

BlueBoard-LPC11U24/37

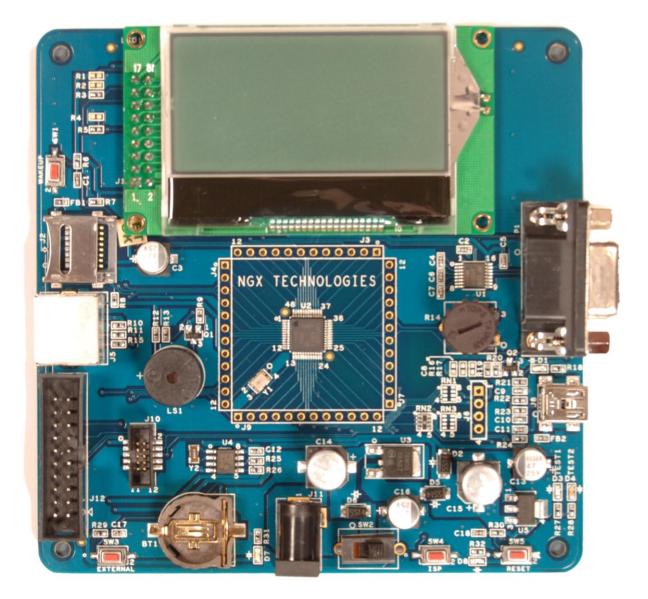


Fig. 1



About NGX Technologies

NGX Technologies is a premier supplier of development tools for the ARM7, ARM Cortex M0, M3 and M4 series of microcontrollers. NGX provides innovative and cost effective design solutions for embedded systems. We specialize in ARM MCU portfolio, which includes ARM7, Cortex-M3, M0 & M4 microcontrollers. Our experience with developing evaluation platforms for NXP controller enables us to provide solutions with shortened development time thereby ensuring reduced time to market and lower development costs for our customers. Our cost effective and feature rich development tool offering, serves as a testimony for our expertise, cost effectiveness and quality.

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CE certification

NGX Technologies BLUEBOARD-LPC11U24/37 board have been tested for radiated emission as per EN55022 class A standard. The device is under the limits of the standard EN55022 class A and hence CE marked. No other test have been conducted other than the radiated emission (EN55022 class A standard). The device was tested with the ports like USB, Serial, and Power excluding the GPIO ports. Any external connection made to the GPIO ports may alter the EMC behaviour. Usage of this device under domestic environment may cause unwanted interference with other electronic equipment's. User is expected to take adequate measures. The device is not intended to be used in and end product or any subsystem unless the user re-evaluates applicable directive/conformance.



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1.0 INTRODUCTION

This document is the User Manual for the BLUEBOARD-LPC11U24/37, a low cost ARM Cortex-M0 based board by NGX Technologies. This document reflects its contents which include system setup, debugging, and software components. This document provides detailed information on the overall design and usage of the board from a systems perspective.

Before proceeding further please refer the quick start guide for BLUEBOARD-LPC11U24/37 features and BLUEBOARD-LPC11U24/37 verification.

For BLUEBOARD-LPC11U24/37 Quick Start Guide: Click here.

For the most updated information on the BLUEBOARD-LPC11U24 board please refer to NGX'website.

For the most updated information on the BLUEBOARD-LPC11U37 board please refer to NGX'website.



2.0 BLUEBOARD-LPC11U24/37 Development Tool Setup

2.1 IDE and debugger

As mentioned in the earlier section, NGX's MCU evaluation platforms are not coupled tightly with any one particular combination of IDE and debugger. The following sections will explain the setup for KEIL and ULINK as the IDE and debugger respectively.

2.2 Installation & Configuration of KEIL software

The Installation of KEIL software is explained below:

Note: We have used **Keil uvision version 4.23** while creating the User manual for this evaluation kit. Please ensure that you are using uvision version 4.23 or above.

Step 1: Open the keil setup

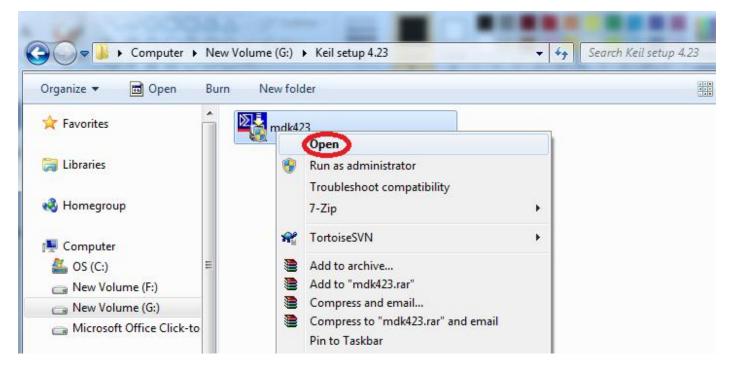


Fig. 2

User Manual: BlueBoard-LPC11U24/37



Step 2: Keil µvision4.23 information Click on Next

Setup MDK-ARM V4.23	×
Welcome to Keil μVision Release 12/2011	
This SETUP program installs: MDK-ARM V4.23 This SETUP program may be used to update a previous pr However, you should make a backup copy before proceed It is recommended that you exit all Windows programs befor Follow the instructions to complete the product installation.	ling.
— Keil µVision4 Setup ————————————————————————————————————	<< Back Next >> [Cancel]

Fig. 3

Step 3: Terms & conditions

Setup MDK-ARM V4.23
License Agreement Please read the following license agreement carefully.
To continue with SETUP, you must accept the terms of the License Agreement. To accept the agreement, click the check box below.
END USER LICENCE AGREEMENT FOR MDK-ARM THIS END USER LICENCE AGREEMENT ("LICENCE") IS A LEGAL AGREEMENT BETWEEN YOU (EITHER A SINGLE INDIVIDUAL, OR SINGLE LEGAL ENTITY) AND ARM LIMITED ("ARM") FOR THE USE OF THE SOFTWARE ACCOMPANYING THIS LICENCE. ARM IS ONLY WILLING TO LICENSE THE SOFTWARE TO YOU ON CONDITION THAT YOU ACCEPT ALL OF THE TERMS IN THIS LICENCE. BY CLICKING "I AGREE" OR BY INSTALLING OR OTHERWISE USING OR COPYING +
 ✓ If agree to all the terms of the preceding License Agreement — Keil μVision4 Setup << Back Next >> Cancel

Fig. 4

User Manual: BlueBoard-LPC11U24/37



Step 4: Provide the destination path and Click on Next

Setup MDK-ARM V4.23	
Folder Selection Select the folder where SETUP will install files.	
SETUP will install $\mu Vision4$ in the following folder.	
To install to this folder, press 'Next'. To install to a diff folder. Destination Fuldor UC:\Keil	erent folder, press 'Browse' and select another BIowse
— Keil µVision4 Setup ————————————————————————————————————	<< Back Next >> Cancel



Step 5: Fill your Personal information and Click on Next

Setup MDK-ARM V4.2	3	×
Customer Informal Please enter your		
	name, the name of the company for whom you	work and your E-mail address.
First Name:	abc	
Company Name:	NGX Technologies Pvt Ltd	/
E-mail: — Keil μVision4 Setup	abc@ngxtechnologies.com	
	<	K Back Next >>> Cancel

Fig. 6

Step 5: Click on Next



		×
	Tools t	™ by ARM
	1	
•		
		EXECUTION

Fig. 7

Step 6: Keil $\mu Vision 4.23$ setup is completed. Click on Finish

Setup MDK-ARM V4.23	×
Keil µVision4 Setup completed MDK-ARM V4.23	
μVision Setup has performed all requested operations successfully. ✓ Launch Driver Installation: "ULINK Pro Driver V1.0"	
☑ Show Release Notes.	
— Keil µVision4 Setup ————————————————————————————————————	
<< Bac	k Finish Cancel

Fig.8



2.3 Setup for ULINK2 and BLUEBOARD-LPC11U24/37 Board

The BlueBoard-LPC11U24/37 board has on board 20 pin SWD box, the ULINK2 is not a part of the BlueBoard-LPC11U24/37 package, user need to buy separately.

To run the BlueBoard-LPC11U24/37 examples you need the following components and the image shows the each components:

- ULINK2
- BlueBoard-LPC11U24/37 Board
- USB type-B cable



Fig. 9

Connections of components are as shows in the following image.



Fig. 10

The above setup is ready to use for development in Keil IDE



2.4 Configuration of ULINK2 Debugger

The configuration flow of ULINK2 Debugger is explained below:

Step 1: Open the Keil Workspace then by clicking on the **target** option, the window opens as shown below. Next click on Debug option and select the ULINK2 debugger as shown in the image.

🔣 Options for Target 'Blinky'	
Device Target Output Listing User C/C++ Asm	Linker Debug Utilities
C Use Simulator Settings	Use ULINK2/ME Cortex Debugger Settings
Load Application at Startup Run to main() Initialization File:	Load Application at Startup Initialization File: VFLASH.ini Edit
Restore Debug Session Settings Preakpoints Watch Windows & Performance Analyzer Memory Display	Restore Debug Session Settings Breakpoints Watch Windows Memory Display
CPU DLL: Parameter: SARMCM3.DLL	Driver DLL: Parameter: SARMCM3.DLL
Dialog DLL: Parameter: DARMP1.DLL pLPC11U24	Dialog DLL: Parameter: TARMP1.DLL pLPC11U24
ОК Са	ncel Defaults Help

Fig.11

Step 2: Click on the settings option, the Cortex-M Target Driver Setup window opens then select SW port. After selection of the SW port the ULINK2 detected is as shown in the image below

Use Simulator	Settings 🔍 Use: ULINK2/ME Cortex Debugger 💌 Settings
ortex-M Target Driver Setup	
Debug Trace Rash Download	
ULINK USB - JTAG/SW Adapter-	SW Device
Serial No: V0168AVR	IDCODE Device Name
ULINK Version: ULINK2	SWDIC Ox0BB11477 ARM CoreSight SW-DP
Device Family: Cortex-M	Dow
Firmware Version: V1.42	Automatic Detection ID CODE:
💌 SWJ Pitt SW 🔍	C Manual Conïguration Device Name:
Max Clock: 1MHz 💌	Add Delete Update IR len:
Debug	Casha Oritina Davialard Oritina
Connect & Reset Options Connect: Normal V Re	set: Autodetect Cache Options Download Options set: Autodetect Verify Code Download
Reset after Connect	Cache Memory Developed to Each

Fig.12



Step 3: Click on Utilities and select ULINK2 Cortex Debugger as shown below

🛛 Options for Ta	rget 'Blinky'	×
Device Target	Output Listing User C/C++ Asm Linker Debug Utilities	
Configure Flash	n Menu Command	
Use Targe	t Driver for Flash Programming	
•	1ULINK2/ME Cortex Debugger 💽 Settings 🔽 Update Target before Debugging	
Init File:	Edit	
O Use Extern	nal Tool for Flash Programming	
Command:		
Arguments:		
	🗖 Run Independent	
	OK Cancel Defaults Help	

Fig.13

Step 4: By Clicking on Settings the Cortex-M Target Driver Setup window opens, Click on Add to select the flash as shown below

Options for Target 'Blinky'				
Device Target Output Listing User C/C++ Asm Configure Rash Menu Command © Use Target Driver for Rash Programming ULINK2/ME Cortex Debugger	Linker Debug Utilities Settings IV Update Target t	before Debugging		
Cortex-M Target Driver Setup Debug Trace Flash Download	Add Flash Programming Algorit	hm		x
Download Function ○ Erase Full Chip ♥ Program ● Erase Sectors ♥ Verify ○ Do not Erase ♥ Reset and Run Programming Algorithm □ □ Description □ □ Device Type □	Description LM4Fxxx 64kB Flash LPC122x IAP 128kB Flash LPC11xx/13xx IAP 16kB Flash LPC11xx/13xx IAP 24kB Flash LPC11xx/13xx IAP 24kB Flash LPC122x IAP 48kB Flash LPC122x IAP 80kB Flash LPC122x IAP 80kB Flash LPC12x IAP 96kB Flash LPC12x IAP 96kB Flash LPC17xx IAP 256kB Flash LPC17xx IAP 256kB Flash LPC17xx IAP 32kB Flash LPC17xx IAP 512kB Flash LPC17x IAP 512kB Flash LPC17x IAP 512kB Flash LPC17x IAP 512kB Flash LPC17x IAP 512kB Flash	Device Type On-chip Flash On-chip Flash	Device Size 64k 128k 16k 24k 48k 64k 8k 80k 96k 128k 256k 32k 512k 64k 256k	* ·
	Add	Cancel		

Fig.14

Click OK to complete the ULINK2 Debugger configuration



3.0 BLUEBOARD-LPC11U24/37 Software Development

3.1 Executing the sample projects

The sample projects are provided with the available kit.

Steps to execute the sample projects:

Step 1: Open the project folder.

Step 2: Then open the file **project_**name.uvproj eg blinky.uvproj.

🔓 C:\Work\ngx\Blueboard_I	LPC11U24\BLUE	BOARD_LPC11U24_Documents	\BLUEBOARD_LPC11U24_Documents\B	lue B	
File Edit View Favorites	<u>T</u> ools <u>H</u> elp				
🕞 Back + 🕑 + 🏄 🎝	🔎 Search 🌔	Folders 🔃 🔞 Folder S	ync		
Address 🔁 C:\Work\ngx\Blueb	oard_LPC11U24\BL	.UEBOARD_LPC11U24_Documents\E	LUEBOARD_LPC11U24_Documents(Blue Boar	d_LPC11U24\Source_programs\BLUEBOARD_L	LPC11U24_KEIL_with_GLCD\Blinky\Keiworkspace
File and Folder Tasks	*	Lst	Cbj	blinky.uvgui.IVSX12 NGX12 Fie 146 KB	blinky.uvgui NGX12.bak BAK File 146 KB
Other Places	*) binky.uvopt	binky.uvproj	blinky_Blinky.dep	blinky_uvopt.bak
🛅 Blinky 🔒 My Documents		UVOPT File 61 KB	William Project	DEP File 2 1/8	BAK File 61 KB
💡 My Computer 🔍 My Network Places	444	BAK File			
V my network mates	*	30 KB			

Fig.15

Step 3: This launches the IDE

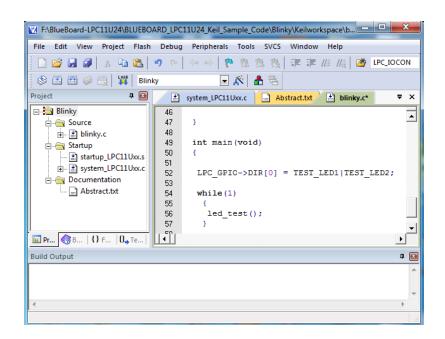


Fig.16



Step 4: Click on Build to build the project as shown in the below image

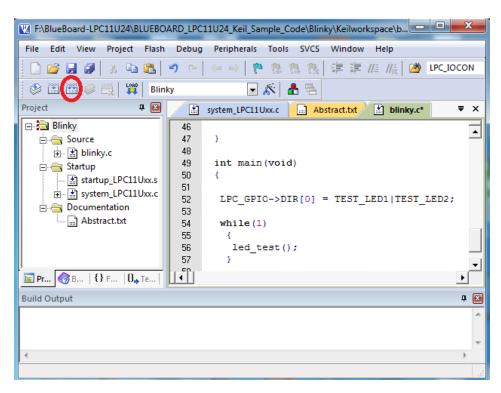


Fig. 17

Step 5: Click on Load to download as shown in the below image

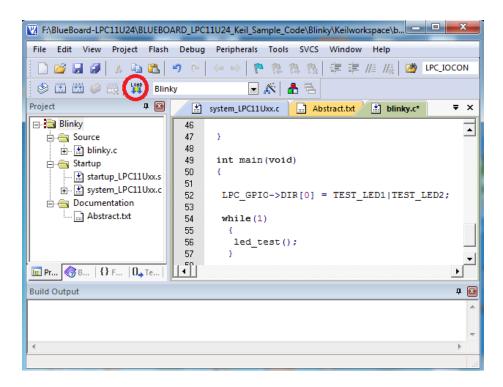


Fig. 18



Step 6: To debug the code click on Debug option then click on Start/Stop Debug session as shown in the below image. Press F5 to free run or press F10 to line by line debug.

F:\BlueBoard-LPC11U24\BLUEBO		Peripherals Tools SV		space\b
		Start/Stop Debug Session	Ctrl+F5	E //2 DC_IOCON
🕸 🏥 🕮 🧼 👯 🛙 Blin	k RST	Reset CPU		
Project 🛛 🗜 🔳		Run	F5	🖹 blinky.c* 🛛 🔻 >
🖃 🔒 Blinky	0	Stop		
ia	{ ¹ }	Step	F11	
E- Startup	9.	Step Over	F10	
startup_LPC11Uxx.s	{}-	Step Out	Ctrl+F11	
	-*{}	Run to Cursor Line	Ctrl+F10	ED1 TEST_LED2;
🖮 🔄 Documentation	\$	Show Next Statement		_
Abstraction		Breakpoints	CtrI+B	
	•	Insert/Remove Breakpoint	F9	
	0	Enable/Disable Breakpoint	Ctrl+F9	
E Pr	0	Disable All Breakpoints		•
Build Output		Kill All Breakpoints	Ctrl+Shift+F9	P (
		OS Support	Þ	
		Execution Profiling	+	
<		Memory Map		Þ
Enter or leave a debug session		Inline Assembly		

Fig. 19

3.2 Creating New project

Follow the below steps, for creating new project:

Step 1: Open the keil IDE.

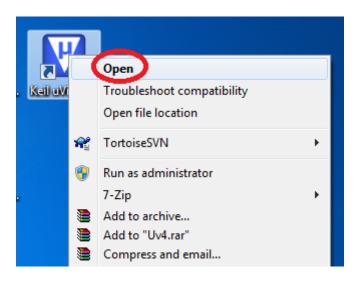


Fig. 20



Step 2: Click on to the Project tab – new uvision project.

👿 μVision4	
File Edit View 💽	oject Flash Debug Peripherals Tools SVCS Window Help
i 🗋 😂 🖌 🗿 🗖	New µVision Project
🖉 🖾 🖉 🥥	New Multi-Project Workspace
Project	Open Project Close Project
	Export Manage
	Select Device for Target Remove Item
S.	Coptions
	Clean target
 ■ Pr 🧑 B {]	
	Rebuild all target files
Build Output	Batch Build

Fig. 21

Step 3: Give project name then click Save.

Create New Project		-				×
🕞 🕞 🗢 📔 🕨 New folder	_	•	4 9	Search New fold	der	٩
Organize 🔻 New folder					-	0
☆ Favorites	-	Name		^		Date
Nesktop	=		No	items match your	search.	
bownloads	=					
🔚 Recent Places						
🧊 Libraries						
🤣 Homegroup						
💻 Computer						
🚨 OS (C:)	-	•				P.
File name: blinky						-
Save as type: Project Files (*.uvproj)						-
) Hide Folders				Save	Canc	el

Fig. 22



Step 4: Select the controller.

Note: Both LPC11U24 and LPC11U3	' are pin and binary co	mpatible; we can select	LPC11U24 device
for BB-LPC11U37.			

Select Device for Target 'Target 1'	x
CPU Vendor: NXP (founded by Philips) Device: LPC11U24/401 Toolset: ARM	
Data base Description: Image: Description in the state of the st	
Cancel Help)

Fig. 23

Step 5: Go to file – new, & start writing the code.

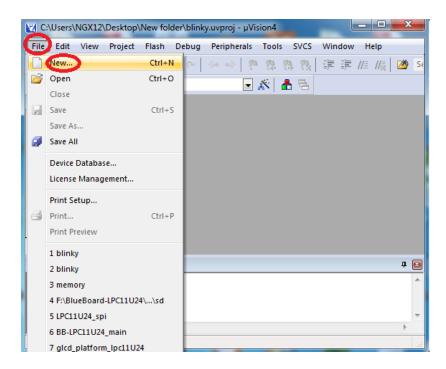


Fig. 24



Step 6: Save the file with some name.

🛛 Save As	other state of the	×
🔾 🖯 📕 🕨 New folder	✓ 4 Search New	folder 🔎
Organize 👻 New folder		H • 📀
🔆 Favorites	Name	Dat
🔜 Desktop	blinky.plg	21-
〕 Downloads	■ ■ blinky	21-
📃 Recent Places	blinky_Target 1.dep	21-
🥽 Libraries	ism startup_LPC11Uxx	17-
📜 Computer		
🙇 OS (C)))
File names <mark>(blinky.c</mark> Save as type: All Files (*.*)		•
Hide Folders	Save	Cancel

Fig. 25

Step 7: Add the file to the source group as shown in the below image.

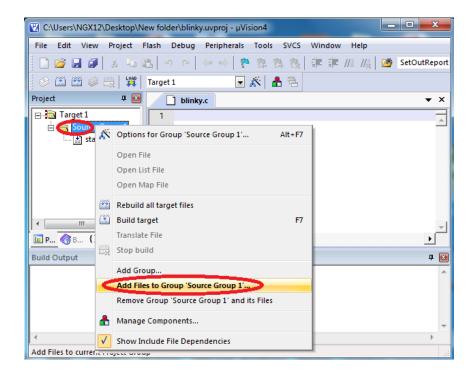




Fig. 26

Add Files to Group 'Source Group 1'		x
Look in: 🌗 New folder 💌	← 🗈 💣 📰 ◄	
Name	Date modified	Ту
blinky	20-06-2012 11:18	С
•]	P.
File name: blinky	Add	
Files of type: C Source file (*.c)	▼ Close	

Step 8: Select the file and click on Add as shown in the below image.

Fig. 27

Step 9: To build, download and debug follow the steps 4, 5 and 6 in section 3.1.

3.3 Creating Bin File

For creating bin file follow the below steps:

Step 1: Open the project & click 'Target Options' and a window will appear.

👿 Options	for Targe	et 'Blinky'		-	-	-	-		×
Device	Target 0	utput Listing	User C/C++	Asm	Linker	Debug l	Jtilities		
NXP (founded by Philips) LPC11U24/401 Xtal (MHz): Code Generation									
Operating	system:	None		•			Nodule Optimizat		
System-V	iewer File	(.Sfr):			U:	e MicroLl	вГ	Big Endian	
SFD\NX	P\LPC11	Jook/LPC11Uxx.	SFR						
	Only Memo	•					iory Areas		
default	off-chip	Start	Size	Startup	default	off-chip	Start	Size	Nolnit
	ROM1:			0		RAM1:			
	ROM2:			0		RAM2:			
	ROM3:			0		RAM3:			
	on-chin		_			on-chip			
	IROM1:	0x0	0×8000	6	•	IRAM1:	0x10000000	0x2000	
	IROM2:			0		IRAM2:			
		[ок	Can	cel	Defa	ults		Help



Fig.	28
115.	40

Step 2: Check the device & the start address of IROM1 should be 0x0.

Step 3: Then go to the User tab & insert the below line in the Run #1:

fromelf --bin "./Obj/file.axf" --output "./Obj/file.bin"

💟 Options for Target 'Blinky'
Device Target Output Listing User C/C++ Asm Linker Debug Utilities
Run User Programs Before Compilation of a C/C++ File
Run #1: DOS16
□ Run #2: □ DOS16
∼ Run User Programs Before Build/Rebuild
□ Run #1: □ DOS16
□ Run #2: □ DOS16
Run User Programs After Build/Rebuild
Run #1: fromelf -bin ".\Obj\Blinky.axf" -output ".\Obj\Blinky.bin"
□ Run #2: □ DOS16
Image: When Complete □ Start Debugging
OK Cancel Defaults Help

Fig. 29

Step 4: Click on the Linker tab & select the 'Use Memory Layout from Target Dialog', then click ok and build the project, finally .bin file will be created.

Options for Target 'Blinky'	×
Device Target Output Listing User	C/C++ Asm Linker Debug Utilities
Use Memory Layout from Target Dialog	
Make RW Sections Position Indep Make RO Sections Position Indep Don't Search Standard Libraries Report 'might fail' Conditions as Err	endent R/W Base 0x10000000
Scatter File	Edit
Misc controls	*
	type=microlib -strict -scatter ",\Obj\Blinky.sct" ▲ narysizes -map -xref -callgraph -symbols ▼
	K Cancel Defaults Help

Fig. 30



Note: For newly built bin file you should update crc. Refer 6.0 Trouble Shooting for more details.

4.0 BLUEBOARD-LPC11U24/37 Programming

4.1 Programming options

BLUEBOARD-LPC11U24/37 can be programmed using the

- On-chip bootloader (USB or UART)
- Debugger (ULINK2)

4.1.1 On-Chip bootloader (USB or UART)

In order to program the board either through USB or UART we need to get the board under programming mode.

Getting the board in programming mode:

Theory: The On-chip bootloader looks for a logic LOW to be present on a pre-defined PIN (ISP pin) during reset. If the ISP pin is held LOW and reset signal is provided to the MCU, the MCU enters into programming mode.

Practical:

On the BLUEBOARD-LPC11U24/37 the RESET and ISP signals are connected to buttons provided on the board. Look for the RESET and ISP marking on the board. Therefore to enter into programming mode:

- A **Press and hold** the ISP button
- \checkmark Press the RESET button and release it
- \checkmark Now release the ISP button
- \checkmark The board is in the programming mode

We know that the on-chip bootloader can be used with USB or UART. Please note that if you have connected a USB cable to the board the USB bootloader is activated else the UART bootloader is activated. Meaning, if you have connected the USB cable as your power source then you cannot use UART bootloader, you need to use an alternate external power source (DC jack) to enable UART bootloader. If a particular MCU supports USB bootloading it is highly recommended to use the same for programming.

Programming through USB is the most convenient way to program the BlueBoard-LPC11U24. The LPC11U24 has an on-chip USB bootloader support which makes programming the board very simple. You don't require any PC application to program using USB bootloader. Once the board enters the programming mode it appears as a drive on your Windows machine and all you need to do is just dragn-drop your binary to this drive.

Note: Not all NXP USB MCUs support USB boot loading. For example the LPC11U14 does not support USB bootloader although it has support for USB on the chip.



4.1.2 Flashing the board using USB

The pre-build binaries can be used to flashing onto to the board for each peripheral by using the USB bootloader as a Mass storage device. Press SW4, then SW5; release SW5, then SW4, the mass storage device will appear on your screen. On the board LED D1 glows. Remove firmware.bin file and then place your bin file and then press reset switch to execute the specific code written on to the flash.

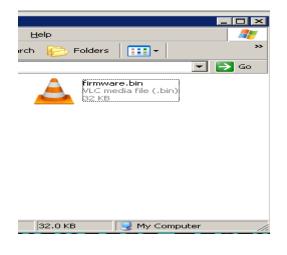


Fig. 31

Flashing the bin file (Drag & drop).



Fig. 32

Note: For newly built bin file you should update crc. Refer 6.0 Trouble Shooting for more details.



4.2 Flashing the Hex file through UART

Step 1: Connect the serial cable to the PC as well as to the board UART0 and open the flash magic tool.

Step 2: Input all the parameters as shown in below Fig.

🏶 Flash Magic	- NON PRODUCTION US	E ONLY			
<u>File ISP Option</u>	s <u>T</u> ools <u>H</u> elp				
🖻 🗟 🔍 🎯	🐗 🗸 🎩 🔈 😻 [💐 🕜 😂			
Step 1 - Communi	cations	Step 2 - Era	se		
Select Device	LPC11U24/401			00-0x000FFF)	^
COM Port:	СОМ 1 🛛 🖌	Erase block	2 (0x0020	00-0x001FFF) 00-0x002FFF)	
Baud Rate:	9600 💌	Erase block	4 (0x0040)	00-0x003FFF) 00-0x004FFF)	
Interface:	None (ISP) 🛛 🗸			00-0x005FFF)	
Oscillator (MHz):	12	Erase all F	cks used b		
Step 3 - Hex File Hex File: C:\Work\ngx\Blueboard_LPC11U24\BLUEBOARD_LPC11U24_D Browse Modified: Monday, November 28, 2011, 7:38:36 PM more info					
Step 4 - Options		Ste	p 5 - Start!		
 ✓ Verify after programming ✓ Fill unused Flash ✓ Gen block checksums ✓ Execute 					
Technical on-line a	articles about 8051 and XA pro	gramming			
www.esacademy.e	com/fag/docs				•
			0 (

Fig. 33

Step 3: Click **Star**t to flash the hex file. Press Reset to run.

NOTE: Make sure that the Board is not powered through USB.



5.0 Schematic & Board Layout

5.1 Schematic

This manual will be periodically updated, but for the latest documentations please check our <u>website</u> for the latest documents. The Board schematic and sample code are available after the product has been registered on our website.

5.2 Board layout

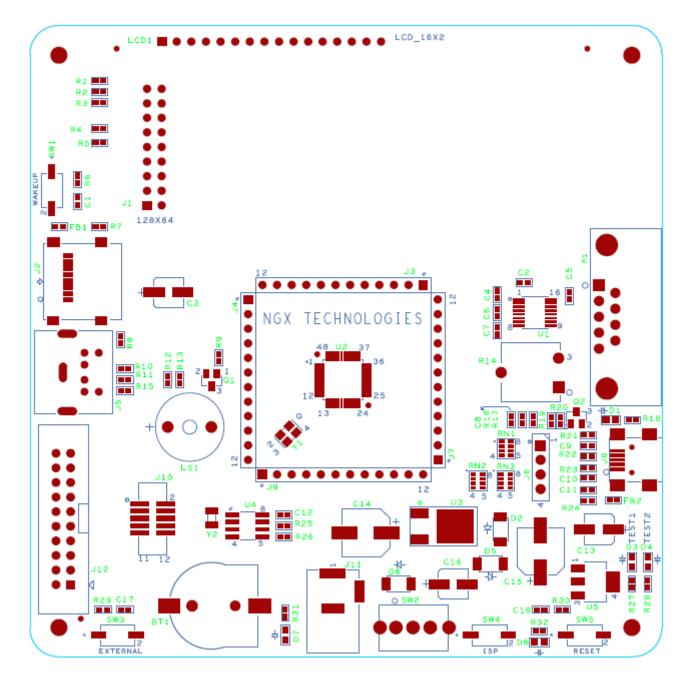


Fig. 34



6.0 Trouble Shooting

For newly created bin file you should update crc.

Unfortunately, the checksum generated is not correct and unless the checksum of the .bin file is modified, the firmware will be rejected by the USB bootloader. Thankfully, this is relatively easy to fix. There is free utility to fix the checksum. A pre-compiled version for Windows (named lpcrc.exe) is also located in the root folder. To fix the checksum, simply go into the command-line and go to the root folder where both the lpcrc.exe tool and your .bin file are located (the file will be named 'firmware.bin' unless you have modified the Makefile), and enter the following command:

Fixing the firmware.bin Checksum

lpcrc firmware.bin

🔤 C:\WIND0W5\system32\cmd.exe				
Directory of C:\Work\ngx\Blueboard_LPC11U24\BLUEBOARD_LPC11U24_Documents\BLUEBO				
ARD_LPC11U24_Documents\Blue Board_LPC11U24\Source_programs\BLUEBOARD_LPC11U24_KE				
IL_with_GLCD\Blinky\Keilworkspace\Obj				
12/09/2011 05:51 PM <dir> .</dir>				
12/09/2011 05:51 PM <dir></dir>				
12/09/2011 05:51 PM 16.112 Blinky.axf				
12/09/2011 05:51 PM 1,300 Blinky.bin				
12/08/2011 12:49 PM 31,238 blinky.crf				
12/08/2011 12:49 PM 366 blinky.d				
12/09/2011 05:51 PM 3,717 Blinky.hex				
12/09/2011 05:51 PM 15,275 Blinky.htm				
12/09/2011 05:51 PM339 Blinky.lnp				
12/08/2011 12:49 PM 33.624 blinky.o				
12/09/2011 05:51 PM 572 Blinky.plg				
10/10/2011 05:08 PM 479 Blinky.sct				
12/09/2011 05:51 PM 1,089 Blinky.tra				
11/09/2011 05:04 PM 19 ExtDll.iex				
03/22/2011 12:49 PM 47,342 lpcrc.exe				
12/08/2011 12:49 PM 4,344 startup_LPC11Uxx.o 12/08/2011 12:49 PM 34.458 system lpc11uxx.crf				
12/08/2011 12:49 PM 34,458 system_lpc11uxx.crf 12/08/2011 12:49 PM 456 system_lpc11uxx.d				
12/08/2011 12:49 PM 37,340 system_lpc11uxx.o				
12/06/2011 12:47 IN 57,540 System_1pt110xx.0 17 File(s) 228.070 bytes				
2 Dir(s) 22.316,539.904 bytes free				
2 DITS/ 22,510,537,701 Bytes 1166				
C:\Work\ngx\Blueboard_LPC11U24\BLUEBOARD_LPC11U24_Documents\BLUEBOARD_LPC11U24_D				
ocuments\Blue Board_LPC11U24\Source_programs\BLUEBOARD_LPC11U24_KEIL_with_GLCD\B				
linky\Keilworkspace\Obj}lpcrc Blinky.bin				
succesfully undated crc to: effff9b3				

Fig. 35



7.0 CHANGE HISTORY

7.1 Change History

Rev	Changes	Date (dd/mm/yy)	Ву
1.0	Initial release of the manual	18/06/2012	Veeresh Tumbaragi

8.0 REFERENCES

In addition to this document, the following references are included on the NGX BLUEBOARD-LPC11U24/37 product and can also be downloaded from <u>www.ngxtechnologies.com</u>:

• NGX BLUEBOARD-LPC11U24/37 schematic for the Development board.

Additional references include:

- Information on development tool being used:
 - Keil uvision 4.23, <u>http://www.keil.com/download/product/</u>
 - Flash magic, http://www.flashmagictool.com/

About this document:

Revision History

Version: V1.0 author: Veeresh Tumbaragi

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