The ERC32 GNU Cross-Compiler System

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European Space Agency jgais@ws.estec.esa.nl The ERC32 GNU cross-compiler system

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1 Introduction

1.1 General

This document describes the ERC32 GNU cross-compiler system version 2.0.6. Discussions are provided for the following topics:

- contents and directory structure of ERC32CCS
- compiling and linking ERC32 applications
- · usage of SIS and MKPROM
- debugging ERC32 application with GDB/SIS

The ERC32 GNU cross-compiler system is a multi-platform development system based on the GNU family of freely available tools with additional 'point' tools developed by Cygnus, OAR and ESTEC. The ERC32CCS consists of the following packages:

- EGCS/GCC C/C++ compiler
- GNAT Ada95 compiler
- GNU binary utilities
- RTEMS C/C++ real-time kernel
- Newlib standalone C-library
- SIS ERC32 simulator
- GDB debugger with ERC32 remote debugging monitor (rdbmon)
- DDD graphical front-end for GDB
- MKPROM boot-prom builder

1.2 News in version 2.0.7

This version of ERC32CCS contains the following changes with respect to 2.0.6:

- · Fixed memory access bug rdbmon
- Added user defined init routines in mkprom
- Minor bug fix in mkprom
- Fixed interrupt handling bug in Ada96

2 Installation and directory structure

2.1 Obtaining ERC32CCS

ERC32CCS is only distributed via anonymous ftp. The primary home of ERC32CCS is ftp://ftp.estec.esa.nl/pub/ws/wsd/erc32/erc32ccs. Two platforms are supported: SPARC Solaris-2.5.1 (or higher), and x86 linux (libc5). Sources for rtems, rdbmon and mkprom are provided with ERC32CCS, the remaining sources can be found at the usual GNU sites or at the OAR home page.

2.2 Installation on a Linux host

The ERC32CCS directory tree is compiled to reside in /usr/local/erc32 on Linux platforms. After obtaining the gzipped tarfile with the binary distribution, un-compress and un-tar it in a suitable location - if this is not /usr/local/erc32 then a link have to be created to point to the location of the ERC32CCS directory. The distribution can be installed with the following command:

```
cd /usr/local
gunzip -c erc32ccs-2.0.5-linux-tar.gz | tar xf -
```

After the compiler is installed, add /usr/local/erc32/bin to your search path.

Note: ERC32CCS is compiled on slackware-3.9 linux using libc5 libraries. To avoid problems with non-existent or outdated libc5 libraries on other systems, all binaries are statically linked.

2.3 Installation on a Solaris host

The ERC32CCS directory tree is compiled to reside in /opt/gnu/erc32 on Solaris platforms. After obtaining the gzipped tarfile with the binary distribution, un-compress and un-tar it in a suitable location - if this is not /usr/lo-cal/erc32 then a link have to be created to point to the location of the ERC32CCS directory. The distribution can be installed with the following command:

```
cd /opt/gnu
gunzip -c erc32ccs-2.0.5-solaris-tar.gz | tar xf -
```

After the compiler is installed, add /opt/gnu/erc32/bin to your search path.

2.4 Contents of /usr/local/erc32 (/opt/gnu/erc32)

The created erc32 directory with the following sub-directories:

bin executables
doc documentation
include host includes
lib host libraries
man man pages
rtems rtems libraries

rtemsnp rtems libraries (no posix) sparc-rtems target libraries (ERC32)

src various sources

2.5 ERC32CCS tools

The following tools are included in ERC32CCS:

ddd graphic X11 front-end to GDB

mkpromboot-prom builderprotoizeGNU protoize utilitysisERC32 simulator

sis64 ERC32 simulator (with 64-bit time)

sparc-rtems-ar library archiver sparc-rtems-as cross-assembler sparc-rtems-c++ C++ cross-compiler

sparc-rtems-c++filt utility to demangle C++ symbols

sparc-rtems-g++ same as sparc-rtems-c++
sparc-rtems-gasp assembler pre-processor
sparc-rtems-gcc C/C++ cross-compiler

sparc-rtems-gdb debugger with ERC32 simulator and remote target interface

sparc-rtems-gdb64 debugger with ERC32 simulator (64-bit time) sparc-rtems-gnatcmd Utility to print all GNAT command switches

sparc-rtems-gnatmake Ada make utility sparc-rtems-gnatbind Ada binder

sparc-rtems-gnatf Ada syntax checker and cross-reference generator

sparc-rtems-gnatprep Ada pre-processor sparc-rtems-gnatbl Ada bind and link sparc-rtems-gnatkr Ada file name kruncher

sparc-rtems-gnatpsta Utility to print the *Standard* package

sparc-rtems-gnatchop Ada source code splitter

sparc-rtems-gnatlink Ada linker

sparc-rtems-gnatpsys Utility to display the *System* package

sparc-rtems-gnatchp Ada source code splitter sparc-rtems-gnatls Ada library lister sparc-rtems-ld GNU linker

sparc-rtems-nm utility to print symbol table

sparc-rtems-objcopy utility to convert between binary formats sparc-rtems-objdump utility to dump various parts of executables

sparc-rtems-ranlib library sorter

sparc-rtems-size utility to display segment sizes

sparc-rtems-strings utility to dump strings from executables

sparc-rtems-strip utility to remove symbol table

unprotoize GNU unprotoize utility

2.6 Documentation

An extensive set of documentation for all tools can be found in doc and man. The following documents are provided:

aarm.pdf Annotated Ada 95 Reference Manual as.bdf Using **as** - the GNU assembler

bfd.pdf Libbfd - the binary file description

binutils.pdf The GNU binary utilities cpp.pdf The C Preprocessor

ddd.pdf DDD - The Data Display Debugger

gcc.pdf Using and porting GCC gdb.pdf Debugging with GDB

gnat_rm.pdf GNAT reference manual gnat_ug.pdf GNAT User's guide ld.pdf Using ld - the GNU linker mkprom.pdf Mkprom manual page

rtems_dev.pdf RTEMS Development environment guide

rtems_relnotes.pdf RTEMS Release notes

rtems_sparc.pdf RTEMS SPARC Applications supplement

rtems_user.pdf RTEMS C User's manual (this is the one you want!) sis.pdf SIS - SPARC instruction set simulator manual

sparcv7.pdf SPARC V7 Instruction set manual

Data sheets for the ERC32 chip-set are also provided:

mecspec.pdf MEC rev.A Device specification tsc961e.pdf TSC961 Integer Unit User's manual

tsc962e.pdf TSC962 Floating-point Unit user's manual

sysover.pdf ERC32 System overview

erc32cba.pdf ERC32 revision CBA bug list erc32cca.pdf ERC32 revision CCA bug list

The documents are all provided in PDF format, with searchable indexes. The GNU documents have embedded hyper-links and searchable document text. A free PDF viewer ('acrobat') can be downloaded from Adobe (http://www.adobe.com/).

2.7 Support

Additional information and commercial technical support for the various tools is available as follows:

rtems, gcc, newlib OAR http://www.oarcorp.com/

sis, rdbmon, mkprom J.Gaisler (ESTEC) jgais@ws.estec.esa.nl

ddd - http://www.cs.tu-bs.de/softech/ddd/

gnat ACT http://www.act-europe.fr/

gcc, gdb, newlib Cygnus Support http://www.cygnus.com/

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3 Using ERC32CCS

3.1 General development flow

The compilation and debugging of ERC32-based applications is done in the following steps:

- 1. Compile and link program with gcc
- 2. Debug program in standalone simulator (SIS) or with gdb
- 3. Debug program on remote target with gdb
- 4. Create boot-prom for a standalone application

The ERC32CCS-2.0 supports three types of applications; ordinary sequential C/C++ programs, multi-tasking real-time C/C++ programs based on the RTEMS kernel, and Ada-95 programs. Compiling and linking is done in much the same manner as with the host-based gcc and GNAT.

3.2 RTEMS applications

As of ERC32CCS-2.0, compiling and linking of RTEMS applications is done by adding the rtems compiler switch to gcc. This will instruct gcc compiler driver to add RTEMS specific include paths and libraries. To compile and link a RTEMS application, use 'sparc-rtems-gcc':

```
sparc-rtems-gcc -g -rtems -O3 rtems-hello.c -o rtems-hello.exe
```

The various compilation switches are explained in the gcc manual (gcc.pdf). The default load address is start of RAM, i.e. 0x2000000. Any load address can be specified through the -Ttext option (see gcc manual).

RTEMS is provided in two versions; with and without POSIX threads interface. If applications are written with the POSIX interface, add the -posix switch during compilation and linking:

```
sparc-rtems-gcc -posix -g -03 posix-app.c -o posix-app.exe
```

Extensive documentation on RTEMS is provided in doc/rtems user.pdf.

3.3 Sequential C-programs

Ordinary sequential C programs can be compiled without any particular switches to the compiler driver:

```
sparc-rtems-qcc -q -02 hello.c -o hello.exe
```

3.4 Ada95 programs

Compiling and linking an Ada95 program is easiest done through gnatmake:

```
sparc-rtems-gnatmake -g -03 -gnatp dais.adb -largs -qgnat -rtems -bargs -r
```

Note that the binder and linker arguments have to be provided to enable the correct libraries.

Individual units can be compiled through gcc:

```
sparc-rtems-gcc -c -g -03 -gnatp dais.adb
```

Binding and linking can also be done separately:

```
sparc-rtems-gnatbind -r dais.ali
sparc-rtems-gnatlink -qgnat -rtems -g -03 dais.ali
```

For details on how to use gnat, see the GNAT User's Manual (gnat_us.pdf) and GNAT Reference Manual (gnat_rm.pdf). ERC32 interrupts can be attached using the Ada95 interrupt_attach pragma. The ERC32 interrupts (numbered 1 - 15), are mapped on Ada interrupt 17 - 31. Avoid ERC32 interrupt 13 which is used for the real-time clock. See the irqtest program in the examples directory on how to attach interrupts. The compiler is configured for a maximum of 20 tasks and 30 mutexes. If you need a different configuration, copy src/libio/gnatinit.c to your local directory and modify it according you system requirement. To use the local file, add it to the linker arguments as follows:

```
sparc-rtems-gcc -03 -g -rtems -posix -c gnatinit.c
sparc-rtems-gnatmake -g -03 -gnatp dais.adb -largs -qgnat -rtems gnatinit.o
-bargs -r
```

The stack size of each Ada task (including the main program) is by default 10 Kbytes. This can be overridden by using the storage_size attribute on the task type used. The stack size for the main task (program) can be set in gnatinit.c. See also "Memory allocation" on page 13 for details on global memory usage.

NOTE: the Ada compiler is only provided for testing purposes, and is not by any means validated or guaranteed. A commercial, validated version is available from Ada Core Technology (http://www.acteurope.fr/).

3.5 Making boot-proms

Both sequential C-programs and RTEMS applications are linked to run from beginning of ram at address 0x2000000. To make a boot-prom that will run on a standalone target, use the mkprom utility. This will create a compressed boot image that will load the application to the beginning of ram, initiate various MEC register, and finally start the application. mkprom will set all target dependent parameters, such as memory sizes, number of memory banks, waitstates, baudrate, and system clock. The applications do not set these parameters themselves, and thus do not need to relinked for different board architectures. The example below creates a boot-prom for a system with 1 Mbyte RAM, one waitstate during write, 3 waitstates for rom access, and 12 MHz system clock. For more details see the mkprom manual

```
mkprom -ramsz 1024 -ramwws 1 -romws 3 hello.exe -freq 12 hello.srec
```

3.6 Simple examples

Following example compiles the famous 'hello world' program and creates a boot-prom in SRECORD format:

```
> sparc-rtems-gcc -nortems -g -O2 hello.c -o hello
> mkprom hello -o hello.exe
> sparc-rtems-objcopy --adjust-vma=0x2000000 -O srec hello.exe hello.srec
```

An Ada application compiled through gnatmake:

```
> sparc-rtems-gnatmake -g -03 -gnatp dais.adb -bargs -r -largs -qgnat -rtems sparc-rtems-gcc -c -g -03 -gnatp dais.adb sparc-rtems-gnatbind -a0./ -I- -r -x dais.ali
```

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```
sparc-rtems-gnatlink -g -rtems -qgnat dais.ali
> sparc-rtems-size dais
text data bss dec hex filename
204720 6392 32268 243380 3b6b4 dais
```

Several example C, C++ and Ada program can be found in src/examples. The RTEMS validation tests can be found in src/examples/RTEMS.

3.7 FPU rev.B bugs

The FPU rev.B (and to some extent rev.C) have two types of bugs; certain lddf/stdf sequences fail and asynchronous interrupts can in some cases cause FPU exceptions. If FPU rev.B or C is used, adding the -revb switch to gcc will work-around the lddf/stdf bugs. Note that the -revb switch also have to be used during linking, to select the correct libraries. The interrupt bug (a.k.a. bug 3.14) is handled directly in the rtems kernel and does not need the -revb switch. Note: the -revb switch incurs approximately 5% performance penalty. It is therefore wise to group all functions with floating-point operations into a separate file which is compiled with -revb, while all non-floating-point code can safely be compiled without -revb.

For Ada programs running on FPU rev.B or C, -revb must be added to both -cargs and -largs of gnat-make.

4 Execution and debugging

The applications built by ERC32CCS can be executed in four different ways; on the standalone simulator, on gdb with integrated simulator, on a remote target connected to gdb and on a standalone target board from prom.

4.1 Standalone simulator

The standalone simulator can run both application produced by the compiler and srecord images produced by MkProm. The following example shows how the 'hello world' program is run:

```
tellus > sis hello

SIS - SPARC instruction simulator 3.0.5, copyright Jiri Gaisler 1995-1998
Bug-reports to jgais@ws.estec.esa.nl

loading hello:
section .text at 0x02000000 (26032 bytes)
section .data at 0x020065b0 (1304 bytes)
section .bss at 0x02006ac8 (40 bytes)(not loaded)
serial port A on stdin/stdout
sis> go
Hello world
Program exited normally
```

Note that the program was started from address 0x2000000, the default start address. Programs always halt the IU after they have terminated, that is why the IU goes into error mode. The boot-prom image can also be simulated:

```
tellus > sparc-rtems-sis hello.srec
SIS - SPARC instruction simulator 3.0.5,
                                          copyright Jiri Gaisler 1995-1998
 Bug-reports to jgais@ws.estec.esa.nl
loading hello.srec:
section .sec1 at 0x00000000 (16784 bytes)
serial port A on stdin/stdout
sis> run
ERC32 boot loader v1.0
  initialising RAM
  decompressing .text
  decompressing .data
  starting hello
Hello world!
Program exited normally
sis>
```

4.2 GDB with simulator

To do symbolic debugging of both C and Ada applications, use gdb. After gdb is started, the simulator has to attached and the program loaded. It is important that the applications have been compiled with the -g switch. Below is a sample session:

```
tellus > sparc-rtems-gdb hello
(qdb)tar sim
 SIS - SPARC instruction simulator 3.0.5
 Bug-reports to Jiri Gaisler ESA/ESTEC (jgais@ws.estec.esa.nl)
serial port A on stdin/stdout
Connected to the simulator.
(qdb)
(qdb) load
(qdb) break main
Breakpoint 1 at 0x20014e4: file hello.c, line 4.
(qdb) run
Starting program: /home/jgais/erc32/src/examples/hello
Breakpoint 1, main () at hello.c:4
                printf("Hello world!\n");
(qdb) cont
Continuing.
Hello world!
Program exited normally.
(qdb)
```

4.3 GDB with remote target

To attach gdb to a remote targets similar to attaching to the simulator. The baud rate for the serial port has to be specified and the remote target monitor has to run on the target. Also, a tip window should be connected to UART A to see the application output. Below is a sample session with a remote target:

```
tellus> xterm -e tip -38400 /dev/ttya &
[234]
tellus > sparc-rtems-gdb hello
(gdb) set remotebaud 19200
(gdb) tar erc32 /dev/ttyb
Remote debugging using /dev/ttyb
0x2000000 in trap_table ()
(gdb) lo
Loading section .text, size 0x65e8 vma 0x2000000
Loading section .data, size 0x4d0 vma 0x20065e8
(gdb) bre main
Breakpoint 1 at 0x20014e4: file hello.c, line 3.
(gdb) run
Starting program: /home/jgais/erc32/src/examples/hello
main () at hello.c:4
```

Note that the program has to be loaded each time before it is started with 'run'. This is to initialise the data segment to the proper start values. It is possible to switch between several targets (real or simulated) in the same GDB session. Use the GDB command **detach** to disconnect from the present target before attaching a new one.

4.4 Using DDD

DDD is a graphical front-end to gdb, and can be used regardless of target. To start DDD with the debugger use:

```
ddd --debugger sparc-rtems-gdb --attach-window
```

A small script, dddx, is provided to start DDD in this configuration. You might need the full path in front of DDD if you already have a version of ddd installed. To get the source code displayed in the ddd window, click on **locate()**. The required gdb commands to connect to a target can be entered in the command window. See the GDB and DDD manuals for how to set the default settings. If you have problems with getting DDD to run, run it with --check-configuration to probe for necessary libraries etc. DDD has many advanced features, see the manual in erc32/doc (ddd.pdf) or the on-line manual under the 'Help' menu.

4.5 Remote target monitor

The directory <code>src/rdbmon</code> contains the remote monitor which needs to be running on the target board to allow remote target debugging with gdb. The monitor supports 'break-in' into a running program by pressing Ctrl-C in GDB or <code>interrupt</code> in DDD. The two timers are stopped during monitor operation to preserve the notion of time for the application. Note that the remote debugger monitor only works with programs compiled with ERC32CCS, and thus NOT with programs compiled with Aonix Ada, VxWorks or similar.

Type make to build the monitor. Depending on desired baudrate type either 'make m38k4', 'make m19k2' or 'make m9k6'. Program the resulting *.srec file to you boot-prom. The remote debugger will be attached via UART B, console is on UART A. The maximum baudrate depends on the system clock of the target, 38K4 has been successfully used with a zero-waitstate ERC32 system running at 10 MHz. The monitor installs it self into the top 32K of ram. It therefore needs to know how large the ram is. The default ram size for the monitor is 4 Mbyte, adjust the Makefile if your system has different size.

NOTE: the monitor from earlier (pre-2.0) ERC32CCS releases is NOT compatible with gdb version supplied with ERC32CCS-2.0 and later. Uses the monitor provided in this version to avoid problems.

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5 Internals

5.1 Memory allocation

The resulting executables are in a.out format and has three segments; text, data and bss. The text segment is by default at address 0x2000000, followed immediately by the data and bss segments. The stack starts at top-of-ram and extends downwards. When the remote debugger is used, a part of the stack is automatically reserved for the debugger monitor.

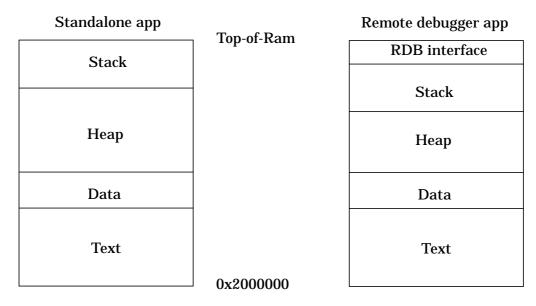


Figure 1: ERC32CCS applications memory map

By default, programs are linked assuming that the target system has 2 Mbyte prom and 4 Mbyte ram. These settings can be overridden at compile time using the linker's --defsym option. On a system with 1 Mbyte prom and 8 Mbyte ram, use:

```
sparc-rtems-gcc -Xlinker --defsym -Xlinker _PROM_SIZE=1M -Xlinker --defsym
-Xlinker _RAM_SIZE=8M ....
```

When using gnatmake, these options should be added after the -cargs switch. Note, these options are only useful when running on the simulator (or gdb/sis) without using mkprom. When mkprom is used or the application is run on a remote target under rdmon, the memory options given to mkprom will be used.

5.2 Sequential C-programs

For sequential C-programs, a posix compatible C-library and math library is provided. However, no file or other I/O related functions will work, with the exception of I/O to stdin/stdout. Stdin/stdout are mapped on UART A, accessible via the usual stdio functions. UART B can be accessed via file handle 3 (input) or 4 (output) using the read() and write() functions:

```
write(4,buf,size);
```

At startup of a program, the MEC real-time counter is programmed to increment one per microsec-

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ond. The function $\verb|clock|()$ will return the value of the counter. The sources to the board-specific part of the C-library is provided in $\verb|erc32/src/libio|$. A user can modify the I/O functions according to his needs and install them into the C-library location ($\verb|erc32/sparc-rtems/lib|$).