WEIHONG CNC System for Engraving Machines

NcStudio-V8

(For PM63A/53B/53C Control Card)

User's Manual

Where there is motion control

there is WEIHONG



Preface

Thank you for choosing our products.

This manual will acquaint you with such detailed information of our products as system components, settings, functions, and operations, etc.

Please read it carefully before using our products and other relative machine equipments to make a better use of them.

Because of continuous updating, the products you bought may differ from the written in this manual, and we apologize for this situation.

Company address, phone number and our website are listed here for your convenience. Any questions, please feel free to contact us. We will always be here and welcome you.

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Cautions

♦ Storage and Transportation

Attention

- The products should be transported properly in terms of the weight;
- Excess of specified quantity of stacking products is prohibited;
- Climbing, standing or placing heavy loads on the products is prohibited;
- Dragging or carrying the products via cables or devices connected to them is prohibited;
- Keep the products free from moisture during storage and transportation.

◆ After Opening the Package

Attention

- Please make sure whether the products are what you have ordered;
- Check if the products are damaged in transit;
- > Check if the components and accessories are damaged or missing in terms of the detailed list;
- Please contact us promptly if product discrepancy, accessory missing or transit damage occurs.



Installation Notices

Attention

- Only when this equipment installed in a qualified electricity cabinet can it be used. The construction of the cabinet must reach IP54 grade of protection;
- Paste sealing strips on the joint of the cabinet to seal all the cracks;
- Cable entry should be sealed while easy-to-open on the spot;
- A fan or heat exchanger should be adopted for the heat dissipation and air convection of the cabinet:
- If a fan is adopted, air strainer is a must in air inlet or air outlet;
- Dust or cutting fluids may have access to the CNC device via the tiny cracks and tuyere. Therefore it is necessary to pay attention to the surroundings and air flow direction of the air vent to make sure that the outflow gas is towards pollution source.
- > 100 mm space should be preserved between the back of the CNC device and the cabinet wall for plugging the cable connected with the device and the ventilation & heat dissipation in the cabinet.
- > Space between this device and other equipments should also be preserved according to the requirements.
- The product should be installed firmly and without vibration. During installing, casting, knocking, striking, or loading on the product is forbidden.
- To reduce electromagnetic interference, power-supply components used should be above AC or DC 50V and the space between the cable and CNC device should be preserved above 100mm.
- It will be better if the CNC device is installed on the position facilitating debugging and maintenance.



Wiring Notices

Attention

- Only qualified people are allowed to participate in the wiring and checking.
- The CNC device should be grounded reliably and grounding resistance should be less than 4 ohm. Neutral line is absolutely not allowed to replace earth wire. Otherwise, the device may be likely to work improperly due to the interference.
- Wiring should be firm and steady, or misoperation may occur.
- Voltage values and positive & negative polarity of any connection plug should be in accordance with the manual, or such breakdowns as short circuit and device permanent damage may occur.
- To guard against electric shock or CNC device damage, fingers should keep dry before plugging or touching a switch.
- The connecting wire should not be damaged and squeezed, or the leakage or short circuit may occur.
- It is prohibited to plug or open the chassis of CNC device when power on.

♦ Running & Debugging Notices

Attention

- Parameters setting should be checked before running, since wrong setting may lead to accidental movements.
- Modification to parameters should be within the allowable range, or such breakdowns as unsteady running and machine damage may occur.

Precautions in Use

Attention

- Before power-on, please make sure that the switch is on blackout to avoid occasional start-up.
- Please check the electromagnetic compatibility during electrical design in order to avoid or reduce electromagnetic interference to the CNC device. A low pass filter should be employed to reduce electromagnetic interference if there are other electrical devices nearby.
- It is not allowed to frequently power on and power off. It is recommended 1 minute interval at least after power failure or blackout before power on.



Contents

1. Su	ımmary	1
1.1.	System Characteristics	1
2 64	estem Installation and Connection	
2. Sy	stem Installation and Connection	4
2.1.	Basic Configurations of NcStudio	4
2.2.	Installation of NcStudio	4
2.2	2.1. Installation of NcStudio Motion Control Card	4
2.2	2.2. Installation of NcStudio Software	5
2.3.	Uninstall of NcStudio	g
2.4.	Connection of NcStudio Motion Control Card and Driving System	10
3. Ba	sic Concepts of NcStudio	11
3.1.	Operation Mode and State	11
	1.1. Operation Mode	
	I.2. Operation State	
3.2.	Coordinate System	
	2.1. Machine Coordinate System (MCS)	
3.2	2.2. Workpiece Coordinate System (WCS)	13
4. Op	peration Interface of NcStudio	14
4.1.	Title Bar	14
4.2.	Menu Bar	15
4.3.	Tool Bar	16
4.4.	CNC Info Bar	17
4.5.	Status Bar	17
4.6.	CNC State Window	17
4.6	S.1. Current Position	17
4.6	S.2. Feed Rate	18
4.6	S.3. Spindle Speed	20
	S.4. Current Interpolation Order Set and Cycle Machining	
	6.5. Too Info	
	S.6. Time Info	
4.7.	Auto Operation Window	
4.8.	Manual Operation Window	22
4.9.	Calibration Operation Window	24



	4.9.	Calibrate the Workpiece Surface	25
	4.9	2. Special Presetting	26
	4.9	3. Fixed Presetting	29
	4.10.	Compensation Operation Window	31
	4.11.	Trace Window	32
	4.12.	Log Window	38
	4.13.	Manager Window	40
	4.14.	Editor Window	43
	4.15.	I/O State Window	44
5.	Ncs	Studio Menu System	45
	5.1.	"File" Menu	45
	5.2.	"Edit" Menu	47
	5.3.	"View" Menu	49
	5.3.	1. "View" Menu When Manger, Editor or I/O State Window Activated	49
	5.3.		
		3. "View" Menu When Log Window Activated	
	5.4.	"Operation" Menu	
	5.5.	"Machine" Menu	
	5.6.	"Window" Menu	
	5.7.	"Help" Menu	64
6.	Par	ameter Setup	67
	6.1.	Parameter Modification Permission	67
	6.2.	Parameter Modification Method	67
	6.3.	Operator's Parameters	68
7.	Ор	eration Steps	74
	7.1.	Starting-up	74
	7.2.	Machine Reset (Optional)	74
	7.3.	Load Machining File	74
	7.4.	Manual Operation	74
	7.5.	Set Workpiece Origin	75
	7.6.	Check Ports in I/O State Window	75
	7.7.	Set Speed Parameters	75
	7.7.	1. LinearAcceleration (N4053)	75
	7.7.	2. ConnectionAcceleration (N4054)	76



	7.7.	3. ReferenceCircleMaxSpeed (N4058)	76
	7.7.	4. MinSpeedInACircularMotion (N4059)	76
7	'.8.	Execute Auto Machining	77
8.	Pre	cautions in Operation	78
8	3.1.	Precautions for Multi-Task Executing	78
8	3.2.	Precautions for Homing	78
9.	Sho	ortcut Key List	79
10.	Sof	tware License Agreement	81





1. Summary

NcStudio, an engraving CNC system, is independently developed by Weihong Electronic Technology Co., Ltd., with copyright reserved. This system can directly support G code and PLT code format files generated by various CAD/CAM software, such as UG, MASTERCAM, CASMATE, Art CAM, AUTOCAD and COREDRAW.

PC-based NcStudio makes full use of 32-bit computing and multi-task handling. In addition, the interface is reliable and user-friendly.

Apart from functions of automatic mode, manual mode and backing to the reference point, this CNC system also features the following functions: simulation, dynamic track, auto Z axis, breakpoint resume (advanced start), rotary axis machining, and so on.

This system can be applied to various three-axis engravers and engraving & milling machines, and used in complex mold machining, advertising, decorating and cutting industries, etc.

1.1. System Characteristics

This system has the following functions:

- Three basic motion axes are available and binary input & output points and analog outputs can be further expanded. The above configuration varies with different choices of machine tool builders.
- 2) It supports CNC rotary table (varying with different versions).
- 3) Auto processing supports G code of ISO standard, HP PLT format, DXF format, JDPaint ENG format and popular CAD/CAM software at home and abroad, like UG, Pro/E, MasterCAM, Cimatron, CASMate and ArtCAM, etc.
- 4) It supports manual operation, like jog mode, stepping (increment) mode and handwheel mode. Under these modes, the user can not only manipulate the machine with the help of machine tool input equipment like hand-held device, but also use computer input equipment such as keyboard and mouse to realize manual operation.
- 5) It supports array processing: the user can repeatedly carry out processing procedure according to columns and arrays defined.
- 6) It supports rotation & image processing. This function can perform rotation & image machining centered on the workpiece origin.



- It supports stepping function: the user can set the precise feed value and adjust the step length value.
- 8) It supports user data input function: the user can input G code online and execute it right away.
- 9) It supports advanced processing instructions. Simply by inputting several parameters, bottom milling and frame milling can be realized.
- 10) It supports single step mode: the user can set a processing task to be executed as single step mode, which provides a good support for error diagnosing and failure recovery.
- 11) Advanced auto functions such as breakpoint resume and advanced start are supported.
- 12) Feed axes can back to mechanical origin (reference point) precisely.
- 13) It supports auto tool presetting function, including fixed presetting, floating presetting and auto centering, etc.
- 14) It supports workpiece field save/restore function. By taking into consideration the problem of sudden power failure customers are likely to meet, the system has been designed to prevent any system file damage caused by sudden power-off. Functions like breakpoint resume, backing to mechanical origin precisely, etc, also guarantee machining field reliable restoration after the system is restarted.
- 15) It supports feedrate override online adjustment. The user can adjust feedrate override freely during machining. The minimum value is 0, equivalent to a pause in processing and the maximum value is 120%.
- 16) It supports high-smooth speed connection function. In an ordinary NC system, the connecting speed between two G codes usually is a fixed value, such as 0 or a very small value. However, by adopting machining speed adaptive forecasting algorithm, our system can decide the connecting speed between the current code and the next code by taking the connecting speed, its direction, and the maximum acceleration speed into consideration and by employing forward predicting function. This not only improves machining efficiency (from 30% to 300%), but also enhances the machining performance by eliminating speed chatter marks left on the surface of the workpiece.
- 17) It supports three-dimensional simulation display function. With simple operation, the user can observe the three-dimensional machining result from various orientations to understand it more accurately and more intuitionally.



- 18) It supports simulation function. This function supports rapid simulation machining which can be finished in an extremely short period of time. The user can check if there is any error in the machining file and whether the machining result is satisfactory and know the actual processing time.
- 19) It supports powerful and agile keyboard operation. The new system strongly supports keyboard operation and thus can fulfill the user's needs in operation.
- 20) It supports log function. The powerful log function can help the user check the detailed processing information and system diagnosis.
- 21) Built-in machining file manager: the user only needs to save the machining files into the designated directory and NcStudio will then manage these files in a built-in manager.
- 22) Built-in file editor: with which, the user can load a machining file into the editor for editing and modifying.
- 23) It displays file machining information; through simulation or actual machining, file machining information window can help the user count such important information as executing time and processing range.
- 24) PCI bus motion control card is adopted.
- 25) It supports auto parameters backup function. The user can back up the parameters according to his needs and recover them as necessary.



2. System Installation and Connection

2.1. Basic Configurations of NcStudio

Host Computer

CPU: basic frequency 1G or above

Memory: above 512M Hard disk: above 20G

Display adapter: 1024*768 at least

Display: above 14" VGA

CD-ROM: 4X or higher (optional)

Main board expansion slot: more than 2 PCI slots

2.2. Installation of NcStudio

If there is already an old version of Ncstudio on the computer, please delete it, and then install the new version. Regarding how to delete the old version, please turn to chapter 2.3.

Nestudio system includes two parts: the software and motion control card. As a result, the setup of the system is also divided into two stages: the software setup and the motion control card setup.

Please install the motion control card before installing the software, including the following steps:

- 1) Close the computer and install the motion control card.
- Restart the computer to enter the operating system, then insert the installation CD and select auto update package, and then double click to start auto update. And then the computer will be restarted automatically.
- 3) Run NcStudio system.

The key steps will be introduced in detail as follows.

2.2.1. Installation of NcStudio Motion Control Card

Power off the host machine, and open the chassis cover, and then insert the card into an available and matched expansion slot.

When installing the motion control card, hold the two sides of the card lightly with your hands to make sure that it is inserted into the slot firmly and well contacted with the computer baseboard without shaking. Then tighten the screw of the control card and lid the cover. The installation of motion control card then finishes.



2.2.2. Installation of NcStudio Software

The installation of software is divided into the following steps:

- 1) Power on and start the computer. The system will automatically access the operating system.
- 2) After the operating system is started, please close all the other running applications.
- 3) Insert the installation CD of NcStudio system into the CD driver.
- 4) Open [My Computer] and double-click the CD-driver icon. After the CD is opened, find and

double click the auto update package file (the icon:). At this time, the following installation picture will be displayed:



Fig. 2-1 Language selection dialog

Select [ENGLISH] to continue, as shown below.

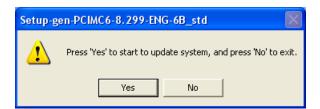


Fig. 2-2 Upgrade prompt dialog

Click [YES] to continue. See Fig. 2-3.





Fig. 2-3 Save parameters before installation

Click [OK] to continue the next step. See Fig. 2-4.

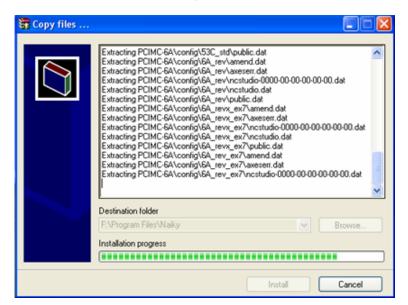


Fig. 2-4 Software installation progress



Fig. 2-5 Whether to turn off computer immediately

- Click [OK] to shut down the computer.
- 5) After the computer is started, the following dialog will be ejected for new hardware drive update.





Fig. 2-6 Hardware installation interface-page one

Select [No, not this time], and click [Next.] A prompt will appear to guide how to install software for Weihong CNC adapter card.



Fig. 2-7 Hardware installation interface-page two

> Select [Install from a list or specific location (Advanced)], and then click [Next]. See Fig. 2-8.





Fig. 2-8 Choose the driver manually

Select [Have Disk...] in the following dialog.

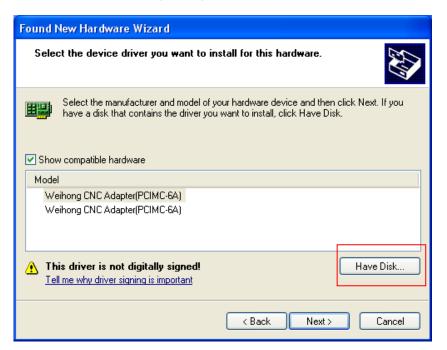


Fig. 2-9 Select the driver manually

Select "Browse" in the pop-up dialog "Install From Disk", and then select the target file "NcadptPci(PCIMC-6A).inf" under "C:\Program Files\Naiky\PCIMC-6A". See Fig. 2-10.





Fig. 2-10 Select the target file of driver

Click "OK" to go back, and then click "Next" to eject the driver installation progress interface.
When the installation is complete, a dialog as shown below will pop up.

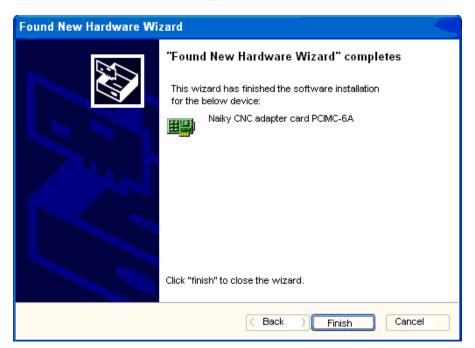


Fig. 2-11 Driver update completed

Click [Finish]. The whole system is installed successfully. Double clicking the icon the desktop will open the CNC system.

Notice:

The installation pictures offered above may vary with different versions, just for reference only.

2.3. Uninstall of NcStudio

NcStudio is green software which has the following advantages: the installation information not written into the registry form; easy to carry and uninstall; available of copying to a USB disk.



Therefore, to delete NcStudio, the user only needs to delete the Naiky folder under C:\Program Files.

When a new version of NcStudio is installed, the new software will update and overwrite the files of the old version.

2.4. Connection of NcStudio Motion Control Card and Driving System

The communication between NcStudio and the feed motor driving system mounted in the electrical box of machine tool is realized by the machine motion control signals given by the motion control card, which is inserted in the expansion slot of the computer.

The machine tool and the electrical box should be installed in place before connecting the NcStudio motion control card with the motor driving system. Then connect the socket of motion control card to the corresponding one of electrical box via an appropriate cable.

Attention:

Regarding how to connect the card with the electrical system, please refer to the manufacturer's manual of specific model for guidance.

Cards of different models may work in different manners, and their functions may also vary.



3. Basic Concepts of NcStudio

3.1. Operation Mode and State

3.1.1. Operation Mode

Under any circumstance, the operation mode of machine tool is in one of the following modes. A good understanding of them is vital for proper operation.

◆ Auto Mode

Under auto operation mode, the machine tool generates motion according to the pre-prepared processing program. Therefore, under auto mode, the processing program must be loaded in advance.

Manual Mode

There are two types of manual operation mode: jog and stepping.

Under jog mode, the user can directly control the motion of the machine tool via manual operation equipment, such as computer keyboard, handheld box, and MPG (manual pulse generator). When the user sends out the motion signal with the help of these equipment, for example, clicking the button on the software interface, the machine tool will move consecutively until the button is released.

Under stepping mode, the user also uses manual operation equipment, such as computer keyboard, handheld box and MPG (manual pulse generator) to control the machine tool. Different from jog mode, when the user clicks a button once (from clicking the button to releasing it), the machine tool only moves a specific distance. As a result, the user can control the displacement of machine tool precisely.

3.1.2. Operation State

In this system, each operation mode can be subdivided into several operation states. The operation mode and the operation state together decide the status of machine tool.

♦ IDLE

Idle state is the most common one. Under this state, the machine tool does not generate motion, but is ready for any new task.



◆ E-STOP

This is an abnormal state. In case of hardware breakdown or the user pressing E-STOP button, the system will enter into this state and execute the preset protection measures, such as turning off the spindle motor and the cooling pump. Under this state, the machine tool is locked and incapable of moving. When the hardware problem is resolved or E-STOP button is released, the system will automatically execute [Reset] and restore the machine tool to IDLE state.

RUNNING

When the machine tool is generating any motion, the system enters into this state.

♦ PAUSE

When the machine tool is running, if the user implements [Operation| Pause], or the system parses a M01 command (Wait Command), the system will enter into PAUSE state and wait for the next instruction. The user can then implement [Operation| Start] to continue the operation or select [Stop] or [Reset] to stop current operation and make the system enter into IDLE state.

♦ LOCK

As an internal state, lock state is rarely seen under normal circumstances and only exists during state-switching.

3.2. Coordinate System

Coordinate system is a terminology describing the motion of machine tool. For the sake of unification, standard coordinate system adopts right-hand rule, as illustrated in Fig 3-1:

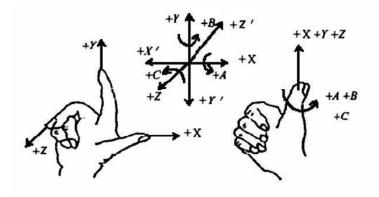


Fig. 3-1 Coordinate system following right-hand rule

For a milling machine, the direction of machine axes is decided by both the type of machine tool and the layout of each component. The basic coordinate axes of milling machine are X-axis, Y-axis, and Z-axis:

—Z-axis coincides with spindle axis, and the direction of the cutter moving away from



workpiece is its positive direction (+Z).

——X-axis is perpendicular to Z-axis and parallel to the clamped surface of workpiece. For the single column vertical milling machine, if the user faces the spindle and looks in the column direction, right moving direction is the positive direction of X-axis (+X).

——X-axis, Y-axis and Z-axis together constitute the coordinate system following right-hand rule.

3.2.1. Machine Coordinate System (MCS)

Machine coordinate system is a set of fixed coordinate system following right-hand rule. Its coordinate origin is always relative to a fixed point of machine tool. Therefore, at any time, a certain point in space can be fixed exclusively by the machine coordinate system.

To completely support the machine coordinate system, the machine tool must have the corresponding function of backing to the mechanical origin. Otherwise, the concept of machine coordinate system only exists in the software.

3.2.2. Workpiece Coordinate System (WCS)

In programming, the programmer select a given point on the workpiece as the origin (i.e. the program origin) to establish a new coordinate system, called workpiece coordinate system, which also adheres to right-hand rule. The origin of WCS (i.e. the workpiece origin) is fixed with respect to a certain point of the workpiece, while probably floating with respect to machine origin (mechanical origin). The choice of workpiece origin should facilitate simple programming, easy dimension conversion and small caused machining error to the greatest extent.



4. Operation Interface of NcStudio

First, install NcStudio according to the above installation instruction and then double-click the shortcut icon of NcStudio on the desktop to start this system. Its main operation interface is as shown in Fig. 4-1.

The interface of NcStudio consists of the title bar, the menu bar, the toolbar, the status bar and several function windows.

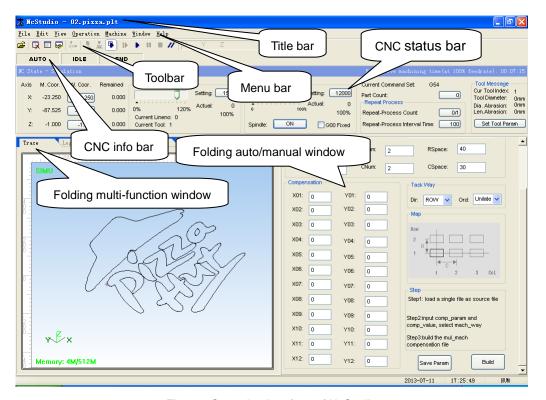


Fig. 4-1 Operation interface of NcStudio

The function windows are divided into three zones, which can be shifted by pressing ESC key, they are:

The first zone: NC state window.

The second zone: trace window, log window, manager window, editor window and I/O state window.

The third zone: auto window, manual window, calibration window and compensation window.

4.1. Title Bar

On the top of the NcStudio is the title bar showing the software name and the name of the loaded machining file. The color of the title bar indicates whether the corresponding window is activated.





Fig. 4-2 Title bar

Note:

An active window means the window that can accept keyboard input at present. At any moment, there is only one active window and all the other windows are inactive.

Please note the difference in the color of the title bar between active window and inactive window. The color of the title bar of an active window is blue, while that of an inactive window is grey.

The icon on the left side of the title bar is system menu box and it can be used to open the window control menu. Clicking this icon or pressing shortcut key "Alt + spacebar" will eject a system menu, as shown in Fig. 4-3.

This menu can control the position and the size of the window, such as restore, move, close, maximize and minimize, etc. On the right side of the title bar, there are three control buttons. They are restoring button, maximizing button and minimizing button respectively. These buttons are used to quickly set the size of the window.

Besides, each subwindow has the corresponding title bar and an active subwindow can also be distinguished from an inactive subwindow by the color of title bar. See the following chapters for details.



Fig. 4-3 System menu

4.2. Menu Bar

Below the title bar is the menu bar; which includes many normally concealed pull-down menus.

Each pull-down menu constitutes several menu items and each menu item corresponds to a specific function, action or state. After a menu item is selected, the system will execute the relevant function or action, or alter the system state. The menu item can be selected either by mouse or by keyboard.

Mouse operation

Clicking a menu on the menu bar, a pull-down menu will pop up. And then click the target item.



Keyboard operation

Simultaneously press down 'Alt' key and the hot letter key. For example, there is a line under 'F' in the "File" menu, so the combination key is "ALT + F". After that, a relative pull-down submenu will pop up.

Shortcut key operation

In a pull-down submenu, some items have relative shortcut keys on their right side. For example, [Operation] → [Start], F9 on its right is the shortcut key. That is to say, the user can directly select the target item by directly pressing the shortcut key, which can avoid the trouble to enter into multilayer menus.

Some menu option has three dots behind. For example, $[\underline{F}ile] \rightarrow [\underline{O}pen \text{ and Load...}]$, which indicates that a dialog will automatically pop up after it is selected. If the item of the submenu shows in grey, it indicates the item is unavailable under current state.

In addition, right clicking on any position of window, a corresponding shortcut menu will pop up for option.

4.3. Tool Bar

Below the menu bar is the tool bar, which is composed of some operation buttons corresponding to specific menu orders or options. Clicking one of these buttons will realize the specified function.

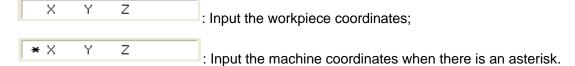


Fig. 4-4 Tool bar

These buttons greatly simplify operation process. They transform the operation process from a sequence of complicated orders to something visual.

♦ Direct positioning function

Under IDLE state, after the user enters the workpiece coordinates into "Direct positioning edit box" and presses [Enter], the system will order the machine to move the tool to the assigned position rapidly.



All the other buttons on the toolbar correspond to a specific item on the menu bar. Hovering over a button, a function prompt will appear. Refer to the sections below for details.



4.4. CNC Info Bar

Below the toolbar is CNC info bar showing the current CNC state and some other info, as shown in

Fig. 4-5.



Fig. 4-5 NC information bar

4.5. Status Bar

At the bottom of the interface is status bar, as illustrated in Fig. 4-6.

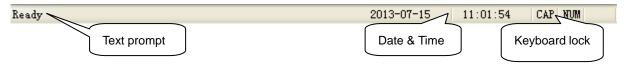


Fig. 4-6 Status bar

♦ Text prompt

It shows the prompt info of current operation or of the selected order.

◆ Date & Time

It shows the current date and time.

◆ Keyboard lock

It shows the current state of the keyboard, including Caps Lock, NUM LOCK or ScrLK.

4.6. CNC State Window

Below the CNC Info Bar is the CNC State window, which can be divided into 5 parts according to functions. They are ①Current Position Area, ②Feed Rate Area, ③Spindle Speed Area, ④ Current Interpolation Order Set Area and ⑤Tool Info Area.



Fig. 4-7 CNC state window



4.6.1. Current Position

To describe various positions, NcStudio supports displaying machine coordinate system and workpiece coordinate system simultaneously. The user can set the relative offset between the two coordinate systems appropriately.

A mark indicating "machine coordinates effective" will appear before each axis after "back to reference point" is executed, as illustrated below.

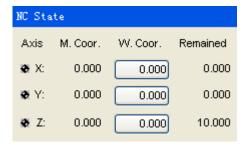


Fig. 4-8 Current position area

It is easy to set and adjust the workpiece origin. To set the current point as the workpiece origin, the user only needs to move the cursor on the workpiece coordinate of the target axis and then click this [workpiece coordinate]. A dialog box will pop up, as illustrated below:

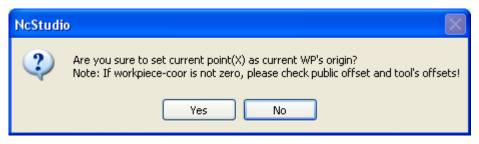


Fig. 4-9 Setting workpiece origin

Clicking "Yes", the coordinate of that axis will become 0. To change the current position of all the three axes into 0, just click each workpiece coordinate.

Prompt:

Please check public offset value and tool offset value if the current workpiece coordinate value is not zero after setting.

Remained: the absolute difference between the commanded position and the instantaneous position under current command.

4.6.2. Feed Rate

This area displays information like the setting speed, the actual speed and the feedrate override. The user can also change the feed rate and feedrate override here.



Sliding Block of Feedrate Override

By dragging the sliding block, the user can regulate the current movement speed within a scope of 0~120%. The direction keys on the keyboard can increase or decrease it by 1% while PageDown and PageUp by 10%. Feedrate override is shown in percentage.

Setting

Under auto mode, when the user clicks the figure after "Setting", a dialog box will pop up for setting machining speed and G00 speed.

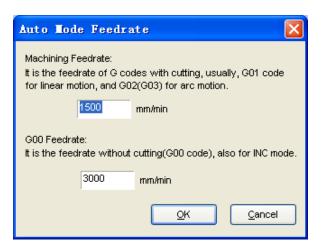


Fig. 4-10 Setting auto speed dialog box

Under manual mode, clicking the figure after "Setting", a dialog box as below will pop up for setting jog speed and rapid jog speed.

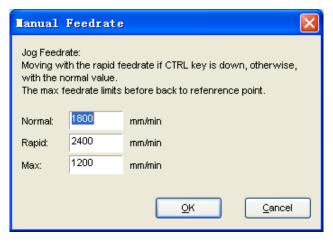


Fig. 4-11 Setting manual speed dialog box

Prompt:

The method to switch between jog speed and rapid jog speed under manual mode: when number key "0" and a direction key of 4(X-), 6 (X+), 2 (Y-), 8 (Y+), 1 (Z-) and 9 (Z+) are pressed simultaneously, it is rapid jog speed; when only one of the direction keys is pressed, it is jog speed.

Note that the setting operation made here works the same as the setting made in [Operator's



parameters] in the parameter window.

◆ Actual

It is the instantaneous value of feed rate which alters with the change of setting value, the current acceleration or deceleration condition and the feedrate override.

Current Tool

It shows the number of the currently used tool.

4.6.3. Spindle Speed

This area displays information like the setting speed, actual speed and spindle override, etc. The user can also change the setting value and spindle override here.

◆ Spindle Override Sliding Block

By dragging the sliding block, the user can regulate the current spindle speed within a scope of 0~100%. The direction keys on the keyboard can increase or decrease it by 1% while PageDown and PageUp by 10%. Spindle override is shown in percentage.

Actual value= Setting value * Current spindle override

◆ Spindle Button

This button controls spindle ON or OFF.

Spindle Speed Setting

Clicking the button after "Setting", a dialog box will pop up, as shown in Fig. 4-12, for setting spindle speed.



Fig. 4-12 Setting spindle speed dialog box

♦ G00 Fixed

Selecting this menu item, the running speed will be 100% of the setting value of G00 speed, unaffected by the change of feedrate override.



4.6.4. Current Interpolation Order Set and Cycle Machining

Current interpolation order set area displays the state of currently executed command, for example, G54, modal/ non-modal, G01, G17, G18, G19...

Part Count: the number of workpieces processed, which can be cleared by clicking on the button.

Repeat-Process Count: displaying the times of finished cycle machining and the preset times of cycle machining. Clicking on this button can set the times of cycle machining.

Repeat-Process Interval Time: displaying the interval time of cycle machining. Clicking on this button can set the interval time.

4.6.5. Too Info

This area displays the current tool No. and info. Clicking "Set Tool Param" will output the parameter window for directly consulting and setting tool parameters, as shown below. 255 tools are supported at most.

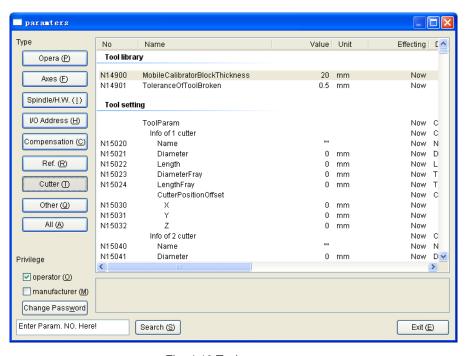


Fig. 4-13 Tool parameters

4.6.6. Time Info

On the right side of the title bar of NC State Window, it is the pre-estimated machining time at 100% of feedrate override under simulation state that is displayed, while it is the actual machining time in actual machining that is displayed.

4.7. Auto Operation Window



The auto operation window displays the currently loaded machining file. At present, NcStudio supports the following file formats: G code of ISO standard, HP plotter (HP PLT) format, DXF format, JDPaint ENG format and NCE format exclusively owned by our company. The user can view and edit the current machining file in this window.

Right clicking on this window, a shortcut menu will pop up, as shown in Fig. 4-14.

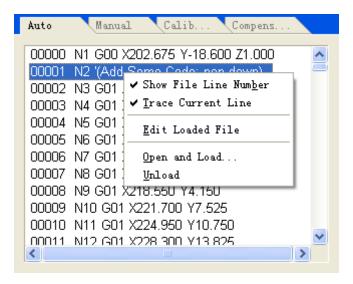


Fig. 4-14 Auto operation window

All of those menu items can also be found in standard menus, among which, "Show File Line Number" and "Trace Current Line" can be found in "View" menu, while the other 3 items can be found in "File" menu. Refer to chapter 5.1 and 5.3 for explanation.

The user can switch among the 4 modal windows: Manual, Auto, Calibration and Compensation.

♦ Methods to Switch to Auto Window:

- Menu method: choose "Window | Show Auto Window".
- Shortcut key method: press "Ctrl+1" key to activate Auto window.
- Mouse method: click the window title "Auto" directly.

Prompt:

In this window, the user can only view the loaded file instead of editing or modifying it. To edit this file, the user needs to execute [File | Edit Loaded File] or click the right mouse button in this area and then choose [Edit Loaded File] before editing the file in [Editor] window.

4.8. Manual Operation Window

Manual window provides the user with an interactive machine tool operation environment, as shown in Fig. 4-15.



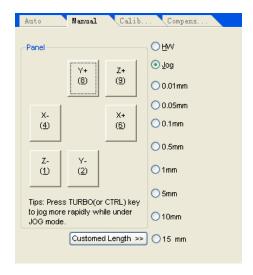


Fig. 4-15 Manual operation window

♦ Direction Buttons:

- > (4) and correspond to positive and negative direction of X axis respectively;
- > (2) and (2) correspond to positive and negative direction of Y axis respectively;
- > (1) and (1) correspond to positive and negative direction of Z axis respectively;

Selection of Feed Mode

There are two feed modes: jog mode and stepping mode, as illustrated below.

Jog Mode

Check og to choose jog mode.

Holding down a direction Num key on the keypad, the machine will move consecutively until this key is released.

Check to control the machine tool via the handwheel; turning the handwheel will make the machine move consecutively until the user stops turning it.

Caution:

When Manual window is active, NUM LOCK will not be taken into consideration.

Stepping Mode

Checking any item in Fig. 4-16, the system will access stepping mode.



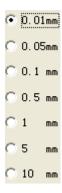


Fig. 4-16 Stepping mode

Under stepping mode, the machining track is shown in G01 color in the [Trace] window.

The user can implement stepping operation via the mouse, keyboard, or operation panel. Each time triggering a direction key, the corresponding axis will move a fixed step length.

Customed Length

Clicking [Customed Length], a dialog box will pop up, as illustrated below:



Fig. 4-17 User-defined step length

Enter the proper step length and click "OK".

Caution:

Avoid setting a too large step length in case of equipment damage caused by maloperation.

As it takes the system a certain period of time to execute each jog order, avoid excessively repeated clicking. Otherwise, the system will give out an error prompt: system is busy now and this operation is invalid.

4.9. Calibration Operation Window

In this window, the user can conduct presetting operation, as shown in Fig. 4-18.



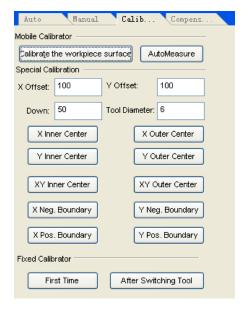


Fig. 4-18 Calibration operation window

4.9.1. Calibrate the Workpiece Surface

Specially designed for Weihong system, this function can help the user to confirm the height of workpiece surface conveniently. It is used to fix the Z axis workpiece origin automatically, equaling mobile presetting when the thickness of tool presetter is 0. To measure workpiece surface, the machine tool worktable must be insulated.

The method of mobile presetting is to place the tool presetter on the workpiece surface and then operate Z axis to make the tool nose touch the tool presetter. At this time, the presetting signal is gotten and calibration stops, the system learning the position of tool nose. Thus, the Z axis coordinate of workpiece origin is gotten after subtracting the thickness of tool presetter from tool nose position.



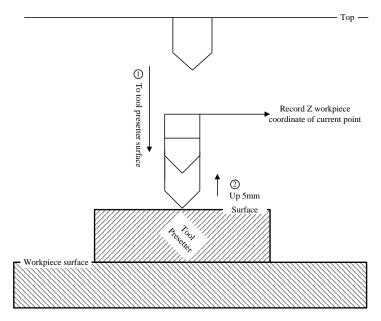


Fig. 4-19 Sketch map of mobile presetting

4.9.2. Special Presetting

Special presetting includes auto presetting of workpiece origin and workpiece boundary. As presetting signal is used, they are called special presetting, exclusively used in Weihong system.

Special presetting is used to calibrate X and Y center of workpiece in order to facilitate machining and generating a machining file, under the precondition that the Z axis workpiece coordinate is confirmed and the worktable of machine tool is insulated.

- > X Offset: during center presetting, the preestimated distance from workpiece center to X boundary. In outer center presetting, this distance must be a little larger than the actual value, while smaller in inner center presetting.
- Y Offset: during center presetting, the preestimated distance from workpiece center to Y boundary. In outer center presetting, this distance must be a little larger than the actual value, while smaller in inner center presetting.
- Down: tool plunging/lifting distance in tool presetting. In inner center presetting, this distance must be a little smaller than the distance from tool nose to workpiece surface, while larger in outer center presetting.
- Tool Diameter: the actual diamter of tool.

Center Presetting

Center presetting is used to confirm the center point of workpiece blank. It includes X inner / outer center presetting, Y inner / outer center presetting, and XY inner / outer center presetting.



Take the process of [X Inner Center] as an example: place a conducting workpiece (copper, iron, aluminum) on the insulated workbench, and connect it to the port CUT on the terminal board, while the cutter to COM port. Before automatic centering, put the cutter on the predicated center point position, and then click [X Inner Center] to make the cutter fall to [Down] distance, and translate towards the workpiece a short distance until reaching the conducting workpiece. At this time, the circuit is conducted and the signal is sent to the system so as to automatically record the current axial coordinate X1. Then the cutter will raise [Down] distance, move two [X Offset], move down [Down] Distance, and translate towards the workpiece a short distance until reaching the conducting workpiece. As a result, the circuit is conducted and the signal is sent to the system so as to automatically record the current axial coordinate X2. The system will then calculate the X coordinate of workpiece center point and move the cutter to this center point. The sketch map is as shown below.

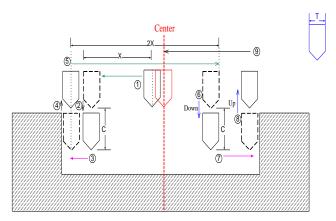


Fig. 4-20 Presetting process of [X Inner Center]

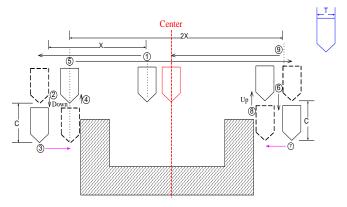


Fig. 4-21 Presetting process of [X Outer Center]



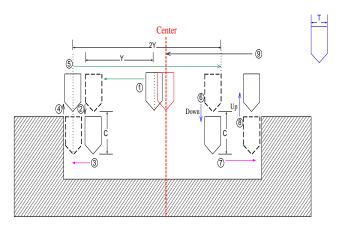


Fig. 4-22 Presetting process of [Y Inner Center]

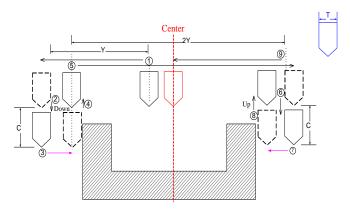


Fig. 4-23 Presetting process of [Y Outer Center]

Before centering, the user must place the tool nose over the pre-estimated center point, as well as set the value of "X\Y Offset", "Down" and "Tool Diameter".

In inner center presetting, the "Down" distance should be smaller than the distance between tool nose and workpiece surface, while larger in outer center presetting.

Boundary Presetting

Boundary presetting includes calibrating +X boundary, -X boundary, +Y boundary and -Y boundary, mainly used for setting the boundary point as workpiece origin.

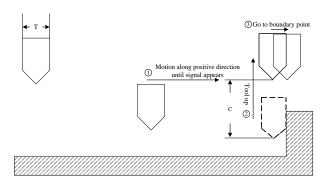


Fig. 4-24 Presetting process of +X boundary

The presetting process of -X boundary, +Y boundary and -Y boundary are the same as that of +X boundary.



4.9.3. Fixed Presetting



Fig. 4-25 Fixed presetting

Fixed presetting refers to the presetting operation on a certain fixed position of machine tool due to tool damage or other causes, frequently used in multi-tool mode. The length of tool and the clamping position may vary, thus tool offset should be reconfirmed by fixed presetting and the sketch map of fixed presetting is as shown in Fig. 4-26.

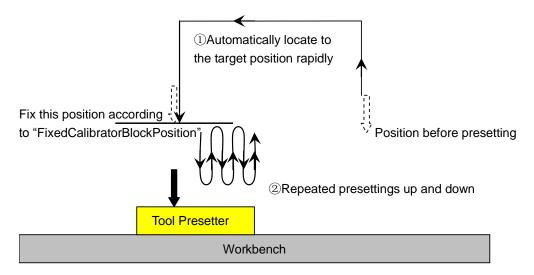


Fig. 4-26 Process of fixed presetting

The process of fixed presetting records the machine coordinate of tool nose when touching the surface of tool presetter. Subtract the thickness of tool presetter from this machine coordinate will get the value of tool offset.

Tool offset= Machine coordinate - Thickness of tool presetter

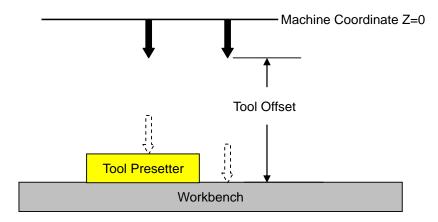


Fig. 4-27 Sketch map of tool offset

When presetting, firstly move Z axis to the workpiece surface, then confirm the workpiece origin



through manual clear or mobile presetting, and then click First Time to make the system automatically record the current Z workpiece coordinate. When tool change or tool break is met, clicking After Switching Tool , the system will automatically restore the Z workpiece origin before tool change or tool break.

Caution:

The above presetting will become invalid automatically after the NcStudio is closed. The user has to execute fixed presetting again when NcStudio is restarted.

Operate according to the prompts made below.

First presetting:

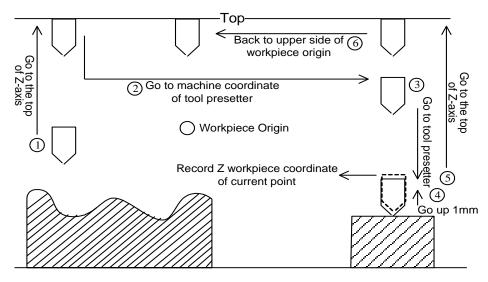


Fig. 4-28 First time tool presetting

Presetting after tool change:

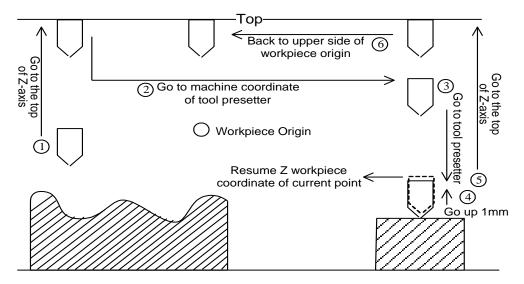


Fig. 4-29 Presetting after tool change



4.10. Compensation Operation Window

The system offers two kinds of workpiece compensation, which are single compensation and row-column compensation. When one of them is selected, the corresponding button will turn to grey. In Fig. 4-30, single compensation is selected. Single compensation is to compensate each workpiece separately, i.e. the compensation for each file can be different, while row-column compensation is to compensate machine files in a row or in a column. For example, X01Y01 in row-column compensation mode can compensate the first row and column of all files, and so on.

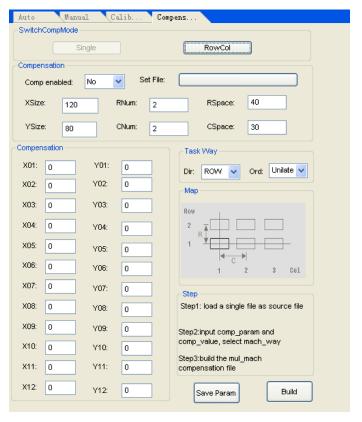


Fig. 4-30 Compensation window

To enable workpiece compensation, select "Comp enabled" as "Yes". Otherwise, workpiece compensation does not work.

Set File: used to load the single workpiece file to be processed. Before clicking this button, load the file into the system and then click this button to load it into this function, or the system will give a prompt that the source file does not exist, as shown below.



Fig. 4-31 Source file error prompt



Firstly, enter the value of X\Y size, row\column number and row\column space, then select direction and order under "Task Way" tab, then enter the relative compensation value of each workpiece, and then click "Build" to generate a multi-workpiece file. After selecting the save path for the new generated file, the file will be loaded into the system automatically.

Note: after the file is loaded into this compensation function, the source file in the system will be unloaded, because the final machining file is the newly generated compensation file.

After parameter setting, remember to click "Save Param". Otherwise, the setting of parameters will be lost after loading a new file.

Some codes are not supported in scale and array functions, like G28, G29, G65, G92, M30 and M2. Neither are the subroutines in the tool path. If there are above-mentioned codes, the system will prompt the user to delete them manually or automatically.

4.11. Trace Window

When machining or simulation is undergoing, the trace window will follow the machining track of tool in real time. In this window, the user then can view the tool path intuitionally in real time so as to ensure the proper implementation of machining file.

Trace window adopts 3D view mode and can be personalized via the option [Customize Trace View...] under [View] menu. Refer to the following contents for detail.

Under 3D tracking mode, the various functions this system provides enable the user to zoom in/out and view the object from different orientations and at proper scaling.

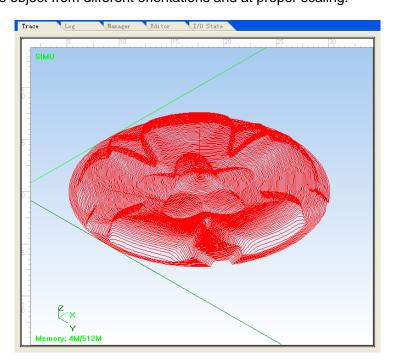


Fig. 4-32 Trace window

Right clicking on the window, a shortcut menu will pop up, as shown in Fig. 4-33. All of these



options can also be found under [View] menu.

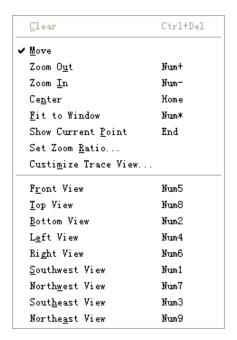


Fig. 4-33 Shortcut menu of trace window

♦ Clear

After a long period of machining, the simulation graph will become very complicated and the temporary file recording the machining track will also become excessively big. As it is time-consuming to redraw, move or revolve the simulative graph, the user needs to clear the machining track regularly.

To clear machining track, several options are available: menu, toolbar, shortcut key or keyboard.

Menu or Toolbar

Choose menu "Edit | Clear View", or choose on the toolbar.

Shortcut Key

At any moment, pressing "CTRL+ DEL" will clear the machining track.

Mouse

Move the mouse into Trace window, right click to eject a shortcut menu, and then choose "Clear".

Keyboard

When the Trace window is active, press "Delete" key.



Move

Mouse

Move the mouse into Trace window. Clicking the right mouse button, a shortcut menu will pop up. Select "Move", the icon changing into ⁽ⁿ⁾. Hold down the left mouse, the icon changing into ⁽ⁿ⁾. At this time, drag the mouse, the machining track also moved.

Keyboard

When the Trace window is active, the machining track can be moved by pressing the four direction keys on the keyboard.

♦ Zoom in/out

The user can zoom in/out the machining track via mouse, keyboard or menu.

Menu

Choose "View | [Zoom in] or [Zoom out]".

Mouse Method

Move the mouse into the Trace window and click the right mouse button. Select "Zoom in" or "Zoom out" in the pop-up menu to switch between $\stackrel{\bullet}{\longrightarrow}$ and $\stackrel{\bullet}{\frown}$.

Prompt:

When zooming the machining track with the mouse, the user can zoom in/out a part of machining track which is dragged by the mouse.

When the track is magnified to the maximum size, the system will automatically switch to "Zoom out" mode.

When the track reduced to the minimum size, the system will automatically switch to "Zoom in" mode.

Keyboard Method

When the Trace window is active, the user can zoom in/out the track by pressing "+" or "-"on the keyboard.

♦ Center

It is used to show the center of current machining scope in the central area of Trace window.

Menu Method

Select "View | Center View".



Mouse Method

Move the mouse into Trace window and click the right mouse button. Then select "Center" in the pop-up shortcut menu.

Keyboard Method

Press "Home" key on the keyboard when the Trace window is active.

♦ Fit to Window

This function can make the entire machining track displayed on the Trace window so that the user can view the whole machining track without scrolling.

Menu Method

Select "View | Fit to Window" on the menu bar.

Mouse Method

Move the mouse into the Trace window and click the right mouse button. Select "Fit to Window" in the pop-up shortcut menu.

Keyboard Method

Press " * " on the keyboard when the Trace window is active.

Show Current Point

The current machining position will be displayed in the center of the Trace window.

Menu Method

Choose "View| Show Current Point".

Mouse Method

Move the mouse into the Trace window and click the right mouse button. Select "Show Current Point".

Keyboard Method

Press "End" on the keyboard when the Trace window is active.

♦ Set Zoom Ratio

To show the machining file track in the Trace window at an appropriate scale. This function (Ratio/Set Zoom Ratio) can be found under "View" menu or right-click menu when Trace window is



active.

After selected, a dialog as shown in Fig. 4-34 will pop up. The user can drag the block or use the direction keys to adjust the display scale.

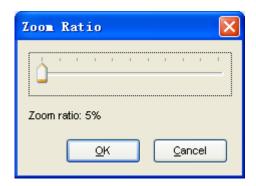


Fig. 4-34 Zoom ratio

♦ Customize Trace View

This function (Customize/ Customize Trace View) can be found under "View" or right-click menu when Trace window is active.

A "Customize" dialog box as below will pop up when this function is selected. This dialog box is used for personalizing the Trace window and self-defining the trace mode and color.

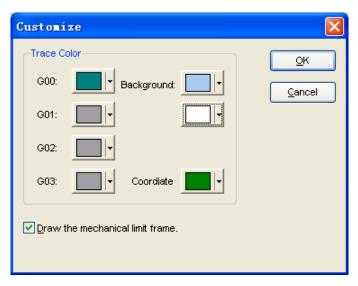


Fig. 4-35 Customize dialog

Clicking on a color button, a color selection box will pop up, as illustrated below.



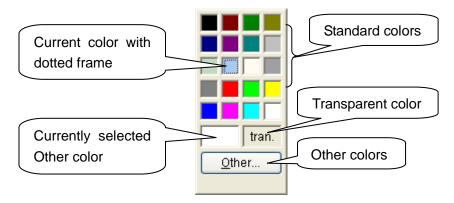


Fig. 4-36 Color selection box

Trace Color

In the Trace window, the user can set different colors for different codes via "Customize Trace View".

- 1) G00 color: this color indicates the track color of G00.
- 2) G01 color: this color indicates the track color of G01.
- 3) G02 color: this color indicates the track color of G02.
- 4) G03 color: this color indicates the track color of G03.

The track color under stepping mode and jog mode is the same as that of G01.

Background Color

It is the background color of Trace window. The user can choose two different colors to realize color gradient.

Coordinate Color

This color is used to highlight the worktable borders and the coordinate system.

Prompt:

If the trace color of a certain code is set as transparent, the track of that code will be hidden. If the background color is set as transparent, the window can't be refreshed properly. Therefore, the user needs to be cautious when selecting "transparent".

♦ View Function

The system provides 9 types of commonly-used views and the user can do swift switching by pressing the Num keys on the small keyboard.

1) Southwest equiaxial lateral view

1



2)	Bottom view	2
3)	Southeast equiaxial lateral view	3
4)	Left view	4
5)	Front view	5
6)	Right view	6
7)	Northwest equiaxial lateral view	7
8)	Top view	8
9)	Northeast equiaxial lateral view	9

Rotation Function

The rotation of machining track can only be realized by the keyboard. The method is to press "ALT" and a direction key simultaneously.

4.12. Log Window

The system log window records all the key operations and events. The user can not only browse all the log information recorded since system start-up this time, but also review the historical log information.

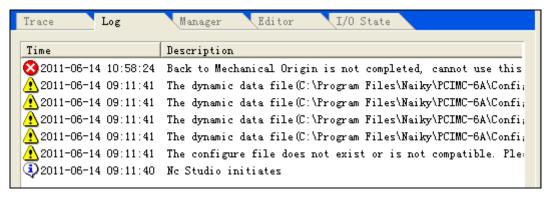


Fig. 4-37 System log window

The log information includes:

- 1) System on/off;
- Auto machining on/off;
- 3) Workpiece coordinates modification;
- 4) Alarms;
- 5) Other system information.

Right clicking on the Log window, a shortcut menu will pop up, as illustrated below.



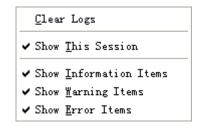


Fig. 4-38 Shortcut menu of system Log window

Clear Logs

It will clear the current log information in the Log window.

Menu method

Choose "Edit| Clear Log".

Mouse method

Move the mouse into the Log window and right click. Then choose "Clear Logs" in the pop-up shortcut menu.

Caution:

Considering that a too large log file will affect system performance and responding time, the system log should be cleared regularly.

Any one of the following items selected, a mark "√" will appear before it. Clicking it again, the mark "√" will disappear, indicating that this item is not selected.

Show This Session

Right click on "Log" window and then choose "Show This Session" from the pop-up shortcut menu, or choose "Show This Session's Logs" under "View".

This function can only show the log information of operation this time. If this item is not selected, the user can view the log information of both operation this time and history operation.

Show Information Items

Right click on "Log" window and then choose "Show Information Items" from the pop-up shortcut menu, or choose "Show Information Items" under "View".

Each information log is marked with the icon .



This function can show the log info like system on/off. If not selected, the log info will be concealed.

Show Warning Items

Right click on "Log" window and then choose "Show Warning Items" from the pop-up shortcut



menu, or choose "Show Warning Items" under "View".

Each warning log is marked with the icon ...



This function can show warning log. If not selected, the warning info will be concealed.

Show Error Items

Right click on "Log" window and then choose "Show Error Items" from the pop-up shortcut menu, or choose "Show Error Items" under "View".

Each error log is marked with the icon .

This function can show error log. If not selected, the error info will be concealed.

Prompt:

The system log information is marked with the icon $\frac{3}{2}$.

4.13. Manager Window

Manager window is where the machining files are managed. NcStudio can manage the machining files saved in the designated directory via a built-in manager. In this window, the user can conduct functions like new, edit, delete, rename and load, etc.

File list box shows the machining files under current folder.

The user can not only enter the designated path into "Current file folder path" or select another path by clicking ... "File list" displays all machining files under current path.

"File extension" box is used to display the extensions of files under current path. The user can delete or add one. The extension of file is also displayed in the "File list" box.

Double clicking one of the files in the "File list" box will load it automatically. The user can also at the lower part to load the selected file. In addition, "File| Open and Load" can click also be used.



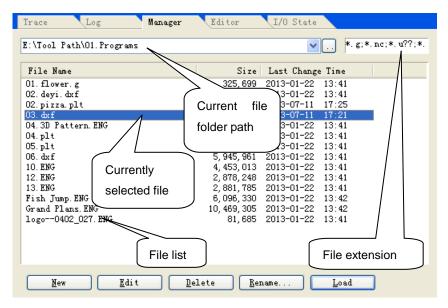


Fig. 4-39 Manager window

Right clicking in the Manager window, a shortcut menu will pop up, as illustrated below:



Fig. 4-40 Shortcut menu in Manager window

♦ New

There are three ways to create a new machining file instantaneously:

One: select "File| New" (shortcut key: Ctrl+N);

Two: right click in the Manager window and select [New] from the pop-up shortcut menu;

Three: click on the lower part of Manager window.

Then the system will automatically generate a new machining file "Untitle1.nc" and the user can decide the save location of the new file.



Fig. 4-41 Save location

Click to choose the save location.

In addition, the user can also edit, delete, rename or load the newly created file. Refer to the contents below for detail.

In addition, the user can also open a processing file by choosing "file (F)| open and load (O)..." from the menu.



Edit

There are three ways to edit the selected machining file;

One: select "Edit| Edit the Selected File";

Two: right click in the Manager window and then select "Edit" from the pop-up shortcut menu;

Three: click on the lower part of Manager window.

And then the system will switch to the Editor window automatically. The user then can do editing in this window. For details, refer to Editor Window.

Delete

There are three ways to delete the selected machining file:

One: select "Edit| Delete the Selected File";

Two: right click in the Manager window and select "Delete" from the pop-up shortcut menu;

Three: click ______ on the lower part of Manager window.

A pop-up dialog box will ask the user whether to delete the selected machining file and whether this file is being edited or processed.

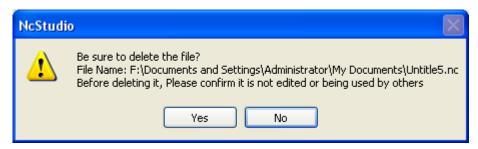


Fig. 4-42 Delete a machining file

Click [Yes] to delete it.

Prompt:

The selected file in the file list box is highlighted (in blue).

Rename

There are three ways to rename the selected machining file:

One: select "Edit| Rename the Selected File";

Two: right click in the Manager window and then select "Rename" from the pop-up shortcut menu;

Three: click Rename... on the lower part of Manager window.

Then the file name will be in edit state, as illustrated in Fig. 4-43:



File Name	Size Last Change Time
Untitle1.nc	8 2011-05-19 17:45
Untitle2.nc	3 2011-06-03 11:13
Untitle3.nc	3 2011-09-13 16:48
Untitle4.nc	3 2013-07-31 13:08
Untitle5.nc	3 2013-07-31 13:08
Untitle6.nc	3 2013-07-31 13:08

Fig. 4-43 Rename dialog box

After entering the file name, click "Enter" key or click on a blank area.

Load

There are five ways to load the selected machining file:

One: select "File| Open and Load";

Two: right click on the Manager window and then select "Load" from the pop-up shortcut menu;

Three: click ____Load on the lower part of Manager window;

Four: click on the toolbar;

Five: right click in the Auto window and then select "Open and Load" from the pop-up shortcut menu.

4.14. Editor Window

On the top of this window are the file name being edited and its path, as shown in Fig. 4-44.

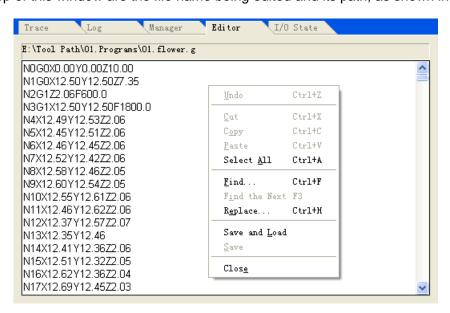


Fig. 4-44 Editor window

It can edit a machining file with a size bigger than 1000M byte (1 G) and thus can fulfill editing requirements of any complex machining file.

Right clicking in the Editor window will eject a shortcut menu for option.

Notice: it is not recommended to edit a file with saved workpiece origin.



4.15. I/O State Window

The I/O State window displays the current state of system I/O ports and is very helpful for system monitoring and breakdown diagnosis.

Caution:

The contents displayed in this window may vary with configuration, control card and requirements of the user. The information provided here is for reference only.

The icons in the front of the ports indicate:

- : Green filled dot means that there is signal input in this port;
- : Red filled dot means that there is no signal input in this port;
- O: Green hollow dot means that there is signal output in this port;
- O: Red hollow dot means that there is no signal output in this port.

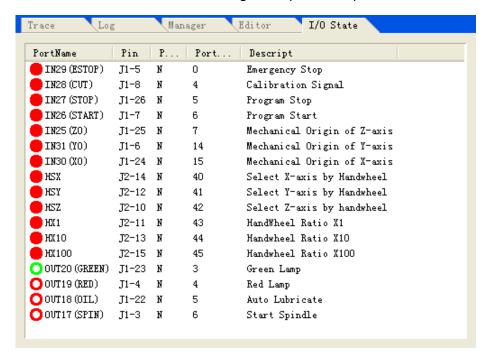


Fig. 4-45 I/O State window



5. NcStudio Menu System

5.1. "File" Menu

This menu includes many options, like "Open and Load", "Unload", "New", as following.

Open and Load

Shortcut key: Ctrl + O. The menu is used for opening a processing file on the hard disk. Clicking the menu item, the system will eject "Open and Load" dialog box, as shown below.

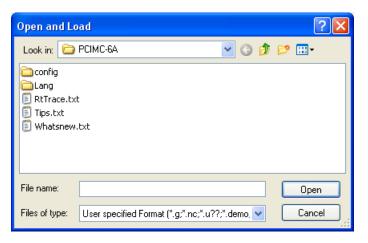


Fig. 5-1 Open and load dialog box

Clicking the drop-down button in Look in: PCIMC-6A can call the processing files under other routes. After selecting the file, click "Open", the name of the file displayed on the title bar.

Unload

It is used to unload the current machining file.

◆ New

It is used to create a new machining file.

After selecting this option, "Editor" window is switched to for file editing. After edit, right click and select "Save" from the pop-up shortcut menu.

Open and Edit

It is used to open an existing machining file and switch to the Editor window to edit it.

Edit Loaded File

It is used to edit the currently loaded machining file.



Save

It is used to save the machining file after editing.

Save as

It is used to resave the current machining file in the Editor window.

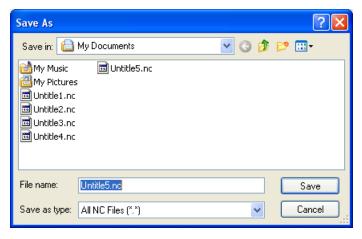


Fig. 5-2 "Save As" dialog

Save and Load

It is used to save and load the current machining file in the Editor window as the currently loaded machining file.

◆ Close

It is used to close the machining file being edited.

Config

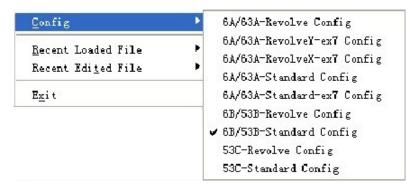


Fig. 5-3 Configuration options

Notice: the configuration is set by the machine tool builder, and the user is not entitled to change it. Otherwise, the machine tool cannot work properly.

Recent Loaded File

This menu item includes a new submenu, displaying the recently loaded machining files. The user can re-load them quickly with this function.



Recent Edited File

This menu item includes a new submenu, displaying the recently edited machining files. The user can re-edit them quickly with this function.

♦ Exit

It is used to close the NcStudio system, invalid in machining state.

5.2. "Edit" Menu

The items in "Edit" menu change with the currently active window in the second window area (including Trace window, Log window, Manager window, Editor window and I/O State window).

Array Machining

This function allows executing array machining on one machining file. Clicking this item, a dialog box will pop up, as illustrated below:

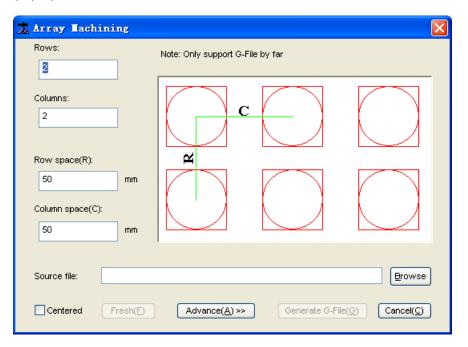


Fig. 5-4 Array machining dialog

Click and select the machining file for array.

After setting the correct columns, rows, row space (as R in the above figure) and column space (as C in the above figure), click [Generate G-File]. And then the newly generated machining file will be loaded to NcStudio automatically.

G codes like G65 and G92 are not supported in array function, neither are subroutines. If they appear in the machining file, the system will prompt to delete them automatically or manually.

To set different row spaces and column spaces, click [Advance], a dialog box ejected, as below.



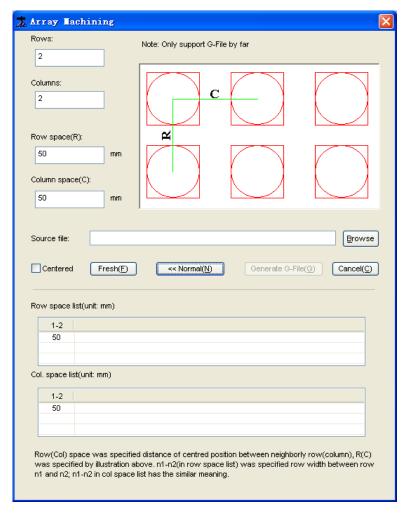


Fig. 5-5 Array machining

"Fresh" is used to update the "Row space list" and "Col. space list" in "Advance" mode after entering the values of "Rows" and "Columns". Then the user can manually set different row/column spaces in these two lists.

Mirror Rotate Machining Setting

This function can conduct mirror and rotation on a machining file. Choosing this menu item, a dialog box will pop up, as shown in Fig. 5-6.



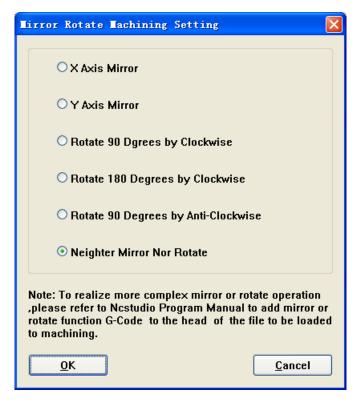


Fig. 5-6 Mirror & rotation machining

After selecting one of the above options and clicking [OK], the newly-generated machining file will be loaded into NcStudio automatically.

5.3. "View" Menu

The items in "View" menu change with the currently active window in the second window area (including Trace window, Log window, Manager window, Editor window and I/O State window).

5.3.1. "View" Menu When Manger, Editor or I/O State Window Activated

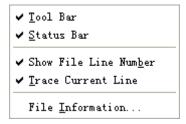


Fig. 5-7 "View" menu 1

Show File Line Number

This function displays/conceals the row number of instructions in the Auto window, only available when the Auto window is activated.



Trace Current Line

The function traces the row number of current instruction in the Auto window during processing.

◆ File Information

Clicking [File Information], a dialog box will pop up, as illustrated below.

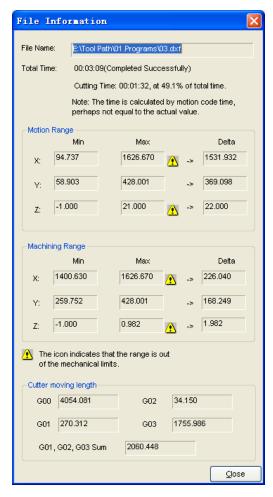


Fig. 5-8 Statistics of machining file

The dialog box displays the statistic information of machining file during auto processing, such as total, machining range, etc. Combining with simulation function, the user can learn various information of machining file quickly and rapidly.

Total Time

Displays the total time of machining and cutting time.

Motion Range

The max. and min. workpiece coordinates of machine tool movement in machining.

Machining Range



The max. and min. workpiece coordinates of machine tool in actual cutting.

5.3.2. "View" Menu When Trace Window Activated

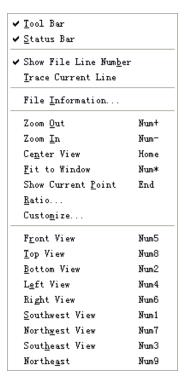


Fig. 5-9 "View" menu 2

Refer to chapter 4.11. Trace window for details of the above submenus.

5.3.3. "View" Menu When Log Window Activated



Fig. 5-10 "View" menu 3

Refer to chapter 4.12 Log Window for details of the above submenus.

5.4. "Operation" Menu

"Operation" menu includes many items, such as "Single Block", "Handwheel Gear", "Set Offsets", etc, which will be introduced separately in the following.



Single Block

Under Single Block mode, the system will enter into Pause state when the motion speed becomes 0. To resume machining, the user needs to click (Start). The system will enter into Pause state again when the speed becomes 0 again. That is to say, Pause state will be entered into after the completion of a block, to resume machining, the user needs to click "Start".

The user can choose this function before or during processing since it is helpful for error diagnosing and failure recovery.

Handwheel Gear

When "Handwheel Gear" is selected under Auto mode, clicking , the system will implement the machining file with the turning of handwheel. When the handwheel is stopped turning, machining will also stop. The machining speed changes with the turning speed of handwheel.

The user can choose this function before machining and this will help him judge whether the machining file is correct.

Set Offsets

Right clicking in any part of NC State Widow can also call this function. Its dialog is as shown in Fig. 5-11.

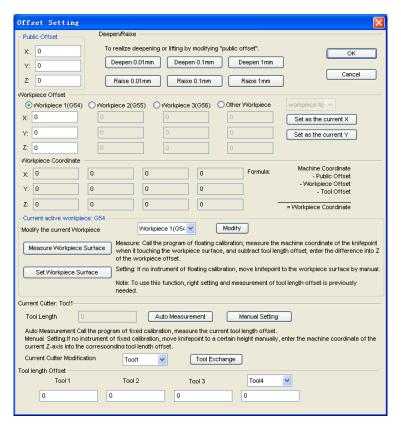


Fig. 5-11 Set offset



Public Offset

Also called external offset. It is used to record the temporary adjustment value of workpiece origin. As it can only be adjusted manually and will not be changed during the execution of any auto function, the value will not be changed during fixed presetting and mobile presetting. For example, if the value is not 0 before presetting, the workpiece coordinate will not be 0 either when presetting completes. The following buttons can be used to modify the value of Z public offset.

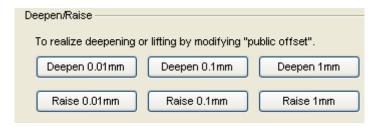


Fig. 5-12 Buttons to modify Z public offset

Clicking one of the above buttons, the Z workpiece origin will move up or down a specified distance to form a new workpiece coordinate system; clicking the button repeatedly, the Z workpiece origin will move a distance accumulated.

Workpiece Offset

The offset of workpiece origin with respect to machine origin. See Fig. 5-13.



Fig. 5-13 Workpiece offset

It displays the machine coordinates of workpiece origin. Manually entering values can be used to set the machine coordinates of workpiece origin, though not recommended.

Workpiece Coordinate

Displaying the workpiece coordinates of current cut point. See below.



Fig. 5-14 Workpiece coordinate

The following buttons can be used to clear X/Y workpiece coordinate, as shown below.



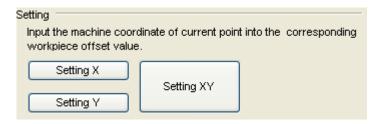


Fig. 5-15 Workpiece coordinate clear

Workpiece coordinate= Machine coordinate- Public offset- Workpiece offset- Tool position offset

Workpiece Surface

The below two buttons are used for auto measure or manually setting current coordinate as Z workpiece origin in floating presetting. See Fig. 5-16.

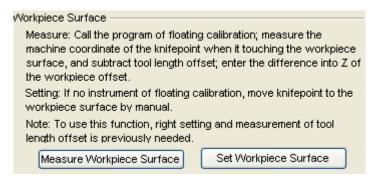


Fig. 5-16 Workpiece surface

Record and Center Division

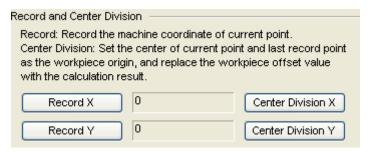


Fig. 5-17 Record and center division

The above buttons are used to get the intermediate point of two points. The method is: first, move the tool to the first target point and then click [Record X], the system recording the X machine coordinate of this point. Secondly, move the tool to the second target point and then click [Center Division X], the system automatically working out the X machine coordinate of the intermediate point. The method to get Y coordinate of intermediate point is similar.

Move to Workpiece Origin

After this function is executed, if the tool nose is below the safe height, the Z axis will move up to the safe height first and then the X axis and Y axis will move to the workpiece origin together; if the tool nose is above the safe height, the X axis and Y axis will move to the workpiece origin together first and then the Z axis will move down to the safe height.



The user can also execute this function by clicking on the toolbar.

Save the Current Workpiece Origin

This function saves the current workpiece origin as well as the name of the file and the machine coordinates of current point into NcStudio, so that the saved workpiece origin can be easily found later. 10 groups of data can be saved at most. See Fig. 5-18.

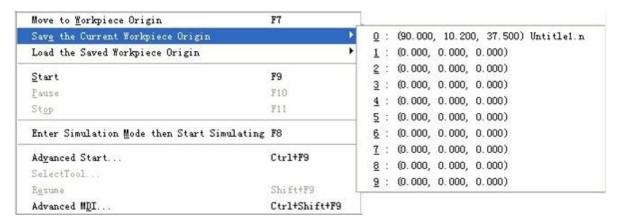


Fig. 5-18 Save the current workpiece origin

◆ Load the Saved Workpiece Origin

It is used to load the coordinate value of the saved workpiece origin.

◆ Start

Clicking [Start], the system will enter into auto processing mode. If the system is under simulation state, it will execute machining file under simulation mode.

This function can also be executed by clicking \textbf{\textbf{N}} on the toolbar.

Pause

During auto processing, selecting [Pause], the system will suspend processing and raise the cutter to enter into "Auto| Pause" state. To resume processing, choose [Start].

When simulating, choosing [Pause], the system will suspend simulation and enter into "Auto| Pause" state. To resume simulation, choose [Start]

The function can also be executed by clicking **u** on the toolbar.

Stop

During auto processing, choosing [Stop], the machine tool will cease processing and raise the cutter to enter into "Auto| Idle" state. This is the normal way to stop when processing.

When simulating, choosing [Stop], the system will suspend simulation and enter into "Auto Idle" state. To start or resume simulation, choose [Start], [Advanced Start] or [Breakpoint Resume], etc.



The function can also be executed by clicking <a>I on the toolbar.

Enter Simulation Mode then Start Simulating

By selecting this menu item, the machine tool will conduct high-speed simulation from the beginning of the machining file, providing a high-speed but vivid simulative processing environment.

Under simulation mode, the system doesn't command the machine tool to do the corresponding mechanical movement, but shows the tool path in the Trace window at a high speed. Through simulation, apart from other appended information, the user can be informed of the machine tool's movement path in advance and thus avoid equipment damage caused by programming errors.

Once simulation starts, this menu item will change into" Stop Simulating then Leave Simulation Mode". Clicking it, the system will stop simulating and exit from the simulation mode immediately.

This function can also be executed by clicking on the toolbar.

♦ Advanced Start

Clicking this menu item, an "Execute (Advanced Options)" dialog box will pop up, as illustrated in Fig. 5-19.

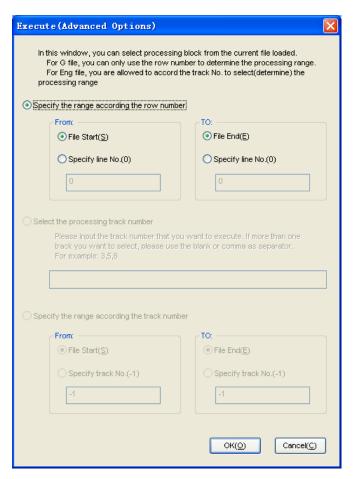


Fig. 5-19 Advanced start

This function allows selecting any blocks for machining. The user can choose the processing



range in the dialog box according to the type of machining file.

Note: if the file loaded is a G code file, only "Specify the range according to the row number" is available, the other two options are unavailable.

If the file loaded is an ENG file, the three options are all available.

♦ Select Tool

It is a function specified for an ENG file. In addition, to enable this function, the parameter "N4093 MachiningEngFileByToolNumber" should be set as "true" first.

Resume

Clicking this menu item, the system will automatically resume processing from the row number stopped last time.

In case of sudden power failure, E-stop, etc, this function (breakpoint resume) can be executed to make the machine tool quickly move to the breakpoint and resume processing, which will save considerable machining time.

This function can also be executed by clicking bon the toolbar.

Advanced MDI

Clicking this menu item, an "Advanced Functions" dialog box will pop up, as shown in Fig. 5-20, including 5 function windows, which are [Rectangle Mill], [Round Mill], [Rectangle Frame Mill], [Round Frame Mill] and [MDI]. Bottom milling and frame milling can be completed in the first four windows simply by entering the values of relevant parameters ("Inner" and "Outer" are used to specify whether milling the inner part of the frame or outer part).



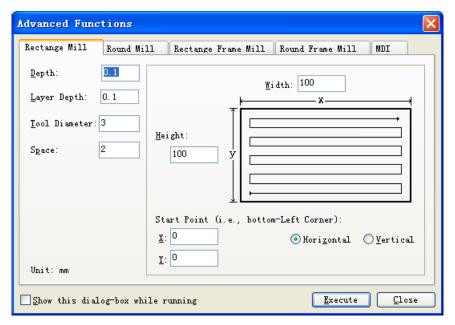


Fig. 5-20 Rectangle bottom milling window

See Fig. 5-21. After entering standard instructions (like G codes, T codes and M Codes, etc) into the edit box of "MDI" window, click "Execute", the system executing the entered instructions instantly. In addition, instructions entered previously are recorded in the window for inquiring. If multiple instructions are entered at one time, ";" is used to separate them from each other. When the instructions are not entered properly, NcStudio will give out a prompt.

If the box before "Show this dialog-box while running" at the bottom is checked, this dialog can still be seen when executing the instructions, for the convenience of rapidly setting relevant parameters of booting milling and frame milling or entering standard instructions.

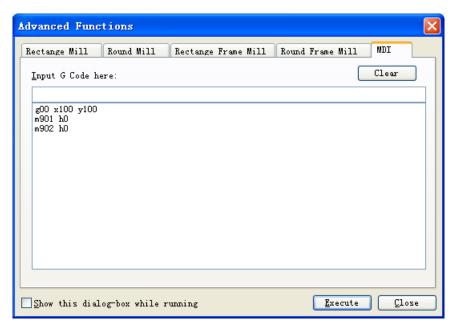


Fig. 5-21 MDI window



Jiggle

This function is for fine tuning without stopping machining, only available during auto processing or in the PAUSE state. See Fig. 5-22.

The result of jiggle will only have an effect on the current machining task. It will become invalid when [Start] or [Resume] is executed after [Stop].

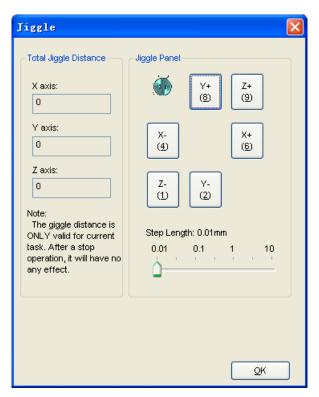


Fig. 5-22 Jiggle dialog box

♦ Mobile Calibrator

Choosing this menu item will eject a dialog box, as shown below.

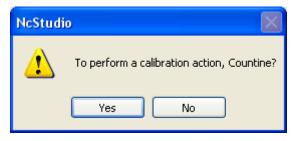


Fig. 5-23 Tool presetting

Choosing "Yes" will execute tool presetting. Refer to chapter 4.9.1 Calibrate the Workpiece Surface for detail.

Choosing "No" will cancel tool presetting.

◆ Fixed Calibrator

Choosing this menu item will eject a dialog box, as illustrated below.



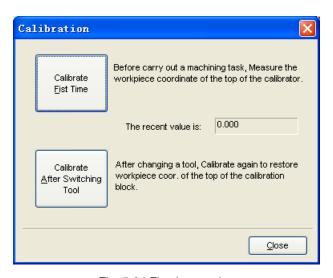


Fig. 5-24 Fixed presetting

Refer to chapter 4.9.3 Fixed Presetting for details. "The recent value" in the above picture is entered automatically by NcStudio.

♦ Back to Mechanical Origin

Also called go home, back to machine origin and back to reference point. Selecting this menu will eject a dialog box, as shown in Fig. 5-25.

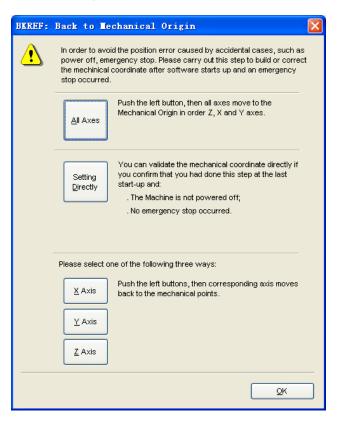


Fig. 5-25 Back to mechanical origin

[All Axes]: all the axes will go home successively (Z axis first and then X and Y axes.).



- [Setting Directly]: directly setting current machine coordinates as correct ones. Before executing this function, the user must confirm that the current X, Y, Z coordinates are right machine coordinates. If the machine tool was turned off or underwent an E-stop before, it is not recommended to execute this function.
- [X Axis], [Y Axis] and [Z Axis]: homing the corresponding axis alone.

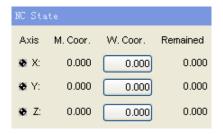


Fig. 5-26 NC state window

After all the axes have returned to machine origin, a mark "*" will appear before each axis in the NC state window.

Back to Fixed Point

The machine tool will move to the fixed point (machine coordinates) automatically when this menu item is selected. The machine coordinates of fixed point should be set in a position facilitating fast tool change and workpiece replacement.

The machine coordinates of fixed point are determined by parameters [N4210], [N4211] and [N4212].

♦ Disable Mechanical Limits

See Fig. 5-27. In case of hard limit alarm, execute this function. The system will disable limit function and remove the alarm. At this time, move the machine tool away from the limit switch to a normal position via the manual buttons in the Manual window.

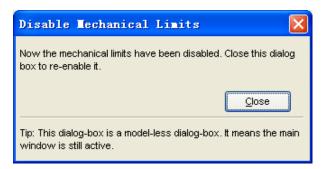


Fig. 5-27 Disable mechanical limits

Caution: pay attention to the direction when moving the machine tool away from the limit switch to a normal position, or the machine tool may be damaged!



Alarm Reset

When an alarm pops up, executing this function will restore the system to the "Idle" state.

♦ Scan Function

Clicking this menu item, a dialog will pop up, as shown in Fig. 5-28.



Fig. 5-28 Scan hole position

This function is mainly for punching. Manually move to the target position (XY), then click "Note" to record the workpiece coordinates, then to the next target position, then record...When finished, click "Save As" to generate a machining file. Since the generated file cannot be loaded into the system automatically, the user needs to load it into NcStudio before machining.

> [Position of REFFER Plane]: a plane from rapid traverse rate to punching speed.

Parameter Restore

NcStudio can backup parameters automatically. Choosing this option, a dialog box will pop up, as illustrated below.



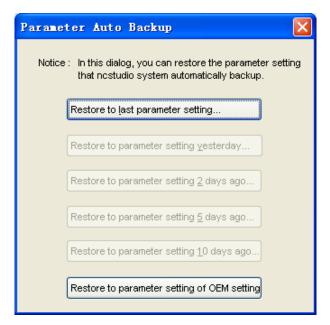


Fig. 5-29 Parameters auto backup

The system provides six kinds of parameter backups: "last parameter setting", "parameter setting yesterday", "parameter setting 2 days ago", "parameter setting 5 days ago", "parameter setting 10 days ago" and "parameter setting of OEM setting". The user can select one of them according to actual situations.

After one of them is selected, NcStudio will exit automatically. At this time, the user needs to re-open it manually.

Set Parameters

It is used to open the parameter window to set parameters. Refer to Chapter 6.3 for details.

5.5. "Machine" Menu

"Machine" menu includes menu items like "Turn on Spindle", "Turn on Coolant", "Turn on Light" and "Modify Tool No.", etc, as following.

♦ Turn on Spindle

It is used to control spindle ON/ OFF.

◆ Turn on Coolant

It is used to control coolant pump ON/ OFF.

♦ Turn on Light

It is used to control lamp ON/ OFF.



Modify Tool No.

This item is used to uniform the current tool No. displayed with the tool No. to be used so that the system can place the current tool to the correct position in the tool magazine or call the right tool from the correct position in the tool magazine, mainly used in tool change.

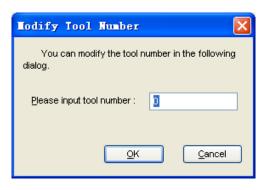


Fig. 5-30 Modify tool number

◆ Feedrate

The feedrate can be 0%, 10%, 20%, 50%, 90%, 100%, and 120%, function similar to "Feedrate" slider block in the "NC State" window. For details, refer to Sliding Block of Feedrate Override in chapter 4.6.2.

♦ Efficiency/Quality Adjustment

Clicking the option, a dialog box will pop up, as illustrated below:



Fig. 5-31 Efficiency – Quality adjustment

Quality and efficiency relates to each other negatively. Giving priority to quality will lead to high processing quality while to speed will result in high processing efficiency.

5.6. "Window" Menu

"Window" menu is consisted of multiple options, such as "Show Auto Window", "Show Manu Window", "Show Calibration Window" and "Show Trace Window", and so on, mainly used to rapidly turn to a window.

5.7. "Help" Menu

"Help" menu includes the following menu items.



◆ Tip of the Day

Selecting this option, a dialog box will pop up, as illustrated below, telling information and operation of NcStudio.

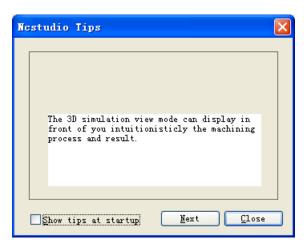


Fig. 5-32 Daily tip

♦ Keyboard Map

Choosing this item, a dialog box will pop up, displaying shortcut key information of NcStudio.

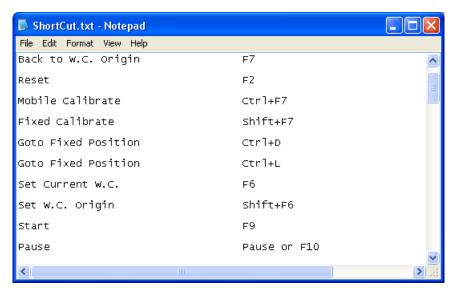


Fig. 5-33 Shortcut key list window

♦ About NcStudio

Choosing this menu item, a dialog box will pop up, telling information about NcStudio version No., control card model number and system registration, etc.



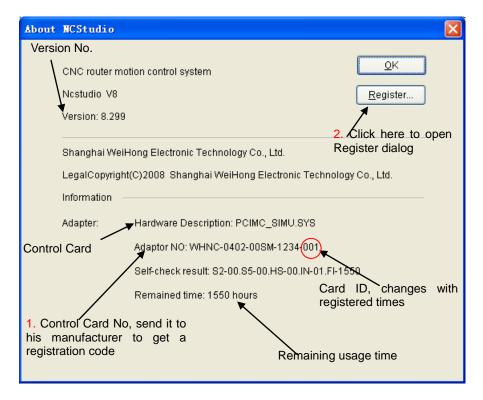


Fig. 5-34 "About NcStudio"

In the above dialog, the user can view such info as version, control card, manufacturer, etc.

Register function is used for limiting the system usage time. When the usage time is used out, the user can write down the Control Card No. and send it to his manufacturer to get a registration code. Then click on the button [Register...] to eject registration code input box, as shown in Fig. 5-35. And then input the received code into the following dialog, and click "OK" to finish register.



Fig. 5-35 Input register

Note: Card ID changes with registered times, reflected in the last three numbers of Control Card No.. When registered times is 0, the last three numbers are 000; when 1, the last three numbers 001.



6. Parameter Setup

Equipped with abundant machining parameters, NcStudio is competent for various machining tasks. This chapter will introduce operator's parameters only. For manufacture's parameters, refer to *Manufacturer's Manual* for detail.

Parameters in NcStudio can also be divided into the following categories: opera parameters, axes parameters, spindle/H.W. parameters, I/O address parameters, compensation parameters, ref. parameters, cutter parameters, other parameters and all parameters.

6.1. Parameter Modification Permission

The parameters viewed vary with privilege. To access manufacture's parameters, password "ncstudio" is needed.



Fig. 6-1 Parameter permission

If there is a need to change the password, click "Change Password" to eject the "Change Password" dialog, as shown below. After entering the old password and new password correctly, click "OK" to validate the new password.



Fig. 6-2 Change password dialog

6.2. Parameter Modification Method

To modify a parameter, double-click on the row where the parameter lies and then enter the data into the pop-up dialog box.

For "True/False" type of parameters, inputting "1" indicates "True" while "0" "False". The user can also directly input "True" or "False".

Prompt: no parameters can be modified in machining.



6.3. Operator's Parameters

No.	Name	Setting Range	Default	When Enabled		
Opera pa	Opera parameters					
	NormalJogFeedrate	0~100000 (mm/min)	1800	Immediately		
N4025	The moving speed of ma	chine tool in manual mode when t	he feedrate	override is 100%.		
	The manual moving spee	d varies with the feedrate override.	i			
	RapidJogFeedrate	0~100000 (mm/min)	2400	Immediately		
N4026	The speed of machine t	ool when one of the manual but	ttons and ac	celeration button		
	(number key 0) are press	ed simultaneously at 100% feedrat	e override.			
N4260	MaxJogFeedrateBefore BKREF	0~100000 (mm/min)	1200	Immediately		
	The max. speed in jog mo	ode before homing.				
N/4024	RapidTravelFeedrate	0~100000 (mm/min)	3000	Immediately		
N4031	The default positioning sp	eed (instead of machining speed).	•			
N/4022	DefaultFeedrate	0~100000 (mm/min)	1500	Immediately		
N4032	The default machining spe	eed (instead of positioning speed).				
	Llas DafaultEs adrata	0: Not use	0	Immediately		
N4034	UseDefaultFeedrate	1: Use	0	Immediately		
	If it is set as "1", the speed	f it is set as "1", the speed specified in the machining file will become invalid.				
	LlcoDofaultSpindloBoy	0: Not use	0	Immediately		
N4035	UseDefaultSpindleRev	1: Use	U	Ininecialely		
	If it is set as "1", the spindle speed specified in the machining file will become invalid.					
	PauseDownSpeed	0~100000 (mm/min)	600	Immediately		
N4027	Plunge rate of Z axis (backing to the cutting point before pause) in continuous machining					
	after pause.					
N4028	PauseUpSpeed	0~100000 (mm/min)	600	Immediately		
144020	Tool lifting speed of Z axis at pause.					
	ToolRasingHWorkCoor	0~9999 (mm)	100	Immediately		
N4049	OnPause	0 3999 (11111)	100	Immediately		
	The pause position of Z a	xis in machining.				
	ToolRasingHeightOnPa	0~500 (mm)	10	Immediately		
N4050	use	0 300 (11111)	10	Ininediately		
	The lifting height of Z axis at pause with respect to cutting point.					
	FixedCalibratorBlockPo	-99999~99999 (mm)	X: 0 Y: 0	Immediately		
	sition (X/Y/Z)	-33333 33333 (11111)	Z: -1			
N4200	X/Y: machine coordinates of X and Y when the tool nose reaching the range of tool					
~	presetting (the nearer to central point, the better).					
N4202		Z axis when the tool nose arriving	=	_		
	surface of tool presetter (running at G00 speed above this height while at presetting spec			presetting speed		
	below this height).					



No.	Name	Setting Range	Default	When Enabled	
N4006	G73_G83SafeHeight	-99999~99999 (mm)	0	Immediately	
144000	Specifying the retract distance after each feed in the G73_G83 cycle drilling comm				
	DirectionWhileFixedDrill	0: +X; 1: -X; 2: +Y; 3: -Y	0	Immediately	
N4007	Stop		Ininiculatory		
	Only valid in X-Y plane (G	617).			
	 IJKIncrementModeValid	0: Invalid	1	Immediately	
N4063	ioranoromentivioue valid	1: Valid	•	Ininiculatory	
111000		e center are with respect to workpi	_		
	1: the coordinates of circle	e center are with respect to the sta	rt point of ma	achining arc.	
	 NeedConfirmClearWC	0: Invalid	1	Immediately	
N1002	11000001111111010011110	1: Valid	•		
11.002		when clearing current workpiece of	coordinates, i	.e. setting current	
	point as workpiece origin,	in order to avoid misoperation.	I	1	
	ActionAfterProgrammin	0: Keep still; 1: Back to fixed			
	g	point; 2: Back to workpiece	0	Immediately	
	9	origin			
	0: Keep still; after machining ends normally, the spindle remains in the stop position.				
N4005	1: Back to fixed point; after machining ends normally, the machine tool will go to the				
	position set by parameters "N4210", "N4211" and "N4212" (machine coordinates)				
	automatically.2: Back to workpiece origin; after machining ends normally, the machine tool will return to				
		the machine	tool will return to		
	the current workpiece origin automatically.				
N4029	JiggleFeedrate	0~100000 (mm/min)	60	Immediately	
	The speed in jiggle.				
N4030	JiggleStepLength	0.01~0.5 (mm)	0.01	Immediately	
	The moving distance of machine tool in each jiggle.				
	ZDownFeedrateOption	0~3	0	Immediately	
	0: No special treatment; parameter "N4045" is invalid.				
	1: N4045 enabled when only Z axis moves downward; feeding speed is decided by				
N4044	parameter N4045 when set as 1.				
	2: N4045 enabled when Z-axis downward movement included; when the Z axis moves				
	downward (no matter whether X axis and Y axis moves or not), feeding speed is decided				
	by N4045.				
	3: Slowly regulate feed sp		1	T	
N4045	Z_DownFeedrate	0~100000 (mm/min)	480	Immediately	
	Enabled when parameter N4044 set as "1" or "2".				
	SafeHeight	0.001~1000 (mm)	10	Immediately	
N4051	Calculated with respect to workpiece origin; the system regards it is safe to move				
	horizontally at this height; mainly used in "back to workpiece origin" and "breakpoint"				
	resume".		1	1	
N4210	FixedPointPosition	-99999~99999 (mm)	0	Immediately	



No.	Name	Setting Range	Default	When Enabled		
~	(X/Y/Z)					
N4212	The machine coordinates of fixed point; used together with parameter N4005.					
PLTFileTi	ranslatingParameters					
N4070	SafeHeightAtG00Feedr ate	0∼99999 (mm/min)	1	After re-loading		
	The tool lifting height of Z	axis in rapid traverse when machi-	ning a PLT fil	e.		
N4071	PLTUnit	0.001~99999 (mm/plu)	10	After re-loading		
	PLTToolsDistanceWhile ProcessArea	0.001~99999 (mm)	0.025	After re-loading		
N4072	The ToolsDistance (tool s	space) should be smaller than too	ol diameter w	hen machining a		
N4073	TwoDimensionalFileDep th	-99999~0 (mm)	-1	After re-loading		
	The machining depth of 2	D PLT file.				
DxfFileTr	anslatingParameters					
N4080	SafeHeightAtG00Feedr ate	0∼99999 (mm/min)	1	After re-loading		
	The tool lifting height of Z axis in rapid traverse when machining a DXF file.					
N4081	TwoDimensionalFileDep th	-99999~0 (mm)	-1	After re-loading		
	The machining depth of 2D DXF file.					
N4082	TheSourceOfMachineD epth	0~1	0	After re-loading		
N4002	0: From parameter 1: From DXF file					
N4083	DepthDelta	-99999~0 (mm)	-1	After re-loading		
114003	The machining depth of 2	D file each time in layer machining	ļ.			
	UseFirstPointAsOriginIn	0: Invalid	1	After re-leading		
	DXFFiles	1: Valid	1	After re-loading		
	0: set the origin in the DXF file as workpiece origin					
N4084	1: set a user-defined point in the DXF file as workpiece origin. For instance, when drawing					
	a picture in CAD, draw a point (better near or inside the picture). The system will treat this					
	point as workpiece origin and not process it. If there are several points in the DXF file, the					
	first drawn point will be set as workpiece origin.					
	EnableMachineDividuall	0: Invalid	0	After re-loading		
N4085	У	1: Valid		, and the second		
	If set as "1", the system will not process the next shape until finishing current one.					
	MethodForDrillingDXFFi	0~1	0	After re-loading		
N4086	les	es a la l				
	Hole machining mode in machining a DXF file. 0: Once done; 1: Reciprocating chip					



No.	Name	Setting Range	Default	When Enabled		
	removal					
N.4007	EachDepthForPolyDrill	0∼99999 (mm)	0.5	After re-loading		
N4087	Each drilling depth in reci	procating chip removal mode.				
ENGFile1	TranslatingParameter					
	SafeHeightAtG00Feedr	0~99999 (mm/min)	1	After re-loading		
N4090	ate	0 199999 (11111/111111)	I	After re-loading		
	The tool lifting height of Z	axis in rapid traverse when machi	ning an ENG	file.		
	PauseAndPromptWhile	0~1	1	After re-loading		
N4091	ChangeTools		-			
11.001	= = = = = = = = = = = = = = = = = = = =	ompt tool change when it is time fo	r tool change	when machining		
		not prompt; 1: Pause and prompt	<u> </u>	ı		
	MachiningEngFileByToo		0	After re-loading		
N4093	INumber "4"		10. 1. 1			
		ng will be executed in terms of the s	-	number, and only		
		onding to this tool will be processe	ea.			
N4094	PauseTimeAfterEachCy	0∼99999 (ms)	0	After re-loading		
N4U94	The dwell time after each cycle in ENG file machining.					
	DeepHoleMachiningWa	cycle in LIVO file machining.				
	y	0~1	0	After re-loading		
N4095	Deep hole machining mode. 0: Reciprocating chip removal; 1: High-speed reciprocating					
	chip removal	and or recorpiosaling outpersons a	.,g op	ood roo.prooduring		
	RETRACT_VALUE	0∼99999 (mm)	1	After re-loading		
N4096	Retract distance after each	ch feed in high-speed reciprocating	chip remova			
	MachiningEngFileModif	0: Invalid		A.C. 1 11		
N4097	yToolNumber	1: Valid	0	After re-loading		
	MachiningGFileByToolN	0: Invalid	0	After a leasting		
N4129	umber	1: Valid	0	After re-loading		
	Whether to execute mach	hining according to the specified tool number.				
	Z_Axis_Stop_Options	0~2	0	Immediately		
N8020	The position of Z axis at pause. 0: To raise a given distance; 1: To specified workpiece					
	coordinate; 2: To specified machine coordinate					
	Z_Axis_Stop_Pos_in_M	-350∼0	0	Immediately		
N8021	CS	330 0	o o	Illinoalatory		
	The machine coordinate of Z axis at pause, available when parameter N8020 is set as "2".					
N8022	 SwitchAxisSafePrompt	0: Invalid	1	Immediately		
	1: Valid					
Axes par			Т			
N1150	CheckWorkCoordinateR	0: Invalid	0	Immediately		
~	ange (X/Y/Z)	1: Valid	-	2 22		



No.	Name	Setting Range	Default	When Enabled		
N1152	If set as "1", the system will check whether machining is within the workpiece coordinate					
	range (upper limit and lower limit).					
N1160 ∼	WorkCoordinateLowerLi mit (X/Y/Z)	-99999~99999 (mm)	-10000	Immediately		
N1162	The lower limit of workpie	ce coordinate in each axis.	•			
N1170 ~	WorkCoordinateUpperLi mit (X/Y/Z)	-99999~99999 (mm)	10000	Immediately		
N1172	· '	ece coordinate in each axis.				
	H.W. parameters	and occidentate in each date.				
Spiriule/i	1.vv. parameters	0: Invalid				
N0004	StopSpindleWhenFinish	1: Valid	1	Immediately		
	Whether the spindle stops	s rotating when machining stops.				
NOOSE	StopSpindleWhilePause	0: Invalid 1: Valid	1	Immediately		
N0005	Stop					
		ating when machining pauses.				
Compens	sation parameters			Т		
N3004	CutterCompensationVali d	0: Invalid 1: Valid	0	Immediately		
110001	-	Whether to enable tool compensation.				
	CUTTER_COMPENSA TION_DIRECTION	0~2	0	Immediately		
	Specifying the direction of tool compensation. 0: No tool compensation; 1: Left tool					
	compensation; 2: Right to	ol compensation	·			
N3004	Tool Rotary Direction Right Compensation along Tool Moving Direction Offset Left Compensation along Tool Moving Direction Offset Tool Moving Direction					
	Left Tool Compensation Right Tool Compensation					
Ref. para	Ref. parameters					
	MoveToMechanicalPoin	0: Invalid	1	Immediately		
N2001	tBeforeMachining	1: Valid	-	•		
	When set as "1", homing will be prompted and must be executed before each machining.					
	when "0", the system will not give a prompt and can execute machining directly.					
Cutter pa	arameters					
N14900	MobileCalibratorBlockT	0~10000 (mm)	20	Immediately		
141-300	hickness 0~10000 (mm) 20 immediately					



No.	Name	Setting Range	Default	When Enabled
	The max. tool length.			
N14901	ToleranceOfToolBroken	0∼100 (mm)	0.5	Immediately
N 14901	The allowable tolerance w	vhen checking broken tools.		
N15021	Diameter	(mm)	0	Immediately
N 15021	Tool diameter.			
N15022	Length	(mm)	0	Immediately
1413022	Tool length.			
N15023	DiameterFray	(mm)	0	Immediately
N 15025	Wear loss of tool diamete	r.		
N15024	LengthFray	(mm)	0	Immediately
N13024	Wear loss of tool length.			
N15030	CutterPositionOffset		0	Immediately
~	(X/Y/Z)			IIIIIIediately
N15032	The offset between current tool and the first tool.			
Other pa	rameters			
	AutoBackToZero	0: Invalid	0	After restart
N7003		1: Valid		/ itel restart
	Whether to go home auto	matically after starting the system	each time.	_
	MachTaskEndInformTyp	0~2	0	Immediately
N7017	е			
	0: Red light off; 1: Red light on for 3s; 2: Red light on until there is mouse or keyboard			
	input, then yellow light on			
	DelayTimeForCloseAirV	0~100000 (ms)	1000	Immediately
N7312	alve			
	The delay time for tool change.			



7. Operation Steps

After installing the control card and software according to chapter 2.2.1 and 2.2.2, the system is ready for use and can be opened. Then load a machining file and start debugging & commissioning.

7.1. Starting-up

Before starting the computer, make sure that the machine tool has been well connected to the computer properly. Then power on the machine tool and computer. Then open NcStudio.

7.2. Machine Reset (Optional)

This operation is provided for machine tools with the function of backing to machine origin.

For machine tools supporting "back to machine origin" function, choosing "back to mechanical origin" menu item will command the machine tool to return to the mechanical origin automatically and adjust the coordinate system.

As NcStudio will save the current coordinates if it exits normally, so under certain circumstances, such as after normal system shutdown, there is no need to "back to mechanical origin" before resuming machining after re-opening the system.

Additionally, this operation can also be skipped if the user is sure about the accuracy of current coordinates.

7.3. Load Machining File

Generally speaking, a machining file has to be loaded before machining begins. Otherwise, some functions related with auto-processing will be unavailable.

Select [Open & Load] from [File] to eject a dialog box, and then choose the file to be processed.

After clicking [Open], the machining file will be loaded into the system automatically. At this time, the user can press "CTRL+1" to switch to "Auto" window, where the user can view the current machining file.

7.4. Manual Operation

After switching to [Manual] window, the number keys on the keyboard can be used to operate the machine tool manually to check whether the direction of each axis is right.

The correlation is as follows:

6 Positive direction of X axis

4 Negative direction of X axis



8	Positive direction of Y axis
2	Negative direction of Y axis
9	Positive direction of Z axis
1	Negative direction of Z axis

Pressing any one of the above keys and the number key 0 simultaneously will command the machine tool to move at rapid jog speed.

7.5. Set Workpiece Origin

The workpiece origin is defined as the coordinate origin of X, Y and Z in the machining file. Before machining starts, the workpiece origin should be fixed first. The steps are:

Manually move X axis and Y axis to the intended workpiece origin position, and then clear the coordinates of current position by clicking the "W.Coor." buttons (X, Y) in the "NC State" window. The system will then conduct machining with the current position as the workpiece origin.

Through the above steps the workpiece origin of X axis and Y axis are fixed. To set the workpiece origin of Z axis, more precise operation is needed. Combined with machine tool hardware, the system supports Z axis presetting (calibration) function.

After all these operations, the workpiece origin is confirmed.

7.6. Check Ports in I/O State Window

I/O state window displays ports that indicate the communication status between hardware and software, used for system monitoring and fault diagnosis. For details, refer to chapter 4.15.

The method to modify the polarity of port: select the port (ports) to be modified polarity, then press "Ctrl+Alt+Shift" and right click simultaneously, a dialog as follow pop-up, then select "Toggle Polarity". Modification to port polarity becomes valid after software restart.



Fig. 7-1 Select toggle polarity

7.7. Set Speed Parameters

7.7.1. LinearAcceleration (N4053)

It is used to describe the acceleration / deceleration ability of a single axis, with unit mm/s². The



value is determined by the physical characteristic of machine tool, such as quality of movement part, torque, resistance, cutting load of feed-motor, and so on. The larger the value is, the less time spent in the process of acceleration / deceleration will be, and the higher the efficiency will be. Generally, for servo motor systems, the value is between 400 and 1200. Set the value smaller at the beginning; make the machine tool perform various typical movements for a period of time, and carefully observe it; if there is no abnormal situation, increase the value gradually; otherwise, decrease the value and reserve 50% ~ 100% insurance allowance.

7.7.2. ConnectionAcceleration (N4054)

It is used to describe the acceleration/deceleration ability in synchronized motion of multi-feed-axis, with unit mm/s². The value limits the maximum speed of machine tool in circular movement. The larger this value is, the higher the maximum allowable speed on circular movement of machine tool will be. Generally, for servo motor systems, the value is between 1000 and 5000; for heavy machine tools, the value should be smaller. Set the value smaller at the beginning; make the machine tool perform various typical movements for a period of time, and carefully observe it; if there is no abnormal situation, increase the value gradually; otherwise, decrease the value and reserve 50% ~ 100% insurance allowance.

7.7.3. ReferenceCircleMaxSpeed (N4058)

Maximum speed of reference circle (ReferenceCircleMaxSpeed) corresponds to arc speed limit function. When a machine tool processes an arc, it will vibrate due to centripetal force. To reduce this kind of vibration, the software limits machining speed during machining an arc in terms of centripetal acceleration. Take default setting as an example, the maximum line velocity of the reference circle (Diameter:10mm) is 1800mm/min.

The formula to calculate centripetal acceleration is as following:

$$a = \frac{v^2}{r}$$

Among the formula, r = (10/2)mm; v = 1800mm/min;

Thus centripetal acceleration a can be calculated; when other arcs are processed, this centripetal acceleration is the maximum allowable centripetal acceleration. Arc speed will be limited, if it is too large causing centripetal acceleration larger than a calculated in this formula.

7.7.4. MinSpeedInACircularMotion (N4059)

Minimum speed of reference circle (MinSpeedInACircularMotion) also corresponds to arc

76



speed limit function. a calculated in the last chapter is not the only criterion for arc speed limit function.

$$a = \frac{v^2}{r}$$

According to the above formula, in processing an arc with small radius, the line speed will be limited quite low caused by arc speed limit, which will be a waste of time. Therefore, the software provides this parameter, which is the minimum speed for circular motion. However small the arc radius is, the machining speed will not be smaller than the value of this parameter.

Usually, given the drive ability of servo motor, frication of machine assembly, and endurance capacity of mechanical components, the maximum speed of the three axes in actual using can be limited by modifying the manufacturer parameter "AxisMaxFeedrate" (N4250~N4252).

7.8. Execute Auto Machining

Auto machining means that the machine tool processes the loaded machining file automatically.

◆ Start Auto Machining

Select [Operation| Start] or click on the toolbar or press the shortcut key F9. The machine tool will execute machining automatically from the first line of machining file.

Stop

During auto machining, selecting [Operation| Stop] or • on the toolbar or pressing the shortcut key F11 will stop machining immediately. The system will then enter into "IDLE" state. This is how to make the system stop in an accurate and orderly way and also the recommend one.

Note:

When high-speed smooth connection is adopted, the system will stop when the connection speed becomes 0.

Pause

During auto processing, to suspend processing, select [Operation| Pause] or click on the toolbar or press the shortcut key F10. The system will then suspend processing immediately. To continue processing, choose [Operation| Start] or click on the tool bar or press F9.

Advanced Start

Selecting [Advanced Start], a dialog box will pop up. Then select start and end row No.. Refer to "Advanced Start" in chapter 5.4 "Operation" Menu for detail.



8. Precautions in Operation

8.1. Precautions for Multi-Task Executing

- It is recommended that the user should consider the computer memory and not open too many windows at the same time.
- For some application procedures, such as games, VCD player, etc, they might not run stably and smoothly. They are likely to take excessive system resources like memory and CPU time-slice during running and at last cause computer crash. Therefore, during processing, in order to avoid processing interruption caused by system crash, it is recommended not to open these procedures.

8.2. Precautions for Homing

Homing (backing to mechanical point/ reference point/ machine origin) process varies with the requirements of different systems. For systems with a high requirement for precision, the process of machine reset will take a long time. Pay attention to system state. Do not exit from the "Back To Mechanical Origin" dialog until the system enters into "Idle" state. Otherwise, the "back to mechanical origin" process will be artificially terminated instead of being normally finished.

If the "back to mechanical origin process" is terminated manually, the consequences will be:

- As the limit (mechanical origin) signal is still on, port alarm may occur;
- Inexact positioning may occur: the calibration function of "back to mechanical origin" is damaged manually and as a result, the machine coordinates become inaccurate;
- Soft limit function becomes ineffective: as the "back to mechanical origin" process has not been finished, the system will regard the soft limit function as ineffective until "back to mechanical origin" process is finished.



9. Shortcut Key List

Shortcut Key	Function	Shortcut Key	Function		
Global shortcut keys					
ESC	Shift among windows	TAB	Shift among controls		
Ctrl+1	Show auto window	Ctrl+2 /ScrollLock	Show manual window		
Ctrl+F1	Switch to Z1	Ctrl+F2	Switch to Z2		
Ctrl+F7	Floating presetting	Ctrl+F9	Advanced start		
Ctrl+Home	Go home	Ctrl+Enter	Full screen		
Ctrl+TAB	Switch among folding windows	Ctrl+Del	Clear trace window		
Ctrl+Shift+F9	Execute machining instructions	Ctrl+A	Select all		
Ctrl+C	Сору	Ctrl+E	Open and edit		
Ctrl+F	Search	Ctrl+H	Replace		
Ctrl+I	Show machining info	Ctrl+N	New		
Ctrl+O	Open and load	Ctrl+P	Edit		
Ctrl+S	Save	Ctrl+U	Unload		
Ctrl+V	Paste	Ctrl+X	Cut		
Ctrl+Z	Undo	ALT+1/F4	Show trace window		
ALT+2	Show log window	ALT+3	Show manager window		
ALT+4	Show editor window	ALT+5	Show I/O state window		
F3	Find next	F5	Direct positioning		
F6	Set workpiece coordinates of current point	F7	Back to workpiece origin		
F8	Enter (exit) simulation	F9	Start		
F10/Pause Break	Pause	F11	Stop		
F12	Return to tool change position	Shift+F6	Set as workpiece origin		
Shift+F7	Fixed presetting	Shift+F9	Breakpoint resume		
Shortcut keys in man	ual window				
ScrollLock	Activate manual window	4	X- (Jog and increment mode)		
6	X+ (Jog and increment mode)	2	Y- (Jog and increment mode)		
8	Y+ (Jog and increment mode)	1	Z- (Jog and increment mode)		
9	Z+ (Jog and increment mode)				
Shortcut keys in trace	e window				



Shortcut Key	Function	Shortcut Key	Function
Home	Center	End	Show current machining point
+	Zoom in	-	Zoom out
*	Fit to window size	5	Front view
8	Top view	2	Bottom view
4	Left view	6	Right view
1	Southwest view	7	Northwest view
3	Southeast view	9	Northeast view
Alt+→ or Alt+←	Rotate around Z axis	Alt+ ↑ or Alt+ ↓	Rotate around X axis
Alt+PgUp/Alt+PgDn	Rotate around Y axis		



10. Software License Agreement

License:

Shanghai Weihong Electronic Technology Co., Ltd. (hereinafter referred to as Weihong Company) grants you the right to use this software, for which you must guarantee that you will not use, copy, revise, rent, or transfer this system or any part of this system for any other purposes beyond clauses made in this agreement.

You must guarantee:

- 1. You use this system only on one set of equipment;
- 2. You make read-only copy of this system only for backup or file management purpose and the copy is to be used on this equipment only;
- 3. You can not transfer this system and license agreement to a third party unless the third party accepts the articles and conditions listed in this agreement;
- 4. When transfer happens, you should pass all the copies of the original documents and the supplementary documents to the third party or destroy all the copies un-transferred.

You can use this system in a multi-user environment or network system only at one of the following premises:

It is stipulated in explicit terms that you are allowed to use this system in a multi-user environment or network system.

You have purchased license for each node and terminal using the system.

You must guarantee not to:

- 1. Re-transfer this permission of this system;
- 2. Conduct reverse engineering, disassembling or disintegration on this system;
- 3. Copy or deliver all or part of this system to a third party unless there is explicit stipulation made in this agreement allowing you to do so.

When you transfer this system or copies of all or part of this system to a third party, your right to use this system terminates automatically.

Copyright and Proprietary Rights:

With copyright reserved, this system and document are protected by the copyright law of China and provisions of international agreement. You are not allowed to remove the copyright statement made in this system and should guarantee to copy the copyright statement in all the duplicates you made for this system (the entire system or part of the system). You agree to stop any form of illegal copying of this system and document.

After-sales Guarantee:

Weihong Company guarantees that within 90 days after the selling of this system, there is no



material or craft defect in the software carrier in normal use. When a defect has been confirmed, our only responsibility is to exchange the software carrier. This is also the only compensation we can make to you. This after-sales guarantee compensation is invalid for any carrier defect caused by accidents, abuse or maloperation. The exchanged software carrier enjoys the remaining guarantee time of the original software carrier or a 30-day guarantee time. Among them, the longer one will be adopted.

Except for the after-sales guarantee made above, this system does not enjoy any other forms of after-sale guarantee.

Responsibility limited:

The above guarantee, whether made explicitly or by implication, constitutes the entire contents of the guarantee, including guarantee for the commerciality and applicability of special application aim. Whether you follow other clauses in this agreement or not, Weihong Company, as well as its agents and sales staff, will not be responsible for any profits loss, availability loss, business break-off or any forms of indirect, special, accidental or inevitable damage or claim made by any third party generated from the using of this system, even Weihong company has been informed of the possible occurrence of such events in advance.

Permission termination:

Weihong Company can terminate the permission at any time once you violate any term or condition made in this agreement. When the permission terminates, you are required to destroy all the copies of this system and documents or return them to Weihong Company.

Applicable Law:

Intellectual Property Rights Protection Regulations, Copyright Law, Patent Law and so on.

Now, we affirm that you have already read through this agreement and understood it thoroughly and agreed to obey all of the provisions and conditions of this agreement strictly.

Shanghai Weihong Electronic Technology Co., Ltd.