

# **Dynamic Path Failover Driver for AIX FibreQuik Host Bus Adapter Installation and User Guide**

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# Dynamic Path Failover for AIX

## Introduction

The Cambex FibreQuik™ Fibre Channel host bus adapters provide attachment of Fibre Channel devices to PCI or Micro Channel based servers. They support the SCSI-FCP protocol.

When used with the Cambex DPF (Dynamic Path Failover) software, two adapters in a system provide greater throughput and total protection from failure of a fibre channel component.

In addition, the Cambex AutoRecover daemon, `cbxdpfar`, will automatically detect when a failed path has been repaired and make it available as a standby path. For arrays that support preferred paths, AutoRecover will automatically resume operation on the repaired path, otherwise, an operator may manually change paths to do load balancing.

Storage (SAN) and communications (LAN) networks have resulted in a physical and logical separation between the storage device (typically a SAN-connected RAID array), the storage user (typically an Enterprise Server, which we will refer to below as the server) and the administration station (typically a remote workstation).

As storage systems have evolved from JBOD (just bunch of disks) to complex shared RAID systems, the management software has also grown in complexity. The following sections describe the different levels of management software.

## **SAN Management**

SAN Management is the top layer. It is responsible for assigning the required access for each server to each storage device. The unit of storage is the LUN (Logical Unit Number) which acts the same as a single disk directly attached to the server. In reality, a LUN is made up of portions of a number of disks under the direction of a RAID controller in the storage device. SAN Management typically requires a process running on each managed server communicating with the manager running on the administering station.

## **Storage Management**

The Storage Management layer, or RAID manager, is the layer that communicates with the RAID controllers on the storage device. This is the layer used to create, modify or delete LUNs.

The Storage Management layer may provide SAN Management functions, but only for the specific storage device being managed. Storage management typically runs on a server attached to the storage device (in-band) but may also run over a network (out-of-band).

## **Path Management**

Path Management includes a variety of software for managing the various fibre channel components such as HBAs (Host Bus Adapters), hubs and switches. It is used to display path status and allow control over multiple paths between servers and storage. To avoid having to access a large number of unrelated software interfaces, integration of the various Path Management components is usually done using a management tool

communicating via a network connection to each managed device.

The Cambex Dynamic Path Failover driver is a Path Management component that allows multiple paths to a storage device and provides automatic failover between available paths. Cambex Dynamic Path Failover software provides both a command line interface and access through smit, the standard integrated management tool for AIX.

## **SCSI and FCP Drivers**

AIX makes two types of device drivers available. SCSI device drivers support SCSI-2 disk and tape devices. FCP device drivers support newer SCSI-3 disk and tape devices, which provides a larger address space for target ID and LUN. When using the FCP device driver, the adapter will be configured with a name like **fscsi2**.

## **Load Balancing**

Selection of which path to use happens in one of three ways. Static load balancing allows the operator to select which path is used to access a LUN. This is the default method. Preferred Paths allow certain RAID arrays to automatically specify a path choice. See the next section on Preferred Paths for more information. Finally, turning on Load Balancing will send I/O on all available paths using round robin scheduling.

## **How Preferred Paths work**

The basic idea of multipathing is fairly simple. Access a disk on one of two paths. If the path fails, move I/O activity to the other path. We build on that basis by adding more factors into the configuration and seeing what effect they have.

A path is defined as an end-to-end connection through a SAN, ignoring any intermediate routing points. A complex SAN may have multiple connections from an HBA to a storage device, but this is invisible to the software. The combination of one HBA to one target is one path, regardless of how it is routed.

### **Multiple LUNs**

The effect of multiple LUNs on a RAID controller is that we can choose to distribute them so as to balance the I/O across multiple paths. The choice can be made in one of two ways. If one RAID controller has preference over the other, we call this "controller preference". If the selection is made in the host software we call this "target preference". A third type of preference is to lock a LUN to a particular HBA, called "HBA preference".

### **More than two paths**

With four paths (for example) we have to sort the paths into an order in which they are chosen when the primary path fails. This order should depend on getting the best performance when a path segment fails. For example, if our performance is limited by the IOPS that can be handled by each RAID controller, then we want to balance the LUNs between the RAID controllers,



and set up preferences so that the remaining paths to the same controller are preferred over paths to the alternate controller.

**Example 1)** Suppose we have two HBAs, a switch, and two RAID controllers. A total of four cables, and four paths to each LUN (2 HBAs x 2 RAID controllers). We use the RAID controller preference to select which controller each LUN is accessed on. The target preference lets me balance those accesses across the two HBAs.

**Example 2)** We have two switches, 2 HBAs and 2 RAID controllers, a fully redundant system. We add an inter-switch link for in-band management, but we do not want to use this as a data path if there are any other paths available. We set the ISL paths' target preference lower than the direct paths, so they will be used last.

**Example 3)** A 2G RAID array is connected to a 2G switch, which does speed matching to two 1G HBAs in the host. To avoid saturating either of the 1G paths, We use HBA preference when balancing the LUNs across the paths.

## Multiple Hosts

When we have more than two hosts accessing the same storage, we find that the limit is usually the number of controller ports. The HBAs will run below the maximum bandwidth, but the controllers need to be balanced. Use the controller preferences and target preferences to balance the loads.

Normally, each host accesses different LUNs through either controller, so all paths are independent. One special case is where a RAID controller has LUN groups. All LUNs in a LUN group are accessed on the same controller. If the different LUNs

are accessed by different hosts, we could have the problem of "thrashing". One host tries to move the LUN group to preferred controller A while the other host tries to move the group to preferred controller B. Anti-thrashing code prevents this problem in the multipathing software.

## Adapter Specifications

	<b>PC2000LC-HPSP</b>	<b>PC4000 (Single Port)</b>	<b>PC2000LC-A</b>	<b>PC4002 (Dual Port)</b>	
Bus		PCI		PCI-X 2.0	
Data rate (each dir.)		100/200		100/200/400	MB/s
Cable length - copper		30			
- multimode optical		500		70	m
- single mode optical		10			
Voltage		3.3 or 5		3.3	V
Power		7.2		8.0	W
Shipping weight		10		10	oz

## Trademarks

Dynamic Path Failover and FibreQuik are trademarks of Cambex Corporation.

# Software and Hardware Installation

## Driver Installation (command line)

The examples assume that the driver CD is mounted at /mnt and that you are installing on AIX 5.1. The name and revision level of the uninstalled driver image may be examined by issuing the command (as root):

```
installp -ld <device>
```

where <device> is the path to the drivers, such as /mnt/AIX4/ for the CD or the name of a driver directory on the hard disk. Example output would be:

```
Fileset Name          Level      I/U Q Content
=====
PC1000.driver.obj    2.5.10.25      I  b  usr
# PC1000 Fibre Channel Adapter Driver (AIX 5L)

cbxdpf.driver.obj    5.1.0.23      I  b  usr
# Cambex Dynamic Path Failover Driver
```

Before installing a new version of the driver, delete the previous version of the driver. Note that any file systems must be unmounted, volume groups exported and SCSI devices must be removed before removing the driver. Be sure to have a complete backup of all data before updating the driver. The command to remove the driver is:

```
installp -u <name>.driver.obj
```

where names are cbxdpf and PC1000 or PC4000 as shown above.

The new driver may be installed on the system with the command:

```
installp -acd <device> all
```

where <device> is as described above.

example:

```
installp -acd /mnt/AIX5.1 all
```

After installing the driver, see the README file for additional information and release notes.

```
/usr/lpp/cbxfc/READ_ME  
/usr/lpp/PC4000/READ_ME  
/usr/lpp/cbxdpf/READ_ME
```

## Driver Installation (smit)

The smit path is

```
Software Installation and Maintenance
Install and Update Software
Install and Update Software by Package Name
```

For item " INPUT device / directory" use `/mnt/AIX5.1` or the directory where the image files are located. A list should pop up with the name of the drivers. Select and press enter.

Also make sure that the following drivers are loaded from the AIX installation media.

```
devices.fcp.disk.rte
devices.fcp.tape.rte
```

The recommended maintenance levels for AIX are specified in the image file *prereq* section. If not at the correct maintenance level, the driver installation will fail. The current level may be found from the command:

```
instfix -i |grep ML
```

Installation may fail if conflicting drivers are present for the same devices. Only one driver may be installed on AIX for a given device type.

## Hardware Installation

Power down the system and install the adapter in a free slot. The PCI cards may be installed in either 32 or 64-bit PCI card slots, however the 32-bit slots may limit performance at high data rates. Make sure that any cables do not block airflow to the card. Observe proper static precautions. Detailed procedures for opening the case and for suggested adapter placement may be found in the *Operator Guide* for the specific server model.

When using copper cable, it is extremely important that the building wiring present a low impedance ground path to the frame of the device and the host with which it will communicate. Noise due to copiers or large machinery sharing the electrical circuits is a common cause of signal integrity problems.

## AutoRecover

cbxdpfar, the AutoRecover daemon, is automatically installed and enabled when the DPF driver is installed. Control of the daemon is done using SRC.

**stopsrc -s cbxdpfar** Stops AutoRecover

**startsrc -s cbxdpfar** Starts AutoRecover

AutoRecover works by periodically polling the standby paths to each LUN. If the polls fail, the path is marked as failed. If the polls succeed, the path is marked as available for use. If path preferences are set up, the AutoRecover daemon will move I/O to the preferred paths when they become available.

AutoRecover also deletes paths to hdisks that have been removed from the system. See the section on SMIT for changing the default AutoRecover timing parameters.



## AIX Configuration

During power-up initialization, AIX will find and configure the new adapter(s) and any supported devices using the driver's configuration method. Devices are assigned a SCSI ID as they are discovered starting with 0. SCSI ID is not related to loop ID, port ID or to SCSI ID assignment on other hosts. It is a logical value bound to the fibre channel WWN of the device. Configuration may also be run from the command line:

```
c fgmgr
```

Once disks have been configured, the standard AIX utilities may be used to build volume groups, logical volumes and file systems. See the *AIX System Management Guide* for a detailed explanation.

Find out the names of the installed adapters with the command:

```
lsdev -Cc adapter
```

In arbitrated loop, the ID of each device must be unique. For disk drives, the ID is typically set by switches on the drive enclosure. The adapter ID is soft assigned and may be examined after it is participating with the *mbtest* command. If the adapter name found by the *lsdev* command were *fscsi1*, the command would be:

```
/usr/lpp/cbxfc/mbtest fscsi1 id
```

The requested ID may be changed in the database to any non-conflicting value in the range 0 to 126 with the command:

```
chdev -l fscsi1 -a id=6 -P
```

The ID attribute has no effect in a fabric environment.

## **Persistent Bindings**

Persistent Bindings is the term used to indicate the mapping of SCSI ID to FC Worldwide Name (WWN). By keeping a persistent binding, the loop ID or port ID of a device may change and the device will still be properly addressed.

In the Cambex AIX driver, persistent binding is automatic. At configuration time, all devices that are found are automatically assigned to a SCSI ID and a persistent binding is created. Persistent bindings are by portname and are kept in the ODM database. They are preserved and restored at reboot for all FC devices.

To display the SCSI ID to WWN mapping for all adapters and devices, issue the command:

```
/usr/lpp/cbxfc/fctest
```

When replacing a failed device on a SAN, we want to keep the same SCSI ID but change the WWN binding to the replacement. A perl script is provided for doing this:

```
/usr/lpp/cbxfc/FRU_replace
```

# SMIT Commands

## Commands

The adapter management commands available in SMIT are in the *devices* menu under *Cambex Fibre Channel Adapter*:

### **List all Cambex FC adapters**

This provides the name and location of each adapter.

### **Change / Show Characteristics of a Cambex FC Adapter**

Allows the user to display and modify attributes. Attributes (and default values) include:

`exec_throttle` (256) number of simultaneous I/O operations.

`dma_window` (64) PCI DMA memory window in MB.

`retry_delay` (3) Delay in seconds after bus reset or other error.

`logout_delay` (7) Time in seconds allowed for ports to be logged out before failing I/O.

`topology_list` (LOOP\_P2P) Automatically detect topology. May also be forced to LOOP\_ONLY or P2P\_ONLY.

`frame_size` (2048) Maximum FC frame size. Choices are 1024 or 2048.

`infinity` (300) Maximum SCSI command timeout in seconds. Set to 0 to disable.

`GHz` (auto) Auto-detect fibre channel rate in GHz. May also be forced to 1 or 2. Ignored on 1GHz cards.

sw\_fc\_class (3) Fibre channel class.

devtype\_exclude ( ) List of SCSI device types to ignore during configuration. For example, specifying "1,5" would exclude both tape and CD devices.

Attributes only used in loop mode include:

id (0) Default L\_ID for adapter. See table of L\_ID to ALPA.

login\_on\_lip (yes) Full login if LIP occurs.

full\_duplex (no) Use full duplex loop open, OPNyx.

### **Generate Error Report**

Accesses the AIX error logging facility.

### **Trace Cambex FC Adapters**

Runs the AIX trace facility, looking only for the entries specific to the adapter driver.

## **Path Management Commands**

The path management commands available in SMIT are in the *devices* menu under *Cambex Dynamic Path Management*:

### **List all Cambex Dynamic Paths**

This provides the information on all paths and devices known to the DPF driver. Use this when installing to verify that all paths have been found and configured.

### **Change / Show Characteristics of a Cambex Dynamic Path**

Displays the current path status and allows the user to place paths online/offline or to change path preferences.

The autorecover daemon will automatically move operation to preferred paths. The preferred path is the combination of path preference values for HBA, device and path. For some arrays, target device preference is read automatically from the array at configuration time. Consult the array user manuals for more information.

### **Change/Show Characteristics of Cambex Managed HBA's**

Used to display and change HBA preference for one or more adapters.

### **Trace Cambex Dynamic Paths**

Runs the trace facility, looking only for the entries specific to the DPF driver and adapter driver.

### **Manage AutoRecovery Subsystem**

Provides the following functions:

Show Status of AutoRecovery Subsystem

Start AutoRecovery Subsystem

Stop AutoRecovery Subsystem

Change / Show AutoRecovery Subsystem Parameters

Parameters are:

- n Number of successful inquiries (3 - 9)
- t Seconds between inquiries (3 - 3599)
- r Seconds between ODM updates (automatic)

### **Manage Load-Balancing**

Enable or disable dynamic load balancing for the selected disks.

### **Manage Licensing**

Allows the user to enter a new license for the DPF software, overwriting the existing license, or to display the expiration date of the current license. To enable a one-time-use, 30-day license

for use until the purchased license is received. Issue the commands:

```
cd /usr/lpp/cbxdpf
mv license.30day license
cfgmgr
```

Licenses for OEM versions of the driver are obtained from the storage vendor who provided the software.

The generic version of DPF purchased from Cambex is licensed for use only on Cambex cards and on only one LPAR. A license token is provided with the purchase. Contact Cambex support by email to obtain a license. You will need to provide

The license tokens for each card  
Host machine ID from 'uname -a -L'  
The output of /usr/lpp/cbxfc/fcinfo

## **How to set path preferences**

Controller preference is set on the RAID controller using RAID Management software provided by the storage vendor. HBA preference and Target preference are set in the host using the dpfutil Path Management software, or in the smit menus. The preference value, although internally combined numerically, is a yes/no value in the user interface. HBA preference outweighs controller preference. It defaults to yes (all HBAs are preferred) but can be changed to no with the tool. Target preference ranks lower than controller preference and defaults to no (no preferred path) but may be changed to yes with the tool.

Path priority is the combination of the following factors, which are listed from highest to lowest.

- failed or offline status is considered first. A path will not be used if failed or offline.
- Anti-thrashing prevents paths to the wrong controller from causing thrashing.
- HBA preference - normally all HBAs have equal preference to paths. To block an hba from using a path, do:

Command line:

```
dpfutil hba_set_wwn cbx0 no (default is yes)
to list HBA preferences:
odmget -q"attribute=hba_pref" CuAt
```

in smit:

Devices

- > Cambex Dynamic Path Management
  - > Change / Show Characteristics of Cambex Managed HBAs

- Controller preference - this is for multi-controller RAID arrays where one or more of the controllers reports that it owns the LUN. Controllers which do not report preference, are treated equally.
- Target preference - To make one path higher preference than other paths to the same LUN, use target preference.

Command line:

```
dpfutil target_set_wwn cbx10 yes (default is no)
to list target preference:
odmget -q"attribute=tgt_pref" CuAt
```

in smit:

Devices

- > Cambex Dynamic Path Management
  - > Change / Show Characteristics of Cambex Dynamic Paths
    - > Change / Show Physical Path Routing Preferences

# Troubleshooting

Use the *errpt* command to identify the cause of failure. The *lsdev* command will provide the location of the component. For example, if *errpt* identifies a loose cable on device *hdisk1*, *lsdev* will give an address similar to:

```
hdisk1    Available 00-02-01    Cambex SCSI...
```

and *lsattr -El hdisk1* will show:

```
clr_q      no                Device CLEARS it's
                    Queue on error
location   Location Label
lun_id     0x0              Logical Unit Num ID
node_name  0x20000080e511b744 FC Node Name
pvid      none         Physical Volume id
q_err     yes           Use QERR bit
q_type    simple       Queuing TYPE
queue_depth 16          Queue DEPTH
reassign_to 120       REASSIGN time out
rw_timeout 30          READ/WRITE timeout
scsi_id    0x0          SCSI ID
start_timeout 60      START UNIT timeout
ww_name    0x23000080e511b744 FC World Wide Name
```

Which indicates that the adapter is in card location 00-02, and the drive is at SCSI ID 0, LUN 0.



## Checklist for driver and HBA installation

The following commands may be used to isolate problems during installation of the fibre channel driver and card. Type the command shown in **bold** and verify the output.

```
lsllpp -l PC1000.driver.obj    must give:  
  Fileset      Path: /usr/lib/objrepos  PC1000.driver.obj  
  Level       01.05.00.00 (or greater)  
  State       Committed  
  Description Cambex Fibre Channel Adapter Driver
```

**lsdev -Cc adapter** should print a line for each card:  
 fscsi<x> <x> is a unique number for each SCSI card  
 Available <SS-SS> <S> is the location in the machine where  
 the card is installed

Check that the number of SCSI cards and their slots are correct  
If 'Available' then card and driver are installed.  
If 'Defined' or not listed then card was not found.

**lscfg -vl fscsi4** should print more information for a card:

```
      DEVICE                LOCATION                DESCRIPTION  
  
  fscsi4                    00-03                  Cambex Fibre  
Channel I/O Controller  
  
  Manufacturer.....CAMBEX  
  Machine Type and Model.....MC1000F  
  ROS Level and ID.....V2.01.04  
  Serial Number.....      2354  
  Displayable Message.....Cambex Fibre ...  
  Network Address.....500502E020000932  
  Device Specific.(Z0).....Build:TMNX
```

```
cfgmgr -v >/tmp/cfg.log 2>&1
```

Should identify the card and configure it.

If `cfg.log` contains the ID 7710002x and no driver is found, then the adapter driver is not installed.

During boot, the number displayed when configuring the adapter is hex 0x911 (FC adapter).

```
/usr/lpp/cbxfc/mbtest fscsil
```

This test code may be used to get fibre channel status from the adapter or from attached devices. Type the command as above for a list of subcommands.

```
/usr/lpp/cbxfc/mbtest fscsil fab
```

This command will list the persistent bindings between SCSI ID and WWN on adapter `scsil`. It will also list the loop ID and port ID (fabric address) which can change dynamically as devices are connected or disconnected.

```
/usr/lpp/cbxfc/mbtest fscsil getp
```

This command will show the fibre channel ports which are currently logged in to adapter `scsil`.

```
/usr/lpp/cbxfc/sctest fscsil
```

This test code may be used to get IOCINFO information from the adapter or to see the results of SCSI Inquiry or TestUnitReady commands to SCSI devices attached to the adapter. Type the command as above for a list of subcommands.

```
/usr/lpp/cbxdpf/dpfutil listall
```

This will list the failover devices and paths. The active path will be shown on the left. Status is shown by letter codes:

“F” indicates a failed path.

“L” indicates dynamic load balancing is active.

“O” indicates offline paths.

The message *no failover devices available* indicates that the attached storage is not yet recognized by the DPF driver. This could mean that a platform kit needs to be installed for your storage or that the storage is not yet configured.

```
/usr/lpp/cbxfc/runtrace
```

This should be run to start a trace if Cambex support requests a trace of the card failure. To stop the trace and generate a trace report, type:

```
trcstop; trcrpt > /tmp/trc.log
```

Questions or problems related to Cambex fibre channel adapters may be e-mailed to: [support@cambex.com](mailto:support@cambex.com)

## Error Messages

Various errors and notifications will be placed in the AIX error log. These can be read using the `errpt` command, or automatic notification may be set up.

### DPF\_FAILOVER

This indicates that the active path to a device has failed, and that DPF successfully transferred I/O to an alternate path.

### DPF\_STDBYDN

This indicates that a path other than the active path has failed to a device.

### DPF\_UNRECOV

This indicates that the active path to a device has failed, and that DPF was not successful in transferring I/O to an alternate path.

### DPF\_OFFLINE

### DPF\_ONLINE

These messages indicate that a path has been manually set to the offline or online state.

### DPF\_LIC\_WARNING

### DPF\_LIC\_EXPIRE

These messages indicate that a temporary license for the DPF software is either close to or has expired. Once the DPF license has expired, you will need to uninstall the DPF driver in order to regain access to the hdisks.

## Upgrading the Driver

When upgrading to a newer version of the driver there are two methods:

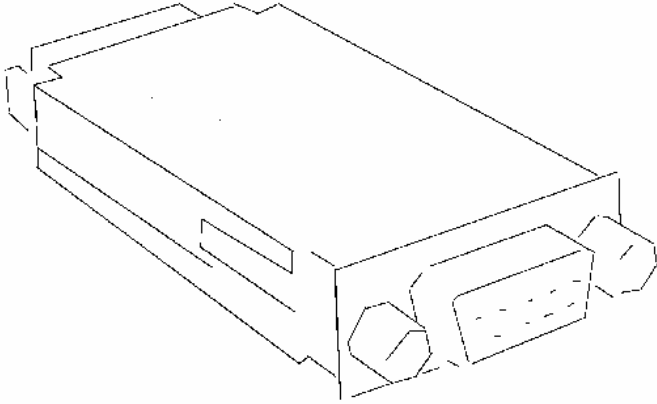
1) Use `rmdev` to remove all dependent devices, remove the existing driver(s), then install the new driver(s) and run `cfgmgr` to recreate the devices. This method allows a new driver to be installed without rebooting the server. File systems which are unmounted before the process may be mounted again afterwards without affecting the data.

2) Install the new driver with devices in place. The server must be rebooted afterwards so that the driver on disk will match the driver in memory.

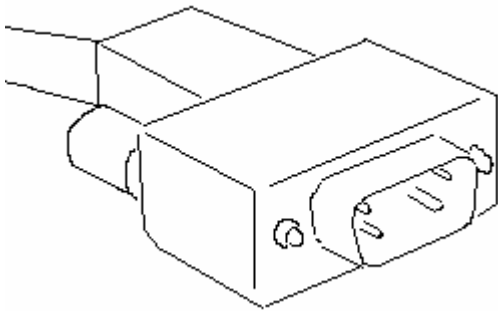
When upgrading AIX to a new major version, remove the drivers beforehand and install the new versions after completing the AIX upgrade.

# Appendix A

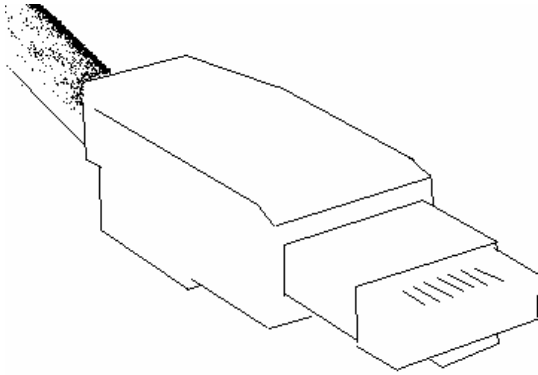
## Identifying Fibre Channel Components



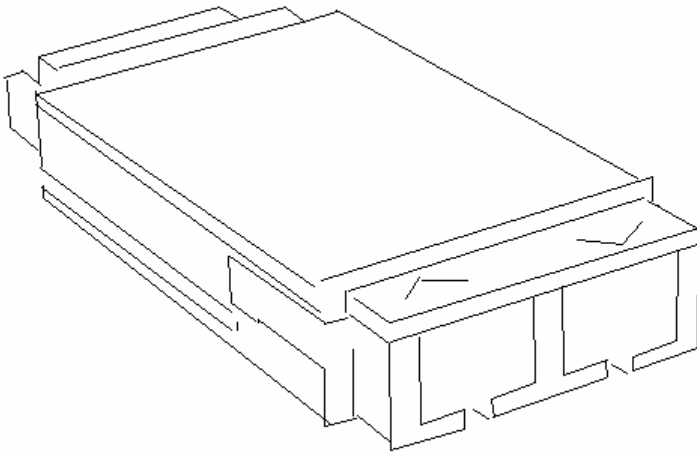
Copper DE9 GBIC



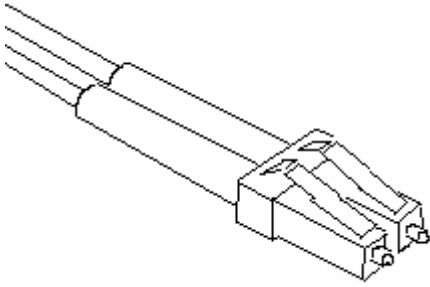
Copper DE9 Cable



Copper HSSDC Cable



Duplex SC Optical GBIC



Small form factor (SFF) optical LC cable

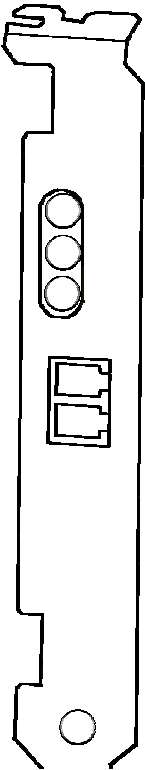


## PC2000 LED Meanings

Top LED – Transceiver hardware is detecting a signal.

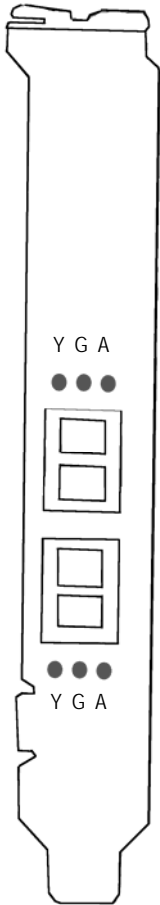
Middle LED – Firmware is being synchronized.

Bottom LED – Flashing amber when not synchronized.



LED	NORM	BAD CABLE	NO CONN
TOP	GREEN	GREEN	OFF
MIDDLE	GREEN	OFF	OFF
BOTTOM	OFF	FLASHING	FLASHING

# PC4000 LED Meanings



Y	G	A	
Off	Off	Off	No Power
On	On	On	Power Applied
Flash	Flash	Flash	Initializing *
Off	Off	On/Flash	1G (Flash indicates active)
Off	On/Flash	Off	2G (Flash indicates active)
On/Flash	Off	Off	4G (Flash indicates active)

\* Flashing in unison indicates initialized, while alternate flashing indicates a firmware error.

## **Declaration of conformity**

We Cambex Corporation of Westborough, Massachusetts, USA, declare under our sole responsibility, that the products PC2000LC-HPSP, PC2000LC-A, and PC4000 are in conformity with the following standards:

EN 55022:1994/A1:1995/A2:1997 Class A ITE emissions requirements

EN 50082-1:1992 EMC residential, commercial and light industrial generic immunity standard

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## **Warning**

This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures.

# Safety Notices

## FCC Warning

This equipment has been tested and found to comply with the limits for a class A computing device pursuant to Part 15 of FCC rules which are designed to provide reasonable protection against interference when operating in a commercial environment. This equipment generates, uses and can radiate radio frequency energy and if not installed and used in accordance with the instruction manual may cause interference to radio communications. Operation of this equipment in a residential area is likely to cause interference in which case the users will be required to take whatever measures may be required to correct the interference at their own expense. Changes or modifications of this device could affect the user's authority to operate this equipment.

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## Safety Notice

### Class 1 Laser Product

Versions of this product supplied with an optical transceiver meet the safety requirements of a class 1 laser as specified by the US Food and Drug Administration Center of Drug and Radiological Health (CDRH) 21 CFR 1040.10 & 1040.11 and by IEC 825-1. The U.S. Department of Health and Human Services (DHHS) does not consider Class 1 lasers to be hazardous. Customer supplied laser GBICs must meet the same requirements. If in doubt, contact Cambex customer support before operating the product.

The International Electrotechnical Commission (IEC) 825 Laser Safety Standard requires labeling in English, German, Finnish, and French stating that the product uses Class 1 lasers. Because it is impractical to label the transceiver, the following label is provided in this manual.

CLASS 1 LASER PRODUCT  
LASER KLASSE 1  
LUOKAN 1 LASERLAITE  
APPAREIL A LASER DE CLASSE 1

TO IEC 825 (1984) + CENELEC HD 482 S1

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