Oriental motor

HM-60093-2

# Network converter

## MECHATROLINK-Ⅲ compatible

# NETC01-M3

## USER MANUAL

CE

Thank you for purchasing an Oriental Motor product.

This manual describes product handling procedures and safety precautions.

- Please read it thoroughly to ensure safe operation.
- Always keep the manual where it is readily available.

## Table of contents

# 1 Safety precautions

The precautions described below are intended to prevent danger or injury to the user and other personnel through safe, correct use of the product. Use the product only after carefully reading and fully understanding these instructions.

## ⚠ Warning

Handling the product without observing the instructions that accompany a "Warning" symbol may result in serious injury or death.

### General

- Do not use the product in explosive or corrosive environments, in the presence of flammable gases, locations subjected to splashing water, or near combustibles. Doing so may result in fire or injury.
- Assign qualified personnel the task of installing, wiring, operating/controlling, inspecting and troubleshooting the product. Failure to do so may result in fire, injury or damage to equipment.

### Connection

- Keep the power supply input voltage of the **NETC01-M3** within the specified range. Failure to do so may result in fire.
- For the power supply of the **NETC01-M3**, use a DC power supply with reinforced insulation on its primary and secondary sides. Failure to do so may cause electric shock.
- Connect the cables securely according to the wiring diagram. Failure to do so may result in fire.
- Do not forcibly bend, pull or pinch the cable. Doing so may cause fire. Applying stress to the connection area of the connectors may cause damage to the product.

### Operation

- Turn off the **NETC01-M3** power in the event of a power failure. Or the motor may suddenly start when the power is restored and may cause injury or damage to equipment.
- When an alarm of the **NETC01-M3** is generated, stop the motor. Failure to do so may result in fire, injury or damage to equipment.

### Repair, disassembly and modification

- Do not disassemble or modify the **NETC01-M3**. Doing so may cause injury. Refer all such internal inspections and repairs to the branch or sales office from which you purchased the product.

## ⚠ Caution

Handling the product without observing the instructions that accompany a "Caution" symbol may result in injury or property damage.

### General

- Do not use the **NETC01-M3** beyond its specifications. Doing so may result in injury or damage to equipment.
- Keep your fingers and objects out of the openings in the **NETC01-M3**. Failure to do so may result in fire or injury.

### Installation

- Install the **NETC01-M3** in the enclosure in order to prevent injury.
- Keep the area around the **NETC01-M3** free of combustible materials in order to prevent fire or a skin burn(s).
- Do not leave anything around the **NETC01-M3** that would obstruct ventilation. Doing so may result in damage to equipment.

### Connection

- The power supply connector (CN1), MECHATROLINK-Ⅲ communication connector (CN2), data edit connector (CN3) and RS-485 communication connector (CN6) of the **NETC01-M3** are not electrically insulated. When grounding the positive terminal of the power supply, do not connect any equipment (PC, etc.) whose negative terminal is grounded. Doing so may cause the **NETC01-M3** and these equipment to short, damaging both.

### Operation

- Use the **NETC01-M3** in combination with the designated applicable product. Failure to do so may result in fire.
- When operating the product, do so after making preparations that an emergency stop can be performed at any time. Failure to do may result in injury.
- Set a suitable operation speed and acceleration/deceleration rate. Improper setting may cause loss of the motor synchronism and moving the load to an unexpected direction, which may result in injury or damage to equipment.
- Immediately when trouble has occurred, stop running and turn off the **NETC01-M3** power. Failure to do so may result in fire or injury.
- Always use an insulated screwdriver to adjust the switches of the **NETC01-M3**.

### Disposal

- To dispose of the **NETC01-M3**, disassemble it into parts and components as much as possible and dispose of individual parts/components as industrial waste. Contact your nearest Oriental Motor office if you have any questions.

# 2 Introduction

## ■ Before use

Only qualified personnel should work with the product.
Use the product correctly after thoroughly reading the section "1 Safety precautions" on p.3.
The product described in this manual has been designed and manufactured for use in general industrial equipment.
Do not use for any other purpose. For the power supply of the **NETC01-M3**, use a DC power supply with reinforced insulation on its primary and secondary sides. Oriental Motor Co., Ltd. is not responsible for any damage caused through failure to observe this warning.

## ■ Operating Manuals for the NETC01-M3

Operating manuals for the **NETC01-M3** are listed below.
After reading the following manuals, keep them in a convenient place so that you can reference them at any time.

- **Network converter MECHATROLINK-Ⅲ compatible NETC01-M3 USER MANUAL**

  This manual explains the function, installation and connection of the **NETC01-M3** as well as operating method.
  For the command code or remote I/O of the RS-485 communication compatible product that can be connected to the **NETC01-M3**, refer to the USER MANUAL of the corresponding RS-485 communication compatible product.

- **Network converter MECHATROLINK-Ⅲ compatible NETC01-M3 OPERATING MANUAL**

  This manual explains safety precautions, connector pin assignments and others.

- **Data setting software MEXE02 OPERATING MANUAL**

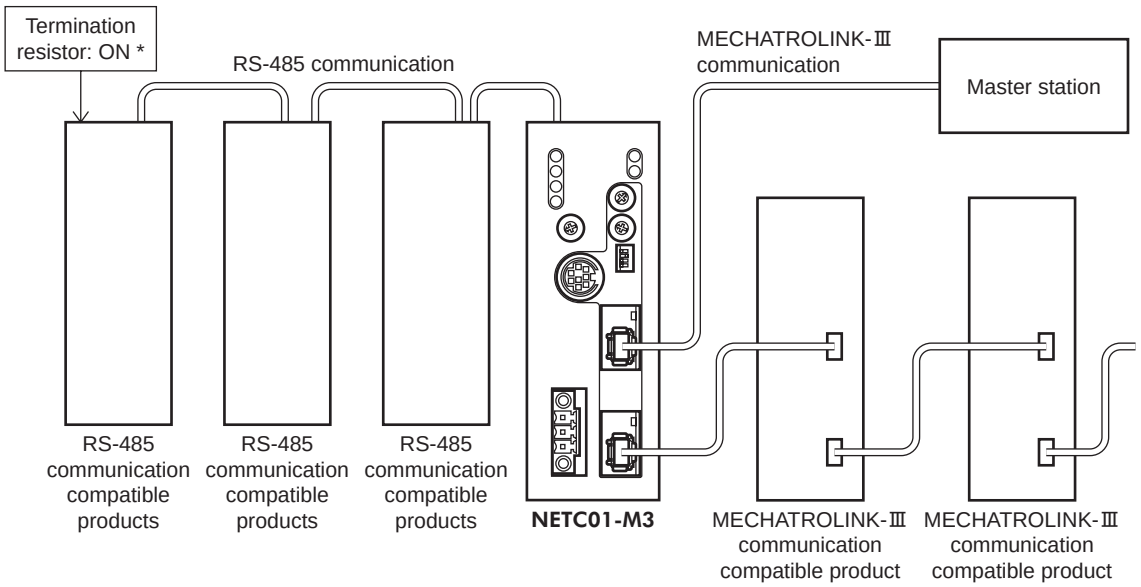
  This manual explains the parameter setting method or monitor function using the **MEXE02**.

## ■ Overview of the product

The **NETC01-M3** is a communication converter between MECHATROLINK-Ⅲ and RS-485 communication.
By converting the MECHATROLINK-Ⅲ communication protocol of the upper level to the RS-485 communication protocol of the lower level, Oriental Motor RS-485 communication compatible products can be operated via MECHATROLINK-Ⅲ communication.
The RS-485 communication protocol of the lower level is Oriental Motor's own RS-485 communication protocol.

**Parameters of the NETC01-M3 cannot be set with the master station.
When setting the parameters of the NETC01-M3, use an accessory OPX-2A or MEXE02 (both are sold separately).**

## ■ System configuration




* The termination resistor for RS-485 communication is built into the product.

## ■ CE Marking

Because the input power supply voltage of this product is 24 VDC, it is not subject to the Low Voltage Directive but install and connect this product as follows.

- This product is designed and manufactured to be installed within another device. Install the product in an enclosure.
- For the power supply of the **NETC01-M3**, use a DC power supply with reinforced insulation on its primary and secondary sides.
- Overvoltage category: Ⅰ
- Pollution degree: 2
- Degree of protection: IP20

- **EMC Directive**

This product has received EMC compliance under the conditions specified in "Example of NETC01-M3 installation and wiring" on p.10.
Since the conformity to the EMC Directive of the customer's equipment will be affected by various conditions such as other control-system devices used together with the **NETC01-M3**, as well as configuration of electrical components, wiring and installation condition, it therefore must be verified through EMC measurements of the equipment by the customer.

**Applicable standards**

- EMI: EN 61000-6-4, EN 55011 group 1 class A
- EMS: EN 61000-6-2

## ■ Hazardous substances

The products do not contain the substances exceeding the restriction values of RoHS Directive (2011/65/EU).

# 3 Preparation

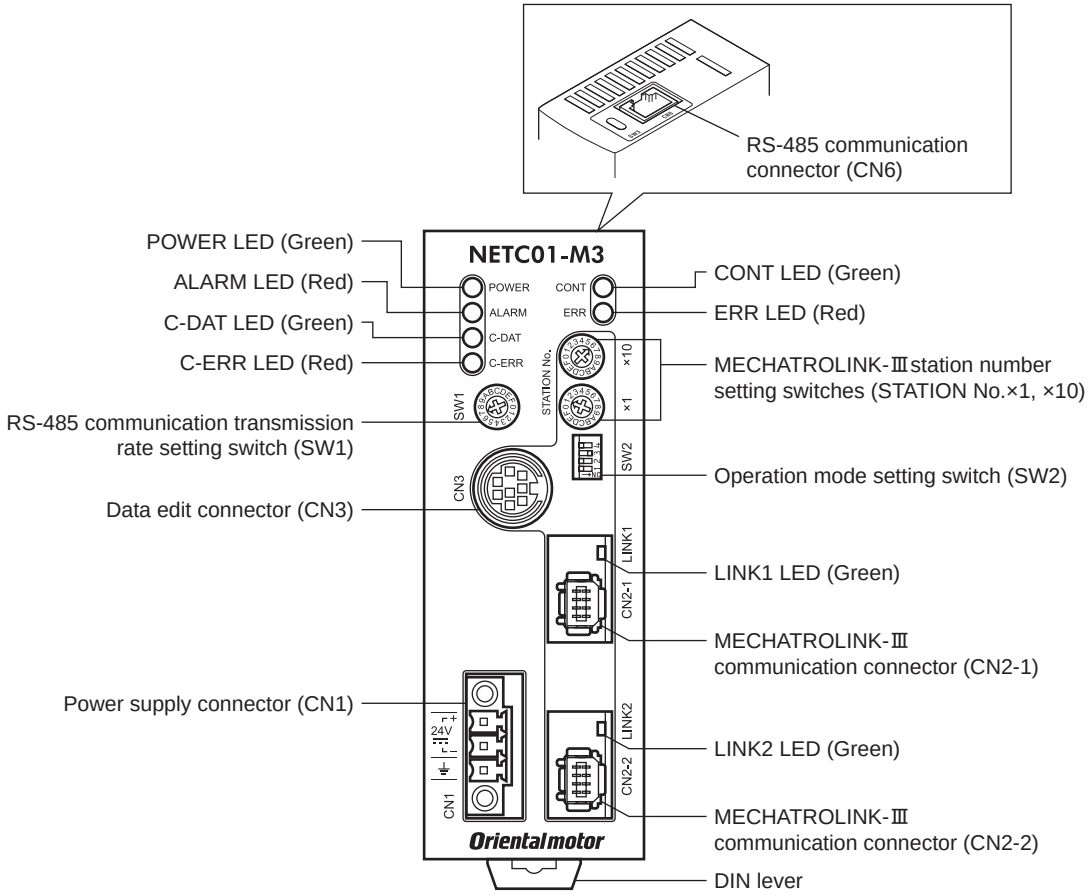
This chapter explains the items you should check, as well as the name and function of each part.

## 3.1 Checking the product

Verify that the items listed below are included. Report any missing or damaged items to the branch or sales office from which you purchased the product.

- **NETC01-M3**.....1 unit
- CN1 connector (3 pins) .....1 pc.
- RS-485 communication cable .....2 pcs. [0.1 m (3.94 in.), 0.25 m (9.84 in.) each 1 pc.]
- OPERATING MANUAL.....1 copy
- USER MANUAL (CD-ROM) .....1 pc.

## 3.2 Names and functions of parts



| Name | Description | Ref. |
|---|---|---|
| POWER LED (Green) | This LED is lit while the power is input. | – |
| ALARM LED (Red) | This LED will blink or illuminate steadily when an alarm or MECHATROLINK-Ⅲ communication error has generated. | p.45 |
| C-DAT LED (Green) | This LED is lit while transmitting and receiving data via RS-485 communication. | – |
| C-ERR LED (Red) | This LED is lit when an error has occurred via RS-485 communication. | – |
| CONT LED (Green) | This LED is lit while a connection is established. | – |
| ERR LED (Red) | This LED is lit when the MECHATROLINK-Ⅲ communication error has generated. | p.45 |
| RS-485 communication transmission rate setting switch (SW1) | Sets the transmission rate of RS-485 communication.<br>Factory setting: 7 (625 kbps) | p.17 |
| Data edit connector (CN3) | Connects a PC in which the **MEXE02** has been installed, or an accessory **OPX-2A** (sold separately). | p.13 |
| Power supply connector (CN1) | Connects a 24 VDC power supply. | p.11 |
| MECHATROLINK-Ⅲ station address setting switches (STATION No.×1, ×10) | Sets the station address in the 03h to EFh range.<br>Factory setting: 61h (×10=6, ×1=1)<br>×10: Sets the upper of the station address<br>×1: Sets the lower of the station address | p.18 |
| Operation mode setting switch (SW2-Nos.1 to 3) | Sets the operation mode.<br>• SW2-No.1: Sets the remote I/O occupied size.<br>Factory setting: OFF (16 bit mode)<br>• SW2-No.2, No.3: Sets the number of transmission bytes.<br>Factory setting: No.2=OFF, No.3=ON (32 bytes) | p.17 |
| LINK1 LED (Green)<br>LINK2 LED (Green) | These LEDs are lit while MECHATROLINK-Ⅲ communication is properly connected. | – |
| MECHATROLINK-Ⅲ communication connector (CN2-1, CN2-2) | Connects the MECHATROLINK-Ⅲ communication cable. | p.13 |
| RS-485 communication connector (CN6) | Connects the RS-485 communication cable. | p.12 |

# 4 Installation

This chapter explains the installation location and installation methods of the **NETC01-M3**.
The installation and wiring methods in compliance with the EMC Directive are also explained.

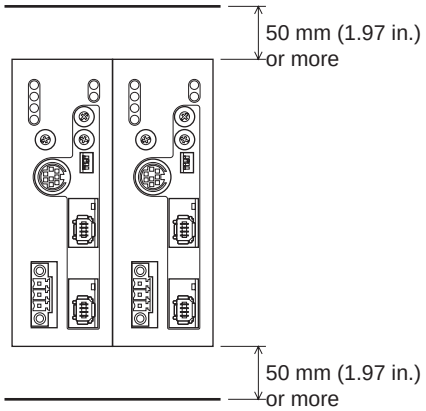
## 4.1 Location for installation

The **NETC01-M3** has been designed and manufactured for use as a component to be installed inside equipment.
Install it in a well-ventilated location that provides easy access for inspection. The location must also satisfy the following conditions:

- Inside an enclosure that is installed indoors (provide vent holes)
- Operating ambient temperature 0 to +40 °C (+32 to +104 °F) (non-freezing)
- Operating ambient humidity 85% or less (non-condensing)
- Area that is free of explosive atmosphere or toxic gas (such as sulfuric gas) or liquid
- Area not exposed to direct sun
- Area free of excessive amount of dust, iron particles or the like
- Area not subject to splashing water (rain, water droplets), oil (oil droplets) or other liquids
- Area free of excessive salt
- Area not subject to continuous vibration or excessive shocks
- Area free of excessive electromagnetic noise (from welders, power machinery, etc.)
- Area free of radioactive materials, magnetic fields or vacuum

## 4.2 Installation method

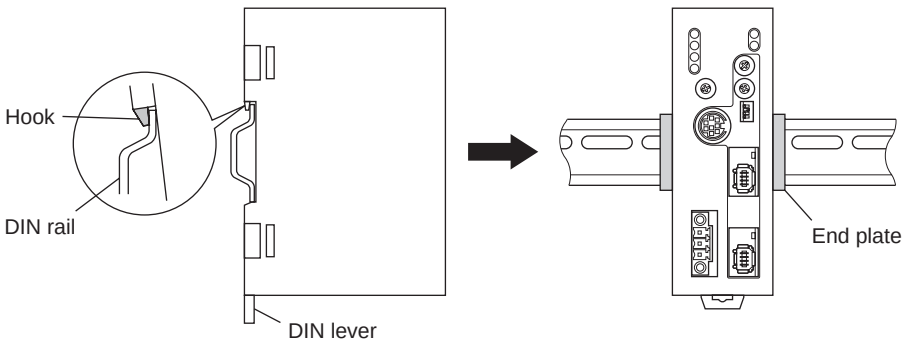
Install the **NETC01-M3** to a 35 mm (1.38 in.) width DIN rail.
There must be a clearance of at least 50 mm (1.97 in.) in the horizontal and vertical directions, between the **NETC01-M3** and enclosure or other equipment within the enclosure.
When installing two or more **NETC01-M3** in parallel, it is possible to install them closely in the horizontal direction. Provide a minimum clearance of 50 mm (1.97 in.) in the vertical direction.




**Note** Be sure to install the **NETC01-M3** vertically (vertical position). If the **NETC01-M3** is installed in the direction other than vertical position, its heat radiation effect will deteriorate.

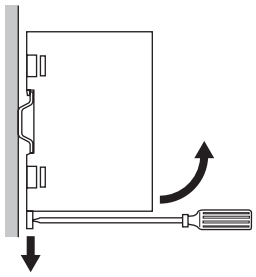
### ■ Mounting to DIN rail

Pull down the DIN lever of the **NETC01-M3** and lock it. Hang the hook at the rear to the DIN rail, and push in the **NETC01-M3**. After installation, secure the both sides of the **NETC01-M3** with the end plate.



**Removing from DIN rail**

Pull the DIN lever down until it locks using a flat tip screwdriver, and lift the bottom of the **NETC01-M3** to remove it from the rail.
Use force of about 10 to 20 N (2.2 to 4.5 lb.) to pull the DIN lever to lock it.
Excessive force may damage the DIN lever.



## 4.3 Installing and wiring in compliance with EMC Directive

Effective measures must be taken against the EMI that the **NETC01-M3** may give to adjacent control-system equipment, as well as the EMS of the **NETC01-M3** itself, in order to prevent a serious functional impediment in the machinery. The use of the following installation and wiring methods will enable the **NETC01-M3** to be compliant with the EMC directive. Refer to "CE Marking" on p.5 for the applicable standards.
Oriental Motor conducts EMC measurements on its **NETC01-M3** in accordance with "Example of NETC01-M3 installation and wiring" on p.10. The user is responsible for ensuring the machine's compliance with the EMC Directive, based on the installation and wiring explained below.

### ■ Power supply

This network converter is a product of DC power supply input.
Use a DC power supply (switching power supply etc.) that conforms to the EMC Directive.

### ■ Noise filter

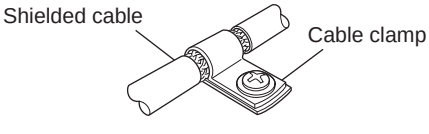
- Connect a noise filter in the DC power supply input to prevent the noise generated in the **NETC01-M3** from propagating externally through the power supply line.
- When using a power supply transformer, be sure to connect a noise filter to the AC input side of the power supply transformer.
- For a noise filter, use HF2010A-UPF (SOSHIN ELECTRIC CO.,LTD), FN2070-10-06 (Schaffner EMC) or equivalent product.
- Install the noise filter as close to the AC input terminal of DC power supply as possible. Use cable clamps and other means to secure the AC input cables (AWG18: 0.75 $mm^2$ or more) and output cables (AWG18: 0.75 $mm^2$ or more) firmly to the surface of the enclosure.
- Connect the ground terminal of the noise filter to the grounding point, using as thick and short a wire as possible.
- Do not place the AC input cable parallel with the noise filter output cable. Parallel placement will reduce noise filter effectiveness if the enclosure's internal noise is directly coupled to the power supply cable by means of stray capacitance.

### ■ How to ground

The cable used to ground the **NETC01-M3** and noise filter must be as thick and short as possible so that no potential difference is generated. Choose a large, thick and uniformly conductive surface for the grounding point.

### ■ Wiring the power supply cable and I/O signal cable

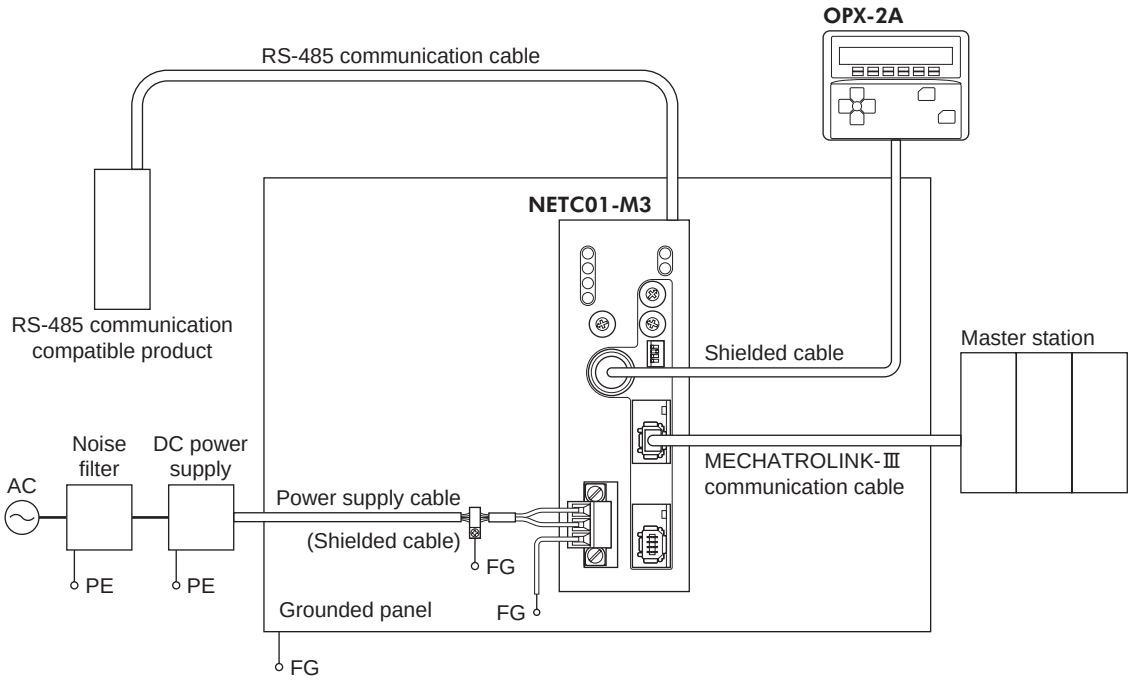
- Use a shielded cable of AWG22 (0.3 $mm^2$) or more for the power supply cable of the **NETC01-M3**, and keep it as short as possible.
- For the MECHATROLINK-Ⅲ communication cable, use a dedicated connector cable.
- To ground the power supply cable , use a metal cable clamp or similar device that will maintain contact with the entire circumference of the cable. Attach a cable clamp as close to the end of the cable as possible, and connect it as shown in the figure.



## ■ Notes about installation and wiring

- Connect the **NETC01-M3** and other peripheral control equipment directly to the grounding point so as to prevent a potential difference from developing between grounds.
- When relays or electromagnetic switches are used together with the system, use noise filters and CR circuits to suppress surges generated by them.
- Keep cables as short as possible without coiling and bundling extra lengths.
- Place the power cables such as the motor and power supply cables as far as 100 mm (3.94 in.) from the signal cables. If the power cables and signal cables have to cross, cross them at a right angle. Place the AC input cable and output cable of a noise filter separately from each other.

## ■ Example of NETC01-M3 installation and wiring




## ■ Precautions about static electricity

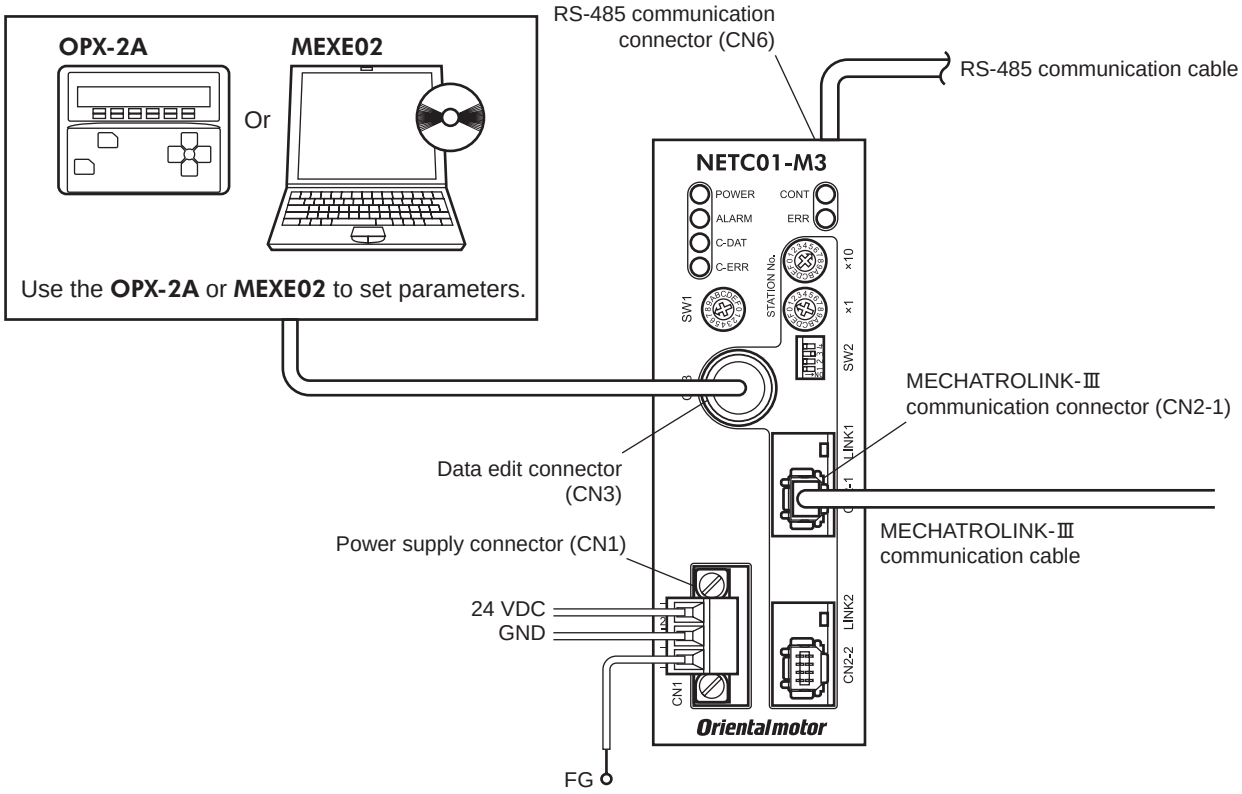
Static electricity may cause the **NETC01-M3** to malfunction or suffer damage. While the **NETC01-M3** is receiving power, handle the **NETC01-M3** with care and do not come near or touch the **NETC01-M3**. Always use an insulated screwdriver to change the switches of the **NETC01-M3**.

**Note** The **NETC01-M3** uses parts that are sensitive to electrostatic charge. Before touching the **NETC01-M3**, turn off the power to prevent electrostatic charge from generating. If an electrostatic charge is impressed on the **NETC01-M3**, the **NETC01-M3** may be damaged.

# 5 Connection

This chapter explains the connection method of the **NETC01-M3** and power supply/communication cable, as well as the grounding method.

## 5.1 Connection example




## 5.2 Connecting the power supply and grounding the NETC01-M3

### ■ Connecting the power supply

Connect the power supply cable (AWG22: 0.3 $mm^2$) to the power supply connector (CN1) of the **NETC01-M3** using the supplied CN1 connector (3 pins).

### ■ Grounding the NETC01-M3

Ground the Frame Ground terminal (FG) of the **NETC01-M3** as necessary.
Ground using a wire of AWG24 to 16 (0.2 to 1.25 $mm^2$), and do not share the protective earth terminal with a welder or any other power equipment.

### ■ CN1 connector pin assignments

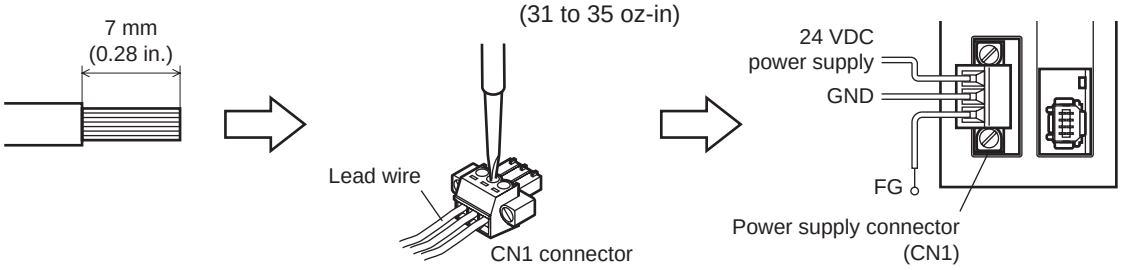
| Pin No. | Signal name | Description |
|---|---|---|
| 1 | +24 VDC | +24 VDC 0.2 A or more |
| 2 | GND | Power supply GND |
| 3 | FG | Frame Ground |

**Note**

- When connecting, pay attention to the polarity of the power supply. Reverse-polarity connection may cause damage to the **NETC01-M3**.
- Do not wire the power supply cable of the **NETC01-M3** in the same cable duct with other power lines. Doing so may cause malfunction due to noise.

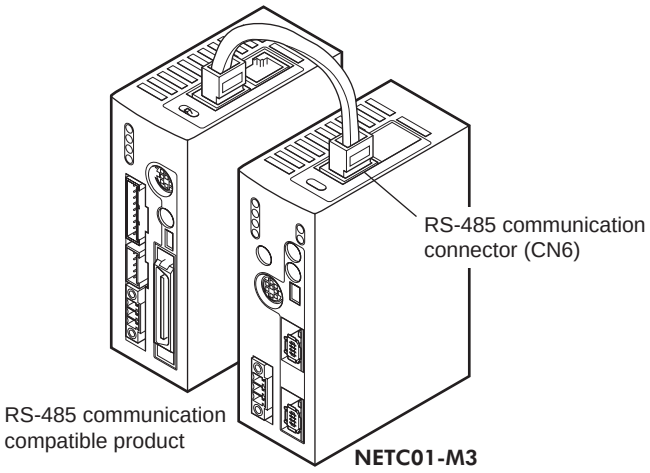
## ■ Connecting method

1. Strip the insulation cover of the lead wire by 7 mm (0.28 in.)
2. Insert each lead wire into the CN1 connector and tighten the screw using a screwdriver.
   Connector screw size: M2
   Tightening torque: 0.22 to 0.25 N·m (31 to 35 oz-in)
3. Insert the CN1 connector into the CN1 and tighten the screws using a screwdriver.
   Connector screw size: M2.5
   Tightening torque: 0.4 N·m (56 oz-in)




# 5.3 Connecting the RS-485 communication cable

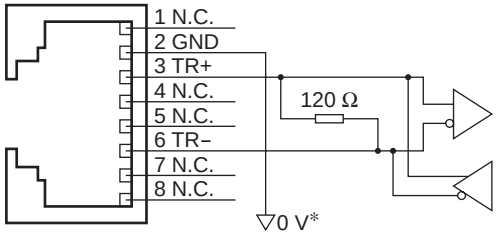
Connect the **NETC01-M3** and RS-485 communication compatible product using the supplied RS-485 communication cable.
Connect the RS-485 communication cable to RS-485 communication connector (CN6). Since RS-485 communication cables of two lengths are supplied, use either one of the two.
You can also use a commercial LAN cable to link drivers.




## ■ CN6 connector pin assignments

| Pin No. | Signal name | Description |
|---|---|---|
| 1 | N.C. | Not used (Do not connect anything.) |
| 2 | GND | GND |
| 3 | TR+ | RS-485 communication signal (+) |
| 4 | N.C. | Not used |
| 5 | | |
| 6 | TR− | RS-485 communication signal (−) |
| 7 | N.C. | Not used |
| 8 | | |

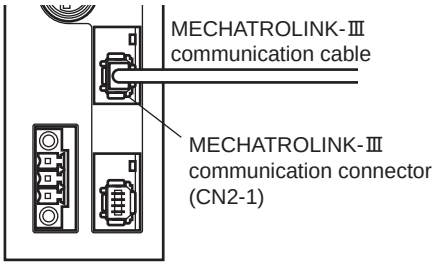
• **NETC01-M3** internal circuit and termination resistor




* The GND line is used in common with CN1 (not insulated)

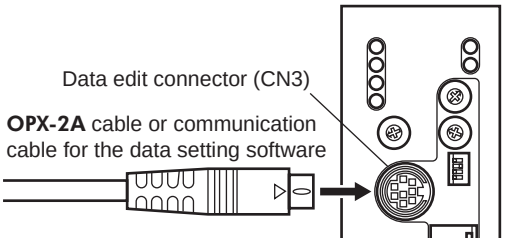
## 5.4 Connecting the MECHATROLINK-Ⅲ communication cable

Connect the MECHATROLINK-Ⅲ communication cable to the MECHATROLINK-Ⅲ communication connector (CN2-1 or CN2-2) of the **NETC01-M3**. For the MECHATROLINK-Ⅲ communication cable, use a dedicated cable with connector. Other MECHATRLINK-Ⅲ communication compatible products can be connected to the vacant connector.




## 5.5 Connecting the data setter

Connect the **OPX-2A** cable or communication cable for the data setting software to the data edit connector (CN3) on the **NETC01-M3**.




**⚠ Caution**

The power supply connector (CN1), MECHATROLINK-Ⅲ communication connector (CN2-1, CN2-2), data edit connector (CN3) and RS-485 communication connector (CN6) of the **NETC01-M3** are not electrically insulated. When grounding the positive terminal of the power supply, do not connect any equipment (PC, etc.) whose negative terminal is grounded. Doing so may cause the **NETC01-M3** and these equipment to short, damaging both.

# 6 Guidance

If you are new to the **NETC01-M3**, read this section to understand the operating methods along with the operation flow.
As an example, this chapter explains how to perform positioning operation for the "**CRK** Series FLEX Built-in controller type [described as the **CRD-KD** in this manual]," using the **NETC01-M3** via MECHATROLINK-Ⅲ communication.

**Note**
- Before operating the motor, check the condition of the surrounding area to ensure safety.
- Refer to "13.8 Parameter mode" on p.57 for how to set parameters.

## STEP 1 Set the transmission rate, station address and address number

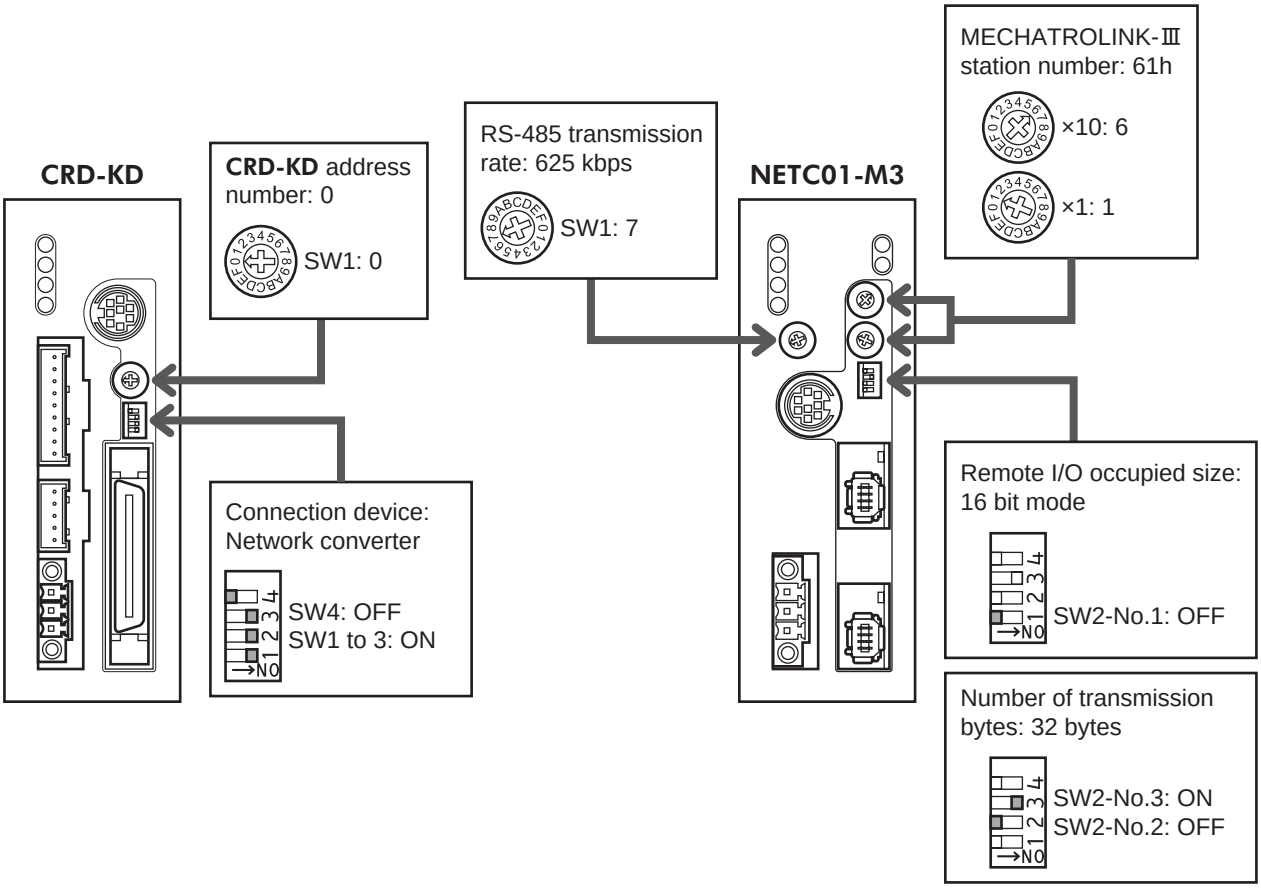
### ■ Using the parameter

1. Set the "connection (address number 0)" parameter of the **NETC01-M3** to "1: Enable."
2. Cycle the **NETC01-M3** power.

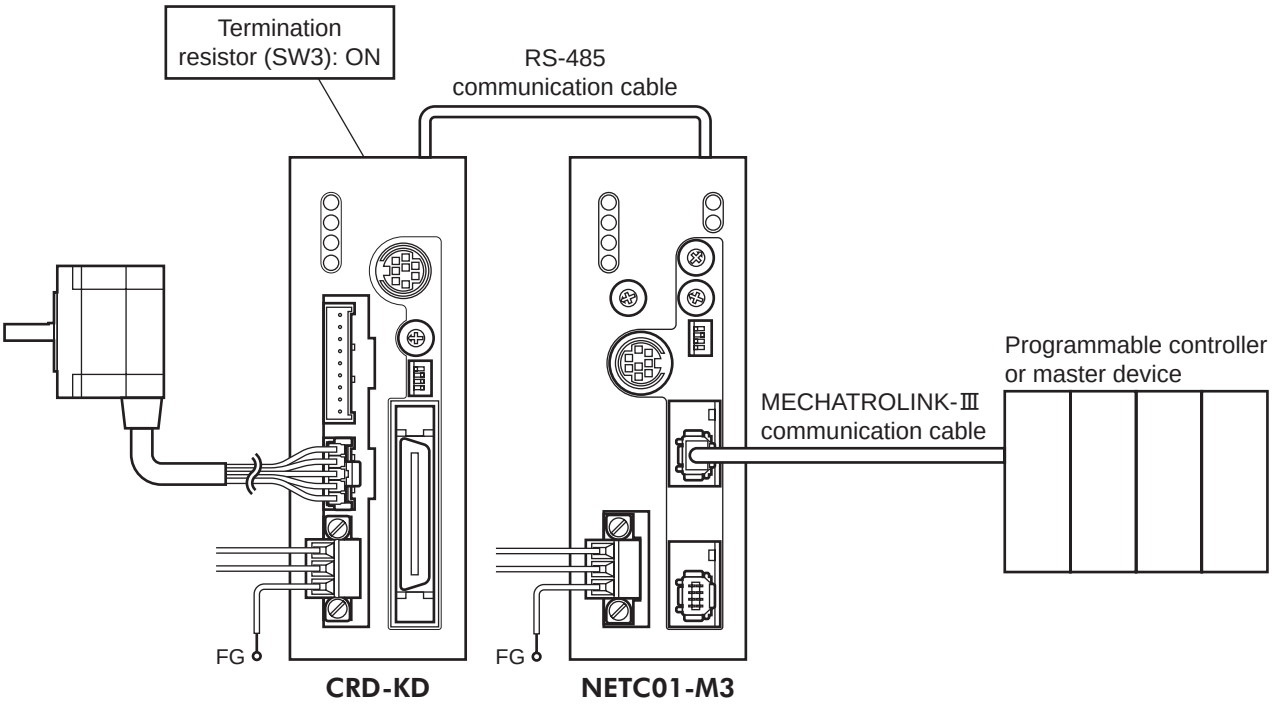
**Note**
- "Connection" parameters will be enabled after the power is cycled.
- When setting the parameters of the **NETC01-M3**, use the **OPX-2A** or **MEXE02**.

### ■ Using the switches

- **Setting condition of CRD-KD**
  - Address number of **CRD-KD**: 0
  - Connection device of **CRD-KD**: Network converter
- **Setting condition of NETC01-M3**
  - MECHATROLINK-Ⅲ station address: 61h
  - RS-485 transmission rate: 625 kbps
  - Remote I/O occupied size: 16 bit mode
  - Number of transmission bytes: 32 bytes

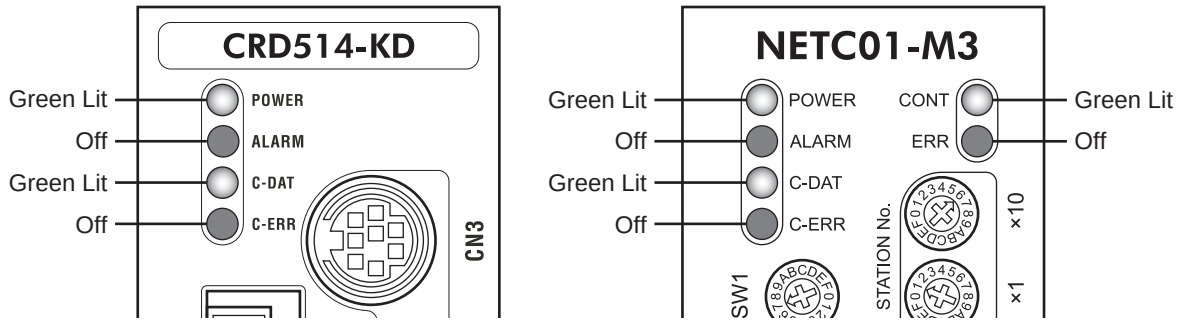


## STEP 2 Check the connection and set the termination resistor




## STEP 3 Turn on the power and check the setting

Check that the LED condition has become as shown in the figures.




- When C-ERR (red) of the **CRD-KD** or **NETC01-M3** is lit: Check the transmission rate or address number of RS-485 communication.
- When ERR (red) of the **NETC01-M3** is lit: Check the type of the MECHATROLINK-Ⅲ communication error.

## STEP 4 Set the parameters of CRD-KD

Set the parameters of the **CRD-KD** using any of the **OPX-2A**, **MEXE02**, RS-485 communication or MECHATROLINK-Ⅲ communication.

1. Set the "START input mode (1C00h)" parameter of the **CRD-KD** to "0: RS-485 communication." (Initial setting: I/O)
2. Set the position (travel amount: 1001h) and operating speed (1101h) to the operation data No.1 of the **CRK-KD**.
3. Set the "Data No. input mode (1C0Dh)" parameter of the **CRD-KD** to "0: RS-485 communication." (Initial setting: I/O)
4. Set the "STOP contact configuration (1C03h)" parameter of the **CRD-KD** to "0: Normally open." (Initial setting: Normally closed)

**Note**

- Operation data or parameters set via RS-485 communication or MECHATROLINK-Ⅲ communication will be written to the RAM of the **CRD-KD**. The data stored in the RAM will be erased when turning off the power supply of the **CRD-KD**. When saving the data to the non-volatile memory, execute the "batch NV memory write" command of the maintenance command.
- The operation data or parameters set by the **OPX-2A** or **MEXE02** will be saved to the non-volatile memory of the **CRD-KD**.
- The non-volatile memory can be rewritten approx. 100,000 times.

## STEP 5 Execute positioning operation

Control the I/O signal of the **CRD-KD** using the standard I/O command (DATA_RWA: 20h) of MECHATROLINK-Ⅲ communication.

1. Select the data No.1 by turning the M0 of the address number 0.
2. Execute positioning operation by turning the START of the address number 0 to ON.

## STEP 6 Were you able to operate the motor properly?

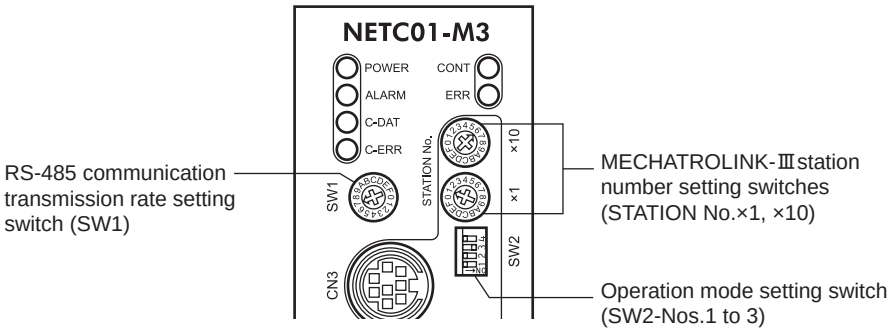
How did it go? Were you able to operate the motor properly? If the motor does not function, check the following points:

- Is any alarm present in the **NETC01-M3** or **CRD-KD**?
- Are the address number, transmission rate and termination resistor set correctly?
- Are the "connection" parameters of the **NETC01-M3** set correctly?
- Is the C-ERR LED lit? (RS-485 communication error)
- Is the ERR LED lit? (MECHATROLINK-Ⅲ communication error)
- Is the operation data set correctly?
- Is the motor for the **CRD-KD** excited? Or is the excitation setting correct?
- Are the **CRD-KD** parameters set correctly?
- Is the STOP input of the **CRD-KD** I/O turned ON?

For more detailed settings and functions, refer to the following pages.

# 7 Setting

This chapter explains how to set the functions of the **NETC01-M3**.




**Note** Be sure to turn off the **NETC01-M3** power before setting the switches. If the switches are set while the power is still on, the new switch settings will not become effective until the **NETC01-M3** power is cycled.

## 7.1 Transmission rate of RS-485 communication

Set the transmission rate using the transmission rate setting switch (SW1).

**Factory setting 7 (625 kbps)**

**Note**
- For the SW1, always set to "7." If the switch is set to the dial of "8" or higher, the communication switch setting error alarm will be generated when turning on the power. And do not set the switch to the dial of "0" to "6" because they cannot be used. (An alarm will not be generated.)
- For the transmission rate of the RS-485 communication compatible product, set to 625 kbps.

## 7.2 Operation mode

Set the remote I/O occupied size and number of transmission bytes for the RS-485 communication compatible product connecting to a **NETC01-M3**. Set the remote I/O occupied size using the operation mode setting switch SW2-No.1, and set the number of transmission bytes using the SW2-No.2 and No.3. If the operation mode is changed, cycle the power.

**Factory setting No.1: OFF (Remote I/O occupied size: 16 bit mode)**
**No.2: OFF, No.3: ON (Number of transmission bytes: 32 bytes)**

| SW2 | Description | Factory setting |
|---|---|---|
| No.1 | Sets the remote I/O occupied size.<br>OFF: 16 bit mode (Up to 8 units can be connected)<br>ON: 8 bit mode (Up to 16 units can be connected) | OFF |
| No.2<br>No.3 | Sets the number of transmission bytes.<br>No.2=OFF, No.3=OFF: 16 bytes<br>No.2=OFF, No.3=ON: 32 bytes<br>No.2=ON, No.3=OFF: 48 bytes<br>No.2=ON, No.3=ON: 64 bytes | No.2: OFF<br>No.3: ON |

**Note** The SW2-No.4 is not used.

## 7.3 Station number

Set the station number using the two MECHATROLINK-Ⅲ station number setting switches (STATION No.×1 and ×10). When connecting two or more MECHATROLINK-Ⅲ compatible products, do not set duplicate station numbers.
Set the tens place with the "STATION No.×10" switch and the ones place with the "STATION No.×1" switch.

**Setting range 03h to EFh**
**Factory setting 61h (×10: 6, ×1: 1)**

**Note** 00h to 02h and F0h to FFh cannot be used.

# 8 MECHATROLINK-Ⅲ communication format

This chapter explains the MECHATROLINK-Ⅲ communication format that the **NETC01-M3** supports.

## 8.1 Data format

The outline of the data format for MECHATROLINK-Ⅲ communication is shown below. The **NETC01-M3** is compatible with the cyclic communication mode.
The cyclic communication mode of MECHATROLINK-Ⅲ communication specifies that the header fields are 0 byte to 3 bytes and the data fields are 4 bytes and later.

| | Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| Header field | 0 | CMD | RCMD |
| | 1 | WDT | RWDT |
| | 2 | CMD_CTRL | CMD_STAT |
| | 3 | | |
| Data field | 4 to 31 | Command data field | Response data field |

## 8.2 Phase

The communication phases of MECHATROLINK-Ⅲ communication are classified as follows.

| Phase | Description |
|---|---|
| 0 | This is a state at power-on. When turning on the power for the master station and slave station, operation switches to the phase 1. |
| 1 | This is a state waiting for the connection establishment between the master station and slave station. |
| 2 | Asynchronous communication between the master station and slave station is enabled. Only asynchronous command can be used. |
| 3 | Synchronous communication between the master station and slave station is enabled. Both asynchronous command and synchronous command can be used. |
| 4 | This is a state that the communication between the master station and slave station is stopped and the connection is disconnected. |
| 5 | This is a state turning off the power for the master station and slave station. |

# 9 Details of command

This chapter explains the common commands and standard I/O command that the **NETC01-M3** supports.

| Profile | Command code (Hex) | Command | Description | Ref. |
|---|---|---|---|---|
| Common command | 00 | NOP | This command is used as "no operation command." | p.20 |
| | 03 | ID_RD | This command is used to read the product information as ID data. | p.21 |
| | 04 | CONFIG | This command is used to set up the **NETC01-M3**. | p.23 |
| | 05 | ALM_RD | This command is used to read the alarm code, warning code or MECHATROLINK-Ⅲ communication error code that is currently occurred. | p.24 |
| | 06 | ALM_CLR | This command is used to reset the alarm, warning or MECHATROLINK-Ⅲ communication error that is currently occurred. | p.24 |
| | 0E | CONNECT | This command is used to establish a connection of MECHATROLINK-Ⅲ communication. | p.25 |
| | 0F | DISCONNECT | This command is used to release a connection of MECHATROLINK-Ⅲ communication. | p.26 |
| Standard I/O command | 20 | DATA_RWA | Operation commands to the RS-485 communication compatible product, reading and writing parameters, and monitoring can be executed via remote I/O or remote register. | p.27 |

## 9.1 No operation command (NOP: 00h)

This command is used as "no operation command." A response returns the present status.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | NOP (00h) | NOP (00h) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 to 31 | Reserved (0h) | Reserved (0h) |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | • Confirms by the response RCMD=NOP (00h) and CMD_STAT.CMDRDY=1.<br>• When the CMD_STAT.D_ALM or CMD_STAT.D_WAR is equal to 1, use the ALM_RD to read out the present alarm or warning codes and take appropriate action.<br>• When the CMD_STAT.CMD_ALM or CMD_STAT.COMM_ALM is other than 0, take appropriate action according to the alarm code. Refer to p.32 "CMD_STAT" for details. |

## 9.2 Read ID command (ID_RD: 03h)

This command is used to read the product information as ID data. Select ID data by specifying the ID_CODE.
Refer to the "ID_CODE list" for details.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | ID_RD (03h) | ID_RD (03h) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 | ID_CODE | ID_CODE |
| 5 | OFFSET | OFFSET |
| 6 | SIZE | SIZE |
| 7 | | |
| 8 to 15 | Reserved (0h) | ID |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | • Confirms by the response RCMD=ID_RD (03h), CMD_STAT.CMDRDY=1, ID_CODE, OFFSET and SIZE.<br>• When the CMD_STAT.D_ALM or CMD_STAT.D_WAR is equal to 1, use the ALM_RD to read out the present alarm or warning codes and take appropriate action.<br>• When the CMD_STAT.CMD_ALM or CMD_STAT.COMM_ALM is other than 0, take appropriate action according to the alarm code. Refer to "Command status (CMD_STAT)" on p.37 for details. |
| Note | • This command can be used in the phase 2 and 3.<br>• ID_CODE: ID data selection code<br>OFFSET: ID read offset<br>SIZE: Read data size (byte)<br>ID: ID data<br>If any of the ID_CODE, OFFSET, SIZE or ID is invalid, "9" is set for the CMD_ALM (CMD_ALM=9). When the CMD_ALM has occurred, the ID data is indefinite. |

### ■ ID_CODE list

| ID_CODE | Description | Data size | Data type |
|---|---|---|---|
| 01h | Vendor ID code | 4 byte | Binary |
| | This is an ID code to specify the vendor.<br>Vendor ID code of ORIENTAL MOTOR CO.,LTD. = 00 00 00 05h | | |
| 02h | Device code | 4 byte | Binary |
| | This is a code specific to each product. It is specified as a unique number for each product series associated with the vendor ID code.<br>Device code of the **NETC01-M3** = 00 00 0C D1h (3281) | | |

<table>
<tr><th>ID_CODE</th><th>Description</th><th>Data size</th><th>Data type</th></tr>
<tr><td rowspan="2">20h</td><td>Supported communication mode</td><td>4 byte</td><td>Binary</td></tr>
<tr><td colspan="3">This is the supported status of the communication mode. The NETC01-M3 is compatible with the cyclic communication mode. (Not supported=0, Supported=1)
<table>
<tr><th>bit7</th><th>bit6</th><th>bit5</th><th>bit4</th></tr>
<tr><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td></tr>
<tr><td>0</td><td>0</td><td>0</td><td>0</td></tr>
</table>
<table>
<tr><th>bit3</th><th>bit2</th><th>bit1</th><th>bit0</th></tr>
<tr><td>Ether net communication</td><td>Message communication</td><td>Cyclic communication</td><td>Event-driven communication</td></tr>
<tr><td>0</td><td>0</td><td>1</td><td>0</td></tr>
</table>
* Bit 8 to bit 31 are all reserved (0)</td></tr>
<tr><td rowspan="2">30h</td><td>List of supported main commands</td><td>32 byte</td><td>Array</td></tr>
<tr><td colspan="3">This is the list of the main commands that the product supports. The main commands of the NETC01-M3 are allocated as shown in the table below (Command not supported = 0, Command supported = 1).
<table>
<tr><th>bit7</th><th>bit6</th><th>bit5</th><th>bit4</th><th>bit3</th><th>bit2</th><th>bit1</th><th>bit0</th></tr>
<tr><td>Reserved (0)</td><td>ALM_CLR</td><td>ALM_RD</td><td>CONFIG</td><td>ID_RD</td><td>PRM_WR</td><td>PRM_RD</td><td>NOP</td></tr>
<tr><td>0</td><td>1</td><td>1</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td></tr>
</table>
<table>
<tr><th>bit15</th><th>bit14</th><th>bit13</th><th>bit12</th><th>bit11</th><th>bit10</th><th>bit9</th><th>bit8</th></tr>
<tr><td>DISCONNECT</td><td>CONNETC</td><td>SYNC_SET</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td></tr>
<tr><td>1</td><td>1</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr>
</table>
* Bit 16 to bit 23 are all reserved (0)
<table>
<tr><th>bit31</th><th>bit30</th><th>bit29</th><th>bit28</th><th>bit27</th><th>bit26</th><th>bit25</th><th>bit24</th></tr>
<tr><td>Reserved (0)</td><td>MEM_WR</td><td>MEM_RD</td><td>PPRM_WR</td><td>PPRM_RD</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td></tr>
<tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr>
</table>
<table>
<tr><th>bit39</th><th>bit38</th><th>bit37</th><th>bit36</th><th>bit35</th><th>bit34</th><th>bit33</th><th>bit32</th></tr>
<tr><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>Reserved (0)</td><td>DATA_RWS</td><td>DATA_RWA</td></tr>
<tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td></tr>
</table>
* Bit 40 to bit 255 are all reserved (0)</td></tr>
<tr><td rowspan="2">80h</td><td>Main device name</td><td>32 byte</td><td>ASCII</td></tr>
<tr><td colspan="3">This is the main device name (ASCII code). The main device name of the NETC01-M3 is "NETC01-M3."
<table>
<tr><th>byte0</th><th>byte1</th><th>byte2</th><th>byte3</th><th>byte4</th><th>byte5</th><th>byte6</th><th>byte7</th></tr>
<tr><td>N</td><td>E</td><td>T</td><td>C</td><td>0</td><td>1</td><td>−</td><td>M</td></tr>
</table>
<table>
<tr><th>byte8</th><th>byte9</th><th>byte10</th><th>byte11</th><th>byte12</th><th>byte13</th><th>byte14</th><th>byte15</th></tr>
<tr><td>3</td><td>00</td><td></td><td></td><td></td><td></td><td></td><td></td></tr>
</table>
* The blank spaces and the byte 16 to byte 31 in the table are all represented by null.</td></tr>
</table>

## 9.3 Setup device command (CONFIG: 04h)

This command is used to set up the **NETC01-M3**.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | CONFIG (04h) | CONFIG (04h) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 | CONFIG_MOD | CONFIG_MOD |
| 5 to 31 | Reserved (0h) | Reserved (0h) |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | • Confirms by the response RCMD=CONFIG (04h), CMD_STAT.CMDRDY=1 and CONFIG_MOD.<br>• When the CMD_STAT.D_ALM or CMD_STAT.D_WAR is equal to 1, use the ALM_RD to read out the present alarm or warning codes and take appropriate action.<br>• When the CMD_STAT.CMD_ALM or CMD_STAT.COMM_ALM is other than 0, take appropriate action according to the code. Refer to "Command status (CMD_STAT)" on p.37 for details. |
| Note | • This command can be used in the phase 2 and 3.<br>• CONFIG_MOD: Configuration mode<br>If the CONFIG_MOD data is invalid, "9" is set for the CMD_ALM (CMD_ALM=9). |
| Command parameter | • CONFIG_MOD<br>0: Parameter re-calculation and setup |

**CONFIG command and operation status**

The following table shows the state of each status before, during and after processing the CONFIG command.

See "Command status (CMD_STAT)" on p.37 for the ALM and CMDRDY.

| Status | Before CONFIG processing | During CONFIG processing | After CONFIG processing |
|---|---|---|---|
| ALM | Current state | Current state | Current state |
| CMDRDY | 1 | 0 | 1 |
| Other status | Current state | Indefinite | Current state |

## 9.4 Read alarm or warning command (ALM_RD: 05h)

This command is used to read the alarm code, warning code or MECHATROLINK-Ⅲ communication error code that is currently occurred.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | ALM_RD (05h) | ALM_RD (05h) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 | ALM_RD_MOD | ALM_RD_MOD |
| 5 | | |
| 6 | ALM_INDEX | ALM_INDEX |
| 7 | | |
| 8 to 31 | Reserved (0h) | ALM_DATA |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | Confirms by the response RCMD=ALM_RD (05h), CMD_STAT.CMDRDY=1, ALM_RD_MOD and ALM_INDEX. |
| Note | • This command can be used in the phase 2 and 3.<br>• ALM_RD_MOD: Reading mode<br>ALM_INDEX: Alarm index<br>ALM_DATA: Stores the alarm codes or warning codes.<br>If any of the ALM_RD_MOD, ALM_INDEX or ALM_DATA is invalid, "9" is set for CMD_ALM (CMD_ALM=9). |
| Command parameter | • ALM_RD_MOD<br>0: Reads the present alarm or warning status.<br>• ALM_INDEX<br>0: If "0" is specified, the latest alarm or warning can be read. |

## 9.5 Clear alarm or warning command (ALM_CLR: 06h)

This command is used to reset the MECHATROLINK-Ⅲ communication error that is currently occurred.

**Note** Only the MECHATROLINK-Ⅲ communication error can be reset by the "clear alarm or warning command." To reset the alarm and warning of the **NETC01-M3**, cycle the power.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | ALM_CLR (06h) | ALM_CLR (06h) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 | ALM_CLR_MOD | ALM_CLR_MOD |
| 5 | | |
| 6 to 31 | Reserved (0h) | Reserved (0h) |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | • Confirms by the response RCMD=ALM_CLR (06h), CMD_STAT.CMDRDY=1 and ALM_CLR_MOD.<br>• When the CMD_STAT.D_ALM or CMD_STAT.D_WAR is equal to 1, use the ALM_RD to read out the present alarm or warning codes and take appropriate action.<br>• When the CMD_STAT.CMD_ALM or CMD_STAT.COMM_ALM is other than 0, take appropriate action according to the code. Refer to p.32 "CMD_STAT" for details. |
| Note | • This command can be used in the phase 2 and 3.<br>• ALM_CLR_MOD: Reading mode<br>If the ALM_CLR_MOD is invalid, "9" is set for CMD_ALM (CMD_ALM=9). |
| Command parameter | • ALM_CLR_MOD<br>0: This command is used to reset the MECHATROLINK-Ⅲ communication error that is currently occurred. |

## 9.6 Establish connection command (CONNECT: 0Eh)

This command is used to establish the MECHATROLINK-Ⅲ communication connection.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | CONNECT (0Eh) | CONNECT (0Eh) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 | VER (30h) | VER (30h) |
| 5 | COM_MODE | COM_MODE |
| 6 | COM_TIME | COM_TIME |
| 7 | PROFILE_TYPE (30h) | PROFILE_TYPE (30h) |
| 8 to 31 | Reserved (0h) | Reserved (0h) |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | • Confirms by the response RCMD=CONNECT (0Eh), CMD_STAT.CMDRDY=1, VER, COM_MODE, COM_TIME and PROFILE_TYPE.<br>• When the CMD_STAT.D_ALM or CMD_STAT.D_WAR is equal to 1, use the ALM_RD to read out the present alarm or warning codes and take appropriate action.<br>• When the CMD_STAT.CMD_ALM or CMD_STAT.COMM_ALM is other than 0, take appropriate action according to the code. Refer to "Command status (CMD_STAT)" on p.37 for details. |
| Note | • This command can be used in the phase 1. It is disregarded in the phase 2 and 3.<br>• VER: MECHATROLINK application layer version<br>COM_MODE: Communication mode<br>COM_TIM: Communication cycle setting<br>PROFILE_TYPE: Profile type setting<br>If any of the VER, COM_MODE, COM_TIM or PROFILE_TYPE is invalid, "9" is set for CMD_ALM (CMD_ALM=9). |

<table>
<tr><td>Command parameter</td><td>
• COM_MODE<br>
The bit allocation is shown in the table below.
<table>
<tr><th>bit7</th><th>bit6</th><th>bit5</th><th>bit4</th><th>bit3</th><th>bit2</th><th>bit1</th><th>bit0</th></tr>
<tr><td>SUBCMD</td><td>0</td><td>0</td><td>0</td><td colspan="2">DTMODE</td><td>SYNCMODE</td><td>0</td></tr>
</table>
· SYNCMODE (Synchronous setting)<br>
0: Asynchronous communication. Detecting the watchdog data error is disabled and synchronous command cannot be used.)<br>
1: Synchronous command (Not used in the NETC01-M3)<br>
· DTMODE (Communication mode)<br>
00b: Single transmission<br>
01b: Consecutive transmission (Not used in the NETC01-M3)<br>
10b, 11b: Reserved<br>
· SUBCMD (Subcommand setting)<br>
0: Subcommand is disabled.<br>
• COM_TIM<br>
Sets a coefficient to calculate the communication cycle (natural number).<br>
COM_TIME = Communication cycle / Transmission cycle<br>
• PROFILE_TYPE<br>
Set "30h" since the NETC01-M3 is the standard I/O profile.
</td></tr>
</table>

## 9.7 Release connection command (DISCONNECT: 0Fh)

This command is used to release a connection of MECHATROLINK-Ⅲ communication.
When releasing a connection, the master station transmits the release connection command for two or more communication cycles. The **NETC01-M3** interrupts the current processing and performs the initialization required to reestablish the connection. Then, it waits for the connect establishment request from the master station. The release connection command can be sent regardless of the state of the CMD_STAT.CMDRDY. If the command is sent when the CMD_STAT.CMDRDY is equal to 0 (CMD_STAT. CMDRDY = 0), the processing is interrupted and the release connection command is processed.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | DISCONNECT (0Fh) | DISCONNECT (0Fh) |
| 1 to 31 | Reserved (0h) | Reserved (0h) |

### ■ Explanation of command

| | |
|---|---|
| Device group | Common command group |
| Communication type | Asynchronous command |
| Completion of command operation | Controls the command transmitting time of the mater station as at least two communication cycles. |
| Note | • This command can be used in all phases.<br>• Upon receipt of this command, the following operation is performed.<br>· Shifts the phase to the phase 1.<br>· The DISCONNECT is sent to the RS-485 communication compatible product. |

## 9.8 Data READ/WRITE_A command (DATA_RWA: 20h)

Operation commands to the RS-485 communication compatible product, reading and writing parameters, and monitoring can be executed via remote I/O or remote register.

- **Remote I/O**

  Remote I/O is one of the data used in communication between the master station and RS-485 communication compatible product. The control like the ON-OFF switching of I/O signals can be executed using serial communication.
  When remote I/O of the **NETC01-M3** is assigned to the register of the master station, it is possible to control using remote I/O via the **NETC01-M3**. The following functions can be executed using remote I/O.
  - Controls the ON-OFF status of the input signal to the RS-485 communication compatible product.
  - Checks the output signal from the RS-485 communication compatible product.

- **Remote register**

  Remote register is one of the data used in communication between the master station and RS-485 communication compatible product. Reading and writing the numerical number can be executed using serial communication.
  When remote register of the **NETC01-M3** is assigned to the register of the master station, it is possible to control using remote register via the **NETC01-M3**. The following functions can be executed using remote register.
  - Reads the parameters from the RS-485 communication compatible product.
  - Writes the parameters to the RS-485 communication compatible product.
  - Monitors the status of the RS-485 communication compatible product.

### ■ Data format

| Byte | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|
| 0 | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | WDT | RWDT |
| 2 | CMD_CTRL | CMD_STAT |
| 3 | | |
| 4 | Reserved (0h) | Connection status |
| 5 | | |
| 6 to 31 | OUTPUT | INPUT |

### ■ Explanation of command

| | |
|---|---|
| Device group | Standard I/O profile group |
| Communication type | Asynchronous command |
| Completion of command operation | Confirms by the response RCMD=DATA_RWA (20h) and CMD_STAT.CMDRDY=1. |
| Note | • This command can be used in the phase 2 and 3.<br>• OUTPUT<br>Output data. Refer to the "I/O data."<br>• INPUT<br>Input data. Refer to the "I/O data." |

## ■ Connection status

The connection status with the RS-485 communication compatible product can be monitored by the response of the DATA_RWA command. For the connection status shown in the next section "I/O data," when the master station properly communicates with the RS-485 communication compatible product, the bit corresponding to the address number shown in the table below becomes "1." If the connection setting is disabled or if the communication error has occurred, the bit becomes "0."

| bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
|---|---|---|---|---|---|---|---|
| Address number 7 | Address number 6 | Address number 5 | Address number 4 | Address number 3 | Address number 2 | Address number 1 | Address number 0 |
| Address number 15 | Address number 14 | Address number 13 | Address number 12 | Address number 11 | Address number 10 | Address number 9 | Address number 8 |

## ■ I/O data

The OUTPUT and INPUT respectively correspond to the command and response of the data field as shown below.
Controlling the I/O signal of the RS-485 communication compatible product, reading and writing operation data or parameters, and monitoring can be executed.

- **Remote I/O occupied size: 16-bit mode**
  **Number of transmission bytes: 16-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | | |
| 8 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 9 | | | |
| 10 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 11 | | | |
| 12 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 13 | | | |
| 14 | – | Reserved | Reserved |
| 15 | | | |

- **Remote I/O occupied size: 16-bit mode**
  **Number of transmission bytes: 32-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | | |
| 8 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 9 | | | |
| 10 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 11 | | | |
| 12 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 13 | | | |
| 14 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 15 | | | |
| 16 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 17 | | | |
| 18 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 19 | | | |
| 20 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 21 | | | |
| 22 | Remote register | Register address number | Register address number response |
| 23 | | | |
| 24 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 25 | | | |
| 26 | | DATA | DATA response |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | – | Reserved | Reserved |
| 31 | | | |

- **Remote I/O occupied size: 16-bit mode**
  **Number of transmission bytes: 48-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | | |
| 8 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 9 | | | |
| 10 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 11 | | | |
| 12 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 13 | | | |
| 14 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 15 | | | |
| 16 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 17 | | | |
| 18 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 19 | | | |
| 20 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 21 | | | |
| 22 | Remote register | Register address number | Register address number response |
| 23 | | | |
| 24 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 25 | | | |
| 26 | | DATA | DATA response |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | | Register address number | Register address number response |
| 31 | | | |
| 32 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 33 | | | |
| 34 | | DATA | DATA response |
| 35 | | | |
| 36 | | | |
| 37 | | | |
| 38 | | Register address number | Register address number response |
| 39 | | | |
| 40 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 41 | | | |
| 42 | | DATA | DATA response |
| 43 | | | |
| 44 | | | |
| 45 | | | |

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 46 | – | Reserved | Reserved |
| 47 | | | |

- **Remote I/O occupied size: 16-bit mode**
  **Number of transmission bytes: 64-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | | |
| 8 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 9 | | | |
| 10 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 11 | | | |
| 12 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 13 | | | |
| 14 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 15 | | | |
| 16 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 17 | | | |
| 18 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 19 | | | |
| 20 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 21 | | | |
| 22 | Remote register | Register address number | Register address number response |
| 23 | | | |
| 24 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 25 | | | |
| 26 | | DATA | DATA response |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | | Register address number | Register address number response |
| 31 | | | |
| 32 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 33 | | | |
| 34 | | DATA | DATA response |
| 35 | | | |
| 36 | | | |
| 37 | | | |
| 38 | | Register address number | Register address number response |
| 39 | | | |
| 40 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 41 | | | |

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 42 | Remote register | DATA | DATA response |
| 43 | | | |
| 44 | | | |
| 45 | | | |
| 46 | | Register address number | Register address number response |
| 47 | | | |
| 48 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 49 | | | |
| 50 | Remote register | DATA | DATA response |
| 51 | | | |
| 52 | | | |
| 53 | | | |
| 54 | | Register address number | Register address number response |
| 55 | | | |
| 56 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 57 | | | |
| 58 | | DATA | DATA response |
| 59 | | | |
| 60 | | | |
| 61 | | | |
| 62 | – | Reserved | Reserved |
| 63 | | | |

- **Remote I/O occupied size: 8-bit mode**
  **Number of transmission bytes: 16-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 8 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 9 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 10 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 11 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 12 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 13 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 14 | – | Reserved | Reserved |
| 15 | | | |

- **Remote I/O occupied size: 8-bit mode**
  **Number of transmission bytes: 32-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 8 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 9 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 10 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 11 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 12 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 13 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 14 | | Address number "8" remote I/O input | Address number "8" remote I/O output |
| 15 | | Address number "9" remote I/O input | Address number "9" remote I/O output |
| 16 | | Address number "10" remote I/O input | Address number "10" remote I/O output |
| 17 | | Address number "11" remote I/O input | Address number "11" remote I/O output |
| 18 | | Address number "12" remote I/O input | Address number "12" remote I/O output |
| 19 | | Address number "13" remote I/O input | Address number "13" remote I/O output |
| 20 | | Address number "14" remote I/O input | Address number "14" remote I/O output |
| 21 | | Address number "15" remote I/O input | Address number "15" remote I/O output |
| 22 | Remote register | Register address number | Register address number response |
| 23 | | | |
| 24 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 25 | | | |
| 26 | | DATA | DATA response |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | – | Reserved | Reserved |
| 31 | | | |

- **Remote I/O occupied size: 8-bit mode**
  **Number of transmission bytes: 48-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 8 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 9 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 10 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 11 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 12 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 13 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 14 | | Address number "8" remote I/O input | Address number "8" remote I/O output |
| 15 | | Address number "9" remote I/O input | Address number "9" remote I/O output |
| 16 | | Address number "10" remote I/O input | Address number "10" remote I/O output |
| 17 | | Address number "11" remote I/O input | Address number "11" remote I/O output |
| 18 | | Address number "12" remote I/O input | Address number "12" remote I/O output |
| 19 | | Address number "13" remote I/O input | Address number "13" remote I/O output |
| 20 | | Address number "14" remote I/O input | Address number "14" remote I/O output |
| 21 | | Address number "15" remote I/O input | Address number "15" remote I/O output |
| 22 | Remote register | Register address number | Register address number response |
| 23 | | | |
| 24 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 25 | | | |
| 26 | | DATA | DATA response |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | | Register address number | Register address number response |
| 31 | | | |
| 32 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 33 | | | |
| 34 | | DATA | DATA response |
| 35 | | | |
| 36 | | | |
| 37 | | | |
| 38 | | Register address number | Register address number response |
| 39 | | | |
| 40 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 41 | | | |
| 42 | | DATA | DATA response |
| 43 | | | |
| 44 | | | |
| 45 | | | |

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 46 | – | Reserved | Reserved |
| 47 | | | |

- **Remote I/O occupied size: 8-bit mode**
  **Number of transmission bytes: 64-byte mode**

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 0 | – | DATA_RWA (20h) | DATA_RWA (20h) |
| 1 | | WDT | RWDT |
| 2 | | CMD_CTRL | CMD_STAT |
| 3 | | | |
| 4 | | Reserved | Connection status |
| 5 | | | |
| 6 | Remote I/O | Address number "0" remote I/O input | Address number "0" remote I/O output |
| 7 | | Address number "1" remote I/O input | Address number "1" remote I/O output |
| 8 | | Address number "2" remote I/O input | Address number "2" remote I/O output |
| 9 | | Address number "3" remote I/O input | Address number "3" remote I/O output |
| 10 | | Address number "4" remote I/O input | Address number "4" remote I/O output |
| 11 | | Address number "5" remote I/O input | Address number "5" remote I/O output |
| 12 | | Address number "6" remote I/O input | Address number "6" remote I/O output |
| 13 | | Address number "7" remote I/O input | Address number "7" remote I/O output |
| 14 | | Address number "8" remote I/O input | Address number "8" remote I/O output |
| 15 | | Address number "9" remote I/O input | Address number "9" remote I/O output |
| 16 | | Address number "10" remote I/O input | Address number "10" remote I/O output |
| 17 | | Address number "11" remote I/O input | Address number "11" remote I/O output |
| 18 | | Address number "12" remote I/O input | Address number "12" remote I/O output |
| 19 | | Address number "13" remote I/O input | Address number "13" remote I/O output |
| 20 | | Address number "14" remote I/O input | Address number "14" remote I/O output |
| 21 | | Address number "15" remote I/O input | Address number "15" remote I/O output |
| 22 | Remote register | Register address number | Register address number response |
| 23 | | | |
| 24 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 25 | | | |
| 26 | | DATA | DATA response |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | | Register address number | Register address number response |
| 31 | | | |
| 32 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 33 | | | |
| 34 | | DATA | DATA response |
| 35 | | | |
| 36 | | | |
| 37 | | | |
| 38 | | Register address number | Register address number response |
| 39 | | | |
| 40 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 41 | | | |

| Byte | Type | Command (Master to **NETC01-M3**) | Response (**NETC01-M3** to master) |
|---|---|---|---|
| 42 | Remote register | DATA | DATA response |
| 43 | | | |
| 44 | | | |
| 45 | | | |
| 46 | | Register address number | Register address number response |
| 47 | | | |
| 48 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 49 | | | |
| 50 | Remote register | DATA | DATA response |
| 51 | | | |
| 52 | | | |
| 53 | | | |
| 54 | | Register address number | Register address number response |
| 55 | | | |
| 56 | | Command code + TRIG | Command code response + TRIG response + STATUS |
| 57 | | | |
| 58 | | DATA | DATA response |
| 59 | | | |
| 60 | | | |
| 61 | | | |
| 62 | – | Reserved | Reserved |
| 63 | | | |

## ■ Watchdog Data (WDT/RWDT)

During synchronous communication, synchronous data is exchanged for every communication cycle between the master station and RS-485 communication compatible product. This synchronous data is called the watchdog data, and used for establishing synchronous communication and detecting watchdog error in synchronous communication.

Since the **NETC01-M3** is a control device by asynchronous command, the WDT is disregarded.

## ■ Command control (CMD_CTRL)

In the cyclic communication mode, the second and third bytes of the command format are specified as the CMD_CTRL area. The bit fields of the CMD_CTRL are shown in the table below.

| bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
|---|---|---|---|---|---|---|---|
| CMD_ID | | Reserved | Reserved | ALM_CLR | Reserved | Reserved | Reserved |

| bit 15 | bit 14 | bit 13 | bit 12 | bit 11 | bit 10 | bit 9 | bit 8 |
|---|---|---|---|---|---|---|---|
| Reserved | | | | | | | |

### Explanation of bit field

| Bit field | Description |
|---|---|
| CMD_ID | This is not used in the **NETC01-M3**. |
| ALM_CLR | 0: Disable alarm clear and warning clear<br>1: Enable alarm clear and warning clear |

## ■ Command status (CMD_STAT)

The bit fields of the CMD_STAT are shown in the table below.

| bit 7 | bit 6 | bit 5 | bit 4 | bit 3 | bit 2 | bit 1 | bit 0 |
|---|---|---|---|---|---|---|---|
| RCMD_ID | | Reserved | Reserved | ALM_CLR_CMP | CMDRDY | D_WAR | D_ALM |

| bit 15 | bit 14 | bit 13 | bit 12 | bit 11 | bit 10 | bit 9 | bit 8 |
|---|---|---|---|---|---|---|---|
| COMM_ALM | | | | CMD_ALM | | | |

### Explanation of bit field

| Bit field | Definition | Description |
|---|---|---|
| D_ALM | 0: No alarm<br>1: The **NETC01-M3** is in the alarm state | This is a bit that indicates the alarm state of the **NETC01-M3**. When the specific alarm of the **NETC01-M3** occurs, the D_ALM status bit is set to 1 (D_ALM=1) [Except for the COMM_ALM, CMD_ALM and MECHATROLINK-Ⅲ communication error].<br>The D_ALM is independent of the COMM_ALM and CMD_ALM. When the **NETC01-M3** shifts from the alarm state to the normal state as a result of the execution of the ALM_CLR command, this bit is set to 0 (D_ALM=0). |
| D_WAR | 0: No warning<br>1: The **NETC01-M3** is in the warning state | This is a bit that indicates the warning state of the **NETC01-M3**. When the specific warning of the **NETC01-M3** occurs, the D_WAR status bit is set to 1 (D_WAR=1) [Except for the COMM_ALM, CMD_ALM and MECHATROLINK-Ⅲ communication error].<br>The D_WAR is independent of the COMM_ALM and CMD_ALM. When the **NETC01-M3** shifts from the warning state to the normal state as a result of the execution of the ALM_CLR command, this bit is set to 0 (D_WAR=0). |
| CMDRDY | 0: Command cannot be accepted.<br>1: Command can be accepted. | CMDRDY=0 (the STATUS bit 2 is equal to "0") represents that the command processing of the **NETC01-M3** is in progress. Although the current command processing is continued, only the DISCONNECT command is executed immediately regardless of the value of the CMDRDY bit. |
| ALM_CLR_CMP | 0: Alarm clear unprocessed<br>1: Completion of alarm clear processing | ALM_CLR_CMP=1 represents that CMD_CTRL.ALM_CLR=1 has been received and the alarm clear processing has been completed. The ALM_CLR_CMP can be cleared by setting the CMD_CTRL.ALM_CLR to "0." |
| RCMD_ID | Echo-back of the CMD_ID in the command format | The RCMD_ID represents the response data of the RS-485 communication compatible product corresponding to the command change. Returns the echo of the CMD_ID of the command format. |
| CMD_ALM | 0: No command error<br>1: Command error state | The CMD_ALM is independent of the COMM_ALM, D_ALM and D_WAR. If a normal command is received after the occurrence of a command error, the CMD_ALM is automatically cleared. The CMD_ALM alarm/warning classification is specified in the **NETC01-M3** specifications. Refer to p.45 for details. |
| COMM_ALM | 0: No communication error<br>1: MECHATROLINK-Ⅲ communication error state | The COMM_ALM is independent of the CMD_ALM, D_ALM and D_WAR. The COMM_ALM is cleared at the leading edge of the CMD_CTRL.ALM_CLR or by the ALM_CLR command. Refer to p.45 for details. |

## 9.9 Timing chart of the data READ/WRITE_A command

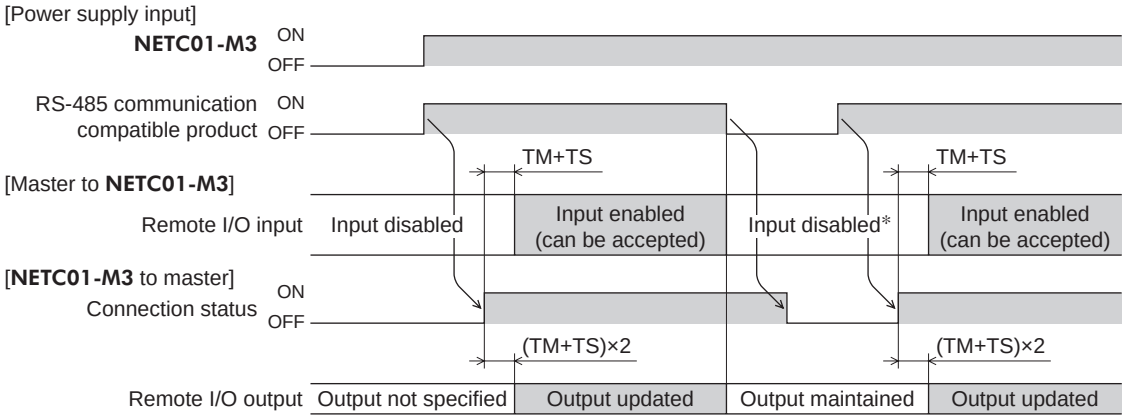
The command codes in the following timing charts are examples of the **AR** Series FLEX DC power input Built-in controller type.

TM: Communication cycle between the master station and **NETC01-M3**

TS: Communication cycle between the **NETC01-M3** and RS-485 communication compatible product.

### ■ When the power supply is turned on (remote I/O)

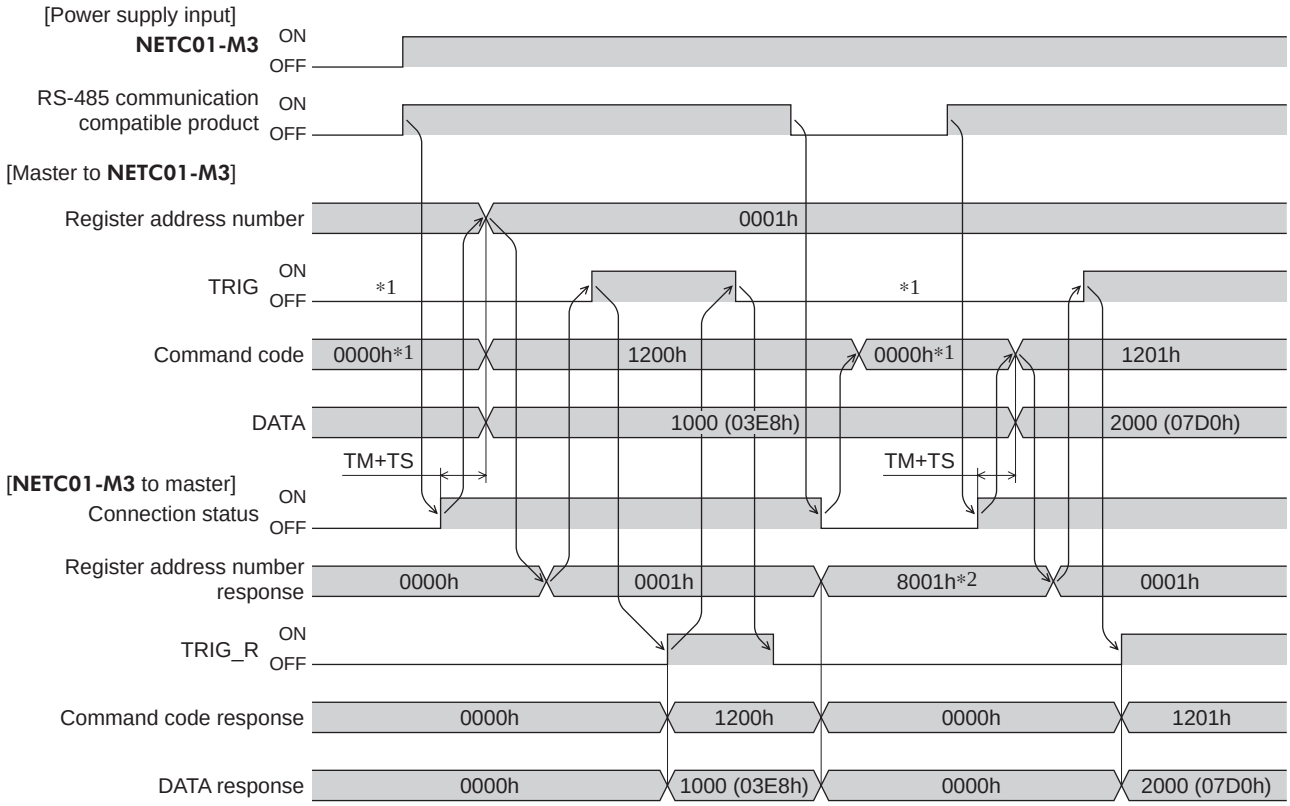
1) Turn on the power supply of the **NETC01-M3**.
2) Turn on the power supply of the RS-485 communication compatible product.
3) Check the connection status is turned from OFF to ON.




* When the connection status is OFF, turn the signals to start operation (START, HOME etc.) to OFF.

## ■ When the power supply is turned on (remote register)

1) Turn on the power supply of the **NETC01-M3**.
2) Turn on the power supply of the RS-485 communication compatible product.
3) Check the connection status is turned from OFF to ON. For the next step, refer to the next section "read parameter and operation data (remote register)."



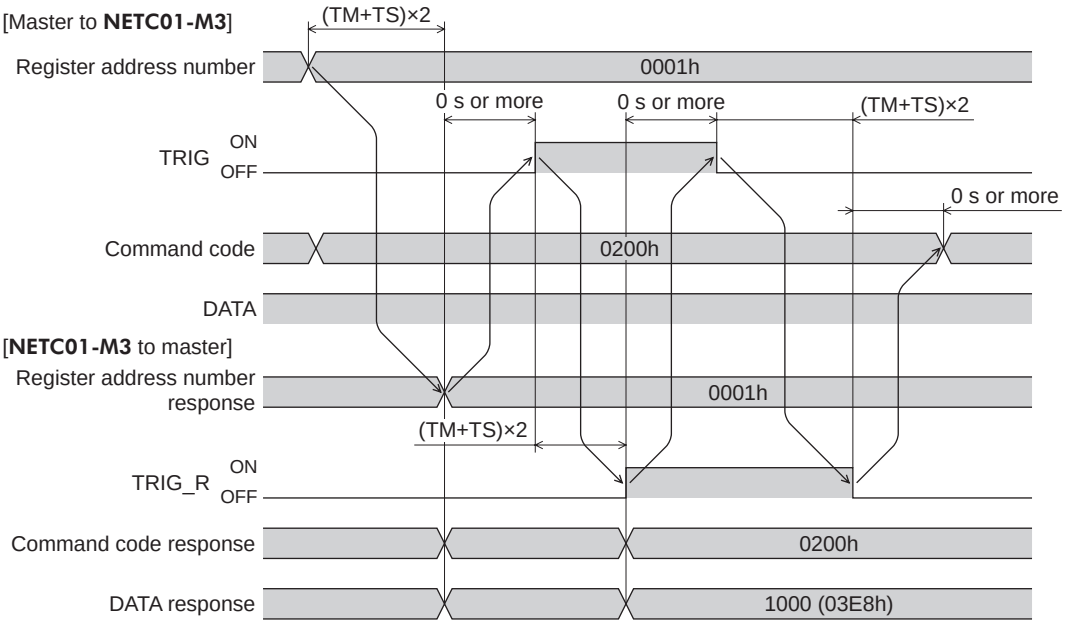

*1 When the connection status is OFF, set the command code to "0000h" and turn the TRIG to OFF.

*2 When the power supply of the RS-485 communication compatible product is OFF, the most significant bit of the register address number response becomes "1."

## ■ Read parameters and operation data (remote register)

1) Specify the register address number.
2) Check the register address number response.
3) Turn the TRIG from OFF to ON. The selected parameter or operation data is started reading.
4) After checking the TRIG_R was turned from OFF to ON, check the command code response and DATA response.
5) Turn the TRIG from ON to OFF, and check that the TRIG_R was turned from ON to OFF.

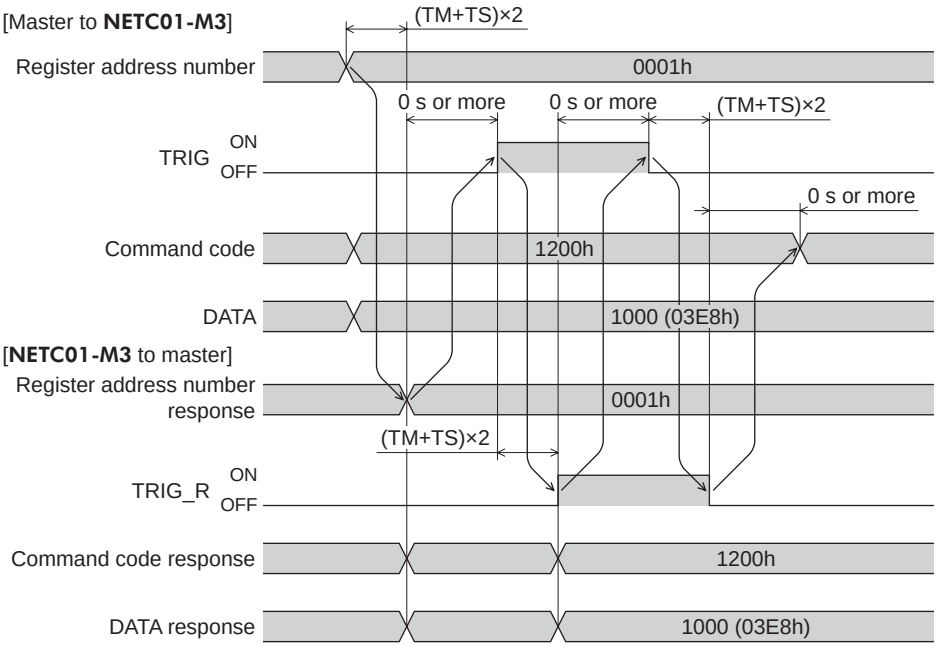
**When reading the "position (1000)" of the operation data No.0**



## ■ Write parameters and operation data (remote register)

1) Specify the register address number.
2) Check the register address number response.
3) Turn the TRIG from OFF to ON. The selected parameter or operation data is started writing.
4) After checking the TRIG_R was turned from OFF to ON, check the command code response and DATA response.
5) Turn the TRIG from ON to OFF, and check that the TRIG_R was turned from ON to OFF.

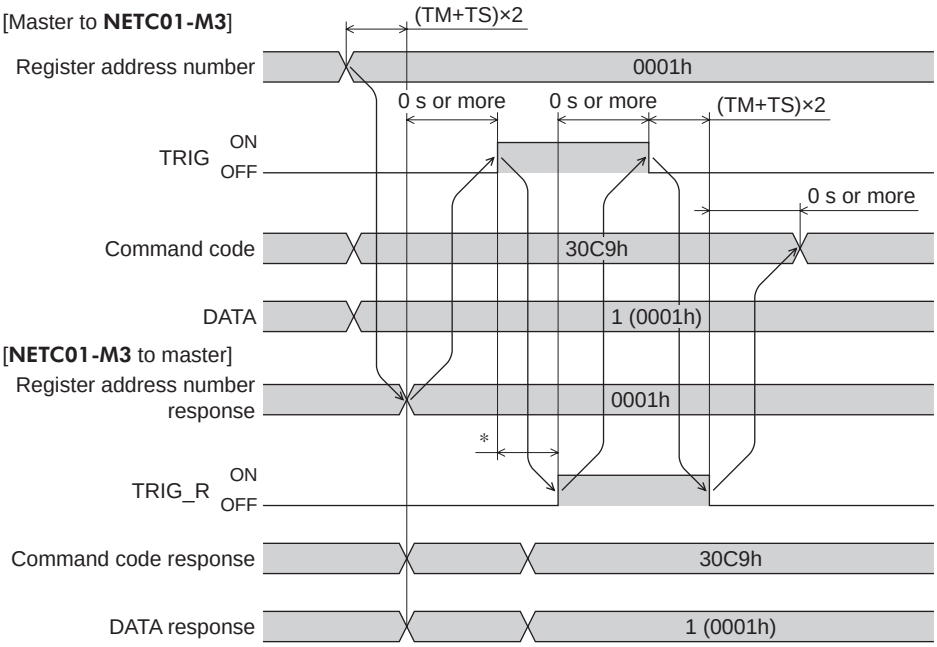
**When writing 1000 to the "position" of the operation data No.0**



## ■ Maintenance (remote register)

1) Specify the register address number.
2) Check the register address number response.
3) Turn the TRIG from OFF to ON. The selected maintenance command is executed.
4) After checking the TRIG_R was turned from OFF to ON, check the command code response and DATA response.
5) Turn the TRIG from ON to OFF, and check that the TRIG_R was turned from ON to OFF.

**When executing "batch NV memory write"**

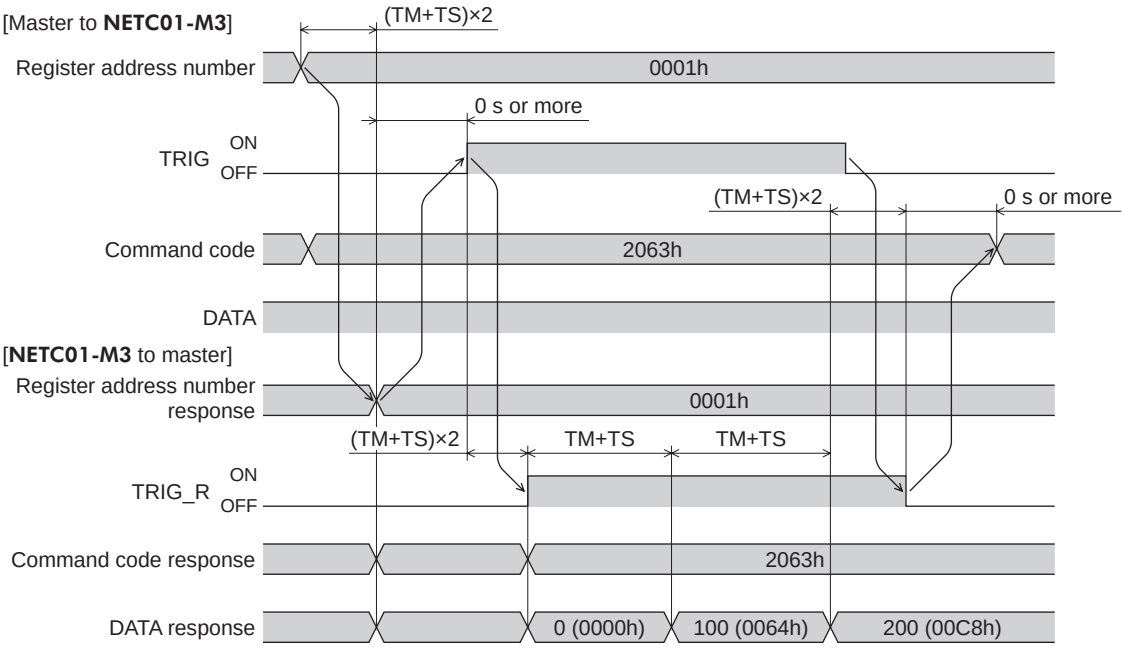



* It varies depending on the type of the RS-485 communication compatible products or commands.

## ■ Monitor (remote register)

1) Specify the register address number.
2) Check the register address number response.
3) Turn the TRIG from OFF to ON. The selected monitor command is executed.
4) After checking the TRIG_R was turned from OFF to ON, check the command code response and DATA response.
   The DATA response value is updated while the TRIG is ON.
5) Turn the TRIG from ON to OFF, and check that the TRIG_R was turned from ON to OFF.

**When monitoring the "command position"**

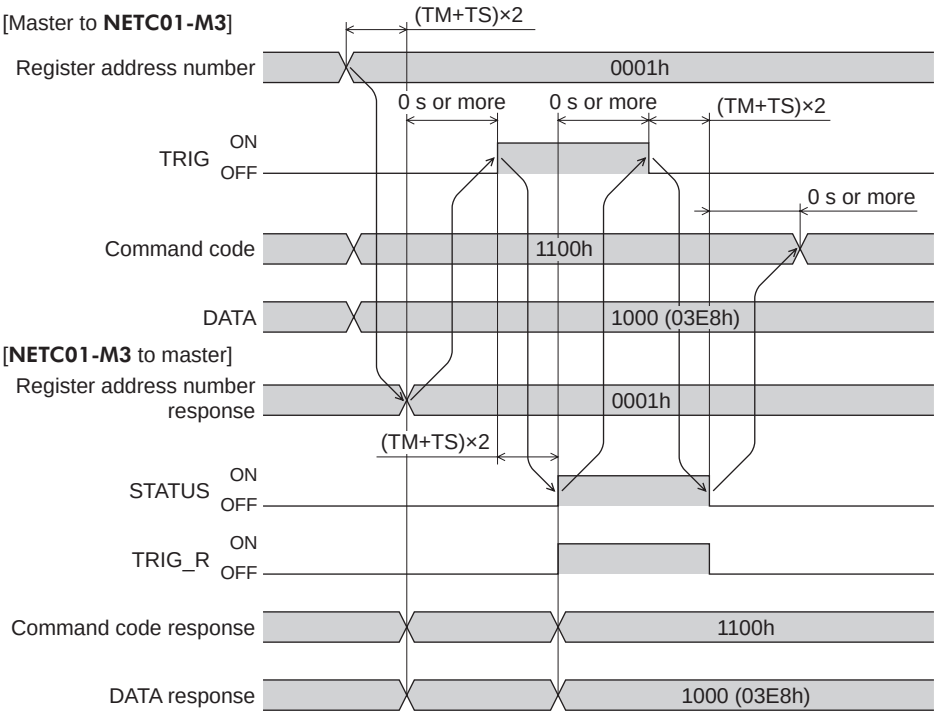


## ■ When an error has occurred (remote register)

1) Specify the register address number.
2) Check the register address number response.
3) Turn the TRIG from OFF to ON. The selected parameter or operation data is started writing.
4) When the written value is an error, the STATUS is turned from OFF to ON. Check the command code and DATA.
5) Turn the TRIG from ON to OFF, and reset the error status.

**Note** If an error has occurred in data transfer, the STATUS is turned ON.

**When specifying data that is outside the setting range (write 1000 to the "STOP input action" parameter)**

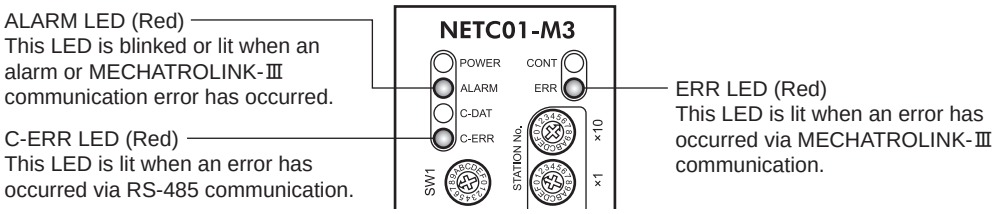


# 10 Troubleshooting and remedial actions

The **NETC01-M3** provides alarms that are designed to protect the **NETC01-M3** from poor connection, error in operation, etc. (protective functions), as well as warnings that are output before the corresponding alarms generate (warning functions).

## 10.1 Alarms and MECHATROLINK-Ⅲ communication error

When an alarm or MECHATROLINK-Ⅲ communication error has occurred, the ALARM LED on the **NETC01-M3** is blinked or lit. If the MECHATROLINK-Ⅲ communication error has occurred, the ERR LED is also lit.



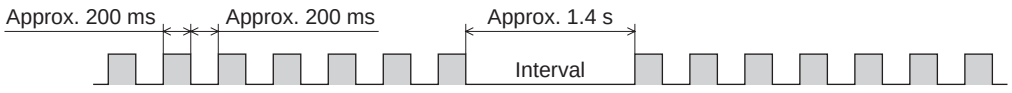

### ■ When an alarm in the NETC01-M3 unit was generated

If an alarm in the **NETC01-M3** unit has generated, RS-485 communication is stopped and the ALARM LED blinks.

The present alarm can be checked by counting the number of times the ALARM LED blinks. The present alarm can also be checked using the **OPX-2A** or **MEXE02**.

You can check the records of up to ten most recent alarms starting from the latest one, or clear the alarm records.

- **ALARM LED status (Example: RS-485 communication error)**




**Note** If an alarm is generated, the communication between the **NETC01-M3** and RS-485 communication compatible product is stopped. When RS-485 communication is stopped, the parameter command, maintenance command and monitor command of the RS-485 communication compatible product cannot be used.

- **Alarm reset**

Before resetting an alarm, always remove the cause of the alarm and ensure safety, and then cycle the power to reset the alarm.

**Note** The alarm in the **NETC01-M3** unit cannot be reset by the **OPX-2A**, **MEXE02** or via MECHATROLINK-Ⅲ communication.

### ■ When the MECHATROLINK-Ⅲ communication error has occurred

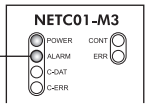
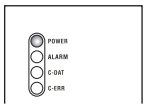
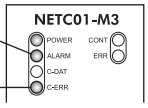
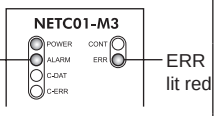
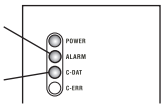
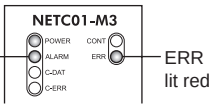
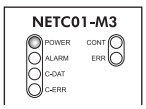
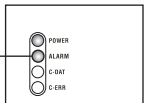
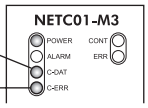
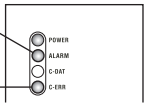
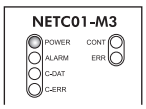
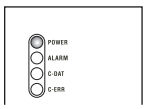
When the MECHATROLINK-III communication error has occurred, the ALARM LED is successively blinking or lit, and the ERR LED is lit. The motor operation is stopped but RS-485 communication is continued.

**How to reset the MECHATROLINK-Ⅲ communication error**

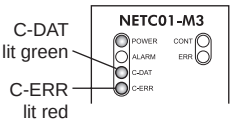
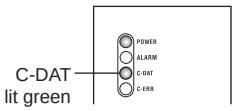
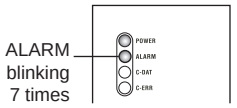
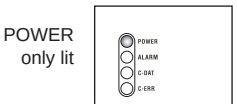
Before resetting an error, always remove the cause of the error and ensure safety, and perform one of the reset operations specified below.

- Execute the alarm reset for the **NETC01-M3** or RS-485 communication compatible product using the **OPX-2A** or **MEXE02**.
- Cycle the power of the **NETC01-M3** or master device.
- Execute the clear alarm or warning command (ALM_CLR: 06h) of MECHATROLINK-Ⅲ communication.

## ■ List of alarm and MECHATROLINK-Ⅲ communication error

<table>
<tr><th rowspan="2">Product</th><th rowspan="2">Type</th><th colspan="2">LED status</th><th rowspan="2">Alarm code</th></tr>
<tr><th>NETC01-M3</th><th>RS-485 communication compatible product</th></tr>
<tr><td rowspan="3">NETC01-M3 unit</td><td rowspan="3">Alarm</td><td>ALARM blinking 9 times<br>  </td><td rowspan="3">POWER only lit<br>  </td><td>A1h</td></tr>
<tr><td>ALARM blinking 7 times<br>C-ERR lit red<br>  </td><td>E3h<br>E4h</td></tr>
<tr><td></td><td>E6h</td></tr>
<tr><td rowspan="5">Between master and NETC01-M3</td><td rowspan="3">MECHATROLINK-Ⅲ command error (CMD_ALM)</td><td rowspan="3">ALARM successively blinking<br>ERR lit red<br>  </td><td rowspan="5">ALARM blinking 7 times<br>C-DAT lit green<br>  </td><td>08h</td></tr>
<tr><td>0Ah</td></tr>
<tr><td>0Ch</td></tr>
<tr><td rowspan="2">MECHATROLINK-Ⅲ communication error (COMM_ALM)</td><td>09h</td></tr>
<tr><td rowspan="2">ALARM lit red<br>ERR lit red<br>  </td><td>08h</td></tr>
<tr><td>09h<br>0Ah<br>0Bh</td></tr>
<tr><td>Between NETC01-M3 and RS-485 communication compatible product</td><td>MECHATROLINK-Ⅲ communication error</td><td>POWER only lit<br>  </td><td>ALARM blinking 7 times<br>  </td><td>–</td></tr>
<tr><td>C-DAT lit green<br>C-ERR lit red<br>  </td><td>ALARM blinking 7 times<br>C-ERR lit red<br>  </td></tr>
<tr><td>POWER only lit<br>  </td><td>POWER only lit<br>  </td></tr>
</table>

| Alarm type | System status | Cause | Remedial action |
|---|---|---|---|
| EEPROM error | Communication between the **NETC01-M3** and RS-485 communication compatible product cannot be performed. | The stored data of the **NETC01-M3** was damaged. | Initialize data using any of the maintenance command, **OPX-2A** or **MEXE02**. |
| Communication switch setting error | | The transmission rate setting switch (SW1) of RS-485 communication was set outside the range (8 and above). | Set the transmission rate setting switch (SW1) to "7". |
| RS-485 communication error | | The RS-485 communication error has been detected three times consecutively. | • Check the transmission rate of RS-485 communication.<br>• Check the connector or cable of RS-485 communication. |
| Network connection product error | | The "communication (address number)" parameter is outside the setting range. | Set either "0: Disable" or "1: Enable." |
| Unsupported command | Communication between the **NETC01-M3** and master station cannot be performed. | The command that was not implemented was executed. | Re-examine the command sending sequence of the master station. |
| Command execution condition error | | The order (sequence) of the command that has been sent is not correct. | |
| Phase error | | The command not being permitted in the current phase was executed. | |
| Invalid data | | • The parameter number or data address is not correct.<br>• The data in the command is not correct. | Re-examine the command data content that the master station sends. |
| FCS error | | The MECHATROLINK-Ⅲ communication cable is affected by electrical noise. | • Check the wiring and surrounding area of the communication cables.<br>• Take measures for protection against electrical noise. |
| Cyclic data not received | | | |
| Synchronous frame not received | | | |
| Synchronization interval error | | The transmission cycle besides specification was set. | Re-examine the setting of the transmission cycle of the master station. |
| – | Communication between the **NETC01-M3** and RS-485 communication compatible product cannot be performed. | The power supply of the **NETC01-M3** was shut off while communicating via RS-485 communication. | Check the power supply of the **NETC01-M3**. |
| | | The setting of the SW1 of the **NETC01-M3** is not the same as that of the transmission rate of RS-485 communication compatible product. | Check the setting of the switch. |
| | | The "communication (address number)" parameter is set to "0: Disable." | Set the "communication (address number)" parameter to "1: Enable." |

| Product | Type | LED status | | Alarm code |
|---|---|---|---|---|
| | | **NETC01-M3** | RS-485 communication compatible product | |
| Between **NETC01-M3** and RS-485 communication compatible product | MECHATROLINK-Ⅲ communication error |  |  <br>  <br>  | – |

## 10.2 Warning

If a warning generates, the D_WAR of the command status (CMD_STAT) for the **NETC01-M3** is turned ON (1).
The motor will continue to operate.
Once the cause of the warning is removed, the warning will automatically cleared and the D_WAR will be turned OFF (0).
The present warning can be checked using the **OPX-2A** or **MEXE02**. You can also check the records of up to ten most recent warnings starting from the latest one, or clear the warning records.

**Note** The warning records can be cleared by turning off the **NETC01-M3** power.

| Warning code | Warning type | Cause | Remedial action |
|---|---|---|---|
| E4h | RS-485 communication error | The RS-485 communication error was detected. | • Check the transmission rate of RS-485 communication.<br>• Check the connector or cable of RS-485 communication. |
| E5h | RS-485 communication timeout | Even though the receiving cycle of RS-485 communication has passed, the response frame was not completed receiving. | • Check the connector or cable of RS-485 communication.<br>• Check the power supply of the RS-485 communication compatible product. |

| Alarm type | System status | Cause | Remedial action |
|---|---|---|---|
| – | Communication between the **NETC01-M3** and RS-485 communication compatible product cannot be performed. | The RS-485 communication compatible product corresponding to the "communication (address number)" parameter does not exist. | Check the address number of the RS-485 communication compatible product. |
| | | The communication of the RS-485 communication compatible product was shut off while communicating. | • Check the RS-485 communication cable.<br>• Check the power supply of the RS-485 communication compatible product. |
| | | When the RS-485 communication cable was connected incompletely or it was not connected, the power supply was turned on. | Check the RS-485 communication cable. |

# 11 Inspection

It is recommended that periodic inspections for the items listed below are conducted after each operation of the motor. If an abnormal condition is noted, discontinue any use and contact your nearest Oriental Motor sales office.

- Is any of the **NETC01-M3** DIN rail mounting parts loose?
- Is any of the connection parts of the **NETC01-M3** loose?
- Is there attachment of dust, etc., on the **NETC01-M3**?
- Are there any strange smells or appearances within the **NETC01-M3**?

**Note** The **NETC01-M3** uses semiconductor elements. Handle the **NETC01-M3** with care since static electricity may damage semiconductor elements. Static electricity may damage the **NETC01-M3**.

# 12 General specifications

## ■ Environment specification

| | Operation environment | Storage environment<br>Shipping environment |
|---|---|---|
| Ambient temperature | 0 to +40 °C (+32 to +104 °F)<br>(non-freezing) | −25 to +70 °C (−13 to +158 °F)<br>(non-freezing) |
| Humidity | 85% or less (non-condensing) | |
| Altitude | Up to 1000 m (3300 ft.) above sea level | Up to 3000 m (10000 ft.) above sea level |
| Surrounding atmosphere | No corrosive gas, dust, water or oil | |

## ■ Insulation specification

| | | |
|---|---|---|
| Insulation resistance | Between FG terminal and power supply terminals | 100 MΩ or more when 500 VDC megger is applied |
| Dielectric strength | | Sufficient to withstand 500 VAC at 50/60 Hz applied for 1 minute, leak current 10 mA or less. |

## ■ RS-485 communication specification

| | |
|---|---|
| Electrical characteristics | In conformance with EIA-485, straight cable<br>Use a twisted pair cable (TIA/EIA-568B CAT5e or higher is recommended) and keep the total wiring distance including extension to 50 m (164 ft.) or less. |
| Communication mode | Half duplex, Asynchronous mode (data: 8 bits, stop bit: 1 bit, parity: none) |
| Transmission rate | 625 kbps |
| Protocol | Frame size: 10 bytes (fix), binary transmission |
| Maximum number of connected units | 8 units or 16 units (it varies depending on the operation mode.) |

## ■ MECHATROLINK-Ⅲ communication specification

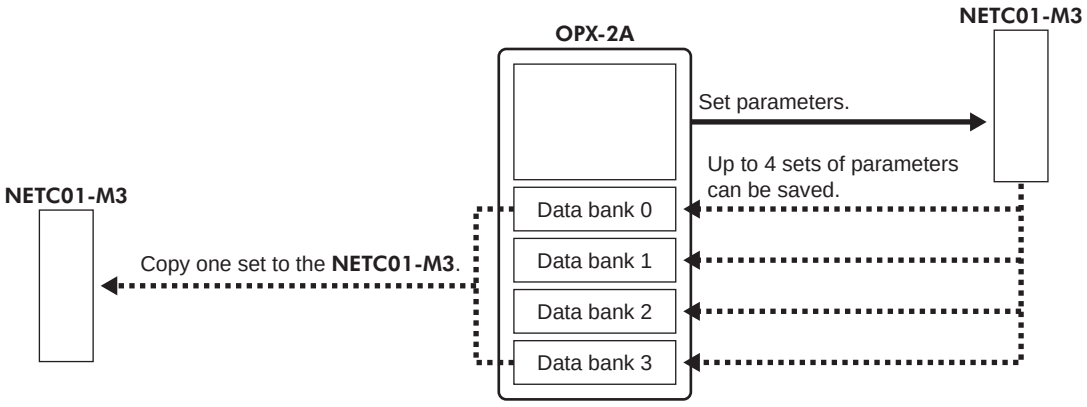
| | |
|---|---|
| Type of Connection | Cascade connection/Star connection/Point to Point connection |
| Transmission cable | MECHATROLINK-Ⅲ dedicated cable (CAT5e STP)<br>To connect the **NETC01-M3**, the dedicated cable with connector is recommended. |
| Connector | Industrial mini I/O connector (Tyco Electronics AMP) |
| Transmission distance | 6300 m (20669.3 ft.) maximum |
| Distance between stations | 100 m (328.1 ft.) maximum, 200 mm (7.87 in.) minimum |
| Baud rate | 100 Mbps |
| Transmission method | 4B/5B MULT-3 |
| Access control method | Master - Slave |
| Electrical insulation between devices and transmission lines | Transformer |
| Number of stations connected | Up to 62 stations |
| Station address | 03h to EFh (Factory setting: 61h) |
| Communication mode | Cyclic communication mode (Asynchronous command) |
| Transmission cycle | 0.5/1.0/1.5/2.0/2.5/3.0/3.5/4.0/8.0 ms |
| Data size | 16/32/48/64 (Factory setting: 32 bytes) |
| Implemented commands | Standard I/O profile command |

# 13 Operation using the OPX-2A

This chapter explains the overview and operation using a data setter **OPX-2A**.

## 13.1 Overview of the OPX-2A

The **OPX-2A** is a data setter that lets you set parameters and monitor the communication time.
In addition, the **OPX-2A** can be used to save the data of **NETC01-M3**. There are four destinations (data banks) to save data.




The **OPX-2A** can be used for the following purposes:

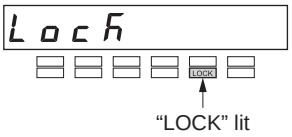
- The parameters for the **NETC01-M3** can be set.
- The communication time and status can be monitored.
- The alarm records can be checked and cleared.
- The parameters set in the **NETC01-M3** can be saved to the **OPX-2A**.
- The parameters saved in the **OPX-2A** can be copied to another **NETC01-M3** connected to the **OPX-2A**.

### ■ Edit lock function

Enable the edit lock function if you want to prevent parameters from being edited or cleared. Parameters cannot be changed or deleted while the edit lock function is enabled.

- **Setting the edit lock function**

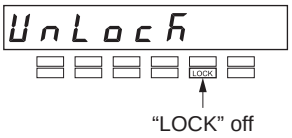
In the top screen of each operation mode, press the【MODE/ESC】key for at least 5 seconds. The display will show “LocK” and the edit lock function will be enabled. The “LOCK” LED in the LED indicator area will also be lit.



“LOCK” lit

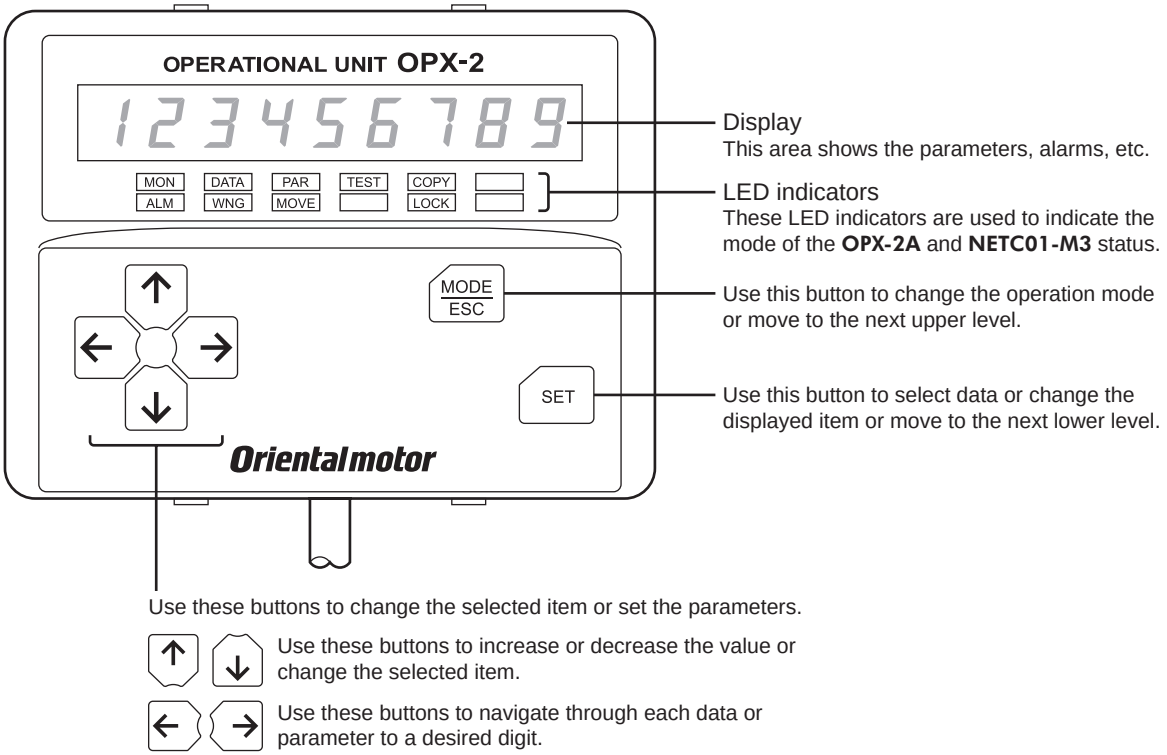
- **Canceling the edit lock function**

Again in the top screen of each operation mode, press the【MODE/ESC】key for at least 5 seconds. The display will show “UnLocK” and the edit lock function will be cancelled. The “LOCK” LED in the LED indicator area will turn off.



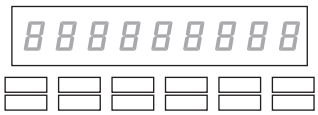
“LOCK” off

## 13.2 Names and functions of parts




## 13.3 Notation

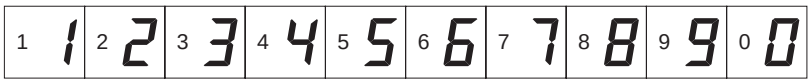
In this manual, keys are denoted by symbols, such as [MODE/ESC][SET][↑][↓][←][→].
In figures, a simplified illustration of the display and LED indicators is used, as shown below.



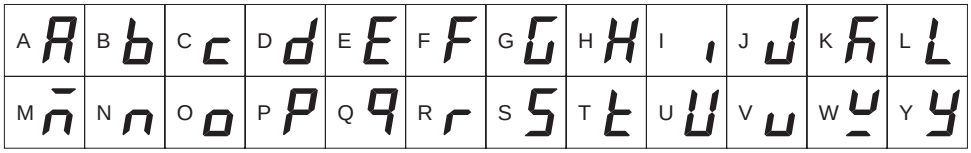
## 13.4 How to read the display

The display consists of 7-segment LEDs. (The number “5” and alphabet “S” are the same.)

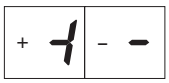
• Numbers




• Alphabets

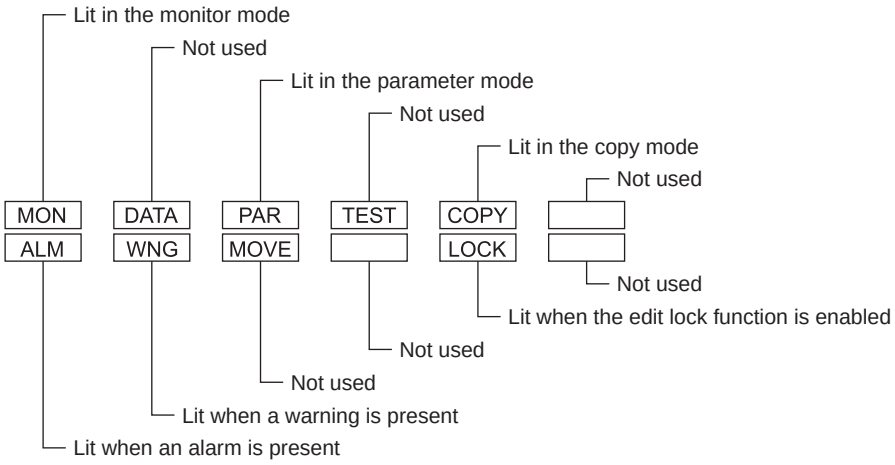



• Signs



### ■ How to read the LED indicators

When the operation mode is changed or an alarm or warning generates, a corresponding LED will be lit. While the edit lock function is enabled, the condition is also indicated by the illumination of a corresponding LED.

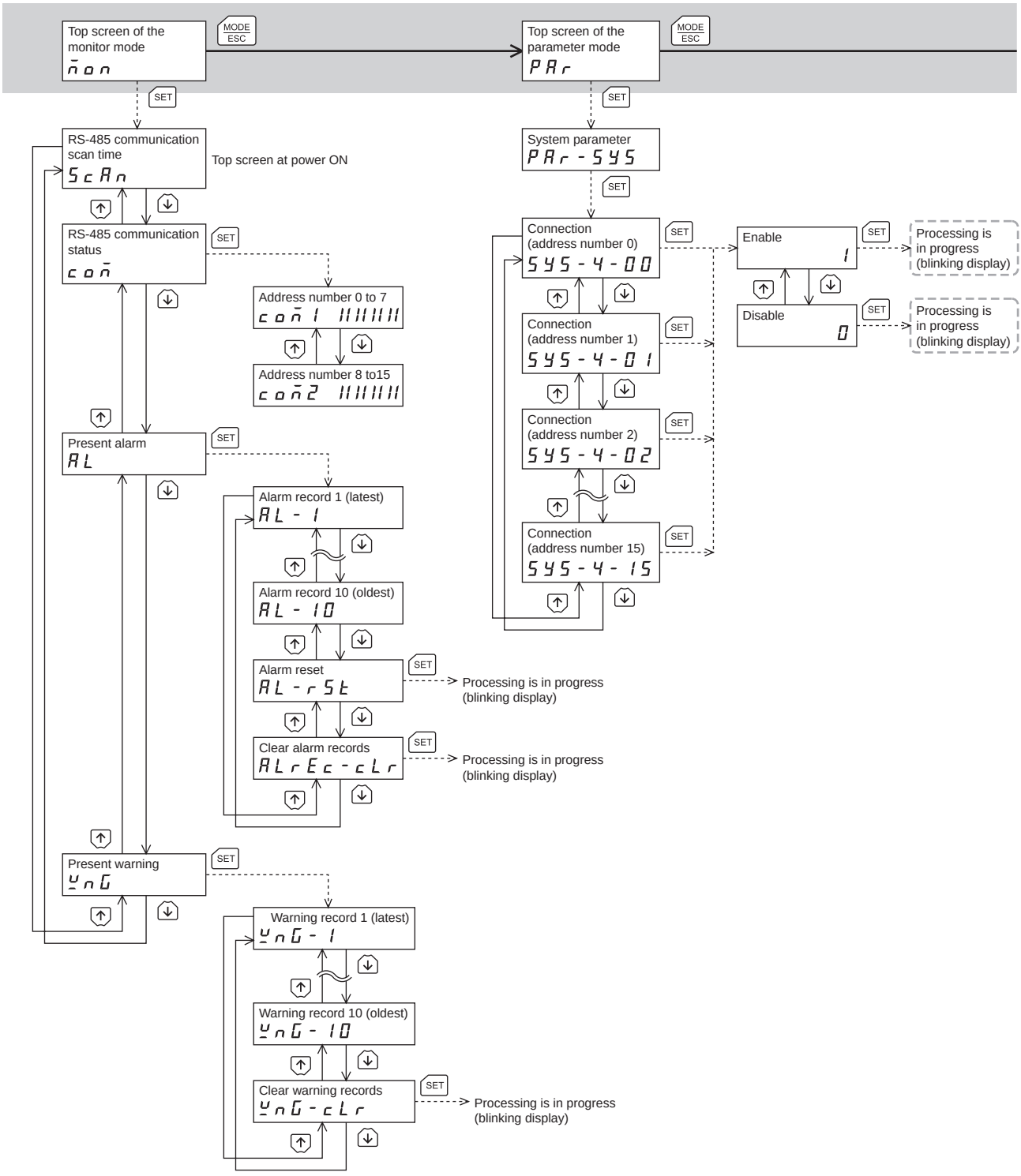



## 13.5 OPX-2A error display

Errors displayed on the **OPX-2A** are explained.

| Error display | Meaning | Action |
|---|---|---|
|  | A communication error occurred between the **OPX-2A** and **NETC01-M3**. | • Check if the **OPX-2A** is connected securely.<br>• Check if the **OPX-2A** cable is disconnected or damaged.<br>• The **OPX-2A** or the communication part of the **NETC01-M3** may have damaged. Contact your nearest Oriental Motor sales office. |

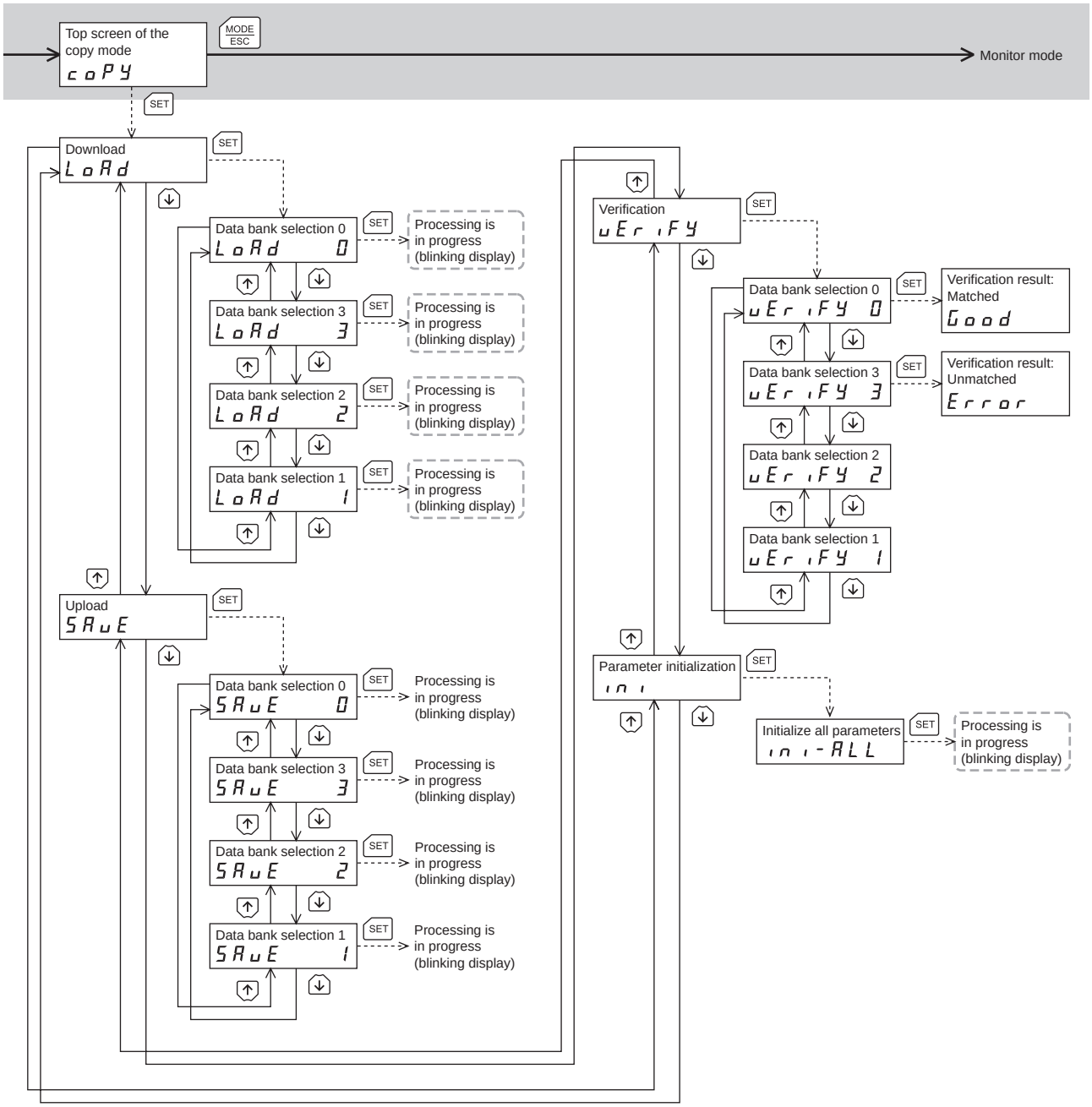
## 13.6 Screen transitions




In the lower level except the top screen, press the MODE ESC key to return to the previous level.

**Note**

- For the parameter mode and copy mode, if the【SET】key is pressed while processing the memory of the **NETC01-M3** via MECHATROLINK-Ⅲ communication, the screen cannot move to the lower level from the top screen and "mEm-busy" is displayed. Be sure to wait until the memory processing is completed, before pressing the【SET】key.
- The following limitations are present while the edit lock function is enabled.
  - Parameter mode, copy mode: Although they are displayed on the screen, they are unable to operate.
  - Clearing the alarm and warning records: They are not displayed on the screen.




- - - Broken line indicates that data writing cannot be executed when internal processing is in progress via MECHATROLINK-Ⅲ communication.
"mEm-bUSy" is displayed even when the SET key is pressed.

# 13.7 Monitor mode

## ■ Overview of the monitor mode

- **Monitoring the communication status**

  The communication scan time and communication status can be monitored.

- **Checking alarms/warnings, clearing alarm/warning records, and resetting alarms**
  - If an alarm or warning generates, a corresponding alarm code or warning code will be displayed. You can check the code to identify the details of the alarm/warning.
  - Up to ten most recent alarms/warnings can be displayed, starting from the latest one.
  - The present alarm can be reset.
  - Alarm/warning records can be cleared.

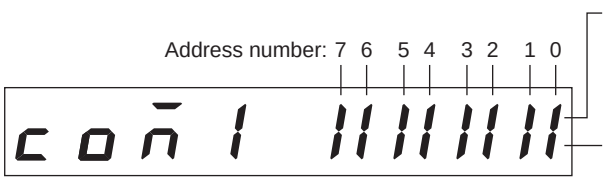
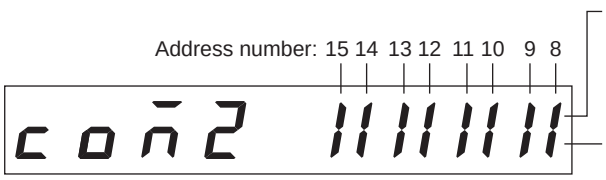
## ■ Monitor items

- **RS-485 communication scan time**

  The communication time between the **NETC01-M3** and connected product can be monitored in real time (unit: msec).

- **RS-485 communication status**

  The communication status of the connected product can be checked.

| | |
|---|---|
| Address number 0 to 7 |  |
| Address number 8 to 15 |  |

- **Present alarm**

  When an alarm generates, a corresponding alarm code will be displayed.
  Also, alarm records can be checked and cleared.

  **Alarm code list**

| No. of ALARM LED blinks | Alarm code | Alarm type |
|---|---|---|
| 9 | A1h | EEPROM error |
| 7 | E3h | Communication switch setting error |
| | E4h | RS-485 communication error |
| | E6h | Network connection product error |

**Note**

- Do not turn off the **NETC01-M3** power while alarm records are being cleared (=while the display is blinking). Doing so may damage the data.
- If an alarm generates, communication between the **NETC01-M3** and RS-485 communication compatible product is stopped. The remote I/O, parameter command, maintenance command and monitor command of the RS-485 communication compatible product cannot be used.
- To reset the alarms, cycle the **NETC01-M3** power.

- **Present warning**

  When a warning generates, a corresponding warning code will be displayed. Warning records can be checked and cleared.

  **Warning code list**

| Warning code | Warning type |
|---|---|
| E4h | RS-485 communication error |
| E5h | RS-485 communication timeout |

**Note**

- Do not turn off the **NETC01-M3** power while a warning records are being cleared (=while the display is blinking). Doing so may damage the data.
- Warning records can be cleared automatically by turning off the **NETC01-M3** power.

## 13.8 Parameter mode

When a parameter has been changed, the new parameter will become effective after the **NETC01-M3** power is cycled.

### ■ Application parameter

| Parameter name | Description | Setting range | Initial value | **OPX-2A** screen display |
|---|---|---|---|---|
| Data setter edit | Sets whether it is possible to edit using the **OPX-2A**. | 0: Disable<br>1: Enable | 1: Enable | −* |

* It can be changed by setting/canceling the edit lock function on the **OPX-2A**.

### ■ System parameter

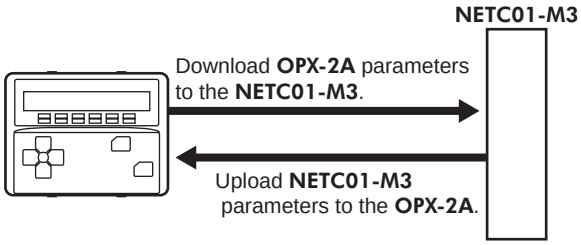
| Parameter name | Description | Setting range | Initial value | **OPX-2A** screen display |
|---|---|---|---|---|
| Connection (address number 0) | Sets whether to enable or disable the communication with the connected product. | 0: Disable<br>1: Enable | 0: Disable | SYS-4-00 |
| Connection (address number 1) | | | | SYS-4-01 |
| Connection (address number 2) | | | | SYS-4-02 |
| Connection (address number 3) | | | | SYS-4-03 |
| Connection (address number 4) | | | | SYS-4-04 |
| Connection (address number 5) | | | | SYS-4-05 |
| Connection (address number 6) | | | | SYS-4-06 |
| Connection (address number 7) | | | | SYS-4-07 |
| Connection (address number 8) | | | | SYS-4-08 |
| Connection (address number 9) | | | | SYS-4-09 |
| Connection (address number 10) | | | | SYS-4-10 |
| Connection (address number 11) | | | | SYS-4-11 |
| Connection (address number 12) | | | | SYS-4-12 |
| Connection (address number 13) | | | | SYS-4-13 |
| Connection (address number 14) | | | | SYS-4-14 |
| Connection (address number 15) | | | | SYS-4-15 |

**Note**
- If operations are limited by the edit lock function (p.51), parameters cannot be edited.
- The non-volatile memory can be rewritten approx. 100,000 times.

## 13.9 Copy mode

### ■ Download

Parameters saved in the **OPX-2A** can be copied to the **NETC01-M3**.
If a download error occurs, a code indicating the description of the error will blink on the display. Download will not be performed and the display will return to the top screen of download.
Refer to "Error of the copy mode" for the error display.




### ■ Upload

Parameters saved in the **NETC01-M3** can be copied to the **OPX-2A**.

### ■ Verification

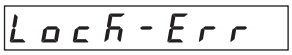
Parameters in the **OPX-2A** can be verified against the corresponding parameters in the **NETC01-M3**.
If the verification finds that the two sets of parameter match, “Good” will be shown. If the two do not match, “Error” will be shown.
If a verification error occurs, a code indicating the description of the error will blink on the display.
Verification will not be performed and the display will return to the top screen of verification.
Refer to "Error of the copy mode" for the error display.

### ■ Initializing parameters

Parameters saved in the **NETC01-M3** can be restored to the initial values.

## ■ What happens when the【SET】key is pressed while the edit lock function is enabled

While the edit lock function is enabled, you cannot move to any lower level from the top screen of the copy mode. Pressing the【SET】key will generate an error, and “LocK-Err” will be shown. Be sure to cancel the edit lock function before pressing the【SET】key. Refer to p.51 for the procedure to cancel the edit lock function.

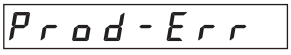
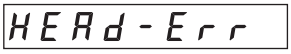
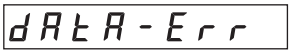



**Note**

- If the【SET】key is pressed while processing the memory of the **NETC01-M3** via MECHATROLINK-Ⅲ communication, the screen cannot move to the lower level from the top screen and "mEm-busy" is displayed. Be sure to wait until the memory processing is completed, before pressing the【SET】key.
- When a system parameter has been changed, the new parameter will become effective after the power is cycled. When system parameters were changed by downloading, cycle the **NETC01-M3** power.
- Do not turn off the **NETC01-M3** power while the download is still in progress (=while the display is blinking). Doing so may damage the data.

## ■ Error of the copy mode

If an error occurs in download or verification, the error code will blink on the display.
At this time, the processing will not be executed and the display will return to the top screen.

| Blinking display | Description | Action |
|---|---|---|
|  | There is a discrepancy between the selected product series and the data being processed. | • Check the product series.<br>• Check the data bank number on the **OPX-2A**. |
|  <br>  | An error occurred while processing. | Execute the processing again. If the same error occurs, the parameters saved in the **OPX-2A** may have damaged. Upload and set the parameters of the **OPX-2A** again. |
|  | The specified data bank number does not contain data. | Check the data bank number. |
|  | An error occurred while parameter was being downloaded. | Perform download again. |

# 14 Accessories (sold separately)

## ■ Data setter

The data setter lets you set parameters for your **NETC01-M3** with ease and monitor the communication time.

Model: **OPX-2A**

## ■ Data setting software

The data setting software lets you set parameters for your **NETC01-M3** and monitor the communication time using a PC. The software comes with a PC interface cable [5 m (16.4 ft.)]. The cable is connected to the USB port on the PC.

Model: **MEXE02**

## ■ RS-485 communication cable

The RS-485 communication compatible product can be connected.

Model: **CC001-RS4** [0.1 m (0.3 ft.)]
**CC002-RS4** [0.25 m (0.8 ft.)]

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