

Power Wiring

Location	Rating/Type
Standard (Option 1)	600V, 90 °C (194 °F) XHHW2/RHW-2 Anixter B209500-B209507, Belden 29501-29507, or equivalent
Standard (Option 2)	Tray rated 600V, 90 °C (194 °F) RHH/RHW-2 Anixter OLF-7xxxxx or equivalent
Class I & II; Division I & II	Tray rated 600V, 90 °C (194 °F) RHH/RHW-2 Anixter 7V-7xxxx-3G or equivalent

Power Terminal Block

Frame A, B, C and D

Frame E

Terminal	Description
L1/R, L2/S, L3/T	Input Line Voltage Connection
T1/U, T2/V, T3/W	Motor Phase Connection 
DC+, DC-	DC Bus Connection
BR+, BR-	Dynamic Brake Resistor Connection
⊖	Safety Ground – PE

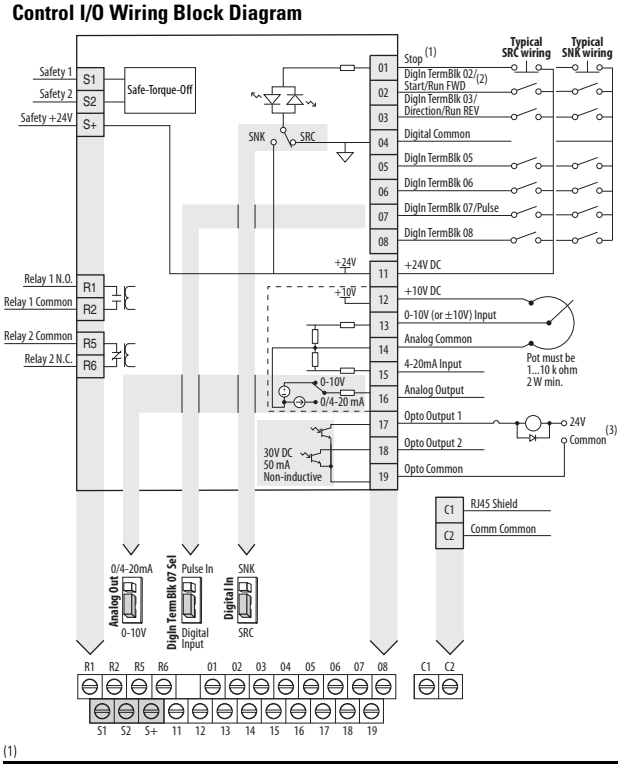
IMPORTANT Terminal screws may become loose during shipment. Ensure that all terminal screws are tightened to the recommended torque before applying power to the drive.

Power Terminal Block Specifications

Frame	Maximum Wire Size ⁽¹⁾	Minimum Wire Size ⁽¹⁾	Torque
A	5.3 mm ² (10 AWG)	0.8 mm ² (18 AWG)	1.76...2.16 Nm (15.6...19.1 lb-in.)
B	8.4 mm ² (8 AWG)	2.1 mm ² (14 AWG)	1.76...2.16 Nm (15.6...19.1 lb-in.)
C	8.4 mm ² (8 AWG)	2.1 mm ² (14 AWG)	1.76...2.16 Nm (15.6...19.1 lb-in.)
D	13.3 mm ² (6 AWG)	5.3 mm ² (10 AWG)	1.76...2.16 Nm (15.6...19.1 lb-in.)
E	26.7 mm ² (3 AWG)	8.4 mm ² (8 AWG)	3.09...3.77 Nm (27.3...33.4 lb-in.)

⁽¹⁾ Maximum/minimum sizes that the terminal block will accept – these are not recommendations.

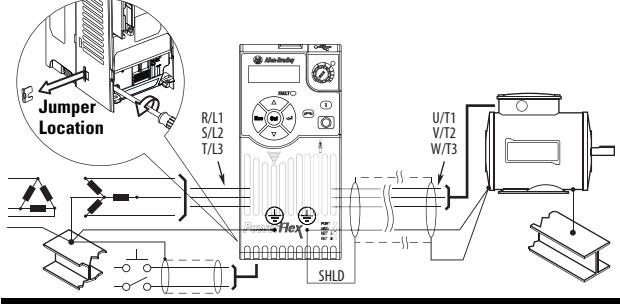
Control Terminal Block



IMPORTANT I/O Terminal 01 is always a stop input. The stopping mode is determined by the drive setting.
The drive is shipped with a jumper installed between I/O Terminals 01 and 11.
Remove this jumper when using I/O Terminal 01 as a stop or enable input.

- Two wire control shown. For three wire control use a momentary input  on I/O Terminal 02 to command a start. Use a maintained input  for I/O Terminal 03 to change direction.
- When using an opto output with an inductive load such as a relay, install a recovery diode parallel to the relay as shown, to prevent damage to the output.

General Grounding Requirements

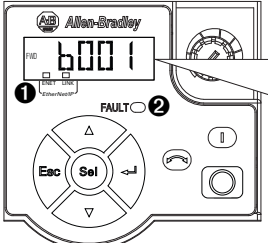


IMPORTANT The MOV to ground jumper must be removed if the drive is installed on an ungrounded (IT mains) or resistive grounded distribution system.
Tighten screw after jumper removal.

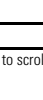
Prepare For Drive Start-Up

ATTENTION: Power must be applied to the drive to perform the following start-up procedures. Some of the voltages present are at incoming line potential. To avoid electric shock hazard or damage to equipment, only qualified service personnel should perform the following procedure. Thoroughly read and understand the procedure before beginning. If an event does not occur while performing this procedure, **Do Not Proceed. Remove All Power** including user supplied control voltages. User supplied voltages may exist even when main AC power is not applied to the drive. Correct the malfunction before continuing.

Integral Keypad



No.	Display/LED (Color)
1	ENET (Steady) – Adapter connected to network and drive controlled via Ethernet. ENET (Flashing) – Adapter connected to network but drive not controlled via Ethernet. LINK (Steady) – Adapter connected to network but not transmitting data. LINK (Flashing) – Adapter connected to network and transmitting data.
2	Fault Status (Red)

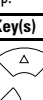
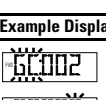
Key	Name	Key	Name
	Escape		Enter
	Up Arrow		Down Arrow
	Select		Stop

Menu	Parameter Group & Description
b	Basic Display Commonly viewed drive operating conditions.
P	Basic Program Commonly used programmable functions.
t	Terminal Blocks Programmable terminal functions.
C	Communications Programmable communication functions.
L	Logic Programmable logic functions.
d	Advanced Display Advanced drive operating conditions.
R	Advanced Program Remaining programmable functions.
f	Fault and Diagnostic Consists of list of codes for specific fault conditions.
M	Modified Functions from the other groups with values changed from default.
N	Network Network functions that are shown only when a comm card is used.
G	AppView and CustomView Functions from the other groups organized for specific applications.

Key	Name	Key	Name
	Start		Reverse
	Potentiometer		

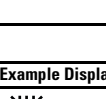
AppView Parameter Groups

The parameters in the AppView™ parameter groups can be quickly added to the CustomView™ parameter group by doing the following:

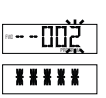
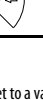
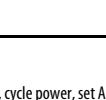
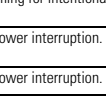
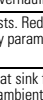
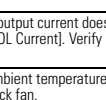
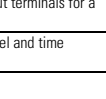
Step	Key(s)	Example Displays
1. Press the Up Arrow or Down Arrow to scroll to an AppView group (G1...G8).	 or 	
2. Press Enter or Sel to enter a group. The rightmost digit of the last viewed parameter in that group will flash.	 or 	
3. Press the Up Arrow or Down Arrow to scroll to the command G1->GC.	 or 	
4. Press Enter or Sel to add all the parameters in this AppView group to the CustomView group. The LCD display will show a confirmation.	 or 	

CustomView Parameter Group

You can copy one entire AppView parameter group to the CustomView parameter group as shown above or add individual parameters as show below.

Step	Key(s)	Example Displays
1. Press the Up Arrow or Down Arrow to scroll to the CustomView group (GC).	 or 	
2. Press Enter to view the parameters that can be added to the CustomView group.		
3. Press the Up Arrow or Down Arrow to scroll through the list of parameters.	 or 	
4. Press Enter to add the parameter to the CustomView group. The LCD display will show a confirmation.		

To delete parameters from the CustomView parameter group:

Step	Key(s)	Example Displays
1. Press the Up Arrow or Down Arrow to scroll to the CustomView group (GC).	 or 	
2. Press Enter to view the parameters that are in the CustomView group.		
3. Press the Up Arrow or Down Arrow to scroll to the command GC---	 or 	
4. Press Enter or Sel to view the parameters that are stored in the CustomView group.	 or 	
5. Press the Up Arrow or Down Arrow to scroll through the list of parameters.	 or 	
6. Press Enter to delete the parameter from the CustomView group. The LCD display will show a confirmation.		

Fault Codes

To clear a fault – press the Stop key if P045 [Stop Mode] is set to a value between 0...3, cycle power, set A551 [Fault Clear] to 1 or 2, or cycle digital input if t062, t063, t065, t068 [Digln Term Blk xx] is set to 13.

No.	Fault	Description
F000	No Fault	–
F002 ⁽¹⁾	Auxiliary Input	Check remote wiring. Verify communications programming for intentional fault.
F003	Power Loss	Monitor the incoming AC line for low voltage or line power interruption. Check input fuses. Reduce load.
F004 ⁽¹⁾	UnderVoltage	Monitor the incoming AC line for low voltage or line power interruption.
F005 ⁽¹⁾	OverVoltage	Monitor the AC line for high line voltage or transient conditions. Bus overvoltage can also be caused by motor regeneration. Extend the decel time or install dynamic brake resistor.
F006 ⁽¹⁾	Motor Stalled	Increase P041, A442, A444 or A446 [Accel Time x] or reduce load so drive output current does not exceed the current set by parameter A484 or A485 [Current Limit x]. Check for overhauling load.
F007 ⁽¹⁾	Motor Overload	An excessive motor load exists. Reduce load so drive output current does not exceed the current set by parameter P033 [Motor OL Current]. Verify A530 [Boost Select] setting.
F008 ⁽¹⁾	Heatsink OvrTmp	Check for blocked or dirty heat sink fins. Verify that ambient temperature has not exceeded the rated ambient temperature. Check fan.
F009 ⁽¹⁾	CC OvrTmp	Check product ambient temperature. Check for airflow obstruction. Check for dirt or debris. Check Fan.
F012	HW OverCurrent	Check programming. Check for excess load, improper A531 [Boost Select] setting, DC brake volts set too high or other causes of excess current.
F013	Ground Fault	Check the motor and external wiring to the drive output terminals for a grounded condition.
F015 ⁽¹⁾	Load Loss	Verify connections between motor and load. Verify level and time requirements.
F021 ⁽¹⁾	Output Ph Loss	Verify motor wiring and motor.
F029 ⁽¹⁾	Analog In Loss	An analog input is configured to fault on a signal loss. A signal loss has occurred. Check for broken/loose connections at inputs. Check parameters.
F033	Auto Rstrt Tries	Correct the cause of the fault and manually clear.
F038	Phase U to Gnd	Check the wiring between the drive and motor. Check motor for grounded phase.
F039	Phase V to Gnd	Replace drive if fault cannot be cleared.
F040	Phase W to Gnd	
F041	Phase UV Short	Check the motor and drive output terminal wiring for a shorted condition.
F042	Phase UW Short	Replace drive if fault cannot be cleared.
F043	Phase VW Short	
F048 ⁽¹⁾	Params Defaulted	The drive was commanded to write default values to EEPROM. Clear the fault or cycle power to the drive. Program the drive parameters as needed.

No.	Fault	Description
F059 ⁽¹⁾	Safety Open	Both of the safety inputs (Safety 1, Safety 2) are not enabled. Check safety input signals. If not using safety, verify and tighten jumper for I/O terminals S1, S2 and S+.
F063 ⁽¹⁾	SW OverCurrent	Verify connections between motor and load. Verify level and time requirements.
F064	Drive Overload	Reduce load or extend Accel Time.
F070	Power Unit	Check maximum ambient temperature has not been exceeded. Cycle power. Replace drive if fault cannot be cleared.
F071	DSI Net Loss	Cycle power. Check communications cabling. Check Modbus or DSI setting. Check external network status.
F072	Opt Net Loss	Cycle power. Check communications cabling. Check network adapter setting. Check external network status.
F073	EN Net Loss	Cycle power. Check communications cabling. Check EtherNet/IP setting. Check external network status.
F080	Autotune Failure	The autotune function was either cancelled by the user or failed. Restart procedure.
F081	DSI Comm Loss	Cycle power. Check communications cabling. Check Modbus or DSI setting. Check Modbus or DSI status. Modify using C125 [Comm Loss Action]. Connecting I/O terminals C1 and C2 to ground may improve noise immunity. Replace wiring, Modbus master device or control module.
F082	Opt Comm Loss	Cycle power. Reinstall option card in drive. Modify using C125 [Comm Loss Action]. Replace wiring, port expander, option card or control module.
F083	EN Comm Loss	Cycle power. Check EtherNet/IP setting. Check drive's Ethernet settings and diagnostic parameters. Modify using C125 [Comm Loss Action]. Replace wiring, Ethernet switch or control module.
F091	Encoder Loss	Check Wiring. If P047, P049 or P051 [Speed Reference] = 16 "Positioning" and A535 [Motor Fdbk Type] = 5 "Quad Check", swap the Encoder channel inputs or swap any two motor leads. Replace encoder.
F094	Function Loss	Close input to the terminal and cycle power.
F100	Parameter Chksum	Set P053 [Reset to Defaults] to 2 "Factory Rset".
F101	External Storage	Set P053 [Reset to Defaults] to 2 "Factory Rset".
F105	C Connect Err	Clear fault and verify all parameter settings. Do not remove or install the control module while power is applied.
F106	Incompat C-P	The control module could not recognize the power module. Cycle power. Flash with new firmware version. Replace drive if fault cannot be cleared.
F107	Replaced C-P	The control module was mounted to a power module with a different power rating. Set P053 [Reset to Defaults] to any of the reset options.
F109	Mismatch C-P	The control module was mounted to a different drive type power module. Set P053 [Reset to Defaults] to any of the reset options.
F110	Keypad Membrane	Keypad membrane failure/disconnected. Cycle power. Replace control module if fault cannot be cleared.
F111	Safety Hardware	Safety input enable hardware malfunction. One of the safety inputs is not enabled. Check safety input signals. If not using safety, verify and tighten jumper for I/O terminals S1, S2 and S+.
F114	uC Failure	Cycle power. Replace control module if fault cannot be cleared.
F122	I/O Board Fail	Cycle power. Replace drive or control module if fault cannot be cleared.
F125	Flash Update Req	Perform a firmware flash update operation to attempt to load a valid set of firmware.
F126	NonRecoverablErr	Clear fault or cycle power to the drive. Replace drive or control module if fault cannot be cleared.
F127	DSIFlashUpdatReq	Perform a firmware flash update operation using DSI communications to attempt to load a valid set of firmware.

⁽¹⁾ These faults may be cleared by the auto-restart routine.

Specifications

Input/Output Ratings	Approvals
Output Frequency: 0...500 Hz (Programmable) Efficiency: 97.5% (Typical)	      LMV Directive 2006/95/EC; EN 61800-5-1 EMC Directive 2004/108/EC; EN 61800-3:2004 AC156 KCC: Article 58-2 of Radio Waves Act, Clause 3 GOST-R: POCC US.ME92.H00040 
Digital Control Inputs (Input Current = 6 mA)	Analog Control Inputs
SRC (Source) Mode: 18...24V = ON 0...6V = OFF	SNK (Sink) Mode: 0...6V = ON 18...24V = OFF
4-20 mA Analog: 250 Ω input impedance 0-10V DC Analog: 100 kΩ input impedance External Pot: 1...10 kΩ, 2 W min.	
Control Output	
Programmable Output, Form A and Form B Resistive Rating: 3.0 A @ 30V DC, 125V AC and 240V AC Inductive Rating: 0.5 A @ 30V DC, 125V AC and 240V AC	Opto Outputs 30V DC, 50 mA Non-inductive
	Analog Outputs (10-bit) 0-10V: 1 kΩ min. 4-20 mA: 525 Ω max.
Fuses and Circuit Breakers	
Recommended Fuse Type: UL Class J, T or Type BS88; 600V (550V) or equivalent. Recommended Circuit Breakers: HMCP or equivalent.	
Protective Features	
Motor Protection: I ² t overload protection – 150% for 60 s, 200% for 3 s (Provides Class 10 protection) Overcurrent: 200% hardware limit, 300% instantaneous fault	
Over Voltage: 100...120V AC Input – Trip occurs @ 405V DC bus voltage (equivalent to 150V AC incoming line) 200...240V AC Input – Trip occurs @ 405V DC bus voltage (equivalent to 290V AC incoming line) 380...480V AC Input – Trip occurs @ 810V DC bus voltage (equivalent to 575V AC incoming line) 525...600V AC Input – Trip occurs @ 1005V DC bus voltage (equivalent to 711V AC incoming line)	
Under Voltage: 100...120V AC Input – Trip occurs @ 190V DC bus voltage (equivalent to 75V AC incoming line) 200...240V AC Input – Trip occurs @ 190V DC bus voltage (equivalent to 150V AC incoming line) 380...480V AC Input – Trip occurs @ 390V DC bus voltage (equivalent to 275V AC incoming line) 525...600V AC Input – If P038 = 3 "600V" trip occurs @ 487V DC bus voltage (344V AC incoming line); – If P038 = 2 "480V" trip occurs @ 390V DC bus voltage (275V AC incoming line)	
Control Ride Through: Minimum ride through is 0.5 s - typical value 2 s Faultless Power Ride Through: 100 ms	

Rockwell Automation Support

Rockwell Automation provides technical information on the Web to assist you in using its products.
At <http://www.rockwellautomation.com/support/>, you can find technical manuals, a knowledge base of FAQs, technical and application notes, sample code and links to software service packs, and a MySupport feature that you can customize to make the best use of these tools.
For an additional level of technical phone support for installation, configuration, and troubleshooting, we offer TechConnect support programs. For more information, contact your local distributor or Rockwell Automation representative, or visit <http://www.rockwellautomation.com/support/>.

Installation Assistance

If you experience a problem within the first 24 hours of installation, review the information that is contained in this manual.
You can contact Customer Support for initial help in getting your product up and running.

United States or Canada	1.440.646.3434
Outside United States or Canada	Use the Worldwide Locator at http://www.rockwellautomation.com/support/americas/phone_en.html , or contact your local Rockwell Automation representative.

New Product Satisfaction Return

Rockwell Automation tests all of its products to ensure that they are fully operational when shipped from the manufacturing facility.
However, if your product is not functioning and needs to be returned, follow these procedures.

United States	Contact your distributor. You must provide a Customer Support case number (call the phone number above to obtain one) to your distributor to complete the return process.
Outside United States	Please contact your local Rockwell Automation representative for the return procedure.

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