	Active
	AOI Count	1
	AOI Selector	1
	AOI Offset X	0
	AOI Width	8184
	<< Less	

Once all AOI are set up change to active.

## Custom AOI Rules

1. The sensor has pixels 0 to 8191.
2. Whether mirroring is on or off, 0 is the leftmost pixel.
3. Whether mirroring is on or off, AOI 1 is readout first.
4. In normal mode, AOI 1 is closest to the sensor's left edge.
5. In mirror mode, AOI 1 is closest to the sensor's right edge.

## Base, Medium and Full Modes

1. The total number of pixels within each AOI must be a multiple of 8 and must be greater than or equal to 40.
2. In normal mode, the first pixel of each AOI (AOI left edge) must have the location  $8i$ , where  $i = 0, 1, 2 \dots, 1023$  (i.e. 8, 960, 7680 are allowed, 12 is not allowed).
3. In mirror mode, the first pixel of each AOI (AOI right edge) must have the location  $8i + 7$ , where  $i = 0, 1, 2 \dots, 1023$  (i.e. 7, 15, 4095 are allowed, 8 is not allowed).

# Instructions on using the camera scan direction to control camera parameters

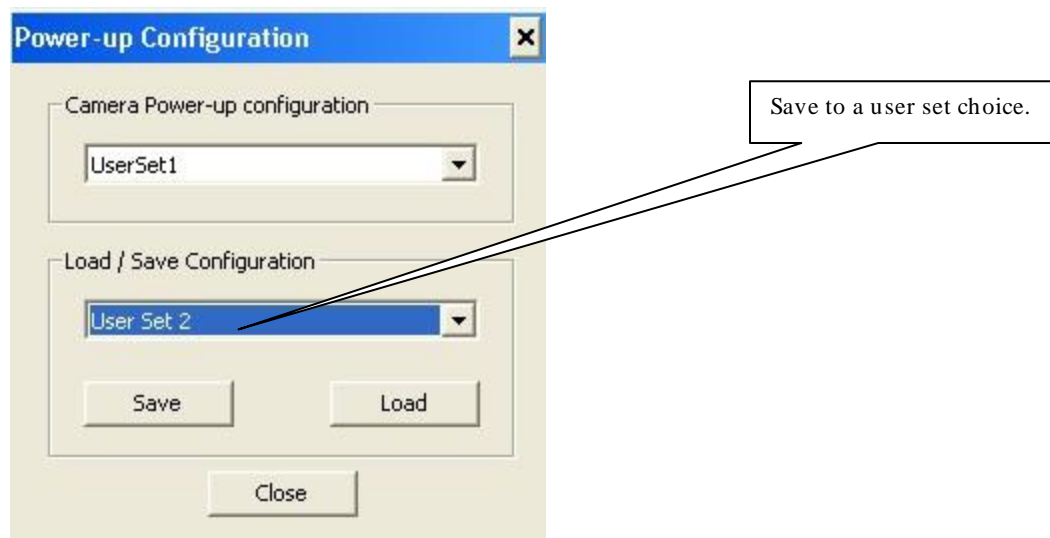
The camera is capable of adjusting camera parameters on-the-fly based on the scan direction of the camera. These parameters include gain, flat field coefficients, white balance and exposure time.

1. The first step is to put the camera in the reverse direction. This can be done using a reverse signal through CC3 and the Direction Source set to external or by having the Direction Source set to Internal and the Internal Direction set to reverse.
2. Set up all the desired parameters, including flat field corrections.

Category	Parameter	Value
Camera Information	Sensor ColorType	Monochrome
Camera Control	Internal Line Rate	10000
I/O Controls	Measured Line Rate	10003
Flat Field	Refresh Measured Line Rate	Press...
Image Format	Exposure Time Source	Timed
Transport Layer	Exposure Time	50
Serial Port	Measured Exposure Time	49993
File Access Control	Refresh Measured Exposure Time	Press...
	TDI Stages	2
	Direction Source	Internal
	Internal Direction	Reverse
	Offset	0
	Gain	1
	<< Less	

First, setup parameters for reverse direction.

3. Save the camera parameters to a User set other than the default user set.



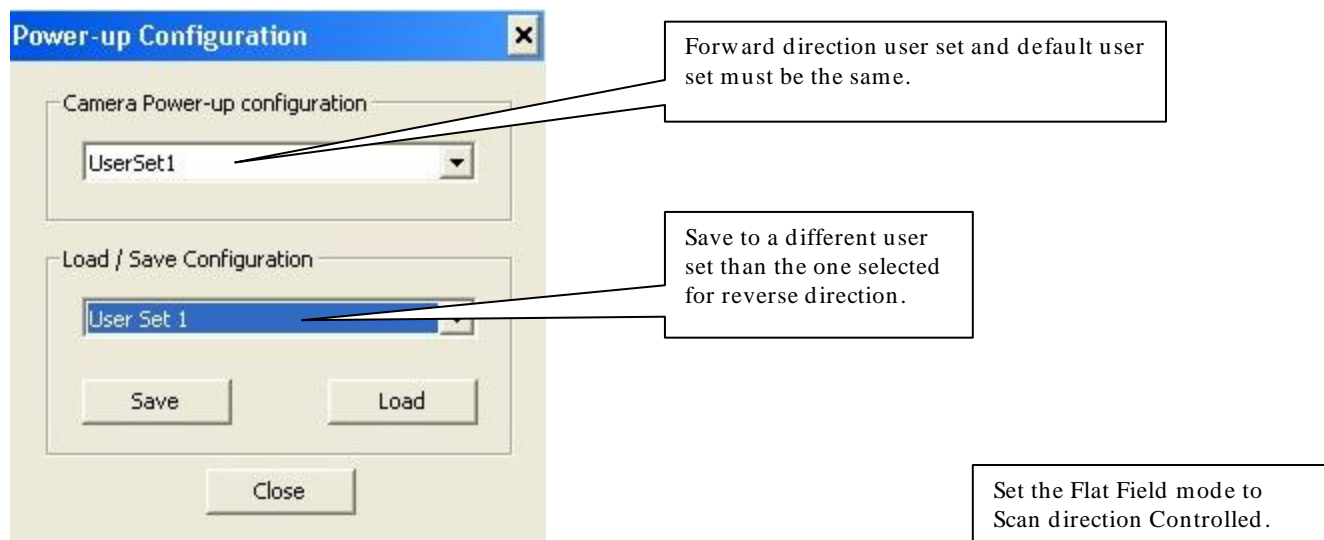
4. The next step is to put the camera in the forward direction. This can be done using a forward signal through CC3 and the Direction Source set to external or by having the Direction Source set to Internal and the Internal Direction set to forward.
5. Set up all the desired parameters including doing a flat field.

Category	Parameter	Value
Camera Information	Sensor ColorType	Monochrome
Camera Control	Internal Line Rate	10000
I/O Controls	Measured Line Rate	10003
Flat Field	Refresh Measured Line Rate	Press...
Image Format	Exposure Time Source	Timed
Transport Layer	Exposure Time	50
Serial Port	Measured Exposure Time	49993
File Access Control	Refresh Measured Exposure Time	Press...
	TDI Stages	2
	Direction Source	Internal
	Internal Direction	Forward
	Offset	0
	Gain	1
	<< Less	

Setup parameters for forward direction.

6. Save the camera set to User Set other than the saved to for the reverse direction. The forward direction user set and the default user set must be the same.





In the Flat Field area change the mode to Scan Direction Controlled.

Category	Parameter	Value
Camera Information	Mode	Scan Direction Controlled
Camera Control	Scan Direction Reverse Set	User Set 2
I/O Controls	Calibration Algorithm	Basic
Flat Field	Calibration Target	150
	Calibration Sample Size	4096
Image Format	ROI Offset X	1
Transport Layer	ROI Width	8192
Serial Port	Calibrate FPN	Press...
File Access Control	Calibrate PRNU	Press...
	Filter Threshold	0
	<< Less	

### A Note on External Direction, Direction Source, and User Sets

If using external direction control through CC3 ensure that the Direction Source is both set to external and saved in the user set. Also ensure that the polarity on CC3 is set appropriately for the desired direction.

# Transport Layer Control Category

Parameters in gray are read only, either always or due to another parameter being disabled. Parameters in black are user set in CamExpert or programmable via an imaging application.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.

Category	Parameter	Value
Camera Information	Camera Link Configuration	Full
Camera Control	Camera Link Clock Frequency	CL85MHz
I/O Controls	Tap Geometry	Geometry_1X8
Flat Field	Restart Camera	Press...
Image Format	XML Major Version	1
	XML Minor Version	0
Transport Layer	Refresh GenCP Status	Press...
Serial Port	Last GenCP Status	0
File Access Control	<< Less	

## Transport Layer Feature Descriptions

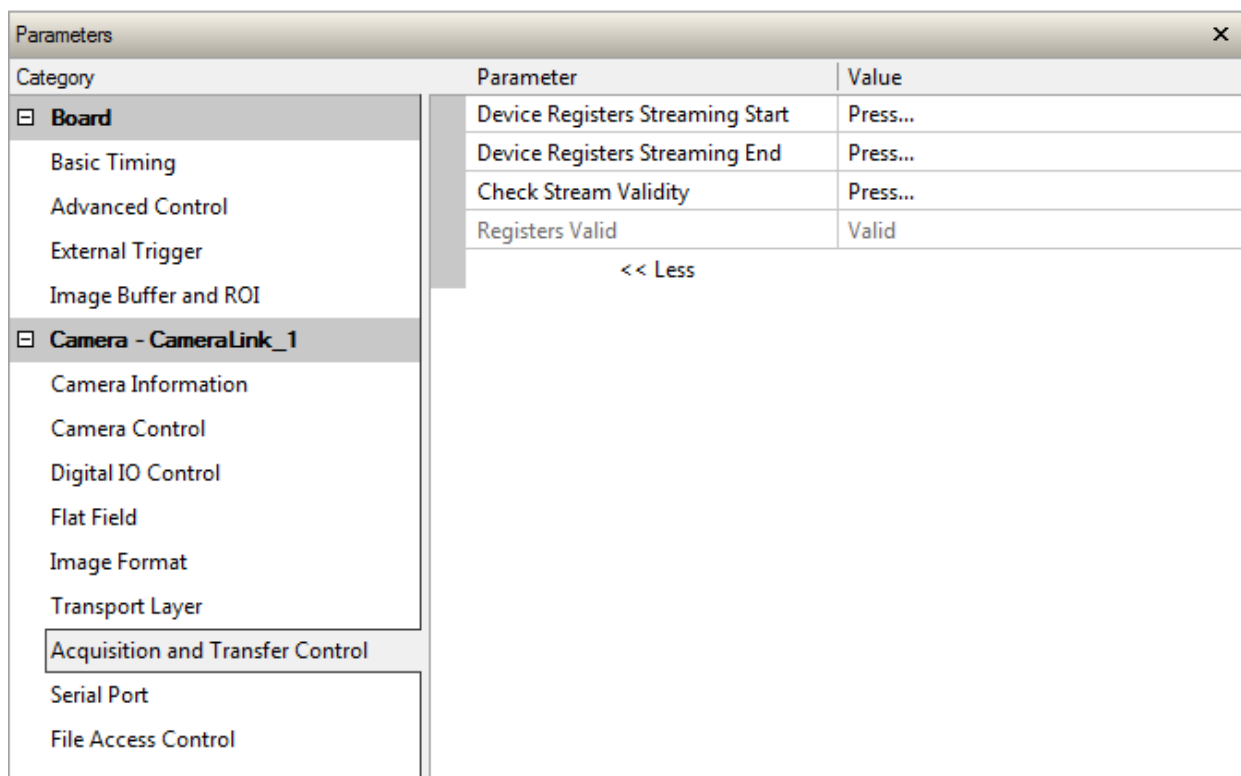
The following table describes these parameters along with their view attribute and minimum camera firmware version required. Additionally the firmware column will indicate which parameter is a member of the DALSA Features Naming Convention (DFNC), versus the GenICam Standard Features Naming Convention (SFNC not shown).

Display Name	Feature	Description	Device Version & View
Restart Camera	DeviceReset	Used to restart the camera, warm reset	1.00 Beginner DFNC
XML Major Version	DeviceManifestXMLMajorVersion	Together with DeviceManifestXMLMinorVersion specifies the GenICam™ feature description XML file version (RO)	1.00 Beginner DFNC
XML Minor Version	DeviceManifestXMLMinorVersion	Together with DeviceManifestXMLMajorVersion specifies the GenICam™ feature description XML file version (RO)	1.00 Beginner DFNC
Last GenCP Status	genCPStatus	If a feature read or write fails then Samera only returns that it fails – read this feature to get the actual reason for the failure Returns the last error Reading this feature clears it	1.00 Beginner DFNC
Refresh GenCP Status	refreshGenCPStatus	Press to return the current status of the GenCP	1.00 Beginner
Camera Link Configuration	ClConfiguration Base Medium Full Deca	Camera Link Output configuration	1.00 Beginner
Camera Link Configuration	clDeviceClockFrequency CL85MHz CL42.5MHz	Set the camera link clock rate	1.00 Beginner
Tap Geometry	DeviceTapGeometry	(RO)	1.00 Beginner

# Acquisition and Transfer Control Category

The P4 Acquisition and Transfer controls, as shown by CamExpert, groups parameters used to configure the optional acquisition modes of the device. Parameters in gray are read only, either always or due to another parameter being disabled. Parameters in black are user set in CamExpert or programmable via an imaging application.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.



## Acquisition and Transfer Control Feature Descriptions

The following table describes these parameters along with their view attribute and minimum camera firmware version required. Additionally the firmware column will indicate which parameter is a member of the DALSA Features Naming Convention (DFNC), versus the GenICam Standard Features Naming Convention (SFNC not shown).

Display Name	Feature	Description	Device Version & View
Device Registers Streaming Start	DeviceRegistersStreamingStart	Announces the start of registers streaming without immediate checking for consistency.	1.00 Beginner DFNC
Device Registers Streaming End	DeviceRegistersStreamingEnd	Announces end of registers streaming and performs validation for registers consistency before activating them.	1.00 Beginner DFNC

Check Stream Validity	DeviceRegistersCheck	Press to check the validity of the current register set.	1.00 Beginner DFNC
Registers Valid	DeviceRegistersValid	States if the current register set is valid and consistent.	1.00 Beginner DFNC

## Serial Port Control Category

The Serial Port control in CamExpert allows the user to select an available camera serial port and review its settings. This section also describes the Genie TS Framework Virtual Serial Port Driver and the use of the Genie TS serial port as an interface from an Ethernet network to a serial port control system for other devices.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.

Category	Parameter	Value
Camera Information	Baud Rate	Baud_115200
Camera Control	Data Size	Eight_bits
I/O Controls	Parity	None
Flat Field	Stop Bits	One
Image Format	<< Less	
Transport Layer		
Serial Port		
File Access Control		

## Serial Port Control Feature Descriptions

The Device Version number represents the camera software functional group, not a firm ware revision number.

Display Name	Feature	Description	View
Baud Rate	DeviceSerialPortBaudRate	Sets the baud rate used by the selected device's serial port. Available baud rates are device-specific.	1.00 Beginner DFNC
Baud 9600	Baud 9600	Baud rate is 9600	
Baud 19200	Baud 19200	Baud rate is 19200	
Baud 57600	Baud 57600	Baud rate is 57600	
Baud 115200	Baud 115200	Baud rate is 115200	
Baud 230400	Baud 230400	Baud rate is 230400	
Baud 460800	Baud 460800	Baud rate is 460800	
Baud 921600	Baud 921600	Baud rate is 921600	
Serial Port Parity	deviceSerialPortParity	Sets the parity checking type on the selected serial port.(RO)	1.00 Beginner DFNC
None	None	Parity checking is disabled	
Data Size	deviceSerialPortDataSize	Sets the bits per character (bpc) to use (RO).	1.00

Display Name	Feature	Description	View
Eight Bits	bpc8	Use 8 bits per character	Beginner DFNC
Stop Bits	deviceSerialPortNumberOf StopBits	Sets the number of stop bits to use.	1.00 Beginner
Stopbits1	Stopbits1	Use 1 stop bit	DFNC

## File Access Control Category

The File Access control in CamExpert allows the user to quickly upload various data files to the connected P4. The supported data files are for P4 firmware updates, Flat Field coefficients, LUT data tables, and a custom image for use as an internal test pattern.

Features listed in the description table but tagged as *Invisible* are usually for Teledyne DALSA or third party software usage—not typically needed by end user applications.

Category	Parameter	Value
Camera Information	Upload/Download File	Setting...
Camera Control	<< Less	
I/O Controls		
Flat Field		
Image Format		
Transport Layer		
Serial Port		
File Access Control		

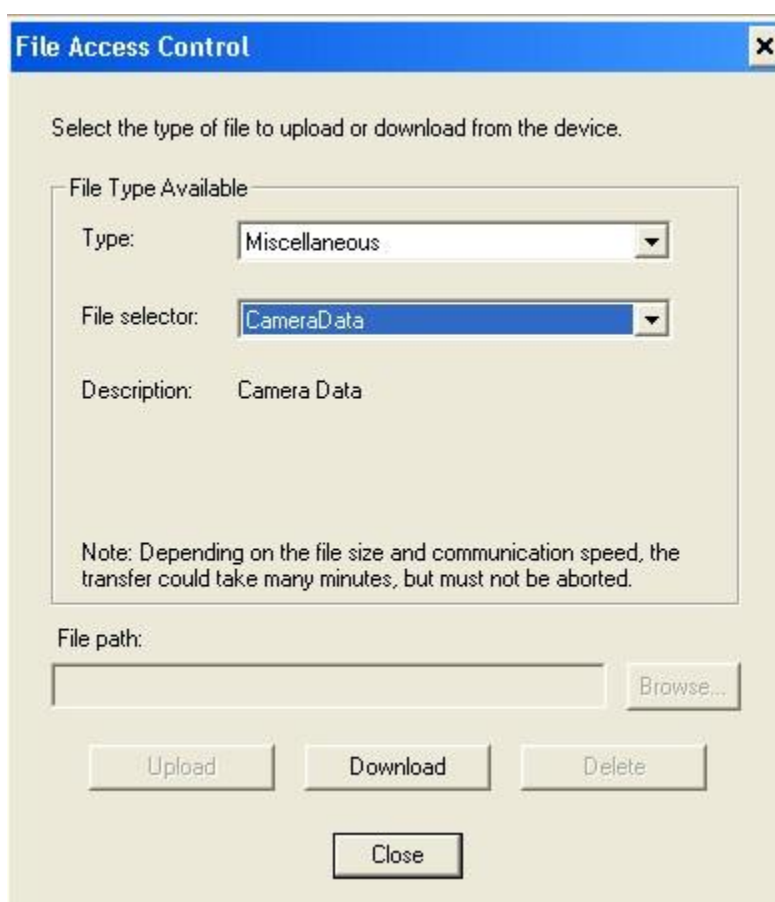
## File Access Control Feature Descriptions

Display Name	Feature	Description	View
File Selector	FileSelector	Selects the file to access. The file types which are accessible are device-dependent.	1.00 Beginner
FPGA Code	Firmware1	Upload new FPGA to the camera which will execute on the next camera reboot cycle.	DFNC
Micro Code		Upload new micro code to the camera which will execute on the next camera reboot cycle.	
CCI		Upload new CCI to the camera which will execute on the next camera reboot cycle.	
XML		Upload new XML to the camera which will execute on the next camera reboot cycle.	
User Set		Use UserSetSelector to specify which user set to access.	
Factory FlatField coefficients		Use UserSetSelector to specify which user flatfield to access.	
User FPN		Use UserSetSelector to specify which user FPN to access.	
CameraData		Download camera information and send for customer support.	
File Operation Selector	FileOperationSelector	Selects the target operation for the selected file in the device. This operation is executed when the File Operation Execute feature is called.	1.00 Guru
Open	Open	Select the Open operation - executed by FileOperationExecute.	
Close	Close	Select the Close operation - executed by FileOperationExecute.	
Read	Read	Select the Read operation - executed by FileOperationExecute.	
Write	Write	Select the Write operation - executed by FileOperationExecute.	
Delete	Delete	Select the Delete operation - executed by FileOperationExecute.	
File Operation Execute	FileOperationExecute	Executes the operation selected by File Operation Selector on the selected file.	1.00 Guru
File Open Mode	FileOpenMode	Selects the access mode used to open a file on the device.	1.00 Guru
Read	Read	Select READ only open mode	
Write	Write	Select WRITE only open mode	
File Access Buffer	FileAccessBuffer	Defines the intermediate access buffer that allows the exchange of data between the device file storage and the application.	1.00 Guru
File Access Offset	FileAccessOffset	Controls the mapping offset between the device file storage and the file access buffer.	1.00 Guru
File Access Length	FileAccessLength	Controls the mapping length between the device file storage and the file access buffer.	1.00 Guru
File Operation Status	FileOperationStatus	Displays the file operation execution status. (RO).	1.00 Guru

Display Name	Feature	Description	View
Success	Success	The last file operation has completed successfully.	
Failure	Failure	The last file operation has completed unsuccessfully for an unknown reason.	
File Unavailable	FileUnavailable	The last file operation has completed unsuccessfully because the file is currently unavailable.	
File Invalid	FileInvalid	The last file operation has completed unsuccessfully because the selected file is not present in this camera model.	
File Operation Result	FileOperationResult	Displays the file operation result. For Read or Write operations, the number of successfully read/ written bytes is returned. (RO)	1.00 Guru
File Size	FileSize	Represents the size of the selected file in bytes.	1.00 Guru

## File Access via the CamExpert Tool

1. Click on the “Setting...” button to show the file selection menu.



2. From the Type drop menu, select the file type that will be uploaded to the camera.
3. From the File Selector drop menu, select the camera memory location for the uploaded data. This menu presents only the applicable data locations for the selected file type.

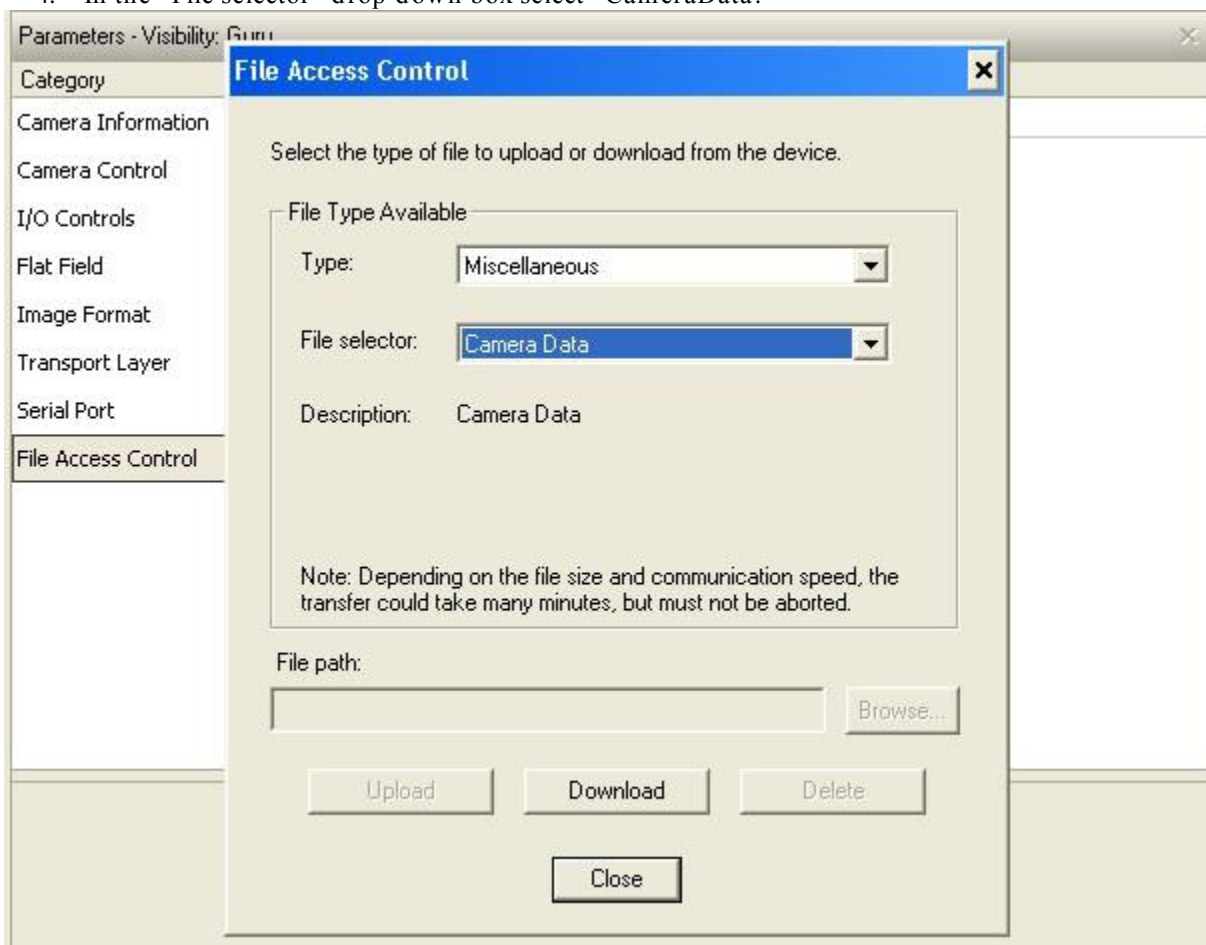


4. Click the Browse button to open a typical Windows Explorer window.
5. Select the specific file from the system drive or from a network location.
6. Click the Upload button to execute the file transfer to the camera.
7. Note that firmware changes require a device reset command from the Camera Information Controls and, additionally, CamExpert should be shutdown and restarted following a reset.

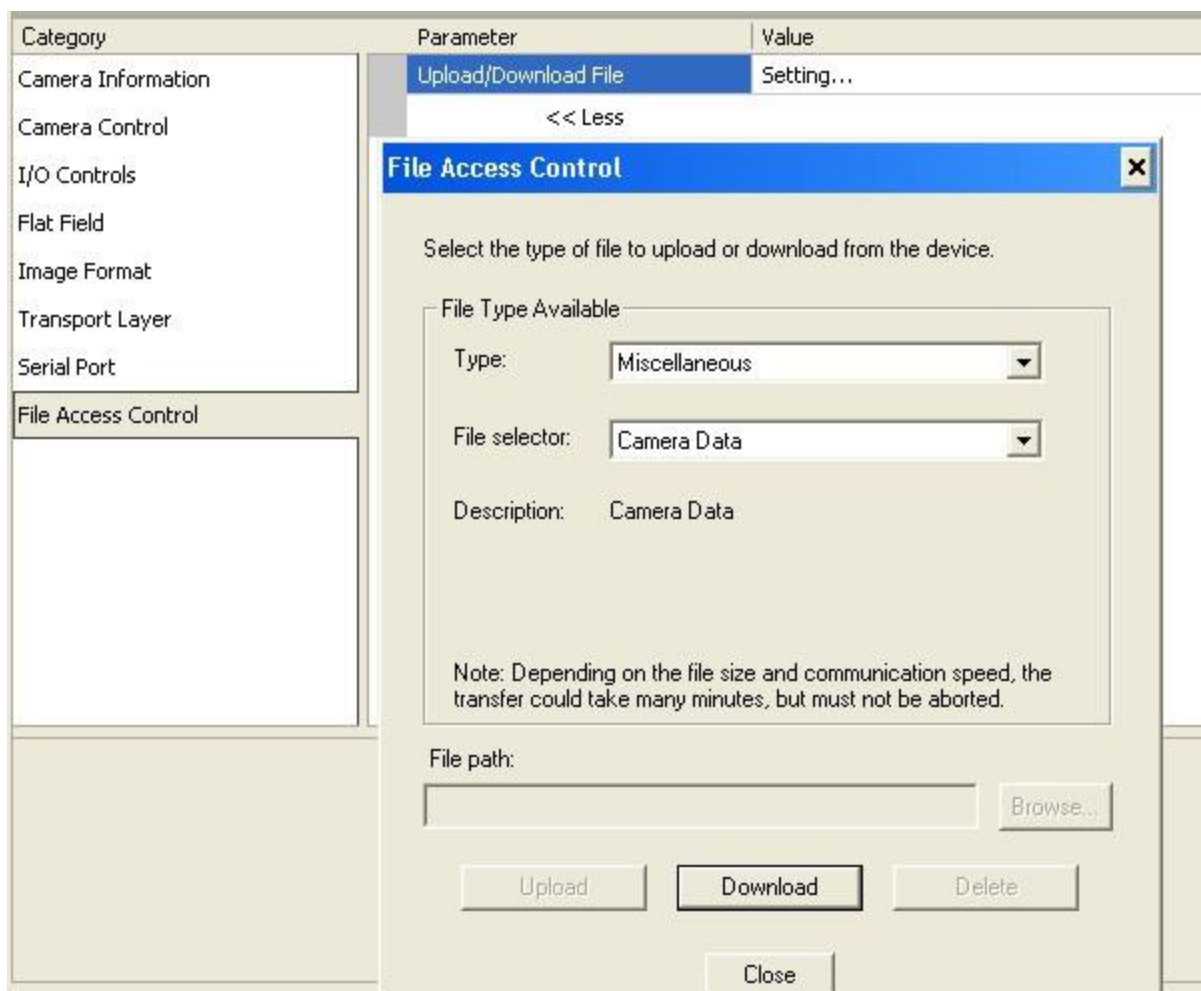
## Download a List of Camera Parameters

For diagnostic purposes you may want to download a list of all the parameters and values associated with the camera.

1. Go to File Access Control
2. Click on Settings
3. In the “Type” drop down box select “Miscellaneous.”
4. In the “File selector” drop down box select “CameraData.”



5. Hit “Download”
6. Save the text file and send the file to Teledyne DALSA customer support.



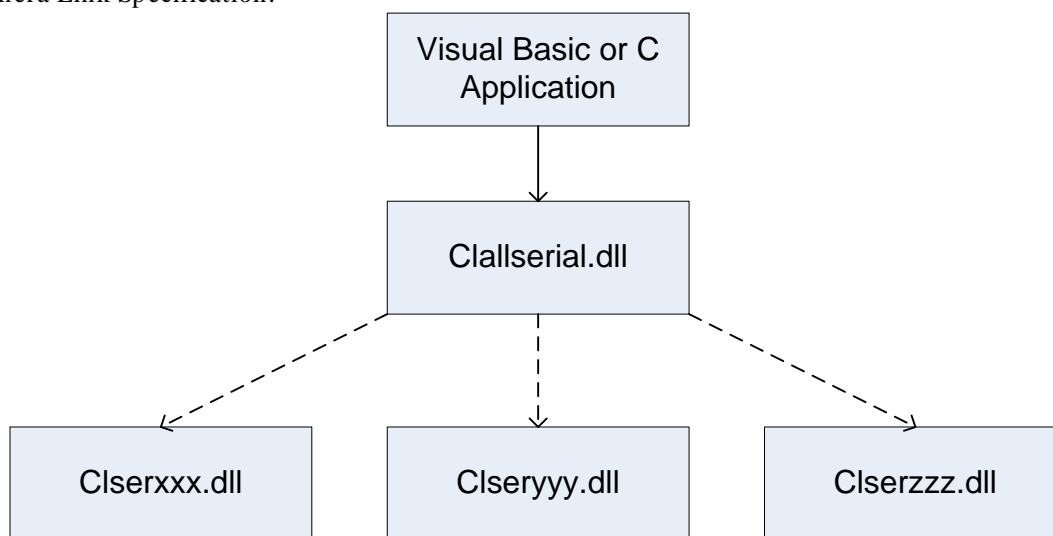
# Appendix B: ASCII Commands

The following commands can be used to control the Teledyne DALSA Piranha4 cameras.

## Accessing the Three Letter Commands (TLC)

To access the TLC an ASCII-based communications interface application, such as HyperTerminal.

Additionally it is possible to use the functions of `clserxxx.dll` or `clallserial.dll` as defined in the Camera Link Specification.



**Figure 25: Serial DLL hierarchy as mentioned in the Camera Link Specification**

1. Cycle power to the camera: by either a) issuing the reset camera command (rc), or b) powering the camera OFF and then ON.
2. Load the ASCII interface using:
  - 9600 baud
  - 8 data bits
  - no parity
  - 1 stop bit
  - no flow control
  - local echo
  - (carriage return / linefeed)
3. Wait for a stable status LED color (green or red) before proceeding. Note that all entries in HyperTerminal will be ignored until a stable LED color is obtained.
4. In case of HyperTerminal, press the <Esc> key.
5. Once <Esc> has been entered the help screen appears.

## Notes on Using Alternatives to HyperTerminal

- If you are using interfaces other than HyperTerminal, the ASCII character, Esc, is decimal 27 and needs to be issued. From the command line insert Esc by using ALT+2+7 of the activated Num-Pad. In some cases this needs to be followed by a carriage return or a linefeed to send this to the camera.
- In ASCII the Esc character may look like this: "←".

## ASCII to GenCP

To switch from the ASCII-command interface to the GenCP interface, the camera must be either reset (RC) or the power must be cycled. Note that GenCP and ASCII commands cannot be accessed simultaneously.

**Note that the HyperTerminal application is not available on the Windows 7 OS.**

### Alternatives to HyperTerminal

The following alternative ASCII-interfaces have been tested and shown to work with this camera: PuTTY and TeraTerm. Note that PuTTY does not have Xmodem capability while TeraTerm does. Xmodem is required to update code in the camera.

TeraTerm <http://logmett.com/index.php?download/tera-term-473-freeware.html>

PuTTY <http://putty.en.softonic.com/>

The camera responds to a simple ASCII-based protocol. A carriage return <CR> ends each command.

### Example: to return the current detector settings

gcp <CR>

A complete list of the available detector commands, their format and parameters can be displayed by sending the help (h) command.

## Port Configuration

Baud: 9,600  
 Bits: 8  
 Parity: None  
 Stop bits: 1  
 Flow Control: None

Echo typed characters locally.

## Rules

- The interface is not case sensitive
- One command and argument(s) per line
- To enter a floating point number prefix it with a "F" – for example "ssg 0 f1.5"
- Error codes returned are the same as the GenICam™ interface – see Diagnostics | Error Codes
- Follow each command with the carriage return character – 0x0D

## Disabling Esc Key for Direct access to ASCII commands

By default the Esc key is enabled and an Esc key sequence has to be issued in order to access the ASCII commands. Using the DEK 1 command the need to issue an Esc key is disabled and access to the ASCII commands are available immediately upon camera boot up. Note: access to GENCP is no longer available with the Esc key disabled unless a DEK 0 command is issued and the camera re-booted.

## Commands

<b>Full Name</b>	<b>Calibrate User FPN</b>	
<b>Mnemonic</b>	<b>CCF</b>	
<b>Argument(s)</b>	# of lines to average	<ul style="list-style-type: none"> <li>• 2048</li> <li>• 4096</li> </ul>
<b>Description</b>	Calibrate user FPN dark flat field coefficients	

<b>Full Name</b>	<b>Camera Link Speed</b>	
<b>Mnemonic</b>	<b>CLS</b>	
<b>Argument(s)</b>	Frequency	0. 85 MHz 1. 42.5 MHz
<b>Description</b>	Camera Link clock frequency	

<b>Full Name</b>	<b>Camera Link Mode</b>	
<b>Mnemonic</b>	<b>CLM</b>	
<b>Argument(s)</b>	Mode	0. Base 1. Medium 2. Full
<b>Description</b>	Camera Link Mode	

<b>Full Name</b>	<b>Calibrate Flatfield</b>	
<b>Mnemonic</b>	<b>CPA</b>	
<b>Argument(s)</b>	Algorithm	0. Basic 1. Low-pass Filter
	# of lines to average	<ul style="list-style-type: none"> <li>• 2048</li> <li>• 4096</li> </ul>
	Target	0 to 4095 DN in 12 bit mode 0 to 1023 DN in 10 bit mode 0 to 255 DN in 8 bit mode
<b>Description</b>	Calibrate user PRNU flat field coefficients	
<b>Notes</b>	<ul style="list-style-type: none"> <li>• Perform flat field calibration using the average of &lt;# lines&gt;.</li> <li>• With filter algorithm this average line is then smoothed and outlier pixels are interpolated. Use this feature if your white reference is not featureless.</li> <li>• Adjust pixel gain such that output will be &lt;target&gt;.</li> <li>• The target is first divided by horizontal binning factor and gain and then the offset is subtracted. Therefore the output will go to the target.</li> <li>• Because the PRNU can be less than 1, the target may be below the current maximum value.</li> <li>• Coefficients are saved and loaded with user set (e.g. USS / USL)</li> </ul>	

<b>Full Name</b>	<b>Disable Esc Key</b>	
<b>Mnemonic</b>	<b>DEK</b>	
<b>Argument(s)</b>	Mode	0. Esc key is enabled 1. Esc key is disabled
<b>Description</b>	Allow the use of the Esc key to be disabled so that upon boot-up the camera will directly enter the ASCII command mode. With the Esc key disabled the GENCP cannot be accessed.	
<b>Notes</b>	To access the GenCP, you have to first issue the DEK 0 command in order to enable the ESC key. Then reboot the camera.	

<b>Full Name</b>	<b>Flatfield Mode</b>	
<b>Mnemonic</b>	<b>FFM</b>	
<b>Argument(s)</b>	Mode	0. Disable use of user FPN and PRNU flat field correction coefficients 1. Enable use of user FPN and PRNU flat field correction coefficients 2. Reset user FPN coefficients to zero and user PRNU coefficients to one 3. Scan direction controlled user set loading
<b>Description</b>	Set flat field mode	
<b>Notes</b>		

<b>Full Name</b>	<b>Set Flatfield Scan Direction Reverse Set</b>	
<b>Mnemonic</b>	<b>FRS</b>	
<b>Argument(s)</b>	User Set Number	1 to 8
<b>Description</b>	Set scan direction controlled reverse set	
<b>Notes</b>		

<b>Full Name</b>	<b>Display Camera Configuration</b>
<b>Mnemonic</b>	<b>GCP</b>
<b>Argument(s)</b>	
<b>Description</b>	Display current value of camera configuration parameters
<b>Notes</b>	<pre> USER&gt;gcp Model      P4_CM_08K070_00_R Microcode  03-081-20235-03 CCI        03-110-20242-04 FPGA       03-056-20378-07 Serial #   14013771 UserID #   6565657 BiST:      Good  DefaultSet 1 Ext Trig   Off Line Rate  10000 [Hz] Meas L.R.  10003 [Hz] Max L.R.   19417 [Hz] Exp. Mode  Timed Exp. Time  50000 [ns] Meas E.T.  49993 [ns] Max E.T.   98500 [ns]  Test Pat.  0:Off Direction  Internal, Forward TDI Stages 2 Vert. Bin  1 Flat Field Internal Filter      0 Offset      0 Gain        1.00 Hor. Bin    1 Mirror      Off CL Config   Full CL Speed    85MHz Pixel Fmt   8 bits CPA ROI     1-8192 AOI Mode:   Off USER&gt; </pre>

<b>Full Name</b>	<b>Get Value</b>
<b>Mnemonic</b>	<b>GET</b>
<b>Argument(s)</b>	<'parameter'>
<b>Description</b>	The “get” command displays the current value(s) of the feature specified in the string parameter. Note that the parameter is preceded by a single quote “'”. Using this command will be easier for control software than parsing the output from the “gcp” command.
<b>Notes</b>	

Full Name	Help
Mnemonic	H
Argument(s)	
Description	Display list of three letter commands
Notes	<p>USER&gt;h  P4 (03-081-20235-03): Command Line Interpreter May 28 2013,  16:49:34</p> <p>ccf - Calibrate User FPN &lt;2048 4096&gt;  clm - Camera Link Mode &lt;0:Base 1:Med 2:Full&gt;  cls - Camera Link Speed &lt;0 - 85MHz, 1 - 42.5MHz&gt;  cpa - Calibrate Flatfield &lt;0:basic 1:filter&gt;&lt;2048 4096&gt;&lt;DN  target&gt;  dek - disESC Esc key &lt;0/1&gt;  ffm - Flat Field Mode &lt;0:Off 1:On 2:Initialiaze 3:Scan  direction controlled&gt;  frs - Set Flatfield Scan Direction Reverse Set &lt;set 1-8&gt;  gcp - Display Camera Configuration  h - Help  lpc - Load Pixel Coefficients &lt;set 0-8&gt;  rc - Reset Camera  roi - Set Flatfield ROI &lt;1st pixel&gt; &lt;last pixel&gt;  rpc - Reset Flatfield Coefficients  sac - Set AOI Count &lt;value 1-4&gt;  sad - Set AOI Selector, Offset and Width &lt;selector 1-AOI  Count&gt; &lt;1st pixel&gt; &lt;width &gt;= 40&gt;  sam - Set AOI Mode AOI &lt;1-enable, 0-disable&gt;  sbh - Horizontal Binning &lt;1 2&gt;  sbr - Set Baud Rate &lt;9600 57600 115200&gt;  sbv - Vertical Binning &lt;1 2&gt;  scd - Direction &lt;0:Fwd, 1:Rev 2:Ext&gt;  sem - Exposure Mode &lt;0:Int 1:Ext&gt;  set - Exposure Time &lt;ns&gt;  sft - Set Filter Threshold &lt;DN&gt;  smm - Mirroring &lt;0:Off 1:On&gt;  spf - Pixel Format &lt;0:8 1:10 2:12 bits&gt;  ssb - Offset &lt;DN&gt;  ssf - Internal Line Rate &lt;Hz&gt;  ssg - Gain f&lt;gain&gt;  stg - TDI Stages &lt;1 2&gt;  stm - External Trigger &lt;0:Off 1:On&gt;  sui - Set User ID '&lt;string&gt;  svm - Test Pattern &lt;0,1,3-6&gt;  usd - Default User Set &lt;0-8&gt;  usl - Load User Set &lt;0-8&gt;  uss - Save User Set &lt;1-8&gt;  vt - Temperature &lt;0&gt;  vv - Input Voltage  USER&gt;</p>



<b>Full Name</b>	<b>Load Pixel Coefficients</b>	
<b>Mnemonic</b>	<b>LPC</b>	
<b>Argument(s)</b>	Set selector	0. Factory set 1-8. User sets
<b>Description</b>	Load user set	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Loads FPN coefficients and PRNU coefficients from a user set ( only coefficeints, no other camera parameters)</li> </ul>	

<b>Full Name</b>	<b>Reset Camera</b>	
<b>Mnemonic</b>	<b>RC</b>	
<b>Argument(s)</b>		
<b>Description</b>	Resets the camera to the saved user default settings. These settings are saved using the usd command.	
<b>Notes</b>	The micro-controller reboots: <ul style="list-style-type: none"> <li>Load any file updates</li> <li>Clear over temperature condition</li> <li>Perform start up camera tests (BiST)</li> <li>Load FPGA code</li> <li>Configure FPGA and sensor.</li> <li>Load default user set</li> <li>Baud rate set to 9600</li> </ul>	

<b>Full Name</b>	<b>Set Flatfield ROI</b>	
<b>Mnemonic</b>	<b>ROI</b>	
<b>Argument(s)</b>	First pixel	1 to 8192
	Last pixel	1 to 8192
<b>Description</b>	Flat field region of interest	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Specifies the pixels that CCF and CPA will calibrate             <ul style="list-style-type: none"> <li>Pixel coefficients outside this region are not changed</li> </ul> </li> <li>Last pixel must be greater than or equal to first pixel</li> </ul>	

<b>Full Name</b>	<b>Reset Flatfield Coefficients</b>	
<b>Mnemonic</b>	<b>RPC</b>	
<b>Argument(s)</b>		
<b>Description</b>	Reset all user FPN values to zero and all user PRNU coefficients to one	
<b>Notes</b>		

<b>Full Name</b>	<b>Set AOI Count</b>	
<b>Mnemonic</b>	<b>SAC</b>	
<b>Argument(s)</b>	Number of AOI's	1 to 4
<b>Description</b>	Set AOI Counter	
<b>Notes</b>		

<b>Full Name</b>	<b>Set AOI Selector</b>	
<b>Mnemonic</b>	<b>SAD</b>	
<b>Argument(s)</b>	Selector	1 to 4
	Offset	1 to AOI Count – any pixel can be starting pixel
	Width	No less than 40 pixels
<b>Description</b>	Define an AOI	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Must not overlap with an already existing AOI</li> </ul>	

<b>Full Name</b>	<b>Set AOI Mode</b>	
<b>Mnemonic</b>	<b>SAM</b>	
<b>Argument(s)</b>	Mode	0. Off / Disable 1. Active / Enable
<b>Description</b>	Set AOI mode	
<b>Notes</b>		

<b>Full Name</b>	<b>Set Binning Horizontal</b>	
<b>Mnemonic</b>	<b>SBH</b>	
<b>Argument(s)</b>	Binning	1. Single pixel 2. Binning of 2 pixels
<b>Description</b>	Set horizontal binning	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Available in all modes: single line, TDI and Area</li> </ul>	

<b>Full Name</b>	<b>Set Baud Rate</b>	
<b>Mnemonic</b>	<b>SBR</b>	
<b>Argument(s)</b>	Baud rate	9600 57600 115200
<b>Description</b>	Set baud rate	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Send command and then change speed of HyperTerminal</li> </ul>	

<b>Full Name</b>	<b>Set Binning Vertical</b>	
<b>Mnemonic</b>	<b>SBV</b>	
<b>Argument(s)</b>		1. Single pixel 2. Binning of 2 pixels
<b>Description</b>	Set vertical binning	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Must be in Single line mode (stg 1)</li> </ul>	
	<ul style="list-style-type: none"> <li>Must be in Line scan mode (dst 0)</li> </ul>	

<b>Full Name</b>	<b>Direction</b>	
<b>Mnemonic</b>	<b>SCD</b>	
<b>Argument(s)</b>	Direction	0. Forward 1. Reverse (not available in single line mode) 2. External – controlled by CC3 signal (not available in single line mode)
<b>Description</b>	Set sensor scan direction	
<b>Notes</b>		

<b>Full Name</b>	<b>Exposure Mode</b>	
<b>Mnemonic</b>	<b>SEM</b>	
<b>Argument(s)</b>	Mode	0. Internal (“Timed”) 1. External (“PulseWidth”)
<b>Description</b>	Set exposure time mode	
<b>Notes</b>	<ul style="list-style-type: none"> <li>In internal mode the exposure time is controlled by the SET command</li> <li>In external mode the sensor is exposed while CC1 signal is high</li> <li>External mode is only available when the trigger mode is also external (STM 1)</li> <li>SEM 1 overrides internally generated independent exposure times</li> <li>When CC1 signal falls line is read</li> </ul>	

<b>Full Name</b>	<b>Exposure Time</b>	
<b>Mnemonic</b>	<b>SET</b>	
<b>Argument(s)</b>	Exposure time	4, 000 to 3, 000, 000 [ns]
<b>Description</b>	Set internal exposure time in nanoseconds – 25 ns resolution	
<b>Notes</b>	<ul style="list-style-type: none"> <li>Line time &gt; ( Exposure time + 1,500 ns )</li> </ul>	

<b>Full Name</b>	<b>Set Filter Threshold</b>	
<b>Mnemonic</b>	<b>SFT</b>	
<b>Argument(s)</b>	TDI stage = 2 TDI stage = 1	Range 0 to 16, default 5. Range 0 to 8, default 2.
<b>Description</b>	The image enhanced filter seeks to improve the visual appearance of an image and to represent the image in a form best suited for machine analysis. It improves signal to noise ratio by applying an adaptive FIR filter spatial domain based on local contrast analysis. Set the threshold at which the filter will be enabled. Contrast between pixels greater than this threshold will not be filtered.	
<b>Notes</b>	<ul style="list-style-type: none"> <li>The smaller the number, the lower the filters effect</li> </ul>	

<b>Full Name</b>	<b>Mirroring</b>	
<b>Mnemonic</b>	<b>SMM</b>	
<b>Argument(s)</b>	Mode	0. Off 1. Image is flipped on the vertical axis
<b>Description</b>	Set mirroring mode	
<b>Notes</b>		

Full Name	Pixel Format		
Mnemonic	SPF		
Argument(s)	Selector	<div>0. 8 bits</div> <div>1. 10 bits</div> <div>2. 12 bits (only available with Base or Medium Camera Link configurations)</div>	
Description	Set pixel format		
Notes			

<b>Full Name</b>	<b>Offset</b>		
<b>Mnemonic</b>	<b>SSB</b>		
<b>Argument(s)</b>	Offset	8 bit 10-bit 12-bit	-32 to 31 -128 to 127 -512 to 511
<b>Description</b>	Set contrast offset – single value added to all pixels after PRNU/ flat field coefficients (before gain).		
<b>Notes</b>	<ul style="list-style-type: none"> <li>Range changes depending on pixel format (SPF)</li> </ul>		

Full Name	Internal Line Rate		
Mnemonic	SSF		
Argument(s)	Line rate	1 to 70,000 [Hz]	
Description	Set internal line rate in Hz		
Notes	<ul style="list-style-type: none"><li>Line time &gt; ( Exposure time + 1,500 ns )</li></ul>		

Full Name	Gain	
Mnemonic	SSG	
Argument(s)	Selector	
	Gain	1.0 to 10.0
Description	Set gain as a single value multiplied by all pixels.	
Notes	<ul style="list-style-type: none"><li>Floating point number: 1.0 to 10.0.</li><li>Note that gain value must be preceded by an “f” (e.g. ssg 0 f1.5)</li></ul>	

Full Name	Set TDI Stages		
Mnemonic	STG		
Argument(s)	Selector		
	TDI stage	<div><div>1.</div>Single line mode (lower sensitivity).</div> <div><div>2.</div>TDI mode (higher sensitivity)</div>	
Description			
Notes	<div><div>•</div>In single line mode the camera must be internal direction control</div> <div><div>•</div>TDI mode: a pair of lines summed with suitable delay</div>		

<b>Full Name</b>	<b>External Trigger</b>	
<b>Mnemonic</b>	<b>STM</b>	
<b>Argument(s)</b>	Mode	<ol style="list-style-type: none"> <li>1. Internal</li> <li>2. External</li> </ol>
<b>Description</b>	Set trigger mode	
<b>Notes</b>	<ul style="list-style-type: none"> <li>• In internal mode line rate is controlled by SSF command</li> <li>• In external mode readout starts on falling edge of CC1 signal and is available only when STM = 1 (external trigger on)</li> <li>• Exposure time equals high time of EXSYNC on signal on CC1</li> </ul>	

<b>Full Name</b>	<b>Test Pattern</b>	
<b>Mnemonic</b>	<b>SVM</b>	
<b>Argument(s)</b>	Mode	<ol style="list-style-type: none"> <li>0. Sensor Video</li> <li>1. Ramp</li> <li>2. A5</li> <li>3. Each_tap_fixed</li> <li>4. All_1365</li> <li>5. All_1</li> </ol>
<b>Description</b>	Select test pattern	
<b>Notes</b>	<ul style="list-style-type: none"> <li>• When a test pattern is selected all digital processing (e.g. flat field, gain) is disabled – it is re-enabled when sensor video is selected</li> </ul>	

<b>Full Name</b>	<b>Default User Set</b>	
<b>Mnemonic</b>	<b>USD</b>	
<b>Argument(s)</b>	Set selector	<ol style="list-style-type: none"> <li>0. Factory set</li> <li>1-8. User sets</li> </ol>
<b>Description</b>	Select user set to load when camera is reset	
<b>Notes</b>	<ul style="list-style-type: none"> <li>• The settings include all those listed by the GCP command plus the user FPN coefficients, and user PRNU coefficients</li> </ul>	

<b>Full Name</b>	<b>Load User Set</b>	
<b>Mnemonic</b>	<b>USL</b>	
<b>Argument(s)</b>	Set selector	<ol style="list-style-type: none"> <li>0. Factory set</li> <li>1-8. User sets</li> </ol>
<b>Description</b>	Load user set	
<b>Notes</b>	<ul style="list-style-type: none"> <li>• Loads and makes current all the settings listed by the GCP command plus the user FPN coefficients, and user PRNU coefficients</li> </ul>	

<b>Full Name</b>	<b>Save User Set</b>	
<b>Mnemonic</b>	<b>USS</b>	
<b>Argument(s)</b>	Set selector	1 to 8
<b>Description</b>	Save user set	
<b>Notes</b>	<ul style="list-style-type: none"> <li>• Saves all the current settings listed by the GCP command plus the user FPN coefficients, and user PRNU coefficients</li> </ul>	

<b>Full Name</b>	<b>Temperature</b>
<b>Mnemonic</b>	<b>VT</b>
<b>Argument(s)</b>	0
<b>Description</b>	Display internal temperature in degrees Celsius
<b>Notes</b>	

<b>Full Name</b>	<b>Voltage</b>
<b>Mnemonic</b>	<b>VV</b>
<b>Argument(s)</b>	
<b>Description</b>	Display supply voltage
<b>Notes</b>	

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# EMC Declaration of Conformity

We, TELEDYNE DALSA  
605 McMurray Road  
Waterloo, Ontario  
CANADA N2V 2E9

Declare under sole responsibility that the cameras:  
Brand Name: Piranha4

Models: P4-CM-08K070-00-R

Which are components to be integrated into larger systems, were evaluated according to the CE Mark, FCC Part 15, VCCI, Israel, Korea, and Industry Canada ICES-003 Evaluation and satisfy the requirements of the following standards:

EN 55011 (2009)  
EN 61326-1 (2006)  
EN 55024 (2010)  
ICES-003  
CISPR-11  
FCC Part 15

Place of issue: Waterloo, Ontario, Canada

Date of Issue: December 22, 2011

Hank Helmond  
Director of Quality, TELEDYNE DALSA Corp.



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# Revision History

Revision	Change Description	Date
00	Initial release.	16 March 2012
01	-Revised list of GenICam commands added. -Calibration process diagram added. -Revised responsivity graph added.	27 June 2012
02	-Control and Data Interface description in specifications table revised: 2 Camera Link MDR26 connectors [used] for transmitting Base, Medium, or Full configurations. -New camera image added to cover. -Operating Range values revised. -Revised AOI rules. -Low and High timing diagram added. -Pixel format values revised.	03 July 2013



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