

## UM1655 User manual

# Audio Engine post-processing on STM32F4xx - Omni2 multichannel library

#### Introduction

The Audio Engine post-processing on STM32F4xx - Omni2 multichannel library user manual describes the software interface and requirements of the Omni2 multichannel module. It has been designed for the audio application developers who integrate this module into a main program. It provides a rough understanding of the underlying algorithm.

The Omni2 multichannel library implements the multichannel audio virtualization from mono to 7.1 input signals, including the stereo widening effect for stereo inputs.

This library is part of the STM32-AUDIO100A firmware package.

July 2015 DocID025072 Rev 4 1/26

Contents UM1655

## **Contents**

1	Mod	Module overview			
	1.1	Algorithm function			
	1.2	Module configuration			
	1.3	Resources summary			
2	Mod	ule Interfaces			
	2.1	APIs			
		2.1.1 omni2_reset function			
		2.1.2 omni2_setParam function			
		2.1.3 omni2_getParam function			
		2.1.4 omni2_setConfig function			
		2.1.5 omni2_getConfig function			
		2.1.6 omni2_process function			
	2.2	External definitions and types			
		2.2.1 Input and output buffers			
		2.2.2 Returned error values			
	2.3	Static parameters structure			
	2.4	Dynamic parameters structure 14			
3	Algo	orithm description			
	3.1	Processing steps			
	3.2	Data formats			
	3.3	Performance assessment			
4	Δnn	lication description			
•		System requirements and hardware setup			
	4.1	4.1.1 Recommended setup for stereo widening effect			
		4.1.2 Recommended setup for multichannel virtualizer effect			
	4.0	·			
	4.2	Recommendations for an optimal setup			
		4.2.3 Module integration summary			



UM1655		Contents
5	How to run and tune the application	24
6	Revision history	25



List of tables UM1655

## List of tables

Table 1.	Sampling rates	6
Table 2.	Resources summary	8
Table 3.	Frequency requirements (MHz)	9
Table 4.	omni2_reset	10
Table 5.	omni2_setParam	11
Table 6.	omni2_getParam	11
Table 7.	omni2_setConfig	11
Table 8.	omni2_getConfig	12
Table 9.	omni2_process	12
Table 10.	Input and output buffers	
Table 11.	Returned error values	13
Table 12.	Static parameters structure	
Table 13.	Dynamic parameters structure	15
Table 14.	Setup examples	18
Table 15.	Virtualized sound compliant with ITU-T 7.1 speaker layout standards	20
Table 16	Document revision history	25



UM1655 List of figures

## List of figures

Figure 1.	Mono to stereo perception for mono inputs	. 7
Figure 2.	Stereo widening perception for stereo inputs	. 7
Figure 3.	Virtualizer perception (up to 7.1 channels)	. 8
Figure 4.	Block diagram of the Omni2 module	16
Figure 5.	Setup for stereo widening effect	18
Figure 6.	Setup for multichannel virtualizer effect	
Figure 7.	API call procedure	23



Module overview UM1655

## 1 Module overview

## 1.1 Algorithm function

The module provides functions to handle mono to stereo expansion, stereo widening and multichannel audio virtualization depending on the used library.

*Table 1* describes the supported sampling rates and the input/output formats depending on which library is used:

Table 1. Sampling rates

Library	Audio effect	Channel conversions	Supported sampling frequencies																					
	Mono2Stereo	1.0 to 2.0																						
		1.0 to 3.0 (2.0 + center)																						
	Stereo Widening	2.x to 2.0																						
		2.x to 3.0 (2.0 + center)																						
lib_omni2_multichannel_m4		Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo Widerling	Stereo widering	Stereo Widerling	Otered Widerling	Otered Widerling	Stereo Widerling	Stereo Widerling	otered widering	3.x to 2.0	32, 44.1 and 48 kHz					
		3.x to 3.0 (2.0 + center)	02, 1111 and 10 mil																					
	Stereo Widening for matrix encoded input	2.xt to 2.0																						
		2.xt to 3.0 (2.0 + center)																						
	Multichannel Virtualization	5.x to 2.0																						
		5.x to 3.0 (2.0 + center)																						
		Virtualization	Virtualization	Virtualization	Virtualization	Virtualization	Virtualization	Virtualization	Virtualization	Virtualization	7.x to 2.0													
		7.x to 3.0 (2.0 + center)																						

The module is fully functional and validated with the configurations in green in *Table 1* above.

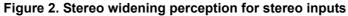
The figures below present the effect perception with only two physical loudspeakers.

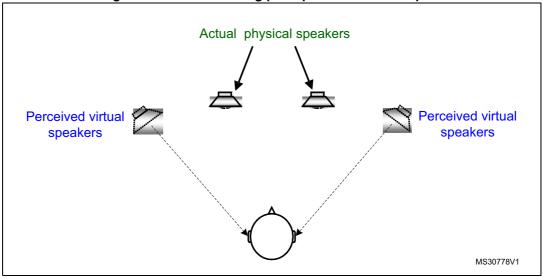
UM1655 Module overview

Sound image has a much larger size if left and right channels are decorrelated

Sound image has a signal spot for mono signal

Figure 1. Mono to stereo perception for mono inputs





Module overview UM1655

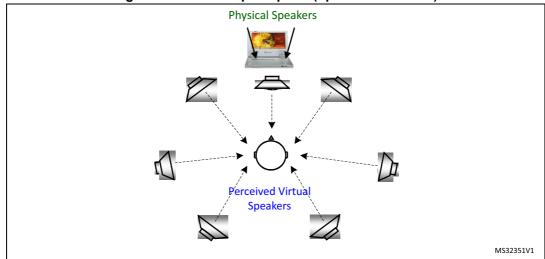


Figure 3. Virtualizer perception (up to 7.1 channels)

The virtualizer perception (up to 7.1 channels) gives the listener the impression of a multispeaker sensation with stereo speakers.

The listening angle corresponds to the angle between the listener and the physical speakers, *Section 4.1: System requirements and hardware setup.* "\_LS" refers to Largely Spaced speakers, that is about 30 degrees listening angle, "\_CS" refers to Closely Spaced speakers, that is about 20 degrees listening angle and "\_VCS" refers to Very Closely Spaced speakers, that is about 10 degrees listening angle.

## 1.2 Module configuration

The module supports mono and multichannel interleaved 16-bit and 32-bit I/O data up to 7.1 format.

lib\_omni2\_multichannel\_m4.a and lib\_omni2\_multichannel\_32b\_m4.a libraries should be used for the multichannel virtualization use case, while it also supports stereo widening effect.

## 1.3 Resources summary

Table 2 contains the module requirements for the Flash, stack and RAM memories.

Flash code Flash data **Static** Dynamic Omni2 Stack stereo (.text) **RAM RAM** (.rodata) Omni2 for multichannel 8136 Bytes virtualization 2064 Bytes 310 Bytes 3100 Bytes 1344 Bytes Omni2 for multichannel 8130 Bytes virtualization, 32 bits I/O

**Table 2. Resources summary** 

The required core frequencies (in MHz) on *Table 3* are measured on real HW running on STM32F407IG chipset, with 10 ms buffers at 48 kHz.



UM1655 Module overview

Table 3. Frequency requirements (MHz)

	Required MHz (for 16 or 32-bit IO)
Mono2Stereo	4.8
2.0 => 2.0 Largely Spaced Speakers	15.5
2.0 => 2.0 Closely Spaced Speakers	17.5
2.0 => 2.0 Very Closely Spaced Speakers	17.5
5.1 => 2.0 Largely Spaced Speakers	25.5
5.1 => 2.0 Closely Spaced Speakers	27.5
5.1 => 2.0 Very Closely Spaced Speakers	27.5
7.1 => 2.0 Largely Spaced Speakers	28
7.1 => 2.0 Closely Spaced Speakers	37
7.1 => 2.0 Very Closely Spaced Speakers	37

Module Interfaces UM1655

## 2 Module Interfaces

Two files are needed to integrate this module: *lib\_omni2\_multichannel\_m4*.a or *lib\_omni2\_multichannel\_32b\_m4*.a library, and the *omni2\_glo.h* header file which contains all definitions and structures to be exported to the software integration framework.

Note:

The audio\_fw\_glo.h file is a generic header file common to all audio modules; it must be included in the audio framework.

## 2.1 APIs

Six generic functions have a software interface to the main program: omni2\_reset, omni2\_setParam, omni2\_getParam, omni2\_setConfig, omni2\_getConfig, and omni2\_process.

### 2.1.1 omni2\_reset function

This procedure initializes the static memory of the module, and initializes static and dynamic parameters with default values.

int32\_t omni2\_reset(void \*static\_mem\_ptr, void \*dynamic\_mem\_ptr);

Table 4. Offiniz_reset				
I/O	Name	Туре	Description	
Input	static_mem_ptr	void *	Pointer to internal static memory	
Input	dynamic_mem_ptr	void *	Pointer to internal dynamic memory	
Returned value	-	int32 t	Error value	

Table 4. omni2\_reset

This routine must be called at least once at initialization time, when the real time processing has not started.

### 2.1.2 omni2 setParam function

This procedure writes module static parameters from the main framework to the module's internal memory. It can be called after the reset routine and before the start of the real time processing. It handles the static parameters, i.e. the parameters with the values which cannot be changed during the module processing (frame by frame).

int32\_t omni2\_setParam(omni2\_static\_param\_t \*input\_static\_param\_ptr, void
\*static\_mem\_ptr);

UM1655 Module Interfaces

I/O	Name	Туре	Description
Input	input_static_param_ptr	omni2_static_param_t*	Pointer to static parameters structure
Input	static_mem_ptr	void *	Pointer to internal static memory
Returned value	-	int32_t	Error value

#### 2.1.3 omni2\_getParam function

This procedure gets the module static parameters from the module's internal memory to the main framework. It can be called after the reset routine and before the start of the real time processing. It handles the static parameters, i.e. the parameters with values which cannot be changed during the module processing (frame by frame).

int32\_t omni2\_setParam(omni2\_static\_param\_t \*input\_static\_param\_ptr, void
\*static\_mem\_ptr);

Table 6. omni2\_getParam

I/O	Name	Туре	Description
Input	input_static_param_ptr	omni2_static_param_t *	Pointer to static parameters structure
Input	static_mem_ptr	void *	Pointer to internal static memory
Returned value	_	int32_t	Error value

## 2.1.4 omni2\_setConfig function

This procedure sets the module dynamic parameters from the main framework to the module internal memory. It can be called at any time during the module processing (after the reset and setParam routines).

int32\_t omni2\_setConfig(omni2\_dynamic\_param\_t \*input\_dynamic\_param\_ptr,
void \*static\_mem\_ptr);

Table 7. omni2\_setConfig

I/O	Name	Туре	Description
Input	input_dynamic_param_ptr	omni2_dynamic_param_t *	Pointer to dynamic parameters structure
Input	static_mem_ptr	void *	Pointer to internal static memory
Returned value	-	int32_t	Error value

Module Interfaces UM1655

#### 2.1.5 omni2\_getConfig function

This procedure gets the module dynamic parameters from the internal static memory to the main framework. It can be called at any time during processing (after the reset and setParam routines).

int32\_t omni2\_getConfig(omni2\_dynamic\_param\_t \*input\_dynamic\_param\_ptr,
void \*static\_mem\_ptr);

<b>Table</b>	8.	omni2	_getConfig
--------------	----	-------	------------

I/O	Name	Туре	Description
Input	input_dynamic_param_ptr	omni2_dynamic_param_t *	Pointer to dynamic parameters structure
Input	static_mem_ptr	void *	Pointer to internal static memory
Returned value	-	int32_t	Error value

## 2.1.6 omni2\_process function

This procedure is the module's main processing routine. It should be called at any time, to process each frame.

int32\_t omni2\_process(buffer\_t \*input\_buffer, buffer\_t \*output\_buffer, void
\*static\_mem\_ptr);

Table 9. omni2\_process

I/O	Name	Туре	Description
Input	input_buffer	buffer_t *	Pointer to input buffer structure
Output	output_buffer	buffer_t *	Pointer to output buffer structure
Input	static_mem_ptr	void *	Pointer to internal static memory
Returned value	-	int32_t	Error value

This process routine can run in place only in case of w.x to y.z with  $(w+x) \ge (y+z)$ . For instance, processing such as the stereo widening effect (2.0 to 2.0) or 5.1 virtualization effect (5.1 to 2.0) can run in place.

## 2.2 External definitions and types

For genericity reasons and to facilitate the integration in the main frameworks, some types and definitions have been defined.

#### 2.2.1 Input and output buffers

The library is using extended I/O buffers which contain, in addition to the samples, some useful information on the stream such as the number of channels, the number of bytes per sample, and the interleaving mode.

An I/O buffer structure type, as described below, must be followed and filled in by the main framework before each call to the processing routine:

47/

UM1655 Module Interfaces

Table 10. Input and output buffers

Name	Туре	Description
nb_channels	int32_t	Number of channels in data: 1 for mono, 2 for stereo
nb_bytes_per_Sample	int32_t	Dynamic data in number of bytes (2 for 16-bit data,)
data_ptr	void *	Pointer to data buffer (must be allocated by the main framework)
buffer_size	int32_t	Number of samples per channel in the data buffer
mode	int32_t	Buffer mode: 0 = not interleaved, 1 = interleaved

#### 2.2.2 Returned error values

Possible returned error values are described below:

Table 11. Returned error values

Definition	Value	Description
OMNI2_ERROR_NONE	0	OK - No error detected
OMNI2_ERROR	-1	Could be a bad sampling frequency, or a bad dynamic memory allocation
OMNI2_ERROR_PARSE_COMMAND	-2	Internal error - covers bad internal settings
OMNI2_BAD_HW	-3	May happen if the library is not used with the right hardware

## 2.3 Static parameters structure

Some static parameters must be set before calling the processing routine.

```
struct omni2_static_param {
    int32_t    Omni2CentreOutput;
    int32_t    AudioMode;
    int32_t    SamplingFreq;
};
typedef struct omni2_static_param omni2_static_param_t;
```

Module Interfaces UM1655

Table 12. Static parameters structure

Name	Туре	Description
Omni2CentreOutput	int32_t	0 to disable the center output (for 3.0), 1 to enable the center output (3.0)
AudioMode	int32_t	Can be one field of the eAcMode_Supported enumeration described below; it is used to describe the input data format
SamplingFreq	int32_t	I/O sampling frequency in Hz

The audio modes available are described below:

```
enum eAcMode_Supported
   AMODE20t = 0x0,/* Stereo channels for dolby pro logic */
   AMODE10 = 0x1,/* Mono channel (1.0) */
   AMODE20 = 0x2, /* Stereo channels (2.0) */
    AMODE30 = 0x3, /* Stereo + Center channel (3.0) */
   AMODE32 = 0x7, /* Stereo + Center channel + Surround Channels (5.0) */
   AMODE34 = 0xB,/* Stereo + Center channel + Surround Channels + Center
Surround Channels (7.0) */
   AMODE20t_LFE = 0x80,/* Stereo channels for dolby pro logic + LFE
channel */
   AMODE20_LFE = 0x82,/* Stereo + LFE channel (2.1) */
   AMODE30\_LFE = 0x83,/* Stereo + Center channel + LFE channel (3.1) */
   AMODE32_LFE = 0x87,/* Stereo + Center channel + LFE channel + Surround
Channels (5.1) */
   AMODE34\_LFE = 0x8B,/* Stereo + Center channel + LFE channel + Surround
Channels + Center Surround Channels (7.1) */
   AMODE_ID = 0xFF/* End of supported configurations */
};
```

## 2.4 Dynamic parameters structure

Three dynamic parameters can be used.

```
struct omni2_dynamic_param {
    int32_t    Omni2Enable;
    int32_t    Omni2Strength;
    int32_t    Omni2ListenigAngle;
};
typedef struct omni2_dynamic_param omni2_dynamic_param_t;
```

UM1655 Module Interfaces

Table 13. Dynamic parameters structure

Name	Туре	Description	
Omni2Enable	int32_t	1 to enable the effect, 0 to disable the effect	
Omni2Strength int32_t		Used to widen front signals from multichannel and stereo inputs. The value is from 0% (no widening perception) to 100% (maximum widening perception)	
Omni2ListeningAngle	int32_t	Can be OMNI2_LISTENING_ANGLE_10 to have optimal effect with 10 degrees listening angle, OMNI2_LISTENING_ANGLE_20 to have optimal effect with 20 degrees listening angle and OMNI2_LISTENING_ANGLE to have optimal effect with 30 degrees listening angle	

## 3 Algorithm description

## 3.1 Processing steps

The block diagram of the Omni2 module is described in Figure 4.

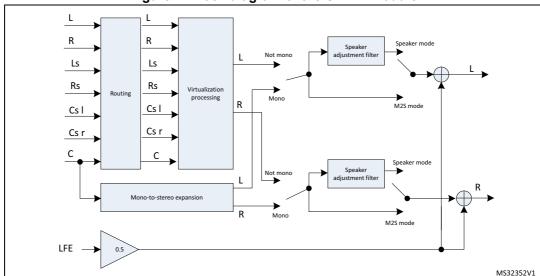


Figure 4. Block diagram of the Omni2 module

**Routing block:** Carries out a premixing of the channels so that it can be processed with a single virtualization structure.

Virtualization block: Applies the HRTF and Crosstalk cancellation function.

**Speaker adjustment filter:** Processes the audio signal after virtualization processing for speaker rendering and spectrum preservation.

**Mono-to-stereo block:** Carries out a mono-to-stereo expansion and bypasses the speaker rendering block.

## 3.2 Data formats

The module supports fixed point data in Q15 or Q31 format, with a mono or a multichannel up to 7.1 interleaved pattern.

577

#### 3.3 Performance assessment

There is no objective measurement available for this module; performances are only based on a subjective assessment.

Below a list of subjective indicators that could be used to evaluate the effect quality:

- Balance between Left Front and Right Front: capacity not to change energy on one front channel as compared to the other.
- Balance between Left Surround and Right Surround: capacity not to change energy on one surround channel as compared to the other.
- **Stereo Widening:** ability to increase the audio perception angle to widen the stereo signal.
- Distinction between front and side surround channels
- **Center image stability:** ability to keep the center image at the center loudspeaker, or between the left and right front loudspeakers.
- **Sensitivity to sweet spot:** ability to feel a widening or surround effect moving away from the sweet spot described in Section 4.1.1 and Section 4.1.2.
- **Spectrum preservation:** ability to keep the original spectrum perception, wherever the virtual sound comes from.

Note:

For more information on the performance, refer to Section 4.1: System requirements and hardware setup and Section 5: How to run and tune the application.



## 4 Application description

## 4.1 System requirements and hardware setup

The library is built to run on a Cortex M4 core without FPU usage. It was integrated and validated on some STM32F4 family devices.

### 4.1.1 Recommended setup for stereo widening effect

The stereo widening effect is designed for 10, 20 and 30 degrees typical listening angles,.

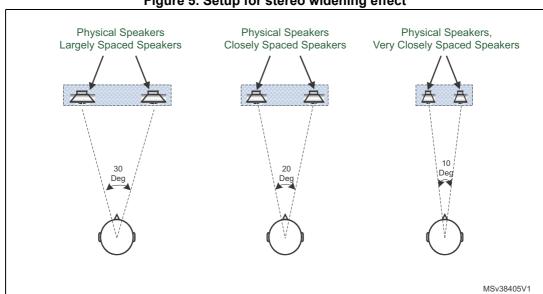


Figure 5. Setup for stereo widening effect

Find in *Table 14* some setup examples and direct impacts on speaker distance to get a typical listening angle and an optimal stereo widening perception.

Inter Speaker Speaker/Listener Corresponding Recommended mode to use Distance Distance **Listening Angle** 2.5 m OMNI2 LISTENING ANGLE 10  $0.3 \, m$ 0.3 m 1.8 m 10 OMNI2 LISTENING ANGLE 10 0.3 m 1.2 m 14 OMNI2\_LISTENING\_ANGLE\_10 0.3 m 0.6 m 28 OMNI2 LISTENING ANGLE 30 0.4 m OMNI2 LISTENING ANGLE 10 2.5 m 9 0.4 m 1.8 m 13 OMNI2\_LISTENING\_ANGLE\_10 0.4 m 1.2 m 19 OMNI2 LISTENING ANGLE 20 0.4 m 37 OMNI2\_LISTENING\_ANGLE\_30 0.6 m 0.6 m 2.5 m 14 OMNI2\_LISTENING\_ANGLE\_10

Table 14. Setup examples

Inter Speaker Distance	Speaker/Listener Distance	Corresponding Listening Angle	Recommended mode to use
0.6 m	1.8 m	19	OMNI2_LISTENING_ANGLE_20
0.6 m	1.2 m	28	OMNI2_LISTENING_ANGLE_30
0.8 m	2.5 m	18	OMNI2_LISTENING_ANGLE_20
0.8 m	1.8 m	25	OMNI2_LISTENING_ANGLE_20 or OMNI2_LISTENING_ANGLE_30
0.8 m	1.2 m	37	OMNI2_LISTENING_ANGLE_30
1.0 m	2.5 m	23	OMNI2_LISTENING_ANGLE_20
1.0 m	1.8 m	31	OMNI2_LISTENING_ANGLE_30
1.2 m	2.5 m	27	OMNI2_LISTENING_ANGLE_30
1.2 m	1.8 m	37	OMNI2_LISTENING_ANGLE_30

Table 14. Setup examples (continued)

It must be noted that the listener must be well centered between the two loudspeakers in order to benefit from the stereo widening effect because this effect is very sensitive to lateral sweet spot.

Listening angle below 20 degrees could correspond to a typical TV watching with down firing speakers, small sound bars or docking stations usage.

Positions of the virtual front channels should vary from ±15° to ±50°.

### 4.1.2 Recommended setup for multichannel virtualizer effect

Like the Stereo Widening effect, the multichannel virtualizer effect has been designed for 10, 20 and 30 degrees listening angles.

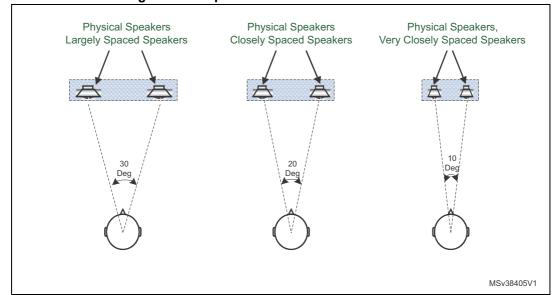


Figure 6. Setup for multichannel virtualizer effect

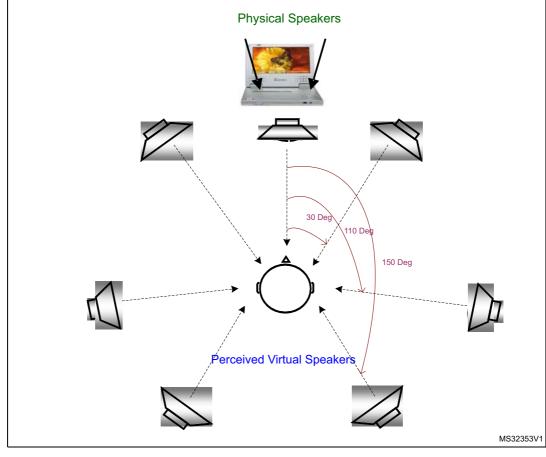


Table 15. Virtualized sound compliant with ITU-T 7.1 speaker layout standards

i.e. Front channels are at  $\pm$  30°, Side channels are at  $\pm$  110° and Rear channels are at  $\pm$  150°.

## 4.2 Recommendations for an optimal setup

The library processing should be placed just after the multichannel decoder and before the sampling rate conversion in order to process the audio signal at 32, 44.1 or 48 kHz, and avoid doing sampling rate conversions on multichannel. Note that only 48kHz sampling frequency is supported in this SW version.

There is no need for this module to be close to the audio DAC, and some graphical equalizer and volume management modules can be placed after it without affecting the widening or virtualization perception.

To integrate this module in an audio software framework, follow the next steps.

#### 4.2.1 Memory allocation

First of all, all the memory used by the module must be allocated.

The static parameters structure and dynamic parameters structure are exported in the omni2\_glo.h file, so that the memory for these structures can be allocated as written in the example below:

```
/* Omni2 static and dynamic parameters structures memory allocation */
omni2_static_param_t *static_param_ptr = malloc(sizeof(omni2_static_
param_t)));
omni2_dynamic_param_t *dynamic_param_ptr = malloc(sizeof(omni2_dynamic_
param_t)));
```

#### Where:

static\_param\_ptr pointer is used by omni2\_setParam() and omni2\_getParam() routines.

dynamic\_param\_ptr pointer is used by omni2\_setConfig() and omni2\_getConfig()
routines.

Next, the static and dynamic memory required by the module must be allocated by the framework. Structures are hidden to the audio framework, but their sizes are exported as a constant in the *omni2\_glo.h* file, so that the memory allocation can be done as written below:

```
/* Omni2 memory structure memory allocation */
void *static_mem_ptr = malloc(omni2_static_mem_size);
void *dynamic_mem_ptr = malloc(omni2_dynamic_mem_size);
```

#### Where:

- dynamic\_mem\_ptr pointer is a parameter of the omni2 reset() routine
- static\_mem\_ptr pointer is a parameter of all exported APIs.

Then, it is necessary to allocate the memory for the input and output audio buffers.

#### 4.2.2 Module API calls

Once the memory as been allocated, the omni2\_reset() routine must be called to initialize the module's static memory. The omni2\_reset() routine must be called each time the audio processing has been stopped and started.

The omni2\_getParam() routine can be called while the run time process has not started to extract the current static parameters used, if needed.

The static parameters can be set as soon as the input sampling frequency and the stream information are known. The omni2\_setParam() routine must be called to configure the module's internal memory with the corresponding sampling frequencies and the audio mode as in the example below:

```
/* Omni2 static parameters setting */
  omni2_static_param.Omni2CentreOutput = 0;/* center output disabled */
  omni2_static_param.SamplingFreq = 48000;/* I/O sampling frequency */
  omni2_static_param.AudioMode = AMODE32_LFE;/* 5.1 -> 2.0 : 5.1
  virtualization */
  error = omni2_setParam(&omni2_static_param, omni2_static_mem_ptr);
```



Now that the hardware has been configured and the module has been initialized and configured, the run time processing can start.

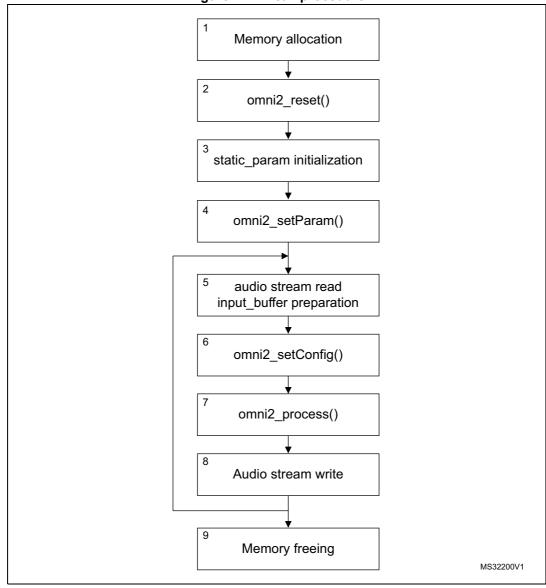
Every time the dynamic parameters change, they are taken into account by the module thanks to the *omni2\_setConfig()* routine:

At each new frame, the input buffer structure fields must be filled in as in the example below, as well as the data address for the output buffer structure. Then, the omni2\_process() routine can be called:

```
/* Omni2 input buffer configuration and processing all */
input_buffer_t.data_ptr = input_buffer_ptr;
input_buffer_t.buffer_size = input_buffer_size;
input_buffer_t.mode = INTERLEAVED;
input_buffer_t.nb_bytes_per_Sample = 2;
input_buffer_t.nb_channels = 6;
output_buffer_t.data_ptr = output_buffer_ptr;
output_buffer_t. buffer_size = input_buffer_size;
output_buffer_t. mode = INTERLEAVED;
output_buffer_t.nb_bytes_per_Sample = 2;
output_buffer_t.nb_channels = 2;
error = omni2_process(&omni2_input_buffer_t, &omni2_output_buffer_t,
omni2_static_mem_ptr);
```

#### 4.2.3 Module integration summary

Figure 7. API call procedure



- 1. As explained above, the module 's static and dynamic structures have to be allocated, as well as the input and output buffer, according to the structures defined in Section 2.2.1: Input and output buffers.
- 2. Once the memory has been allocated, the call to omni2\_reset() function initializes the internal variables.
- 3. The module's static configuration can now be set by initializing the static\_param structure, once the input sampling frequency and the audio mode are known.
- 4. Call the omni2\_setParam() routine to send the static parameters from the audio framework to the module.
- 5. The audio stream is read from the proper interface and the input\_buffer structure has to be filled in according to the stream characteristics (number of channels, sample rate, interleaving and data pointer). The output buffer structure has to be set as well.
- 6. Get the dynamic parameters when they are updated and call the omni2\_setConfig() routine to send the dynamic parameters from the audio framework to the module.
- 7. Call the processing main routine to apply the effect.
- 8. The output audio stream can now be written in the proper interface.
- 9. Once the processing loop is over, the allocated memory has to be freed.



## 5 How to run and tune the application

Once the module has been integrated into an audio framework to play samples at 48 kHz, just launch the Audio player and choose a .WAV or .MP3 file with a 48 kHz sampling frequency if no sampling rate conversion is available.

The Omni2Enable from the module's dynamic parameters is used to enable and disable the effect.

The Omni2Strength field is used to change the virtual listening angle. 0% means that virtual speakers are close to physical speakers, while 100% leads to the widest virtual angle (typically 100 degrees).

Omni2ListeningAngle field from the module's dynamic parameters is modified by selecting between "LargeSpacedS", "CloseSpacedS" and "VCloseSpacedS".



UM1655 Revision history

## 6 Revision history

Table 16. Document revision history

Date	Revision	Changes
26-Aug-2013	1	Initial release.
28-Nov-2014	2	Updated RPN on cover page
10-Dec-2014	3	Updated Section 5.
22-Jul-2015	4	Updated:  - Section 1.1, Section 1.3, Section 2.4, Section 4.1.1, Section 4.2, Section 4.2.2  - Table 2, Table 3, Table 13  - Figure 5, Added:  - Table 14  Removed:  - section: "Recommended setup for stereo widening effect for closely spaced speakers (Omni2DownFiringSpeakers set)"

#### **IMPORTANT NOTICE - PLEASE READ CAREFULLY**

STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, enhancements, modifications, and improvements to ST products and/or to this document at any time without notice. Purchasers should obtain the latest relevant information on ST products before placing orders. ST products are sold pursuant to ST's terms and conditions of sale in place at the time of order acknowledgement.

Purchasers are solely responsible for the choice, selection, and use of ST products and ST assumes no liability for application assistance or the design of Purchasers' products.

No license, express or implied, to any intellectual property right is granted by ST herein.

Resale of ST products with provisions different from the information set forth herein shall void any warranty granted by ST for such product.

ST and the ST logo are trademarks of ST. All other product or service names are the property of their respective owners.

Information in this document supersedes and replaces information previously supplied in any prior versions of this document.

© 2015 STMicroelectronics - All rights reserved

**577**