

Computer-Based Instruments

NI 5401 User Manual

PXI™/PCI Arbitrary Function Generator

Worldwide Technical Support and Product Information

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The following conventions are used in this manual:

» The » symbol leads you through nested menu items and dialog box options to a final action. The sequence **File»Page Setup»Options** directs you to pull down the **File** menu, select the **Page Setup** item, and select **Options** from the last dialog box.

◆

The ◆ symbol indicates that the following text applies only to a specific product, a specific operating system, or a specific software version.



This icon denotes a note, which alerts you to important information.



This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash.



This icon denotes a warning, which advises you of precautions to take to avoid being electrically shocked.

bold

Bold text denotes items that you must select or click on in the software, such as menu items and dialog box options. Bold text also denotes parameter names.

italic

Italic text denotes variables, emphasis, a cross reference, or an introduction to a key concept.

`monospace`

Text in this font denotes text or characters that you should enter from the keyboard. This font is also used for the proper names of functions, variables, and filenames and extensions.

`monospace italic`

Italic text in this font denotes text that is a placeholder for a word or value that you must supply.

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Generating Functions with the NI 5401

The *NI 5401 User Manual* describes the features, functions, and operation of the NI 5401 arbitrary function generator. This device performs comparably to standalone instruments while providing the flexibility of computer-based operation.

About Your NI 5401

Thank you for buying a National Instruments NI 5401 arbitrary function generator. The NI 5401 family consists of two different devices:

- NI 5401 for PCI
- NI 5401 for PXI

Your NI 5401 device has the following features:

- One 12-bit resolution output channel
- Up to 16 MHz sine and transistor-transistor logic (TTL) waveform output
- Software-selectable output impedances of 50 Ω and 75 Ω
- Output attenuation levels from 0 to 73 dB
- Phase-locked loop (PLL) synchronization to external clocks
- Sampling rate of 40 MS/s
- Digital and analog filter
- 32-bit direct digital synthesis (DDS) for standard function generation
- External trigger input
- Real-Time System Integration (RTSI) and PXI triggers

All NI 5401 devices follow industry-standard Plug and Play specifications on both buses and offer seamless integration with compliant systems.

Detailed specifications for the NI 5401 are in Appendix A, [Specifications](#).

Connecting Signals

Figure 1-1 shows the front panels for the NI 5401 for the PXI and PCI buses. The front panel contains three types of connectors: BNC, SMB, and 50-pin very high-density SCSI (VHDSCSI). The main waveform is generated through the connector labeled ARB.

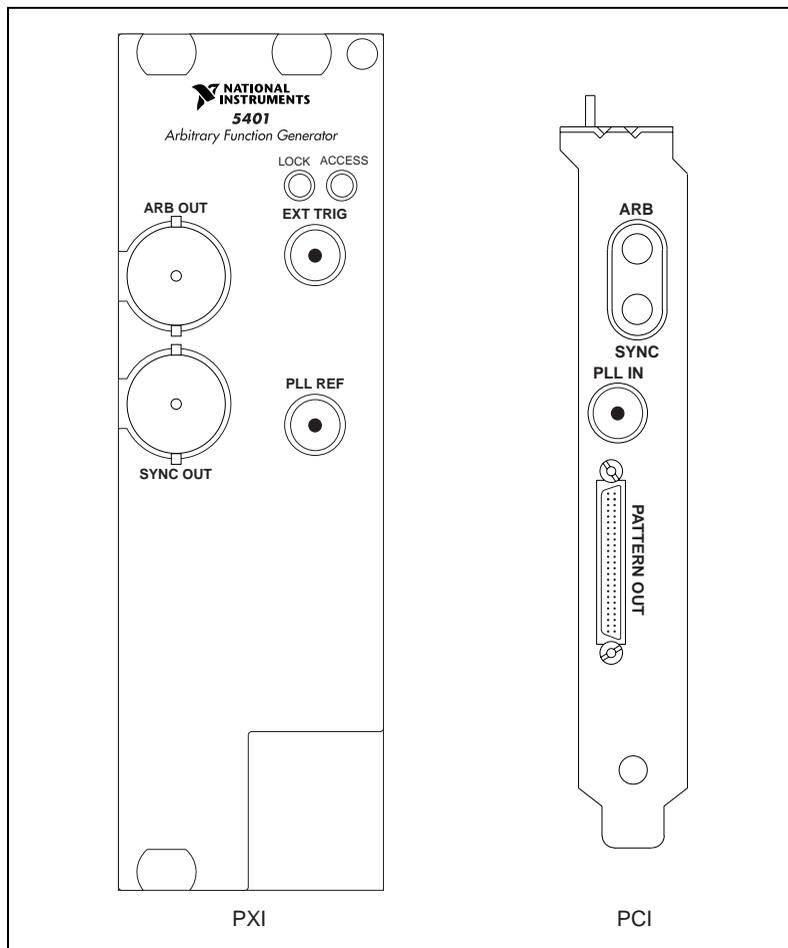


Figure 1-1. NI 5401 I/O Connectors

ARB Connector

The ARB connector provides the waveform output. The maximum output levels on this connector depend on the type of load termination. If the output of your NI 5401 terminates into a 50 Ω load, the output levels are ± 5 V, as shown in Figure 1-2. If the output of your NI 5401 terminates into a high-impedance load (HiZ), the output levels are ± 10 V. If the output terminates into any other load, the levels are as follows:

$$V_{out} = \pm \frac{R_L}{R_L + R_O} \times 10 \text{ V}$$

where V_{out} is the maximum output voltage level
 R_L is the load impedance in ohms, and
 R_O is the output impedance on the NI 5401.

By default, $R_O = 50 \Omega$, but you can use your software to set it to 75 Ω .

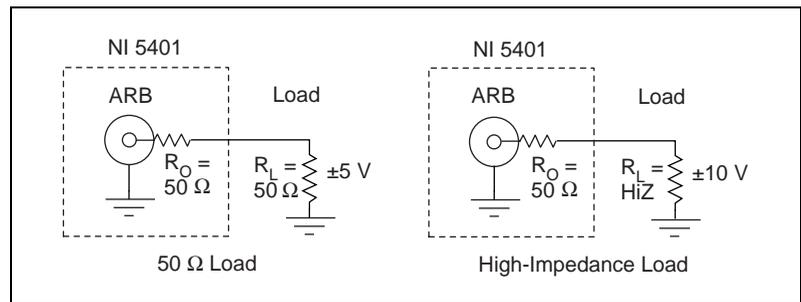


Figure 1-2. Output Levels and Load Termination Using a 50 Ω Output Impedance



Note Software sets the voltage output levels based on a 50 Ω load termination.

For more information on waveform generation and analog output operation, refer to Chapter 2, [Function Generator Operation](#). For specifications on the waveform output signal, see Appendix A, [Specifications](#).

SYNC Connector

The SYNC connector provides a TTL version of the sine waveform being generated at the output. You can think of the SYNC output as a very high-frequency resolution, software-programmable clock source for many applications. You can also vary the duty cycle of the SYNC output on the fly by software control, as shown in Figure 1-3. t_p is the time period of the

sine wave being generated and t_w is the pulse width of the SYNC output. The duty cycle is $(t_w/t_p) \times 100\%$.

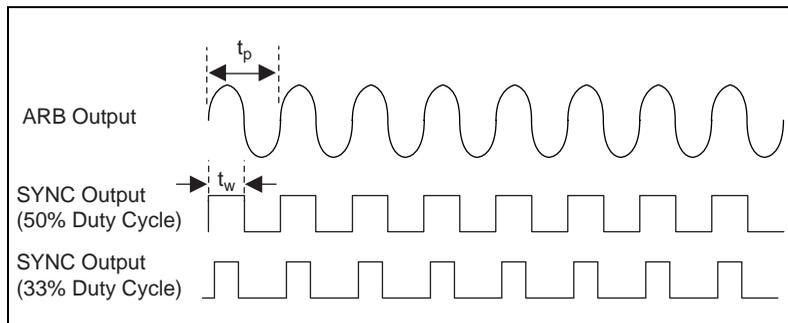


Figure 1-3. SYNC Output and Duty Cycle

For your NI 5401 for PCI, you can route the SYNC output to the RTSI lines over the RTSI bus. For your NI 5401 for PXI, you can route the SYNC output to the TTL trigger lines over the TTL trigger bus. The SYNC output is derived from a comparator connected to the analog waveform and provides a meaningful waveform only when you are generating a sine wave on the ARB output. For more information on SYNC output, see Chapter 2, [Function Generator Operation](#).

PLL Ref Connector

The PLL Ref connector is a phase-locked loop (PLL) input connector that can accept a reference clock from an external source and frequency lock the NI 5401 internal clock to this external clock. The reference clock should not deviate more than ± 100 ppm from its nominal frequency. The minimum amplitude levels of $1 V_{pk-pk}$ are required on this clock. You can lock reference clock frequencies of 1 MHz and 5–20 MHz in 1 MHz steps.



Note You can frequency lock the NI 5401 for PCI to other National Instruments devices over the RTSI bus using the 20 MHz RTSI clock signal. You can frequency lock the NI 5401 for PXI to other National Instruments devices using the 10 MHz backplane clock.

If no external reference clock is available, the NI 5401 automatically tunes the internal clock to the highest accuracy possible. For more information on PLL operation, refer to Chapter 2, [Function Generator Operation](#).

Pattern Out Connector (PCI Only)

This connector is used on the NI 5401 for PCI to supply the external trigger input to the board.

Connector Pin Assignments

Figure 1-4 shows the NI 5401 50-pin digital connector. Refer to Table 1-1 for a description of the signals.

DGND	50	25	EXT_TRIG
NC	49	24	NC
DGND	48	23	NC
NC	47	22	NC
DGND	46	21	NC
NC	45	20	NC
DGND	44	19	NC
RFU	43	18	RFU
DGND	42	17	RFU
RFU	41	16	RFU
DGND	40	15	RFU
RFU	39	14	RFU
DGND	38	13	RFU
RFU	37	12	RFU
DGND	36	11	RFU
RFU	35	10	RFU
DGND	34	9	RFU
RFU	33	8	RFU
DGND	32	7	RFU
RFU	31	6	RFU
DGND	30	5	RFU
RFU	29	4	RFU
DGND	28	3	RFU
RFU	27	2	RFU
DGND	26	1	RFU

Figure 1-4. NI 5401 50-Pin Digital Connector Pin Assignments

Signal Descriptions

Table 1-1 shows the pin names and signal descriptions used on the NI 5401 digital output connector.

Table 1-1. Digital Connector Signal Descriptions

Signal Name	Type	Description
DGND	–	Digital ground
EXT_TRIG	Input	External trigger—The external trigger input signal is a TTL-level signal that you can use to start or step through a waveform generation. For more information on trigger sources and trigger mode, see Chapter 2, <i>Function Generator Operation</i> .
NC	–	Not connected.
RFU	–	Reserved for future use. Do not connect signals to this pin.

SHC50-68 50-Pin Cable Connector

You can use an optional SHC50-68 50-pin to 68-pin cable for external trigger input. The cable connects to the digital connector on the NI 5401. Figure 1-5 shows the 68-pin connector pin assignments on the SHC50-68 cable.



Note The SHC50-68 connector uses the same signals as the NI 5401 digital output connector shown in Table 1-1.

RFU	1	35	DGND
RFU	2	36	DGND
RFU	3	37	DGND
RFU	4	38	DGND
RFU	5	39	DGND
RFU	6	40	DGND
RFU	7	41	DGND
RFU	8	42	DGND
RFU	9	43	DGND
RFU	10	44	DGND
RFU	11	45	DGND
RFU	12	46	DGND
RFU	13	47	DGND
RFU	14	48	DGND
RFU	15	49	DGND
RFU	16	50	DGND
RFU	17	51	DGND
RFU	18	52	DGND
RFU	19	53	DGND
RFU	20	54	DGND
RFU	21	55	DGND
RFU	22	56	DGND
RFU	23	57	DGND
RFU	24	58	RFU
NC	25	59	DGND
NC	26	60	DGND
NC	27	61	DGND
NC	28	62	DGND
NC	29	63	DGND
NC	30	64	DGND
NC	31	65	DGND
NC	32	66	DGND
NC	33	67	DGND
EXT_TRIG	34	68	DGND

Figure 1-5. SHC50-68 68-Pin Connector Pin Assignments

Software Options for Your NI 5401

This section describes the NI-FGEN driver software and development tools that you can use to create application software for your NI 5401.

Software Included with Your NI 5401

Your NI 5401 kit includes several VirtualBench *soft front panels* to help you get up and running quickly with your waveform generator. These soft front panels are an onscreen interface similar to standalone instruments. An NI-FGEN instrument driver is also included, which you can use with a wide variety of development tools to build applications for your NI 5401.

These software tools are discussed in the following sections.

VirtualBench

Similar to standalone instruments, VirtualBench acquires, controls, analyzes, and presents data. However, since VirtualBench operates on your PC, it provides additional processing, storage, and display capabilities.

VirtualBench loads and saves waveform data in a form that popular spreadsheet programs and word processors can use. It can also generate reports—a complement to the raw data storage—by adding timestamps, measurements, user names, and comments. You can print the waveforms and the settings of VirtualBench to a printer connected to the PC.

VirtualBench has two components—VirtualBench-FG and Waveform Editor—that you can use with your NI 5401. These components are described in the following sections.

VirtualBench-FG

VirtualBench-FG transforms your PC into a fully featured function generator that rivals desktop models by using the DDS capabilities of your NI 5401. VirtualBench-FG emulates benchtop function generators, so you can quickly learn to use computer-based instruments.

With VirtualBench-FG, you can generate a variety of waveforms, including five standard waveforms: sine, square, triangle, rising exponential, and falling exponential. Using VirtualBench-FG, you load waveforms from an ASCII text file and generate them repeatedly. You can generate these waveforms with a resolution of approximately 10 mHz and perform frequency sweeps and shift-keying. As with all VirtualBench instruments, you can load and save instrument settings.

Waveform Editor

You use the Waveform Editor to create, sketch, and edit complex waveforms that the VirtualBench-FG player can then generate. A library of standard waveforms for creating complex waveforms is included, and you can also write equations to create arbitrary waveforms and view the waveforms in a time or frequency domain.

NI-FGEN Instrument Driver

To create your application, you need an industry-standard software driver such as NI-FGEN to control your instrument. The NI-FGEN driver includes a set of standard functions for configuring, creating, starting, and stopping waveform generation. The instrument driver reduces your program development time and simplifies instrument control by eliminating the need to learn a complex programming protocol for your instrument.

NI-FGEN is in a standard instrument driver format that works with LabVIEW, LabWindows/CVI, and conventional programming languages such as C, C++, and Visual Basic.

Refer to the NI-FGEN `readme.txt` file for more details on the NI-FGEN instrument driver. This file can be launched from the **Start»Programs»National Instruments FGEN** menu.



Note An *NI-FGEN Instrument Driver Quick Reference Guide* is included in your NI 5401 kit. This reference guide helps you program your NI 5401.

Additional National Instruments Development Tools

The following sections describe several additional tools that you can use to develop complex applications for your NI 5401. The NI-FGEN instrument driver exposes the Application Programming Interfaces (APIs) to these development environments.

LabVIEW

LabVIEW is a graphical programming language for building instrumentation systems. With LabVIEW, you quickly create front panel user interfaces, giving you interactive control of your software system. To specify the functionality, you assemble block diagrams—a natural design notation for engineers and scientists. LabVIEW has all of the same development tools and language capabilities of a standard language such

as C, including looping and case structures, configuration management tools, and compiled performance.



Note Use the NI-FGEN instrument driver to program and control your NI 5401 using LabVIEW.

LabWindows/CVI

LabWindows/CVI is an interactive, ANSI C programming environment designed for automated test applications.

LabWindows/CVI has an interactive drag-and-drop editor for building your user interface and a complete ANSI C development environment for building your test program logic. The LabWindows/CVI environment has a wide collection of automatic code-generation tools and utilities that accelerate your development process, without sacrificing any of the power and flexibility of a language such as C. In addition, the LabWindows/CVI run-time libraries are compatible with standard C/C++ compilers, including Visual C++ and Borland C++ under Windows.



Note Use the NI-FGEN instrument driver to program and control your NI 5401 using LabWindows/CVI.

ComponentWorks

ComponentWorks is a collection of 32-bit ActiveX controls for building virtual instrumentation systems. ComponentWorks gives you the power and flexibility of standard development tools, such as Microsoft Visual Basic or Visual C++, with the instrumentation expertise of National Instruments. Based on ActiveX technology, ComponentWorks controls are easy to configure using property sheets and are easy to control from your programs using high-level properties and methods. ComponentWorks features instrumentation-based graphical user interface (GUI) tools, including graphs, meters, gauges, knobs, dials, and switches.



Note Use the NI-FGEN instrument driver to program and control your NI 5401 using ComponentWorks.

Using the Soft Front Panels to Generate Waveforms

You use the VirtualBench soft front panels to interactively control your NI 5401 as you would a desktop function generator.

Generating Standard Functions

If you need to generate standard waveforms such as a sine, square, ramp, or DC signal, you can use the VirtualBench-FG soft front panel shown in Figure 1-6. Launch the front panel by selecting **Start»Programs»National Instruments FGEN»VirtualBench FG**. You use this front panel to control the frequency, amplitude, offset, and type of waveform generated. The maximum sine frequency you can generate is 16 MHz. The maximum amplitude is 5 V_{pk} into a 50 Ω load. If the load is a high-impedance load, the actual levels will be twice that shown on the front panel.

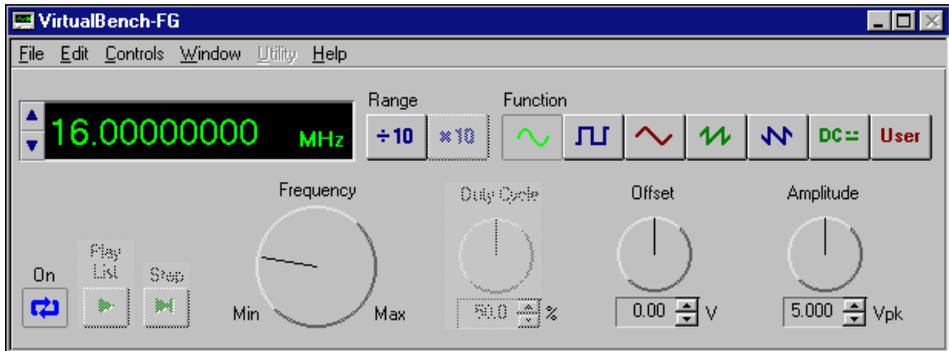


Figure 1-6. VirtualBench-FG Soft Front Panel for Function Generation

To control additional instrument parameters, select **Edit>54xx Settings** to bring up the dialog box shown in Figures 1-7 and 1-8.

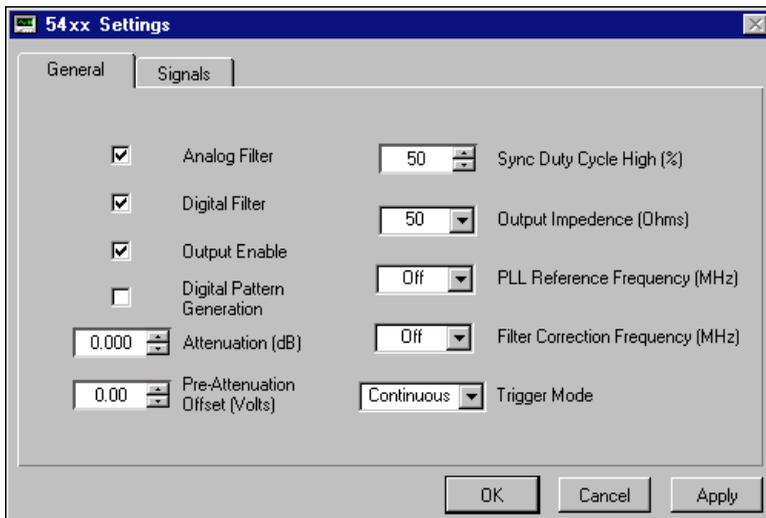


Figure 1-7. VirtualBench-FG General Settings Dialog Box for the NI 5401

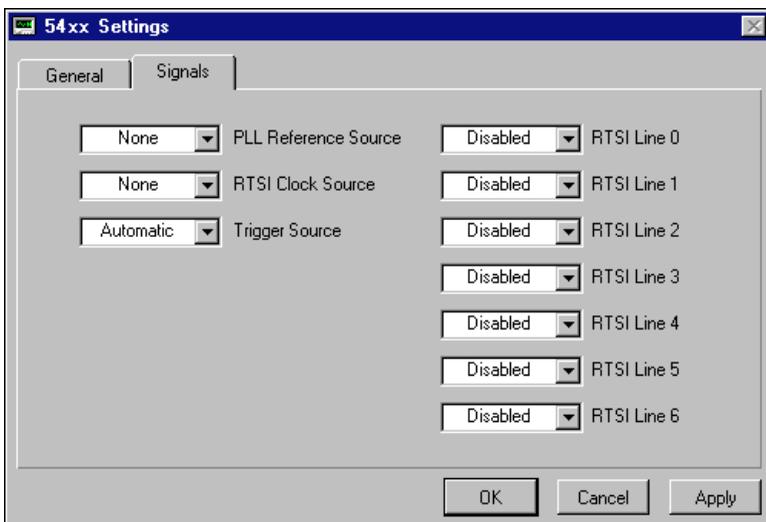


Figure 1-8. VirtualBench-FG Signals Settings Dialog Box for the NI 5401



Note Refer to the online help for further information about the 54xx Settings dialog box.

You can also load a custom waveform pattern with VirtualBench-FG. This waveform should be a text file and should contain exactly 16,384 samples. If the defined waveform does not contain exactly 16,384 samples, you may see undesired effects in your waveform output. Follow these steps to load a custom waveform:

1. Select **File»Load Waveform** to bring up the dialog box shown in Figure 1-9.

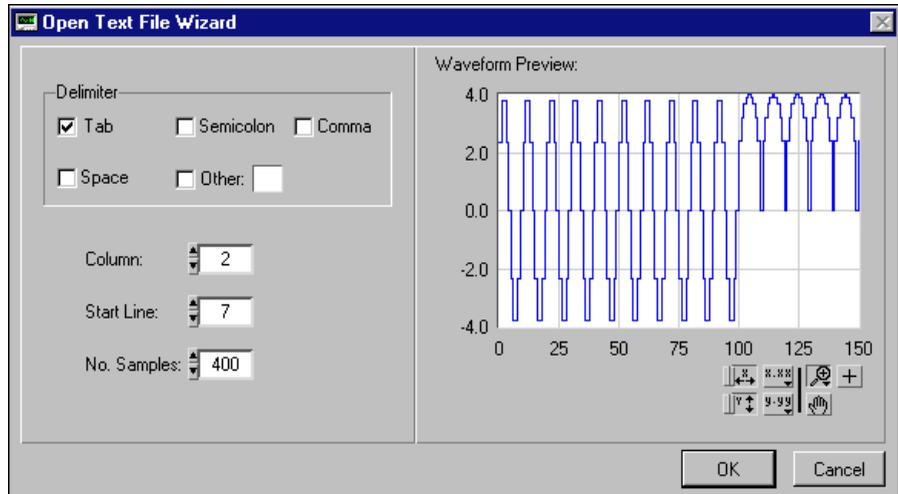


Figure 1-9. VirtualBench-FG Load Waveform Dialog Box

2. Specify the delimiter used in the text file, the number of columns, the start line, and the number of samples.
3. Click **OK** to return to the main VirtualBench-FG screen shown in Figure 1-6.
4. Click the **User** button to use the information in the text file as the source for the waveform.
5. Click the **On** button to generate the waveform.

Generating Multiple Frequencies in a Sequence

If desired, you can generate multiple frequencies in a sequence, which can include frequency sweeping, hopping, and so on. You can list up to 512 different frequencies and specify the duration of generation for each of

them using the VirtualBench-FG Frequency List Editor. Follow these steps to create a list of multiple frequencies:

1. Select **Window»Frequency List Editor** from the VirtualBench-FG soft front panel to bring up the dialog box shown in Figure 1-10.

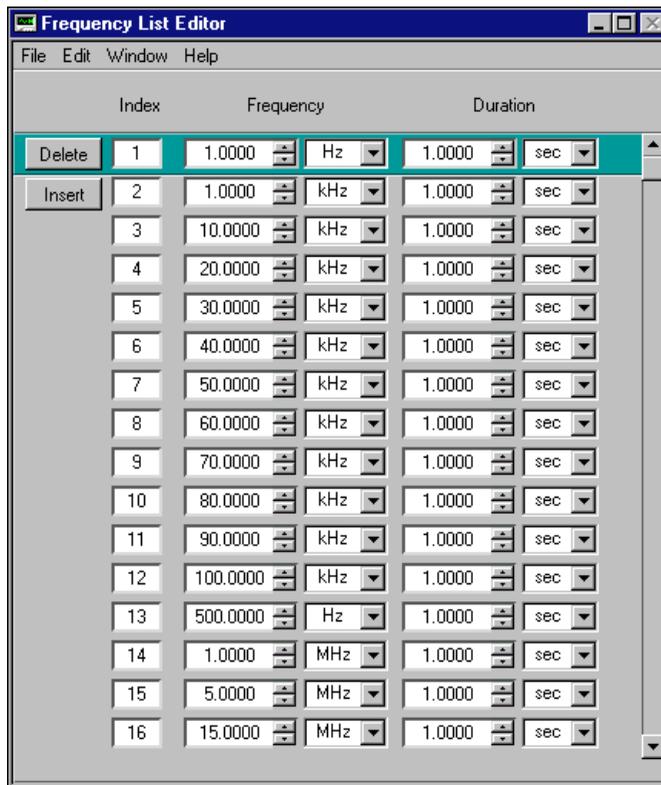


Figure 1-10. VirtualBench-FG Frequency List Editor Dialog Box

2. Specify the frequency and duration of each function in the sequence.
3. Save the sequence by selecting **File»Save**.
4. To return to the main VirtualBench-FG screen shown in Figure 1-6, select **File»Close**.
5. Select **File»Load Frequency List** to load the frequency list.

You can combine the frequency list generation with different trigger modes to get the desired frequency generation.

Waveform Editor

You can use the Waveform Editor shown in Figure 1-11 to create a custom waveform. To launch the Waveform Editor, select **Start»Programs»National Instruments FGEN»Waveform Editor**. You can select waveforms from the function library, write equations, or draw them manually. Each segment can have more than one waveform component in it, and you can perform a variety of math functions on each component.

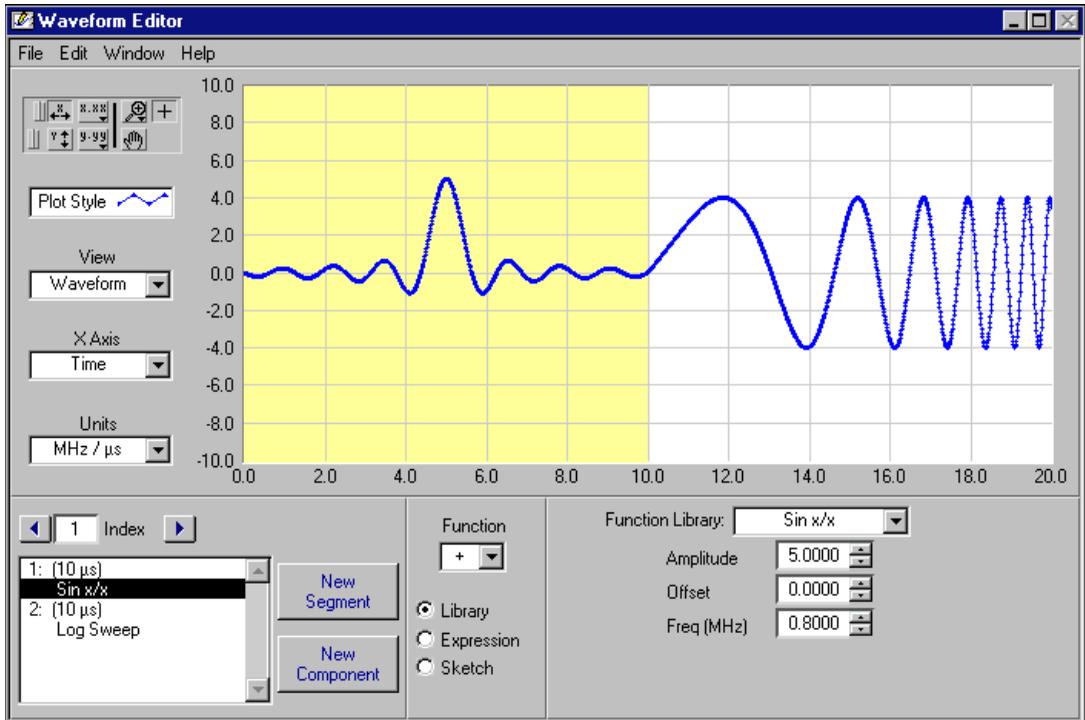


Figure 1-11. Waveform Editor Soft Front Panel

This soft front panel is resizable so you can view the waveforms you create with as much precision as you wish. You can save the waveforms in the following formats:

- Voltage (.wfm)
- Text (.txt)
- Binary (.bin)

Text waveforms are the only format you can use with the NI 5401, and they must contain exactly 16,384 samples to function properly.

Power-Up and Reset Conditions

When you power up your computer, the NI 5401 is in the following state:

- The output is disabled and set to 0 V.
- The trigger mode is set to continuous.
- The trigger source is set to automatic (the software provides the triggers).
- The digital filter is enabled.
- Output attenuation remains unchanged from its previous setting.
- The analog filter remains unchanged from its previous setting.
- Output impedance remains unchanged from its previous setting.

When you reset the board using NI-FGEN or any other application software, your NI 5401 is in the same state as shown at power up, previously listed, with the following differences:

- Output attenuation is set to 0 dB.
- The analog filter is enabled.
- Output impedance is set to 50 Ω .
- The PLL reference source is set to internal tuning.
- The SYNC duty cycle is set to 50%.

Function Generator Operation

This chapter describes how to use your NI 5401.

Figure 2-1 shows the NI 5401 block diagram.

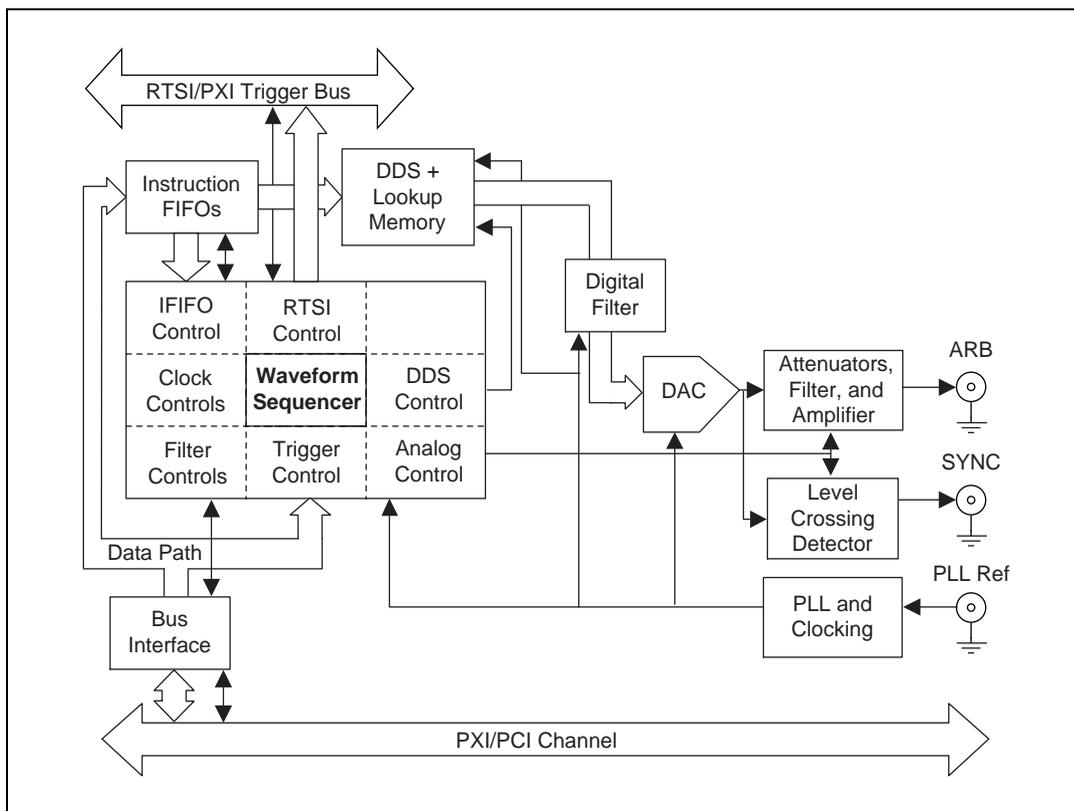


Figure 2-1. NI 5401 Block Diagram

The NI 5401 has several main components:

- A PXI or PCI bus interface that handles Plug and Play protocols for assigning resources to the device and providing drivers for the data and address bus that are local to the device
- A waveform sequencer that performs multiple functions such as arbitrating the data buses and controlling the triggers, filters, attenuators, clocks, PLL, RTSI switch, instruction FIFO, and DDS
- The data from the memory is fed to a digital-to-analog converter (DAC) through a half-band interpolating digital filter. The output from the DAC goes through the filter to the amplifiers, attenuators, and, finally, the I/O connector.

Generating Waveforms

The NI 5401 generates waveforms using DDS, which is used for generating standard waveforms that are repetitive in nature, such as sine, TTL, square, and triangular waveforms. DDS mode limits you to one buffer, and the buffer size must be exactly equal to 16,384 samples.

Figure 2-2 shows a block diagram of the data path for waveform generation. The data for waveform generation comes from DDS lookup memory. This data is interpolated by a half-band digital filter and then fed to a high-speed DAC. The data has a pipeline delay of 26 update clocks through this digital filter. Although the digital filter can be disabled through software, there will still be a 26 update clock delay.

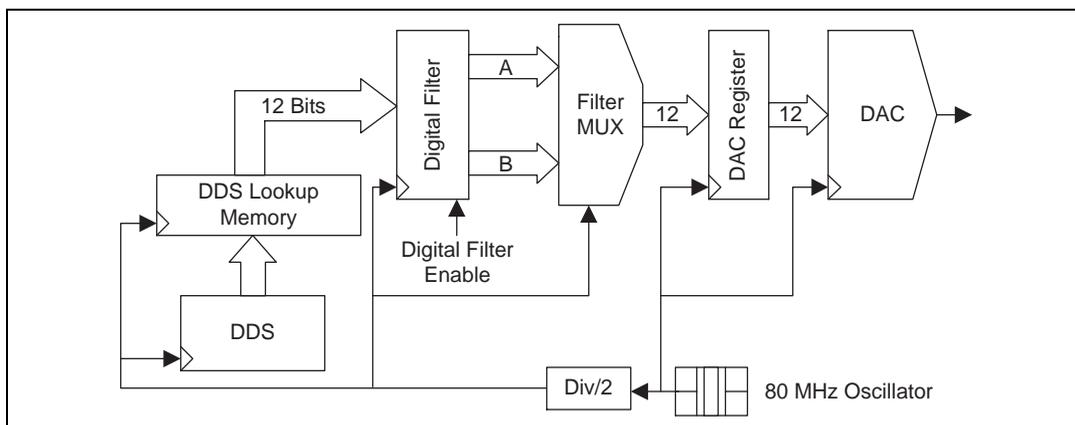


Figure 2-2. Waveform Data Path Block Diagram

On the NI 5401, the high-speed DAC is always updated at 80 MHz, but the update clock for memory is 40 MHz.

Direct Digital Synthesis (DDS)

Direct digital synthesis (DDS) is a technique for deriving, under digital control, an analog frequency source from a single reference clock frequency. This technique produces high-frequency accuracy and resolution, temperature stability, wideband tuning, and rapid and phase-continuous frequency switching.

The NI 5401 uses a 32-bit, high-speed accumulator with a lookup memory and a 12-bit DAC for DDS-based waveform generation. Figure 2-3 shows the building blocks for DDS-based waveform generation.

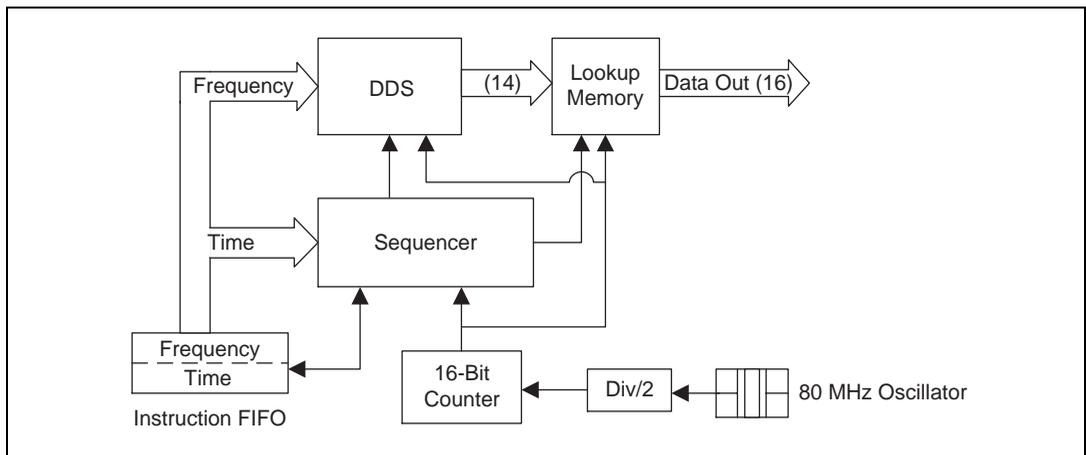


Figure 2-3. DDS Building Blocks

The lookup memory is dedicated to the DDS. You can store one cycle of a repetitive waveform—a sine, triangular, square, or arbitrary wave—in the lookup memory. Then, you can change the frequency of that waveform by sending just one instruction. You can use DDS mode for very fine frequency resolution function generation. You can generate sine waves of up to 16 MHz with the NI 5401. Waveform generation always loops back to the beginning of the lookup memory after passing through the end of the lookup memory.

The NI 5401 uses a lookup *waveform memory* for storing the waveform buffer and FIFO memory for storing the *staging list*, which contains multiple frequency list information. This FIFO is referred to as an *instruction FIFO*.

Each stage is made up of two instructions: the *frequency*, which specifies the frequency of the waveform to be generated, and the *time*, which specifies the time for which the frequency is to be generated.



Note You cannot specify the number of iterations for a waveform to be generated.

Frequency Hopping and Sweeping

You can define a staging list for performing *frequency hops and sweeps*. The entire staging list uses the same buffer loaded into the lookup memory. All stages differ in the frequency to be generated.



Note The minimum time that a frequency should be generated is 2 μ s. Therefore, the maximum hop rate from frequency to frequency is 500 kHz.

The maximum number of stages that can be stored in the instruction FIFO for DDS mode is 512. For more information on the waveform generation process, refer to your software documentation.

Triggering

You use triggering to start and step through a waveform generation. The trigger sources and modes of operation are explained in the following sections.

Trigger Sources

Trigger sources are software selectable. By default, the software produces the trigger sources. You can also use an external trigger from a pin on the digital I/O connector, the RTSI trigger lines on the RTSI bus, or the TTL trigger lines on the PXI trigger bus on the backplane. Figure 2-4 shows the trigger sources for the NI 5401.

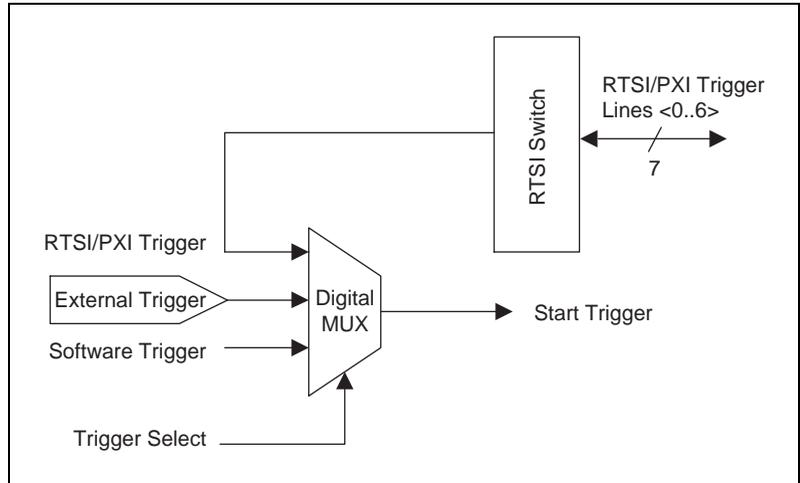


Figure 2-4. Waveform Generation Trigger Sources

If you need to automatically trigger the waveform generation, use software to generate the triggers. A rising TTL edge is required for external triggering. For more information on triggering over RTSI lines, see the [RTSI/PXI Trigger Lines](#) section later in this chapter.

Modes of Operation

The NI 5401 has three triggering modes—single, continuous, and stepped—described in the following sections.

Single Trigger Mode

The waveform you define in the staging list is generated only once by going through the entire staging list. Only one trigger is required to start the waveform generation.

In single trigger mode, after the NI 5401 receives a trigger, the waveform generation starts at the first stage and continues through the last stage. The last stage is generated repeatedly until you stop the waveform generation. Figure 2-5 illustrates a single trigger mode of operation.

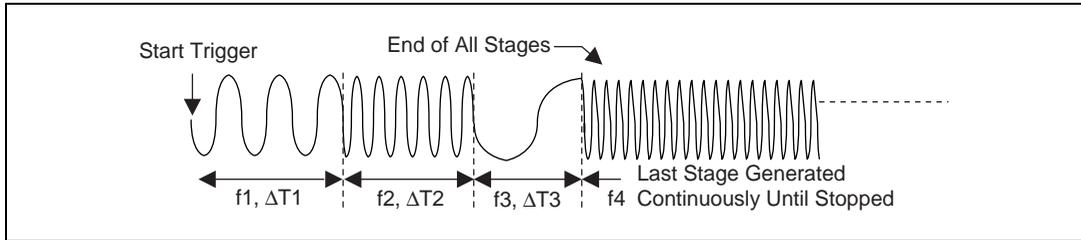


Figure 2-5. Single Trigger Mode

For example, assume that one cycle of a sine wave is stored in the DDS lookup memory. For stage 1, f_1 specifies the sine frequency to be generated for time ΔT_1 , f_2 and ΔT_2 for stage 2, and so on. If there are four stages in the staging list, f_4 will be generated continuously until the waveform generation is stopped.

Continuous Trigger Mode

The waveform you define in the staging list is generated infinitely by continually cycling through the staging list. After a trigger is received, the waveform generation starts at the first stage, continues through the last stage, and loops back to the start of the first stage, continuing until you stop the waveform generation. Only one trigger is required to start the waveform generation.

Figure 2-6 illustrates a continuous trigger mode of operation.

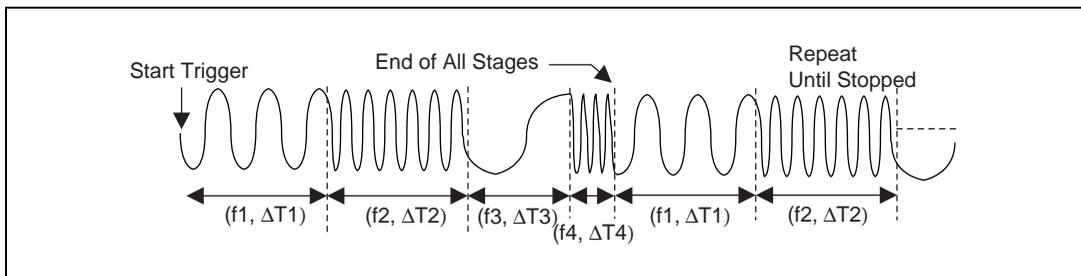


Figure 2-6. Continuous Trigger Mode

Stepped Trigger Mode

After a start trigger is received, the waveform defined by the first stage is generated. Then, the device waits for the next trigger signal. On the next trigger, the waveform described by the second stage is generated, and so on. Once the staging list is exhausted, the waveform generation returns to the first stage and continues in a cyclic fashion.

Figure 2-7 illustrates a stepped trigger mode of operation. Switching from stage to stage is phase continuous. In this mode, the time instruction is not used. The trigger paces the waveform generation from one frequency to the other.

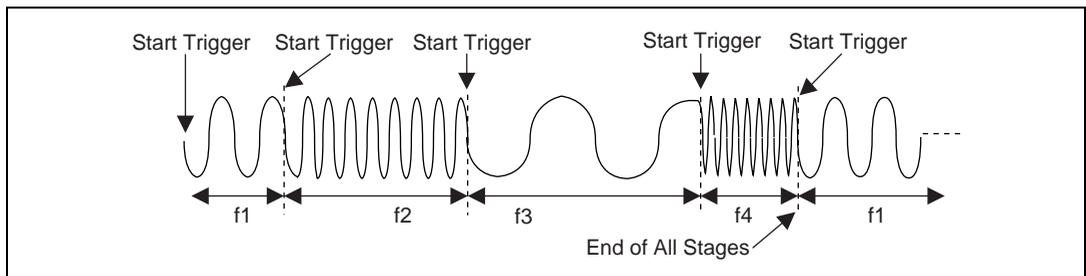


Figure 2-7. Stepped Trigger Mode

Analog Output

Analog waveforms are generated as follows:

1. The 12-bit digital waveform data is fed to a high-speed DAC.
2. A *lowpass filter* filters the DAC output.
3. This filtered signal is amplified before it goes to a 10 dB attenuator.



Note The DAC output can be fine-tuned for gain and offset. Since the offset is adjusted before the main attenuators and amplifier, it is referred to as *pre-attenuation offset*. This fine-tuning of gain and offset is performed by separate DACs.

4. The output from the 10 dB attenuator then goes to the main amplifier, which can provide up to ± 5 V levels into 50Ω . An output relay can switch between ground level and the main amplifier. Refer to the [Output Enable](#) section of this document for additional information about this relay.
5. The output of this relay goes to a series of passive attenuators.
6. The output of the attenuators goes through a selectable output impedance of 50 or 75Ω to the I/O connector.

Figure 2-8 shows the essential block diagram of analog waveform generation.

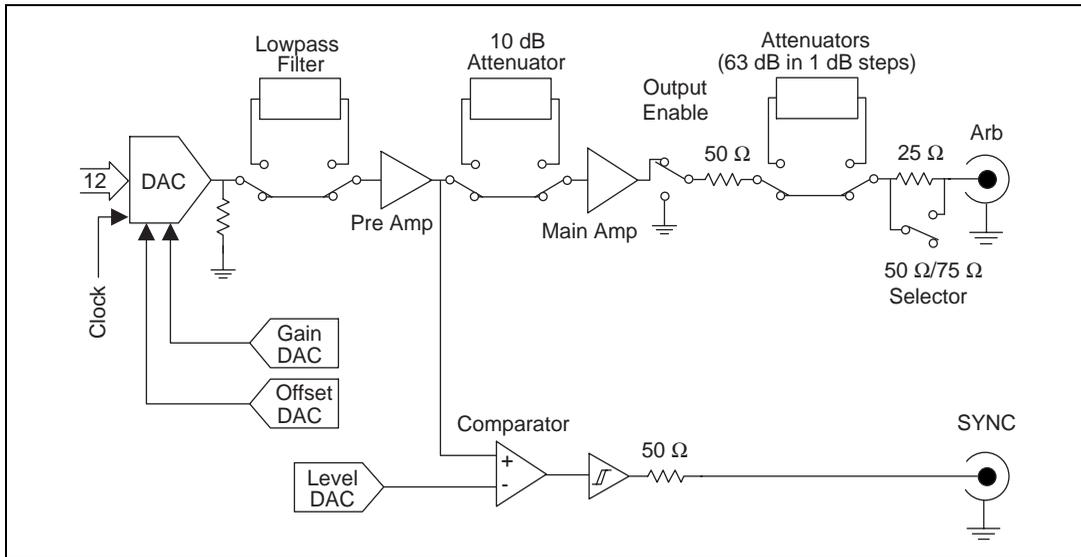


Figure 2-8. Analog Output and SYNC Out Block Diagram

Figure 2-9 shows the timing relationships of the trigger input and waveform output. T_{d1} is the pulse width on the trigger signal. T_{d2} is the time delay from trigger to output on Arb output. Refer to Appendix A, *Specifications*, for more information on these timing parameters.

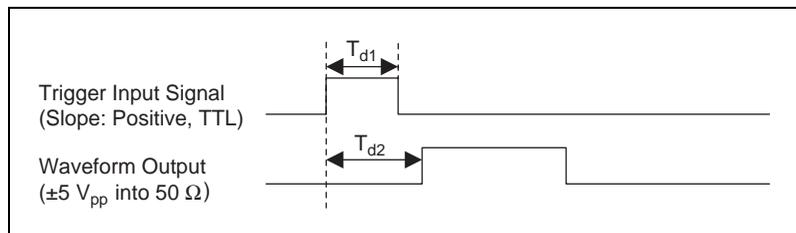


Figure 2-9. Waveform and Trigger Timings



Note You can switch off the analog lowpass filter at any time during waveform generation. When you change this setting, the bouncing of electromechanical relays on the NI 5401 distorts the output signal for about 10 ms.

SYNC Output and Duty Cycle

The SYNC output is a TTL version of the sine waveform generated at the output. The signal from the pre-amplifier is sent to a comparator, where it is compared against a level set by the *level DAC*. The output of this comparator is sent to the SYNC connector through a hysteresis buffer and a 50 Ω series resistor to reverse terminate reflected pulses.

You can use the SYNC output as a very high-frequency resolution, software-programmable clock source for many applications. You also can vary the duty cycle of SYNC output, on the fly, by changing the output of the level DAC. The SYNC output might not carry meaning for other types of generated waveforms.



Note You can change the duty cycle of the SYNC output at any time during waveform generation.

Output Attenuation

Figure 2-10 shows the NI 5401 output attenuator chain. The output attenuators are made of resistor networks and may be switched in any combination. The maximum attenuation possible on the NI 5401 is 73 dB.

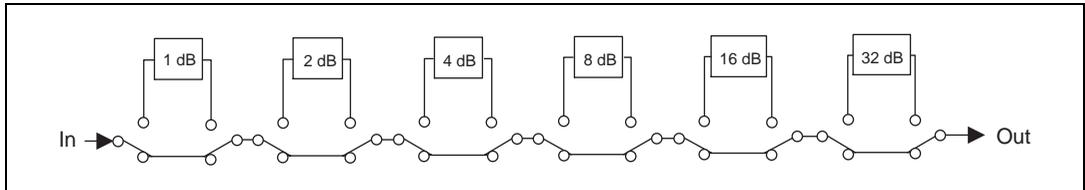


Figure 2-10. Output Attenuation Chain

By attenuating the output signal, you keep the *dynamic range* of the DAC; that is, you do not lose any bits from the digital representation of the signal because the attenuation is done after the DAC and not before it.

$$\text{attenuation (in decibels)} = -20 \log_{10} (V_o / V_i)$$

where V_o = desired voltage level for the output signal
 V_i = input voltage level.



Note For the NI 5401, $V_i = \pm 5$ V for a terminated load and ± 10 V for an unterminated load.

NI-FGEN calculates the value of the output attenuation chain, which you can control by changing the peak-to-peak amplitude parameter. 0 dB attenuation corresponds to an amplitude of $10 V_{\text{pk-pk}}$. The maximum attenuation of 73 dB corresponds to an amplitude of $2.24 mV_{\text{pk-pk}}$. Any amplitude less than this is coerced to this value.



Note You can change the output attenuation at any time during waveform generation. When you change this setting, the bouncing of electromechanical relays on the NI 5401 distorts the output signal for about 10 ms.

Output Impedance

As shown in Figure 2-10, before the signal reaches the output connector, you can select an output impedance of 50Ω or 75Ω . If the load impedance is 50Ω and all the attenuators are off (an output attenuation of 0 dB), the output levels are $\pm 5 V$.

Most applications use a load impedance of 50Ω , but applications such as video device testers require 75Ω . If the load is a very high-input impedance load ($\sim 1 M\Omega$), you will see output levels up to $\pm 10 V$.



Note You can change the output impedance at any time during waveform generation. When you change this setting, the bouncing of electromechanical relays on the NI 5401 distorts the output signal for about 10 ms.

Output Enable

You can switch off the waveform generation at the output connector by controlling the *output enable relay*, as shown in Figure 2-8. When the output enable relay is off, the output signal level goes to ground level.



Note Even though the output enable relay is in the off position, the waveform generation process continues internally on the NI 5401.

You can use this feature to disconnect and connect different devices to the NI 5401 on the fly.



Note You can change the output enable state at any time during waveform generation. When you change this setting, the bouncing of electromechanical relays on the NI 5401 distorts the output signal for about 10 ms.

Pre-Attenuation Offset

The NI 5401 hardware supports a DC offset of up to ± 2.5 V before the attenuation chain. Unless the 10 dB attenuator is switched in, which occurs when the amplitude is less than $3.16 V_{\text{pk-pk}}$, the waveform maximum plus the offset must not exceed ± 5 V into 50Ω . If it does, the waveform is clipped. Refer to Figure 2-8 for a diagram showing the location of the 10 dB attenuator.

NI-FGEN automatically calculates the pre-attenuation offset value based on the DC offset and amplitude values, so the allowable DC offset range is dependent on the amplitude. For example, if you have an amplitude of $1 V_{\text{pk-pk}}$, the maximum DC offset you can apply is 0.25 V, which corresponds to a pre-attenuation offset of 2.5 V.



Note You can change the DC Offset at any time during waveform generation. Refer to your software documentation for additional information.

Phase-Locked Loops and Board Synchronization

Figure 2-11 illustrates the block diagram for the NI 5401 for PCI PLL circuit. Figure 2-12 illustrates the block diagram for the NI 5401 for PXI PLL circuit. The PLL consists of a voltage-controlled crystal oscillator (VCXO) with a tuning range of ± 100 ppm. This VCXO generates the main clock of 80 MHz.

The PLL can lock to a reference clock source from the external connector, from a RTSI Osc line on the RTSI bus (NI 5401 for PCI), or from a 10 MHz Osc line on the PXI backplane bus (for NI 5401 for PXI). The PLL can also be tuned internally using a calibration DAC (CalDAC). National Instruments accurately performs this tuning during manufacturing. Refer to the [RTSI/PXI Trigger Lines](#) section later in this manual for additional information on using the RTSI and 10 MHz Osc lines.

The reference and VCXO clock are compared by a phase comparator running at 1 MHz. The loop filters the error signal and sends it to the control pin of the VCXO to complete the loop.

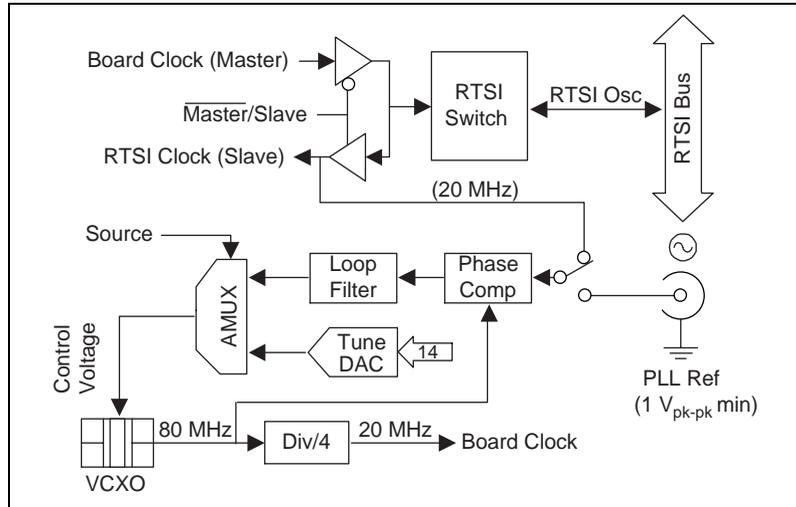


Figure 2-11. PLL Architecture for the NI 5401 for PCI

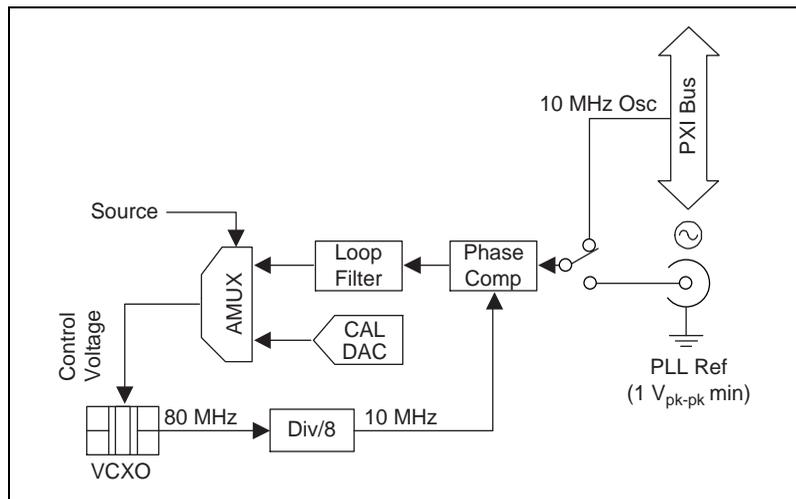


Figure 2-12. PLL Architecture for the NI 5401 for PXI

You can frequency lock to an external reference clock source of 1 MHz and from 5–20 MHz in 1 MHz increments. The PLL can lock to a signal level of at least 1 V_{pk-pk}.



Caution Do not increase the voltage level of the clock signal at the PLL reference input connector by more than the specified limit, 5 V_{pk-pk}.



Note If two or more NI 5401 devices are locked to each other using the same reference clock, they are frequency locked, but the phase relationship is indeterminate.

Analog Filter Correction

The NI 5401 can correct for slight deviations in the flatness of the frequency characteristic of the analog lowpass filter in its *passband*, as shown in Figure 2-13. Curve A shows a typical lowpass filter curve. The response of the filter is stored in an onboard *EEPROM* in 1 MHz increments up to 16 MHz. Curve C is the correction applied to the frequency response. The resulting Curve B is a flat response over the entire passband. If you want to generate a sine wave at a particular frequency with filter correction applied, you have to specify that frequency through your software.

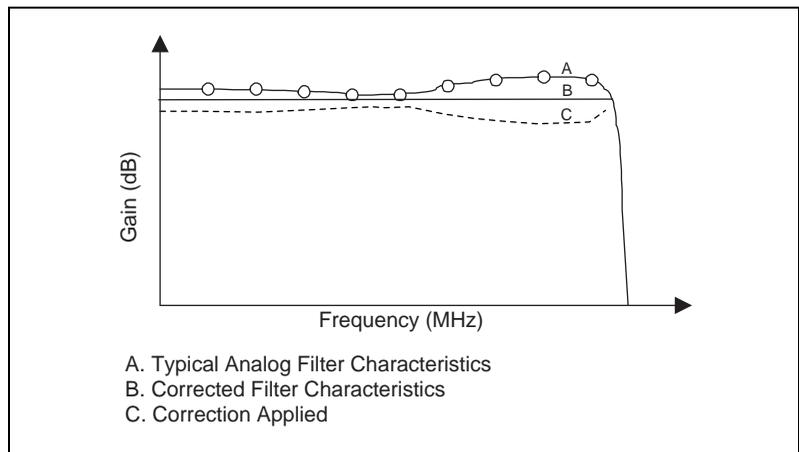


Figure 2-13. Analog Filter Correction



Note You can change the filter frequency correction at any time during waveform generation.

RTSI/PXI Trigger Lines

The NI 5401 for PCI contains seven trigger lines and one RTSI clock line available over the RTSI bus to send and receive NI 5401-specific information to other boards that have RTSI connectors. Figure 2-14 shows the RTSI trigger lines and routing of NI 5401 for PCI signals to the RTSI switch.

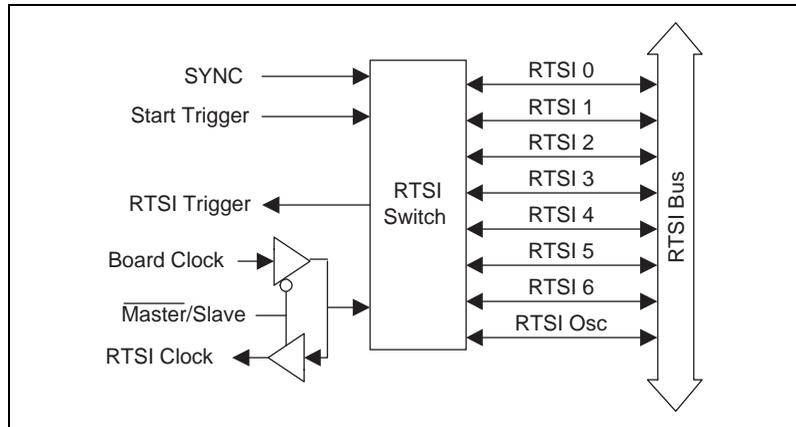


Figure 2-14. RTSI Trigger Lines and Routing for the NI 5401 for PCI

Figure 2-15 shows the PXI trigger lines and routing of NI 5401 for PXI signals to the RTSI switch.

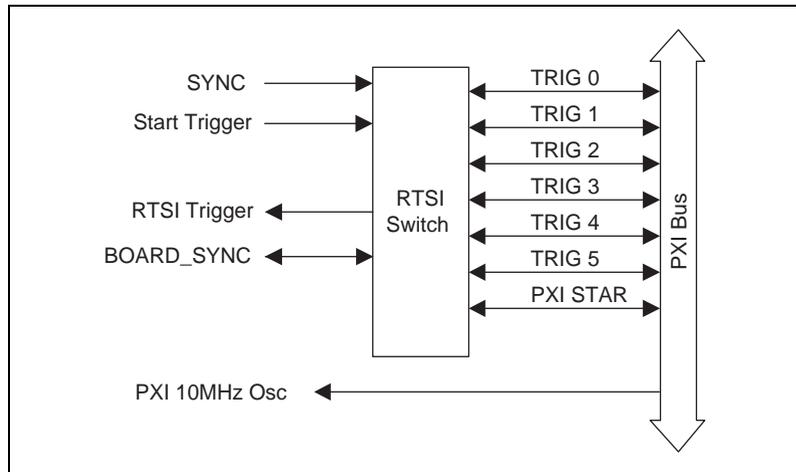


Figure 2-15. PXI Trigger Lines, 10 MHz Backplane Oscillator, and Routing for the NI 5401 for PXI

The NI 5401 can receive a hardware trigger from another board as a RTSI trigger signal on any of the RTSI/PXI trigger lines.

You can also route signals as follows:

- Route the Start Trigger signal generated on the NI 5401 to other boards through any of the RTSI/PXI bus trigger lines.
- Route the SYNC output generated on the NI 5401 to other boards through any of the RTSI/PXI bus trigger lines. You can use this signal to give other boards an accurate and fine frequency resolution clock.

◆ NI 5401 for PCI

For frequency locking to other boards as a master, the NI 5401 sends an onboard 20 MHz signal to the RTSI Osc line as a board clock signal. For locking to other devices as a slave, the NI 5401 receives the RTSI Osc line as a RTSI clock signal.

◆ NI 5401 for PXI

For frequency locking to other boards, the NI 5401 for PXI receives the PXI backplane 10 MHz Osc as a reference clock signal. All the NI 5401s for PXI use this common signal as the reference clock for frequency locking.



Note Refer to your software documentation for selecting and routing signals to the RTSI/PXI trigger bus.

Calibration

Calibration is the process of minimizing measurement errors by making small circuit adjustments. On the NI 5401, NI-FGEN automatically makes these adjustments by retrieving predetermined constants from the onboard EEPROM, calculating correction values, and writing those values to the CalDACs.

National Instruments calibrates all NI 5401 devices to the levels indicated in Appendix A, *Specifications*. Factory calibration involves procedures such as nulling the offset and gain errors. However, since offset and gain errors may drift with time and temperature, you may need to recalibrate your device. Contact National Instruments to recalibrate your NI 5401.

Specifications

This appendix lists the specifications for the NI 5401. These specifications are typical at 25 °C unless otherwise stated. The operating temperature range is 0 to 50 °C.

Analog Output

Number of channels	1
Resolution	12 bits
Maximum update rate	40 MHz
DDS accumulator	32 bits
Frequency range	
Sine	16 MHz, max
SYNC (TTL)	16 MHz, max
Square	1 MHz, max
Ramp	1 MHz, max
Triangle	1 MHz, max
Frequency resolution	9.31 mHz

Voltage Output

Ranges	± 5 V into a 50 Ω load ± 10 V into a high-impedance load
Accuracy	± 0.1 dB
Output attenuation	0 to 73 dB
Resolution	0.001 dB steps

Pre-attenuation offset	
Range	± 2.5 V into $50 \Omega^1$
Accuracy	± 5 mV
Output coupling	DC
Output impedance	50Ω or 75Ω software selectable
Load impedance	50Ω or greater
Output enable	Software switchable
Protection	Short-circuit protected

Sine Spectral Purity

Harmonic products and spurs	
Up to 1 MHz	-60 dBc
Up to 16 MHz	-35 dBc
Phase noise	-105 dBc/Hz at 10 kHz from carrier

Filter Characteristics

Digital

Type	Half-band interpolating
Selection	Software switchable (enable or disable)
Taps	67
Filter coefficients	Fixed 20-bit
Data interpolating frequency	80 MS/s
Pipeline signal delay	26 sampling periods

Analog

Type	7th-order L-C lowpass filter
Passband ripple	± 2 dB

¹ With less than 10 dB of attenuation, signal maximum plus offset (before attenuation) must not exceed ± 5 V (into 50Ω)

Waveform Specifications

Memory	16,384 16-bit samples
Segment length.....	16,384 samples, exact
Segment linking (instruction FIFO).....	512 links

Timing I/O

Update clock	Internal, 40 MHz only
Frequency locking	
External reference sources	Input connector, RTSI clock line, or internal
Reference clock frequencies	1 MHz, 5–20 MHz in 1 MHz steps
Frequency locking range.....	± 100 ppm

Triggers

Digital Trigger

Compatibility	TTL
Response	Rising edge
Pulse width (T_{d1}).....	20 ns min
Trigger to waveform output delay (T_{d2}).....	28 sample clocks + 150 ns max

RTSI

Trigger lines	7
Clock lines.....	1

Bus Interface

Type	Slave
------------	-------

Operational Modes

Type	Single, continuous, stepped
------------	-----------------------------

SYNC Out

Level	TTL
Duty cycle.....	20% to 80%, software controllable

External Clock Reference Input

Frequency	1 MHz or 5–20 MHz in 1 MHz steps
Amplitude	$1 V_{pk-pk} \leq \text{level} \leq 5 V_{pk-pk}$

Internal Clock

Frequency	40 MHz
Initial accuracy	± 5 ppm
Temperature stability (0 to 5 °C).....	± 25 ppm
Aging (1 year).....	± 5 ppm

Mechanical

Connectors

ARB (output)	SMB/BNC
SYNC (output).....	SMB/BNC
PLL reference (input)	SMB
External trigger in.....	50-pin digital (PCI), SMB (PXI)

Size1 slot

Power requirements5 V, 3.5 A max
12 V, 125 mA

Optional Accessories

National Instruments offers a variety of products to use with your NI 5401, including probes, cables, and other accessories:

- Shielded and unshielded I/O connector blocks (SCB-68, TBX-68, CB-68)
- RTSI bus cables

For more specific information about these products, refer to your National Instruments catalogue or Web site, or call the office nearest you.

Cabling

The following list gives recommended part numbers for cables that you can use with your NI 5401 device:

- BNC male to BNC male, 50 Ω cable from ITT Pomona Electronics (part number BNC-C-xx)
- BNC male to BNC male, 75 Ω cable from ITT Pomona Electronics (part number 2249-E-xx)
- BNC female to RCA phono plug adapter, from ITT Pomona Electronics (part number 5319)
- BNC 50 Ω feed-through terminator adapter from ITT Pomona Electronics (part number 4119-50)
- BNC female-female adapter from ITT Pomona Electronics (part number 3283)



Frequency Resolution and Lookup Memory

For DDS-based waveform generation, you must first load one cycle of the desired waveform into the lookup memory. The size of the DDS lookup memory is 16,384 samples. Each sample is 16 bits wide.



Note One cycle of the waveform buffer loaded into the memory should be exactly equal to the size of the DDS lookup memory.

F_c = update clock for the accumulator.

For the NI 5401, $F_c = 40$ MHz.

F_a = desired frequency of the output signal

N = accumulator size in bits

For the NI 5401, $N = 32$.

FCW = frequency control word to be loaded into the accumulator to generate F_a .

The frequency control word is calculated using the formula:

$$\text{FCW} = (2^N * F_a) / F_c$$

The frequency resolution is then given by:

$$\text{frequency resolution} = F_c / 2^N = (40 \times 10^6) / 2^{32} = 9.31322 \text{ mHz}$$

For example, if you need to generate a frequency of 10 MHz, then the FCW is $(2^{32} * 10E6)/40E6$, which equals 1,073,741,824. If you need to generate a frequency of 1 Hz, then the FCW is $(2^{32} * 1)/40E6$, which equals 107.



Note On the NI 5401, the maximum frequency of a sine wave you can generate reliably is limited to 16 MHz. Other waveforms such as square or triangular waves are limited to 1 MHz.

You can also synthesize arbitrary waveforms using DDS. Generating arbitrary waveforms this way will be very limited; you are restricted to a single buffer, and this buffer should be exactly equal to the size of the lookup memory (16,384 samples).

To update every sample of an arbitrary waveform in lookup memory at the maximum clock rate of 40 MHz, the software writes an FCW value of $2^{(N-L)}$, where N is the size of the accumulator and L is the number of address bits of lookup memory (L = 14 bits). Thus, the FCW value for the NI 5401 equals 262,144. Since $FCW = (2^N * F_a) / F_c$, $F_a = (2^{(N-L)} * F_c) / 2^N$, so you would write a frequency value of $(2^{(32-14)} \times (40 \times 10^6)) / 2^{32}$, which equals 2.441 kHz

If you want to update every sample in lookup memory at an integral subdivision, D, of the maximum clock rate, then you want an FCW value of $2^{(N-L-D+1)}$. In other words, for an effective update rate of every sample at half the maximum clock rate, write a frequency value of $(2^{(32-14-2+1)} \times (40 \times 10^6)) / 2^{32}$, which equals 1.221 kHz.

Technical Support Resources

This appendix describes the comprehensive resources available to you in the Technical Support section of the National Instruments Web site and provides technical support telephone numbers for you to use if you have trouble connecting to our Web site or if you do not have internet access.

NI Web Support

To provide you with immediate answers and solutions 24 hours a day, 365 days a year, National Instruments maintains extensive online technical support resources. They are available to you at no cost, are updated daily, and can be found in the Technical Support section of our Web site at www.natinst.com/support.

On-Line Problem-Solving and Diagnostic Resources

- **KnowledgeBase**—A searchable database containing thousands of frequently asked questions (FAQs) and their corresponding answers or solutions, including special sections devoted to our newest products. The database is updated daily in response to new customer experiences and feedback.
- **Troubleshooting Wizards**—Step-by-step guides lead you through common problems and answer questions about our entire product line. Wizards include screen shots that illustrate the steps being described and provide detailed information ranging from simple getting started instructions to advanced topics.
- **Product Manuals**—A comprehensive, searchable library of the latest editions of National Instruments hardware and software product manuals.
- **Hardware Reference Database**—A searchable database containing brief hardware descriptions, mechanical drawings, and helpful images of jumper settings and connector pinouts.
- **Application Notes**—A library with more than 100 short papers addressing specific topics such as creating and calling DLLs, developing your own instrument driver software, and porting applications between platforms and operating systems.

Software-Related Resources

- **Instrument Driver Network**—A library with hundreds of instrument drivers for control of standalone instruments via GPIB, VXI, or serial interfaces. You also can submit a request for a particular instrument driver if it does not already appear in the library.
- **Example Programs Database**—A database with numerous, non-shipping example programs for National Instruments programming environments. You can use them to complement the example programs that are already included with National Instruments products.
- **Software Library**—A library with updates and patches to application software, links to the latest versions of driver software for National Instruments hardware products, and utility routines.

Worldwide Support

National Instruments has offices located around the globe. Many branch offices maintain a Web site to provide information on local services. You can access these Web sites from www.natinst.com/worldwide.

If you have trouble connecting to our Web site, please contact your local National Instruments office or the source from which you purchased your National Instruments product(s) to obtain support.

For telephone support in the United States, dial 512 795 8248. For telephone support outside the United States, contact your local branch office:

Australia 03 9879 5166, Austria 0662 45 79 90 0, Belgium 02 757 00 20,
Brazil 011 284 5011, Canada (Ontario) 905 785 0085,
Canada (Québec) 514 694 8521, China 0755 3904939,
Denmark 45 76 26 00, Finland 09 725 725 11, France 01 48 14 24 24,
Germany 089 741 31 30, Hong Kong 2645 3186, India 91805275406,
Israel 03 6120092, Italy 02 413091, Japan 03 5472 2970,
Korea 02 596 7456, Mexico (D.F.) 5 280 7625,
Mexico (Monterrey) 8 357 7695, Netherlands 0348 433466,
Norway 32 27 73 00, Singapore 2265886, Spain (Madrid) 91 640 0085,
Spain (Barcelona) 93 582 0251, Sweden 08 587 895 00,
Switzerland 056 200 51 51, Taiwan 02 2377 1200,
United Kingdom 01635 523545

Glossary

Prefix	Meaning	Value
μ -	micro-	10^{-6}
m-	milli-	10^{-3}
k-	kilo-	10^3
M-	mega-	10^6

Numbers/Symbols

%	percent
+	positive of, or plus
-	negative of, or minus
\pm	plus or minus
/	per
$^{\circ}$	degree
Ω	ohm
+5 V	+5 V output signal

A

A	amperes
amplification	method of scaling the signal level to a higher level
ARB	normal waveform output signal
attenuation	decreasing the amplitude of a signal

B

b	bit—one binary digit, either 0 or 1
B	byte—eight related bits of data, an eight-bit binary number. Also used to denote the amount of memory required to store one byte of data.
BNC	a type of coaxial signal connector
buffer	temporary storage for acquired or generated data
bus	the group of conductors that interconnect individual circuitry in a computer. Typically, a bus is the expansion vehicle to which I/O or other devices are connected. Examples of PC buses are the AT bus (also known as the ISA bus) and the PCI bus.

C

C	Celsius
CalDAC	calibration DAC
clock	hardware component that controls timing for reading from or writing to groups
CMOS	complementary metal-oxide semiconductor
continuous trigger mode	repeats a staging list until waveform generation is stopped
counter	a circuit that counts external pulses or clock pulses (timing)
coupling	the manner in which a signal is connected from one location to another

D

DAC	digital-to-analog converter—an electronic device, often an integrated circuit, that converts a digital number into a corresponding analog voltage or current
dB	decibel—the unit for expressing a logarithmic measure of the ratio of two signal levels: $\text{dB} = 20 \log_{10} V1/V2$, for signals in volts
dBc	decibel referred to carrier level

DC	direct current
DC coupled	allowing the transmission of both AC and DC signals
DDS	direct digital synthesis—a digital technique of frequency generation using a numerically controlled oscillator (NCO), a dedicated lookup memory, and a DAC
DDS mode	a method of waveform generation that uses built-in DDS functionality to generate very high frequency resolution standard waveforms
DGND	digital ground signal
digital word	<i>See</i> word.
driver	software that controls a specific hardware device
dynamic range	the ratio of the largest signal level a circuit can handle to the smallest signal level it can handle (usually taken to be the noise level), normally expressed in dB
E	
EEPROM	electrically erasable programmable read-only memory—ROM that can be erased with an electrical signal and reprogrammed
external trigger	a voltage pulse from an external source that triggers an event such as A/D conversion
EXT_TRIG	external trigger input signal

F

FIFO	first-in first-out memory buffer—the first data stored is the first data sent to the acceptor. FIFOs are often used on DAQ devices to temporarily store incoming or outgoing data until that data can be retrieved or output. For example, an analog input FIFO stores the results of A/D conversions until the data can be retrieved into system memory, a process that requires the servicing of interrupts and often the programming of the DMA controller. This process can take several milliseconds in some cases. During this time, data accumulates in the FIFO for future retrieval. With a larger FIFO, longer latencies can be tolerated. In the case of analog output, a FIFO permits faster update rates, because the waveform data can be stored on the FIFO ahead of time. This again reduces the effect of latencies associated with getting the data from system memory to the DAQ device.
filters	digital or analog circuits that change the frequency characteristics of a waveform
frequency hop	change from one frequency to another
frequency resolution	the smallest frequency change that can be generated by a NI 5411/5431
frequency sweep	change the frequency of a waveform in a controlled manner

G

gain	the factor by which a signal is amplified, sometimes expressed in decibels
GUI	graphical user interface

H

hardware	the physical components of a computer system, such as the circuit boards, plug-in boards, chassis, enclosures, peripherals, cables, and so on
HiZ	high impedance
Hz	hertz—the number of cycles or repetitions per second

I

I/O	input/output—the transfer of data to/from a computer system involving communications channels, operator interface devices, and/or data acquisition and control interfaces
IFIFO	instruction FIFO
instruction FIFO	the FIFO that stores the waveform generation staging list

K

k	kilo—the standard metric prefix for 1,000, or 10^3 , used with units of measure such as volts, hertz, and meters
K	kilo—the prefix for 1,024, or 2^{10} , used with B in quantifying data or computer memory
kS	1,000 samples
Kword	1,024 words of memory

L

latch	a digital device that stores digital data based on a control signal
level DAC	the calibration DAC used to change the voltage levels to another device
linking	linking different buffers stored in the waveform memory
looping	repeating the same buffer in the waveform memory. This method of waveform generation decreases memory requirements.
lowpass filter	a circuit used to smooth the waveform output and removed unwanted high frequency contents from the signal

M

m	meters
M	(1) Mega, the standard metric prefix for 1 million or 10^6 , when used with units of measure such as volts and hertz; (2) mega, the prefix for 1,048,576, or 2^{20} , when used with B to quantify data or computer memory
master/slave	locking the NI 5401 clock in frequency to an external phase locking reference clock source
MB	megabytes of memory

N

noise	an undesirable electrical signal—Noise comes from external sources such as the AC power line, motors, generators, transformers, fluorescent lights, soldering irons, CRT displays, computers, electrical storms, welders, radio transmitters, and internal sources such as semiconductors, resistors, and capacitors. Noise corrupts signals you are trying to send or receive.
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O

output enable relay	a relay switch at the output of the NI 5401 that can enable the waveform generation at any time or that can connect the output to ground
---------------------	--

P

passband	the range of frequencies which a device can properly propagate or measure
PCI	Peripheral Component Interconnect—a high-performance expansion bus architecture originally developed by Intel to replace ISA and EISA. It is achieving widespread acceptance as a standard for PCs and work-stations; it offers a theoretical maximum transfer rate of 132 Mbytes/s.
PCLK	digital pattern clock output
peak-to-peak	a measure of signal amplitude; the difference between the highest and lowest excursions of the signal

pipeline	a high-performance processor structure in which the completion of an instruction is broken into its elements so that several elements can be processed simultaneously from different instructions
PLL	phase-locked loop—a circuit that synthesizes a signal whose frequency is exactly proportional to the frequency of a reference signal
PLL Ref	a PLL input that accepts an external reference clock signal and phase locks to it the NI 5401 internal clock
Plug and Play devices	devices that do not require dip switches or jumpers to configure resources on the devices—also called switchless devices
ppm	parts per million
pre-attenuation offset	an offset provided to the signal before it reaches the attenuators
protocol	the exact sequence of bits, characters, and control codes used to transfer data between computers and peripherals through a communications channel, such as the GPIB bus
PXI	PCI eXtensions for Instrumentation

R

resolution	the smallest signal increment that can be detected by a measurement system. Resolution can be expressed in bits, in proportions, or in percent of full scale. For example, a system has 12-bit resolution, one part in 4,096 resolution, and 0.0244 percent of full scale.
RTSI bus	Real-Time System Integration bus—the National Instruments timing bus that connects DAQ boards directly, by means of connectors on top of the boards, for precise synchronization of functions

S

s	seconds
S	samples
sampling rate	the rate, in samples per second (S/s), at which each sample in the waveform buffer is updated

SCSI	Small Computer System Interface (bus)
sequence list	<i>See</i> staging list.
shift-keying	frequency shift keying (FSK)
single trigger mode	when the arbitrary waveform generator goes through the staging list only once
SMB	Sub Miniature Type B connector that features a snap coupling for fast connection
S/s	samples per second—used to express the rate at which a DAQ board samples an analog signal
stage	in Arb mode, specifies the buffer to be generated, the number of loops on that buffer, the marker position for that buffer, and the sample count for the buffer; for DDS mode, specifies the frequency to be generated of the waveform in the lookup memory and the time for which that frequency has to be generated
staging list	a buffer that contains linking and looping information for multiple waveforms; also known as a sequence list or waveform sequence
stepped trigger mode	a mode of waveform generation used when you want a trigger to advance the waveforms specified by the stages in the staging list
SYNC	TTL version of the sine waveform output signal generated by the NI 5401
T	
trigger	any event that causes or starts some form of data capture
TTL	transistor-transistor logic
U	
update rate	the rate at which a DAC is updated

V

V	volts
VCXO	voltage controlled crystal oscillator
VHDSCSI	very high-density SCSI

W

waveform	multiple voltage readings taken at a specific sampling rate
waveform buffer	the collection of 16-bit data samples stored in the waveform memory that represent a desired waveform. Also known as a waveform segment.
waveform linking and looping	<i>See</i> linking, looping.
waveform memory	physical data storage on the NI 5401 for storing the waveform data samples
waveform segment	<i>See</i> waveform buffer.
waveform sequence	<i>See</i> staging list.
waveform staging	<i>See</i> linking, looping.
word	The standard number of bits that a processor or memory manipulates at one time. Microprocessors typically use 8-, 16-, or 32-bit words.

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